

# 74HC191

## Presettable synchronous 4-bit binary up/down counter

Rev. 5 — 13 August 2019

Product data sheet

### 1. General description

The 74HC191 is an asynchronously presettable 4-bit binary up/down counter. It contains four master/slave flip-flops with internal gating and steering logic to provide asynchronous preset and synchronous count-up and count-down operation. Asynchronous parallel load capability permits the counter to be preset to any desired value. Information present on the parallel data inputs (D0 to D3) is loaded into the counter and appears on the outputs when the parallel load ( $\overline{PL}$ ) input is LOW. This operation overrides the counting function. Counting is inhibited by a HIGH level on the count enable ( $\overline{CE}$ ) input. When  $\overline{CE}$  is LOW internal state changes are initiated synchronously by the LOW-to-HIGH transition of the clock input. The up/down ( $\overline{U/D}$ ) input signal determines the direction of counting as indicated in the function table. The  $\overline{CE}$  input may go LOW when the clock is in either state, however, the LOW-to-HIGH  $\overline{CE}$  transition must occur only when the clock is HIGH. Also, the  $\overline{U/D}$  input should be changed only when either  $\overline{CE}$  or CP is HIGH. Overflow/underflow indications are provided by two types of outputs, the terminal count (TC) and ripple clock ( $\overline{RC}$ ). The TC output is normally LOW and goes HIGH when a circuit reaches zero in the count-down mode or reaches '15' in the count-up-mode. The TC output will remain HIGH until a state change occurs, either by counting or presetting, or until  $\overline{U/D}$  is changed. Do not use the TC output as a clock signal because it is subject to decoding spikes. The TC signal is used internally to enable the  $\overline{RC}$  output. When TC is HIGH and  $\overline{CE}$  is LOW, the  $\overline{RC}$  output follows the clock pulse (CP). This feature simplifies the design of multistage counters as shown in [Fig. 5](#) and [Fig. 6](#). In [Fig. 5](#), each  $\overline{RC}$  output is used as the clock input to the next higher stage. It is only necessary to inhibit the first stage to prevent counting in all stages, since a HIGH on  $\overline{CE}$  inhibits the  $\overline{RC}$  output pulse. The timing skew between state changes in the first and last stages is represented by the cumulative delay of the clock as it ripples through the preceding stages. This can be a disadvantage of this configuration in some applications. [Fig. 6](#) shows a method of causing state changes to occur simultaneously in all stages. The  $\overline{RC}$  outputs propagate the carry/borrow signals in ripple fashion and all clock inputs are driven in parallel. In this configuration the duration of the clock LOW state must be long enough to allow the negative-going edge of the carry/borrow signal to ripple through to the last stage before the clock goes HIGH. Since the  $\overline{RC}$  output of any package goes HIGH shortly after its CP input goes HIGH there is no such restriction on the HIGH-state duration of the clock. In [Fig. 7](#), the configuration shown avoids ripple delays and their associated restrictions. Combining the TC signals from all the preceding stages forms the  $\overline{CE}$  input for a given stage. An enable must be included in each carry gate in order to inhibit counting. The TC output of a given stage is not affected by its own  $\overline{CE}$  signal therefore the simple inhibit scheme of [Fig. 5](#) and [Fig. 6](#) does not apply. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of  $V_{CC}$ .

### 2. Features and benefits

- Complies with JEDEC standard no. 7A
- CMOS input levels:
- Synchronous reversible counting
- Asynchronous parallel load
- Count enable control for synchronous expansion
- Single up/down control input
- ESD protection:
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-A exceeds 200 V
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

### 3. Ordering information

Table 1. Ordering information

Type number	Package			Version
	Temperature range	Name	Description	
74HC191D	-40 °C to +125 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1
74HC191DB	-40 °C to +125 °C	SSOP16	plastic shrink small outline package; 16 leads; body width 5.3 mm	SOT338-1
74HC191PW	-40 °C to +125 °C	TSSOP16	plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1

