

74AUP1T45

Low-power dual supply translating transceiver; 3-state

Rev. 5 — 9 August 2012

Product data sheet

1. General description

The 74AUP1T45 is a single bit transceiver featuring two data input-outputs (A and B), a direction control input (DIR) and dual supply pins ($V_{CC(A)}$ and $V_{CC(B)}$) which enable bidirectional level translation. Both $V_{CC(A)}$ and $V_{CC(B)}$ can be supplied at any voltage between 1.1 V and 3.6 V making the device suitable for interfacing between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V and 3.3 V). Pins A and DIR are referenced to $V_{CC(A)}$ and pin B is referenced to $V_{CC(B)}$. A HIGH on DIR allows transmission from A to B and a LOW on DIR allows transmission from B to A.

Schmitt trigger action on all inputs makes the circuit tolerant of slower input rise and fall times across the entire $V_{CC(A)}$ and $V_{CC(B)}$ ranges. The device ensures low static and dynamic power consumption and is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either $V_{CC(A)}$ or $V_{CC(B)}$ are at GND, both A and B are in the high-impedance OFF-state.

2. Features and benefits

- Wide supply voltage range:
 - ◆ $V_{CC(A)}$: 1.1 V to 3.6 V
 - ◆ $V_{CC(B)}$: 1.1 V to 3.6 V
- High noise immunity
- Complies with JEDEC standards:
 - ◆ JESD8-7 (1.2 V to 1.95 V)
 - ◆ JESD8-5 (1.8 V to 2.7 V)
 - ◆ JESD8-B (2.7 V to 3.6 V)
- ESD protection:
 - ◆ HBM JESD22-A114F Class 3A exceeds 5000 V
 - ◆ MM JESD22-A115-A exceeds 200 V
 - ◆ CDM JESD22-C101E exceeds 1000 V
- Low static power consumption; $I_{CC} = 0.9 \mu\text{A}$ (maximum)
- Suspend mode
- Latch-up performance exceeds 100 mA per JESD 78 Class II
- Inputs accept voltages up to 3.6 V
- Low noise overshoot and undershoot $< 10\%$ of V_{CC}
- I_{OFF} circuitry provides partial power-down mode operation
- Multiple package options
- Specified from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$ and $-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$

3. Ordering information

Table 1. Ordering information

Type number	Package			
	Temperature range	Name	Description	Version
74AUP1T45GW	−40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363
74AUP1T45GM	−40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 × 1.45 × 0.5 mm	SOT886
74AUP1T45GF	−40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 × 1 × 0.5 mm	SOT891
74AUP1T45GN	−40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body 0.9 × 1.0 × 0.35 mm	SOT1115
74AUP1T45GS	−40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body 1.0 × 1.0 × 0.35 mm	SOT1202

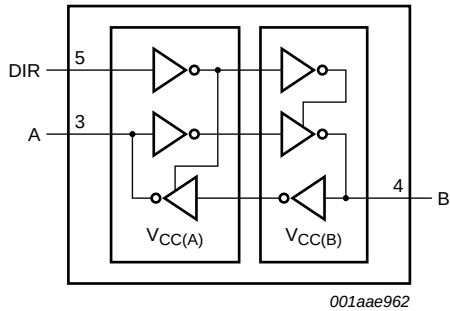
4. Marking

Table 2. Marking

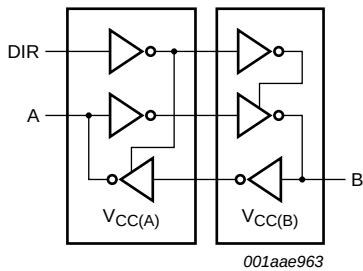
Type number	Marking code ^[1]
74AUP1T45GW	p5
74AUP1T45GM	p5
74AUP1T45GF	p5
74AUP1T45GN	p5
74AUP1T45GS	p5

[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

5. Functional diagram



Logic symbol for the 74AUP1T45 transceiver. It shows a rectangular box with two internal blocks, each containing two inverters. The left block is labeled V_{CC}(A) and the right block is labeled V_{CC}(B). The input DIR (pin 5) is connected to the top inputs of both inverter pairs. The input A (pin 3) is connected to the bottom inputs of both inverter pairs. The output B (pin 4) is connected to the outputs of both inverter pairs. The symbol is identified by the code 001aae962.



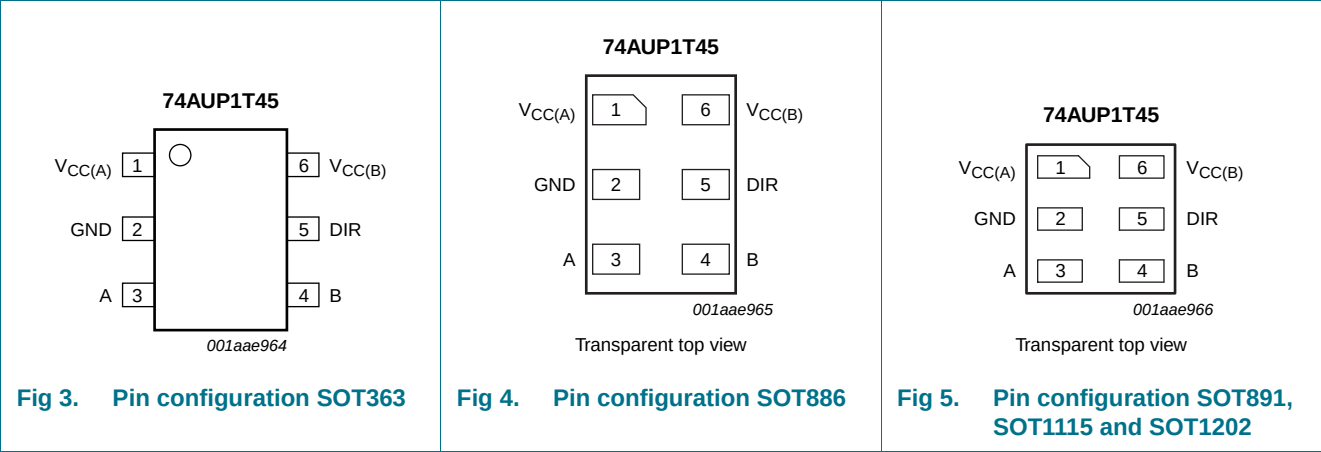
Logic diagram for the 74AUP1T45 transceiver. It shows two identical inverter blocks side-by-side. The left block is labeled V_{CC}(A) and the right block is labeled V_{CC}(B). The input DIR is connected to the top inputs of both inverter blocks. The input A is connected to the bottom inputs of both inverter blocks. The output B is connected to the outputs of both inverter blocks. The diagram is identified by the code 001aae963.

Fig 1. Logic symbol

Fig 2. Logic diagram

6. Pinning information

6.1 Pinning



6.2 Pin description

Table 3. Pin description

Symbol	Pin	Description
V _{CC(A)}	1	supply voltage A
GND	2	ground (0 V)
A	3	data input or output A
B	4	data input or output B
DIR	5	direction control DIR
V _{CC(B)}	6	supply voltage B

7. Functional description

Table 4. Function table^[1]

Supply voltage	Input ^[2]	Input/output ^[3]	
V _{CC(A)} , V _{CC(B)}	DIR	A	B
1.1 V to 3.6 V	L	A = B	input
1.1 V to 3.6 V	H	input	B = A
GND	X	suspend mode	suspend mode

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care.
[2] The DIR input circuit is referenced to V_{CC(A)}.
[3] The input circuit of the data I/Os are always active.

8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+4.6	V
$V_{CC(B)}$	supply voltage B		-0.5	+4.6	V
I_{IK}	input clamping current	$V_I < 0$ V	-50	-	mA
V_I	input voltage		[1] -0.5	+4.6	V
I_{OK}	output clamping current	$V_O < 0$ V	-50	-	mA
V_O	output voltage	Active mode			
		A port	[1][2] -0.5	$V_{CC(A)} + 0.5$	V
		B port	[1][2] -0.5	$V_{CC(B)} + 0.5$	V
		suspend or 3-state mode	[1][2] -0.5	+4.6	V
I_O	output current	$V_O = 0$ V to V_{CC}	-	± 20	mA
I_{CC}	supply current		-	50	mA
I_{GND}	ground current		-50	-	mA
T_{stg}	storage temperature		-65	+150	°C
P_{tot}	total power dissipation	$T_{amb} = -40$ °C to +125 °C	[3] -	250	mW

[1] The minimum input and output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] The values of $V_{CC(A)}$ and $V_{CC(B)}$ are provided in the recommended operating conditions; see [Table 6](#).

[3] For SC-88 packages: above 87.5 °C the value of P_{tot} derates linearly with 4.0 mW/K.

For XSON6 packages: above 118 °C the value of P_{tot} derates linearly with 7.8 mW/K.

9. Recommended operating conditions

Table 6. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		1.1	3.6	V
$V_{CC(B)}$	supply voltage B		1.1	3.6	V
V_I	input voltage		0	3.6	V
V_O	output voltage		[1] 0	V_{CCO}	V
T_{amb}	ambient temperature		-40	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{CCI} = 1.1$ V to 3.6 V	0	200	ns/V

[1] V_{CCO} is the supply voltage associated with the output port.

10. Static characteristics

Table 7. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
T_{amb} = 25 °C						
V _{IH}	HIGH-level input voltage	data input [1][3]				
		V _{CCI} = 1.1 V to 1.95 V	0.65 × V _{CCI}	-	-	V
		V _{CCI} = 2.3 V to 2.7 V	1.6	-	-	V
		V _{CCI} = 3.0 V to 3.6 V	2.0	-	-	V
		DIR input [1][4]				
		V _{CCI} = 1.1 V to 1.95 V	0.65 × V _{CC(A)}	-	-	V
		V _{CCI} = 2.3 V to 2.7 V	1.6	-	-	V
		V _{CCI} = 3.0 V to 3.6 V	2.0	-	-	V
V _{IL}	LOW-level input voltage	data input [1][3]				
		V _{CCI} = 1.1 V to 1.95 V	-	-	0.35 × V _{CCI}	V
		V _{CCI} = 2.3 V to 2.7 V	-	-	0.7	V
		V _{CCI} = 3.0 V to 3.6 V	-	-	0.9	V
		DIR input [1][4]				
		V _{CCI} = 1.1 V to 1.95 V	-	-	0.35 × V _{CC(A)}	V
		V _{CCI} = 2.3 V to 2.7 V	-	-	0.7	V
		V _{CCI} = 3.0 V to 3.6 V	-	-	0.9	V
V _{OH}	HIGH-level output voltage	V _I = V _{IH}				
		I _O = -20 µA; V _{CC(A)} = V _{CC(B)} = 1.1 V to 3.6 V [2]	V _{CCO} - 0.1	-	-	V
		I _O = -1.1 mA; V _{CC(A)} = V _{CC(B)} = 1.1 V [2]	0.75 × V _{CCO}	-	-	V
		I _O = -1.7 mA; V _{CC(A)} = V _{CC(B)} = 1.4 V	1.11	-	-	V
		I _O = -1.9 mA; V _{CC(A)} = V _{CC(B)} = 1.65 V	1.32	-	-	V
		I _O = -2.3 mA; V _{CC(A)} = V _{CC(B)} = 2.3 V	2.05	-	-	V
		I _O = -3.1 mA; V _{CC(A)} = V _{CC(B)} = 2.3 V	1.9	-	-	V
		I _O = -2.7 mA; V _{CC(A)} = V _{CC(B)} = 3.0 V	2.72	-	-	V
		I _O = -4.0 mA; V _{CC(A)} = V _{CC(B)} = 3.0 V	2.6	-	-	V
V _{OL}	LOW-level output voltage	V _I = V _{IL}				
		I _O = 20 µA; V _{CC(A)} = V _{CC(B)} = 1.1 V to 3.6 V	-	-	0.1	V
		I _O = 1.1 mA; V _{CC(A)} = V _{CC(B)} = 1.1 V [2]	-	-	0.3 × V _{CCO}	V
		I _O = 1.7 mA; V _{CC(A)} = V _{CC(B)} = 1.4 V	-	-	0.31	V
		I _O = 1.9 mA; V _{CC(A)} = V _{CC(B)} = 1.65 V	-	-	0.31	V
		I _O = 2.3 mA; V _{CC(A)} = V _{CC(B)} = 2.3 V	-	-	0.31	V
		I _O = 3.1 mA; V _{CC(A)} = V _{CC(B)} = 2.3 V	-	-	0.44	V
		I _O = 2.7 mA; V _{CC(A)} = V _{CC(B)} = 3.0 V	-	-	0.31	V
		I _O = 4.0 mA; V _{CC(A)} = V _{CC(B)} = 3.0 V	-	-	0.44	V
I _I	input leakage current	DIR input; V _I = GND to V _{CC(A)} ; V _{CC(A)} = V _{CC(B)} = 1.1 V to 3.6 V	-	-	±0.1	µA

