

Hysteretic, Buck, High Brightness LED Driver with High-Side Current Sensing

Features

- ▶ Hysteretic control with high-side current sensing
- ▶ Wide input voltage range: 4.5 to 40V
- ▶ >90% Efficiency
- ▶ Typical $\pm 5\%$ LED current accuracy
- ▶ Up to 2.0MHz switching frequency
- ▶ Adjustable constant LED current
- ▶ Analog or PWM control signal for PWM dimming
- ▶ Over-temperature protection
- ▶ -40°C to $+125^{\circ}\text{C}$ operating temperature range
- ▶ AEC-Q100 compliant

Applications

- ▶ Automotive LED lighting applications

General Description

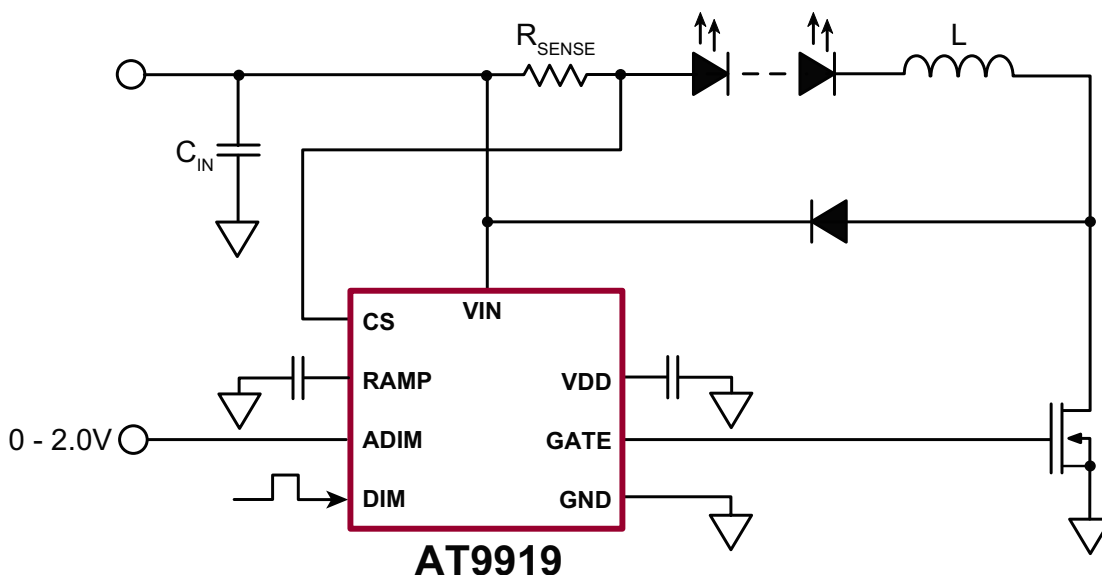
The AT9919 is a PWM controller IC designed to drive high brightness LEDs using a buck topology. It operates from an input voltage of 4.5 to 40VDC and employs hysteretic control with a high-side current sense resistor to set the constant output current.

The operating frequency range can be set by selecting the proper inductor. Operation at high switching frequency is possible since the hysteretic control maintains accuracy even at high frequencies. This permits the use of small inductors and capacitors minimizing space and cost in the overall system.

LED brightness control is achieved with PWM dimming from an analog or PWM input signal. Unique PWM circuitry allows true constant color with a high dimming range. The dimming frequency is programmed using a single external capacitor.

The AT9919 comes in a small, 8-Lead DFN package and is qualified for automotive LED lighting applications.

Typical Application Circuit



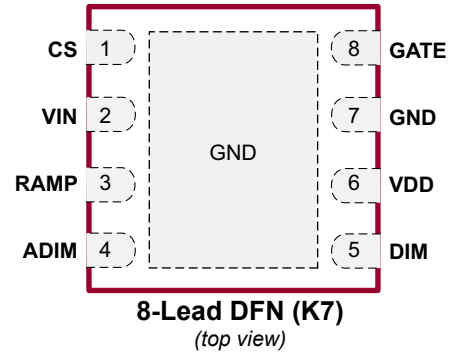
Ordering Information

Part Number	Package	Packing
AT9919K7-G	8-Lead DFN	3000/Reel

-G indicates package is RoHS compliant ('Green')



