

General Description

The MAX186/MAX188 are 12-bit data-acquisition systems that combine an 8-channel multiplexer, high-bandwidth track/hold, and serial interface together with high conversion speed and ultra-low power consumption. The devices operate with a single +5V supply or dual $\pm5V$ supplies. The analog inputs are software configurable for unipolar/bipolar and single-ended/differential operation.

The 4-wire serial interface directly connects to SPI[™], QSPI[™] and Microwire[™] devices without external logic. A serial strobe output allows direct connection to TMS320 family digital signal processors. The MAX186/MAX188 use either the internal clock or an external serial-interface clock to perform successive-approximation A/D conversions. The serial interface can operate beyond 4MHz when the internal clock is used.

The MAX186 has an internal 4.096V reference while the MAX188 requires an external reference. Both parts have a reference-buffer amplifier that simplifies gain trim .

The MAX186/MAX188 provide a hard-wired \overline{SHDN} pin and two software-selectable power-down modes. Accessing the serial interface automatically powers up the devices, and the quick turn-on time allows the MAX186/MAX188 to be shut down between every conversion. Using this technique of powering down between conversions, supply current can be cut to under 10µA at reduced sampling rates.

The MAX186/MAX188 are available in 20-pin DIP and SO packages, and in a shrink small-outline package (SSOP), that occupies 30% less area than an 8-pin DIP. For applications that call for a parallel interface, see the MAX180/MAX181 data sheet. For anti-aliasing filters, consult the MAX274/MAX275 data sheet.



High-Accuracy Process Control

Automatic Testing

Data-Acquisition

Portable Data Logging

Robotics

- Battery-Powered Instruments
- Medical Instruments

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Low-Power, 8-Channel, Serial 12-Bit ADCs

_Features

- 8-Channel Single-Ended or 4-Channel Differential Inputs
- Single +5V or ±5V Operation
- Low Power: 1.5mA (operating mode) 2μA (power-down mode)
- Internal Track/Hold, 133kHz Sampling Rate
- Internal 4.096V Reference (MAX186)
- SPI-, QSPI-, Microwire-, TMS320-Compatible 4-Wire Serial Interface
- ♦ Software-Configurable Unipolar or Bipolar Inputs
- 20-Pin DIP, SO, SSOP Packages
- Evaluation Kit Available

_Ordering Information

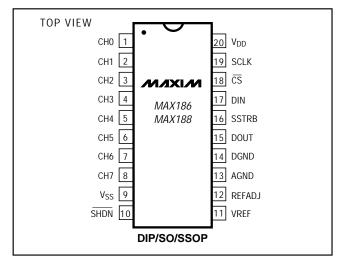
PART [†]	TEMP. RANGE	PIN-PACKAGE
MAX186_CPP	0°C to +70°C	20 Plastic DIP
MAX186_CWP	0°C to +70°C	20 SO
MAX186_CAP	0°C to +70°C	20 SSOP
MAX186DC/D	0°C to +70°C	Dice*
MAX186_EPP	-40°C to +85°C	20 Plastic DIP
MAX186_EWP	-40°C to +85°C	20 SO
MAX186_EAP	-40°C to +85°C	20 SSOP
MAX186_MJP	-55°C to +125°C	20 CERDIP**

Ordering Information continued on last page.

 NOTE: Parts are offered in grades A, B, C and D (grades defined in Electrical Characteristics). When ordering, please specify grade. Contact factory for availability of A-grade in SSOP package.
 * Dice are specified at +25°C, DC parameters only.

* * Contact factory for availability and processing to MIL-STD-883.

Pin Configuration



Maxim Integrated Products 1

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ABSOLUTE MAXIMUM RATINGS

VDD to AGND	-0.3V to $+6V$	C
88		C
V _{SS} to AGND	+0.3V to -6V	
VDD to Vss	0.3V to +12V	
AGND to DGND	0.3V to +0.3V	
CH0-CH7 to AGND, DGND	(V _{SS} - 0.3V) to (V _{DD} + 0.3V)	
CH0-CH7 Total Input Current	±20mA	C
VREF to AGND	0.3V to (V _{DD} + 0.3V)	
REFADJ to AGND	0.3V to (V _{DD} + 0.3V)	
Digital Inputs to DGND	0.3V to (V _{DD} + 0.3V)	
Digital Outputs to DGND	0.3V to (V _{DD} + 0.3V)	S
Digital Output Sink Current		L

Continuous Power Dissipation ($T_A = +70^{\circ}C$)
Plastic DIP (derate 11.11mW/°C above +70°C)889mW
SO (derate 10.00mW/°C above +70°C)800mW
SSOP (derate 8.00mW/°C above +70°C)640mW
CERDIP (derate 11.11mW/°C above +70°C)889mW
Operating Temperature Ranges:
MAX186_C/MAX188_C0°C to +70°C
MAX186_E/MAX188_E40°C to +85°C
MAX186_M/MAX188_M55°C to +125°C
Storage Temperature Range60°C to +150°C
Lead Temperature (soldering, 10sec)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

 $(V_{DD} = 5V \pm 5\%)$; VSS = 0V or -5V; f_{CLK} = 2.0MHz, external clock (50% duty cycle); 15 clocks/conversion cycle (133ksps); MAX186-4.7µF capacitor at VREF pin; MAX188-external reference, VREF = 4.096V applied to VREF pin; T_A = T_{MIN} to T_{MAX}, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
DC ACCURACY (Note 1)	1						1
Resolution				12			Bits
		MAX186A/MAX188A				±0.5	
		MAX186B/MAX188B	MAX186B/MAX188B			±0.5	
Relative Accuracy (Note 2)		MAX186C				±1.0	LSB
		MAX188C				±0.75	
		MAX186D/MAX188D				±1.0]
Differential Nonlinearity	DNL	No missing codes ov	er temperature			±1	LSB
		MAX186A/MAX188A				±2.0	
Offset Error		MAX186B/MAX188B MAX186C/MAX188C MAX186D/MAX188D				±3.0	LSB
Unset en or						±3.0	
						±3.0	
		MAX186 (all grades)				±3.0	
			MAX188A			±1.5	LSB
Gain Error (Note 3)		External reference 4.096V (MAX188)	MAX188B			±2.0	
			MAX188C			±2.0	
			MAX188D			±3.0	
Gain Temperature Coefficient		External reference, 4.	096V		±0.8		ppm/°C
Channel-to-Channel Offset Matching					±0.1		LSB
DYNAMIC SPECIFICATIONS (1	0kHz sine w	ave input, 4.096V _{P-P} , 1	33ksps, 2.0MHz external	clock, bip	olar input	mode)	
Signal-to-Noise + Distortion Ratio	SINAD			70			dB
Total Harmonic Distortion (up to the 5th harmonic)	THD					-80	dB
Spurious-Free Dynamic Range	SFDR			80			dB
Channel-to-Channel Crosstalk		65kHz, V _{IN} = 4.096V _F	P-P (Note 4)		-85		dB