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{OZ}	OFF-state output current	A or B port; $V_I = V_{IH}$ or V_{IL} ; $V_O = 0$ V to V_{CCO} ; $V_{CC(A)} = V_{CC(B)} = 1.1$ V to 3.6 V	[2] -	-	± 0.1	μ A
I_{OFF}	power-off leakage current	A port; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 1.1$ V to 3.6 V	-	-	± 0.2	μ A
		B port; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 1.1$ V to 3.6 V	-	-	± 0.2	μ A
		DIR input; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 1.1$ V to 3.6 V	-	-	± 0.2	μ A
ΔI_{OFF}	additional power-off leakage current	A port; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V to 0.2 V; $V_{CC(B)} = 1.1$ V to 3.6 V	-	-	± 0.2	μ A
		B port; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(B)} = 0$ V to 0.2 V; $V_{CC(A)} = 1.1$ V to 3.6 V	-	-	± 0.2	μ A
		DIR input; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V to 0.2 V; $V_{CC(B)} = 1.1$ V to 3.6 V	-	-	± 0.2	μ A
I_{CC}	supply current	A port; $V_I = \text{GND}$ or V_{CCI} ; $I_O = 0$ A	[1]			
		$V_{CC(A)} = V_{CC(B)} = 1.1$ V to 3.6 V	-	-	0.5	μ A
		$V_{CC(A)} = 3.6$ V; $V_{CC(B)} = 0$ V	-	-	0.5	μ A
		$V_{CC(A)} = 0$ V; $V_{CC(B)} = 3.6$ V	-	0	-	μ A
		B port; $V_I = \text{GND}$ or V_{CCI} ; $I_O = 0$ A	[1]			
		$V_{CC(A)} = V_{CC(B)} = 1.1$ V to 3.6 V	-	-	0.5	μ A
		$V_{CC(A)} = 3.6$ V; $V_{CC(B)} = 0$ V	-	0	-	μ A
		$V_{CC(A)} = 0$ V; $V_{CC(B)} = 3.6$ V	-	-	0.5	μ A
ΔI_{CC}	additional supply current	A plus B port ($I_{CC(A)} + I_{CC(B)}$); $I_O = 0$ A; $V_I = \text{GND}$ or V_{CCI} ; $V_{CC(A)} = V_{CC(B)} = 1.1$ V to 3.6 V	[1]	-	0.5	μ A
		A port; $V_{CC(A)} = V_{CC(B)} = 3.3$ V; A port at $V_{CC(A)} - 0.6$ V; DIR at $V_{CC(A)}$; B port = open	-	-	40	μ A
		B port; $V_{CC(A)} = V_{CC(B)} = 3.3$ V; B port at $V_{CC(B)} - 0.6$ V; DIR at GND; A port = open	-	-	40	μ A
		DIR input; $V_{CC(A)} = V_{CC(B)} = 3.3$ V; A port at $V_{CC(A)}$ or GND; B port = open; DIR at $V_{CC(A)} - 0.6$ V	-	-	40	μ A
C_I	input capacitance	DIR input; $V_I = \text{GND}$ or $V_{CC(A)}$; $V_{CC(A)} = V_{CC(B)} = 1.1$ V to 3.6 V	-	0.9	-	pF
$C_{I/O}$	input/output capacitance	A and B port; suspend mode; $V_{CCI} = 0$ V; $V_{CCO} = 1.1$ V to 3.6 V; $V_O = V_{CCO}$ or GND	[1][2] -	2.0	-	pF

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$T_{amb} = -40\text{ °C to }+85\text{ °C}$						
V_{IH}	HIGH-level input voltage	data input	[1][3]			
		$V_{CCI} = 1.1\text{ V to }1.95\text{ V}$	$0.65 \times V_{CCI}$	-	-	V
		$V_{CCI} = 2.3\text{ V to }2.7\text{ V}$	1.6	-	-	V
		$V_{CCI} = 3.0\text{ V to }3.6\text{ V}$	2.0	-	-	V
		DIR input	[1][4]			
		$V_{CCI} = 1.1\text{ V to }1.95\text{ V}$	$0.65 \times V_{CC(A)}$	-	-	V
		$V_{CCI} = 2.3\text{ V to }2.7\text{ V}$	1.6	-	-	V
		$V_{CCI} = 3.0\text{ V to }3.6\text{ V}$	2.0	-	-	V
V_{IL}	LOW-level input voltage	data input	[1][3]			
		$V_{CCI} = 1.1\text{ V to }1.95\text{ V}$	-	-	$0.35 \times V_{CCI}$	V
		$V_{CCI} = 2.3\text{ V to }2.7\text{ V}$	-	-	0.7	V
		$V_{CCI} = 3.0\text{ V to }3.6\text{ V}$	-	-	0.9	V
		DIR input	[1][4]			
		$V_{CCI} = 1.1\text{ V to }1.95\text{ V}$	-	-	$0.35 \times V_{CC(A)}$	V
		$V_{CCI} = 2.3\text{ V to }2.7\text{ V}$	-	-	0.7	V
		$V_{CCI} = 3.0\text{ V to }3.6\text{ V}$	-	-	0.9	V
V_{OH}	HIGH-level output voltage	$V_I = V_{IH}$				
		$I_O = -20\text{ }\mu\text{A}$; $V_{CC(A)} = V_{CC(B)} = 1.1\text{ V to }3.6\text{ V}$	[2] $V_{CCO} - 0.1$	-	-	V
		$I_O = -1.1\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.1\text{ V}$	[2] $0.7 \times V_{CCO}$	-	-	V
		$I_O = -1.7\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.4\text{ V}$	1.03	-	-	V
		$I_O = -1.9\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.65\text{ V}$	1.30	-	-	V
		$I_O = -2.3\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 2.3\text{ V}$	1.97	-	-	V
		$I_O = -3.1\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 2.3\text{ V}$	1.85	-	-	V
		$I_O = -2.7\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 3.0\text{ V}$	2.67	-	-	V
		$I_O = -4.0\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 3.0\text{ V}$	2.55	-	-	V
V_{OL}	LOW-level output voltage	$V_I = V_{IL}$				
		$I_O = 20\text{ }\mu\text{A}$; $V_{CC(A)} = V_{CC(B)} = 1.1\text{ V to }3.6\text{ V}$	-	-	0.1	V
		$I_O = 1.1\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.1\text{ V}$	[2] -	-	$0.3 \times V_{CCO}$	V
		$I_O = 1.7\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.4\text{ V}$	-	-	0.37	V
		$I_O = 1.9\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.65\text{ V}$	-	-	0.35	V
		$I_O = 2.3\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 2.3\text{ V}$	-	-	0.33	V
		$I_O = 3.1\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 2.3\text{ V}$	-	-	0.45	V
		$I_O = 2.7\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 3.0\text{ V}$	-	-	0.33	V
		$I_O = 4.0\text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 3.0\text{ V}$	-	-	0.45	V
I_I	input leakage current	DIR input; $V_I = \text{GND to }V_{CC(A)}$; $V_{CC(A)} = V_{CC(B)} = 1.1\text{ V to }3.6\text{ V}$	-	-	± 0.5	μA
I_{OZ}	OFF-state output current	A or B port; $V_I = V_{IH}$ or V_{IL} ; $V_O = 0\text{ V to }V_{CCO}$; $V_{CC(A)} = V_{CC(B)} = 1.1\text{ V to }3.6\text{ V}$	[2] -	-	± 0.5	μA

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I _{OFF}	power-off leakage current	A port; V _I or V _O = 0 V to 3.6 V; V _{CC(A)} = 0 V; V _{CC(B)} = 1.1 V to 3.6 V	-	-	±0.5	μA
		B port; V _I or V _O = 0 V to 3.6 V; V _{CC(B)} = 0 V; V _{CC(A)} = 1.1 V to 3.6 V	-	-	±0.5	μA
		DIR input; V _I or V _O = 0 V to 3.6 V; V _{CC(A)} = 0 V; V _{CC(B)} = 1.1 V to 3.6 V	-	-	±0.5	μA
ΔI _{OFF}	additional power-off leakage current	A port; V _I or V _O = 0 V to 3.6 V; V _{CC(A)} = 0 V to 0.2 V; V _{CC(B)} = 1.1 V to 3.6 V	-	-	±0.6	μA
		B port; V _I or V _O = 0 V to 3.6 V; V _{CC(B)} = 0 V to 0.2 V; V _{CC(A)} = 1.1 V to 3.6 V	-	-	±0.6	μA
		DIR input; V _I or V _O = 0 V to 3.6 V; V _{CC(A)} = 0 V to 0.2 V; V _{CC(B)} = 1.1 V to 3.6 V	-	-	±0.6	μA
I _{CC}	supply current	A port; V _I = GND or V _{CCI} ; I _O = 0 A	[1]			
		V _{CC(A)} = V _{CC(B)} = 1.1 V to 3.6 V	-	-	0.9	μA
		V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V	-	-	0.9	μA
		V _{CC(A)} = 0 V; V _{CC(B)} = 3.6 V	-	0	-	μA
		B port; V _I = GND or V _{CCI} ; I _O = 0 A	[1]			
		V _{CC(A)} = V _{CC(B)} = 1.1 V to 3.6 V	-	-	0.9	μA
		V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V	-	0	-	μA
		V _{CC(A)} = 0 V; V _{CC(B)} = 3.6 V	-	-	0.9	μA
		A plus B port (I _{CC(A)} + I _{CC(B)}); I _O = 0 A; V _I = GND or V _{CCI} ; V _{CC(A)} = V _{CC(B)} = 1.1 V to 3.6 V	[1]	-	-	0.9
ΔI _{CC}	additional supply current	A port; V _{CC(A)} = V _{CC(B)} = 3.3 V; A port at V _{CC(A)} − 0.6 V; DIR at V _{CC(A)} ; B port = open	-	-	50	μA
		B port; V _{CC(A)} = V _{CC(B)} = 3.3 V; B port at V _{CC(B)} − 0.6 V; DIR at GND; A port = open	-	-	50	μA
		DIR input; V _{CC(A)} = V _{CC(B)} = 3.3 V; A port at V _{CC(A)} or GND; B port = open; DIR at V _{CC(A)} − 0.6 V	-	-	50	μA
T _{amb} = −40 °C to +125 °C						
V _{IH}	HIGH-level input voltage	data input	[1][3]			
		V _{CCI} = 1.1 V to 1.95 V	0.7 × V _{CCI}	-	-	V
		V _{CCI} = 2.3 V to 2.7 V	1.6	-	-	V
		V _{CCI} = 3.0 V to 3.6 V	2.0	-	-	V
		DIR input	[1][4]			
		V _{CCI} = 1.1 V to 1.95 V	0.7 × V _{CC(A)}	-	-	V
		V _{CCI} = 2.3 V to 2.7 V	1.6	-	-	V
		V _{CCI} = 3.0 V to 3.6 V	2.0	-	-	V

