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**Features** 

## 12-Bit Plus Sign Temperature Sensors with SMBus/I2C-Compatible Serial Interface

### **General Description**

The MAX6633/MAX6634/MAX6635 combine a temperature sensor, a programmable overtemperature alarm, and an SMBus<sup>™</sup>/I<sup>2</sup>C<sup>™</sup>-compatible serial interface into a single package. They convert their die temperatures into digital values using internal analog-to-digital converters (ADCs). The result of the conversion is then held in a temperature register as a 12-bit + sign value, allowing 0.0625°C resolution, readable at any time through the serial interface. The devices are capable of reading temperatures up to +150°C.

The MAX6633/MAX6634/MAX6635 feature a shutdown mode that saves power by turning off everything except the power-on reset (POR) and the serial interface. The devices can be configured to separate addresses, allowing multiple devices to be used on the same bus.

The MAX6633 has four address pins, allowing up to 16 devices to be connected to a single bus. The MAX6634 has three address pins, allowing up to eight devices to be connected to a single bus. The MAX6635 has two address pins, allowing up to four devices to be connected to a single bus.

The MAX6633/MAX6634/MAX6635 make temperature data available for transfer over the serial interface. The MAX6634 incorporates a dual-mode ALERT output (open drain) and can serve as an upgraded alternative to the LM75. The MAX6635 includes an ALERT output and an OVERT output (both open drain) and can function as an upgraded replacement for the LM76 in most applications. The MAX6634/MAX6635 feature user-programmable temperature thresholds. All three devices come in an 8-pin SO package.

### **Applications**

**Battery Temperature Alarms** PC Temperature Control Automotive Equipment

Pin Configurations appear at end of data sheet.

SMBus is a trademark of Intel Corp. I<sup>2</sup>C is a trademark of Philips Corp.

♦ +3V to +5.5V Supply Range

**♦** Accuracy

±1°C max (0°C to +50°C)

±1.5°C max (-20°C to +85°C)

±2.5°C max (-40°C to +125°C)

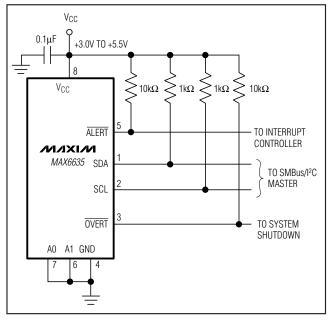
±2.5°C typ (+150°C)

- **♦** User-Programmable Temperature Thresholds (MAX6634/MAX6635)
- ◆ User-Configurable Alarm Output(s) (MAX6634/MAX6635)
- ♦ Ability to Respond to SMBus/I<sup>2</sup>C-Compatible Alert Response Address (MAX6634/MAX6635)
- ♦ OVERT Output for System Shutdown (MAX6635)
- ♦ Multiple Devices per Bus
  - **16 devices (MAX6633)**
  - 8 devices (MAX6634)
  - 4 devices (MAX6635)

### **Ordering Information**

PART	TEMP. RANGE	PIN-PACKAGE
MAX6633MSA	-55°C to +150°C	8 SO
MAX6634MSA	-55°C to +150°C	8 SO
MAX6635MSA	-55°C to +150°C	8 SO

## **Typical Operating Circuit**



#### **ABSOLUTE MAXIMUM RATINGS**

V <sub>CC</sub> , SDA, SCL0.3V to +6.0V	Junction Temperature+150°C
All Other Pins0.3V to V <sub>CC</sub> +0.3V	Operating Temperature Range55°C to +150°C
SDA, ALERT, OVERT Current1mA to +50mA	Storage Temperature Range65°C to +150°C
ESD Protection (Human Body Model)2000V	Lead Temperature (soldering, 10s)+300°C
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	• • • • • • • • • • • • • • • • • • • •
8-Pin SO (derate 5.88mW/°C above +70°C)471mW	

