

Genum Products

Key Features

- SMPTE ST 2081, ST 424, ST 292, and ST 259-C compliant
- Supports retiming data at rates of 125Mb/s, 270Mb/s, 1.485 and 1.485/1.001Gb/s, 2.97 and 2.97/1.001Gb/s, 5.94 and 5.94/1.001Gb/s
- Supports retiming of DVB-ASI signals
- Automatic or Manual Rate Selection
 - ◆ Detected rate indication in Auto Mode
- 4:1 input selector patented technology
- Option of two reclocked data outputs
- Four configurable GPIO pins with ability to output device status, including:
 - ◆ Lock Detect
 - ◆ Loss of Signal (LOS)
 - ◆ Low/High bit-rate indication for slew-rate control of SDI cable drivers
- On-chip 100Ω differential input and output termination
- Bypass support for rates up to 5940Mb/s
 - ◆ Manual Bypass function
 - ◆ Configurable automatic Bypass when not locked
- Option to use external reference or operate referenceless
- Cascading reference buffer supports multiple reclockers using a single reference source
- Input signal equalization and output signal de-emphasis to compensate for trace dielectric losses
- Single power supply operation at 1.8V
- 130mW typical power consumption (150mW with second output enabled)
- Pb-free and RoHS compliant
- Operating temperature range: -40°C to 85°C

Applications

- SMPTE ST 2081, SMPTE ST 424, SMPTE ST 292, SMPTE ST 259-C coaxial cable serial digital interfaces
- EN50083-9 DVB-ASI interfaces
- MADI standard

Description

The GS6150 is a low-power, multi-rate serial digital reclocker designed to automatically recover the embedded clock from a digital video signal and re-time the incoming video data.

The GS6150 will recover the embedded clock signal and re-time the data from 6G UHD-SDI signals compliant with SMPTE ST 2081. In addition, it can also re-time SMPTE ST 259-C, SMPTE ST 292, SMPTE ST 424 or DVB-ASI compliant digital video signals as well as MADI audio streams.

The GS6150 features four high-speed differential signal inputs feeding a 4:1 input selector. Input termination is on-chip for seamless matching to 100Ω differential transmission lines. The input selector is a component of a video switching system with tightly constrained timing requirements.

The GS6150 includes programmable trace equalization to compensate for high-frequency losses associated with board-level interconnect.

Two CML outputs interface seamlessly to devices with a CML input reference between 1.2V and 2.5V. Programmable output swing and de-emphasis provide flexibility in managing signal integrity of the output signals.

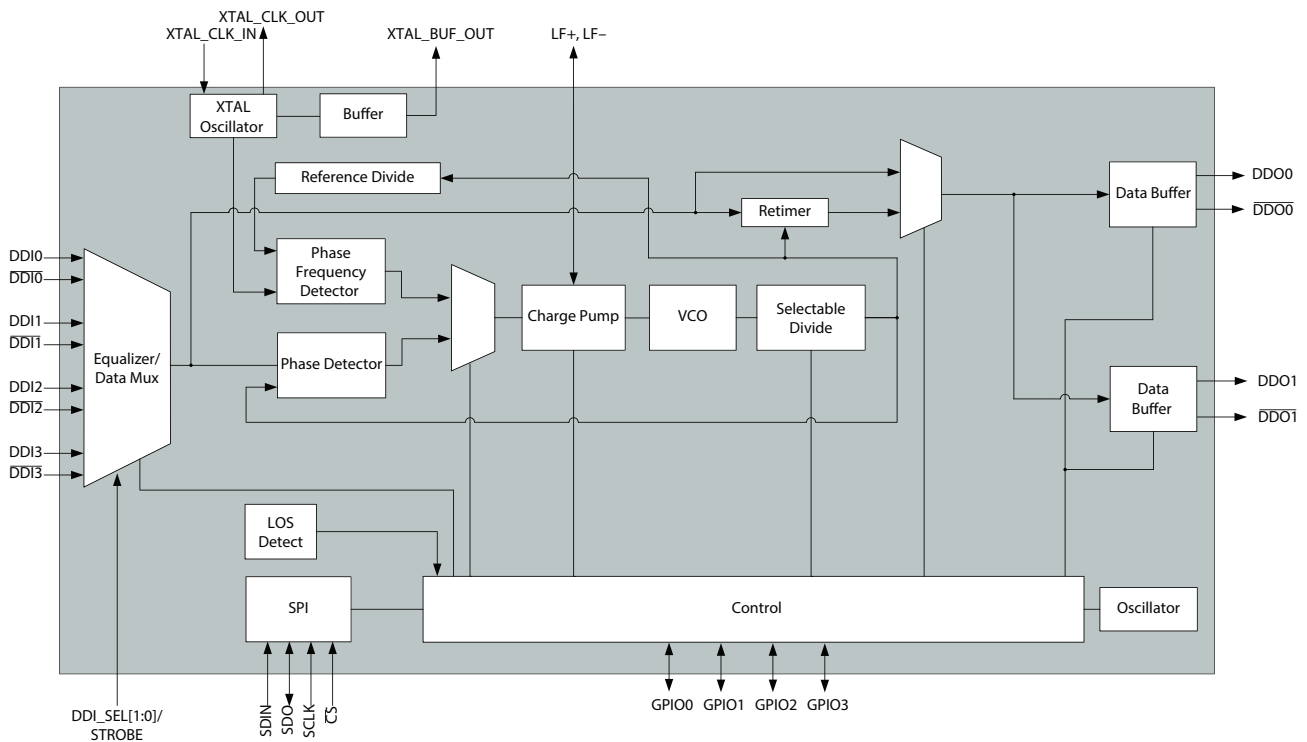
The GS6150 can operate in either automatic rate detection or manual rate selection mode. In auto mode the device will automatically detect and lock onto incoming data signals at any supported rate.

The device can operate without an external 27MHz frequency reference. For applications which require rapid signal lock, an external 27MHz reference may be used to set the VCO frequency when not locked to the input signal. The presence of an external reference crystal is automatically detected by the device.

In systems that require passing of non-supported data rates, the GS6150 can be configured to either automatically or manually enter a bypass mode in order to pass the signal without relocking.

A four-wire serial Genum Serial Peripheral Interface (GSPI) facilitates configuration and status monitoring of the device. Multiple GS6150 devices can be daisy-chained together with a single 4-pin connection to the host system.

This device is Pb-free, and the encapsulation compound does not contain halogenated flame retardant. This component and all homogenous sub-components are RoHS compliant.



GS6150 Functional Block Diagram

Revision History

| Version | ECO | PCN | Date | Changes and/or Modifications |
|---------|--------|-----|----------------|---|
| 2 | 024967 | — | March 2015 | Updated Table 2-2 and Table 2-3 . Updated Section 4.11 and Section 5 . Updated to Final Data Sheet. |
| 1 | 022115 | — | September 2014 | Changed product title. Updated Table 5-1 format. Updates throughout Table 2-2 and Table 2-3 . Added Section 4.5.5 . Updated Table 5-1 . |
| 0 | 016784 | — | December 2013 | New Document |

Contents

| | |
|---|----|
| 1. Pin Out | 5 |
| 1.1 Pin Assignment | 5 |
| 1.2 Pin Descriptions | 6 |
| 2. Electrical Characteristics..... | 10 |
| 2.1 Absolute Maximum Ratings | 10 |
| 2.2 DC Electrical Characteristics | 10 |
| 2.3 AC Electrical Characteristics | 12 |
| 3. Input/Output Circuits..... | 15 |
| 4. Detailed Description..... | 17 |
| 4.1 Serial Data Inputs | 17 |
| 4.1.1 Input Trace Equalization | 17 |
| 4.1.2 Input Selection | 17 |
| 4.2 Reference Clock | 19 |
| 4.3 Signal Monitoring | 19 |
| 4.3.1 Loss of Signal Detection..... | 19 |
| 4.3.2 Lock Detection | 21 |
| 4.3.3 Rate Detection..... | 22 |
| 4.3.4 Low/High Bit Rate Detection for Slew Rate Control | 23 |
| 4.4 Low Power Modes | 23 |
| 4.5 Serial Data Output | 24 |
| 4.5.1 Output Impedance | 24 |
| 4.5.2 Output Signal Interface Levels | 24 |
| 4.5.3 Adjustable Output Swing | 24 |
| 4.5.4 Output De-emphasis..... | 25 |
| 4.5.5 Output Common Mode Voltage | 26 |
| 4.6 Output Mute, Disable, and Data Selection | 26 |
| 4.7 Bypass Mode | 27 |
| 4.8 DVB-ASI | 27 |

| | |
|---|----|
| 4.9 Device Power Up | 27 |
| 4.9.1 Power on Reset (POR) | 27 |
| 4.9.2 Reset Pin (RST) | 27 |
| 4.10 GPIO Pins Configuration | 27 |
| 4.11 GSPI Host Interface | 29 |
| 4.11.1 \overline{CS} Pin..... | 29 |
| 4.11.2 SDIN Pin..... | 29 |
| 4.11.3 SDOOUT Pin | 29 |
| 4.11.4 SCLK Pin..... | 31 |
| 4.11.5 Command Word Description..... | 31 |
| 4.11.6 GSPI Transaction Timing | 34 |
| 4.11.7 Single Read/Write Access..... | 36 |
| 4.11.8 Auto-increment Read/Write Access | 37 |
| 4.11.9 Setting a Device Unit Address..... | 38 |
| 4.11.10 Default GSPI Operation | 39 |
| 5. Host Interface Register Map..... | 41 |
| 6. Typical Application Circuit | 60 |
| 7. Package and Ordering Information | 61 |
| 7.1 Package Dimensions | 61 |
| 7.2 Recommended PCB Footprint | 62 |
| 7.3 Packaging Data | 62 |
| 7.4 Marking Diagram | 63 |
| 7.5 Solder Reflow Profile | 63 |
| 7.6 Ordering Information | 63 |

1. Pin Out

1.1 Pin Assignment

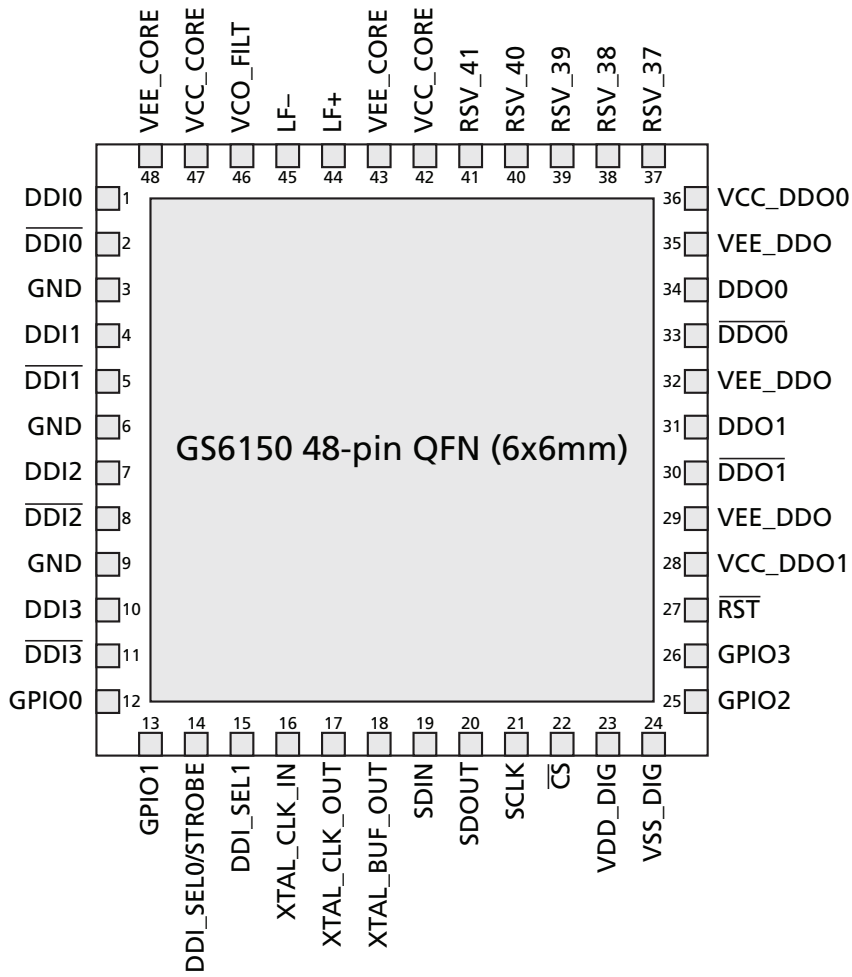


Figure 1-1: GS6150 Pin Out

1.2 Pin Descriptions

Table 1-1: GS6150 Pin Descriptions

| Pin Number | Name | Type | Description |
|------------|--------------------------------|----------------------|--|
| 1, 2 | DDI0, $\overline{\text{DDI0}}$ | Input | Serial Digital Differential Input 0. |
| 3, 6, 9 | GND | Power | Input channel isolation. Connect to ground or leave unconnected. |
| 4, 5 | DDI1, $\overline{\text{DDI1}}$ | Input | Serial Digital Differential Input 1. |
| 7, 8 | DDI2, $\overline{\text{DDI2}}$ | Input | Serial Digital Differential Input 2. |
| 10, 11 | DDI3, $\overline{\text{DDI3}}$ | Input | Serial Digital Differential Input 3. |
| 12 | GPIO0 | Digital Input/Output | <p>Multi-function Control/Status Input/Output 0.</p> <p>Signal options are:</p> <ul style="list-style-type: none"> LOS (output; default) LOCKED LBR_HBR RATE_DET0 RATE_DET1 RATE_DET2 LOCKED_125M LOCKED_270M LOCKED_1G485 LOCKED_2G97 LOCKED_5G94 RATE_CHANGE DDO0_DISABLE DDO1_DISABLE <p>This pin is configured using the GPIO0_SELECT and GPIO0_IO_SELECT bits in the GPIO_CONTROL_REG_0 register.</p> |
| 13 | GPIO1 | Digital Input/Output | <p>Multi-function Control/Status Input/Output 1.</p> <p>Signal options are:</p> <ul style="list-style-type: none"> LOS LOCKED (output; default) LBR_HBR RATE_DET0 RATE_DET1 RATE_DET2 LOCKED_125M LOCKED_270M LOCKED_1G485 LOCKED_2G97 LOCKED_5G94 RATE_CHANGE DDO0_DISABLE DDO1_DISABLE <p>This pin is configured using the GPIO1_SELECT and GPIO1_IO_SELECT bits in the GPIO_CONTROL_REG_0 register.</p> |

Table 1-1: GS6150 Pin Descriptions (Continued)

| Pin Number | Name | Type | Description |
|------------|------------------------------|----------------|---|
| 14, 15 | DDI_SELO/STROBE, DDI_SEL1 | Logic Input | Input selection control. Used to select the high-speed input for processing through the device. Refer to Table 4-1 for details on input selection. |
| 16 | XTAL_CLK_IN | Input | Reference Crystal Pin/27MHz clock input. Connect to an external circuit as shown in Figure 6-1: GS6150 Typical Application Circuit or to a digital clock source (XTAL_BUF_OUT of another GS6150 or GS6151). Connect to ground if operating referenceless. |
| 17 | XTAL_CLK_OUT | Output | Reference Crystal Pin. Connect to a external circuit as shown in Figure 6-1: GS6150 Typical Application Circuit , or leave unconnected if XTAL_CLK_IN is driven by an external clock source or if XTAL_CLK_IN is connected to ground (referenceless). |
| 18 | XTAL_BUF_OUT | Output | Buffered clock reference output. Leave unconnected if not used to drive 27MHz clock input of another device. |
| 19 | SDIN | Digital Input | Serial digital data input for the Gennum Serial Peripheral Interface (GSPI) host control/status port. Refer to 4.11 GSPI Host Interface for more details. |
| 20 | SDOUT | Digital Output | Serial digital data output for the Gennum Serial Peripheral Interface (GSPI) host control/status port. Refer to 4.11 GSPI Host Interface for more details. |
| 21 | SCLK | Digital Input | Burst-mode clock input for the Gennum Serial Peripheral Interface (GSPI) host control/status port. Refer to 4.11 GSPI Host Interface for more details. |
| 22 | \overline{CS} | Digital Input | Chip select input for the Gennum Serial Peripheral Interface (GSPI) host control/status port. Active-low input. Refer to 4.11 GSPI Host Interface for more details. |
| 23 | VDD_DIG | Power | Most positive power supply for the internal logic Connect to 1.8V. |
| 24 | VSS_DIG | Power | Most negative power supply for the internal logic Connect to ground. |

Table 1-1: GS6150 Pin Descriptions (Continued)

| Pin Number | Name | Type | Description |
|------------|---------------------------------|----------------------|---|
| 25 | GPIO2 | Digital Input/Output | <p>Multi-function Control/Status Input/Output 2.</p> <p>Signal options are:</p> <p>LOS LOCKED LBR_HBR (output; default) RATE_DET0 RATE_DET1 RATE_DET2 LOCKED_125M LOCKED_270M LOCKED_1G485 LOCKED_2G97 LOCKED_5G94 RATE_CHANGE DDO0_DISABLE DDO1_DISABLE</p> <p>This pin is configured using the GPIO2_SELECT and GPIO2_IO_SELECT bits in the GPIO_CONTROL_REG_1 register.</p> |
| 26 | GPIO3 | Digital Input/Output | <p>Multi-function Control/Status Input/Output 3.</p> <p>Signal options are:</p> <p>LOS LOCKED LBR_HBR RATE_DET0 RATE_DET1 RATE_DET2 LOCKED_125M LOCKED_270M LOCKED_1G485 LOCKED_2G97 LOCKED_5G94 RATE_CHANGE DDO0_DISABLE DDO1_DISABLE (input; default)</p> <p>This pin is configured using the GPIO3_SELECT and GPIO3_IO_SELECT bits in the GPIO_CONTROL_REG_1 register.</p> |
| 27 | $\overline{\text{RST}}$ | Digital Input | Reset pin. If set LOW, all blocks set to default conditions and inputs/ outputs set to high impedance. If HIGH, normal operation of the device resumes. By default, internally pulled HIGH. |
| 28 | VCC_DDO1 | Power | Most positive power supply connection for the DDO1/ $\overline{\text{DDO1}}$ output driver. Connect to any voltage between 1.2V and 2.5V. |
| 29, 32, 35 | VEE_DDO | Power | Most negative power supply connections for the output drivers. Connect to ground. |
| 30, 31 | $\overline{\text{DDO1}}$, DDO1 | Output | Differential serial data output 1. |
| 33, 34 | $\overline{\text{DDO0}}$, DDO0 | Output | Differential serial data output 0. |
| 36 | VCC_DDO0 | Power | Most positive power supply connection for the DDO0/ $\overline{\text{DDO0}}$ output driver. Connect to any voltage between 1.2V and 2.5V. |

Table 1-1: GS6150 Pin Descriptions (Continued)

| Pin Number | Name | Type | Description |
|------------|----------------|------------------|---|
| 37 | RSV_37 | Power Decoupling | Connect through decoupling capacitor to ground. |
| 38 | RSV_38 | Power | Connect to 1.8V. |
| 39 | RSV_39 | Power | Connect to ground. |
| 40, 41 | RSV_40, RSV_41 | Input | Leave unconnected. |
| 42 | VCC_CORE | Power | Most positive power supply connection to the analog core Connect to 1.8V. |
| 43 | VEE_CORE | Power | Most negative power supply connection to the analog core Connect to ground. |
| 44 | LF+ | Passive | Connect to LF- through C_{LF} Refer to Figure 6-1: GS6150 Typical Application Circuit . |
| 45 | LF- | Passive | Connect to LF+ through C_{LF} Refer to Figure 6-1: GS6150 Typical Application Circuit . |
| 46 | VCO_FILT | Power | External decoupling for the VCO. Refer to Figure 6-1: GS6150 Typical Application Circuit . |
| 47 | VCC_CORE | Power | Most positive power supply connection for the analog core Connect to 1.8V. |
| 48 | VEE_CORE | Power | Most negative power supply connection to the analog core Connect to ground. |
| — | Center Pad | Power | Ground pad on bottom of package. |

2. Electrical Characteristics

2.1 Absolute Maximum Ratings

Table 2-1: Absolute Maximum Ratings

| Parameter | Value |
|---|---|
| Supply Voltage – Core (VCC_CORE, VDD_DIG) | -0.5 to +2.1V _{DC} |
| Supply Voltage – Output Driver (VCC_DDO0, VCC_DDO1) | -0.5 to +2.8V _{DC} |
| Input ESD Voltage | 4kV |
| Storage Temperature Range (T _S) | -50°C to +125°C |
| Operating Temperature Range (T _A) | -40°C to +85°C |
| Input Voltage Range (any input pin) | -0.3 to (V _{CC_CORE} + 0.3)V _{DC} |
| Solder Reflow Temperature | +260°C |

Note: Absolute Maximum Ratings are those values beyond which damage may occur. Functional operation outside of the ranges shown in the AC/DC electrical characteristics tables is not guaranteed.

