

High Speed, Fast Settling Precision Operational Amplifier



FEATURES

Fast

Slew Rate	50V/μs Min
 Settling-Time (0.01%) 	1us Max
Gain-Bandwidth Product	10MHz Typ
Precise	
Common-Mode Rejection	88dB Min
Open-Loop Gain	500V/mV Min
Offset Voltage	750µV Max

Excellent Radiation Hardness Available in Die Form

ORDERING INFORMATION[†]

T, = 25°	c		OPERATING				
V _{os} MA (mV)		CERDIP 8-PIN	PLASTIC SO 8-PIN 8-PIN		LCC 20-CONTACT	TEMPERATURE	
1.0	OP42AJ*	OP42AZ*	_	_	OP42ARC/883	MIL	
0.75	OP42EJ	OP42EZ		-	-	IND	
1.5	OP42FJ	OP42FZ	-	-	_	IND	
5.0	-	-	OP42GP	OP42GS	-	XIND	

 For devices processed in total compliance to MIL-STD-883, add /883 after part number. Consult factory for 883 data sheet.

Burn-in is available on commercial and industrial temperature range parts in cerdip, plastic dip, and TO-can packages.

GENERAL DESCRIPTION

The OP-42 is a fast precision JFET-input operational amplifier. Similar in speed to the OP-17, the OP-42 offers a symmetric

SIMPLIFIED SCHEMATIC

 $58V/\mu s$ slew rate and is internally compensated for unity-gain operation. OP-42 speed is achieved with a supply current of less than 6mA. Unity-gain stability, a wide full-power bandwidth of 900kHz, and a fast settling-time of 800ns to 0.01% make the OP-42 an ideal output amplifier for fast digital-to-analog converters.

Equal attention was given to both speed and precision in the OP-42 design. Its tight 750μ V maximum input offset voltage combined with well-controlled drift of less than 10μ V/°C eliminates the need for external nulling in many circuits. The OP-42's *Continued*

PIN CONNECTIONS





GENERAL DESCRIPTION Continued

common-mode rejection of 88dB minimum over a $\pm 11V$ input voltage range is exceptional for a high-speed amplifier. High CMR combined with a minimum 500V/mV gain into $10k\Omega$ load ensure excellent linearity in both noninverting and inverting gain configurations. The low input bias and offset currents provided by the JFET input stage suit the OP-42 for use in high-speed sample and hold circuits, peak detectors, and log amplifiers. Excellent radiation hardness characteristics make the OP-42 ideal for military and aerospace applications.

The OP-42 conforms to the standard 741 pinout with nulling to V–. The OP-42 upgrades the performance of circuits using the AD544, AD611, AD711, and LF400 by direct replacement. In circuits without nulling, the OP-42 offers an upgrade for designs using the OP-16, OP-17, LT1022, LT1056, and HA2510.

ABSOLUTE MAXIMUM RATINGS (Note 1)

Supply Voltage	±20V
Input Voltage (Note 2)	±20V
Differential Input Voltage (Note 2)	40V
Output Short-Circuit Duration	Indefined

Storage Temperature Range	65°C to +175°C
Operating Temperature Range	
OP42A (J, Z)	55°C to +125°C
OP42E, F (J, Z)	25°C to +85°C
OP42G	40°C to +85°C
Junction Temperature	65°C to +175°C
Lead Temperature Range (Soldering, 60	sec.) +300°C

PACKAGE TYPE	Θ _{jA} (NOTE 3)	θ _{ic}	UNITS
TO-99 (J)	150	18	°C/W
8-Pin Hermetic DIP (Z)	148	16	°C/W
8-Pin Plastic DIP (P)	103	43	°C/W
20-Contact LCC (RC,TC)	98	38	°C/W
8-Pin SO (S)	158	43	°C/W

NOTES:

 Absolute maximum ratings apply to both DICE and packaged parts, unless otherwise noted.

2. For supply voltages less than ±20V, the absolute maximum input voltage is equal to the supply voltage.

 Θ_{jA} is specified for worst case mounting conditions, i.e., Θ_{jA} is specified for device in socket for TO, CERDIP, P-DIP, and LCC packages; Θ_{jA} is specified for device soldered to printed circuit board for SO package.

ELECTRICAL CHARACTERISTICS at $V_s = \pm 15V$, $T_a = \pm 25^{\circ}C$, unless otherwise noted.

