

# High Current Synchronous Step-Down LED Driver with Three-State Control

## FEATURES

- **PWM Dimming Provides Up to 3000:1 Dimming Ratio**
- **CTRL\_SEL Dimming Provides Up to 3000:1 Dimming Ratio Between Any Current**
- **Three-State Current Control for Color Mixing**
- **±6% Current Regulation Accuracy**
- **6V to 36V Input Voltage Range**
- **Average Current Mode Control**
- **2μs Maximum Recovery Time Between Any Current Regulation State**
- **<1μA Shutdown Current**
- **Output Voltage Regulation and Open-LED Protection**
- **Thermally Enhanced 4mm × 5mm QFN and 28-Pin FE Package**

## APPLICATIONS

- DLP Projectors
- High Power Architectural Lighting
- Laser Diodes

## DESCRIPTION

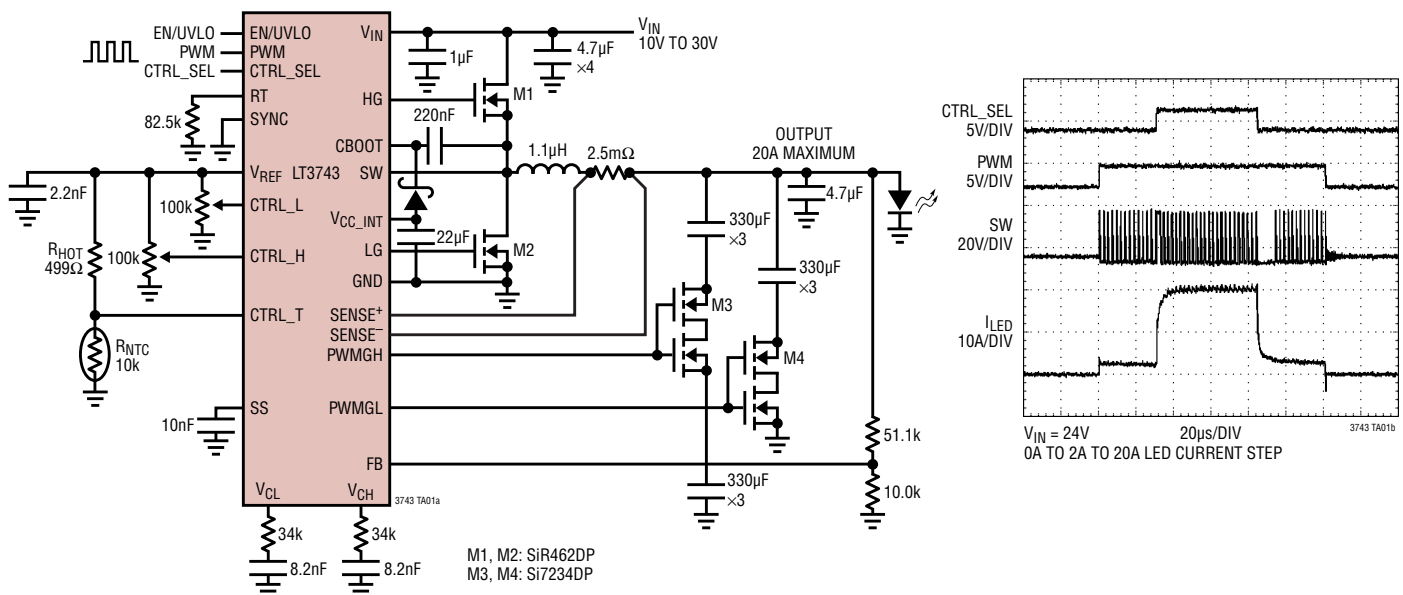
The LT<sup>®</sup>3743 is a fixed frequency synchronous step-down DC/DC controller designed to drive high current LEDs. The average current mode controller will maintain inductor current regulation over a wide output voltage range of 0V to ( $V_{IN} - 2V$ ). LED dimming is achieved through analog dimming on the CTRL\_L, CTRL\_H and CTRL\_T pins and with PWM dimming on the PWM and CTRL\_SEL pins. Through the use of externally switched load capacitors, the LT3743 is capable of changing regulated LED current levels within several  $\mu$ s, providing accurate, high speed PWM dimming between two current levels. The switching frequency is programmable from 200kHz to 1MHz through an external resistor on the RT pin.

Additional features include voltage regulation and overvoltage protection set with a voltage divider from the output to the FB pin. Overcurrent protection is provided and set by the CTRL\_H pin.

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## TYPICAL APPLICATION

## 92% Efficient 20A LED Driver

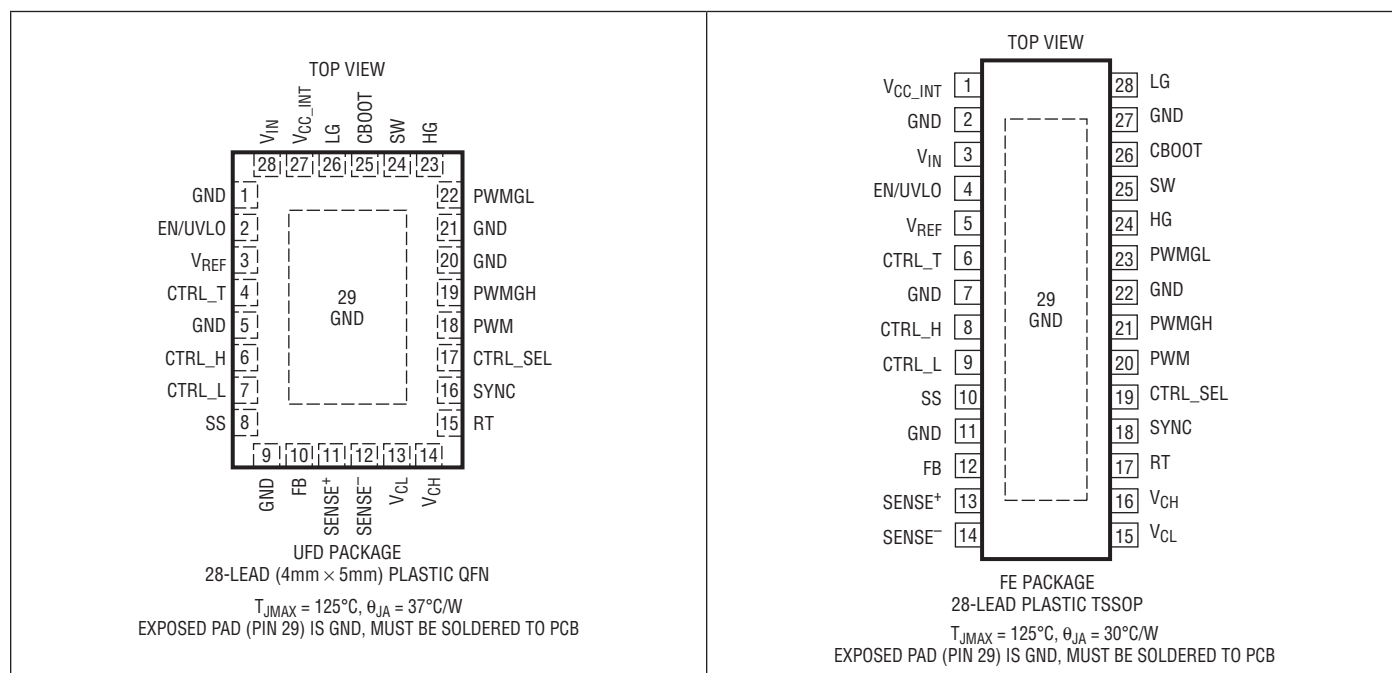


# LT3743

## ABSOLUTE MAXIMUM RATINGS (Note 1)

|                                     |     |                                      |                |
|-------------------------------------|-----|--------------------------------------|----------------|
| $V_{IN}$ Voltage.....               | 40V | CBOOT .....                          | 46V            |
| EN/UVLO Voltage.....                | 6V  | RT Voltage .....                     | 3V             |
| $V_{REF}$ Voltage.....              | 3V  | FB Voltage.....                      | 3V             |
| CTRL_L, CTRL_H, CTRL_T Voltage..... | 3V  | SS Voltage .....                     | 6V             |
| PWM, CTRL_SEL Voltage.....          | 6V  | SYNC Voltage.....                    | 6V             |
| SENSE <sup>+</sup> Voltage .....    | 40V | Storage Temperature Range .....      | –65°C to 150°C |
| SENSE <sup>–</sup> Voltage .....    | 40V | Lead Temperature (Soldering, 10 sec) |                |
| $V_{CH}$ , $V_{CL}$ Voltage .....   | 3V  | TSSOP .....                          | 300°C          |
| SW Voltage .....                    | 40V |                                      |                |

## PIN CONFIGURATION



## ORDER INFORMATION (Note 2)

| LEAD FREE FINISH | TAPE AND REEL    | PART MARKING* | PACKAGE DESCRIPTION             | TEMPERATURE RANGE |
|------------------|------------------|---------------|---------------------------------|-------------------|
| LT3743EUFD#PBF   | LT3743EUFD#TRPBF | 3743          | 28-Lead (4mm × 5mm) Plastic QFN | –40°C to 125°C    |
| LT3743IUFD#PBF   | LT3743IUFD#TRPBF | 3743          | 28-Lead (4mm × 5mm) Plastic QFN | –40°C to 125°C    |
| LT3743EFE#PBF    | LT3743EFE#TRPBF  | LT3743FE      | 28-Lead Plastic TSSOP           | –40°C to 125°C    |
| LT3743IFE#PBF    | LT3743IFE#TRPBF  | LT3743FE      | 28-Lead Plastic TSSOP           | –40°C to 125°C    |

Consult LTC Marketing for parts specified with wider operating temperature ranges. \*The temperature grade is identified by a label on the shipping container. Consult LTC Marketing for information on non-standard lead based finish parts.

For more information on lead free part marking, go to: <http://www.linear.com/leadfree/>

For more information on tape and reel specifications, go to: <http://www.linear.com/tapeandree/>

**ELECTRICAL CHARACTERISTICS** The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ .  $V_{IN} = 12\text{V}$ ,  $V_{EN/UVLO} = 5\text{V}$ ,  $V_{SYNC} = 0\text{V}$ ,  $V_{CTRL\_SEL} = 0\text{V}$ ,  $V_{PWM} = 2\text{V}$ , unless otherwise noted.

| PARAMETER                               | CONDITIONS  | MIN  | TYP  | MAX  | UNITS         |
|---|---|------|------|------|---------------|
| Input Voltage Range                     |   | 6    |      | 36   | V             |
| $V_{IN}$ Pin Quiescent Current (Note 3) |   |      |      |      |               |
| Non-Switching Operation                 | $V_{PWM} = V_{CTRL\_SEL} = 0\text{V}$ , Not Switching, $R_T = 40\text{k}$ |      | 1.8  | 2.5  | mA            |
| Shutdown Mode                           | $V_{EN/UVLO} = 0\text{V}$   | ●    | 0.1  | 1    | $\mu\text{A}$ |
| EN/UVLO Pin Falling Threshold           |   | 1.49 | 1.55 | 1.61 | V             |
| EN/UVLO Hysteresis                      |   |      | 130  |      | mV            |
| EN/UVLO Pin Current                     | $V_{IN} = 6\text{V}$ , $EN/UVLO = 1.45\text{V}$                           |      | 5.5  |      | $\mu\text{A}$ |
| PWM Pin Threshold                       |   |      | 1.0  |      | V             |
| CTRL_SEL Threshold                      |   |      | 1.0  |      | V             |
| SYNC Pin Threshold                      |   |      | 1.0  |      | V             |
| CTRL_H and CTRL_L Pin Control Range     |   | 0    |      | 1.5  | V             |
| CTRL_H and CTRL_L Pin Current           |   |      | 100  |      | nA            |

#### Reference

|                                    |   |      |   |      |   |
|------------------------------------|---|------|---|------|---|
| Reference Voltage ( $V_{REF}$ Pin) | ● | 1.96 | 2 | 2.04 | V |
|------------------------------------|---|------|---|------|---|

#### Inductor Current Sensing

|   |   |   |    |    |    |               |
|---|---|---|----|----|----|---------------|
| Full Range SENSE <sup>+</sup> to SENSE <sup>-</sup> | $V_{CTRL\_H} = 1.5\text{V}$ , $V_{SENSE^-} = 6\text{V}$ | ● | 48 | 51 | 54 | mV            |
| SENSE <sup>+</sup> Pin Current                      | $V_{SENSE^+} = V_{SENSE^-} = 6\text{V}$                 |   |    | 50 |    | nA            |
| SENSE <sup>-</sup> Pin Current                      | $V_{SENSE^+} = V_{SENSE^-} = 6\text{V}$                 |   |    | 10 |    | $\mu\text{A}$ |

#### Internal $V_{CC}$ Regulator ( $V_{CC\_INT}$ Pin)

|                    |   |     |   |     |   |
|--------------------|---|-----|---|-----|---|
| Regulation Voltage | ● | 4.7 | 5 | 5.2 | V |
|--------------------|---|-----|---|-----|---|

#### NMOS FET Driver (Note 2)

|                                       |                                  |  |     |  |          |
|---------------------------------------|----------------------------------|--|-----|--|----------|
| Non-Overlap time HG to LG             |                                  |  | 100 |  | ns       |
| Non-Overlap time LG to HG             |                                  |  | 60  |  | ns       |
| Minimum On-Time LG                    | (Note 3)                         |  | 50  |  | ns       |
| Minimum On-Time HG                    | (Note 3)                         |  | 80  |  | ns       |
| Minimum Off-Time LG                   | (Note 3)                         |  | 60  |  | ns       |
| High Side Driver Switch On-Resistance | $V_{CB00T} - V_{SW} = 5\text{V}$ |  |     |  |          |
| Gate Pull Up                          |                                  |  | 2.3 |  | $\Omega$ |
| Gate Pull Down                        |                                  |  | 1.3 |  | $\Omega$ |
| Low Side Driver Switch On-Resistance  | $V_{CC\_INT} = 5\text{V}$        |  |     |  |          |
| Gate Pull Up                          |                                  |  | 2.5 |  | $\Omega$ |
| Gate Pull Down                        |                                  |  | 1.3 |  | $\Omega$ |


#### Switching Frequency

|          |                           |   |     |      |      |     |
|----------|---------------------------|---|-----|------|------|-----|
| $f_{SW}$ | $R_T = 40\text{k}\Omega$  | ● | 900 | 1000 | 1070 | kHz |
|          | $R_T = 200\text{k}\Omega$ |   | 190 | 200  | 233  | kHz |