Pin Description

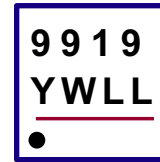


Absolute Maximum Ratings

Parameter	Value
VIN, CS to GND	-0.3 to +45V
VDD, GATE, RAMP, DIM, ADIM to GND	-0.3 to +6.0V
CS to VIN	-1.0 to +0.3V
Continuous power dissipation, ($T_A = +25^\circ\text{C}$)	1.6W
Operating temperature range	-40°C to $+125^\circ\text{C}$
Junction temperature	$+150^\circ\text{C}$
Storage temperature range	-65°C to $+150^\circ\text{C}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Product Marking



Y = Last Digit of Year Sealed
W = Code for Week Sealed
L = Lot Number
— = "Green" Packaging

8-Lead DFN (K7)

Typical Thermal Resistance

Package	θ_{ja}
8-Lead DFN	37°C/W

Mounted on FR-4 board, 25mm x 25mm x 1.57mm

Electrical Characteristics

($V_{IN} = 12\text{V}$, $V_{DIM} = V_{DD}$, $V_{RAMP} = \text{GND}$, $C_{VDD} = 1.0\mu\text{F}$, $R_{CS} = 0.5\Omega$, $T_A = T_J = -40^\circ\text{C}$ to $+125^\circ\text{C}$ * unless otherwise noted)

Sym	Description	Min	Typ	Max	Units	Conditions
V_{IN}	Input DC supply voltage range	4.5	-	40	V	DC input voltage
V_{DD}	Internally regulated voltage	4.5	-	5.5	V	$V_{IN} = 6.0$ to 40V
I_{IN}	Supply current	-	-	1.5	mA	GATE open
$I_{IN, SDN}$	Shutdown supply current	-	-	900	μA	$\text{DIM} < 0.7\text{V}$
$I_{IN, LIM}$	Current limit	-	30	-	mA	$V_{IN} = 4.5\text{V}$, $V_{DD} = 0\text{V}$
		-	8.0	-		$V_{IN} = 4.5\text{V}$, $V_{DD} = 4.0\text{V}$
f_{OSC}	Oscillator frequency	-	-	2.0	MHz	---
UVLO	V_{DD} Undervoltage lockout threshold	-	-	4.5	V	V_{DD} rising
ΔUVLO	V_{DD} Undervoltage lockout hysteresis	-	500	-	mV	V_{DD} falling

* Guaranteed by design and characterization, 100% tested at $T_A = 25^\circ\text{C}$. Typical characteristics are given at $T_A = 25^\circ\text{C}$.

Electrical Characteristics

($V_{IN} = 12V$, $V_{DIM} = V_{DD}$, $V_{RAMP} = GND$, $C_{VDD} = 1.0\mu F$, $R_{CS} = 0.5\Omega$, $T_A = T_J = -40^\circ C$ to $+125^\circ C$ * unless otherwise noted)

Sym	Description	Min	Typ	Max	Units	Conditions
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Sense Comparator

$V_{CS(HI)}$	Sense voltage threshold high	198	230	257	mV	$(V_{IN} - V_{CS})$ rising
$V_{CS(LO)}$	Sense voltage threshold low	147	170	195	mV	$(V_{IN} - V_{CS})$ falling
$V_{CS(AVG)}$	Average reference voltage	186	200	214	mV	$V_{CS(AVG)} = 0.5V_{CS(HI)} + 0.5V_{CS(LO)}$
t_{DPDH}	Propagation delay to output high	-	70	-	ns	Falling edge of $(V_{IN} - V_{CS}) = V_{RS(LO)} - 70mV$
t_{DPDL}	Propagation delay to output low	-	70	-	ns	Rising edge of $(V_{IN} - V_{CS}) = V_{RS(HI)} + 70mV$
I_{CS}	Current-sense input current	-	-	1.0	μA	$(V_{IN} - V_{CS}) = 200mV$
$V_{CS(HYS)}$	Current-sense threshold hysteresis	-	56	80	mV	---

DIM Input

V_{IH}	Pin DIM input high voltage	2.2	-	-	V	---
V_{IL}	Pin DIM input low voltage	-	-	0.7	V	---
t_{ON}	Turn-on time	-	100	-	ns	DIM rising edge to $V_{GATE} = 0.5 \times V_{DD}$, $C_{GATE} = 2.0nF$
t_{OFF}	Turn-off time	-	100	-	ns	DIM falling edge to $V_{GATE} = 0.5 \times V_{DD}$, $C_{GATE} = 2.0nF$