				OP-42E			OP-42F			OP-42G	i	
PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	МАХ	MIN	түр	MAX	MIN	TYP	MAX	UNITS
Offset Voltage	v _{cs}		-	0.3	0.75	-	0.4	1.5	-	1.5	5.0	mV
Input Bias Current		V _{CM} = 0V T _i = 25°C		80	200		130	250		130	250	pA
Input Offset Current	los	$V_{CM} = 0V T_1 = 25^{\circ}C$	-	4	40	_	6	50	_	6	50	рА
Input Voltage Range	IVR	(Note 1)	±11	+12.5 12.0	-	±11	+12.5 -12.0	-	±11	+12.5 12.0	-	v
Common-Mode Rejection	CMR	V _{CM} = ±11V	88	98		80	92	-	80	92	-	dB
Power-Supply Rejection Ratio	PSRR	$V_{s} = \pm 10V$ to $\pm 20V$	-	9	40	-	12	50	-	12	50	μV/V
Laura Cianal		$R_{L} = 10k\Omega$ $V_{-} = \pm 10V$	500	900	_	500	900	_	500	900	-	
Large-Signal Voltage Gain	$A_{VO} = R_1 = 2k\Omega - \frac{1}{2}O$	$R_1 = 2k\Omega$ $T_0 = \pm 10V$	200	260	-	200	260	-	200	260		V/mV
voltage Gall		$R_{L}^{T} = 1k\Omega$ $I_{j}^{T} = 25 C$	100	170	-	100	170	-	100	170	-	
Output Voltage Swing	vo	R _L = 1kΩ	±11.5	+12.5 –11.9	_	±11.5	+12.5 11.9	_	±11.5	+12.5 11.9		v
Short-Circuit Current Limit	I _{sc}	Output Shorted to Ground	±20	+33 -28	±60	±20	+33 –28	±60	±20	+33 –28	±60	mA
Supply Current	I _{SY}	No Load V _O = 0V	-	5.1	6.0	-	5.1	6.5	-	5.1	6.5	mA
Slew Rate	SR		50	58	-	40	50	-	40	50	-	V/µs
Full-Power Bandwidth	BWp	(Note 2)	750	900	-	600	800	-	600	800	-	kHz
Gain-Bandwidth Product	GBW	f _o = 10kHz	_	10	_	-	10	-	_	10	-	MHz
Settling -Time	t _s	10V Step 0.01% (Note 3)	-	0.8	1.0	-	0.9	1.2	_	0.9	1.2	με
Overload Recovery Time	t _{on}		_	700	_		700		_	700	-	ns
Phase Margin	φ _o	0db Gain	_	47	-	-	47	-	-	47	-	degrees
Gain Margin	A ₁₈₀	180° Open-Loop Phase Shift	-	9			9		_	9	-	dE
Capacitive Load Drive Capability	СL	Unity-Gain Stable (Note 4)	100	300	-	100	300	-	100	300	-	pF

				OP-42	E		OP-42	=		OP-420	3	
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
Differential Input Impedance	Z _{IN}	- <u></u>	-	10 ^{1 2} 6	-	_	10 ^{† 2} 6	-	_	10 ¹² 6	-	Ω pF
Open-Loop Output Resistance	R _o		_	50	_	_	50			50	_	Ω
Voltage Noise	e _{n p-p}	0.1Hz to 10Hz	-	2	_		2	-		2	-	μV _{p-p}
		f _o = 10Hz		38	_	_	38	-	-	38	-	
Voltage Noise		f _o = 100Hz	-	16	-	-	16	-	-	16	-	nV/√Hz
Density	e _n	$f_0 = 1 \text{ kHz}$		13		-	13	-	-	13	-	NV/∨ HZ
		$f_0 = 10$ kHz	-	12	-	-	12	-	-	12	-	-
Current Noise Density	i _n	f _o = 1kHz	-	0.007		_	0.007	_		0.007	-	pA/√Hz
External V _{OS} Trim Range		R _{pot} = 20kΩ	-	4	_	_	4	-	-	4	_	mV
Long-Term V _{O S} Drift			_	5		_	5	-	_	5	-	µV/month
Supply Voltage Range	v _s		±8	±15	±20	±8	±15	±20	±8	±15	±20	v

ELECTRICAL CHARACTERISTICS at $V_s = \pm 15V$, $T_A = \pm 25^{\circ}C$, unless otherwise noted. Continued

NOTES:

1. Guaranteed by CMR test. 2. Guaranteed by slew-rate test and formula $BW_p = SR/(2\pi 10V_{PEAK})$.

Settling-time is sample tested for A and E grades. Test circuit is shown in Figure 4. Settling-time for F grade is guaranteed but not tested.
 Guaranteed but not tested.

ELECTRICAL CHARACTERISTICS at $V_s = \pm 15V$, $T_A = \pm 25^{\circ}C$, unless otherwise noted.