#### Soft-Start

|                  |  |  |     |  |               |
|------------------|--|--|-----|--|---------------|
| Charging Current |  |  | 5.5 |  | $\mu\text{A}$ |
|------------------|--|--|-----|--|---------------|

#### Voltage Regulation Amplifier

|                             |  |   |       |   |       |                 |
|-----------------------------|--|---|-------|---|-------|-----------------|
| Input Bias Current          |  |   | 1     |   |       | nA              |
| $g_m$                       |  |   | 200   |   |       | $\mu\text{A/V}$ |
| Feedback Regulation Voltage | $V_{\text{CTRL\_H}} = 0\text{V}$ , $V_{\text{CTRL\_L}} = 2\text{V}$ , $V_{\text{SENSE}^+} = 2\text{V}$ |  | 0.945 | 1 | 1.025 | V               |

## ELECTRICAL CHARACTERISTICS

The ● denotes the specifications which apply over the full operating temperature range, otherwise specifications are at  $T_A = 25^\circ\text{C}$ .  $V_{IN} = 12\text{V}$ ,  $V_{EN/UVLO} = 5\text{V}$ , unless otherwise noted.

| PARAMETER  | CONDITIONS  |   | MIN | TYP  | MAX | UNITS           |
|--|---|---|-----|------|-----|-----------------|
| <b>PWMG Control Signals</b>                      |   |   |     |      |     |                 |
| CTRL_SEL High to PWMGL Low Delay                 |   |   |     | 10   | 40  | ns              |
| CTRL_SEL High to PWMGH High Delay                |   |   |     | 150  | 200 | ns              |
| CTRL_SEL Low to PWMGH Low Delay                  |   |   |     | 30   | 60  | ns              |
| CTRL_SEL Low to PWMGL High Delay                 |   |   |     | 170  | 220 | ns              |
| PWMGH and PWMGL Pull-up Impedance                |   |   |     | 3.2  |     | $\Omega$        |
| PWMGH and PWMGL Pull-Down Impedance              |   |   |     | 1.75 |     | $\Omega$        |
| <b>Current Control Loop <math>g_m</math> Amp</b> |   |   |     |      |     |                 |
| Offset Voltage                                   | $V_{SENSE^+} = 4\text{V}$ , $V_{SENSE^-} = 4\text{V}$ | ● | -3  | 0    | 3   | mV              |
| Input Common Mode Range                          | $V_{CM(HIGH)}$ Measured from $V_{IN}$ to $V_{CM}$     |   |     | 0    |     | V               |
| $V_{CM(LOW)}$<br>$V_{CM(HIGH)}$                  |   |   |     | 2    |     | V               |
| Output Impedance                                 |   |   |     | 3.5  |     | $M\Omega$       |
| $g_m$  |   |   | 375 | 475  | 625 | $\mu\text{A/V}$ |
| Differential Gain                                |   |   |     | 1.7  |     | V/mV            |

**Note 1:** Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

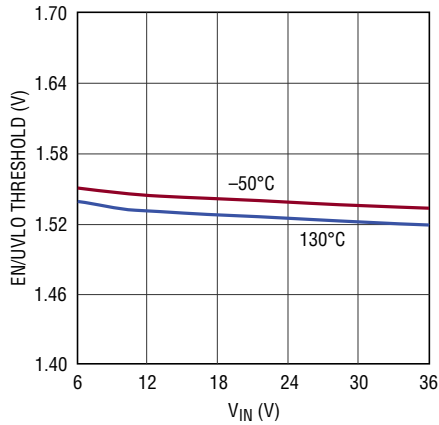
**Note 2:** The LT3743E is guaranteed to meet performance specifications from  $0^\circ\text{C}$  to  $125^\circ\text{C}$  junction temperature. Specifications over the  $-40^\circ\text{C}$

to  $125^\circ\text{C}$  operating junction temperature range are assured by design, characterization and correlation with statistical process controls. The LT3743I is guaranteed to meet performance specifications over the  $-40^\circ\text{C}$  to  $125^\circ\text{C}$  operating junction temperature range.

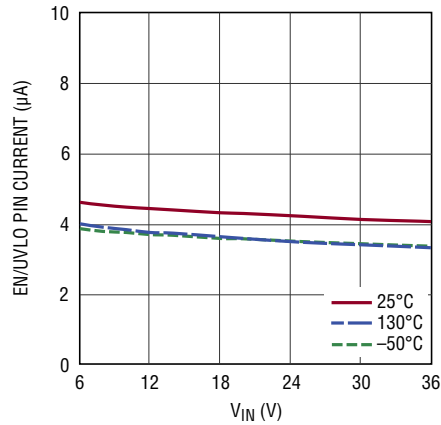
**Note 3:** The minimum on and off times are guaranteed by design and are not tested.

# TYPICAL PERFORMANCE CHARACTERISTICS

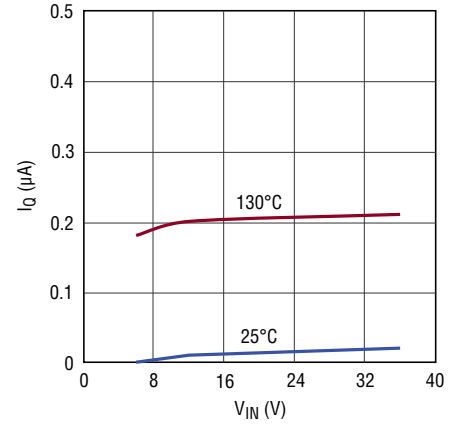
EN/UVLO Threshold (Falling)



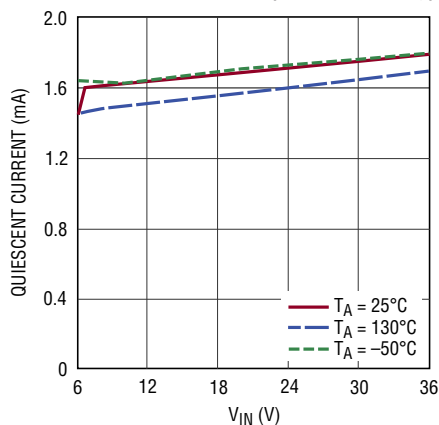
EN/UVLO Pin Current



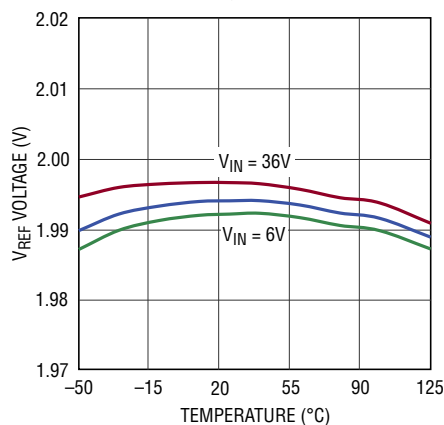
I<sub>Q</sub> in Shutdown



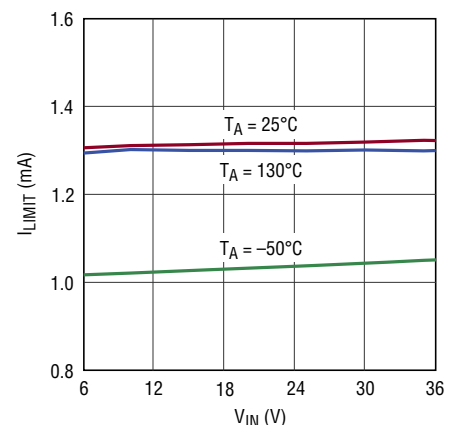
Quiescent Current (Non-Switching)



