

## Memory for Plug &amp; Play

# DDR/DDR2

## (For memory module) SPD Memory


**BR34E02FVT-W, BR34E02NUX-W**

No.09002EBT03

## ●Description

BR34E02FVT-W is 256 × 8 bit Electrically Erasable PROM (Based on Serial Presence Detect)

## ●Features

- 1) 256 × 8 bit architecture serial EEPROM
- 2) Wide operating voltage range: 1.7V-3.6V
- 3) Two-wire serial interface
- 4) High reliability connection using Au pads and Au wires
- 5) Self-Timed Erase and Write Cycle
- 6) Page Write Function (16byte)
- 7) Write Protect Mode
  - Settable Reversible Write Protect Function: 00h-7Fh
  - Write Protect 1 (Onetime Rom) : 00h-7Fh
  - Write Protect 2 (Hardwire WP PIN) : 00h-FFh
- 8) Low Power consumption
  - Write (at 1.7V) : 0.4mA (typ.)
  - Read (at 1.7V) : 0.1mA (typ.)
  - Standby (at 1.7V) : 0.1μA (typ.)
- 9) DATA security
  - Write protect feature (WP pin)
  - Inhibit to WRITE at low Vcc
- 10) Compact package: TSSOP-B8, VSON008X2030
- 11) High reliability fine pattern CMOS technology
- 12) Rewriting possible up to 1,000,000 times
- 13) Data retention: 40 years
- 14) Noise reduction Filtered inputs in SCL / SDA
- 15) Initial data FFh at all addresses

## ●BR34E02-W Series

| Capacity | Bit format | Type      | Power Source Voltage | TSSOP-B8 | VSON008X2030 |
|----------|------------|-----------|----------------------|----------|--------------|
| 2Kbit    | 256X8      | BR34E02-W | 1.7V~3.6V            | ●        | ●            |

## ●Absolute Maximum Ratings (Ta=25°C)

| Parameter                   | Symbol | Rating                          | Unit |
|-----------------------------|--------|---------------------------------|------|
| Supply Voltage              | Vcc    | -0.3~+6.5                       | V    |
| Power Dissipation           | Pd     | 330(BR34E02FVT-W) <sup>*1</sup> | mW   |
|                             |        | 300(BR34E02NUX-W) <sup>*2</sup> |      |
| Storage Temperature         | Tstg   | -65~+125                        | °C   |
| Operating Temperature       | Topr   | -40~+85                         | °C   |
| Terminal Voltage (A0)       | -      | -0.3~10.0                       | V    |
| Terminal Voltage (etcetera) | -      | -0.3~Vcc+0.3                    | V    |

<sup>\*</sup> Reduce by 3.3mW(\*1), 3.0 mW(\*2)/°C over 25°C

## ●Recommended operating conditions

| Parameter      | Symbol | Rating  | Unit |
|----------------|--------|---------|------|
| Supply Voltage | Vcc    | 1.7~3.6 | V    |
| Input Voltage  | VIN    | 0~Vcc   | V    |

●Memory cell characteristics(Ta=25°C, Vcc=1.7V~3.6V)

| Parameter                         | Specification |      |      | Unit   |
|-----------------------------------|---------------|------|------|--------|
|                                   | Min.          | Typ. | Max. |        |
| Write / Erase Cycle <sup>*1</sup> | 1,000,000     | -    | -    | Cycles |
| Data Retention <sup>*1</sup>      | 40            | -    | -    | Years  |

<sup>\*1</sup>:Not 100% TESTED

●Electrical characteristics - DC(Unless otherwise specified Ta=-40°C~+85°C, Vcc=1.7V~3.6V)

| Parameter               | Symbol | Specification |      |         | Unit | Test Condition   |
|-------------------------|--------|---------------|------|---------|------|--|
|                         |        | Min.          | Typ. | Max.    |      |  |
| "H" Input Voltage       | VIH1   | 0.7 Vcc       | -    | Vcc+0.3 | V    |  |
| "L" Input Voltage       | VIL1   | -             | -    | 0.3 Vcc | V    |  |
| "L" Output Voltage 1    | VOL1   | -0.3          | -    | 0.4     | V    | IOL=2.1mA, 2.5V≤Vcc≤3.6V(SDA)  |
| "L" Output Voltage 2    | VOL2   | -             | -    | 0.2     | V    | IOL=0.7mA, 1.7V≤Vcc<2.5V(SDA)  |
| Input Leakage Current 1 | ILI1   | -1            | -    | 1       | μA   | VIN=0V~Vcc(A0,A1,A2,SCL)   |
| Input Leakage Current 2 | ILI2   | -1            | -    | 15      | μA   | VIN=0V~Vcc(WP)   |
| Input Leakage Current 3 | ILI3   | -1            | -    | 20      | μA   | VIN=VHV(A0)  |
| Output Leakage Current  | ILO    | -1            | -    | 1       | μA   | VOUT=0V~Vcc  |
| Operating Current       | ICC1   | -             | -    | 1.0     | mA   | Vcc=1.7V,fSCL=100kHz, tWR=5ms<br>Byte Write<br>Page Write<br>Write Protect |
|                         | ICC2   | -             | -    | 3.0     | mA   | Vcc=3.6V,fSCL=100kHz, tWR=5ms<br>Byte Write<br>Page Write<br>Write Protect |
|                         | ICC3   | -             | -    | 0.5     | mA   | Vcc=3.6V,fSCL=100kHz<br>Random Read<br>Current Read<br>Sequential Read     |
| Standby Current         | ISB    | -             | -    | 2.0     | μA   | Vcc=3.6V,SDA,SCL=Vcc<br>A0,A1,A2=GND,WP=GND                                |
| A0 HV Voltage           | VHV    | 7             | -    | 10      | V    | VHV-Vcc≥4.8V   |

○Note: This IC is not designed to be radiation-resistant.

●Electrical characteristics - AC(Unless otherwise specified Ta=-40°C~+85°C, VCC=1.7V~3.6V)

| Parameter                           | Symbol     | FAST-MODE<br>2.5V≤Vcc≤5.5V |      |      | STANDARD-MODE<br>1.7V≤Vcc≤5.5V |      |      | Unit |
|-------------------------------------|------------|----------------------------|------|------|--------------------------------|------|------|------|
|                                     |            | Min.                       | Typ. | Max. | Min.                           | Typ. | Max. |      |
| Clock Frequency                     | fSCL       | -                          | -    | 400  | -                              | -    | 100  | kHz  |
| Data Clock High Period              | tHIGH      | 0.6                        | -    | -    | 4.0                            | -    | -    | μs   |
| Data Clock Low Period               | tLOW       | 1.2                        | -    | -    | 4.7                            | -    | -    | μs   |
| SDA and SCL Rise Time <sup>*1</sup> | tR         | -                          | -    | 0.3  | -                              | -    | 1.0  | μs   |
| SDA and SCL Fall Time <sup>*1</sup> | tF         | -                          | -    | 0.3  | -                              | -    | 0.3  | μs   |
| Start Condition Hold Time           | tHD:STA    | 0.6                        | -    | -    | 4.0                            | -    | -    | μs   |
| Start Condition Setup Time          | tSU:STA    | 0.6                        | -    | -    | 4.7                            | -    | -    | μs   |
| Input Data Hold Time                | tHD:DAT    | 0                          | -    | -    | 0                              | -    | -    | ns   |
| Input Data Setup Time               | tSU:DAT    | 100                        | -    | -    | 250                            | -    | -    | ns   |
| Output Data Delay Time              | tPD        | 0.1                        | -    | 0.9  | 0.1                            | -    | 3.5  | μs   |
| Output Data Hold Time               | tDH        | 0.1                        | -    | -    | 0.1                            | -    | -    | μs   |
| Stop Condition Setup Time           | tSU:STO    | 0.6                        | -    | -    | 4.0                            | -    | -    | μs   |
| Bus Free Time                       | tBUF       | 1.2                        | -    | -    | 4.7                            | -    | -    | μs   |
| Write Cycle Time                    | tWR        | -                          | -    | 5    | -                              | -    | 5    | ms   |
| Noise Spike Width (SDA and SCL)     | tI         | -                          | -    | 0.1  | -                              | -    | 0.1  | μs   |
| WP Hold Time                        | tHD : WP   | 0                          | -    | -    | 0                              | -    | -    | ns   |
| WP Setup Time                       | tSU : WP   | 0.1                        | -    | -    | 0.1                            | -    | -    | μs   |
| WP High Period                      | tHIGH : WP | 1.0                        | -    | -    | 1.0                            | -    | -    | μs   |

<sup>\*1</sup> : Not 100% TESTED

### ■ Fast / Standard Modes

Fast mode and Standard mode differ only in operation frequency. Operations performed at 100kHz are considered in "Standard-mode", while those conducted at 400kHz are in "Fast-mode".

Please note that these clock frequencies are maximum values. At lower power supply voltage it is difficult to operate at high speeds. The EEPROM can operate at 400kHz, between 2.5V and 3.6V, and at 100kHz from 1.7V-2.5V.

### ● Synchronous Data Timing

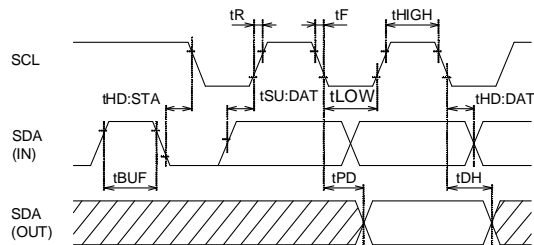


Fig.1-(a) Synchronous Data Timing

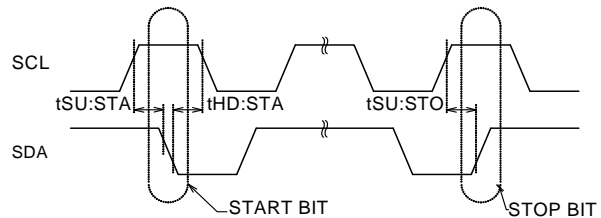


Fig.1-(b) Start/Stop Bit Timing

○SDA data is latched into the chip at the rising edge of SCL clock.