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{CC} = +3.0 \text{V to } +5.5 \text{V}, T_A = -55 ^{\circ}\text{C} \text{ to } +125 ^{\circ}\text{C}, \text{ unless otherwise noted.}$  Typical values are  $V_{CC} = +3.3 \text{V}, T_A = +25 ^{\circ}\text{C}, \text{ unless otherwise noted.})$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
TEMPERATURE-TO-DIGITAL CO	NVERTER	CHARACTERISTICS	•			
Supply Range	Vcc		3.0		5.5	V
		$0^{\circ}\text{C} \le \text{T}_{A} = \le +50^{\circ}\text{C}, \text{ V}_{CC} = +3.3\text{V}$	-1.0	±0.4	+1.0	
		$-20^{\circ}\text{C} \le \text{T}_{\text{A}} = \le +85^{\circ}\text{C}, \text{ V}_{\text{CC}} = +3.3\text{V}$	-1.5	±0.6	+1.5	
Accuracy (Note 1)		$-40^{\circ}\text{C} \le \text{T}_{\text{A}} = \le 125^{\circ}\text{C}, \text{V}_{\text{CC}} = +3.3\text{V}$	-2.5	±1.0	+2.5	°C
		T <sub>A</sub> = -55°C, V <sub>CC</sub> = +3.3V		±1.5	+2.8	
		$T_A = +150$ °C, $V_{CC} = +3.3V$		±2.5		
Power-Supply Rejection Ratio	PSRR			0.2	0.5	°C/V
POR Threshold Hysteresis				90		mV
Cupaly Current in Chutdown		V <sub>CC</sub> = +3.0V, SMBus inactive		12	20	
Supply Current in Shutdown		V <sub>CC</sub> = +5.5V, SMBus inactive		20	30	μA
Average Operating Current		V <sub>CC</sub> = +3.0V, SMBus inactive		150		μΑ
Average Operating Ourrent		V <sub>CC</sub> = +5.5V, SMBus inactive		200		μΛ
Peak Operating Current (Note 2)		V <sub>CC</sub> = +3.0V, SMBus inactive		270	350	μΑ
Teak Operating Current (Note 2)		V <sub>CC</sub> = +5.5V, SMBus inactive		350	700	μΛ
Conversion Rate			1.4	2	2.4	Hz
DIGITAL INTERFACE						
Logic Input Low Voltage	VIL	$V_{CC} = +3.0V \text{ to } +5.5V$			0.65	V
Logic Input High	VIH	$V_{CC} = +3V$	2.2			V
Voltage	VIH	$V_{CC} = +5.5V$	2.4			
Input Leakage Current	I <sub>L</sub> LEAK	V <sub>IN</sub> = GND or V <sub>CC</sub>			±1	μΑ
Output Low Sink Current	I <sub>OL</sub>	V <sub>OL</sub> = 0.6V (SMBDATA, ALERT, OVERT)	6			mA
Output Leakage Current	IO_LEAK	ALERT, OVERT at VCC			±1	μΑ
Input Capacitance	C <sub>IN</sub>			5		рF

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### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{CC} = +3.0 \text{V to } +5.5 \text{V}, T_A = -55 ^{\circ}\text{C} \text{ to } +125 ^{\circ}\text{C}, \text{ unless otherwise noted.}$  Typical values are  $V_{CC} = +3.3 \text{V}, T_A = +25 ^{\circ}\text{C}, \text{ unless otherwise noted.}$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SMBus TIMING (Note 3, Figures	1, 2, and 3)					
Serial Clock Frequency	fscl		10		100	kHz
Bus Free Time Between STOP and START Condition	tBUF		4.7			μs
START Condition Setup Time			4.7			μs
Repeat START Condition Setup Time	tsu:sta	90% to 90%	4.7			μs
START Condition Hold Time	thd:STA	10% of SMBDATA to 90% of SMBCLK	4			μs
STOP Condition Setup Time	tsu:sto	90% of SMBCLK to 10% of SMBDATA	4			μs
Data Setup Time	tsu: DAT	90% of SMBDATA to 10% of SMBCLK	250			ns
Data Hold Time (Note 4)	thd: dat		300			ns
Receive SCL/SDA Rise Time	t <sub>R</sub>				1	μs
SCL/SDA Fall Time (Note 4)	tF				300	ns
Clock Low Period	tLOW	10% to 10%	4.7			μs
Clock High Period	thigh	90% to 90%	4			μs
SMBus Timeout			25		48	ms

**Note 1:** Guaranteed by design and characterization.

Note 2: Peak operating current measured during conversion. See Figure 4.

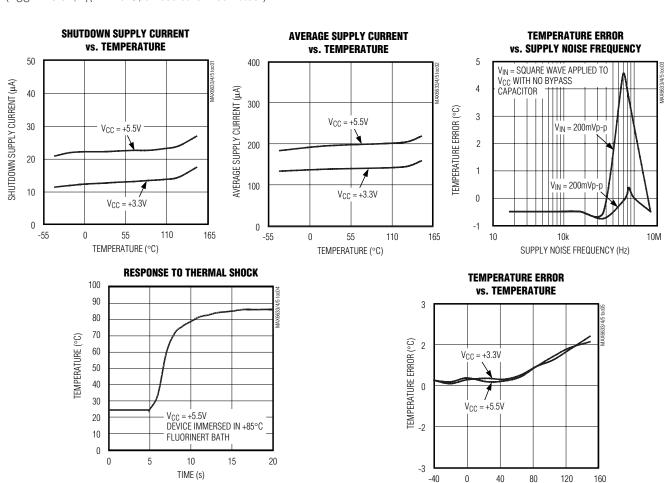
Note 3: Guaranteed by design, not production tested.