### 4. Functional diagram

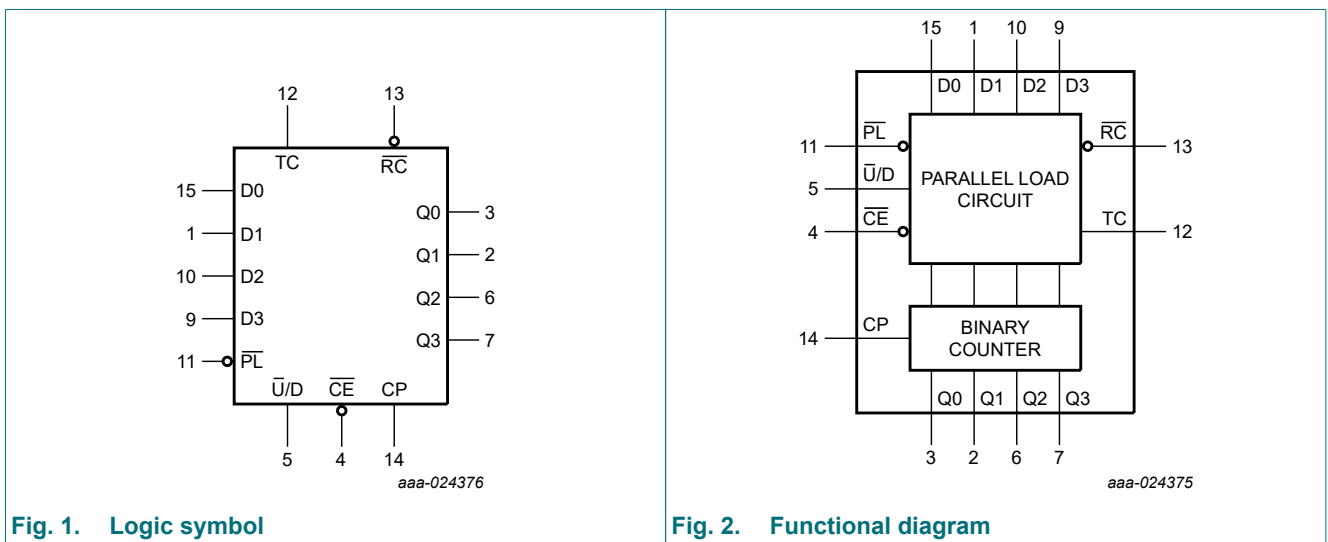


Fig. 1. Logic symbol

Fig. 2. Functional diagram

### 5. Pinning information

#### 5.1. Pinning

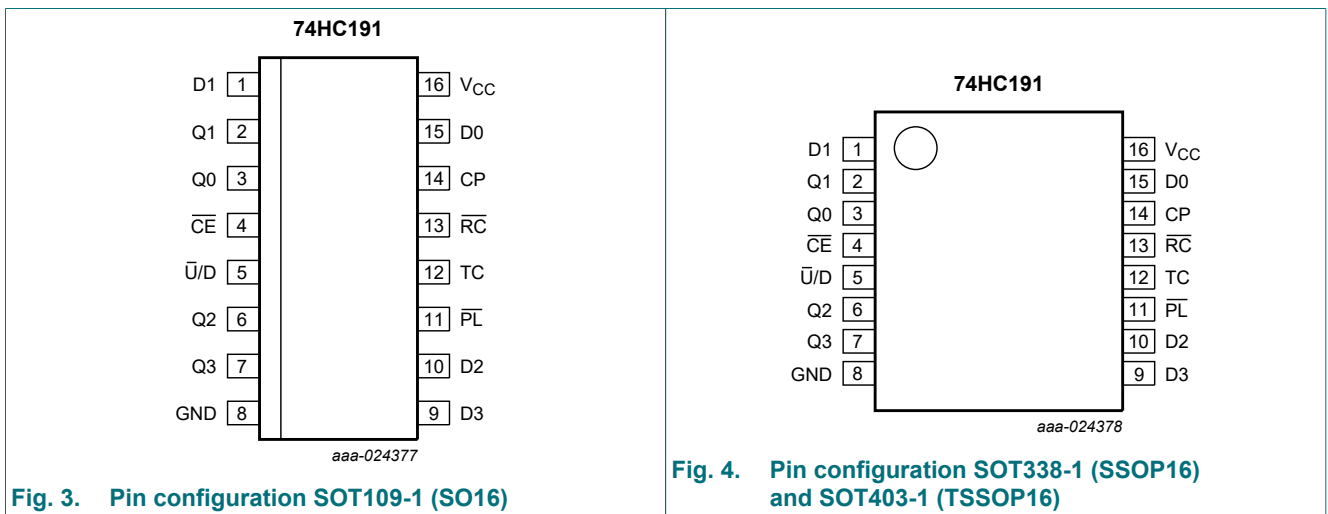


Fig. 3. Pin configuration SOT109-1 (SO16)

Fig. 4. Pin configuration SOT338-1 (SSOP16) and SOT403-1 (TSSOP16)

## 5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
D0, D1, D2, D3	15, 1, 10, 9	data input
Q0, Q1, Q2, Q3	3, 2, 6, 7	flip-flop output
$\overline{\text{CE}}$	4	count enable input (active LOW)
$\overline{\text{U/D}}$	5	up/down input
GND	8	ground (0 V)
$\overline{\text{PL}}$	11	parallel load input (active LOW)
TC	12	terminal count output
$\overline{\text{RC}}$	13	ripple clock output (active LOW)
CP	14	clock input (LOW-to-HIGH, edge-triggered)
V <sub>CC</sub>	16	supply voltage

## 6. Functional description

Table 3. Function table

H = HIGH voltage level; L = LOW voltage level;

I = LOW voltage level one set-up time prior to the LOW-to-HIGH clock transition; X = don't care;







↑ = LOW-to-HIGH clock transition

Operating mode	Input					Output
	PL	$\overline{\text{U/D}}$	$\overline{\text{CE}}$	CP	Dn	Qn
parallel load	L	X	X	X	L	L
	L	X	X	X	H	H
count up	H	L	I	↑	X	count up
count down	H	H	I	↑	X	count down
Hold (do nothing)	H	X	H	X	X	no change

Table 4. TC and  $\overline{\text{RC}}$  Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care;  = one LOW level pulse;

 = TC goes LOW on a LOW-to-HIGH clock transition.

Input			Terminal count state				Output	
$\overline{\text{U/D}}$	$\overline{\text{CE}}$	CP	Q0	Q1	Q2	Q3	TC	$\overline{\text{RC}}$
H	H	X	H	H	H	H	L	H
L	H	X	H	H	H	H	H	H
L	L		H	H	H	H		
L	H	X	L	L	L	L	L	H
H	H	X	L	L	L	L	H	H
H	L		L	L	L	L		