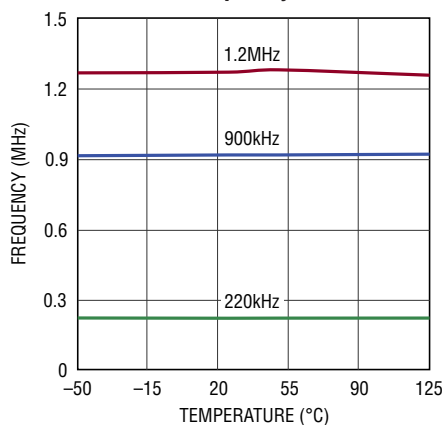
V<sub>REF</sub> Pin Voltage



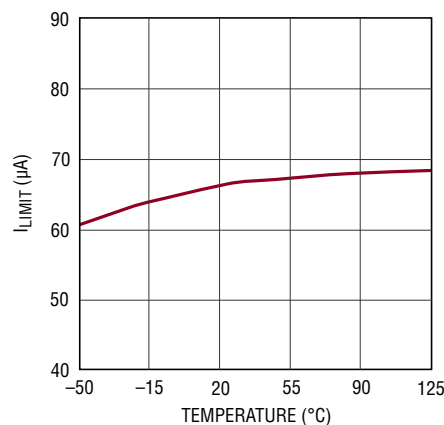
V<sub>REF</sub> Current Limit



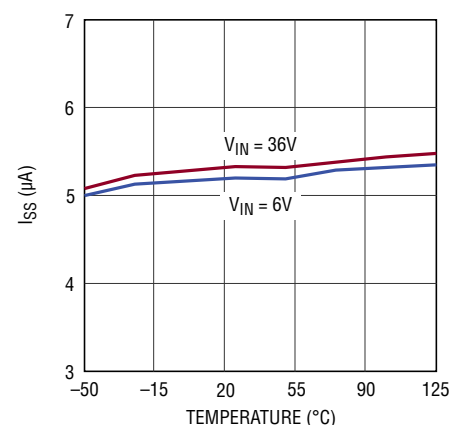
Oscillator Frequency



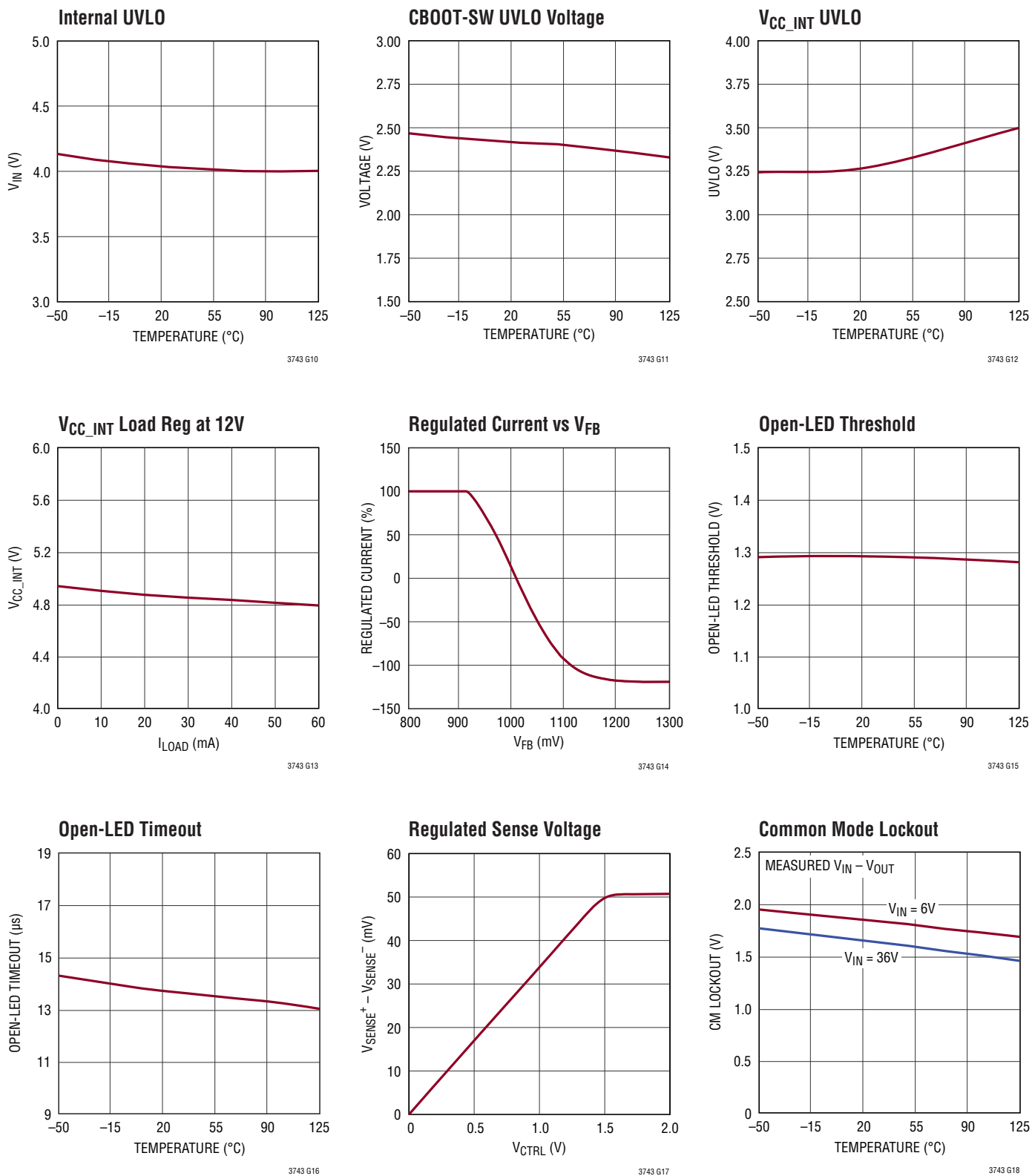
RT Pin Current Limit



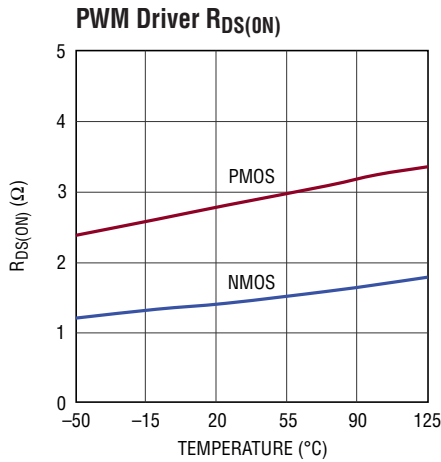
Soft-Start Pin Current



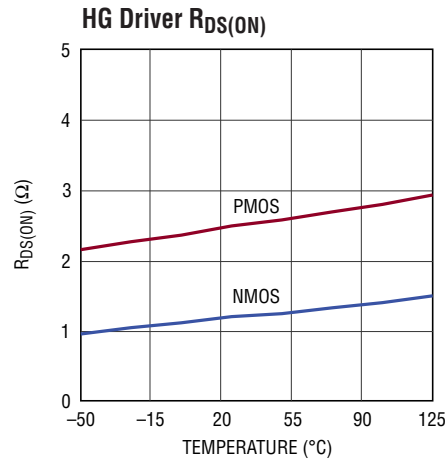
TYPICAL PERFORMANCE CHARACTERISTICS



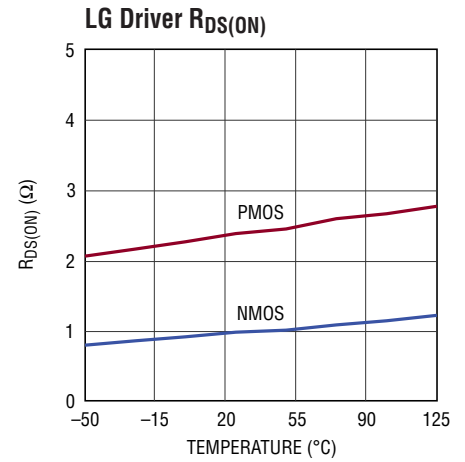
# TYPICAL PERFORMANCE CHARACTERISTICS



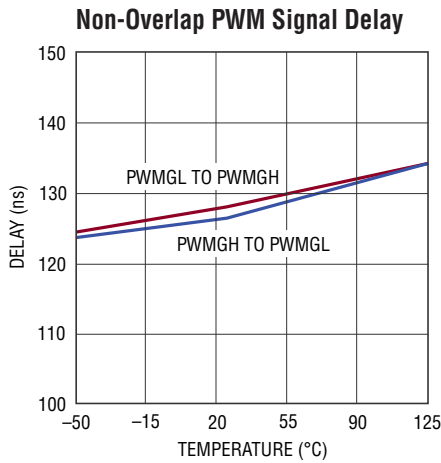
3743 G19



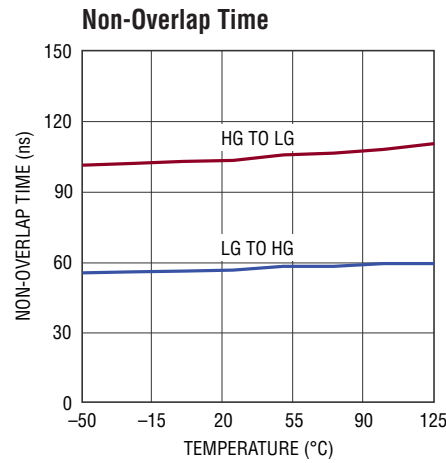
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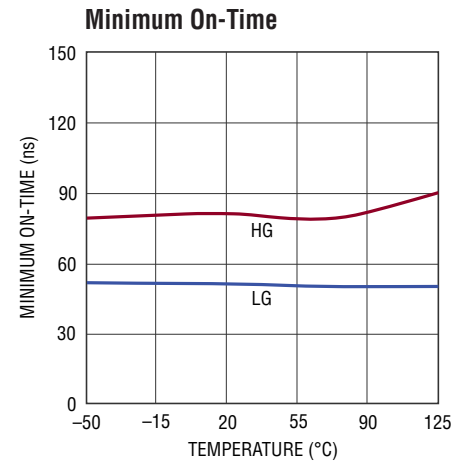
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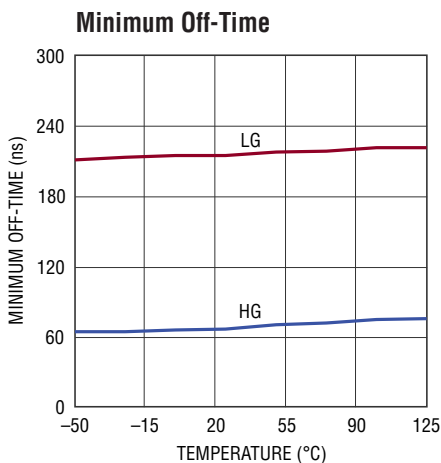
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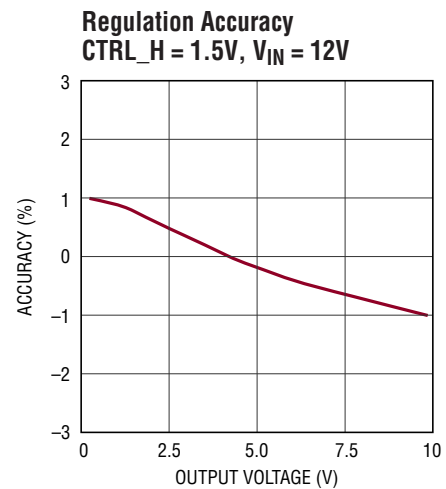
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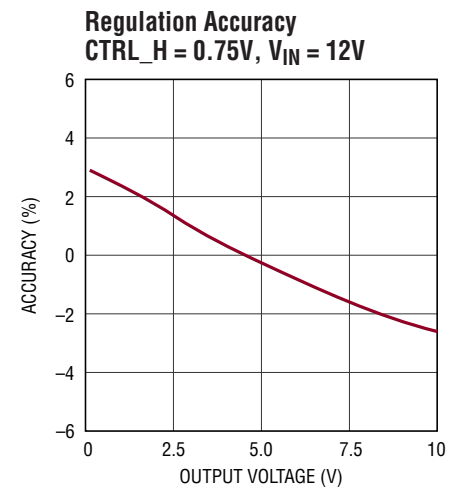
3743 G24



3743 G25



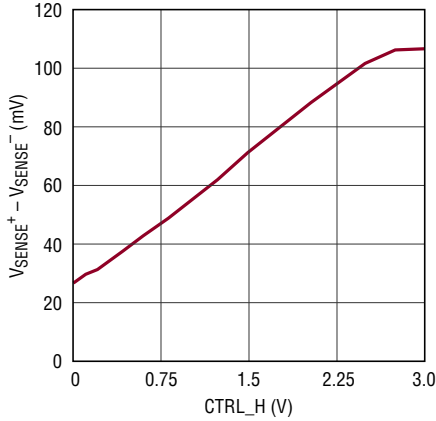
3743 G26



3743 G27

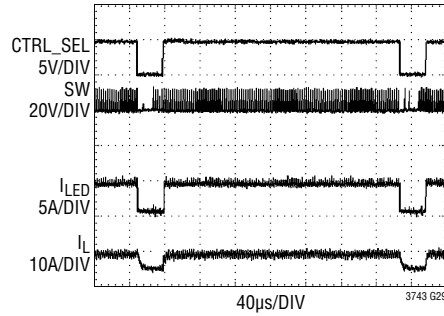
# TYPICAL PERFORMANCE CHARACTERISTICS

Overcurrent Threshold



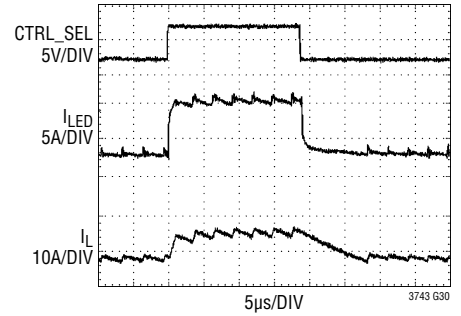
3743 G28

LED Current Waveforms (90% PWM) 0.5A to 5A



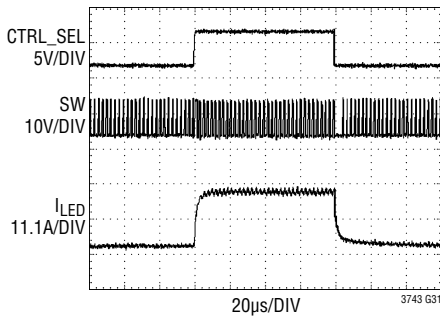
3743 G29

LED Current Waveforms (2000:1) 3A to 10A



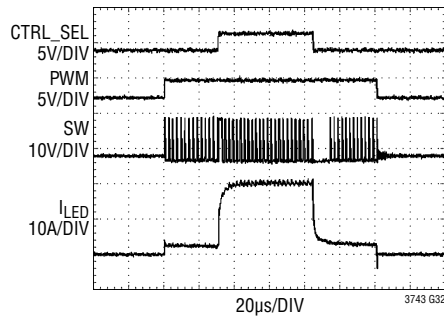
3743 G30

LED Current Waveforms (3000:1) 2A to 20A



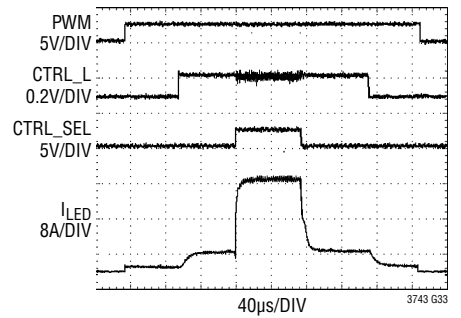
3743 G31

LED Current Waveforms (3000:1) 0A to 2A to 20A



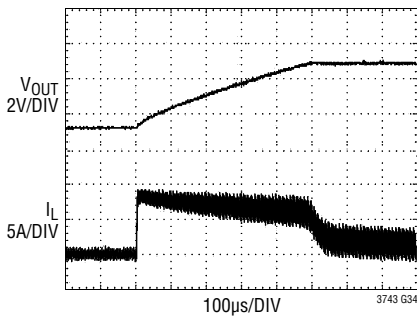
3743 G32

LED Current Waveforms (3000:1) Analog Dimming on CTRL\_L  
 $C_{OUT(LOW)} = 22\mu F$ ,  $C_{OUT(HIGH)} = 1mF$



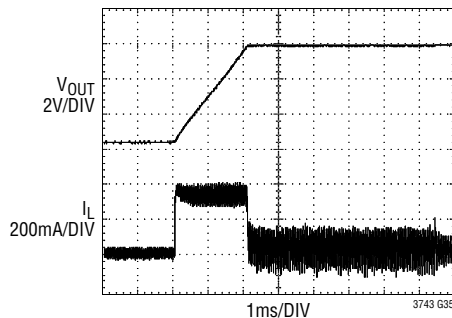
3743 G33

Voltage Regulation with 10A Regulated Inductor Current



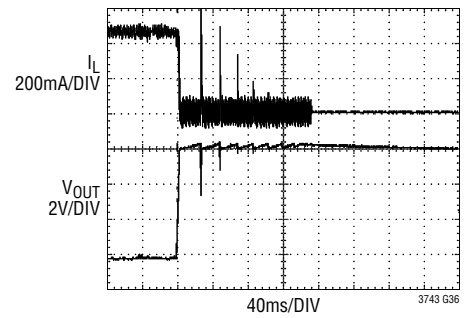
3743 G34

Common Mode Lockout ( $V_{IN} = 7V$ )



3743 G35

Overvoltage Lockout Operation With Open-Load Condition



3743 G36



## PIN FUNCTIONS (QFN/TSSOP)

**GND (Pins 1, 5, 9, 20, 21, Exposed Pad Pin 29/Pins 2, 7, 11, 22, 27, Exposed Pad Pin 29):** Ground. The exposed pad must be soldered to the PCB.

**EN/UVLO (Pin 2/Pin 4):** Enable Pin. The EN/UVLO pin acts as an enable pin and turns on the internal current bias core and subregulators at 1.55V. The pin does not have any pull-up or pull-down, requiring a voltage bias for normal part operation. Full shutdown occurs at approximately 0.5V.

**V<sub>REF</sub> (Pin 3/Pin 5):** Buffered 2V Reference Capable of 0.5mA Drive.

**CTRL\_T (Pin 4/Pin 6):** The thermal control input to reduce the regulated current level for both current levels (CTRL\_L and CTRL\_H).

**CTRL\_H (Pin 6/Pin 8):** The CTRL\_H pin sets the high level regulated output current and overcurrent. The maximum input voltage is internally clamped to 1.5V. The overcurrent set point is equal to the high level regulated current level set by the CTRL\_H pin with an additional 23mV offset between the SENSE<sup>+</sup> and SENSE<sup>-</sup> pins.

**CTRL\_L (Pin 7/Pin 9):** The CTRL\_L pin sets the low level regulated output current. It is not recommended that the CTRL\_L voltage be higher than the CTRL\_H voltage.

**SS (Pin 8/Pin 10):** Soft-Start Pin. Place an external capacitor to ground to limit the regulated current during start-up conditions. The SS pin has a 5.5μA charging current. This pin controls both of the regulated inputs determined by CTRL\_L and CTRL\_H.

**FB (Pin 10/Pin 12):** Feedback Pin for Overvoltage Protection. The feedback voltage is 1V. Overvoltage/Open LED is sensed through the FB pin. When the feedback voltage exceeds 1.3V, the overvoltage lockout prevents switching and connects both output capacitors to discharge the inductor current.

**SENSE<sup>+</sup> (Pin 11/Pin 13):** SENSE<sup>+</sup> is the inverting input of the average current mode loop error amplifier. This pin is connected to the external current sense resistor, R<sub>S</sub>. The voltage drop between SENSE<sup>+</sup> and SENSE<sup>-</sup> referenced to the voltage drop across an internal resistor produces the input voltages to the current regulation loop.

**SENSE<sup>-</sup> (Pin 12/Pin 14):** SENSE<sup>-</sup> is the noninverting input of the average current mode loop error amplifier. The reference current, based on CTRL\_L or CTRL\_H flows out of the pin to the output (LED) side of the sense resistor, R<sub>S</sub>.

**V<sub>CL</sub> (Pin 13/Pin 15):** V<sub>CL</sub> provides the necessary compensation for the average current loop stability during low level current regulation. Typical compensation values are 15k to 80k for the resistor and 2nF to 10nF for the capacitor.

**V<sub>CH</sub> (Pin 14/Pin 16):** V<sub>CH</sub> provides the necessary compensation for the average current loop stability during high level current regulation. Typical compensation values are 15k to 80k for the resistor and 2nF to 10nF for the capacitor.

**RT (Pin 15/Pin 17):** A resistor to ground sets the switching frequency between 200kHz and 1MHz. When using the SYNC function, set the frequency to be 20% lower than the SYNC pulse frequency. This pin is current limited to 60μA. Do not leave this pin open.

**SYNC (Pin 16/Pin 18):** Frequency Synchronization Pin. This pin allows the switching frequency to be synchronized to an external clock. The R<sub>T</sub> resistor should be chosen to operate the internal clock at 20% slower than the SYNC pulse frequency. The synchronization range is 240kHz to 1.2MHz. This pin should be grounded when not in use.

**CTRL\_SEL (Pin 17/Pin 19):** The CTRL\_SEL pin selects between the high current control, CTRL\_H and the low current control, CTRL\_L. When high, the V<sub>CH</sub> pin is connected to the error amp output and the PWMGH gate signal is high. When low, the V<sub>CL</sub> pin is connected to the error amp output and the PWMGL gate signal is high. This pin is used for current level dimming of the LED. This pin should be grounded when not in use.

