

512Kbit SPI Serial SRAM with SDI and SQI Interface

Device Selection Table

Part Number	Vcc Range	Dual I/O (SDI)	Quad I/O (SQI)	Max. Clock Frequency	Packages	
23A512	1.7-2.2V	Yes	Yes	20 MHz	SN, ST, P	
23LC512	2.5-5.5V	Yes	Yes	20 MHz	SN, ST, P	

Features:

- SPI-Compatible Bus Interface:
 - 20 MHz Clock rate
 - SPI/SDI/SQI mode
- · Low-Power CMOS Technology:
 - Read Current: 3 mA at 5.5V, 20 MHz
- Standby Current: 4 μA at +85°C
- Unlimited Read and Write Cycles
- · Zero Write Time
- 64K x 8-bit Organization:
 - 32-byte page
- Byte, Page and Sequential mode for Reads and Writes
- · High Reliability
- Temperature Range Supported:
- Industrial (I): -40°C to +85°C
- Pb-Free and RoHS Compliant, Halogen Free
- 8-Lead SOIC, TSSOP and PDIP Packages

Pin Function Table

Name	Function
CS	Chip Select Input
SO/SIO1	Serial Output/SDI/SQI Pin
SIO2	SQI Pin
Vss	Ground
SI/SIO0	Serial Input/SDI/SQI Pin
SCK	Serial Clock
HOLD/SIO3	Hold/SQI Pin
Vcc	Power Supply

Description:

The Microchip Technology Inc. 23A512/23LC512 are 512Kbit Serial SRAM devices. The memory is accessed via a simple Serial Peripheral Interface (SPI) compatible serial bus. The bus signals required are a clock input (SCK) plus separate data in (SI) and data out (SO) lines. Access to the device is controlled through a Chip Select (\overline{CS}) input. Additionally, SDI (Serial Dual Interface) and SQI (Serial Quad Interface) is supported if your application needs faster data rates.

This device also supports unlimited reads and writes to the memory array.

The 23A512/23LC512 is available in standard packages including 8-lead SOIC, PDIP and advanced 8-lead TSSOP.

Package Types (not to scale)



1.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings (†)

Vcc	6.5V
All inputs and outputs w.r.t. Vss	-0.3V to Vcc +0.3V
Storage temperature	-65°C to +150°C
Ambient temperature under bias	-40°C to +85°C

† NOTICE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational listings of this specification is not implied. Exposure to maximum rating conditions for an extended period of time may affect device reliability.

DC CHARACTERISTICS		Industrial	(I): T	A = -40°C to				
Param. No. Sym.		Characteristic	Min.	Тур. ⁽¹⁾	Max.	Units	Test Conditions	
D001	Vcc	Supply voltage	1.7 2.5		2.2 5.5	V	23A512 23LC512	
D002	Vih	High-level input voltage	.7 Vcc	—	Vcc +0.3	V		
D003	VIL	Low-level input voltage	-0.3	—	0.2xVcc 0.10xVcc	V	23A512 23LC512	
D004	Vol	Low-level output voltage	—	—	0.2	V	IOL = 1 mA	
D005	Vон	High-level output voltage	Vcc -0.5	—	_	V	Іон = -400 μА	
D006	ILI	Input leakage current	_	_	±1	μA	CS = Vcc, VIN = Vss or Vcc	
D007	Ilo	Output leakage current	-	_	±1	μA	CS = Vcc, Vout = Vss or Vcc	
D008	Icc Read	Operating current	_	1 3	10 10	mA mA	Fclk = 20 MHz; SO = 0, 2.2V Fclk = 20 MHz; SO = 0, 5.5V	
D009	Iccs	Standby current	_	1	4 10	μΑ μΑ	\overline{CS} = Vcc = 2.2V, Inputs tied to Vcc or Vss \overline{CS} = Vcc = 5.5V, Inputs tied to	
				-	10	μ	Vcc or Vss	
D010	CINT	Input capacitance	-		7	pF	Vcc = 0V, f = 1 MHz, Ta = 25°C (Note 1)	
D011	Vdr	RAM data retention voltage ⁽²⁾	_	1.0	_	V		

TABLE 1-1: DC CHARACTERISTICS

Note 1: This parameter is periodically sampled and not 100% tested. Typical measurements taken at room temperature (25°C).

2: This is the limit to which VDD can be lowered without losing RAM data. This parameter is periodically sampled and not 100% tested.

