

# 74LVC2T45-Q100; 74LVCH2T45-Q100

Dual supply translating transceiver; 3-state

Rev. 3 — 28 January 2019

Product data sheet

## 1. General description

The 74LVC2T45-Q100; 74LVCH2T45-Q100 are dual bit, dual supply translating transceivers with 3-state outputs that enable bidirectional level translation. They feature two 2-bits input-output ports (nA and nB), a direction control input (DIR) and dual supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ). Both  $V_{CC(A)}$  and  $V_{CC(B)}$  can be supplied at any voltage between 1.2 V and 5.5 V making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins nA and DIR are referenced to  $V_{CC(A)}$  and pins nB are referenced to  $V_{CC(B)}$ . A HIGH on DIR allows transmission from nA to nB and a LOW on DIR allows transmission from nB to nA.

The devices are fully specified for partial power-down applications using  $I_{OFF}$ . The  $I_{OFF}$  circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either  $V_{CC(A)}$  or  $V_{CC(B)}$  are at GND level, both A port and B port are in the high-impedance OFF-state.

Active bus hold circuitry in the 74LVCH2T45-Q100 holds unused or floating data inputs at a valid logic level.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

## 2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
  - Specified from -40 °C to +85 °C and from -40 °C to +125 °C
- Wide supply voltage range:
  - $V_{CC(A)}$ : 1.2 V to 5.5 V
  - $V_{CC(B)}$ : 1.2 V to 5.5 V
- High noise immunity
- Complies with JEDEC standards:
  - JESD8-7 (1.2 V to 1.95 V)
  - JESD8-5 (1.8 V to 2.7 V)
  - JESD8C (2.7 V to 3.6 V)
  - JESD36 (4.5 V to 5.5 V)
- ESD protection:
  - MIL-STD-883, method 3015 Class 3A exceeds 4000 V
  - HBM JESD22-A114F Class 3A exceeds 4000 V
  - MM JESD22-A115-A exceeds 200 V (C = 200 pF, R = 0 Ω)
- Maximum data rates:
  - 420 Mbps (3.3 V to 5.0 V translation)
  - 210 Mbps (translate to 3.3 V)
  - 140 Mbps (translate to 2.5 V)
  - 75 Mbps (translate to 1.8 V)
  - 60 Mbps (translate to 1.5 V)
- Suspend mode
- Latch-up performance exceeds 100 mA per JESD 78 Class II
- ±24 mA output drive ( $V_{CC} = 3.0 V$ )
- Inputs accept voltages up to 5.5 V
- Low power consumption: 16 µA maximum  $I_{CC}$

- I<sub>OFF</sub> circuitry provides partial Power-down mode operation

### 3. Ordering information

Table 1. Ordering information

Type number	Package			Version
	Temperature range	Name	Description	
74LVC2T45DC-Q100	-40 °C to +125 °C	VSSOP8	plastic very thin shrink small outline package; 8 leads; body width 2.3 mm	SOT765-1
74LVCH2T45DC-Q100				
74LVC2T45GT-Q100	-40 °C to +125 °C	XSON8	plastic extremely thin small outline package; no leads; 8 terminals; body 1 × 1.95 × 0.5 mm	SOT833-1
74LVC2T45GS-Q100	-40 °C to +125 °C	XSON8	extremely thin small outline package; no leads; 8 terminals; body 1.35 × 1.0 × 0.35 mm	SOT1203

### 4. Marking

Table 2. Marking

Type number	Marking code [1]
74LVC2T45DC-Q100	V45
74LVCH2T45DC-Q100	X45
74LVC2T45GT-Q100	V45
74LVC2T45GS-Q100	V5

[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

### 5. Functional diagram

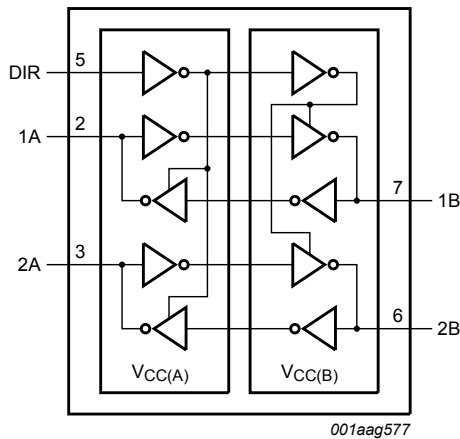


Fig. 1. Logic symbol

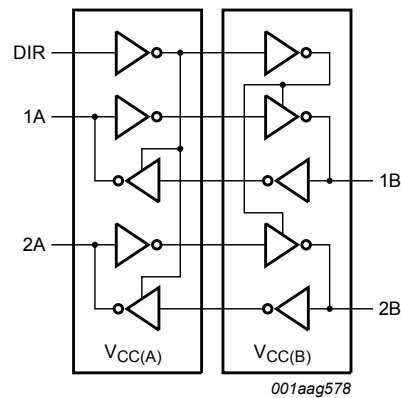


Fig. 2. Logic diagram

## 6. Pinning information

### 6.1. Pinning

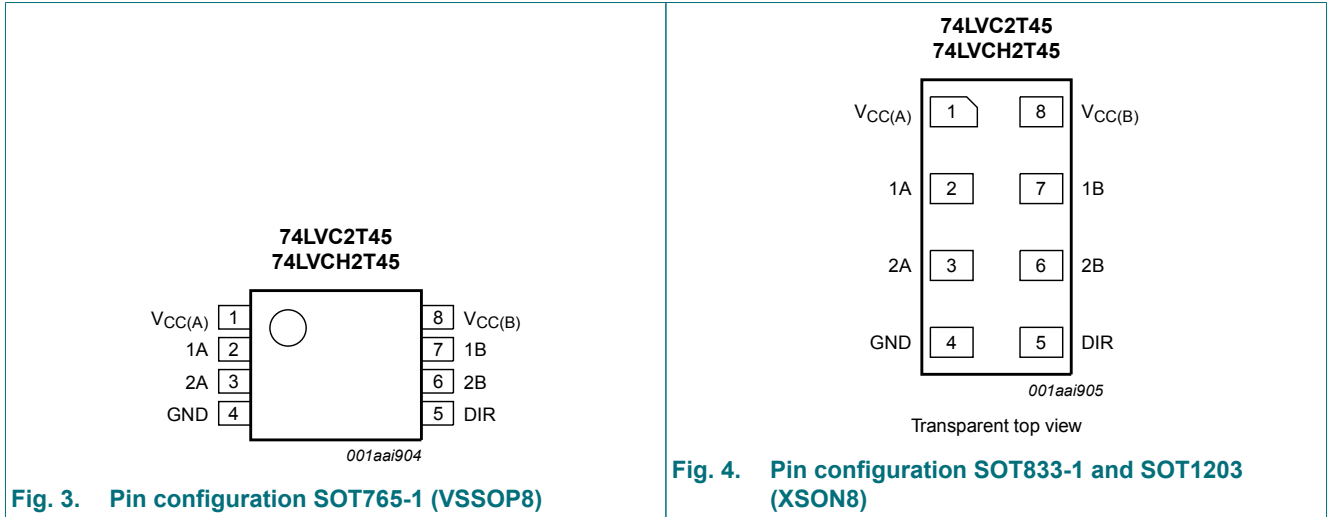


Fig. 3. Pin configuration SOT765-1 (VSSOP8)

Fig. 4. Pin configuration SOT833-1 and SOT1203 (XSON8)

### 6.2. Pin description

Table 3. Pin description

Symbol	Pin	Description
V <sub>CC(A)</sub>	1	supply voltage A (port A and DIR)
1A	2	data input or output
2A	3	data input or output
GND	4	ground (0 V)
DIR	5	direction control
2B	6	data input or output
1B	7	data input or output
V <sub>CC(B)</sub>	8	supply voltage B (port B)

## 7. Functional description

Table 4. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

Supply voltage	Input	Input/output [1]	
V <sub>CC(A)</sub> , V <sub>CC(B)</sub>	DIR	nA	nB
1.2 V to 5.5 V	L	nA = nB	input
1.2 V to 5.5 V	H	input	nB = nA
GND [2]	X	Z	Z

[1] The input circuit of the data I/O is always active.

[2] When either V<sub>CC(A)</sub> or V<sub>CC(B)</sub> is at GND level, the device goes into suspend mode.

## 8. Limiting values

**Table 5. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
$V_{CC(B)}$	supply voltage B		-0.5	+6.5	V
$I_{IK}$	input clamping current	$V_I < 0$ V	-50	-	mA
$V_I$	input voltage	[1]	-0.5	+6.5	V
$I_{OK}$	output clamping current	$V_O < 0$ V	-50	-	mA
$V_O$	output voltage	Active mode [1][2][3]	-0.5	$V_{CCO} + 0.5$	V
		Suspend or 3-state mode [1]	-0.5	+6.5	V
$I_O$	output current	$V_O = 0$ V to $V_{CCO}$ [2]	-	±50	mA
$I_{CC}$	supply current	$I_{CC(A)}$ or $I_{CC(B)}$	-	100	mA
$I_{GND}$	ground current		-100	-	mA
$T_{stg}$	storage temperature		-65	+150	°C
$P_{tot}$	total power dissipation	$T_{amb} = -40$ °C to +125 °C [4]	-	250	mW

- [1] The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed.  
 [2]  $V_{CCO}$  is the supply voltage associated with the output port.  
 [3]  $V_{CCO} + 0.5$  V should not exceed 6.5 V.  
 [4] For VSSOP8 packages: above 110 °C the value of  $P_{tot}$  derates linearly with 8.0 mW/K.  
 For XSON8 packages: above 118 °C the value of  $P_{tot}$  derates linearly with 7.8 mW/K.

