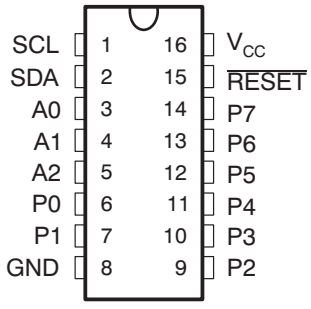
REMOTE 8-BIT I²C AND SMBus LOW-POWER I/O EXPANDER WITH RESET AND CONFIGURATION REGISTERS

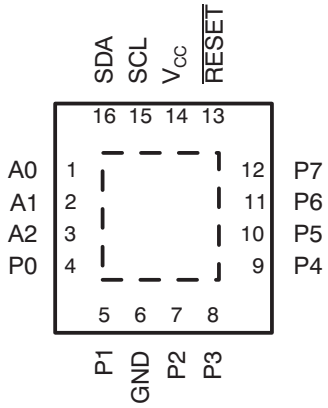
FEATURES

- Low Standby Current Consumption of 1 μA Max
- I²C to Parallel Port Expander
- Operating Power-Supply Voltage Range of 2.3 V to 5.5 V
- 5-V Tolerant I/O Ports
- 400-kHz Fast I²C Bus
- Three Hardware Address Pins Allow for Use of up to Eight Devices on I²C/SMBus
- Lower-Voltage Higher-Performance Migration Path for PCA9556
- Input/Output Configuration Register
- Polarity Inversion Register
- Active-Low Reset Input
- Internal Power-On Reset
- High-Impedance Open Drain on P0
- Power Up With All Channels Configured as Inputs
- No Glitch on Power Up
- Noise Filter on SCL/SDA Inputs
- Latched Outputs With High Current Drive Maximum Capability for Directly Driving LEDs
- Latch-Up Performance Exceeds 100 mA Per JESD 78, Class II
- ESD Protection Exceeds JESD 22
  - 2000-V Human-Body Model (A114-A)
  - 200-V Machine Model (A115-A)
  - 1000-V Charged-Device Model (C101)

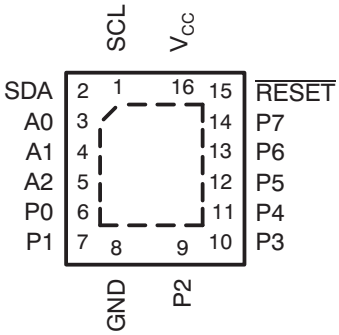
D, DB, DGV, OR PW PACKAGE
(TOP VIEW)



RGV PACKAGE
(TOP VIEW)



RGY PACKAGE
(TOP VIEW)



DESCRIPTION/ORDERING INFORMATION

This 8-bit I/O expander for the two-line bidirectional bus (I²C) is designed for 2.3-V to 5.5-V V_{CC} operation. The device provides general-purpose remote I/O expansion for most microcontroller families via the I²C interface [serial clock (SCL) and serial data (SDA)].

The PCA9557 consists of one 8-bit configuration (input or output selection), input port, output port, and polarity inversion (active-high) registers. At power on, the I/Os are configured as inputs. However, the system master can enable the I/Os as either inputs or outputs by writing to the I/O configuration bits. The data for each input or output is kept in the corresponding input or output register. The polarity of the input port register can be inverted with the polarity inversion register. All registers can be read by the system master.

The device outputs (latched) have high-current drive capability for directly driving LEDs. The device has low current consumption.

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

PRODUCTION DATA information is current as of publication date. Products conform to specifications per the terms of the Texas Instruments standard warranty. Production processing does not necessarily include testing of all parameters.

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DESCRIPTION/ORDERING INFORMATION (CONTINUED)

The system master can reset the PCA9557 in the event of a timeout or other improper operation by asserting a low in the active-low reset ($\overline{\text{RESET}}$) input. The power-on reset puts the registers in their default state and initializes the I^2C/SMBus state machine. Asserting $\overline{\text{RESET}}$ causes the same reset/initialization to occur without depowering the part.

Three hardware pins (A0, A1, and A2) are used to program and vary the fixed I^2C address, allowing up to eight devices to share the same I^2C bus or SMBus.

ORDERING INFORMATION

T_A	PACKAGE(1)(2)		ORDERABLE PART NUMBER	TOP-SIDE MARKING
–40°C to 85°C	QFN – RGV	Reel of 2000	PCA9557RGVR	PD557
	QFN – RGY	Reel of 1000	PCA9557RGYR	PD557
	SOIC – D	Reel of 2500	PCA9557DR	PCA9557
		Reel of 250	PCA9557DT	
		Tube of 40	PCA9557D	
	SSOP – DB	Reel of 2000	PCA9557DBR	PD557
		Tube of 80	PCA9557DB	
	TSSOP – PW	Reel of 2000	PCA9557PWR	PD557
		Reel of 250	PCA9557PWT	
		Tube of 90	PCA9557PW	
	TVSOP – DGV	Reel of 2000	PCA9557DGVR	PD557

(1) Package drawings, thermal data, and symbolization are available at www.ti.com/packaging.
(2) For the most current package and ordering information, see the Package Option Addendum at the end of this document, or see the TI website at www.ti.com.

TERMINAL FUNCTIONS

NO.		NAME	DESCRIPTION
QFN (RGY) SOIC (D), SSOP (DB), TSSOP (PW), AND TVSOP (DGV)	QFN (RGV)		
1	15	SCL	Serial clock bus. Connect to V_{CC} through a pullup resistor.
2	16	SDA	Serial data bus. Connect to V_{CC} through a pullup resistor.
3	1	A0	Address input. Connect directly to V_{CC} or ground.
4	2	A1	Address input. Connect directly to V_{CC} or ground.
5	3	A2	Address input. Connect directly to V_{CC} or ground.
6	4	P0	P-port input/output. High impedance open-drain design structure. Connect to V_{CC} through a pullup resistor.
7	5	P1	P-port input/output. Push-pull design structure.
8	6	GND	Ground
9	7	P2	P-port input/output. Push-pull design structure.
10	8	P3	P-port input/output. Push-pull design structure.
11	9	P4	P-port input/output. Push-pull design structure.
12	10	P5	P-port input/output. Push-pull design structure.
13	11	P6	P-port input/output. Push-pull design structure.
14	12	P7	P-port input/output. Push-pull design structure.
15	13	$\overline{\text{RESET}}$	Active-low reset input. Connect to V_{CC} through a pullup resistor if no active connection is used.
16	14	V_{CC}	Supply voltage

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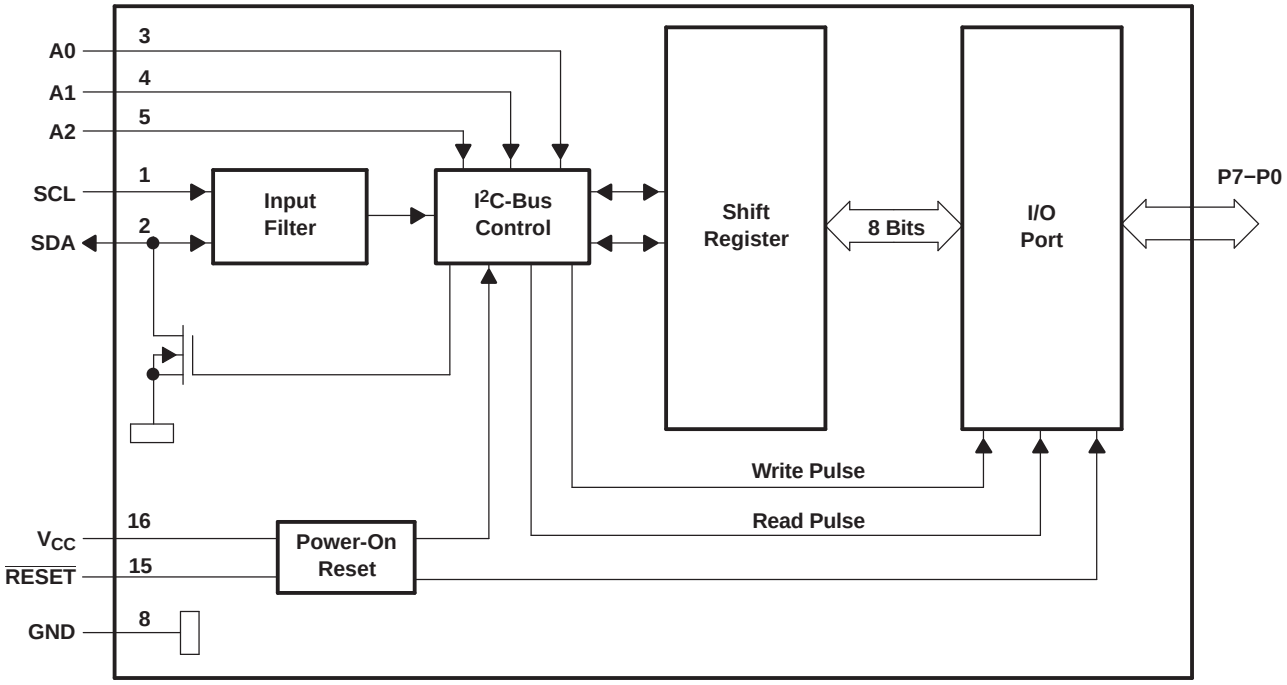
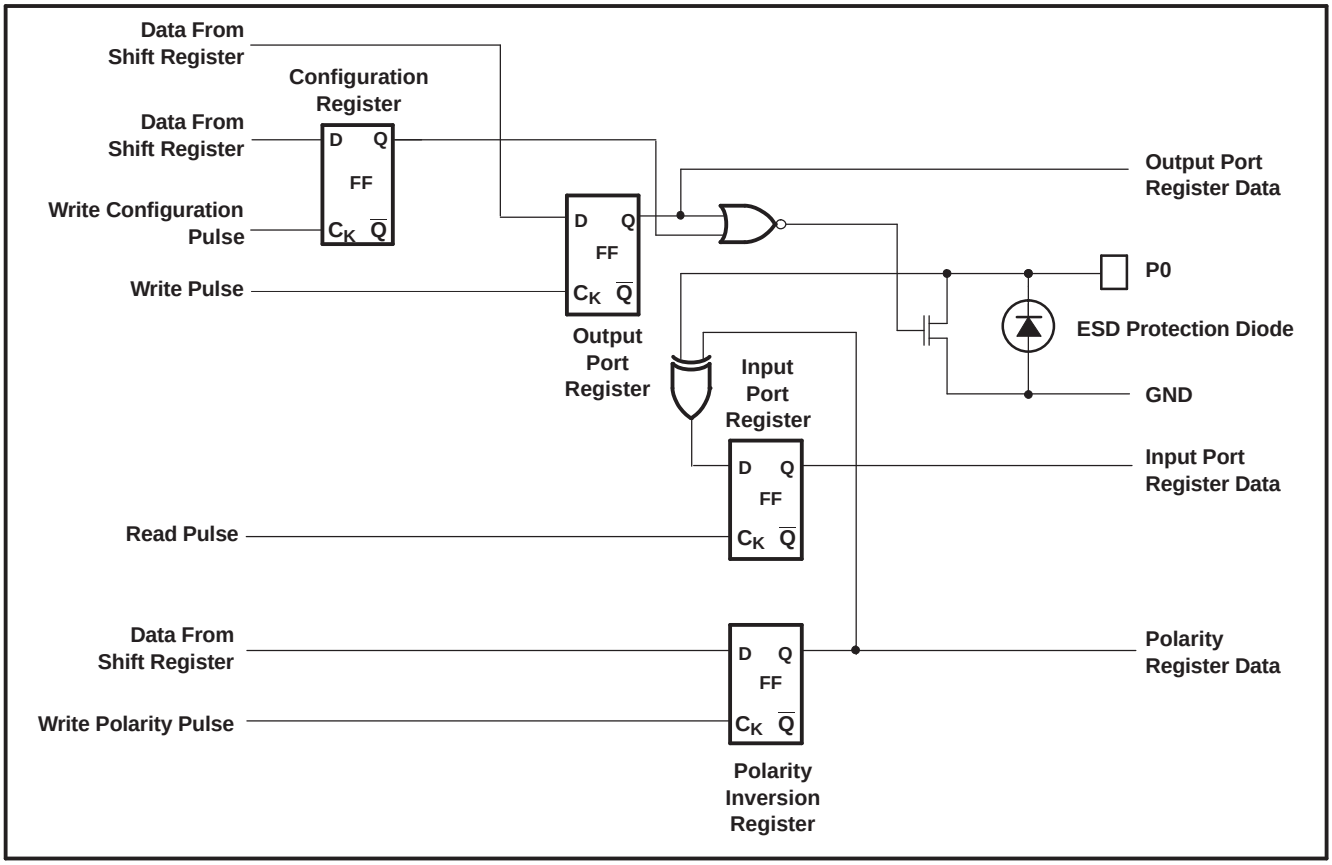
LOGIC DIAGRAM (POSITIVE LOGIC)