○Output data toggles at the falling edge of SCL clock.

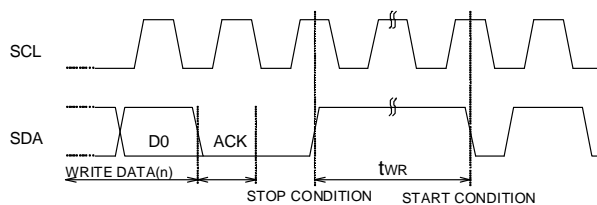


Fig.1-(c) Write Cycle Timing

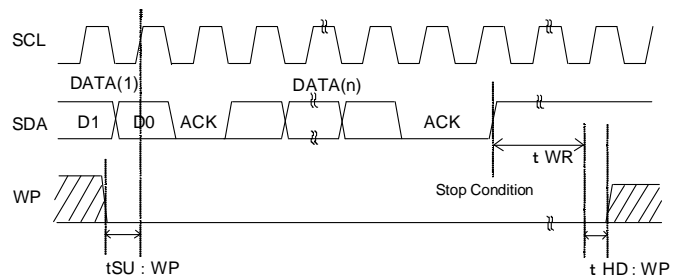


Fig.1-(d) WP Timing Of The Write Operation

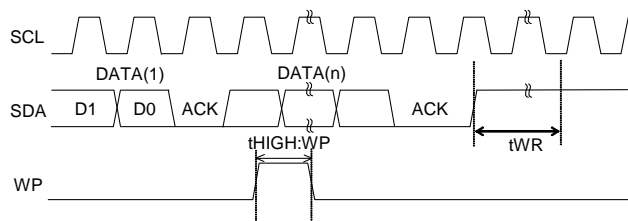


Fig.1-(e) WP Timing Of The Write Cancel Operation

○For WRITE operation, WP must be "Low" from the rising edge of the clock (which takes in D0 of first byte) until the end of tWR. (See Fig.1-(d) ) During this period, WRITE operation can be canceled by setting WP "High". (See Fig.1-(e) )

○When WP is set to "High" during tWR, WRITE operation is immediately ceased, making the data unreliable. It must then be re-written.

●Block diagram

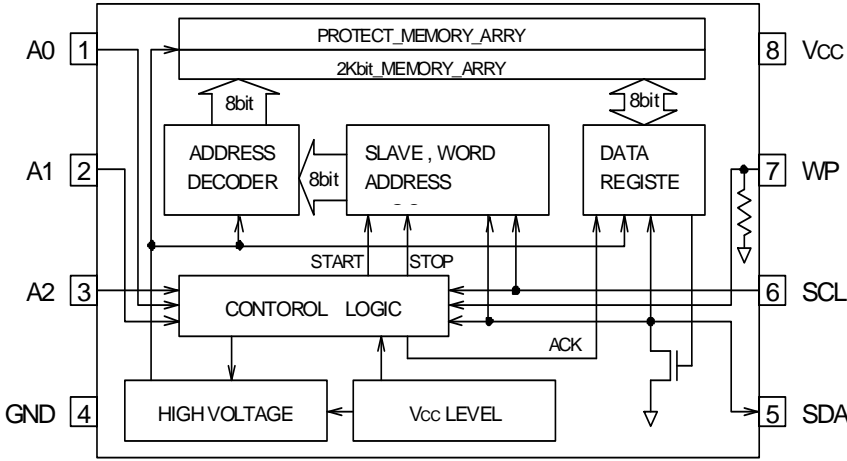


Fig.2 Blo

●Pinout diagram and description

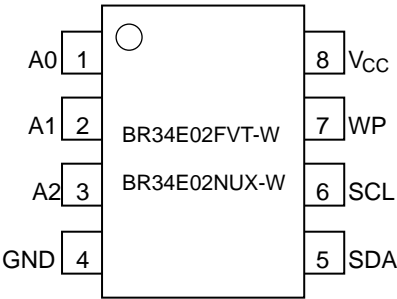


Fig.3 Pin Configuration

| Pin Name | Input/Output | Functions  |
|----------|--------------|--|
| Vcc      | -            | Power Supply   |
| GND      | -            | Ground 0V  |
| A0,A1,A2 | IN           | Slave Address Set.   |
| SCL      | IN           | Serial Clock Input   |
| SDA      | IN / OUT     | Slave and Word Address,<br>Serial Data Input, Serial Data Output |
| WP       | IN           | Write Protect Input  |

\*1 Open drain output requires a pull-up resistor.

\*2 WP Pin has a Pull-Down resistor. Please leave unconnected or connect to GND when not in use.

●Electrical characteristics curves

The following characteristic data are typ. value.

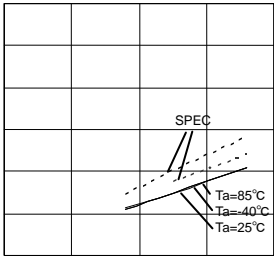


Fig.4 "H" Input Voltage VIH  
(A0,A1,A2,SCL,SDA,WP)

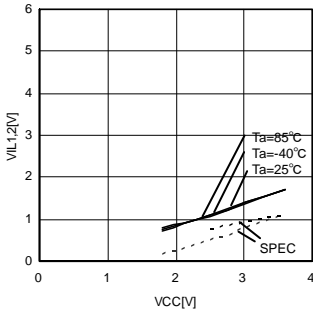


Fig.5 "L" Input Voltage VIL  
(A0,A1,A2,SCL,SDA,WP)

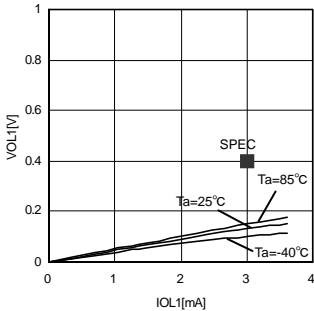


Fig.6 "L" Output Voltage VOL1-IOL1  
(Vcc=2.5V)

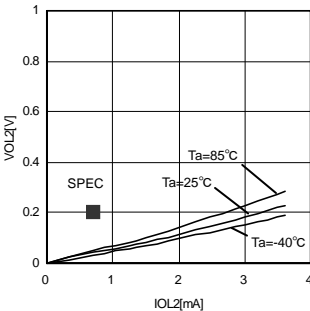


Fig.7 "L" Output Voltage VOL2-IOL2  
(Vcc=1.7V)

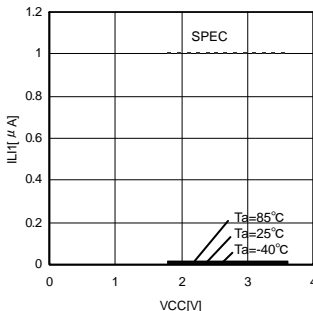


Fig.8 Input Leakage Current ILI1  
(A0,A1,A2,SCL,SDA)

