

# MC13234/MC13237

Low Cost SoC Remote Control Platform for the 2.4 GHz IEEE® 802.15.4 Standard

## 1 Introduction

The MC13234/MC13237 is Freescale's low cost System-on-Chip (SoC) solution for the IEEE® 802.15.4 Standard that incorporates a complete, low power, 2.4 GHz radio frequency transceiver with TX/RX switch, an 8-bit HCS08 CPU, and a functional set of MCU peripherals into a 48-pin LGA package. This product targets wireless RF remote control and other cost-sensitive applications ranging from home TV and entertainment systems to medical and supports all ZigBee node types. The MC13234/MC13237 is a highly integrated solution, with very low power consumption.

The MC13234/MC13237 contains an RF transceiver that is an 802.15.4 Standard 2006 compliant radio that operates in the 2.4 GHz ISM frequency band. The transceiver includes a low noise amplifier, 1 mW nominal output power amplifier (PA), internal voltage controlled oscillator (VCO), integrated transmit/receive switch, on-board power supply regulation, 12-bit ADC and full spread-spectrum encoding and decoding.

The on-chip CPU is based on the Freescale HCS08 family of microcontroller units (MCU). The onboard

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MCU peripheral set has been defined to support the targeted applications. A dedicated DMA block transfers packet data between RAM and the transceiver to off-load the CPU and allow higher efficiency and increased performance.

## 1.1 Ordering information

Table 1 provides ordering information to include RAM, flash, and feature detail differences associated with the MC1323x family of devices

**Table 1. Orderable parts details**

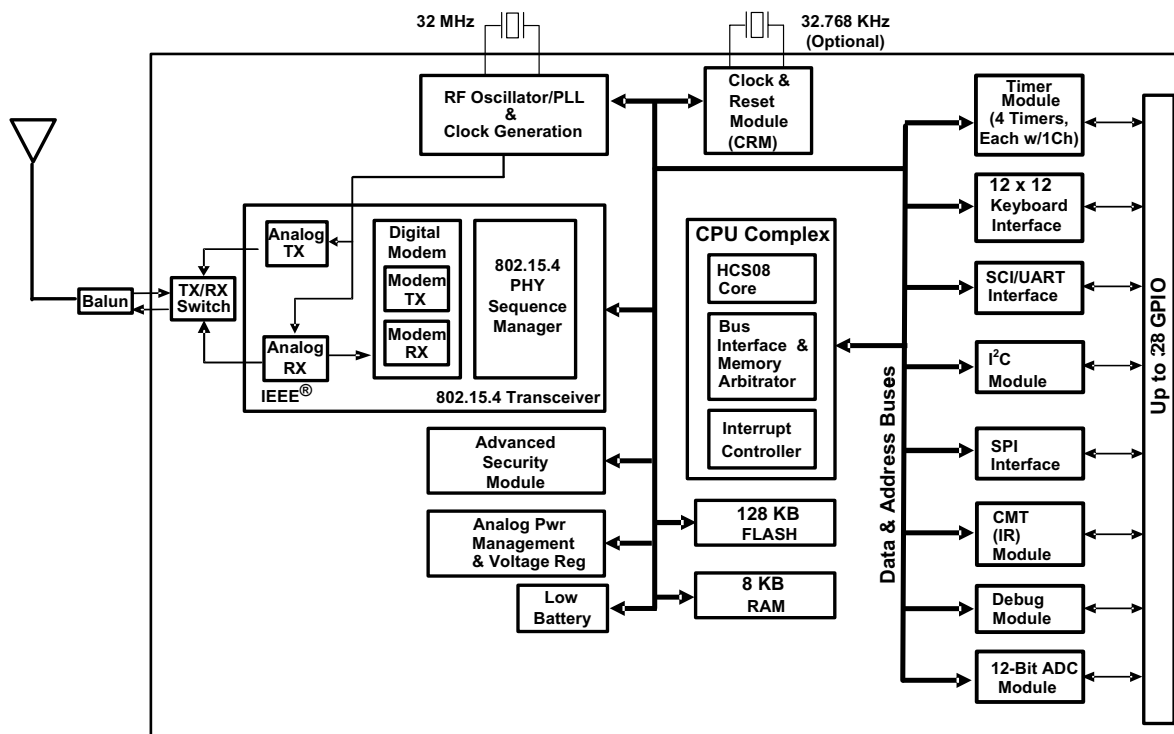
Device	Operating Temp Range (TA.)	Package	Memory Options
MC13234CHT	–40° to 85° C	LGA-48	8 KB RAM, 128 KB flash
MC13234CHTR2	–40° to 85° C	LGA-48 Tape and Reel	8 KB RAM, 128 KB flash
MC13237CHT	–40° to 85° C	LGA-48	8 KB RAM, 128 KB flash
MC13237CHTR2	–40° to 85° C	LGA-48 Tape and Reel	8 KB RAM, 128 KB flash

## 2 Features

This section provides a simplified block diagram and highlights the MC13234/MC13237 features.

### 2.1 Block diagram

Figure 1 shows a simplified block diagram of the MC13234/MC13237.



NOTE: MC13237 Rev 1.1 does not support SPI module. It is planned to be fixed in a future revision. The 12-Bit ADC module is available only in MC13237 and not available in MC13234.

**Figure 1. MC13234/MC13237 simplified block diagram**

## 2.2 Features summary

- Fully compliant IEEE 802.15.4 Standard 2006 transceiver supports 250 kbps O-QPSK data in 5.0 MHz channels and full spread-spectrum encode and decode
  - 2.4 GHz
  - Operates on one of 16 selectable channels per IEEE 802.15.4
  - Programmable output power with 0 dBm nominal output power, programmable from -30 dBm to +2 dBm typical
  - Receive sensitivity of -93 dBm (typical) at 1% PER, 20-byte packet, much better than the IEEE 802.15.4 Standard requirement of -85 dBm
  - Partial power down (PPD\_RX) Listen mode available to reduce current while in receive mode and waiting for an incoming frame
- Small RF footprint
  - Integrated transmit/receive switch
  - Differential input/output port (typically used with a balun)
  - Low external component count
- Hardware acceleration for IEEE<sup>®</sup> 802.15.4 applications
  - DMA interface

- AES-128 security module
- 16-bit random number generator
- 802.15.4 auto-sequence support
- 802.15.4 receiver frame filtering
- 32 MHz crystal reference oscillator; onboard load trim capability supplements external load capacitors
- Onboard 1 kHz oscillator for wake-up timing or an optional 32.768 kHz crystal for accurate low power timing
- Transceiver event timer module has 4 timer comparators available to help manage the auto-sequencer and to supplement MCU TPM resources
- HCS08 8-bit, 32 MHz CPU
- Flash memory
  - 131072<sub>dec</sub> bytes organized as 128 segments by 1024 bytes
  - Programmable over the full power supply range of 1.8 V–3.6 V
  - Automated program and erase algorithms
  - Flexible protection scheme to prevent accidental program or erase
  - Security feature to prevent unauthorized access to the flash
- RAM
  - 8 KBytes of SRAM
- Powerful in-circuit debug and flash programming available via on-chip module (BDM)
  - Two comparator and 9 trigger modes
  - Eight deep FIFO for storing change-of-flow addresses and event-only data
  - Tag and force breakpoints
  - In-circuit debugging with single breakpoint
- Multiple low power modes (less than 1  $\mu$ A in Stop3)
- Keyboard interrupt (KBI) modules
  - MC13234
    - Two keyboard control modules capable of supporting up to a 12 x 12 keyboard matrix
    - 12 dedicated KBI pins support a 6 x 6 matrix without impacting other IO resources
    - 12 KBI interrupts with selectable polarity
  - MC13237
    - One keyboard control module capable of supporting up to a 8 x 8 keyboard matrix
    - 8 dedicated KBI pins support a 4 x 4 matrix without impacting other IO resources
    - 8 KBI interrupts with selectable polarity
- Serial communication interface (SCI)
  - Full duplex non-return to zero (NRZ)
  - Baud rates as high as 1 Mbps can be supported
  - LIN master extended break generation

- LIN slave extended break detection
- Wake-up on active edge
- Serial peripheral interface (SPI)
  - Full-duplex or single-wire bidirectional
  - Double-buffered transmit and receive
  - Master or slave mode; MSB-first or LSB-first shifting
- Inter-integrated circuit (IIC) interface
  - Up to 100 kbps baud rate with maximum bus loading
  - Baud rates as high as 800 kbps can be programmed
  - Multi-master operation
  - Programmable slave address
  - Interrupt driven byte-by-byte data transfer
  - Supports broadcast mode and 10-bit addressing
- Four 16-bit timer/pulse width modulators (TPM[4:1]) — each TPM module has an assigned GPIO pin and provides
  - Single channel capability
  - Input capture
  - Output compare
  - Buffered edge-aligned or center-aligned PWM
- 8-Channel, 12-bit resolution ADC (available only in MC13237)
  - 11.2 Effective Number of Bits (ENOB)
  - 2.5  $\mu$ s conversion time
  - Internal 1.7 mV/°C temperature sensor
  - Internal bandgap reference
  - Operation in Stop3
  - Fully functional from 1.8 V to 3.6 V
- Carrier modulator timer (CMT) — IR remote carrier generator, modulator, and transmitter.
- Real-time counter (RTC)
  - 16-bit modulus counter with binary or decimal based prescaler;
  - External clock source for precise time base, time-of-day, calendar or task scheduling functions
  - Capable of greater than one day interrupt.
- System protection features
  - Programmable low voltage warning and interrupt (LVI)
  - Optional watchdog timer (COP)
  - Illegal opcode detection
- 1.8 V to 3.6 V operating voltage with on-chip voltage regulators.
- Up to 32 GPIO

- MC13234: 32 GPIOs
- MC13237: 28 GPIOs
- Hysteresis and selectable pullup resistors on all input pins
- Configurable slew rate and drive strength on all output pins
- -40°C to +85°C operating temperature range
- RoHS-compliant 7 x 7 mm 48-pin LGA package

**Table 2. MC13234 and MC13237 Comparison**

Feature	MC13234	MC13237
Radio	IEEE 802.15.4 compliant	
CPU	32 MHz HCS08	
Flash memory	128K	
RAM	8K	
BDM	Yes	
Low power modes	Yes	
KBI	Two (12 interrupts)	One (8 interrupts)
SCI	Yes	
SPI	Yes	
IIC	Yes	
TPM	Yes	
CMT	Yes	
RTC	Yes	
LVD	Yes	
COP	Yes	
ADC	No	Yes
GPIO	32	28

## 2.3 Software solutions

Freescall provides a powerful software environment called the Freescall BeeKit Wireless Connectivity Toolkit. BeeKit is a comprehensive codebase of wireless networking libraries, application templates, and sample applications. The BeeKit Graphical User Interface (GUI), part of the BeeKit Wireless Connectivity Toolkit, allows users to create, modify, and update various wireless networking implementations. A wide range of software functionality is available to complement the MC13234/MC13237 and these are provided as codebases within BeeKit. The following sections describe the available tools, however due to continuous updates that occur on FSL software inquiries to applications engineering is recommended.

### 2.3.1 Simple Media Access Controller (SMAC)

The Freescale Simple Media Access Controller (SMAC) is a simple ANSI C based code stack available as sample source code. The SMAC can be used for developing proprietary RF transceiver applications using the MC13234/MC13237.

- Supports point-to-point and star network configurations
- Proprietary networks
- Source code and application examples provided

### 2.3.2 IEEE® 802.15.4 2006 Standard-Compliant MAC

The Freescale 802.15.4 Standard-Compliant MAC is a code stack available as object code. The 802.15.4 MAC can be used for developing MC13234/MC13237 networking applications based on the full IEEE® 802.15.4 Standard that use custom Network Layer and application software.

- Supports star, mesh, and cluster tree topologies
- Supports beacons networks
- Supports GTS for low latency
- Multiple power saving modes
- AES-128 security module
- 802.15.4 sequence support
- 802.15.4 receiver frame filtering.

### 2.3.3 SynkroRF platform

The SynkroRF Network is a general purpose, proprietary networking layer that sits on top of the IEEE® 802.15.4 MAC and PHY layers. It is designed for wireless personal area networks (WPANs) and conveys information over short distances among the participants in the network. It enables small, power efficient, inexpensive solutions to be implemented for a wide range of applications. Some key characteristics of an SynkroRF network are:

- An over-the-air data rate of 250 kbps in the 2.4 GHz band.
- 3 independent communication channels in the 2.4 GHz band (15, 20, and 25).
- 2 network node types, controller and controlled nodes.
- Channel agility mechanism.
- Low latency TX mode automatically enabled in conditions of radio interference.
- Fragmented mode transmission and reception, automatically enabled in conditions of radio interference.
- Robustness and ease of use.
- Essential functionality to build and support a CE network.

The SynkroRF network layer uses components from the standard HC(S)08 Freescale platform, which is also used by the Freescale's implementations of 802.15.4. MAC and ZigBee™ layers. For more details about the platform components, see the *Freescale Platform Reference Manual*.

### 2.3.4 BeeStack Consumer

Freescall's ZigBee RF4CE stack, called BeeStack Consumer, is a networking layer that sits on top of the IEEE® 802.15.4 MAC and PHY layers. It is designed for standards-based wireless personal area networks (WPANs) of home entertainment products and conveys information over short distances among the participants in the network. It enables small, power efficient, inexpensive solutions to be implemented for a wide range of applications. Targeted applications include DTV, set top box, A/V receivers, DVD players, security, and other consumer products.

Some key characteristics of a BeeStack Consumer network are:

- An over-the-air data rate of 250 kbps in the 2.4 GHz band
- 3 independent communication channels in the 2.4 GHz band
- 2 network node types, controller node and target node
- Channel agility mechanism
- Provides robustness and ease of use
- Includes essential functionality to build and support a CE network

The BeeStack Consumer layer uses components from the standard HCS08 Freescale platform, which is also used by the Freescale implementations of 802.15.4. MAC or ZigBee™ layers. For more details about the platform components, see the *Freescale Platform Reference Manual*.

### 2.3.5 ZigBee-Compliant Network Stack

Freescall's BeeStack architecture builds on the ZigBee protocol stack. Based on the OSI Seven-Layer model, the ZigBee stack ensures inter-operability among networked devices. The physical (PHY), media access control (MAC), and network (NWK) layers create the foundation for the application (APL) layers. BeeStack defines additional services to improve the communication between layers of the protocol stack.

At the application layer, the application support layer (ASL) facilitates information exchange between the application support sub-layer (APS) and application objects. Finally, ZigBee Device Objects (ZDO), in addition to other manufacturer-designed applications, allow for a wide range of useful tasks applicable to home and industrial automation.