A. Pin numbers shown are for the D, DB, DGV, PW, and RGY packages.

B. All I/Os are set to inputs at reset.

SIMPLIFIED SCHEMATIC DIAGRAM OF P0



A. On power up or reset, all registers return to default values.

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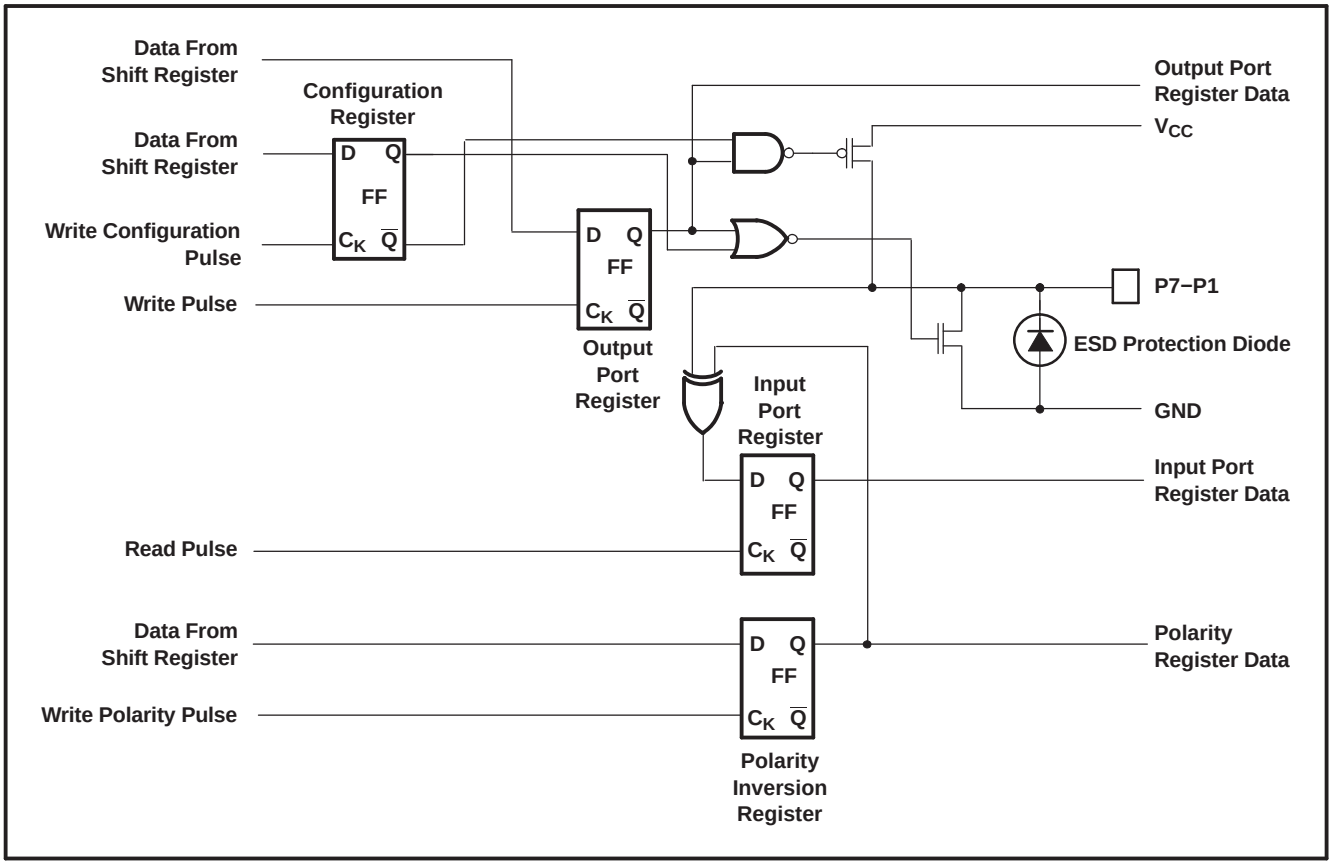
SIMPLIFIED SCHEMATIC DIAGRAM OF P7–P1



A. On power up or reset, all registers return to default values.

I²C Interface

The bidirectional I²C bus consists of the serial clock (SCL) and serial data (SDA) lines. Both lines must be connected to a positive supply through a pullup resistor when connected to the output stages of a device. Data transfer may be initiated only when the bus is not busy.

I²C communication with this device is initiated by a master sending a start condition, a high-to-low transition on the SDA input/output while the SCL input is high (see Figure 1). After the start condition, the device address byte is sent, most-significant bit (MSB) first, including the data direction bit (R/$\overline{W}$).

After receiving the valid address byte, this device responds with an acknowledge (ACK), a low on the SDA input/output during the high of the ACK-related clock pulse. The address (A2–A0) inputs of the slave device must not be changed between the start and the stop conditions.

On the I²C bus, only one data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the high pulse of the clock period, as changes in the data line at this time are interpreted as control commands (start or stop) (see Figure 2).

A stop condition, a low-to-high transition on the SDA input/output while the SCL input is high, is sent by the master (see Figure 1).

Any number of data bytes can be transferred from the transmitter to the receiver between the Start and the Stop conditions. Each byte of eight bits is followed by one ACK bit. The transmitter must release the SDA line before the receiver can send an ACK bit. The device that acknowledges must pull down the SDA line during the ACK clock pulse, so that the SDA line is stable low during the high pulse of the ACK-related clock period (see Figure 3). When a slave receiver is addressed, it must generate an ACK after each byte is received. Similarly, the master must generate an ACK after each byte that it receives from the slave transmitter. Setup and hold times must be met to ensure proper operation.

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A master receiver signals an end of data to the slave transmitter by not generating an acknowledge (NACK) after the last byte has been clocked out of the slave. This is done by the master receiver by holding the SDA line high. In this event, the transmitter must release the data line to enable the master to generate a stop condition.

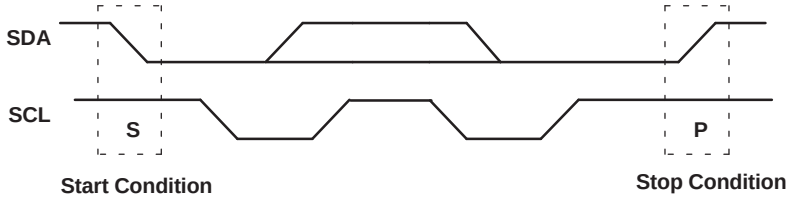

Figure 1. Definition of Start and Stop Conditions

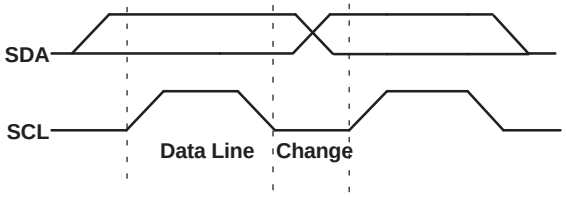

Figure 2. Bit Transfer

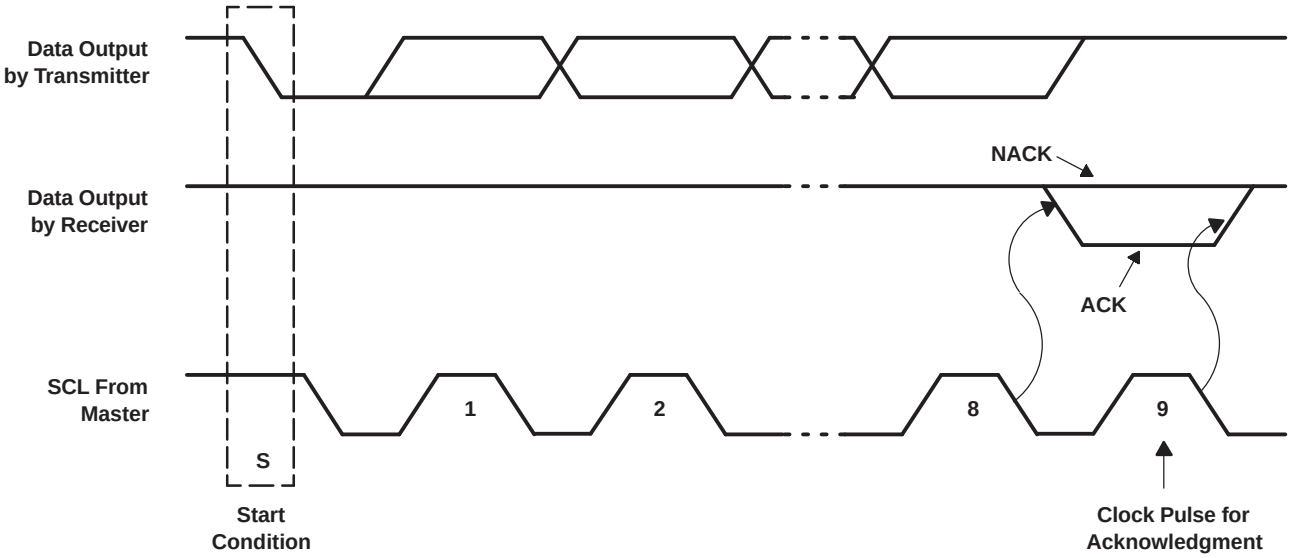

Figure 3. Acknowledgment on the I^2C Bus

Interface Definition

BYTE	BIT							
	7 (MSB)	6	5	4	3	2	1	0 (LSB)
I^2C slave address	L	L	H	H	A2	A1	A0	R/$\overline{W}$
Px I/O data bus	P7	P6	P5	P4	P3	P2	P1	P0

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Device Address

The address of the PCA9557 is shown in Figure 4.

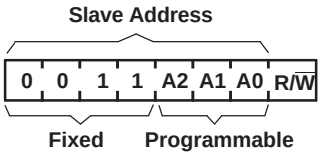

Figure 4. PCA9557 Address

Address Reference

INPUTS			I^2C BUS SLAVE ADDRESS
A2	A1	A0	
L	L	L	24 (decimal), 18 (hexadecimal)
L	L	H	25 (decimal), 19 (hexadecimal)
L	H	L	26 (decimal), 1A (hexadecimal)
L	H	H	27 (decimal), 1B (hexadecimal)
H	L	L	28 (decimal), 1C (hexadecimal)
H	L	H	29 (decimal), 1D (hexadecimal)
H	H	L	30 (decimal), 1E (hexadecimal)
H	H	H	31 (decimal), 1F (hexadecimal)

The last bit of the slave address defines the operation (read or write) to be performed. A high (1) selects a read operation, while a low (0) selects a write operation.

Control Register and Command Byte

Following the successful acknowledgment of the address byte, the bus master sends a command byte that is stored in the control register in the PCA9557. Two bits of this data byte state the operation (read or write) and the internal registers (input, output, polarity inversion or configuration) that will be affected. This register can be written or read through the I^2C bus. The command byte is sent only during a write transmission.

Once a new command byte has been sent, the register that was addressed continues to be accessed by reads until a new command byte has been sent.

0	0	0	0	0	0	B1	B0

Figure 5. Control Register Bits

Command Byte

CONTROL REGISTER BITS		COMMAND BYTE (HEX)	REGISTER	PROTOCOL	POWER-UP DEFAULT
B1	B0				
0	0	0x00	Input Port	Read byte	xxxx xxxx
0	1	0x01	Output Port	Read/write byte	0000 0000
1	0	0x02	Polarity Inversion	Read/write byte	1111 0000
1	1	0x03	Configuration	Read/write byte	1111 1111

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Register Descriptions

The input port register (register 0) reflects the incoming logic levels of the pins, regardless of whether the pin is defined as an input or an output by the configuration register. It only acts on read operation. Writes to these registers have no effect. The default value, X, is determined by the externally applied logic level.

Before a read operation, a write transmission is sent with the command byte to signal the I^2C device that the input port register will be accessed next.

Register 0 (Input Port Register)

BIT	I7	I6	I5	I4	I3	I2	I1	I0
DEFAULT	X	X	X	X	X	X	X	X

The output port register (register 1) shows the outgoing logic levels of the pins defined as outputs by the configuration register. Bit values in this register have no effect on pins defined as inputs. In turn, reads from this register reflect the value that is in the flip-flop controlling the output selection, not the actual pin value.

Register 1 (Output Port Register)

BIT	O7	O6	O5	O4	O3	O2	O1	O0
DEFAULT	0	0	0	0	0	0	0	0

The polarity inversion register (register 2) allows polarity inversion of pins defined as inputs by the configuration register. If a bit in this register is set (written with 1), the corresponding port pin's polarity is inverted. If a bit in this register is cleared (written with a 0), the corresponding port pin's original polarity is retained.

Register 2 (Polarity Inversion Register)

BIT	N7	N6	N5	N4	N3	N2	N1	N0
DEFAULT	1	1	1	1	0	0	0	0

The configuration register (register 3) configures the directions of the I/O pins. If a bit in this register is set to 1, the corresponding port pin is enabled as an input with high impedance output driver. If a bit in this register is cleared to 0, the corresponding port pin is enabled as an output.

Register 3 (Configuration Register)

BIT	C7	C6	C5	C4	C3	C2	C1	C0
DEFAULT	1	1	1	1	1	1	1	1

Power-On Reset

When power (from 0 V) is applied to V_{CC}, an internal power-on reset holds the PCA9557 in a reset condition until V_{CC} has reached V_{POR}. At that time, the reset condition is released, and the PCA9557 registers and I^2C/SMBus state machine initialize to their default states. After that, V_{CC} must be lowered to below 0.2 V and back up to the operating voltage for a power-reset cycle. The $\overline{\text{RESET}}$ input can be asserted to reset the system, while keeping the V_{CC} at its operating level.

$\overline{\text{RESET}}$

A reset can be accomplished by holding the $\overline{\text{RESET}}$ pin low for a minimum of t_W. The PCA9557 registers and I^2C/SMBus state machine are held in their default states until $\overline{\text{RESET}}$ again is high. This input requires a pullup resistor to V_{CC} if no active connection is used.

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Bus Transactions

Data is exchanged between the master and PCA9557 through write and read commands.

Writes

Data is transmitted to the PCA9557 by sending the device address and setting the least-significant bit (LSB) to a logic 0 (see Figure 4 for device address). The command byte is sent after the address and determines which register receives the data that follows the command byte. There is no limitation on the number of data bytes sent in one write transmission (see Figure 6 and Figure 7).