AC CHARACTERISTICS			Industrial (I): $TA = -40^{\circ}C \text{ to } +85^{\circ}C$				
Param. No.	Sym. Characteristic		Min.	Max.	Units	Test Conditions	
1	FCLK	Clock frequency	—	20	MHz		
2	Tcss	CS setup time	25	_	ns		
3	TCSH	CS hold time	50		ns		
4	TCSD	CS disable time	25		ns		
5	Tsu	Data setup time	10	_	ns		
6	Thd	Data hold time	10	—	ns		
7	TR	CLK rise time	—	20	ns	Note 1	
8	Tf	CLK fall time	—	20	ns	Note 1	
9	Тні	Clock high time	25	_	ns		
10	Tlo	Clock low time	25		ns		
11	TCLD	Clock delay time	25	_	ns		
12	Τv	Output valid from clock low	_	25	ns		
13	Тно	Output hold time	0		ns	Note 1	
14	TDIS	Output disable time	_	20	ns		
15	THS	HOLD setup time	10	—	ns	—	
16	Тнн	HOLD hold time	10	—	ns	-	
17	Тнг	HOLD low to output High-Z	10	_	ns	_	
18	Тну	HOLD high to output valid		50	ns	_	

TABLE 1-2: AC CHARACTERISTICS

Note 1: This parameter is periodically sampled and not 100% tested.

TABLE 1-3: AC TEST CONDITIONS

AC Waveform:					
Input pulse level	0.1 Vcc to 0.9 Vcc				
Input rise/fall time	5 ns				
Operating temperature	-40°C to +85°C				
CL = 30 pF	—				
Timing Measurement Reference Level:					
Input	0.5 Vcc				
Output	0.5 Vcc				

FIGURE 1-1: HOLD TIMING



FIGURE 1-2: SERIAL INPUT TIMING (SPI MODE)



FIGURE 1-3: SERIAL OUTPUT TIMING (SPI MODE)



2.0 FUNCTIONAL DESCRIPTION

2.1 **Principles of Operation**

The 23A512/23LC512 is an 512Kbit Serial SRAM designed to interface directly with the Serial Peripheral Interface (SPI) port of many of today's popular microcontroller families, including Microchip's PIC[®] microcontrollers. It may also interface with microcontrollers that do not have a built-in SPI port by using discrete I/O lines programmed properly in firmware to match the SPI protocol. In addition, the 23A512/23LC512 is also capable of operating in SDI/SQI high speed SPI mode.

The 23A512/23LC512 contains an 8-bit instruction register. The device is accessed via the SI pin, with data being clocked in on the rising edge of SCK. The $\overline{\text{CS}}$ pin must be low for the entire operation.

Table 2-1contains a list of the possible instructionbytes and format for device operation. All instructions,addresses and data are transferred MSB first, LSB last.

2.2 Modes of Operation

The 23x512 has three modes of operation that are selected by setting bits 7 and 6 in the MODE register. The modes of operation are Byte, Page and Burst.

Byte Operation – is selected when bits 7 and 6 in the MODE register are set to 00. In this mode, the read/ write operations are limited to only one byte. The Command followed by the 16-bit address is clocked into the device and the data to/from the device is transferred on the next eight clocks (Figure 2-1, Figure 2-2).

Page Operation – is selected when bits 7 and 6 in the MODE register are set to 10. The 23x512 has 2048 pages of 32 bytes. In this mode, the read and write operations are limited to within the addressed page (the address is automatically incremented internally). If the data being read or written reaches the page boundary, then the internal address counter will increment to the start of the page (Figure 2-3, Figure 2-4).

Sequential Operation – is selected when bits 7 and 6 in the MODE register are set to 01. Sequential operation allows the entire array to be written to and read from. The internal address counter is automatically incremented and page boundaries are ignored. When the internal address counter reaches the end of the array, the address counter will roll over to 0×0000 (Figure 2-5, Figure 2-6).

2.3 Read Sequence

The device is selected by pulling $\overline{\text{CS}}$ low. The 8-bit READ instruction is transmitted to the 23A512/23LC512 followed by the 16-bit address. After the correct READ instruction and address are sent, the data stored in the memory at the selected address is shifted out on the SO pin.