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = 5V \pm 5\%; V_{SS} = 0V \text{ or } -5V; f_{CLK} = 2.0MHz$, external clock (50% duty cycle); 15 clocks/conversion cycle (133ksps); MAX186—4.7µF capacitor at VREF pin; MAX188—external reference, VREF = 4.096V applied to VREF pin; TA = T_{MIN} to T_MAX, unless otherwise noted.)

PARAMETER	SYMBOL	COND	ITIONS	MIN	TYP	MAX	UNITS	
Small-Signal Bandwidth		-3dB rolloff			4.5		MHz	
Full-Power Bandwidth					800		kHz	
CONVERSION RATE	1					1		
Conversion Time (Note 5)	teenu	Internal clock		5.5		10	110	
	t conv	External clock, 2MHz	, 12 clocks/conversion	6			μs	
Track/Hold Acquisition Time	t _{AZ}					1.5	μs	
Aperture Delay					10		ns	
Aperture Jitter					<50		ps	
Internal Clock Frequency					1.7		MHz	
		External compensation	on, 4.7µF	0.1		2.0		
External Clock Frequency Range		Internal compensation	n (Note 6)	0.1		0.4	MHz	
		Used for data transfe	r only		10			
ANALOG INPUT								
Input Voltage Range, Single-Ended and Differential		Unipolar, V _{SS} = 0V				0 to VREF	V	
(Note 9)		Bipolar, V _{SS} = -5V				±VREF/2	v	
Multiplexer Leakage Current		On/off leakage currer	nt, $V_{IN} = \pm 5V$		±0.01	±1	μA	
Input Capacitance		(Note 6)			16		рF	
INTERNAL REFERENCE (MAX18	86 only, refe	,						
VREF Output Voltage		$T_A = +25^{\circ}C$		4.076	4.096	4.116	V	
VREF Short-Circuit Current						30	mA	
			MAX186_C		±30	±50		
VREF Tempco		MAX186A, MAX186B, MAX186C MAX186	MAX186_E		±30	±60	ppm/°C	
Viter rempto		11# 011000	MAX186_M		±30	±80		
		MAX186D			±30			
Load Regulation (Note 7)		0mA to 0.5mA output	load		2.5		mV	
	Internal compensation		0			uЕ		
Canacitive Bypass at VPEE							μF	
Capacitive Bypass at VREF		External compensation		4.7			P	
		External compensation	n	4.7 0.01				
		External compensation	n				μF	
Capacitive Bypass at REFADJ REFADJ Adjustment Range		External compensation Internal compensation External compensation	n n n	0.01	±1.5			
Capacitive Bypass at REFADJ	EF (Buffer c	External compensation Internal compensation External compensation	n n n	0.01	±1.5		μF	
Capacitive Bypass at REFADJ REFADJ Adjustment Range EXTERNAL REFERENCE AT VR	EF (Buffer c	External compensation Internal compensation External compensation	n n n	0.01	±1.5	V _{DD +} 50mV	μF	
Capacitive Bypass at REFADJ REFADJ Adjustment Range	EF (Buffer c	External compensation Internal compensation External compensation	n n n	0.01	±1.5		μF %	
Capacitive Bypass at REFADJ REFADJ Adjustment Range EXTERNAL REFERENCE AT VR Input Voltage Range Input Current	EF (Buffer c	External compensation Internal compensation External compensation	n n n	0.01		50mV	μF % V	
Capacitive Bypass at REFADJ REFADJ Adjustment Range EXTERNAL REFERENCE AT VR Input Voltage Range	EF (Buffer o	External compensation Internal compensation External compensation	n n n	0.01 0.01 2.50	200	50mV	μF % V μA	



ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = 5V \pm 5\%; V_{SS} = 0V \text{ or } -5V; f_{CLK} = 2.0MHz$, external clock (50% duty cycle); 15 clocks/conversion cycle (133ksps); MAX186—4.7µF capacitor at VREF pin; MAX188—external reference, VREF = 4.096V applied to VREF pin; TA = T_{MIN} to T_{MAX}, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
EXTERNAL REFERENCE AT RE	FADJ						
		Internal compensation mode	0				
Capacitive Bypass at VREF		External compensation mode	4.7			μF	
Deference Duffer Cain		MAX186		1.678		V/V	
Reference-Buffer Gain		MAX188		1.638		V/V	
		MAX186			±50	μA	
REFADJ Input Current		MAX188			±5		
DIGITAL INPUTS (DIN, SCLK, C	S, SHDN)	L					
DIN, SCLK, CS Input High Voltage	VINH		2.4			V	
DIN, SCLK, CS Input Low Voltage	VINL				0.8	V	
DIN, SCLK, CS Input Hysteresis	VHYST			0.15		V	
DIN, SCLK, CS Input Leakage	l _{IN}	$V_{IN} = OV \text{ or } V_{DD}$			±1	μA	
DIN, SCLK, CS Input Capacitance	CIN	(Note 6)			15	рF	
SHDN Input High Voltage	V _{INH}		V _{DD} - 0.5			V	
SHDN Input Low Voltage	VINL				0.5	V	
SHDN Input Current, High	linh	SHDN = V _{DD}			4.0	μA	
SHDN Input Current, Low	linl	SHDN = 0V	-4.0			μA	
SHDN Input Mid Voltage	VIM		1.5		V _{DD} -1.5	V	
SHDN Voltage, Floating	VFLT	SHDN = open		2.75		V	
SHDN Max Allowed Leakage, Mid Input		SHDN = open	-100		100	nA	
DIGITAL OUTPUTS (DOUT, SST	RB)						
	N	I _{SINK} = 5mA			0.4	V	
Output Voltage Low	Vol	I _{SINK} = 16mA		0.3		V	
Output Voltage High	Voh	ISOURCE = 1mA	4			V	
Three-State Leakage Current	ΙL	$\overline{\text{CS}} = 5\text{V}$			±10	μA	
Three-State Output Capacitance	Соит	$\overline{\text{CS}} = 5\text{V}$ (Note 6)			15	рF	
POWER REQUIREMENTS					I		
Positive Supply Voltage	V _{DD}			$5\pm5\%$		V	
Negative Supply Voltage	V _{SS}			0 or -5 ±5%		V	
		Operating mode		1.5	2.5	mA	
Positive Supply Current	IDD	Fast power-down		30	70	^	
		Full power-down		2	10	μA	
Negative Supply Current	100	Operating mode and fast power-down		50			
Negative Supply Current	ISS	Full power-down			10	μΑ	

