

General Description

The MAX34407 is a current and voltage monitor that is specialized for determining power consumption. The device has a wide dynamic range to allow it to accurately measure power in systems that consume small to large amounts of power. The device is configured and monitored with a standard I²C/SMBus serial interface. The unidirectional current sensor offers precision high-side operation with a low full-scale sense voltage. The device automatically collects the current-sense and voltage samples. The samples are then multiplied to obtain a power value and the power values are then accumulated. Upon a command from the host, the device transfers the accumulated power samples as well as the accumulation count to a set of registers that the host can access. This transfer occurs without missing a sample and allows the host to retrieve the data not in real time, but at any time interval.

Applications

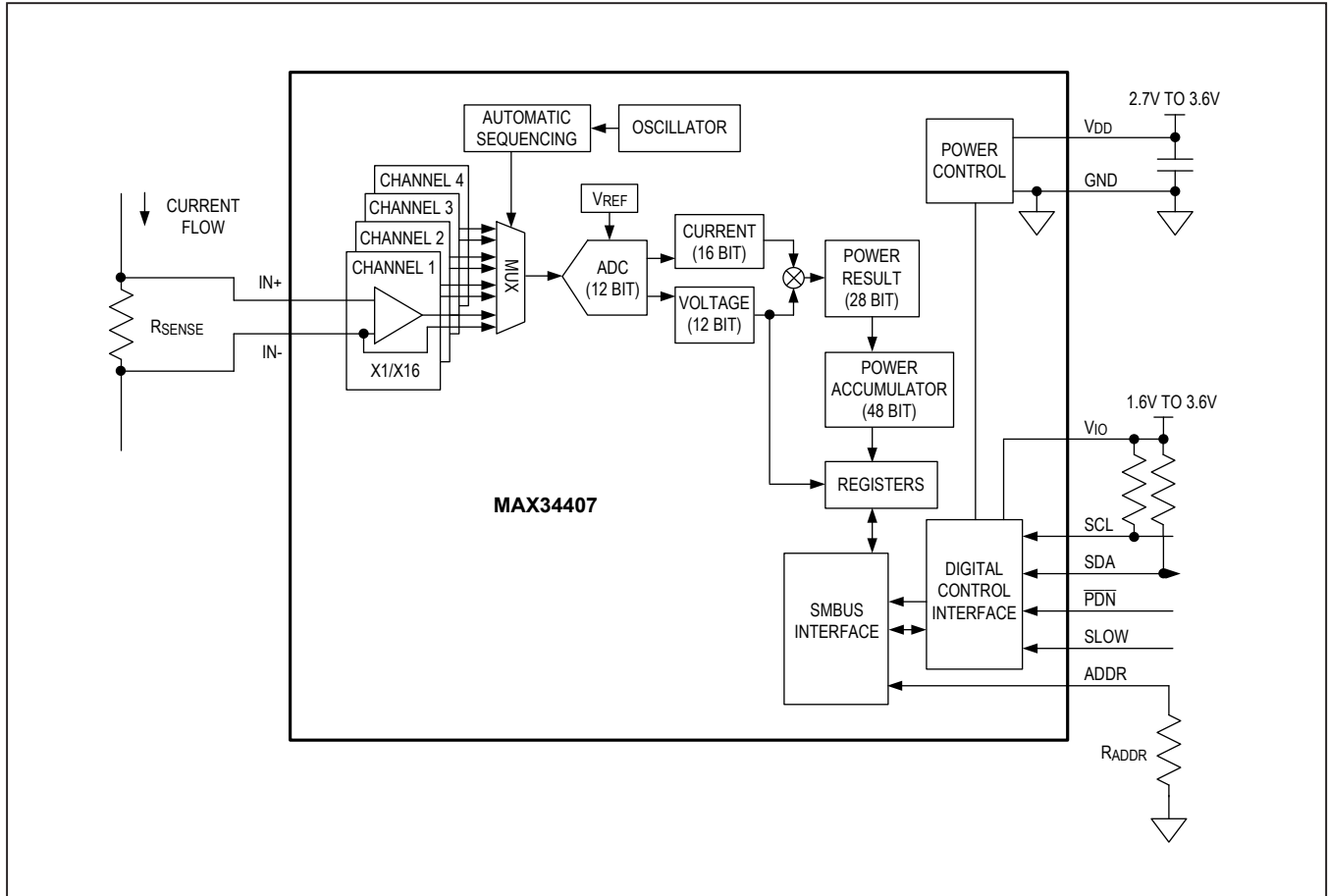
- Tablets
- Ultra Notebooks
- Smartphones

Ordering Information appears at end of data sheet.

Features and Benefits

- Enables Code Optimization to Minimize Power Consumption in Portable Platforms
 - Four Power Monitors with Wide 66dB Dynamic Range
 - Measures Both Current and Voltage
 - Low Power Consumption
 - Slow Mode for Reduced Power Consumption
 - Power-Down Mode
- Minimizes Processor Overhead with Autonomous Operation
 - Per Channel 48-Bit Power Accumulators Capture 17 Minutes of Data at 1024 Samples per Second
 - Per Channel 12-Bit Voltage Registers
- High-Integration Solution Minimizes Parts Count, PCB Space, and BOM Cost
 - Wide Current Common-Mode Range of 2.5V to 15V
 - Low Full-Scale, Current-Sense Voltage of 100mV
 - I²C/SMBus Interface
 - Temperature Range: -40°C to +85°C
 - Small, 2.285mm x 2.185mm Footprint WLP Package with 16 Bumps at 0.5mm Pitch
- Ease of Development
 - Evaluation Kit with Advanced GUI Available (MAX34407EVKIT#)
 - Windows Driver Available

Typical Application Circuit and Block Diagram



Absolute Maximum Ratings

IN+ and IN- to GND.....-0.3V to +16V
 Differential Input Voltage, IN+ to IN-±16V
 V_{DD} or V_{IO} to GND-0.3V to +4V
 SDA or SCL to GND.....-0.3V to +4V
 All Other Pins-0.3V to V_{IO} + 0.3V (not to exceed +4V)