If operating in Sequential mode, the data stored in the memory at the next address can be read sequentially by continuing to provide clock pulses. The internal Address Pointer is automatically incremented to the next higher address after each byte of data is shifted out. When the highest address is reached (FFFFh), the address counter rolls over to address 0000h, allowing the read cycle to be continued indefinitely. The read operation is terminated by raising the CS pin.

2.4 Write Sequence

Prior to any attempt to write data to the $23A5\underline{12/}$ 23LC512, the device must be selected by bringing \overline{CS} low.

Once the device is selected, the Write command can be started by issuing a WRITE instruction, followed by the 16-bit address, and then the data to be written. A write is terminated by the \overline{CS} being brought high.

If operating in Page mode, after the initial data byte is shifted in, additional bytes can be shifted into the device. The Address Pointer is automatically incremented. This operation can continue for the entire page (32 bytes) before data will start to be overwritten.

If operating in Sequential mode, after the initial data byte is shifted in, additional bytes can be clocked into the device. The internal Address Pointer is automatically incremented. When the Address Pointer reaches the highest address (FFFFh), the address counter rolls over to (0000h). This allows the operation to continue indefinitely, however, previous data will be overwritten.

TABLE 2-1: INSTRUCTION SET

Instruction Name	Instruction Format	Hex Code	Description		
READ	0000 0011	0x03	Read data from memory array beginning at selected address		
WRITE	0000 0010	0x02	Write data to memory array beginning at selected address		
EDIO	0011 1011	0x3B	Enter Dual I/O access		
EQIO	0011 1000	0x38	Enter Quad I/O access		
RSTIO	1111 1111	OxFF	Reset Dual and Quad I/O access		
RDMR	0000 0101	0x05	Read Mode Register		
WRMR	0000 0001	0x01	Write Mode Register		

FIGURE 2-1: BYTE READ SEQUENCE (SPI MODE)



FIGURE 2-2: BYTE WRITE SEQUENCE (SPI MODE)











2.5 Read Mode Register Instruction (RDMR)

The Read Mode Register instruction (RDMR) provides access to the MODE register. The MODE register may be read at any time. The MODE register is formatted as follows:

TABLE 2-2: MODE REGISTER

7	6	5	4	3	2	1	0
W/R	W/R	-	-	I	-	-	-
MODE	MODE MODE		0	0	0	0	0
W/R = writable/readable							

The mode bits indicate the operating mode of the SRAM. The possible modes of operation are:

- 0 0 = Byte mode
- 1 0 = Page mode
- 0 1 = Sequential mode (default operation)
- 1 1 = Reserved

Bits 0 through 5 are reserved and should always be set to '0'.

See Figure 2-7 for the RDMR timing sequence.

FIGURE 2-7: READ MODE REGISTER TIMING SEQUENCE (RDMR)



2.6 Write Mode Register Instruction (WRMR)

The Write Mode Register instruction (WRMR) allows the user to write to the bits in the MODE register as shown in Table 2-2. This allows for setting of the Device Operating mode. Several of the bits in the MODE register must be cleared to '0'. See Figure 2-8 for the WRMR timing sequence.



FIGURE 2-8: WRITE MODE REGISTER TIMING SEQUENCE (WRMR)

2.7 Power-On State

The 23A512/23LC512 powers on in the following state:

- The device is in low-power Standby mode $(\overline{CS} = 1)$
- A high-to-low-level transition on CS is required to enter active state

3.0 PIN DESCRIPTIONS

The descriptions of the pins are listed in Table 3-1.

TABLE 3-1: PIN FUNCTION TABLE

Name	SOIC/ PDIP TSSOP	Function
CS	1	Chip Select Input
SO/SIO1	2	Serial Data Output/SDI/SQI Pin
SIO2	3	SQI Pin
Vss	4	Ground
SI/SIO0	5	Serial Data Input/SDI/SQI Pin
SCK	6	Serial Clock Input
HOLD/SIO3	7	Hold/SQI Pin
Vcc	8	Power Supply

3.1 Chip Select (CS)

A low level on this pin selects the device. A high level deselects the device and forces it into Standby mode. When the device is deselected, SO goes to the high-impedance state, allowing multiple parts to share the same SPI bus. After power-up, a low level on $\overline{\text{CS}}$ is required, prior to any sequence being initiated.

3.2 Serial Output (SO)

The SO pin is used to transfer data out of the 23A512/ 23LC512. During a read cycle, data is shifted out on this pin after the falling edge of the serial clock.

