# SiT9001
## High Performance Spread Spectrum Oscillator

The Smart Timing Choice™

## Features

- Frequency range from 1 MHz to 200 MHz
- Center Spread Modulation: ±0.25%, ±0.5%, ±1%
- Down Spread Modulation: -0.5%, -1%, -2%; spread disable option available
- Power down or output enable option available
- Frequency stability: ±25 ppm, ±50 ppm and ±100 ppm (Spread = OFF)
- Operating voltage: 1.8V or 2.5 or 3.3 V; other voltages up to 3.63 V (contact SiTime)
- Operating temperature range: Industrial, -40°C to +85°C, Extended Commercial, -20°C to +70°C
- Industry-standard packages: 2.5 x 2.0, 3.2 x 2.5, 5.0 x 3.2, 7.0 x 5.0 mm x mm
- Pb-free, RoHS and REACH compliant
- High drive option: 30pF load (contact factory)
- 30 ps Ultra-low cycle-to-cycle jitter

## Applications

- Set-top boxes and LCD displays
- Scanners, printers and copiers
- Interface controllers and graphics cards
- PCI, CPU and memory buses
- Routers and modems

## DC Electrical Characteristics

| Parameters | Symbol | Min. | Typ. | Max. | Unit | Condition |
|---|---|---|---|---|---|---|
| **Vdd = 3.3V ±10%, -40°C to 85°C** | | | | | | |
| **Output Voltage High** | VOH | 90 | – | – | %Vdd | IOH = -9 mA |
| **Output Voltage Low** | VOL | – | – | 10 | %Vdd | IOL = 9 mA |
| **Input Voltage High** | VIH | 70 | – | – | %Vdd | Pin 1 |
| **Input Voltage Low** | VIL | – | – | 30 | %Vdd | Pin 1 |
| **Operating Current** | Idd | – | – | 27 | mA | Output frequency = 30 MHz, 15 pF load |
| | | – | – | 34 | mA | Output frequency = 125 MHz, 15 pF load |
| **Standby Current** | I_std | – | 30 | 50 | µA | Output is weakly pulled down, $\overline{ST}$ = GND |
| **Power Up Time** | | – | – | 10 | ms | Time from minimum power supply voltage to the first cycle (Guaranteed no runt pulses) |
| **Vdd = 2.5V ±10%, -40°C to 85°C** | | | | | | |
| **Output Voltage High** | VOH | 90 | – | – | %Vdd | IOH = -7 mA |
| **Output Voltage Low** | VOL | – | – | 10 | %Vdd | IOL = 7 mA |
| **Input Voltage High** | VIH | 70 | – | – | %Vdd | Pin 1 |
| **Input Voltage Low** | VIL | – | – | 30 | %Vdd | Pin 1 |
| **Operating Current** | Idd | – | – | 26 | mA | Output frequency = 30 MHz, 15 pF load |
| | | – | – | 31 | mA | Output frequency = 125 MHz, 15 pF load |
| **Standby Current** | I_std | – | 30 | 50 | µA | Output is weakly pulled down, $\overline{ST}$ = GND |
| **Power Up Time** | | – | – | 10 | ms | Time from minimum power supply voltage to the first cycle (Guaranteed no runt pulses) |
| **Vdd = 1.8V ±5%, -40°C to 85°C** | | | | | | |
| **Output Voltage High** | VOH | 90 | – | – | %Vdd | IOH = -5 mA |
| **Output Voltage Low** | VOL | – | – | 10 | %Vdd | IOL = 5mA |
| **Input Voltage High** | VIH | 70 | – | – | %Vdd | Pin 1 |
| **Input Voltage Low** | VIL | – | – | 30 | %Vdd | Pin 1 |
| **Operating Current** | Idd | – | – | 26 | mA | Output frequency = 30 MHz, 15 pF load |
| | | – | – | 31 | mA | Output frequency = 125 MHz, 15 pF load |
| **Standby Current** | I_std | – | 30 | 50 | µA | Output is weakly pulled down, $\overline{ST}$ = GND |
| **Power Up Time** | | – | – | 10 | ms | Time from minimum power supply voltage to the first cycle (Guaranteed no runt pulses) |