Operating Temperature Range..... -40°C to +85°C
 Storage Temperature Range..... -55°C to +125°C
 Soldering Temperature See the IPC/JEDEC
 J-STD-020A Specification

Package Thermal Characteristics (Note 1)

WLP

Junction-to-Ambient Thermal Resistance (θ_{JA})49°C/W

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Electrical Characteristics

(V_{DD} = 2.7V to 3.6V, V_{IO} = 1.6V to 3.6V, T_A = -40°C to +85°C, unless otherwise noted. Typical values are T_A = +25°C.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|-----------------|---|-----|------|-----|-------|
| V _{DD} Operating Range | | | 2.7 | | 3.6 | V |
| V _{DD} Average Supply Current (Note 2) | I _{DD} | P _{DN} = V _{IO} and SLOW = GND | | 300 | 450 | μA |
| | | P _{DN} = V _{IO} and SLOW = V _{IO} | | 2.4 | 4 | μA |
| | | P _{DN} = GND | | 0.7 | 2 | μA |
| V _{IO} Operating Range | | | 1.6 | | 3.6 | V |
| V _{IO} Average Supply Current (Note 2) | I _{IO} | | | 0.2 | 1 | μA |
| Common-Mode Voltage Range (Note 3) | V _{CM} | | 2.5 | | 15 | V |
| IN+ Average Input Bias Current (Note 3) | | P _{DN} = GND or SLOW = V _{IO} | | 1 | | μA |
| | | V _{CM} = 2.5V and V _{SENSE} = 0mV P _{DN} = V _{IO} and SLOW = GND | | 3.1 | | |
| | | V _{CM} = 1.5V and V _{SENSE} = 0mV P _{DN} = V _{IO} and SLOW = GND | | 4.8 | | |
| Per Channel Current and Voltage Sample Rate | | SLOW = GND | | 1024 | | sps |
| | | SLOW = V _{IO} | | 8 | | sps |
| Per Channel Power Calculation Rate | | SLOW = GND | | 1024 | | sps |
| | | SLOW = V _{IO} | | 8 | | sps |
| Current Sample Resolution | | V _{SENSE} < 4mV | | 16 | | Bits |
| Voltage Sample Resolution | | | | 12 | | Bits |
| Current-Sense Full Scale | | | | 100 | | mV |
| Voltage-Sense Full Scale | | | | 16 | | V |
| Power Measurement Accumulation Accuracy (1 Sigma Error Range with > 1000 Accumulations) (Note 4) | | V _{SENSE} = 97mV | | ±0.8 | | % |
| | | V _{SENSE} = 10mV | | ±1 | | |
| | | V _{SENSE} = 1mV | | ±1.5 | | |
| | | V _{SENSE} = 100μV | | ±8 | | |
| | | V _{SENSE} = 50μV | | ±15 | | |

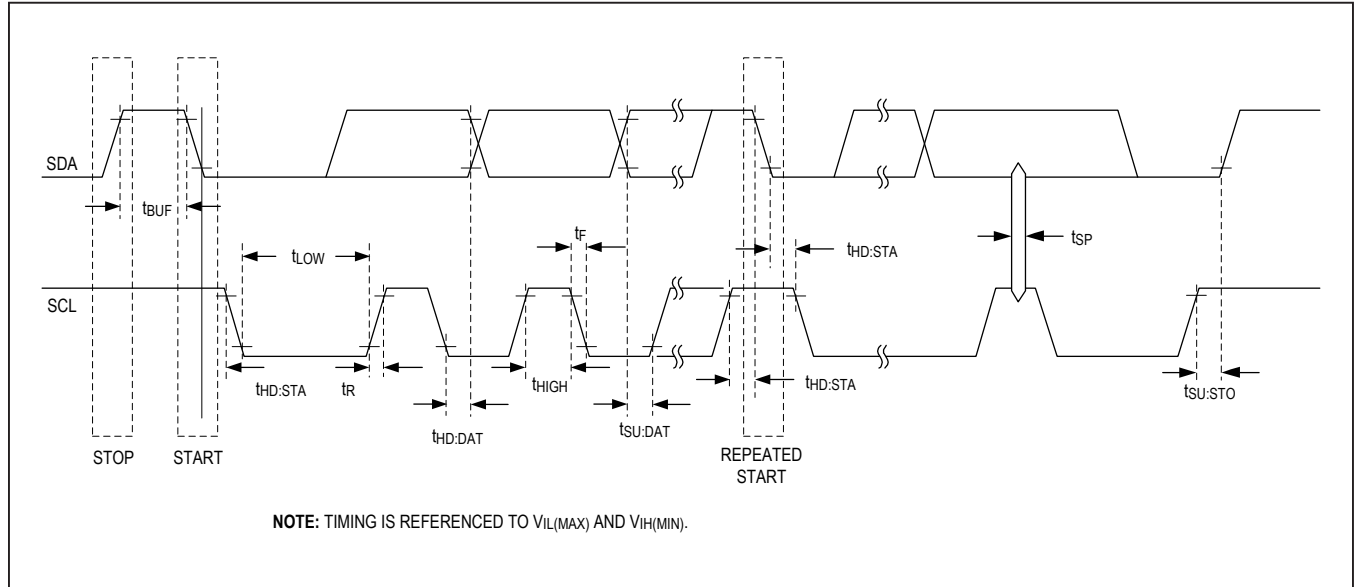
Electrical Characteristics (continued)(V_{DD} = 2.7V to 3.6V, V_{IO} = 1.6V to 3.6V, T_A = -40°C to +85°C, unless otherwise noted. Typical values are T_A = +25°C.)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--------------------------------------|-----------------|---|---------------------------|-----|---------------------------|-------|
| Input Bandwidth | | | | 200 | | kHz |
| Input Logic-High SCL/SDA/PDN/SLOW | V _{IH} | | 0.75 x V _{IO} | | | V |
| Input Logic-Low SCL/SDA/PDN/SLOW | V _{IL} | | | | 0.25 x V _{IO} | V |
| SDA Output Logic-Low | V _{OL} | I _{OL} = 4mA | | | 0.4 | V |
| SDA Output Leakage | | | | | ±1 | µA |
| SCL, SDA Leakage | | | | | ±5 | µA |
| SLOW, PDN Leakage | | | | | ±1 | µA |
| Power-Up Time | | Measured from V _{DD} > 2.7V and V _{IO} > 1.6V and PDN deasserted to SMBus port active | | 650 | | µs |

Note 2: SMBus not active.**Note 3:** Common-mode voltage applies to the IN+ and IN- pins.**Note 4:** Not production tested; bench characterization data.**AC Electrical Characteristics: I²C/SMBus Interface**(V_{IO} = 1.6V to 3.6V, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at V_{IO} = 3.3, T_A = +25°C.)