3.3 Serial Input (SI)

The SI pin is used to transfer data into the device. It receives instructions, addresses, and data. Data is latched on the rising edge of the serial clock.

3.4 Serial Dual Interface Pins(SIO0, SIO1)

The SIO0 and SIO1 pins are used for SDI mode of operation. Functionality of these I/O pins is shared with SO and SI.

3.5 Serial Quad Interface Pins (SIO0 – SIO3)

The SIO0 through SIO3 pins are used for SQI mode of operation. Because of the shared functionality of these pins the HOLD feature is not available when using SQI mode.

3.6 Serial Clock (SCK)

The SCK is used to synchronize the communication between a master and the 23A512/23LC512. Instructions, addresses or data present on the SI pin are latched on the rising edge of the clock input, while data on the SO pin is updated after the falling edge of the clock input.

3.7 Hold Function (HOLD)

The HOLD pin is used to suspend transmission to the 23A512/23LC512 while in the middle of a serial sequence without having to re-transmit the entire sequence over again. It must be held high any time this function is not being used. Once the device is selected and a serial sequence is underway, the HOLD pin may be pulled low to pause further serial communication without resetting the serial sequence.

The HOLD pin should be brought low while SCK is low, otherwise the HOLD function will not be invoked until the next SCK high-to-low transition. The 23A512/ 23LC512 must remain selected during this sequence. The SI and SCK levels are "don't cares" during the time the device is paused and any transitions on these pins will be ignored. To resume serial communication, HOLD should be brought high while the SCK pin is low, otherwise serial communication will not be resumed until the next SCK high-to-low transition.

The SO line will tri-state immediately upon a high-to low transition of the HOLD pin, and will begin outputting again immediately upon a subsequent lowto-high transition of the HOLD pin, independent of the state of SCK.

Hold functionality is not available when operating in SQI mode.





4.0 DUAL AND QUAD SERIAL MODE

The 23A512/23LC512 also supports SDI (Serial Dual) and SQI (Serial Quad) mode of operation when used with compatible master devices. As a convention for SDI mode of operation, two bits are entered per clock using the SIO0 and SIO1 pins. Bits are clocked MSB first.

For SQI mode of operation, four bits of data are entered per clock, or one nibble per clock. The nibbles are clocked MSB first.

4.1 Dual Interface Mode

The 23A512/23LC512 supports Serial Dual Input (SDI) mode of operation. To enter SDI mode the EDIO command must be clocked in (Figure 4-1). It should be noted that if the MCU resets before the SRAM, the user will need to determine the serial mode of operation of the SRAM and reset it accordingly. Byte read and write sequence in SDI mode is shown in Figure 4-2 and Figure 4-3.





4.2 Quad Interface Mode

In addition to the Serial Dual Interface (SDI) mode of operation Serial Quad Interface (SQI) is also supported. In this mode the HOLD functionality is not available. To enter SQI mode the EQIO command must be clocked in (Figure 4-4).









4.3 Exit SDI or SQI Mode

To exit from SDI mode, the RSTIO command must be issued. The command must be entered in the current device configuration, either SDI or SQI, see Figure 4-7 and Figure 4-8.



FIGURE 4-5: BYTE READ MODE SQI



FIGURE 4-7: RESET SDI MODE (RSTIO) – FROM SDI MODE



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DS25155A-page 17



5.0 PACKAGING INFORMATION

5.1 Package Marking Information



8-Lead PDIP (300 mil)

8-Lead SOIC (3.90 mm)









Example:						
	3LAI	\vdash				
\$	1837 1L7					

Legend	d: XXX T Y YY WW NNN @3	Part number or part number code Temperature (I, E) Year code (last digit of calendar year) Year code (last 2 digits of calendar year) Week code (week of January 1 is week '01') Alphanumeric traceability code (2 characters for small packages) Pb-free JEDEC designator for Matte Tin (Sn)
Note:		mall packages with no room for the Pb-free JEDEC designator narking will only appear on the outer carton or reel label.
Note:	be carrie	nt the full Microchip part number cannot be marked on one line, it will d over to the next line, thus limiting the number of available s for customer-specific information.