Gate Driver

I_{GATE}	GATE current, source†	0.3	0.5	-	A	$V_{GATE} = GND$
	GATE current, sink†	0.7	1.0	-	A	$V_{GATE} = V_{DD}$
T_{RISE}	GATE output rise time	-	40	55	ns	$C_{GATE} = 2.0nF$
T_{FALL}	GATE output fall time	-	17	25	ns	$C_{GATE} = 2.0nF$
$V_{GATE(HI)}$	GATE high output voltage	$V_{DD} - 0.5$	-	-	V	$I_{GATE} = 10mA$
$V_{GATE(LO)}$	GATE low output voltage	-	-	0.5	V	$I_{GATE} = -10mA$

Over-Temperature Protection

T_{OT}	Over temperature trip limit†	128	140	-	$^\circ C$	---
ΔT_{HYST}	Temperature hysteresis†	-	60	-	$^\circ C$	---

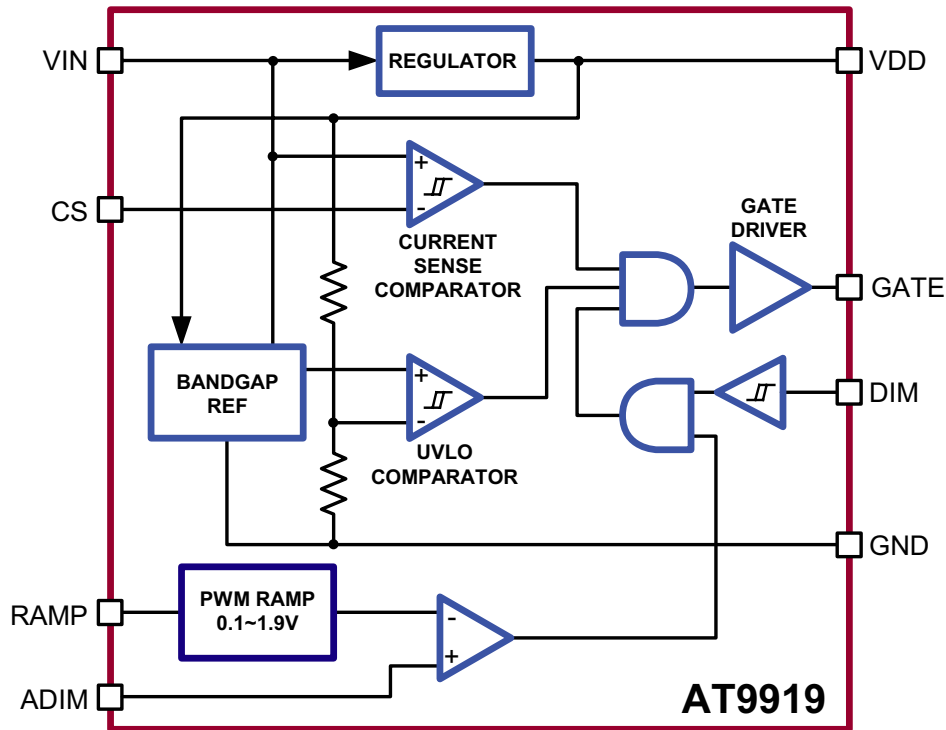
Analog Control of PWM Dimming

f_{RAMP}	Dimming frequency	130	-	300	Hz	$C_{RAMP} = 47nF$
		550	-	1250		$C_{RAMP} = 10nF$
V_{LOW}	RAMP threshold, Low	-	0.1	-	V	---
V_{HIGH}	RAMP threshold, High	1.8	-	2.1	V	---
V_{OS}	ADIM offset voltage	-35	-	+35	mV	---

* Guaranteed by design and characterization, 100% tested at $T_A = 25^\circ C$. Typical characteristics are given at $T_A = 25^\circ C$.

† Guaranteed by design and characterization.

Block Diagram



Application Information

General Description

The AT9919 is a step-down, constant current, high-brightness LED (HB LED) driver. The device operates from a 4.5 to 40V input voltage range and provides the gate drive output to an external N-channel MOSFET. A high-side current sense resistor sets the output current and a dedicated PWM dimming input (DIM) allows for a wide range of dimming duty ratios. The PWM dimming could also be achieved by applying a DC voltage between 0 and 2.0V to the analog dimming input (ADIM). In this case, the dimming frequency can be programmed using a single capacitor at the RAMP pin. The high-side current setting and sensing scheme minimizes the number of external components while delivering LED current with a $\pm 8\%$ accuracy, using a 1% sense resistor.