**PWM (Pin 18/Pin 20):** The input pin for PWM dimming of the LED. When low, all switching is terminated and the output caps are disconnected. This pin should be pulled to V<sub>CC\_INT</sub> when not in use.

**PWMGH (Pin 19/Pin 21):** The PWMGH output pin drives the gate of an external FET to connect one of the switching regulator output capacitors to the load. The driver pull-up impedance is 3.2Ω and pull-down impedance is 1.75Ω.

## PIN FUNCTIONS (QFN/TSSOP)

**PWMGL (Pin 22/Pin 23):** The PWMGL output pin drives the gate of an external FET to connect one of the switching regulator output capacitors to the load. The driver pull-up impedance is  $3.2\Omega$  and pull-down impedance is  $1.75\Omega$ .

**HG (Pin 23/Pin 24):** HG is the top FET gate drive signal that controls the state of the high side external power FET. The driver pull-up impedance is  $2.3\Omega$  and pull-down impedance is  $1.3\Omega$ .

**SW (Pin 24/Pin 25):** The SW pin is used internally as the lower rail for the floating high side driver. Externally, this node connects the two power FETs and the inductor.

**CBOOT (Pin 25/Pin 26):** The CBOOT pin provides a floating 5V regulated supply for the high side FET driver. An external Schottky diode is required from the  $V_{CC\_INT}$  pin to the CBOOT pin to charge the  $C_{BOOT}$  capacitor when the switch pin is near ground.

**LG (Pin 26/Pin 28):** LG is the bottom FET gate drive signal that controls the state of the low side external power FET. The driver pull-up impedance is  $2.5\Omega$  and pull-down impedance is  $1.3\Omega$ .

**$V_{CC\_INT}$  (Pin 27/Pin 1):** A regulated 5V output for charging the  $C_{BOOT}$  capacitor.  $V_{CC\_INT}$  also provides the power for the digital and switching subcircuits. Below 6V  $V_{IN}$ , tie this pin to the rail.  $V_{CC\_INT}$  is current limited to  $\approx 50\text{mA}$ . Shutdown operation disables the output voltage drive.

**$V_{IN}$  (Pin 28/Pin 3):** Input Supply Pin. Must be locally bypassed with a  $1\mu\text{F}$  low ESR capacitor to ground.

# BLOCK DIAGRAM (QFN Package)

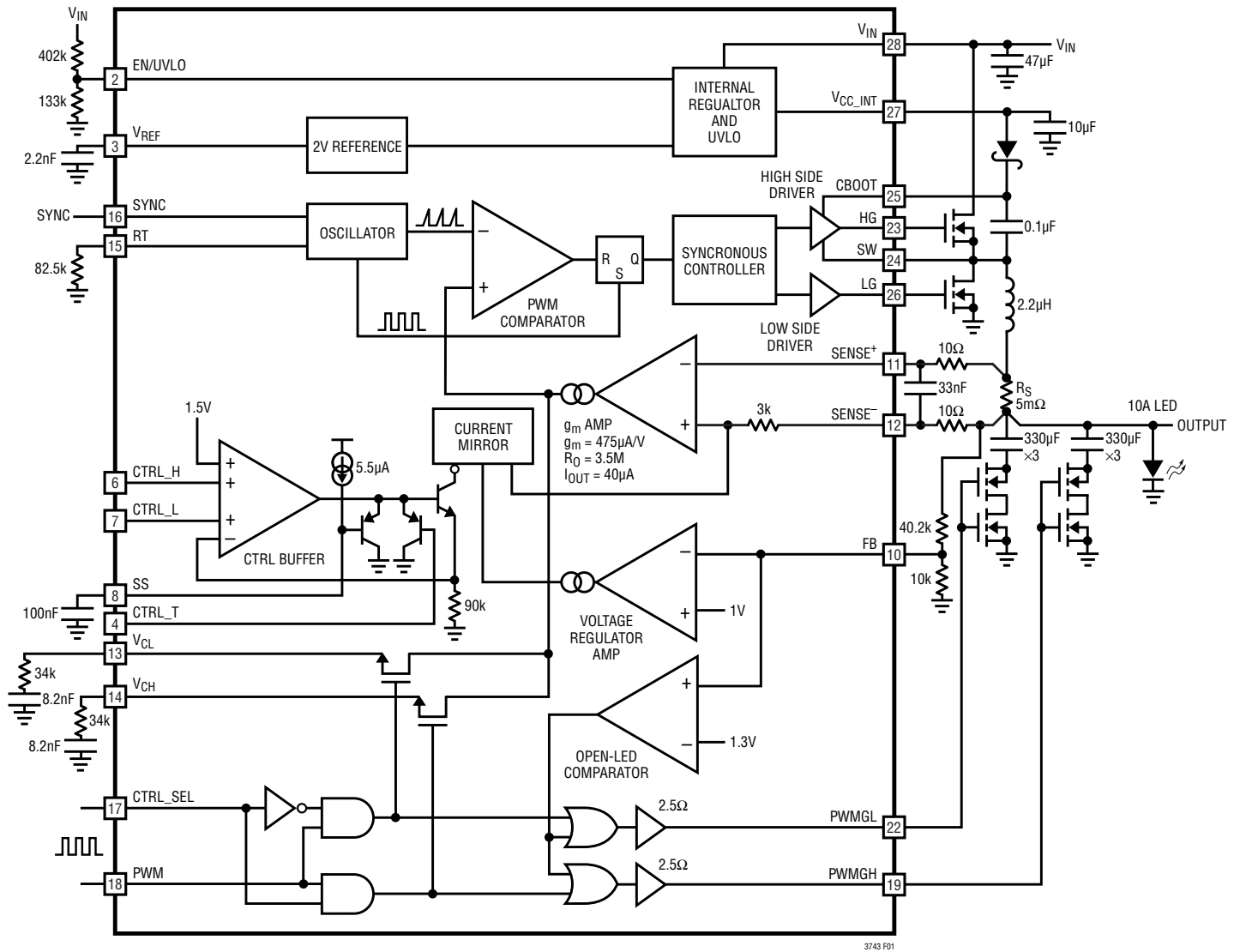


Figure 1. Block Diagram

## OPERATION

The LT3743 utilizes fixed frequency, average current mode control to accurately regulate the inductor current, independently from the output voltage. This is an ideal solution for applications requiring a regulated current source including driving high current LEDs where the forward junction voltage can range from 2V to 6V with a dynamic resistance of 20m $\Omega$  to 40m $\Omega$ . The control loop will regulate the current in the inductor at an accuracy of 6%. For additional operation information, refer to the Block Diagram in Figure 1.

The control loop has two independent reference inputs, determined by the analog control pins, CTRL\_H and CTRL\_L. When the CTRL\_SEL pin is low, the control loop uses the reference determined by the CTRL\_L pin and when high, the loop uses the reference determined by the CTRL\_H pin. The analog voltage at the CTRL\_L and CTRL\_H pins is buffered and produces a reference voltage across an internal resistor. The internal buffers have a 1.5V clamp on the output, limiting the analog control range of the CTRL\_L and CTRL\_H pins from 0V to 1.5V. The average current mode control loop uses the internal reference voltage to regulate the inductor current, as a voltage drop across the external sense resistor, R<sub>S</sub>.

In many applications, a rapid transition between the two regulated current states is desirable to provide background LED color mixing for pure colors in an RGB projector or display. For this purpose, pulse width modulation dimming can be achieved with both the PWM and CTRL\_SEL pins. When the PWM pin is low, the regulated current in the inductor is zero and both output capacitors are disconnected. When the PWM pin is high, and the CTRL\_SEL pin is low, the regulated current in the inductor is determined by the analog voltage at the CTRL\_L pin. When the PWM and CTRL\_SEL pins are both high, the regulated current in the inductor is determined by the analog voltage at the CTRL\_H pin.

The LT3743 uses a unique switched output capacitor topology and two independent compensation networks to transition between the two regulated current states in less than 2 $\mu$ s. When the CTRL\_SEL pin is low and the PWM pin is high, the PWMGL output pin is high, switching in the output capacitor for the CTRL\_L current level. The

CTRL\_L output capacitor stores the LED forward voltage drop when the control loop regulates the low current level. When the CTRL\_SEL pin changes to the high state, a 150ns delay ensures that the output capacitors are not connected at the same time. After this delay, the output capacitor for the CTRL\_H level is switched in when PWMGH goes high and immediately delivers current to the LED. The CTRL\_H output capacitor has the voltage drop of the LED with the regulated current determined by the analog voltage at the CTRL\_H pin. To achieve minimum transition delay, the inductor is precharged to 70% of the regulation current level just after the PWMGH pin goes high. Conversely, when the PWM pin goes low, the inductor is discharged to 70% of the low current level before normal switching at the low current level commences. The error amplifier for the average current mode control loop also has a common mode lockout that regulates the inductor current so that the error amplifier is never operated out of the common mode range. The common mode range is with an output voltage from 0V to 2V below the V<sub>IN</sub> supply rail.

The overcurrent set point is equal to the high level regulated current level set by the CTRL\_H pin with an additional 23mV offset between the SENSE<sup>+</sup> and SENSE<sup>-</sup> pins. The overcurrent is limited on a cycle-by-cycle basis; shutting switching down once the overcurrent level is reached. Overcurrent is not soft started.

The output voltage may be limited with a resistor divider from the output back to the FB pin. The reference at the FB pin is 1.0V. If the output voltage level is high enough to engage the voltage loop, the regulated inductor current will be reduced so that the output voltage is limited. If the voltage at the FB pin reaches 1.3V (30% higher than the regulation level), an internal open-LED flag is set, shutting down switching for 13 $\mu$ s and switching in both output capacitors to fully drain the inductor's current.

During start-up, the SS pin is held low until the first time the PWM pin goes high. Once the PWM signal goes high, the capacitor at the SS pin is charged with a 5.5 $\mu$ A current source. The internal buffers for the CTRL\_L and CTRL\_H signals are limited by the voltage at the SS pin, slowly ramping the regulated inductor current to the current determined by the voltage at the CTRL\_H or CTRL\_L pins.

# APPLICATIONS INFORMATION

## Programming Inductor Current

The analog voltage at the CTRL\_L and CTRL\_H pins is buffered and produces a reference voltage,  $V_{CTRL}$ , across an internal resistor. The regulated average inductor current is determined by:

$$I_0 = \frac{V_{CTRL}}{30 \cdot R_S}$$

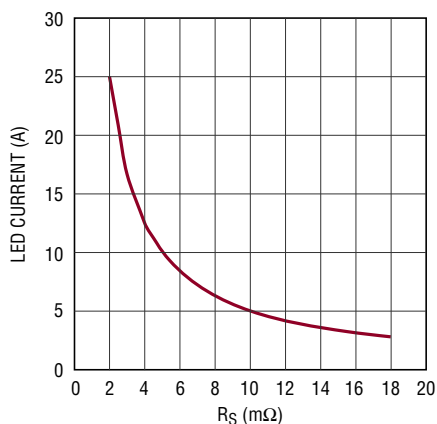
where  $R_S$  is the external sense resistor and  $I_0$  is the average inductor current, which is equal to the LED current. Figure 2 shows the LED current vs  $R_S$ . The maximum power dissipation in the resistor will be:

$$P_{RS} = \frac{(0.05V)^2}{R_S}$$

Table 1 contains several resistors values, the corresponding maximum current and power dissipation in the sense resistor. Figure 3 shows the power dissipation in  $R_S$ .

**Table 1. Sense Resistor Values**

| MAXIMUM LED CURRENT (A) | RESISTOR, $R_S$ (m $\Omega$ ) | POWER DISSIPATION (W) |
|-------------------------|-------------------------------|-----------------------|
| 1                       | 50                            | 0.05                  |
| 5                       | 10                            | 0.25                  |
| 10                      | 5                             | 0.5                   |
| 25                      | 2                             | 1.25                  |



**Figure 2.  $R_S$  Value Selection for LED Current**

## Inductor Selection

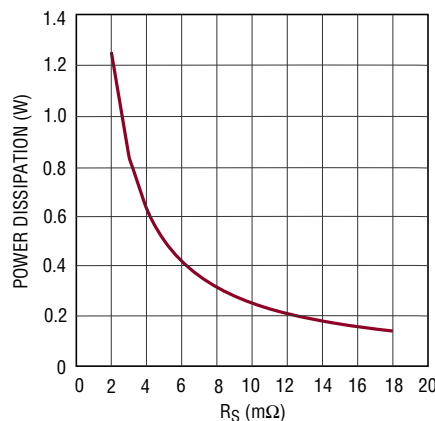
The recovery time between regulated states is critical to maintaining accurate control of the LED current. For this reason, sizing the inductor to have no less than 30% peak-to-peak ripple will provide excellent recovery time with reasonable ripple. The overcurrent set point is equal to the high level regulated current level set by the CTRL\_H pin with an additional 23mV offset between the SENSE+ and SENSE- pins. The saturation current for the inductor should be at least 20% higher than the maximum regulated current. The following equation sizes the inductor to achieve a reasonable recovery time while minimizing the inductor ripple:

$$L = \left( \frac{V_{IN} \cdot (V_F) - (V_F)^2}{0.2 \cdot f_S \cdot I_0 \cdot V_{IN}} \right)$$

where  $V_F$  is the LED forward voltage drop,  $I_0$  is the maximum regulated current in the inductor and  $f_S$  is the switching frequency. Using this equation, the inductor will have approximately 10% ripple at maximum regulated current.

**Table 2. Recommended Inductor Manufacturers**

| VENDOR            | WEBSITE  |
|-------------------|--|
| Coilcraft         | <a href="http://www.coilcraft.com">www.coilcraft.com</a> |
| Sumida            | <a href="http://www.sumida.com">www.sumida.com</a>       |
| Vishay            | <a href="http://www.vishay.com">www.vishay.com</a>       |
| Würth Electronics | <a href="http://www.we-online.com">www.we-online.com</a> |
| NEC-Tokin         | <a href="http://www.nec-tokin.com">www.nec-tokin.com</a> |



**Figure 3. Power Dissipation in  $R_S$**

## APPLICATIONS INFORMATION

### Switching MOSFET Selection

When selecting switching MOSFETs, the following parameters are critical in determining the best devices for a given application: total gate charge ( $Q_G$ ), on-resistance ( $R_{DS(ON)}$ ), gate to drain charge ( $Q_{GD}$ ), gate-to-source charge ( $Q_{GS}$ ), gate resistance ( $R_G$ ), breakdown voltages (maximum  $V_{GS}$  and  $V_{DS}$ ) and drain current (maximum  $I_D$ ). The following guidelines provide information to make the selection process easier.