Presettable synchronous 4-bit binary up/down counter

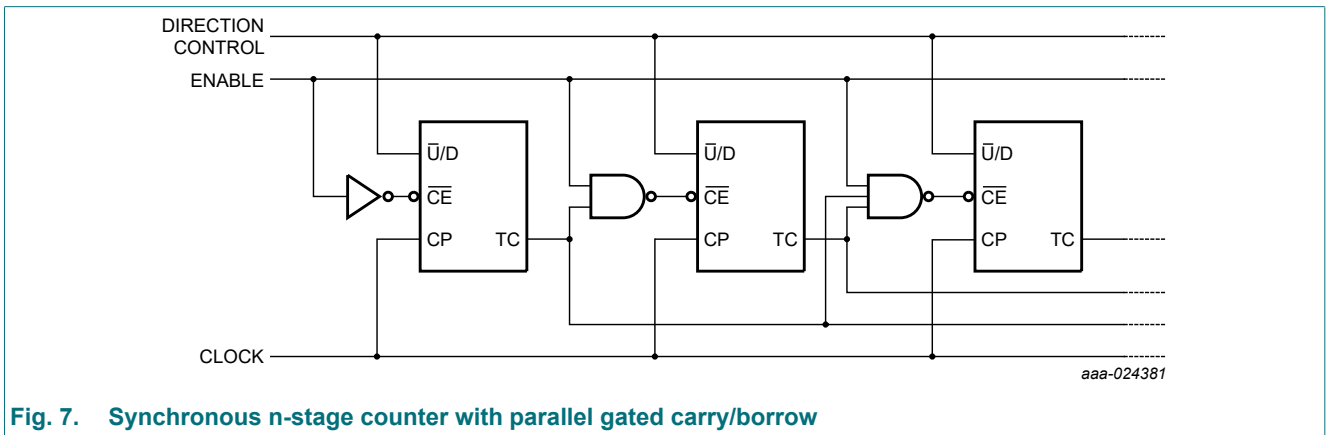
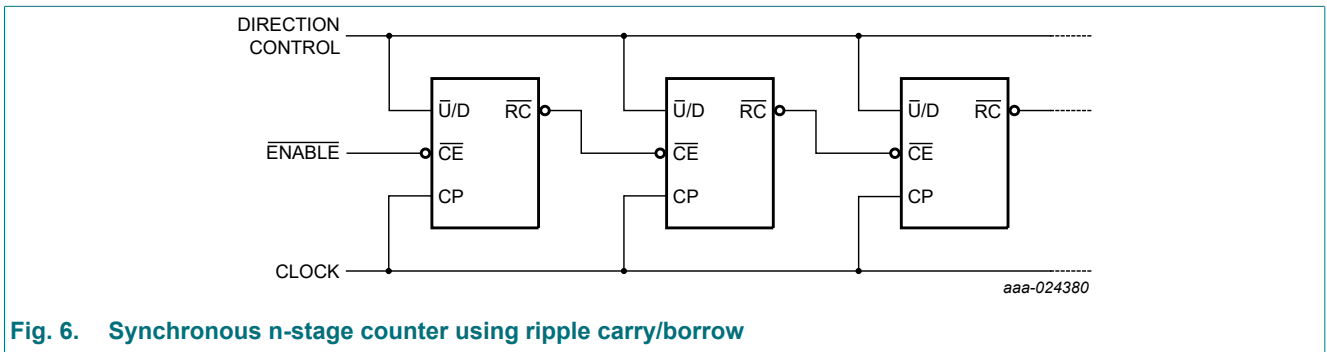




Fig. 8. Logic diagram



## 7. Limiting values

**Table 5. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC}$	supply voltage		-0.5	+7.0	V
$I_{IK}$	input clamping current	$V_I < -0.5\text{ V}$ or $V_I > V_{CC} + 0.5\text{ V}$	-	$\pm 20$	mA
$I_{OK}$	output clamping current	$V_O < -0.5\text{ V}$ or $V_O > V_{CC} + 0.5\text{ V}$	-	$\pm 20$	mA
$I_O$	output current	$V_O = -0.5\text{ V}$ to $V_{CC} + 0.5\text{ V}$	-	$\pm 25$	mA
$I_{CC}$	supply current		-	50	mA
$I_{GND}$	ground current		-50	-	mA
$T_{stg}$	storage temperature		-65	+150	°C
$P_{tot}$	total power dissipation	[1]	-	500	mW

[1] For SOT109-1 (SO16) packages:  $P_{tot}$  derates linearly with 12.4 mW/K above 110 °C.  
 For SOT338-1 (SSOP16) packages:  $P_{tot}$  derates linearly with 8.5 mW/K above 91 °C.  
 For SOT403-1 (TSSOP16) packages:  $P_{tot}$  derates linearly with 8.5 mW/K above 91 °C.

## 8. Recommended operating conditions

**Table 6. Recommended operating conditions**

Voltages are referenced to GND (ground = 0 V)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{CC}$	supply voltage		2.0	5.0	6.0	V
$V_I$	input voltage		0	-	$V_{CC}$	V
$V_O$	output voltage		0	-	$V_{CC}$	V
$T_{amb}$	ambient temperature		-40	+25	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{CC} = 2.0\text{ V}$	-	-	625	ns/V
		$V_{CC} = 4.5\text{ V}$	-	1.67	139	ns/V
		$V_{CC} = 6.0\text{ V}$	-	-	83	ns/V