## 9. Recommended operating conditions

**Table 6. Recommended operating conditions**

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		1.2	5.5	V
$V_{CC(B)}$	supply voltage B		1.2	5.5	V
$V_I$	input voltage		0	5.5	V
$V_O$	output voltage	Active mode [1]	0	$V_{CCO}$	V
		Suspend or 3-state mode	0	5.5	V
$T_{amb}$	ambient temperature		-40	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{CCI} = 1.2$ V [2]	-	20	ns/V
		$V_{CCI} = 1.4$ V to 1.95 V	-	20	ns/V
		$V_{CCI} = 2.3$ V to 2.7 V	-	20	ns/V
		$V_{CCI} = 3$ V to 3.6 V	-	10	ns/V
		$V_{CCI} = 4.5$ V to 5.5 V	-	5	ns/V

- [1]  $V_{CCO}$  is the supply voltage associated with the output port.  
 [2]  $V_{CCI}$  is the supply voltage associated with the input port.

## 10. Static characteristics

**Table 7. Typical static characteristics at  $T_{amb} = 25\text{ °C}$**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{OH}$	HIGH-level output voltage	$V_I = V_{IH}$ or $V_{IL}$ ; $I_O = -3\text{ mA}$ ; $V_{CCO} = 1.2\text{ V}$ [1]	-	1.09	-	V
$V_{OL}$	LOW-level output voltage	$V_I = V_{IH}$ or $V_{IL}$ ; $I_O = 3\text{ mA}$ ; $V_{CCO} = 1.2\text{ V}$ [1]	-	0.07	-	V
$I_I$	input leakage current	DIR input; $V_I = 0\text{ V}$ to $5.5\text{ V}$ ; $V_{CCI} = 1.2\text{ V}$ to $5.5\text{ V}$ [2]	-	-	$\pm 1$	$\mu\text{A}$
$I_{BHL}$	bus hold LOW current	A or B port; $V_I = 0.42\text{ V}$ ; $V_{CCI} = 1.2\text{ V}$ [2]	-	19	-	$\mu\text{A}$
$I_{BHH}$	bus hold HIGH current	A or B port; $V_I = 0.78\text{ V}$ ; $V_{CCI} = 1.2\text{ V}$ [2]	-	-19	-	$\mu\text{A}$
$I_{BHLO}$	bus hold LOW overdrive current	A or B port; $V_{CCI} = 1.2\text{ V}$ [2][3]	-	19	-	$\mu\text{A}$
$I_{BHHO}$	bus hold HIGH overdrive current	A or B port; $V_{CCI} = 1.2\text{ V}$ [2][3]	-	-19	-	$\mu\text{A}$
$I_{OZ}$	OFF-state output current	A or B port; $V_O = 0\text{ V}$ or $V_{CCO}$ ; $V_{CCO} = 1.2\text{ V}$ to $5.5\text{ V}$ [1]	-	-	$\pm 1$	$\mu\text{A}$
$I_{OFF}$	power-off leakage current	A port; $V_I$ or $V_O = 0\text{ V}$ to $5.5\text{ V}$ ; $V_{CC(A)} = 0\text{ V}$ ; $V_{CC(B)} = 1.2\text{ V}$ to $5.5\text{ V}$	-	-	$\pm 1$	$\mu\text{A}$
		B port; $V_I$ or $V_O = 0\text{ V}$ to $5.5\text{ V}$ ; $V_{CC(B)} = 0\text{ V}$ ; $V_{CC(A)} = 1.2\text{ V}$ to $5.5\text{ V}$	-	-	$\pm 1$	$\mu\text{A}$
$C_I$	input capacitance	DIR input; $V_I = 0\text{ V}$ or $3.3\text{ V}$ ; $V_{CC(A)} = V_{CC(B)} = 3.3\text{ V}$	-	2.2	-	pF
$C_{I/O}$	input/output capacitance	A and B port; suspend mode; $V_O = 3.3\text{ V}$ or $0\text{ V}$ ; $V_{CC(A)} = V_{CC(B)} = 3.3\text{ V}$	-	6.0	-	pF

[1]  $V_{CCO}$  is the supply voltage associated with the output port.

[2]  $V_{CCI}$  is the supply voltage associated with the data input port.

[3] To guarantee the node switches, an external driver must source/sink at least  $I_{BHLO}/I_{BHHO}$  when the input is in the range  $V_{IL}$  to  $V_{IH}$ .

**Table 8. Static characteristics**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Max	Min	Max	
$V_{IH}$	HIGH-level input voltage	data input [1]					
		$V_{CCI} = 1.2\text{ V}$	$0.8V_{CCI}$	-	$0.8V_{CCI}$	-	V
		$V_{CCI} = 1.4\text{ V}$ to $1.95\text{ V}$	$0.65V_{CCI}$	-	$0.65V_{CCI}$	-	V
		$V_{CCI} = 2.3\text{ V}$ to $2.7\text{ V}$	1.7	-	1.7	-	V
		$V_{CCI} = 3.0\text{ V}$ to $3.6\text{ V}$	2.0	-	2.0	-	V
		$V_{CCI} = 4.5\text{ V}$ to $5.5\text{ V}$	$0.7V_{CCI}$	-	$0.7V_{CCI}$	-	V
		DIR input					
		$V_{CCI} = 1.2\text{ V}$	$0.8V_{CC(A)}$	-	$0.8V_{CC(A)}$	-	V
		$V_{CCI} = 1.4\text{ V}$ to $1.95\text{ V}$	$0.65V_{CC(A)}$	-	$0.65V_{CC(A)}$	-	V
		$V_{CCI} = 2.3\text{ V}$ to $2.7\text{ V}$	1.7	-	1.7	-	V
$V_{CCI} = 3.0\text{ V}$ to $3.6\text{ V}$	2.0	-	2.0	-	V		
$V_{CCI} = 4.5\text{ V}$ to $5.5\text{ V}$	$0.7V_{CC(A)}$	-	$0.7V_{CC(A)}$	-	V		

Symbol	Parameter	Conditions	-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Max	Min	Max	
V <sub>IL</sub>	LOW-level input voltage	data input [1]					
		V <sub>CCI</sub> = 1.2 V	-	0.2V <sub>CCI</sub>	-	0.2V <sub>CCI</sub>	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	-	0.8	-	0.8	V
		V <sub>CCI</sub> = 4.5 V to 5.5 V	-	0.3V <sub>CCI</sub>	-	0.3V <sub>CCI</sub>	V
		DIR input					
		V <sub>CCI</sub> = 1.2 V	-	0.2V <sub>CC(A)</sub>	-	0.2V <sub>CC(A)</sub>	V
		V <sub>CCI</sub> = 1.4 V to 1.95 V	-	0.35V <sub>CC(A)</sub>	-	0.35V <sub>CC(A)</sub>	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	-	0.8	-	0.8	V
V <sub>CCI</sub> = 4.5 V to 5.5 V	-	0.3V <sub>CC(A)</sub>	-	0.3V <sub>CC(A)</sub>	V		
V <sub>OH</sub>	HIGH-level output voltage	V <sub>I</sub> = V <sub>IH</sub>					
		I <sub>O</sub> = -100 µA; V <sub>CCO</sub> = 1.2 V to 4.5 V [2]	V <sub>CCO</sub> - 0.1	-	V <sub>CCO</sub> - 0.1	-	V
		I <sub>O</sub> = -6 mA; V <sub>CCO</sub> = 1.4 V	1.0	-	1.0	-	V
		I <sub>O</sub> = -8 mA; V <sub>CCO</sub> = 1.65 V	1.2	-	1.2	-	V
		I <sub>O</sub> = -12 mA; V <sub>CCO</sub> = 2.3 V	1.9	-	1.9	-	V
		I <sub>O</sub> = -24 mA; V <sub>CCO</sub> = 3.0 V	2.4	-	2.4	-	V
I <sub>O</sub> = -32 mA; V <sub>CCO</sub> = 4.5 V	3.8	-	3.8	-	V		
V <sub>OL</sub>	LOW-level output voltage	V <sub>I</sub> = V <sub>IL</sub> [2]					
		I <sub>O</sub> = 100 µA; V <sub>CCO</sub> = 1.2 V to 4.5 V	-	0.1	-	0.1	V
		I <sub>O</sub> = 6 mA; V <sub>CCO</sub> = 1.4 V	-	0.3	-	0.3	V
		I <sub>O</sub> = 8 mA; V <sub>CCO</sub> = 1.65 V	-	0.45	-	0.45	V
		I <sub>O</sub> = 12 mA; V <sub>CCO</sub> = 2.3 V	-	0.3	-	0.3	V
		I <sub>O</sub> = 24 mA; V <sub>CCO</sub> = 3.0 V	-	0.55	-	0.55	V
I <sub>O</sub> = 32 mA; V <sub>CCO</sub> = 4.5 V	-	0.55	-	0.55	V		
I <sub>I</sub>	input leakage current	DIR input; V <sub>I</sub> = 0 V to 5.5 V; V <sub>CCI</sub> = 1.2 V to 5.5 V	-	±2	-	±10	µA
I <sub>BHL</sub>	bus hold LOW current	A or B port [1]					
		V <sub>I</sub> = 0.49 V; V <sub>CCI</sub> = 1.4 V	15	-	10	-	µA
		V <sub>I</sub> = 0.58 V; V <sub>CCI</sub> = 1.65 V	25	-	20	-	µA
		V <sub>I</sub> = 0.70 V; V <sub>CCI</sub> = 2.3 V	45	-	45	-	µA
		V <sub>I</sub> = 0.80 V; V <sub>CCI</sub> = 3.0 V	100	-	80	-	µA
V <sub>I</sub> = 1.35 V; V <sub>CCI</sub> = 4.5 V	100	-	100	-	µA		
I <sub>BHH</sub>	bus hold HIGH current	A or B port [1]					
		V <sub>I</sub> = 0.91 V; V <sub>CCI</sub> = 1.4 V	-15	-	-10	-	µA
		V <sub>I</sub> = 1.07 V; V <sub>CCI</sub> = 1.65 V	-25	-	-20	-	µA
		V <sub>I</sub> = 1.60 V; V <sub>CCI</sub> = 2.3 V	-45	-	-45	-	µA
		V <sub>I</sub> = 2.00 V; V <sub>CCI</sub> = 3.0 V	-100	-	-80	-	µA
V <sub>I</sub> = 3.15 V; V <sub>CCI</sub> = 4.5 V	-100	-	-100	-	µA		