BeeStack uses the IEEE 802.15.4-compliant MAC/PHY layer that is not part of ZigBee itself. The NWK layer defines routing, network creation and configuration, and device synchronization. The application framework (AF) supports a rich array of services that define ZigBee functionality. ZigBee Device Objects (ZDO) implement application-level services in all nodes via profiles. A security service provider (SSP) is available to the layers that use encryption (NWK and APS), i.e., Advanced Encryption Standard (AES) 128-bit security.

The complete Freescale BeeStack protocol stack includes the following components:

- ZigBee Device Objects (ZDO) and ZigBee Device Profile (ZDP)
- Application support sub-layer (APS)
- Application framework (AF)
- Network (NWK) layer
- Security service provider (SSP)
- IEEE 802.15.4-compliant MAC and Physical (PHY) layer



### 3 Integrated IEEE 802.15.4 Transceiver (radio and modem)

The MC13234/MC13237 is a IEEE<sup>®</sup> 802.15.4 fully-compliant transceiver providing a complete 2.4 GHz radio solution with 250 kbps offset-quadrature phase shift keying (O-QPSK) data in 5.0 MHz channel spacings with full spread-spectrum encode and decode. The modem supports the full requirement of the IEEE<sup>®</sup> 802.15.4 Standard functionality to transmit, receive, and do clear channel assessment (CCA), energy detect (ED), and link quality indication (LQI). Some top level transceiver features supported are listed below:

- Programmable output power with 0 dBm nominal output power, programmable from –30 dBm to +2 dBm typical
- Receive sensitivity of –93 dBm (typical) at 1% PER, 20-byte packet
- Differential bidirectional RF input/output port
- Integrated transmit/receive switch
- Receive current can be reduced while waiting or listening for an incoming frame using partial power down (PPD) mode1 (see [Table 11](#))

#### 3.1 RF interface and usage

The MC13234/MC13237 RF interface provides a bidirectional, differential port that connects directly to a balun. The balun connects directly to a single-ended antenna and converts that interface to a full differential, bidirectional, on-chip interface with transmit/receive switch, LNA, and complementary PA outputs. This combination allows for a small footprint and low cost RF solution to be realized.

#### 3.2 Transceiver register interface and operation

The transceiver is controlled by set of interface registers that are memory-mapped into the CPU address space. MC13234/MC13237 supports independent transmit, receive, or CCA/ED (energy detection) modes of operation and combinations. Additional features of the transceiver include:

- DMA function that moves data directly between RAM and transceiver buffers during diplexed transmit and receive operation on a cycle-steal basis. This feature offloads the data transfer from the CPU, thus providing higher performance.
- Interrupt capability that is dependent on RX packet data availability. An interrupt can be generated based on a programmed count of RX data bytes that have been received and moved to RAM. This allows CPU filtering of RX data before completion of the packet reception to accelerate response to the packet.
- Four (4) transceiver event timer comparators to supplement MCU peripheral timer resources for PHY and MAC timing requirements.

#### 3.3 IEEE 802.15.4 acceleration hardware

MC13234/MC13237 transceiver has several hardware features to reduce the software stack size, offload the function from the CPU, and improve performance. A list of features supported is provided below:

- 2003 & 2006 versions of the IEEE<sup>®</sup> 802.15.4 standard is full supported.
- Slotted and unslotted modes
- Beacon enabled and non-beacon enabled networks
- DMA data transfer between RAM and radio
- Separate AES-128 security module
- 16-bit random number generator
- 802.15.4 sequence support
  - RX (conditionally followed by TXAck)
  - TX
  - CCA (used for CCA and ED cycles)
  - TX/RX (TX followed by unconditional RX or RCACK)
  - Continuous CCA
- 802.15.4 receiver frame filtering

### 3.4 Partial Power Down Receive mode (PPD\_RX)

The MC13234/MC13237 provides a unique Partial Power Down Receive (PPD\_RX) mode. A summary of PPD\_RX mode of operation when selected is described below:

- Whenever a receive cycle is initiated, the receiver is not turned fully on to save current until receive energy of a preset level is detected
- The receiver will turn fully on only when triggered by energy at a pre-determined preset level thus enabling reception of the expected frame. Afterwards, the receiver will begin operating in the full-on state that is considered to be the same as the standard receive state
- The preset level can be programmed for various RX input power levels

Use of the PPD\_RX mode provides two distinct advantages:

- Reduced “Listen” mode current — The receive current is significantly reduced while waiting for a frame. If a node is a coordinator, router, or gateway and it spends a significant percentage of its RF-active time waiting for incoming frames from clients or other devices, the net power savings can be significant.
- Reduced sensitivity as a desired effect — The PPD\_RX mode provides different levels of reduced sensitivity. If a node operates in a densely populated area, it may be desirable to de-sensitize the receiver such that the device does not respond to incoming frames with an energy level below the desired threshold. This could be useful for security, net efficiency, reduced noise triggering, and many other purposes.

## 4 HCS08 8-bit central processing unit (CPU)

The onboard CPU is a 32 MHz 8-bit HCS08 core. It executes a super set of the 68HC08 instruction set with added BGND instructions. The HCS08 CPU is fully source and object code compatible with the M68HC08 CPU. Several instructions and enhanced addressing modes are added to improve C compiler efficiency and to support a new background debug system. It has an 8-bit data bus, a 16-bit address bus, and a 2-stage instruction pipe that facilitates the overlapping of instruction fetching and execution. There are 29 vectors for internal interrupt sources and one vector for an external interrupt pin. The debug or BDM module provides a serial one-wire interface for non-intrusive debugging of application programs.

Features of the HCS08 CPU include:

- Object code fully upward-compatible with M68HC05 and M68HC08 Families
- 64-KB CPU address space with banked memory management unit for greater than 64 KB
- 16-bit stack pointer (any size stack anywhere in 64-KB CPU address space)
- 16-bit index register (H:X) with powerful indexed addressing modes
- 8-bit accumulator (A)
- Many instructions treat X as a second general-purpose 8-bit register
- Seven addressing modes:
  - Inherent — Operands in internal registers
  - Relative — 8-bit signed offset to branch destination
  - Immediate — Operand in next object code byte(s)
  - Direct — Operand in memory at 0x0000–0x00FF
  - Extended — Operand anywhere in 64-KB address space
  - Indexed relative to H:X — Five submodes including auto increment
  - Indexed relative to SP — Improves C efficiency dramatically
- Memory-to-memory data move instructions with four address mode combinations
- Overflow, half-carry, negative, zero, and carry condition codes support conditional branching on the results of signed, unsigned, and binary-coded decimal (BCD) operations
- Efficient bit manipulation instructions
- Fast 8-bit by 8-bit multiply and 16-bit by 8-bit divide instructions
- STOP and WAIT instructions to invoke low-power operating modes

## 5 System clocks

The primary system reference frequency is a 32 MHz crystal oscillator. The crystal requirements for the oscillator and oscillator performance must support a  $\pm 40$  ppm frequency accuracy to meet the IEEE<sup>®</sup> 802.15.4 Standard requirements. All system clocks are generated from this source. Features of the clock system include:

- The 32 MHz reference oscillator has onboard programmable capacitive loading that allows software tuning of frequency accuracy
- CPU clock as high as 32 MHz
- Bus clock (and peripheral clock) equals 1/2 CPU clock
- Clocks to individual peripherals can be independently disabled for best power management
- CPU clock can be lowered to 500 kHz for lower power (250 kHz bus clock)

An optional 32.768 kHz crystal oscillator is available for accurate low power timing and the real time clock (RTC). Also, an onboard, low accuracy 1 kHz oscillator is available for sleep timing wake-up.

## 6 Memory

The MC13234/MC13237 memory resources consist of RAM, Flash program memory for nonvolatile data storage, control/status registers for I/O, peripherals, management, and the transceiver. Features include:

- 128 Kbyte flash
- 8 Kbyte SRAM
- Security circuitry to prevent unauthorized access to RAM and flash contents

## 7 System and power management

MC13234/MC13237 is a low power device that also supports extensive system control and power management modes to maximize battery life and provide system protection.

### 7.1 Modes of operation

The MC13234/MC13237 modes of operation include:

- Active background mode for code development
- Run mode — CPU clocks can be run at full speed and the internal supply is fully regulated.

- LPRun mode — CPU clock is set to 500 kHz and peripheral clocks (bus clock) to 250 kHz and the internal voltage regulators are in standby
- Wait mode — CPU shuts down to conserve power; system clocks are running and full regulation is maintained
- LPWait mode — CPU shuts down to conserve power; peripheral clocks are restricted to 250 kHz and the internal voltage regulator is in standby
- Stop modes — System clocks are stopped and voltage regulator is in standby
  - Stop3 — All internal circuits are powered for fast recovery (32 MHz oscillator on-off optional)

**NOTE:** See [Table 9](#) for further details on modes of operation

## 7.2 Power management

The MC13234/MC13237 power management is controlled through programming of the modes of operation. Different modes allow for different levels of power-down. Additional features include:

- The transceiver is powered as required
- The analog radio is only powered-up as required to do a TX, RX, or CCA/ED operation
- Peripheral control clock gating can be disabled on an MCU module-by-module basis to provide lowest power
- Programmed mode manages
  - Degree of chip power down
  - Retention of programmed parameters
  - Clock management
- Power-down and wake-up (clocks and analog blocks) are gracefully controlled
- RTC can be used as wake-up timer
- Wake-up available through KBI and UART RX asynchronous interrupts
- Real-time counter (RTC) module
  - 16-bit modulus counter with binary or decimal based prescaler for precise time base, time-of-day, calendar or task scheduling functions
  - Capable of greater than one day interrupt
  - Can also be used for device wake-up

## 7.3 System protection

The MC13234/MC13237 provides several vehicles to maintain security or a high level of system robustness:

- Watchdog computer operating properly (COP) reset with option to run from dedicated internal clock source or bus clock
- Low-voltage warning and detection with reset or interrupt; selectable trip points
- Illegal opcode detection with reset
- Flash block protection

## 8 MCU peripherals

The MC13234/MC13237 has a functional set of MCU peripherals focused for intended applications. For further information on application use-cases please refer to the Reference Manual.

### 8.1 Parallel input/output (GPIO)

MC13234 and MC13237 have 32 and 28 general purpose I/O signals, respectively. These GPIO signals are distributed among four I/O ports (PTA, PTB, PTC, and PTD). Many of these pins are shared with on-chip peripherals such as timer systems, communication ports, or keyboard interrupts. When these other modules are not controlling the port pins, they revert to general-purpose I/O control. For each I/O pin, a port data bit provides access to input (read) and output (write) data, a data direction bit controls the direction of the pin, and a pullup enable bit enables an internal pullup device (provided the pin is configured as an input), and a slew rate control bit controls the rise and fall times of the pins.

Parallel I/O features include:

- A total of 32 or 28 general-purpose I/O pins in four ports (PTA2 is output only)
- Hysteresis input buffers
- Software-controlled pullups on each input pin
- Software-controlled slew rate output buffers

### 8.2 Keyboard interrupt modules (KBI)

MC13234 has two (2) KBI modules; KBI1 shares eight (8) port B pins and KBI2 shares four (4) port C pins. MC13237 has one (1) KBI module; KBI1 shares eight (8) port B pins. Any KBI pin can be enabled as a keyboard input that can act as an interrupt request. As a result, the total 12 KBI inputs (MC13234) allows as large as a 12x12 keyboard matrix. The total 8 KBI inputs (MC13237) allows as large as a 8x8 keyboard matrix with use of other GPIO pins as outputs to the matrix.

All enabled KBI inputs can be configured for edge-only sensitivity or edge-and-level sensitivity. They also can be configured for either rising edge / high-level or falling-edge/low-level sensitivity. When enabled for rising edge / high level sensitivity, a pulldown resistor is enabled, and when enabled for falling edge / low level sensitivity, a pullup resistor is enabled.

The KBI features include:

- KBI1 has eight (8) keyboard interrupt pins with individual pin enable bits.
- KBI2 (available only in MC13234) has four (4) keyboard interrupt pins with individual pin enable bits.
- Supports up to a 12x12 (MC13234) or 8x8 (MC13237) keyboard matrix. An 8x8 matrix (MC13234) or 4x4 (MC13237) matrix can be supported without impacting other I/O functions.
- Each keyboard interrupt pin is programmable as falling edge (or rising edge) only, or both falling edge and low level (or both rising edge and high level) interrupt sensitivity. pullups and pulldowns enabled by selected mode.
- Individual signal software enabled interrupts for KBI1 and KBI2.
- Can be used for device wake-up

## 8.3 Serial communications interface (SCI) module

The MC13234/MC13237 has one serial communications interface module — sometimes called a universal asynchronous receiver/transmitter (UART). Typically, this port is used to connect to the RS232 serial input/output (I/O) port of a personal computer or workstation, and it can also be used to communicate with other embedded controllers.

The SCI module has a single, flexible frac-N (13-bit modulo counter, 5-bit fractional counter) baud rate generator used both for transmit and receive. With a maximum 16 MHz peripheral clock, baud rates as high as 1 Mbps can be supported (standard is 921,600 baud).

This SCI system offers many advanced features not commonly found on other asynchronous serial I/O peripherals on other embedded controllers. The receiver employs an advanced data sampling technique that ensures reliable communication and noise detection. Hardware parity, receiver wake-up, and double buffering on transmit and receive are also included.

Features of SCI module include:

- Dedicated TXD and RXD pins
- Full-duplex, standard non-return-to-zero (NRZ) format
- Double-buffered transmitter and receiver with separate enables
- Programmable high accuracy baud rates (frac-N generator)
- Interrupt-driven or polled operation:
  - Transmit data register empty and transmission complete
  - Receive data register full
  - Receive overrun, parity error, framing error, and noise error
  - Idle receiver detect
  - Active edge on receive pin
  - Break detect supporting LIN
- Hardware parity generation and checking
- Programmable 8-bit or 9-bit character length
- Receiver wake-up by idle-line or address-mark
- Optional 13-bit break character generation / 11-bit break character detection
- Selectable transmitter output polarity

## 8.4 Serial peripheral interface (SPI) module

The MC13234/MC13237 has one serial peripheral interface module. The SPI is a synchronous serial data input/output port used for interfacing with serial memories, peripheral devices, or other processors. The SPI allows an 8-bit serial bit stream to be shifted simultaneously into and out of the device at a programmed bit-transfer rate (called 4-wire mode). There are four (4) pins associated with the SPI port (SPICLK, MOSI, MISO, and  $\overline{SS}$ ).

The SPI module can be programmed for master or slave operation. It also supports a 3-wire mode where for master mode the MOSI becomes MOMI, a bidirectional data pin, and for slave mode the MISO becomes SISO, a bidirectional data pin. In 3-wire mode, data is transferred in only one direction at a time.

