



SANYO Semiconductors

DATA SHEET

LB1938FA — Monolithic Digital IC

1ch, Low-saturation Forward/Reverse Motor Driver

Overview

The LB1938FA is an H-bridge motor driver that supports low-voltage drive and features low-saturation outputs in an ultraminiature slim package. The LB1938FA provides forward, reverse, brake, and standby modes controlled by two input signals, and is an optimal DC motor driver for notebook personal computers, digital cameras, cell phones, and other portable equipment.

Features

- Ultraminiature Micro8 package
- The low saturation voltage means that the voltage applied to the motor is higher and IC heat generation is reduced. This allows this IC to be used in environments with higher ambient operating temperatures.
Output saturation voltage (high side + low side): $V_{OSat} = 0.15V$ typical ($I_O = 100mA$)
- The wide usable voltage range and the low standby mode current drain of $0.1 \mu A$ make this IC optimal for battery operated equipment.
- There are no constraints on the relationship between the input signal voltage and the supply voltage. For example, this IC can be use at $V_{CC} = 3V$ and $V_{IN} = 5V$.
- Thermal protection circuit limits the drive current and prevents the IC from causing a fire or being destroyed if the IC chip temperature reaches or exceeds $180^\circ C$ due to large currents flowing when the outputs are shorted due to, for example, motor layer shorting or other phenomena.

Specifications

Absolute Maximum Ratings at $T_a = 25^\circ C$

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V_{CC} max		10.5	V
Output current	I_{OUT} max		800	mA
Output voltage	V_{OUT} max		$V_{CC} + V_{SF}$	V
Input applied voltage	V_{IH} max		10	V

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LB1938FA

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Parameter	Symbol	Conditions	Ratings	Unit
Allowable power dissipation	Pd max	Mounted on a specified board *	400	mW
Operating temperature range	Topr		-30 to +85	°C
Storage temperature range	Tstg		-55 to +150	°C

Note *: Mounted on a specified board: 114.3mm×76.1mm×1.5mm, glass epoxy resin, wiring density 20%

Caution 1) Absolute maximum ratings represent the value which cannot be exceeded for any length of time.

Caution 2) Even when the device is used within the range of absolute maximum ratings, as a result of continuous usage under high temperature, high current, high voltage, or drastic temperature change, the reliability of the IC may be degraded. Please contact us for the further details.

Allowable Operating Range at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V _{CC}		2.2 to 10	V
Input high-level voltage	V _{IH}		2.0 to 9.5	V
Input low-level voltage	V _{IL}		-0.3 to +0.3	V

Electrical Characteristics at Ta = 25°C, V_{CC} = 3V

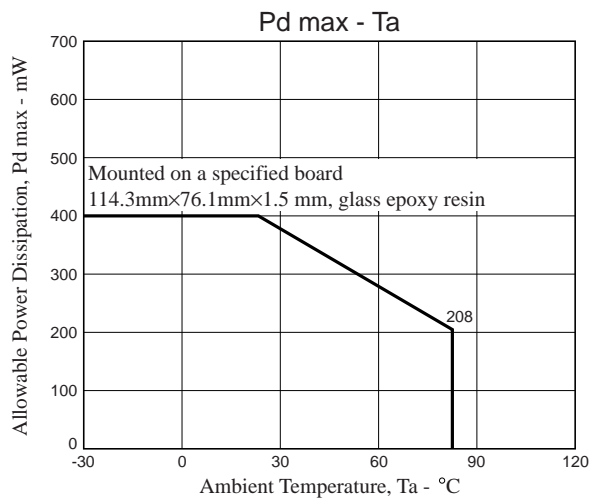
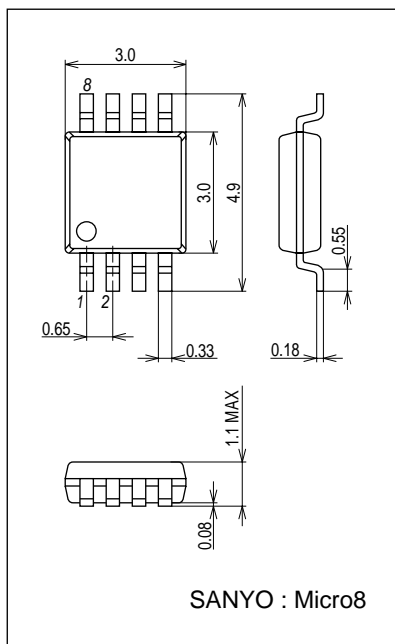
Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
Circuit current	I _{CC1}	Standby		0.1	5	μA
	I _{CC2}	Forward/reverse drive		14	19	mA
	I _{CC3}	Brake		20	29	mA
Output saturation voltage	V _{OSat1}	Upper+lower I _O = 100mA for forward/reverse rotation		0.15	0.2	V
	V _{OSat2}	Upper+lower I _O = 300mA for forward/reverse rotation		0.35	0.5	V
	V _{OSat3}	Upper I _O = 100mA for braking		0.1	0.15	V
Spark killer diode forward voltage	V _{SF}	I _O = 300mA		0.9	1.7	V
Spark killer diode inverse current	I _{RS}	V _{OUT} = 10V		0.1	5	μA
Input current	I _{IN}	V _{IN} = 5V		75	98	μA
Thermal protection operating temperature	TSD	Design target value *		180		°C

