

512Mb(32Mx16) GDDR SDRAM

HY5DU121622CTP

Revision History

Revision No.	History	Draft Date	Remark
0.1	Initial Graphics Version Release	Jan. 2005	
0.2	Lead free Support & DC parameter change	Apr. 2005	
0.3	IDD Value change	Apr. 2005	

DESCRIPTION

The HY5DU121622CTP is a 536,870,912-bit CMOS Double Data Rate(DDR) Synchronous DRAM, ideally suited for the main memory applications which requires large memory density and high bandwidth.

This Hynix 512Mb DDR SDRAMs offer fully synchronous operations referenced to both rising and falling edges of the clock. While all addresses and control inputs are latched on the rising edges of the CK (falling edges of the /CK), Data, Data strobes and Write data masks inputs are sampled on both rising and falling edges of it. The data paths are internally pipelined and 2-bit prefetched to achieve very high bandwidth. All input and output voltage levels are compatible with SSTL_2.

FEATURES

- VDD, VDDQ = 2.5V +/- 0.1V
- All inputs and outputs are compatible with SSTL_2 interface
- Fully differential clock inputs (CK, /CK) operation
- Double data rate interface
- Source synchronous - data transaction aligned to bidirectional data strobe (DQS)
- x16 device has two byte-wide data strobes (UDQS, LDQS) per each x8 I/O
- Data outputs on DQS edges when read (edged DQ)
Data inputs on DQS centers when write (centered DQ)
- On chip DLL align DQ and DQS transition with CK transition
- DM mask write data-in at the both rising and falling edges of the data strobe
- All addresses and control inputs except data, data strobes and data masks latched on the rising edges of the clock
- Programmable /CAS latency 3 supported
- Programmable burst length 2 / 4 / 8 with both sequential and interleave mode
- Internal four bank operations with single pulsed /RAS
- Auto refresh and self refresh supported
- tRAS lock out function supported
- 8192 refresh cycles / 64ms
- JEDEC standard 400mil 66pin TSOP-II with 0.65mm pin pitch
- Full and Half strength driver option controlled by EMRS

ORDERING INFORMATION

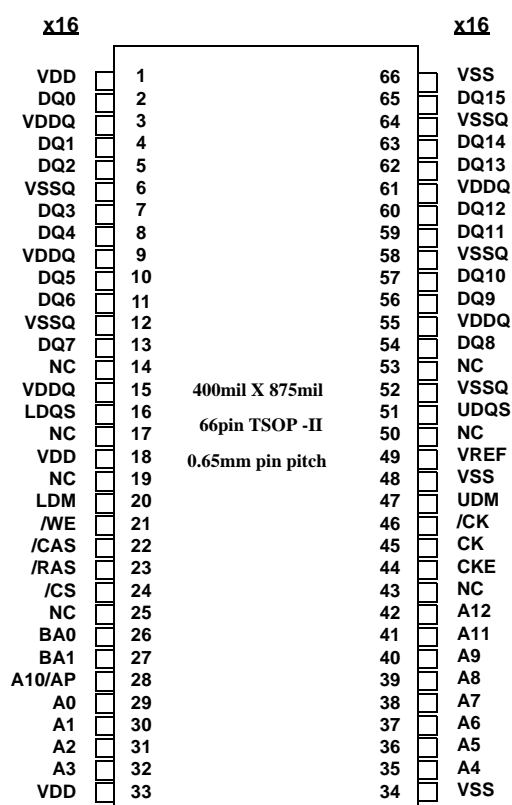
Part No.	Power Supply	Clock Frequency	Max Data Rate	Interface	Package
HY5DU121622CTP - 4	VDD/ VDDQ=2.5V	250Mhz	500Mbps/pin	SSTL_2	400mil 66pin TSOP-II
HY5DU121622CTP - 5		200Mhz	400Mbps/pin		
HY5DU121622CTP - 6		166Mhz	333Mbps/pin		

Note) Hynix supports Pb free parts for each speed grade with same specification, except Lead free material.

We'll add "P" character after "T" for Lead free product.

For example, the part number of 200Mhz Lead free product is HY5DU121622CTP-5.

PIN CONFIGURATION



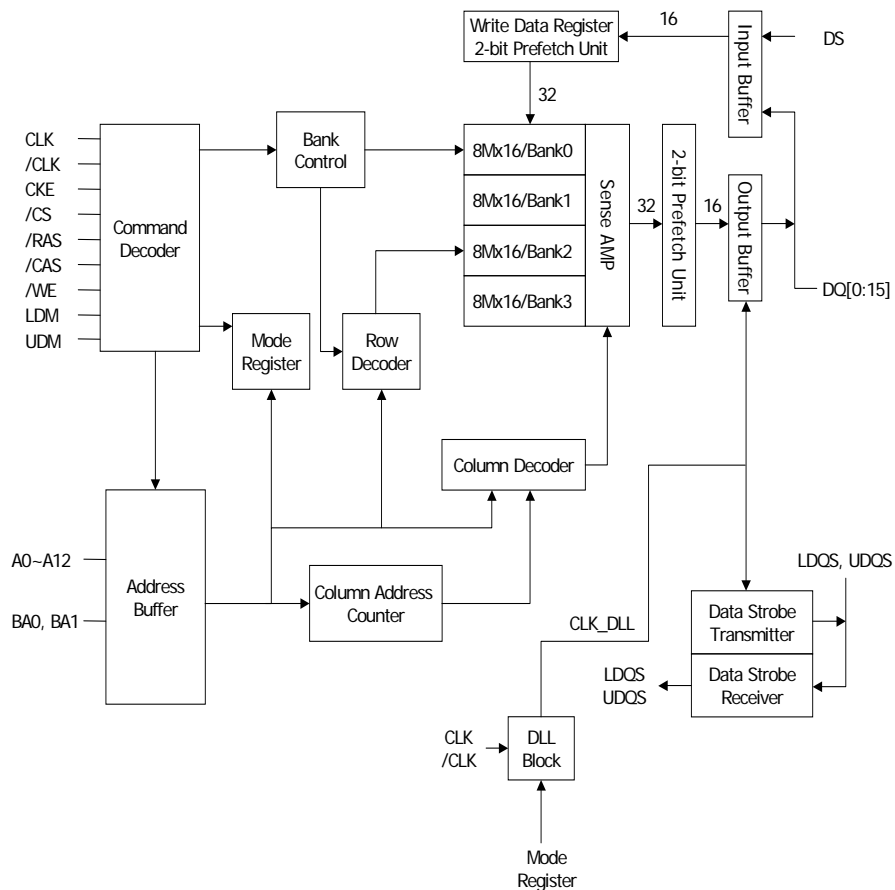
ROW AND COLUMN ADDRESS TABLE

ITEMS	32Mx16
Organization	8M x 16 x 4banks
Row Address	A0 - A12
Column Address	A0-A9
Bank Address	BA0, BA1
Auto Precharge Flag	A10
Refresh	8K

PIN DESCRIPTION

PIN	TYPE	DESCRIPTION
CK, /CK	Input	Clock: CK and /CK are differential clock inputs. All address and control input signals are sampled on the crossing of the positive edge of CK and negative edge of /CK. Output (read) data is referenced to the crossings of CK and /CK (both directions of crossing).
CKE	Input	Clock Enable: CKE HIGH activates, and CKE LOW deactivates internal clock signals, and device input buffers and output drivers. Taking CKE LOW provides PRECHARGE POWER DOWN and SELF REFRESH operation (all banks idle), or ACTIVE POWER DOWN (row ACTIVE in any bank). CKE is synchronous for POWER DOWN entry and exit, and for SELF REFRESH entry. CKE is asynchronous for SELF REFRESH exit, and for output disable. CKE must be maintained high throughout READ and WRITE accesses. Input buffers, excluding CK, /CK and CKE are disabled during POWER DOWN. Input buffers, excluding CKE are disabled during SELF REFRESH. CKE is an SSTL_2 input, but will detect an LVCMOS LOW level after Vdd is applied.
/CS	Input	Chip Select : Enables or disables all inputs except CK, /CK, CKE, DQS and DM. All commands are masked when CS is registered high. CS provides for external bank selection on systems with multiple banks. CS is considered part of the command code.
BA0, BA1	Input	Bank Address Inputs: BA0 and BA1 define to which bank an ACTIVE, Read, Write or PRECHARGE command is being applied.
A0 ~ A12	Input	Address Inputs: Provide the row address for ACTIVE commands, and the column address and AUTO PRECHARGE bit for READ/WRITE commands, to select one location out of the memory array in the respective bank. A10 is sampled during a precharge command to determine whether the PRECHARGE applies to one bank (A10 LOW) or all banks (A10 HIGH). If only one bank is to be precharged, the bank is selected by BA0, BA1. The address inputs also provide the op code during a MODE REGISTER SET command. BA0 and BA1 define which mode register is loaded during the MODE REGISTER SET command (MRS or EMRS).
/RAS, /CAS, /WE	Input	Command Inputs: /RAS, /CAS and /WE (along with /CS) define the command being entered.
DM (LDM,UDM)	Input	Input Data Mask: DM is an input mask signal for write data. Input data is masked when DM is sampled HIGH along with that input data during a WRITE access. DM is sampled on both edges of DQS. Although DM pins are input only, the DM loading matches the DQ and DQS loading. For the x16, LDM corresponds to the data on DQ0-Q7; UDM corresponds to the data on DQ8-Q15.
DQS (LDQS,UDQS)	I/O	Data Strobe: Output with read data, input with write data. Edge aligned with read data, centered in write data. Used to capture write data. For the x16, LDQS corresponds to the data on DQ0-Q7; UDQS corresponds to the data on DQ8-Q15.
DQ	I/O	Data input / output pin : Data bus
VDD/VSS	Supply	Power supply for internal circuits and input buffers.
VDDQ/VSSQ	Supply	Power supply for output buffers for noise immunity.
VREF	Supply	Reference voltage for inputs for SSTL interface.
NC	NC	No connection.