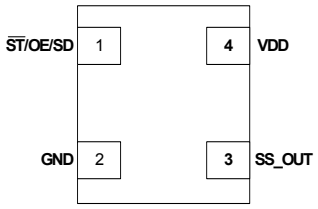
## AC Electrical Characteristics

| Parameters | Symbol | Min. | Typ. | Max. | Unit | Condition |
|---|---|---|---|---|---|---|
| **Vdd = 3.3V ±10%, -40°C to 85°C** | | | | | | |
| **Clock Output Frequency** | Fout | 1 | – | 200 | MHz | |
| **Clock Output Duty Cycle** | DC | 45 | 50 | 55 | % | Output frequency = 1 MHz to 75 MHz |
| | | 40 | – | 60 | % | Output frequency = 75 MHz to 200 MHz |
| **Clock Output Rise Time** | tr | – | 1.0 | 1.5 | ns | 15 pF Load, 20% to 80% Vdd |
| **Clock Output Fall Time** | tf | – | 1.0 | 1.5 | ns | 15 pF Load, 80% to 20% Vdd |
| **Cycle-to-cycle Jitter** | Tccj | – | 22 | 29 | ps | Spread = OFF, Output frequency = 133.33 MHz |
| | | – | 22 | 29 | ps | Spread = ON, Output frequency = 133.33 MHz<br>2% down spread |
| **Vdd = 2.5V ±10%, -40°C to 85°C** | | | | | | |
| **Clock Output Frequency** | Fout | 1 | – | 200 | MHz | |
| **Clock Output Duty Cycle** | DC | 45 | 50 | 55 | % | Output frequency = 1 MHz to 125 MHz |
| | | 40 | – | 60 | % | Output frequency = 125 MHz to 200 MHz |
| **Clock Output Rise Time** | tr | – | 1.0 | 1.5 | ns | 15 pF Load, 20% to 80% Vdd |
| **Clock Output Fall Time** | tf | – | 1.0 | 1.5 | ns | 15 pF Load, 80% to 20% Vdd |
| **Cycle-to-cycle Jitter** | Tccj | – | 26 | 37 | ps | Spread = OFF, Output frequency = 133.33 MHz |
| | | – | 26 | 37 | ps | Spread = ON, Output frequency = 133.33 MHz<br>2% down spread |
| **Vdd = 1.8V ±5%, -40°C to 85°C** | | | | | | |
| **Clock Output Frequency** | Fout | 1 | – | 200 | MHz | |
| **Clock Output Duty Cycle** | DC | 45 | 50 | 55 | % | Output frequency = 1 MHz to 75 MHz |
| | | 40 | – | 60 | % | Output frequency = 75 MHz to 200 MHz |
| **Clock Output Rise Time** | tr | – | 1.0 | 1.5 | ns | 15 pF Load, 20% to 80% Vdd |
| **Clock Output Fall Time** | tf | – | 1.0 | 1.5 | ns | 15 pF Load, 80% to 20% Vdd |
| **Cycle-to-cycle Jitter** | Tccj | – | 45 | 57 | ps | Spread = OFF, Output frequency = 133.33 MHz |
| | | – | 45 | 57 | ps | Spread = ON, Output frequency = 133.33 MHz<br>2% down spread |

## Pin Configuration

| Pin | Symbol | | Functionality |
|---|---|---|---|
| 1 | $\overline{ST}$/OE/SD | Standby | H or Open[1]: specified frequency output<br>L: output is low (weak pull down). Oscillator stops |
| | | Output Enable | H or Open[1]: specified frequency output<br>L: output is high impedance.<br>Standby/ Output Enable/ Spread Disable. |
| | | SD (Down Spread) only | H or Open: Spread = ON<br>L: Spread =OFF |
| 2 | GND | Power | Connect to Ground |
| 3 | SS_OUT | Output | 1 to 200 MHz Spread Spectrum Clock Output |
| 4 | VDD | | Connect to 1.8V or 2.5V or 3.3V |