Note *: Design target value: Measurement with a single unit not made.

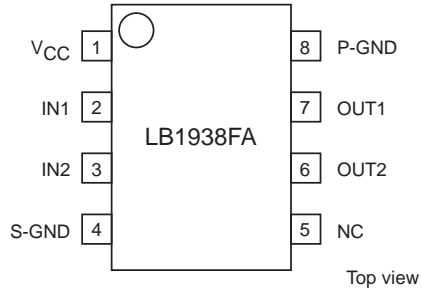
Package Dimensions

unit : mm (typ)

3427



Pin Assignment



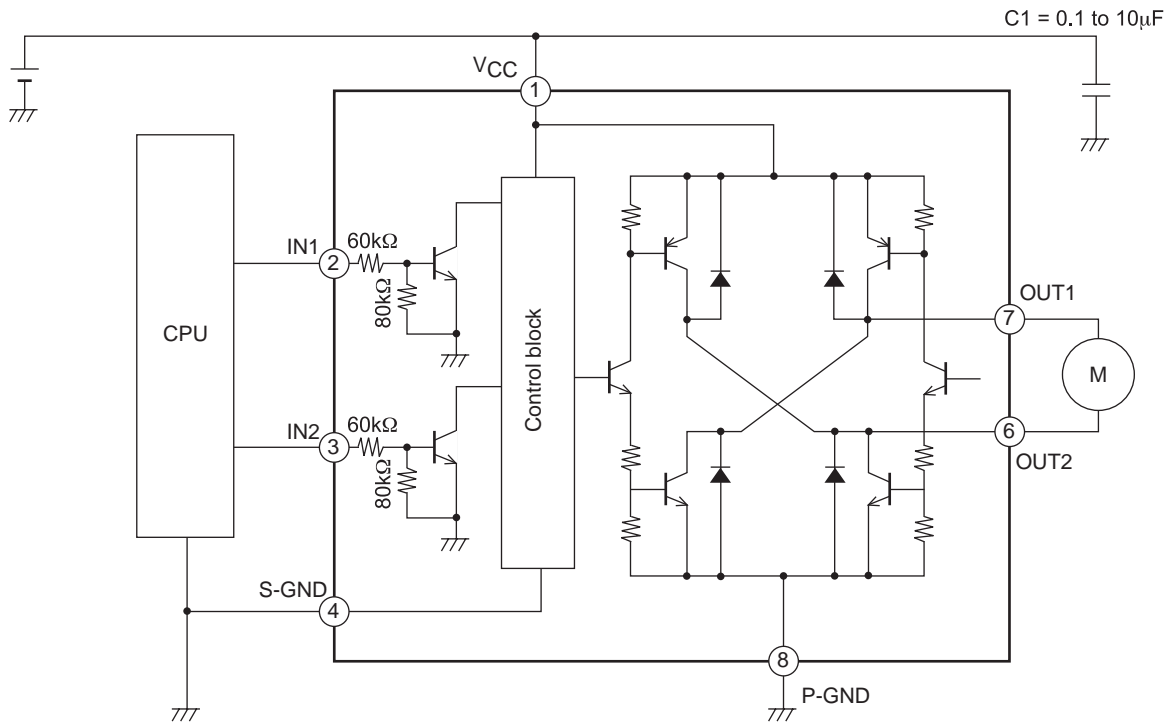
S-GND: GND for the control system

P-GND: GND for the power system

Truth Table

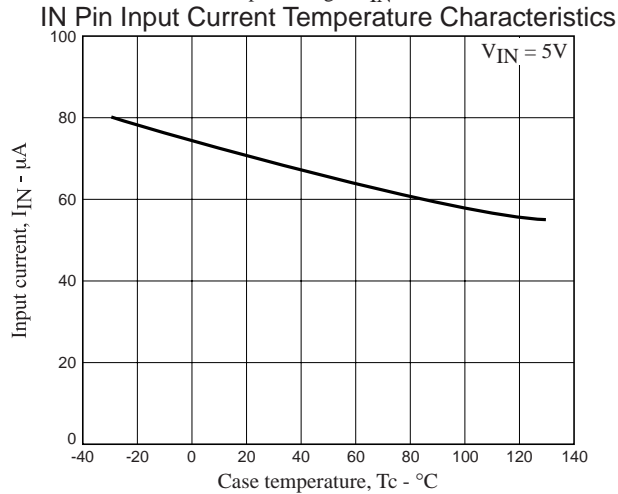
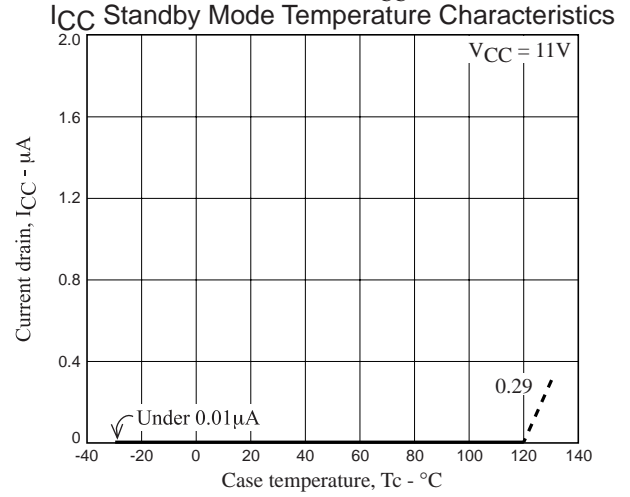
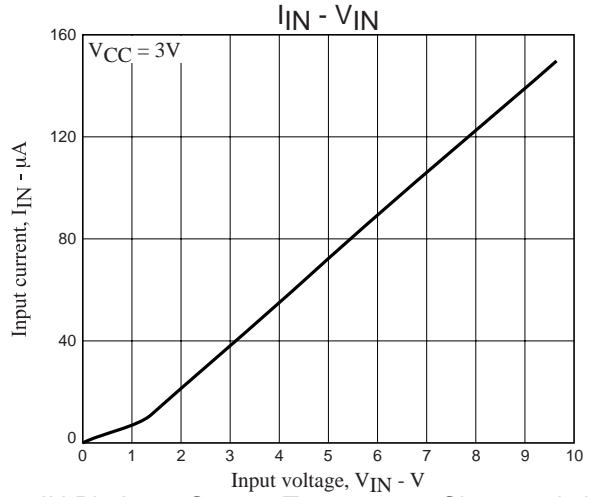
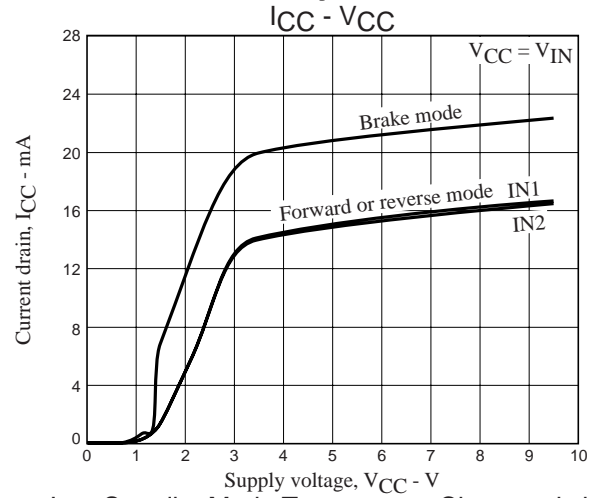