0.0.0.WETE0	0)44501			OP-42A	МАХ	UNITS
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP		
Offset Voltage	v _{os}		-	0.3	1.0	mV
Input Bias Current	B	V _{СМ} = 0V Т _j = 25°С	_	80	200	рA
Input Offset Current	los	V _{СМ} = 0V Т _j = 25°С	_	4	40	рA
Input Voltage Range	IVR	(Note 1)	±11	+12.5 12.0	-	v
Common-Mode Rejection	CMR	V _{CM} = ±11V	86	96	-	dB
Power-Supply Rejection Ratio	PSRR	$V_{S} = \pm 10V$ to $\pm 20V$	-	9	40	μV/V
Large-Signal	····	$R_{L} = 10k\Omega$ $V_{L} = +10V$	500	900	_	
Voltage Gain	Avo	$R_1 = 2k\Omega$ $T_0 = \pm 100$	200	260	_	V/mV
Vollage Galli		$\mathbf{H}_{L}^{T} = 1 \mathbf{k} \mathbf{\Omega}$ $\mathbf{j} = 25^{\circ} \mathbf{C}$	100	170	-	
Output Voltage Swing	v _o	$R_{L} = 1k\Omega$	±11.5	+12.5 11.9	-	v
Short-Circuit Current Limit	lsc	Output Shorted to Ground	±20	+33 28	±60	mA
Supply Current	I _{SY}	No Load V _O = 0V	-	5.1	6.0	mA
Slew Rate	SR		45	52	-	V/µs
Full-Power Bandwidth	BW _p	(Note 2)	700	850	-	kHz
Gain-Bandwidth Product	GBW	f _o = 10kHz		10	-	MHz
Settling -Time	t _s	10V Step 0.01% (Note 3)	-	0.8	1.0	μs
Overload Recovery Time	^t оя		_	700	-	ns
Phase Margin	φ _o	0db Gain	_	47		degrees

ELECTRICAL CHARACTERISTICS at $V_s = \pm 15V$, $T_A = 25^{\circ}C$, unless otherwise noted. Continued

PARAMETER	SYMBOL	CONDITIONS	MIN	OP-42A TYP	MAX	UNITS
Gain Margin	A ₁₈₀	180° Open-Loop Phase Shift	-	9		dB
Capacitive Load Drive Capability	CL	Unity-Gain Stable (Note 4)	100	300	_	pF
Differential Input Impedance	Z _{IN}	"	_	10 ¹² 6	-	Ω pF
Open-Loop Output Resistance	R _O		-	50	_	Ω
Voltage Noise	e _{n p-p}	0.1Hz to 10Hz	· –	2	_	μV _{p-p}
Voltage Noise Density	e _n	$f_{O} = 10Hz$ $f_{O} = 100Hz$ $f_{O} = 1kHz$ $f_{O} = 10kHz$		38 16 13 12	-	nV∱∕Hz
Current Noise Density	i _n	f _o = 1kHz	_	0.007	_	pA/√Hz
External V _{OS} Trim Range		R _{pot} = 20kΩ	-	4	-	mV
Long-Term V _{O S} Drift	49 Mar 1997 - San			5	_	μV/month
Supply Voltage Range	v _s		±8	±15	±20	v

NOTES:

1. Guaranteed by CMR test.

2. Guaranteed by slew-rate test and formula $BW_p = SR/(2\pi 10V_{PEAK})$.

3. Settling-time is sample tested for A and E grades. Test circuit is shown in

Figure 4. Settling-time for F grade is guaranteed but not tested. 4. Guaranteed but not tested.

ELECTRICAL CHARACTERISTICS at $V_s = \pm 15V$, $-25^{\circ}C \le T_A \le 85^{\circ}C$ for E/F grades, and $-40^{\circ}C \le T_A \le +85^{\circ}C$ for G grade, unless otherwise noted.