## 9. Static characteristics

**Table 7. Static characteristics**

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	25 °C			-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ	Max	Min	Max	Min	Max	
$V_{IH}$	HIGH-level input voltage	$V_{CC} = 2.0\text{ V}$	1.5	1.2	-	1.5	-	1.5	-	V
		$V_{CC} = 4.5\text{ V}$	3.15	2.4	-	3.15	-	3.15	-	V
		$V_{CC} = 6.0\text{ V}$	4.2	3.2	-	4.2	-	4.2	-	V
$V_{IL}$	LOW-level input voltage	$V_{CC} = 2.0\text{ V}$	-	0.8	0.5	-	0.5	-	0.5	V
		$V_{CC} = 4.5\text{ V}$	-	2.1	1.35	-	1.35	-	1.35	V
		$V_{CC} = 6.0\text{ V}$	-	2.8	1.8	-	1.8	-	1.8	V
$V_{OH}$	HIGH-level output voltage	$V_I = V_{IH}$ or $V_{IL}$								
		$I_O = -20\text{ }\mu\text{A}$ ; $V_{CC} = 2.0\text{ V}$	1.9	2.0	-	1.9	-	1.9	-	V
		$I_O = -20\text{ }\mu\text{A}$ ; $V_{CC} = 4.5\text{ V}$	4.4	4.5	-	4.4	-	4.4	-	V
		$I_O = -20\text{ }\mu\text{A}$ ; $V_{CC} = 6.0\text{ V}$	5.9	6.0	-	5.9	-	5.9	-	V
		$I_O = -4.0$ ; $V_{CC} = 4.5\text{ V}$	3.98	4.32	-	3.84	-	3.7	-	V
		$I_O = -5.2$ ; $V_{CC} = 6.0\text{ V}$	5.48	5.81	-	5.34	-	5.2	-	V
$V_{OL}$	LOW-level output voltage	$V_I = V_{IH}$ or $V_{IL}$								
		$I_O = 20\text{ }\mu\text{A}$ ; $V_{CC} = 2.0\text{ V}$	-	0	0.1	-	0.1	-	0.1	V
		$I_O = 20\text{ }\mu\text{A}$ ; $V_{CC} = 4.5\text{ V}$	-	0	0.1	-	0.1	-	0.1	V
		$I_O = 20\text{ }\mu\text{A}$ ; $V_{CC} = 6.0\text{ V}$	-	0	0.1	-	0.1	-	0.1	V
		$I_O = 4.0\text{ mA}$ ; $V_{CC} = 4.5\text{ V}$	-	0.15	0.26	-	0.33	-	0.4	V
		$I_O = 5.2\text{ mA}$ ; $V_{CC} = 6.0\text{ V}$	-	0.16	0.26	-	0.33	-	0.4	V
$I_I$	input leakage current	$V_I = V_{CC}$ or GND; $V_{CC} = 6.0\text{ V}$	-	-	$\pm 0.1$	-	$\pm 1.0$	-	$\pm 1.0$	$\mu\text{A}$
$I_{CC}$	supply current	$V_I = V_{CC}$ or GND; $I_O = 0\text{ A}$ ; $V_{CC} = 6.0\text{ V}$	-	-	8.0	-	80.0	-	160.0	$\mu\text{A}$
$C_I$	input capacitance		-	3.5	-	-	-	-	-	pF

## 10. Dynamic characteristics

**Table 8. Dynamic characteristics**

Voltages are referenced to GND (ground = 0 V);  $C_L = 50$  pF unless otherwise specified; for test circuit see Fig. 18.

Symbol	Parameter	Conditions	25 °C			-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ	Max	Min	Max	Min	Max	
$t_{pd}$	propagation delay	CP to Qn; see Fig. 10 [1]								
		$V_{CC} = 2.0$ V	-	72	220	-	275	-	330	ns
		$V_{CC} = 4.5$ V	-	26	44	-	55	-	66	ns
		$V_{CC} = 5.0$ V; $C_L = 15$ pF	-	22	-	-	-	-	-	ns
		$V_{CC} = 6.0$ V	-	21	37	-	47	-	56	ns
		CP to TC; see Fig. 10								
		$V_{CC} = 2.0$ V	-	83	255	-	320	-	395	ns
		$V_{CC} = 4.5$ V	-	30	51	-	64	-	77	ns
		$V_{CC} = 6.0$ V	-	24	43	-	54	-	65	ns
		CP to $\overline{RC}$ ; see Fig. 11								
		$V_{CC} = 2.0$ V	-	47	150	-	190	-	225	ns
		$V_{CC} = 4.5$ V	-	17	30	-	38	-	45	ns
		$V_{CC} = 6.0$ V	-	14	26	-	33	-	38	ns
		$\overline{CE}$ to $\overline{RC}$ ; see Fig. 11								
		$V_{CC} = 2.0$ V	-	33	130	-	165	-	195	ns
		$V_{CC} = 4.5$ V	-	12	26	-	33	-	39	ns
		$V_{CC} = 6.0$ V	-	10	22	-	28	-	33	ns
		Dn to Qn; see Fig. 12								
		$V_{CC} = 2.0$ V	-	61	220	-	275	-	330	ns
		$V_{CC} = 4.5$ V	-	22	44	-	55	-	66	ns
		$V_{CC} = 6.0$ V	-	18	37	-	47	-	56	ns
		$\overline{PL}$ to Qn; see Fig. 13								
		$V_{CC} = 2.0$ V	-	61	220	-	275	-	330	ns
		$V_{CC} = 4.5$ V	-	22	44	-	55	-	66	ns
		$V_{CC} = 6.0$ V	-	18	37	-	47	-	56	ns
		$\overline{U/D}$ to TC; see Fig. 14								
		$V_{CC} = 2.0$ V	-	44	190	-	240	-	285	ns
$V_{CC} = 4.5$ V	-	16	38	-	48	-	57	ns		
$V_{CC} = 6.0$ V	-	13	32	-	41	-	48	ns		
$\overline{U/D}$ to $\overline{RC}$ ; see Fig. 14										
$V_{CC} = 2.0$ V	-	50	210	-	265	-	315	ns		
$V_{CC} = 4.5$ V	-	18	42	-	53	-	63	ns		
$V_{CC} = 6.0$ V	-	14	36	-	45	-	54	ns		
$t_t$	transition time	see Fig. 15 [2]								
		$V_{CC} = 2.0$ V	-	19	75	-	95	-	110	ns
		$V_{CC} = 4.5$ V	-	7	15	-	19	-	22	ns
		$V_{CC} = 6.0$ V	-	6	13	-	16	-	19	ns