Both of the switching MOSFETs need to have their maximum rated drain currents greater than the maximum inductor current. The following equation calculates the peak inductor current:

$$I_{MAX} = I_O + \left( \frac{V_{IN} \cdot (V_F + R_D I_O) - (V_F + R_D I_O)^2}{2 \cdot f_S \cdot L \cdot V_{IN}} \right)$$

where  $V_{IN}$  is the input voltage,  $L$  is the inductance value,  $V_F$  is the LED forward voltage drop,  $R_D$  is the dynamic series resistance of the LED,  $I_O$  is the regulated output current and  $f_S$  is the switching frequency. During MOSFET selection, notice that the maximum drain current is temperature dependant. Most data sheets include a table or graph of the maximum rated drain current vs temperature.

The maximum  $V_{DS}$  should be selected to be higher than the maximum input supply voltage (including transient) for both MOSFETs. The signals driving the gates of the switching MOSFETs have a maximum voltage of 5V with respect to the source. During start-up and recovery conditions, the gate drive signals may be as low as 3V. To ensure that the LT3743 recovers properly, the maximum threshold should be less than 2V. For a robust design, select the maximum  $V_{GS}$  greater than 7V.

Power losses in the switching MOSFETs are related to the on-resistance,  $R_{DS(ON)}$ ; the transitional loss related to the gate resistance,  $R_G$ ; gate-to-drain capacitance,  $Q_{GD}$  and gate-to-source capacitance,  $Q_{GS}$ . Power loss to the on-resistance is an Ohmic loss,  $I^2 R_{DS(ON)}$ , and usually dominates for input voltages less than ~15V. Power losses to the gate capacitance dominate for voltages greater than ~12V. When operating at higher input voltages, efficiency

can be optimized by selecting a high side MOSFET with higher  $R_{DS(ON)}$  and lower  $C_{GD}$ . The power loss in the high side MOSFET can be approximated by:

$$P_{LOSS} = (\text{ohmic loss}) + (\text{transition loss})$$

$$P_{LOSS} \approx \left( \frac{(V_F + R_D I_O)}{V_{IN}} \cdot I_O^2 R_{DS(ON)} \cdot \rho_T \right) + \left( \left( \frac{V_{IN} \cdot I_{OUT}}{5V} \right) \cdot ((Q_{GD} + Q_{GS}) \cdot (2 \cdot R_G + R_{PU} + R_{PD})) \cdot f_S \right)$$

where  $\rho_T$  is a temperature-dependant term of the MOSFET's on-resistance. Using 70°C as the maximum ambient operating temperature,  $\rho_T$  is roughly equal to 1.3.  $R_{PD}$  and  $R_{PU}$  are the LT3743 high side gate driver output impedance, 1.3Ω and 2.3Ω respectively.

A good approach to MOSFET sizing is to select a high side MOSFET, then select the low side MOSFET. The trade-off between  $R_{DS(ON)}$ ,  $Q_G$ ,  $Q_{GD}$  and  $Q_{GS}$  for the high side MOSFET is shown in the following example.  $V_O$  is equal to 4V. Comparing two N-channel MOSFETs, with a rated  $V_{DS}$  of 40V and in the same package, but with 8× different  $R_{DS(ON)}$  and 4.5× different  $Q_G$  and  $Q_{GD}$ :

$$\text{M1: } R_{DS(ON)} = 2.3\text{m}\Omega, Q_G = 45.5\text{nC}, \\ Q_{GS} = 13.8\text{nC}, Q_{GD} = 14.4\text{nC}, R_G = 1\Omega$$

$$\text{M2: } R_{DS(ON)} = 18\text{m}\Omega, Q_G = 10\text{nC}, \\ Q_{GS} = 4.5\text{nC}, Q_{GD} = 3.1\text{nC}, R_G = 3.5\Omega$$

Power loss for both MOSFETs is shown in Figure 4. Observe that while the  $R_{DS(ON)}$  of M1 is eight times lower, the power loss at low input voltages is equal, but four times higher at high input voltages than the power loss for M2.

Another power loss related to switching MOSFET selection is the power lost to driving the gates. The total gate charge,  $Q_G$ , must be charged and discharged each switching cycle. The power is lost to the internal LDO within the LT3743. The power lost to the charging of the gates is:

$$P_{LOSS\_LDO} \approx (V_{IN} - 5V) \cdot (Q_{GLG} + Q_{GHG}) \cdot f_S$$

where  $Q_{GLG}$  is the low side gate charge and  $Q_{GHG}$  is the high side gate charge.



## APPLICATIONS INFORMATION

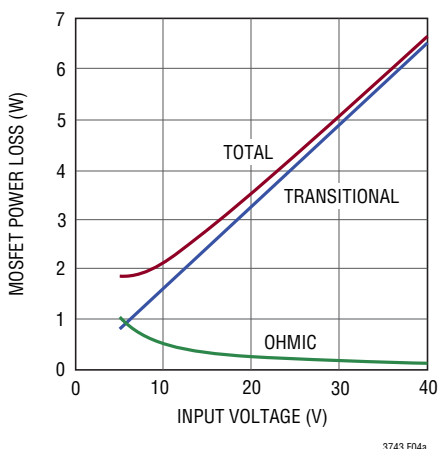


Figure 4a. Power Loss Example for M1

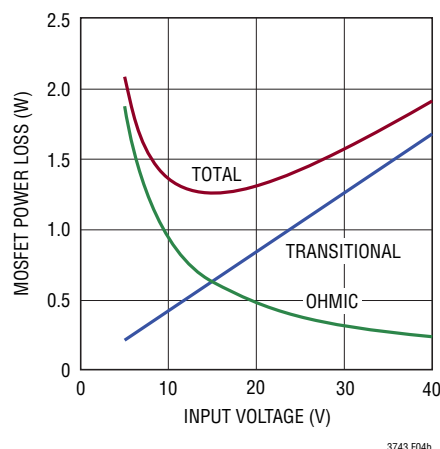


Figure 4b. Power Loss Example for M2

Figure 4

Whenever possible, utilize a switching MOSFET that minimizes the total gate charge to limit the internal power dissipation of the LT3743.

Table 3. Recommended Switching FETs

| $V_{IN}$<br>(V) | $V_{OUT}$<br>(V) | $I_D$<br>(A) | TOP FET      | BOTTOM FET | MANUFACTURER                       |
|-----------------|------------------|--------------|--------------|------------|------------------------------------|
| 8               | 4                | 5-10         | RJK0365DPA   | RJK0330DPB | Renesas<br>www.renesas.com         |
| 24              | 4                | 5            | RJK0368DPA   | RJK0332DPB |                                    |
| 24              | 2-4              | 20           | RJK0365DPA   | RJK0346DPA |                                    |
| 12              | 2-4              | 10           | FDMS8680     | FDMS8672AS | Fairchild<br>www.fairchildsemi.com |
| 36              | 4                | 20           | Si7884BDP    | SiR470DP   | Vishay<br>www.vishay.com           |
| 24              | 4                | 40           | PSMN4R0-30YL | RJK0346DPA | NXP/Philips<br>www.nxp.com         |

## Input Capacitor Selection

The input capacitor should be sized at 4 $\mu$ F for every 1A of output current and placed very close to the high side MOSFET. A small 1 $\mu$ F ceramic capacitor should be placed near the  $V_{IN}$  and ground pins of the LT3743 for optimal noise immunity. The input capacitor should have a ripple current rating equal to half of the maximum output current.

It is recommended that several low ESR ceramic capacitors be used as the input capacitance. Use only type X5R or X7R capacitors as they maintain their capacitance over a wide range of operating voltages and temperatures.

## Output Capacitor Selection

The output capacitors need to have very low ESR (equivalent series resistance) to allow the LED current to ramp quickly. A minimum of 50 $\mu$ F/A of load current should be used in most designs. The capacitors also need to be surge rated to the maximum output current. To achieve the lowest possible ESR, several low ESR capacitors should be used in parallel. Many applications benefit from the use of high density POSCAP capacitors, which are easily destroyed when exposed to overvoltage conditions. To prevent this, select POSCAP capacitors that have a voltage rating that is at least 50% higher than the regulated voltage.

 $C_{BOOT}$  Capacitor Selection

The  $C_{BOOT}$  capacitor must be sized less than 220nF and more than 50nF to ensure proper operation of the LT3743. Use 220nF for high current switching MOSFETs with high gate charge.

## APPLICATIONS INFORMATION

### $V_{CC\_INT}$ Capacitor Selection

The bypass capacitor for the  $V_{CC\_INT}$  pin should be larger than 5 $\mu$ F for stability and has no ESR requirement. It is recommended that the ESR be lower than 50m $\Omega$  to reduce noise within the LT3743. For driving MOSFETs with gate charges larger than 10nC, use 0.5 $\mu$ F/nC of total gate charge.

### LED Current Dimming

The LT3743 provides the capability of traditional zero to full current PWM dimming as well as PWM dimming between two regulated LED current states. When the PWM signal is low, no switching occurs and the output capacitors are disconnected from ground. When PWM is high and CTRL\_SEL is low, the inductor current is regulated to the low current state. In this state, the PWMGL signal is high, connecting the output capacitor for the low regulated current state. When PWM and CTRL\_SEL are both high, the inductor current is regulated to the high current state. In this state, the PWMGH signal is high, connecting the output capacitor for the high regulated current state. The transition time between each of the regulated inductor currents is determined by the inductor size,  $V_{IN}$  and  $V_O$ . Due to the use of the switched output capacitors, the LED current will begin to flow within 130ns of the transition on the CTRL\_SEL pin. Figure 8 shows the LED and inductor current waveforms with the various states of the control signals.

To adjust the regulated LED current for the two control states, an analog voltage is applied to the CTRL\_L and CTRL\_H pins. Figure 6 shows the regulated voltage across the sense resistor for control voltages up to 2V. Figure 7 shows the CTRL\_L voltage created by a voltage divider from  $V_{REF}$  to ground. When sizing the resistor divider, please be aware that the  $V_{REF}$  pin is current limited to 500 $\mu$ A. Above 1.5V, the control voltage has no effect on the regulated LED current.

For the widest dimming range, use the highest switching frequency possible and lowest PWM frequency. For configuration with the maximum PWM range, please contact factory for optimized component selection.

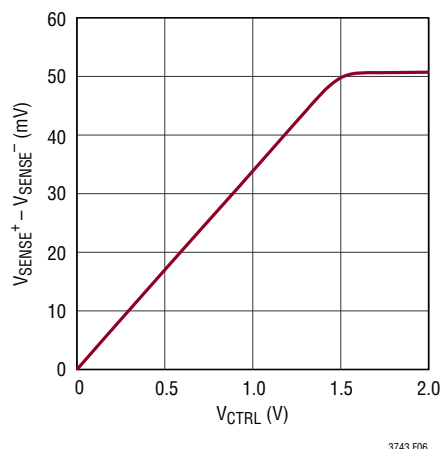


Figure 6. LED Current vs CTRL Voltage

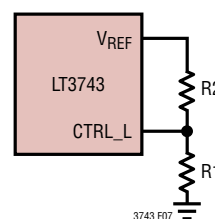


Figure 7. Analog Control of LED Current

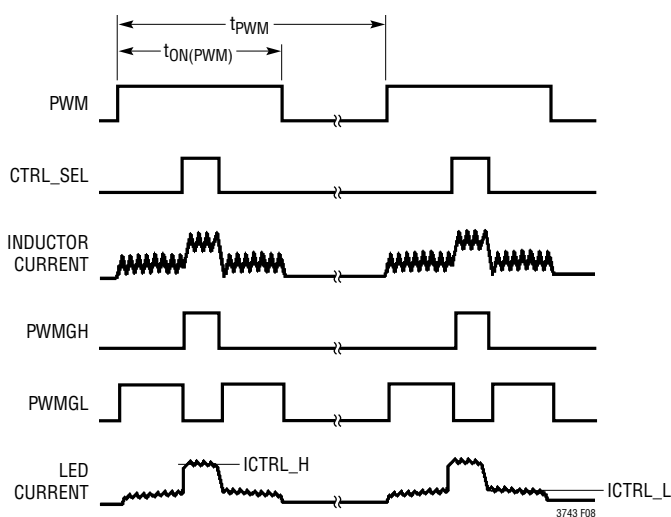


Figure 8. LED Current vs CTRL Voltage



## APPLICATIONS INFORMATION

### MOSFET Selection for the Switched Output Capacitors

The MOSFETs used for the switched-output capacitor need to also handle the maximum regulated current while the capacitor is charged. The output drivers on the PWMGH and PWMGL pins have a pull-up impedance of  $3.2\Omega$  and a pull-down impedance of  $1.75\Omega$ . This provides adequate gate drive for the PWM MOSFETs without the need for an additional gate driver. If the LED forward resistance and the difference between the two regulated currents is large enough, then two MOSFETs are required to prevent the body diode of the MOSFET from conducting and discharging the capacitor for the high current state. Figure 9 shows the output capacitor for the high current regulation state discharged with the body diode when a single MOSFET is used. Figure 10 shows the application circuit with a drain-to-drain configuration for the high current output capacitor. In this configuration, the body diode of the upper MOSFET blocks conduction and prevents discharge of the high current output capacitor.

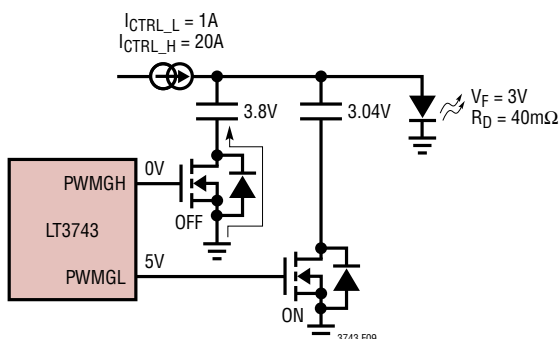


Figure 9. Body Diode of High Current FET Discharges the Output Capacitor

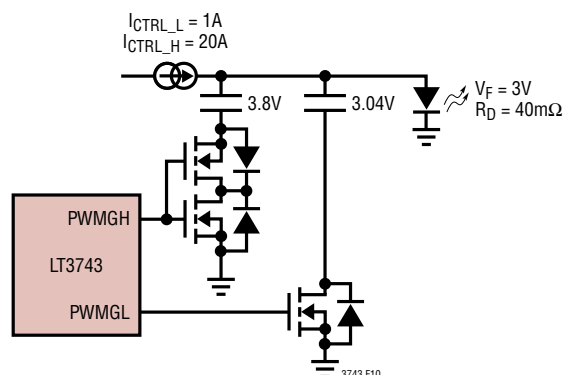


Figure 10. With a Drain-to-Drain Configuration, the Body Diode of the Top FET Blocks the Current Path That Would Discharge the High Current Output Capacitor

If the voltage between the low state and the high state is very large (greater than the threshold of the MOSFET) then the capacitor may once again be discharged. To account for this, choose a MOSFET that has a threshold greater than the voltage difference. If the voltage difference exceeds 1.5V, use the circuit shown in Figure 11. The circuit shown will keep the capacitor from discharging to a voltage difference of approximately  $2V + V_{TH}$ .