ELECTRICAL CHARACTERISTICS (continued)

 $(V_{DD} = 5V \pm 5\%; V_{SS} = 0V \text{ or } -5V; f_{CLK} = 2.0MHz$, external clock (50% duty cycle); 15 clocks/conversion cycle (133ksps); MAX186-4.7µF capacitor at VREF pin; MAX188-external reference, VREF = 4.096V applied to VREF pin; TA = T_{MIN} to T_{MAX}, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS		ТҮР	MAX	UNITS
Positive Supply Rejection (Note 8)	PSR	$V_{DD} = 5V \pm 5\%$; external reference, 4.096V; full-scale input		±0.06	±0.5	mV
Negative Supply Rejection (Note 8)	PSR	$V_{SS} = -5V \pm 5\%$; external reference, 4.096V; full-scale input		±0.01	±0.5	mV

Note 1: Tested at $V_{DD} = 5.0V$; $V_{SS} = 0V$; unipolar input mode.

Note 2: Relative accuracy is the deviation of the analog value at any code from its theoretical value after the full-scale range has been calibrated.

Note 3: MAX186 – internal reference, offset nulled; MAX188 – external reference (VREF = +4.096V), offset nulled.

Note 4: Ground on-channel; sine wave applied to all off channels.

Note 5: Conversion time defined as the number of clock cycles times the clock period; clock has 50% duty cycle.

Note 6: Guaranteed by design. Not subject to production testing.

Note 7: External load should not change during conversion for specified accuracy.

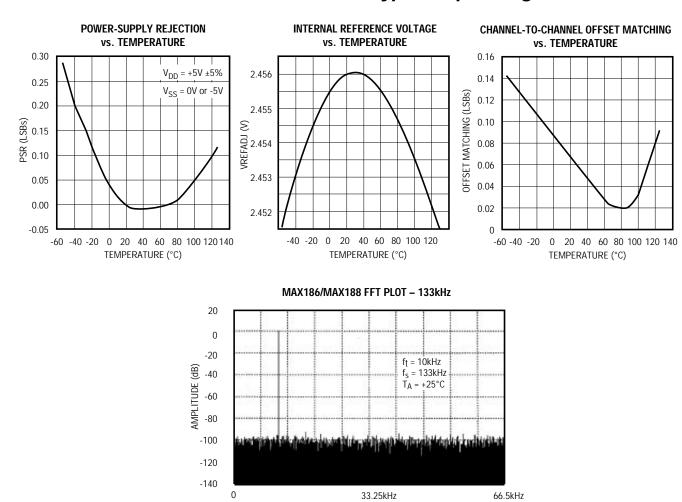
Note 8: Measured at V_{SUPPLY} +5% and V_{SUPPLY} -5% only.

Note 9: The common-mode range for the analog inputs is from V_{SS} to $V_{DD}.$

TIMING CHARACTERISTICS

(V_{DD} = 5V \pm 5%; V_{SS} =0V or -5V, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.)

PARAMETER	SYMBOL	COND	DITIONS	MIN	ТҮР	МАХ	UNITS
Acquisition Time	t _{AZ}			1.5			μs
DIN to SCLK Setup	t _{DS}			100			ns
DIN to SCLK Hold	t _{DH}					0	ns
SCLK Fall to Output Data Valid	t _{DO}	C _{LOAD} = 100pF	MAX18C/E	20		150	ns
	¹ DO		MAX18M	20		200	ns
CS Fall to Output Enable	t _{DV}	$C_{LOAD} = 100 pF$				100	ns
CS Rise to Output Disable	t _{TR}	$C_{LOAD} = 100 pF$				100	ns
CS to SCLK Rise Setup	t _{CSS}			100			ns
CS to SCLK Rise Hold	t _{CSH}			0			ns
SCLK Pulse Width High	t _{CH}			200			ns
SCLK Pulse Width Low	t _{CL}			200			ns
SCLK Fall to SSTRB	t _{SSTRB}	$C_{LOAD} = 100 pF$				200	ns
CS Fall to SSTRB Output Enable (Note 6)	t _{SDV}	External clock mode only, C _{LOAD} = 100pF				200	ns
CS Rise to SSTRB Output Disable (Note 6)	t _{STR}	External clock mode only, C _{LOAD} = 100pF				200	ns
SSTRB Rise to SCLK Rise (Note 6)	t _{SCK}	Internal clock mode	only	0			ns



FREQUENCY

_Pin Description

PIN	NAME	FUNCTION
1-8	CH0-CH7	Sampling Analog Inputs
9	V _{SS}	Negative Supply Voltage. Tie to -5V ±5% or AGND
10	SHDN	Three-Level Shutdown Input. Pulling SHDN low shuts the MAX186/MAX188 down to 10µA (max) supply current, otherwise the MAX186/MAX188 are fully operational. Pulling SHDN high puts the reference-buffer amplifier in internal compensation mode. Letting SHDN float puts the reference-buffer amplifier in external compensation mode.
11	VREF	Reference Voltage for analog-to-digital conversion. Also, Output of the Reference Buffer Amplifier (4.096V in the MAX186, 1.638 x REFADJ in the MAX188). Add a 4.7µF capacitor to ground when using external compensation mode. Also functions as an input when used with a precision external reference.