The SPI bit clock is derived from the peripheral input clock with a maximum 16 MHz operation. A programmable prescaler (maximum divide-by-8) drives a second baud rate programmable divider (maximum divide-by-256) to develop the bit clock. The maximum SPI transfer rate is 8 MHz.

Features of the SPI module include:

- Master or slave mode operation
- Full-duplex or single-wire bidirectional option
- 8-bit only transfer size
- Programmable transmit bit rate (8 MHz max)
- Double-buffered transmit and receive
- Serial clock phase and polarity options (supports all 4 options)
- Optional slave select output
- Selectable MSB-first or LSB-first shifting

## 8.5 Inter-integrated circuit (IIC) interface module

The MC13234/MC13237 has one inter-integrated circuit interface module that provides a method of communication between a number of other integrated circuits. The IIC Bus interface provides a bidirectional, 2-pin (SDA bus data and SCL bus clock) serial bus designed to operate up to 100 kbps with maximum bus loading and timing. The module is capable of operating at higher baud rates, up to a maximum of peripheral clock/20 (800 kbps), with reduced bus loading.

Features of IIC module include:

- Compatible with IIC bus standard
- Multi-master operation
- Software programmable clock frequencies
- Software selectable acknowledge bit
- Interrupt driven byte-by-byte data transfer
- Arbitration lost interrupt with automatic mode switching from master to slave
- Calling address identification interrupt
- START and STOP signal generation/detection
- Repeated START signal generation
- Acknowledge bit generation/detection
- Bus busy detection
- General call recognition
- 10-bit address extension



## 8.6 Timer/PWM (TPM) modules

The MC13234/MC13237 has four (4) independent timer/PWM modules, each with one channel. Each TPM module is based on a 16-bit counter and provides input capture, output compare, and Pulse Width Modulation (PWM). Each TPM module has one associated I/O pin for input capture or counter/PWM output.

TPM module features include:

- Each TPM may be configured for buffered, center-aligned pulse-width modulation (CPWM) on all channels
- Module clock source is peripheral clock or reference oscillator divided-by-1024
- Clock prescaler taps for divide by 1, 2, 4, 8, 16, 32, 64, or 128
- 16-bit free-running or up/down (CPWM) count operation
- 16-bit modulus register to control counter range
- Module enable
- One interrupt per channel plus a terminal count interrupt for each TPM module
- Channel features:
  - Each channel may be input capture, output compare, or buffered edge-aligned PWM
  - Rising-edge, falling-edge, or any-edge input capture trigger
  - Set, clear, or toggle output compare action
  - Selectable polarity on PWM outputs

## 8.7 Carrier Modulator Timer (CMT) Module

The MC13234/MC13237 Carrier Modulator Timer module is intended as an IR LED driver for remote control “blaster” applications. The module consists of a carrier generator, modulator, and transmitter that drives data to package pin # 31 (PTD4/CMT/AD3) either in baseband or in FSK mode. The CMT.../IRO pin drives (modulates) the IR diode directly or through a buffer depending on the applications current requirement. The current drive capability of this pin is specified for 20mA.

The CMT module features include:

- Four (4) modes of operation:
  - Time with independent control of high and low times
  - Baseband
  - Frequency Shift Key (FSK)
  - Direct software control of CMT...IRO pin
- Extended space operation in time, baseband, and FSK modes
- Module clock source is peripheral clock (16 MHz max)
- Interrupt on end of cycle
- Ability to disable CMT...IRO pin and use as timer interrupt

## 8.8 Real Time Counter (RTC) Module

The MC13234/MC13237 Real Time Counter module consists of one(1) 16-bit counter, one(1) 16-bit comparator, several binary-based and decimal-based prescaler dividers, three (3) clock sources, and one(1) programmable periodic interrupt. This module can be used for time-of-day, calendar or any task scheduling functions. It can also serve as a cyclic wake-up from low power modes (Stop2, Stop3, and Wait). RTC can be clocked from bus clock, the optional 32.768 kHz oscillator or the onboard 1 kHz low power oscillator.

Features of the RTC module include:

- 16-bit up-counter
  - 16-bit modulo match limit
  - Software controllable periodic interrupt on match
- Three software selectable clock sources for input to prescaler with programmable 16 bit prescaler
  - 32.768 kHz optional crystal oscillator.
  - 32 MHz reference oscillator
  - 1 kHz low power RC oscillator
- Useful for time base tick or time-of-day clock
- Can be used for device wake-up; capable of greater than one day time-out period.

## 8.9 12-Bit Analog-to-Digital Conversion (ADC) Module

The MC13237 integrates an 8 channel, 12-bit resolution Successive Approximation Register (SAR) analog-to-digital conversion (ADC) module. The analog input channels are shared/multiplexed with standard GPIO pins as shown in [Figure 3](#). The ADC module is available in MC13237 only; not available in MC13234.

Features of the ADC module include:

- 11.2 Effective Number of Bits (ENOB)
- Linear successive approximation algorithm with 12-bits resolution
- Operation in Stop3 mode
- 2.5  $\mu$ s conversion time
- Internal bandgap reference
- Operation over full VBATT voltage range
- Internal 1.7 mV/°C temperature sensor
- Output data can be formatted in 8-, 10-, or 12-bit justified format
- Single or continuous conversion
- Configurable sample time and conversion speed / power.
- Auto compare for less-than, greater than, or equal to programmable value
- Converter subsystem shut-down

## 9 Development Environment

Development support for the HCS08 on the MC13234/MC13237 includes the background debug controller (BDC) and the on-chip debug module (DBG). The BDC provides a single-wire (signal BKGD) debug interface to the MCU that provides a convenient interface for programming the on-chip flash and other storage. The BDC is also the primary debug interface for development and allows non-intrusive access to memory data and traditional debug features such as CPU register modify, breakpoints, and single instruction trace commands.

Address and data bus signals are not available on external pins. Debug is done through commands fed into the MCU via the single-wire background debug interface. The debug module provides a means to selectively trigger and capture bus information so an external development system can reconstruct what happened inside the MCU on a cycle-by-cycle basis without having external access to the address and data signals. Features include:

- Single-wire background debug interface
- Breakpoint capability to allow single breakpoint setting during in-circuit debugging (plus two more breakpoints in on-chip debug module)
- On-chip in-circuit emulator (ICE) debug module containing three comparators and nine trigger modes.
- Eight deep FIFO for storing change-of-flow addresses and event-only data. Debug module supports both tag and force breakpoints.

# 10 Pin Assignment and Connections

## 10.1 Device Pin Assignments

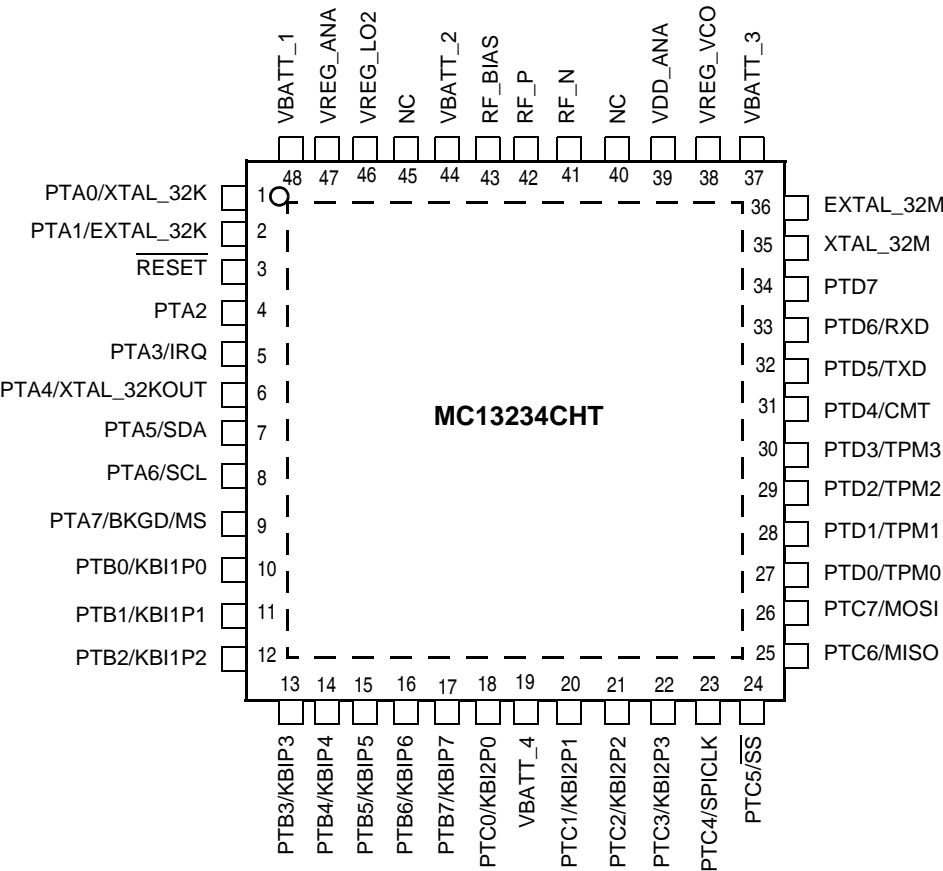


Figure 2. MC13234 Pinout

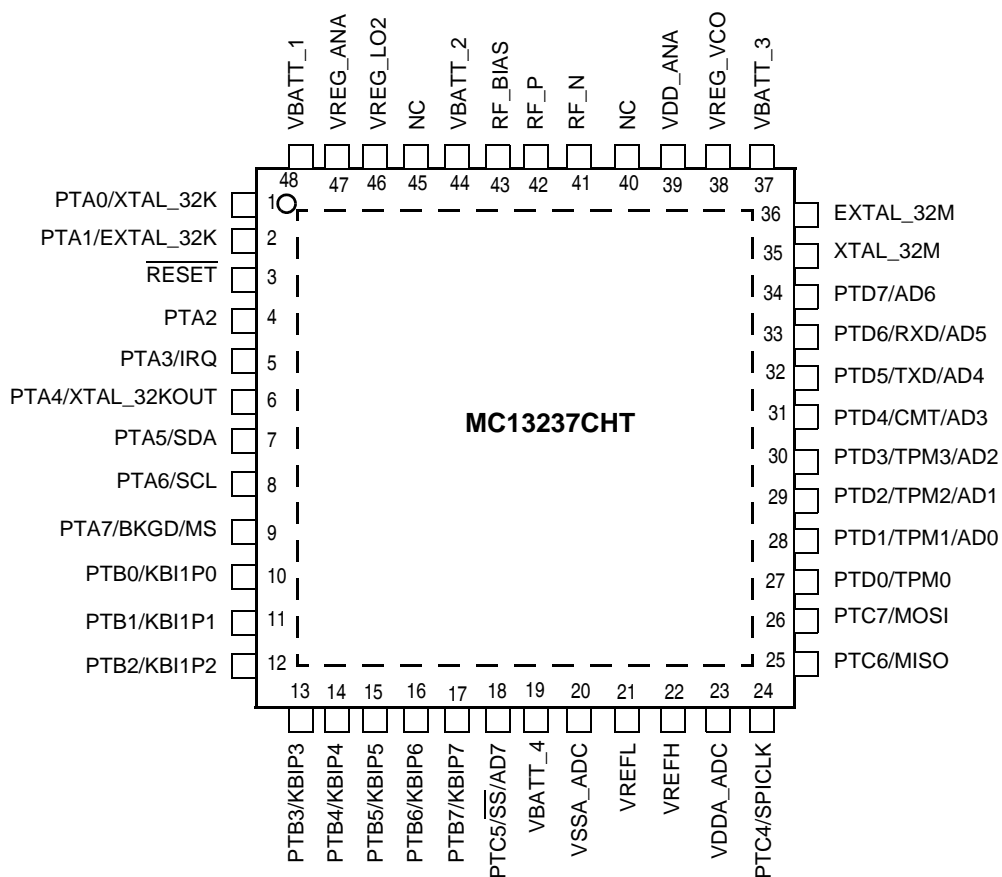


Figure 3. MC13237 Pinout

## 10.2 Pin Definitions

Table 4 details the MC13234 pinout and functionality.

**Table 3. MC13234 Pin Function Description**

Pin #	Pin Name	Type	Description	Functionality
1	PTA0/XTAL_32K	Digital Input/Output	Port A Bit 0 / 32.768 kHz oscillator output	
2	PTA1/EXTAL_32K	Digital Input/Output	Port A Bit 1 / 32.768 kHz oscillator input	For normal use, 10 kOhm resistor to ground recommended
3	RESET	Digital Input/Output	Device asynchronous hardware reset. Active low. Onboard Pullup	Normally input; gets driven low for a period after a reset
4	PTA2	Digital Output	Port A Bit 2 / Test Mode enable.	TM mode input. Must be biased low exiting POR for normal operation
5	PTA3/IRQ	Digital Input/Output	Port A Bit 3 / IRQ.	
6	PTA4/XTAL_32KOUT	Digital Input/Output	Port A Bit 4 / Buffered 32.768 kHz clock output	Optional 32.768 kHz output clock for measuring 32 kHz oscillator accuracy (ppm)
7	PTA5/SDA	Digital Input/Output	Port A Bit 5 / IIC Bus data	Defaults to open drain for IIC
8	PTA6/SCL	Digital Input/Output	Port A Bit 6 / IIC Bus clock	Defaults to open drain for IIC
9	PTA7/BKGD/MS	Digital Input/Output	Port A Bit 7 / Background / Mode Select	Debug signal
10	PTB0/KBI1P0	Digital Input/Output	Port B Bit 0 / KBI1 Input Bit 0	Wake-up capability
11	PTB1/KBI1P1	Digital Input/Output	Port B Bit 1 / KBI1 Input Bit 1	Wake-up capability
12	PTB2/KBI1P2	Digital Input/Output	Port B Bit 2 / KBI1 Input Bit 2	Wake-up capability
13	PTB3/KBI1P3	Digital Input/Output	Port B Bit 3 / KBI1 Input Bit 3	Wake-up capability
14	PTB4/KBI1P4	Digital Input/Output	Port B Bit 4 / KBI1 Input Bit 4	Wake-up capability
15	PTB5/KBI1P5	Digital Input/Output	Port B Bit 5 / KBI1 Input Bit 5	Wake-up capability
16	PTB6/KBI1P6	Digital Input/Output	Port B Bit 6 / KBI1 Input Bit 6	Wake-up capability
17	PTB7/KBI1P7	Digital Input/Output	Port B Bit 7 / KBI1 Input Bit 7	Wake-up capability
18	PTC0/KBI2P0	Digital Input/Output	Port C Bit 0 / KBI2 Input Bit 0	
19	VBATT_4	Power Input	VDD supply input <sup>1</sup>	Connect to system VDD supply
20	PTC1/KBI2P1	Digital Input/Output	Pot C Bit 1 / KBI2 Input Bit 1	
21	PTC2/KBI2P2	Digital Input/Output	Pot C Bit 2 / KBI2 Input Bit 2	
22	PTC3/KBI2P3	Digital Input/Output	Pot C Bit 3 / KBI2 Input Bit 3	
23	PTC4/SPICLK	Digital Input/Output	Port C Bit 4 / SPI clock	
24	PTC5/SS	Digital Input/Output	Port C Bit 5 / SPI slave select	
25	PTC6/MISO	Digital Input/Output	Port C Bit 6 / SPI MISO	
26	PTC7/MOSI/32M_OUT	Digital Input/Output	Port C Bit 7 / SPI MOSI / 32 MHz XTAL output	