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{IL}	LOW-level input voltage	data input [1][3]				
		$V_{CCI} = 1.1 \text{ V to } 1.95 \text{ V}$	-	-	$0.3 \times V_{CCI}$	V
		$V_{CCI} = 2.3 \text{ V to } 2.7 \text{ V}$	-	-	0.7	V
		$V_{CCI} = 3.0 \text{ V to } 3.6 \text{ V}$	-	-	0.9	V
		DIR input [1][4]				
		$V_{CCI} = 1.1 \text{ V to } 1.95 \text{ V}$	-	-	$0.3 \times V_{CC(A)}$	V
		$V_{CCI} = 2.3 \text{ V to } 2.7 \text{ V}$	-	-	0.7	V
		$V_{CCI} = 3.0 \text{ V to } 3.6 \text{ V}$	-	-	0.9	V
V_{OH}	HIGH-level output voltage	$V_I = V_{IH}$				
		$I_O = -20 \mu\text{A}$; $V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$	[2] $V_{CCO} - 0.11$	-	-	V
		$I_O = -1.1 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V}$	[2] $0.6 \times V_{CCO}$	-	-	V
		$I_O = -1.7 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$	0.93	-	-	V
		$I_O = -1.9 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$	1.17	-	-	V
		$I_O = -2.3 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$	1.77	-	-	V
		$I_O = -3.1 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$	1.67	-	-	V
		$I_O = -2.7 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$	2.40	-	-	V
V_{OL}	LOW-level output voltage	$V_I = V_{IL}$				
		$I_O = 20 \mu\text{A}$; $V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$	-	-	0.11	V
		$I_O = 1.1 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V}$	[2] -	-	$0.33 \times V_{CCO}$	V
		$I_O = 1.7 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$	-	-	0.41	V
		$I_O = 1.9 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$	-	-	0.39	V
		$I_O = 2.3 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$	-	-	0.36	V
		$I_O = 3.1 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$	-	-	0.50	V
		$I_O = 2.7 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$	-	-	0.36	V
I_I	input leakage current	$I_O = 4.0 \text{ mA}$; $V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$	-	-	0.50	V
		DIR input; $V_I = \text{GND to } V_{CC(A)}$; $V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$	-	-	± 0.75	μA
		A or B port; $V_I = V_{IH}$ or V_{IL} ; $V_O = 0 \text{ V to } V_{CCO}$; $V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$	[2] -	-	± 0.75	μA
I_{OZ}	OFF-state output current	A port; V_I or $V_O = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$	-	-	± 0.75	μA
		B port; V_I or $V_O = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$; $V_{CC(A)} = 1.1 \text{ V to } 3.6 \text{ V}$	-	-	± 0.75	μA
		DIR input; V_I or $V_O = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$	-	-	± 0.75	μA
I_{OFF}	power-off leakage current	A port; V_I or $V_O = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$	-	-	± 0.75	μA
		B port; V_I or $V_O = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(B)} = 0 \text{ V}$; $V_{CC(A)} = 1.1 \text{ V to } 3.6 \text{ V}$	-	-	± 0.75	μA
		DIR input; V_I or $V_O = 0 \text{ V to } 3.6 \text{ V}$; $V_{CC(A)} = 0 \text{ V}$; $V_{CC(B)} = 1.1 \text{ V to } 3.6 \text{ V}$	-	-	± 0.75	μA

Table 7. Static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
ΔI_{OFF}	additional power-off leakage current	A port; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V to 0.2 V; $V_{CC(B)} = 1.1$ V to 3.6 V	-	-	± 0.75	μA
		B port; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(B)} = 0$ V to 0.2 V; $V_{CC(A)} = 1.1$ V to 3.6 V	-	-	± 0.75	μA
		DIR input; V_I or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V to 0.2 V; $V_{CC(B)} = 1.1$ V to 3.6 V	-	-	± 0.75	μA
I_{CC}	supply current	A port; $V_I = GND$ or V_{CCI} ; $I_O = 0$ A	[1]			
		$V_{CC(A)} = V_{CC(B)} = 1.1$ V to 3.6 V	-	-	1.4	μA
		$V_{CC(A)} = 3.6$ V; $V_{CC(B)} = 0$ V	-	-	1.4	μA
		$V_{CC(A)} = 0$ V; $V_{CC(B)} = 3.6$ V	-	0	-	μA
		B port; $V_I = GND$ or V_{CCI} ; $I_O = 0$ A	[1]			
		$V_{CC(A)} = V_{CC(B)} = 1.1$ V to 3.6 V	-	-	1.4	μA
		$V_{CC(A)} = 3.6$ V; $V_{CC(B)} = 0$ V	-	0	-	μA
		$V_{CC(A)} = 0$ V; $V_{CC(B)} = 3.6$ V	-	-	1.4	μA
		A plus B port ($I_{CC(A)} + I_{CC(B)}$); $I_O = 0$ A; $V_I = GND$ or V_{CCI} ; $V_{CC(A)} = V_{CC(B)} = 1.1$ V to 3.6 V	[1]	-	1.4	μA
ΔI_{CC}	additional supply current	A port; $V_{CC(A)} = V_{CC(B)} = 3.3$ V; A port at $V_{CC(A)} - 0.6$ V; DIR at $V_{CC(A)}$; B port = open	-	-	75	μA
		B port; $V_{CC(A)} = V_{CC(B)} = 3.3$ V; B port at $V_{CC(B)} - 0.6$ V; DIR at GND; A port = open	-	-	75	μA
		DIR input; $V_{CC(A)} = V_{CC(B)} = 3.3$ V; A port at $V_{CC(A)}$ or GND; B port = open; DIR at $V_{CC(A)} - 0.6$ V	-	-	75	μA

[1] V_{CCI} is the supply voltage associated with the data input port.[2] V_{CCO} is the supply voltage associated with the output port.[3] For V_{CCI} values not specified in the data sheet: minimum $V_{IH} = 0.7 \times V_{CCI}$ and maximum $V_{IL} = 0.3 \times V_{CCI}$.[4] For V_{CCI} values not specified in the data sheet: minimum $V_{IH} = 0.7 \times V_{CC(A)}$ and maximum $V_{IL} = 0.3 \times V_{CC(A)}$.[5] All unused data inputs of the device must be held at V_{CCI} or GND to ensure proper device operation.

11. Dynamic characteristics

Table 8. Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	

$C_L = 5 \text{ pF}$; $V_{CC(A)} = 1.1 \text{ V to } 1.3 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.8	15.4	28.0	2.4	28.3	31.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.8	10.2	16.2	2.6	17.5	19.3	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.4	8.1	13.0	2.2	14.4	15.9	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.5	6.3	10.0	2.1	10.7	11.8	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.3	5.6	9.0	1.9	9.7	10.7	ns
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.7	5.3	8.5	2.5	8.7	9.6	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.9	5.3	8.4	2.7	8.7	9.7	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.7	5.3	8.5	2.5	9.0	10.0	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.7	5.3	8.7	2.5	8.9	9.9	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.9	5.3	8.7	2.5	9.1	10.1	ns
	DIR to B; see Figure 7 ^[3]	$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.1	13.2	22.1	5.4	23.4	25.8	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	5.0	9.3	13.9	4.4	15.2	16.7	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	4.2	8.1	12.3	3.6	13.5	14.9	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.3	6.3	9.3	2.9	10.2	11.2	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.6	6.3	9.2	3.2	9.7	10.7	ns

$C_L = 5 \text{ pF}$; $V_{CC(A)} = 1.4 \text{ V to } 1.6 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.5	14.5	26.6	2.2	27.1	29.9	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.5	9.4	14.5	2.3	15.9	17.5	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.1	7.4	11.2	1.9	12.7	14.0	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.2	5.5	8.0	1.8	8.9	9.8	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.0	4.7	6.8	1.6	7.6	8.4	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.0	3.8	5.3	1.9	5.7	6.3	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.2	3.8	5.3	2.0	5.7	6.4	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.1	3.8	5.5	1.8	5.9	6.6	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.1	3.8	5.5	1.9	5.9	6.6	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.2	3.8	5.5	1.9	6.0	6.6	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	5.7	12.7	21.0	5.2	22.3	24.6	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	4.7	8.7	12.7	4.1	14.1	15.5	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.9	7.4	10.9	3.3	12.3	13.5	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.0	5.6	7.8	2.6	8.8	9.7	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.3	5.5	7.4	2.9	8.1	8.9	ns

 $C_L = 5 \text{ pF}$; $V_{CC(A)} = 1.65 \text{ V to } 1.95 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.4	14.2	26.1	2.0	26.5	29.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.4	9.1	13.9	2.1	15.4	17.0	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.0	7.0	10.7	1.7	12.1	13.4	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.0	5.1	7.4	1.6	8.2	9.1	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	1.9	4.3	6.1	1.5	6.9	7.7	ns
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.0	3.5	4.8	1.8	5.2	5.8	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.1	3.5	4.8	1.9	5.2	5.7	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.0	3.5	5.0	1.8	5.4	6.0	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.0	3.5	4.9	1.8	5.4	6.0	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.1	3.5	4.9	1.8	5.4	6.0	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	5.8	12.4	20.6	5.1	21.9	24.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	4.6	8.4	12.2	3.9	13.5	14.9	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.8	7.1	10.4	3.2	11.8	13.0	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.9	5.2	7.3	2.5	8.3	9.1	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.1	5.1	6.9	2.7	7.5	8.3	ns

 $C_L = 5 \text{ pF}$; $V_{CC(A)} = 2.3 \text{ V to } 2.7 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.4	13.6	25.5	2.0	25.9	28.6	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.3	8.5	13.3	2.1	14.7	16.2	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	1.9	6.5	10.0	1.7	11.4	12.5	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	1.9	4.6	6.7	1.6	7.5	8.3	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	1.8	3.8	5.3	1.4	6.2	6.8	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	1.4	2.5	3.3	1.3	3.6	4.0	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	1.6	2.5	3.3	1.4	3.6	4.0	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	1.5	2.5	3.4	1.3	3.8	4.2	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	1.4	2.5	3.4	1.3	3.8	4.2	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	1.6	2.5	3.4	1.3	3.7	4.1	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	5.8	12.3	20.4	5.1	21.8	24.0	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	4.5	8.3	11.9	4.0	13.2	14.5	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.7	7.0	10.0	3.2	11.3	12.5	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.8	5.0	6.8	2.5	7.8	8.6	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.1	4.9	6.4	2.7	7.0	7.8	ns