4Banks x 8Mbit x 16 I/O Double Data Rate Synchronous DRAM



SIMPLIFIED COMMAND TRUTH TABLE

Command		CKEn-1	CKEn	CS	RAS	CAS	WE	ADDR	A10/ AP	BA	Note
Extended Mode Register Set		H	X	L	L	L	L	OP code			1,2
Mode Register Set		H	X	L	L	L	L	OP code			1,2
Device Deselect		H	X	H	X	X	X	X			1
No Operation				L	H	H	H				
Bank Active		H	X	L	L	H	H	RA		V	1
Read		H	X	L	H	L	H	CA	L	V	1
Read with Autoprecharge									H		1,3
Write		H	X	L	H	L	L	CA	L	V	1
Write with Autoprecharge									H		1,4
Precharge All Banks		H	X	L	L	H	L	X	H	X	1,5
Precharge selected Bank									L	V	1
Read Burst Stop		H	X	L	H	H	L	X			1
Auto Refresh		H	H	L	L	L	H	X			1
Self Refresh	Entry	H	L	L	L	L	H	X			1
	Exit	L	H	H	X	X	X				1
				L	H	H	H				
Precharge Power Down Mode	Entry	H	L	H	X	X	X	X			1
				L	H	H	H				1
	Exit	L	H	H	X	X	X				1
				L	H	H	H				1
Active Power Down Mode	Entry	H	L	H	X	X	X	X			1
				L	V	V	V				1
	Exit	L	H	X							1

(H=Logic High Level, L=Logic Low Level, X=Don't Care, V=Valid Data Input, OP Code=Operand Code, NOP=No Operation)

Note :

1. LDM/UDM states are Don't Care. Refer to below Write Mask Truth Table.
2. OP Code(Operand Code) consists of A0~A12 and BA0~BA1 used for Mode Register setting during Extended MRS or MRS.
Before entering Mode Register Set mode, all banks must be in a precharge state and MRS command can be issued after tRP period from Prechagre command.
3. If a Read with Autoprecharge command is detected by memory component in CK(n), then there will be no command presented to activated bank until CK(n+BL/2+tRP).
4. If a Write with Autoprecharge command is detected by memory component in CK(n), then there will be no command presented to activated bank until CK(n+BL/2+1+tDPL+tRP). Last Data-In to Prechage delay(tDPL) which is also called Write Recovery Time (tWR) is needed to guarantee that the last data has been completely written.
5. If A10/AP is High when Precharge command being issued, BA0/BA1 are ignored and all banks are selected to be precharged.

WRITE MASK TRUTH TABLE

Function	CKEn-1	CKEn	/CS, /RAS, /CAS, /WE	DM	ADDR	A10/ AP	BA	Note
Data Write	H	X	X	L		X		1
Data-In Mask	H	X	X	H		X		1

Note :

1. Write Mask command masks burst write data with reference to LDQS/UDQS(Data Strokes) and it is not related with read data. In case of x16 data I/O, LDM and UDM control lower byte(DQ0~7) and Upper byte(DQ8~15) respectively.

OPERATION COMMAND TRUTH TABLE-I

Current State	/CS	/RAS	/CAS	/WE	Address	Command	Action
IDLE	H	X	X	X	X	DSEL	NOP or power down ³
	L	H	H	H	X	NOP	NOP or power down ³
	L	H	H	L	X	BST	ILLEGAL ⁴
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL ⁴
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL ⁴
	L	L	H	H	BA, RA	ACT	Row Activation
	L	L	H	L	BA, AP	PRE/PALL	NOP
	L	L	L	H	X	AREF/SREF	Auto Refresh or Self Refresh ⁵
	L	L	L	L	OPCODE	MRS	Mode Register Set
ROW ACTIVE	H	X	X	X	X	DSEL	NOP
	L	H	H	H	X	NOP	NOP
	L	H	H	L	X	BST	ILLEGAL ⁴
	L	H	L	H	BA, CA, AP	READ/READAP	Begin read : optional AP ⁶
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	Begin write : optional AP ⁶
	L	L	H	H	BA, RA	ACT	ILLEGAL ⁴
	L	L	H	L	BA, AP	PRE/PALL	Precharge ⁷
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
READ	H	X	X	X	X	DSEL	Continue burst to end
	L	H	H	H	X	NOP	Continue burst to end
	L	H	H	L	X	BST	Terminate burst
	L	H	L	H	BA, CA, AP	READ/READAP	Term burst, new read:optional AP ⁸
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL
	L	L	H	H	BA, RA	ACT	ILLEGAL ⁴
	L	L	H	L	BA, AP	PRE/PALL	Term burst, precharge
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
WRITE	H	X	X	X	X	DSEL	Continue burst to end
	L	H	H	H	X	NOP	Continue burst to end
	L	H	H	L	X	BST	ILLEGAL ⁴
	L	H	L	H	BA, CA, AP	READ/READAP	Term burst, new read:optional AP ⁸
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	Term burst, new write:optional AP

OPERATION COMMAND TRUTH TABLE-II

Current State	/CS	/RAS	/CAS	/WE	Address	Command	Action
WRITE	L	L	H	H	BA, RA	ACT	ILLEGAL ⁴
	L	L	H	L	BA, AP	PRE/PALL	Term burst, precharge
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
READ WITH AUTOPRE-CHARGE	H	X	X	X	X	DSEL	Continue burst to end
	L	H	H	H	X	NOP	Continue burst to end
	L	H	H	L	X	BST	ILLEGAL
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL ¹⁰
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL ¹⁰
	L	L	H	H	BA, RA	ACT	ILLEGAL ^{4,10}
	L	L	H	L	BA, AP	PRE/PALL	ILLEGAL ^{4,10}
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
WRITE AUTOPRE-CHARGE	H	X	X	X	X	DSEL	Continue burst to end
	L	H	H	H	X	NOP	Continue burst to end
	L	H	H	L	X	BST	ILLEGAL
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL ¹⁰
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL ¹⁰
	L	L	H	H	BA, RA	ACT	ILLEGAL ^{4,10}
	L	L	H	L	BA, AP	PRE/PALL	ILLEGAL ^{4,10}
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
PRE-CHARGE	H	X	X	X	X	DSEL	NOP-Enter IDLE after tRP
	L	H	H	H	X	NOP	NOP-Enter IDLE after tRP
	L	H	H	L	X	BST	ILLEGAL ⁴
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL ^{4,10}
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL ^{4,10}
	L	L	H	H	BA, RA	ACT	ILLEGAL ^{4,10}
	L	L	H	L	BA, AP	PRE/PALL	NOP-Enter IDLE after tRP
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹