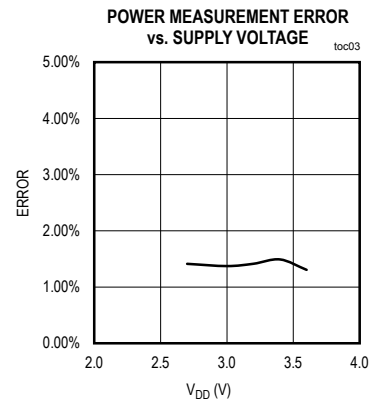
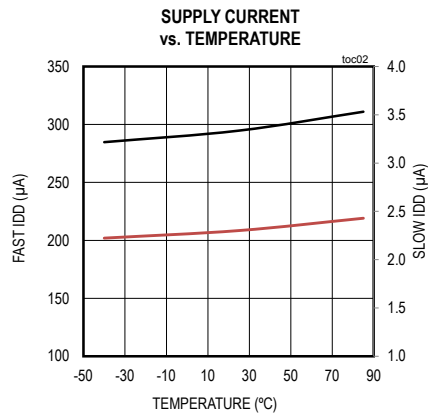
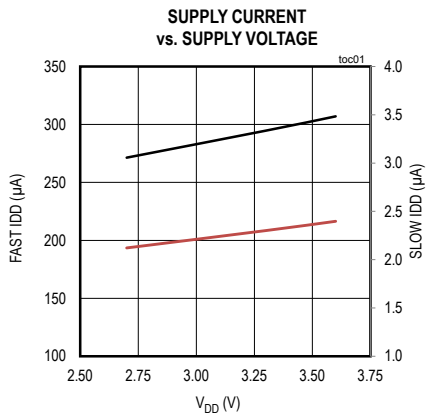
| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|---------------------|------------|-----|-----|-----|-------|
| SCL Clock Frequency | f _{SCL} | | 10 | | 400 | kHz |
| Bus Free Time Between STOP and START Conditions | t _{BUF} | | 1.3 | | | µs |
| Hold Time (Repeated) START Condition | t _{HD:STA} | | 0.6 | | | µs |
| Low Period of SCL | t _{LOW} | | 1.3 | | | µs |
| High Period of SCL | t _{HIGH} | | 0.6 | | | µs |
| Data Hold Time | t _{HD:DAT} | Receive | 0 | | | ns |
| | | Transmit | 300 | | | ns |
| Data Set-Up Time | t _{SU:DAT} | | 100 | | | ns |
| Start Set-Up Time | t _{SU:STA} | | 0.6 | | | µs |
| SDA and SCL Rise Time | t _R | | | | 300 | ns |
| SDA and SCL Fall Time | t _F | | | | 300 | ns |
| Stop Set-Up Time | t _{SU:STO} | | 0.6 | | | µs |
| Noise Spike Reject | t _{SP} | | | 30 | | ns |

I²C/SMBus Timing



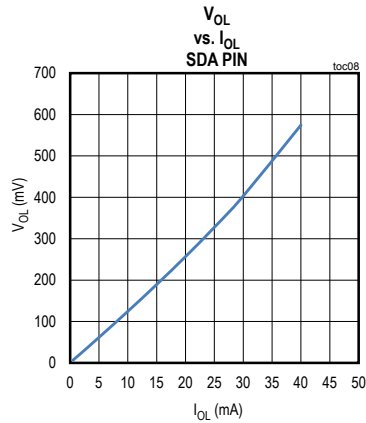
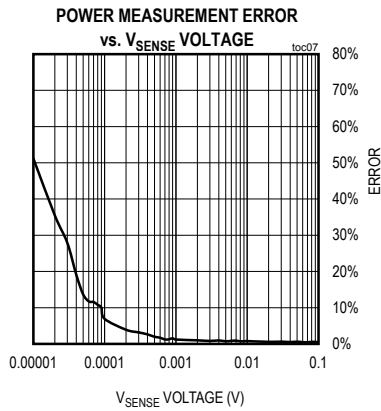
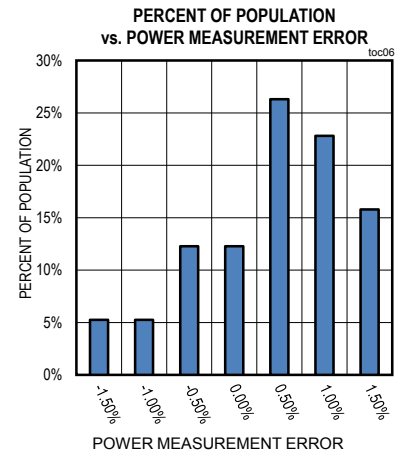
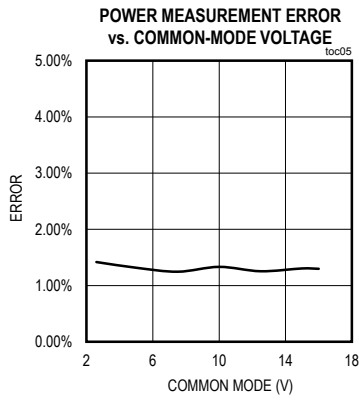
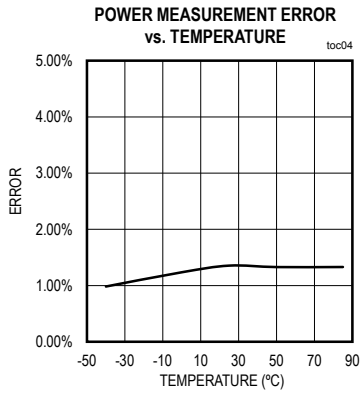
Typical Operating Characteristics

(V_{DD} = V_{IO} = 3.3V, T_A = +25°C, V_{CM} = 5V, V_{SENSE} = 1mV.)