Symbol	Parameter	Conditions	-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Max	Min	Max	
I <sub>BHLO</sub>	bus hold LOW overdrive current	A or B port [1][3]					
		V <sub>CCI</sub> = 1.6 V	125	-	125	-	μA
		V <sub>CCI</sub> = 1.95 V	200	-	200	-	μA
		V <sub>CCI</sub> = 2.7 V	300	-	300	-	μA
		V <sub>CCI</sub> = 3.6 V	500	-	500	-	μA
	V <sub>CCI</sub> = 5.5 V	900	-	900	-	μA	
I <sub>BHHO</sub>	bus hold HIGH overdrive current	A or B port [1][3]					
		V <sub>CCI</sub> = 1.6 V	-125	-	-125	-	μA
		V <sub>CCI</sub> = 1.95 V	-200	-	-200	-	μA
		V <sub>CCI</sub> = 2.7 V	-300	-	-300	-	μA
		V <sub>CCI</sub> = 3.6 V	-500	-	-500	-	μA
	V <sub>CCI</sub> = 5.5 V	-900	-	-900	-	μA	
I <sub>OZ</sub>	OFF-state output current	A or B port; V <sub>O</sub> = 0 V or V <sub>CCO</sub> ; V <sub>CCO</sub> = 1.2 V to 5.5 V [2]	-	±2	-	±10	μA
I <sub>OFF</sub>	power-off leakage current	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 1.2 V to 5.5 V	-	±2	-	±10	μA
		B port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 5.5 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 1.2 V to 5.5 V	-	±2	-	±10	μA
I <sub>CC</sub>	supply current	A port; V <sub>I</sub> = 0 V or V <sub>CCI</sub> ; I <sub>O</sub> = 0 A [1]					
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.2 V to 5.5 V	-	8	-	8	μA
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	3	-	3	μA
		V <sub>CC(A)</sub> = 5.5 V; V <sub>CC(B)</sub> = 0 V	-	2	-	2	μA
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 5.5 V	-2	-	-2	-	μA
		B port; V <sub>I</sub> = 0 V or V <sub>CCI</sub> ; I <sub>O</sub> = 0 A					
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.2 V to 5.5 V	-	8	-	8	μA
		V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	3	-	3	μA
		V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 5.5 V	-2	-	-2	-	μA
		V <sub>CC(B)</sub> = 5.5 V; V <sub>CC(A)</sub> = 0 V	-	2	-	2	μA
		A plus B port (I <sub>CC(A)</sub> + I <sub>CC(B)</sub> ); I <sub>O</sub> = 0 A; V <sub>I</sub> = 0 V or V <sub>CCI</sub>					
V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.2 V to 5.5 V	-	16	-	16	μA		
V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 1.65 V to 5.5 V	-	4	-	4	μA		
ΔI <sub>CC</sub>	additional supply current	per input; V <sub>CC(A)</sub> , V <sub>CC(B)</sub> = 3.0 V to 5.5 V					
		A port; A port at V <sub>CC(A)</sub> - 0.6 V; DIR at V <sub>CC(A)</sub> ; B port = open [4]	-	50	-	75	μA
		DIR input; DIR at V <sub>CC(A)</sub> - 0.6 V; A port at V <sub>CC(A)</sub> or GND; B port = open	-	50	-	75	μA
		B port; B port at V <sub>CC(B)</sub> - 0.6 V; DIR at GND; A port = open [4]	-	50	-	75	μA

[1] V<sub>CCI</sub> is the supply voltage associated with the data input port.

[2] V<sub>CCO</sub> is the supply voltage associated with the output port.

[3] To guarantee the node switches, an external driver must source/sink at least I<sub>BHLO</sub>/I<sub>BHHO</sub> when the input is in the range V<sub>IL</sub> to V<sub>IH</sub>.

[4] For non bus hold parts only (74LVC2T45-Q100).

## 11. Dynamic characteristics

**Table 9. Typical dynamic characteristics at  $V_{CC(A)} = 1.2\text{ V}$  and  $T_{amb} = 25\text{ °C}$**

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6.

Symbol	Parameter	Conditions	$V_{CC(B)}$						Unit
			1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
$t_{PLH}$	LOW to HIGH propagation delay	A to B	10.6	8.1	7.0	5.8	5.3	5.1	ns
		B to A	10.6	9.5	9.0	8.5	8.3	8.2	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	10.1	7.1	6.0	5.3	5.2	5.4	ns
		B to A	10.1	8.6	8.1	7.8	7.6	7.6	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	9.4	9.4	9.4	9.4	9.4	9.4	ns
		DIR to B	12.0	9.4	9.0	7.8	8.4	7.9	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	7.1	7.1	7.1	7.1	7.1	7.1	ns
		DIR to B	9.5	7.8	7.7	6.9	7.6	7.0	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	20.1	17.3	16.7	15.4	15.9	15.2	ns
		DIR to B [1]	17.7	15.2	14.1	12.9	12.4	12.2	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	22.1	18.0	17.1	15.6	16.0	15.5	ns
		DIR to B [1]	19.5	16.5	15.4	14.7	14.6	14.8	ns

[1]  $t_{PZH}$  and  $t_{PZL}$  are calculated values using the formula shown in Section 13.4.

**Table 10. Typical dynamic characteristics at  $V_{CC(B)} = 1.2\text{ V}$  and  $T_{amb} = 25\text{ °C}$**

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6.

Symbol	Parameter	Conditions	$V_{CC(A)}$						Unit
			1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	5.0 V	
$t_{PLH}$	LOW to HIGH propagation delay	A to B	10.6	9.5	9.0	8.5	8.3	8.2	ns
		B to A	10.6	8.1	7.0	5.8	5.3	5.1	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	10.1	8.6	8.1	7.8	7.6	7.6	ns
		B to A	10.1	7.1	6.0	5.3	5.2	5.4	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	9.4	6.5	5.7	4.1	4.1	3.0	ns
		DIR to B	12.0	6.1	5.4	4.6	4.3	4.0	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	7.1	4.9	4.5	3.2	3.4	2.5	ns
		DIR to B	9.5	7.3	6.6	5.9	5.7	5.6	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	20.1	15.4	13.6	11.7	11.0	10.7	ns
		DIR to B [1]	17.7	14.4	13.5	11.7	11.7	10.7	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	22.1	13.2	11.4	9.9	9.5	9.4	ns
		DIR to B [1]	19.5	15.1	13.8	11.9	11.7	10.6	ns

[1]  $t_{PZH}$  and  $t_{PZL}$  are calculated values using the formula shown in Section 13.4.



**Table 11. Typical power dissipation capacitance at  $V_{CC(A)} = V_{CC(B)}$  and  $T_{amb} = 25\text{ °C}$**

*Voltages are referenced to GND (ground = 0 V).*

Symbol	Parameter	Conditions	$V_{CC(A)}$ and $V_{CC(B)}$				Unit
			1.8 V	2.5 V	3.3 V	5.0 V	
C <sub>PD</sub>	power dissipation capacitance[1] [2]	A port: (direction A to B); B port: (direction B to A)	2	3	3	4	pF
		A port: (direction A to B); B port: (direction B to A)	15	16	16	18	pF

[1] C<sub>PD</sub> is used to determine the dynamic power dissipation (P<sub>D</sub> in μW).

$$P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma(C_L \times V_{CC}^2 \times f_o) \text{ where:}$$

f<sub>i</sub> = input frequency in MHz;

f<sub>o</sub> = output frequency in MHz;

C<sub>L</sub> = load capacitance in pF;

V<sub>CC</sub> = supply voltage in V;

N = number of inputs switching;

$\Sigma(C_L \times V_{CC}^2 \times f_o)$  = sum of the outputs.

[2] f<sub>i</sub> = 10 MHz; V<sub>i</sub> = GND to V<sub>CC</sub>; t<sub>r</sub> = t<sub>f</sub> = 1 ns; C<sub>L</sub> = 0 pF; R<sub>L</sub> = ∞ Ω.

**Table 12. Dynamic characteristics for temperature range -40 °C to +85 °C**

*Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 7; for waveforms see Fig. 5 and Fig. 6.*

Symbol	Parameter	Conditions	$V_{CC(B)}$										Unit
			1.5 V ± 0.1 V		1.8 V ± 0.15 V		2.5 V ± 0.2 V		3.3 V ± 0.3 V		5.0 V ± 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
<b><math>V_{CC(A)} = 1.4\text{ V to }1.6\text{ V}</math></b>													
t <sub>PLH</sub>	LOW to HIGH propagation delay	A to B	2.8	21.3	2.4	17.6	2.0	13.5	1.7	11.8	1.6	10.5	ns
		B to A	2.8	21.3	2.6	19.1	2.3	14.9	2.3	12.4	2.2	12.0	ns
t <sub>PHL</sub>	HIGH to LOW propagation delay	A to B	2.6	19.3	2.2	15.3	1.8	11.8	1.7	10.9	1.7	10.8	ns
		B to A	2.6	19.3	2.4	17.3	2.3	13.2	2.2	11.3	2.3	11.0	ns
t <sub>PHZ</sub>	HIGH to OFF-state propagation delay	DIR to A	3.0	18.7	3.0	18.7	3.0	18.7	3.0	18.7	3.0	18.7	ns
		DIR to B	3.5	24.8	3.5	23.6	3.0	11.0	3.3	11.3	2.8	10.3	ns
t <sub>PLZ</sub>	LOW to OFF-state propagation delay	DIR to A	2.4	11.4	2.4	11.4	2.4	11.4	2.4	11.4	2.4	11.4	ns
		DIR to B	2.8	18.3	3.0	17.2	2.5	9.4	3.0	10.1	2.5	9.4	ns
t <sub>PZH</sub>	OFF-state to HIGH propagation delay	DIR to A [1]	-	39.6	-	36.3	-	24.3	-	22.5	-	21.4	ns
		DIR to B [1]	-	32.7	-	29.0	-	24.9	-	23.2	-	21.9	ns
t <sub>PZL</sub>	OFF-state to LOW propagation delay	DIR to A [1]	-	44.1	-	40.9	-	24.2	-	22.6	-	21.3	ns
		DIR to B [1]	-	38.0	-	34.0	-	30.5	-	29.6	-	29.5	ns