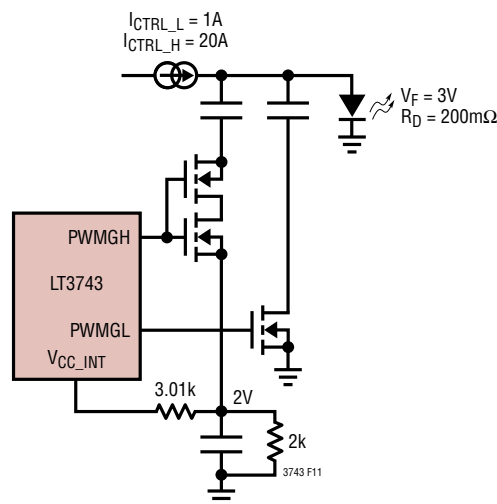


Figure 11. Application for Large Differences in Regulated Currents

### Board and Interconnect Inductance

The board and interconnect inductance from the output capacitors to the load also determine the rate of change in load (LED) current. The rate of change in load current will be:

$$\frac{dI_L}{dt} = \frac{V_{HIGH} - V_{LOW}}{L_{BOARD}}$$

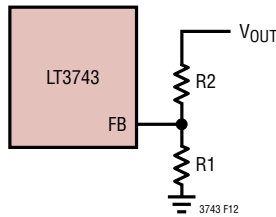
where  $dI_L/dt$  is the rate of change in the load current,  $V_{HIGH}$  is the output voltage when the inductor is regulated at the high level, and  $V_{LOW}$  is the output voltage when the inductor is regulated at the low state. When measuring the LED current do not use a current probe. The core material used in most probes adds inductance and slows the rise time of the LED current. Instead, when measuring the current, use a sense resistor.

## APPLICATIONS INFORMATION

### Voltage Regulation and Overvoltage Protection

The LT3743 uses the FB pin to regulate the output to a maximum voltage and to provide a high speed overvoltage lockout to avoid high voltage conditions that may damage expensive high current LEDs. The regulated output voltage is programmed using a resistor divider from the output and ground (Figure 12). When the output voltage exceeds 130% of the regulated voltage level (1.3V at the FB pin), the internal open-LED flag is set, terminating switching and forcing both PWMGL and PWMGH signals high. The regulated output voltage must be greater than 2V and is set by the equation:

$$V_{OUT} = 1V \left( 1 + \frac{R2}{R1} \right)$$



**Figure 12. Output Voltage Regulation and Overvoltage Protection Feedback Connections**

### Soft-Start

Unlike conventional voltage regulators, the LT3743 utilizes the soft-start function to control the regulated inductor current. The charging current is 5.5μA and reduces the regulated current for both the high and low regulated current states. The SS pin is latched in a discharge state until the first PWM pulse and is reset by UVLO and thermal shutdown.

### Programming Switching Frequency

The LT3743 has an operational switching frequency range between 200kHz and 1MHz. This frequency is programmed with an external resistor from the RT pin to ground. Do not leave this pin open under any condition. The RT pin is also current limited to 60μA. See Table 4 and Figure 13 for resistor values and the corresponding switching frequencies.

The internal power consumption of the LT3743 is determined by the switching frequency,  $V_{IN}$ , and the gate charge,  $Q_G$  of the external switching MOSFETs selected. The 4mm × 5mm QFN package has a  $\theta_{JA}$  of 35°C/W. The following equation calculates the maximum switching frequency to avoid current limit and thermal shutdown at a given ambient operating temperature,  $T_A$ :

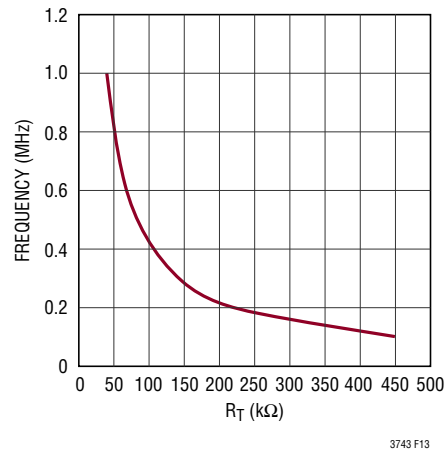
$$f_s \leq \frac{(163^\circ\text{C} - T_A)}{(35^\circ\text{C/W}) \cdot (V_{IN} - 5V) \cdot (Q_{GHG} + Q_{GLG})}$$

$$f_s \leq \frac{60\text{mA}}{(Q_{GLG} + Q_{GHG})}$$

Since the regulated output current flowing into the LED may be very large, the switching frequency needs to be carefully considered. Higher switching frequencies will reduce the large size of high saturation current inductors, while reducing efficiency and increasing power loss within the LT3743.

**Table 4. Switching Frequency**

| SWITCHING FREQUENCY (MHz) | $R_T$ (kΩ) |
|---------------------------|------------|
| 1                         | 40.2       |
| 0.750                     | 53.6       |
| 0.5                       | 82.5       |
| 0.3                       | 143        |
| 0.2                       | 221        |



**Figure 13. Frequency vs  $R_T$  Resistance**

## APPLICATIONS INFORMATION

### Thermal Shutdown

The internal thermal shutdown within the LT3743 engages at 163°C and terminates switching, resets soft-start and shuts down the PWMGL and PWMGH drivers. When the part has cooled to 155°C, the internal reset is cleared and soft-start is allowed to charge once the PWM signal is asserted.

### Switching Frequency Synchronization

The nominal switching frequency of the LT3743 is determined by the resistor from the RT pin to ground and may be set from 200kHz to 1MHz. The internal oscillator may also be synchronized to an external clock through the SYNC pin. The external clock applied to the SYNC pin must have a logic low below 0.3V and a logic high higher than 1.25V. The input frequency must be 20% higher than the frequency determined by the resistor at the RT pin. Input signals outside of these specified parameters will cause erratic switching behavior and subharmonic oscillations. The synchronization range is 240kHz to 1.2MHz. Synchronization is tested at 500kHz with a 200k  $R_T$  resistor. Operation under other conditions is guaranteed by design. When synchronizing to an external clock, please be aware that there will be a fixed delay from the input clock edge to the edge of switch. The SYNC pin must be grounded if the synchronization to an external clock is not required. When SYNC is grounded, the switching frequency is determined by the resistor at the RT pin.

### Shutdown and UVLO

The LT3743 has an internal UVLO that terminates switching, resets all synchronous logic, and discharges the soft-start capacitor for input voltages below 4.2V. The LT3743 also has a precision shutdown at 1.55V on the EN/UVLO pin. Partial shutdown occurs at 1.55V and full shutdown is guaranteed below 0.5V with  $<1\mu A$   $I_Q$  in the full shutdown state. Below 1.5V, an internal current source provides 5.5 $\mu A$  of pull-down current to allow for programmable UVLO hysteresis. The following equations determine the voltage divider resistors for programming the UVLO voltage and hysteresis as configured in Figure 14.

$$R2 = \frac{V_{HYST}}{5.5\mu A}$$

$$R1 = \left( \frac{1.55V \cdot R2}{V_{UVLO} - 1.55V} \right)$$

The EN/UVLO pin as an absolute maximum voltage of 6V. To accommodate the largest range of applications, there is an internal Zener diode that clamps this pin. For applications where the supply range is greater than 4:1, size R2 greater than 375k.

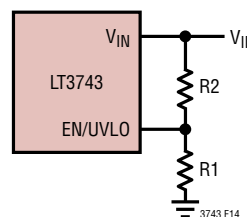


Figure 14. UVLO Configuration

### LED Current Derating Using the CTRL\_T Pin

The LT3743 is designed specifically for driving high current LEDs. Most high current LEDs require derating the maximum current based on operating temperature to prevent damage to the LED. In addition, many applications have thermal limitations that will require the regulated current to be reduced based on LED and/or board temperature. To achieve this, the LT3743 uses the CTRL\_T pin to reduce the effective regulated current in the LED for both the high and low control currents. While CTRL\_H and CTRL\_L program the regulated current in the LED, CTRL\_T can be configured to reduce this regulated current based on the analog voltage at the CTRL\_T pin. The LED/board temperature derating is programmed using a resistor divider with a temperature dependant resistance (Figure 15). When the board/LED temperature rises, the CTRL\_T voltage will decrease. To reduce the regulated current, the CTRL\_T voltage must be lower than voltage at the CTRL\_L and CTRL\_H pins.

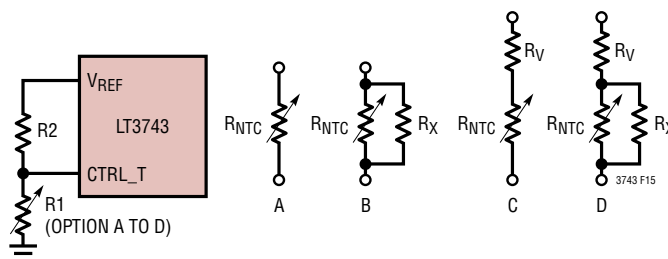


Figure 15. LED Current Derating vs Temperature Using NTC Resistor

## APPLICATIONS INFORMATION

### Average Current Mode Control Compensation

The use of average current mode control allows for precise regulation of the inductor and LED currents. Figure 16 shows the average current mode control loop used in the LT3743, where the regulation current is programmed by a current source and a 3k resistor.

To design the compensation network, the maximum compensation resistor needs to be calculated. In current mode controllers, the ratio of the sensed inductor current ramp to the slope compensation ramp determines the stability of the current regulation loop above 50% duty cycle. In the same way, average current mode controllers require the slope of the error voltage to not exceed the PWM ramp slope during the switch off-time.

Since the closed-loop gain at the switching frequency produces the error signal slope, the output impedance of the error amplifier will be the compensation resistor,  $R_C$ .

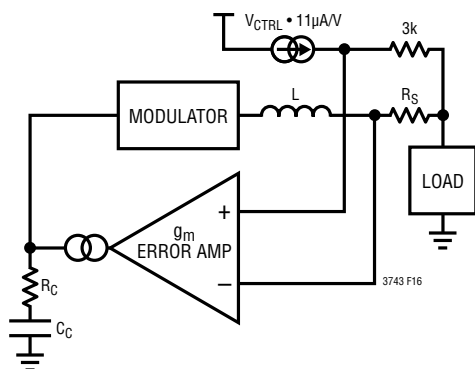


Figure 16. LT3743 Average Current Mode Control Scheme

Use the following equations as a good starting point for compensation component sizing:

$$R_C = \frac{f_s \cdot L \cdot 1000V}{V_0 \cdot R_S} [\Omega], C_C = \frac{0.002}{f_s} [F]$$

where  $f_s$  is the switching frequency,  $L$  is the inductance value,  $V_{IN}$  is the input voltage and  $R_S$  is the sense resistor. For most LED applications, a 4.7nF compensation capacitor is adequate and provides excellent phase margin with optimized bandwidth. Please refer to Table 6 for recommended compensation values.

For applications where the load is not an LED, please call the factory for additional compensation assistance.

### Board Layout Considerations

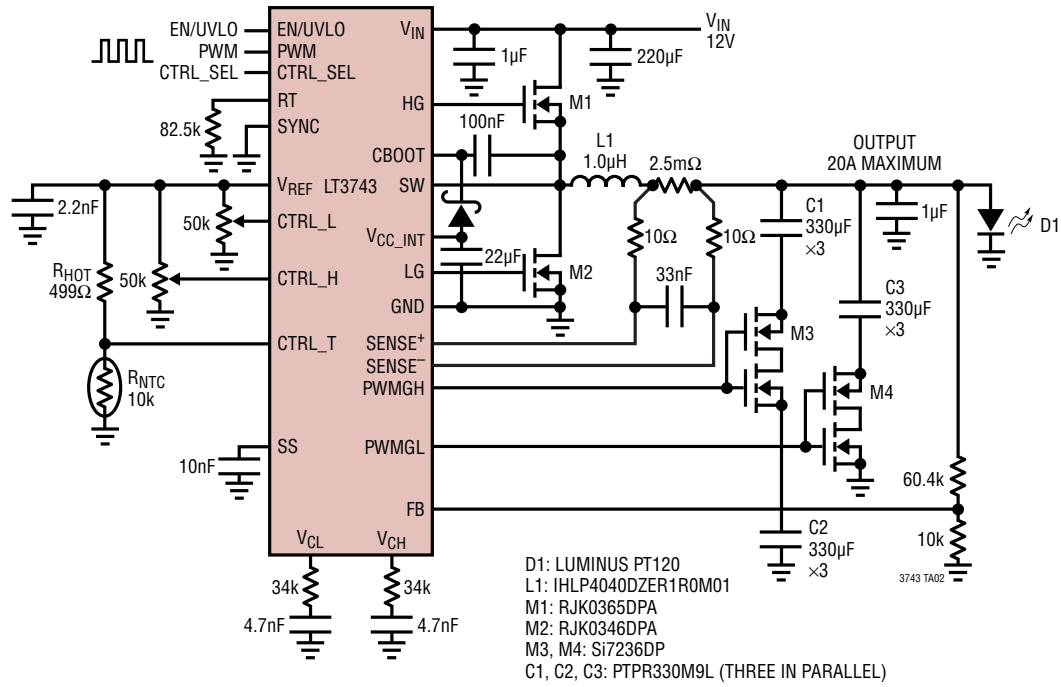
Average current mode control is relatively immune to the switching noise associated with other types of control schemes. Placing the sense resistor as close as possible to the SENSE+ and SENSE- pins avoids noise issues and ensures the fastest LED current transition time. For currents exceeding 5A, use 10Ω resistors in-series with SENSE+ and SENSE-, with a 33nF capacitor placed as close as possible to the SENSE+ and SENSE- pins. Utilizing a good ground plane underneath the switching components will minimize interplane noise coupling. To dissipate the heat from the switching components, increase the area of the switching node as much as possible without negatively affecting the radiated noise. The interconnect inductance and resistance between the output capacitors and the LED load directly impacts the rise time of the load current. To reduce the inductance and resistance, make the traces as wide as physically possible and minimize the trace length.