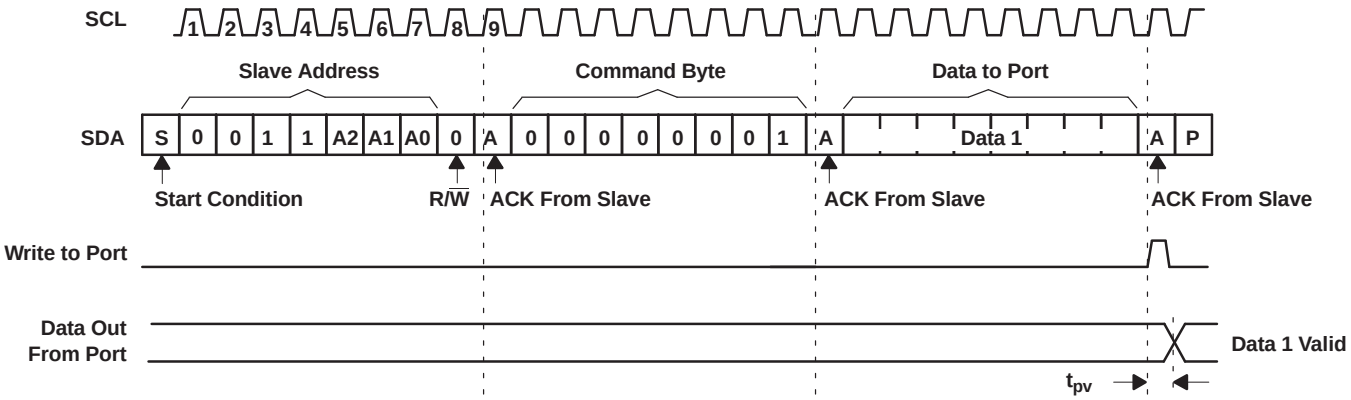


Figure 6. Write to Output Port Register

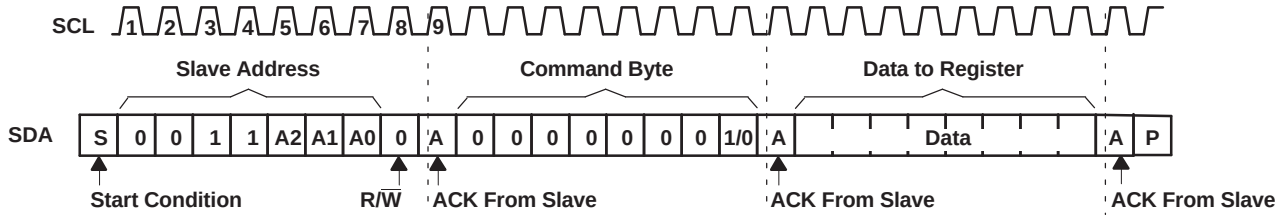


Figure 7. Write to Configuration or Polarity Inversion Registers

Reads

The bus master first must send the PCA9557 address with the LSB set to a logic 0 (see Figure 4 for device address). The command byte is sent after the address and determines which register is accessed. After a restart, the device address is sent again but, this time, the LSB is set to a logic 1. Data from the register defined by the command byte then is sent by the PCA9557 (see Figure 8 and Figure 9). After a restart, the value of the register defined by the command byte matches the register being accessed when the restart occurred. Data is clocked into the register on the rising edge of the ACK clock pulse. There is no limitation on the number of data bytes received in one read transmission, but when the final byte is received, the bus master must not acknowledge the data.

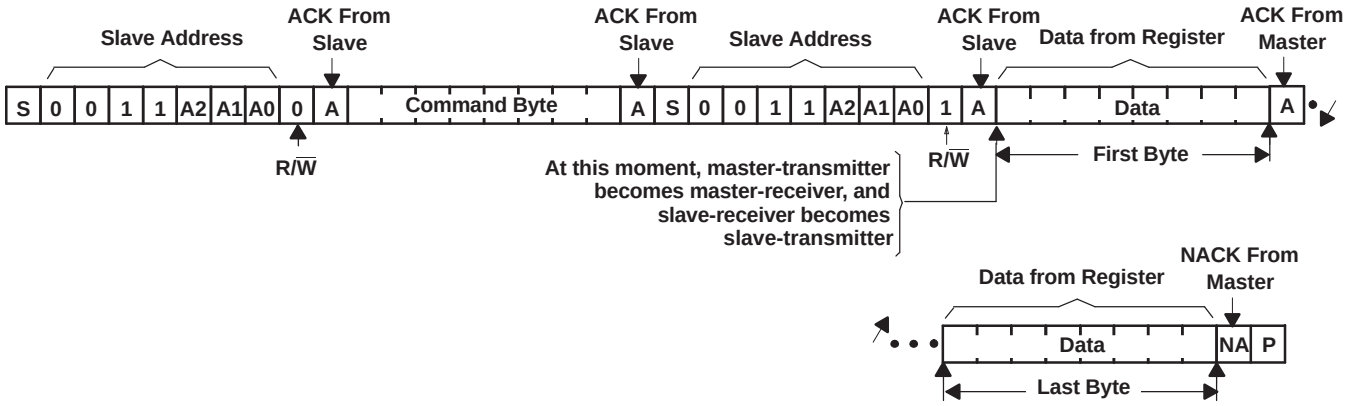
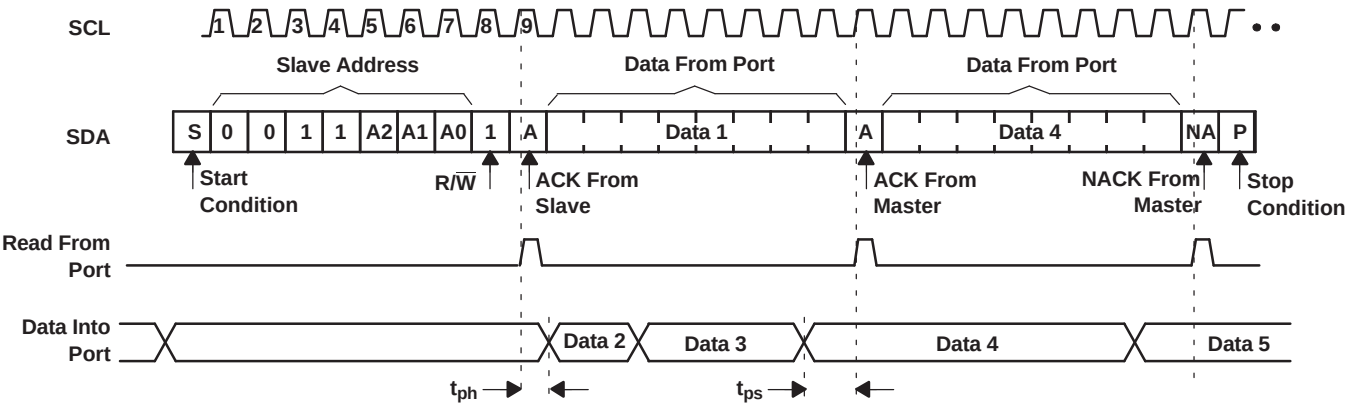


Figure 8. Read From Register



A. This figure assumes the command byte has been previously programmed with 00h.

B. Transfer of data can be stopped at any moment by a stop condition. When this occurs, data present at the last acknowledge phase is valid (output mode). Input data is lost.

C. This figure eliminates the command byte transfer, a restart, and slave address call between the initial slave address call and actual data transfer from the P port (see Figure 8).

Figure 9. Read Input Port Register

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ABSOLUTE MAXIMUM RATINGS(1)

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
V_{CC}	Supply voltage range		–0.5	6	V
V_I	Input voltage range(2)		–0.5	6	V
V_O	Output voltage range(2)		–0.5	6	V
I_{IK}	Input clamp current	$V_I < 0$		–20	mA
I_{OK}	Output clamp current	$V_O < 0$		–20	mA
I_{IOK}	Input/output clamp current	$V_O < 0$ or $V_O > V_{CC}$		–20	µA
I_{OL}	Continuous output low current	V_O = 0 to V_{CC}		50	mA
I_{OH}	Continuous output high current	V_O = 0 to V_{CC}		–50	mA
I_{CC}	Continuous current through GND			–250	mA
	Continuous current through V_{CC}			160	
θ_{JA}	Package thermal impedance(3)	D package		73	°C/W
		DB package		82	
		DGV package		120	
		PW package		108	
		RGV package		51	
		RGY package		47	
T_{stg}	Storage temperature range		–65	150	°C

(1) Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) The input negative-voltage and output voltage ratings may be exceeded if the input and output current ratings are observed.
(3) The package thermal impedance is calculated in accordance with JESD 51-7.

RECOMMENDED OPERATING CONDITIONS

			MIN	MAX	UNIT
V_{CC}	Supply voltage		2.3	5.5	V
V_{IH}	High-level input voltage	SCL, SDA	0.7 × V_{CC}	5.5	V
		A2–A0, P7–P0, $\overline{RESET}$	2	5.5	
V_{IL}	Low-level input voltage	SCL, SDA	–0.5	0.3 × V_{CC}	V
		A2–A0, P7–P0, $\overline{RESET}$	–0.5	0.8	
I_{OH}	High-level output current	P7–P1		–10	mA
I_{OL}	Low-level output current	P7–P0		25	mA
T_A	Operating free-air temperature		–40	85	°C

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ELECTRICAL CHARACTERISTICS

over recommended operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS	V_{CC}	MIN	TYP(1)	MAX	UNIT
V_{IK}	Input diode clamp voltage	I_I = –18 mA	2.3 V to 5.5 V	–1.2			V
V_{POR}	Power-on reset voltage	$V_I = V_{CC}$ or GND, I_O = 0	V_{POR}		1.65	2.1	V
V_{OH}	P-port high-level output voltage(2)	I_{OH} = –8 mA	2.3 V	1.8			V
			3 V	2.6			
			4.5 V	3			
			4.75 V	4.1			
		I_{OH} = –10 mA	2.3 V	1.5			
			3 V	2.5			
			4.5 V	3			
			4.75 V	4			
I_{OL}	SDA	V_{OL} = 0.4 V	2.3 V to 5.5 V	3			mA
	P port(3)	V_{OL} = 0.5 V	2.3 V to 5.5 V	8	20		
		V_{OL} = 0.55 V		8	20		
		V_{OL} = 0.7 V		10	24		
I_{OH}	P port, except for P0(3)	V_{OH} = 2.3 V	2.3 V to 5.5 V	–4			mA
	P0(3)	V_{OH} = 4.6 V	4.6 V to 5.5 V			1	µA
		V_{OH} = 3.3 V	3.3 V to 5.5 V			1	
I_I	SCL, SDA	$V_I = V_{CC}$ or GND	2.3 V to 5.5 V			±1	µA
	A2–A0, $\overline{\text{RESET}}$					±1	
I_{IH}	P port	$V_I = V_{CC}$	2.3 V to 5.5 V			1	µA
I_{IL}	P port	V_I = GND	2.3 V to 5.5 V			1	µA
I_{CC}	Operating mode	$V_I = V_{CC}$ or GND, I_O = 0, I/O = inputs, f_{SCL} = 400 kHz	5.5 V		19	25	µA
			3.6 V		12	22	
			2.7 V		8	20	
		$V_I = V_{CC}$ or GND, I_O = 0, I/O = inputs, f_{SCL} = 100 kHz	5.5 V		1.5	5	
			3.6 V		1	4	
			2.7 V		0.6	3	
	Standby mode	$V_I = V_{CC}$ or GND, I_O = 0, I/O = inputs, f_{SCL} = 0 kHz	5.5 V		0.25	1	
			3.6 V		0.25	0.9	
			2.7 V		0.2	0.8	
ΔI_{CC}	Additional current in Standby mode	One input at V_{CC} – 0.6 V, Other inputs at V_{CC} or GND	2.3 V to 5.5 V			0.2	mA
		Every LED I/O at V_I = 4.3 V, f_{SCL} = 0 kHz	5.5 V			0.4	
C_I	SCL	$V_I = V_{CC}$ or GND	2.3 V to 5.5 V		4	6	pF
C_{io}	SDA	$V_{IO} = V_{CC}$ or GND	2.3 V to 5.5 V		5.5	8	pF
	P port				7.5	9.5	

(1) All typical values are at nominal supply voltage (2.5-V, 3.3-V, or 5-V V_{CC}) and T_A = 25°C.
(2) The total current sourced by all I/Os must be limited to 85 mA per bit.
(3) Each I/O must be externally limited to a maximum of 25 mA, and the P port (P7–P0) must be limited to a maximum current of 200 mA.

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I²C INTERFACE TIMING REQUIREMENTS

over recommended operating free-air temperature range (unless otherwise noted) (see Figure 10)

		STANDARD MODE I²C BUS		FAST MODE I²C BUS		UNIT
		MIN	MAX	MIN	MAX	
f_{scl}	I²C clock frequency	0	100	0	400	kHz
t_{sch}	I²C clock high time	4		0.6		µs
t_{scl}	I²C clock low time	4.7		1.3		µs
t_{sp}	I²C spike time		50		50	ns
t_{sds}	I²C serial data setup time	250		100		ns
t_{sdh}	I²C serial data hold time	0		0		ns
t_{icr}	I²C input rise time		1000	$20 + 0.1C_b$ (1)	300	ns
t_{icf}	I²C input fall time		300	$20 + 0.1C_b$ (1)	300	ns
t_{ocf}	I²C output fall time, 10-pF to 400-pF bus		300	$20 + 0.1C_b$ (1)	300	ns
t_{buf}	I²C bus free time between Stop and Start	4.7		1.3		µs
t_{sts}	I²C Start or repeated Start condition setup time	4.7		0.6		µs
t_{sth}	I²C Start or repeated Start condition hold time	4		0.6		µs
t_{sps}	I²C Stop condition setup time	4		0.6		µs
$t_{vd(data)}$	Valid data time, SCL low to SDA output valid		1		0.9	µs
$t_{vd(ack)}$	Valid data time of ACK condition, ACK signal from SCL low to SDA (out) low		1		0.9	µs
C_b	I²C bus capacitive load		400		400	pF

(1) C_b = total capacitance of one bus line in pF

RESET TIMING REQUIREMENTS

over recommended operating free-air temperature range (unless otherwise noted) (see Figure 13)

		STANDARD MODE I²C BUS		FAST MODE I²C BUS		UNIT
		MIN	MAX	MIN	MAX	
t_W	Reset pulse duration (1)	16		16		ns
t_{REC}	Reset recovery time	0		0		ns
t_{RESET}	Time to reset (2)	400		400		ns

(1) A pulse duration of 16 ns minimum must be applied to $\overline{\text{RESET}}$ to return the PCA9557 to its default state.
(2) The PCA9557 requires a minimum of 400 ns to be reset.