OPERATION COMMAND TRUTH TABLE-III

Current State	/CS	/RAS	/CAS	/WE	Address	Command	Action
ROW ACTIVATING	H	X	X	X	X	DSEL	NOP - Enter ROW ACT after tRCD
	L	H	H	H	X	NOP	NOP - Enter ROW ACT after tRCD
	L	H	H	L	X	BST	ILLEGAL ⁴
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL ^{4,10}
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL ^{4,10}
	L	L	H	H	BA, RA	ACT	ILLEGAL ^{4,9,10}
	L	L	H	L	BA, AP	PRE/PALL	ILLEGAL ^{4,10}
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
WRITE RECOVERING	H	X	X	X	X	DSEL	NOP - Enter ROW ACT after tWR
	L	H	H	H	X	NOP	NOP - Enter ROW ACT after tWR
	L	H	H	L	X	BST	ILLEGAL ⁴
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL
	L	L	H	H	BA, RA	ACT	ILLEGAL ^{4,10}
	L	L	H	L	BA, AP	PRE/PALL	ILLEGAL ^{4,11}
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
WRITE RECOVERING WITH AUTOPRE-CHARGE	H	X	X	X	X	DSEL	NOP - Enter precharge after tDPL
	L	H	H	H	X	NOP	NOP - Enter precharge after tDPL
	L	H	H	L	X	BST	ILLEGAL ⁴
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL ^{4,8,10}
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL ^{4,10}
	L	L	H	H	BA, RA	ACT	ILLEGAL ^{4,10}
	L	L	H	L	BA, AP	PRE/PALL	ILLEGAL ^{4,11}
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
REFRESHING	H	X	X	X	X	DSEL	NOP - Enter IDLE after tRC
	L	H	H	H	X	NOP	NOP - Enter IDLE after tRC
	L	H	H	L	X	BST	ILLEGAL ¹¹
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL ¹¹

OPERATION COMMAND TRUTH TABLE-IV

Current State	/CS	/RAS	/CAS	/WE	Address	Command	Action
WRITE	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL ¹¹
	L	L	H	H	BA, RA	ACT	ILLEGAL ¹¹
	L	L	H	L	BA, AP	PRE/PALL	ILLEGAL ¹¹
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹
MODE REGISTER ACCESSING	H	X	X	X	X	DSEL	NOP - Enter IDLE after tMRD
	L	H	H	H	X	NOP	NOP - Enter IDLE after tMRD
	L	H	H	L	X	BST	ILLEGAL ¹¹
	L	H	L	H	BA, CA, AP	READ/READAP	ILLEGAL ¹¹
	L	H	L	L	BA, CA, AP	WRITE/WRITEAP	ILLEGAL ¹¹
	L	L	H	H	BA, RA	ACT	ILLEGAL ¹¹
	L	L	H	L	BA, AP	PRE/PALL	ILLEGAL ¹¹
	L	L	L	H	X	AREF/SREF	ILLEGAL ¹¹
	L	L	L	L	OPCODE	MRS	ILLEGAL ¹¹

Note :

1. H - Logic High Level, L - Logic Low Level, X - Don't Care, V - Valid Data Input,
BA - Bank Address, AP - AutoPrecharge Address, CA - Column Address, RA - Row Address, NOP - NO Operation.
2. All entries assume that CKE was active(high level) during the preceding clock cycle.
3. If both banks are idle and CKE is inactive(low level), then in power down mode.
4. Illegal to bank in specified state. Function may be legal in the bank indicated by Bank Address(BA) depending on the state of that bank.
5. If both banks are idle and CKE is inactive(low level), then self refresh mode.
6. Illegal if tRCD is not met.
7. Illegal if tRAS is not met.
8. Must satisfy bus contention, bus turn around, and/or write recovery requirements.
9. Illegal if tRRD is not met.
10. Illegal for single bank, but legal for other banks in multi-bank devices.
11. Illegal for all banks.

CKE FUNCTION TRUTH TABLE

Current State	CKEn-1	CKEn	/CS	/RAS	/CAS	/WE	/ADD	Action
SELF REFRESH ¹	H	X	X	X	X	X	X	INVALID
	L	H	H	X	X	X	X	Exit self refresh, enter idle after tSREX
	L	H	L	H	H	H	X	Exit self refresh, enter idle after tSREX
	L	H	L	H	H	L	X	ILLEGAL
	L	H	L	H	L	X	X	ILLEGAL
	L	H	L	L	X	X	X	ILLEGAL
	L	L	X	X	X	X	X	NOP, continue self refresh
POWER DOWN ²	H	X	X	X	X	X	X	INVALID
	L	H	H	X	X	X	X	Exit power down, enter idle
	L	H	L	H	H	H	X	Exit power down, enter idle
	L	H	L	H	H	L	X	ILLEGAL
	L	H	L	H	L	X	X	ILLEGAL
	L	H	L	L	X	X	X	ILLEGAL
	L	L	X	X	X	X	X	NOP, continue power down mode
ALL BANKS IDLE ⁴	H	H	X	X	X	X	X	See operation command truth table
	H	L	L	L	L	H	X	Enter self refresh
	H	L	H	X	X	X	X	Exit power down
	H	L	L	H	H	H	X	Exit power down
	H	L	L	H	H	L	X	ILLEGAL
	H	L	L	H	L	X	X	ILLEGAL
	H	L	L	L	H	X	X	ILLEGAL
	H	L	L	L	L	L	X	ILLEGAL
	L	L	X	X	X	X	X	NOP
ANY STATE OTHER THAN ABOVE	H	H	X	X	X	X	X	See operation command truth table
	H	L	X	X	X	X	X	ILLEGAL ⁵
	L	H	X	X	X	X	X	INVALID
	L	L	X	X	X	X	X	INVALID

Note :

When CKE=L, all DQ and DQS must be in Hi-Z state.

1. CKE and /CS must be kept high for a minimum of 200 stable input clocks before issuing any command.

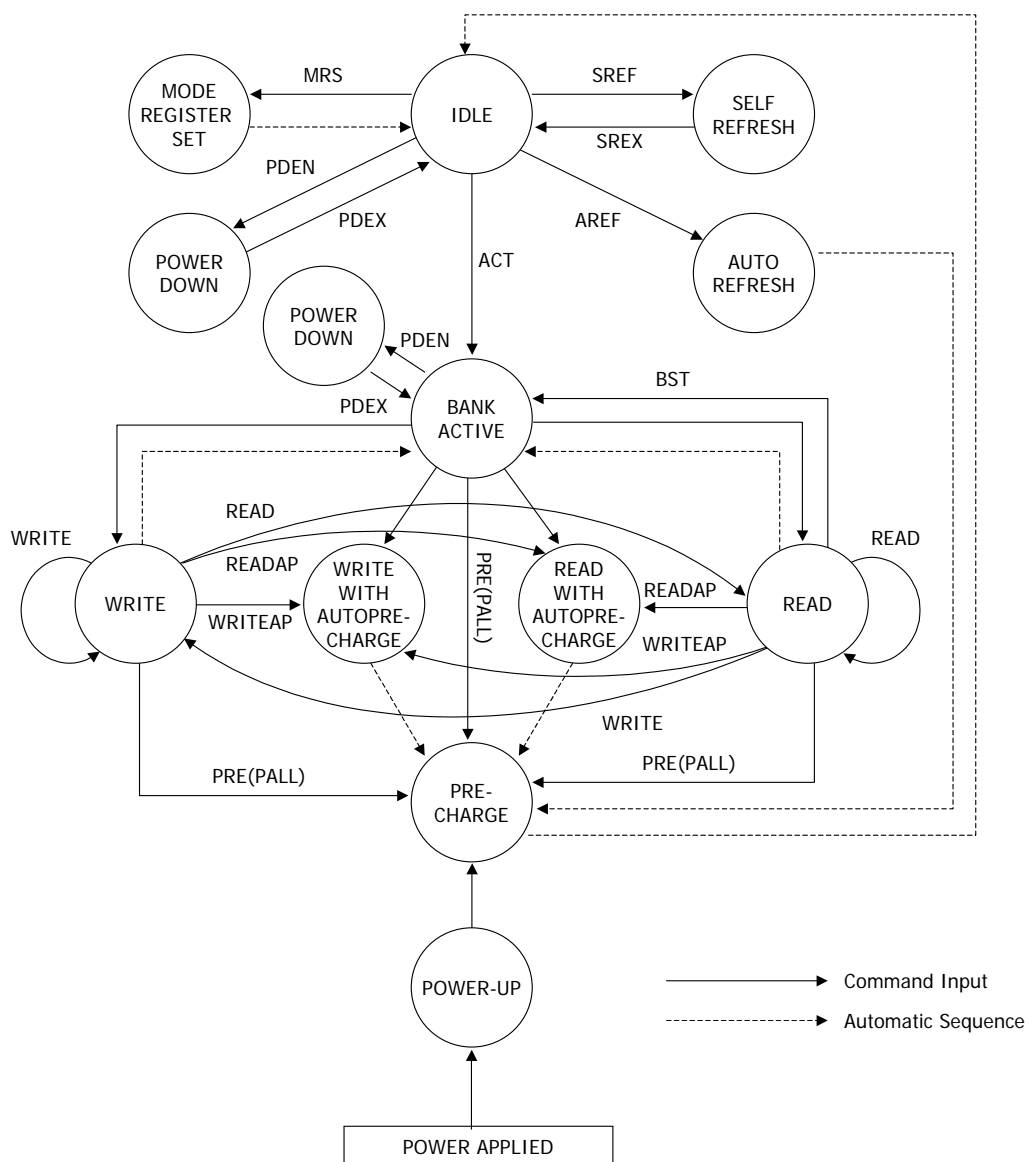
2. All command can be stored after 2 clocks from low to high transition of CKE.