8-Lead Plastic Dual In-Line (P) – 300 mil Body [PDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units			INCHES			
Dimension	n Limits	MIN	NOM	MAX			
Number of Pins	Ν		8				
Pitch	е		.100 BSC				
Top to Seating Plane	Α	-	-	.210			
Molded Package Thickness	A2	.115	.130	.195			
Base to Seating Plane	A1	.015	-	-			
Shoulder to Shoulder Width	E	.290	.310	.325			
Molded Package Width	E1	.240	.250	.280			
Overall Length	D	.348	.365	.400			
Tip to Seating Plane	L	.115	.130	.150			
Lead Thickness	С	.008	.010	.015			
Upper Lead Width	b1	.040	.060	.070			
Lower Lead Width	b	.014	.018	.022			
Overall Row Spacing §	eВ	-	_	.430			

Notes:

1. Pin 1 visual index feature may vary, but must be located with the hatched area.

2. § Significant Characteristic.

3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.

4. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-018B



8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging

Microchip Technology Drawing No. C04-057C Sheet 1 of 2

8-Lead Plastic Small Outline (SN) - Narrow, 3.90 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS				
Dimension Limits		MIN	NOM	MAX	
Number of Pins N		8			
Pitch	е		1.27 BSC		
Overall Height	А	-	-	1.75	
Molded Package Thickness	A2	1.25	-	-	
Standoff §	A1	0.10	-	0.25	
Overall Width	E	6.00 BSC			
Molded Package Width		3.90 BSC			
Overall Length	D	4.90 BSC			
Chamfer (Optional)	h	0.25	-	0.50	
Foot Length	L	0.40	-	1.27	
Footprint		1.04 REF			
Foot Angle	φ	0°	-	8°	
Lead Thickness	С	0.17	-	0.25	
Lead Width	b	0.31	-	0.51	
Mold Draft Angle Top	α	5°	-	15°	
Mold Draft Angle Bottom	β	5°	-	15°	

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. § Significant Characteristic

3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.

4. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing No. C04-057C Sheet 2 of 2

8-Lead Plastic Small Outline (SN) – Narrow, 3.90 mm Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch	E	1.27 BSC		
Contact Pad Spacing	С		5.40	
Contact Pad Width (X8)	X1			0.60
Contact Pad Length (X8)	Y1			1.55

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2057A

8-Lead Plastic Thin Shrink Small Outline (ST) – 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS			
Dimension Limits		MIN	NOM	MAX
Number of Pins N		8		
Pitch	е	0.65 BSC		
Overall Height	Α	-	-	1.20
Molded Package Thickness	A2	0.80	1.00	1.05
Standoff	A1	0.05	-	0.15
Overall Width	E		6.40 BSC	
Molded Package Width	E1	4.30	4.40	4.50
Molded Package Length	D	2.90	3.00	3.10
Foot Length	L	0.45	0.60	0.75
Footprint L1		1.00 REF		
Foot Angle	ф	0°	-	8°
Lead Thickness	с	0.09	-	0.20
Lead Width	b	0.19	_	0.30

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15 mm per side.

3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-086B

8-Lead Plastic Thin Shrink Small Outline (ST) - 4.4 mm Body [TSSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Contact Pitch E			0.65 BSC	
Contact Pad Spacing	C1		5.90	
Contact Pad Width (X8)	X1			0.45
Contact Pad Length (X8)	Y1			1.45
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2086A

APPENDIX A: REVISION HISTORY

Revision A (09/2012)

Initial release.

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6.	Is there any incorrect or misleading information (what a	and where)?
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PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office. Not all possible ordering options are shown below.

PART N	<u>0. 2</u>	<u>x</u> _ <u>x</u>	<u>/xx</u>	Examples:
Device			Package	 a) 23A512-I/ST = 512 Kbit, 1.7 - 2.2V Serial SRAM, Industrial temp., TSSOP package b) 23LC512-I/SN = 512 Kbit, 2.5-5.5V Serial SRAM, Industrial temp., Tape & Reel, SOIC package
Device:	23A512 = 23LC512 =	512 Kbit, 1.7 - 2.2V 512 Kbit, 2.5 - 5.5V	,	c) 23LC512-I/P = 512 Kbit, 2.5-5.5V Serial SRAM, Industrial temp., PDIP package
Tape & Reel:	Blank = T =	Standard packagir Tape & Reel	ng (tube)	
Temperature Range:	=	-40°C to+85°C		
Package:	SN = ST = P =) mm body), 8-lead 4 mm body), 8-lead mil body), 8-lead	

NOTES:

Note the following details of the code protection feature on Microchip devices:

- · Microchip products meet the specification contained in their particular Microchip Data Sheet.
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- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
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