



SANYO Semiconductors DATA SHEET

LB1938FA — Monolithic Digital IC 1ch, Low-saturation Forward/Reverse Motor Driver

Overview

The LB1938FA is an H-bridge motor driver that supports low-voltage drive and features low-saturation outputs in an ultraminiature slim package. The LB1938FA provides forward, reverse, brake, and standby modes controlled by two input signals, and is an optimal DC motor driver for notebook personal computers, digital cameras, cell phones, and other portable equipment.

Features

- Ultraminiature Micro8 package
- The low saturation voltage means that the voltage applied to the motor is higher and IC heat generation is reduced. This allows this IC to be used in environments with higher ambient operating temperatures.
Output saturation voltage (high side + low side): $V_{OSat} = 0.15V$ typical ($I_O = 100mA$)
- The wide usable voltage range and the low standby mode current drain of $0.1 \mu A$ make this IC optimal for battery operated equipment.
- There are no constraints on the relationship between the input signal voltage and the supply voltage. For example, this IC can be use at $V_{CC} = 3V$ and $V_{IN} = 5V$.
- Thermal protection circuit limits the drive current and prevents the IC from causing a fire or being destroyed if the IC chip temperature reaches or exceeds $180^{\circ}C$ due to large currents flowing when the outputs are shorted due to, for example, motor layer shorting or other phenomena.

Specifications

Absolute Maximum Ratings at $T_a = 25^{\circ}C$

| Parameter | Symbol | Conditions | Ratings | Unit |
|-----------------------|---------------|------------|-------------------|------|
| Supply voltage | V_{CC} max | | 10.5 | V |
| Output current | I_{OUT} max | | 800 | mA |
| Output voltage | V_{OUT} max | | $V_{CC} + V_{SF}$ | V |
| Input applied voltage | V_{IH} max | | 10 | V |

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| Parameter | Symbol | Conditions | Ratings | Unit |
|-----------------------------|--------|--------------------------------|-------------|------|
| Allowable power dissipation | Pd max | Mounted on a specified board * | 400 | mW |
| Operating temperature range | Topr | | -30 to +85 | °C |
| Storage temperature range | Tstg | | -55 to +150 | °C |

Note *: Mounted on a specified board: 114.3mm×76.1mm×1.5mm, glass epoxy resin, wiring density 20%

Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.

Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

Allowable Operating Range at Ta = 25°C

| Parameter | Symbol | Conditions | Ratings | Unit |
|--------------------------|-----------------|------------|--------------|------|
| Supply voltage | V _{CC} | | 2.2 to 10 | V |
| Input high-level voltage | V _{IH} | | 2.0 to 9.5 | V |
| Input low-level voltage | V _{IL} | | -0.3 to +0.3 | V |