3. Illegal if CK is suspended or stopped during the power down mode.

4. Self refresh can be entered only from the all banks idle state.

5. Disabling CK may cause malfunction of any bank which is in active state.

SIMPLIFIED STATE DIAGRAM



POWER-UP SEQUENCE AND DEVICE INITIALIZATION

DDR SDRAMs must be powered up and initialized in a predefined manner. Operational procedures other than those specified may result in undefined operation. Power must first be applied to VDD, then to VDDQ, and finally to VREF (and to the system VTT). VTT must be applied after VDDQ to avoid device latch-up, which may cause permanent damage to the device. VREF can be applied anytime after VDDQ, but is expected to be nominally coincident with VTT. Except for CKE, inputs are not recognized as valid until after VREF is applied. CKE is an SSTL_2 input, but will detect an LVCMOS LOW level after VDD is applied. Maintaining an LVCMOS LOW level on CKE during power-up is required to guarantee that the DQ and DQS outputs will be in the High-Z state, where they will remain until driven in normal operation (by a read access). After all power supply and reference voltages are stable, and the clock is stable, the DDR SDRAM requires a 200us delay prior to applying an executable command.

Once the 200us delay has been satisfied, a DESELECT or NOP command should be applied, and CKE should be brought HIGH. Following the NOP command, a PRECHARGE ALL command should be applied. Next a EXTENDED MODE REGISTER SET command should be issued for the Extended Mode Register, to enable the DLL, then a MODE REGISTER SET command should be issued for the Mode Register, to reset the DLL, and to program the operating parameters. After the DLL reset, tXSRD(DLL locking time) should be satisfied for read command. After the Mode Register set command, a PRECHARGE ALL command should be applied, placing the device in the all banks idle state.

Once in the idle state, two AUTO REFRESH cycles must be performed. Additionally, a MODE REGISTER SET command for the Mode Register, with the reset DLL bit deactivated low (i.e. to program operating parameters without resetting the DLL) must be performed. Following these cycles, the DDR SDRAM is ready for normal operation.

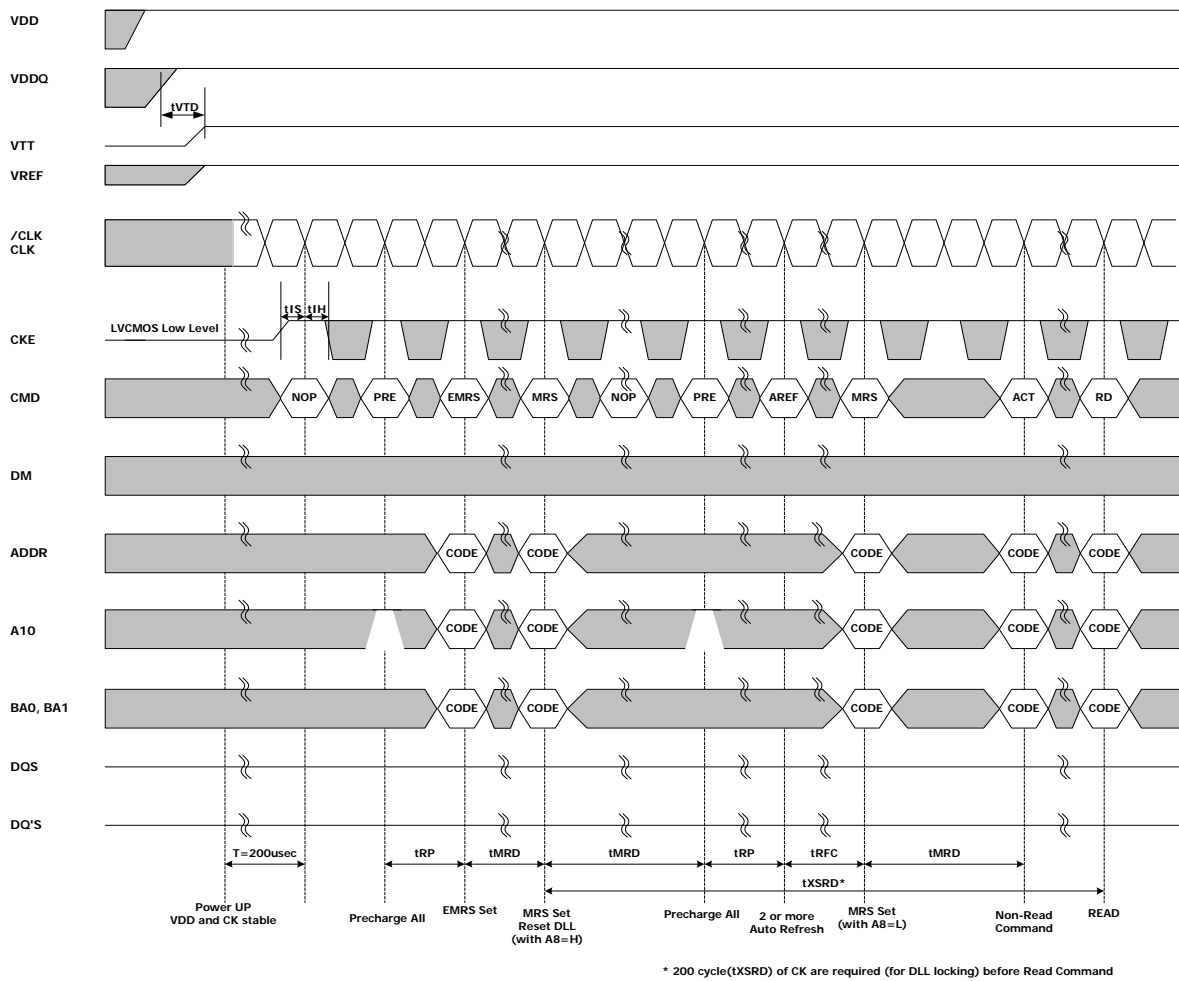
1. Apply power - VDD, VDDQ, VTT, VREF in the following power up sequencing and attempt to maintain CKE at LVCMOS low state. (All the other input pins may be undefined.)
 - VDD and VDDQ are driven from a single power converter output.
 - VTT is limited to $1.44V$ (reflecting $VDDQ(max)/2 + 50mV$ VREF variation + $40mV$ VTT variation).
 - VREF tracks $VDDQ/2$.
 - A minimum resistance of 42 Ohms (22 ohm series resistor + 22 ohm parallel resistor - 5% tolerance) limits the input current from the VTT supply into any pin.
 - If the above criteria cannot be met by the system design, then the following sequencing and voltage relationship must be adhered to during power up.

Voltage description	Sequencing	Voltage relationship to avoid latch-up
VDDQ	After or with VDD	$< VDD + 0.3V$
VTT	After or with VDDQ	$< VDDQ + 0.3V$
VREF	After or with VDDQ	$< VDDQ + 0.3V$

2. Start clock and maintain stable clock for a minimum of 200usec.
3. After stable power and clock, apply NOP condition and take CKE high.
4. Issue Extended Mode Register Set (EMRS) to enable DLL.
5. Issue Mode Register Set (MRS) to reset DLL and set device to idle state with bit A8=high. (An additional 200 cycles(tXSRD) of clock are required for locking DLL)
6. Issue Precharge commands for all banks of the device.