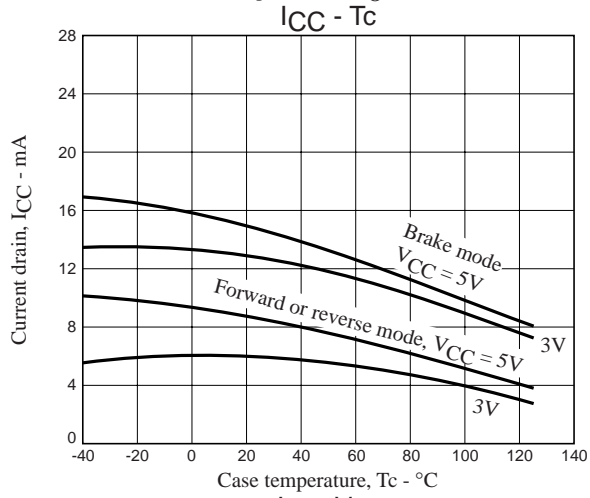
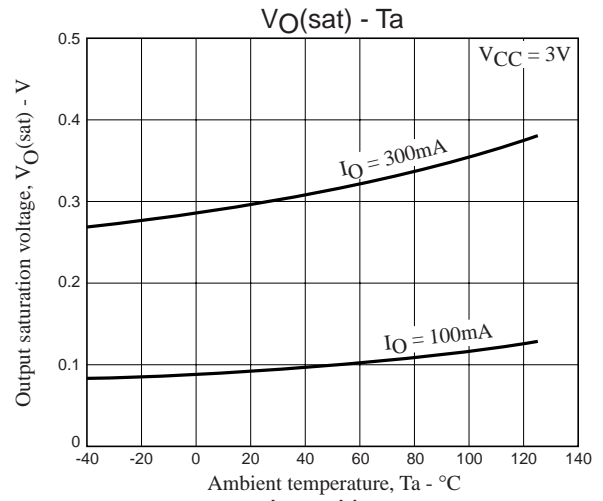
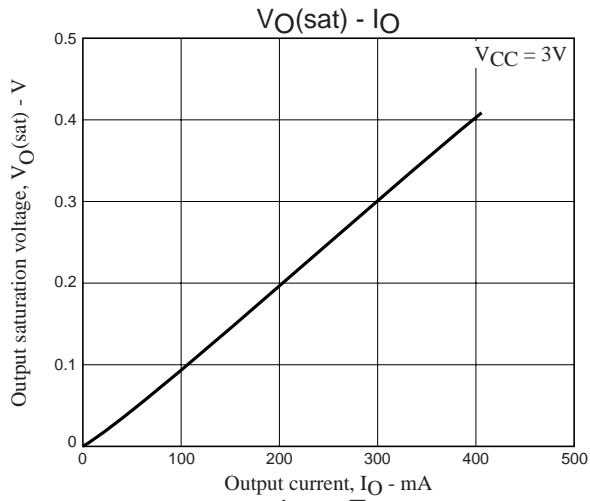
IN1	IN2	OUT1	OUT2	Mode
L	L	OFF	OFF	Standby
H	L	H	L	Forward rotation
L	H	L	H	Reverse rotation
H	H	H	H	Brake

Sample Application Circuit



Cautions:

- V_{CC} and GND lines suffer substantial fluctuation in the current quantity, causing a problem of line oscillation in certain cases. In this case, take following points into account:
 - (1) Use a thick and short wiring to reduce the wiring inductance.
 - (2) Insert a capacitor with satisfactory frequency characteristics near IC.
 - (3) Connect S-GND to the control system GND on the CPU side and P-GND to the power system GND.



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- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



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