Note 4: A master device must provide a hold time of at least 300ns for the SDA signal in order to bridge the undefined region of SCL's falling edge.

Typical Operating Characteristics

TEMPERATURE (°C)

 $(V_{CC} = +3.3V, T_A = +25^{\circ}C, \text{ unless otherwise noted.})$ 



### **Pin Description**

	PIN		NAME	FUNCTION
MAX6633	MAX6634	MAX6635	NAME	FUNCTION
1	1	1	SDA	Serial Data Input/Output. Open drain.
2	2	2	SCL	Serial Clock Input
3	_	_	A3	Address Pin
4	4	4	GND	Ground
5	5	_	A2	Address Pin
6	6	6	A1	Address Pin
7	7	7	A0	Address Pin
8	8	8	Vcc	Supply Voltage Input. +3.0V to +5.5V. Bypass V <sub>CC</sub> to GND with a 0.1µF capacitor.
_	3	5	ALERT	ALERT Output. Open drain.
_	_	3	OVERT	OVERT Output. Open drain.

### **Detailed Description**

The MAX6633/MAX6634/MAX6635 continuously convert their die temperatures into digital values using their integrated ADCs. The resulting data is readable at any time through the SMBus/I<sup>2</sup>C-compatible serial interface. The device functions as a slave on the SMBus interface, supporting Write Byte, Write Word, Read Byte, and Read Word commands. Separate addresses can be configured using the individual address pins. Figures 5, 6, and 7 show the functional diagrams of the MAX6633/MAX6634/MAX6635, respectively.

#### SMBus/I<sup>2</sup>C-Compatible Operation

The MAX6633/MAX6634/MAX6635 are readable and programmable through their SMBus/I<sup>2</sup>C-compatible serial interface. Figures 1, 2, and 3 show the timing details of the clock (SCL) and data (SDA) signals. The devices function as slaves on the SMBus and support Write Byte, Write Word, Read Byte, and Read Word commands. Figure 8 is the MAX6633/MAX6634/MAX6635 programmer's model.

#### **Addressing**

Separate addresses can be configured using the individual address pins. The address of each device is selected by connecting the address (A\_) pins to one of two potentials: GND or V<sub>CC</sub>. The MAX6635 makes two address pins available (A0, A1), allowing up to four devices to be connected to a single bus line. The MAX6634 makes three address pins available (A0, A1, A2), allowing up to eight devices to be connected to a single bus line. The MAX6633 makes four address pins available (A0, A1, A2, A3), allowing as many as 16

devices to be connected to a single bus line. Table 1 shows the full SMBus/I<sup>2</sup>C address for each device type.

### **Control Registers (MAX6633)**

Three registers control the operation of the MAX6633 (Figure 5 and Tables 2 through 6). The Pointer register is the first addressed and determines which of the other two registers is acted upon. The other two are the Temperature and Configuration registers. The temperature value is stored as 12 bits plus a sign bit, read only, and contains the latest temperature data. The true register length is 16 bits, with the lower 3 unused in this part. The digital temperature data contained in the temperature register is in °C, using a two's-complement format with 1LSB corresponding to 0.0625°C.

The Configuration register is 8 bits, read/write, and contains the SMBus timeout disable bit, fault queue enable bit, and the shutdown bit.

#### **Control Registers (MAX6634)**

Six registers control the operation of the MAX6634 (Figure 6 and Tables 2 through 7). The pointer register is the first addressed and determines which of the other five registers is acted upon. The other five are the Temperature, Configuration, High-Temperature (THIGH), Low-Temperature (TLOW), and Hysteresis (THYST) registers. The temperature value is stored as 12 bits plus a sign bit, read only, and contains the latest temperature data. The true register length is 16 bits, with the lowest 2 used as status bits, and the third bit (D2) is unused. The digital temperature data contained in the temperature register is in °C, using a two's-complement format with 1LSB corresponding to 0.0625°C.