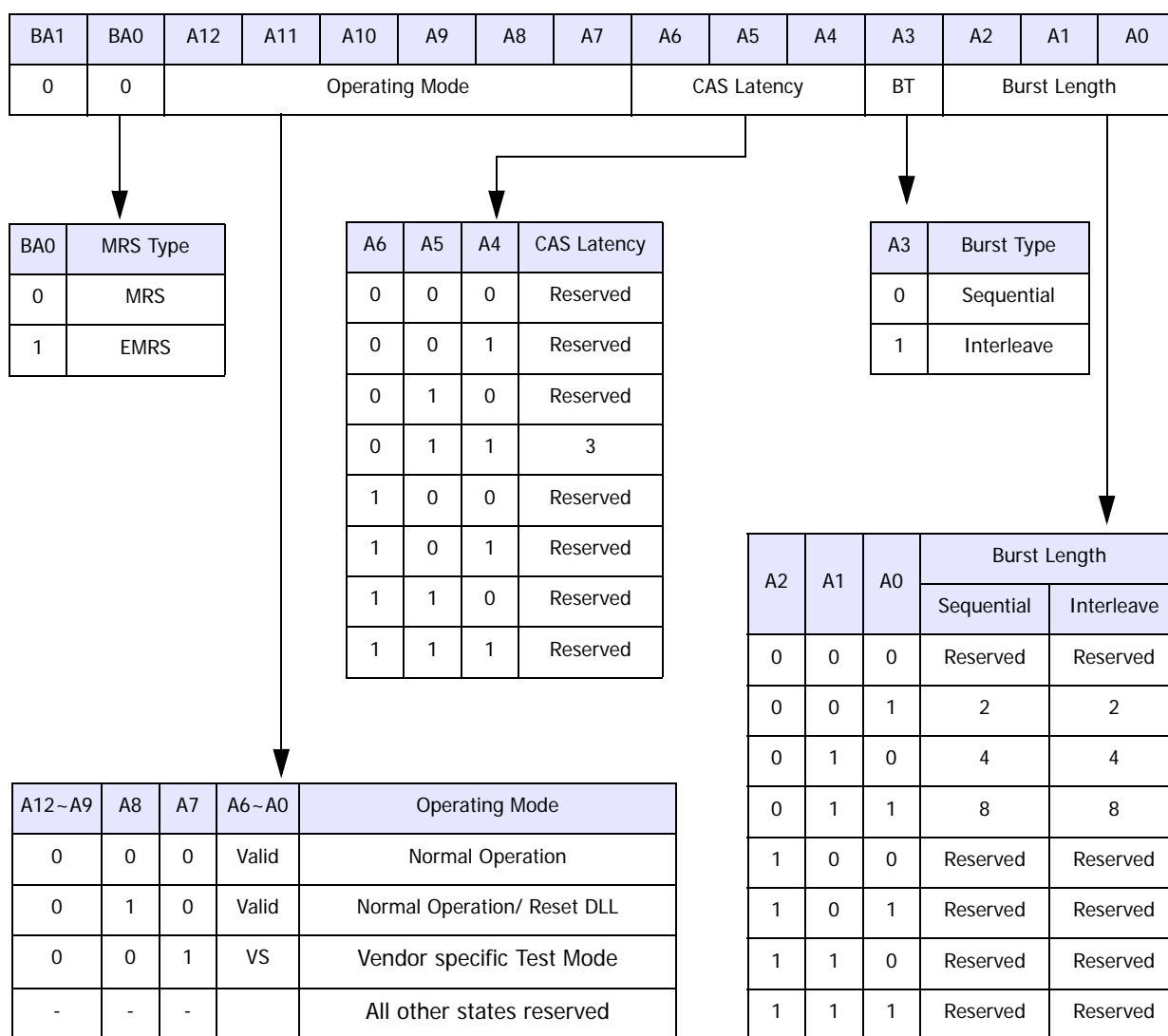
7. Issue 2 or more Auto Refresh commands.
8. Issue a Mode Register Set command to initialize the mode register with bit A8 = Low

Power-Up Sequence



MODE REGISTER SET (MRS)

The mode register is used to store the various operating modes such as /CAS latency, addressing mode, burst length, burst type, test mode, DLL reset. The mode register is programmed via MRS command. This command is issued by the low signals of /RAS, /CAS, /CS, /WE and BA0. This command can be issued only when all banks are in idle state and CKE must be high at least one cycle before the Mode Register Set Command can be issued. Two cycles are required to write the data in mode register. During the MRS cycle, any command cannot be issued. Once mode register field is determined, the information will be held until resetted by another MRS command.



BURST DEFINITION

Burst Length	Starting Address (A2,A1,A0)	Sequential	Interleave
2	XX0	0, 1	0, 1
	XX1	1, 0	1, 0
4	X00	0, 1, 2, 3	0, 1, 2, 3
	X01	1, 2, 3, 0	1, 0, 3, 2
	X10	2, 3, 0, 1	2, 3, 0, 1
	X11	3, 0, 1, 2	3, 2, 1, 0
8	000	0, 1, 2, 3, 4, 5, 6, 7	0, 1, 2, 3, 4, 5, 6, 7
	001	1, 2, 3, 4, 5, 6, 7, 0	1, 0, 3, 2, 5, 4, 7, 6
	010	2, 3, 4, 5, 6, 7, 0, 1	2, 3, 0, 1, 6, 7, 4, 5
	011	3, 4, 5, 6, 7, 0, 1, 2	3, 2, 1, 0, 7, 6, 5, 4
	100	4, 5, 6, 7, 0, 1, 2, 3	4, 5, 6, 7, 0, 1, 2, 3
	101	5, 6, 7, 0, 1, 2, 3, 4	5, 4, 7, 6, 1, 0, 3, 2
	110	6, 7, 0, 1, 2, 3, 4, 5	6, 7, 4, 5, 2, 3, 0, 1
	111	7, 0, 1, 2, 3, 4, 5, 6	7, 6, 5, 4, 3, 2, 1, 0

BURST LENGTH & TYPE

Read and write accesses to the DDR SDRAM are burst oriented, with the burst length being programmable. The burst length determines the maximum number of column locations that can be accessed for a given Read or Write command. Burst lengths of 2, 4 or 8 locations are available for both the sequential and the interleaved burst types. Reserved states should not be used, as unknown operation or incompatibility with future versions may result.

When a Read or Write command is issued, a block of columns equal to the burst length is effectively selected. All accesses for that burst take place within this block, meaning that the burst wraps within the block if a boundary is reached. The block is uniquely selected by A1-Ai when the burst length is set to two, by A2 -Ai when the burst length is set to four and by A3 -Ai when the burst length is set to eight (where Ai is the most significant column address bit for a given configuration). The remaining (least significant) address bit(s) is (are) used to select the starting location within the block. The programmed burst length applies to both Read and Write bursts.

Accesses within a given burst may be programmed to be either sequential or interleaved; this is referred to as the burst type and is selected via bit A3. The ordering of accesses within a burst is determined by the burst length, the burst type and the starting column address, as shown in Burst Definitionon Table

CAS LATENCY

The Read latency or CAS latency is the delay in clock cycles between the registration of a Read command and the availability of the first burst of output data. The latency can be programmed 3 clocks.

If a Read command is registered at clock edge n , and the latency is m clocks, the data is available nominally coincident with clock edge $n + m$.

Reserved states should not be used as unknown operation or incompatibility with future versions may result.

DLL RESET

The DLL must be enabled for normal operation. DLL enable is required during power up initialization, and upon returning to normal operation after having disabled the DLL for the purpose of debug or evaluation. The DLL is automatically disabled when entering self refresh operation and is automatically re-enabled upon exit of self refresh operation. Any time the DLL is enabled, 200 clock cycles must occur to allow time for the internal clock to lock to the externally applied clock before an any command can be issued.