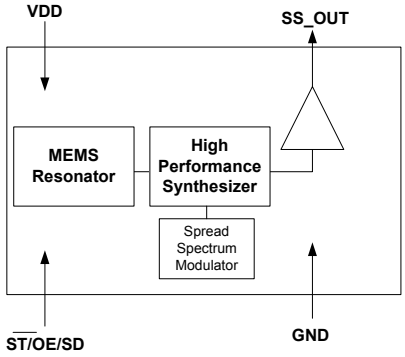
**Top View**




**Note:**

1. A pull-up resistor of <10 kΩ between $\overline{ST}$/OE/SD pin and Vdd is recommended in high noise environment.

## Block Diagram



## Absolute Maximum

Attempted operation outside the absolute maximum ratings of the part may cause permanent damage to the part. Actual performance of the IC is only guaranteed within the operational specifications, not at absolute maximum ratings.

| Parameters | Min. | Max. | Unit |
|---|---|---|---|
| **Storage Temperature** | -65 | 150 | °C |
| **VDD** | -0.5 | +3.66 | V |
| **Electrostatic Discharge** | – | 2000 | V |
| **Theta JA (with copper plane on VDD and GND)** | – | 75 | °C/W |
| **Theta JC (with PCB traces of 0.010 inch to all pins)** | – | 24 | °C/W |
| **Soldering Temperature (follow standard Pb free soldering guidelines)** | – | 260 | °C |
| **Number of Program Writes** | – | 1 | NA |
| **Program Retention over -40 to 125C, Process, VDD (0 to 3.65V)** | – | 1,000+ | years |

## Operating Conditions

| Parameters | Min. | Typ. | Max. | Unit |
|---|---|---|---|---|
| **Supply Voltages, VDD[2]** | 2.97 | 3.3 | 3.63 | V |
| | 2.25 | 2.5 | 2.75 | V |
| | 1.7 | 1.8 | 1.9 | V |
| **Frequency Stability, Spread = OFF (down spread only) (Inclusive of Initial stability, operating temperature, rated power supply voltage change, load change, aging (1 ppm first year @ 25°C), shock and vibration)** | -50 | – | +50 | ppm |
| | -100 | – | +100 | ppm |
| **Extended Commercial Operating Temperature** | -20 | – | 70 | °C |
| **Industrial Operating Temperature** | -40 | – | 85 | °C |
| **Maximum Load Capacitance[3]** | – | – | 15 | pF |

**Notes:**

2. The 3.3V device can operate from 2.25V to 3.63V with higher output drive strength, however, the data sheet specifications cannot be guaranteed. Please contact factory for this option.
3. The output driver strength can be programmed to drive up to 30 pF load. Please contact factory for this option.

## Thermal Considerations

| Package | θJA, 4 Layer Board (°C/W) | θJA, 2 Layer Board (°C/W) | θJC, Bottom (°C/W) |
|---|---|---|---|
| **7050** | 191 | 263 | 30 |
| **5032** | 97 | 199 | 24 |
| **3225** | 109 | 212 | 27 |
| **2520** | 117 | 222 | 26 |

## Environmental Compliance

| Parameter | Condition/Test Method |
|---|---|
| **Mechanical Shock** | MIL-STD-883F, Method 2002 |
| **Mechanical Vibration** | MIL-STD-883F, Method 2007 |
| **Temperature Cycle** | JESD22, Method A104 |
| **Solderability** | MIL-STD-883F, Method 2003 |
| **Moisture Sensibility Level** | MSL1 @ 260°C |

## Description

The SiT9001 is a spread-spectrum capable, programmable MEMS oscillator. The SiT9001 offers unparalleled flexibility in terms of frequency range, frequency accuracy stability, supply voltage, and operating temperature range while simultaneously offering outstanding performance in terms of low jitter and a higher frequency range. This flexibility and high performance is made available in packages down to 2.5 x 2.0 mm, making the SiT9001 the smallest programmable spread-spectrum oscillator available.

The SiT9001 is factory programmable and offers two types of spread modulation: down spread modulation, and center spread modulation. In down spread modulation mode, a spread disable pin is available (Pin 1).

Power down (either output enable or standby) mode options are available for both down spread and center spread versions of the SiT9001.

The SiT9001, by eliminating the quartz crystal, has improved immunity, shock, strain and humidity.

To order samples, go to www.sitime.com and click on Request Sample" link.