Typical Operating Characteristics

6

Pin Description (continued)

PIN	NAME	FUNCTION
12	REFADJ	Input to the Reference-Buffer Amplifier. To disable the reference-buffer amplifier, tie REFADJ to V_{DD} .
13	AGND	Analog Ground. Also IN- Input for single-ended conversions.
14	DGND	Digital Ground
15	DOUT	Serial Data Output. Data is clocked out at the falling edge of SCLK. High impedance when \overline{CS} is high.
16	SSTRB	Serial Strobe Output. In internal clock mode, SSTRB goes low when the MAX186/MAX188 begin the A/D conversion and goes high when the conversion is done. In external clock mode, SSTRB pulses high for one clock period before the MSB decision. High impedance when CS is high (external mode).
17	DIN	Serial Data Input. Data is clocked in at the rising edge of SCLK.
18	CS	Active-Low Chip Select. Data will not be clocked into DIN unless \overline{CS} is low. When \overline{CS} is high, DOUT is high impedance.
19	SCLK	Serial Clock Input. Clocks data in and out of serial interface. In external clock mode, SCLK also sets the conversion speed. (Duty cycle must be 40% to 60% in external clock mode.)
20	V _{DD}	Positive Supply Voltage, +5V ±5%

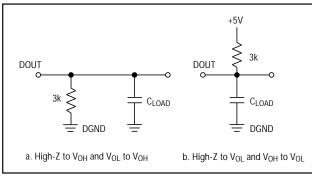


Figure 1. Load Circuits for Enable Time

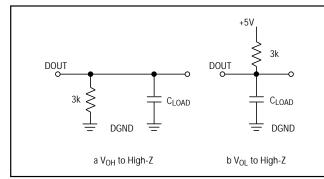


Figure 2. Load Circuits for Disabled Time

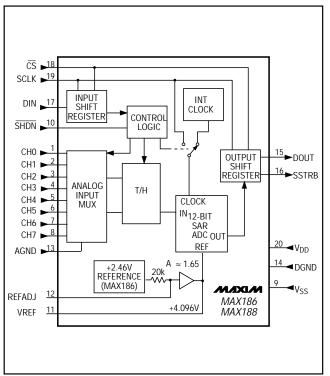


Figure 3. Block Diagram

MAX186/MAX188

MAX186/MAX188

_Detailed Description

The MAX186/MAX188 use a successive-approximation conversion technique and input track/hold (T/H) circuitry to convert an analog signal to a 12-bit digital output. A flexible serial interface provides easy interface to microprocessors. No external hold capacitors are required. Figure 3 shows the block diagram for the MAX186/MAX188.

Pseudo-Differential Input

The sampling architecture of the ADC's analog comparator is illustrated in the Equivalent Input Circuit (Figure 4). In single-ended mode, IN+ is internally switched to CH0-CH7 and IN- is switched to AGND. In differential mode, IN+ and IN- are selected from pairs of CH0/CH1, CH2/CH3, CH4/CH5 and CH6/CH7. Configure the channels with Table 3 and Table 4.

In differential mode, IN- and IN+ are internally switched to either one of the analog inputs. This configuration is pseudo-differential to the effect that only the signal at IN+ is sampled. The return side (IN-) must remain stable within ± 0.5 LSB (± 0.1 LSB for best results) with respect to AGND during a conversion. Accomplish this by connecting a 0.1μ F capacitor from AIN- (the selected analog input, respectively) to AGND.

During the acquisition interval, the channel selected as the positive input (IN+) charges capacitor C_{HOLD} . The acquisition interval spans three SCLK cycles and ends on the falling SCLK edge after the last bit of the input control word has been entered. At the end of the acquisition interval, the T/H switch opens, retaining charge on C_{HOLD} as a sample of the signal at IN+.

The conversion interval begins with the input multiplexer switching C_{HOLD} from the positive input (IN+) to the negative input (IN-). In single-ended mode, IN- is simply AGND. This unbalances node ZERO at the input of the comparator. The capacitive DAC adjusts during the remainder of the conversion cycle to restore node ZERO to 0V within the limits of 12-bit resolution. This action is equivalent to transferring a charge of 16pF x [(V_{IN}+) - (V_{IN}-)] from C_{HOLD} to the binary-weighted capacitive DAC, which in turn forms a digital representation of the analog input signal.

The T/H enters its tracking mode on the falling clock edge after the fifth bit of the 8-bit control word has been shifted in. The T/H enters its hold mode on the falling clock edge after the eighth bit of the control word has been shifted in. If the converter is set up for

Track/Hold

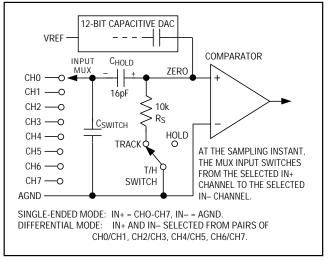


Figure 4. Equivalent Input Circuit

single-ended inputs, IN- is connected to AGND, and the converter samples the "+" input. If the converter is set up for differential inputs, IN- connects to the "-" input, and the difference of |IN+ - IN-| is sampled. At the end of the conversion, the positive input connects back to IN+, and C_{HOLD} charges to the input signal.