SWITCHING CHARACTERISTICS

over recommended operating free-air temperature range (unless otherwise noted) (see Figure 10)

PARAMETER		FROM	TO	STANDARD MODE I²C BUS		FAST MODE I²C BUS		UNIT
				MIN	MAX	MIN	MAX	
t_{pv}	Output data valid	SCL	P0		250		250	ns
		SCL	P1–P7		200		200	
t_{ps}	Input data setup time	P port	SCL	0		0		ns
t_{ph}	Input data hold time	P port	SCL	200		200		ns

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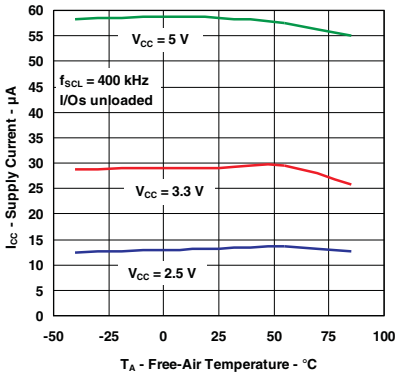
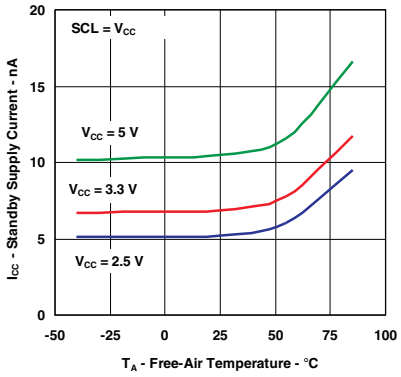
TYPICAL CHARACTERISTICS

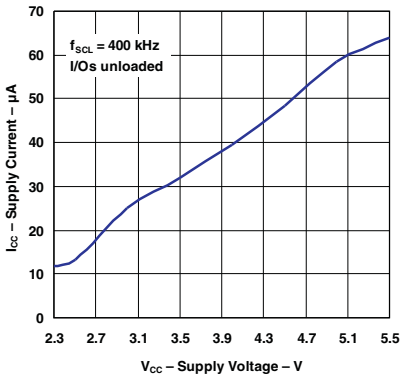
SUPPLY CURRENT VS TEMPERATURE



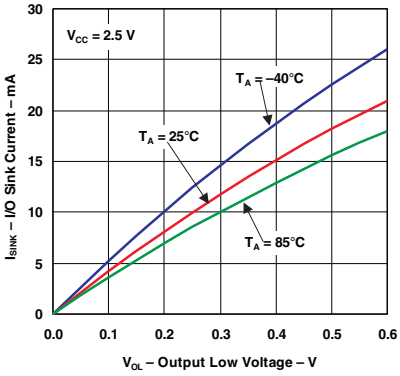
STANDBY SUPPLY CURRENT VS TEMPERATURE



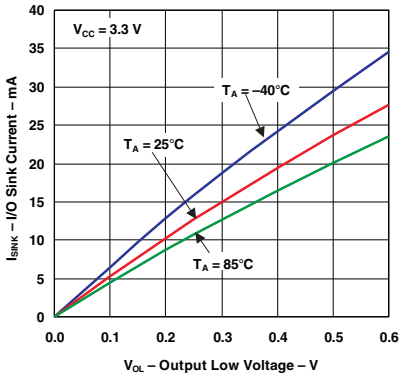
SUPPLY CURRENT VS SUPPLY VOLTAGE



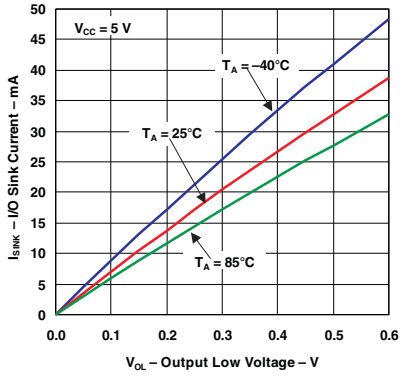
I/O SINK CURRENT VS OUTPUT LOW VOLTAGE



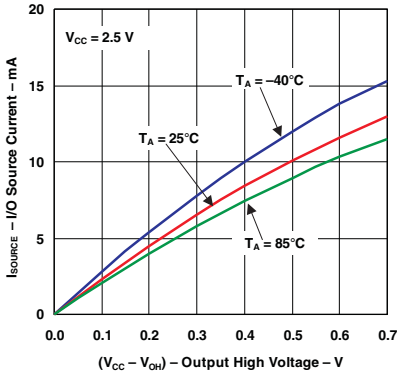
I/O SINK CURRENT VS OUTPUT LOW VOLTAGE



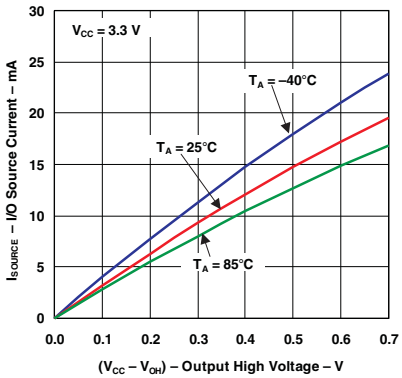
I/O SINK CURRENT VS OUTPUT LOW VOLTAGE



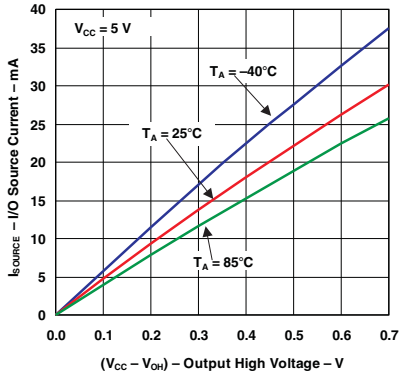
I/O SOURCE CURRENT VS OUTPUT HIGH VOLTAGE (P7–P1)



I/O SOURCE CURRENT VS OUTPUT HIGH VOLTAGE (P7–P1)



I/O SOURCE CURRENT VS OUTPUT HIGH VOLTAGE (P7–P1)



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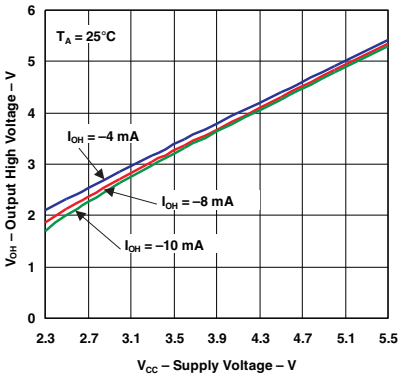
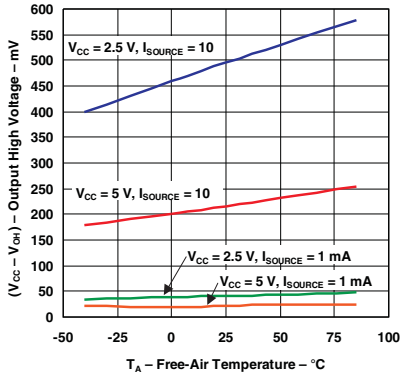
TYPICAL CHARACTERISTICS (continued)

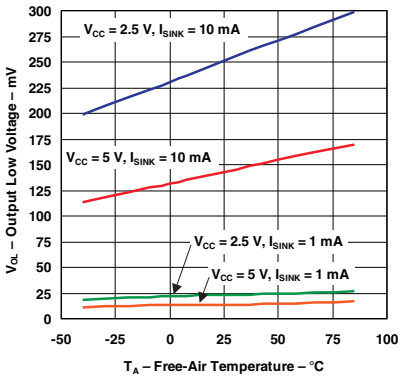
OUTPUT HIGH VOLTAGE VS SUPPLY VOLTAGE (P7–P1)



OUTPUT HIGH VOLTAGE VS TEMPERATURE (P7–P1)



OUTPUT LOW VOLTAGE VS TEMPERATURE



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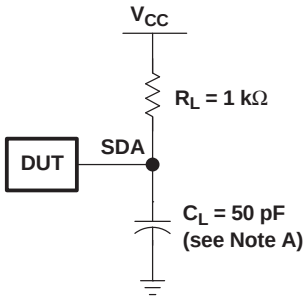
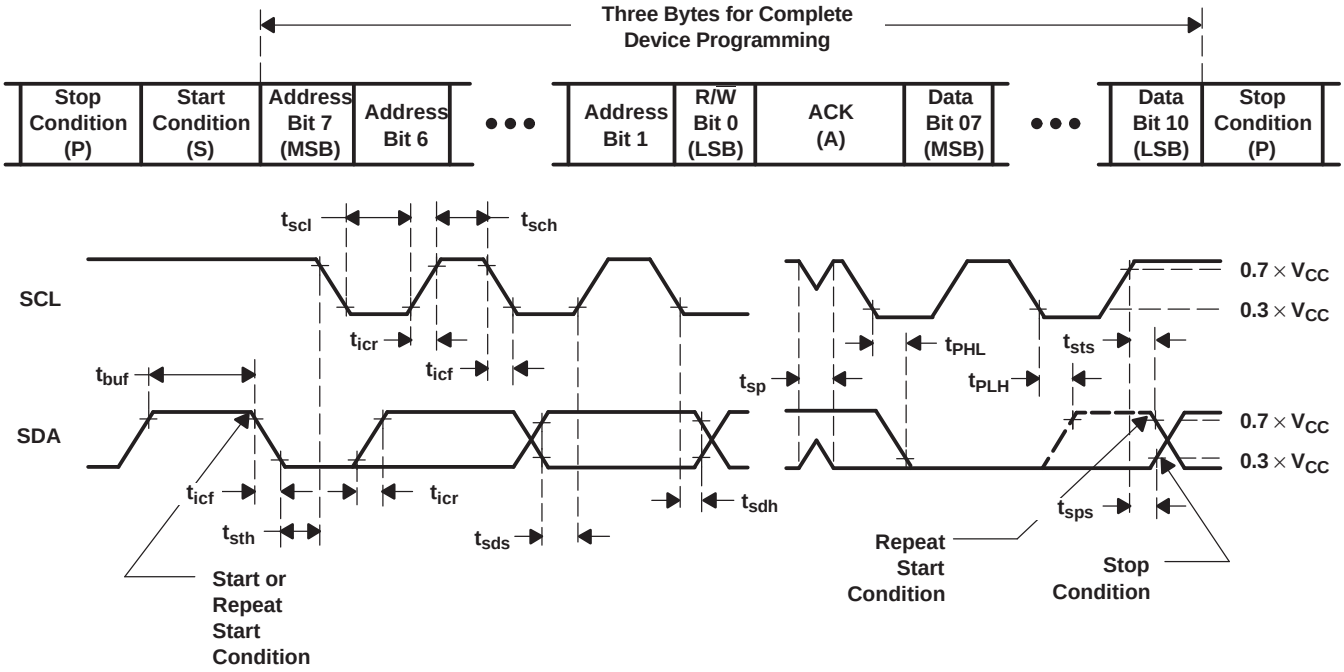
PARAMETER MEASUREMENT INFORMATION



SDA LOAD CONFIGURATION



VOLTAGE WAVEFORMS

BYTE	DESCRIPTION
1	I^2C address
2, 3	P-port data

A. C_L includes probe and jig capacitance.

B. All inputs are supplied by generators having the following characteristics: PRR ≤ 10 MHz, Z_O = 50 Ω, t_r/t_f ≤ 30 ns.

C. All parameters and waveforms are not applicable to all devices.

Figure 10. I^2C Interface Load Circuit and Voltage Waveforms

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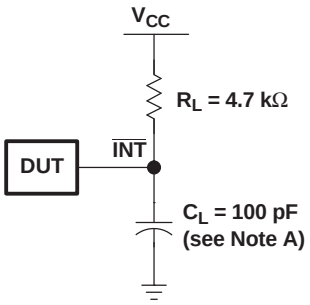
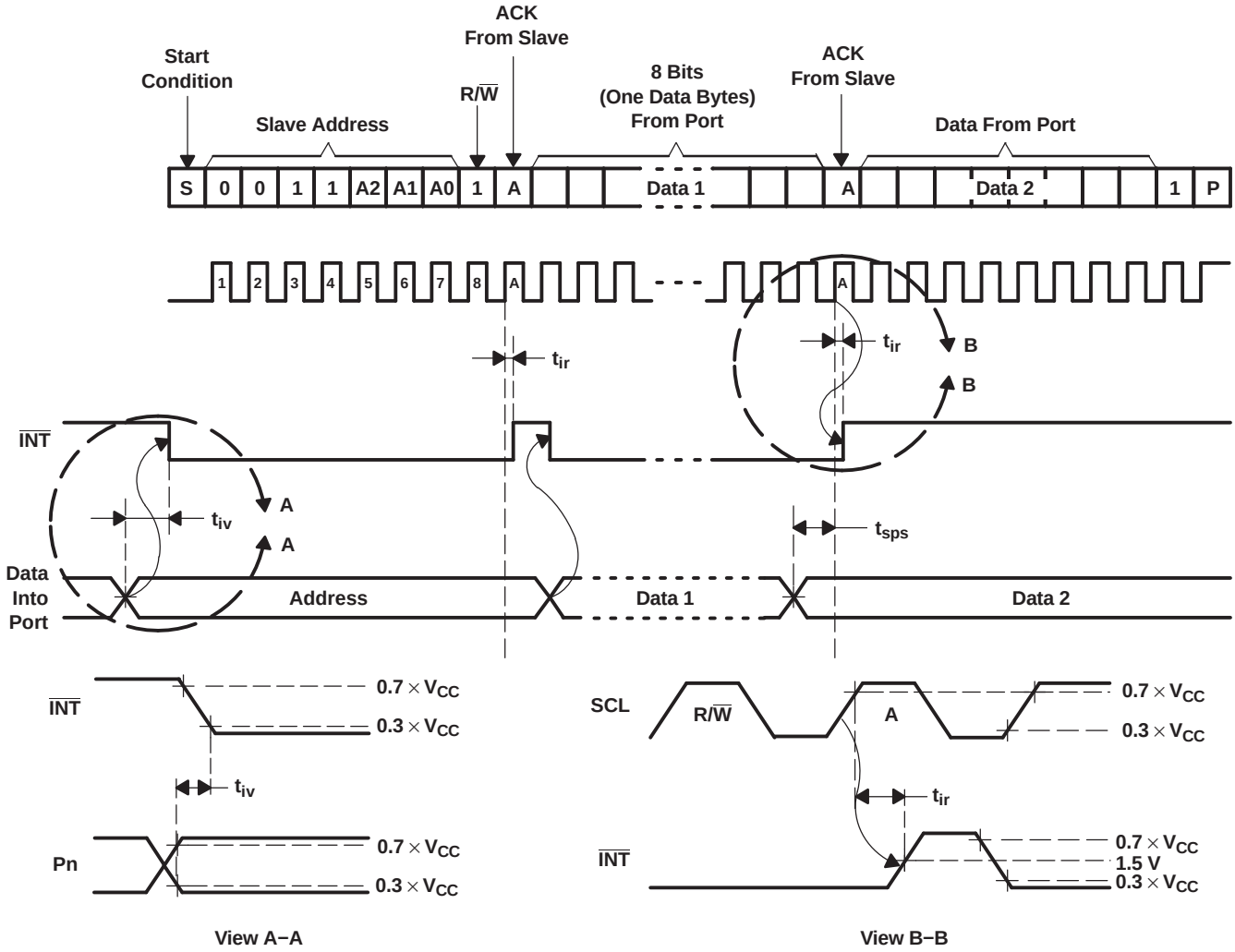
PARAMETER MEASUREMENT INFORMATION (continued)