**Table 3. MC13234 Pin Function Description (continued)**

Pin #	Pin Name	Type	Description	Functionality
27	PTD0/TPM0	Digital Input/Output	Port D Bit 0 / TPM0 signal	TPM0 timer output / gate input signal
28	PTD1/TPM1	Digital Input/Output	Port D Bit 1/ TPM1 signal	TPM1 timer output / gate input signal.
29	PTD2/TPM2	Digital Input/Output	Port D Bit 2 / TPM2 signal	TPM2 timer output / gate input signal.
30	PTD3/TPM3	Digital Input/Output	Port D Bit 3 / TPM3 signal	TPM3 timer output / gate input signal.
31	PTD4/CMT	Digital Input/Output	Port D Bit 4 / CMT output	Hi drive output for IR diode.
32	PTD5/TXD	Digital Input/Output	Port D Bit 5 / UART TXD output	UART has no hardware flow control.
33	PTD6/RXD	Digital Input/Output	Port D Bit 6 / UART RXD input / AD5 signal	UART has no hardware flow control.
34	PTD7	Digital Input/Output	Port D Bit 7	
35	XTAL_32M	Analog Output	32 MHz reference oscillator output	
36	EXTAL_32M	Analog input	32 MHz reference oscillator input	
37	VBATT_3	Power Input	VDD supply input <sup>1</sup>	Connect to system VDD supply
38	VREG_VCO	VCO Reg Out / in	VCO regulator output and input to VCO 1.8 Vdc VDD	Bypass to ground with 220 nF capacitor.
39	VDD_ANA	Analog Power Input	Analog 1.8 Vdc Input	Connect to VREG_ANA
40	NC		No connection to device	May be left open or connect to ground
41	RF_N	RF Input/Output	Modem RF input/output negative	Bi-directional RF port for the internal LNA and PA
42	RF_P	RF Input/Output	Modem RF input/output positive	Bi-directional RF port for the internal LNA and PA
43	RF_BIAS	RF Voltage Output	Switched RF bias voltage (1.8 Vdc)	High for TX; low for RX
44	VBATT_2	Power Input	VDD supply input <sup>1</sup>	Connect to system VDD supply
45	NC			May be left open or connect to ground
46	VREG_LO2	LO2 Reg Out	LO2 regulator output @ 1.8 Vdc	Bypass to ground with 220 nF capacitor.
47	VREG_ANA	ANA Reg Out	Analog regulator output @ 1.8 Vdc	Bypass to ground with 220 nF capacitor. Connect to VDD_ANA
48	VBATT_1	Power Input	VDD supply to Analog regulator <sup>1</sup>	Connect to system VDD supply
Flag	GND	Power Input	System ground	

<sup>1</sup> VBATT\_1, VBATT\_2, VBATT\_3 and VBATT\_4 signals are not connected onboard MC13234/MC13237.

Table 4 details the MC13237 pinout and functionality.

**Table 4. MC13237 Pin Function Description**

Pin #	Pin Name	Type	Description	Functionality
1	PTA0/XTAL_32K	Digital Input/Output	Port A Bit 0 / 32.768 kHz oscillator output	
2	PTA1/EXTAL_32K	Digital Input/Output	Port A Bit 1 / 32.768 kHz oscillator input	For normal use, 10 kOhm resistor to ground recommended
3	RESET	Digital Input/Output	Device asynchronous hardware reset. Active low. Onboard Pullup	Normally input; gets driven low for a period after a reset
4	PTA2	Digital Output	Port A Bit 2 / Test Mode enable.	TM mode input. Must be biased low exiting POR for normal operation
5	PTA3/IRQ	Digital Input/Output	Port A Bit 3 / IRQ.	
6	PTA4/XTAL_32KOUT	Digital Input/Output	Port A Bit 4 / Buffered 32.768 kHz clock output	Optional 32.768 kHz output clock for measuring 32 kHz oscillator accuracy (ppm)
7	PTA5/SDA	Digital Input/Output	Port A Bit 5 / IIC Bus data	Defaults to open drain for IIC
8	PTA6/SCL	Digital Input/Output	Port A Bit 6 / IIC Bus clock	Defaults to open drain for IIC
9	PTA7/BKGD/MS	Digital Input/Output	Port A Bit 7 / Background / Mode Select	Debug signal
10	PTB0/KBI1P0	Digital Input/Output	Port B Bit 0 / KBI1 Input Bit 0	Wake-up capability
11	PTB1/KBI1P1	Digital Input/Output	Port B Bit 1 / KBI1 Input Bit 1	Wake-up capability
12	PTB2/KBI1P2	Digital Input/Output	Port B Bit 2 / KBI1 Input Bit 2	Wake-up capability
13	PTB3/KBI1P3	Digital Input/Output	Port B Bit 3 / KBI1 Input Bit 3	Wake-up capability
14	PTB4/KBI1P4	Digital Input/Output	Port B Bit 4 / KBI1 Input Bit 4	Wake-up capability
15	PTB5/KBI1P5	Digital Input/Output	Port B Bit 5 / KBI1 Input Bit 5	Wake-up capability
16	PTB6/KBI1P6	Digital Input/Output	Port B Bit 6 / KBI1 Input Bit 6	Wake-up capability
17	PTB7/KBI1P7	Digital Input/Output	Port B Bit 7 / KBI1 Input Bit 7	Wake-up capability
18	PTC5/SS/AD7	Digital Input/Output	Port C Bit 5 / SPI Slave Select / AD7 Signal	
19	VBATT_4	Power Input	VDD supply input <sup>1</sup>	Connect to system VDD supply
20	VSSA_ADC	Digital Input/Output	ADC analog ground	
21	VREFL	Digital Input/Output	ADC low reference voltage	
22	VREFH	Digital Input/Output	ADC high reference voltage	
23	VDDA_ADC	Digital Input/Output	ADC analog power supply	
24	PTC4/SPICLK	Digital Input/Output	Port C Bit 4 / SPI Clock	
25	PTC6/MISO	Digital Input/Output	Port C Bit 6 / SPI MISO	
26	PTC7/MOSI	Digital Input/Output	Port C Bit 7 / SPI MOSI	
27	PTD0/TPM0	Digital Input/Output	Port D Bit 0 / TPM0 signal	TPM0 timer output / gate input signal



**Table 4. MC13237 Pin Function Description (continued)**

Pin #	Pin Name	Type	Description	Functionality
28	PTD1/TPM1/AD0	Digital Input/Output	Port D Bit 1/ TPM1 signal /AD0 signal	TPM1 timer output / gate input signal. ADC input 0
29	PTD2/TPM2/AD1	Digital Input/Output	Port D Bit 2 / TPM2 signal /AD1 signal	TPM2 timer output / gate input signal. ADC input 1
30	PTD3/TPM3/AD2	Digital Input/Output	Port D Bit 3 / TPM3 signal /AD2 signal	TPM3 timer output / gate input signal. ADC input 2
31	PTD4/CMT/AD3	Digital Input/Output	Port D Bit 4/ CMT output / AD3 signal	Hi drive output for IR diode. ADC input 3
32	PTD5/TXD/AD4	Digital Input/Output	Port D Bit 5 / UART TXD output / AD4 signal	UART has no hardware flow control. ADC input 4
33	PTD6/RXD/AD5	Digital Input/Output	Port D Bit 6 / UART RXD input / AD5 signal	UART has no hardware flow control. ADC input 5
34	PTD7/AD6	Digital Input/Output	Port D Bit 7 / AD6 signal	ADC input 6
35	XTAL_32M	Analog Output	32 MHz reference oscillator output	
36	EXTAL_32M	Analog input	32 MHz reference oscillator input	
37	VBATT_3	Power Input	VDD supply input <sup>1</sup>	Connect to system VDD supply
38	VREG_VCO	VCO Reg Out / in	VCO regulator output and input to VCO 1.8 Vdc VDD	Bypass to ground with 220 nF capacitor.
39	VDD_ANA	Analog Power Input	Analog 1.8 Vdc Input	Connect to VREG_ANA
40	NC		No connection to device	May be left open or connect to ground
41	RF_N	RF Input/Output	Modem RF input/output negative	Bi-directional RF port for the internal LNA and PA
42	RF_P	RF Input/Output	Modem RF input/output positive	Bi-directional RF port for the internal LNA and PA
43	RF_BIAS	RF Voltage Output	Switched RF bias voltage (1.8 Vdc)	High for TX; low for RX
44	VBATT_2	Power Input	VDD supply input <sup>1</sup>	Connect to system VDD supply
45	NC	Input	No connection to device	May be left open or connect to ground
46	VREG_LO2	LO2 Reg Out	LO2 regulator output @ 1.8 Vdc	Bypass to ground with 220 nF capacitor.
47	VREG_ANA	ANA Reg Out	Analog regulator output @ 1.8 Vdc	Bypass to ground with 220 nF capacitor. Connect to VDD_ANA
48	VBATT_1	Power Input	VDD supply to Analog regulator <sup>1</sup>	Connect to system VDD supply
Flag	GND	Power Input	System ground	

<sup>1</sup> VBATT\_1, VBATT\_2, VBATT\_3 and VBATT\_4 signals are not connected onboard MC13234/MC13237.

# 11 Electrical Specifications

This section details maximum ratings for the 48-pin LGA package, recommended operating conditions, DC characteristics, and AC characteristics.

## 11.1 Package Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maximum rating is not guaranteed. Stress beyond the limits specified in [Table 5](#) may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either  $V_{SS}$  or  $V_{BATT}$ ) or the programmable pullup resistor associated with the pin is enabled.

[Table 5](#) shows the maximum ratings for the 48-Pin LGA package.

**Table 5. LGA Package Maximum Ratings**

Rating	Symbol	Value	Unit
Maximum Junction Temperature	$T_J$	125	°C
Storage Temperature Range	$T_{stg}$	125	°C
Moisture Sensitivity Level		MSL3-260	
Reflow Soldering Temperature		260	°C
Power Supply Voltage	$V_{BATT}$	−0.3 to 3.7	Vdc
Digital Input Voltage	$V_{in}$	−0.3 to ( $V_{DD} + 0.3$ )	Vdc
RF Input Power	$P_{max}$	10	dBm

**Note:** Maximum Ratings are those values beyond which damage to the device may occur. Functional operation should be restricted to the limits in the Electrical Characteristics or Recommended Operating Conditions tables.

**Note:** All pins meets ESD Human Body Model (HBM) = 2 kV

## 11.2 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions should be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with the JESD22 Stress Test Qualification for Commercial Grade Integrated Circuits. During the device qualification ESD stresses were performed for the human body model (HBM), the machine model (MM) and the charge device model (CDM).

All latchup test testing is in conformity with the JESD78 IC Latch-Up Test.

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification.

**Table 6. ESD and Latch-up Test Conditions<sup>1</sup>**

Model	Description	Symbol	Value	Unit
Human Body	Series resistance	R1	1500	$\Omega$
	Storage capacitance	C	100	pF
	Number of pulses per pin <sup>2</sup>	—	1	
Machine	Series resistance	R1	0	$\Omega$
	Storage capacitance	C	200	pF
	Number of pulses per pin <sup>2</sup>	—	1	
Latch-up	Minimum input voltage limit		- 1.8	V
	Maximum input voltage limit		4.32	V

<sup>1</sup> There is no equivalent circuit (model) for CDM per JESD22-C101-A.

<sup>2</sup> This number represents a minimum number for both positive pulse(s) and negative pulse(s)

**Table 7. ESD and Latch-Up Protection Characteristics**

No.	Rating <sup>1, 2</sup>	Symbol	Min	Max	Unit
1	Human body model (HBM)	$V_{HBM}$	$\pm 2000$	—	V
2	Machine model (MM)	$V_{MM}$	$\pm 200$	—	V
3	Charge device model (CDM)	$V_{CDM}$	$\pm 750$	—	V
4	Latch-up current at $T_A = 85^\circ\text{C}$	$I_{LAT}$	$\pm 100$	—	mA

<sup>1</sup> Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

<sup>2</sup> All package pins including RF pins.

## 11.3 Recommended Operating Conditions

### NOTE

The MC13234/MC13237 transceiver provides an IEEE<sup>®</sup> 802.15.4 Standard PHY compliant node over all recommended operating conditions.

**Table 8. Recommended Operating Conditions**

Characteristic	Symbol	Min	Typ	Max	Unit
Power Supply Voltage ( $V_{BATT}$ )	$V_{BATT}$	1.8 <sup>1</sup>	2.7	3.6	Vdc
Input Frequency	$f_{in}$	2.405	—	2.480	GHz
Operating Temperature Range	$T_A$	-40	25	85	$^\circ\text{C}$
Logic Input Voltage Low	$V_{IL}$	0	—	30% $V_{BATT}$	V

**Table 8. Recommended Operating Conditions (continued)**

Characteristic	Symbol	Min	Typ	Max	Unit
Logic Input Voltage High	$V_{IH}$	70% $V_{BATT}$	—	$V_{BATT}$	V
Output Load Current (with specified $V_{OLmax}$ and $V_{OHmin}$ ) All standard GPIO CMT output IRO	$I_O$	— —	— —	3 20	mA
RF Input Power	$P_{max}$	—	—	10	dBm
Crystal Reference Oscillator Frequency ( $\pm 40$ ppm over operating conditions to meet the 802.15.4 Standard.)	$f_{ref}$	32 MHz Only			

<sup>1</sup> Although the device functions at  $V_{DDmin}$ , the supply must first rise above  $V_{LVDL}$ . As the supply voltage rises, the LVD circuit will hold the MCU in reset until the supply has risen above  $V_{LVDL}$ .