## Presettable synchronous 4-bit binary up/down counter

Symbol	Parameter	Conditions	25 °C			-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ	Max	Min	Max	Min	Max	
t <sub>w</sub>	pulse width	CP; HIGH or LOW; see Fig. 10								
		V <sub>CC</sub> = 2.0 V	125	28	-	155	-	195	-	ns
		V <sub>CC</sub> = 4.5 V	25	10	-	31	-	39	-	ns
		V <sub>CC</sub> = 6.0 V	21	8	-	26	-	33	-	ns
		PL; LOW; see Fig. 15								
		V <sub>CC</sub> = 2.0 V	100	22	-	125	-	150	-	ns
		V <sub>CC</sub> = 4.5 V	20	8	-	25	-	30	-	ns
V <sub>CC</sub> = 6.0 V	17	6	-	21	-	26	-	ns		
t <sub>rec</sub>	recovery time	PL to CP; see Fig. 15								
		V <sub>CC</sub> = 2.0 V	35	8	-	45	-	55	-	ns
		V <sub>CC</sub> = 4.5 V	7	3	-	9	-	11	-	ns
		V <sub>CC</sub> = 6.0 V	6	2	-	8	-	9	-	ns
t <sub>su</sub>	set-up time	U/D to CP; see Fig. 16								
		V <sub>CC</sub> = 2.0 V	205	50	-	255	-	310	-	ns
		V <sub>CC</sub> = 4.5 V	41	18	-	51	-	62	-	ns
		V <sub>CC</sub> = 6.0 V	35	14	-	43	-	53	-	ns
		Dn to PL; see Fig. 17								
		V <sub>CC</sub> = 2.0 V	100	19	-	125	-	150	-	ns
		V <sub>CC</sub> = 4.5 V	20	7	-	25	-	30	-	ns
		V <sub>CC</sub> = 6.0 V	17	6	-	21	-	26	-	ns
		CE to CP; see Fig. 16								
		V <sub>CC</sub> = 2.0 V	140	44	-	175	-	210	-	ns
		V <sub>CC</sub> = 4.5 V	28	16	-	35	-	42	-	ns
		V <sub>CC</sub> = 6.0 V	24	13	-	30	-	36	-	ns
t <sub>h</sub>	hold time	U/D to CP; see Fig. 16								
		V <sub>CC</sub> = 2.0 V	0	-39	-	0	-	0	-	ns
		V <sub>CC</sub> = 4.5 V	0	-14	-	0	-	0	-	ns
		V <sub>CC</sub> = 6.0 V	0	-11	-	0	-	0	-	ns
		Dn to PL; see Fig. 17								
		V <sub>CC</sub> = 2.0 V	0	-11	-	0	-	0	-	ns
		V <sub>CC</sub> = 4.5 V	0	-4	-	0	-	0	-	ns
		V <sub>CC</sub> = 6.0 V	0	-3	-	0	-	0	-	ns
		CE to CP; see Fig. 16								
		V <sub>CC</sub> = 2.0 V	0	-28	-	0	-	0	-	ns
		V <sub>CC</sub> = 4.5 V	0	-10	-	0	-	0	-	ns
		V <sub>CC</sub> = 6.0 V	0	-8	-	0	-	0	-	ns
f <sub>max</sub>	maximum frequency	CP; see Fig. 10								
		V <sub>CC</sub> = 2.0 V	4.0	11	-	3.2	-	2.6	-	MHz
		V <sub>CC</sub> = 4.5 V	20	33	-	16	-	13	-	MHz
		V <sub>CC</sub> = 5.0 V; C <sub>L</sub> = 15 pF	-	36	-	-	-	-	-	MHz
		V <sub>CC</sub> = 6.0 V	24	39	-	19	-	15	-	MHz

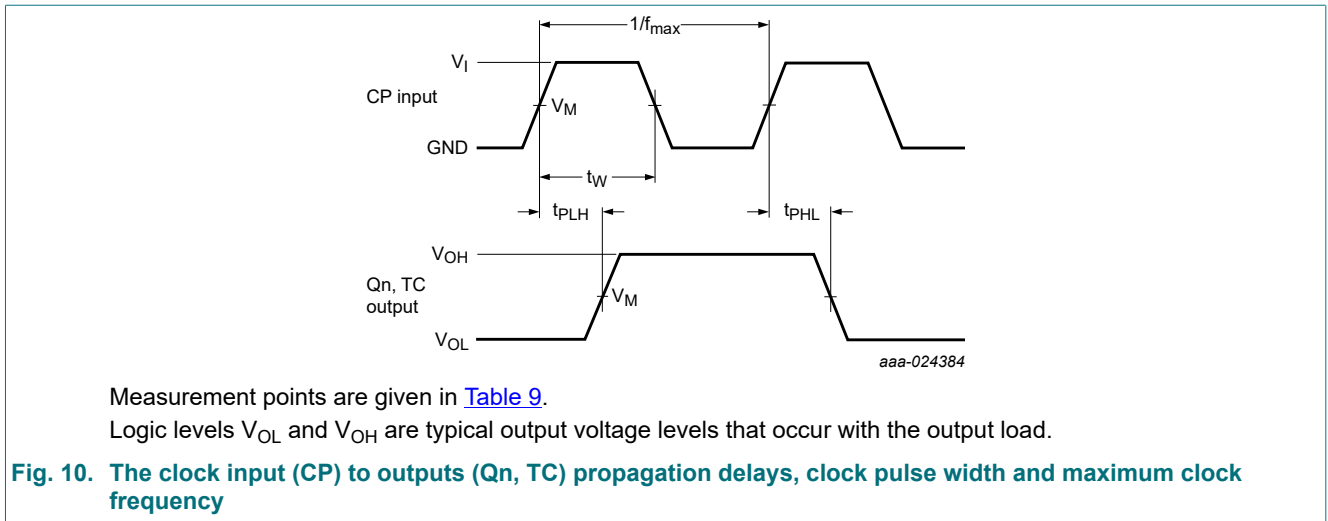
Presetable synchronous 4-bit binary up/down counter

Symbol	Parameter	Conditions	25 °C			-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ	Max	Min	Max	Min	Max	
C <sub>PD</sub>	power dissipation capacitance	V <sub>I</sub> = GND to V <sub>CC</sub> ; V <sub>CC</sub> = 5 V; f <sub>i</sub> = 1 MHz [3]	-	31	-	-	-	-	-	pF