2.2 DC Electrical Characteristics

Table 2-2: DC Electrical Characteristics

VCC_CORE, VDD_DIG = +1.8V ± 5%, T_A = -40°C to +85°C unless otherwise specified

| Parameter | Symbol | Conditions | Min | Typ | Max | Units | Notes |
|---|--|------------|-------|-----|-------|-------|-------|
| Supply Voltage – Core (VCC_CORE, VDD_DIG) | V _{CC_CORE} , V _{DD_DIG} | — | 1.710 | 1.8 | 1.890 | V | |
| Supply Voltage – Output Driver (VCC_DDO0, VCC_DDO1) | V _{CC_DDO0} , V _{CC_DDO1} | — | 1.140 | — | 2.625 | V | |

Table 2-2: DC Electrical Characteristics (Continued)VCC_CORE, VDD_DIG = +1.8V ± 5%, T_A = -40°C to +85°C unless otherwise specified

| Parameter | Symbol | Conditions | Min | Typ | Max | Units | Notes |
|----------------------------------|--|--|-----|-----|--------------------------------|-------|-------|
| Power | P _D | Data Rate 6G, DDO1/DDO1 disabled | — | 140 | 185 | mW | 1, 2 |
| | | Data Rate <6G, DDO1/DDO1 disabled | — | 130 | 170 | mW | 1, 2 |
| | | Data Rate 6G, Default Settings, DDO1/DDO1 enabled | — | 210 | 280 | mW | 3, 4 |
| | | Data Rate <6G, Default Settings, DDO1/DDO1 enabled | — | 190 | 255 | mW | 3, 4 |
| | | Maximum Supply and Power Settings | — | 280 | 360 | mW | 5 |
| Power (Sleep operation) | P _{SLEEP} | — | — | 20 | 35 | mW | |
| Power (Standby operation) | P _{STANDBY} | — | — | 80 | 110 | mW | |
| Supply Current - Output Driver | I _{CC_DDO0} I _{CC_DDO1} | Output Swing Register Setting = 0000 _b | — | 4.8 | 7 | mA | 6, 7 |
| | | Output Swing Register Setting = 0100 _b | — | 7.5 | 12 | mA | 6, 7 |
| | | Output Swing Register Setting = 1100 _b | — | 15 | 22 | mA | 6, 7 |
| Supply Current - Core | I _{CC_CORE} | Output De-emphasis Disabled Data Rate 6G | — | 82 | — | mA | 8 |
| | | Output De-emphasis Disabled Data Rate 3G | — | 74 | — | mA | 8 |
| | | Output De-emphasis Enabled Data Rate 6G | — | 90 | — | mA | 8 |
| | | Output De-emphasis Enabled Data Rate 3G | — | 81 | — | mA | 8 |
| Supply Current - Digital | I _{CC_DIG} | External Crystal Referenced | — | 7 | 12 | mA | |
| Serial Input Termination | | Differential | 75 | 100 | 125 | Ω | |
| Serial Output Termination | | Differential | 75 | 100 | 125 | Ω | |
| Serial Input Common Mode Voltage | V _{CMIN} | — | 0.9 | — | V _{CC_CORE} - 50mV | V | 9, 10 |

Table 2-2: DC Electrical Characteristics (Continued)VCC_CORE, VDD_DIG = +1.8V ± 5%, T_A = -40°C to +85°C unless otherwise specified

| Parameter | Symbol | Conditions | Min | Typ | Max | Units | Notes |
|---|-----------------|------------------------|-------------------|-----|------------------|-------|-------|
| Input Voltage - Digital Pins (\overline{CS} , SDIN, CLK, GPIO[0:3]) | V _{IH} | — | 0.65* VDD_DIG | — | VDD_DIG | V | |
| | V _{IL} | — | 0 | — | 0.35* VDD_DIG | V | |
| Output Voltage - Digital Pins (SDOUT, GPIO[0:3]) | V _{OH} | I _{OH} = -2mA | VDD_DIG - 0.45 | — | — | V | |
| | V _{OL} | I _{OL} = 2mA | — | — | 0.45 | V | |

Notes:

1. Normal operation in referenceless mode, minimum output swing with de-emphasis disabled
2. VCC_DDO0/1 = 1.2V
3. The swing is default and de-emphasis is on
4. VCC_DDO0/1 = 1.8V
5. DDO0/ $\overline{DDO0}$ and DDO1/ $\overline{DDO1}$ set to maximum swing setting, external crystal reference used
6. Consumption per enabled DDO output
7. Refer to Table 4-3 for the exact register settings for each ΔV_{DDO} output swing listed
8. For two enabled outputs
9. Maximum input voltage level = 1.8V ± 5%
10. Up to a maximum swing of 800mV

2.3 AC Electrical Characteristics

Table 2-3: AC Electrical CharacteristicsVCC_CORE, VDD_DIG = +1.8V ± 5%, T_A = -40°C to +85°C unless otherwise specified

| Parameter | Symbol | Conditions | Min | Typ | Max | Units | Notes |
|-------------------------------|----------------------|---|-----|-----|------|-------------------|-------|
| Input Data Rate (Bypass) | DR _{BYPASS} | Bypass mode enabled | 3 | — | 5940 | Mb/s | 1 |
| Input Sensitivity | ΔV_{SDI} | Differential | 200 | — | 800 | mV _{ppd} | |
| Output Voltage Swing | ΔV_{DDO} | Output Swing Register Setting = 0100 _b | 310 | 410 | 510 | mV _{ppd} | 2 |
| | | Output Swing Register Setting = 1100 _b | 600 | 800 | 1000 | mV _{ppd} | 2 |
| Serial Input Jitter Tolerance | IJT | Square wave modulation | 0.8 | — | — | UI | |
| PLL Lock Time — Asynchronous | t _{ALOCK} | Referenceless | — | — | 50 | ms | |
| | | With External Reference (MADI enabled) | — | — | 30 | ms | |
| | | With External Reference (MADI disabled) | — | — | 20 | ms | |

Table 2-3: AC Electrical Characteristics (Continued)

VCC_CORE, VDD_DIG = +1.8V ± 5%, T_A = -40°C to +85°C unless otherwise specified

| Parameter | Symbol | Conditions | Min | Typ | Max | Units | Notes |
|---|-----------------------------|--|-----|------|------|-------------------|-------|
| PLL Lock Time — Synchronous | t _{SLOCK} | Referenceless | — | — | 10 | µs | |
| | | With External Reference | — | — | 10 | µs | |
| Serial Data (DDO0 and DDO1) Output Rise And Fall Time | t _{riseDDO} | 20% ~ 80% rising edge into 50Ω load | — | — | 70 | ps | |
| | t _{fallDDO} | 20% ~ 80% falling edge into 50Ω load | — | — | 70 | ps | |
| Rise And Fall Time Mismatch (DDO0 and DDO1) | — | — | — | — | 15 | ps | |
| Duty Cycle Distortion (DDO0 and DDO1) | — | Data Rate 6G | — | — | 10 | % | |
| | — | Data Rate < 6G | — | — | 5 | % | |
| Serial Data Output Jitter Intrinsic | t _{OJ(125Mb/s)} | BW = Nominal PRN 2 ²³ - 1 test pattern | — | 0.02 | 0.03 | UI _{p-p} | 3, 4 |
| | t _{OJ(270Mb/s)} | | — | 0.02 | 0.03 | UI _{p-p} | 3, 4 |
| | t _{OJ(1485Mb/s)} | | — | 0.03 | 0.06 | UI _{p-p} | 3, 4 |
| | t _{OJ(2970Mb/s)} | | — | 0.04 | 0.09 | UI _{p-p} | 3, 4 |
| | t _{OJ(5940Mb/s)} | | — | 0.07 | 0.13 | UI _{p-p} | 3, 4 |
| | t _{OJ(BYPASS)} | | — | 0.06 | 0.09 | UI _{p-p} | 3, 4 |
| PLL Loop Bandwidth | BW _{LOOP(125Mb/s)} | PLL_LOOP_BANDWIDTH = 00001 | — | 37 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 00010 | — | 74 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 00100 (default) | — | 148 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 01000 | — | 296 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 10000 | — | 590 | — | kHz | |
| | BW _{LOOP(270Mb/s)} | PLL_LOOP_BANDWIDTH = 00001 | — | 80 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 00010 | — | 160 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 00100 (default) | — | 320 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 01000 | — | 640 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 10000 | — | 1.28 | — | MHz | |

Table 2-3: AC Electrical Characteristics (Continued)

VCC_CORE, VDD_DIG = +1.8V ± 5%, T_A = -40°C to +85°C unless otherwise specified

| Parameter | Symbol | Conditions | Min | Typ | Max | Units | Notes |
|--------------------|------------------------------|--------------------------------------|-----|------|-----|-------|-------|
| PLL Loop Bandwidth | BW _{LOOP(1485Mb/s)} | PLL_LOOP_BANDWIDTH = 00001 | — | 438 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 00010 | — | 875 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 00100 (default) | — | 1.75 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 01000 | — | 3.5 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 10000 | — | 7 | — | MHz | |
| | BW _{LOOP(2970Mb/s)} | PLL_LOOP_BANDWIDTH = 00001 | — | 875 | — | kHz | |
| | | PLL_LOOP_BANDWIDTH = 00010 | — | 1.75 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 00100 (default) | — | 3.5 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 01000 | — | 7.0 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 10000 | — | 14.0 | — | MHz | |
| | BW _{LOOP(5940Mb/s)} | PLL_LOOP_BANDWIDTH = 00001 | — | 1.75 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 00010 | — | 3.5 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 00100 (default) | — | 7.0 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 01000 | — | 14.0 | — | MHz | |
| | | PLL_LOOP_BANDWIDTH = 10000 | — | 28.0 | — | MHz | |

Note:

1. Edge detection method for LOS detection should be used for data rates below 20Mb/s
2. Refer to Table 4-3 for the exact register settings for each ΔV_{DDO} output swing listed
3. Jitter measured using an oscilloscope according to SMPTE RP-184
4. Accumulated jitter measured peak to peak differential over 2000 hits

3. Input/Output Circuits

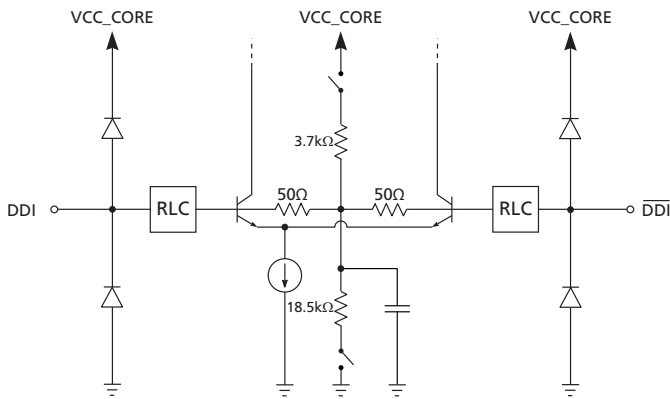


Figure 3-1: DDI0, $\overline{\text{DDI0}}$, DDI1, $\overline{\text{DDI1}}$, DDI2, $\overline{\text{DDI2}}$, DDI3, $\overline{\text{DDI3}}$ Serial Digital Differential Inputs

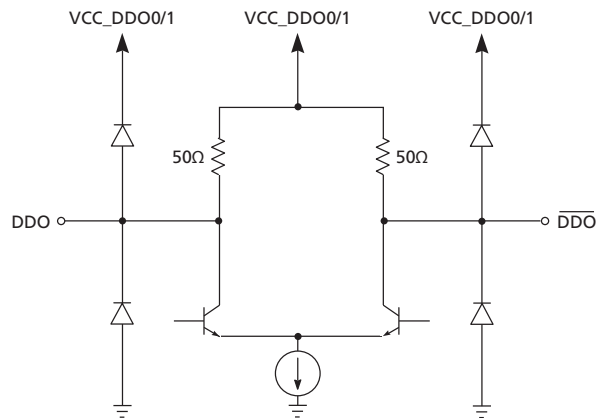


Figure 3-2: DDO0, $\overline{\text{DDO0}}$, DDO1, $\overline{\text{DDO1}}$ Serial Digital Differential Output

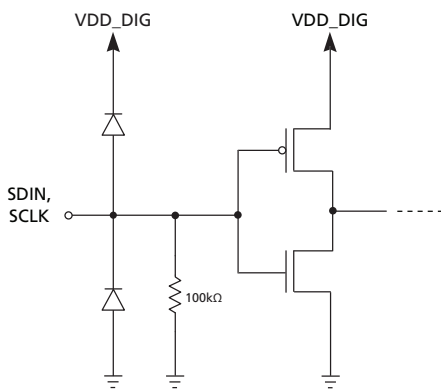


Figure 3-3: SDIN and SCLK

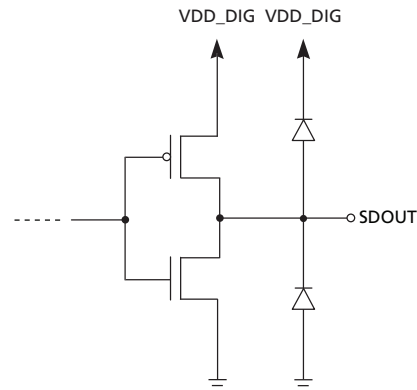


Figure 3-4: SDOUT

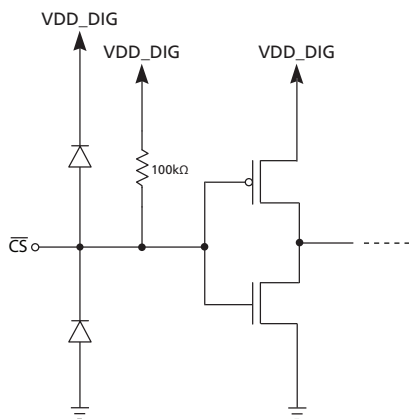


Figure 3-5: $\overline{\text{CS}}$

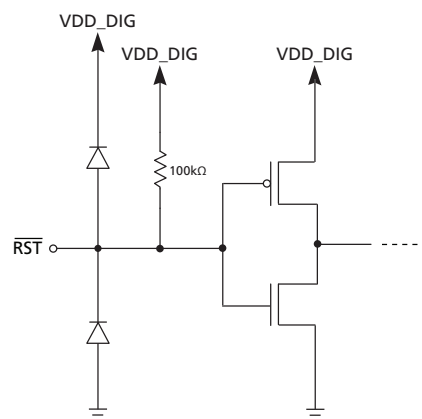


Figure 3-6: $\overline{\text{RST}}$

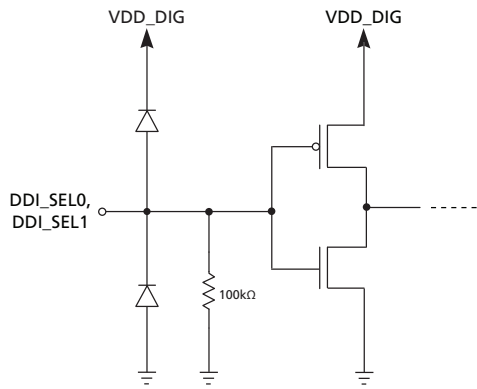


Figure 3-7: DDI_SEL0/STROBE and DDI_SEL1

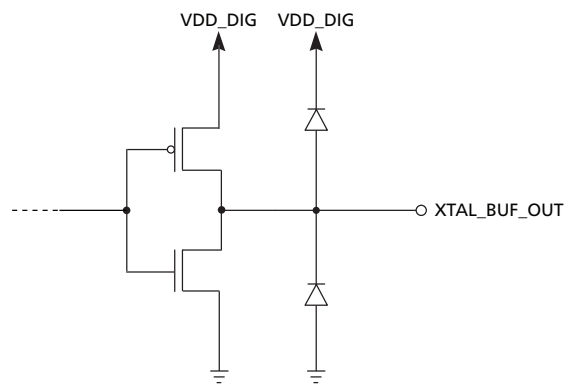


Figure 3-8: XTAL_BUF_OUT

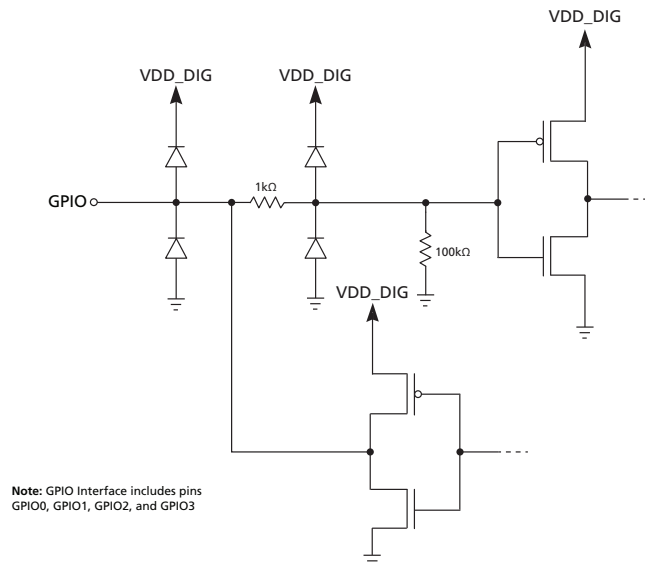


Figure 3-9: General Purpose Inputs/Outputs (GPIO)

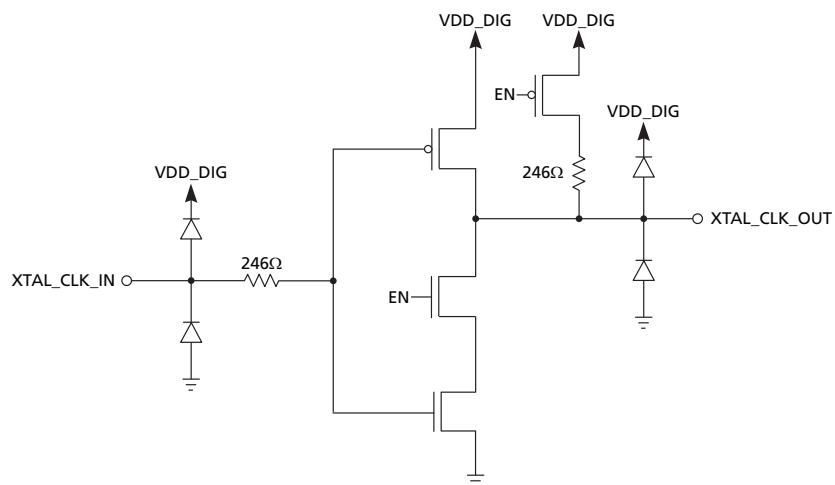


Figure 3-10: XTAL_CLK_IN and XTAL_CLK_OUT

4. Detailed Description

The GS6150 is a multi-standard reclocker for serial digital SDTV SDI and DVB-ASI signals operating at 270Mb/s, HDTV SDI signals operating at 1.485Gb/s and 1.485/1.001Gb/s, 3G SDI signals operating at 2.97Gb/s and 2.97/1.001Gb/s, and 6G UHD-SDI signals operating at 5.94Gb/s and 5.94/1.001Gb/s and MADl audio streams at 125Mb/s.