			OP-42	E		OP-42	F		OP-420	G	
SYMBOL	CONDITIONS	MIN	TYP	MAX	MIN	TYP	MAX	MIN	TYP	MAX	UNITS
v _{os}		-	0.4	1.2		0.6	2.5		2.0	6.0	mV
TCV _{OS}		_	4	10	_	8	_	-	8	-	μV/°C
I _B	(Note 1)	-	0.5	1.2	_	0.6	2.0	-	0.6	2.0	nA
los	(Note 1)	_	0.05	0.2	-	0.06	0.4	-	0.06	0.4	nA
IVR	(Note 2)	±11	+12.5 -12.0	-	±11	+12.5 -12.0	-	±11	+12.5 -12.0	-	v
CMR	V _{CM} = ±11V	86	96	_	80	94		80	94	-	dB
PSRR	V _s = ±10V to ±20V	-	2	40	-	6	50	-	6	50	μV/V
Avo	R _L = 10kΩ (Note 1) R _L = 2kΩ V _O = ±10V	200 100	500 160		200 100	500 160	-	200 100	500 160	-	V/mV
v _o	R _L = 2kΩ	±11.0	+12.3 –11.8	-	±11.0	+12.3 11.8	_	±11.0	+12.3 -11.8		v
I _{sc}	Output Shorted to Ground	±8	-	±60	±8	_	±60	±8	-	±60	mA
I _{SY}	No Load V _O = 0V	-	5.1	6.0	-	5.1	6.5	-	5.1	6.5	mA
SR	R _L = 2kΩ	45	57		40	50	-	40	50	-	V/µs
cL	Unity-Gain Stable (Note 3)	100	250		100	250	-	100	250	-	pF
	V _{OS} TCV _{OS} I _B I _{OS} IVR CMR PSRR A _{VO} V _O I _{SC} I _{SY} SR	V_{OS} TCV _{OS} I _B (Note 1) I _{OS} (Note 1) IVR (Note 2) CMR $V_{CM} = \pm 11V$ PSRR $V_S = \pm 10V$ A_{VO} $R_L = 10k\Omega$ (Note 1) $R_L = 2k\Omega$ $V_O = \pm 10V$ V_O $R_L = 2k\Omega$ I_{SC} Output Shorted to Ground I_{SY} $V_O = 0V$ SR $R_L = 2k\Omega$ C Unity-Gain Stable	V_{OS} - TCV _{OS} - I _B (Note 1) - I _{OS} (Note 1) - IVR (Note 2) ±11 CMR V _{CM} = ±11V 86 PSRR V _S = ±10V to ±20V - A _{VO} R _L = 10kΩ (Note 1) 200 A _{VO} R _L = 2kΩ V _O = ±10V 100 V _O R _L = 2kΩ ±11.0 100 V _O R _L = 2kΩ ±11.0 100 V _O R _L = 2kΩ ±11.0 100 Sc Output Shorted to Ground ±8 I _{SY} V _O = 0V - SR R _L = 2kΩ 45 C Unity-Gain Stable 100	SYMBOL CONDITIONS MIN TYP V_{OS} - 0.4 TCV_{OS} - 4 I_B (Note 1) - 0.5 I_{OS} (Note 1) - 0.05 I_{OS} (Note 1) - 0.05 IVR (Note 2) ± 11 ± 12.5 CMR $V_{CM} = \pm 11V$ 86 96 PSRR $V_S = \pm 10V$ - 2 A_{VO} $R_L = 10k\Omega$ (Note 1) 200 500 $R_L = 2k\Omega$ V_{O} 500 160 V_O $R_L = 2k\Omega$ (Note 1) 200 500 $R_L = 2k\Omega$ $V_{O} = \pm 10V$ 100 160 V_O $R_L = 2k\Omega$ ± 11.0 ± 12.3 I_{SC} Output Shorted ± 8 - I_{SY} $V_O = 0V$ - 5.1 SR $R_L = 2k\Omega$ 45 57 G Unity-Gain Stable 100 250	V_{OS} - 0.4 1.2 TCV_{OS} - 4 10 I_B (Note 1) - 0.5 1.2 I_{OS} (Note 1) - 0.05 0.2 IVR (Note 2) ± 11 ± 12.5 - CMR $V_{CM} = \pm 11V$ 86 96 - PSRR $V_S = \pm 10V$ - 2 40 A_{VO} $R_L = 10k\Omega$ (Note 1) 200 500 - R_Vo $R_L = 10k\Omega$ (Note 1) 200 500 - V_O $R_L = 2k\Omega$ $\psi_0 = \pm 10V$ 100 160 - V_O $R_L = 2k\Omega$ ± 11.0 ± 12.3 - - V_O $R_L = 2k\Omega$ ± 11.0 ± 12.3 - - I_{SC} Output Shorted ± 8 - ± 60 - I_{SY} $V_O = 0V$ - 5.1 6.0 - SR $R_L = 2k\Omega$ 45 57 - - G Unity-Gain Stable 100	SYMBOL CONDITIONS MIN TYP MAX MIN V_{OS} - 0.4 1.2 - TCV _{OS} - 4 10 - I _B (Note 1) - 0.5 1.2 - I _{OS} (Note 1) - 0.05 0.2 - IVR (Note 2) ±11 +12.5 - ±11 CMR V _{CM} = ±11V 86 96 - 80 PSRR V _S = ±10V - 2 40 - A _{VO} R _L = 10kΩ (Note 1) 200 500 - 200 A _{VO} R _L = 2kΩ V _O = ±10V 100 160 - 100 V _O R _L = 2kΩ ±11.0 +12.3 - ±11.0 I _{SC} Output Shorted ±8 - ±60 ±8 I _{SY} No Load - 57 - 40 G Unity-Gain Stable 100 250 </td <td>SYMBOL CONDITIONS MIN TYP MAX MIN TYP V_{OS} - 0.4 1.2 - 0.6 TCV_{OS} - 4 10 - 8 I_B (Note 1) - 0.5 1.2 - 0.6 I_OS (Note 1) - 0.05 0.2 - 0.06 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 VRR $V_S = \pm 10V$ - 2 40 - 6 $PSRR$ $V_S = \pm 10V$ - 200 