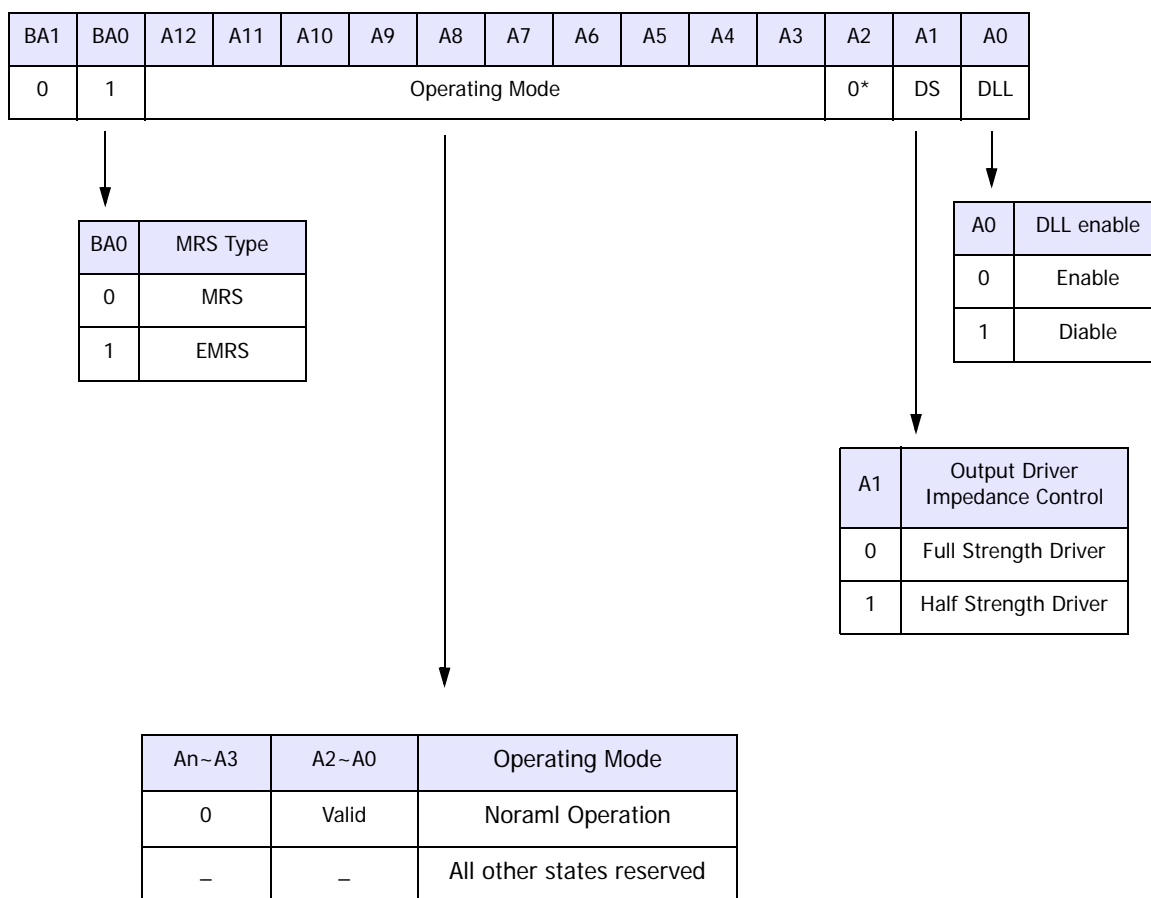
OUTPUT DRIVER IMPEDANCE CONTROL

The normal drive strength for all outputs is specified to be SSTL_2, Class II. Hynix also supports a half strength driver option, intended for lighter load and/or point-to-point environments. Selection of the half strength driver option will reduce the output drive strength by 50% of that of the full strength driver. I-V curves for both the full strength driver and the half strength driver are included in this document.

EXTENDED MODE REGISTER SET (EMRS)

The Extended Mode Register controls functions beyond those controlled by the Mode Register; these additional functions include DLL enable/disable, output driver strength selection(optional). These functions are controlled via the bits shown below. The Extended Mode Register is programmed via the Mode Register Set command (BA0=1 and BA1=0) and will retain the stored information until it is programmed again or the device loses power.

The Extended Mode Register must be loaded when all banks are idle and no bursts are in progress, and the controller must wait the specified time before initiating any subsequent operation. Violating either of these requirements will result in unspecified operation.



* This part do not support/QFC function, A2 must be programmed to Zero.

ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Rating	Unit
Ambient Temperature	TA	0 ~ 70	°C
Storage Temperature	TSTG	-55 ~ 125	°C
Voltage on Any Pin relative to VSS	VIN, VOUT	-0.5 ~ 3.6	V
Voltage on VDD relative to VSS	VDD	-0.5 ~ 3.6	V
Voltage on VDDQ relative to VSS	VDDQ	-0.5 ~ 3.6	V
Output Short Circuit Current	IOS	50	mA
Power Dissipation	PD	1	W
Soldering Temperature P Time	TSOLDER	260 P 10	°C P sec

Note : Operation at above absolute maximum rating can adversely affect device reliability

DC OPERATING CONDITIONS (TA=0 to 70 °C, Voltage referenced to VSS = 0V)

Parameter	Symbol	Min	Typ.	Max	Unit	Note
Power Supply Voltage	VDD	2.4	2.5	2.6	V	
Power Supply Voltage	VDDQ	2.4	2.5	2.6	V	1
Input High Voltage	VIH	VREF + 0.15	-	VDDQ + 0.3	V	
Input Low Voltage	VIL	-0.3	-	VREF - 0.15	V	2
Termination Voltage	VTT	VREF - 0.04	VREF	VREF + 0.04	V	
Reference Voltage	VREF	0.49*VDDQ	0.5*VDDQ	0.51*VDDQ	V	3
Input Voltage Level, CK and CK inputs	VIN(DC)	-0.3	VDDQ+0.3	V		
Input Differential Voltage, CK and CK inputs	VID(DC)	0.36	VDDQ+0.6	V	4	
V-I Matching: Pullup to Pulldown Current Ratio	VI(RATIO)	0.71	1.4	-	5	
Input Leakage Current	ILI	-5	5	uA	6	
Output Leakage Current	ILO	-5	5	uA		
Output High Voltage	VOH	VTT + 0.76	-	V	IOH = -15.2mA	
Output Low Voltage	VOL	-	VTT - 0.76	V	IOL = +15.2mA	

Note :

- VDDQ must not exceed the level of VDD.
- VIL (min) is acceptable -1.5V AC pulse width with ≤ 5 ns of duration.
- VREF is expected to be equal to 0.5*VDDQ of the transmitting device, and to track variations in the dc level of the same.
Peak to peak noise on VREF may not exceed +/- 2% of the DC value
- VID is the magnitude of the difference between the input level on CK and the input level on /CK.
- The ratio of the pullup current to the pulldown current is specified for the same temperature and voltage, over the entire temperature and voltage range, for device drain to source voltages from 0.25V to 1.0V. For a given output, it represents the maximum difference between pullup and pulldown drivers due to process variation. The full variation in the ratio of the maximum to minimum pullup and pulldown current will not exceed 1/7 for device drain to source voltages from 0.1 to 1.0.
- VIN=0 to VDD, All other pins are not tested under VIN =0V. 2. DOUT is disabled, VOUT=0 to VDDQ

DC CHARACTERISTICS II (TA=0 to 70 °C, Voltage referenced to VSS = 0V)

Parameter	Symbol	Test Condition	Speed			Unit	Note
			4	5	6		
Operating Current	IDD0	One bank; Active - Precharge ; tRC=tRC(min); tCK=tCK(min) ; DQ,DM and DQS inputs changing twice per clock cycle; address and control inputs changing once per clock cycle	150	130	120	mA	
Operating Current	IDD1	One bank; Active - Read - Precharge; Burst Length=2; tRC=tRC(min); tCK=tCK(min); address and control inputs changing once per clock cycle	190	170	150	mA	
Precharge Power Down Standby Current	IDD2P	All banks idle; Power down mode; CKE=Low, tCK=tCK(min)	15	10	10	mA	
Idle Standby Current	IDD2N	Vin>=Vih(min) or Vin<=Vil(max) for DQ, DQS and DM	35	35	35	mA	
Active Power Down Standby Current	IDD3P	One bank active; Power down mode; CKE=Low, tCK=tCK(min)	45	45	45	mA	
Active Standby Current	IDD3N	/CS=HIGH; CKE=HIGH; One bank; Active-Precharge; tRC=tRAS(max); tCK=tCK(min); DQ, DM and DQS inputs changing twice per clock cycle; Address and other control inputs changing once per clock cycle	60	60	60	mA	
Operating Current	IDD4R	Burst=2; Reads; Continuous burst; One bank active; Address and control inputs changing once per clock cycle; tCK=tCK(min); IOU=0mA	230	210	190	mA	
Operating Current	IDD4W	Burst=2; Writes; Continuous burst; One bank active; Address and control inputs changing once per clock cycle; tCK=tCK(min); DQ, DM and DQS inputs changing twice per clock cycle	250	230	210		
Auto Refresh Current	IDD5	tRC=tRFC(min) - 14*tCK for DDR400 at 200Mhz	280	260	240		
Self Refresh Current	IDD6	CKE =< 0.2V; External clock on; tCK=tCK(min)	5	5	5	mA	
Operating Current - Four Bank Operation	IDD7	Four bank interleaving with BL=4, Refer to the following page for detailed test condition	370	360	350	mA	

AC OPERATING CONDITIONS (TA=0 to 70 °C, Voltage referenced to VSS = 0V)

Parameter	Symbol	Min	Max	Unit	Note
Input High (Logic 1) Voltage, DQ, DQS and DM signals	VIH(AC)	VREF + 0.31		V	
Input Low (Logic 0) Voltage, DQ, DQS and DM signals	VIL(AC)		VREF - 0.31	V	
Input Differential Voltage, CK and /CK inputs	VID(AC)	0.7	VDDQ + 0.6	V	1
Input Crossing Point Voltage, CK and /CK inputs	VIX(AC)	0.5*VDDQ-0.2	0.5*VDDQ+0.2	V	2

Note :

1. VID is the magnitude of the difference between the input level on CK and the input on /CK.
2. The value of VIX is expected to equal 0.5*V DDQ of the transmitting device and must track variations in the DC level of the same.