4.1 Serial Data Inputs

The GS6150 features four 100Ω terminated differential input buffers.

A serial data input signal may be connected to any of the following input pin pairs of the device: DDI0/DDI0̄, DDI1/DDI1̄, DDI2/DDI2̄, and DDI3/DDI3̄.

By default, the self-biasing circuit at the input is enabled to allow AC coupling to upstream devices. To enable DC coupling of the inputs, the user must disable the self-biasing network by setting bits 4:4 through 5:5 to 0 in the register 7_h:
DDI[0:1]_TRACE_EQ_DC_TERM_ENABLE.

In order to select DC coupling, please ensure that the output common mode of the upstream device is in range of the input common mode voltage range shown in [Table 2-2](#).

The serial digital input buffer is capable of operation with any binary coded signal that meets the input signal level requirements defined below, with any data rate between 3Mb/s and 5.94Gb/s.

4.1.1 Input Trace Equalization

The GS6150 features adjustable trace equalization to compensate for PCB trace dielectric losses up to half the maximum supported data rate, or 3GHz. The equalization has three settings: the LOW (default) setting is optimized for compensating the high-frequency losses associated with 0-7dB of trace loss at 1.5GHz for data rates of 2.97Gb/s and below, and for 0-10dB of trace loss at 3GHz for 5.94Gb/s. The HIGH setting is optimized for trace loss between 7-14dB at 1.5GHz for data rates 2.97Gb/s and below. The 0dB or EQ_BYPASS setting may be used in systems with negligible trace loss. These settings are selected using the DDI0_TRACE_EQ_CONTROL, DDI1_TRACE_EQ_CONTROL, DDI2_TRACE_EQ_CONTROL and DDI3_TRACE_EQ_CONTROL bits in the INPUT_CONTROL_REG_0 register at address 5_h.

The default state of the device is input trace equalization on all inputs set to LOW.

4.1.2 Input Selection

The GS6150 incorporates a 4:1 input selector which allows the connection of four independent streams of video/data.

The selector is controllable in three separate ways:

1. The DDI_SEL0 and DDI_SEL1 pins can be used to select the input.
2. A GSPI accessible register can be used to select the input, with the state change occurring as soon as the register value changes.
3. A GSPI accessible register can be used to select the input, with a rising edge on the STROBE pin triggering a change to the next state.

Since these states are mutually exclusive, the DDI_SEL0 pin is shared with the STROBE function.

In the case of using the DDI_SEL0/STROBE and DDI_SEL1 pins (#1 above) or the STROBE pre-select method (#3 above), the input selector will switch within 1µs of the change of state on the corresponding pin(s). This strict timing requirement is not maintained when using GSPI register selection (#2 above).

Each of the device's four inputs is selected as shown in Table 4-1.

Table 4-1: Pin and Register Settings for Input Selection

| Register Settings | | | Pin Settings | | Differential High-speed Input Selected |
|---|-----------------------------------|-----------------------------------|--------------|---------------------------|--|
| INPUT_SELECTION_CONTROL 7 _h [9:8] | DDI_SELECT 7 _h [11] | DDI_SELECT 7 _h [10] | DDI_SEL1 | DDI_SEL0/ STROBE | |
| X0 (default) | X | X | LOW | LOW | DDI0, $\overline{\text{DDI0}}$ |
| X0 (default) | X | X | LOW | HIGH | DDI1, $\overline{\text{DDI1}}$ |
| X0 (default) | X | X | HIGH | LOW | DDI2, $\overline{\text{DDI2}}$ |
| X0 (default) | X | X | HIGH | HIGH | DDI3, $\overline{\text{DDI3}}$ |
| 01 | 0 | 0 | X | X | DDI0, $\overline{\text{DDI0}}$ |
| 01 | 0 | 1 | X | X | DDI1, $\overline{\text{DDI1}}$ |
| 01 | 1 | 0 | X | X | DDI2, $\overline{\text{DDI2}}$ |
| 01 | 1 | 1 | X | X | DDI3, $\overline{\text{DDI3}}$ |
| 11 | 0 | 0 | X | on LOW-to-HIGH transition | DDI0, $\overline{\text{DDI0}}$ |
| 11 | 0 | 1 | X | on LOW-to-HIGH transition | DDI1, $\overline{\text{DDI1}}$ |
| 11 | 1 | 0 | X | on LOW-to-HIGH transition | DDI2, $\overline{\text{DDI2}}$ |
| 11 | 1 | 1 | X | on LOW-to-HIGH transition | DDI3, $\overline{\text{DDI3}}$ |

Note: 'X' indicates 'Do Not Care'

The DDI_SEL0/STROBE and DDI_SEL1 pins include internal pull-downs, which pulls the input voltage LOW if either pin is unconnected.

When using the STROBE pre-select method (#3 above), the pre-selected input buffer and trace EQ is powered up in advance of the STROBE pulse.

4.2 Reference Clock

The GS6150 can operate with or without an external frequency reference. For applications requiring rapid asynchronous locking, a 27MHz reference or crystal is required.

The PLL lock times for both referenceless and external crystal reference operation are given in [Table 2-3: AC Electrical Characteristics](#).

If a reference is connected to the XTAL_CLK_IN pin or a crystal is connected to the XTAL_CLK_IN and XTAL_CLK_OUT pins of the device, it will automatically be used as the reference frequency for rapid asynchronous lock. If XTAL_CLK_IN is not connected to a crystal, XTAL_CLK_OUT must be left unconnected.

The XTAL_CLK_IN pin operates correctly when connected directly to the XTAL_BUF_OUT from another GS6150, or a 27MHz output of a different device.

4.3 Signal Monitoring

The GS6150 measures and reports the following signal status and quality monitoring parameters:

- Loss of Signal
- Lock Detection
- Rate Detection
- Low/High Bit Rate Detection

4.3.1 Loss of Signal Detection

LOS (Loss of Signal) detection is an active HIGH output available to the application on any of the GPIO[3:0] multi-function status and control pins. It is selected for output using the GPIO[3:0]_IO_SELECT and GPIO[3:0]_SELECT bits accessible in the GPIO_CONTROL_REG_0 and GPIO_CONTROL_REG_1 registers. It is the default output of the GPIO0 pin.

LOS indicates when the serial digital signal selected by the input selector is invalid. This function is always active.

Two methods can be used to detect loss of signal: strength (default) and edge. Either method can be selected with LOS_DETECTION_METHOD bits of register PLL_CONTROL.

When strength detection is used as the method of LOS detection the corresponding GPIO pin will be HIGH (signal lost) when the input signal amplitude within a predefined window falls below the threshold set by the bits DDI[0:3]_LOS_THRESHOLD_CONTROL in the LOS_CONTROL_REG_1 and LOS_CONTROL_REG_2 registers. The LOS threshold hysteresis can be set by the LOS_HYSTERESIS bits in the LOS_CONTROL_REG_0 register at address F_h .

The corresponding GPIO pin will be LOW (signal present) when the input signal amplitude within a predefined window is above the defined threshold.

The method of strength detection is measurement of the average rectified differential voltage on the input pins. The strength detection method is therefore inherently dependent on the input signal's eye shape, particularly the rise/fall times of the input signal relative to the data rate. Additionally, the circuit has a lower bandwidth limit of operation (20Mb/s) below which it is recommended that the edge detection method is used. The absolute value of the threshold can be determined for any input swings according to Equation 4-1 below:

$$\text{Threshold} = \frac{1.9\text{mV} \times (\text{DDI}[0..3]_{\text{LOS_THRESHOLD_CONTROL}}) \times 53}{(\text{DEVICE_SPECIFIC_LOS_THRESHOLD})} \quad \text{Equation 4-1}$$

where DEVICE_SPECIFIC_LOS_THRESHOLD specifies the LOS threshold value for a 100mV input swing at SD-rate specific to each device. The other rates scale according to the fractional relationship given in Figure 4-1 and Figure 4-2 below.

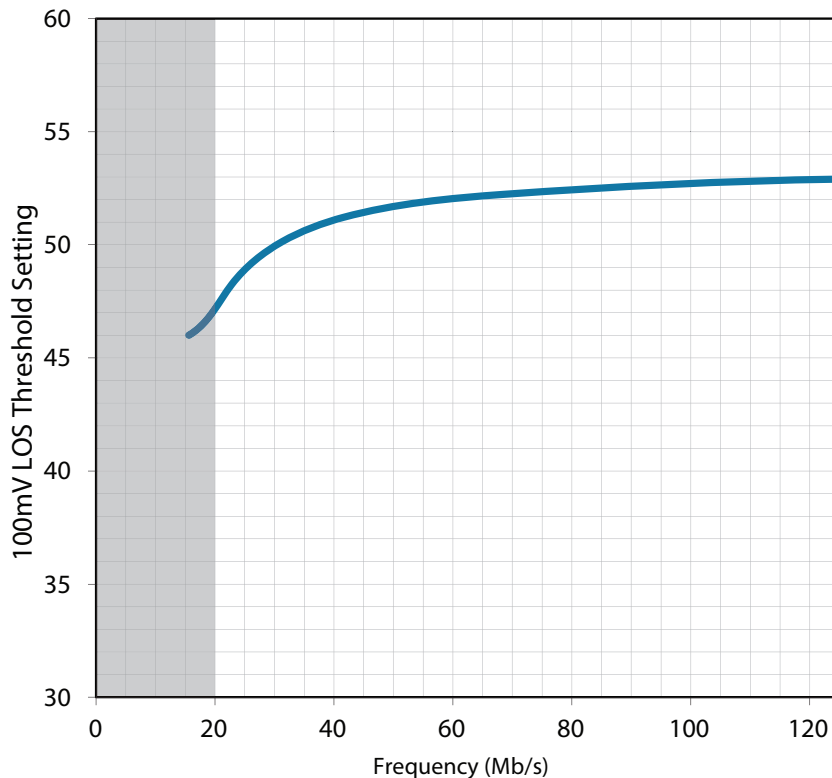


Figure 4-1: LOS Threshold at 100mV Input Swing vs. Low Frequency Rates for a Nominal DEVICE_SPECIFIC_LOS_THRESHOLD of 53

Note: Edge detection method is recommended for signals in shaded areas.

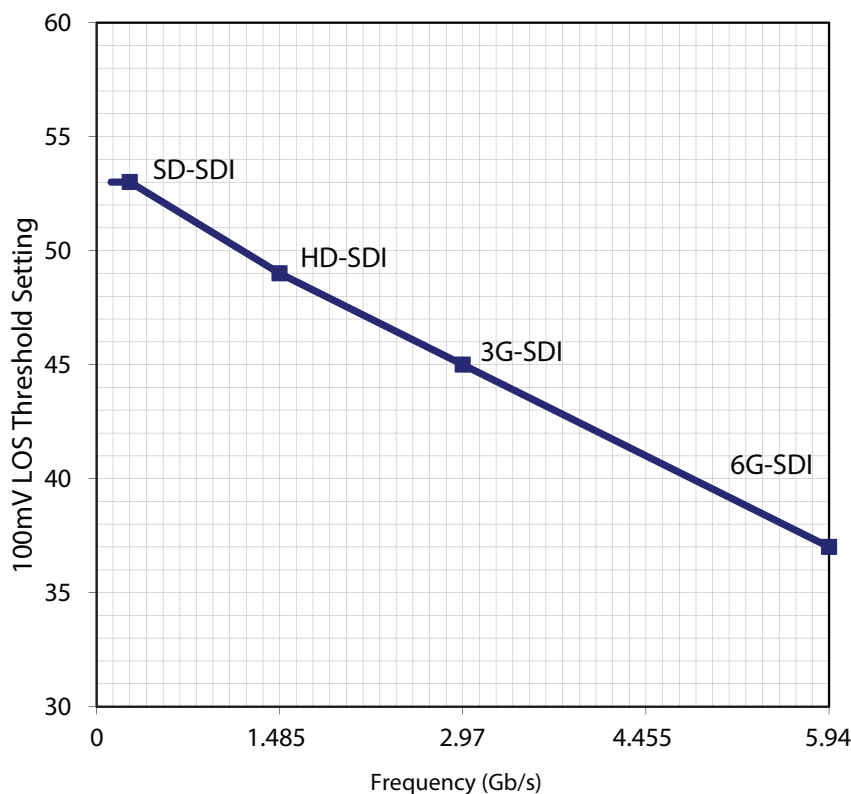


Figure 4-2: LOS Threshold at 100mV Input Swing vs. SDI Data Rates for a Nominal DEVICE_SPECIFIC_LOS_THRESHOLD of 53

Strength detection is unaffected by the Trace EQ settings in INPUT_CONTROL_REG_0.

When edge detection is used as the method of LOS detection the corresponding GPIO pin will be HIGH (signal lost) when no transitions are detected on the selected input. The corresponding GPIO pin will be LOW (signal present) when transitions are detected on the input. The LOS status is also available through the LOS bit in the PLL_STATUS register, and as a sticky status through the LOS_STICKY bit in the STICKY_STATUS register at address 50_h.

4.3.2 Lock Detection

The GS6150 lock detection circuitry outputs a LOCKED status signal which indicates that the CDR has achieved phase lock to the incoming data stream. The LOCKED signal is an active HIGH output available to the application on any of the GPIO[3:0] multi-function status and control pins. It is selected for output using the GPIO[3:0]_IO_SELECT and GPIO[3:0]_SELECT bits accessible in the GPIO_CONTROL_REG_0 and GPIO_CONTROL_REG_1 registers. By default, LOCKED is output on GPIO1.

The LOCKED status is available from the LOCKED bit in the PLL_STATUS register, and the LOCK_LOST_STICKY bit in the STICKY_STATUS register indicates whether lock has been lost since the bit was last cleared.

To optimize systems with high DCD and/or high residual ISI the LOCK_SAMPLE bit of the PD_CONTROL register should be set to 1_b in conjunction with reducing the Loop Bandwidth.

4.3.2.1 Synchronous and Asynchronous Lock Time

Asynchronous lock time is defined as the time it takes the device to lock when a signal is first applied to the serial digital inputs, or when the signal rate changes.

The synchronous lock time is defined as the time it takes the device to lock to a signal which has been momentarily interrupted.

The asynchronous and synchronous lock times are defined in [Table 2-3: AC Electrical Characteristics](#).

To qualify for synchronous lock time, the maximum interruption time of the signal is 10µs for a 270Mb/s signal. 1.485Gb/s, 2.97Gb/s, and 5.94Gb/s signals, as well as their f/1.001 components have a maximum interruption time of 6µs. The new signal, after interruption, must have the same frequency as the original signal but can have arbitrary phase.

4.3.3 Rate Detection

The GS6150 can be manually forced to lock to a specific supported data rate, or automatically search for and lock to supported rates. The selection between manual and automatic rate selection is through the FORCE_PLL_RATE and FORCE_PLL_RATE_ENABLE bits of the PLL_CONTROL register at address 4C_h. By default the device is set to automatically search for supported SDI rates.

When set to automatically detect supported data rates, the device repeatedly cycles through each supported rate that is enabled through the RATE_ENABLE_5G94, RATE_ENABLE_2G97, RATE_ENABLE_1G485, RATE_ENABLE_270M and RATE_ENABLE_125M bits of the PLL_CONTROL register, until the device phase locks to one of the enabled rates. If lock is lost the rate search resumes, continuously testing for each rate in sequence until lock is regained.

The device reports the current data rate setting of the automatic rate search state machine through the DETECTED_RATE bits in the PLL_STATUS register at address 4F_h. Each bit of DETECTED_RATE is also available to output through the GPIO pins, selected for output using the GPIO[3:0]_IO_SELECT and GPIO[3:0]_SELECT bits accessible in the GPIO_CONTROL_REG_0 register. The supported rates that the DETECTED_RATE bits can output are shown in [Table 4-2](#) below.

Table 4-2: Automatic Rate Detection - Supported Data Rates

| DETECTED_RATE | Data Rate |
|---------------|----------------|
| 000 | 125Mb/s – MADI |
| 001 | 270Mb/s – SD |
| 010 | 1.485Gb/s – HD |
| 011 | 2.97Gb/s – 3G |
| 100 | 5.94Gb/s – 6G |

4.3.4 Low/High Bit Rate Detection for Slew Rate Control

A status output named LBR_HBR is provided to control the slew rate selection input of a downstream SDI cable driver. It can be connected to the SD_EN input of drivers such as the GS6080 or GS6081 using the Semtech recommended application circuit.

When this signal is HIGH, the data rate is 270Mb/s (SD) or 125Mb/s (MADI). This signal is LOW for all other supported data rates, and when the GS6150 is operating in Bypass Mode or any time the device is not locked.

The LBR_HBR output signal is available to the application on any of the GPIO[3:0] multifunction status and control pins. It is selected for output using the GPIO[3:0]_IO_SELECT and GPIO[3:0]_SELECT bits accessible in the GPIO_CONTROL_REG_0 and GPIO_CONTROL_REG_1 registers. By default, LBR_HBR is output on GPIO2.

4.4 Low Power Modes

The device can be programmed via the GSPI to operate in two different low power modes. SLEEP mode has minimum power consumption at the expense of recovery time upon de-assertion of the FORCE_PWRDN_SLEEP bit. STANDBY mode has higher power consumption relative to SLEEP mode but minimizes time to return to operation on de-assertion of the FORCE_PWRDN_STANDBY bit. The features affected by each mode are outlined below.

SLEEP mode:

- LOS detection remains functional
- The GSPI remains functional
- The reference oscillator remains functional

STANDBY mode:

- LOS detection remains functional
- The GSPI remains functional
- The reference oscillator remains functional
- The VCO and PLL remains functional so as to minimize the lock time when a signal is detected
- The rate detector remains set to the last valid data rate. On detection of a signal, the last valid rate is tested first by the rate detect state machine

The device can be programmed to automatically enter into SLEEP or STANDBY mode when LOS is asserted by programming the AUTO_PWRDN_DISABLE bit in the PWRDN_CONTROL register at address 17_h. The AUTO_PWRDN_MODE bit in the same register selects which mode, SLEEP or STANDBY, is entered into upon assertion of LOS.