500 - 200 500 A_{VO} $R_L = 2k\Omega$ ± 11.0 ± 12.3 <td< td=""><td>SYMBOL CONDITIONS MIN TYP MAX MIN TYP MAX V_{OS} - 0.4 1.2 - 0.6 2.5 TCV_{OS} - 4 10 - 8 - I_B (Note 1) - 0.5 1.2 - 0.6 2.0 I_{OS} (Note 1) - 0.05 0.2 - 0.06 0.4 IVR (Note 1) - 0.05 0.2 - 0.06 0.4 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 - CMR $V_{CM} = \pm 11V$ 86 96 - 80 94 - PSRR $V_S = \pm 10V$ - 2 40 - 6 50 A_{VO} $R_L = 10k\Omega$ (Note 1) 200 500 - 200 500 - V_O $R_L = 2k\Omega$ ± 11.0 ± 12.3 - ± 11.0<td>SYMBOL CONDITIONS MIN TYP MAX MIN V_{OS} - 0.4 1.2 - 0.6 2.5 - TCV_{OS} - 4 10 - 8 - - I_B (Note 1) - 0.5 1.2 - 0.6 2.0 - IVR (Note 1) - 0.05 0.2 - 0.06 0.4 - IVR (Note 2) ±11 ±12.5 - ±11 ±12.5 - ±11 CMR V_G = ±10V - 20 - - 6 50 - A_{VO} R_L = 2kQ v_O = ±10V 100</td><td>$\begin{array}{c c c c c c c c c c c c c c c c c c c$</td><td>$\begin{array}{c c c c c c c c c c c c c c c c c c c$</td></td></td<></td>	SYMBOL CONDITIONS MIN TYP MAX MIN TYP V_{OS} - 0.4 1.2 - 0.6 TCV _{OS} - 4 10 - 8 I_B (Note 1) - 0.5 1.2 - 0.6 I_OS (Note 1) - 0.05 0.2 - 0.06 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 VRR $V_S = \pm 10V$ - 2 40 - 6 $PSRR$ $V_S = \pm 10V$ - 200 500 - 200 500 A_{VO} $R_L = 2k\Omega$ ± 11.0 ± 12.3 <td< td=""><td>SYMBOL CONDITIONS MIN TYP MAX MIN TYP MAX V_{OS} - 0.4 1.2 - 0.6 2.5 TCV_{OS} - 4 10 - 8 - I_B (Note 1) - 0.5 1.2 - 0.6 2.0 I_{OS} (Note 1) - 0.05 0.2 - 0.06 0.4 IVR (Note 1) - 0.05 0.2 - 0.06 0.4 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 - CMR $V_{CM} = \pm 11V$ 86 96 - 80 94 - PSRR $V_S = \pm 10V$ - 2 40 - 6 50 A_{VO} $R_L = 10k\Omega$ (Note 1) 200 500 - 200 500 - V_O $R_L = 2k\Omega$ ± 11.0 ± 12.3 - ± 11.0<td>SYMBOL CONDITIONS MIN TYP MAX MIN V_{OS} - 0.4 1.2 - 0.6 2.5 - TCV_{OS} - 4 10 - 8 - - I_B (Note 1) - 0.5 1.2 - 0.6 2.0 - IVR (Note 1) - 0.05 0.2 - 0.06 0.4 - IVR (Note 2) ±11 ±12.5 - ±11 ±12.5 - ±11 CMR V_G = ±10V - 20 - - 6 50 - A_{VO} R_L = 2kQ v_O = ±10V 100</td><td>$\begin{array}{c c c c c c c c c c c c c c c c c c c$</td><td>$\begin{array}{c c c c c c c c c c c c c c c c c c c$</td></td></td<>	SYMBOL CONDITIONS MIN TYP MAX MIN TYP MAX V_{OS} - 0.4 1.2 - 0.6 2.5 TCV _{OS} - 4 10 - 8 - I_B (Note 1) - 0.5 1.2 - 0.6 2.0 I_{OS} (Note 1) - 0.05 0.2 - 0.06 0.4 IVR (Note 1) - 0.05 0.2 - 0.06 0.4 IVR (Note 2) ± 11 ± 12.5 - ± 11 ± 12.5 - CMR $V_{CM} = \pm 11V$ 86 96 - 80 94 - PSRR $V_S = \pm 10V$ - 2 40 - 6 50 A_{VO} $R_L = 10k\Omega$ (Note 1) 200 500 - 200 500 - V_O $R_L = 2k\Omega$ ± 11.0 ± 12.3 - ± 11.0 <td>SYMBOL CONDITIONS MIN TYP MAX MIN V_{OS} - 0.4 1.2 - 0.6 2.5 - TCV_{OS} - 4 10 - 8 - - I_B (Note 1) - 0.5 1.2 - 0.6 2.0 - IVR (Note 1) - 0.05 0.2 - 0.06 0.4 - IVR (Note 2) ±11 ±12.5 - ±11 ±12.5 - ±11 CMR V_G = ±10V - 20 - - 6 50 - A_{VO} R_L = 2kQ v_O = ±10V 100</td> <td>$\begin{array}{c c c c c c c c c c c c c c c c c c c$</td> <td>$\begin{array}{c c c c c c c c c c c c c c c c c c c$</td>	SYMBOL CONDITIONS MIN TYP MAX MIN V_{OS} - 0.4 1.2 - 0.6 2.5 - TCV _{OS} - 4 10 - 8 - - I_B (Note 1) - 0.5 1.2 - 0.6 2.0 - IVR (Note 1) - 0.05 0.2 - 0.06 0.4 - IVR (Note 2) ±11 ±12.5 - ±11 ±12.5 - ±11 CMR V _G = ±10V - 20 - - 6 50 - A_{VO} R_L = 2kQ v _O = ±10V 100	$\begin{array}{c c c c c c c c c c c c c c c c c c c $	$\begin{array}{c c c c c c c c c c c c c c c c c c c $