Electrical Characteristics at Ta = 25°C, V_{CC} = 3V

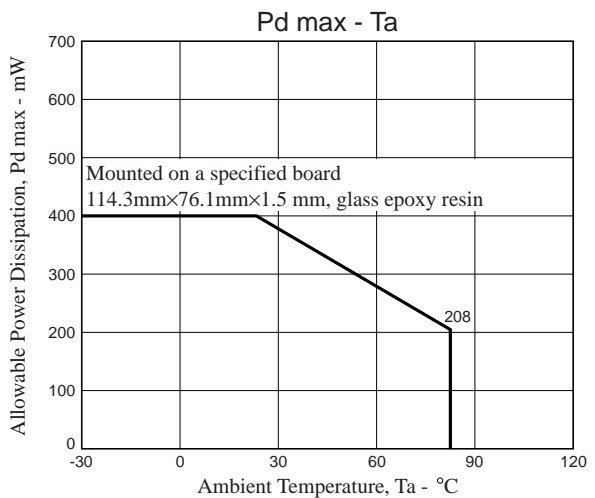
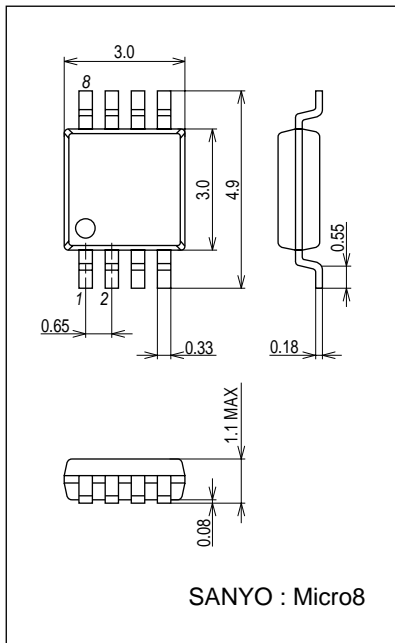
| Parameter | Symbol | Conditions | Ratings | | | Unit |
|--|--------------------|--|---------|------|------|------|
| | | | min | typ | max | |
| Circuit current | I _{CC1} | Standby | | 0.1 | 5 | μA |
| | I _{CC2} | Forward/reverse drive | | 14 | 19 | mA |
| | I _{CC3} | Brake | | 20 | 29 | mA |
| Output saturation voltage | V _{OSat1} | Upper+lower I _O = 100mA for forward/reverse rotation | | 0.15 | 0.2 | V |
| | V _{OSat2} | Upper+lower I _O = 300mA for forward/reverse rotation | | 0.35 | 0.5 | V |
| | V _{OSat3} | Upper I _O = 100mA for braking | | 0.1 | 0.15 | V |
| Spark killer diode forward voltage | V _{SF} | I _O = 300mA | | 0.9 | 1.7 | V |
| Spark killer diode inverse current | I _{RS} | V _{OUT} = 10V | | 0.1 | 5 | μA |
| Input current | I _{IN} | V _{IN} = 5V | | 75 | 98 | μA |
| Thermal protection operating temperature | TSD | Design target value * | | 180 | | °C |

Note *: Design target value: Measurement with a single unit not made.

Package Dimensions

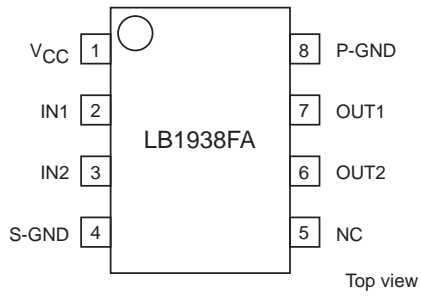
unit : mm (typ)