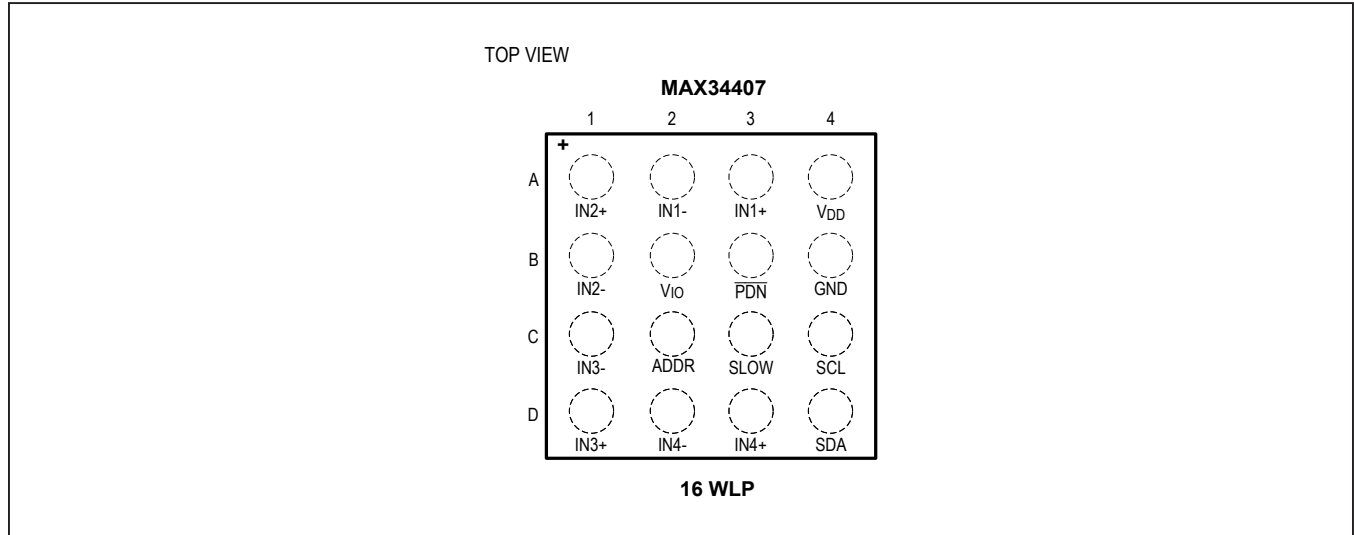


Typical Operating Characteristics (continued)

($V_{DD} = V_{IO} = 3.3V$, $T_A = +25^\circ C$, $V_{CM} = 5V$, $V_{SENSE} = 1mV$.)



Pin Configuration



Pin Description

| PIN | NAME | FUNCTION |
|-----|-----------------|--|
| A1 | IN2+ | External-Sense Resistor Power-Side Connection for Current-Sense Amplifier 2. Voltages can be applied to these pins in the absence of power being applied to V _{DD} or V _{IO} . Unused current-sense inputs should be tied together and left unconnected. |
| A2 | IN1- | External-Sense Resistor Load-Side Connection for Current-Sense Amplifier 1. Voltages can be applied to these pins in the absence of power being applied to V _{DD} or V _{IO} . Unused current-sense inputs should be tied together and left unconnected. |
| A3 | IN1+ | External-Sense Resistor Power-Side Connection for Current-Sense Amplifier 1. Voltages can be applied to these pins in the absence of power being applied to V _{DD} or V _{IO} . Unused current-sense inputs should be tied together and left unconnected. |
| A4 | V _{DD} | Supply Voltage for Current-Sense Amplifiers. +2.7V to +3.6V supply. This pin should be decoupled to GND with a 100nF ceramic capacitor. Power can be applied to V _{DD} either before or after or in the absence of V _{IO} . |
| B1 | IN2- | External-Sense Resistor Load-Side Connection for Current-Sense Amplifier 2. Voltages can be applied to these pins in the absence of power being applied to V _{DD} or V _{IO} . Unused current-sense inputs should be tied together and left unconnected. |
| B2 | V _{IO} | Supply Voltage for Digital Interface. +1.6V to +3.6V supply. This pin should be decoupled to GND with a 100nF ceramic capacitor. Power can be applied to V _{IO} either before or after or in the absence of V _{DD} . |
| B3 | PDN | Power-Down Mode Input. When this pin is tied low, the device is completely powered down including the I ² C/SMBus interface. |
| B4 | GND | Ground Connection |

Pin Description (continued)

| PIN | NAME | FUNCTION |
|-----|------|--|
| C1 | IN3- | External-Sense Resistor Load-Side Connection for Current-Sense Amplifier 3. Voltages can be applied to these pins in the absence of power being applied to V_{DD} or V_{IO} . Unused current-sense inputs should be tied together and left unconnected. |
| C2 | ADDR | I ² C/SMBus-Compatible Address Select Input. A resistor tied to GND from this pin selects the SMBus slave address. See the <i>Addressing</i> section for more details. |
| C3 | SLOW | Slow Accumulate Mode Input. When this pin is tied high, the power accumulation is slowed to reduce overall device power consumption. |
| C4 | SCL | I ² C/SMBus-Compatible Clock Input. SCL does not load the SMBus when either V_{DD} or V_{IO} is not present. |
| D1 | IN3+ | External-Sense Resistor Power-Side Connection for Current-Sense Amplifier 3. Voltages can be applied to these pins in the absence of power being applied to V_{DD} or V_{IO} . Unused current-sense inputs should be tied together and left unconnected. |
| D2 | IN4- | External-Sense Resistor Load-Side Connection for Current-Sense Amplifier 4. Voltages can be applied to these pins in the absence of power being applied to V_{DD} or V_{IO} . Unused current-sense inputs should be tied together and left unconnected. |
| D3 | IN4+ | External-Sense Resistor Power-Side Connection for Current-Sense Amplifier 4. Voltages can be applied to these pins in the absence of power being applied to V_{DD} or V_{IO} . Unused current-sense inputs should be tied together and left unconnected. |
| D4 | SDA | I ² C/SMBus-Compatible Data Input/Output. Output is open drain. SDA does not load the SMBus when either V_{DD} or V_{IO} is not present. |