Symbol	Parameter	Conditions	$V_{CC(B)}$										Unit
			$1.5\text{ V} \pm 0.1\text{ V}$		$1.8\text{ V} \pm 0.15\text{ V}$		$2.5\text{ V} \pm 0.2\text{ V}$		$3.3\text{ V} \pm 0.3\text{ V}$		$5.0\text{ V} \pm 0.5\text{ V}$		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
<b><math>V_{CC(A)} = 1.65\text{ V to }1.95\text{ V}</math></b>													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	2.6	19.1	2.2	17.7	2.2	9.3	1.7	7.2	1.4	6.8	ns
		B to A	2.4	17.6	2.2	17.7	2.3	16.0	2.1	15.5	1.9	15.1	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	2.4	17.3	2.0	14.3	1.6	8.5	1.8	7.1	1.7	7.0	ns
		B to A	2.2	15.3	2.0	14.3	2.1	12.9	2.0	12.6	1.8	12.2	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	2.9	17.1	2.9	17.1	2.9	17.1	2.9	17.1	2.9	17.1	ns
		DIR to B	3.2	24.1	3.2	21.9	2.7	11.5	3.0	10.3	2.5	8.2	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	2.4	10.5	2.4	10.5	2.4	10.5	2.4	10.5	2.4	10.5	ns
		DIR to B	2.5	17.6	2.6	16.0	2.2	9.2	2.7	8.4	2.4	7.1	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	35.2	-	33.7	-	25.2	-	23.9	-	22.2	ns
		DIR to B [1]	-	29.6	-	28.2	-	19.8	-	17.7	-	17.3	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	39.4	-	36.2	-	24.4	-	22.9	-	20.4	ns
		DIR to B [1]	-	34.4	-	31.4	-	25.6	-	24.2	-	24.1	ns
<b><math>V_{CC(A)} = 2.3\text{ V to }2.7\text{ V}</math></b>													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	2.3	17.9	2.3	16.0	1.5	8.5	1.3	6.2	1.1	4.8	ns
		B to A	2.0	13.5	2.2	9.3	1.5	8.5	1.4	8.0	1.0	7.5	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	2.3	15.8	2.1	12.9	1.4	7.5	1.3	5.4	0.9	4.6	ns
		B to A	1.8	11.8	1.9	8.5	1.4	7.5	1.3	7.0	0.9	6.2	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	2.1	8.1	2.1	8.1	2.1	8.1	2.1	8.1	2.1	8.1	ns
		DIR to B	3.0	22.5	3.0	21.4	2.5	11.0	2.8	9.3	2.3	6.9	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	1.7	5.8	1.7	5.8	1.7	5.8	1.7	5.8	1.7	5.8	ns
		DIR to B	2.3	14.6	2.5	13.2	2.0	9.0	2.5	8.4	1.8	5.8	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	28.1	-	22.5	-	17.5	-	16.4	-	13.3	ns
		DIR to B [1]	-	23.7	-	21.8	-	14.3	-	12.0	-	10.6	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	34.3	-	29.9	-	18.5	-	16.3	-	13.1	ns
		DIR to B [1]	-	23.9	-	21.0	-	15.6	-	13.5	-	12.7	ns
<b><math>V_{CC(A)} = 3.0\text{ V to }3.6\text{ V}</math></b>													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	2.3	17.1	2.1	15.5	1.4	8.0	0.8	5.6	0.7	4.4	ns
		B to A	1.7	11.8	1.7	7.2	1.3	6.2	0.7	5.6	0.6	5.4	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	2.2	15.6	2.0	12.6	1.3	7.0	0.8	5.0	0.7	4.0	ns
		B to A	1.7	10.9	1.8	7.1	1.3	5.4	0.8	5.0	0.7	4.5	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	2.3	7.3	2.3	7.3	2.3	7.3	2.3	7.3	2.7	7.3	ns
		DIR to B	2.9	18.0	2.9	16.5	2.3	10.1	2.7	8.6	2.2	6.3	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	2.0	5.6	2.0	5.6	2.0	5.6	2.0	5.6	2.0	5.6	ns
		DIR to B	2.3	13.6	2.4	12.5	1.9	7.8	2.3	7.1	1.7	4.9	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	25.4	-	19.7	-	14.0	-	12.7	-	10.3	ns
		DIR to B [1]	-	22.7	-	21.1	-	13.6	-	11.2	-	10.0	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	28.9	-	23.6	-	15.5	-	13.6	-	10.8	ns
		DIR to B [1]	-	22.9	-	19.9	-	14.3	-	12.3	-	11.3	ns

Symbol	Parameter	Conditions	$V_{CC(B)}$										Unit
			1.5 V $\pm$ 0.1 V		1.8 V $\pm$ 0.15 V		2.5 V $\pm$ 0.2 V		3.3 V $\pm$ 0.3 V		5.0 V $\pm$ 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
<b><math>V_{CC(A)} = 4.5 \text{ V to } 5.5 \text{ V}</math></b>													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	2.2	16.6	1.9	15.1	1.0	7.5	0.7	5.4	0.5	3.9	ns
		B to A	1.6	10.5	1.4	6.8	1.0	4.8	0.7	4.4	0.5	3.9	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	2.3	15.3	1.8	12.2	1.0	6.2	0.7	4.5	0.5	3.5	ns
		B to A	1.7	10.8	1.7	7.0	0.9	4.6	0.7	4.0	0.5	3.5	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	1.7	5.4	1.7	5.4	1.7	5.4	1.7	5.4	1.7	5.4	ns
		DIR to B	2.9	17.3	2.9	16.1	2.3	9.7	2.7	8.0	2.5	5.7	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	1.4	3.7	1.4	3.7	1.3	3.7	1.0	3.7	0.9	3.7	ns
		DIR to B	2.3	13.1	2.4	12.1	1.9	7.4	2.3	7.0	1.8	4.5	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	23.6	-	18.9	-	12.2	-	11.4	-	8.4	ns
		DIR to B [1]	-	20.3	-	18.8	-	11.2	-	9.1	-	7.6	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	28.1	-	23.1	-	14.3	-	12.0	-	9.2	ns
		DIR to B [1]	-	20.7	-	17.6	-	11.6	-	9.9	-	8.9	ns

[1]  $t_{PZH}$  and  $t_{PZL}$  are calculated values using the formula shown in [Section 13.4](#).

**Table 13. Dynamic characteristics for temperature range -40 °C to +125 °C**

Voltages are referenced to GND (ground = 0 V); for test circuit see [Fig. 7](#); for waveforms see [Fig. 5](#) and [Fig. 6](#).

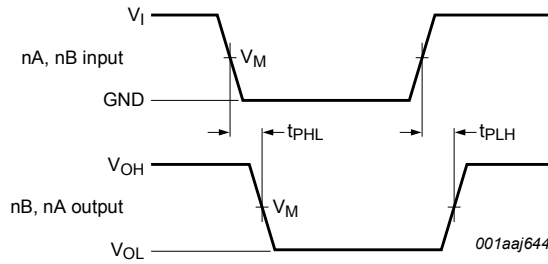
Symbol	Parameter	Conditions	$V_{CC(B)}$										Unit
			1.5 V $\pm$ 0.1 V		1.8 V $\pm$ 0.15 V		2.5 V $\pm$ 0.2 V		3.3 V $\pm$ 0.3 V		5.0 V $\pm$ 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
<b><math>V_{CC(A)} = 1.4 \text{ V to } 1.6 \text{ V}</math></b>													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	2.5	23.5	2.1	19.4	1.8	14.9	1.5	13.0	1.4	11.6	ns
		B to A	2.5	23.5	2.3	21.1	2.0	16.4	2.0	13.7	1.9	13.2	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	2.3	21.3	1.9	16.9	1.6	13.0	1.5	12.0	1.5	11.9	ns
		B to A	2.3	21.3	2.1	19.1	2.0	14.6	1.9	12.5	2.0	12.1	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	2.7	20.6	2.7	20.6	2.7	20.6	2.7	20.6	2.7	20.6	ns
		DIR to B	3.1	27.3	3.1	26.0	2.7	12.1	2.9	12.5	2.5	11.4	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	2.1	12.6	2.1	12.6	2.1	12.6	2.1	12.6	2.1	12.6	ns
		DIR to B	2.5	20.2	2.7	19.0	2.2	10.4	2.7	11.2	2.2	10.4	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	43.7	-	40.1	-	26.8	-	24.9	-	23.6	ns
		DIR to B [1]	-	36.1	-	32.0	-	27.5	-	25.6	-	24.2	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	48.6	-	45.1	-	26.7	-	25.0	-	23.5	ns
		DIR to B [1]	-	41.9	-	37.5	-	33.6	-	32.6	-	32.5	ns