Table 6. Recommended Compensation Values

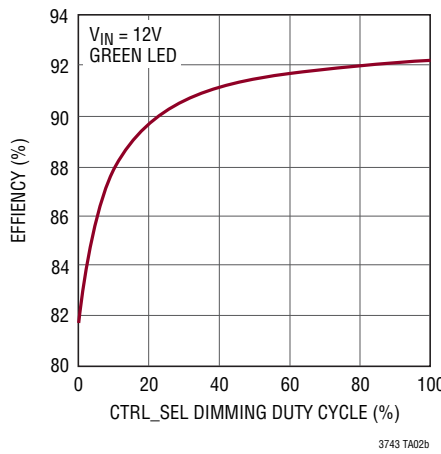
| $V_{IN}$ (V) | $V_0$ (V) | $I_L$ (A) | $f_{sw}$ (MHz) | $L$ (μH) | $R_S$ (mΩ) | $R_C$ (kΩ) | $C_C$ (nF) |
|--------------|-----------|-----------|----------------|----------|------------|------------|------------|
| 12           | 4         | 5         | 0.5            | 1.5      | 5          | 47.5       | 4.7        |
| 12           | 4         | 10        | 0.5            | 1.5      | 5          | 47.5       | 4.7        |
| 12           | 5         | 20        | 0.25           | 1.8      | 2.5        | 38.3       | 8.2        |
| 24           | 4         | 2         | 0.5            | 1.0      | 2.5        | 52.3       | 4.7        |
| 24           | 4         | 20        | 0.5            | 1.0      | 2.5        | 52.3       | 4.7        |

TYPICAL APPLICATIONS

12V, 20A LED Driver

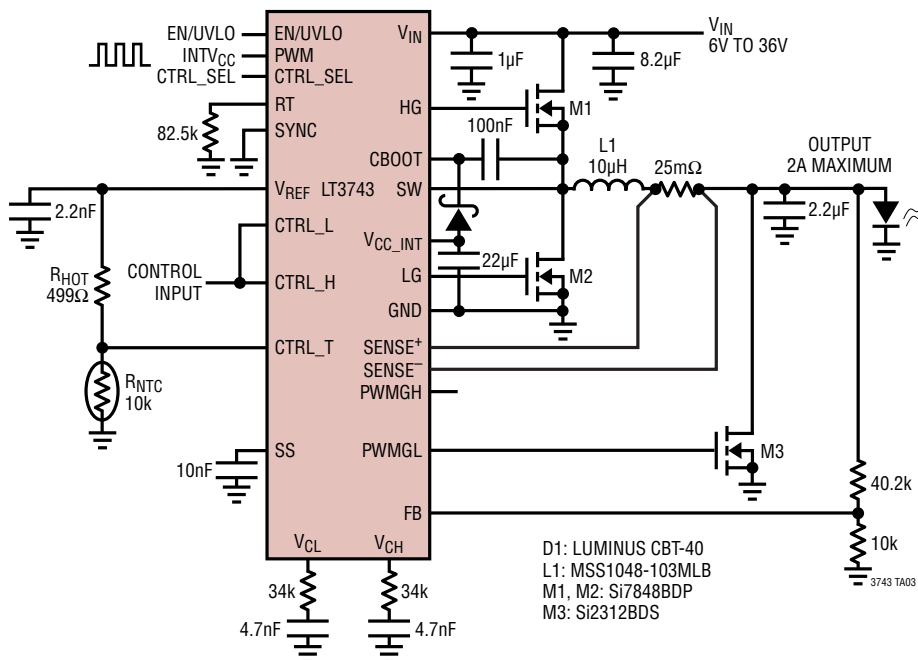


Efficiency (Stepping from 2A to 20A)

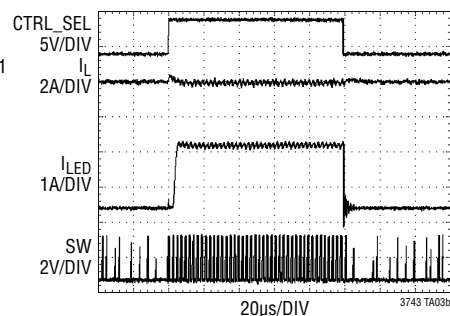


## TYPICAL APPLICATIONS

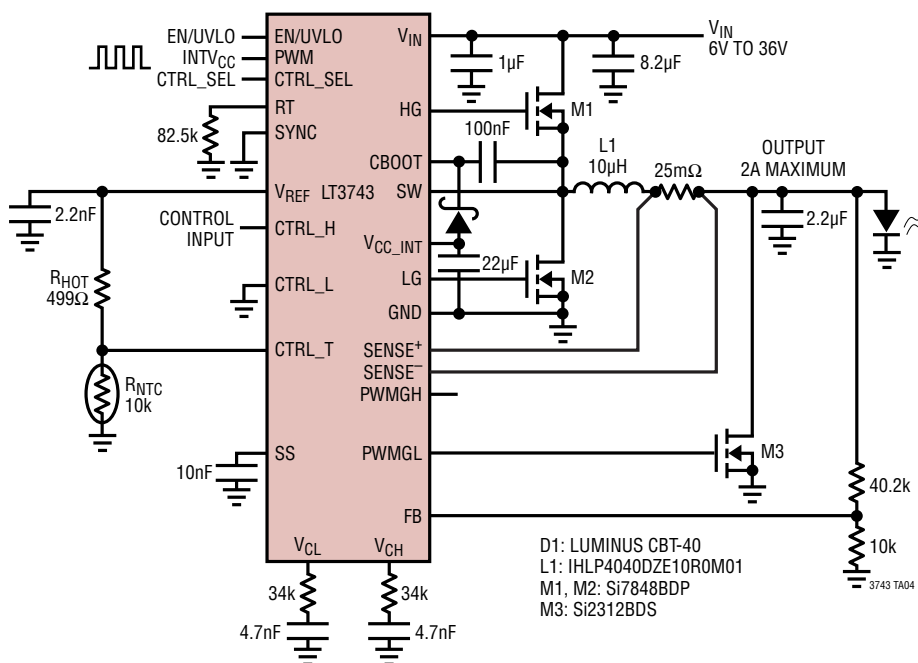
### 6V to 36V, 2A LED Driver With Shunted Output



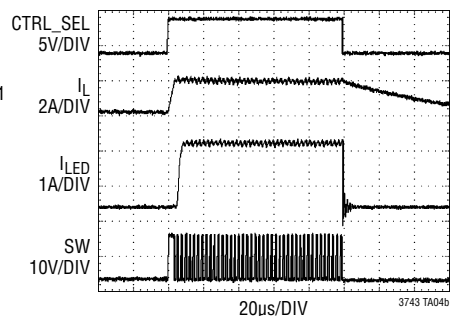
Shunted Output with CTRL\_H Equal to CTRL\_L



### 6V to 36V, 2A LED Driver With Current Limited Shunted Output

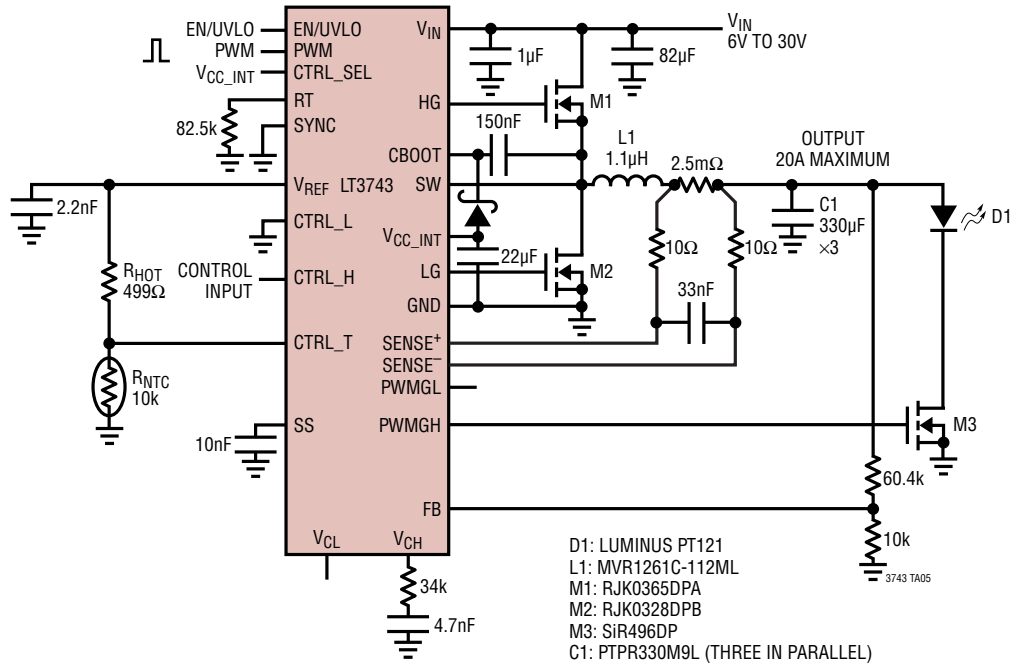


Shunted Output with CTRL\_L at GND

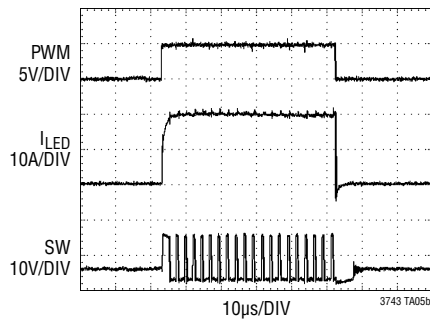


# TYPICAL APPLICATIONS

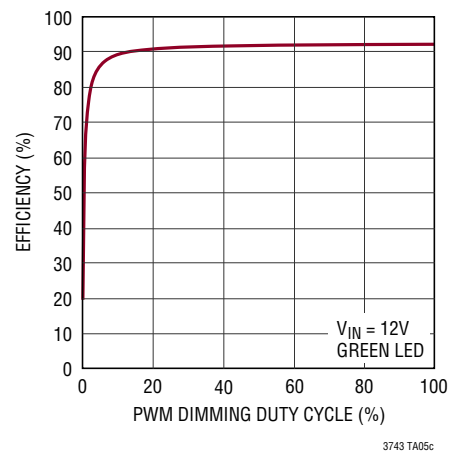
## 6V to 30V, 20A LED Driver with Switched Cathode



## Switched Cathode PWM Dimming (100:1) 0A to 20A

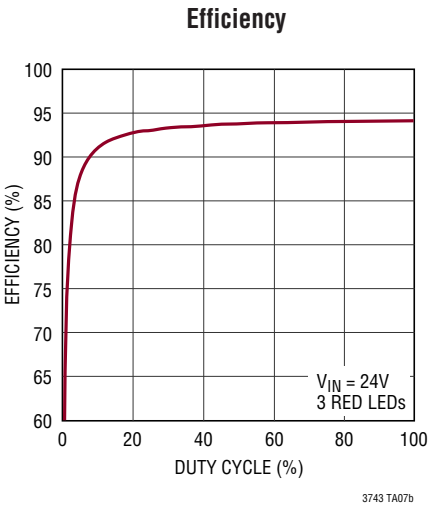
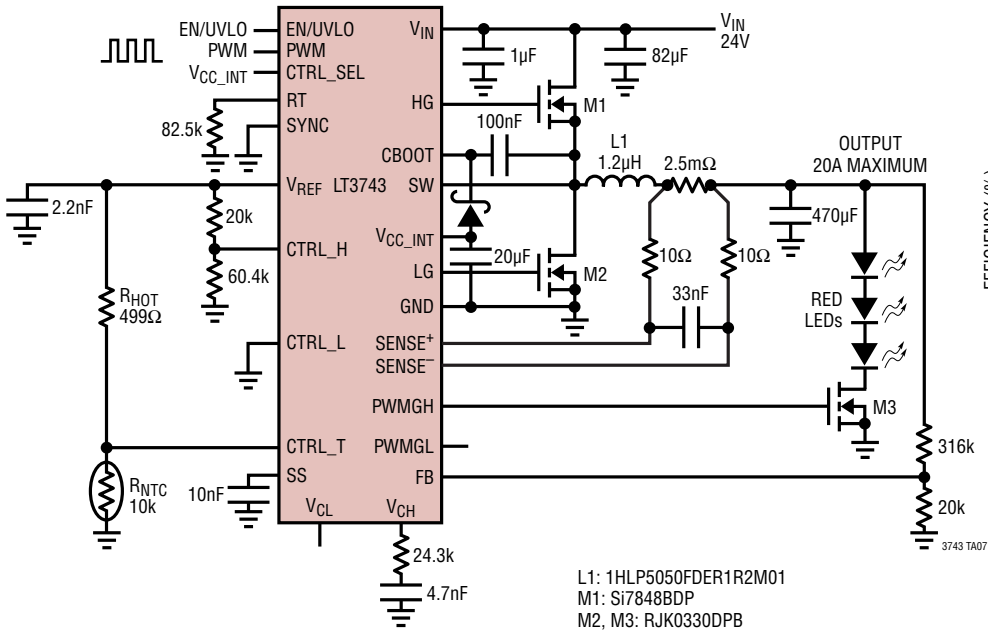