NOTES:

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1. $T_j = 85^{\circ}C$ for E/F/G Grades; $T_j = 125^{\circ}C$ for A grade.

2. Guaranteed by CMR test.

3. Guaranteed but not tested.

ELECTRICAL CHARACTERISTICS at $V_s = \pm 15V$, $-55^{\circ}C \le T_A \le 125^{\circ}C$ for A grade, unless otherwise noted.

				OP-42A		
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Offset Voltage	Vos		_	0.5	2.0	mV
Offset Voltage Temperature Coefficient	TCV _{OS}		_	4	10	µV/°C
Input Bias Current	۱ _в	(Note 1)	-	6	20	nA
Input Offset Current	los	(Note 1)	-	0.2	1.0	nA
Input Voltage Range	IVR	(Note 2)	±11	+12.5 12.0		v
Common-Mode Rejection	CMR	V _{CM} = ±11V	80	94	-	dB
Power-Supply Rejection Ratio	PSRR	$V_{s} = \pm 10V$ to $\pm 20V$	-	10	50	μV/V
Large-Signal Voltage Gain	A _{vo}	R _L = 10kΩ (Note 1) R _L = 2kΩ V _O = ±10V	160 80	350 110		V/mV
Output Voltage Swing	v _o	R _L = 2kΩ	±11.0	+12.3 11.8	_	v
Short-Circuit Current Limit	Isc	Output Shorted to Ground	±8	_	±60	mA
Supply Current	I _{SY}	No Load V _O = 0V		5.1	6.0	mA
Slew Rate	SR	$R_{L} = 2k\Omega$	40	52	-	V/µs
Capacitive Load Drive Capability	CL	Unity-Gain Stable (Note 3)	100	250	-	pF

NOTES:

1. $T_j = 85^{\circ}C$ for E/F Grades; $T_j = 125^{\circ}C$ for A grade. 2. Guaranteed by CMR test.

3. Guaranteed but not tested.

OP-42 dice characteristics



1. OFFSET VOLTAGE NULL 2. INVERTING INPUT 3. NONINVERTING INPUT 4. NEGATIVE SUPPLY 5. OFFSET VOLTAGE NULL 6. AMPLIFIER OUTPUT 7. POSITIVE SUPPLY

WAFER TEST LIMITS at $V_S = \pm 15V$, $T_j = 25^{\circ}C$, unless otherwise noted.

			OP-42N	
PARAMETER	SYMBOL	CONDITIONS	LIMIT	UNITS
Offset Voltage	V _{OS}		1.5	mV MAX
Input Bias Current	۱ _B	V _{CM} = 0V	250	pA MAX
Input Offset Current	los	V _{CM} = 0V	50	pA MAX
Input Voltage Range	IVR	(Note 1)	±11	V MIN
Common-Mode Rejection	CMR	$V_{CM} = \pm 11V$	80	dB MIN
Power-Supply Rejection Ratio	PSRR	$V_{\rm S} = \pm 10$ V to ± 20 V	50	μV/V MAX
Large-Signal Voltage Gain	A _{VO}	$R_{L} = 10 k\Omega$ $R_{L} = 2 k\Omega$ $R_{L} = 1 k\Omega$	500 200 100	V/mV MIN
Output Voltage Swing	Vo	$R_L = 1 k \Omega$	±11.5	V MIN
Short-Circuit Current Limit	' _{SC}	Output Shorted to Ground	±20/±60	mA MIN/MAX
Supply Current	Ι _{SY}	No Load V _O = 0V	6.5	mA MAX
Slew Rate	SR		40	V∕µs MIN
Capacitive Load Drive Capability	CL	Unity-Gain Stable (Note 2)	100	pF MIN

NOTES:

1. Guaranteed by CMR test.

2. Guaranteed but not tested.

Electrical tests are performed at wafer probe to the limits shown. Due to variations in assembly methods and normal yield loss, yield after packaging is not guaranteed for standard product dicc. Consult factory to negotiate specifications based on dice lot qualification through sample lot assembly and testing.