INTERRUPT LOAD CONFIGURATION



View A–A

View B–B

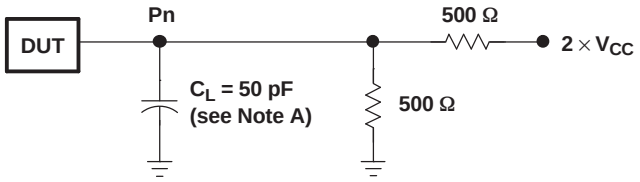
A. C_L includes probe and jig capacitance.

B. All inputs are supplied by generators having the following characteristics: PRR ≤ 10 MHz, Z_O = 50 Ω, t_r/t_f ≤ 30 ns.

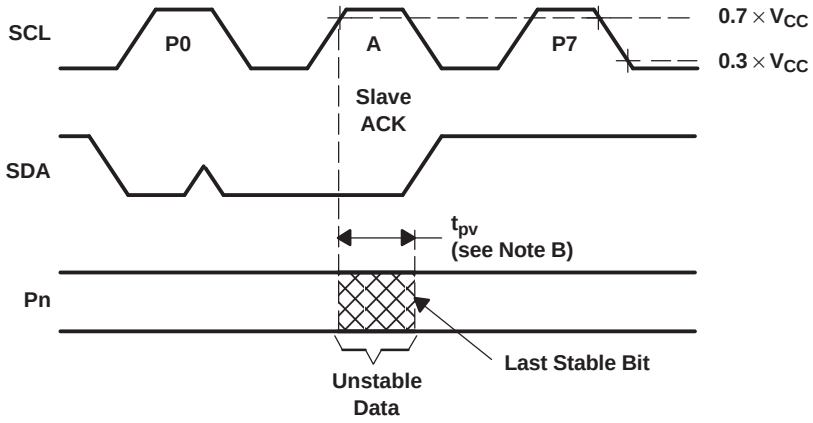
C. All parameters and waveforms are not applicable to all devices.

Figure 11. Interrupt Load Circuit and Voltage Waveforms

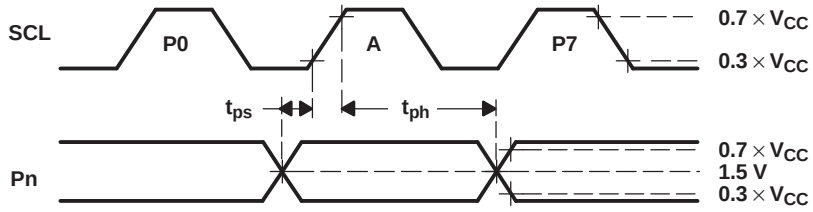
PARAMETER MEASUREMENT INFORMATION (continued)



P-PORT LOAD CONFIGURATION



WRITE MODE (R/$\overline{W}$ = 0)



READ MODE (R/$\overline{W}$ = 1)

A. C_L includes probe and jig capacitance.

B. t_{pv} is measured from 0.7 × V_{CC} on SCL to 50% I/O (Pn) output.

C. All inputs are supplied by generators having the following characteristics: PRR ≤ 10 MHz, Z_O = 50 Ω, t_r/t_f ≤ 30 ns.

D. The outputs are measured one at a time, with one transition per measurement.

E. All parameters and waveforms are not applicable to all devices.

Figure 12. P-Port Load Circuit and Voltage Waveforms

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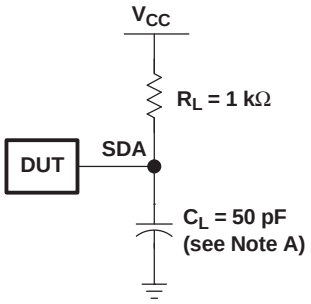
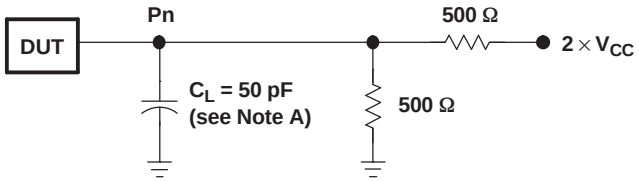
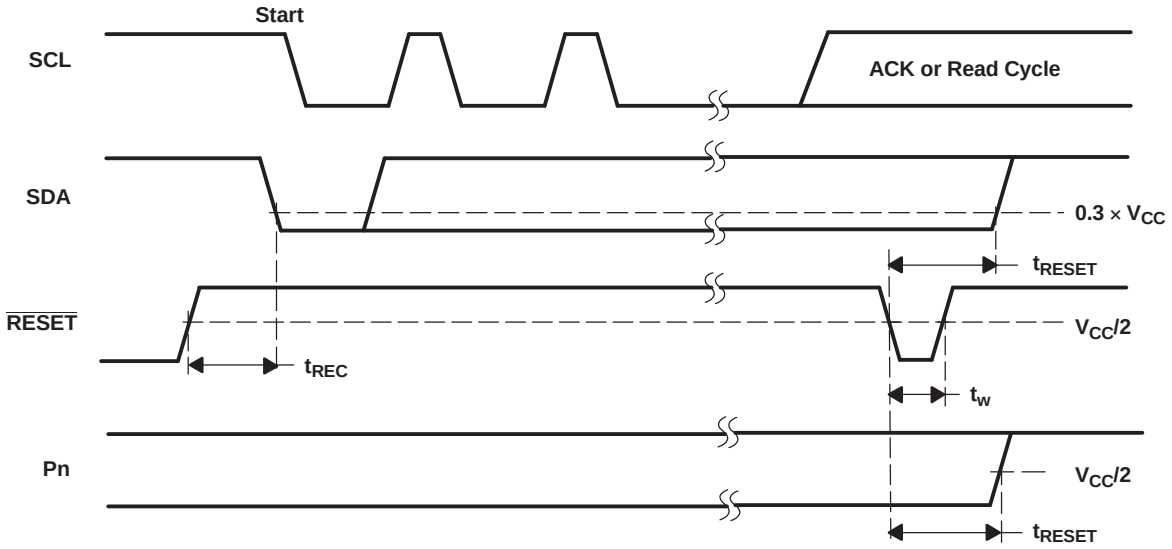
PARAMETER MEASUREMENT INFORMATION (continued)



SDA LOAD CONFIGURATION



P-PORT LOAD CONFIGURATION



A. C_L includes probe and jig capacitance.

B. All inputs are supplied by generators having the following characteristics: PRR ≤ 10 MHz, Z_O = 50 Ω, t_r/t_f ≤ 30 ns.

C. I/Os are configured as inputs.

D. All parameters and waveforms are not applicable to all devices.

Figure 13. Reset Load Circuits and Voltage Waveforms

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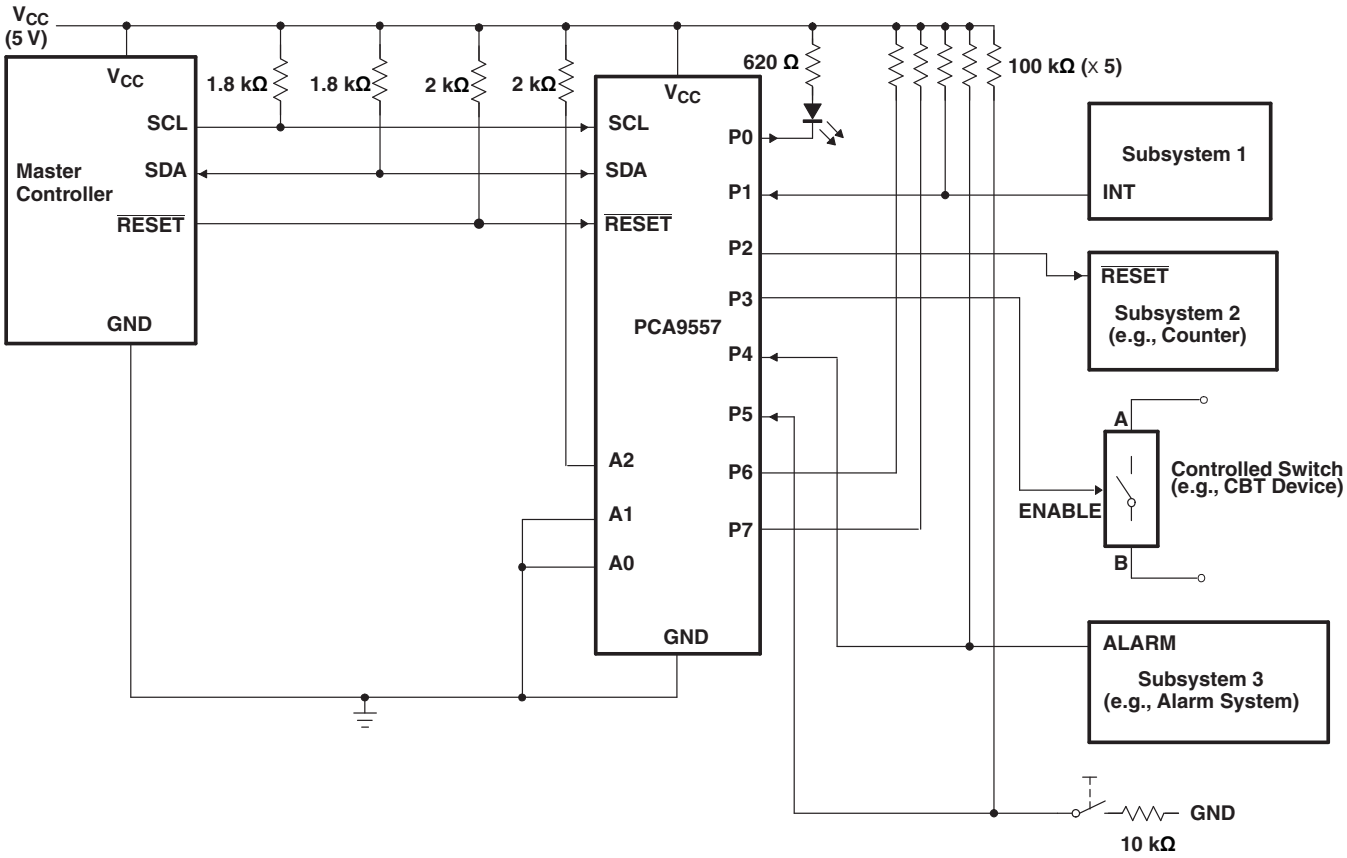
APPLICATION INFORMATION

Figure 14 shows an application in which the PCA9557 can be used.



A. Device address is configured as 0011100 for this example.

B. P1, P4, and P5 are configured as inputs.

C. P0, P2, and P3 are configured as outputs.

D. P6 and P7 are not used and must be configured as outputs.

Figure 14. Typical Application

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Minimizing I_{CC} When I/O Is Used to Control LED

When an I/O is used to control an LED, normally it is connected to V_{CC} through a resistor as shown in Figure 14. The LED acts as a diode so, when the LED is off, the I/O V_{IN} is about 1.2 V less than V_{CC}. The ΔI_{CC} parameter in *Electrical Characteristics* shows how I_{CC} increases as V_{IN} becomes lower than V_{CC}. Designs needing to minimize current consumption, such as battery power applications, should consider maintaining the I/O pins greater than or equal to V_{CC} when the LED is off.

Figure 15 shows a high-value resistor in parallel with the LED. Figure 16 shows V_{CC} less than the LED supply voltage by at least 1.2 V. Both of these methods maintain the I/O V_{IN} at or above V_{CC} and prevent additional supply-current consumption when the LED is off.