## 0A to 20A Efficiency



TYPICAL APPLICATIONS

24V, 20A 3-LED Driver

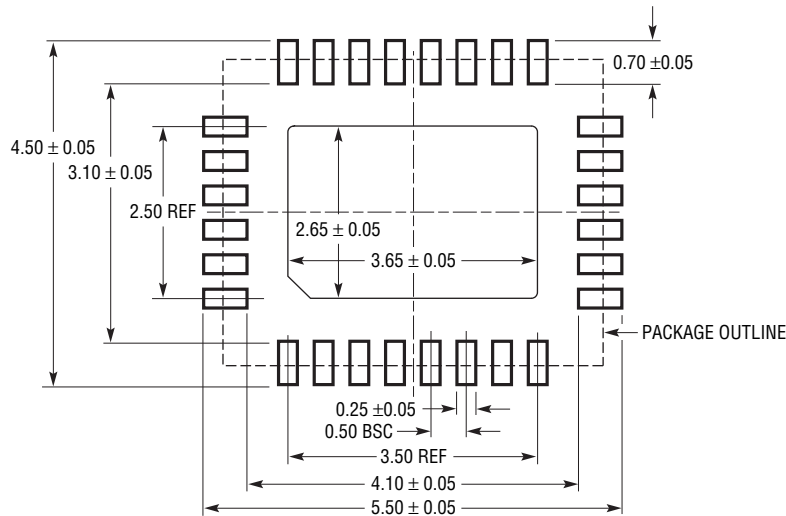




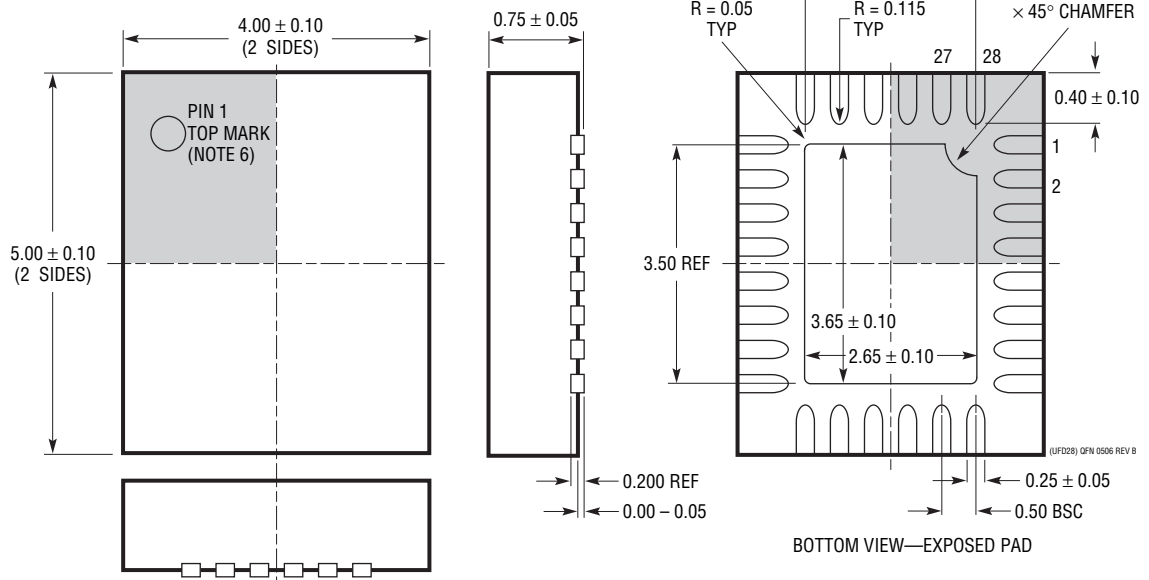
# PACKAGE DESCRIPTION

Please refer to <http://www.linear.com/designtools/packaging/> for the most recent package drawings.

## UFD Package 28-Lead Plastic QFN (4mm × 5mm) (Reference LTC DWG # 05-08-1712 Rev B)



RECOMMENDED SOLDER PAD PITCH AND DIMENSIONS  
APPLY SOLDER MASK TO AREAS THAT ARE NOT SOLDERED



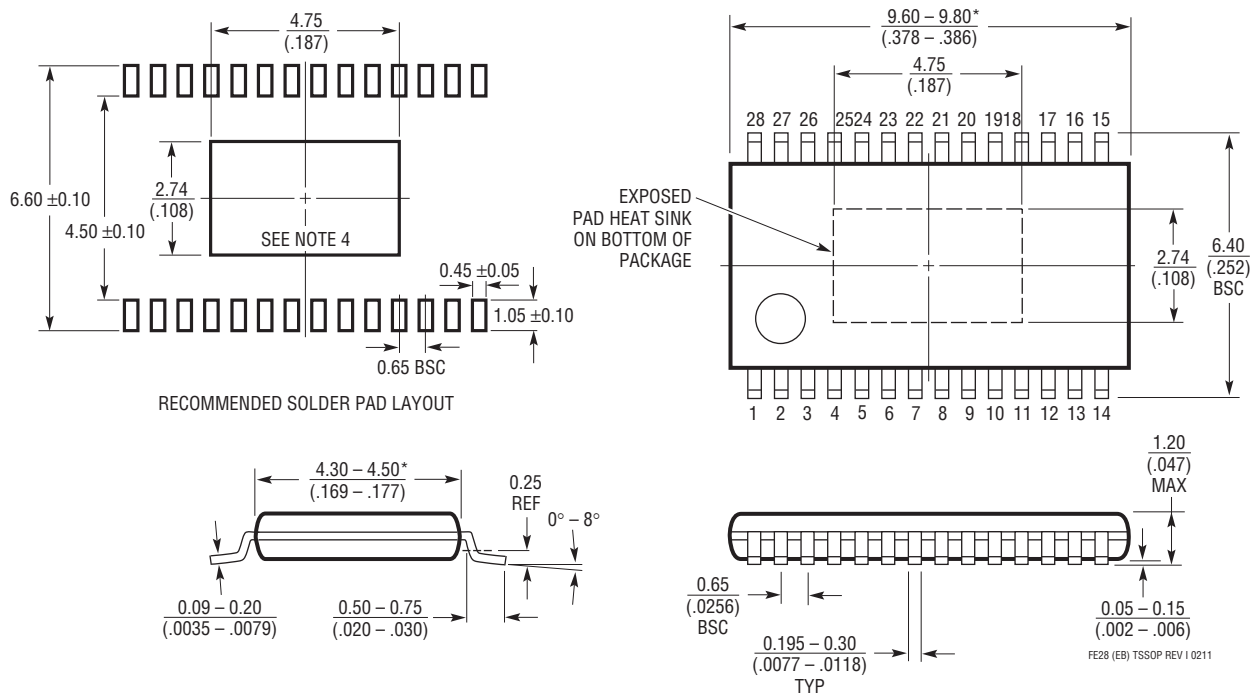
### NOTE:

1. DRAWING PROPOSED TO BE MADE A JEDEC PACKAGE OUTLINE MO-220 VARIATION (WXXX-X).
2. DRAWING NOT TO SCALE
3. ALL DIMENSIONS ARE IN MILLIMETERS
4. DIMENSIONS OF EXPOSED PAD ON BOTTOM OF PACKAGE DO NOT INCLUDE MOLD FLASH. MOLD FLASH, IF PRESENT, SHALL NOT EXCEED 0.15mm ON ANY SIDE
5. EXPOSED PAD SHALL BE SOLDER PLATED
6. SHADED AREA IS ONLY A REFERENCE FOR PIN 1 LOCATION ON THE TOP AND BOTTOM OF PACKAGE

## PACKAGE DESCRIPTION

Please refer to <http://www.linear.com/designtools/packaging/> for the most recent package drawings.

**FE Package**  
**28-Lead Plastic TSSOP (4.4mm)**  
 (Reference LTC DWG # 05-08-1663 Rev I)  
**Exposed Pad Variation EB**



**NOTE:**

1. CONTROLLING DIMENSION: MILLIMETERS
  2. DIMENSIONS ARE IN MILLIMETERS (INCHES)
  3. DRAWING NOT TO SCALE
  4. RECOMMENDED MINIMUM PCB METAL SIZE FOR EXPOSED PAD ATTACHMENT
- \*DIMENSIONS DO NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED 0.150mm (.006") PER SIDE

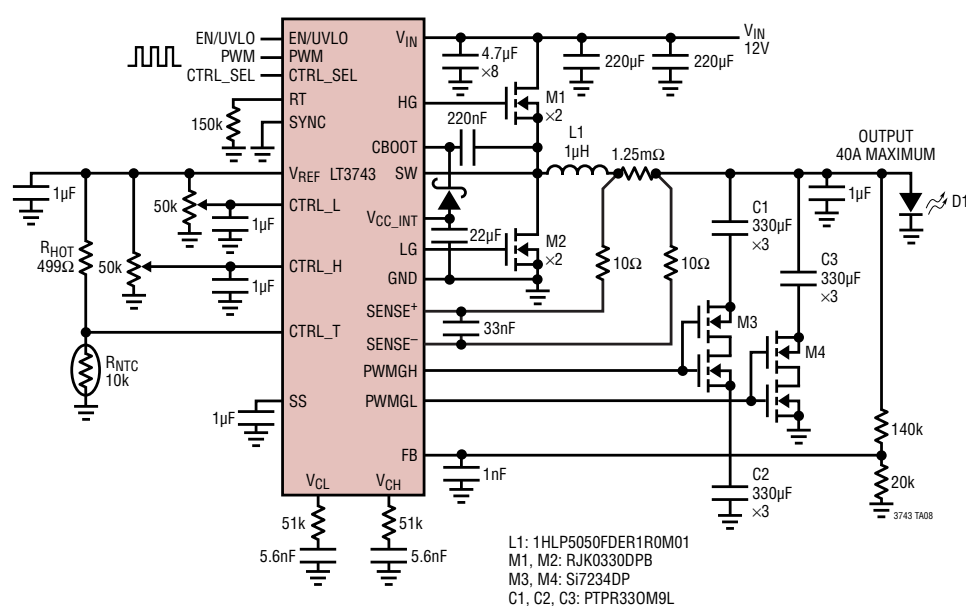
FE28 (EB) TSSOP REV I 0211

## REVISION HISTORY

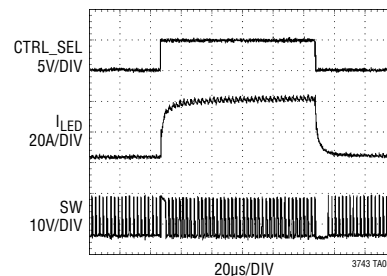
| REV | DATE  | DESCRIPTION  | PAGE NUMBER        |
|-----|-------|--|--------------------|
| A   | 2/10  | Revised Features and Typical Application   | 1                  |
|     |       | Updated Electrical Characteristics values  | 3, 4               |
|     |       | Revised values on curves G32 and G33 in the Typical Performance Characteristics section  | 8                  |
|     |       | Revised the Block Diagram  | 11                 |
|     |       | Changed value in equation and made minor text edit in the Inductor Selection section   | 13                 |
|     |       | Revised Table 4 values   | 18                 |
|     |       | Added text to Average Current Mode Control Compensation and Board Layout Considerations sections in the Applications Information section | 20                 |
|     |       | Revised all Typical Applications drawings  | 21 to 25, 28       |
|     |       |  |                    |
| B   | 8/10  | Updated Electrical Characteristics values and conditions   | 3, 4               |
|     |       | Revised Pin Functions  | 9, 10              |
|     |       | Revised Block Diagram  | 11                 |
|     |       | Changed soft-start current in Operation section  | 12                 |
|     |       | Revised units for M1 and M2 equations  | 14                 |
|     |       | Removed 0.1MHz switching frequency from Table 4  | 18                 |
|     |       | Added text to Switching Frequency Synchronization, Shutdown and UVLO sections in the Applications Information section                    | 19                 |
|     |       | Corrected M2 and M3 part numbers on Typical Applications drawings  | 24, 28             |
|     |       |  |                    |
| C   | 9/11  | Revised Feedback Regulation Voltage listing in Electrical Characteristics section  | 3                  |
| D   | 11/12 | Clarified $V_{CL}$ and $V_{CH}$ pins   | 1, 2, 9, 11, 21-24 |
|     |       | Clarified Regulated Current vs $V_{FB}$ graph  | 6                  |
|     |       | Clarified Minimum Off-Time graph   | 7                  |

## TYPICAL APPLICATION

## 12V, 40A Pulsed LED Driver



**V<sub>IN</sub> = 12V**  
**4A to 40A LED Current Step**



## RELATED PARTS

| PART NUMBER     | DESCRIPTION   | COMMENTS   |
|-----------------|---|--|
| LT3755/LT3755-1 | High Side 40V, 1MHz LED Controller with True Color 3000:1 PWM Dimming   | $V_{IN}$ : 4.5V to 40V, $V_{OUT(MAX)}$ = 60V, Dimming = 3000:1 True Color PWM™, $I_{SD}$ < 1μA, 3mm × 3mm QFN16, MSOP16E |
| LT3756/LT3756-1 | High Side 100V, 1MHz LED Controller with True Color 3000:1 PWM Dimming  | $V_{IN}$ : 6V to 100V, $V_{OUT(MAX)}$ = 100V, Dimming = 3000:1 True Color PWM, $I_{SD}$ < 1μA, 3mm × 3mm QFN16, MSOP16E  |
| LTC3783         | High Side 36V, 1MHz LED Controller with True Color 3000:1 PWM Dimming   | $V_{IN}$ : 3V to 36V, $V_{OUT(MAX)}$ = 40V, Dimming = 3000:1 True Color PWM, $I_{SD}$ < 20μA, 4mm × 5mm DFN16, TSSOP16E  |
| LT3517          | 1.3A, 2.5MHz High Current LED Driver with 3000:1 Dimming                | $V_{IN}$ : 3V to 30V, Dimming = 3000:1 True Color PWM, $I_{SD}$ < 1μA, 4mm × 4mm QFN16                                   |
| LT3518          | 2.3A, 2.5MHz High Current LED Driver with 3000:1 Dimming                | $V_{IN}$ : 3V to 30V, Dimming = 3000:1 True Color PWM, $I_{SD}$ < 1μA, 4mm × 4mm QFN16                                   |
| LT3496          | Triple Output 750mA, 2.1MHz High Current LED Driver with 3000:1 Dimming | $V_{IN}$ : 3V to 30V, $V_{OUT(MAX)}$ = 40V, Dimming = 3000:1 True Color PWM, $I_{SD}$ < 1μA, 4mm × 5mm QFN28             |
| LT3474/LT3474-1 | 36V, 1A ( $I_{LED}$ ), 2MHz Step-Down LED Driver                        | $V_{IN}$ : 4V to 36V, $V_{OUT(MAX)}$ = 13.5V, Dimming = 400:1 True Color PWM, $I_{SD}$ < 1μA, TSSOP16E                   |
| LT3475/LT3475-1 | Dual 1.5A ( $I_{LED}$ ), 36V Step-Down LED Driver                       | $V_{IN}$ : 4V to 36V, $V_{OUT(MAX)}$ = 13.5V, Dimming = 3000:1 True Color PWM, $I_{SD}$ < 1μA, TSSOP20E                  |
| LT3476          | Quad Output 1.5A, 2MHz High Current LED Driver with 1000:1 Dimming      | $V_{IN}$ : 2.8V to 16V, $V_{OUT(MAX)}$ = 36V, Dimming = 1000:1 True Color PWM, $I_{SD}$ < 10μA, 5mm × 7mm QFN10          |
| LT3478/LT3478-1 | 4.5A, 2MHz High Current LED Driver with 3000:1 Dimming                  | $V_{IN}$ : 2.8V to 36V, $V_{OUT(MAX)}$ = 40V, Dimming = 1000:1 True Color PWM, $I_{SD}$ < 10μA, 5mm × 7mm QFN10          |



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