Write B	yte Format							
S	ADDRESS WR A		ACK	COMMAND	ACK	DATA	ACK	Р
	7 bits			8 bits		8 bits		
	Slave Address equivalent to chip-select wire interface			Command Byte: register you are v		Data Byte: data command byte	O .	e register set by the

#### **Write Word Format**

S	ADDRESS	WR	ACK	COMMAND	ACK	DATA	ACK	DATA	ACK	Р
	7 bits			8 bits		8 bits (MSB)		8 bits (LSB)		
	Slave Address equivalent to d line of a 3-wire interfac	chip-select		Command Byt selects registe are writing to		Data Byte register se byte	_	es into the ommand		

#### **Read Byte Format**

S	ADDRESS	WR	ACK	COMMAND	ACK	s	ADDRESS	RD	ACK	DATA	///	Р
	7 bits			8 bits			7 bits			8 bits		
	7 bits  Slave Address: equivalent to chip-select line		alent	Command Byte selects register are reading from	er you		Slave Addres change in da			Data Byte: re register set b byte		

#### **Read Word Format**

S	ADDRESS	WR	ACK	COMMAND	ACK	S	ADDRESS	RD	ACK	DATA	ACK	DATA	///	Р
	7 bits			8 bits			7 bits			8 bits		8 bits		
										(MSB)		(LSB)		
	Slave Address:			Command Byt		Slave Addres	s: repe	ated	Data By	tes: read	s from the			
	equivalent to	ent to chip- selects register you		er you		due to chang	e in da	ta-flow	register set by the comma			nd		
	select line			are reading fro	om		direction			byte				

S = Start condition Shaded = Slave transmission
P = Stop condition /// = Not acknowledged

Figure 1. SMBus Protocols

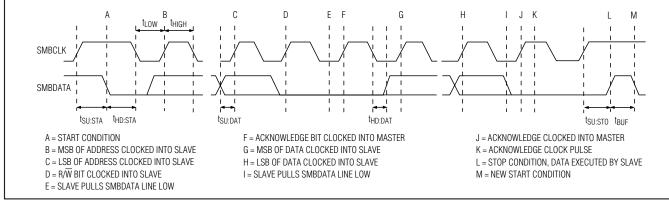


Figure 2. SMBus Write Timing Diagram

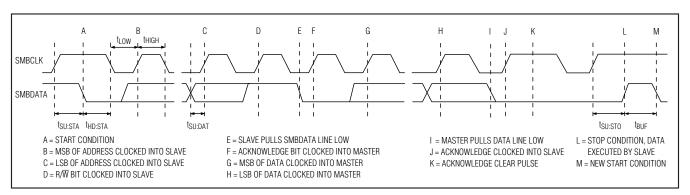


Figure 3. SMBus Read Timing Diagram

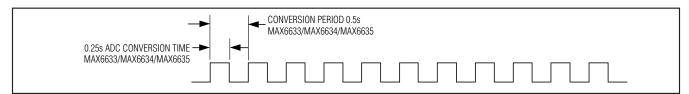


Figure 4. ADC Conversion Timing Diagram

The Configuration register is 8 bits, read/write, and contains the SMBus timeout disable bit, fault queue enable bit, the temperature alarm output polarity select bits, the interrupt mode select bit, and the shutdown bit. Registers THIGH and TLOW are 16 bits, read/write, and contain the values that trigger ALERT. Register THYST is 16 bits, read/write, and contains the values by which the temperature must rise or fall beyond THIGH or TLOW, before ALERT deasserts.

#### **Control Registers (MAX6635)**

Seven registers control the operation of the MAX6635 (Figure 7 and Tables 2 through 7). The Pointer register is the first addressed and determines which of the other six registers is acted upon. The other six are the Temperature, Configuration, High-Temperature (T<sub>HIGH</sub>), Low-Temperature (T<sub>LOW</sub>), Maximum Temperature (T<sub>MAX</sub>), and Hysteresis (T<sub>HYST</sub>) registers. The temperature value is stored as 12 bits plus a sign bit, read only, and contains the latest temperature data. The true register length is 16 bits, with the lower three used as status bits. The digital temperature data contained in the temperature register is in °C, using a two's-complement format with 1LSB corresponding to 0.0625°C.