 $C_L = 5 \text{ pF}$; $V_{CC(A)} = 3.0 \text{ V to } 3.6 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.3	13.1	24.9	2.0	25.2	27.8	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.3	8.1	12.8	2.0	14.1	15.5	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	1.9	6.1	9.5	1.7	10.8	12.0	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	1.9	4.3	6.2	1.6	7.0	7.7	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	1.7	3.5	5.0	1.4	5.7	6.3	ns
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	1.7	2.8	3.5	1.5	3.8	4.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	1.8	2.8	3.5	1.7	3.8	4.2	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	1.7	2.8	3.6	1.5	4.0	4.4	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	1.7	2.8	3.6	1.5	3.9	4.4	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	1.8	2.8	3.6	1.5	3.9	4.3	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	5.8	12.3	20.6	5.1	22.0	24.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	4.6	8.3	11.8	4.0	13.1	14.5	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.8	6.9	10.0	3.2	11.3	12.5	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.8	5.0	6.7	2.5	7.6	8.4	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.1	4.9	6.3	2.7	6.9	7.6	ns

 $C_L = 10 \text{ pF}$; $V_{CC(A)} = 1.1 \text{ V to } 1.3 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.0	16.2	29.8	2.7	30.2	33.3	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.0	10.8	17.5	2.7	18.6	20.5	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.1	8.7	13.5	2.8	14.6	16.1	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.7	6.8	10.5	2.4	11.2	12.4	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.7	6.1	9.6	2.4	10.1	11.1	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.2	6.5	9.9	3.1	10.2	11.3	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.5	6.5	10.0	3.2	10.2	11.3	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.7	6.5	9.8	3.5	10.1	11.1	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.2	6.5	10.1	3.1	10.2	11.3	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.6	6.5	10.1	3.2	10.3	11.4	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.4	14.3	23.5	5.8	24.8	27.4	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	5.3	10.2	15.4	4.6	16.6	18.4	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	5.2	9.2	13.6	4.7	14.7	16.2	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.6	7.1	10.1	3.2	11.0	12.1	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	4.4	7.6	10.8	3.8	11.4	12.5	ns

 $C_L = 10 \text{ pF}$; $V_{CC(A)} = 1.4 \text{ V to } 1.6 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.7	15.3	28.3	2.4	29.0	31.9	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.7	10.0	15.8	2.5	17.0	18.7	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.8	7.9	11.8	2.5	13.0	14.4	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.4	6.0	8.6	2.2	9.4	10.4	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.4	5.2	7.4	2.1	8.0	8.9	ns
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.5	4.7	6.4	2.3	6.8	7.6	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.7	4.7	6.5	2.4	6.9	7.6	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.9	4.7	6.5	2.6	6.9	7.6	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.5	4.7	6.5	2.3	6.9	7.6	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.8	4.7	6.6	2.4	6.9	7.7	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.1	13.7	22.4	5.6	23.8	26.3	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	5.0	9.6	14.2	4.3	15.5	17.1	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	4.9	8.5	12.3	4.4	13.4	14.8	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.3	6.4	8.7	3.0	9.6	10.6	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	4.1	6.7	9.1	3.5	9.7	10.8	ns

 $C_L = 10 \text{ pF}$; $V_{CC(A)} = 1.65 \text{ V to } 1.95 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.6	15.0	27.8	2.3	28.3	31.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.6	9.7	15.2	2.3	16.5	18.2	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.7	7.5	11.2	2.3	12.4	13.7	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.3	5.6	7.9	2.0	8.8	9.7	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.3	4.8	6.7	1.9	7.4	8.2	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.5	4.6	6.2	2.4	6.6	7.3	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.7	4.6	6.3	2.5	6.7	7.4	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.9	4.6	6.3	2.7	6.7	7.4	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.5	4.6	6.2	2.4	6.7	7.4	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.8	4.6	6.3	2.5	6.7	7.4	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.1	13.5	22.1	5.4	23.4	25.8	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	5.0	9.3	13.6	4.2	14.9	16.5	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	4.8	8.3	11.8	4.2	13.0	14.3	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.2	6.0	8.1	2.8	9.1	10.0	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.9	6.4	8.5	3.3	9.2	10.2	ns

 $C_L = 10 \text{ pF}$; $V_{CC(A)} = 2.3 \text{ V to } 2.7 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.5	14.4	27.2	2.3	27.8	30.6	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.5	9.1	14.6	2.3	15.8	17.4	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.6	7.0	10.5	2.2	11.7	12.9	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.2	5.1	7.2	1.9	8.0	8.9	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.2	4.3	5.9	1.9	6.6	7.3	ns
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	1.8	3.3	4.2	1.7	4.6	5.1	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.0	3.3	4.4	1.8	4.7	5.2	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.1	3.3	4.4	2.0	4.7	5.2	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	1.8	3.3	4.3	1.7	4.7	5.2	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.1	3.3	4.4	1.8	4.7	5.2	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.1	13.4	21.8	5.4	23.2	25.6	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	4.9	9.2	13.3	4.2	14.6	16.1	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	4.8	8.1	11.4	4.2	12.5	13.8	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.1	5.8	7.7	2.8	8.6	9.5	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.9	6.2	8.0	3.3	8.7	9.6	ns

 $C_L = 10 \text{ pF}$; $V_{CC(A)} = 3.0 \text{ V to } 3.6 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.5	14.0	26.6	2.2	27.0	29.8	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.5	8.7	14.0	2.3	15.1	16.7	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.5	6.6	10.1	2.2	11.2	12.4	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.2	4.8	6.8	1.9	7.5	8.3	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.1	4.0	5.5	1.9	6.1	6.8	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t _{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		V _{CC(B)} = 1.1 V to 1.3 V	2.3	4.0	5.0	2.2	5.3	5.9	ns
		V _{CC(B)} = 1.4 V to 1.6 V	2.5	4.0	5.2	2.3	5.4	6.0	ns
		V _{CC(B)} = 1.65 V to 1.95 V	2.6	4.0	5.2	2.5	5.4	6.0	ns
		V _{CC(B)} = 2.3 V to 2.7 V	2.3	4.0	5.1	2.2	5.4	6.0	ns
		V _{CC(B)} = 3.0 V to 3.6 V	2.6	4.0	5.2	2.3	5.4	6.0	ns
		DIR to B; see Figure 7 ^[3]							
		V _{CC(B)} = 1.1 V to 1.3 V	6.2	13.5	22.0	5.5	23.4	25.8	ns
		V _{CC(B)} = 1.4 V to 1.6 V	4.9	9.2	13.2	4.2	14.6	16.1	ns
		V _{CC(B)} = 1.65 V to 1.95 V	4.8	8.1	11.3	4.3	12.4	13.7	ns
		V _{CC(B)} = 2.3 V to 2.7 V	3.1	5.8	7.6	2.8	8.5	9.4	ns
		V _{CC(B)} = 3.0 V to 3.6 V	3.9	6.2	7.9	3.3	8.5	9.5	ns

C_L = 15 pF; V_{CC(A)} = 1.1 V to 1.3 V

t _{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		V _{CC(B)} = 1.1 V to 1.3 V	3.4	16.9	31.6	3.0	32.0	35.2	ns
		V _{CC(B)} = 1.4 V to 1.6 V	3.7	11.3	18.2	3.1	19.5	21.5	ns
		V _{CC(B)} = 1.65 V to 1.95 V	3.2	9.1	14.3	3.0	15.6	17.2	ns
		V _{CC(B)} = 2.3 V to 2.7 V	3.2	7.3	11.2	2.8	12.0	13.2	ns
		V _{CC(B)} = 3.0 V to 3.6 V	3.1	6.5	10.2	2.6	10.7	11.8	ns
t _{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		V _{CC(B)} = 1.1 V to 1.3 V	3.9	7.6	11.4	3.8	11.7	12.9	ns
		V _{CC(B)} = 1.4 V to 1.6 V	4.5	7.6	11.3	4.1	11.7	12.9	ns
		V _{CC(B)} = 1.65 V to 1.95 V	4.2	7.6	11.3	4.1	11.7	12.9	ns
		V _{CC(B)} = 2.3 V to 2.7 V	3.9	7.6	11.7	3.8	11.9	13.1	ns
		V _{CC(B)} = 3.0 V to 3.6 V	4.5	7.6	11.7	4.1	11.9	13.1	ns
		DIR to B; see Figure 7 ^[3]							
		V _{CC(B)} = 1.1 V to 1.3 V	7.2	15.4	24.9	6.5	26.3	29.0	ns
		V _{CC(B)} = 1.4 V to 1.6 V	6.3	11.1	16.3	5.4	17.7	19.5	ns
		V _{CC(B)} = 1.65 V to 1.95 V	5.7	10.4	15.0	5.2	16.2	17.9	ns
		V _{CC(B)} = 2.3 V to 2.7 V	4.1	7.9	11.4	3.8	12.1	13.4	ns
		V _{CC(B)} = 3.0 V to 3.6 V	5.3	8.8	12.2	4.9	12.7	14.1	ns

C_L = 15 pF; V_{CC(A)} = 1.4 V to 1.6 V

t _{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		V _{CC(B)} = 1.1 V to 1.3 V	3.1	16.1	30.1	2.8	30.7	33.8	ns
		V _{CC(B)} = 1.4 V to 1.6 V	3.4	10.5	16.5	2.8	17.9	19.7	ns
		V _{CC(B)} = 1.65 V to 1.95 V	3.0	8.4	12.6	2.7	13.9	15.4	ns
		V _{CC(B)} = 2.3 V to 2.7 V	2.9	6.4	9.3	2.5	10.1	11.2	ns
		V _{CC(B)} = 3.0 V to 3.6 V	2.8	5.6	8.0	2.3	8.7	9.6	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.1	5.6	7.6	2.9	8.0	8.9	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.5	5.6	7.5	3.1	8.0	8.8	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.3	5.6	7.6	3.1	8.0	8.9	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.1	5.6	7.7	2.9	8.1	9.0	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.5	5.6	7.8	3.1	8.1	9.0	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.9	14.9	23.8	6.4	25.3	27.9	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	6.0	10.5	15.1	5.2	16.6	18.3	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	5.4	9.7	13.7	5.0	15.0	16.5	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.8	7.2	9.9	3.5	10.7	11.9	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	5.0	8.0	10.5	4.6	11.1	12.3	ns

 $C_L = 15 \text{ pF}$; $V_{CC(A)} = 1.65 \text{ V to } 1.95 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.0	15.8	29.6	2.6	30.1	33.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.2	10.2	15.9	2.6	17.4	19.2	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.8	8.0	12.0	2.5	13.4	14.8	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.8	6.0	8.6	2.3	9.5	10.5	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.6	5.2	7.3	2.2	8.0	8.9	ns

t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.2	5.8	7.6	3.1	8.0	8.9	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.7	5.8	7.6	3.3	8.1	8.9	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.5	5.8	7.7	3.3	8.1	9.0	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.2	5.8	7.8	3.1	8.2	9.0	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.7	5.8	7.8	3.4	8.1	9.0	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.9	14.7	23.4	6.2	24.9	27.4	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	5.9	10.2	14.6	5.0	16.0	17.7	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	5.3	9.4	13.2	4.8	14.5	16.0	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.7	6.8	9.4	3.4	10.2	11.3	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	4.9	7.6	9.9	4.4	10.6	11.7	ns