The time required for the T/H to acquire an input signal is a function of how quickly its input capacitance is charged. If the input signal's source impedance is high, the acquisition time lengthens and more time must be allowed between conversions. Acquisition time is calculated by:

$$t_{AZ} = 9 x (R_S + R_{IN}) x 16 pF$$
,

where $R_{IN} = 5k\Omega$, $R_S =$ the source impedance of the input signal, and t_{AZ} is never less than 1.5µs. Note that source impedances below $5k\Omega$ do not significantly affect the AC performance of the ADC. Higher source impedances can be used if an input capacitor is connected to the analog inputs, as shown in Figure 5. Note that the input capacitor forms an RC filter with the input source impedance, limiting the ADC's signal bandwidth.

Input Bandwidth

The ADC's input tracking circuitry has a 4.5MHz small-signal bandwidth, so it is possible to digitize high-speed transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using undersampling techniques. To avoid high-frequency signals being aliased into the frequency band of interest, anti-alias filtering is recommended.



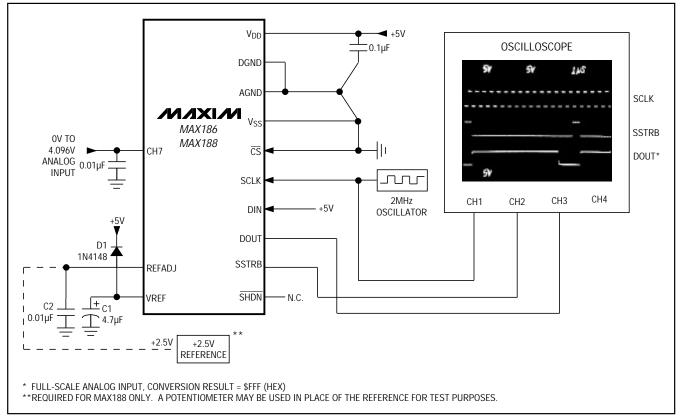


Figure 5. Quick-Look Circuit

Analog Input Range and Input Protection

Internal protection diodes, which clamp the analog input to V_{DD} and V_{SS}, allow the channel input pins to swing from V_{SS} - 0.3V to V_{DD} + 0.3V without damage. However, for accurate conversions near full scale, the inputs must not exceed V_{DD} by more than 50mV, or be lower than V_{SS} by 50mV.

If the analog input exceeds 50mV beyond the supplies, do not forward bias the protection diodes of off-channels over two milliamperes, as excessive current will degrade the conversion accuracy of the on-channel.

The full-scale input voltage depends on the voltage at VREF. See Tables 1a and 1b.

Quick Look

To evaluate the analog performance of the MAX186/MAX188 quickly, use the circuit of Figure 5. The MAX186/MAX188 require a control byte to be written to DIN before each conversion. Tying DIN to +5V feeds in control bytes of \$FF (HEX), which trigger



Table 1a.	Unipolar Full Scale and Zero Scale
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Reference	Zero Scale	Full Scale
Internal Reference (MAX186 only)	0V	+4.096V
External Reference at REFADJ	0V	V _{REFADJ} x A*
at VREF	0V	VREF

* A = 1.678 for the MAX186, 1.638 for the MAX188

Table 1b. Bipolar Full Scale, Zero Scale, andNegative Full Scale

Reference	Negative Full Scale	Zero Scale	Full Scale
Internal Reference (MAX186 only)	-4.096V/2	0V	+4.096V/2
External Reference at REFADJ	-1/2V _{REFADJ} x A*	0V	+1/2V _{REFADJ} x A*
at VREF	-1/2 VREF	0V	+1/2 VREF

* A = 1.678 for the MAX186, 1.638 for the MAX188

single-ended unipolar conversions on CH7 in external clock mode without powering down between conversions. In external clock mode, the SSTRB output pulses high for one clock period before the most significant bit of the 12-bit conversion result comes out of DOUT. Varying the analog input to CH7 should alter the sequence of bits from DOUT. A total of 15 clock cycles is required per conversion. All transitions of the SSTRB and DOUT outputs occur on the falling edge of SCLK.

How to Start a Conversion

A conversion is started on the MAX186/MAX188 by clocking a control byte into DIN. Each rising edge on SCLK, with \overline{CS} low, clocks a bit from DIN into the MAX186/MAX188's internal shift register. After \overline{CS} falls, the first arriving logic "1" bit defines the MSB of the control byte. Until this first "start" bit arrives, any number of logic "0" bits can be clocked into DIN with no effect. Table 2 shows the control-byte format.

The MAX186/MAX188 are fully compatible with Microwire and SPI devices. For SPI, select the correct clock polarity and sampling edge in the SPI control registers: set CPOL = 0 and CPHA = 0. Microwire and SPI both transmit a byte and receive a byte at the same time. Using the Typical Operating Circuit, the simplest software interface requires only three 8-bit transfers to perform a conversion (one 8-bit transfer to configure the ADC, and two more 8-bit transfers to clock out the 12-bit conversion result).

Example: Simple Software Interface

Make sure the CPU's serial interface runs in master mode so the CPU generates the serial clock. Choose a clock frequency from 100kHz to 2MHz.

1) Set up the control byte for external clock mode, call it TB1. TB1 should be of the format: 1XXXXX11 Binary, where the Xs denote the particular channel and conversion-mode selected.

Bit 7 (MSB)	Bit 6	Bit 5	Bit 4	4 Bit 3	Bit 2	Bit 1	Bit 0 (LSB)
START	SEL2	SEL1	SEL	0 UNI/BIP	SGL/DIF	PD1	PD0
Bit	Name	Descrip	otion				
7(MSB)	START	The firs	t logic " 1 " bit	after $\overline{\text{CS}}$ goes low de	efines the beginnin	g of the contro	ol byte.
6 5 4	SEL2 SEL1 SEL0		hree bits sele bles 3 and 4.	ect which of the eight	channels are used	for the conver	rsion.
3	UNI/BIP	mode, a	an analog inp	olar. Selects unipolar out signal from 0V to V om -VREF/2 to +VREF/	REF can be conve		
2	SGL/DIF	single-e	ended mode,	 differential. Selects input signal voltages e between two chann 	are referred to AG	ND. In differer	ntial mode,
1 0(LSB)	PD1 PD0	Selects PD1 0 0 1 1	PD0 0 1 0	ower-down modes. Mode Full power-down (I _Q = Fast power-down (I _Q = Internal clock mode External clock mode			