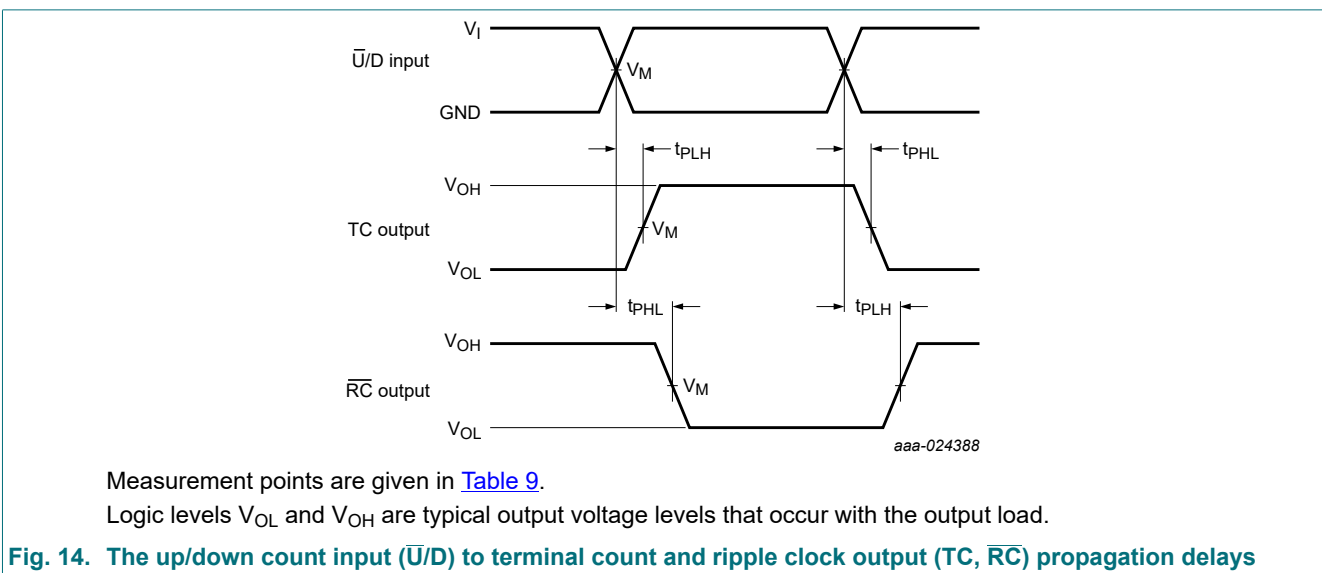
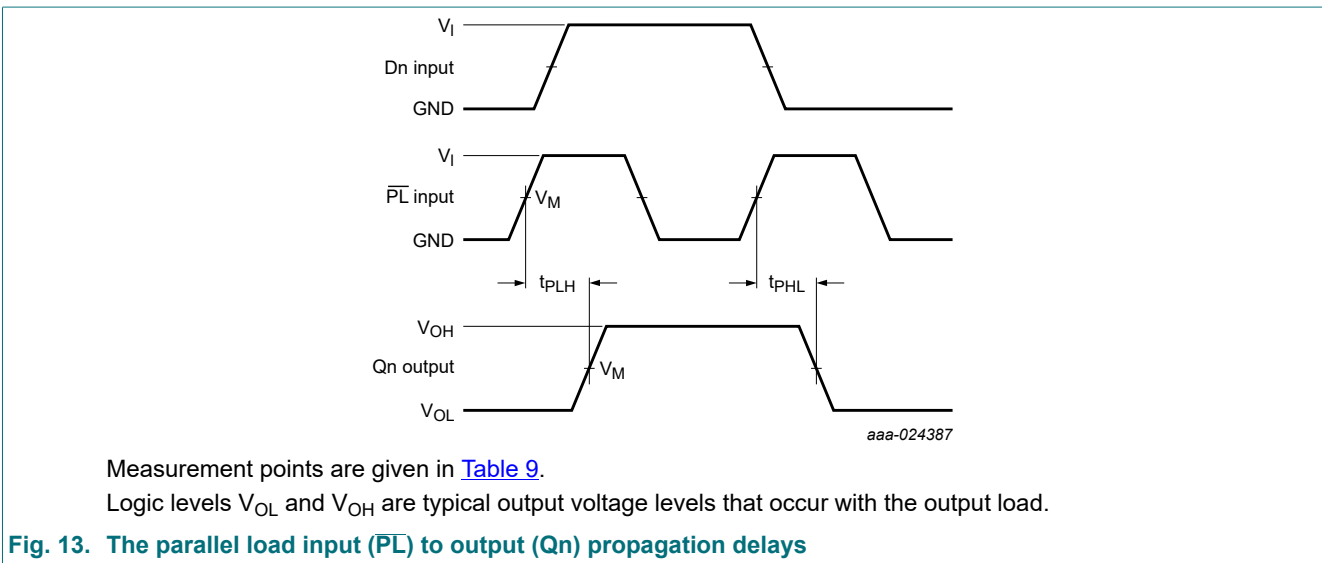
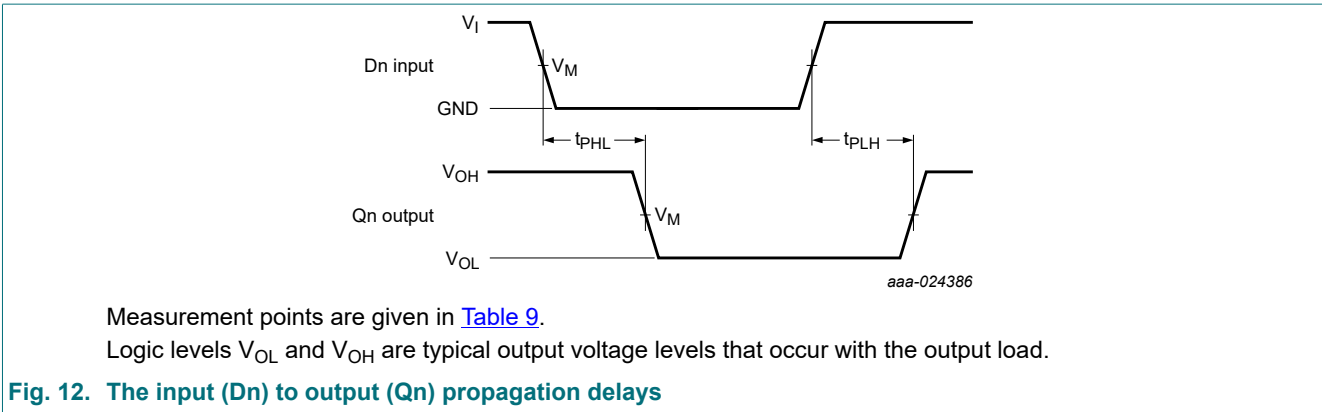
- [1] t<sub>pd</sub> is the same as t<sub>PHL</sub> and t<sub>PLH</sub>.
- [2] t<sub>i</sub> is the same as t<sub>THL</sub> and t<sub>TLH</sub>.
- [3] C<sub>PD</sub> is used to determine the dynamic power dissipation (P<sub>D</sub> in μW):  