 $C_L = 15 \text{ pF}$; $V_{CC(A)} = 2.3 \text{ V to } 2.7 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.0	15.2	29.0	2.6	29.5	32.5	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.1	9.6	15.3	2.6	16.7	18.4	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.7	7.5	11.3	2.5	12.6	13.9	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.7	5.5	7.9	2.3	8.7	9.6	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.5	4.7	6.5	2.1	7.2	8.0	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.4	4.1	5.2	2.2	5.6	6.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	2.7	4.1	5.3	2.4	5.7	6.3	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.5	4.1	5.4	2.4	5.7	6.3	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.4	4.1	5.4	2.2	5.7	6.3	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.7	4.1	5.3	2.4	5.6	6.2	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.9	14.6	23.2	6.2	24.7	27.2	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	5.9	10.1	14.2	5.0	15.6	17.3	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	5.3	9.2	12.8	4.8	14.0	15.5	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.7	6.7	8.9	3.4	9.8	10.8	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	4.8	7.4	9.4	4.4	10.1	11.2	ns

 $C_L = 15 \text{ pF}$; $V_{CC(A)} = 3.0 \text{ V to } 3.6 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	2.9	14.7	28.3	2.6	28.8	31.7	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.1	9.2	14.7	2.6	16.0	17.7	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	2.7	7.1	10.9	2.4	12.1	13.4	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	2.7	5.2	7.4	2.2	8.2	9.1	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	2.5	4.5	6.1	2.1	6.8	7.5	ns
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.1	5.3	6.5	3.0	6.9	7.6	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.5	5.3	6.6	3.2	7.0	7.7	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.3	5.3	6.7	3.2	7.0	7.8	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.1	5.3	6.8	3.0	7.1	7.8	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.5	5.3	6.6	3.2	6.9	7.6	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	6.9	14.6	23.4	6.3	24.9	27.4	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	5.9	10.1	14.2	5.0	15.6	17.2	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	5.3	9.2	12.7	4.8	13.9	15.4	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.7	6.6	8.8	3.4	9.6	10.6	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	4.8	7.4	9.3	4.4	10.0	11.0	ns

 $C_L = 30 \text{ pF}$; $V_{CC(A)} = 1.1 \text{ V to } 1.3 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	4.2	19.1	36.0	3.8	36.8	40.5	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	4.5	12.8	20.6	4.0	22.0	24.2	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	4.2	10.4	16.2	3.8	17.4	19.2	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	4.0	8.3	12.4	3.5	13.2	14.5	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	4.0	7.5	11.5	3.7	12.5	13.8	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t _{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		V _{CC(B)} = 1.1 V to 1.3 V	5.6	11.0	15.7	5.5	16.2	17.9	ns
		V _{CC(B)} = 1.4 V to 1.6 V	6.1	11.0	15.6	6.0	15.9	17.5	ns
		V _{CC(B)} = 1.65 V to 1.95 V	6.6	11.0	15.5	6.5	15.8	17.4	ns
		V _{CC(B)} = 2.3 V to 2.7 V	5.6	11.0	15.6	5.5	15.8	17.5	ns
		V _{CC(B)} = 3.0 V to 3.6 V	7.0	11.0	15.9	6.6	16.7	18.4	ns
		DIR to B; see Figure 7 ^[3]							
		V _{CC(B)} = 1.1 V to 1.3 V	8.7	18.9	29.0	8.1	30.5	33.6	ns
		V _{CC(B)} = 1.4 V to 1.6 V	7.3	13.8	19.3	6.8	20.7	22.8	ns
		V _{CC(B)} = 1.65 V to 1.95 V	8.1	13.7	19.2	7.7	20.3	22.4	ns
		V _{CC(B)} = 2.3 V to 2.7 V	5.2	10.3	14.0	4.9	14.7	16.2	ns
		V _{CC(B)} = 3.0 V to 3.6 V	8.1	12.5	16.5	7.5	18.0	19.9	ns
C_L = 30 pF; V_{CC(A)} = 1.4 V to 1.6 V									
t _{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		V _{CC(B)} = 1.1 V to 1.3 V	4.0	18.2	34.5	3.5	35.5	39.1	ns
		V _{CC(B)} = 1.4 V to 1.6 V	4.2	12.0	18.9	3.7	20.3	22.4	ns
		V _{CC(B)} = 1.65 V to 1.95 V	3.9	9.6	14.4	3.5	15.8	17.4	ns
		V _{CC(B)} = 2.3 V to 2.7 V	3.8	7.5	10.4	3.2	11.4	12.6	ns
		V _{CC(B)} = 3.0 V to 3.6 V	3.7	6.7	9.3	3.4	10.4	11.4	ns
t _{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		V _{CC(B)} = 1.1 V to 1.3 V	4.4	8.3	10.8	4.3	11.4	12.6	ns
		V _{CC(B)} = 1.4 V to 1.6 V	4.8	8.3	10.7	4.6	11.2	12.3	ns
		V _{CC(B)} = 1.65 V to 1.95 V	5.2	8.3	10.8	5.0	11.2	12.4	ns
		V _{CC(B)} = 2.3 V to 2.7 V	4.4	8.3	10.8	4.3	11.1	12.3	ns
		V _{CC(B)} = 3.0 V to 3.6 V	5.5	8.3	11.0	5.1	11.8	13.0	ns
		DIR to B; see Figure 7 ^[3]							
		V _{CC(B)} = 1.1 V to 1.3 V	8.4	18.3	27.9	7.9	29.5	32.5	ns
		V _{CC(B)} = 1.4 V to 1.6 V	7.1	13.2	18.2	6.6	19.6	21.6	ns
		V _{CC(B)} = 1.65 V to 1.95 V	7.8	13.1	17.9	7.4	19.1	21.0	ns
		V _{CC(B)} = 2.3 V to 2.7 V	4.9	9.6	12.6	4.6	13.4	14.8	ns
		V _{CC(B)} = 3.0 V to 3.6 V	7.7	11.7	14.8	7.2	16.3	18.0	ns
C_L = 30 pF; V_{CC(A)} = 1.65 V to 1.95 V									
t _{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		V _{CC(B)} = 1.1 V to 1.3 V	3.9	18.0	34.0	3.4	34.9	38.4	ns
		V _{CC(B)} = 1.4 V to 1.6 V	4.1	11.7	18.3	3.5	19.8	21.9	ns
		V _{CC(B)} = 1.65 V to 1.95 V	3.8	9.2	13.9	3.4	15.2	16.8	ns
		V _{CC(B)} = 2.3 V to 2.7 V	3.6	7.1	9.8	3.1	10.8	11.9	ns
		V _{CC(B)} = 3.0 V to 3.6 V	3.5	6.3	8.6	3.2	9.7	10.7	ns

Table 8. Dynamic characteristics ...continuedVoltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	5.0	9.2	11.7	4.8	12.3	13.6	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	5.4	9.2	11.7	5.3	12.1	13.4	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	5.8	9.1	11.9	5.7	12.3	13.6	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	5.0	9.1	11.7	4.8	12.1	13.4	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	6.2	9.2	11.9	5.8	12.7	14.1	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	8.4	18.1	27.6	7.8	29.1	32.0	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	7.0	12.9	17.7	6.4	19.1	21.0	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	7.7	12.8	17.4	7.2	18.6	20.6	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	4.8	9.3	12.0	4.5	12.9	14.2	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	7.6	11.3	14.2	7.0	15.8	17.4	ns

 $C_L = 30 \text{ pF}$; $V_{CC(A)} = 2.3 \text{ V to } 2.7 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.8	17.4	33.4	3.4	34.3	37.8	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	4.0	11.1	17.7	3.5	19.1	21.1	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.7	8.7	13.2	3.3	14.4	15.9	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.4	6.5	9.1	3.0	10.0	11.1	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.5	5.7	7.8	3.1	8.9	9.8	ns
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.6	6.5	8.1	3.5	8.5	9.4	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.9	6.5	8.1	3.8	8.5	9.4	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	4.2	6.5	8.3	4.1	8.6	9.5	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.6	6.5	8.2	3.5	8.5	9.4	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	4.5	6.5	8.2	4.2	8.9	9.8	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	8.4	18.0	27.4	7.8	28.8	31.8	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	7.0	12.8	17.3	6.4	18.7	20.6	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	7.7	12.6	17.0	7.2	18.2	20.0	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	4.8	9.1	11.6	4.5	12.4	13.7	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	7.6	11.1	13.7	7.0	15.3	16.9	ns

 $C_L = 30 \text{ pF}$; $V_{CC(A)} = 3.0 \text{ V to } 3.6 \text{ V}$

t_{pd}	propagation delay	A to B or B to A; see Figure 6 ^[2]							
		$V_{CC(B)} = 1.1 \text{ V to } 1.3 \text{ V}$	3.8	16.9	32.8	3.3	33.5	36.9	ns
		$V_{CC(B)} = 1.4 \text{ V to } 1.6 \text{ V}$	3.9	10.7	17.1	3.5	18.5	20.4	ns
		$V_{CC(B)} = 1.65 \text{ V to } 1.95 \text{ V}$	3.7	8.3	12.7	3.3	13.9	15.4	ns
		$V_{CC(B)} = 2.3 \text{ V to } 2.7 \text{ V}$	3.2	6.3	8.6	2.9	9.5	10.5	ns
		$V_{CC(B)} = 3.0 \text{ V to } 3.6 \text{ V}$	3.4	5.5	7.4	3.1	8.4	9.3	ns

Table 8. Dynamic characteristics ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
t_{dis}	disable time	DIR to A; see Figure 7 ^[3]							
		$V_{\text{CC(B)}} = 1.1 \text{ V to } 1.3 \text{ V}$	5.0	9.0	11.0	4.9	11.5	12.7	ns
		$V_{\text{CC(B)}} = 1.4 \text{ V to } 1.6 \text{ V}$	5.4	9.0	11.1	5.3	11.4	12.6	ns
		$V_{\text{CC(B)}} = 1.65 \text{ V to } 1.95 \text{ V}$	5.9	9.0	11.3	5.7	11.6	12.8	ns
		$V_{\text{CC(B)}} = 2.3 \text{ V to } 2.7 \text{ V}$	5.0	9.0	11.2	4.9	11.4	12.6	ns
		$V_{\text{CC(B)}} = 3.0 \text{ V to } 3.6 \text{ V}$	6.2	9.0	11.2	5.9	11.9	13.2	ns
		DIR to B; see Figure 7 ^[3]							
		$V_{\text{CC(B)}} = 1.1 \text{ V to } 1.3 \text{ V}$	8.4	18.1	27.6	7.8	29.1	32.0	ns
		$V_{\text{CC(B)}} = 1.4 \text{ V to } 1.6 \text{ V}$	7.0	12.8	17.3	6.4	18.6	20.6	ns
		$V_{\text{CC(B)}} = 1.65 \text{ V to } 1.95 \text{ V}$	7.7	12.6	17.0	7.2	18.1	19.9	ns
		$V_{\text{CC(B)}} = 2.3 \text{ V to } 2.7 \text{ V}$	4.8	9.0	11.5	4.5	12.3	13.6	ns
		$V_{\text{CC(B)}} = 3.0 \text{ V to } 3.6 \text{ V}$	7.6	11.1	13.6	7.0	15.1	16.7	ns

Table 8. Dynamic characteristics ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see [Figure 8](#).