BURN-IN CIRCUIT



100k

1M

TYPICAL PERFORMANCE CHARACTERISTICS





SLEW RATE vs TEMPERATURE





SLEW RATE vs

SLEW RATE vs CAPACITIVE LOAD



SETTLING-TIME vs STEP SIZE $T_A = 25^{\circ}C$

10







CLOSED-LOOP GAIN vs FREQUENCY



TYPICAL PERFORMANCE CHARACTERISTICS



TYPICAL PERFORMANCE CHARACTERISTICS



BIAS CURRENT vs COMMON-MODE VOLTAGE 104 V₈ = ±15V T_J = 25°C 103 BIAS CURRENT (pA) 102 101 10º L −15 -10 -5 0 5 10 15 COMMON-MODE VOLTAGE (VOLTS)



SHORT CIRCUIT OUTPUT CURRENT vs JUNCTION TEMPERATURE



OFFSET CURRENT vs JUNCTION TEMPERATURE





OPEN-LOOP GAIN vs

VOLTAGE NOISE DENSITY



0P-42

APPLICATIONS INFORMATION

The OP-42 combines speed with a high level of input precision usually found only with slower devices. Well-behaved AC performance in the form of clean transient response, symmetrical slew-rates and a high degree of forgiveness to supply decoupling are the hallmarks of this amplifier. AC gain and phase response are quite independent of temperature or supply voltage. Figure 1 shows the OP-42's smallsignal response. Even with 75pF loads, there is minimal ringing in the output waveform. Large-signal response is shown in Figure 2. This figure clearly shows the OP-42's exceptionally close matching between positive and negative slewrates. Slew-rate symmetry decreases the DC offset a system encounters when processing high-frequency signals, and thus reduces the DC current necessary for load driving.









As with most JFET-input amplifiers, the output of the OP-42 may undergo phase inversion if either input exceeds the specified input voltage range. Phase inversion will not damage the amplifier, nor will it cause an internal latch-up.

Supply decoupling should be used to overcome inductance and resistance associated with supply lines to the amplifier. For most applications a $0.1 \mu F$ to $0.01 \mu F$ capacitor should be placed between each supply pin and ground.

The OP-42 displays excellent resistance to radiation. Radiation hardness data is available by contacting the factory.

OFFSET VOLTAGE ADJUSTMENT

Offset voltage is adjusted with a 10k Ω to 100k Ω potentiometer as shown in Figure 3. The potentiometer should be connected between pins 1 and 5 with its wiper connected to the V- supply. Nulling V_{OS} in this manner changes TCV_{OS} by no more than 5 μ V/°C per millivolt of V_{OS} change. Alternately, V_{OS} may be nulled by attaching the potentiometer wiper through a 1M Ω resistor to the positive supply rail.





SETTLING-TIME

Guaranteed fast-settling is assured by sample-testing during production. The OP-42 is configured as a unity-gain follower in the test circuit of Figure 4. This test method has advantages over false-sum-node techniques in that the actual output of the amplifier is measured, instead of an error-voltage at the sum node. Common-mode settling effects are exercised in this circuit, in addition to the slew-rate and bandwidth effects measured by the false-sum-node method. A reasonably flat-top pulse is required as a stimulus.

The output waveform of the OP-42 being tested is clamped by Schottky diodes and buffered by the JFET sourcefollower. The signal is amplified by a factor of ten by the fast amplifier IC1, then Schottky-clamped before being output. The OP-41 provides overall offset nulling. Analysis of the waveform using a digitizing oscilloscope determines the op amp's settling-time.

FIGURE 4: Settling-Time Test Fixture



FIGURE 5: OP-42 Settling-Characteristics



DAC OUTPUT AMPLIFIER

The OP-42 is an excellent choice for a DAC output amplifier, since its high speed and fast settling-time allow quick transitions between codes, even for full-scale changes in output level. The DAC output capacitance appears at the operational amplifier inputs, and must be compensated to ensure optimal settling speed. Compensation is achieved with capacitor C in Figure 6. C must be adjusted to account for the DAC's output capacitance, the op amp's input capacitance, and any stray capacitance at the inputs. With a bipolar DAC, an additional shunt resistor may be used to optimize response. This technique is described in PMI's application note AN-24.

FIGURE 6: DAC Output Amplifier Circuit



Highest speed is achieved using bipolar DACs such as PMI's DAC-08, DAC-10 or DAC-312. The output capacitances of these converters are up to an order of magnitude lower than their CMOS counterparts, resulting in substantially faster settling-times. The high output impedance of bipolar DACs allows the output amplifier to operate in a true current-to-voltage mode, with a noise gain of unity, thereby retaining the amplifier's full bandwidth. Offset voltage has minimal effect on linearity with bipolar converters.

CMOS digital-to-analog converters have higher output capacitances and lower output resistances than bipolar DACs.

This results in slower settling-times, higher sensitivity to offset voltages and a reduction in the output amplifier's bandwidth. These trade-offs must be balanced against the CMOS DAC's advantages in terms of interfacing capability, power dissipation, accuracy levels and cost. Using the internal feedback resistor which is present on most CMOS converters, the gain applied to offset voltage varies between 4/3 and 2, depending upon output code. Contributions to linearity error will be as much as $2/3V_{OS}$. In a 10-volt 12-bit system, this may add up to an additional 1/5LSB DNL with the OP-42E. Amplifier bandwidth is reduced by the same gain factor applied to offset voltage, however the OP-42's 10MHz gainbandwidth product results in no reduction of the CMOS converter's multiplying bandwidth.