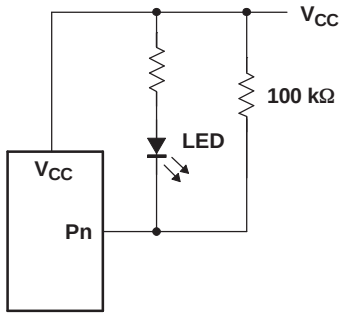

Figure 15. High-Value Resistor in Parallel With the LED

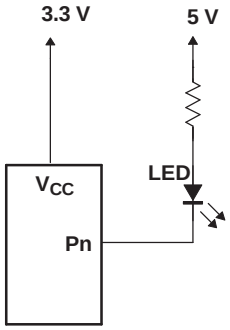

Figure 16. Device Supplied by a Low Voltage

PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp (3)
PCA9557D	ACTIVE	SOIC	D	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DB	ACTIVE	SSOP	DB	16	80	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DBG4	ACTIVE	SSOP	DB	16	80	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DBR	ACTIVE	SSOP	DB	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DBRG4	ACTIVE	SSOP	DB	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DG4	ACTIVE	SOIC	D	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DGVR	ACTIVE	TVSOP	DGV	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DGVRG4G4	ACTIVE	TVSOP	DGV	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DR	ACTIVE	SOIC	D	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DRG4	ACTIVE	SOIC	D	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DT	ACTIVE	SOIC	D	16	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557DTG4	ACTIVE	SOIC	D	16	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557PW	ACTIVE	TSSOP	PW	16	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557PWG4	ACTIVE	TSSOP	PW	16	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557PWR	ACTIVE	TSSOP	PW	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557PWRG4	ACTIVE	TSSOP	PW	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557PWT	ACTIVE	TSSOP	PW	16	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557PWTG4	ACTIVE	TSSOP	PW	16	250	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
PCA9557RGVR	ACTIVE	QFN	RGV	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
PCA9557RGVRG4	ACTIVE	QFN	RGV	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
PCA9557RGYR	ACTIVE	QFN	RGY	16	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
PCA9557RGYRG4	ACTIVE	QFN	RGY	16	1000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR

(1) The marketing status values are defined as follows:
ACTIVE: Product device recommended for new designs.
LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.
NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.
PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.
TBD: The Pb-Free/Green conversion plan has not been defined.
Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.
Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.
Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

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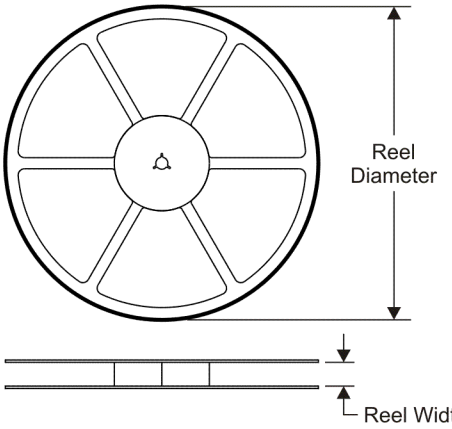
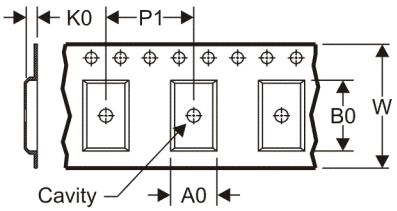
TAPE AND REEL INFORMATION

REEL DIMENSIONS

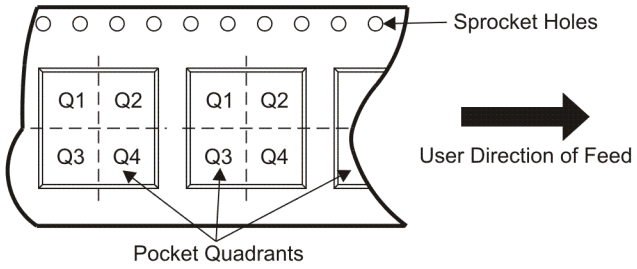


TAPE DIMENSIONS



A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

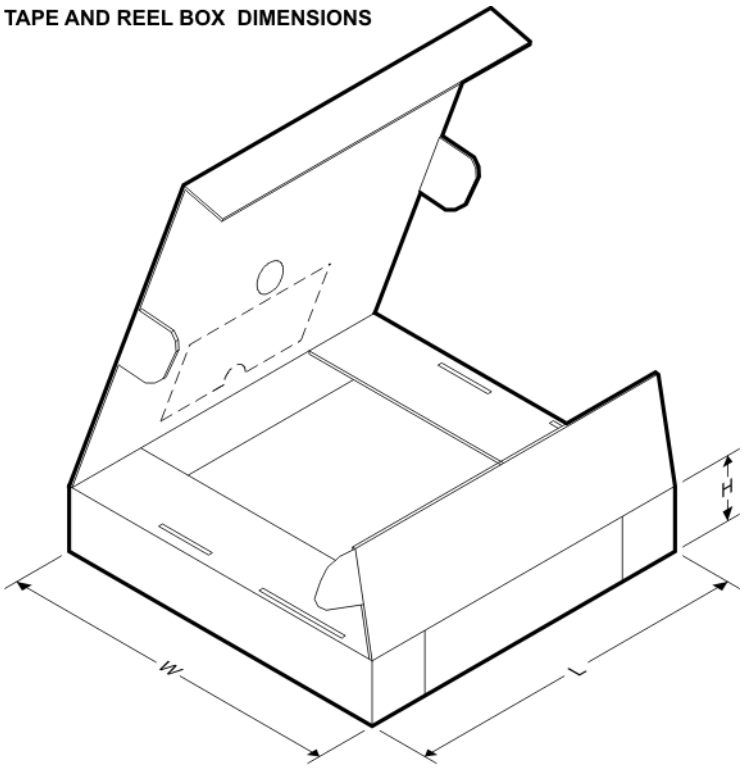
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
PCA9557DBR	SSOP	DB	16	2000	330.0	16.4	8.2	6.6	2.5	12.0	16.0	Q1
PCA9557DGVR	TVSOP	DGV	16	2000	330.0	12.4	6.8	4.0	1.6	8.0	12.0	Q1
PCA9557DR	SOIC	D	16	2500	330.0	16.4	6.5	10.3	2.1	8.0	16.0	Q1
PCA9557PWR	TSSOP	PW	16	2000	330.0	12.4	7.0	5.6	1.6	8.0	12.0	Q1
PCA9557RGVR	QFN	RGV	16	2500	330.0	12.4	4.3	4.3	1.5	8.0	12.0	Q2
PCA9557RGYR	QFN	RGY	16	1000	180.0	12.4	3.8	4.3	1.5	8.0	12.0	Q1

TAPE AND REEL BOX DIMENSIONS



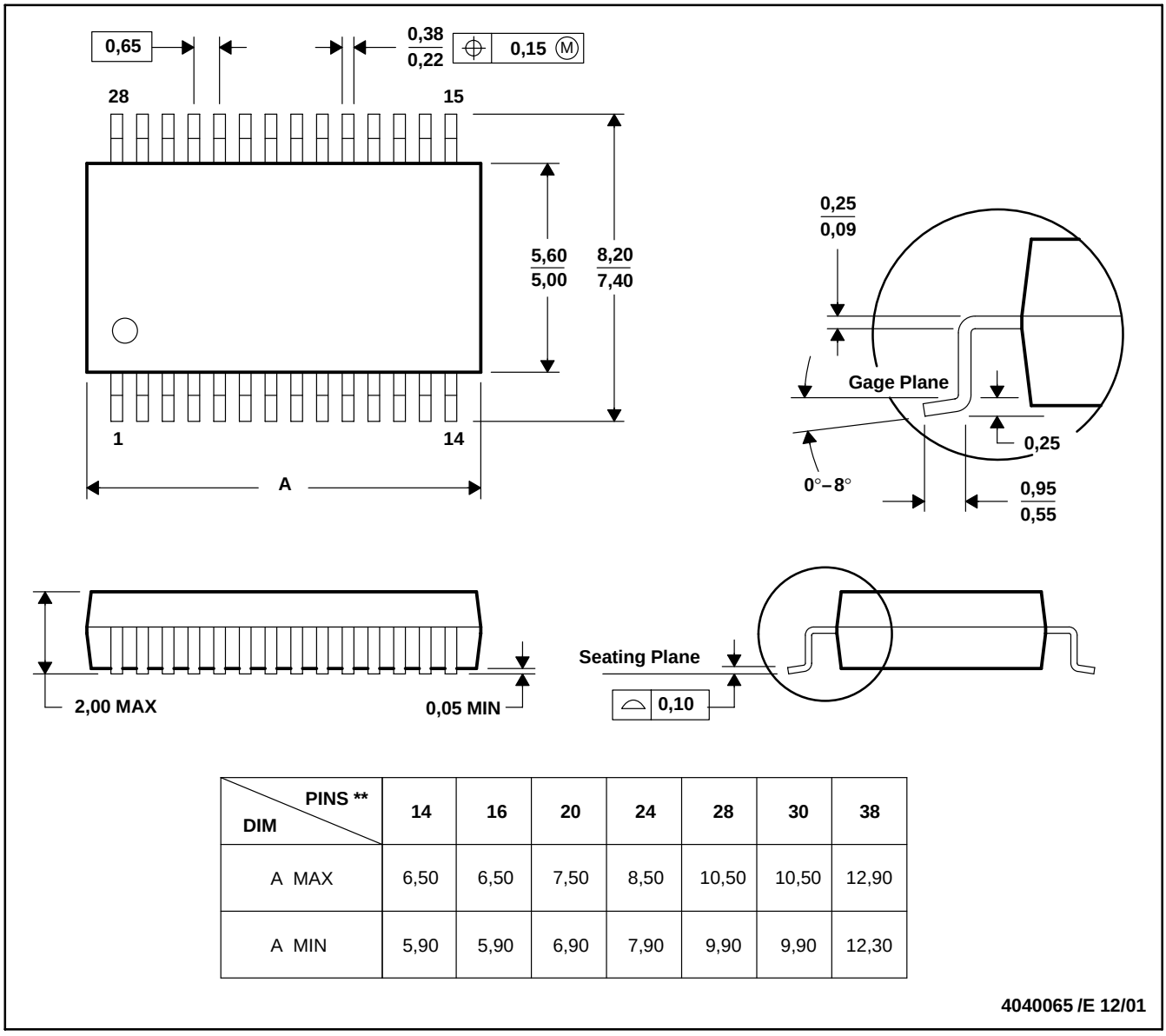
*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
PCA9557DBR	SSOP	DB	16	2000	346.0	346.0	33.0
PCA9557DGVR	TVSOP	DGV	16	2000	346.0	346.0	29.0
PCA9557DR	SOIC	D	16	2500	346.0	346.0	33.0
PCA9557PWR	TSSOP	PW	16	2000	346.0	346.0	29.0
PCA9557RGVR	QFN	RGV	16	2500	346.0	346.0	29.0
PCA9557RGYR	QFN	RGY	16	1000	190.5	212.7	31.8

MSSO002E – JANUARY 1995 – REVISED DECEMBER 2001

DB (R-PDSO-G)** **PLASTIC SMALL-OUTLINE**

28 PINS SHOWN



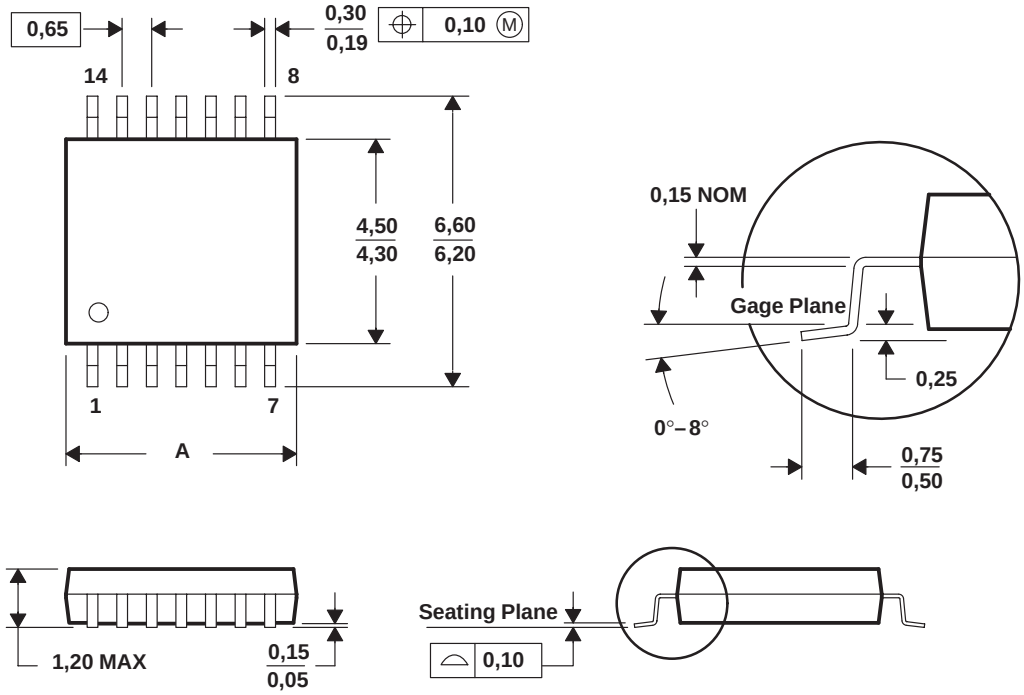
DIM \ PINS **	14	16	20	24	28	30	38
A MAX	6,50	6,50	7,50	8,50	10,50	10,50	12,90
A MIN	5,90	5,90	6,90	7,90	9,90	9,90	12,30

4040065 /E 12/01

NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
D. Falls within JEDEC MO-150