Table 2. Control-Byte Format

SEL2	SEL1	SEL0	CH0	CH1	CH2	СНЗ	CH4	CH5	CH6	CH7	AGND
0	0	0	+								_
1	0	0		+							_
0	0	1			+						_
1	0	1				+					_
0	1	0					+				-
1	1	0						+			_
0	1	1							+		_
1	1	1								+	_

Table 3. Channel Selection in Single-Ended Mode (SGL/DIFF = 1)

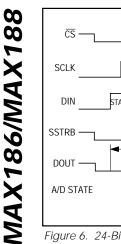
SEL2	SEL1	SEL0	CH0	CH1	CH2	CH3	CH4	CH5	CH6	CH7
0	0	0	+	_						
0	0	1			+	_				
0	1	0					+	_		
0	1	1							+	_
1	0	0	_	+						
1	0	1			_	+				
1	1	0					_	+		
1	1	1							_	+

- 2) Use a general-purpose I/O line on the CPU to pull $\overline{\text{CS}}$ on the MAX186/MAX188 low.
- 3) Transmit TB1 and simultaneously receive a byte and call it RB1. Ignore RB1.
- 4) Transmit a byte of all zeros (\$00 HEX) and simultaneously receive byte RB2.
- 5) Transmit a byte of all zeros (\$00 HEX) and simultaneously receive byte RB3.
- 6) Pull $\overline{\text{CS}}$ on the MAX186/MAX188 high.

Figure 6 shows the timing for this sequence. Bytes RB2 and RB3 will contain the result of the conversion padded with one leading zero and three trailing zeros. The total conversion time is a function of the serial clock frequency and the amount of dead time between 8-bit transfers. Make sure that the total conversion time does not exceed 120µs, to avoid excessive T/H droop.

Digital Output

In unipolar input mode, the output is straight binary (see Figure 15). For bipolar inputs, the output is twos-complement (see Figure 16). Data is clocked out at the falling edge of SCLK in MSB-first format.



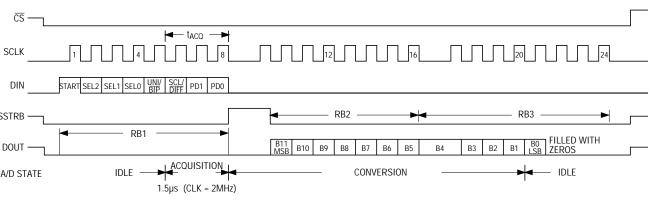


Figure 6. 24-Bit External Clock Mode Conversion Timing (SPI, QSPI and Microwire Compatible)

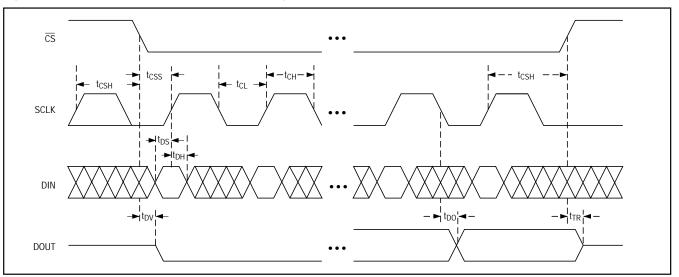


Figure 7. Detailed Serial-Interface Timing

Internal and External Clock Modes

The MAX186/MAX188 may use either an external serial clock or the internal clock to perform the successive-approximation conversion. In both clock modes, the external clock shifts data in and out of the MAX186/MAX188. The T/H acquires the input signal as the last three bits of the control byte are clocked into DIN. Bits PD1 and PD0 of the control byte program the clock mode. Figures 7 through 10 show the timing characteristics common to both modes.

External Clock

In external clock mode, the external clock not only shifts data in and out, it also drives the analog-to-digital con-

version steps. SSTRB pulses high for one clock period after the last bit of the control byte. Successive-approximation bit decisions are made and appear at DOUT on each of the next 12 SCLK falling edges (see Figure 6). SSTRB and DOUT go into a high-impedance state when CS goes high; after the next CS falling edge, SSTRB will output a logic low. Figure 8 shows the SSTRB timing in external clock mode.

The conversion must complete in some minimum time, or else droop on the sample-and-hold capacitors may degrade conversion results. Use internal clock mode if the clock period exceeds 10µs, or if serial-clock interruptions could cause the conversion interval to exceed 120µs.



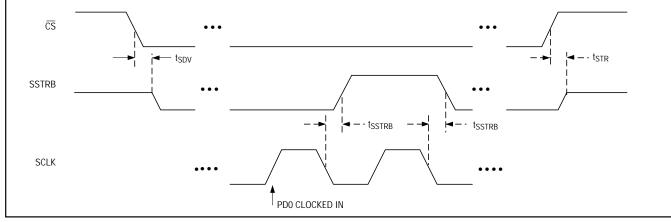


Figure 8. External Clock Mode SSTRB Detailed Timing

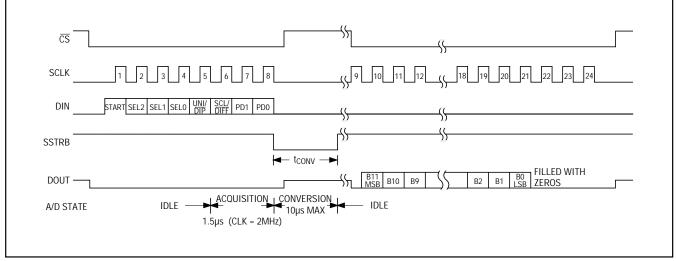


Figure 9. Internal Clock Mode Timing

Internal Clock

In internal clock mode, the MAX186/MAX188 generate their own conversion clock internally. This frees the microprocessor from the burden of running the SAR conversion clock, and allows the conversion results to be read back at the processor's convenience, at any clock rate from zero to typically 10MHz. SSTRB goes low at the start of the conversion and then goes high when the conversion is complete. SSTRB will be low for a maximum of 10µs, during which time SCLK should remain low for best noise performance. An internal register stores data when the conversion is in progress. SCLK clocks the data out at this register at any time after the conversion is complete. After SSTRB goes high, the next falling clock edge will produce the MSB of the conversion at DOUT, followed by the remaining bits in MSB-first format (see Figure 9). \overline{CS} does not need to be held low once a conversion is started. Pulling \overline{CS} high prevents data from being clocked into the MAX186/MAX188 and three-states DOUT, but it does not adversely effect an internal clock-mode conversion already in progress. When internal clock mode is selected, SSTRB does not go into a high-impedance state when \overline{CS} goes high.