Symbol	Parameter	Conditions	25 °C			–40 °C to +125 °C			Unit
			Min	Typ ^[1]	Max	Min	Max (85 °C)	Max (125 °C)	
C _L = 5 pF, 10 pF, 15 pF and 30 pF									
C _{PD}	power dissipation capacitance	A port; (direction A to B)	[4][5]						
		V _{CC(A)} = V _{CC(B)} = 1.2 V	-	0.6	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 1.5 V	-	0.7	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 1.8 V	-	0.7	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 2.5 V	-	0.9	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 3.3 V	-	1.1	-	-	-	-	pF
		A port; (direction B to A)	[4][5]						
		V _{CC(A)} = V _{CC(B)} = 1.2 V	-	3.7	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 1.5 V	-	3.8	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 1.8 V	-	4.0	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 2.5 V	-	4.6	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 3.3 V	-	5.2	-	-	-	-	pF
		B port; (direction A to B)	[4][5]						
		V _{CC(A)} = V _{CC(B)} = 1.2 V	-	3.7	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 1.5 V	-	3.8	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 1.8 V	-	4.0	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 2.5 V	-	4.6	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 3.3 V	-	5.2	-	-	-	-	pF
		B port; (direction B to A)	[4][5]						
		V _{CC(A)} = V _{CC(B)} = 1.2 V	-	0.6	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 1.5 V	-	0.7	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 1.8 V	-	0.7	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 2.5 V	-	0.9	-	-	-	-	pF
		V _{CC(A)} = V _{CC(B)} = 3.3 V	-	1.1	-	-	-	-	pF

[1] All typical values are measured at nominal V_{CC(A)} and V_{CC(B)}.

[2] t_{pd} is the same as t_{PLH} and t_{PHL}.

[3] t_{dis} is the same as t_{PLZ} and t_{PHZ}.

[4] C_{PD} is used to determine the dynamic power dissipation (P_D in μW).

$P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma(C_L \times V_{CC}^2 \times f_o)$ where:

f_i = input frequency in MHz;

f_o = output frequency in MHz;

C_L = load capacitance in pF;

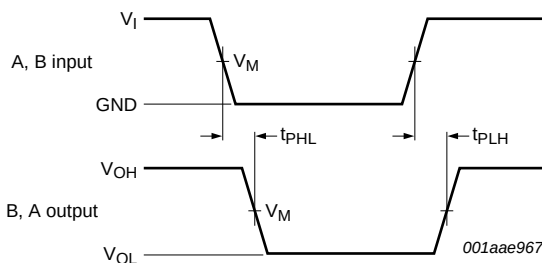
V_{CC} = supply voltage in V;

N = number of inputs switching;

$\Sigma(C_L \times V_{CC}^2 \times f_o)$ = sum of the outputs.

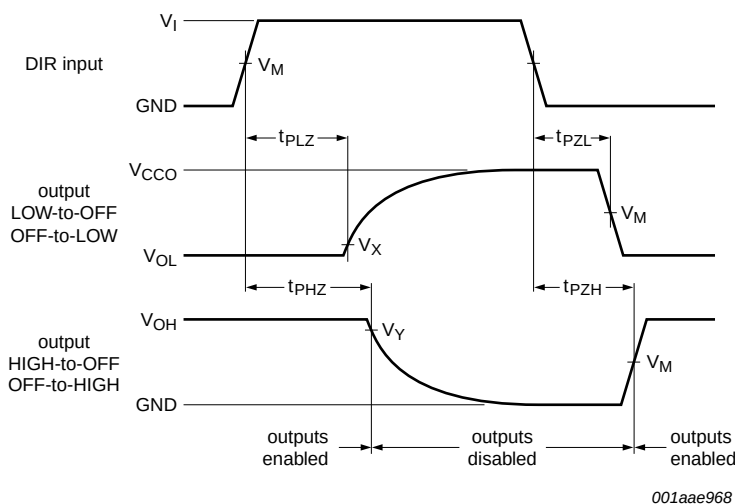
[5] f_i = 1 MHz; V_I = GND to V_{CC}

12. Waveforms



Measurement points are given in [Table 9](#).
 V_{OL} and V_{OH} are typical output voltage drops that occur with the output load.

Fig 6. The data input (A, B) to output (B, A) propagation delay times



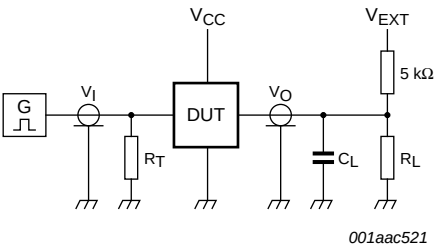
Measurement points are given in [Table 9](#).
 V_{OL} and V_{OH} are typical output voltage drops that occur with the output load.

Fig 7. Enable and disable times

Table 9. Measurement points

Supply voltage	Input ^[1]	Output ^[2]		
$V_{CC(A)}, V_{CC(B)}$	V_M	V_M	V_X	V_Y
1.1 V to 1.6 V	$0.5 \times V_{CCI}$	$0.5 \times V_{CCO}$	$V_{OL} + 0.1 \text{ V}$	$V_{OH} - 0.1 \text{ V}$
1.65 V to 2.7 V	$0.5 \times V_{CCI}$	$0.5 \times V_{CCO}$	$V_{OL} + 0.15 \text{ V}$	$V_{OH} - 0.15 \text{ V}$
3.0 V to 3.6 V	$0.5 \times V_{CCI}$	$0.5 \times V_{CCO}$	$V_{OL} + 0.3 \text{ V}$	$V_{OH} - 0.3 \text{ V}$

[1] V_{CCI} is the supply voltage associated with the data input port.
[2] V_{CCO} is the supply voltage associated with the output port.



Test data is given in [Table 10](#).
 R_L = Load resistance.
 C_L = Load capacitance including jig and probe capacitance.
 R_T = Termination resistance.
 V_{EXT} = External voltage for measuring switching times.

Fig 8. Test circuit for measuring switching times

Table 10. Test data

Supply voltage	Input		Load		V_{EXT}		
$V_{CC(A)}, V_{CC(B)}$	V_I ^[1]	$t_r = t_f$	C_L	R_L ^[2]	t_{PLH}, t_{PHL}	t_{PZH}, t_{PHZ}	t_{PZL}, t_{PLZ} ^[3]
1.1 V to 3.6 V	V_{CCI}	≤ 3.0 ns	5 pF, 10 pF, 15 pF and 30 pF	5 kΩ or 1 MΩ	open	GND	$2 \times V_{CCO}$

[1] V_{CCI} is the supply voltage associated with the data input port.
[2] For measuring enable and disable times $R_L = 5$ kΩ, for measuring propagation delays, setup and hold times and pulse width $R_L = 1$ MΩ.
[3] V_{CCO} is the supply voltage associated with the output port.

13. Application information

13.1 Unidirectional logic level-shifting application

The circuit given in [Figure 9](#) is an example of the 74AUP1T45 being used in an unidirectional logic level-shifting application.

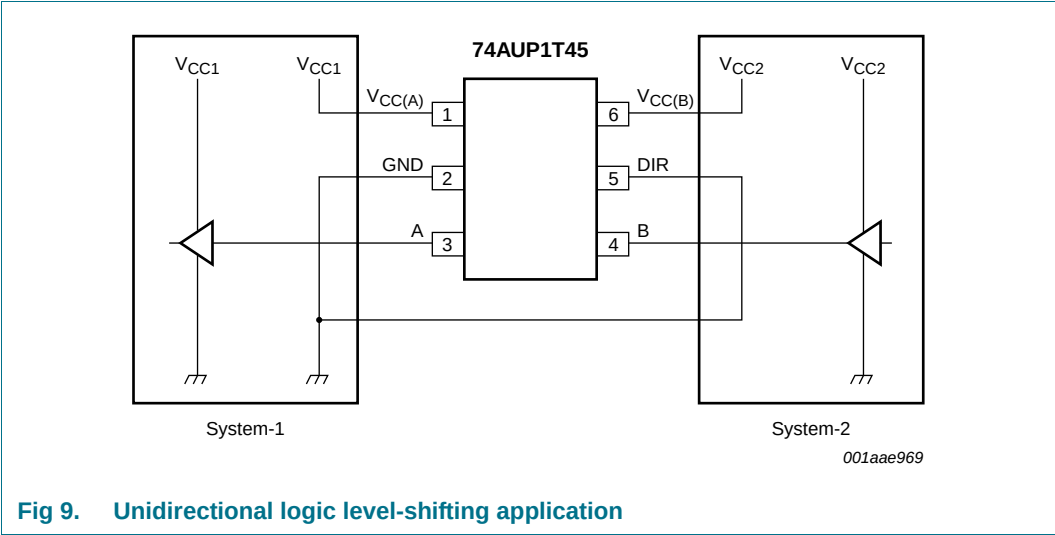


Table 11. Description unidirectional logic level-shifting application

Pin	Name	Function	Description
1	V _{CC(A)}	V _{CC1}	supply voltage of system-1 (1.1 V to 3.6 V)
2	GND	GND	device ground (0 V)
3	A	OUT	output level depends on V _{CC1} voltage
4	B	IN	input threshold value depends on V _{CC2} voltage
5	DIR	DIR	the GND (LOW level) determines B port to A port direction
6	V _{CC(B)}	V _{CC2}	supply voltage of system-2 (1.1 V to 3.6 V)

13.2 Bidirectional logic level-shifting application

Figure 10 shows the 74AUP1T45 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable (OE) pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.

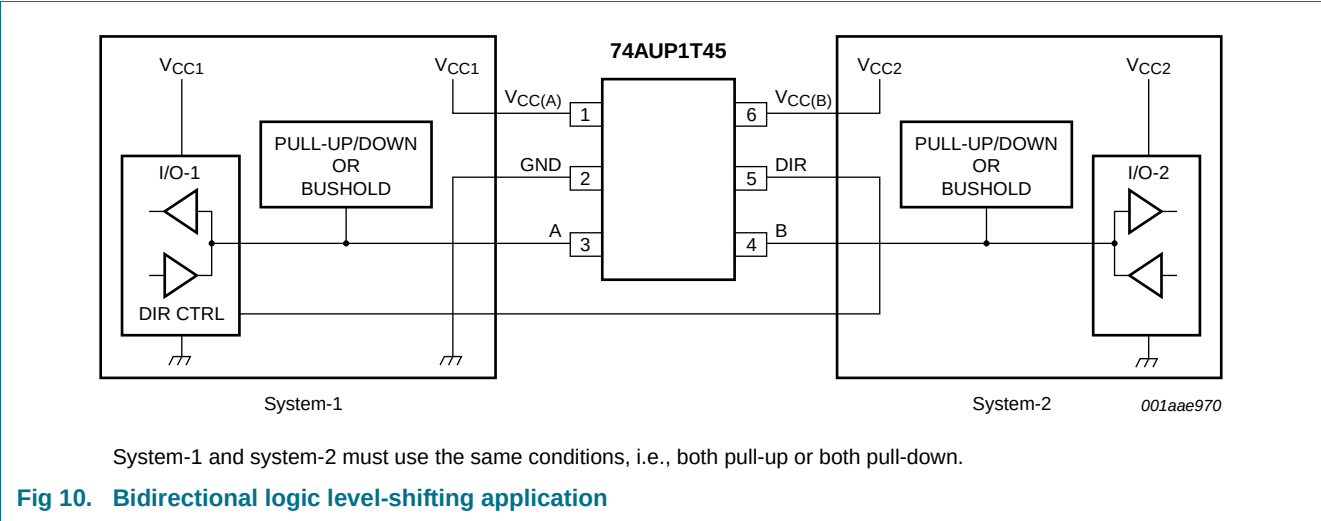


Table 12 gives a sequence that will illustrate data transmission from system-1 to system-2 and then from system-2 to system-1.