Undervoltage Lockout (UVLO)

The AT9919 includes a 3.7V under-voltage lockout (UVLO) with 500mV hysteresis. When V_{IN} falls below 3.7V, GATE goes low, turning off the external n-channel MOSFET. GATE goes high once V_{IN} is 4.5V or higher.

5.0V Regulator

VDD is the output of a 5.0V regulator capable of sourcing 8.0mA. Bypass VDD to GND with a 1.0 μ F capacitor.

DIM Input

The AT9919 allows dimming with a PWM signal at the DIM input. A logic level below 0.7V at DIM forces the $GATE_{OUTPUT}$ low, turning off the LED current. To turn the LED current on, the logic level at DIM must be at least 2.2V.

ADIM and RAMP Inputs

The PWM dimming scheme can be also implemented by applying an analog control signal to ADIM pin. If an analog control signal of 0~2.0V is applied to ADIM, the device compares this analog input to a voltage ramp to pulse-width-modulate the LED current. Connecting an external capacitor to RAMP programs the PWM dimming ramp frequency.

$$f_{PWM} = \frac{1}{C_{RAMP} \cdot 120k\Omega}$$

DIM and ADIM inputs can be used simultaneously. In such case, $f_{PWM(MAX)}$ must be selected lower than the frequency of the dimming signal at DIM. The smaller dimming duty cycle of ADIM and DIM will determine the GATE signal.

When the analog control of PWM dimming feature is not used, RAMP must be wired to GND, and ADIM should be connected to VDD.

One possible application of the ADIM feature of the AT9919 may include protection of the LED load from over-temperature by connecting an NTC thermistor at ADIM, as shown in Figure 1.

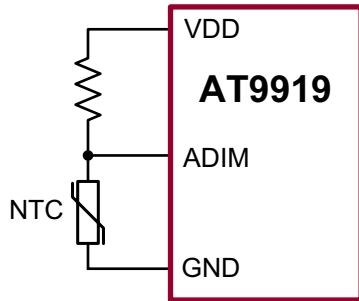


Figure 1

Setting LED Current with External Resistor R_{SENSE}

The output current in the LED is determined by the external current sense resistor (R_{SENSE}) connected between V_{IN} and CS. Disregarding the effect of the propagation delays, the sense resistor can be calculated as:

$$R_{SENSE} \approx \frac{1}{2} \cdot \frac{(V_{RS(HI)} + V_{RS(LO)})}{I_{LED}} = \frac{200mV}{I_{LED}}$$

Selecting Buck Inductor L

The AT9919 regulates the LED output current using an input

comparator with hysteresis (Figure 2). As the current through the inductor ramps up and the voltage across the sense resistor reaches the upper threshold, the voltage at GATE goes low, turning off the external MOSFET. The MOSFET turns on again when the inductor current ramps down through the freewheeling diode until the voltage across the sense resistor equals the lower threshold. Use the following equation to determine the inductor value for a desired value of operating frequency f_s :

$$L = \frac{(V_{IN} - V_{OUT})V_{OUT}}{f_s V_{IN} \Delta I_O} - \frac{(V_{IN} - V_{OUT})t_{DPDL}}{\Delta I_O} - \frac{V_{OUT}t_{DPDH}}{\Delta I_O}$$

where:

$$\Delta I_O = \frac{V_{RS(HI)} - V_{RS(LO)}}{R_{SENSE}}$$

and t_{DPDL} , t_{DPDH} are the propagation delays. Note, that the current ripple ΔI in the inductor L is greater than ΔI_O . This ripple can be calculated from the following equation:

$$\Delta I = \Delta I_O + \frac{(V_{IN} - V_{OUT})t_{DPDL}}{L} + \frac{V_{OUT}t_{DPDH}}{L}$$

For the purpose of the proper inductor selection, note that the maximum switching frequency occurs at the highest V_{IN} and $V_{OUT} = V_{IN}/2$.