## 11.4 DC Electrical Characteristics

**Table 9. DC Electrical Characteristics<sup>1</sup>**

(Typical conditions:  $V_{BATT} = 2.7$  V,  $T_A = 25$  °C, unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
Power Supply Voltage (voltage applied to power input pins; $V_{BATT\_1}$ , $V_{BATT\_2}$ , $V_{BATT\_3}$ , $V_{BATT\_4}$ and $V_{DDA\_ADC}$ )	$V_{DD}$	1.8 <sup>2</sup>	2.7	3.6	Vdc
Minimum CPU RUN voltage (Radio and peripherals not guaranteed operational; CPU, RAM, and Flash operational)	$V_{DD\_RUN}$	1.6			Vdc
ADC Voltage Reference High	$V_{REFH}$	1.8	2.7	$V_{DDA\_ADC}$	Vdc
ADC Voltage Reference Low	$V_{REFL}$		$V_{SSA\_ADC}$		Vdc
Minimum RAM retention voltage (voltage applied to $V_{BATT}$ power input pins)	$V_{RAM}$	$V_{POR}$			Vdc
Low-voltage detection threshold - high range (all conditions <sup>3</sup> ) $V_{DD}$ falling $V_{DD}$ rising	$V_{LVDH}$	2.18 2.20	2.23 2.26	2.32 2.32	Vdc
Low-voltage detection threshold - low range (all conditions) $V_{DD}$ falling $V_{DD}$ rising	$V_{LVDL}$	1.67 1.68	1.70 1.77	1.80 1.96	Vdc
Low-voltage warning threshold - high range (all conditions) $V_{DD}$ falling $V_{DD}$ rising	$V_{LVWH}$	2.25 2.30	2.32 2.36	2.45 2.42	Vdc
Low-voltage warning threshold - low range (all conditions) $V_{DD}$ falling $V_{DD}$ rising	$V_{LVWL}$	1.79 1.74	1.81 1.84	1.91 1.99	Vdc
Power-on reset (POR) voltage	$V_{POR}$	—	1.0	—	Vdc
High impedance (off-state) leakage current (per pin) ( $V_{In} = V_{DD}$ or $V_{SS}$ , all input/outputs, device must not be in low power mode)	$ I_{OZ} $	−1.0	—	1.0	μA

**Table 9. DC Electrical Characteristics<sup>1</sup> (continued)**  
(Typical conditions:  $V_{BATT} = 2.7\text{ V}$ ,  $T_A = 25\text{ }^{\circ}\text{C}$ , unless otherwise noted)

Characteristic	Symbol	Min	Typ	Max	Unit
Input Current ( $V_{IN} = 0\text{ V}$ or $V_{DDINT}$ ) ( $V_{IN} = V_{DD}$ or $V_{SS}$ , all input/outputs, device must not be in low power mode)	$I_{IN}$	-1.0	—	+1.0	$\mu\text{A}$
Input Low Voltage (All digital inputs)	$V_{IL}$	0	—	30% $V_{BATT}$	V
Input High Voltage (all digital inputs)	$V_{IH}$	70% $V_{BATT}$	—	$V_{BATT}$	V
Input hysteresis (all digital inputs)	$V_{hys}$	$0.06 \times V_{DD}$	—	—	V
Internal pull up resistors <sup>4</sup> (all port pins and IRQ except CMT)	$R_{PU}$	—	20	—	kOhm
Internal CMT pull up resistor <sup>4</sup>	$R_{PU}$	—	10	—	kOhm
Internal pull down resistors <sup>4</sup> (KBI pins and IRQ)	$R_{PD}$	—	20	—	kOhm
Output High Voltage All standard GPIO = 3 mA CMT output IRO = 20 mA	$V_{OH}$	80% $V_{BATT}$	—	$V_{BATT}$	V
Output Low Voltage (All digital outputs) All standard GPIO = 3 mA CMT output IRO = 20 mA	$V_{OL}$	0	—	20% $V_{BATT}$	V
Input capacitance (all non-supply pins)	$C_{In}$	—	3	—	pF

<sup>1</sup> All ADC-related specifications apply only to the MC13237.

<sup>2</sup> Although the device functions at  $V_{DDmin}$ , the supply must first rise about  $V_{LVDL}$ . As the supply voltage rises, the LVD circuit will hold the MCU in reset until the supply has risen above  $V_{LVDL}$ .

<sup>3</sup> Denotes full voltage supply and temperature ranges.

<sup>4</sup> Measurement condition for pull resistors:  $V_{IN} = V_{SS}$  for pullup and  $V_{IN} = V_{DD}$  for pulldown.

## 11.5 Supply Current Characteristics

**Table 10. Supply Current Characteristics<sup>1</sup>**

(Typical conditions: VBATT = 2.7 V, T<sub>A</sub> = 25 °C, unless otherwise noted.)

Mode	Details	Min.	Typ.	Max.	Unit
<b>Stop3</b>	<ul style="list-style-type: none"> <li>All internal circuitry off, RAM, I/O, internal registers &amp; selectable peripheral registers retained, 32 MHz reference oscillator off, KBI active, RTC off, LVD off. RF in reset.</li> </ul>	—	0.45	—	uA
	<ul style="list-style-type: none"> <li>All internal circuitry off, RAM, I/O, internal registers &amp; selectable peripheral registers retained, 32 MHz reference oscillator off, KBI active, RTC on with 1 kHz oscillator, LVD off. RF in reset.</li> </ul>	—	0.55	—	
	<ul style="list-style-type: none"> <li>All internal circuitry off, RAM, I/O, internal registers &amp; selectable peripheral registers retained, 32 MHz reference oscillator off, KBI active, RTC on with 32.768 kHz oscillator, LVD off. RF in reset.</li> </ul>	—	2.65	—	
	<ul style="list-style-type: none"> <li>All internal circuitry off, RAM, I/O, internal registers &amp; selectable peripheral registers retained, 32 MHz reference oscillator on, KBI active, RTC on with 32 MHz oscillator, LVD off. RF in reset.</li> </ul>	—	330	—	
	<ul style="list-style-type: none"> <li>All internal circuitry off, RAM, I/O, internal registers &amp; selectable peripheral registers retained, 32 MHz reference oscillator on, KBI active, RTC on with 32 MHz oscillator, LVD on. RF in reset.</li> <li>ADC optionally on<sup>2</sup>.</li> </ul>	—	450	—	
Low Power Wait (LPWait)	<ul style="list-style-type: none"> <li>Entered from LPRun.</li> <li>Processor off, bus clock @ 250 kHz, voltage regulator in standby.</li> <li>Peripherals and modem clock disabled. RF in reset.</li> </ul>	0.50	0.56	0.62	mA
Wait	Processor off, system clocks are running and voltage regulator on. RF in reset or active mode.	—	2.9	—	mA
Low Power Run (LPRun)	<ul style="list-style-type: none"> <li>Processor forced to 500 kHz and bus clock @ 250 kHz.</li> <li>Peripheral state and RAM retained. Voltage regulators in standby.</li> <li>Peripherals and modem clocks disabled. RF in reset.</li> </ul>	0.53	0.75	0.85	mA
<b>Run</b>	<ul style="list-style-type: none"> <li>Processor running @ 32 MHz and peripheral clock @ 16 MHz.</li> <li>All peripherals clocks disabled<sup>3</sup> &amp; RAM active, voltage regulators fully on.</li> <li>RF in reset.</li> </ul>	4.0	4.7	4.9	mA

**Table 10. Supply Current Characteristics<sup>1</sup>** (continued)  
(Typical conditions: VBATT = 2.7 V, T<sub>A</sub> = 25 °C, unless otherwise noted.)

Mode	Details	Min.	Typ.	Max.	Unit
Transmit (TX)	<ul style="list-style-type: none"> <li>MCU in LPRUN (peripheral clock @ 250 kHz)</li> <li>RF in transmit mode (nominal power out)<sup>4</sup></li> </ul>	21.3	26.6	28.2	mA
Receive Partial Power Down (RX_PPD)	<ul style="list-style-type: none"> <li>MCU in LPRUN (peripheral clock @ 250 kHz)</li> <li>RF in Receive Partial Power Down Mode</li> </ul>	—	22.3	—	mA
Receive (RX)	<ul style="list-style-type: none"> <li>MCU in LPRUN (peripheral clock @ 250 kHz)</li> <li>RF in receive mode either 1) waiting @ full sensitivity or 2) receiving an actual frame.</li> </ul>	26.8	34.2	35	mA

<sup>1</sup> For ADC supply current specifications, see Table 24.

<sup>2</sup> Requires the asynchronous ADC clock. For Stop3, LVD must be enabled to run in Stop if converting bandgap channel.

<sup>3</sup> Register adjustment is per MC1323x Advance information, Rev 0.0 document: set SCGC1 and SCGC2 = 0X00

<sup>4</sup> TX output power set to nominal (0 dBm)

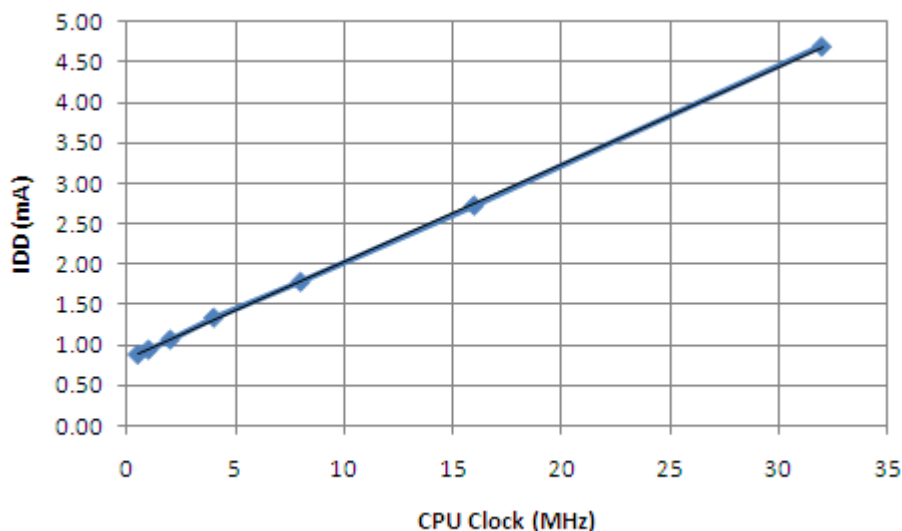


Figure 4. Typical RUN Current versus CPU Clock (only 0.5, 1, 2, 4, 8, 16, and 32 MHz available)

## 11.6 RF AC Electrical Characteristics

### NOTE

All specified RF parameters are referenced to the package pins and are the result of measurements with instrumentation in the reference circuit shown in [Figure 5](#).

**Table 11. Receiver AC Electrical Characteristics for 802.15.4 Modulation Mode**

(Typical conditions: VBATT = 2.7 V, TA = 25 °C, f<sub>ref</sub> = 32MHz, unless otherwise noted.)

Characteristic	Symbol	Min	Typ	Max	Unit
Sensitivity for 1% Packet Error Rate (PER) (+25 °C, @ package interface) <sup>1</sup>	SENS <sub>25 °C</sub>	—	−93	—	dBm
Sensitivity for 1% Packet Error Rate (PER) (Over all conditions) <sup>2</sup>	SENS	—	—	−89	dBm
Saturation (maximum input level)	SENS <sub>max</sub>	10	—	—	dBm
Channel Rejection for 1% PER					
+5 MHz (adjacent channel) <sup>3</sup>		—	35	—	dB
−5 MHz (adjacent channel) <sup>3</sup>		—	25	—	
+10 MHz (alternate channel) <sup>4</sup>		—	45	—	
−10 MHz (alternate channel) <sup>4</sup>		—	43	—	
≥ 15 MHz <sup>5</sup>		—	50	—	
Frequency Error Tolerance <sup>6</sup>		200	—	—	kHz
Symbol Rate Error Tolerance <sup>6</sup>		80	—	—	ppm

<sup>1</sup> Measured at f<sub>c</sub> = 2450 MHz.

<sup>2</sup> All conditions includes −40°C to +85°C, VBATT = 1.8 V to 3.6 V, and full frequency range

<sup>3</sup> IEEE 802.15.4 Standard specifies minimum adjacent channel rejection as 0 dB

<sup>4</sup> IEEE 802.15.4 Standard specifies minimum alternate channel rejection as 30 dB

<sup>5</sup> This parameter represents an average of all readings across all channels

<sup>6</sup> Minimum set by IEEE 802.15.4 Standard

**Table 12. Transmitter AC Electrical Characteristics for 802.15.4 Modulation Mode**

(Typical conditions: VBATT = 2.7 V, T<sub>A</sub> = 25 °C, f<sub>ref</sub> = 32 MHz, unless otherwise noted.)

Characteristic	Symbol	Min	Typ	Max	Unit
Nominal Output Power <sup>1</sup>	P <sub>out</sub>	−2.5	0	2.3	dBm
Maximum Output Power <sup>2</sup>		—	+2	—	dBm
Error Vector Magnitude	EVM	—	<16	18	%
Output Power Control Range		—	30	—	dB
Over the Air Data Rate		—	250	—	kbps
2nd Harmonic <sup>3</sup>		—	−44 <sup>4</sup>	—	dBm/(100 kHz)
3rd Harmonic and greater <sup>3</sup>		—	−54 <sup>4</sup>	—	dBm/(100 kHz)
Spurious Emissions <sup>5</sup>		—	—	—	
<1 GHz (quasi-peak detection mode)			−66		dBm
>1 GHz (peak detection mode)			−40		dBm/MHz
Lower Band Edge (peak detection mode)			−34		dBm/MHz
Upper Band Edge (peak detection mode)			−23		dBm/MHz

<sup>1</sup> Register sets output power to nominal (0 dBm).

<sup>2</sup> Register sets output power to maximum.

<sup>3</sup> Measurements taken at output of evaluation circuit set for maximum power out and averaged over 100 ms.

<sup>4</sup> With use of external filtering / harmonic trap as implemented in reference circuit.

<sup>5</sup> Derived from measured radiated values in units of dBuV/m and converted to EIRP (dBm).