$$P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \sum(C_L \times V_{CC}^2 \times f_o)$$
 where:  
 f<sub>i</sub> = input frequency in MHz;  
 f<sub>o</sub> = output frequency in MHz;  
 C<sub>L</sub> = output load capacitance in pF;  
 V<sub>CC</sub> = supply voltage in V;  
 N = number of inputs switching;  
 ∑(C<sub>L</sub> × V<sub>CC</sub><sup>2</sup> × f<sub>o</sub>) = sum of outputs.

10.1. Waveforms and test circuit



Presettable synchronous 4-bit binary up/down counter

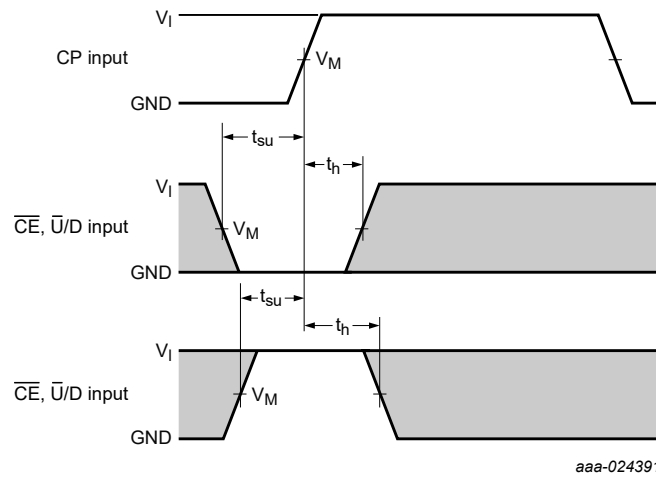




Measurement points are given in [Table 9](#).

Logic levels  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

**Fig. 15. The parallel load input ( $\overline{PL}$ ) to clock ( $CP$ ) recovery times, parallel load pulse width and output ( $Qn$ ) transition times**

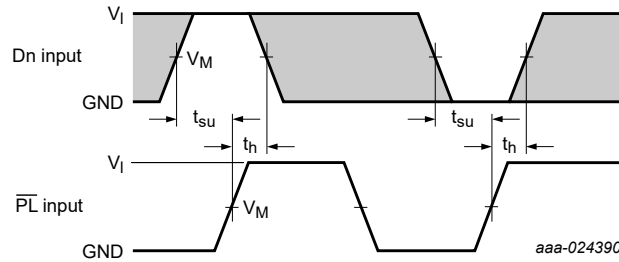


Measurement points are given in [Table 9](#).

The shaded areas indicate when the input is permitted to change for predictable output performance.

**Fig. 16. The count enable and up/down count inputs ( $\overline{CE}$ ,  $\overline{U/D}$ ) to clock input ( $CP$ ) set-up and hold times**

Presettable synchronous 4-bit binary up/down counter

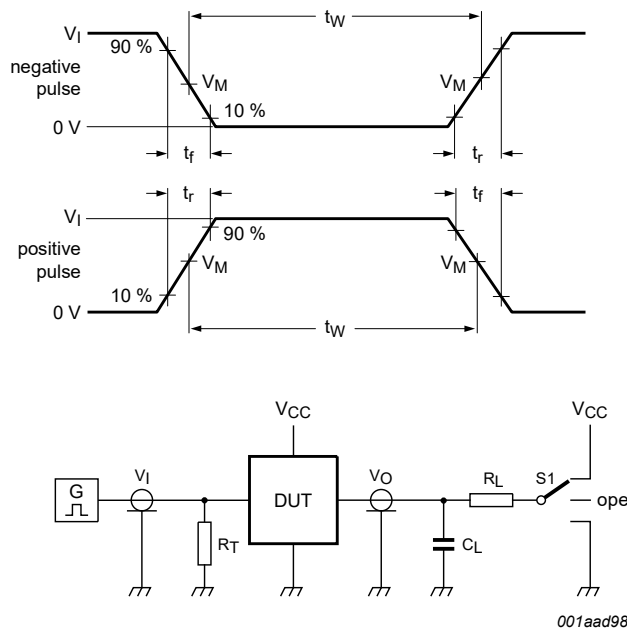


Measurement points are given in [Table 9](#).  
The shaded areas indicate when the input is permitted to change for predictable output performance.