Figure 10 shows the SSTRB timing in internal clock mode. In internal clock mode, data can be shifted in and out of the MAX186/MAX188 at clock rates exceeding 4.0MHz, provided that the minimum acquisition time, t_{AZ} , is kept above 1.5µs.



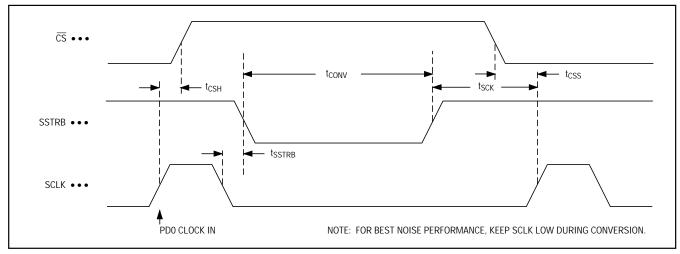


Figure 10. Internal Clock Mode SSTRB Detailed Timing

Data Framing

The falling edge of \overline{CS} does **not** start a conversion on the MAX186/MAX188. The first logic high clocked into DIN is interpreted as a start bit and defines the first bit of the control byte. A conversion starts on the falling edge of SCLK, after the eighth bit of the control byte (the PD0 bit) is clocked into DIN. The start bit is defined as:

The first high bit clocked into DIN with \overline{CS} low anytime the converter is idle, e.g. after V_{CC} is applied.

OR

The first high bit clocked into DIN after bit 5 of a conversion in progress is clocked onto the DOUT pin.

If a falling edge on $\overline{\text{CS}}$ forces a start bit before bit 5 (B5) becomes available, then the current conversion will be terminated and a new one started. Thus, the fastest the MAX186/MAX188 can run is 15 clocks per conversion. Figure 11a shows the serial-interface timing necessary to perform a conversion every 15 SCLK cycles in external clock mode. If $\overline{\text{CS}}$ is low and SCLK is continuous, guarantee a start bit by first clocking in 16 zeros.

Most microcontrollers require that conversions occur in multiples of 8 SCLK clocks; 16 clocks per conversion will typically be the fastest that a microcontroller can drive the MAX186/MAX188. Figure 11b shows the serial-interface timing necessary to perform a conversion every 16 SCLK cycles in external clock mode.

Applications Information

Power-On Reset

When power is first applied and if \overline{SHDN} is not pulled low, internal power-on reset circuitry will activate the MAX186/MAX188 in internal clock mode, ready to convert with SSTRB = high. After the power supplies have been stabilized, the internal reset time is 100µs and no conversions should be performed during this phase. SSTRB is high on power-up and, if \overline{CS} is low, the first logical 1 on DIN will be interpreted as a start bit. Until a conversion takes place, DOUT will shift out zeros.

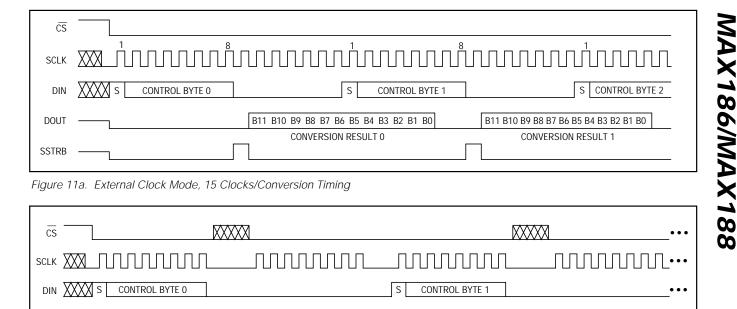
Reference-Buffer Compensation

In addition to its shutdown function, the SHDN pin also selects internal or external compensation. The compensation affects both power-up time and maximum conversion speed. Compensated or not, the minimum clock rate is 100kHz due to droop on the sample-and-hold.

To select external compensation, float \overline{SHDN} . See the *Typical Operating Circuit*, which uses a 4.7µF capacitor at VREF. A value of 4.7µF or greater ensures stability and allows operation of the converter at the full clock speed of 2MHz. External compensation increases power-up time (see the *Choosing Power-Down Mode* section, and Table 5).

Internal compensation requires no external capacitor at VREF, and is selected by pulling SHDN high. Internal compensation allows for shortest power-up times, but is only available using an external clock and reduces the maximum clock rate to 400kHz.





B11 B10 B9 B8 B7 B6 B5 B4 B3 B2 B1 B0

CONVERSION RESULT 0

XXXXX

Figure 11b. External Clock Mode, 16 Clocks/Conversion Timing

Power-Down

Choosing Power-Down Mode

You can save power by placing the converter in a low-current shutdown state between conversions. Select full power-down or fast power-down mode via bits 7 and 8 of the DIN control byte with SHDN high or floating (see Tables 2 and 6). Pull SHDN low at any time to shut down the converter completely. SHDN overrides bits 7 and 8 of DIN word (see Table 7).

Full power-down mode turns off all chip functions that draw quiescent current, reducing I_{DD} and I_{SS} typically to 2μ A.

Fast power-down mode turns off all circuitry except the bandgap reference. With the fast power-down mode, the supply current is 30μ A. Power-up time can be shortened to 5μ s in internal compensation mode.

In both software shutdown modes, the serial interface remains operational, however, the ADC will not convert. Table 5 illustrates how the choice of reference-buffer compensation and power-down mode affects both power-up delay and maximum sample rate.