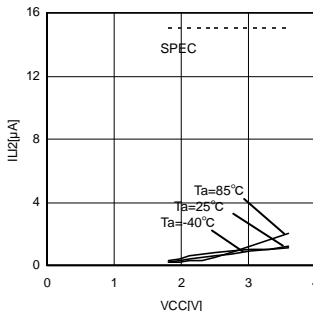
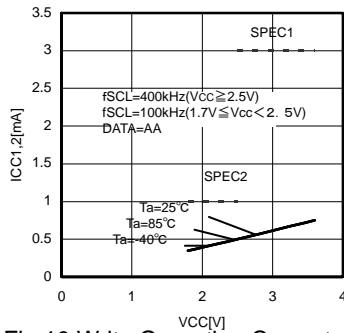
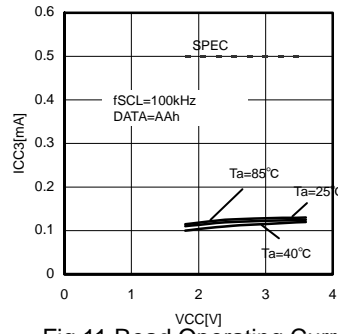
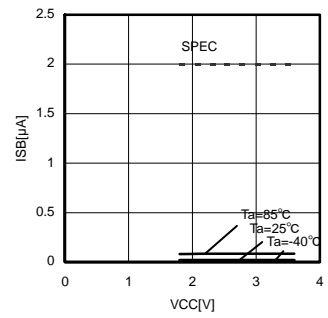
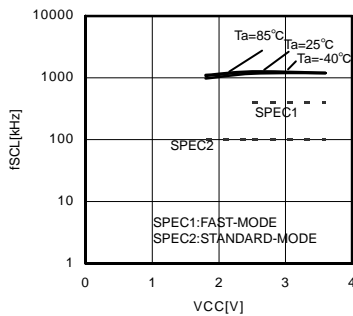
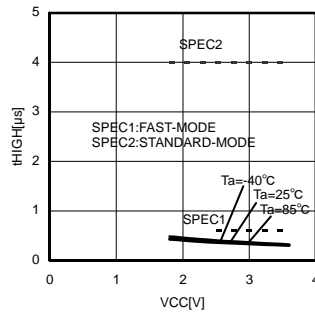
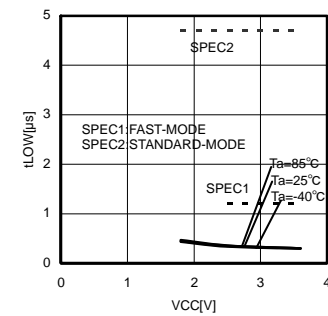
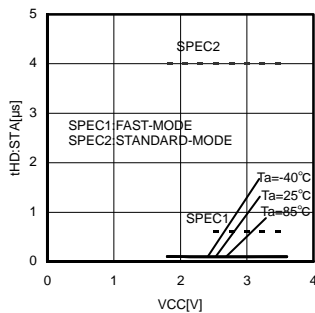
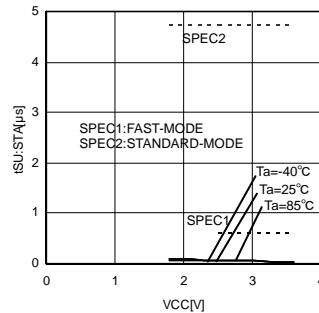
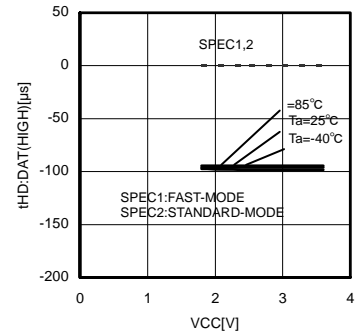
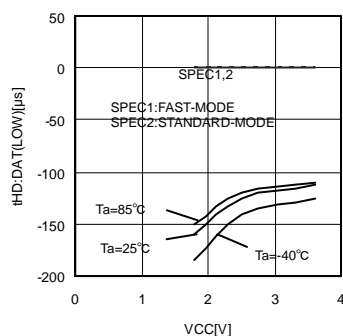
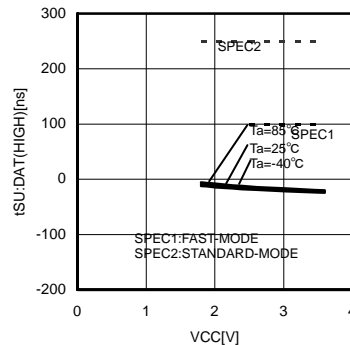
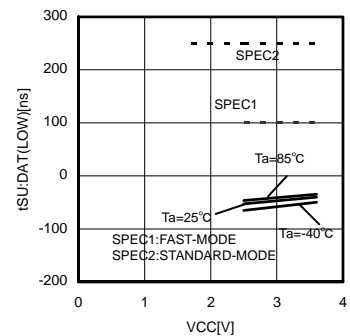
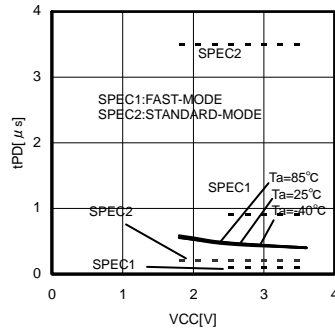
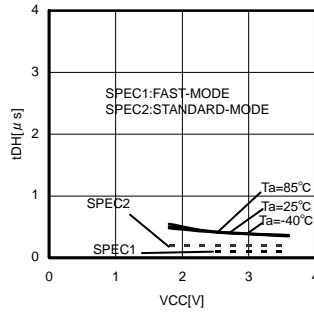
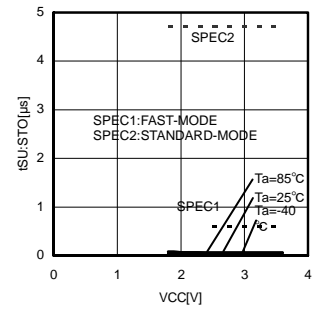
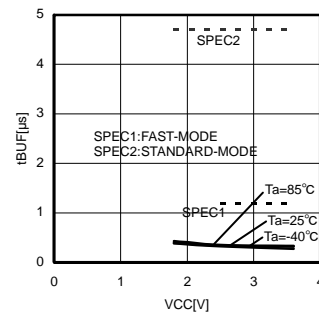
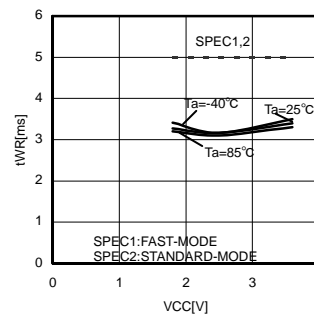
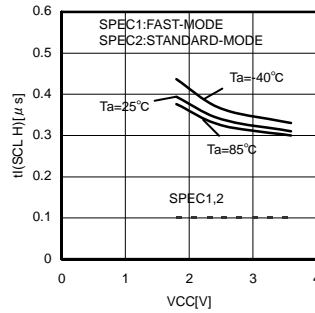
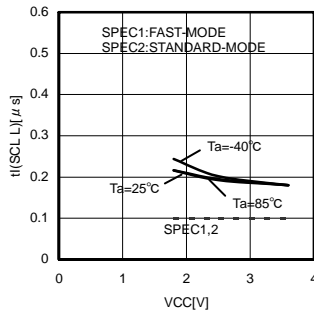
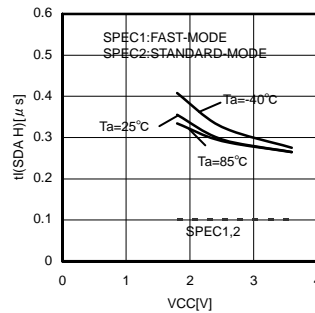
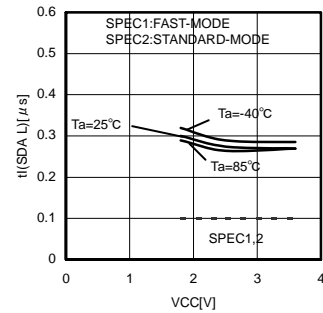
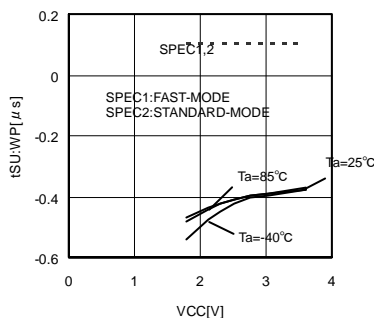
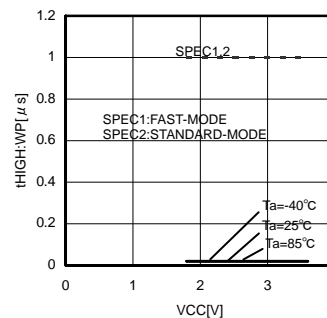


Fig.9 Input Leakage Current ILI2  
(WP)

Fig.10 Write Operating Current  $ICC_{1,2}$  ( $f_{SCL}=100\text{kHz}, 400\text{kHz}$ )Fig.11 Read Operating Current  $ICC_3$  ( $f_{SCL}=400\text{kHz}$ )Fig.12 Standby Current  $ISB$ Fig.13 Clock Frequency  $f_{SCL}$ Fig.14 Data Clock High Period  $t_{HIGH}$ Fig.15 Data Clock Low Period  $t_{LOW}$ Fig.16 Start Condition Hold Time  $t_{HD:STA}$ Fig.17 Start Condition Setup Time  $t_{SU:STA}$ Fig.18 Data Hold Time  $t_{HD:DAT(HIGH)}$ Fig.19 Data Hold Time  $t_{HD:DAT(LOW)}$ Fig.20 Input Data Setup Time  $t_{SU:DAT(HIGH)}$ Fig.21 Input Data Setup Time  $t_{SU:DAT(LOW)}$

Fig.22 Output Data Delay Time  $t_{PD}$ Fig.23 Output Data Hold Time  $t_{DH}$ Fig.24 Stop Condition Setup Time  $t_{SU:STO}$ Fig.25 Bus Free Time  $t_{BUF}$ Fig.26 Write Cycle Time  $t_{WR}$ Fig.27 Noise Spike Width  $t_I(\text{SCL H})$ Fig.28 Noise Spike Width  $t_I(\text{SCL L})$ Fig.29 Noise Spike Width  $t_I(\text{SDA H})$ Fig.30 Noise Spike Width  $t_I(\text{SDA L})$ Fig.31 WP Setup Time  $t_{SU:WP}$ Fig.32 WP High Period  $t_{HIGH:WP}$

## ●Data transfer on the I<sup>2</sup>C BUS

### ○Data transfer on the I<sup>2</sup>C BUS

The BUS is considered to be busy after the START condition and free a certain time after the STOP condition.

Every SDA byte must be 8-bits long and requires an ACKNOWLEDGE signal after each byte. The devices have Master and Slave configurations. The Master device initiates and ends data transfer on the BUS and generates the clock signals in order to permit transfer.

The EEPROM in a slave configuration is controlled by a unique address. Devices transmitting data are referred to as the Transmitter. The devices receiving the data are called Receiver.

### ○START Condition (Recognition of the START bit)

- All commands are proceeded by the start condition, which is a High to Low transition of SDA when SCL is High.
- The device continuously monitors the SDA and SCL lines for the start condition and will not respond to any command until this condition has been met. (See Fig.1-(b) START/STOP Bit Timing)

### ○STOP Condition (Recognition of STOP bit)

- All communications must be terminated by a stop condition, which is a Low to High transition of SDA when SCL is High. (See Fig.1-(b) START/STOP Bit Timing)

### ○Write Protect By Soft Ware

- Set Write Protect command and permanent set Write Protect command set data of 00h~7Fh in 256 words write protection block. Clear Write Protect command can cancel write protection block which is set by set write Protect command. Cancel of write protection block which is set by permanent set Write Protect command at once is impossibility. When these commands are carried out, WP pin must be OPEN or GND.