Symbol	Parameter	Conditions	$V_{CC(B)}$										Unit
			$1.5\text{ V} \pm 0.1\text{ V}$		$1.8\text{ V} \pm 0.15\text{ V}$		$2.5\text{ V} \pm 0.2\text{ V}$		$3.3\text{ V} \pm 0.3\text{ V}$		$5.0\text{ V} \pm 0.5\text{ V}$		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
<b><math>V_{CC(A)} = 1.65\text{ V to }1.95\text{ V}</math></b>													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	2.3	21.1	1.9	19.5	1.9	10.3	1.5	8.0	1.2	7.5	ns
		B to A	2.1	19.4	1.9	19.5	2.0	17.6	1.8	17.1	1.7	16.7	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	2.1	19.1	1.8	15.8	1.4	9.4	1.6	7.9	1.5	7.7	ns
		B to A	1.9	16.9	1.8	15.8	1.8	14.2	1.8	13.9	1.6	13.5	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	2.6	18.9	2.6	18.9	2.6	18.9	2.6	18.9	2.6	18.9	ns
		DIR to B	2.8	26.6	2.8	24.1	2.4	12.7	2.7	11.4	2.2	9.1	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	2.1	11.6	2.1	11.6	2.1	11.6	2.1	11.6	2.1	11.6	ns
		DIR to B	2.2	19.4	2.3	17.6	1.9	10.2	2.4	9.3	2.1	7.9	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	38.8	-	37.1	-	27.8	-	26.4	-	24.6	ns
		DIR to B [1]	-	32.7	-	31.1	-	21.9	-	19.6	-	19.1	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	43.5	-	39.9	-	26.9	-	25.3	-	22.6	ns
		DIR to B [1]	-	38.0	-	34.7	-	28.3	-	26.8	-	26.6	ns
<b><math>V_{CC(A)} = 2.3\text{ V to }2.7\text{ V}</math></b>													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	2.0	19.7	2.0	17.6	1.3	9.4	1.1	6.9	0.9	5.3	ns
		B to A	1.8	14.9	1.9	10.3	1.3	9.4	1.2	8.8	0.9	8.3	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	2.0	17.4	1.8	14.2	1.2	8.3	1.1	6.0	0.8	5.1	ns
		B to A	1.6	13.0	1.7	9.4	1.2	8.3	1.1	7.7	0.8	6.9	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	1.8	9.0	1.8	9.0	1.8	9.0	1.8	9.0	1.8	9.0	ns
		DIR to B	2.7	24.8	2.7	23.6	2.2	12.1	2.5	10.3	2.0	7.6	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	1.5	6.4	1.5	6.4	1.5	6.4	1.5	6.4	1.5	6.4	ns
		DIR to B	2.0	16.1	2.2	14.6	1.8	9.9	2.2	9.3	1.6	6.4	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	31.0	-	24.9	-	19.3	-	18.1	-	14.7	ns
		DIR to B [1]	-	26.1	-	24.0	-	15.8	-	13.3	-	11.7	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	37.8	-	33.0	-	20.4	-	18.0	-	14.5	ns
		DIR to B [1]	-	26.4	-	23.2	-	17.3	-	15.0	-	14.1	ns
<b><math>V_{CC(A)} = 3.0\text{ V to }3.6\text{ V}</math></b>													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	2.0	18.9	1.8	17.1	1.2	8.8	0.7	6.2	0.6	4.9	ns
		B to A	1.5	13.0	1.5	8.0	1.1	6.9	0.6	6.2	0.5	6.0	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	1.9	17.2	1.8	13.9	1.1	7.7	0.7	5.5	0.6	4.4	ns
		B to A	1.5	12.0	1.6	7.9	1.1	6.0	0.7	5.5	0.6	5.0	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	2.0	8.1	2.0	8.1	2.0	8.1	2.0	8.1	2.4	8.1	ns
		DIR to B	2.6	19.8	2.6	18.2	2.0	11.2	2.4	9.5	1.9	7.0	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	1.8	6.2	1.8	6.2	1.8	6.2	1.8	6.2	1.8	6.2	ns
		DIR to B	2.0	15.0	2.1	13.8	1.7	8.6	2.0	7.9	1.5	5.4	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	28.0	-	21.8	-	15.5	-	14.1	-	11.4	ns
		DIR to B [1]	-	25.1	-	23.3	-	15.0	-	12.4	-	11.1	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	31.8	-	26.1	-	17.2	-	15.0	-	12.0	ns
		DIR to B [1]	-	25.3	-	22.0	-	15.8	-	13.6	-	12.5	ns

Symbol	Parameter	Conditions	$V_{CC(B)}$										Unit
			1.5 V $\pm$ 0.1 V		1.8 V $\pm$ 0.15 V		2.5 V $\pm$ 0.2 V		3.3 V $\pm$ 0.3 V		5.0 V $\pm$ 0.5 V		
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	
$V_{CC(A)} = 4.5 \text{ V to } 5.5 \text{ V}$													
$t_{PLH}$	LOW to HIGH propagation delay	A to B	1.9	18.3	1.7	16.7	0.9	8.3	0.6	6.0	0.4	4.3	ns
		B to A	1.4	11.6	1.2	7.5	0.9	5.3	0.6	4.9	0.4	4.3	ns
$t_{PHL}$	HIGH to LOW propagation delay	A to B	2.0	16.9	1.6	13.5	0.9	6.9	0.6	5.0	0.4	3.9	ns
		B to A	1.5	11.9	1.5	7.7	0.8	5.1	0.6	4.4	0.4	3.9	ns
$t_{PHZ}$	HIGH to OFF-state propagation delay	DIR to A	1.5	6.0	1.5	6.0	1.5	6.0	1.5	6.0	1.5	6.0	ns
		DIR to B	2.6	19.1	2.6	17.8	2.0	10.7	2.4	8.8	2.2	6.3	ns
$t_{PLZ}$	LOW to OFF-state propagation delay	DIR to A	1.2	4.1	1.2	4.1	1.1	4.1	0.9	4.1	0.8	4.1	ns
		DIR to B	2.0	14.5	2.1	13.4	1.7	8.2	2.0	7.7	1.6	5.0	ns
$t_{PZH}$	OFF-state to HIGH propagation delay	DIR to A [1]	-	26.1	-	20.9	-	13.5	-	12.6	-	9.3	ns
		DIR to B [1]	-	22.4	-	20.8	-	12.4	-	10.1	-	8.4	ns
$t_{PZL}$	OFF-state to LOW propagation delay	DIR to A [1]	-	31.0	-	25.5	-	15.8	-	13.2	-	10.2	ns
		DIR to B [1]	-	22.9	-	19.5	-	12.9	-	11.0	-	9.9	ns

[1]  $t_{PZH}$  and  $t_{PZL}$  are calculated values using the formula shown in [Section 13.4](#).

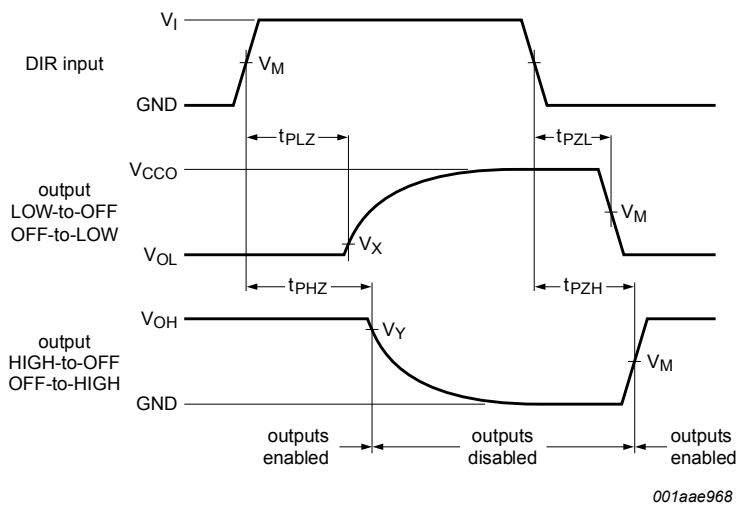
11.1. Waveforms and test circuit



Measurement points are given in Table 14.

$V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Fig. 5. The data input (A, B) to output (B, A) propagation delay times



Measurement points are given in Table 14.

$V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

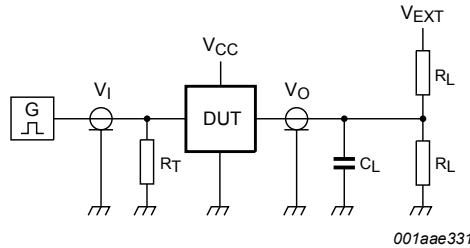
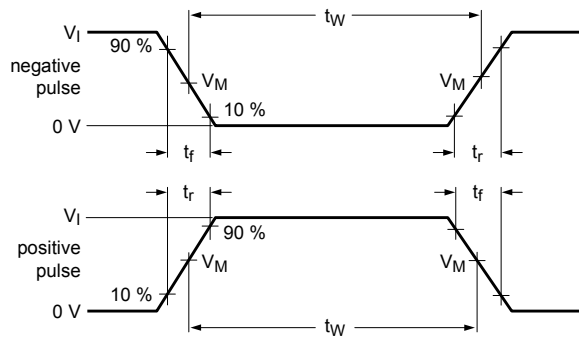
Fig. 6. Enable and disable times

Table 14. Measurement points

Supply voltage	Input [1]	Output [2]		
$V_{CC(A)}, V_{CC(B)}$	$V_M$	$V_M$	$V_X$	$V_Y$
1.2 V to 1.6 V	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.1 V$	$V_{OH} - 0.1 V$
1.65 V to 2.7 V	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.15 V$	$V_{OH} - 0.15 V$
3.0 V to 5.5 V	$0.5V_{CCI}$	$0.5V_{CCO}$	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$

[1]  $V_{CCI}$  is the supply voltage associated with the data input port.

[2]  $V_{CCO}$  is the supply voltage associated with the output port.



001aae331

Test data is given in [Table 15](#).

$R_L$  = Load resistance.

$C_L$  = Load capacitance including jig and probe capacitance.

$R_T$  = Termination resistance.

$V_{EXT}$  = External voltage for measuring switching times.