Detailed Description

The MAX34407 automatically sequences through the channels to collect samples from the common-mode voltage and the current-sense amplifiers. The 16-bit current value and the 12-bit voltage value are then multiplied to create a 28-bit power value that is then written to the power accumulator.

The MAX34407 contains a 48-bit power accumulator for each channel. This accumulator is updated 1024 times per second to allow the device to operate for at least 17 minutes without the host retrieving the results. When the host is ready to pull the latest accumulation data, it first sends the UPDATE command that causes the MAX34407 to load the latest accumulation data and accumulation count into the internal MAX34407 registers so the host can read them at any time. This type of operation allows the host to control the accumulation period. The only constraint is that the host should access the data before the accumulators can overflow. If the accumulators overflow, they do not roll over.

The MAX34407 contains a 12-bit ADC. During each sample time, a 12-bit voltage sample is resolved and a 16-bit current sample. To create a 16-bit current value from the

12-bit ADC, the device takes two current samples; one with the current sense amplifier in a high-gain mode and another with the amplifier in a low-gain mode. The high-gain setting is 16 times the low-gain setting. Based on the two current-sense ADC results, the device determines which result provides the best accuracy and fills the 16-bit current sample accordingly.

SMBus Operation

The MAX34407 uses the SMBus command/response format as described in the System Management Bus Specification Version 2.0. The structure of the data flow between the host and the slave is shown below for several different types of transactions. Data is sent MSB first. The fixed slave address of the MAX34407 is determined on device power-up by sampling the resistor tied to the ADDR pin. See the *Addressing* section for details. On device power-up, the device defaults to the CONTROL command code (01h). If the host sends an invalid command code, the device does not acknowledge (NACK) the command code. If the host attempts to read the device with an invalid command code, all ones (FFh) are returned in the data byte.

Table 1. Read Byte Format

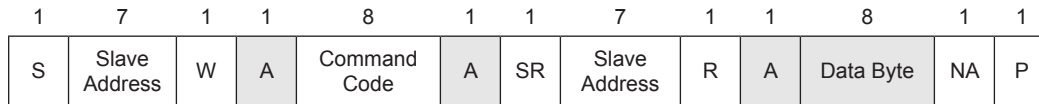


Table 2. Write Byte Format

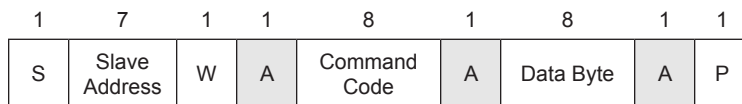


Table 3. Send Byte Format

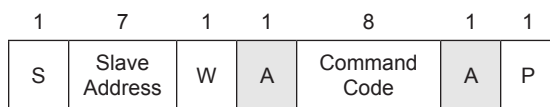
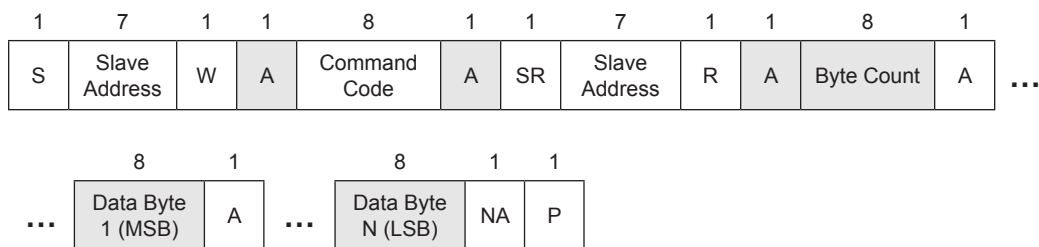


Table 4. Block Read Format



Key:
 S = Start
 SR = Repeated Start
 P = Stop
 W = Write Bit (0)
 R = Read Bit (1)
 A = Acknowledge (0)
 NA = Not Acknowledge (1)
 Shaded Block = Slave Transaction

Addressing

The MAX34407 responds to receiving its fixed slave address by asserting an ACK on the bus. The fixed slave address of the MAX34407 is determined on device

power-up by sampling the resistor tied to the ADDR pin when V_{DD} rises to a valid range. See the [Table 5](#) for more details. The device does not respond to a general call address, only when it receives its fixed slave address.

Table 5. SMBus Slave Address Select

| RADDR ($\pm 1\%$) (k Ω) | SLAVE ADDRESS | RADDR ($\pm 1\%$) (Ω) | SLAVE ADDRESS |
|-----------------------------------|----------------|----------------------------------|----------------|
| 20.5 | 0011 110 (3Ch) | 1.74k | 0010 110 (2Ch) |
| 11.0 | 0011 100 (38h) | 931 | 0010 100 (28h) |
| 5.90 | 0011 010 (34h) | 442 | 0010 010 (24h) |
| 3.16 | 0011 000 (30h) | Tie to GND | 0010 000 (20h) |