Table 12. Description bidirectional logic level-shifting application^{[1][2]}

State	DIR CTRL	I/O-1	I/O-2	Description
1	H	output	input	system-1 data to system-2
2	H	Z	Z	system-2 is getting ready to send data to system-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on the pull-up or pull-down.
3	L	Z	Z	DIR bit is flipped. I/O-1 and I/O-2 still are disabled. The bus-line state depends on the pull-up or pull-down.
4	L	input	output	system-2 data to system-1

[1] System-1 and system-2 must use the same conditions, i.e., both pull-up or both pull-down.

[2] H = HIGH voltage level;
L = LOW voltage level;
Z = high-impedance OFF-state.

13.3 Power-up considerations

A proper power-up sequence always should be followed to avoid excessive supply current, bus contention, oscillations, or other anomalies. Take the following precautions to guard against such power-up problems:

- Connect ground before any supply voltage is applied.
- Power-up $V_{CC(A)}$.
- $V_{CC(B)}$ can be ramped up along with or after $V_{CC(A)}$.

13.4 Enable times

Calculate the enable times for the 74AUP1T45 using the following formulas:

- $t_{PZH} \text{ (DIR to A)} = t_{PLZ} \text{ (DIR to B)} + t_{PLH} \text{ (B to A)}$
- $t_{PZL} \text{ (DIR to A)} = t_{PHZ} \text{ (DIR to B)} + t_{PHL} \text{ (B to A)}$
- $t_{PZH} \text{ (DIR to B)} = t_{PLZ} \text{ (DIR to A)} + t_{PLH} \text{ (A to B)}$
- $t_{PZL} \text{ (DIR to B)} = t_{PHZ} \text{ (DIR to A)} + t_{PHL} \text{ (A to B)}$

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74AUP1T45 initially is transmitting from A to B, then the DIR bit is switched, the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.

14. Package outline

Plastic surface-mounted package; 6 leads

SOT363

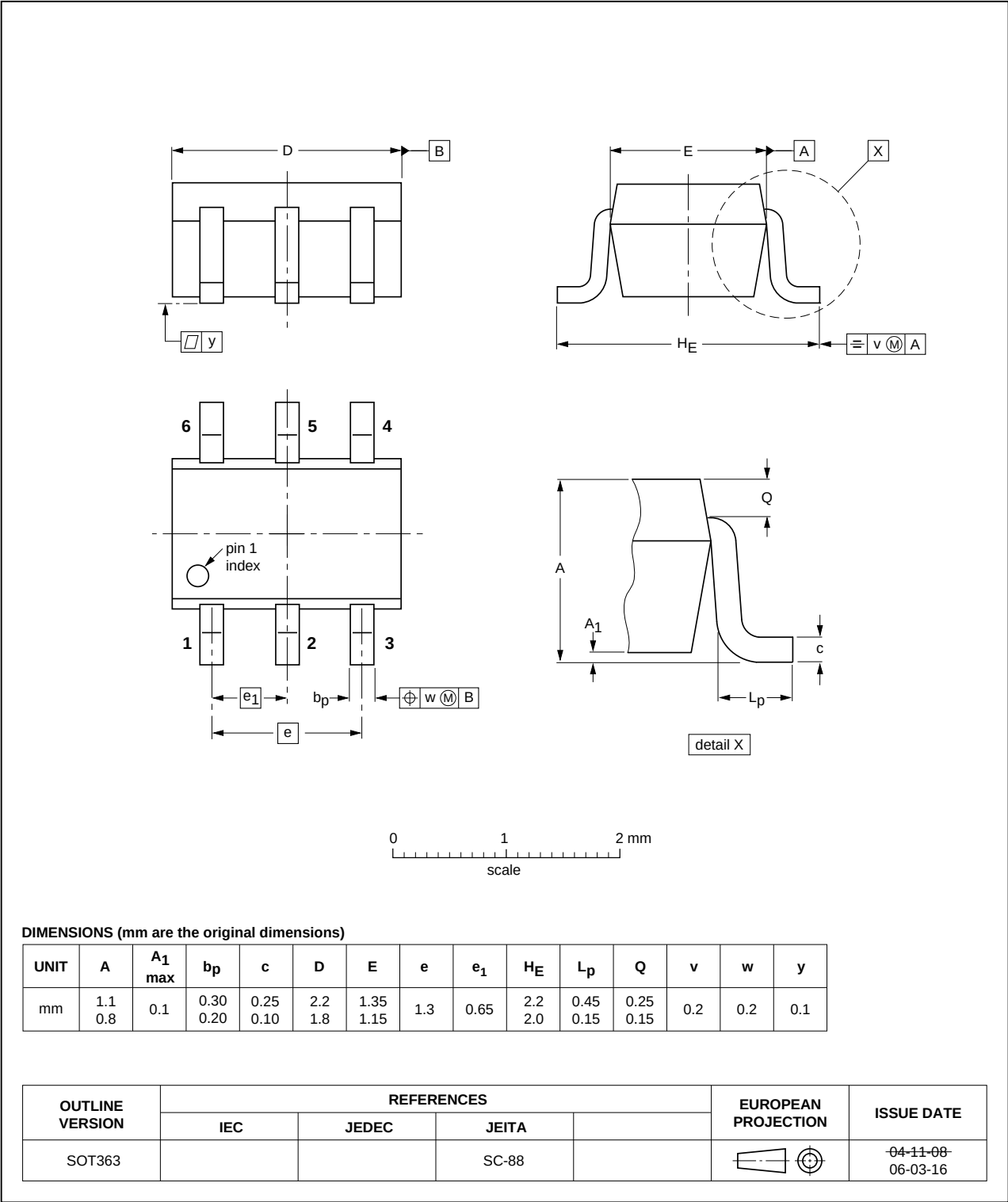


Fig 11. Package outline SOT363 (SC-88)

XSON6: plastic extremely thin small outline package; no leads; 6 terminals; body 1 x 1.45 x 0.5 mm

SOT886

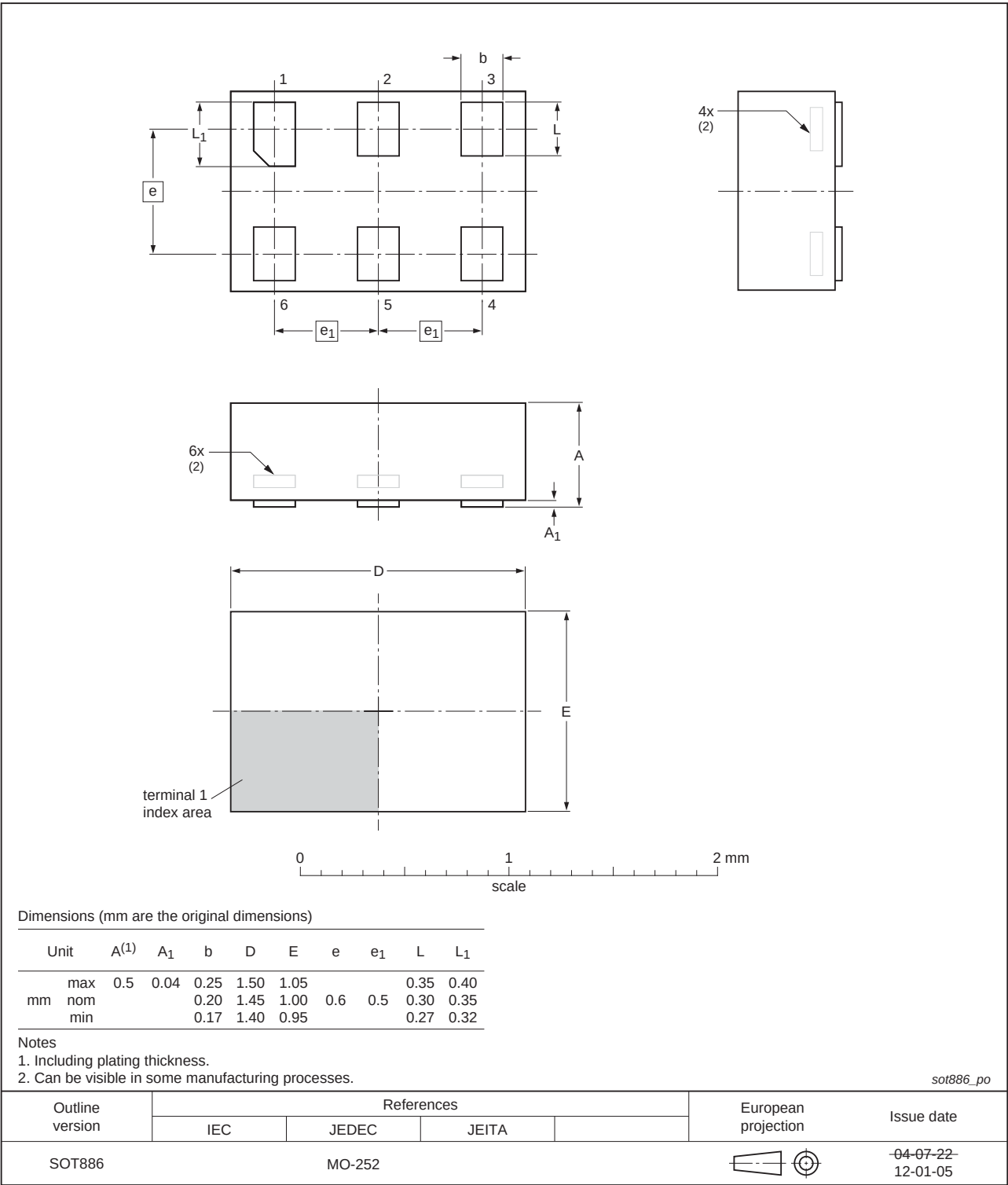


Fig 12. Package outline SOT886 (XSON6)

XSON6: plastic extremely thin small outline package; no leads; 6 terminals; body 1 x 1 x 0.5 mm