**Fig. 7. Test circuit for measuring switching times**

**Table 15. Test data**

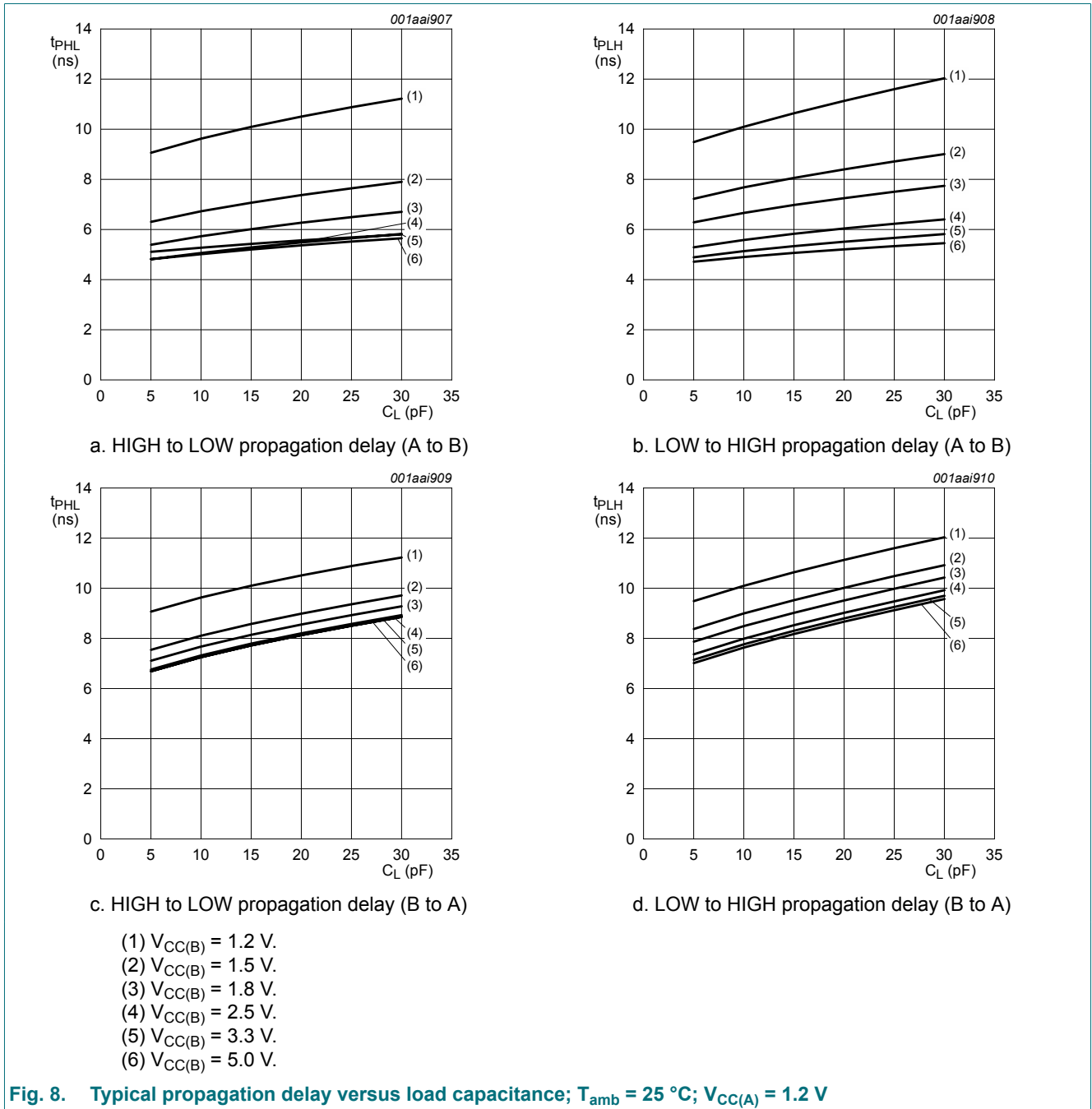
Supply voltage	Input		Load		$V_{EXT}$		
$V_{CC(A)}, V_{CC(B)}$	$V_I$ [1]	$\Delta t/\Delta V$ [2]	$C_L$	$R_L$	$t_{PLH}, t_{PHL}$	$t_{PZH}, t_{PHZ}$	$t_{PZL}, t_{PLZ}$ [3]
1.2 V to 5.5 V	$V_{CCI}$	$\leq 1.0 \text{ ns/V}$	15 pF	2 k $\Omega$	open	GND	$2V_{CCO}$

[1]  $V_{CCI}$  is the supply voltage associated with the data input port.

[2]  $dV/dt \geq 1.0 \text{ V/ns}$ .

[3]  $V_{CCO}$  is the supply voltage associated with the output port.

## 12. Typical propagation delay characteristics







a. HIGH to LOW propagation delay (A to B)



b. LOW to HIGH propagation delay (A to B)



c. HIGH to LOW propagation delay (B to A)



d. LOW to HIGH propagation delay (B to A)

- (1)  $V_{CC(B)} = 1.2 \text{ V}$ .
- (2)  $V_{CC(B)} = 1.5 \text{ V}$ .
- (3)  $V_{CC(B)} = 1.8 \text{ V}$ .
- (4)  $V_{CC(B)} = 2.5 \text{ V}$ .
- (5)  $V_{CC(B)} = 3.3 \text{ V}$ .
- (6)  $V_{CC(B)} = 5.0 \text{ V}$ .

Fig. 9. Typical propagation delay versus load capacitance;  $T_{amb} = 25 \text{ }^\circ\text{C}$ ;  $V_{CC(A)} = 1.5 \text{ V}$



a. HIGH to LOW propagation delay (A to B)



b. LOW to HIGH propagation delay (A to B)



c. HIGH to LOW propagation delay (B to A)



d. LOW to HIGH propagation delay (B to A)

- (1)  $V_{CC(B)} = 1.2\text{ V}$ .
- (2)  $V_{CC(B)} = 1.5\text{ V}$ .
- (3)  $V_{CC(B)} = 1.8\text{ V}$ .
- (4)  $V_{CC(B)} = 2.5\text{ V}$ .
- (5)  $V_{CC(B)} = 3.3\text{ V}$ .
- (6)  $V_{CC(B)} = 5.0\text{ V}$ .

Fig. 10. Typical propagation delay versus load capacitance;  $T_{amb} = 25\text{ }^\circ\text{C}$ ;  $V_{CC(A)} = 1.8\text{ V}$



a. HIGH to LOW propagation delay (A to B)



b. LOW to HIGH propagation delay (A to B)



c. HIGH to LOW propagation delay (B to A)



d. LOW to HIGH propagation delay (B to A)

- (1)  $V_{CC(B)} = 1.2\text{ V}$ .
- (2)  $V_{CC(B)} = 1.5\text{ V}$ .
- (3)  $V_{CC(B)} = 1.8\text{ V}$ .
- (4)  $V_{CC(B)} = 2.5\text{ V}$ .
- (5)  $V_{CC(B)} = 3.3\text{ V}$ .
- (6)  $V_{CC(B)} = 5.0\text{ V}$ .

Fig. 11. Typical propagation delay versus load capacitance;  $T_{amb} = 25\text{ }^\circ\text{C}$ ;  $V_{CC(A)} = 2.5\text{ V}$



a. HIGH to LOW propagation delay (A to B)



b. LOW to HIGH propagation delay (A to B)



c. HIGH to LOW propagation delay (B to A)



d. LOW to HIGH propagation delay (B to A)

- (1)  $V_{CC(B)} = 1.2 \text{ V}$ .
- (2)  $V_{CC(B)} = 1.5 \text{ V}$ .
- (3)  $V_{CC(B)} = 1.8 \text{ V}$ .
- (4)  $V_{CC(B)} = 2.5 \text{ V}$ .
- (5)  $V_{CC(B)} = 3.3 \text{ V}$ .
- (6)  $V_{CC(B)} = 5.0 \text{ V}$ .

Fig. 12. Typical propagation delay versus load capacitance;  $T_{amb} = 25 \text{ }^\circ\text{C}$ ;  $V_{CC(A)} = 3.3 \text{ V}$



a. HIGH to LOW propagation delay (A to B)



b. LOW to HIGH propagation delay (A to B)



c. HIGH to LOW propagation delay (B to A)



d. LOW to HIGH propagation delay (B to A)

- (1)  $V_{CC(B)} = 1.2\text{ V}$ .
- (2)  $V_{CC(B)} = 1.5\text{ V}$ .
- (3)  $V_{CC(B)} = 1.8\text{ V}$ .
- (4)  $V_{CC(B)} = 2.5\text{ V}$ .
- (5)  $V_{CC(B)} = 3.3\text{ V}$ .
- (6)  $V_{CC(B)} = 5.0\text{ V}$ .

Fig. 13. Typical propagation delay versus load capacitance;  $T_{amb} = 25\text{ }^\circ\text{C}$ ;  $V_{CC(A)} = 5.0\text{ V}$

### 13. Application information

#### 13.1. Unidirectional logic level-shifting application

The circuit given in Fig. 14 is an example of the 74LVC2T45-Q100; 74LVCH2T45-Q100 being used in a unidirectional logic level-shifting application.