Table 6. Command Codes

| COMMAND CODE | NAME | DETAILED DESCRIPTION | TYPE | NUMBER OF BYTES | POR (Note 5) |
|--------------|-----------|---------------------------------|------------|-----------------|--------------|
| 00h | UPDATE | Request Accumulator Update | Send Byte | 0 | — |
| 01h | CONTROL | Device Configuration and Status | R/W Byte | 1 | 00h |
| 02h | ACC_COUNT | Accumulator Counter | Block Read | 3 | Note 6 |
| 03h | PWR_ACC_1 | Power Accumulator for Channel 1 | Block Read | 6 | Note 6 |
| 04h | PWR_ACC_2 | Power Accumulator for Channel 2 | Block Read | 6 | Note 6 |
| 05h | PWR_ACC_3 | Power Accumulator for Channel 3 | Block Read | 6 | Note 6 |
| 06h | PWR_ACC_4 | Power Accumulator for Channel 4 | Block Read | 6 | Note 6 |
| 07h | VOLTAGE_1 | Voltage for Channel 1 | Block Read | 2 | Note 6 |
| 08h | VOLTAGE_2 | Voltage for Channel 2 | Block Read | 2 | Note 6 |
| 09h | VOLTAGE_3 | Voltage for Channel 3 | Block Read | 2 | Note 6 |
| 0Ah | VOLTAGE_4 | Voltage for Channel 4 | Block Read | 2 | Note 6 |
| 0Fh | DID | Device ID and Revision | Read Byte | 1 | Note 7 |

Note 5: The acronym POR means power-on reset. This is the default value when power is applied to the device.

Note 6: These registers are set to all zeros upon POR.

Note 7: The device ID is factory set and varies based on the die revision.

Update (00h)—Send Byte

The UPDATE send byte command does not contain any data. The UPDATE command must be sent to the device before reading any of the other commands, and it must be sent after writing to the CONTROL command. After sending the UPDATE command, the host should wait

at least 500µs before reading any command. Each time the device receives this command, it transfers the all of the data in the power accumulators and the accumulator counter to a set of registers that can be read with the SMBus interface, and it resets all of the counters. See [Figure 1](#) for more details.

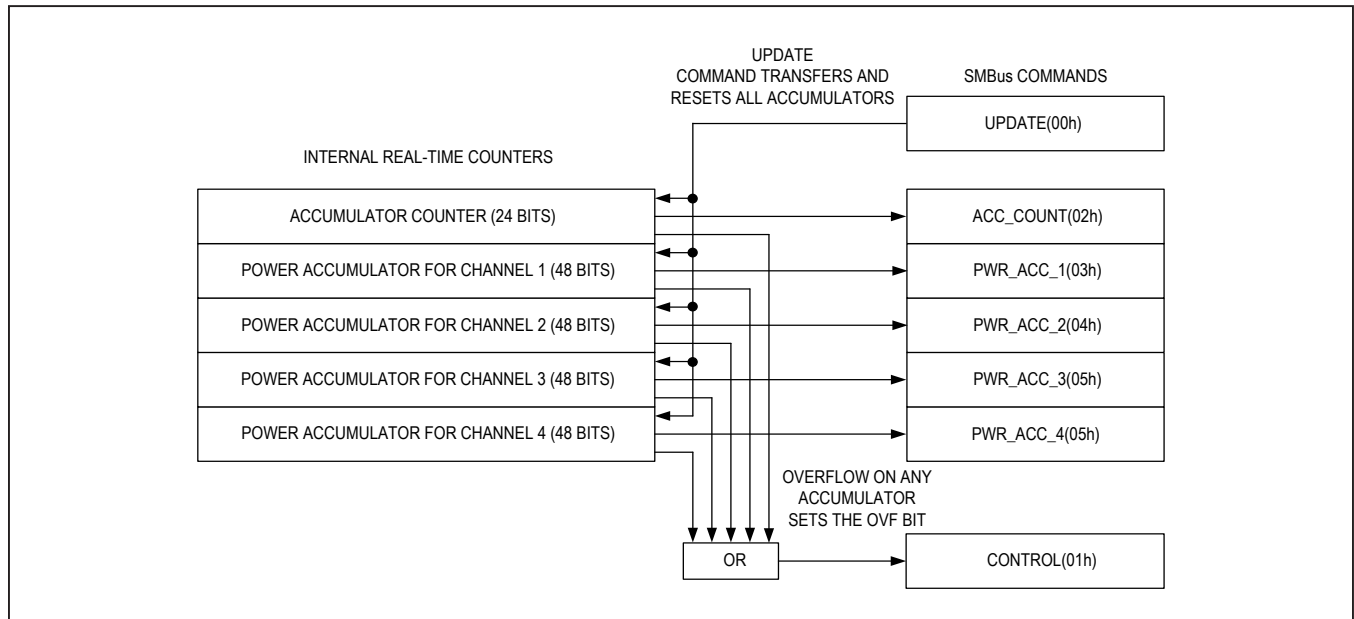


Figure 1. MAX34407 Register Structure

Table 7. Control (01h)—R/W Byte

| | BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |
|-------|-------|-------|-------|---------|-------|-------|-------|-------|
| NAME: | 0 | 0 | SMM | PARK_EN | PARK1 | PARK0 | SLOW | OVF |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Note: Bit positions 6 and 7 must be written to 0 for proper device operation.

Bit 5: SMM (Single Measure Mode)

When this bit is set, the device performs only one measure and accumulation cycle for the four input channels (normal scan mode) or four samples of one channel in channel park mode in response to an UPDATE command. The data can be read by issuing another UPDATE command that moves the previous UPDATE data into the SMBus read registers and starts another measurement cycle. Data should be read between UPDATE commands. UPDATE commands should be no less than 500µs apart for reliable measurements. The power accumulators remain at 48-bits even though the single calculated power is a 28-bit value. After the SMM bit is changed, the UPDATE command should be sent to reset the accumulators and perform the selected scan operation.

0 = Single-measure mode is disabled.

1 = Single-measure mode is enabled.

Bit 4: PARK_EN

This bit enables the channel park feature. If this bit is set, only one channel is enabled, and the device samples the selected channel four times faster than the normal round robin rate. The channel to monitor is selected with the PARK0 and PARK1 bits. After the PARK_EN bit is changed, the UPDATE command should be sent to clear out the accumulators and start a new accumulation period. When the channel park feature is enabled, the minimum time before the power accumulators can overflow reduces by a factor of four since the selected channel is being updated four times faster. Also, the power accumulators for the disabled channels do not contain any meaningful data.

