

# *Errata SLAZ358D–October 2012–Revised April 2015*

# MSP430FE4272 Device Erratasheet

## 1 Revision History

 $\checkmark$  The check mark indicates that the issue is present in the specified revision.

Errata Number	Rev C
CPU4	$\checkmark$
EEM20	✓
ESP1	<
ESP4	$\checkmark$
FLL3	$\checkmark$
TA12	$\checkmark$
TA16	$\checkmark$
TA21	$\checkmark$
TAB22	<
US15	~
WDG2	$\checkmark$



Package Markings

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## 2 Package Markings

```
PM64
```

LQFP (PM), 64 Pin





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Detailed Bug Description

3 Detailed Bug Description				
CPU4	CPU Module			
Function	PUSH #4, PUSH #8			
Description	The single operand instruction PUSH cannot use the internal constants (CG) 4 and 8. The other internal constants (0, 1, 2, -1) can be used. The number of clock cycles is different:			
	PUSH #CG uses address mode 00, requiring 3 cycles, 1 word instruction			
	PUSH #4/#8 uses address mode 11, requiring 5 cycles, 2 word instruction			
Workaround	Workaround implemented in assembler.			
EEM20	EEM Module			
Function	Debugger might clear interrupt flags			
Description	During debugging read-sensitive interrupt flags might be cleared as soon as the debugger stops. This is valid in both single-stepping and free run modes.			
Workaround	None.			
ESP1	ESP Module			
Function	Suspending the ESP430CE1			
Description	Suspending the ESP430 may create an invalid interrupt which can lead to a reset-like behavior of the module.			
Workaround	Set the bit 0x08 together with the ESPSUSP bit:			
	bis.w #08h+ESPSUSP, &ESPCTL			
	This bit also must be cleared when the suspend mode is exited.			
	bic.w #08h+ESPSUSP, &ESPCTL			
	NOTE:			
	<ul> <li>After suspending the ESP430CE1 it can take up to 9 MCLK clock cycles before the CPU can access the SD16 registers.</li> </ul>			
	- An interrupt service routine for the SD16 is required.			
	// Shut down ESP (set Embedded Signal Processing into			
	// "Suspend" mode)			
	// ensure that it is not in measurement or calibration mode,			
	ESPCTL  = 0x08 + ESPSUSP;			
	// Set ESP into Suspend Mode			
	// incl. Bug Fix for Suspend Mode			
	// wait 9 clocks until proper access to the SD16 is possible			
	delay_cycles(9);			
	MBCTL &= ~(IN0IFG + IN0IE);			



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// Clear any Pending MB interrupt and disable	
// ESP interrupt	
SD16CTL &= ~SD16REFON; // Switch Referen	ce off

ESP4	ESP Module			
Function	Suspending the ESP430 activity			
Description	Due to timing violations between the ESP CPU and the MSP430 CPU, the SD16 converters are not switched off correctly if the ESP CPU is set into suspend mode immediately after the ESP CPU is checked for idle mode. This leads to an higher current consumption in low-power modes.			
Workaround	Implement an additional wait loop of 16 clock cycles between checking the ESP for idle mode and set the ESP CPU into suspend mode.			
	while ((RET0 & 0x8000) != 0); // Wait for Idle mode			
	// wait 16 clocks to exclude timing violations between MSP430 CPU			
	// and ESP CPU			
	_NOP();_NOP();_NOP();_NOP();_NOP();_NOP();_NOP();_NOP();_NOP();			
	_NOP();_NOP();_NOP();_NOP();_NOP();_NOP();_NOP();			
	// Shut down ESP (set Embedded Signal Processing into "Suspend" mode)			
	// ensure that it is not in measurement or calibration mode,			
	if ((RET0 & 0x8000) == 0)			
	{			
	ESPCTL  = 0x08 + ESPSUSP; // Set ESP into Suspend Mode			
	// incl. Bug Fix for Suspend Mode			
	}			
FLL3	FLL+ Module			
Function	FLLDx = 11 for /8 may generate an unstable MCLK frequency			
Description	When setting the FLL to higher frequencies using $FLLDx = 11$ (/8) the output frequency of the FLL may have a larger frequency variation (e.g. averaged over 2sec) as well as a lower average output frequency than expected when compared to the other FLLDx bit settings.			
Workaround	None			
TA12	TIMER_A Module			
Function	Interrupt is lost (slow ACLK)			
Description	Timer_A counter is running with slow clock (external TACLK or ACLK)compared to MCLK. The compare mode is selected for the capture/compare channel and the CCRx register is incremented by one with the occurring compare interrupt (if TAR = CCRx). Due to the fast MCLK the CCRx register increment (CCRx = CCRx+1) happens before the Timer_A counter has incremented again. Therefore the next compare interrupt			