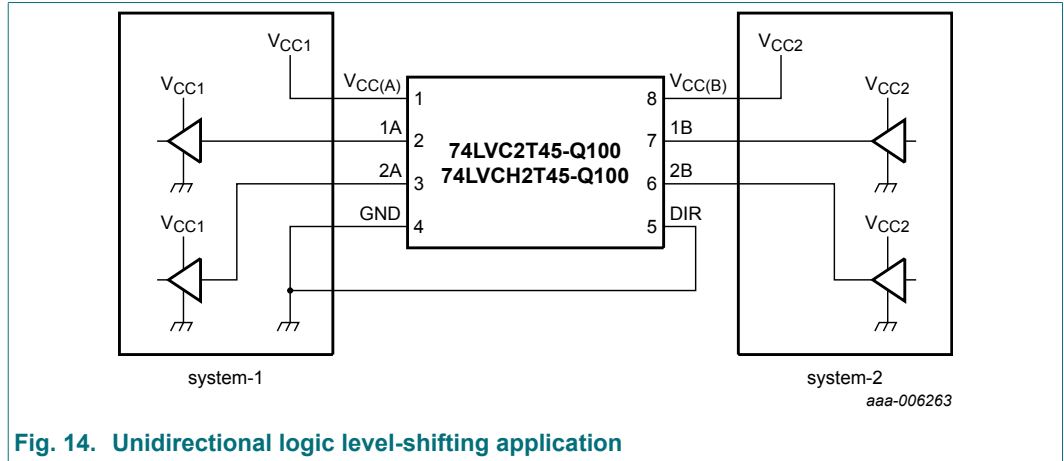


Fig. 14. Unidirectional logic level-shifting application

Table 16. Description of unidirectional logic level-shifting application

Pin	Name	Function	Description
1	V <sub>CC(A)</sub>	V <sub>CC1</sub>	supply voltage of system-1 (1.2 V to 5.5 V)
2	1A	OUT	output level depends on V <sub>CC1</sub> voltage
3	2A	OUT	output level depends on V <sub>CC1</sub> voltage
4	GND	GND	device GND
5	DIR	DIR	the GND (LOW level) determines B port to A port direction
6	2B	IN	input threshold value depends on V <sub>CC2</sub> voltage
7	1B	IN	input threshold value depends on V <sub>CC2</sub> voltage
8	V <sub>CC(B)</sub>	V <sub>CC2</sub>	supply voltage of system-2 (1.2 V to 5.5 V)

### 13.2. Bidirectional logic level-shifting application

Fig. 15 shows the 74LVC2T45-Q100; 74LVCH2T45-Q100 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.

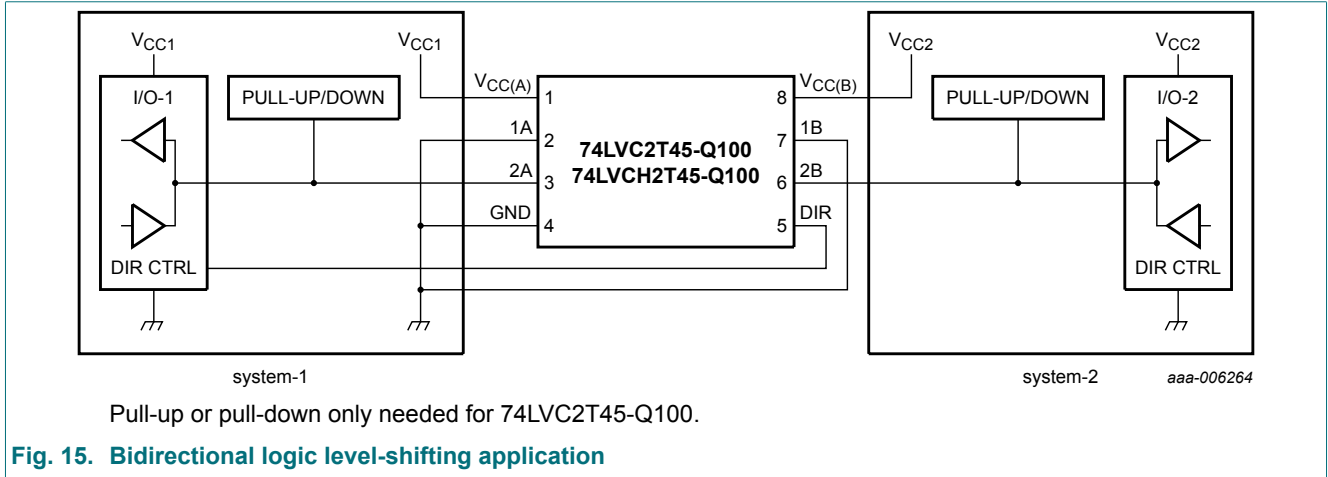


Fig. 15. Bidirectional logic level-shifting application

Table 17 gives a sequence that will illustrate data transmission from system-1 to system-2 and then from system-2 to system-1.

Table 17. Description of bidirectional logic level-shifting application

H = HIGH voltage level;  
 L = LOW voltage level;  
 Z = high-impedance OFF-state.

State	DIR CTRL	I/O-1	I/O-2	Description
1	H	output	input	system-1 data to system-2
2	H	Z	Z	system-2 is getting ready to send data to system-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on bus hold
3	L	Z	Z	DIR bit is set LOW. I/O-1 and I/O-2 still are disabled. The bus-line state depends on bus hold
4	L	input	output	system-2 data to system-1

### 13.3. Power-up considerations

The device is designed such that no special power-up sequence is required other than GND being applied first.

Table 18. Typical total supply current (I<sub>CC(A)</sub> + I<sub>CC(B)</sub>)

V <sub>CC(A)</sub>	V <sub>CC(B)</sub>					Unit
	0 V	1.8 V	2.5 V	3.3 V	5.0 V	
0 V	0	< 1	< 1	< 1	< 1	µA
1.8 V	< 1	< 2	< 2	< 2	2	µA
2.5 V	< 1	< 2	< 2	< 2	< 2	µA
3.3 V	< 1	< 2	< 2	< 2	< 2	µA
5.0 V	< 1	2	< 2	< 2	< 2	µA

### 13.4. Enable times

Calculate the enable times for the 74LVC2T45-Q100; 74LVCH2T45-Q100 using the following formulas:

- $t_{PZH} \text{ (DIR to A)} = t_{PLZ} \text{ (DIR to B)} + t_{PLH} \text{ (B to A)}$
- $t_{PZL} \text{ (DIR to A)} = t_{PHZ} \text{ (DIR to B)} + t_{PHL} \text{ (B to A)}$
- $t_{PZH} \text{ (DIR to B)} = t_{PLZ} \text{ (DIR to A)} + t_{PLH} \text{ (A to B)}$
- $t_{PZL} \text{ (DIR to B)} = t_{PHZ} \text{ (DIR to A)} + t_{PHL} \text{ (A to B)}$

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74LVC2T45-Q100; 74LVCH2T45-Q100 initially is transmitting from A to B, then the DIR bit is switched, the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.



### 14. Package outline

VSSOP8: plastic very thin shrink small outline package; 8 leads; body width 2.3 mm

SOT765-1

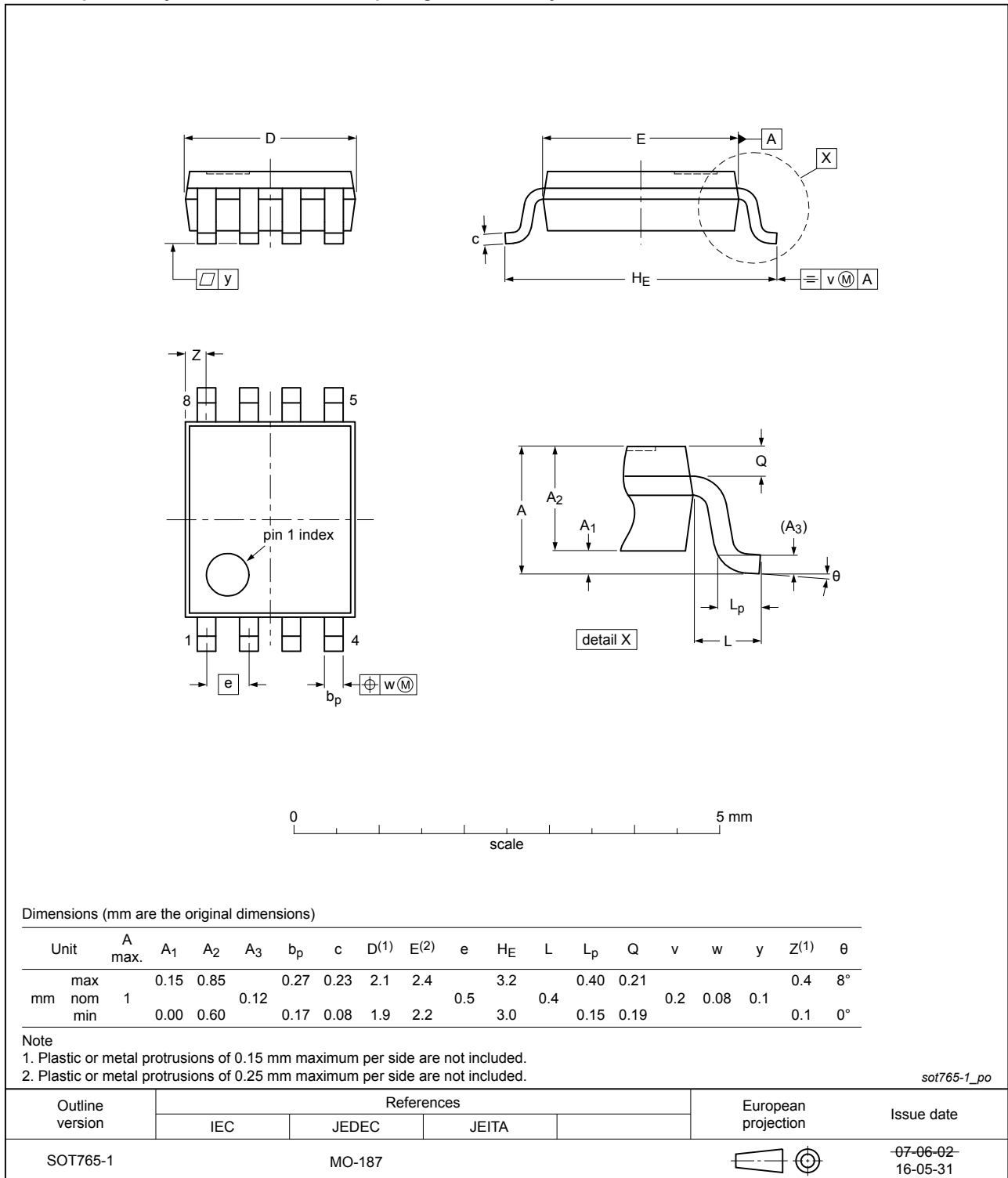


Fig. 16. Package outline SOT765-1 (VSSOP8)