PW (R-PDSO-G)** **PLASTIC SMALL-OUTLINE PACKAGE**

14 PINS SHOWN



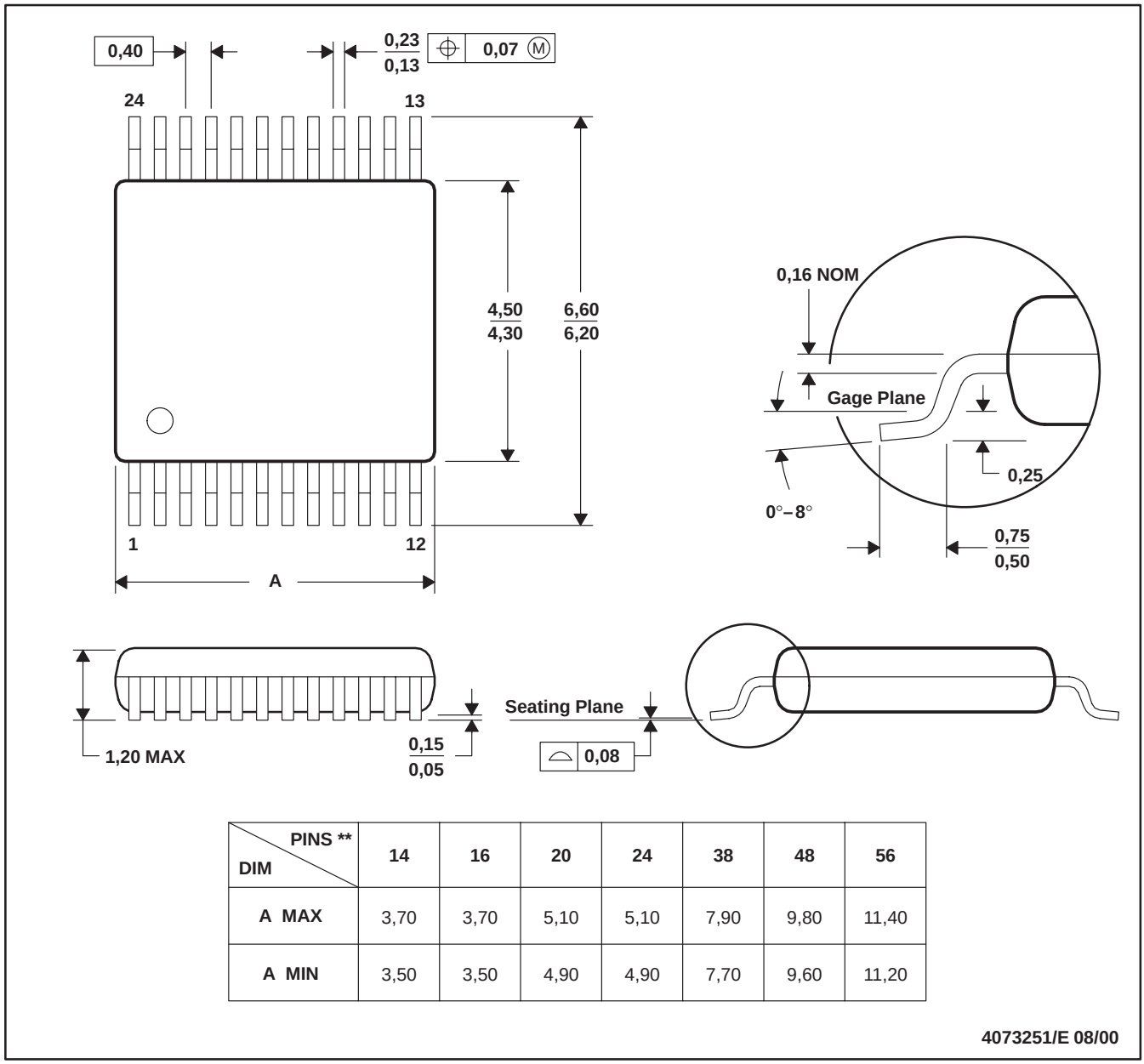
DIM \ PINS **	8	14	16	20	24	28
A MAX	3,10	5,10	5,10	6,60	7,90	9,80
A MIN	2,90	4,90	4,90	6,40	7,70	9,60

4040064/F 01/97

NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.
D. Falls within JEDEC MO-153

DGV (R-PDSO-G)** **PLASTIC SMALL-OUTLINE**

24 PINS SHOWN

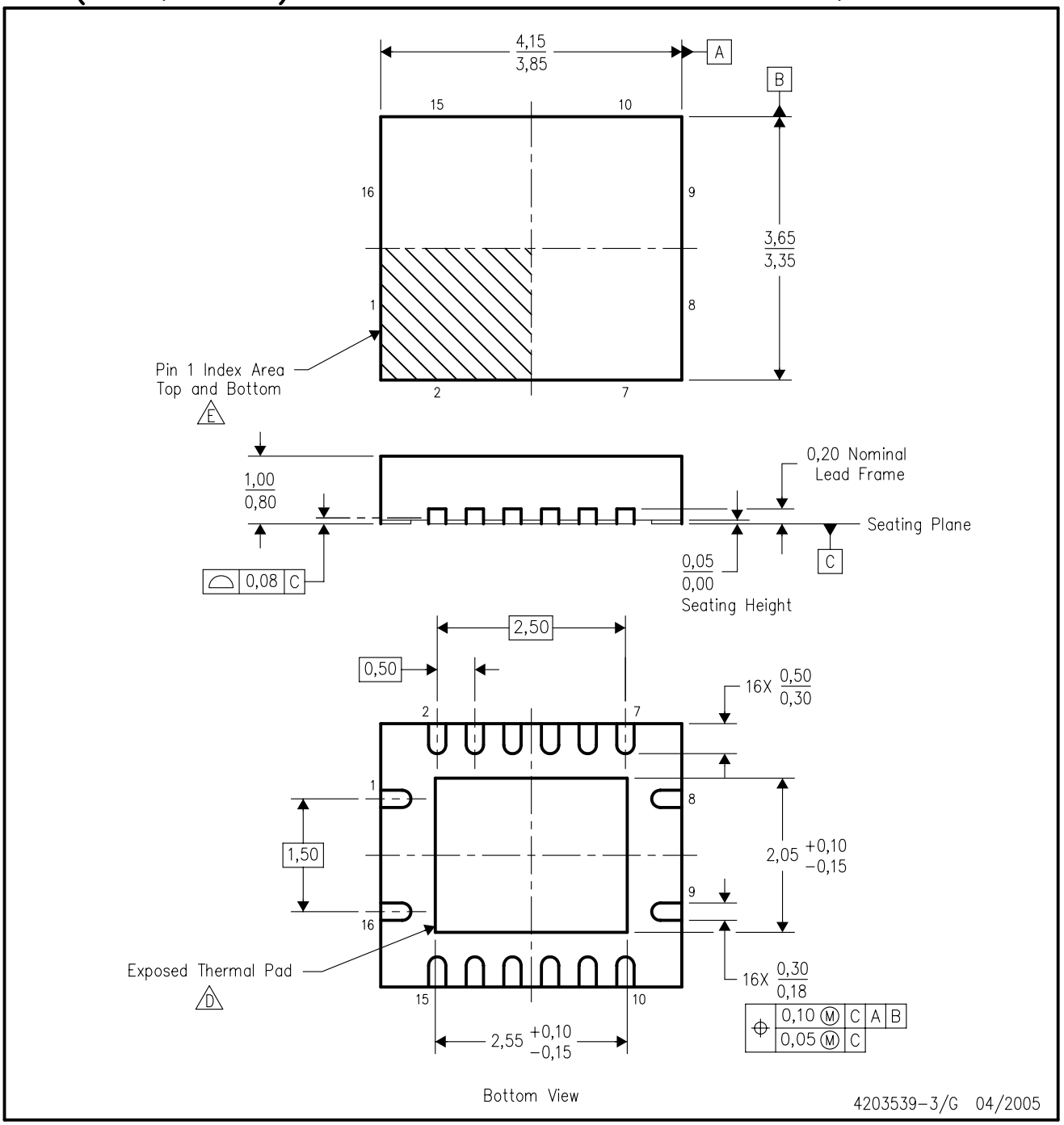


DIM \ PINS **	14	16	20	24	38	48	56
A MAX	3,70	3,70	5,10	5,10	7,90	9,80	11,40
A MIN	3,50	3,50	4,90	4,90	7,70	9,60	11,20

4073251/E 08/00

NOTES: A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion, not to exceed 0,15 per side.
D. Falls within JEDEC: 24/48 Pins – MO-153
14/16/20/56 Pins – MO-194

RGY (R–PQFP–N16) PLASTIC QUAD FLATPACK



NOTES:
A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M–1994.
B. This drawing is subject to change without notice.
C. QFN (Quad Flatpack No–Lead) package configuration.
D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
E. Pin 1 identifiers are located on both top and bottom of the package and within the zone indicated. The Pin 1 identifiers are either a molded, marked, or metal feature.
F. Package complies to JEDEC MO–241 variation BB.

THERMAL PAD MECHANICAL DATA

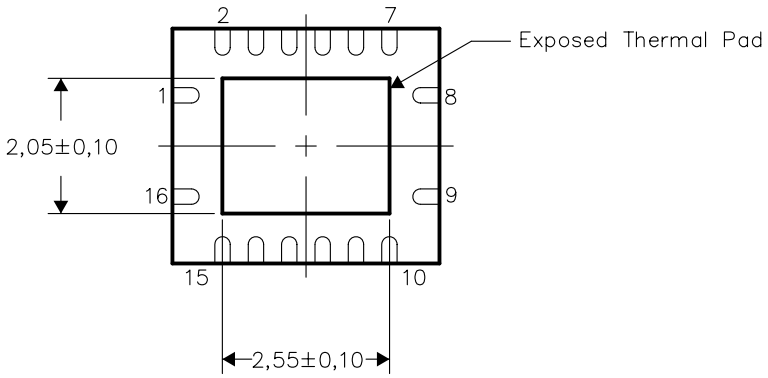
RGY (R–PQFP–N16)

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No–Lead (QFN) package and its advantages, refer to Application Report, Quad Flatpack No–Lead Logic Packages, Texas Instruments Literature No. SCBA017. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