**Fig. 17. The parallel load input (PL) to data input (Dn) set-up and hold times**

**Table 9. Measurement points**

Input		Output
$V_M$	$V_I$	$V_M$
$0.5 \times V_{CC}$	GND to $V_{CC}$	$0.5 \times V_{CC}$



Test data is given in [Table 10](#).  
Test circuit definitions:  
 $R_T$  = Termination resistance should be equal to output impedance  $Z_o$  of the pulse generator  
 $C_L$  = Load capacitance including jig and probe capacitance  
 $R_L$  = Load resistance.  
 $S1$  = Test selection switch

**Fig. 18. Test circuit for measuring switching times**

**Table 10. Test data**

Input		Load		S1 position
$V_I$	$t_r, t_f$	$C_L$	$R_L$	$t_{PHL}, t_{PLH}$
$V_{CC}$	6 ns	15 pF, 50 pF	1 kΩ	open

### 11. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



**DIMENSIONS** (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(1)</sup>	e	H <sub>E</sub>	L	L <sub>p</sub>	Q	v	w	y	Z <sup>(1)</sup>	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	10.0 9.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8° 0°
inches	0.069	0.010 0.004	0.057 0.049	0.01	0.019 0.014	0.0100 0.0075	0.39 0.38	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.020	0.01	0.01	0.004	0.028 0.012	

**Note**

1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT109-1	076E07	MS-012				99-12-27 03-02-19

**Fig. 19. Package outline SOT109-1 (SO16)**

SSOP16: plastic shrink small outline package; 16 leads; body width 5.3 mm

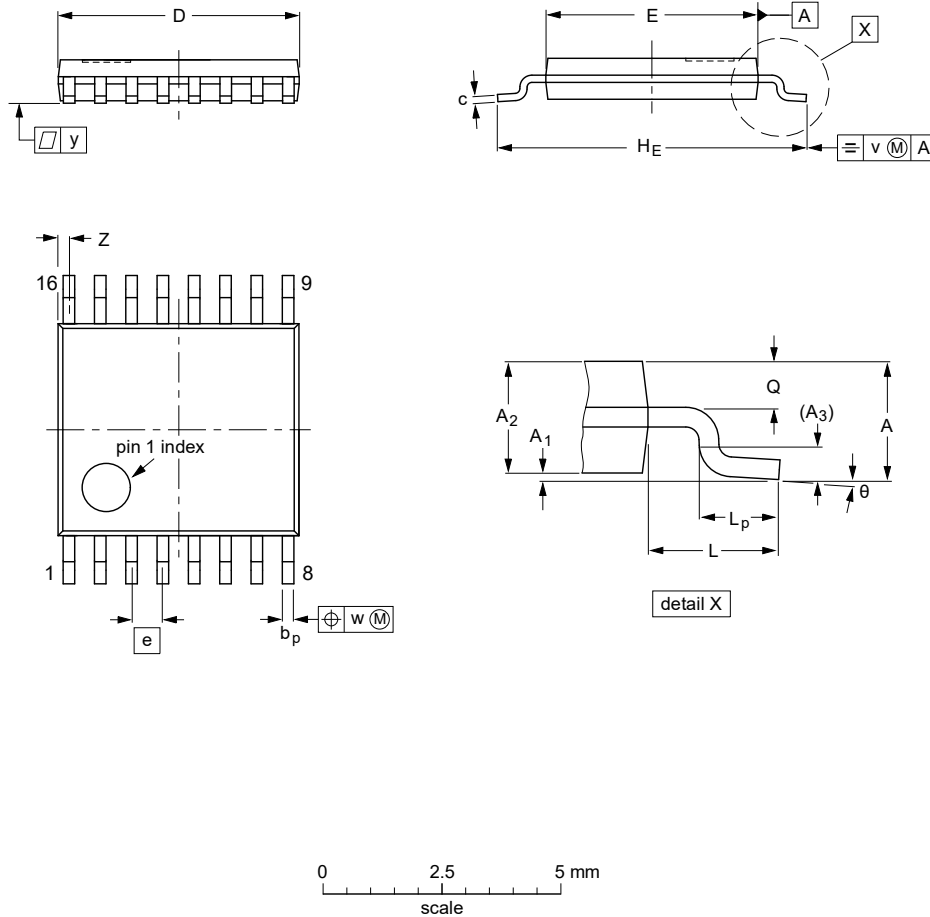
SOT338-1



Fig. 20. Package outline SOT338-1 (SSOP16)

TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

SOT403-1



**DIMENSIONS (mm are the original dimensions)**

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(2)</sup>	e	H <sub>E</sub>	L	L <sub>p</sub>	Q	v	w	y	z <sup>(1)</sup>	θ
mm	1.1	0.15 0.05	0.95 0.80	0.25	0.30 0.19	0.2 0.1	5.1 4.9	4.5 4.3	0.65	6.6 6.2	1	0.75 0.50	0.4 0.3	0.2	0.13	0.1	0.40 0.06	8° 0°

**Notes**

1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT403-1		MO-153				99-12-27 03-02-18

Fig. 21. Package outline SOT403-1 (TSSOP16)



## 12. Abbreviations

Table 11. Abbreviations

Acronym	Description
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

## 13. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74HC191 v.5	20190813	Product data sheet	-	74HC191 v.4
Modifications:	<ul style="list-style-type: none"> <li>Type number 74HC191DB (SOT338-1 / SSOP16) added.</li> <li><a href="#">Table 5</a>: Derating values for <math>P_{tot}</math> total power dissipation updated</li> </ul>			
74HC191 v.4	20181005	Product data sheet	-	74HC191 v.3
Modifications:	<ul style="list-style-type: none"> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li>Type number 74HC191DB (SOT338-1 / SSOP16) removed.</li> </ul>			
74HC191 v.3	20170103	Product data sheet	-	74HC_HCT191 v.2
Modifications:	<ul style="list-style-type: none"> <li>The format of this data sheet has been redesigned to comply with the new identity guidelines of NXP Semiconductors.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li>Type numbers 74HCT191D, 74HCT191DB, 74HCT191PW removed.</li> </ul>			
74HC_HCT191_CNV v.2	19901201	Product specification	-	-

## 14. Legal information

### Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
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