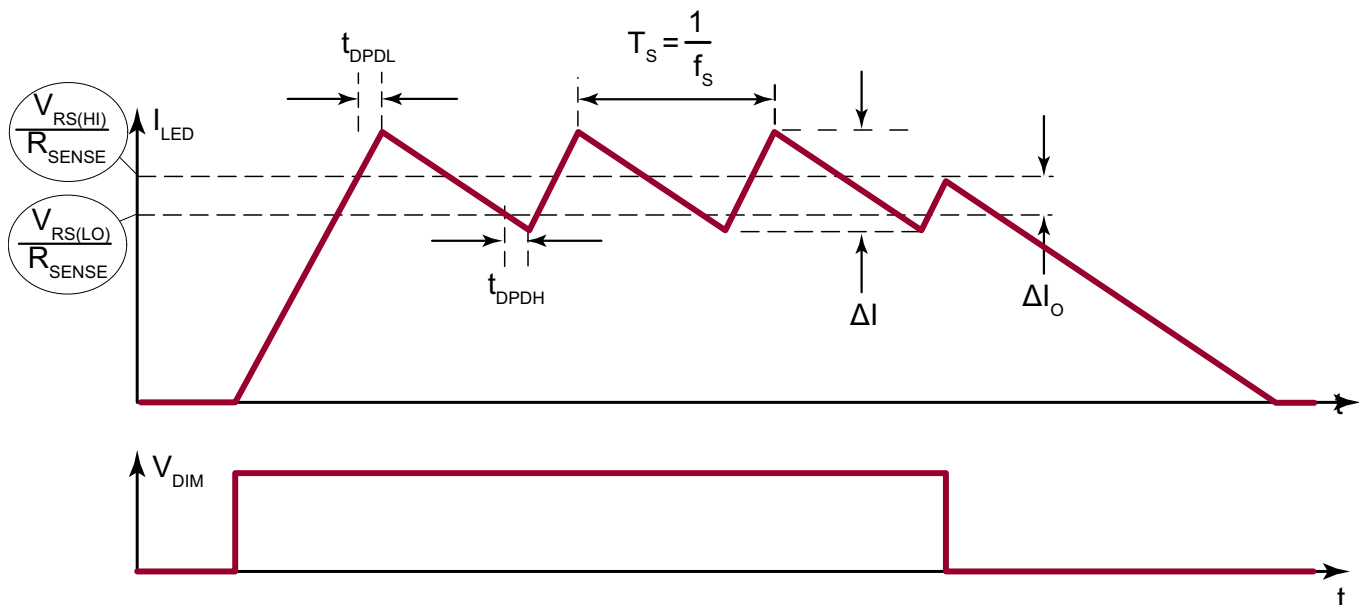


Figure 2

MOSFET Selection

MOSFET selection is based on the maximum input operating voltage V_{IN} , output current I_{LED} , and operating switching frequency. Choose a MOSFET that has a higher breakdown voltage than the maximum operation voltage, low $R_{DS(ON)}$, and low total charge for better efficiency. MOSFET threshold voltage must be adequate if operated at the low end of the input-voltage operating range.

Freewheeling Diode Selection

The forward voltage of the freewheeling diode should be as low as possible for better efficiency. A Schottky diode is a good choice as long as the breakdown voltage is high enough to withstand the maximum operating voltage. The forward current rating of the diode must be at least equal to the maximum LED current.

LED Current Ripple

The LED current ripple is equal to the inductor current ripple. In cases when a lower LED current ripple is needed, a capacitor can be placed across the LED terminals.

PCB Layout Guidelines

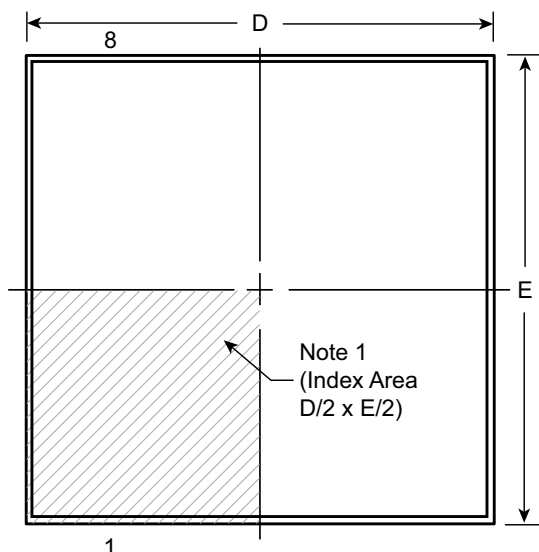
Careful PCB layout is critical to achieve low switching losses and stable operation. Use a multilayer board whenever possible for better noise immunity. Minimize ground noise by connecting high-current ground returns, the input bypass capacitor ground lead, and the output filter ground lead to a single point (star ground configuration). The fast di/dt loop is formed by the input capacitor C_{IN} , the free-wheeling diode and the MOSFET. To minimize noise interaction, this loop area should be as small as possible. Place R_{SENSE} as close as possible to the input filter and V_{IN} . For better noise immunity, a Kelvin connection is strongly recommended between CS and R_{SENSE} . Connect the exposed tab of the IC to a large-area ground plane for improved power dissipation.