The Configuration register is 8 bits, read/write, and contains the SMBus timeout disable bit, fault queue enable bit, the temperature alarm output polarity select bits, the interrupt mode select bit, and the shutdown

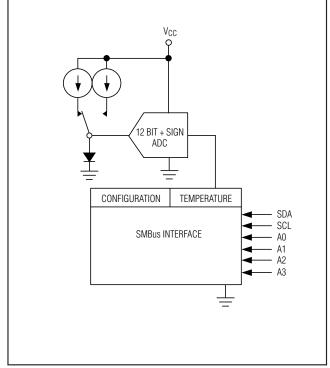


Figure 5. MAX6633 Functional Diagram

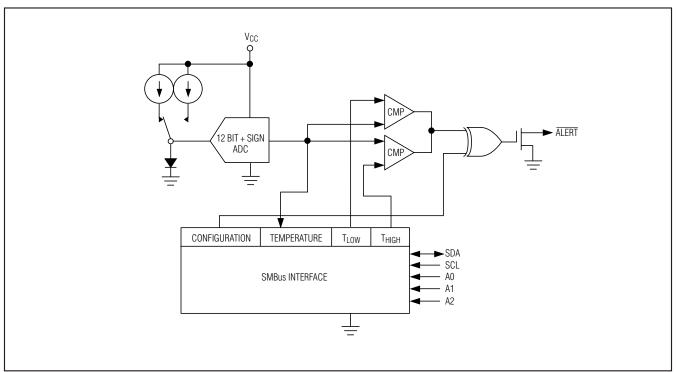


Figure 6. MAX6634 Functional Diagram

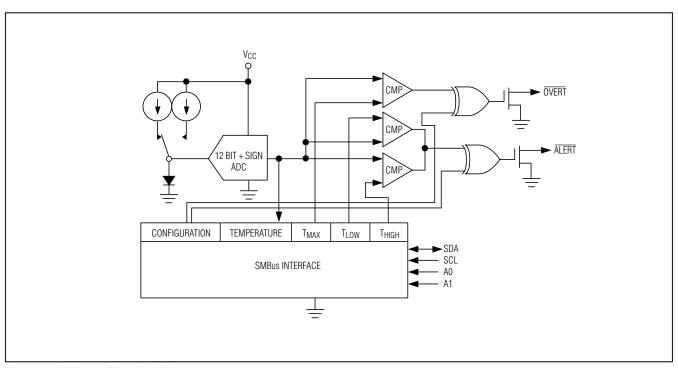


Figure 7. MAX6635 Functional Diagram

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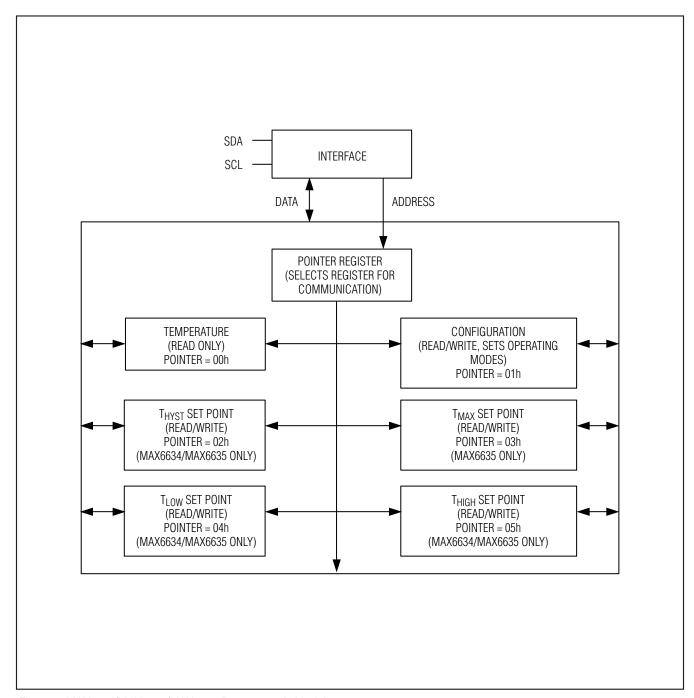