## Spread Spectrum Modes[4]

| | | | | |
|---|---|---|---|---|
| **Center Spread** | **Code** | **1** | **2** | **3** |
| | Down Spread | Down Spread | Down Spread | Down Spread |
| **Down Spread** | **Code** | **4** | **5** | **6** |
| | Down Spread | Down Spread | Down Spread | Down Spread |

**Note:**

4. In both modes, triangle modulation is employed with a frequency of ~32 kHz.

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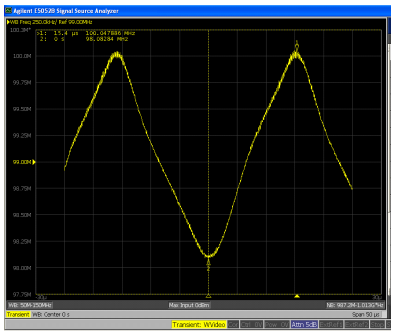
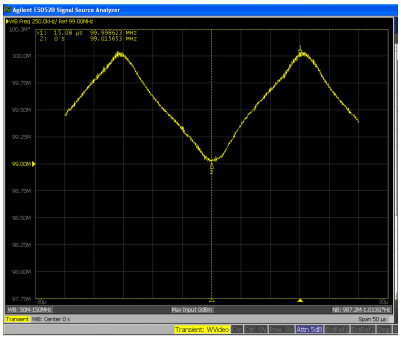
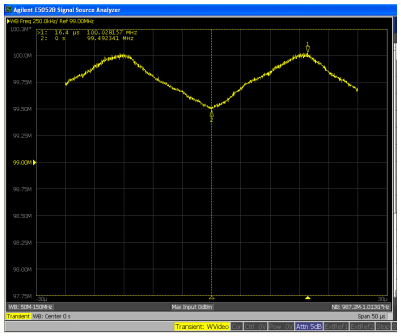
**Down Spread: -2%**



**Down Spread: -1%**



**Down Spread: -0.5%**



The SiT9001 can be factory programmed to provide down spread modulation or center spread modulation. In the down spread modulation mode, pin 1 can be factory programmed as a spread disable pin. In both the down spread and center spread modulation modes, pin can be factory programmed to be either output enable or standby.

## Programmable Drive Strength

The SiT9001 includes a programmable drive strength feature to provide a simple, flexible tool to optimize the clock rise/fall time for specific applications. Benefits from the programmable drive strength feature are:

- Improves system radiated electromagnetic interference (EMI) by slowing down the clock rise/fall time
- Improves the downstream clock receiver's (RX) jitter by decreasing (speeding up) the clock rise/fall time.
- Ability to drive large capacitive loads while maintaining full swing with sharp edge rates.

For more detailed information about rise/fall time control and drive strength selection, see the SiTime Applications Note section; http://www.sitime.com/support/application-notes.

### EMI Reduction by Slowing Rise/Fall Time

Figure 1 shows the harmonic power reduction as the rise/fall times are increased (slowed down). The rise/fall times are expressed as a ratio of the clock period. For the ratio of 0.05, the signal is very close to a square wave. For the ratio of 0.45, the rise/fall times are very close to near-triangular waveform. These results, for example, show that the 11th clock harmonic can be reduced by 35 dB if the rise/fall edge is increased from 5% of the period to 45% of the period.

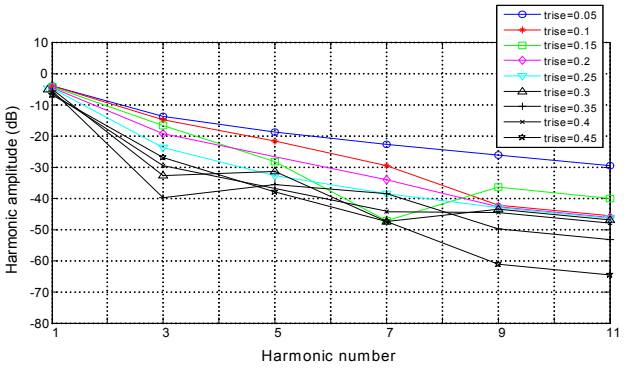



**Figure 1. Harmonic EMI reduction as a Function of Slower Rise/Fall Time**

### Jitter Reduction with Faster Rise/Fall Time

Power supply noise can be a source of jitter for the downstream chipset. One way to reduce this jitter is to increase rise/fall time (edge rate) of the input clock. Some chipsets would require faster rise/fall time in order to reduce their sensitivity to this type of jitter. The SiT9001 provides up to 3 additional high drive strength settings for very fast rise/fall time. Refer to the Drive Strength Settings Table to determine the proper drive strength.