### ○Acknowledge

- Acknowledge is a software used to indicate successful data transfers. The Transmitter device will release the BUS after transmitting eight bits. When inputting the slave address during write or read operation, the Transmitter is the  $\mu$ -COM. When outputting the data during read operation, the Transmitter is the EEPROM.
- During the ninth clock cycle the Receiver will pull the SDA line Low to verify that the eight bits of data have been received. (When inputting the slave address during write or read operation, EEPROM is the receiver. When outputting the data during read operation the receiver is the  $\mu$ -COM.)
- The device will respond with an Acknowledge after recognition of a START condition and its slave address (8bit).
- In WRITE mode, the device will respond with an Acknowledge after the receipt of each subsequent 8-bit word (word address and write data).
- In READ mode, the device will transmit eight bits of data, release the SDA line, and monitor the line for an Acknowledge.
- If an Acknowledge is detected and no STOP condition is generated by the Master, the device will continue to transmit the data. If an Acknowledge is not detected, the device will terminate further data transmissions and await a STOP condition before returning to standby mode.

### ○Device Addressing

- Following a START condition, the Master outputs the Slave address to be accessed. The most significant four bits of the slave address are the "device type identifier." For this EEPROM it is "1010."  
(For WP register access this code is "0110".)
- The next three bits identify the specified device on the BUS (device address).  
The device address is defined by the state of the A0,A1 and A2 input pins. This IC works only when the device address input from the SDA pin corresponds to the status of the A0,A1 and A2 input pins. Using this address scheme allows up to eight devices to be connected to the BUS.
- The last bit of the stream ( $\overline{R/W}$ ...READ/WRITE) determines the operation to be performed.

$\overline{R/W}=0$     ....    WRITE (including word address input of Random Read)  
 $\overline{R/W}=1$     ....    READ

| Slave Address Set Pin |     |     | Device Type | Device Address |    |    | Read Write Mode  | Access Area                                  |
|-----------------------|-----|-----|-------------|----------------|----|----|------------------|--|
| A2                    | A1  | A0  | 1010        | A2             | A1 | A0 | $\overline{R/W}$ | 2kbit Access to Memory                       |
| A2                    | A1  | A0  |             | A2             | A1 | A0 | $\overline{R/W}$ | Access to Permanent Set Write Protect Memory |
| GND                   | GND | VHV |             | 0              | 0  | 1  | R/W              | Access to Set Write Protect Memroy           |
| GND                   | Vcc | VHV |             | 0              | 1  | 1  | R/W              | Access to Clear Write Protect MEMORY         |

### OWRITE PROTECT PIN(WP)

When WP pin set to Vcc (H level), write protect is set for 256 words (all address). When WP pin set to GND (L level), it is enable to write 256 words (all address).

If permanent protection is done by Write Protect command, lower half area (00~7Fh address) is inhibited writing regardless of WP pin state.

WP pin has a Pull-Down resistor. Please be left unconnected or connect to GND when WP feature is not in use.

### Confirm Write Protect Resistor by ACK

According to state of Write Protect Resistor, ACK is as follows.

| State of Write Protect Register | WP Input | Input Command               | ACK    | Address | ACK    | Data  | ACK    | Write Cycle(tWR) |
|---------------------------------|----------|-----------------------------|--------|---------|--------|-------|--------|------------------|
| In case, protect by PSWP        | -        | PSWP, SWP, CWP              | No ACK | -       | No ACK | -     | No ACK | No               |
|                                 |          | Page or Byte Write (00~7Fh) | ACK    | WA7~WA0 | ACK    | D7~D0 | No ACK | No               |
| In case, protect by SWP         | 0        | SWP                         | No ACK | -       | No ACK | -     | No ACK | No               |
|                                 |          | CWP                         | ACK    | -       | ACK    | -     | ACK    | Yes              |
|                                 |          | PSWP                        | ACK    | -       | ACK    | -     | ACK    | Yes              |
|                                 |          | Page or Byte Write (00~7Fh) | ACK    | WA7~WA0 | ACK    | D7~D0 | No ACK | No               |
|                                 | 1        | SWP                         | No ACK | -       | No ACK | -     | No ACK | No               |
|                                 |          | CSP                         | ACK    | -       | ACK    | -     | No ACK | No               |
|                                 |          | PSWP                        | ACK    | -       | ACK    | -     | No ACK | No               |
|                                 |          | Page or Byte Write          | ACK    | WA7~WA0 | ACK    | D7~D0 | No ACK | No               |
| In case, Not protect            | 0        | PSWP, SWP, CWP              | ACK    | -       | ACK    | -     | ACK    | Yes              |
|                                 |          | Page or Byte Write          | ACK    | WA7~WA0 | ACK    | D7~D0 | ACK    | Yes              |
|                                 | 1        | PSWP, SWP, CWP              | ACK    | -       | ACK    | -     | No ACK | No               |
|                                 |          | Page or Byte Write          | ACK    | WA7~WA0 | ACK    | D7~D0 | No ACK | No               |

\*- is Don't Care

| State of Write Protect Register | Command        | ACK    | Address | ACK    | Data | ACK    |
|---------------------------------|----------------|--------|---------|--------|------|--------|
| In case, protect by PSWP        | PSWP, SWP, CWP | No ACK | -       | No ACK | -    | No ACK |
| In case, protect by SWP         | SWP            | No ACK | -       | No ACK | -    | No ACK |
|                                 | CWP            | ACK    | -       | No ACK | -    | No ACK |
|                                 | PSWP           | ACK    | -       | No ACK | -    | No ACK |
| In case, Not protect            | PSWP, SWP, CWP | ACK    | -       | No ACK | -    | No ACK |

### OWrite Cycle

During WRITE CYCLE operation data is written in the EEPROM. The Byte Write Cycle is used to write only one byte. In the case of writing continuous data consisting of more than one byte, Page Write is used. The maximum bytes that can be written at one time is 16 bytes.

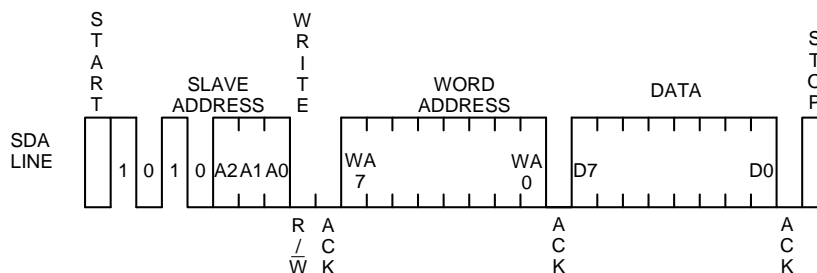


Fig.33 Byte Write Cycle Timing

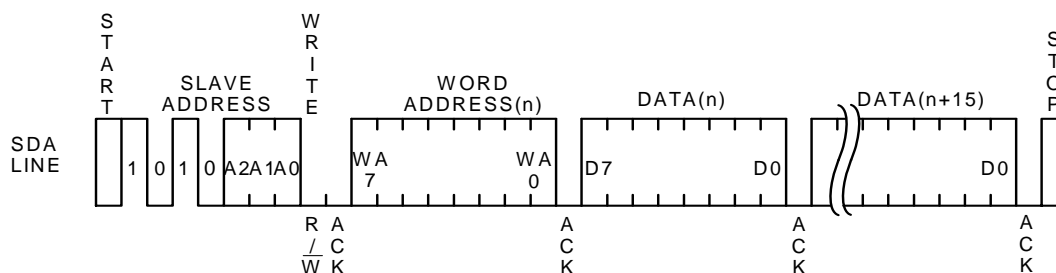


Fig.34 Page Write Cycle Timing



- With this command the data is programmed into the indicated word address.
- When the Master generates a STOP condition, the device begins the internal write cycle to the nonvolatile memory array.
- Once programming is started no commands are accepted for  $t_{WR}$  (5ms max.).
- This device is capable of sixteen-byte Page Write operations.
- If the Master transmits more than sixteen words prior to generating the STOP condition, the address counter will “roll over” and the previously transmitted data will be overwritten.
- When two or more byte of data are input, the four low order address bits are internally incremented by one after the receipt of each word, while the four higher order bits of the address (WA7~WA4) remain constant.

#### ○Read Cycle

During Read Cycle operation data is read from the EEPROM. The Read Cycle is composed of Random Read Cycle and Current Read Cycle. The Random Read Cycle reads the data in the indicated address.

The Current Read Cycle reads the data in the internally indicated address and verifies the data immediately after the Write Operation. The Sequential Read operation can be performed with both Current Read and Random Read. With the Sequential Read Cycle it is possible to continuously read the next data.