0 = Round-robin sampling of all four channels.

1 = One channel is selected (with the PARK0/1 bits).

Bits 3 to 2: PARK1 to PARK0

If the PARK_EN (Park Enable) bit is set, then these bits select which channel is to be monitored at the exclusion of the other channels.

| PARK1 | PARK0 | SELECTED CHANNEL |
|-------|-------|------------------|
| 0 | 0 | Channel 1 |
| 0 | 1 | Channel 2 |
| 1 | 0 | Channel 3 |
| 1 | 1 | Channel 4 |

Bit 1: SLOW

This bit is logically OR'ed with the SLOW input pin. If either this bit is set or the SLOW pin is high, then the power accumulation calculation rate is slowed in order to lower the power consumption of the device.

Bit 0: OVF

This status bit is set to a one if any of the power accumulators or the accumulator counter overflows. When the accumulators or counter overflow, they do not roll over. This status bit can be cleared by writing a 0. If any of the power accumulators or the accumulator counter are still full, then this bit immediately sets again. Accumulators and the counter that have overflowed can be cleared by sending the UPDATE command.

Table 8. Accumulator Counter (02h)—Block Read

| | | | | | | | | |
|-------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| | BIT 23 | BIT 22 | BIT 21 | BIT 20 | BIT 19 | BIT 18 | BIT 17 | BIT 16 |
| NAME: | CNT23 | CNT22 | CNT21 | CNT20 | CNT19 | CNT18 | CNT17 | CNT16 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | BIT 15 | BIT 14 | BIT 13 | BIT 12 | BIT 11 | BIT 10 | BIT 9 | BIT 8 |
| NAME: | CNT15 | CNT14 | CNT13 | CNT12 | CNT11 | CNT10 | CNT9 | CNT8 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |
| NAME: | CNT7 | CNT6 | CNT5 | CNT4 | CNT3 | CNT2 | CNT1 | CNT0 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 23 to 0: CNT23 to CNT0

These bits report the number of times the accumulators have been updated. Send the UPDATE command before reading this register. By dividing the total accumulated power reported in each power accumulator by this count, the average power can be determined. The accumulator counter does not roll over. If the accumulator counter overflows, the OVF bit in the CONTROL command is set and remains set until the UPDATE command is sent.

Table 9. Power Accumulator for Channel 1 (03h)—Block Read
Power Accumulator for Channel 2 (04h)—Block Read
Power Accumulator for Channel 3 (05h)—Block Read
Power Accumulator for Channel 4 (06h)—Block Read

| | | | | | | | | |
|-------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|---------------|
| | BIT 47 | BIT 46 | BIT 45 | BIT 44 | BIT 43 | BIT 42 | BIT 41 | BIT 40 |
| NAME: | ACC47 | ACC46 | ACC45 | ACC44 | ACC43 | ACC42 | ACC41 | ACC40 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | BIT 39 | BIT 38 | BIT 37 | BIT 36 | BIT 35 | BIT 34 | BIT 33 | BIT 32 |
| NAME: | ACC39 | ACC38 | ACC37 | ACC36 | ACC35 | ACC34 | ACC33 | ACC32 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | BIT 31 | BIT 30 | BIT 29 | BIT 28 | BIT 27 | BIT 26 | BIT 25 | BIT 24 |
| NAME: | ACC31 | ACC30 | ACC29 | ACC28 | ACC27 | ACC26 | ACC25 | ACC24 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | BIT 23 | BIT 22 | BIT 21 | BIT 20 | BIT 19 | BIT 18 | BIT 17 | BIT 16 |
| NAME: | ACC23 | ACC22 | ACC21 | ACC20 | ACC19 | ACC18 | ACC17 | ACC16 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | BIT 15 | BIT 14 | BIT 13 | BIT 12 | BIT 11 | BIT 10 | BIT 9 | BIT 8 |
| NAME: | ACC15 | ACC14 | ACC13 | ACC12 | ACC11 | ACC10 | ACC9 | ACC8 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |
| NAME: | ACC7 | ACC6 | ACC5 | ACC4 | ACC3 | ACC2 | ACC1 | ACC0 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Bits 47 to 0: ACC47 to ACC0

These bits report the total power accumulated by each channel. Send the UPDATE command before reading these registers. The power accumulators do not roll over. If any of the power accumulator overflows, the OVF bit in the CONTROL command is set and remains set until the UPDATE command is sent.

**Table 10. Voltage for Channel 1 (07h)—Block Read
Voltage for Channel 2 (08h)—Block Read
Voltage for Channel 3 (09h)—Block Read
Voltage for Channel 4 (0Ah)—Block Read**

| | BIT 15 | BIT 14 | BIT 13 | BIT 12 | BIT 11 | BIT 10 | BIT 9 | BIT 8 |
|-------|--------|--------|--------|--------|--------|--------|-------|-------|
| NAME: | V11 | V10 | V9 | V8 | V7 | V6 | V5 | V4 |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |
| NAME: | V3 | V2 | V1 | V0 | N/A | N/A | N/A | N/A |
| POR: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Note: Bit positions marked as N/A are not assigned and have no meaning. These bits can be either 0 or 1 when read.

Bits 15 to 4: V11 to V0

These bits report the last measured common-mode voltage for each channel. The LSB bit weighting is 3.9mV (16V full scale/4096). The UPDATE command must be sent before reading the channel voltages. The host should wait 500µs after sending the UPDATE command before reading the VOLTAGE commands.

Table 11. Device ID & Revision Register (0Fh)—Read Byte

| | BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |
|-------|-------|-------|-------|-------|-------|-------------|-------|-------|
| NAME: | ID4 | ID3 | ID2 | ID1 | ID0 | REV2 | REV1 | REV0 |
| POR: | 0 | 0 | 1 | 0 | 1 | Factory set | | |

Bits 7 to 3: ID4 to ID0

These bits report the device identification (ID). The ID is fixed at 05h.

Bits 2 to 0: REV2 to REV0

These bits report the device revision. The device revision is factory set.