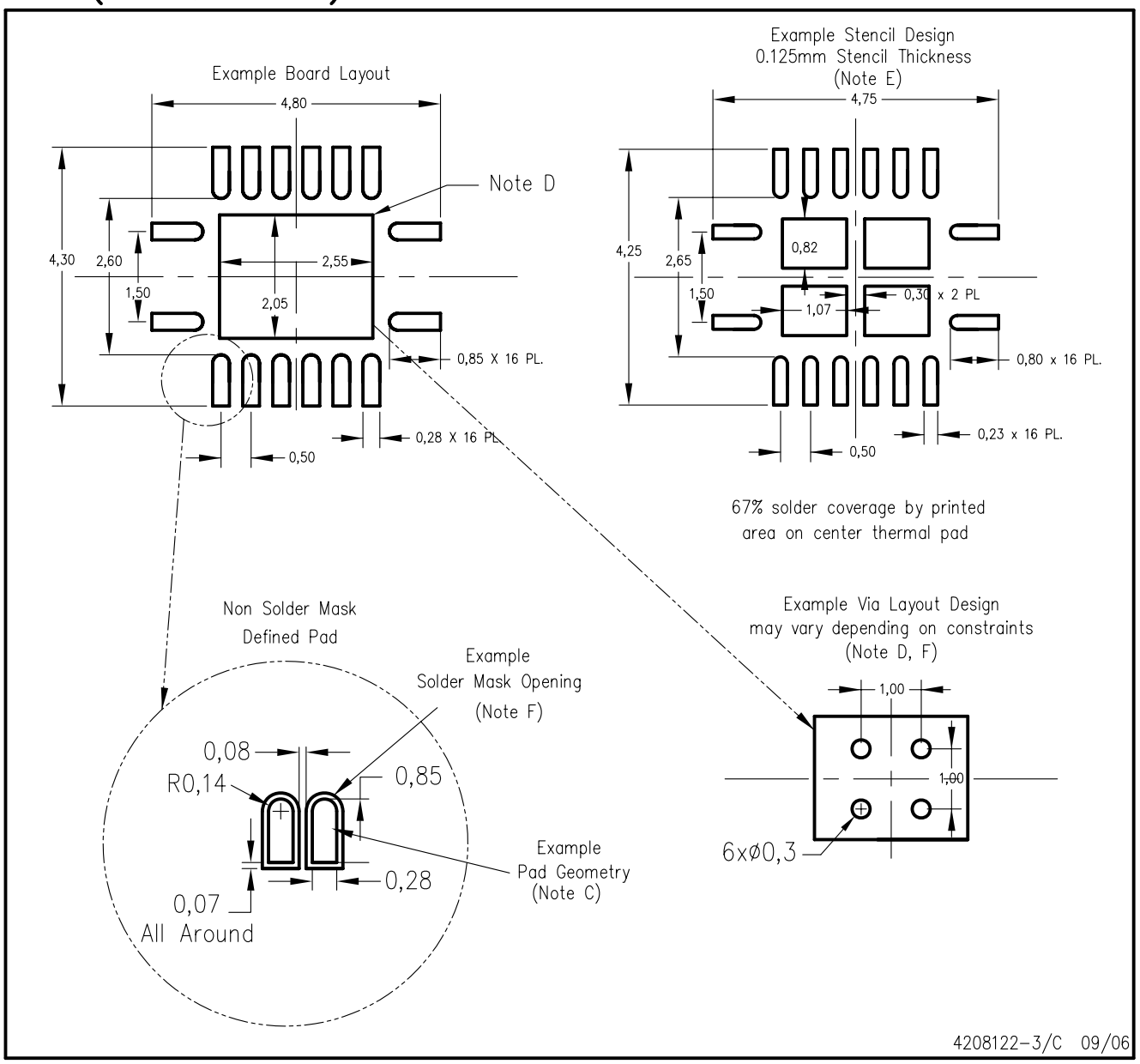


Bottom View

NOTE: All linear dimensions are in millimeters

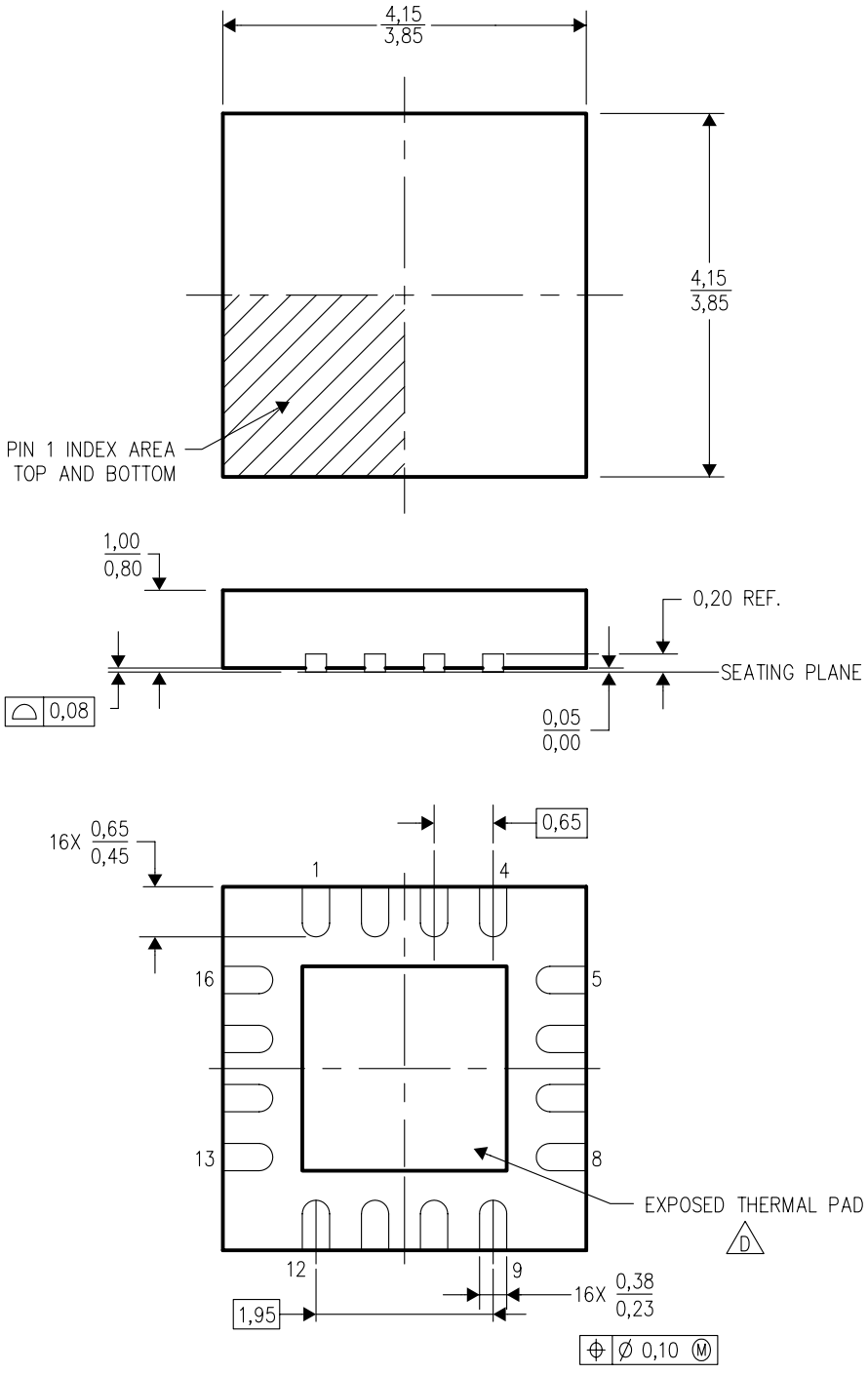
Exposed Thermal Pad Dimensions

RGY (R–PQFP–N16)



NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC–7351 is recommended for alternate designs.
D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat–Pack Packages, Texas Instruments Literature No. SCBA017, SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>.
E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
F. Customers should contact their board fabrication site for minimum solder mask web tolerances between signal pads.

RGV (S–PQFP–N16) PLASTIC QUAD FLATPACK



NOTES:
A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M–1994.
B. This drawing is subject to change without notice.
C. Quad Flatpack, No–leads (QFN) package configuration.
D. The package thermal pad must be soldered to the board for thermal and mechanical performance. See the Product Data Sheet for details regarding the exposed thermal pad dimensions.
E. Falls within JEDEC MO–220.

THERMAL PAD MECHANICAL DATA

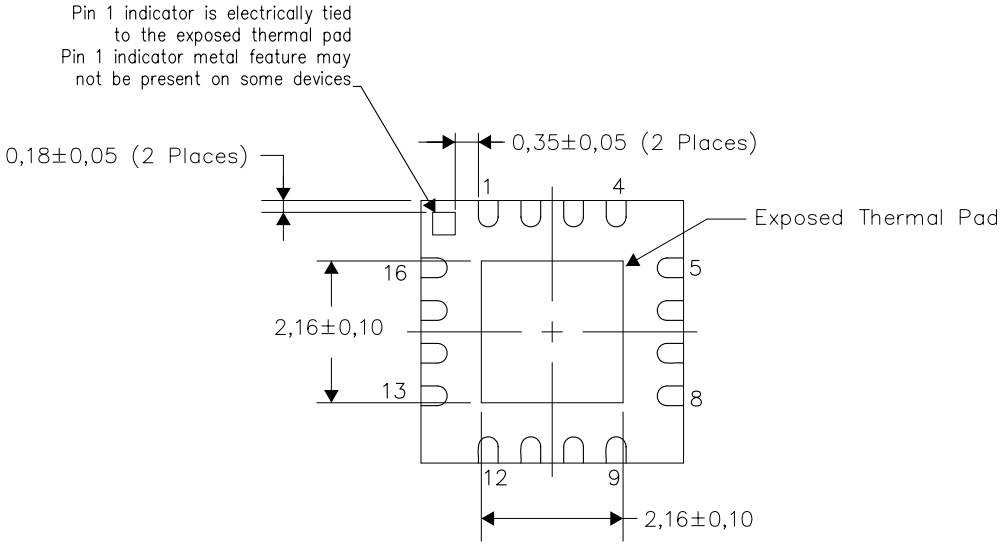
RGV (S–PVQFN–N16)

THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No–Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.

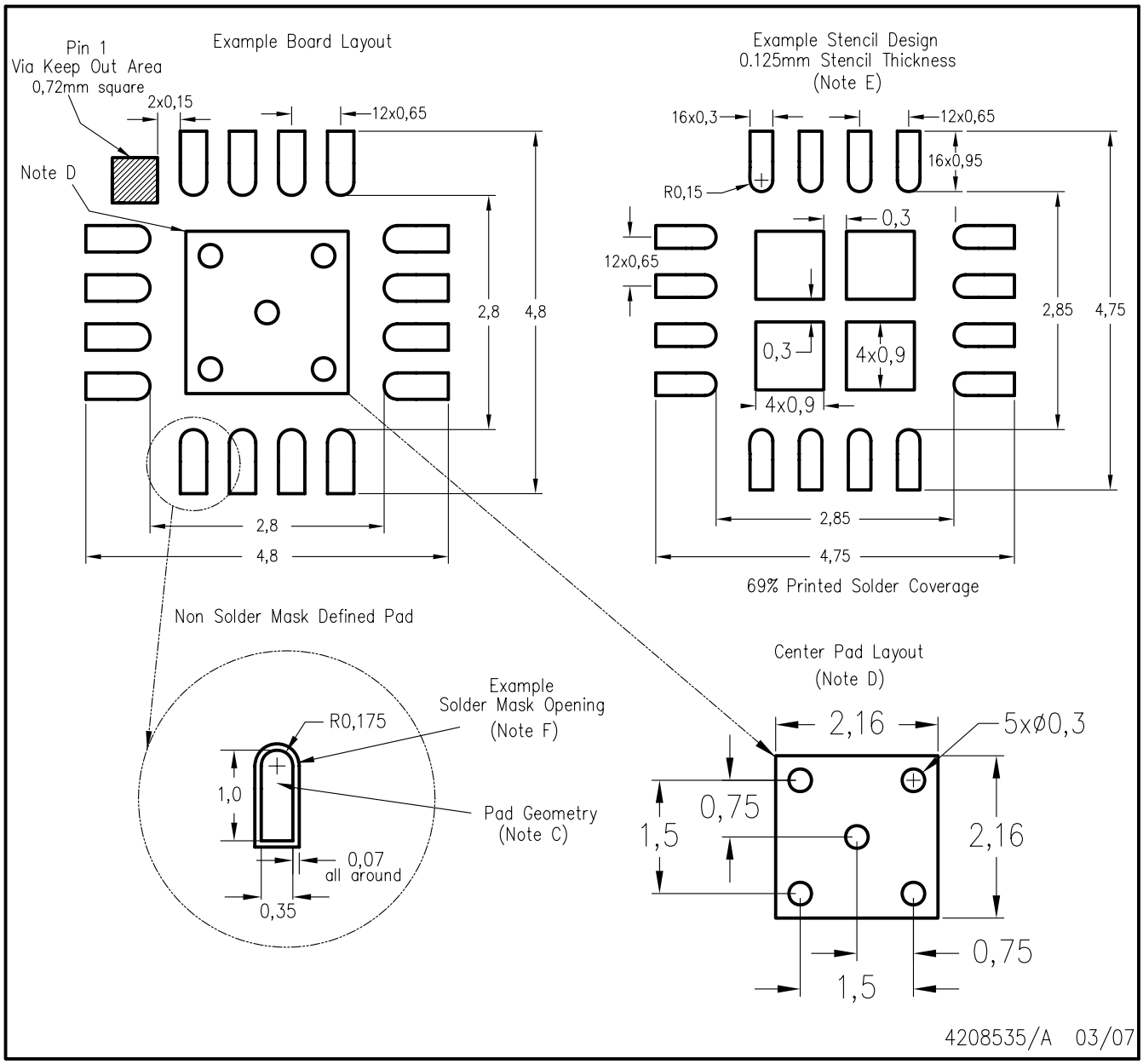


Bottom View

NOTE: All linear dimensions are in millimeters

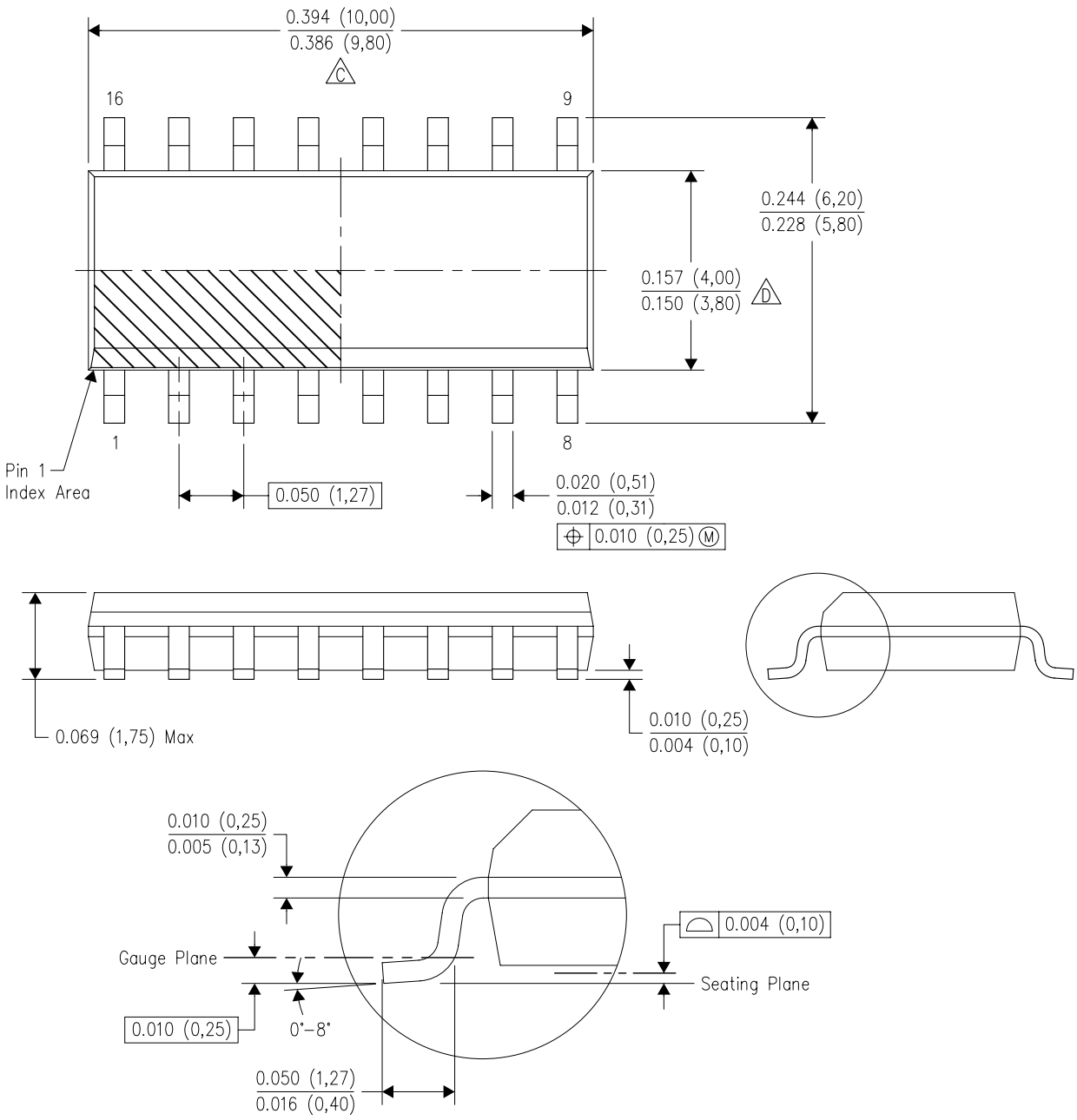
Exposed Thermal Pad Dimensions

RGV (S–PQFP–N16)



NOTES:
A. All linear dimensions are in millimeters.
B. This drawing is subject to change without notice.
C. Publication IPC–7351 is recommended for alternate designs.
D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, QFN Packages, Texas Instruments Literature No. SCBA017, SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>.
E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
F. Customers should contact their board fabrication site for solder mask tolerances.

D (R–PDSO–G16) PLASTIC SMALL–OUTLINE PACKAGE



NOTES:
A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 (0,15) per end.
D. Body width does not include interlead flash. Interlead flash shall not exceed .017 (0,43) per side.
E. Reference JEDEC MS–012 variation AC.

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		Wireless	www.ti.com/wireless

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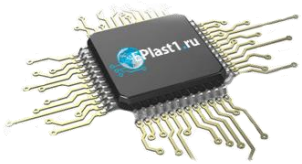

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