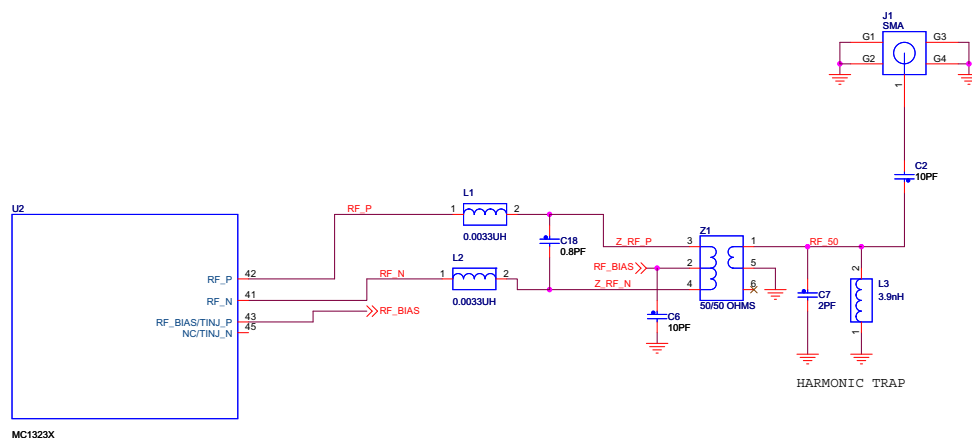


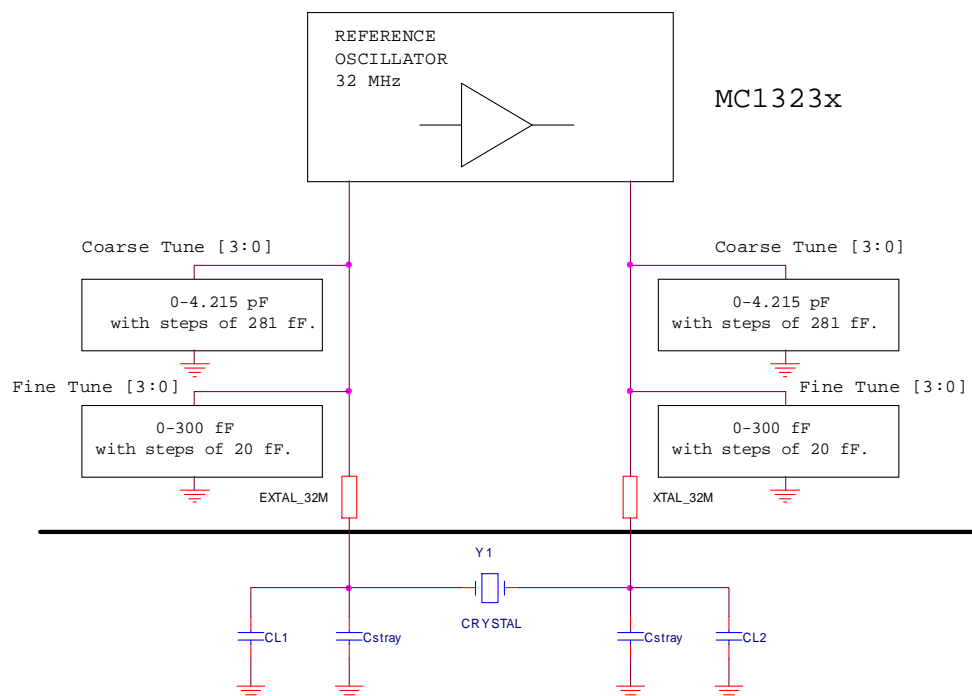
Figure 5. RF Parameter Reference Circuit

Table 13. RF Port Impedance, Pin RF\_P and RF\_N

Description	Frequency	Symbol	Typical	Unit
Series equivalent effective device impedance across the differential port derived from characterization of match network	2.405 GHz	$Z_{in}$	22.2 – j74.8	$\Omega$
	2.442 GHz		20.6 – j89.9	
	2.480 GHz		20.2 – j98.4	

## 11.7 Crystal Reference Clock Oscillator Characteristics

The reference oscillator model including external crystal is shown in Figure 6. The IEEE 802.15.4 Standard requires a frequency tolerance less than or equal to  $\pm 40$  ppm as shown in the oscillator specification Table 14. With a suitable crystal (refer to Table 15), the device frequency tolerance can typically be trimmed to be held to  $\pm 30$  ppm over all conditions.



**Figure 6. 32MHz Reference Oscillator Model**

**Table 14. Reference Oscillator Specifications**

Characteristic	Symbol	Min	Typ	Max	Unit
Frequency (nominal)			32.000000		MHz
Oscillator frequency tolerance over temperature range.			$\pm 30$	$\pm 40$	ppm
External load capacitance	$C_{Lext}$		8		pF
Internal Osc startup time <sup>1</sup>	$t_{cst}$		800		$\mu s$

<sup>1</sup> This is part of device wake-up time.

**Table 15. Recommended 32 MHz Crystal Specifications**

Parameter	Value	Unit	Condition
Frequency	32.000000	MHz	
Frequency tolerance (cut tolerance)	$\pm 10$	ppm	max at 25 °C
Frequency stability (temperature drift)	$\pm 16-18$	ppm	Over desired temperature range
Aging	$\pm 2$	ppm	max
Equivalent series resistance	60	$\Omega$	max
Load capacitance	9	pF	
Shunt capacitance	<2	pF	max
Mode of oscillation			fundamental

# 11.8 Optional 32.768 kHz Crystal Oscillator Specifications

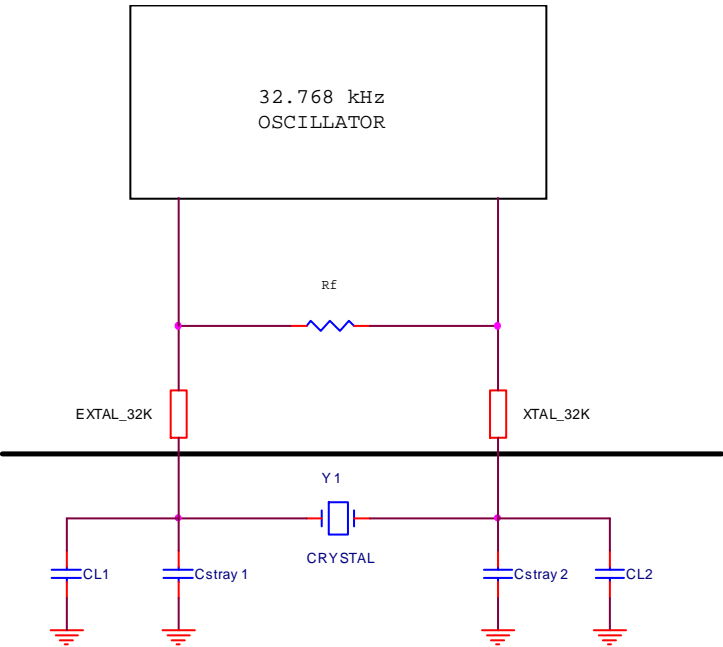


Figure 7. 32.768 kHz Oscillator Mode

Table 16. 32.768 Oscillator Crystal Typical Specifications

Characteristic	Symbol	Min	Typ	Max	Unit
Crystal frequency		32.768			kHz
Frequency tolerance @ 25 °C			± 20		ppm
Load capacitance		12	12.5	16	pF
Equivalent series resistance (ESR)		40		130	kΩ
Shunt capacitance				2	pF
Tolerated drive level				1	μW

# 11.9 Internal Low Speed Reference Oscillator Specifications

Table 17. Internal 1 kHz Oscillator Specifications

Characteristic	Symbol	Min	Typ	Max	Unit
Default Frequency @ 25 °C		0.80	1.0	1.40	kHz
Oscillator frequency variation over temperature <sup>1</sup> Deviation at -40 °C from 25 °C frequency Deviation at +85 °C from 25 °C frequency		—	-13 +6	—	%

<sup>1</sup> This percentage deviation is typical change from the individual device oscillator frequency at 25°C

## 11.10 Control Timing and CPU Bus Specifications

**Table 18. MCU Control Timing**

(Typical conditions: VBATT = 2.7 V, T<sub>A</sub> = 25 °C, f<sub>ref</sub> = 32MHz, unless otherwise noted.)

Parameter	Symbol	Min	Typical	Max	Unit
CPU frequency (t <sub>cyc</sub> = 1/RDIV)	f <sub>CPU</sub>	f <sub>ref</sub> /64 <sup>1</sup>	—	32 <sup>1</sup>	MHz
Bus Frequency (always 1/2 CPU clock) (t <sub>cyc</sub> = f <sub>BUS</sub> )	f <sub>BUS</sub>		f <sub>CPU</sub> /2		MHz
External reset pulse width		100	—	—	ns
External asynchronous minimum interrupt pulse width (KBI or IRQ) <sup>2</sup>		100	—	—	ns
External synchronous minimum interrupt pulse width (KBI or IRQ) <sup>3 4</sup>		1.5 t <sub>cyc</sub>	—	—	ns
Wake-up time from Stop3			800		μs

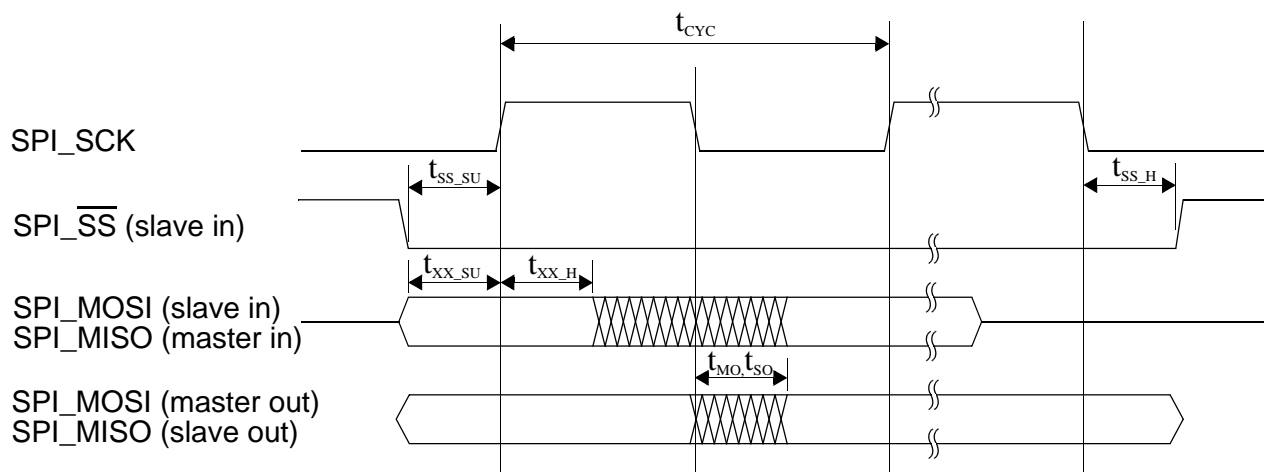
<sup>1</sup> The 32 MHz reference clock.

<sup>2</sup> Minimum pulse to recognize a asynchronous transition

<sup>3</sup> Minimum pulse to recognize a level sensitive

<sup>4</sup> For determination of an actual key/push button in a matrix, this pulse with must remain present for the keyboard scan routine duration. Thus, the minimum pulse width would be determined by the software, not the detection hardware.

## 11.11 SPI Timing



**Figure 8. SPI Timing Diagram**

Table 19 describes the timing requirements for the SPI system.

**Table 19. SPI Timing**

Parameter	Symbol	Min	Typical	Max	Unit
Master SPI_SCK Period	$t_{CYC}$	bus_Clk*2		bus_Clk *256	ns
Slave SPI_SCK Period	$t_{CYC}$	10			ns
Slave SPI_SS Setup Time	$t_{SS\_SU}$	10			ns
Slave SPI_SS Hold Time	$t_{SS\_H}$	10			ns
Slave SPI_MOSI Setup Time	$t_{SI\_SU}$	10			ns
Slave SPI_MOSI Hold Time	$t_{SI\_H}$	10			ns
Master SPI_MISO Setup Time	$t_{MI\_SU}$	20			ns
Master SPI_MISO Hold Time	$t_{MI\_H}$	0			ns
Master SPI_MOSI Output Time	$t_{MO}$			5	ns
Slave SPI_MISO Output Time (with 15 pf load)	$t_{SO}$			20	ns

## 11.12 I<sup>2</sup>C Specifications

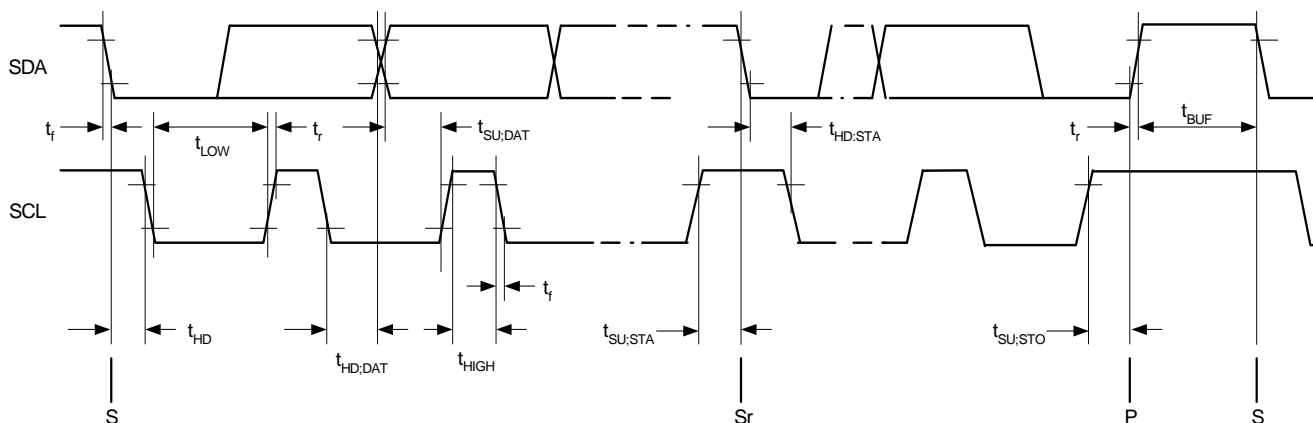
Table 20 describes the timing requirements for the I<sup>2</sup>C system.

The I<sup>2</sup>C module is driven by the peripheral bus clock (typically max 16 MHz) and the SCL bit clock is generated from a prescaler.

**Table 20. I<sup>2</sup>C Signal DC Specifications (I2C\_SDA and I2C\_SCL)**

Parameter	Symbol	Min	Typical	Max	Unit
Input Low Voltage	$V_{IL}$	-0.3	—	0.3 $V_{DDINT}$	V
Input High Voltage	$V_{IH}$	0.7 VBATT	—	VBATT + 0.3	V
Input hysteresis	$V_{hys}$	0.06 × VBATT	—	—	V
Output Low Voltage <sup>1</sup> ( $I_{OL} = 5$ mA)	$V_{OL}$	0	—	0.2 VBATT	V
Input Current ( $V_{IN} = 0$ V or $V_{DDINT}$ )	$I_{IN}$	—	—	±1	μA
Pin capacitance	$C_{in}$	—	—	<10	pF

<sup>1</sup> SDA and SCL are open drain outputs



**Figure 9. I²C Timing Diagram**

**NOTE**

The I²C timing limits reflect values that are necessary meet to the I²C Bus specification.