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	should happen at once with the next Timer_A counter increment (if TAR = CCRx + 1). This interrupt gets lost.		
Workaround	Switch capture/compare mode to capture mode before the CCRx register increment. Switch back to compare mode afterwards.		
TA16	TIMER_A Module		
Function	First increment of TAR erroneous when $IDx > 00$		
Description	The first increment of TAR after any timer clear event (POR/TACLR) happens immediately following the first positive edge of the selected clock source (INCLK, SMCLK, ACLK or TACLK). This is independent of the clock input divider settings (ID0, ID1). All following TAR increments are performed correctly with the selected IDx settings.		
Workaround	None		
TA21	TIMER_A Module		
Function	TAIFG Flag is erroneously set after Timer A restarts in Up Mode		
Description	In Up Mode, the TAIFG flag should only be set when the timer counts from TACCR0 to zero. However, if the Timer A is stopped at TAR = TACCR0, then cleared (TAR=0) by setting the TACLR bit, and finally restarted in Up Mode, the next rising edge of the TACLK will erroneously set the TAIFG flag.		
Т			
	Timer CCR0-1 CCR0 Oh A 1h CSS A CCR0-1 CCR0 Oh		
	Set TAIFG		
Set TACC	R0 CCIFG		
Workaround	None.		
TAB22	TIMER_A/TIMER_B Module		
Function	Timer_A/Timer_B register modification after Watchdog Timer PUC		
Description	Unwanted modification of the Timer_A/Timer_B registers TACTL/TBCTL and TAIV/TBIV can occur when a PUC is generated by the Watchdog Timer(WDT) in Watchdog mode and any Timer_A/Timer_B counter register TACCRx/TBCCRx is incremented/decremented (Timer_A/Timer_B does not need to be running).		
Workaround	Initialize TACTL/TBCTL register after the reset occurs using a MOV instruction (BIS/BIC may not fully initialize the register). TAIV/TBIV is automatically cleared following this initialization.		
	Example code:		
	MOV.W #VAL, &TACTL		



## or

MOV.W #VAL, &TBCTL

Where, VAL=0, if Timer is not used in application otherwise, user defined per desired function.

US15	USART Module			
Function	UART receive with two stop bits			
Description	USART hardware does not detect a missing second stop bit when SPB = 1.			
	The Framing Error Flag (FE) will not be set under this condition and erroneous data reception may occur.			
Workaround	None (Configure USART for a single stop bit, SPB = 0)			
WDG2	WDT Module			
Function	Incorrectly accessing a flash control register			
Description	If a key violation is caused by incorrectly accessing a flash control register, the watchdog interrupt flag is set in addition to the expected PUC.			
Workaround	None			



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### 4 Document Revision History

Changes from family erratasheet to device specific erratasheet.

- 1. Errata XOSC5 was removed
- 2. Errata TA22 was renamed to TAB22
- 3. Description for TAB22 was updated

Changes from device specific erratasheet to document Revision A.

1. Errata EEM20 was added to the errata documentation.

Changes from document Revision A to Revision B.

1. Errata TA21 was added to the errata documentation.

Changes from document Revision B to Revision C.

1. Package Markings section was updated.

Changes from document Revision C to Revision D.

1. TA21 Description was updated.

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