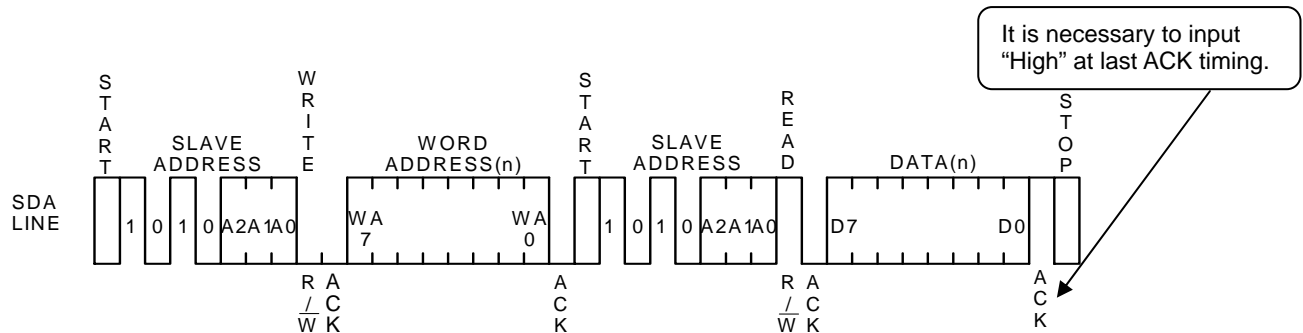


Fig.35 Random Read Cycle Timing

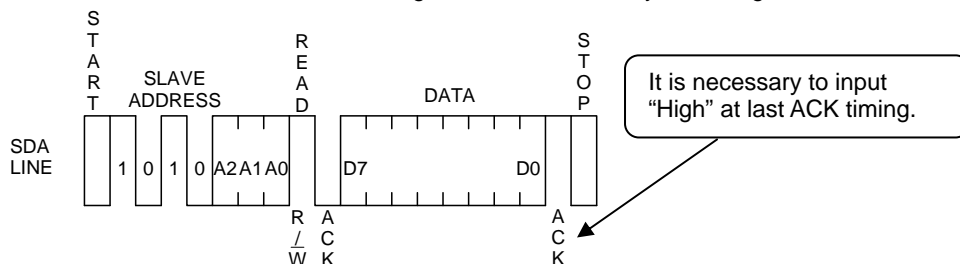


Fig.36 Current Read Cycle Timing

- Random Read operation allows the Master to access any memory location indicated by word address.
- In cases where the previous operation is Random or Current Read (which includes Sequential Read), the internal address counter is increased by one from the last accessed address (n). Thus Current Read outputs the data of the next word address (n+1).
- If an Acknowledge is detected and no STOP condition is generated by the Master ( $\mu$ -COM), the device will continue to transmit data. (It can transmit all data (2kbit 256word))
- If an Acknowledge is not detected, the device will terminate further data transmissions and await a STOP condition before returning to standby mode.
- If an Acknowledge is detected with the "Low" level (not "High" level), the command will become Sequential Read, and the next data will be transmitted. Therefore, the Read command is not terminated. In order to terminate Read input Acknowledge with "High" always, then input a STOP condition.

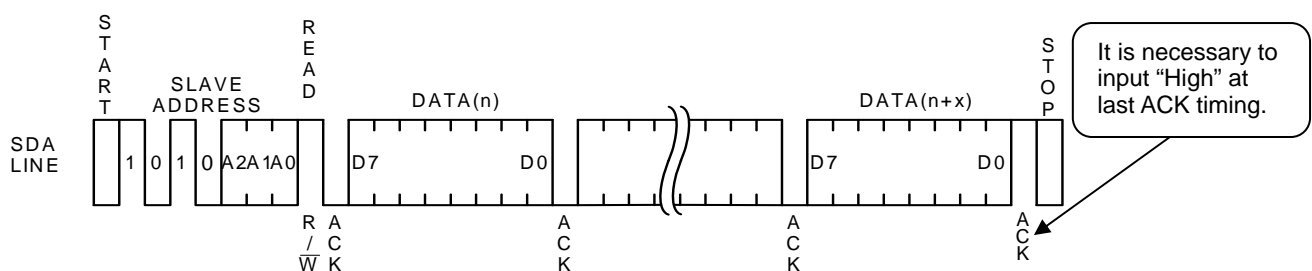


Fig.37 Sequential Read Cycle Timing (With Current Read)

## OWrite Protect Cycle

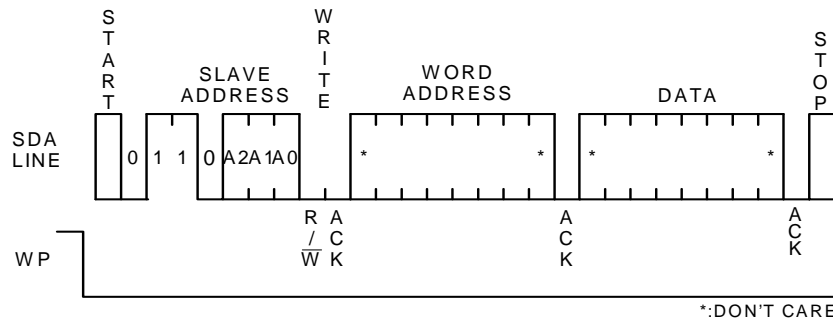


Fig. 38 Permanent Write Protect Cycle

- Permanent set Write Protect command set data of 00h~7Fh in 256 words write protection block. Clear Write Protect command can cancel write protection block which is set by set write Protect command. Cancel of write protection block which is set by permanent set Write Protect command at once is impossibility. When these commands are carried out, WP pin must be OPEN or GND.
- Permanent Set Write Protect command needs tWR from stop condition same as Byte Write and Page Write, During tWR, input command is canceled.
- Refer to P8/19 about reply of ACK in each protect state.

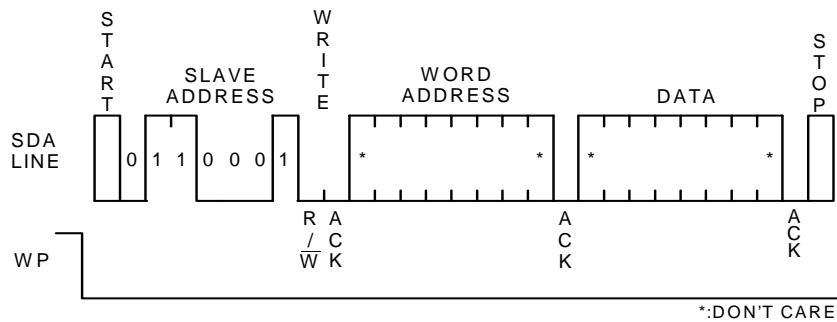


Fig. 39 Set Write Protect Cycle

- Permanent set Write Protect command set data of 00h~7Fh in 256 words write protection block. Clear Write Protect command can cancel write protection block which is set by set write Protect command. Cancel of write protection block which is set by permanent set Write Protect command at once is impossibility. When these commands are carried out, WP pin must be OPEN or GND.
- Permanent Set Protect command needs tWR from stop condition same as Byte Write and Page Write, During tWR, input command is canceled.
- Refer to P8/19 about reply of ACK in each protect state.

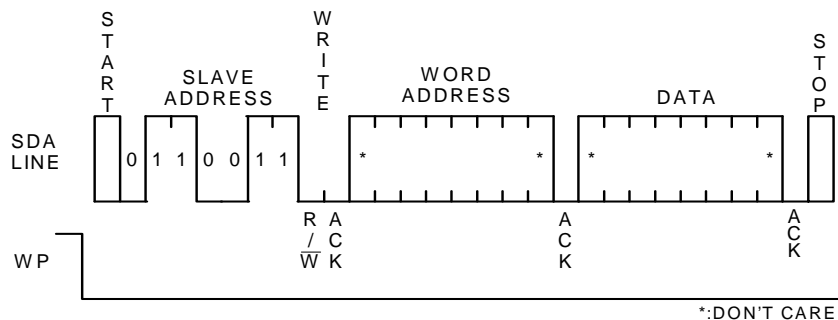
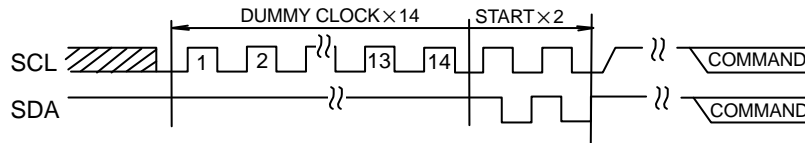
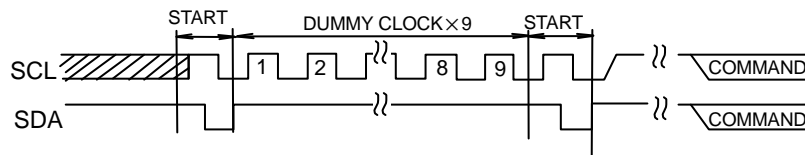
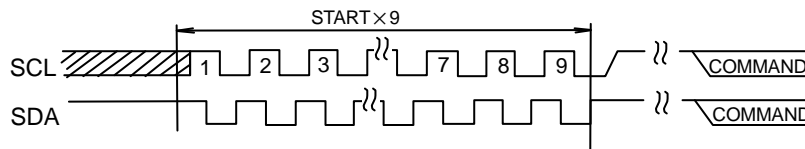


Fig. 40 Clear Write Protect Cycle

- Clear Write Protect command can cancel write protection block which is set by set write Protect command. Cancel of write protection block which is set by permanent set Write Protect command at once is impossibility. When these commands are carried out, WP pin must be OPEN or GND.
- Permanent Clear Write Protect command needs tWR from stop condition same as Byte Write and Page Write, During tWR, input command is canceled.
- Refer to P8/19 about reply of ACK in each protect state.

### ● Software Reset

Execute software reset in the event that the device is in an unexpected state after power up and/or the command input needs to be reset. Below are three types (Fig.39 –(a), (b), (c)) of software reset:  
During dummy clock, release the SDA BUS (tied to VCC by a pull-up resistor). During this time the device may pull the SDA line Low for Acknowledge or the outputting of read data. If the Master sets the SDA line to High, it will conflict with the device output Low, which can cause current overload and result in instantaneous power down, which may damage the device.

Fig.39-(a) DUMMY CLOCK  $\times$  14 + START  $\times$  2Fig.39-(b) START + DUMMY CLOCK  $\times$  9 + STARTFig.39-(c) START  $\times$  9

\* COMMAND starts with start condition.

### ● Acknowledge polling

Since the IC ignores all input commands during the internal write cycle, no ACK signal will be returned.

When the Master sends the next command after the Write command, if the device returns an ACK signal it means that the program is completed. No ACK signal indicates that the device is still busy.