4.5 Serial Data Output

The GS6150 has two current-mode differential output drivers, each capable of driving up to $1V_{pp}$ differential into an external 100Ω differential load.

The output drivers operate with any binary coded signal with supported data rates up to 5.94Gb/s. This is applicable to both the serial data (DDO, \overline{DDO}) and serial data (DDO1, $\overline{DDO1}$) outputs of the device.

4.5.1 Output Impedance

Each of the GS6150's output buffers include two on-chip, 50Ω termination resistors.

4.5.2 Output Signal Interface Levels

The serial digital outputs operate within specification with an output CML power supply of 1.2V to 2.5V.

4.5.3 Adjustable Output Swing

Through the GSPI, the output swing can be set in the range from approximately $230mV_{ppd}$ to $930mV_{ppd}$ in $45mV_{ppd}$ increments, when the outputs are terminated with 50Ω loads. For the exact values, please see [Table 4-3](#) below.

The output swing for each data rate is controlled using the bits in the DRIVER_CONTROL_REG_3, DRIVER_CONTROL_REG_4, DRIVER_CONTROL_REG_5, and DRIVER_CONTROL_REG_6 registers at addresses $1C_h$ through $1F_h$.

The device automatically adjusts the swing setting depending on the state of the device (i.e. detected rate, bypass mode, or mute). There are separate register controls for mute, bypass and each data rate.

Table 4-3: Serial Digital Output Swing Settings

| Register Setting (See Note 1) | Min | Typ | Max | Units |
|----------------------------------|-----|-----|-----|-------|
| 0000 _b | 175 | 230 | 290 | mV |
| 0001 _b | 205 | 275 | 345 | mV |
| 0010 _b | 245 | 325 | 405 | mV |
| 0011 _b (default) | 280 | 370 | 460 | mV |
| 0100 _b | 310 | 410 | 510 | mV |
| 0101 _b | 345 | 460 | 575 | mV |
| 0110 _b | 380 | 510 | 640 | mV |
| 0111 _b | 420 | 560 | 700 | mV |

Table 4-3: Serial Digital Output Swing Settings (Continued)

| Register Setting (See Note 1) | Min | Typ | Max | Units |
|----------------------------------|-----|-----|------|-------|
| 1000 _b | 455 | 605 | 760 | mV |
| 1001 _b | 490 | 655 | 820 | mV |
| 1010 _b | 530 | 705 | 880 | mV |
| 1011 _b | 565 | 755 | 945 | mV |
| 1100 _b | 600 | 800 | 1000 | mV |
| 1101 _b | 630 | 840 | 1050 | mV |
| 1110 _b | 670 | 890 | 1110 | mV |
| 1111 _b | 700 | 930 | 1160 | mV |

Note:

1. Applicable registers that can be programmed with the values shown above are DDO0_SWING_1G485, DDO0_SWING_270M, DDO0_SWING_125M, DDO0_SWING_BYPASS, DDO0_SWING_MUTE, DDO0_SWING_5G94, DDO0_SWING_2G97, DDO1_SWING_1G485, DDO1_SWING_270M, DDO1_SWING_125M, DDO1_SWING_BYPASS, DDO1_SWING_MUTE, DDO1_SWING_5G94, and DDO1_SWING_2G97

4.5.4 Output De-emphasis

The GS6150 features adjustable output de-emphasis to compensate for PCB dielectric trace loss. Each output can be independently set to a different de-emphasis setting for each detected rate through controls found in the DRIVER_CONTROL_REG_1 and DRIVER_CONTROL_REG_2 registers.

The effect of de-emphasis, illustrated in Figure 4-3, is to attenuate the swing of bits that do not follow a bit transition (V_{DE}). The swing of bits that do follow a bit transition (V_{nom}) is set by the output swing registers found in Section 4.5.3 and do not depend on the de-emphasis settings.

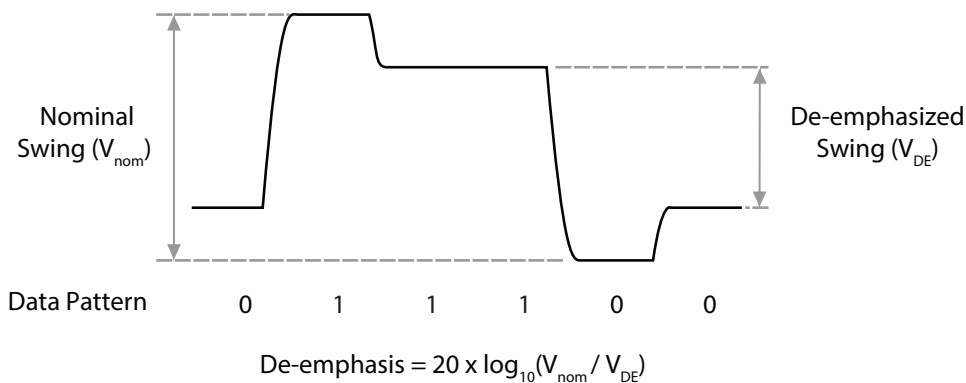


Figure 4-3: De-emphasis Waveform

The default de-emphasis settings for each rate are given in the register descriptions for DRIVER_CONTROL_REG_1 and DRIVER_CONTROL_REG_2 in Table 5-1. De-emphasis is disabled on both outputs in Bypass mode, when the output is muted, or when the device is not locked.

4.5.5 Output Common Mode Voltage

The output common mode voltage level (V_{CMOUT}) is a function of the output voltage swing, the output driver supply voltage (V_{CC_DDO}) and how the transmission line is terminated. If the outputs are terminated through 50Ω resistors to a voltage V_{TERM} equal to V_{CC_DDO} , as shown in Figure 4-5 below, the output common mode voltage is given by the following expression:

$$V_{CMOUT} = V_{CC_DDO} - \frac{\Delta V_{DDO}}{4} \tag{Equation 4-2}$$

If the differential outputs are terminated across a 100Ω resistor, as shown in Figure 4-4 below, the output common mode voltage is given by the following expression:

$$V_{CMOUT} = V_{CC_DDO} - \frac{\Delta V_{DDO}}{2} \tag{Equation 4-3}$$

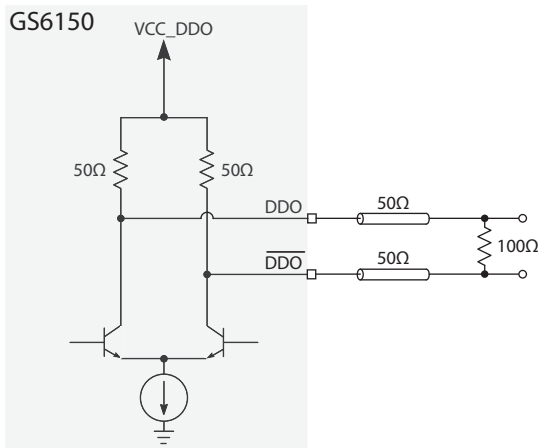


Figure 4-4: 100Ω Parallel Output Termination

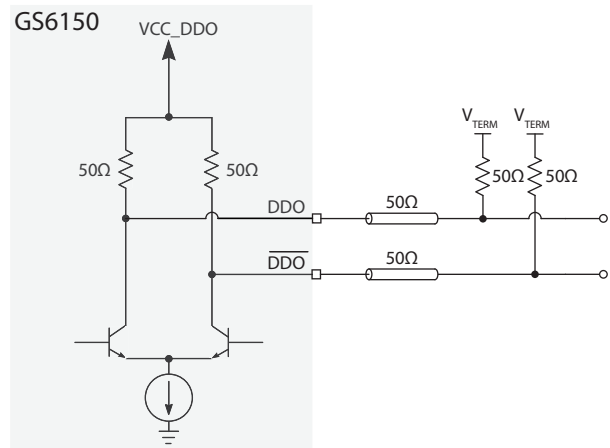


Figure 4-5: 50Ω Termination to V_{TERM}

4.6 Output Mute, Disable, and Data Selection

The GS6150 outputs can each be individually muted using the DDO0_MUTE and DDO1_MUTE bits in the DRIVER_CONTROL_REG_0 register at address 19_h .

Each output can also be independently disabled through either register or GPIO control. When disabled each pin of the output is pulled to V_{CC_DDO} . Register DRIVER_CONTROL_REG_0 contains both register based disable bits (DDO0_DISABLE, DDO1_DISABLE) and bits for selection between register and GPIO control (DDO0_DISABLE_SELECT, DDO1_DISABLE_SELECT). For GPIO control refer to Section 4.10.

By default $\overline{DDO0}$, $\overline{DDO1}$ is enabled/disabled through register control and set to enabled. $\overline{DDO1}$, $\overline{DDO1}$ is enabled/disabled through GPIO3 and set to output data.

4.7 Bypass Mode

In CDR Bypass mode, the GS6150 passes the input data to the outputs, bypassing the retiming functionality.

There are two bits in the control registers that control the bypass function: MANUAL_BYPASS and AUTO_BYPASS in the RECLOCKER_BYPASS register at address 20_h. The MANUAL_BYPASS bit is inactive (set to 0) by default. The AUTO_BYPASS bit is active (set to 1) by default, and places the GS6150 reclocker into bypass mode when the PLL is not locked to a data rate. The bypass function does not affect the trace equalization function of the device.

Note: If MANUAL_BYPASS is active, it overrides the AUTO_BYPASS bit setting.

4.8 DVB-ASI

The GS6150 has the ability to reclock DVB-ASI signals at 270Mb/s. All relevant settings and control registers that apply to SD-SDI signals at 270Mb/s are also compatible with DVB-ASI signals at 270Mb/s.

4.9 Device Power Up

4.9.1 Power on Reset (POR)

The GS6150 features an on-chip power-on-reset that places all registers and internal state machines into their known, default states when the chip is powered up.

4.9.2 Reset Pin (\overline{RST})

When the \overline{RST} pin is set LOW, all functional blocks are set to their default conditions and high-speed data and digital functionality is suspended. When it is set HIGH, normal operation of the device resumes 0.5ms after the LOW-to-HIGH transition of the signal. This pin is not required at power up and may be left unconnected.

4.10 GPIO Pins Configuration

The GS6150 has four GPIO pins that can each be configured as outputs for various internal status signals, or as inputs to disable either output-driver through pin control. The bits GPIO[0:3]_IO_SELECT are used to configure the GPIO pins as outputs (0) or inputs (1). The signals that are output or input on the GPIO pins are selected on GPIO_CONTROL_REG_0 and GPIO_CONTROL_REG_1. The signals that can be output on the GPIO pins are listed in [Table 4-4](#) below.

Table 4-4: GPIO Status Outputs

| GPIO[0:3]_SELECT | Parameter | Description |
|------------------|--------------|--|
| 0000 | LOS | Loss of signal indication - High when there is no detected signal on the selected DDI input |
| 0001 | LOCKED | Phase lock indication - High when the CDR has phase-locked to a valid input signal |
| 0010 | LBR_HBR | Low bit-rate/High bit-rate - High when the part is locked to the SD data rate; low for all other data rates and in bypass. |
| 0101 | RATE_DET0 | Rate Detect - Three bits used in conjunction that represent the data rate detected by the rate search state machine. Refer to Table 4-2 for rate encoding details. |
| 0110 | RATE_DET1 | |
| 0111 | RATE_DET2 | |
| 1000 | LOCKED_125M | High when the rate search state machine is locked to a MADI data rate (125Mb/s) |
| 1001 | LOCKED_270M | High when the rate search state machine is locked to an SD data rate (270Mb/s) |
| 1010 | LOCKED_1G485 | High when the rate search state machine is locked to an HD data rate (1.485Gb/s) |
| 1011 | LOCKED_2G97 | High when the rate search state machine is locked to a 3G data rate (2.97Gb/s) |
| 1100 | LOCKED_5G94 | High when the rate search state machine is locked to a 6G data rate (5.94Gb/s) |
| 1101 | RATE_CHANGE | When a change in the data rate is detected by the rate search state machine, the RATE_CHANGE signal is pulsed high for a duration of 37ns |

The signals that can be input on the GPIOs are listed in [Table 4-5](#) below.

Table 4-5: GPIO Signal Inputs

| GPIO[0:3]_SELECT | Parameter | Description |
|------------------|--------------|---|
| 0000 | DDO0_DISABLE | Disables serial data output 0 ($\overline{DDO0}$, DDO0) |
| 0001 | DDO1_DISABLE | Disables serial data output 1 ($\overline{DDO1}$, DDO1) |

By default, the GPIO pins are configured to the following parameters:

- GPIO0: LOS (output)
- GPIO1: LOCKED (output)
- GPIO2: LBR_HBR (output)
- GPIO3: DDO1_DISABLE (input)

4.11 GSPI Host Interface

The GS6150 is controlled via the Gennum Serial Peripheral Interface (GSPI).

The GSPI host interface is comprised of a serial data input signal (SDIN pin), serial data output signal (SDOUT pin), an active-low chip select (\overline{CS} pin) and a burst clock (SCLK pin).

The GS6150 is a slave device, therefore the SCLK, SDIN and \overline{CS} signals must be sourced by the application host processor.

All read and write access to the device is initiated and terminated by the application host processor.

It is strongly recommended to connect the GSPI pins of the GS6150 to a host/system processor/controller or FPGA to facilitate optimization of the device to meet specific application requirements. Modification of many device settings is only facilitated through the GSPI of the GS6150, and is not available on external pins.

4.11.1 \overline{CS} Pin

The Chip Select pin (\overline{CS}) is an active-low signal provided by the host processor to the GS6150.

The high-to-low transition of this pin marks the start of serial communication to the GS6150.

The low-to-high transition of this pin marks the end of serial communication to the GS6150.

There is an option for each device to use a separate unique Chip Select signal from the host processor or for up to 32 devices to be connected to a single Chip Select when making use of the Unit Address feature.

Only those devices whose Unit Address matches the UNIT ADDRESS in the GSPI Command Word will respond to communication from the host processor (unless the B'CAST ALL bit in the GSPI Command Word is set to 1).

4.11.2 SDIN Pin

The SDIN pin is the GSPI serial data input pin of the GS6150.

The 16-bit Command and Data Words from the host processor or from the SDOUT pin of other devices are shifted into the device on the rising edge of SCLK when the \overline{CS} pin is low.

4.11.3 SDOUT Pin

The SDOUT pin is the GSPI serial data output of the GS6150.

All data transfers out of the GS6150 to the host processor or to the SDIN pin of other connected devices occur from this pin.

By default at power up or after system reset, the SDOUT pin provides a non-clocked path directly from the SDIN pin, regardless of the \overline{CS} pin state, except during the GSPI Data

Word portion for read operations to the device. This allows multiple devices to be connected in Loop-Through configuration.

For read operations, the SDOOUT pin is used to output data read from an internal Configuration and Status Register (CSR) when \overline{CS} is LOW. Data is shifted out of the device on the falling edge of SCLK, so that it can be read by the host processor or other downstream connected device on the subsequent SCLK rising edge.

4.11.3.1 GSPI Link Disable Operation

It is possible to disable the direct SDIN to SDOOUT (Loop-Through) connection by writing a value of 1 to the GSPI_LINK_DISABLE bit in REGISTER_0. When disabled, any data appearing at the SDIN pin will not appear at the SDOOUT pin and the SDOOUT pin is HIGH.

Note: Disabling the Loop-Through operation is temporarily required when initializing the Unit Address for up to 32 connected devices.

The time required to enable/disable the Loop-Through operation from assertion of the register bit is less than the GSPI configuration command delay as defined by the parameter $t_{cmd_GSPI_config}$ (5 SCLK cycles).

Table 4-6: GSPI_LINK_DISABLE Bit Operation

| Bit State | Description |
|-----------|---|
| 0 | SDIN pin is looped through to the SDOOUT pin |
| 1 | Data appearing at SDIN does not appear at SDOOUT, and SDOOUT pin is HIGH. |

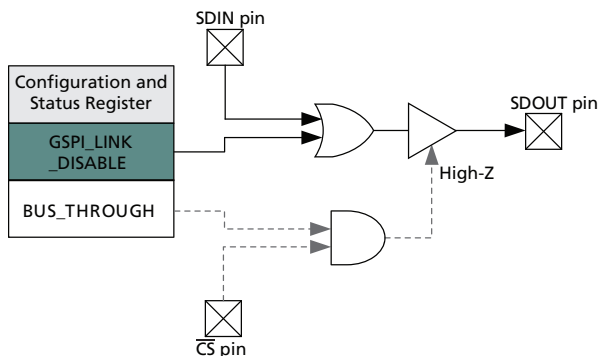


Figure 4-6: GSPI_LINK_DISABLE Operation

4.11.3.2 GSPI Bus-Through Operation

Using GSPI Bus-Through operation, the GS6150 can share a common PCB trace with other GSPI devices for SDOOUT output.

When configured for Bus-Through operation, by setting GSPI_BUS_THROUGH_ENABLE bit to 1, the SDOOUT pin will be high-impedance when the \overline{CS} pin is HIGH.

When the \overline{CS} pin is LOW, the SDOOUT pin will be driven and will follow regular read and write operation as described in [Section 4.11.3](#).

Multiple chains of GS6150 devices can share a single SDOUT bus connection to host by configuring the devices for Bus-Through operation. In such configuration, each chain requires a separate Chip Select (\overline{CS}).

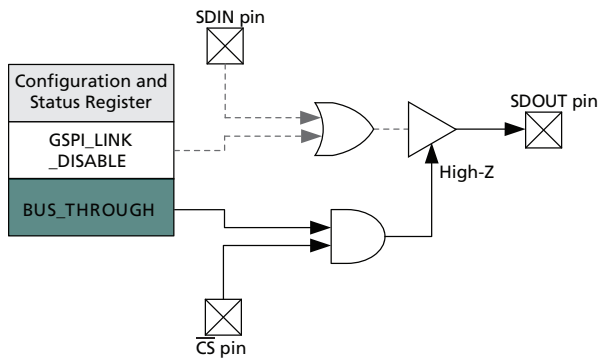


Figure 4-7: GSPI_BUS_THROUGH_ENABLE Operation

4.11.4 SCLK Pin

The SCLK pin is the GSPI serial data shift clock input to the device, and must be provided by the host processor.

Serial data is clocked into the GS6150 SDIN pin on the rising edge of SCLK. Serial data is clocked out of the device from the SDOUT pin on the falling edge of SCLK (read operation). SCLK is ignored when \overline{CS} is HIGH.

The maximum interface clock rate is 27MHz.

4.11.5 Command Word Description

All GSPI accesses are a minimum of 32 bits in length (a 16-bit Command Word followed by a 16-bit Data Word) and the start of each access is indicated by the high-to-low transition of the chip select (\overline{CS}) pin of the GS6150.

The format of the Command Word and Data Words are shown in [Figure 4-8](#).

Data received immediately following this high-to-low transition will be interpreted as a new Command Word.

4.11.5.1 R/ \overline{W} bit - B15 Command Word

This bit indicates a read or write operation.

When R/ \overline{W} is set to 1, a read operation is indicated, and data is read from the register specified by the ADDRESS field of the Command Word.