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Pin Assignment



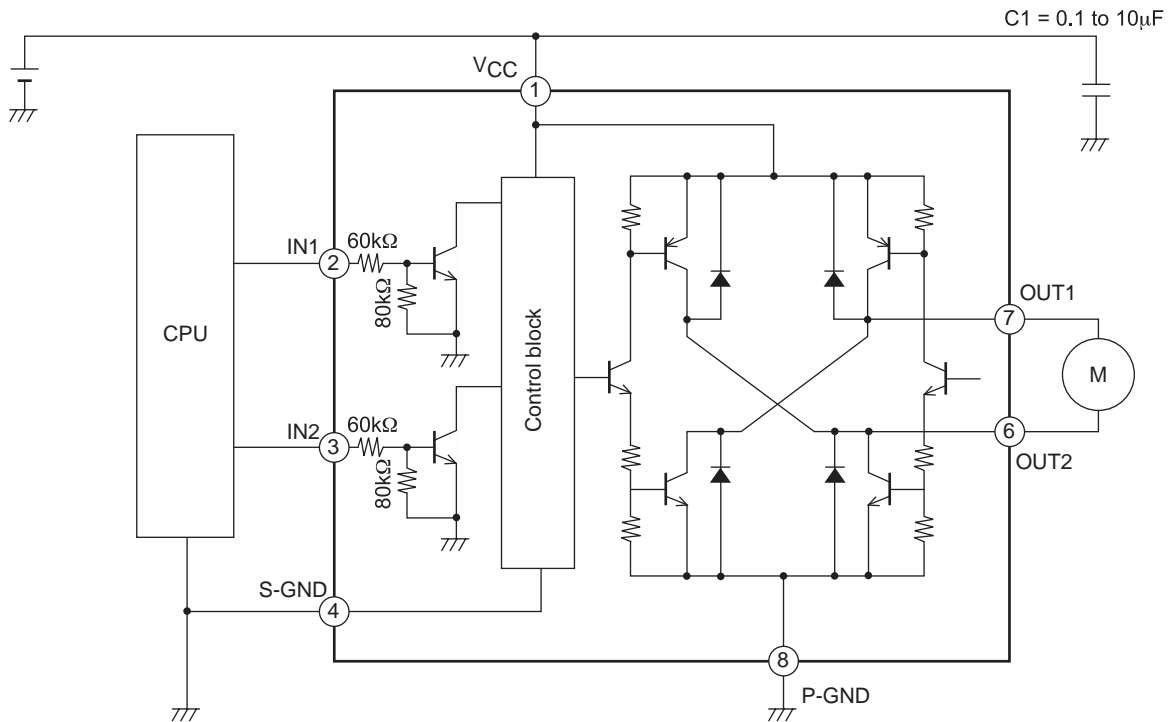
S-GND: GND for the control system

P-GND: GND for the power system

Truth Table

| IN1 | IN2 | OUT1 | OUT2 | Mode |
|-----|-----|------|------|------------------|
| L | L | OFF | OFF | Standby |
| H | L | H | L | Forward rotation |
| L | H | L | H | Reverse rotation |
| H | H | H | H | Brake |