Using Acknowledge polling decreases the waiting time by  $t_{WR}=5\text{ms}$ .

When operating Write or Current Read after Write, first transmit the Slave address (R/W is "High" or "Low"). After the device returns the ACK signal continue word address input or data output.

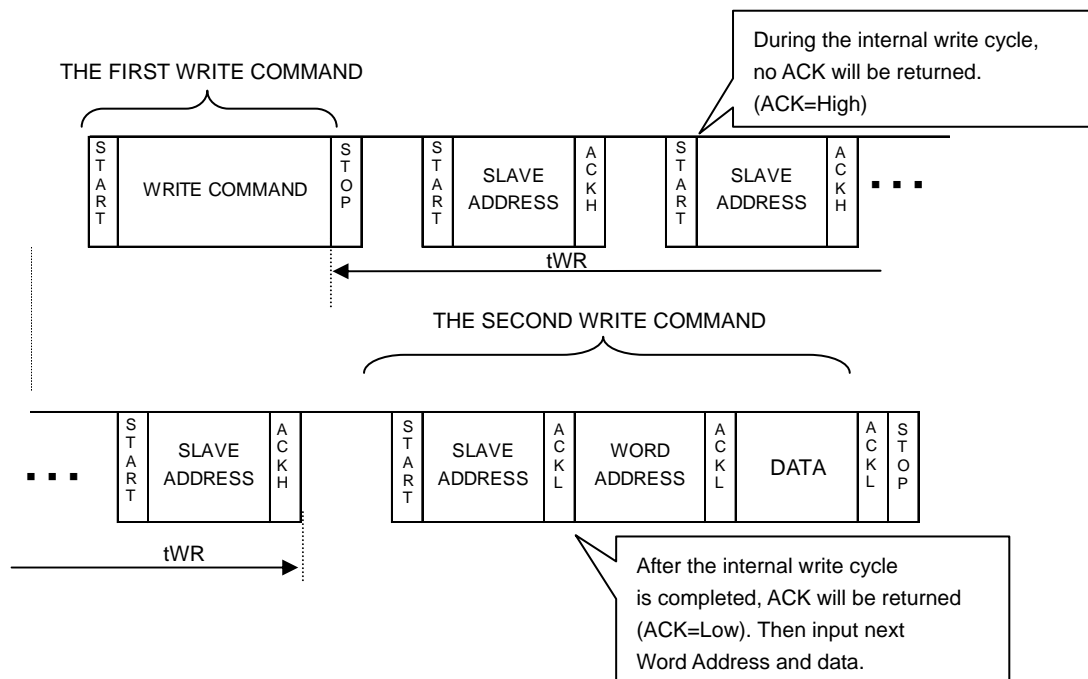


Fig.40 Successive Write Operation By Acknowledge Polling

### ● WP effective timing

WP is normally fixed at "H" or "L". However, in case WP needs to be controlled in order to cancel the Write command, pay attention to "WP effective timing" as follows:

The Write command is canceled by setting WP to "H" within the WP cancellation effective period.

The period from the START condition to the rising edge of the clock (which takes in the data D0 - the first byte of the Page Write data) is the 'invalid cancellation period'. WP input is considered inconsequential during this period. The setup time for the rising edge of the SCL, which takes in D0, must be more than 100ns.

The period from the rising edge of SCL (which takes in the data D0) to the end of internal write cycle (tWR) is the 'effective cancellation period'. When WP is set to "H" during tWR, Write operation is stopped, making it necessary to rewrite the data. It is not necessary to wait for tWR (5ms max.) after stopping the Write command by WP because the device is in standby mode.

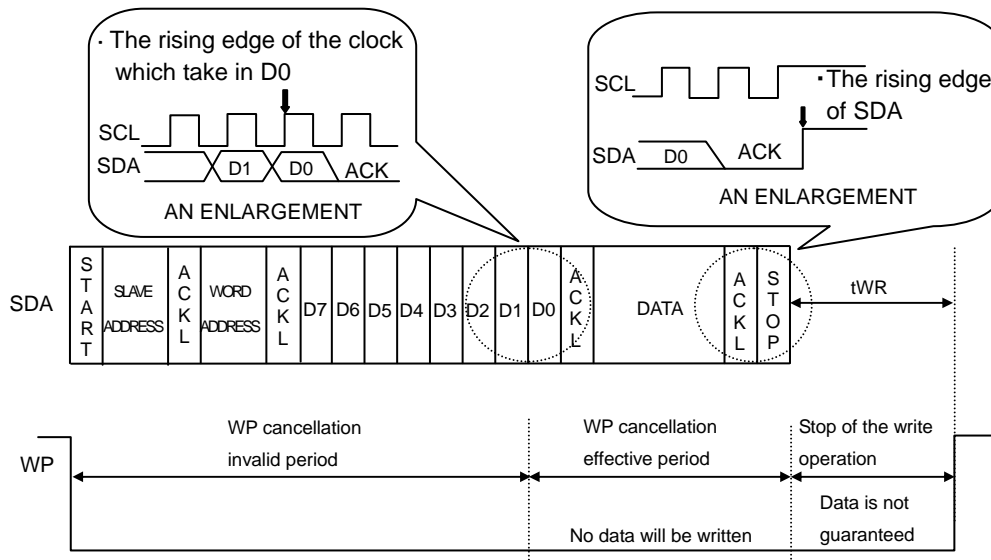


Fig.41 WP effective timing

### ● Command cancellation from the START and STOP conditions

Command input is canceled by successive inputs of START and STOP conditions. (Refer to Fig.42)

However, during ACK or data output, the device may set the SDA line to Low, making operation of the START and STOP conditions impossible, and thus preventing reset. In this case execute reset by software. (Refer to Fig.39)

The internal address counter will not be determined when operating the Cancel command by the START and STOP conditions during Random, Sequential or Current Read. Operate a Random Read in this case.

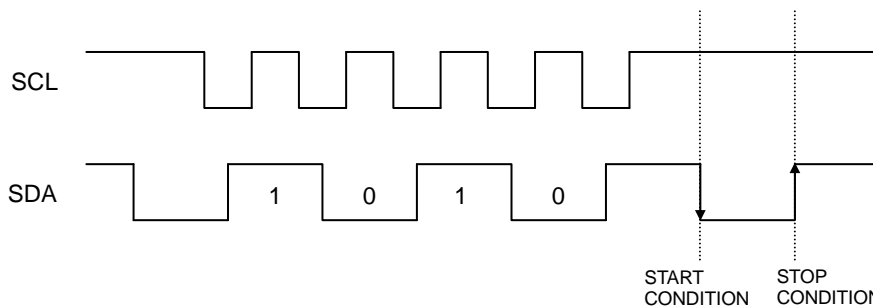


Fig.42 Command cancellation by the START and STOP conditions during input of the Slave Address

## ● I/O Circuit

### ○ SDA Pin Pull-up Resistor

A pull-up resistor is required because SDA is an NMOS open drain. Determine the resistor value of (RPU) by considering the  $V_{IL}$  and  $I_L$ , and  $V_{OL}$ - $I_{OL}$  characteristics. If a large RPU is chosen, the clock frequency needs to be slow. A smaller RPU will result in a larger operating current.

### ○ Maximum RPU

The maximum of RPU can be determined by the following factors.

① The SDA rise time determined by RPU and the capacitance of the BUS line (CBUS) must be less than  $t_R$ .

In addition, all other timings must be kept within the AC specifications.

② When the SDA BUS is High, the voltage  $\textcircled{A}$  at the SDA BUS is determined from the total input leakage ( $I_L$ ) of all devices connected to the BUS. RPU must be higher than the input High level of the microcontroller and the device, including a noise margin  $0.2V_{CC}$ .

$$V_{CC} - I_L R_{PU} - 0.2 V_{CC} \geq V_{IH}$$

$$\therefore R_{PU} \leq \frac{0.8V_{CC} - V_{IH}}{I_L}$$

Examples: When  $V_{CC} = 3V$ ,  $I_L = 10\mu A$ ,  $V_{IH} = 0.7 V_{CC}$

According to ②

$$\begin{aligned} R_{PU} &\leq \frac{0.8 \times 3 - 0.7 \times 3}{10 \times 10^{-6}} \\ &\leq 300 \text{ [k}\Omega\text{]} \end{aligned}$$

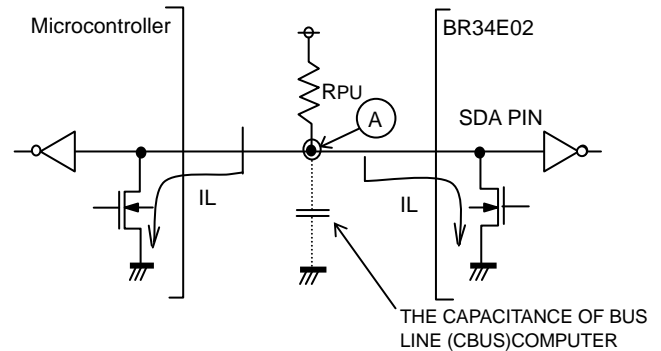


Fig.43 I/O Circuit

### ○ Minimum RPU

The minimum value of RPU is determined by following factors.