**Table 21. I²C Signal AC Specifications<sup>1</sup>**

Parameter	Symbol	Standard-Mode		Fast-Mode		Unit
		Min	Max	Min	Max	
SCL clock frequency (when source)	$f_{SCL}$	0	100	0	150	kHz
Hold time (repeated) Start condition. After this period, the first clock pulse is generated	$t_{HD:STA}$	4.0	—	0.6	—	$\mu s$
LOW period of the SCL clock	$t_{LOW}$	4.7	—	1.3	—	$\mu s$
HIGH period of the SCL clock	$t_{HIGH}$	4.0	—	0.6	—	$\mu s$
Set-up time for a repeated Start condition	$t_{SU:STA}$	4.7	—	0.6	—	$\mu s$
Data hold time	$t_{SHD:DAT}$	0 <sup>2</sup>	3.45 <sup>3</sup>	0 <sup>2</sup>	0.9 <sup>3</sup>	$\mu s$
Data setup time	$t_{SU:DAT}$	250	—	100 <sup>4</sup>	—	ns
Rise time for both SDA and SCL signals	$t_r$	—	1000	$20 + 0.1C_b^5$	300	ns
Fall time for both SDA and SCL signals	$t_f$	—	300	$20 + 0.1C_b^5$	300	ns
Bus free time between a Stop and Start condition	$t_{BUF}$	4.7	—	1.3	—	$\mu s$
Capacitive load for each bus line	$C_b$	—	400	—	400	pF

<sup>1</sup> All values referred to  $V_{IHmin}$  and  $V_{ILmax}$  levels

<sup>2</sup> A device must internally provide a hold time of at least 300 ns for the SDA signal (referred to the  $V_{IHmin}$  of the SCL signal) to bridge the undefined region of the falling edge of SCL.

<sup>3</sup> The maximum  $t_{HD:DAT}$  has to be met only if the device does not stretch the LOW period ( $t_{LOW}$ ) of the SCL signal.

<sup>4</sup> A Fast-mode I2C-bus device can be used in a Standard-mode I2C-bus system, but the requirement  $t_{SU;DAT} \geq 250$  ns must then be met. This will automatically be the case if the device does not stretch the LOW period of the SCL signal. If such a device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line  $t_{r\max} + t_{SU;DAT} = 1000 + 250 = 1250$  ns (according to the Standard-mode I2C-bus specification) before the SCL line is released.

<sup>5</sup>  $C_b$  = total capacitance of one bus line in pF. If mixed with Hs-mode devices, the faster fall-times are allowed.

## 11.13 Flash Specifications

This section provides details about program/erase times and program-erase endurance for the flash memory. Program and erase operations do not require any special power sources other than the normal  $V_{DD}$  supply. The flash is 131072 bytes organized as 128 pages by 1024 bytes.

### NOTE

Flash erase and program may be executed only with CPU clock programmed for 32 MHz (default). Flash operations are hardware state machine controlled. User code need not count cycles. The following information is supplied for calculating approximate time to program and erase.

**Table 22. Flash Characteristics**

Characteristic	Symbol	Min	Typical	Max	Unit
Supply voltage for program/erase/read operation	$V_{BATT}$	1.6		3.6	V
Byte program time (random location)	$t_{prog}$	40			$\mu s$
Per Byte program time (burst mode) - excludes start/end overhead	$t_{Burst}$	20			$\mu s$
Sector erase time	$t_{Sector}$	20			ms
Mass erase time	$t_{Mass}$	20.1			ms
Program/erase endurance $T_L$ to $T_H = -40^\circ C$ to $+85^\circ C$ $T = 25^\circ C$		20,000	100,000	—	cycles
Data retention @ $25^\circ C$	$t_{D\_ret}$	100		—	years

## 11.14 ADC Characteristics

ADC characteristics are applicable only to MC13237.

**Table 23. 12-bit ADC Operating Conditions**

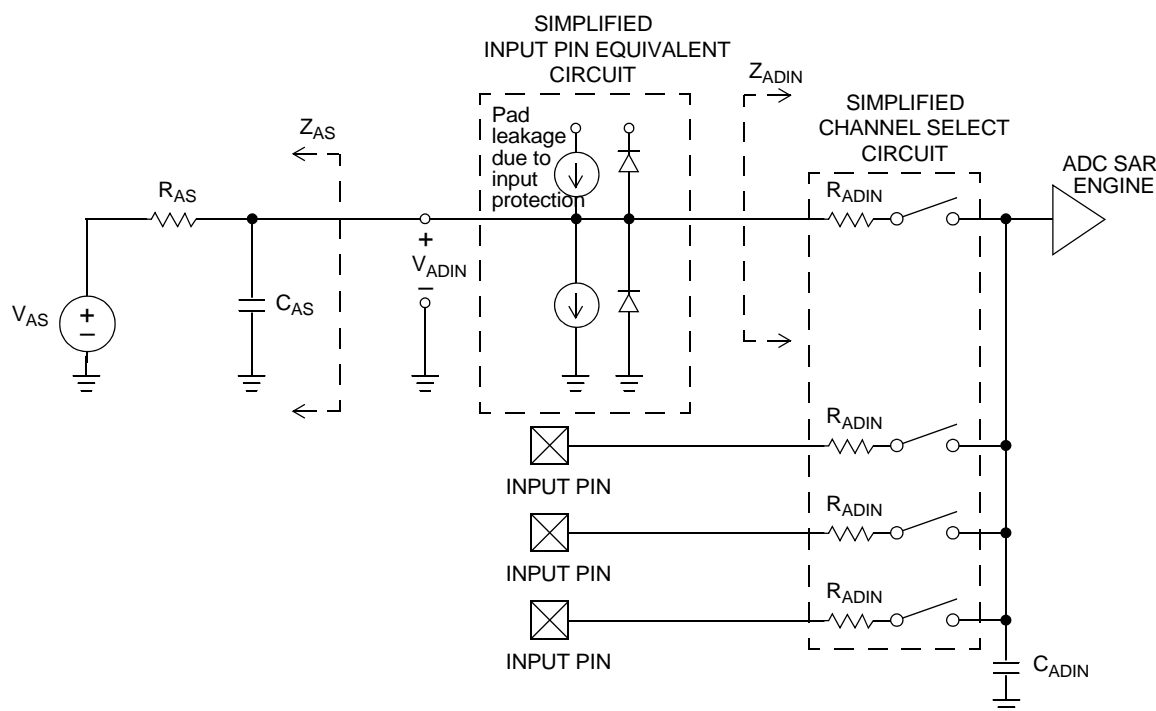
Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
Supply voltage	Absolute	$V_{DDA}$	1.8	—	3.6	V	
	Delta to $V_{DD}$ ( $V_{DD} - V_{DDA}$ ) <sup>2</sup>	$\Delta V_{DDA}$	-100	0	+100	mV	
Ground voltage	Delta to $V_{SS}$ ( $V_{SS} - V_{SSA}$ ) <sup>2</sup>	$\Delta V_{SSA}$	-100	0	+100	mV	
Ref Voltage High		$V_{REFH}$	1.8	$V_{DDA}$	$V_{DDA}$	V	

**Table 23. 12-bit ADC Operating Conditions (continued)**

Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
Ref Voltage Low		$V_{REFL}$	$V_{SSA}$	$V_{SSA}$	$V_{SSA}$	V	
Input Voltage		$V_{ADIN}$	$V_{REFL}$	—	$V_{REFH}$	V	
Input Capacitance		$C_{ADIN}$	—	4.5	5.5	pF	
Input Resistance		$R_{ADIN}$	—	5	7	k $\Omega$	
Analog Source Resistance	12 bit mode $f_{ADCK} > 4\text{MHz}$ $f_{ADCK} < 4\text{MHz}$	$R_{AS}$	— —	— —	2 5	k $\Omega$	External to MCU
	10 bit mode $f_{ADCK} > 4\text{MHz}$ $f_{ADCK} < 4\text{MHz}$		— —	— —	5 10		
	8 bit mode (all valid $f_{ADCK}$ )		—	—	10		
ADC Conversion Clock Freq.	High Speed (ADLPC=0)	$f_{ADCK}$	0.4	—	8.0	MHz	
	Low Power (ADLPC=1)		0.4	—	4.0		

<sup>1</sup> Typical values assume  $V_{DDA} = 3.0\text{V}$ , Temp = 25°C,  $f_{ADCK}=1.0\text{MHz}$  unless otherwise stated. Typical values are for reference only and are not tested in production.

<sup>2</sup> DC potential difference.



**Figure 10. ADC Input Impedance Equivalency Diagram**



**Table 24. 12-bit ADC Characteristics ( $V_{REFH} = V_{DDA_{SSA}}$ ,  $V_{REFL} = V_{SSA}$ )**

Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
Supply Current ADLPC=1 ADLSMP=1 ADCO=1		I <sub>DDA</sub>	—	120	—	μA	
Supply Current ADLPC=1 ADLSMP=0 ADCO=1		I <sub>DDA</sub>	—	202	—	μA	
Supply Current ADLPC=0 ADLSMP=1 ADCO=1		I <sub>DDA</sub>	—	288	—	μA	
Supply Current ADLPC=0 ADLSMP=0 ADCO=1		I <sub>DDA</sub>	—	0.532	1	mA	
Supply Current	Stop, Reset, Module Off	I <sub>DDA</sub>	—	0.007	0.8	μA	
ADC Asynchronous Clock Source	High Speed (ADLPC=0)	f <sub>ADACK</sub>	2	3.3	5	MHz	t <sub>ADACK</sub> = 1/f <sub>ADACK</sub>
	Low Power (ADLPC=1)		1.25	2	3.3		
Conversion Time (Including sample time)	Short Sample (ADLSMP=0)	t <sub>ADC</sub>	—	20	—	ADCK cycles	
	Long Sample (ADLSMP=1)		—	40	—		
Sample Time	Short Sample (ADLSMP=0)	t <sub>ADS</sub>	—	3.5	—	ADCK cycles	
	Long Sample (ADLSMP=1)		—	23.5	—		
Total Unadjusted Error	12-bit mode, 3.6> V <sub>DDA</sub> > 2.7	E <sub>TUE</sub>	—	±2.0	±4.5	LSB <sup>2</sup>	
	12-bit mode, 2.7> V <sub>DDA</sub> > 1.8V		—	±2.0	±4.5		
	10 bit mode		—	±1	±2.5		
	8 bit mode		—	±0.5	±1.0		
Differential Non-Linearity	12 bit mode	DNL	—	±0.7	−1.5 to +1.9	LSB <sup>2</sup>	
	10 bit mode <sup>3</sup>		—	±0.5	±1.0		
	8 bit mode <sup>3</sup>		—	±0.3	±0.5		
Integral Non-Linearity	12 bit mode	INL	—	±1.4	±2.5	LSB <sup>2</sup>	
	10 bit mode		—	±0.5	±1.0		
	8 bit mode		—	±0.3	±0.5		
Zero-Scale Error	12 bit mode	E <sub>ZS</sub>	—	±0.5	±0.5	LSB <sup>2</sup>	V <sub>ADIN</sub> = V <sub>SSA</sub>
	10 bit mode		—	±0.5	±1.5		
	8 bit mode		—	±0.5	±0.5		

**Table 24. 12-bit ADC Characteristics ( $V_{REFH} = V_{DDA\text{SSA}}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
Full-Scale Error	12 bit mode	$E_{FS}$	—	$\pm 1.0$	$-3.5$ to $1.0$	LSB <sup>2</sup>	$V_{ADIN} = V_{DDA}$
	10 bit mode		—	$\pm 0.5$	$\pm 1$		
	8 bit mode		—	$\pm 0.5$	$\pm 0.5$		
Quantization Error	12 bit mode	$E_Q$	—	$-1$ to $0$	—	LSB <sup>2</sup>	
	10 bit mode		—	—	$\pm 0.5$		
	8 bit mode		—	—	$\pm 0.5$		
Input Leakage Error	12 bit mode	$E_{IL}$	—	$\pm 2$	—	LSB <sup>2</sup>	Pad leakage <sup>4</sup> * $R_{AS}$
	10 bit mode		—	$\pm 0.2$	$\pm 4$		
	8 bit mode		—	$\pm 0.1$	$\pm 1.2$		
Temp Sensor Slope	$-40^{\circ}\text{C}$ to $25^{\circ}\text{C}$	m	—	1.646	—	mV/ $^{\circ}\text{C}$	
	$25^{\circ}\text{C}$ to $85^{\circ}\text{C}$		—	1.769	—		
Temp Sensor Voltage	$25^{\circ}\text{C}$	$V_{TEMP25}$	—	701.2	—	mV	
Effective Number Of Bits <sup>5</sup>		ENOB	10.66	11.2	—	Bits	
Spurious Free Dynamic Range	12 bit mode		71	81	—	dB	

<sup>1</sup> Typical values assume  $V_{DDA} = 3.0\text{V}$ , Temp =  $25^{\circ}\text{C}$ ,  $f_{ADCK} = 1.0\text{ MHz}$  unless otherwise stated. Typical values are for reference only and are not tested in production.

<sup>2</sup>  $1\text{ LSB} = (V_{REFH} - V_{REFL})/2^N$

<sup>3</sup> Monotonicity and No-Missing-Codes guaranteed in 10 bit and 8 bit modes

<sup>4</sup> Based on input pad leakage current. Refer to pad electricals.

<sup>5</sup> Dynamic performance of the ADC @  $V_{DDA} = 3.0\text{ V}$ , Temp =  $25^{\circ}\text{C}$ ,  $f_{ADCK} = 1.0\text{ MHz}$  and typical sampling rate values with 1 kHz sinewave applied @ the selected channel.

$\text{ENOB} = (\text{SINAD} - 1.76) / 6.02$  where SINAD is Signal-to-Noise plus distortion.  $\text{SINAD}(\text{dB}) = 20 \times \log [\text{Signal}_{\text{RMS}} / (\text{Noise} + \text{Distortion})_{\text{RMS}}]$

## 12 Applications Information

### NOTE

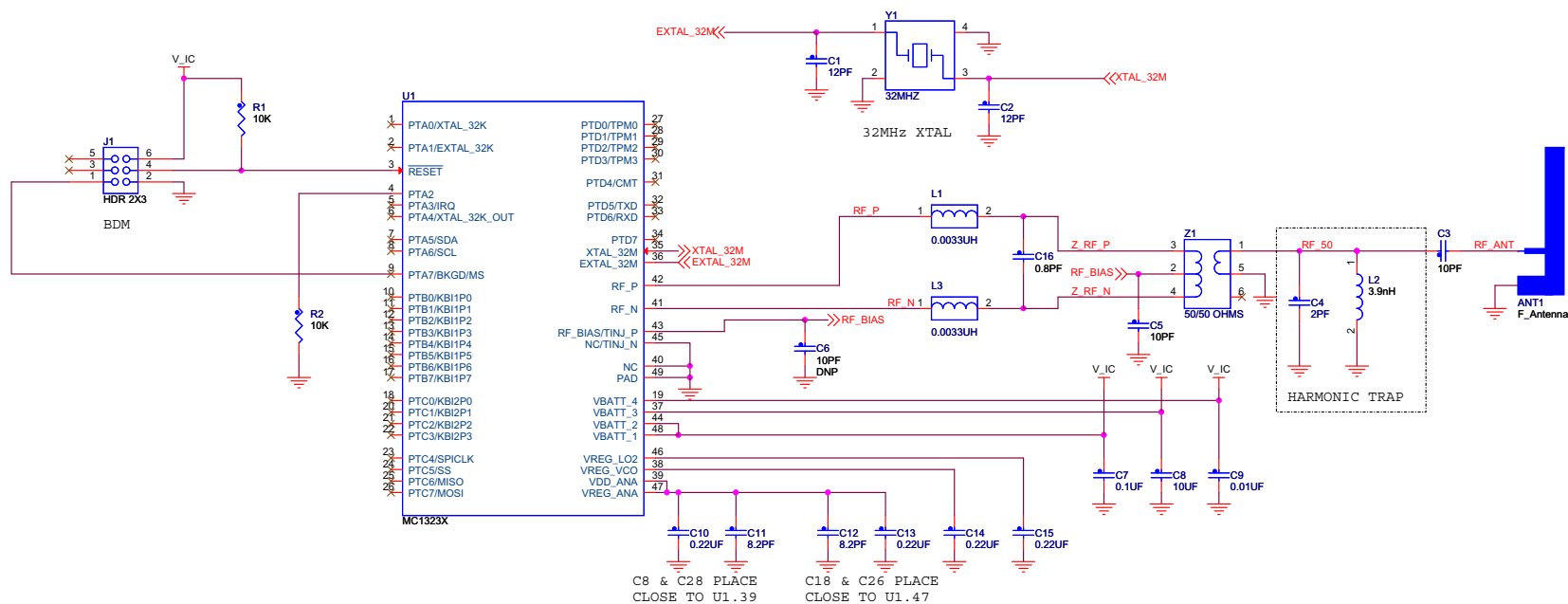
Freescall provides a complete suite of design support material including development hardware and software, reference manuals, and hardware references designs for the MC13234/MC13237. The applications material presented here is primarily for illustrative purposes.