Individual DAC data-sheets should be consulted for more complete descriptions of the converters and their circuit applications.



FIGURE 7: DAC Output Amplifier Response (PM-7545 DAC)

DRIVING A HIGH-SPEED ADC

The OP-42's open-loop output resistance is approximately 50 Ω . When feedback is applied around the amplifier, output resistance decreases in proportion to open-loop gain divided by closed-loop gain (A_{VOL}/A_{VCL}). Output impedance increases as open-loop gain rolls-off with frequency. High-speed analog-to-digital converters require low source impedances at high frequency. Output impedance at 1MHz is typically 5 Ω for an OP-42 operating at unity-gain. If lower output impedances are required, an output buffer may be placed at the output of the OP-42.

HIGH-CURRENT OUTPUT BUFFER

The circuit in Figure 8 shows a high-current output stage for the OP-42. Output current is limited by R1 and R2. For good tracking between the output transistors Q1, Q2 and their biasing diodes D1 and D2, thermal contact must be maintained between the transistor and its associated diode. If good thermal contact is not maintained, R1 and R2 must be increased to 5-6 Ω in order to prevent thermal runaway. Using 5 Ω resistors, the circuit easily drives a 75 Ω load (Figure 9). Output resistance is decreased and heavier loads may be driven by decreasing R1 and R2.

Base current and biasing for Q1 and Q2 are provided by two current sources, the MAT-02 and the JFET. The $2k\Omega$ potentiometer in the JFET current source should be trimmed for optimum transient performance. The case of the MAT-02 should be connected to V-, and decoupled to ground with a

 0.1μ F capacitor. Compensation for the OP-42's input capacitance is provided by C_C. The circuit may be operated at any gain, in the usual op amp configurations.





FIGURE 9: Output Buffer Large-Signal Response



DRIVING CAPACITIVE LOADS

Best performance will always be achieved by minimizing input and load capacitances around any high-speed amplifier. However, the OP-42 is guaranteed capable of driving a 100pF capacitive load over its full operating temperature range while operating at any gain including unity. Typically, an OP-42 will drive more than 250pF at any temperature. Supply decoupling does affect capacitive load driving ability. Extra care should be given to ensure good decoupling when driving capacitive loads, and a larger decoupling capacitor between 1μ F and 10μ F should be placed in parallel with the usual decoupling capacitor on each supply.

O VOUT

Large capacitive loads may be driven utilizing the circuit shown in Figure 10. R1 and C1 introduce a small amount of feedforward compensation around the amplifier to counteract the phase lag induced by the output impedance and load capacitance. At DC and low frequencies, R1 is contained within the feedback loop. At higher frequencies, feedforward compensation becomes increasingly dominant, and R1's effect on output impedance will become more noticeable.

When driving very large capacitances, slew-rate will be limited by the short-circuit current limit. Although the unloaded slew-rate is insensitive to variations in temperature, the output current limit has a negative temperature coefficient, and is asymmetrical with regards to sourcing and sinking current. Therefore, slew-rate into excessive capacities will decrease with increasing temperature, and will lose symmetry.

COMPUTER SIMULATIONS

Many electronic design and analysis programs include models for op amps which calculate AC performance from the location of poles and zeros. As an aid to designers utilizing such a program, major poles and zeros of the OP-42 are listed below. Their location will vary slightly between production lots. Typically, they will be within $\pm 15\%$ of the frequency listed. Use of this data will enable the designer to evaluate gross circuit performance quickly, but should not supplant rigorous characterization of a breadboarded circuit.

POLES ZEROS 20Hz 1MHz 300kHz 3MHz



AUTOZEROING OFFSET VOLTAGE

Figure 11 describes a circuit for automatic offset voltage and drift correction. The OP-41 is used in a servo loop to force the OP-42 output equal to the OP-41's offset voltage. Thus, the OP-42's effective input offset is held below $10\mu V$ (1mV/A_{VCL} = 100) despite any temperature variations. This circuit will be most advantageous in high-gain applications.

Feedback is accomplished using the OP-42's null pins, leaving both inputs free for other purposes. In the application



FIGURE 11: OP-41 Servo Amplifier Provides Offset Correction

FIGURE 10: Compensation for Large Capacitive Loads

R1

₩ 10Ω

0.1 µF

OP-42

VIN C

shown, the OP-42 has seven multiplexed inputs, while the eighth input provides a ground reference. Nulling is accomplished by addressing the grounded channel. This address should be held for at least 200μ s. After this time, the address may be changed to another channel. The MUX-08 ENABLE pin must be high during the entire nulling cycle. During this time, JFET switch J1 turns on, completing feedback around

the OP-41 servo amplifier. A charge is developed across C_H to compensate for the OP-42's offset voltage. When another channel is addressed, J1 turns off, and the correction charge is maintained across C_H by the OP-41. Droop is exceptionally low — only 1.3μ V/s at 25° C. A correction range of more than 4mV allows nulling of minor system offsets as well as the OP-42's offset voltage.



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