Figure 8. MAX6633/MAX6634/MAX6635 Programmer's Model

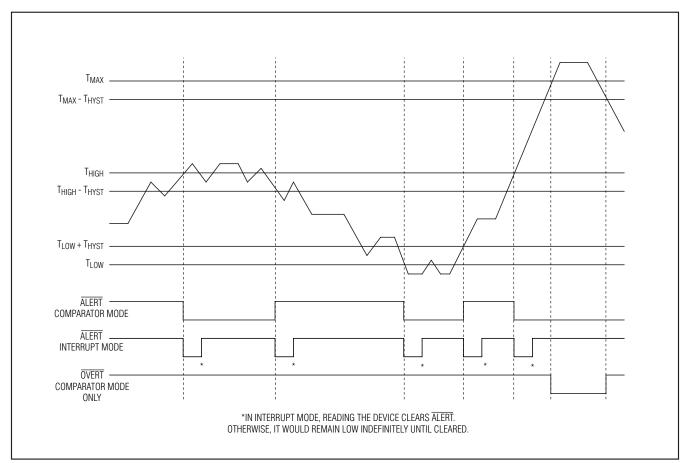


Figure 9. Alarm Output and Reset Diagram

bit. Registers T<sub>HIGH</sub> and T<sub>LOW</sub> are 16 bits, read/write, and contain values that trigger ALERT and OVERT. Register T<sub>HYST</sub> is 16 bits, read/write, and contains the values by which the temperature must rise or fall beyond T<sub>HIGH</sub>, T<sub>LOW</sub>, or T<sub>MAX</sub>, before ALERT or OVERT deassert.

#### **Temperature Conversion**

An on-chip bandgap reference produces a signal proportional to absolute temperature (PTAT), as well as the temperature-stable reference voltage necessary for the analog-to-digital conversion. The PTAT signal is digitized by the on-board ADC to a resolution of 0.0625°C. The resulting digital value is placed in the Temperature register. The temperature conversion runs continuously and asynchronously from the serial interface at a rate of 500ms per conversion. When the Temperature register is read, the conversion in progress is aborted. The bus transaction is completed by a stop condition.

#### Fault Queue (MAX6634/MAX6635)

A programmable fault queue on the MAX6634/ MAX6635 eliminates spurious alarm activity in noisy environments. The queue sets the number of consecutive out-of-tolerance temperature readings that must occur before the ALERT or OVERT alarm outputs are toggled. An out-of-tolerance reading is above THIGH or TMAX or below TLOW. The fault queue depth defaults to 1 at power-up and may be programmed—through the Configuration register—to four consecutive conversions. Any time the conversion result is in tolerance, and the particular alarm output is not asserted, the queue is cleared, even if it contains some out-of-tolerance counts. Additionally, the fault queue automatically clears at power-up and in shutdown. Whenever the fault queue is cleared, the alarm outputs are deasserted. Figure 9 is the alarm output and reset diagram.

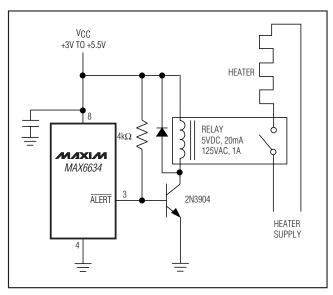


Figure 10. Simple Thermostat

# Temperature Alert (MAX6634/MAX6635)

ALERT has programmable polarity and two modes: comparator and interrupt. Polarity and mode are selected through the Configuration register (Table 4). The ALERT output is open drain.

#### Interrupt Mode

With ALERT in interrupt mode, the MAX6634/MAX6635 look for a Thigh or a TLOW fault. The ALERT pin asserts an alarm for an undertemperature fault, as well as for an overtemperature fault. Once either fault has occurred, it remains active until deasserted by a read of any register. The device then begins to look for a temperature change crossing the hysteresis level. The activation of ALERT is subject to the depth of the fault queue.

For example: If THIGH is set to 100°C, THYST is set to 20°C, and the fault queue depth is set to 4, ALERT does not assert until four consecutive conversions exceed 100°C. If the temperature is then read through the I<sup>2</sup>C-compatible interface, ALERT deasserts. ALERT asserts again when four consecutive conversions are less than 80°C.

#### Comparator Mode

In comparator mode,  $\overline{\text{ALERT}}$  is asserted when the number of consecutive conversions exceeding the value in the Thigh register, or lower than the value in the TLOW register, is equal to the depth of the fault queue.  $\overline{\text{ALERT}}$  deasserts when the number of consecutive conversions

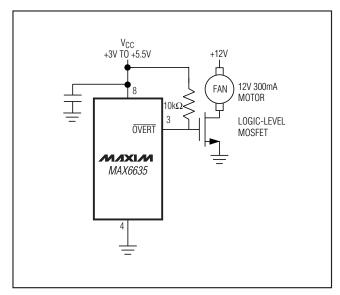


Figure 11. Fan Controller

less than  $T_{HIGH}$  -  $T_{HYST}$  or greater than  $T_{LOW}$  +  $T_{HYST}$  is equal to the depth of the fault queue.

For example: If Thigh is set to 100°C, TLOW is set to 80°C, and the fault queue depth is set to four, ALERT does not assert until four consecutive conversions exceed 100°C, or are below 80°C. ALERT only deasserts if four consecutive conversions are less than Thigh - Thyst or greater than TLOW + Thyst.