When R/ \overline{W} is set to 0, a write operation is indicated, and data is written to the register specified by the ADDRESS field of the Command Word.

4.11.5.2 B'CAST ALL - B14 Command Word

This bit is used in write operations to configure all devices connected in Loop-Through and Bus-Through configuration with a single command.

When B'CAST ALL is set to 1, the following Data Word (AUTOINC = 0) or Data Words (AUTOINC = 1) are written to the register specified by the ADDRESS field of the Command Word (and subsequent addresses when AUTOINC = 1), regardless of the setting of the UNIT ADDRESS(es).

When B'CAST ALL is set to 0, a normal write operation is indicated. Only those devices that have a Unit Address matching the UNIT ADDRESS field of the Command Word write the Data Word to the register specified by the ADDRESS field of the Command Word.

4.11.5.3 EMEM - B13 Command Word

When the EMEM bit is 1 the Address Word is extended to 23 bits to allow access to registers located in the extended memory space.

When the EMEM bit is 0, the address word is limited to 7 bits.

4.11.5.4 AUTOINC - B12 Command Word

When AUTOINC is set to 1, Auto-Increment read or write access is enabled.

In Auto-Increment Mode, the device automatically increments the register address for each contiguous read or write access, starting from the address defined in the ADDRESS field of the Command Word.

The internal address is incremented for each 16-bit read or write access until a low-to-high transition on the \overline{CS} pin is detected.

When AUTOINC is set to 0, single read or write access is required.

Auto-Increment write must not be used to update values in HOST_CONFIG.

4.11.5.5 UNIT ADDRESS - B11:B7 Command Word

The 5 bits of the UNIT ADDRESS field of the Command Word are used to select one of 32 devices connected on a single chip select in Loop-Through or Bus-Through configurations.

Read and write accesses are only accepted if the UNIT ADDRESS field matches the programmed DEVICE_UNIT_ADDRESS in HOST_CONFIG.

By default at power-up or after a device reset, the DEVICE_UNIT_ADDRESS is set to 00h

4.11.5.6 ADDRESS - B6:B0 Command Word

If the extended memory is not being accessed (EMEM = 0), the 7 bits of the ADDRESS field are used to select one of 128 register addresses in the device in single read or write access mode, or to set the starting address for read or write accesses in Auto-Increment Mode.

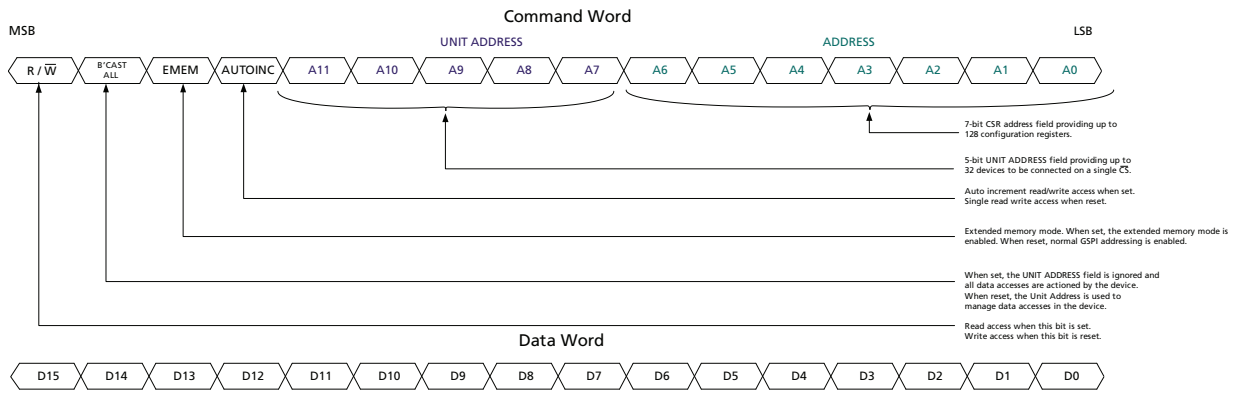


Figure 4-8: Command and Data Word Format

When EMEM is set to 1, the Address Word is extended to 23 bits. The Command and Data Word format will be extended by another 16 bits, and is shown in Figure 4-9 below.

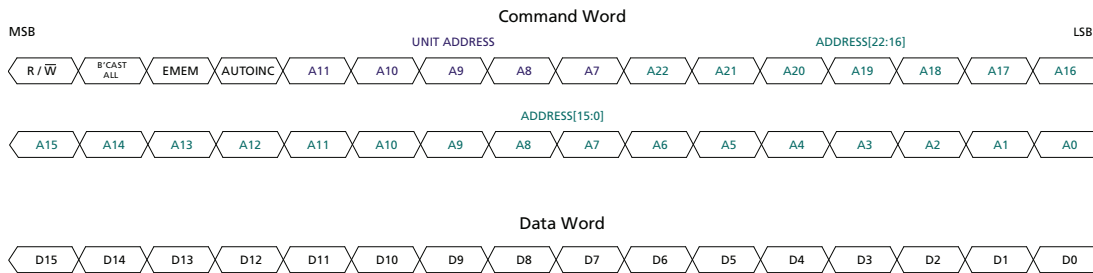


Figure 4-9: Command and Data Word Format with EMEM set to 1

4.11.6 GSPI Transaction Timing

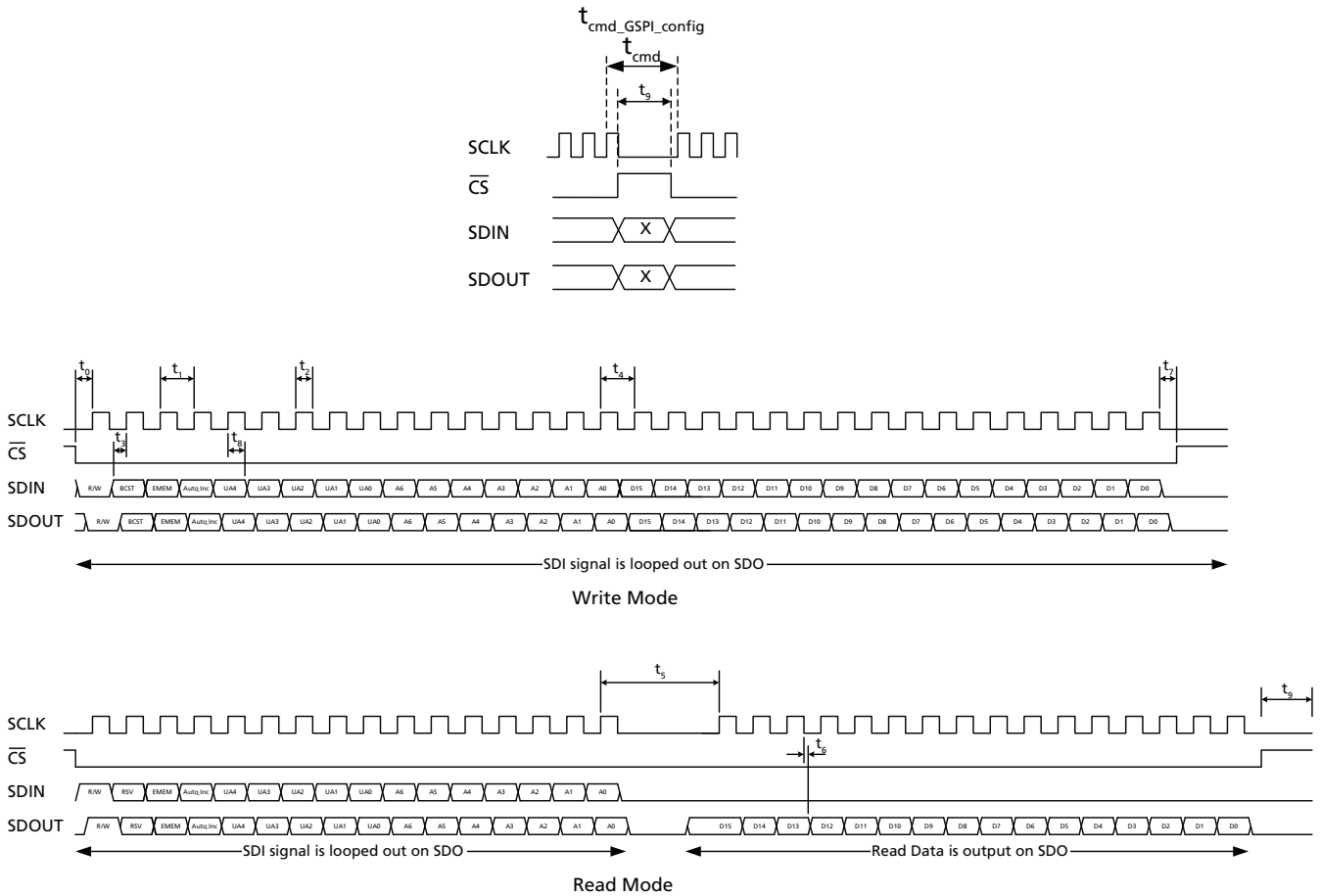


Figure 4-10: GSPI External Interface Timing

Table 4-7: GSPI Timing Parameters

| Parameter | Symbol | Equivalent SCLK Cycles (at 27MHz) | Min | Typ | Max | Units |
|--------------------------------|--------|-----------------------------------|-------|-----|-----|-------|
| SCLK frequency | | | — | — | 27 | MHz |
| CS low before SCLK rising edge | t_0 | | 2.0 | — | — | ns |
| SCLK period | t_1 | | 37 | — | — | ns |
| SCLK duty cycle | t_2 | | 40 | 50 | 60 | % |
| Input data setup time | t_3 | | 2.7 | — | — | ns |
| SCLK idle time - write | t_4 | 1 | 37 | — | — | ns |
| SCLK idle time - read | t_5 | 5 | 161.0 | — | — | ns |

Table 4-7: GSPI Timing Parameters (Continued)

| Parameter | Symbol | Equivalent SCLK Cycles (at 27MHz) | Min | Typ | Max | Units |
|---|--|-----------------------------------|-------|-----|-----|--------------|
| Inter-command delay time | t_{cmd} | 4 | 120.0 | — | — | ns |
| Inter-command delay time (after GSPI configuration write) | $t_{cmd_GSPI_conf}^1$ | 5 | 162.0 | — | — | ns |
| SDO after SCLK falling edge | t_6 | | — | — | 7.5 | ns |
| CS high after final SCLK falling edge | t_7 | | 0.0 | — | — | ns |
| Input data hold time | t_8 | | 1.0 | — | — | ns |
| \overline{CS} high time | t_9 | | 57.0 | — | — | ns |
| SDIN to SDOUT combinational delay | | | — | — | 5.0 | ns |
| Max. chips daisy chained at max SCLK frequency | When host clocks in SDOUT data on rising edge of SCLK | | — | — | 1 | GS6150 chips |
| Max. frequency for 32 daisy-chained devices | | | — | — | 2.1 | MHz |
| Max. chips daisy-chained at max. SCLK frequency | When host clocks in SDOUT data on falling edge of SCLK | | — | — | 3 | GS6150 chips |
| Max. frequency for 32 daisy-chained devices | | | — | — | 2.2 | MHz |

Note:

- $t_{cmd_GSPI_conf}$ inter-command delay must be used whenever modifying HOST_CONFIG register at address 0x00

4.11.7 Single Read/Write Access

Single read/write access timing for the GSPI interface is shown in Figure 4-11 to Figure 4-15.

When performing a single read or write access, one Data Word is read from/written to the device per access. Each access is a minimum of 32-bits long, consisting of a Command Word and a single Data Word. The read or write cycle begins with a high-to-low transition of the \overline{CS} pin. The read or write access is terminated by a low-to-high transition of the \overline{CS} pin.

The maximum interface clock rate is 27MHz and the inter-command delay time indicated in the figures as t_{cmd} , is a minimum of 4 SCLK clock cycles. After modifying values in HOST_CONFIG, the inter-command delay time, $t_{cmd_GSPI_config}$, is a minimum of 5 SCLK clock cycles.

For read access, the time from the last bit of the Command Word to the start of the data output, as defined by t_5 , corresponds to no less than 5 SCLK clock cycles at 27MHz.

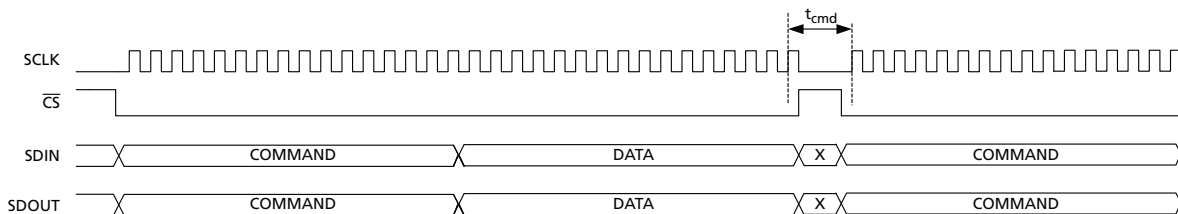


Figure 4-11: GSPI Write Timing – Single Write Access with Loop-Through Operation (default)

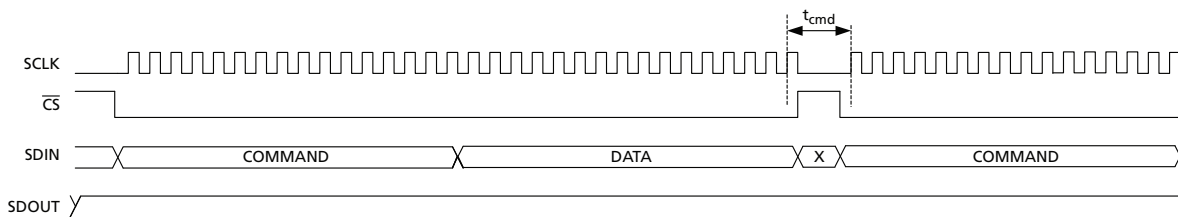


Figure 4-12: GSPI Write Timing – Single Write Access with GSPI Link-Disable Operation

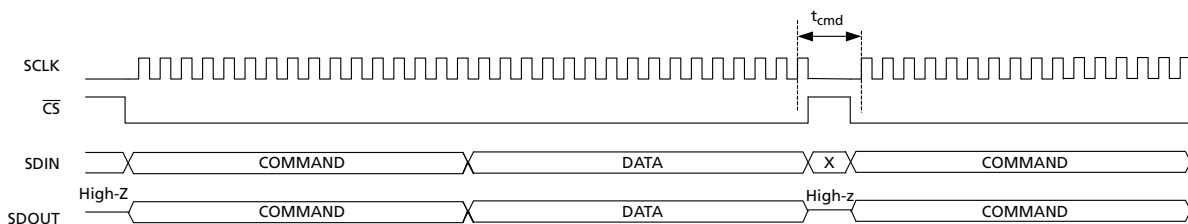


Figure 4-13: GSPI Write Timing – Single Write Access with Bus-Through Operation

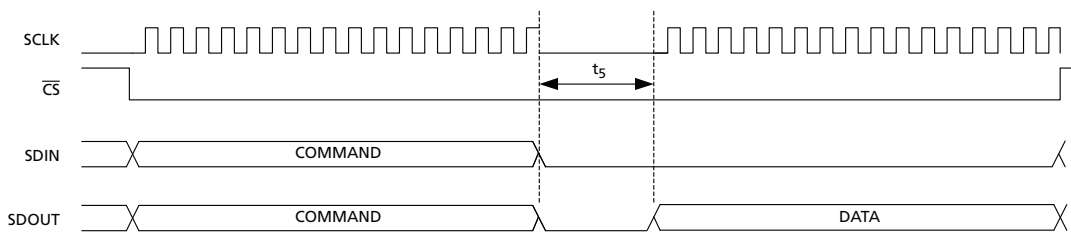


Figure 4-14: GSPI Read Timing – Single Read Access with Loop-Through Operation (default)

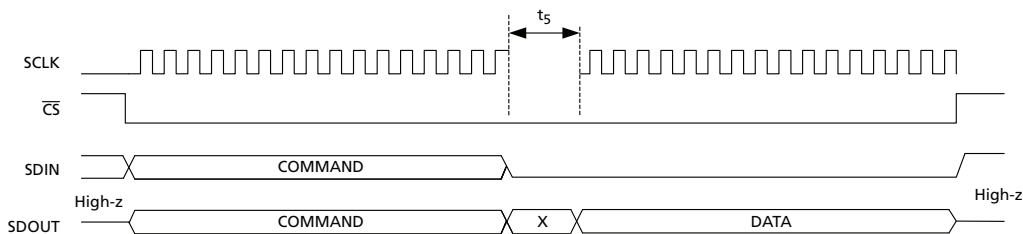


Figure 4-15: GSPI Read Timing – Single Read Access with Bus-Through Operation

4.11.8 Auto-increment Read/Write Access

Auto-increment read/write access timing for the GSPI interface is shown in [Figure 4-16](#) to [Figure 4-20](#).

Auto-increment mode is enabled by the setting of the AUTOINC bit of the Command Word.

In this mode, multiple Data Words can be read from/written to the device using only one starting address. Each access is initiated by a high-to-low transition of the \overline{CS} pin, and consists of a Command Word and one or more Data Words. The internal address is automatically incremented after the first read or write Data Word, and continues to increment until the read or write access is terminated by a low-to-high transition of the \overline{CS} pin.

Note: Writing to HOST_CONFIG using Auto-increment access is not allowed.

The maximum interface clock rate is 27MHz and the inter-command delay time indicated in the diagram as t_{cmd} , is a minimum of 4 SCLK clock cycles.

For read access, the time from the last bit of the first Command Word to the start of the data output of the first Data Word as defined by t_5 , will be no less than 5 SCLK cycles at 27MHz. All subsequent read data accesses will not be subject to this delay during an Auto-Increment read.