AC OPERATING TEST CONDITIONS (TA=0 to 70°C, Voltage referenced to VSS = 0V)

Parameter	Value	Unit
Reference Voltage	VDDQ x 0.5	V
Termination Voltage	VDDQ x 0.5	V
AC Input High Level Voltage (VIH, min)	VREF + 0.31	V
AC Input Low Level Voltage (VIL, max)	VREF - 0.31	V
Input Timing Measurement Reference Level Voltage	VREF	V
Output Timing Measurement Reference Level Voltage	VTT	V
Input Signal maximum peak swing	1.5	V
Input minimum Signal Slew Rate	1	V/ns
Termination Resistor (RT)	50	Ω
Series Resistor (RS)	25	W
Output Load Capacitance for Access Time Measurement (CL)	30	pF

AC Overshoot/Undershoot Specification for Address and Control Pins

This specification is intended for devices with no clamp protection and is guaranteed by design

Parameter	Specification
Maximum peak amplitude allowed for overshoot (See Figure 1):	1.5V
Maximum peak amplitude allowed for undershoot (See Figure 1):	1.5V
The area between the overshoot signal and VDD must be less than or equal to (See Figure 1):	4.5V - ns
The area between the undershoot signal and GND must be less than or equal to (See Figure 1):	4.5V - ns

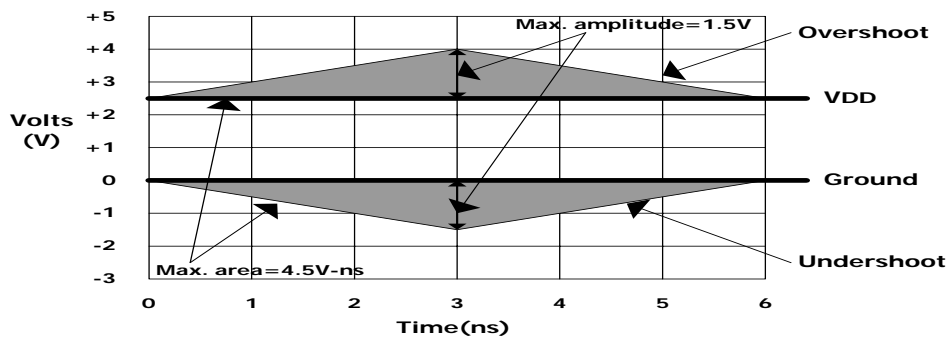


Figure 1: Address and Control AC Overshoot and Undershoot Definition
Overshoot/Undershoot Specification for Data, Strobe, and Mask Pins

Parameter	Specification
Maximum peak amplitude allowed for overshoot (See Figure 2):	1.2V
Maximum peak amplitude allowed for undershoot (See Figure 2):	1.2V
The area between the overshoot signal and VDD must be less than or equal to (See Figure 2):	2.4V - ns
The area between the undershoot signal and GND must be less than or equal to (See Figure 2):	2.4V - ns

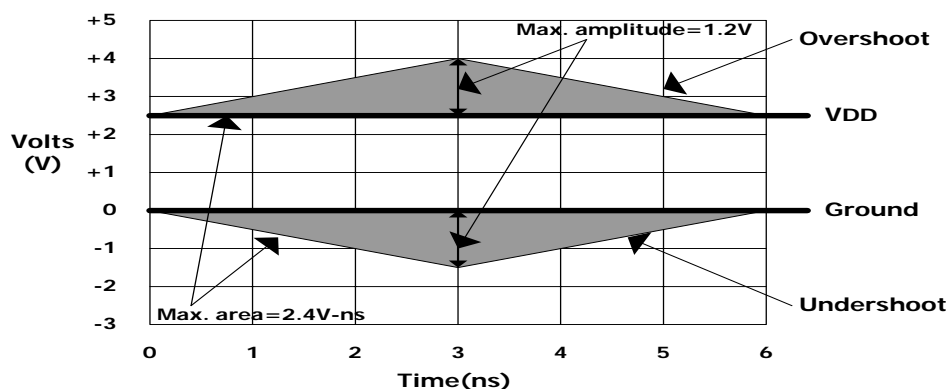


Figure 2: DQ/DM/DQS AC Overshoot and Undershoot Definition

AC CHARACTERISTICS I (AC operating conditions unless otherwise noted)

Parameter		Symbol	4		5		6		Unit	Note
			Min	Max	Min	Max	Min	Max		
Row Cycle Time		tRC	15	-	12	-	10	-	tCK	
Auto Refresh Row Cycle Time		tRFC	15	-	14	-	12	-	tCK	
Row Active Time		tRAS	40	100K	40	100K	42	100K	ns	
Active to Read with Auto Precharge Delay		tRAP	tRCD or tRASmin	-	tRCD or tRASmin	-	tRCD or tRASmin	-	ns	16
Row Address to Column Address Delay		tRCD	5	-	4	-	3	-	tCK	
Row Active to Row Active Delay		tRRD	2	-	2	-	2	-	tCK	
Column Address to Column Address Delay		tCCD	1	-	1	-	1	-	tCK	
Row Precharge Time		tRP	5	-	4	-	3	-	tCK	
Write Recovery Time		tWR	3	-	3	-	3	-	tCK	
Internal Write to Read Command Delay		tWTR	2	-	2	-	2	-	tCK	
Auto Precharge Write Recovery + Precharge Time		tDAL	8	-	7	-	6	-	tCK	15
System Clock Cycle Time	CL = 3	tCK	4	7	5	10	6	10	ns	
Clock High Level Width		tCH	0.45	0.55	0.45	0.55	0.45	0.55	tCK	
Clock Low Level Width		tCL	0.45	0.55	0.45	0.55	0.45	0.55	tCK	
Data-Out edge to Clock edge Skew		tAC	-0.7	0.7	-0.7	0.7	-0.7	0.7	ns	
DQS-Out edge to Clock edge Skew		tDQSCK	-0.7	0.7	-0.7	0.7	-0.7	0.7	ns	
DQS-Out edge to Data-Out edge Skew		tDQSQ	-	0.4	-	0.4	-	0.45	ns	
Data-Out hold time from DQS		tQH	tHP -tQHS	-	tHP -tQHS	-	tHP -tQHS	-	ns	1,10
Clock Half Period		tHP	min (tCL,tCH)	-	min (tCL,tCH)	-	min (tCL,tCH)	-	ns	1,9
Data Hold Skew Factor		tQHS	-	0.4	-	0.4	-	0.45	ns	10
Input Setup Time		tIS	0.6	-	0.6	-	0.75	-	ns	2,3, 5,6
Input Hold Time		tIH	0.6	-	0.6	-	0.75	-	ns	
Write DQS High Level Width		tDQSH	0.4	0.6	0.4	0.6	0.4	0.6	tCK	
Write DQS Low Level Width		tDQSL	0.4	0.6	0.4	0.6	0.4	0.6	tCK	
Clock to First Rising edge of DQS-In		tDQSS	0.75	1.25	0.75	1.25	0.75	1.25	tCK	

-Continue-

Parameter	Symbo	4		5		6		Uni	Note
		Min	Max	Min	Max	Min	Max		
Data-In Setup Time to DQS-In (DQ & DM)	tDS	0.4	-	0.4	-	0.45	-	ns	6,7, 11, 12, 13
Data-in Hold Time to DQS-In (DQ & DM)	tDH	0.4	-	0.4	-	0.45	-	ns	
Read DQS Preamble Time	tRPRE	0.9	1.1	0.9	1.1	0.9	1.1	tCK	
Read DQS Postamble Time	tRPST	0.4	0.6	0.4	0.6	0.4	0.6	tCK	
Write DQS Preamble Setup Time	tWPRES	0	-	0	-	0	-	tCK	
Write DQS Preamble Hold Time	tWPREH	0.25	-	0.25	-	0.25	-	tCK	
Write DQS Postamble Time	tWPST	0.4	0.6	0.4	0.6	0.4	0.6	tCK	
Mode Register Set Delay	tMRD	2	-	2	-	2	-	tCK	
Exit Self Refresh to Any Execute Command	tXSC	200	-	200	-	200	-	tCK	8
Average Periodic Refresh Interval	tREFI	-	7.8	-	7.8	-	7.8	us	

Note :

1. This calculation accounts for tDQSQ(max), the pulse width distortion of on-chip circuit and jitter.
2. Data sampled at the rising edges of the clock : A0~A12, BA0~BA1, CKE, /CS, /RAS, /CAS, /WE.
3. For command/address input slew rate $\geq 1.0V/ns$
4. For command/address input slew rate $\geq 0.5V/ns$ and $< 1.0V/ns$
This derating table is used to increase tIS/tIH in case where the input slew-rate is below 0.5V/ns.
Input Setup / Hold Slew-rate Derating Table.