Applications Information**Average Power Calculation Example**

The average power can be derived in an external calculation as shown below if the current sense resistor value is known.

Power accumulator (48 bit) = 0001CEFBD314h (7767577364 decimal)

Accumulator counter (24 bit) = 0005DEh (1502 decimal)

Current-sense resistor = 10mΩ

Step 1

Calculate the unscaled average power by dividing the power accumulator value with the accumulator *count value*:

0001CEFBD314h/0005DEh = 4EE921h (5171489 decimal)

Step 2

Calculate the ratio of the Step 1 result to the calculated power full-scale value which is a 28-bit value:

5171489/2²⁸ = 0.019265

Step 3

Multiply the result from Step 2 by the correction factor listed in [Table 12](#) that matches the current-sense resistor value:
 $0.019265 \times 160 = 3.08W$

Table 12. Correction Factors for Various Current-Sense Resistor Values

| CURRENT-SENSE RESISTOR VALUE (mΩ) | FULL-SCALE CURRENT (A) | FULL-SCALE VOLTAGE (V) | POWER SCALE CORRECTION CALCULATION | POWER SCALE CORRECTION FACTOR (W) |
|-----------------------------------|------------------------|------------------------|------------------------------------|-----------------------------------|
| 100 | 1 | 16 | 1 x 16 | 16 |
| 50 | 2 | 16 | 2 x 16 | 32 |
| 40 | 2.5 | 16 | 2.5 x 16 | 40 |
| 25 | 4 | 16 | 4 x 16 | 64 |
| 20 | 5 | 16 | 5 x 16 | 80 |
| 15 | 6.667 | 16 | 6.667 x 16 | 106.667 |
| 10 | 10 | 16 | 10 x 16 | 160 |
| 5 | 20 | 16 | 20 x 16 | 320 |
| 4 | 25 | 16 | 25 x 16 | 400 |
| 2 | 50 | 16 | 50 x 16 | 800 |
| 1 | 100 | 16 | 100 x 16 | 1600 |

Kelvin Sense

For best performance, a Kelvin sense arrangement is recommended. See [Figure 2](#). In a Kelvin sense arrangement, the voltage sensing nodes across the sense element are placed so that they measure the true voltage drop across the sense element and not any additional excess voltage drop that can occur in the copper PCB traces or the solder mounting of the sense element. Routing the differential sense lines along the same path to the MAX34407 and keeping the path short also improve the system performance.

Minimizing Trace Resistance

PCB trace resistance from the sense resistor (RSENSE) to the IN+ inputs can affect the MAX34407 power measurement accuracy. Every 1 ohm of PCB trace resistance will add about 25µV of error. It is recommended to place the sense resistors as close as possible to the MAX34407 and not to use minimum width PCB traces.

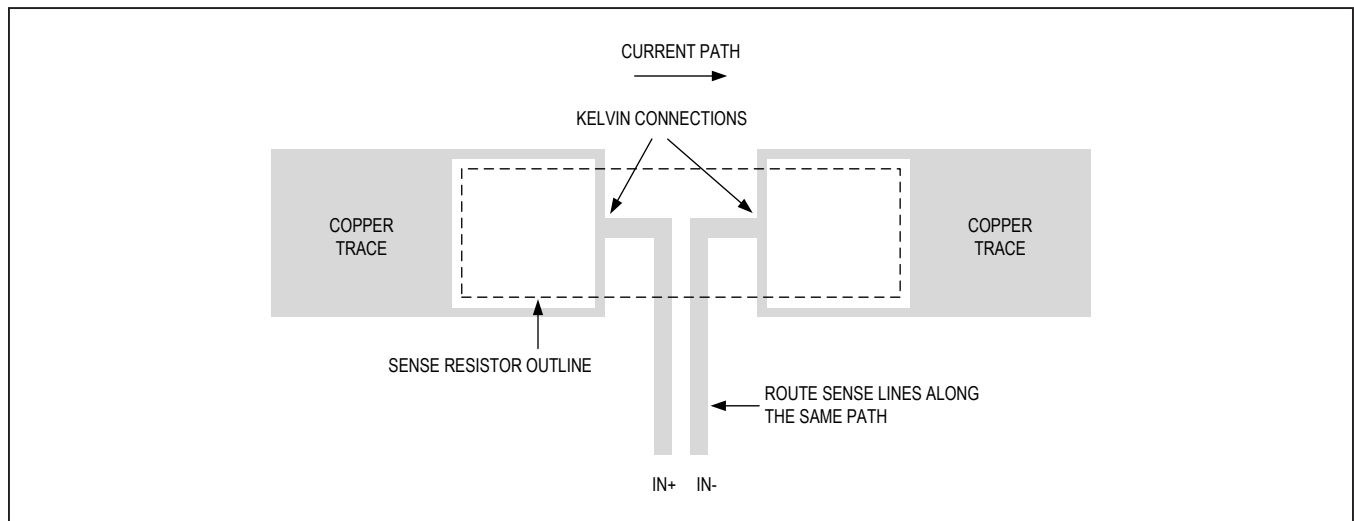


Figure 2. Kelvin Sense Connection Layout Example

Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE |
|---------------|----------------|-------------|
| MAX34407EWE+ | -40°C to +85°C | 16 WLP |
| MAX34407EWE+T | -40°C to +85°C | 16 WLP |

+Denotes a lead(Pb)-free/RoHS-compliant package.
T = Tape and reel.

Package Information

For the latest package outline information and land patterns (footprints), go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

| PACKAGE TYPE | PACKAGE CODE | OUTLINE NO. | LAND PATTERN NO. |
|--------------|--------------|-------------------------|--|
| 16 WLP | W16N2+1 | 21-0893 | Refer to Application Note 1891 |

Revision History

| REVISION NUMBER | REVISION DATE | DESCRIPTION | PAGES CHANGED |
|-----------------|---------------|-----------------|---------------|
| 0 | 11/14 | Initial release | — |

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at www.maximintegrated.com.

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- Техническая поддержка проекта;
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