Pin Description

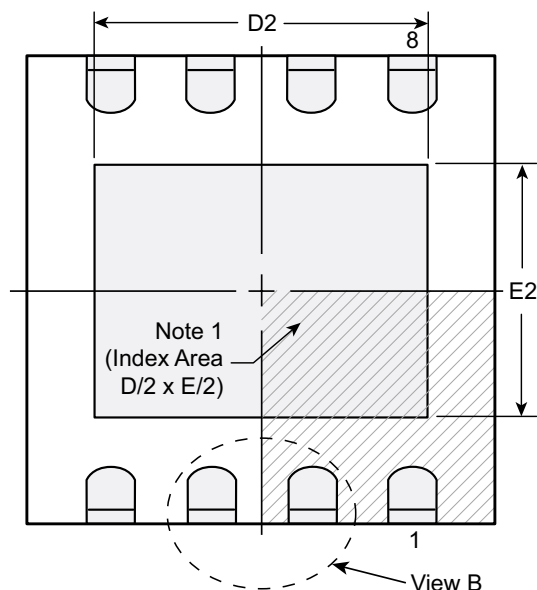
Pin #	Pin	Description
1	CS	Current sense input. Senses LED string current.
2	VIN	Input voltage 4.5 to 40VDC.
3	RAMP	Analog PWM dimming ramp output.
4	ADIM	Analog 0~2.0V signal input for analog control of PWM dimming.
5	DIM	PWM signal input.
6	VDD	Internally regulated supply voltage. Connect a capacitor from VDD to ground.
7	GND	Device ground.
8	GATE	Drives gate of external MOSFET.
TAB	GND	Must be wired to pin 7 on PCB.

8-Lead DFN Package Outline (K7)

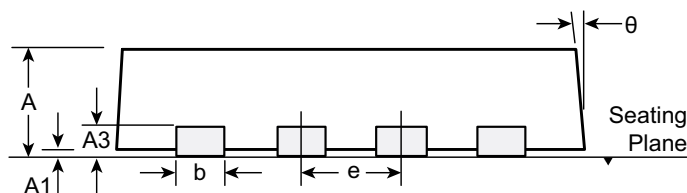
3.00x3.00mm body, 0.80mm height (max), 0.65mm pitch



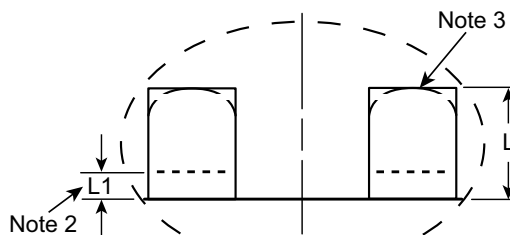
Top View



Bottom View



Side View



View B

Notes:

1. A Pin 1 identifier must be located in the index area indicated. The Pin 1 identifier can be: a molded mark/identifier; an embedded metal marker; or a printed indicator.
2. Depending on the method of manufacturing, a maximum of 0.15mm pullback (L1) may be present.
3. The inner tip of the lead may be either rounded or square.

Symbol		A	A1	A3	b	D	D2	E	E2	e	L	L1	θ
Dimension (mm)	MIN	0.70	0.00	0.20 REF	0.25	2.85*	1.60	2.85*	1.35	0.65 BSC	0.30	0.00*	0°
	NOM	0.75	0.02		0.30	3.00	-	3.00	-		0.40	-	-
	MAX	0.80	0.05		0.35	3.15*	2.50	3.15*	1.75		0.50	0.15	14°

JEDEC Registration MO-229, Variation WEEC-2, Issue C, Aug. 2003.

* This dimension is not specified in the JEDEC drawing.

Drawings not to scale.

Supertex Doc. #: DSPD-8DFNK73X3P065, Version C081109.

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to <http://www.supertex.com/packaging.html>.)

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- Техническая поддержка проекта;
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