① Meets the condition that  $V_{OLMAX} = 0.4V$ ,  $I_{OLMAX} = 3mA$  when the output is Low.

$$\frac{V_{CC} - V_{OL}}{R_{PU}} \leq I_{OL}$$

$$\therefore R_{PU} \geq \frac{V_{CC} - V_{OL}}{I_{OL}}$$

②  $V_{OLMAX} = 0.4V$  must be lower than the input Low level of the microcontroller and the EEPROM including the recommended noise margin of  $0.1V_{CC}$ .

$$V_{OLMAX} \leq V_{IL} - 0.1 V_{CC}$$

Examples:  $V_{CC} = 3V$ ,  $V_{OL} = 0.4V$ ,  $I_{OL} = 3mA$ , the  $V_{IL}$  of the controller and the EEPROM is  $V_{IL} = 0.3V_{CC}$ , According to ①

$$R_{PU} \geq \frac{3 - 0.4}{3 \times 10^{-3}}$$

$$\geq 867 \text{ [}\Omega\text{]}$$

$$\text{and } V_{OL} = 0.4 \text{ [V]}$$

$$\text{and } V_{IL} = 0.3 \times 3$$

$$= 0.9 \text{ [V]}$$

o that condition ② is met

### ○ SCL Pin Pull-up Resistor

When SCL is controlled by the CMOS output the pull-up resistor at SCL is not required.

However, should SCL be set to Hi-Z, connection of a pull-up resistor between SCL and  $V_{CC}$  is recommended.

Several k $\Omega$  are recommended for the pull-up resistor in order to drive the output port of the microcontroller.

## ● A0, A1, A2, WP Pin connections

### ○ Device Address Pin (A0, A1, A2) connections

The status of the device address pins is compared with the device address sent by the Master. One of the devices that is connected to the identical BUS is selected. Pull up or down these pins or connect them to  $V_{CC}$  or GND. Pins that are not used as device address (N.C.Pins) may be High, Low, or Hi-Z.

### ○ WP Pin connection

The WP input allows or prohibits write operations. When WP is High, only Read is available and Write to all address is prohibited. Both Read and Write are available when WP is Low.

In the event that the device is used as a ROM, it is recommended that the WP input be pulled up or connected to  $V_{CC}$ .

When both READ and WRITE are operated, the WP input must be pulled down or connected to GND or controlled.

## ●Microcontroller connection

### ○Concerning Rs

The open drain interface is recommended for the SDA port in the I<sup>2</sup>C BUS. However, if the Tri-state CMOS interface is applied to SDA, insert a series resistor (Rs) between the SDA pin of the device and the pull up resistor RPU is recommended, since it will serve to limit the current between the PMOS of the microcontroller, and the NMOS of the EEPROM. Rs also protects the SDA pin from surges. Therefore, Rs is able to be used though open drain in/out of the SDA port.

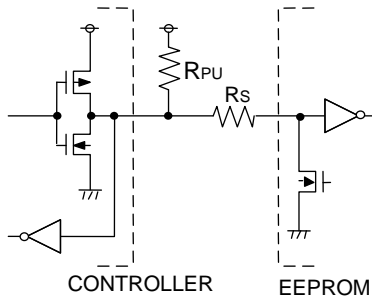


Fig.44 I/O Circuit

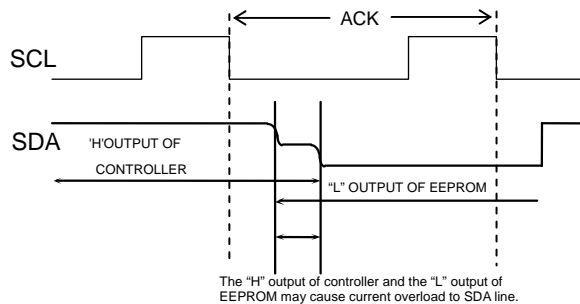


Fig.45 Input/Output Collision Timing

### ○Rs Maximum

The maximum value of Rs is determined by following factors.

- ① SDA rise time determined by RPU and the capacitance value of the BUS line (CBUS) of SDA must be less than tR. In addition, the other timings must be within the timing conditions of the AC.
- ② When the output from SDA is Low, the voltage of the BUS at ④ is determined by RPU, and Rs must be lower than the input Low level of the microcontroller, including recommended noise margin (0.1VCC).

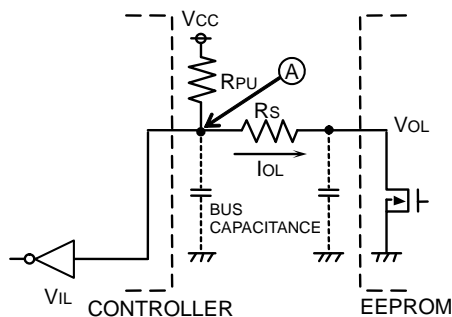


Fig.46 I/O Circuit

$$\frac{(V_{CC}-V_{OL}) \times R_S}{R_{PU}+R_S} + V_{OL} + 0.1V_{CC} \leq V_{IL}$$

$$\therefore R_S \leq \frac{V_{IL}-V_{OL}-0.1V_{CC}}{1.1V_{CC}-V_{IL}} \times R_{PU}$$

Examples : When VCC=3V VIL=0.3VCC VOL=0.4V RPU=20kΩ

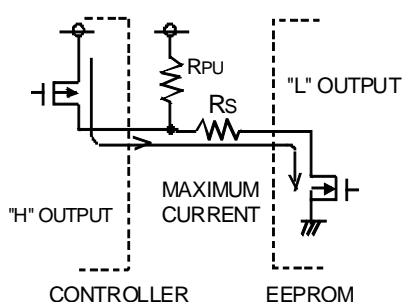
$$\begin{aligned} \text{According to ② } R_S &\leq \frac{0.3 \times 3 - 0.4 - 0.1 \times 3}{1.1 \times 3 - 0.3 \times 3} \times 20 \times 10^3 \\ &\leq 1.67 \text{ [k}\Omega\text{]} \end{aligned}$$

### ○Rs Minimum

The minimum value of Rs is determined by the current overload during BUS conflict.

Current overload may cause noises in the power line and instantaneous power down.

The following conditions must be met, where "I" is the maximum permissible current, which depends on the VCC line impedance as well as other factors. "I" current must be less than 10mA for EEPROM.



$$\frac{V_{CC}}{R_S} \leq I$$

$$\therefore R_S \geq \frac{V_{CC}}{I}$$

Examples: When VCC=3V, I=10mA

$$\begin{aligned} R_S &\geq \frac{3}{10 \times 10^{-3}} \\ &\geq 300 \text{ [}\Omega\text{]} \end{aligned}$$

Fig.47 I/O Circuit

● I<sup>2</sup>C BUS Input / Output equivalent circuits

OInput (A0,A2,SCL)

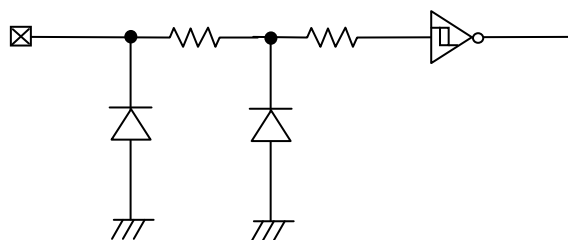


Fig.48 Input Pin Circuit

OInput / Output (SDA)

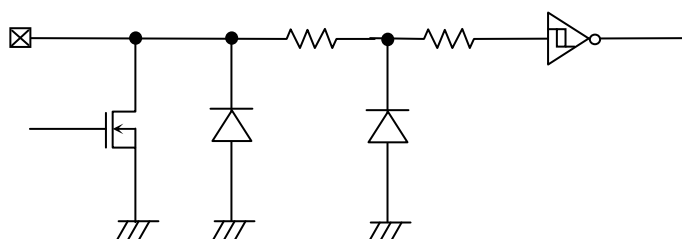


Fig.49 Input / Output Pin Circuit

OInput (A1)

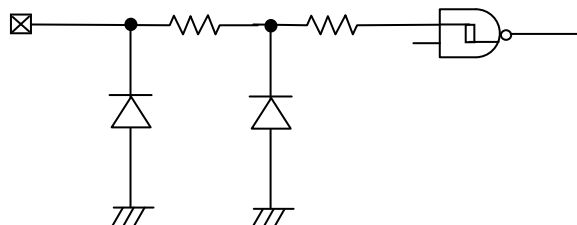


Fig.50 Input Pin Circuit

OInput (WP)

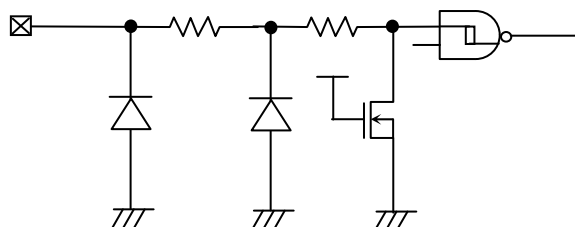


Fig.51 Input Pin Circuit

### ●Power Supply Notes

Vcc increases through the low voltage region where the internal circuit of IC and the microcontroller are unstable. In order to prevent malfunction, the IC has P.O.R. and LVcc functionality. During power up, ensure that the following conditions are met to guaranty P.O.R. and LVcc operability.

1. "SDA='H'" and "SCL='L' or 'H'".
2. Follow the recommended conditions of tR, tOFF, Vbot so that P.O.R. will be activated during power up.

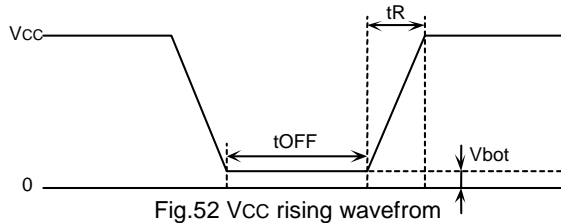


Fig.52 Vcc rising waveform

Recommended conditions of tR, tOFF, Vbot

| tR          | tOFF       | Vbot       |
|-------------|------------|------------|
| Below 10ms  | Above 10ms | Below 0.3V |
| Below 100ms | Above 10ms | Below 0.2V |

3. Prevent SDA and SCL from being "Hi-Z".

In case that condition 1. and/or 2. cannot be met, take following actions.