SOT891

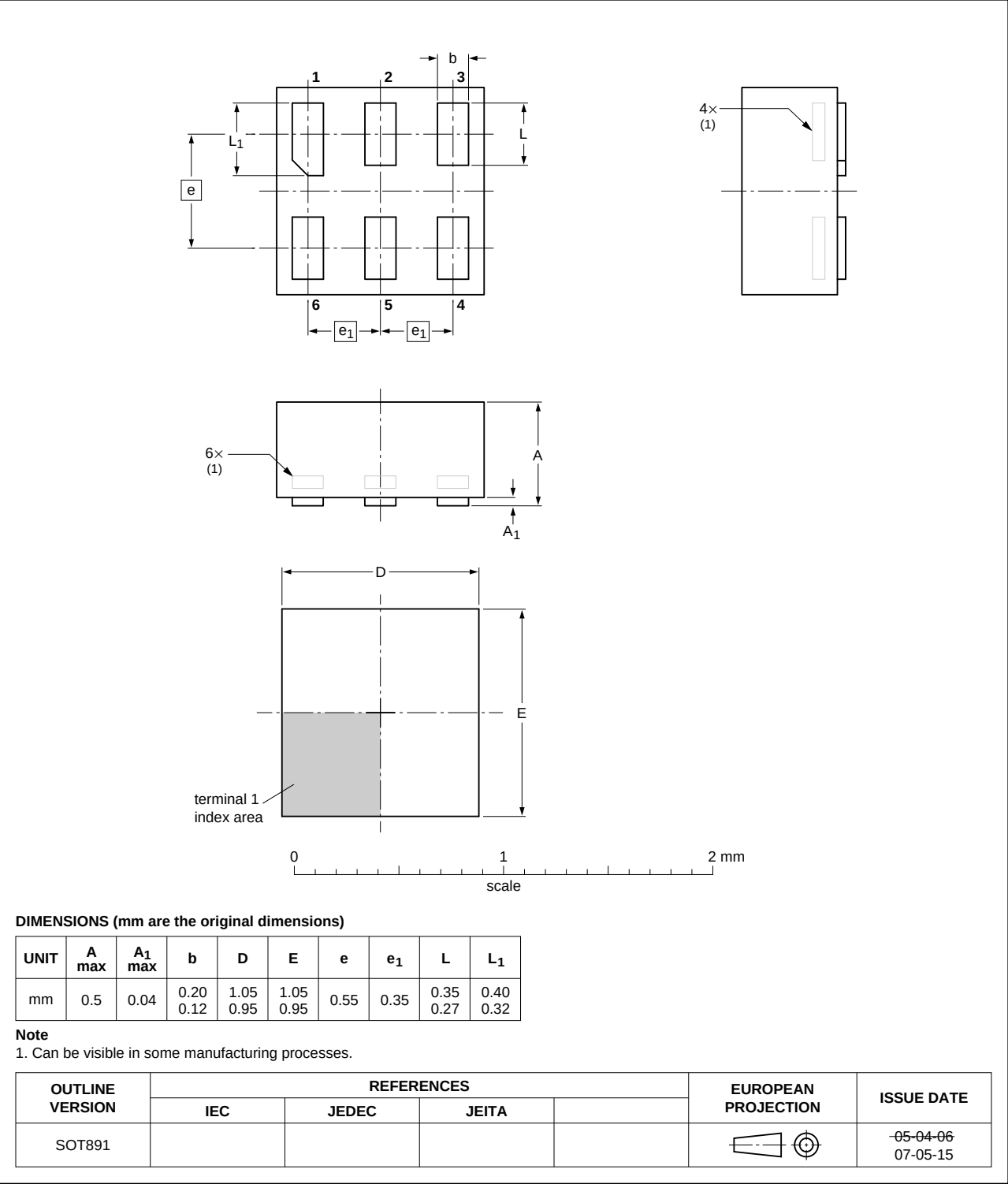
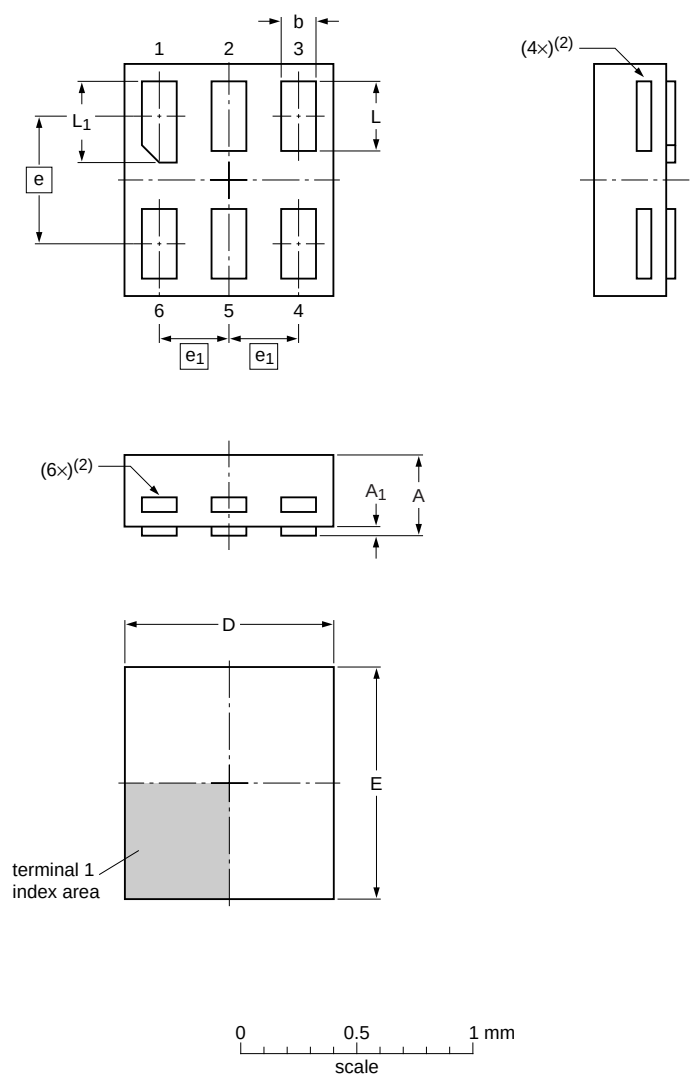


Fig 13. Package outline SOT891 (XSON6)

XSON6: extremely thin small outline package; no leads;
6 terminals; body 0.9 x 1.0 x 0.35 mm

SOT1115



Dimensions

Unit	A ⁽¹⁾	A ₁	b	D	E	e	e ₁	L	L ₁
mm	max	0.35	0.04	0.20	0.95	1.05		0.35	0.40
	nom			0.15	0.90	1.00	0.55	0.30	0.35
	min			0.12	0.85	0.95		0.27	0.32

Note

- 1. Including plating thickness.
- 2. Visible depending upon used manufacturing technology.

sot1115_po

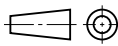
Outline version	References				European projection	Issue date
	IEC	JEDEC	JEITA			
SOT1115						10-04-02 10-04-07

Fig 14. Package outline SOT1115 (XSON6)

XSON6: extremely thin small outline package; no leads;
6 terminals; body 1.0 x 1.0 x 0.35 mm

SOT1202

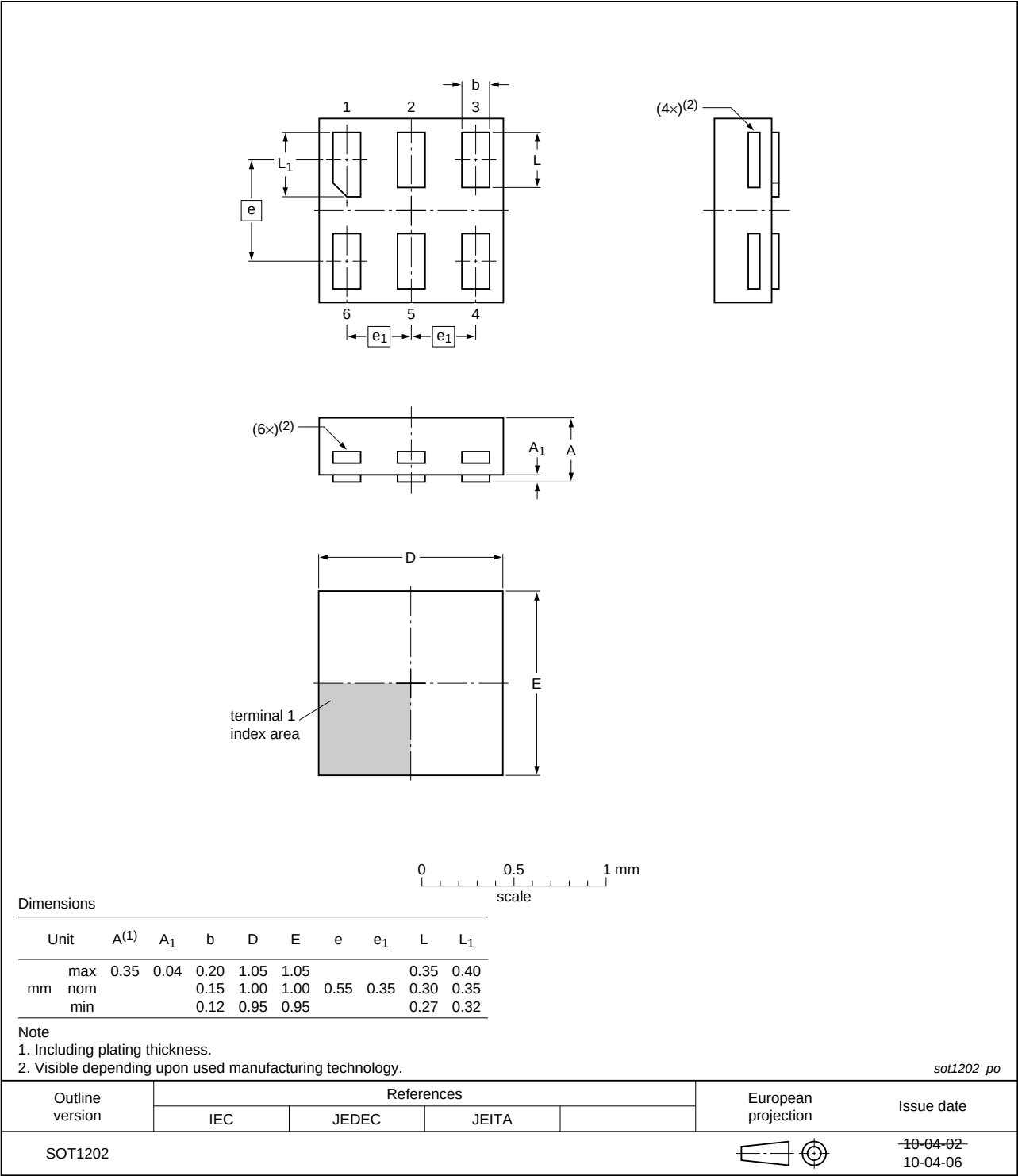


Fig 15. Package outline SOT1202 (XSON6)

15. Abbreviations

Table 13. Abbreviations

Acronym	Description
CDM	Charged Device Model
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

16. Revision history

Table 14. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74AUP1T45 v.5	20120809	Product data sheet	-	74AUP1T45 v.4
Modifications:	• Package outline drawing of SOT886 (Figure 12) modified.			
74AUP1T45 v.4	20111128	Product data sheet	-	74AUP1T45 v.3
Modifications:	• Legal pages updated.			
74AUP1T45 v.3	20101104	Product data sheet	-	74AUP1T45 v.2
74AUP1T45 v.2	20090803	Product data sheet	-	74AUP1T45 v.1
74AUP1T45 v.1	20061018	Product data sheet	-	-

17. Legal information

17.1 Data sheet status

Document status ^{[1][2]}	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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