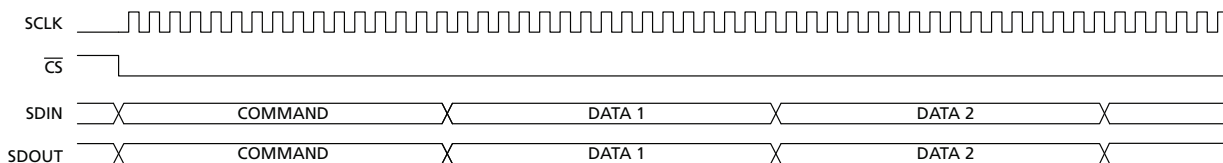


Figure 4-16: GSPI Write Timing – Auto-Increment with Loop-Through Operation (default)

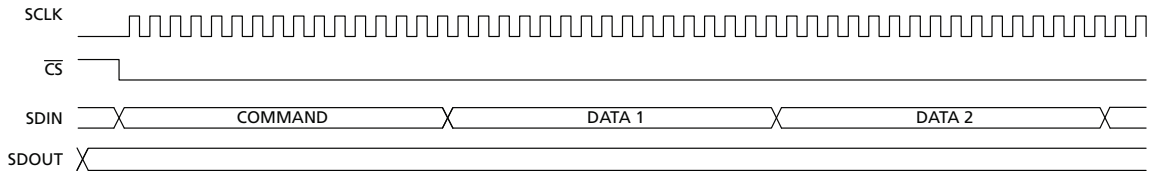


Figure 4-17: GSPI Write Timing – Auto-Increment with GSPI Link Disable Operation

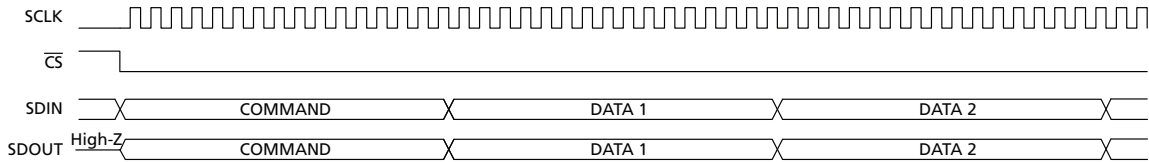


Figure 4-18: GSPI Write Timing – Auto-Increment with Bus-Through Operation

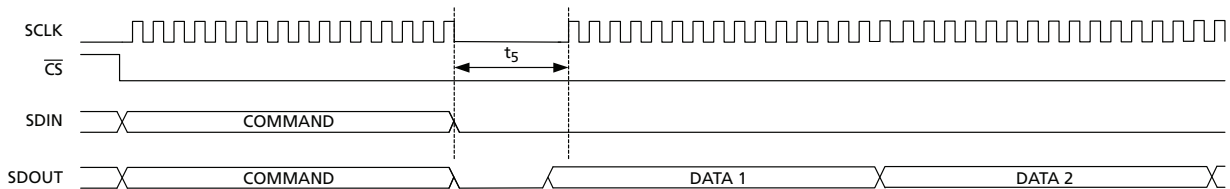


Figure 4-19: GSPI Read Timing – Auto-Increment Read with Loop-Through Operation (default)

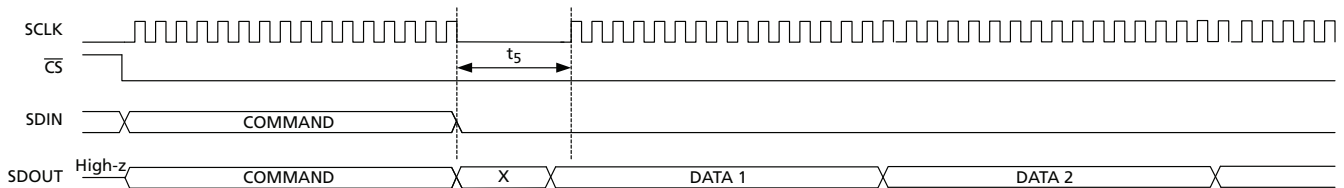


Figure 4-20: GSPI Read Timing – Auto-Increment Read with Bus-through Operation

4.11.9 Setting a Device Unit Address

Multiple (up to 32) GS6150 devices can be connected to a common Chip Select (\overline{CS}) in Loop-Through or Bus-Through operation.

To ensure that each device selected by a common \overline{CS} can be separately addressed, a unique Unit Address must be programmed by the host processor at start-up as part of system initialization or following a device reset.

Note: By default at power up or after a device reset, the `DEVICE_UNIT_ADDRESS` of each device is set to 0h and the `SDIN->SDOUT` non-clocked loop-through for each device is enabled.

These are the steps required to set the `DEVICE_UNIT_ADDRESS` of devices in a chain to values other than 0:

1. Write to Unit Address 0 selecting `HOST_CONFIG` (`ADDRESS = 0`), with the `GSPI_LINK_DISABLE` bit set to 1 and the `DEVICE_UNIT_ADDRESS` field set to 0. This disables the direct `SDIN->SDOUT` non-clocked path for all devices on chip select.

- Write to Unit Address 0 selecting HOST_CONFIG (ADDRESS = 0), with the GSPI_LINK_DISABLE bit set to 0 and the DEVICE_UNIT_ADDRESS field set to a unique Unit Address. This configures DEVICE_UNIT_ADDRESS for the first device in the chain. Each subsequent such write to Unit Address 0 will configure the next device in the chain. If there are 32 devices in a chain, the last (32nd) device in the chain must use DEVICE_UNIT_ADDRESS value 0.
- Repeat step 2 using new, unique values for the DEVICE_UNIT_ADDRESS field in HOST_CONFIG until all devices in the chain have been configured with their own unique Unit Address value.

Note: $t_{cmd_GSPI_conf}$ delay must be observed after every write that modifies HOST_CONFIG.

All connected devices receive this command (by default the Unit Address of all devices is 0), and the Loop-Through operation will be re-established for all connected devices.

Once configured, each device will only respond to Command Words with a UNIT ADDRESS field matching the DEVICE_UNIT_ADDRESS in HOST_CONFIG

Note: Although the Loop-Through and Bus-Through configurations are compatible with previous generation GSPI enabled devices (backward compatibility), only devices supporting Unit Addressing can share a chip select. All devices on any single chip select must be connected in a contiguous chain with only the last device's SDOUT connected to the application host processor. Multiple chains configured in Bus-Through mode can have their final SDOUT outputs connected to a single application host processor input.

4.11.10 Default GSPI Operation

By default at power up or after a device reset, the GS6150 is set for Loop-Through Operation and the internal DEVICE_UNIT_ADDRESS field of the device is set to 0.

Figure 4-21 shows a functional block diagram of the Configuration and Status Register (CSR) map in the GS6150 for non-extended memory accesses (EMEM = 0).

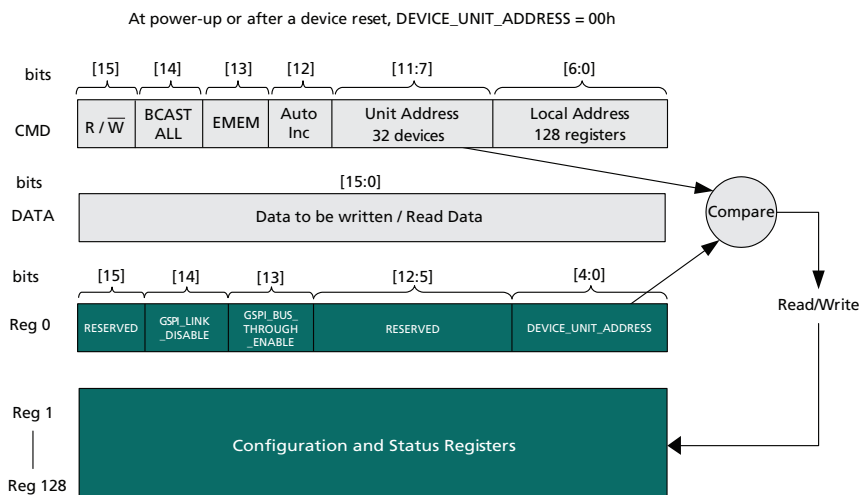


Figure 4-21: Internal Register Map Functional Block Diagram

The steps required for the application host processor to write to the Configuration and Status Registers via the GSPI, are as follows:

1. Set Command Word for write access ($R/\overline{W} = 0$) to the local registers 0h-80h; set Auto Increment; set the Unit Address field in the Command Word to match the configured DEVICE_UNIT_ADDRESS which will be zero. Write the Command Word.
2. Write the Data Word to be written to the first register.
3. Write the Data Word to be written to the next register in Auto Increment mode, etc.

Read access is the same as the above with the exception of step 1, where the Command Word is set for read access ($R/\overline{W} = 1$).

Note: The UNIT ADDRESS field of the Command Word must always match DEVICE_UNIT_ADDRESS for an access to be accepted by the device. Changing DEVICE_UNIT_ADDRESS to a value other than 0 is only required if multiple devices are connected to a single chip select (in Loop-Through or Bus-Through configuration.)