XSON8: plastic extremely thin small outline package; no leads; 8 terminals; body 1 x 1.95 x 0.5 mm

SOT833-1

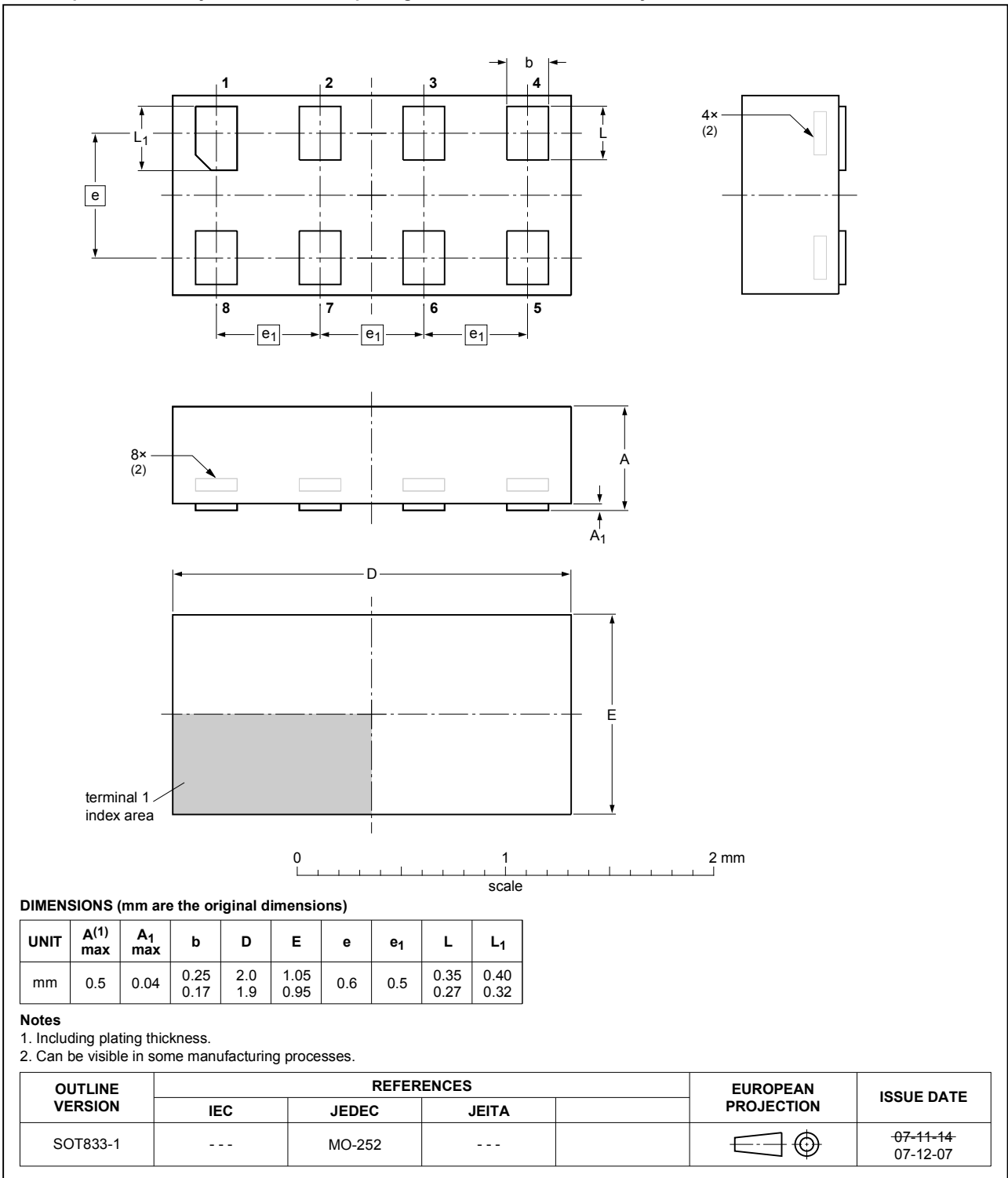


Fig. 17. Package outline SOT833-1 (XSON8)

XSON8: extremely thin small outline package; no leads;  
8 terminals; body 1.35 x 1.0 x 0.35 mm

SOT1203



Fig. 18. Package outline SOT1203 (XSON8)

## 15. Abbreviations

Table 19. Abbreviations

Acronym	Description
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MIL	Military
MM	Machine Model

## 16. Revision history

Table 20. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74LVC_LVCH2T45_Q100 v.3	20190128	Product data sheet	-	74LVC_LVCH2T45_Q100 v.2
Modifications:	<ul style="list-style-type: none"> <li>Added type numbers 74LVC2T45GT-Q100 (SOT833-1) and 74LVC2T45GS-Q100 (SOT1203)</li> </ul>			
74LVC_LVCH2T45_Q100 v.2	20180813	Product data sheet	-	74LVC_LVCH2T45_Q100 v.1
Modifications:	<ul style="list-style-type: none"> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li><a href="#">Package outline drawing</a> (SOT765-1) modified.</li> </ul>			
74LVC_LVCH2T45_Q100 v.1	20130222	Product data sheet	-	-

## 17. Legal information

### Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <https://www.nexperia.com>.

### Definitions

**Draft** — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. Nexperia does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

**Short data sheet** — A short data sheet is an extract from a full data sheet with the same product type number(s) and title. A short data sheet is intended for quick reference only and should not be relied upon to contain detailed and full information. For detailed and full information see the relevant full data sheet, which is available on request via the local Nexperia sales office. In case of any inconsistency or conflict with the short data sheet, the full data sheet shall prevail.

**Product specification** — The information and data provided in a Product data sheet shall define the specification of the product as agreed between Nexperia and its customer, unless Nexperia and customer have explicitly agreed otherwise in writing. In no event however, shall an agreement be valid in which the Nexperia product is deemed to offer functions and qualities beyond those described in the Product data sheet.

### Disclaimers

**Limited warranty and liability** — Information in this document is believed to be accurate and reliable. However, Nexperia does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. Nexperia takes no responsibility for the content in this document if provided by an information source outside of Nexperia.

In no event shall Nexperia be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory.

Notwithstanding any damages that customer might incur for any reason whatsoever, Nexperia's aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of Nexperia.

**Right to make changes** — Nexperia reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

**Suitability for use in automotive applications** — This Nexperia product has been qualified for use in automotive applications. Unless otherwise agreed in writing, the product is not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or

equipment, nor in applications where failure or malfunction of an Nexperia product can reasonably be expected to result in personal injury, death or severe property or environmental damage. Nexperia and its suppliers accept no liability for inclusion and/or use of Nexperia products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Quick reference data** — The Quick reference data is an extract of the product data given in the Limiting values and Characteristics sections of this document, and as such is not complete, exhaustive or legally binding.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. Nexperia makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification.

Customers are responsible for the design and operation of their applications and products using Nexperia products, and Nexperia accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the Nexperia product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products.

Nexperia does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using Nexperia products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). Nexperia does not accept any liability in this respect.

**Limiting values** — Stress above one or more limiting values (as defined in the Absolute Maximum Ratings System of IEC 60134) will cause permanent damage to the device. Limiting values are stress ratings only and (proper) operation of the device at these or any other conditions above those given in the Recommended operating conditions section (if present) or the Characteristics sections of this document is not warranted. Constant or repeated exposure to limiting values will permanently and irreversibly affect the quality and reliability of the device.

**Terms and conditions of commercial sale** — Nexperia products are sold subject to the general terms and conditions of commercial sale, as published at <http://www.nexperia.com/profile/terms>, unless otherwise agreed in a valid written individual agreement. In case an individual agreement is concluded only the terms and conditions of the respective agreement shall apply. Nexperia hereby expressly objects to applying the customer's general terms and conditions with regard to the purchase of Nexperia products by customer.

**No offer to sell or license** — Nothing in this document may be interpreted or construed as an offer to sell products that is open for acceptance or the grant, conveyance or implication of any license under any copyrights, patents or other industrial or intellectual property rights.

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

**Translations** — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

### Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

## Contents

---

<b>1. General description</b> .....	<b>1</b>
<b>2. Features and benefits</b> .....	<b>1</b>
<b>3. Ordering information</b> .....	<b>2</b>
<b>4. Marking</b> .....	<b>2</b>
<b>5. Functional diagram</b> .....	<b>2</b>
<b>6. Pinning information</b> .....	<b>3</b>
6.1. Pinning.....	3
6.2. Pin description.....	3
<b>7. Functional description</b> .....	<b>3</b>
<b>8. Limiting values</b> .....	<b>4</b>
<b>9. Recommended operating conditions</b> .....	<b>4</b>
<b>10. Static characteristics</b> .....	<b>5</b>
<b>11. Dynamic characteristics</b> .....	<b>8</b>
11.1. Waveforms and test circuit.....	14
<b>12. Typical propagation delay characteristics</b> .....	<b>16</b>
<b>13. Application information</b> .....	<b>22</b>
13.1. Unidirectional logic level-shifting application.....	22
13.2. Bidirectional logic level-shifting application.....	23
13.3. Power-up considerations.....	23
13.4. Enable times.....	24
<b>14. Package outline</b> .....	<b>25</b>
<b>15. Abbreviations</b> .....	<b>28</b>
<b>16. Revision history</b> .....	<b>28</b>
<b>17. Legal information</b> .....	<b>29</b>

---

© Nexperia B.V. 2019. All rights reserved

For more information, please visit: <http://www.nexperia.com>

For sales office addresses, please send an email to: [salesaddresses@nexperia.com](mailto:salesaddresses@nexperia.com)

Date of release: 28 January 2019

---



Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



#### Как с нами связаться

**Телефон:** 8 (812) 309 58 32 (многоканальный)

**Факс:** 8 (812) 320-02-42

**Электронная почта:** [org@eplast1.ru](mailto:org@eplast1.ru)

**Адрес:** 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.