A) If unable to keep Condition 1 (SDA is "Low" during power up)

→Make sure that SDA and SCL are "High" as in the figure below.

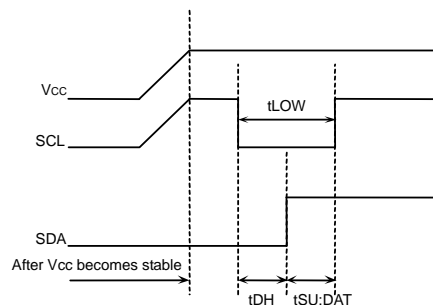


Fig.53 SCL="H" and SDA="L"

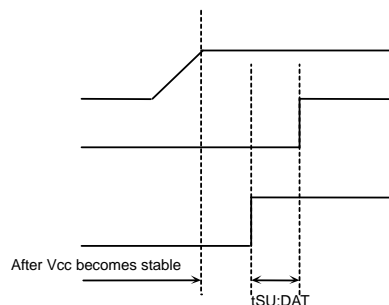


Fig.54 SCL="L" and SDA="L"

B) If unable to keep Condition 2

→After the power stabilizes, execute software reset. (See page 9,10)

C) If unable to keep either Condition 1 or 2

→Follow Instruction A first, then B

### ●LVcc Circuit

The LVcc circuit prevents Write operation at low voltage and prevents inadvertent writing. A voltage below the LVcc voltage (1.2V typ.) prohibits Write operation.

### ●Vcc Noise

#### ○Bypass Capacitor

Noise and surges on the power line may cause abnormal function. It is recommended that bypass capacitors (0.1μF) be attached between Vcc and GND externally.



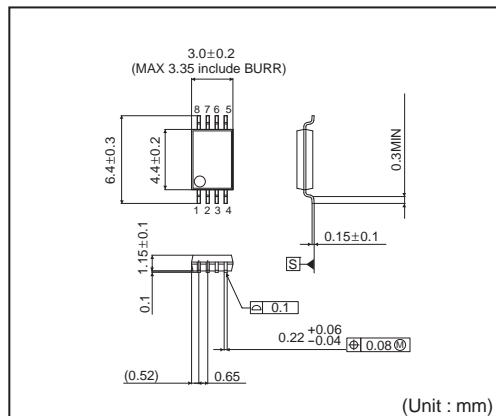
## ●Notes for Use

- 1) Described numeric values and data are design representative values, and the values are not guaranteed.
- 2) We believe that application circuit examples are recommendable, however, in actual use, confirm characteristics further sufficiently. In the case of use by changing the fixed number of external parts, make your decision with sufficient margin in consideration of static characteristics and transition characteristics and fluctuations of external parts and our LSI.
- 3) Absolute maximum ratings  
If the absolute maximum ratings such as impressed voltage and action temperature range and so forth are exceeded, LSI may be destructed. Do not impress voltage and temperature exceeding the absolute maximum ratings. In the case of fear exceeding the absolute maximum ratings, take physical safety countermeasures such as fuses, and see to it that conditions exceeding the absolute maximum ratings should not be impressed to LSI.
- 4) GND electric potential  
Set the voltage of GND terminal lowest at any action condition. Make sure that each terminal voltage is lower than that of GND terminal.
- 5) Heat design  
In consideration of permissible dissipation in actual use condition, carry out heat design with sufficient margin.
- 6) Terminal to terminal short circuit and wrong packaging  
When to package LSI on to a board, pay sufficient attention to LSI direction and displacement. Wrong packaging may destruct LSI. And in the case of short circuit between LSI terminals and terminals and power source, terminal and GND owing to foreign matter, LSI may be destructed.
- 7) Use in a strong electromagnetic field may cause malfunction, therefore, evaluate design sufficiently.

## ●Ordering part number

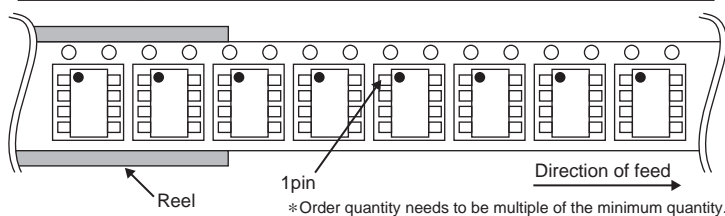
|           |          |                                   |          |              |                    |          |  |          |          |   |  |          |          |
|-----------|----------|-----------------------------------|----------|--------------|--------------------|----------|--|----------|----------|---|--|----------|----------|
| <b>B</b>  | <b>R</b> | <b>3</b>                          | <b>4</b> | <b>E</b>     | <b>0</b>           | <b>2</b> | <b>F</b>                                   | <b>V</b> | <b>T</b> | - | <b>W</b>   | <b>E</b> | <b>2</b> |
| ROHM type |          | BUS type<br>34 : I <sup>2</sup> C |          | Product type | Capacity<br>02= 2K |          | Packag<br>FVT:TSSOP-B8<br>NUX:VSON008X2030 |          |          |   | W : Double cell<br>Packaging and forming specification<br>E2: Embossed tape and reel<br>(TSSOP-B8)<br>TR: Embossed tape and reel<br>(VSON008X2030) |          |          |

## SSOP-B8

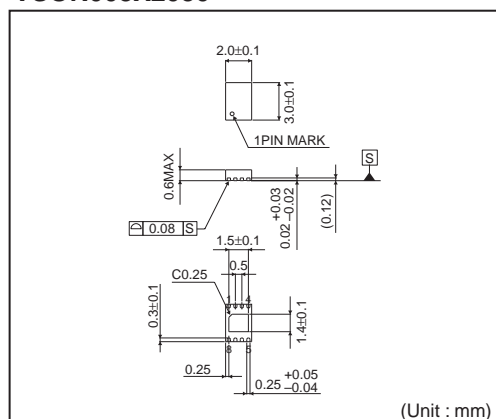


## &lt;Tape and Reel information&gt;

|                   |   |
|-------------------|---|
| Tape              | Embossed carrier tape   |
| Quantity          | 2500pcs   |
| Direction of feed | E2<br>(The direction is the 1pin of product is at the upper left when you hold reel on the left hand and you pull out the tape on the right hand) |

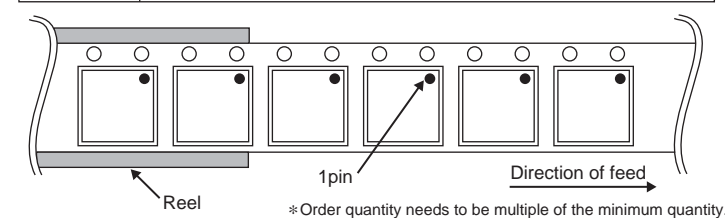


## VSON008X2030



## &lt;Tape and Reel information&gt;

|                   |  |
|-------------------|--|
| Tape              | Embossed carrier tape  |
| Quantity          | 4000pcs  |
| Direction of feed | TR<br>(The direction is the 1pin of product is at the upper right when you hold reel on the left hand and you pull out the tape on the right hand) |



## Notes

No copying or reproduction of this document, in part or in whole, is permitted without the consent of ROHM Co.,Ltd.

The content specified herein is subject to change for improvement without notice.

The content specified herein is for the purpose of introducing ROHM's products (hereinafter "Products"). If you wish to use any such Product, please be sure to refer to the specifications, which can be obtained from ROHM upon request.

Examples of application circuits, circuit constants and any other information contained herein illustrate the standard usage and operations of the Products. The peripheral conditions must be taken into account when designing circuits for mass production.

Great care was taken in ensuring the accuracy of the information specified in this document. However, should you incur any damage arising from any inaccuracy or misprint of such information, ROHM shall bear no responsibility for such damage.

The technical information specified herein is intended only to show the typical functions of and examples of application circuits for the Products. ROHM does not grant you, explicitly or implicitly, any license to use or exercise intellectual property or other rights held by ROHM and other parties. ROHM shall bear no responsibility whatsoever for any dispute arising from the use of such technical information.

The Products specified in this document are intended to be used with general-use electronic equipment or devices (such as audio visual equipment, office-automation equipment, communication devices, electronic appliances and amusement devices).

The Products specified in this document are not designed to be radiation tolerant.

While ROHM always makes efforts to enhance the quality and reliability of its Products, a Product may fail or malfunction for a variety of reasons.

Please be sure to implement in your equipment using the Products safety measures to guard against the possibility of physical injury, fire or any other damage caused in the event of the failure of any Product, such as derating, redundancy, fire control and fail-safe designs. ROHM shall bear no responsibility whatsoever for your use of any Product outside of the prescribed scope or not in accordance with the instruction manual.

The Products are not designed or manufactured to be used with any equipment, device or system which requires an extremely high level of reliability the failure or malfunction of which may result in a direct threat to human life or create a risk of human injury (such as a medical instrument, transportation equipment, aerospace machinery, nuclear-reactor controller, fuel-controller or other safety device). ROHM shall bear no responsibility in any way for use of any of the Products for the above special purposes. If a Product is intended to be used for any such special purpose, please contact a ROHM sales representative before purchasing.

If you intend to export or ship overseas any Product or technology specified herein that may be controlled under the Foreign Exchange and the Foreign Trade Law, you will be required to obtain a license or permit under the Law.



Thank you for your accessing to ROHM product informations.  
More detail product informations and catalogs are available, please contact us.

## ROHM Customer Support System

<http://www.rohm.com/contact/>



Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



#### Как с нами связаться

**Телефон:** 8 (812) 309 58 32 (многоканальный)

**Факс:** 8 (812) 320-02-42

**Электронная почта:** [org@eplast1.ru](mailto:org@eplast1.ru)

**Адрес:** 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.