5. Host Interface Register Map

Table 5-1: Register Descriptions - Standard Address Space

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|----------------|--------------------|-------------------------|----------------|--------------------------|----------------|--|
| 0 _h | HOST_CONFIG | RSVD | 15:15 | RW | 0 _h | Reserved. Do not change. |
| | | GSPI_LINK_DISABLE | 14:14 | RW | 0 _h | GSPI loop-through disable. |
| | | GSPI_BUS_THROUGH_ENABLE | 13:13 | RW | 0 _h | GSPI bus-through enable. |
| | | RSVD | 12:5 | RW | 0 _h | Reserved. Do not change. |
| | | DEVICE_UNIT_ADDRESS | 4:0 | RW | 0 _h | Device address programmed by application. |
| 1 _h | DEVICE_INFO | RSVD | 15:8 | RO | 1 _h | Reserved. |
| | | DEVICE_VERSION_ID | 7:0 | RO | - | Device Version Identifier. |
| 2 _h | GPIO_CONTROL_REG_0 | RSVD | 15:14 | RW | 0 _h | Reserved. Do not change. |
| | | GPIO1_IO_SELECT | 13:13 | RW | 0 _h | GPIO1 Input/Output Select 0 _b : Output 1 _b : Input |
| | | RSVD | 12:11 | RW | 0 _h | Reserved. Do not change. |
| | | GPIO1_SELECT | 10:7 | RW | 1 _h | GPIO1 Signal Selection If GPIO1_IO_SELECT is set to 0: 0000 _b : LOS 0001 _b : LOCKED (default) 0010 _b : LBR_HBR 0011 _b : Reserved 0100 _b : Reserved 0101 _b : RATE_DET0 0110 _b : RATE_DET1 0111 _b : RATE_DET2 1000 _b : LOCKED_125M 1001 _b : LOCKED_270M 1010 _b : LOCKED_1G485 1011 _b : LOCKED_2G97 1100 _b : LOCKED_5G94 1101 _b : RATE_CHANGE If GPIO1_IO_SELECT is set to 1: 0000 _b : DDO0_DISABLE 0001 _b : DDO1_DISABLE |
| | | GPIO0_IO_SELECT | 6:6 | RW | 0 _h | GPIO0 Input/Output Select 0 _b : Output 1 _b : Input |
| RSVD | 5:4 | RW | 0 _h | Reserved. Do not change. | | |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|----------------|--------------------|----------------|-----------|-----|----------------|---|
| 2 _h | GPIO_CONTROL_REG_0 | GPIO0_SELECT | 3:0 | RW | 0 _h | <p>GPIO0 Signal Selection</p> <p>If GPIO0_IO_SELECT is set to 0:</p> <p>0000_b: LOS (default)</p> <p>0001_b: LOCKED</p> <p>0010_b: LBR_HBR</p> <p>0011_b: Reserved</p> <p>0100_b: Reserved</p> <p>0101_b: RATE_DET0</p> <p>0110_b: RATE_DET1</p> <p>0111_b: RATE_DET2</p> <p>1000_b: LOCKED_125M</p> <p>1001_b: LOCKED_270M</p> <p>1010_b: LOCKED_1G485</p> <p>1011_b: LOCKED_2G97</p> <p>1100_b: LOCKED_5G94</p> <p>1101_b: RATE_CHANGE</p> <p>If GPIO0_IO_SELECT is set to 1:</p> <p>0000_b: DDO0_DISABLE</p> <p>0001_b: DDO1_DISABLE</p> |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|----------------|--------------------|-----------------|-----------|-----|----------------|--|
| | | RSVD | 15:14 | RW | 0 _h | Reserved. Do not change. |
| | | GPIO3_IO_SELECT | 13:13 | RW | 1 _h | GPIO3 Input/Output Select 0 _b : Output 1 _b : Input |
| | | RSVD | 12:11 | RW | 0 _h | Reserved. Do not change. |
| 3 _h | GPIO_CONTROL_REG_1 | GPIO3_SELECT | 10:7 | RW | 1 _h | GPIO3 Signal Selection If GPIO3_IO_SELECT is set to 0: 0000 _b : LOS 0001 _b : LOCKED 0010 _b : LBR_HBR 0011 _b : Reserved 0100 _b : Reserved 0101 _b : RATE_DET0 0110 _b : RATE_DET1 0111 _b : RATE_DET2 1000 _b : LOCKED_125M 1001 _b : LOCKED_270M 1010 _b : LOCKED_1G485 1011 _b : LOCKED_2G97 1100 _b : LOCKED_5G94 1101 _b : RATE_CHANGE If GPIO3_IO_SELECT is set to 1: 0000 _b : DDO0_DISABLE 0001 _b : DDO1_DISABLE (default) |
| | | GPIO2_IO_SELECT | 6:6 | RW | 0 _h | GPIO2 Input/Output Select 0 _b : Output 1 _b : Input |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|----------------|---------------------|-----------------------|-----------|-----|-----------------|---|
| | | RSVD | 5:4 | RW | 0 _h | Reserved. Do not change. |
| 3 _h | GPIO_CONTROL_REG_1 | GPIO2_SELECT | 3:0 | RW | 2 _h | <p>GPIO2 Signal Selection</p> <p>If GPIO2_IO_SELECT is set to 0:</p> <p>0000_b: LOS</p> <p>0001_b: LOCKED</p> <p>0010_b: LBR_HBR (default)</p> <p>0011_b: Reserved</p> <p>0100_b: Reserved</p> <p>0101_b: RATE_DET0</p> <p>0110_b: RATE_DET1</p> <p>0111_b: RATE_DET2</p> <p>1000_b: LOCKED_125M</p> <p>1001_b: LOCKED_270M</p> <p>1010_b: LOCKED_1G485</p> <p>1011_b: LOCKED_2G97</p> <p>1100_b: LOCKED_5G94</p> <p>1101_b: RATE_CHANGE</p> <p>If GPIO2_IO_SELECT is set to 1:</p> <p>0000_b: DDO0_DISABLE</p> <p>0001_b: DDO1_DISABLE</p> |
| 4 _h | RESERVED | RSVD | 15:0 | RW | 1C _h | Reserved. Do not change. |
| | | DDI3_TRACE_EQ_CONTROL | 7:6 | RW | 0 _h | <p>DDI3 Trace-EQ Configuration</p> <p>00_b: OFF</p> <p>01_b: 0dB/EQ BYPASS</p> <p>10_b: LOW</p> <p>11_b: HIGH</p> |
| | | DDI2_TRACE_EQ_CONTROL | 5:4 | RW | 0 _h | <p>DDI2 Trace-EQ Configuration</p> <p>00_b: OFF</p> <p>01_b: 0dB/EQ BYPASS</p> <p>10_b: LOW</p> <p>11_b: HIGH</p> |
| 5 _h | INPUT_CONTROL_REG_0 | DDI1_TRACE_EQ_CONTROL | 3:2 | RW | 0 _h | <p>DDI1 Trace-EQ Configuration</p> <p>00_b: OFF</p> <p>01_b: 0dB/EQ BYPASS</p> <p>10_b: LOW</p> <p>11_b: HIGH</p> |
| | | DDIO_TRACE_EQ_CONTROL | 1:0 | RW | 0 _h | <p>DDIO Trace-EQ Configuration</p> <p>00_b: OFF</p> <p>01_b: 0dB/EQ BYPASS</p> <p>10_b: LOW</p> <p>11_b: HIGH</p> |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|----------------|---------------------|------------------------------|-----------|------|----------------|---|
| 6 _h | RESERVED | RSVD | 15:0 | RW | 0 _h | Reserved. Do not change. |
| | | RSVD | 15:12 | RW | 0 _h | Reserved. Do not change. |
| 7 _h | INPUT_CONTROL_REG_2 | DDI_SELECT | 11:10 | RW | 0 _h | Input Selection 00 _b : DDI0 01 _b : DDI1 10 _b : DDI2 11 _b : DDI3 Used when INPUT_SELECTION_CONTROL is set to 01 _b or 11 _b |
| | | INPUT_SELECTION_CONTROL | 9:8 | RW | 0 _h | Determines the source for the input selection block. X0 _b : Use DDI_SEL0_STROBE and DDI_SEL1 pins. 01 _b : Use DDI_SELECT bits 11 _b : Use DDI_SELECT bits; update occurs on low-to-high transition of DDI_SEL0_STROBE pin. |
| | | DDI3_TRACE_EQ_DC_TERM_ENABLE | 7:7 | RW | 1 _h | Enable DDI3 on-chip Trace-EQ DC termination. 0 _b : Disabled 1 _b : Enabled |
| | | DDI2_TRACE_EQ_DC_TERM_ENABLE | 6:6 | RW | 1 _h | Enable DDI2 on-chip Trace-EQ DC termination. 0 _b : Disabled 1 _b : Enabled |
| | | DDI1_TRACE_EQ_DC_TERM_ENABLE | 5:5 | RW | 1 _h | Enable DDI1 on-chip Trace-EQ DC termination. 0 _b : Disabled 1 _b : Enabled |
| | | DDI0_TRACE_EQ_DC_TERM_ENABLE | 4:4 | RW | 1 _h | Enable DDI0 on-chip Trace-EQ DC termination. 0 _b : Disabled 1 _b : Enabled |
| | | RSVD | 3:0 | RW | 0 _h | Reserved. Do not change. |
| | | 8 _h | RESERVED | RSVD | 15:0 | ROCW |
| 9 _h | RESERVED | RSVD | 15:0 | RO | — | Reserved. |
| A _h | RESERVED | RSVD | 15:0 | RO | — | Reserved. |
| B _h | RESERVED | RSVD | 15:0 | RO | — | Reserved. |
| C _h | RESERVED | RSVD | 15:0 | RO | — | Reserved. |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|----------------|-------------------|------------------------------|-----------|-----|----------------|---|
| D _h | RESERVED | RSVD | 15:0 | RO | — | Reserved. |
| E _h | RESERVED | RSVD | 15:0 | RO | — | Reserved. |
| | | RSVD | 15:10 | RW | 0 _h | Reserved. Do not change. |
| | | LOS_THRESHOLD_CONTROL_ENABLE | 9:9 | RW | 0 _h | Enables LOS threshold adjustment based on the settings in the DD[3:0]_LOS_THRESHOLD_CONTROL bits in the LOS_CONTROL_REG_1 and LOS_CONTROL_REG_2 registers. 0 _b : Default internal thresholds are used 1 _b : Thresholds used in the LOS_CONTROL_REG_1 and LOS_CONTROL_REG_2 registers |
| | | LOS_DEASSERT_TIME | 8:7 | RW | 2 _h | LOS De-Assert Time Delay: 00 _b : 2.30μs 01 _b : 1.50μs 10 _b : 1.20μs 11 _b : 0.90μs |
| | | LOS_ASSERT_TIME | 6:5 | RW | 2 _h | LOS Assert Time Delay: 00 _b : 68μs 01 _b : 64μs 10 _b : 62μs 11 _b : 61μs |
| F _h | LOS_CONTROL_REG_0 | LOS_HYSTERESIS | 4:1 | RW | 0 _h | LOS Threshold Hysteresis Adjustment: 0000 _b : 0 dB 0001 _b : 0.32 dB 0010 _b : 0.64 dB 0011 _b : 0.98 dB 0100 _b : 1.34 dB 0101 _b : 1.70 dB 0110 _b : 2.09 dB 0111 _b : 2.49 dB 1000 _b : 2.84 dB 1001 _b : 3.28 dB 1010 _b : 3.74 dB 1011 _b : 4.23 dB 1100 _b : 4.75 dB 1101 _b : 5.30 dB 1110 _b : 5.89 dB 1111 _b : 6.53 dB |
| | | LOS_PWRDN_OVERRIDE | 0:0 | RW | 0 _h | Override the internal power-down control for the LOS circuit. 0 _b : LOS active 1 _b : LOS powered down |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|-------------------|-------------------------------|-----------|-----|------------------|--|
| 10 _h | LOS_CONTROL_REG_1 | DDI1_LOS_THRESHOLD_CONTROL | 15:8 | RW | 5A _h | LOS signal threshold for input DDI1 at device pins is: 1.9mV _{ppd} x DDI1_LOS_THRESHOLD_CONTROL x (53/DEVICE_SPECIFIC_LOS_THRESHOLD) (All above values are in decimal) |
| | | DDI0_LOS_THRESHOLD_CONTROL | 7:0 | RW | 5A _h | LOS signal threshold for input DDI0 at device pins is: 1.9mV _{ppd} x DDI0_LOS_THRESHOLD_CONTROL x (53/DEVICE_SPECIFIC_LOS_THRESHOLD) (All above values are in decimal) |
| 11 _h | LOS_CONTROL_REG_2 | DDI3_LOS_THRESHOLD_CONTROL | 15:8 | RW | 5A _h | LOS signal threshold for input DDI3 at device pins is: 1.9mV _{ppd} x DDI3_LOS_THRESHOLD_CONTROL x (53/DEVICE_SPECIFIC_LOS_THRESHOLD) (All above values are in decimal) |
| | | DDI2_LOS_THRESHOLD_CONTROL | 7:0 | RW | 5A _h | LOS signal threshold for input DDI2 at device pins is: 1.9mV _{ppd} x DDI2_LOS_THRESHOLD_CONTROL x (53/DEVICE_SPECIFIC_LOS_THRESHOLD) (All above values are in decimal) |
| 12 _h | LOS_STATUS | RSVD | 15:8 | RO | — | Reserved. |
| | | DEVICE_SPECIFIC_LOS_THRESHOLD | 7:0 | RO | — | Trimmed setting to achieve LOS threshold of 100mV _{ppd} |
| 13 _h | RESERVED | RSVD | 15:0 | RW | 280 _h | Reserved. Do not change. |
| 14 _h | RESERVED | RSVD | 15:0 | RO | — | Reserved. |
| | | RSVD | 15:3 | RW | 0 _h | Reserved. Do not change. |
| 15 _h | REF_CLK_CONTROL | XTAL_BUF_OUT_ENABLE | 2:2 | RW | 1 _h | Enables/Disables the reference buffer output. 0 _b : XTAL_BUF_OUT disabled 1 _b : XTAL_BUF_OUT enabled |
| | | RSVD | 1:1 | RW | 0 _h | Reserved. Do not change. |
| | | RSVD | 0:0 | RW | 0 _h | Reserved. Do not change. |
| | | RSVD | 15:1 | RO | — | Reserved. |
| 16 _h | REF_CLK_STATUS | XTAL_CLK_DET | 0:0 | RO | - | Indicates whether an external 27MHz reference is being used by the device or its internal oscillator. 0 _b : Internal oscillator being used 1 _b : External crystal being used |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|-------------------|---------------------|-----------|-----|----------------|---|
| 17 _h | PWRDN_ CONTROL | AUTO_PWRDN_MODE | 3:3 | RW | 0 _h | Selects the low power mode, SLEEP or STANDBY that is entered into when AUTO_PWRDN_DISABLE is set to 0 and LOS is asserted. 0 _b : SLEEP mode is selected (default) 1 _b : STANDBY mode is selected |
| | | FORCE_PWRDN_STANDBY | 2:2 | RW | 0 _h | Forces the device into STANDBY mode when FORCE_PWRDN_SLEEP is set to 0. 0 _b : Device not in STANDBY mode 1 _b : Device in STANDBY mode |
| | | FORCE_PWRDN_SLEEP | 1:1 | RW | 0 _h | Forces the device into SLEEP mode when AUTO_PWRDN_DISABLE is set to 1. 0 _b : Device not in SLEEP mode 1 _b : Device in SLEEP mode When FORCE_PWRDN_SLEEP is set to 1, it takes precedence over the FORCE_PWRDN_STANDBY bit. |
| | | AUTO_PWRDN_DISABLE | 0:0 | RW | 1 _h | Disables Auto Powerdown mode which automatically enters SLEEP or STANDBY mode when LOS is asserted. 0 _b : Device automatically enters SLEEP or STANDBY when LOS is 1 1 _b : Device only enters SLEEP or STANDBY when FORCE_PWRDN_SLEEP or FORCE_PWRDN_STANDBY are set to 1 |
| 18 _h | RESERVED | RSVD | 15:0 | RO | — | Reserved. |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|----------------------|----------------------|-----------|-----|----------------|---|
| | | RSVD | 15:8 | RW | 0 _h | Reserved. Do not change. |
| | | RSVD | 7:7 | RW | 1 _h | Reserved. Do not change. |
| | | AUTO_LOS_MUTE_ENABLE | 6:6 | RW | 0 _h | Auto-Mute Enable on LOS. 0 _b : Output is unaffected by LOS 1 _b : Output is muted when LOS is asserted |
| | | DDO1_MUTE | 5:5 | RW | 0 _h | Mute control for the DDO1 output. 0 _b : DDO1 output not muted 1 _b : DDO1 output muted Output across DDO1 and $\overline{DDO1}$ is static and of magnitude DDO1_SWING_MUTE/2 when DDO1_DISABLE is set to 0. |
| | | DDO0_MUTE | 4:4 | RW | 0 _h | Mute control for the DDO0 output. 0 _b : DDO0 output not muted 1 _b : DDO0 output muted Output across DDO0 and $\overline{DDO0}$ is static and of magnitude DDO0_SWING_MUTE/2 when DDO0_DISABLE is set to 0. |
| 19 _h | DRIVER_CONTROL_REG_0 | DDO1_DISABLE | 3:3 | RW | 0 _h | Disable control for the DDO1 output. 0 _b : DDO1 output not disabled 1 _b : DDO1 output disabled Output of both DDO1 and $\overline{DDO1}$ is VCC_DDO1. This bit takes precedence over DDO1_MUTE. |
| | | DDO0_DISABLE | 2:2 | RW | 0 _h | Disable control for the DDO0 output. 0 _b : DDO0 output not disabled 1 _b : DDO0 output disabled Output of both DDO0 and $\overline{DDO0}$ is VCC_DDO0. This bit takes precedence over DDO0_MUTE. |
| | | DDO1_DISABLE_SELECT | 1:1 | RW | 0 _h | Controls whether DDO1 is disabled using an assigned GPIO pin or the DDO1_DISABLE bit. 0 _b : DDO1 is disabled using assigned GPIO 1 _b : DDO1 is disabled using the DDO1_DISABLE bit |
| | | DDO0_DISABLE_SELECT | 0:0 | RW | 1 _h | Controls whether DDO0 is disabled using an assigned GPIO pin or the DDO0_DISABLE bit. 0 _b : DDO0 is disabled using assigned GPIO 1 _b : DDO0 is disabled using the DDO0_DISABLE bit |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|----------------------|-----------------------|-----------|-----|----------------|--|
| | | RSVD | 15:15 | RW | 0 _h | Reserved. Do not change. |
| | | DDO0_DEEMPHASIS_5G94 | 14:12 | RW | 2 _h | De-emphasis control for 5.94Gb/s (6Gb/s UHD-SDI) signals output on DDO0 000 _b : 0dB 001 _b : 0.3dB 010 _b : 0.6dB (default) 011 _b : 2.3 B 100 _b : 4.0dB 101 _b : 6.6dB 110 _b : 10.0dB |
| | | DDO0_DEEMPHASIS_2G97 | 11:9 | RW | 1 _h | De-emphasis control for 2.97Gb/s (3Gb/s SDI) signals output on DDO0 000 _b : 0dB 001 _b : 0.4dB (default) 010 _b : 1.5dB 011 _b : 3.2dB 100 _b : 4.9dB 101 _b : 7.6dB 110 _b : 11.0dB |
| 1A _h | DRIVER_CONTROL_REG_1 | DDO0_DEEMPHASIS_1G485 | 8:6 | RW | 1 _h | De-emphasis control for 1.485Gb/s (HD-SDI) signals output on DDO0 000 _b : 0dB 001 _b : 1.1dB (default) 010 _b : 2.4dB 011 _b : 4.0dB 100 _b : 5.7dB 101 _b : 8.2dB 110 _b : 11.5dB |
| | | DDO0_DEEMPHASIS_270M | 5:3 | RW | 0 _h | De-emphasis control for 0.27Gb/s (SD-SDI) signals output on DDO0 000 _b : 0dB (default) 001 _b : 1.2dB 010 _b : 2.5dB 011 _b : 4.1dB 100 _b : 6.0dB 101 _b : 8.5dB 110 _b : 12.0dB |
| | | DDO0_DEEMPHASIS_125M | 2:0 | RW | 0 _h | De-emphasis control for 0.125Gb/s (MADI) signals output on DDO0 000 _b : 0dB (default) 001 _b : 1.2dB 010 _b : 2.5dB 011 _b : 4.1dB 100 _b : 6.0dB 101 _b : 8.5dB 110 _b : 12.0dB |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|----------------------|-----------------------|-----------|-----|----------------|--|
| | | RSVD | 15:15 | RW | 0 _h | Reserved. Do not change. |
| | | DDO1_DEEMPHASIS_5G94 | 14:12 | RW | 2 _h | De-emphasis control for 5.94Gb/s (6Gb/s UHD-SDI) signals output on DDO1 000 _b : 0dB 001 _b : 0.3dB 010 _b : 0.6dB (default) 011 _b : 2.3 B 100 _b : 4.0dB 101 _b : 6.6dB 110 _b : 10.0dB |
| | | DDO1_DEEMPHASIS_2G97 | 11:9 | RW | 1 _h | De-emphasis control for 2.97Gb/s (3Gb/s SDI) signals output on DDO1 000 _b : 0dB 001 _b : 0.4dB (default) 010 _b : 1.5dB 011 _b : 3.2dB 100 _b : 4.9dB 101 _b : 7.6dB 110 _b : 11.0dB |
| 1B _h | DRIVER_CONTROL_REG_2 | DDO1_DEEMPHASIS_1G485 | 8:6 | RW | 1 _h | De-emphasis control for 1.485Gb/s (HD-SDI) signals output on DDO1 000 _b : 0dB 001 _b : 1.1dB (default) 010 _b : 2.4dB 011 _b : 4.0dB 100 _b : 5.7dB 101 _b : 8.2dB 110 _b : 11.5dB |
| | | DDO1_DEEMPHASIS_270M | 5:3 | RW | 0 _h | De-emphasis control for 0.27Gb/s (SD-SDI) signals output on DDO1 000 _b : 0dB (default) 001 _b : 1.2dB 010 _b : 2.5dB 011 _b : 4.1dB 100 _b : 6.0dB 101 _b : 8.5dB 110 _b : 12.0dB |
| | | DDO1_DEEMPHASIS_125M | 2:0 | RW | 0 _h | De-emphasis control for 0.125Gb/s (MADI) signals output on DDO1 000 _b : 0dB (default) 001 _b : 1.2dB 010 _b : 2.5dB 011 _b : 4.1dB 100 _b : 6.0dB 101 _b : 8.5dB 110 _b : 12.0dB |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|----------------------|-------------------|-----------|-----|----------------|---|
| | | RSVD | 15:12 | RW | 0 _h | Reserved. Do not change. |
| 1C _h | DRIVER_CONTROL_REG_3 | DDO0_SWING_1G485 | 11:8 | RW | 3 _h | Differential swing (amplitude) control for 1.485Gb/s (HD-SDI) signals output on DDO0. For details refer to Section 4.5.3 . |
| | | DDO0_SWING_270M | 7:4 | RW | 3 _h | Differential swing (amplitude) control for 0.27Gb/s (SD-SDI) signals output on DDO0. For details refer to Section 4.5.3 . |
| | | DDO0_SWING_125M | 3:0 | RW | 3 _h | Differential swing (amplitude) control for 0.125Gb/s (MADI) signals output on DDO0. For details refer to Section 4.5.3 . |
| 1D _h | DRIVER_CONTROL_REG_4 | DDO0_SWING_BYPASS | 15:12 | RW | 3 _h | Differential swing (amplitude) control for unlocked signals output on DDO0 (when reclocker is operating in BYPASS mode). For details refer to Section 4.5.3 . Takes precedence over rate-specific swing controls |
| | | DDO0_SWING_MUTE | 11:8 | RW | 3 _h | Differential static amplitude control for DDO0 when the output is muted. For details refer to Section 4.5.3 . Takes precedence over rate-specific swing controls and bypass swing control |
| | | DDO0_SWING_5G94 | 7:4 | RW | 3 _h | Differential swing (amplitude) control for 5.94Gb/s (6G UHD-SDI) signals output on DDO0. For details refer to Section 4.5.3 . |
| | | DDO0_SWING_2G97 | 3:0 | RW | 3 _h | Differential swing (amplitude) control for 2.97Gb/s (3Gb/s SDI) signals output on DDO0. For details refer to Section 4.5.3 . |
| | | RSVD | 15:12 | RW | 0 _h | Reserved. Do not change. |
| 1E _h | DRIVER_CONTROL_REG_5 | DDO1_SWING_1G485 | 11:8 | RW | 3 _h | Differential swing (amplitude) control for 1.485Gb/s (HD-SDI) signals output on DDO1. For details refer to Section 4.5.3 . |
| | | DDO1_SWING_270M | 7:4 | RW | 3 _h | Differential swing (amplitude) control for 0.27Gb/s (SD-SDI) signals output on DDO1. For details refer to Section 4.5.3 . |
| | | DDO1_SWING_125M | 3:0 | RW | 3 _h | Differential swing (amplitude) control for 0.125Gb/s (MADI) signals output on DDO1. For details refer to Section 4.5.3 . |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|----------------------|-------------------|-----------|-----|----------------|--|
| 1F _h | DRIVER_CONTROL_REG_6 | DDO1_SWING_BYPASS | 15:12 | RW | 3 _h | Differential swing (amplitude) control for unlocked signals output on DDO1 (when reclocker is operating in BYPASS mode). For details refer to Section 4.5.3 . Also applies when the device is not locked. Takes precedence over rate-specific swing controls |
| | | DDO1_SWING_MUTE | 11:8 | RW | 3 _h | Differential static amplitude control for DDO1 when the output is muted. For details refer to Section 4.5.3 . Takes precedence over rate-specific swing controls and bypass swing control |
| | | DDO1_SWING_5G94 | 7:4 | RW | 3 _h | Differential swing (amplitude) control for 5.94Gb/s (6G UHD-SDI) signals output on DDO1. For details refer to Section 4.5.3 . |
| | | DDO1_SWING_2G97 | 3:0 | RW | 3 _h | Differential swing (amplitude) control for 2.97Gb/s (3Gb/s SDI) signals output on DDO1. For details refer to Section 4.5.3 . |
| 20 _h | RECLOCKER_BYPASS | RSVD | 15:2 | RW | 0 _h | Reserved. Do not change. |
| | | MANUAL_BYPASS | 1:1 | RW | 0 _h | Used to manually bypass the retiming block in the reclocker. 0 _b : Retimer not bypassed 1 _b : Retimer bypassed The assertion of MANUAL_BYPASS takes precedence irrespective of the setting of AUTO_BYPASS |
| | | AUTO_BYPASS | 0:0 | RW | 1 _h | Selects between automatic and manual bypass of the retiming block when the reclocker is not locked. 0 _b : Auto-Bypass is disabled 1 _b : Auto-Bypass is enabled Even if AUTO_BYPASS is asserted, the assertion of MANUAL_BYPASS will still cause the retimer to be bypassed. |
| 21 _h | PD_CONTROL | RSVD | 15:7 | RW | 1 _h | Reserved. Do not change. |
| | | LOCK_SAMPLE | 6:6 | RW | 0 _h | Selects sampling method for LOCK DETECTION 0 _b : Strict sampling 1 _b : High-jitter sampling |
| | | RSVD | 5:1 | RW | 2 _h | Reserved. Do not change. |
| | | POLARITY_INVERT | 0:0 | RW | 0 _h | — |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|---------------|----------------|-----------|------|-------------------|--------------------------|
| 22 _h | RESERVED | RSVD | 15:0 | RW | 4208 _h | Reserved. Do not change. |
| 23 _h | RESERVED | RSVD | 15:0 | RW | 0 _h | Reserved. Do not change. |
| 24 _h | RESERVED | RSVD | 15:0 | ROSW | 0 _h | Reserved. Do not change. |
| 25 _h | RESERVED | RSVD | 15:0 | RW | 0 _h | Reserved. Do not change. |
| 26 _h | RESERVED | RSVD | 15:0 | RW | 2 _h | Reserved. Do not change. |
| 27 _h | RESERVED | RSVD | 15:0 | RW | A8B _h | Reserved. Do not change. |
| 28 _h | RESERVED | RSVD | 15:0 | RW | 3 _h | Reserved. Do not change. |
| 29 _h | RESERVED | RSVD | 15:0 | RW | 3 _h | Reserved. Do not change. |
| 2A _h | RESERVED | RSVD | 15:0 | RW | 3 _h | Reserved. Do not change. |
| 2B _h | RESERVED | RSVD | 15:0 | RW | 2 _h | Reserved. Do not change. |
| 2C _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 2D _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 2E _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 2F _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 30 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 31 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 32 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 33 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 34 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 35 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 36 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 37 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 38 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 39 _h | RESERVED | RSVD | 15:0 | RW | 2 _h | Reserved. Do not change. |
| 3A _h | RESERVED | RSVD | 15:0 | ROSW | 0 _h | Reserved. Do not change. |
| 3B _h | RESERVED | RSVD | 15:0 | RW | 0 _h | Reserved. Do not change. |
| 3C _h | RESERVED | RSVD | 15:0 | RW | 2 _h | Reserved. Do not change. |
| 3D _h | RESERVED | RSVD | 15:0 | RW | A8B _h | Reserved. Do not change. |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|---------------|----------------|-----------|-----|----------------|--------------------------|
| 3E _h | RESERVED | RSVD | 15:0 | RW | 3 _h | Reserved. Do not change. |
| 3F _h | RESERVED | RSVD | 15:0 | RW | 3 _h | Reserved. Do not change. |
| 40 _h | RESERVED | RSVD | 15:0 | RW | 0 _h | Reserved. Do not change. |
| 41 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. Do not change. |
| 42 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 43 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 44 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 45 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 46 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 47 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 48 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 49 _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 4A _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |
| 4B _h | RESERVED | RSVD | 15:0 | RO | 0 _h | Reserved. |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|---------------|-----------------------|-----------|-----|----------------|---|
| | | RSVD | 15:12 | RW | 0 _h | Reserved. Do not change. |
| | | LOS_DETECTION_METHOD | 11:10 | RW | 1 _h | Determines the source of CARRIER_DETECT. 00 _b : Edge detection 01 _b : Strength detection |
| | | FORCE_PLL_RATE | 9:7 | RW | 1 _h | Force the PLL to retime a specific data rate. 000 _b : Reserved 001 _b : 0.270Gb/s 010 _b : 1.485Gb/s 011 _b : 2.97Gb/s 100 _b : 5.94Gb/s 101 _b : Reserved 110 _b : Reserved 111 _b : Reserved Used when FORCE_PLL_RATE_ENABLE is set to 1. |
| | | FORCE_PLL_RATE_ENABLE | 6:6 | RW | 0 _h | Enables the forced PLL rate override set using the FORCE_PLL_RATE bits. |
| | | RATE_ENABLE_125M | 5:5 | RW | 0 _h | Enables auto-detection of 0.125Gb/s (MADI) signals 0 _b : 0.125Gb/s signals will not be detected 1 _b : 0.125Gb/s signals will be detected |
| 4C _h | PLL_CONTROL | RATE_ENABLE_5G94 | 4:4 | RW | 1 _h | Enables auto-detection of 5.94Gb/s (6G UHD-SDI) signals. 0 _b : 5.94Gb/s signals will not be detected 1 _b : 5.94Gb/s signals will be detected |
| | | RATE_ENABLE_2G97 | 3:3 | RW | 1 _h | Enables auto-detection of 2.97Gb/s (3G SDI) signals. 0 _b : 2.97Gb/s signals will not be detected 1 _b : 2.97Gb/s signals will be detected |
| | | RATE_ENABLE_1G485 | 2:2 | RW | 1 _h | Enables auto-detection of 1.485Gb/s (HD-SDI) signals. 0 _b : 1.485Gb/s signals will not be detected 1 _b : 1.485Gb/s signals will be detected |
| | | RATE_ENABLE_270M | 1:1 | RW | 1 _h | Enables auto-detection of 0.27Gb/s (SD-SDI) signals. 0 _b : 0.27Gb/s signals will not be detected 1 _b : 0.27Gb/s signals will be detected |
| | | PLL_SOFT_RESET | 0:0 | RW | 0 _h | Synchronous soft-reset for the PLL rate detection state machine. 0 _b : Normal operation of the PLL rate detection state machine 1 _b : Resets the PLL rate detection state machine |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|---------------|----------------|-----------|-----|------------------|--|
| 4D _h | RESERVED | RSVD | 15:0 | RW | 110 _h | Reserved. Do not change. |
| 4E _h | RESERVED | RSVD | 15:0 | RW | 110 _h | Reserved. Do not change. |
| 4F _h | PLL_STATUS | RETIMER_BYPASS | 15:15 | RO | — | Indicates whether the retimer is active or bypassed. 0 _b : Retimer is active 1 _b : Retimer is bypassed |
| | | LBR_HBR | 14:14 | RO | — | Indicates high-bit-rate versus low-bit-rate. 0 _b : Input data rate is 5.94Gb/s, 2.97Gb/s, 1.485Gb/s, or BYPASS 1 _b : Input data rate is 270Mb/s or 125Mb/s |
| | | DETECTED_RATE | 13:11 | RO | — | Indicates the current rate found by the PLL rate detection state machine. 000 _b : 0.125Gb/s 001 _b : 0.270Gb/s 010 _b : 1.485Gb/s 011 _b : 2.97Gb/s 100 _b : 5.94Gb/s 101 _b : Reserved 110 _b : Reserved 111 _b : Reserved |
| | | RSVD | 10:10 | RO | — | Reserved. |
| | | LOCKED | 9:9 | RO | — | Indicates if the CDR is locked or unlocked. 0 _b : CDR is unlocked 1 _b : CDR is locked |
| | | LOS | 8:8 | RO | — | Indicates whether or not the CDR has lost the signal. 0 _b : Signal is present 1 _b : Loss of signal |
| | | RSVD | 7:0 | RO | — | Reserved. |