Comparator mode allows autonomous clearing of an ALERT fault without the intervention of a master and is ideal to use for driving a thermostat (Figure 10).

#### **Overtemperature Alarm (MAX6635)**

The MAX6635 also includes an overtemperature output that is always in comparator mode. Whenever the temperature exceeds a value in the programmable TMAX register, OVERT is asserted. OVERT only deasserts after the temperature drops below TMAX - THYST. When the fault queue is activated, OVERT is subject to that queue, which sets the number of faults that must occur before OVERT asserts or deasserts. This helps prevent spurious alarms in noisy environments.

Comparator mode also allows autonomous clearing of an OVERT fault without the intervention of a master and thus is ideal to use for driving a cooling fan (Figure 11). In this application, the polarity of OVERT is active high.

#### Shutdown

The MAX6633/MAX6634/MAX6635 feature a shutdown mode, accessible through the serial interface that saves power by turning off everything except the POR

and the serial interface. Enter shutdown by programming the shutdown bit of the Configuration register high. While in shutdown, the Temperature register retains the last conversion result and can be read at any time. The ADC is turned off, reducing the device current draw to 30µA (max). The outputs of ALERT and OVERT are latched upon entering shutdown, and the fault queue is held in reset. After coming out of shutdown, the Temperature register continues to read the last converted temperature, until the next conversion result is available.

#### **Thermal Considerations**

The MAX6633/MAX6634/MAX6635 supply current is typically 200µA when the serial interface is inactive. When used to drive high-impedance loads, the devices dissipate negligible power; therefore, the die temperature is essentially the same as the package temperature. The key to accurate temperature monitoring is good thermal contact between the MAX6633/MAX6634/MAX6635 package and the monitored device or circuit. Heat flows in and out of plastic packages primarily through the leads. Short, wide copper traces leading to the temperature monitor ensure that heat transfers quickly and reliably. The rise in die temperature due to self-heating is given by the following formula:

#### $\Delta T_J = PDISSIPATION \times \theta_{JA}$

where PDISSIPATION is the power dissipated by the MAX6633/MAX6634/MAX6635, and  $\theta_{JA}$  is the package's thermal resistance.

The typical thermal resistance is 170°C/W for the 8-pin SO package. To limit the effects of self-heating, minimize the output currents. For example, if the MAX6634/MAX6635 sink 4mA with the maximum  $\overline{\text{ALERT}}$  VL specification of 0.8V, an additional 3.2mW of power is dissipated within the IC. This corresponds to a 0.54°C rise in the die temperature.

### **Applications Information**

Figure 10 shows the MAX6634 used as a simple thermostat to control a heating element. Figure 11 shows the MAX6635 used as a temperature-triggered fan controller.

Chip Information

TRANSISTOR COUNT: 12,085

PROCESS: BICMOS

**Table 1. Address Selection** 

		MAX663	3	
A3	A2	A1	A0	ADDRESS
GND	GND	GND	GND	1000 000
GND	GND	GND	Vcc	1000 001
GND	GND	Vcc	GND	1000 010
GND	GND	Vcc	Vcc	1000 011
GND	Vcc	GND	GND	1000 100
GND	Vcc	GND	Vcc	1000 101
GND	Vcc	Vcc	GND	1000 110
GND	Vcc	Vcc	Vcc	1000 111
Vcc	GND	GND	GND	1001 000
Vcc	GND	GND	Vcc	1001 001
Vcc	GND	Vcc	GND	1001 010
Vcc	GND	Vcc	Vcc	1001 011
Vcc	Vcc	GND	GND	1001 100
Vcc	Vcc	GND	Vcc	1001 101
Vcc	Vcc	Vcc	GND	1001 110
Vcc	Vcc	Vcc	Vcc	1001 111
		MAX663	4	
	A2	A1	A0	ADDRESS
	GND	GND	GND	1001 000
	GND	GND	Vcc	1001 001
	GND	Vcc	GND	1001 010
	GND	Vcc	Vcc	1001 011
	Vcc	GND	GND	1001 100
	Vcc	GND	Vcc	1001 101
	Vcc	Vcc	GND	1001 110
	Vcc	Vcc	Vcc	1001 111
	ı	MAX663	5	1
		<b>A</b> 1	A0	ADDRESS
		GND	GND	1001 000
		GND	Vcc	1001 001
		Vcc	GND	1001 010
		Vcc	Vcc	1001 011

**Table 2. Pointer Register Bit Assignments** 

ADDRESS	DESCRIPTION	POR STATE
00h	Temperature register (READ only)	0000h
01h	Configuration-Byte register	00h
02h	T <sub>HYST</sub> register	0100h
03h	T <sub>MAX</sub> register	2800h
04h	T <sub>LOW</sub> register	0500h
05h	T <sub>HIGH</sub> register	2000h

### **Table 3. Temperature Register**

D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
MSB (Sign)	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	T <sub>MAX</sub>	THIGH	T <sub>LOW</sub>

D15: MSB is the first sign bit.