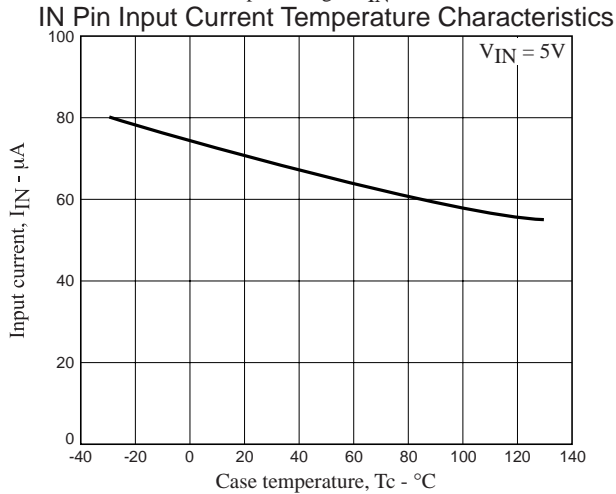
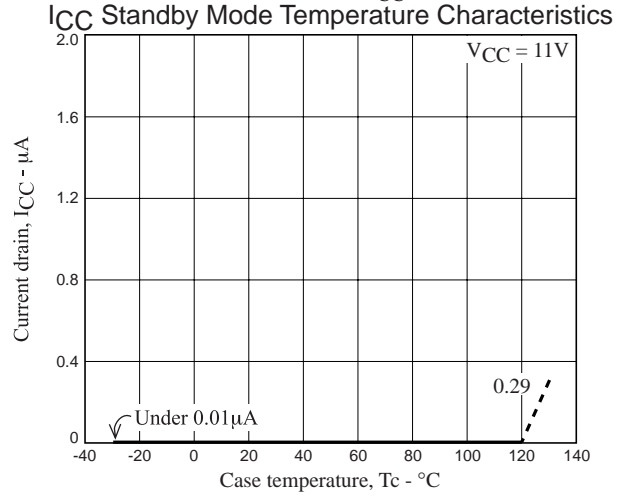
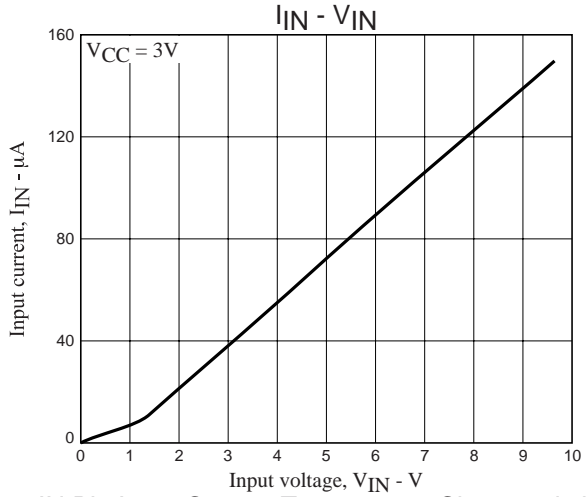
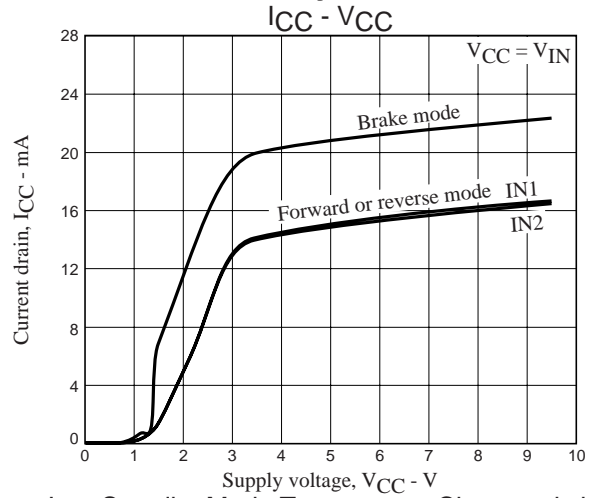
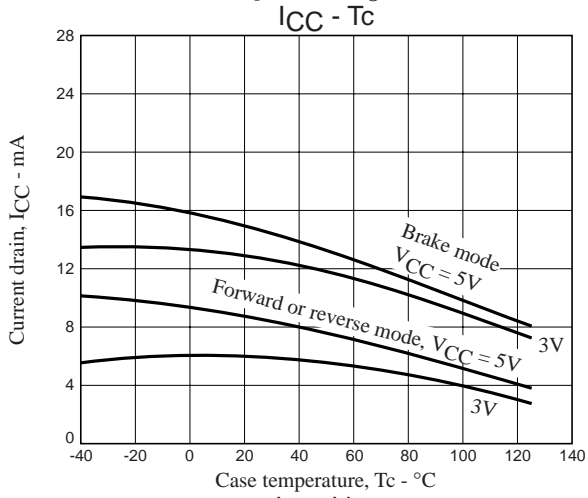
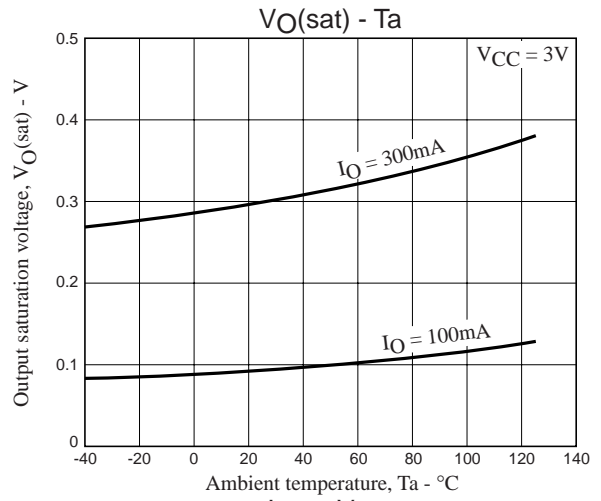
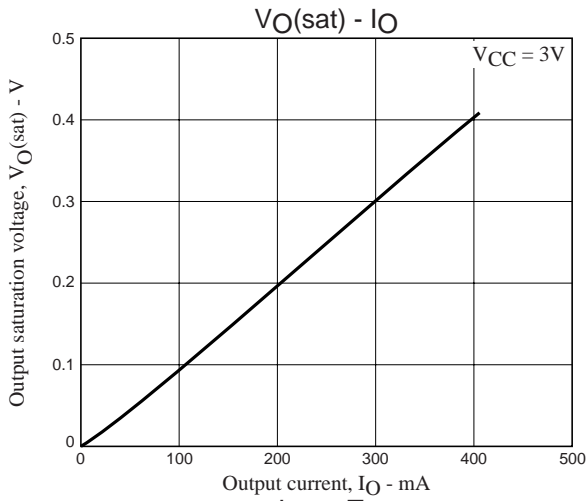
Sample Application Circuit



Cautions:

- VCC and GND lines suffer substantial fluctuation in the current quantity, causing a problem of line oscillation in certain cases. In this case, take following points into account:
 - (1) Use a thick and short wiring to reduce the wiring inductance.
 - (2) Insert a capacitor with satisfactory frequency characteristics near IC.
 - (3) Connect S-GND to the control system GND on the CPU side and P-GND to the power system GND.

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- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



Как с нами связаться

Телефон: 8 (812) 309 58 32 (многоканальный)

Факс: 8 (812) 320-02-42

Электронная почта: org@eplast1.ru

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.