Table 5-1: Register Descriptions - Standard Address Space (Continued)

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value | Description |
|-----------------|---------------|-----------------------|-----------|------|-------------|--|
| 50 _h | STICKY_STATUS | STANDBY_STICKY | 11:11 | ROCW | — | Sticky bit indicating that the device entered STANDBY mode at least once. 0 _b : Device has not entered STANDBY mode since this bit was last cleared 1 _b : Device has entered STANDBY mode since this bit was last cleared |
| | | SLEEP_STICKY | 10:10 | ROCW | — | Sticky bit indicating that the device entered SLEEP mode at least once 0 _b : Device has not entered SLEEP mode since this bit was last cleared 1 _b : Device has entered SLEEP mode since this bit was last cleared |
| | | RETIMER_BYPASS_STICKY | 9:9 | ROCW | — | Sticky bit indicating that the retimer is/has been bypassed. 0 _b : Retimer has not been bypassed since this bit was last cleared 1 _b : Retimer has been bypassed since this bit was last cleared This bit is cleared by writing any value to it. |
| | | LBR_HBR_STICKY | 8:8 | ROCW | — | Sticky bit indicating that the rate is/has been 270Mb/s (low bit-rate). 0 _b : Rate has not been 270Mb/s since this bit was last cleared 1 _b : Rate has been 270Mb/s since this bit was last cleared This bit is cleared by writing any value to it. |
| | | RATE_CHANGE_STICKY | 7:7 | ROCW | — | Sticky bit indicating that a rate change has occurred. 0 _b : Rate has not changed since this bit was last cleared 1 _b : Rate has changed since this bit was last cleared This bit is cleared by writing any value to it. |
| | | LOCK_LOST_STICKY | 6:6 | ROCW | — | Sticky bit indicating that lock was lost. 0 _b : Lock has not been lost since this bit was last cleared 1 _b : Lock has been lost since this bit was last cleared This bit is cleared by writing any value to it. |
| | | RSVD | 5:5 | ROCW | — | Reserved. |
| | | LOS_STICKY | 4:4 | ROCW | — | Sticky bit indicating a loss of signal. 0 _b : Signal has not been lost since this bit was last cleared 1 _b : Signal has been lost since this bit was last cleared This bit is cleared by writing any value to it. |
| | | RSVD | 3:0 | ROCW | — | Reserved. |

Table 5-2: Register Descriptions - Extended Address Space

| Address | Register Name | Parameter Name | Bit Slice | R/W | Reset Value (Dec) | Description |
|-----------------|-----------------------|--------------------|-----------|-----|-------------------|--|
| | | RSVD | 15:5 | RW | 4 _h | Reserved. Do not change. |
| E4 _h | PLL_LBW_CONTROL_REG_0 | PLL_LOOP_BANDWIDTH | 4:0 | RW | 4 _h | <p>Sets the rate specific PLL loop-bandwidth when the device is locked.</p> <p>00001_b: Nominal / 4 00010_b: Nominal / 2 00100_b: Nominal (default) 01000_b: Nominal x 2 11100_b: Nominal x 4</p> <p>See Table 2-3: AC Electrical Characteristics for the PLL loop-bandwidth value set at each rate by each of these settings.</p> |

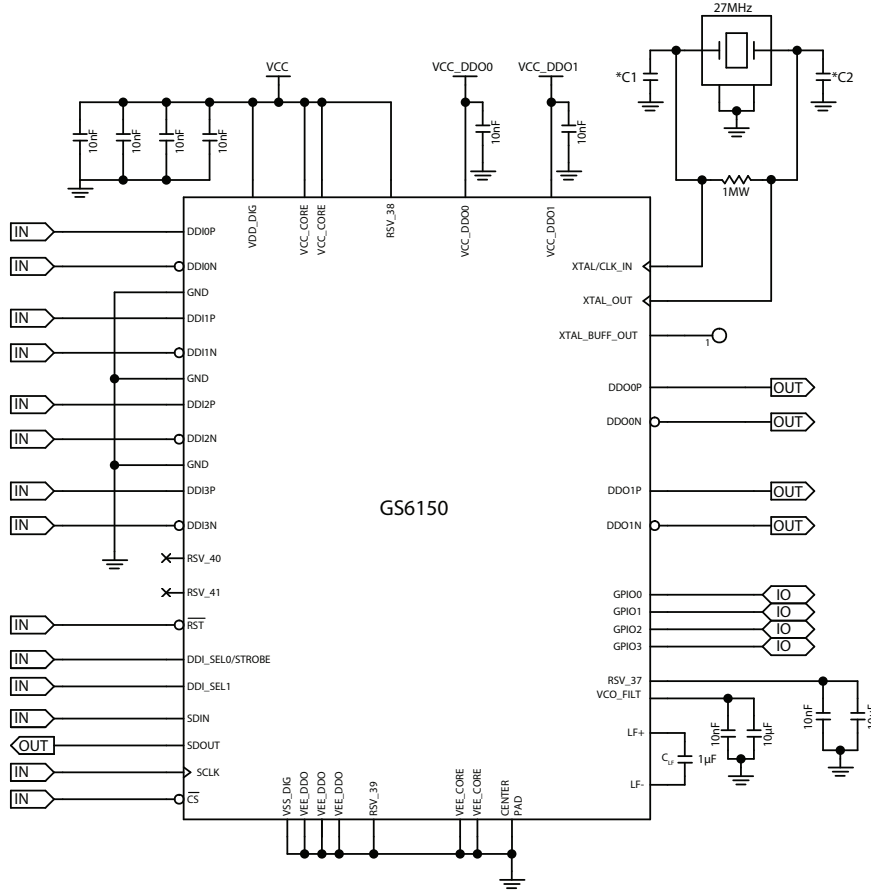
RW = Read/Write

RO = Read Only

ROCW = Read Only/ Clear on Write

ROSW = Read Only/ Set on Write

6. Typical Application Circuit

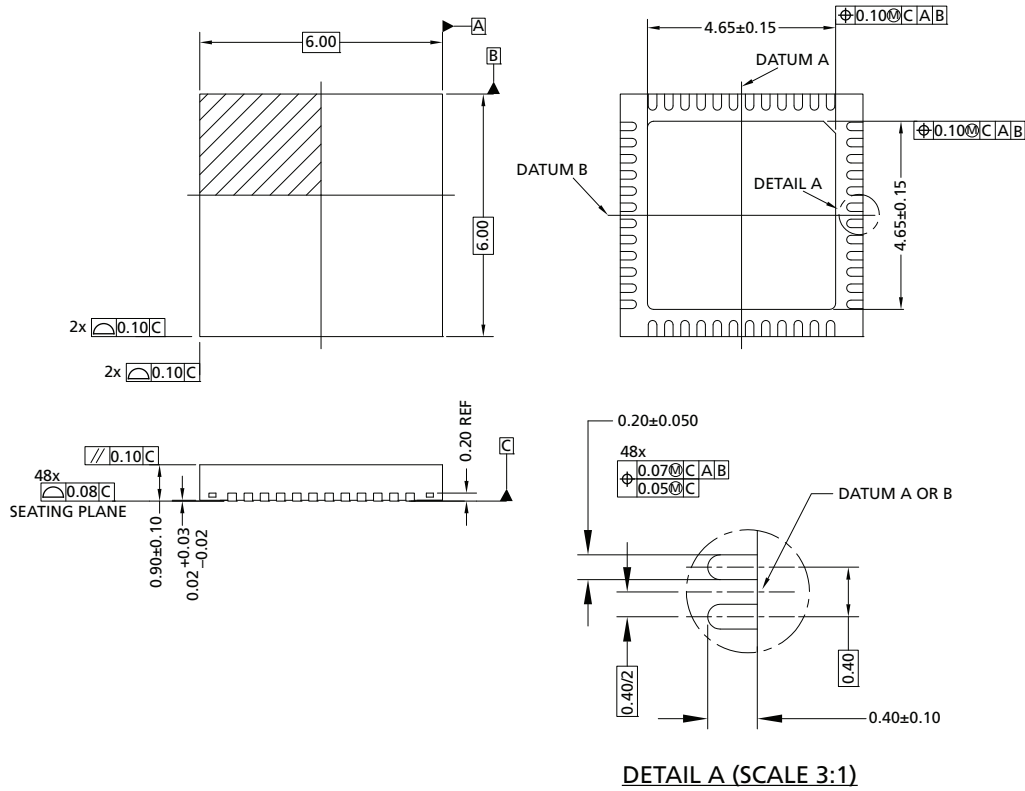


Notes:
 VCC IS 1.8V
 VCC_DDO0 AND VCC_DDO1 ARE IN THE RANGE +1.2V TO +2.5V
 XTAL IS OPTIONAL
 *VALUES FOR C1 AND C2 ARE CHOSEN BASED ON THE REQUIRED LOADING FOR THE SELECTED CRYSTAL
 IF AC COUPLING IS REQUIRED ON THE HIGH-SPEED SERIAL INPUTS AND OUTPUTS BY THE APPLICATION, A CERAMIC CAPACITOR 4.7μF OR HIGHER WITH A STABLE DIELECTRIC IS RECOMMENDED

Figure 6-1: GS6150 Typical Application Circuit

7. Package and Ordering Information

7.1 Package Dimensions



- NOTES:
1. DIMENSIONS AND TOLERANCE IS IN CONFORMANCE TO ASME Y14.5-1994
2. ALL DIMENSIONS ARE IN MILLIMETERS OR IN DEGREES

Figure 7-1: Package Dimensions

7.2 Recommended PCB Footprint

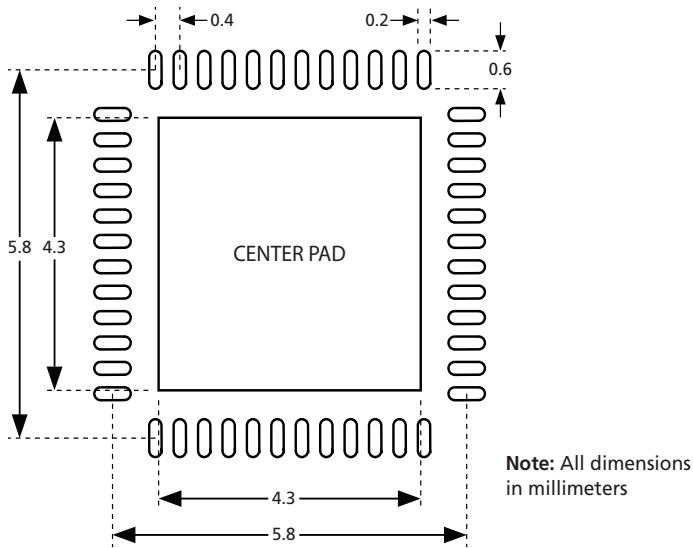


Figure 7-2: GS6150 PCB Footprint

7.3 Packaging Data

Table 7-1: Packaging Data

| Parameter | Value |
|--|----------------------|
| Package Type | 6mm x 6mm 48-pin QFN |
| Moisture Sensitivity Level (Note 1) | 3 |
| Junction to Case Thermal Resistance, θ_{j-c} | 26.2°C/W |
| Junction to Air Thermal Resistance, θ_{j-a} | 21.6°C/W |
| Junction to Board Thermal Resistance, θ_{j-b} | 4.4°C/W |
| Psi, Ψ | 0.2°C/W |
| Pb-free and RoHS Compliant | Yes |

Note:

1. Value per JEDEC J-STD-020C

7.4 Marking Diagram

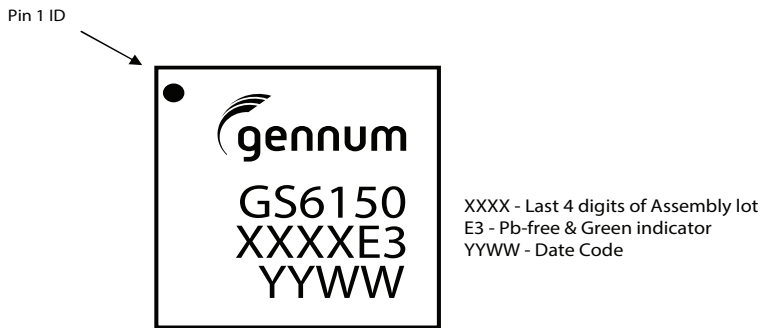


Figure 7-3: GS6150 Marking Diagram

7.5 Solder Reflow Profile

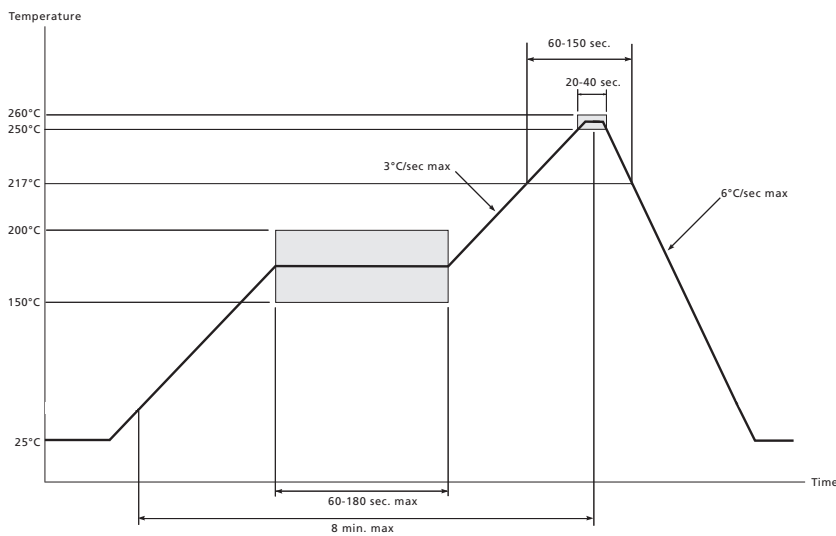


Figure 7-4: Maximum Pb-free Solder Reflow Profile

7.6 Ordering Information

Table 7-2: Ordering Information

| Part Number | Package | Temperature Range |
|---------------|--|-------------------|
| GS6150-INE3 | Pb-free 48-pin QFN | -40°C to 85°C |
| GS6150-INTE3 | Pb-free 48-pin QFN (250pc. tape and reel) | -40°C to 85°C |
| GS6150-INTE3Z | Pb-free 48-pin QFN (2.5k tape and reel) | -40°C to 85°C |



DOCUMENT IDENTIFICATION
FINAL DATA SHEET

The product is in production. Semtech reserves the right to make changes to the product at any time without notice to improve reliability, function or design, in order to provide the best product possible.

CAUTION

ELECTROSTATIC SENSITIVE DEVICES

DO NOT OPEN PACKAGES OR HANDLE EXCEPT AT A STATIC-FREE WORKSTATION



© Semtech 2014

All rights reserved. Reproduction in whole or in part is prohibited without the prior written consent of the copyright owner. The information presented in this document does not form part of any quotation or contract, is believed to be accurate and reliable and may be changed without notice. No liability will be accepted by the publisher for any consequence of its use. Publication thereof does not convey nor imply any license under patent or other industrial or intellectual property rights. Semtech assumes no responsibility or liability whatsoever for any failure or unexpected operation resulting from misuse, neglect improper installation, repair or improper handling or unusual physical or electrical stress including, but not limited to, exposure to parameters beyond the specified maximum ratings or operation outside the specified range.

SEMTECH PRODUCTS ARE NOT DESIGNED, INTENDED, AUTHORIZED OR WARRANTED TO BE SUITABLE FOR USE IN LIFE-SUPPORT APPLICATIONS, DEVICES OR SYSTEMS OR OTHER CRITICAL APPLICATIONS. INCLUSION OF SEMTECH PRODUCTS IN SUCH APPLICATIONS IS UNDERSTOOD TO BE UNDERTAKEN SOLELY AT THE CUSTOMER'S OWN RISK. Should a customer purchase or use Semtech products for any such unauthorized application, the customer shall indemnify and hold Semtech and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs damages and attorney fees which could arise.

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

Contact Information

Semtech Corporation
200 Flynn Road, Camarillo, CA 93012
Phone: (805) 498-2111, Fax: (805) 498-3804
www.semtech.com



Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



Как с нами связаться

Телефон: 8 (812) 309 58 32 (многоканальный)

Факс: 8 (812) 320-02-42

Электронная почта: org@eplast1.ru

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.