Figure 11 and Figure 12 illustrate a basic applications circuit based on the MC13234 and MC13237 MRB development boards. Features of the circuit include:

- 32 MHz reference oscillator crystal (Y1) is required, and must meet defined specifications
- Pulldown resistor on signal PTA2 assures that device does not enter factory test mode on power-up
- Power supply voltage (V<sub>IC</sub>) can range from 1.8 Vdc to 3.6 Vdc (see [Table 9](#) for usage notes)
- RF Interface circuitry -
  - 50/50 (unbal/bal) balun converts device differential, bidirectional RF port to single-ended 50-ohm antenna port
  - Control signal RF\_Bias switches RF reference voltage to the balun as required for TX or RX
  - L1 provides impedance matching for MC1323x RF port
  - C4 and L2 network provides a harmonic trap for out-of-band harmonics and spurs on TX
  - A low-cost, copper pcb “F” antenna is shown. This is a common option, although other antennas such as a chip antenna or antenna module may also be used

#### NOTE

- RF circuitry at 2.4 GHz is very dependent on board layout and component usage. [Figure 11](#) shows a typical RF configuration, however component value and use can vary based on customer application.
- Mechanical design information for the MC1323x package and assembly recommendations can be found in the *Freescale IEEE 802.15.4 / ZigBee Package and Hardware Layout Considerations Reference Manual*, Doc No. ZHDCRM.pdf



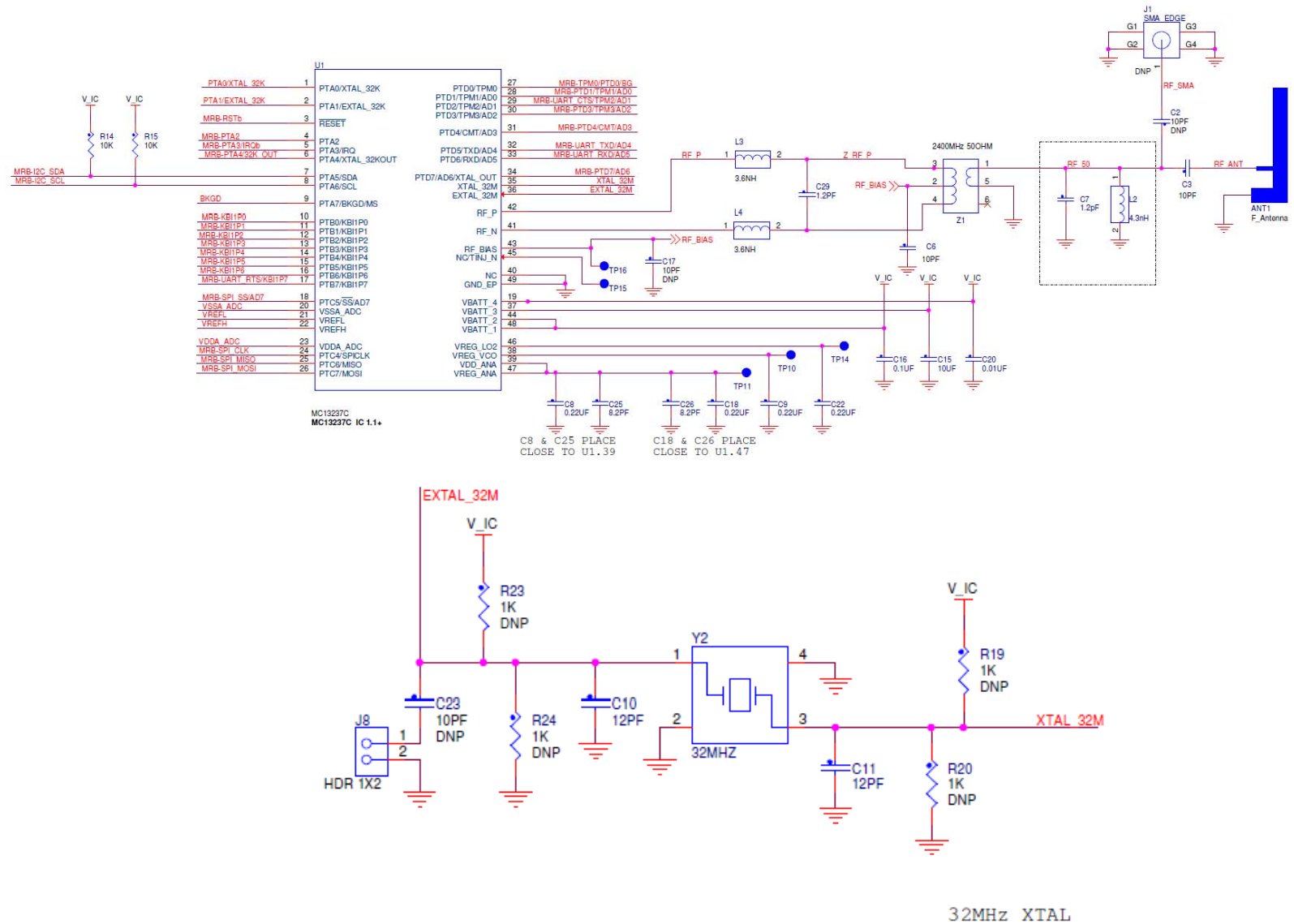


Figure 12. MC13237 Basic Applications Circuit (Note: Refer to the reference manual for the latest MRB schematic)

# 13 Mechanical Diagrams (Case 2124-02, Non-JEDEC)

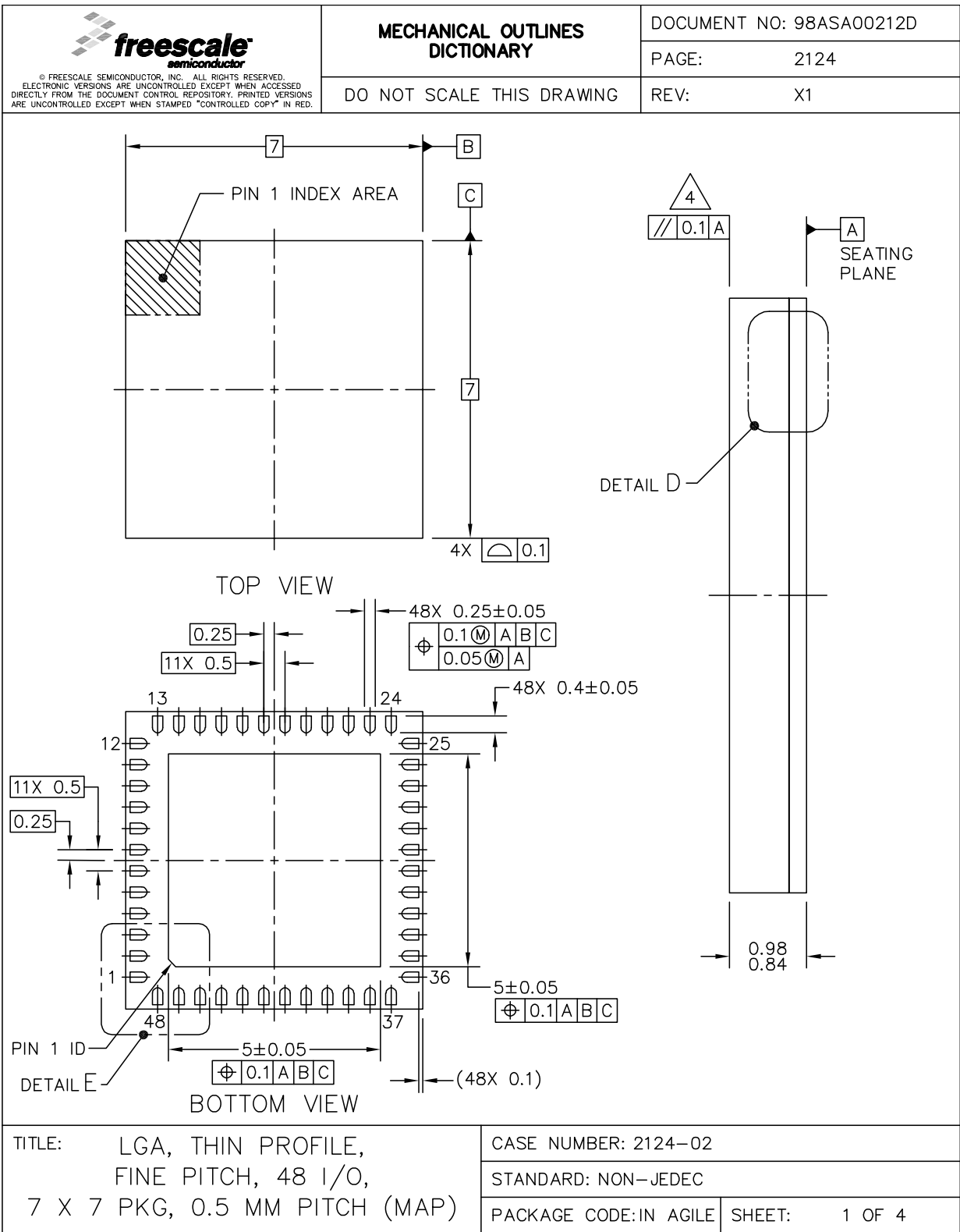
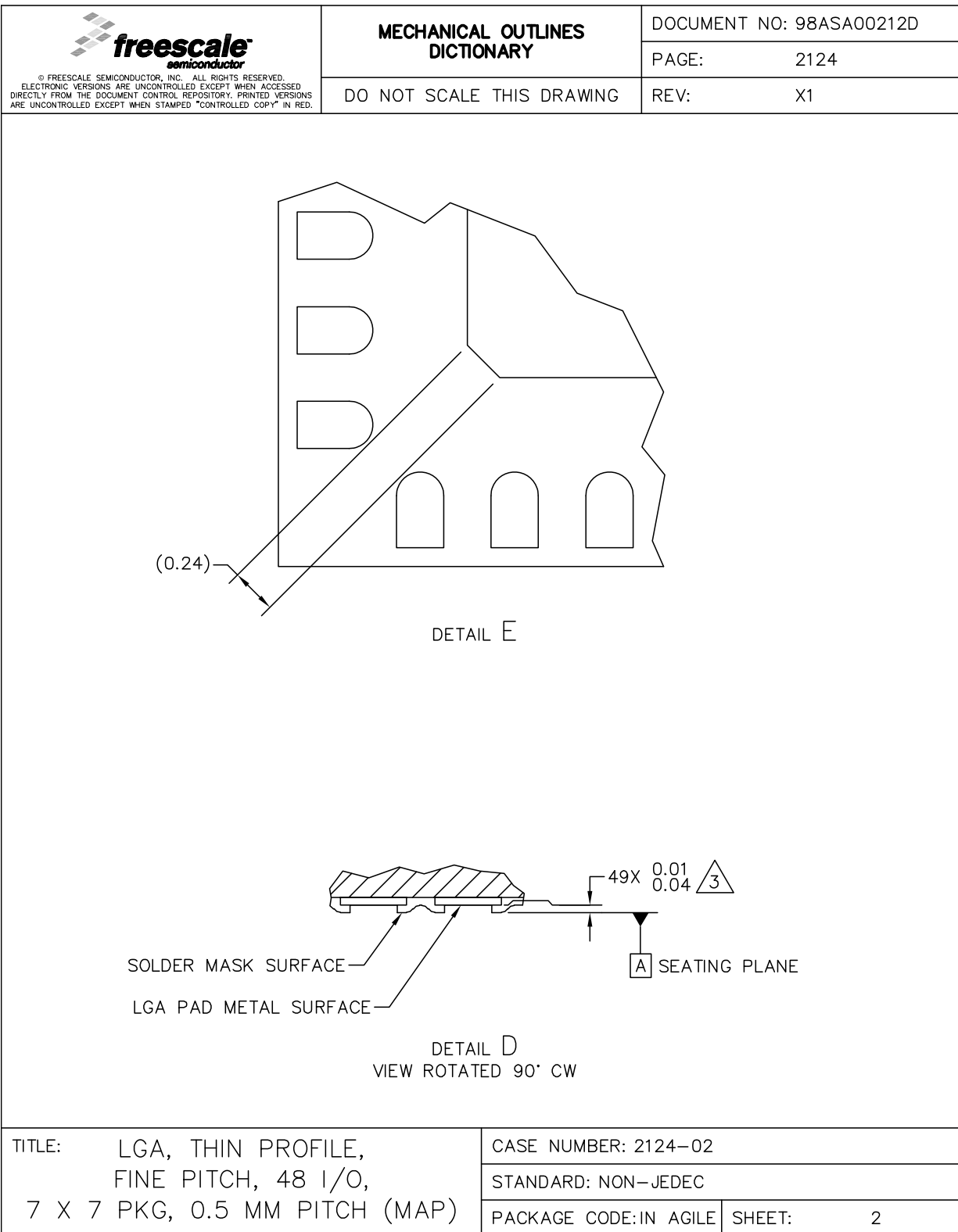


Figure 13. Mechanical Diagram (1 of 2)



**Figure 14. Mechanical Diagram (2 of 2)**

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