### High Output Load Capability

The rise/fall time of the input clock varies as a function of the actual capacitive load the clock drives. At any given drive strength, the rise/fall time becomes slower as the output load increases. As an example, for a 3.3V SiT9001 device with default drive strength setting, the typical rise/fall time is 1ns for 15 pF output load. The typical rise/fall time slows down to 2.6ns when the output load increases to 45 pF. One can choose to speed up the rise/fall time to 1.68ns by then increasing the drive strength setting on the SiT9001.

The SiT9001 can support up to 60 pF or higher in maximum capacitive loads with up to 3 additional drive strength settings. Refer to the Drive Strength Settings Table to determine the proper drive strength for the desired combination of output load vs. rise/fall time

### SiT9001 Drive Strength Selection

The Drive Strength Settings Table define the rise/fall time for a given capacitive load and supply voltage.

1. Select the table that matches the SiT9001 nominal supply voltage (1.8V, 2.5V, 2.8V, 3.0V, 3.3V).
2. Select the capacitive load column that matches the application requirement (5 pF to 60 pF)
3. Under the capacitive load column, select the desired rise/fall times.
4. The left-most column represents the part number code for the corresponding drive strength.
5. Add the drive strength code to the part number for ordering purposes.

### Calculating Maximum Frequency

Based on the rise and fall time data given in Tables 1 through 4, the maximum frequency the oscillator can operate with guaranteed full swing of the output voltage over temperature as follows:

$$\text{Max Frequency} = \frac{1}{5 \times \text{Trf_20/80}}$$

Where Trf_20/80 is the typical rise/fall time at 20% to 80% Vdd

***Example 1***

Calculate $f_{MAX}$ for the following condition:

- Vdd = 1.8V
- Capacitive Load: 30 pF
- Desired Tr/f time = 3 ns (rise/fall time part number code = E)

Part number for the above example:

SiT9001AI**E**14-33E6-123.12345

Drive strength code is inserted here. Default setting is "-"

## Drive Strength Settings

| Drive Strength | Designator | SiT9001 | | |
|---|---|---|---|---|
| | | 1.8V | 2.5V | 3.3V |
| 1X | L | – | – | – |
| 3X | R | – | – | – |
| 5X | S | – | – | X |
| 7X | T | – | X | – |
| 9X | U | X | – | – |
| 11X | W | – | – | – |
| 13X | X | – | – | – |
| 15X | Y | – | – | – |
| 17X | Z | x | x | x |
| 21X | H | x | x | x |

**Legend:**
X = Default Drive Strength
– = Valid Drive Strength Setting
x = Invalid Drive Strength Setting

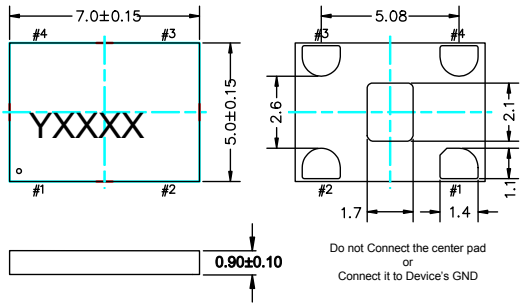
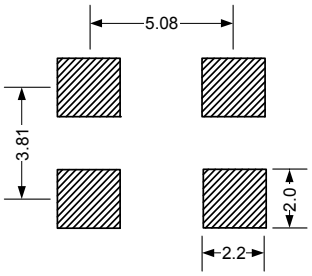
## Dimensions and Patterns

| Package Size – Dimensions (Unit: mm)[5] | Recommended Land Pattern (Unit: mm)[6] |
|---|---|
| **2.5 x 2.0 x 0.75 mm** | |
| **3.2 x 2.5 x 0.75 mm** | |
| **5.0 x 3.2 x 0.75 mm** | |
| **7.0 x 5.0 x 0.90 mm (without center-pad)** | |

**Notes:**

5. Top marking: Y denotes manufacturing origin and XXXX denotes manufacturing lot number. The value of "Y" will depend on the assembly location of the device.
6. A capacitor of value 0.1 µF between Vdd and GND is required.