D2, D1, D0: Flag bits for T<sub>MAX</sub>, T<sub>HIGH</sub>, T<sub>LOW</sub>.

1LSB = 0.0625°C.

Temperature is stored in two's complement format.

## **Table 4. Configuration Register**

D7	D6	D5	D4	D3	D2	D1	D0
0	0	SMB Timeout Disable	Fault Queue Enable	ALERT Polarity	OVERT Polarity	Comparator or Interrupt	Shutdown

Power-on default = 0h.

D0: 0 = normal operation; 1 = shutdown.

D1: 0 = comparator mode; 1 = interrupt mode.

D2 to D3: 0 = active low; 1 = active high.

D5: 0 = normal SMBus operation;  $1 = \text{full } I^2C \text{ compatibility}$ .

D7 to D6: Reserved locations, always write zeros.

**Table 5. Fault Queue Depth** 

D4	NO. OF FAULTS					
0	1 (DEFAULT)					
1	4					

### **Table 6. Output Code vs. Temperature**

TEMP (OC)	DIGITAL OUTPUT CODE							
TEMP. (°C)	BIN	HEX						
	MSB	LSB						
+150.0000	0100 1011	0000 0XXX	4B00					
+125.0000	0011 1110	1000 0XXX	3E80					
+25.0000	0000 1100	1000 0XXX	0C80					
+0.0625	0000 0000	0000 1XXX	8000					
0.0000	0000 0000	0000 0XXX	0000					
-0.0625	1111 1111	1111 1XXX	FFF8					
-25.0000	1111 0011	0111 0XXX	F370					
-55.0000	1110 0100	0111 0XXX	E470					

### Table 7. THIGH, TLOW, TMAX, and THYST Registers

D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
MSB (Sign)	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	LSB	0	0	0	0	0	0	0

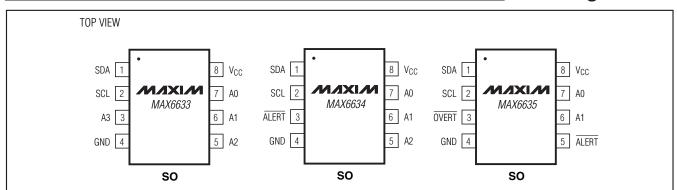
D6 to D0: Reads all zeros, cannot be written.

 $1LSB = 1^{\circ}C.$ 

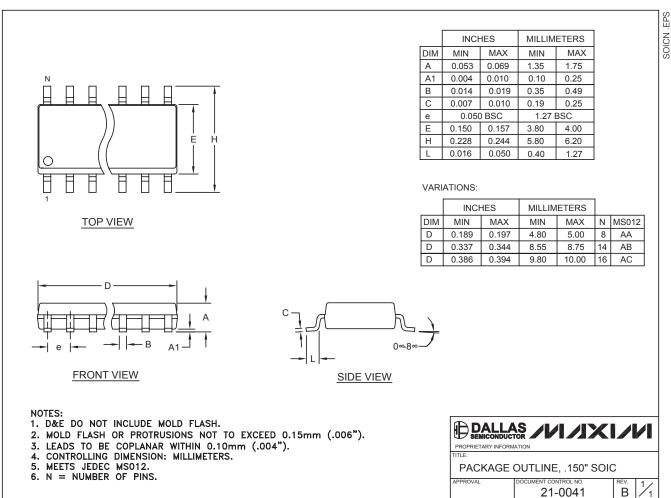
Power-On Default:  $T_{HIGH} = +64^{\circ}C$  (2000h),  $T_{LOW} = +10^{\circ}C$  (0500h),  $T_{MAX} = +80^{\circ}C$  (2008h),  $T_{HYST} = 2^{\circ}C$  (0100h).

\_\_\_\_\_\_/N/XI/M

## **Pin Configurations**



### Package Information



Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.



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#### Наши преимущества:

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- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001:
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

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- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



#### Как с нами связаться

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