Input Setup / Hold Slew-rate	Delta tIS	Delta tIH
V/ns	ps	ps
0.5	0	0
0.4	+50	0
0.3	+100	0

5. CK, /CK slew rates are $\geq 1.0V/ns$
6. These parameters guarantee device timing, but they are not necessarily tested on each device, and they may be guaranteed by design or tester correlation.
7. Data latched at both rising and falling edges of Data Strobes(LDQS/UDQS) : DQ, LDM/UDM.
8. Minimum of 200 cycles of stable input clocks after Self Refresh Exit command, where CKE is held high, is required to complete Self Refresh Exit and lock the internal DLL circuit of DDR SDRAM.
9. Min (tCL, tCH) refers to the smaller of the actual clock low time and the actual clock high time as provided to the device (i.e. this value can be greater than the minimum specification limits for tCL and tCH).
10. tHP = minimum half clock period for any given cycle and is defined by clock high or clock low (tCH, tCL). tQHS consists of

tDQSQmax, the pulse width distortion of on-chip clock circuits, data pin to pin skew and output pattern effects and p-channel to n-channel variation of the output drivers.

11. This derating table is used to increase tDS/tDH in case where the input slew-rate is below 0.5V/ns.
Input Setup / Hold Slew-rate Derating Table.

Input Setup / Hold Slew-rate	Delta tDS	Delta tDH
V/ns	ps	ps
0.5	0	0
0.4	+75	+75
0.3	+150	+150

12. I/O Setup/Hold Plateau Derating. This derating table is used to increase tDS/tDH in case where the input level is flat below VREF +/-310mV for a duration of up to 2ns.

I/O Input Level	Delta tDS	Delta tDH
mV	ps	ps
+280	+50	+50

13. I/O Setup/Hold Delta Inverse Slew Rate Derating. This derating table is used to increase tDS/tDH in case where the DQ and DQS slew rates differ. The Delta Inverse Slew Rate is calculated as $(1/\text{SlewRate1}) - (1/\text{SlewRate2})$. For example, if slew rate 1 = 0.5V/ns and Slew Rate2 = 0.4V/n then the Delta Inverse Slew Rate = -0.5ns/V.

$(1/\text{SlewRate1}) - (1/\text{SlewRate2})$	Delta tDS	Delta tDH
ns/V	ps	ps
0	0	0
+/-0.25	+50	+50
+/- 0.5	+100	+100

14. DQS, DM and DQ input slew rate is specified to prevent double clocking of data and preserve setup and hold times. Signal transitions through the DC region must be monotonic.
15. $tDAL = 2 \text{ clocks} + (tRP / tCK)$. For each of the terms above, if not already an integer, round to the next highest integer. tCK is equal to the actual system clock cycle time.
Example: 200MHz at CL=3 and tCK = 5 ns,
 $tDAL = (15 \text{ ns} / 5\text{ns}) + (15 \text{ ns} / 5 \text{ ns}) = (3.0) + (3.0)$
Round up each non-integer to the next highest integer: = (3) + (4), tDAL = 6 clocks
16. For the parts which do not has internal RAS lockout circuit, Active to Read with Auto precharge delay should be $tRAS - BL/2 \times tCK$.

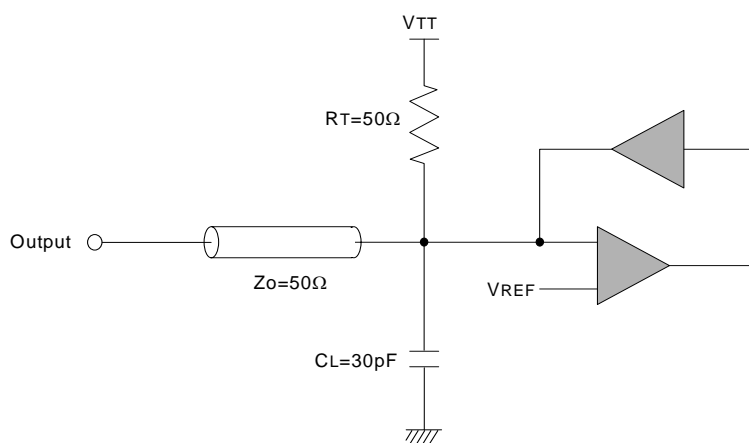
CAPACITANCE (TA=25°C, f=100MHz)

Parameter	Pin	Symbol	Min	Max	Unit
Input Clock Capacitance	CK, /CK	C11	2.0	3.0	pF
Delta Input Clock Capacitance	CK, /CK	Delta C11	-	0.25	pF
Input Capacitance	All other input-only pins	C11	2.0	3.0	pF
Delta Input Capacitance	All other input-only pins	Delta C12	-	0.5	pF
Input / Output Capacitance	DQ, DQS, DM	C10	4.0	5.0	pF
Delta Input / Output Capacitance	DQ, DQS, DM	Delta C10	-	0.5	pF

Note :

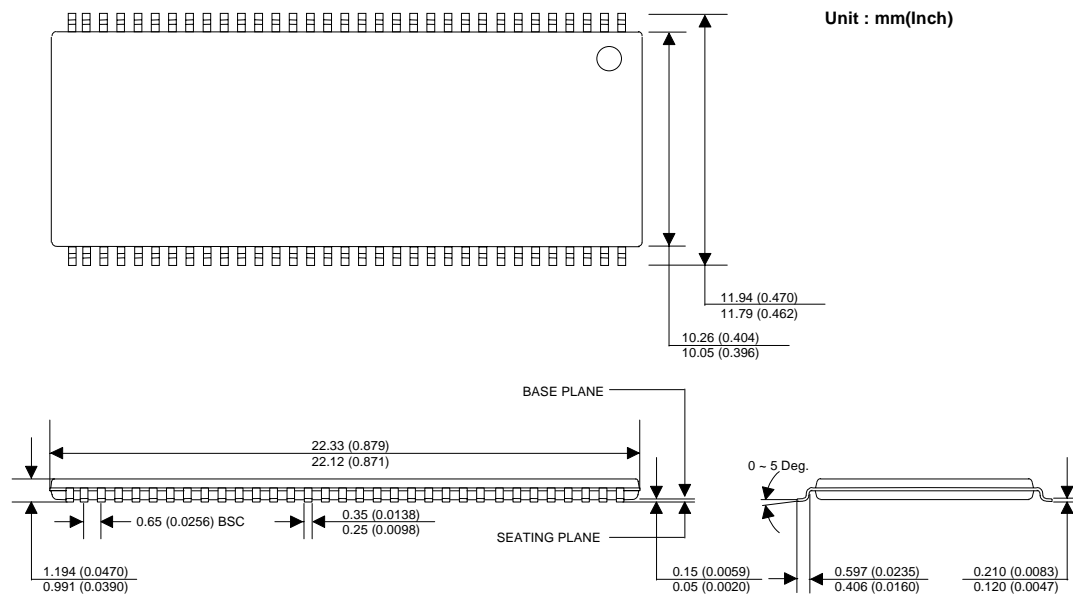
1. VDD = min. to max., VDDQ = 2.5V to 2.7V, VoDC = VDDQ/2, Vopeak-to-peak = 0.2V
2. Pins not under test are tied to GND.
3. These values are guaranteed by design and are tested on a sample basis only.

OUTPUT LOAD CIRCUIT



PACKAGE INFORMATION

400mil 66pin Thin Small Outline Package





Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



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