## Dimensions and Patterns

| Package Size – Dimensions (Unit: mm)[5] | Recommended Land Pattern (Unit: mm)[6] |
|---|---|
| **7.0 x 5.0 x 0.90 mm (with Center-Pad)**  |  |



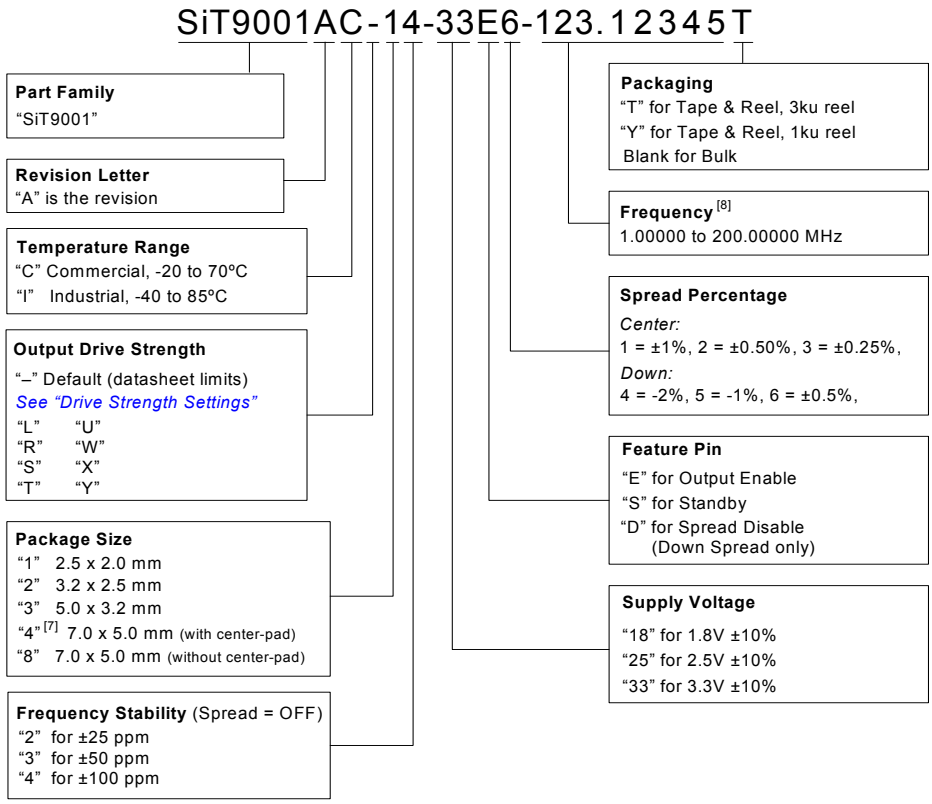


**Notes:**

5. Top marking: Y denotes manufacturing origin and XXXX denotes manufacturing lot number. The value of "Y" will depend on the assembly location of the device.
6. A capacitor of value 0.1 µF between Vdd and GND is required.

## Ordering Information

**The Part No. Guide is for reference only. To customize and build an exact part number, use the SiTime Part Number Generator.**




**Notes:**

7. Not recommended for new designs. Please use "8".
8. Please refer to 'Part Number Generator' of 9001 (9001 product page on SiTime.com) to check for details on supported frequencies. http://www.sitime.com/products/spread-spectrum/sit9001#magictabs_JdxGM_3

## Revision History

| Version | Release Date | Change Summary |
|---|---|---|
| 1.09 | 8/2013 | Initial Release |
| 1.10 | 4/1/14 | • Added a note to clarify frequency support in ordering information |
| 1.2 | 9/17/14 | • Included ±25 ppm support |

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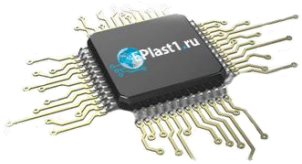


**Как с нами связаться**

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