In external compensation mode, the power-up time is 20ms with a $4.7\mu F$ compensation capacitor (200ms with a $33\mu F$ capacitor) when the capacitor is fully discharged. In fast power-down, you can eliminate start-up time by

using low-leakage capacitors that will not discharge more than 1/2LSB while shut down. In shutdown, the capacitor has to supply the current into the reference (1.5µA typ) and the transient currents at power-up.

XXXXX

Figures 12a and 12b illustrate the various power-down sequences in both external and internal clock modes.

Software Power-Down

B11 B10 B9 B8

CONVERSION RESULT 1

Software power-down is activated using bits PD1 and PD0 of the control byte. As shown in Table 6, PD1 and PD0 also specify the clock mode. When software shutdown is asserted, the ADC will continue to operate in the last specified clock mode until the conversion is complete. Then the ADC powers down into a low quiescent-current state. In internal clock mode, the interface remains active and conversion results may be clocked out while the MAX186/MAX188 have already entered a software power-down.

The first logical 1 on DIN will be interpreted as a start bit, and powers up the MAX186/MAX188. Following the start bit, the data input word or control byte also determines clock and power-down modes. For example, if the DIN word contains PD1 = 1, then the chip will remain powered up. If PD1 = 0, a power-down will resume after one conversion.

M/IXI/M

DOUT



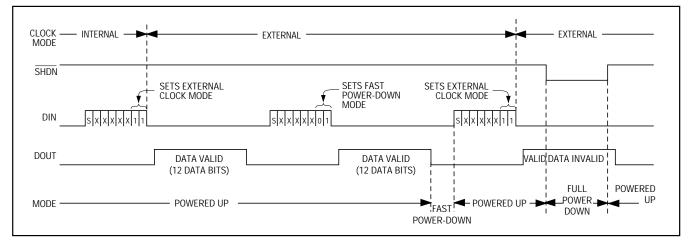


Figure 12a. Timing Diagram Power-Down Modes, External Clock

Table 5. Typical Power-Up Delay Times

Reference Buffer	Reference- Buffer Compensation Mode	VREF Capacitor (µF)	Power- Down Mode	Power-Up Delay (sec)	Maximum Sampling Rate (ksps)
Enabled	Internal		Fast	5µ	26
Enabled	Internal		Full	300µ	26
Enabled	External	4.7	Fast	See Figure 14c	133
Enabled	External	4.7	Full	See Figure 14c	133
Disabled			Fast	2μ	133
Disabled			Full	2μ	133

Table 6. Software Shutdown and Clock Mode

PD1	PD0	Device Mode		
1	1	External Clock Mode		
1	0	Internal Clock Mode		
0	1	Fast Power-Down Mode		
0	0	Full Power-Down Mode		

Table 7. Hard-Wired Shutdown andCompensation Mode

SHDN State	Device Mode	Reference-Buffer Compensation
1	Enabled	Internal Compensation
Floating	Enabled	External Compensation
0	Full Power-Dow	/n N/A

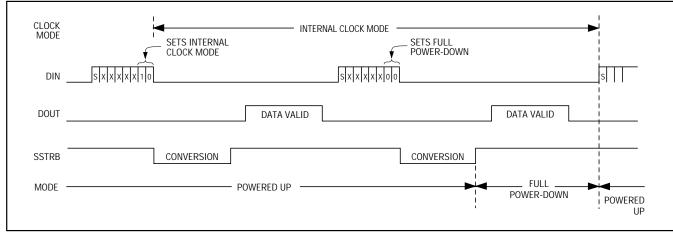


Figure 12b. Timing Diagram Power-Down Modes, Internal Clock

Hardware Power-Down

The SHDN pin places the converter into the full power-down mode. Unlike with the software shut-down modes, conversion is not completed. It stops coincidentally with SHDN being brought low. There is no power-up delay if an external reference is used and is not shut down. The SHDN pin also selects internal or external reference compensation (see Table 7).

Power-Down Sequencing

The MAX186/MAX188 auto power-down modes can save considerable power when operating at less than maximum sample rates. The following discussion illustrates the various power-down sequences.

Lowest Power at up to 500 Conversions/Channel/Second

MAX186/MAX188

The following examples illustrate two different power-down sequences. Other combinations of clock rates, compensation modes, and power-down modes may give lowest power consumption in other applications.

Figure 14a depicts the MAX186 power consumption for one or eight channel conversions utilizing full power-down mode and internal reference compensation. A 0.01µF bypass capacitor at REFADJ forms an RC filter with the internal 20k Ω reference resistor with a 0.2ms time constant. To achieve full 12-bit accuracy, 10 time constants or 2ms are required after power-up. Waiting 2ms in FASTPD mode instead of full power-up will reduce the power consumption by a factor of 10 or more. This is achieved by using the sequence shown in Figure 13.

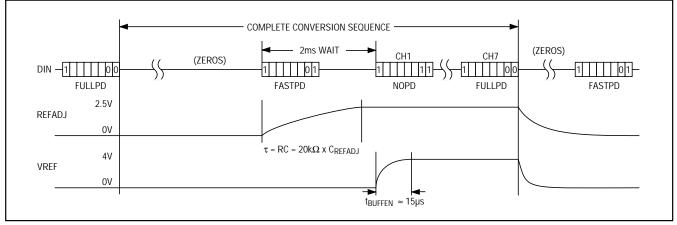


Figure 13. MAX186 FULLPD/FASTPD Power-Up Sequence



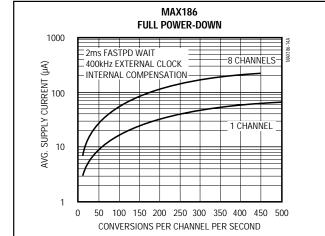


Figure 14a. MAX186 Supply Current vs. Sample Rate/Second, FULLPD, 400kHz Clock

Lowest Power at Higher Throughputs

Figure 14b shows the power consumption with external-reference compensation in fast power-down, with one and eight channels converted. The external 4.7µF compensation requires a 50µs wait after power-up, accomplished by 75 idle clocks after a dummy conversion. This circuit combines fast multi-channel conversion with lowest power consumption possible. Full power-down mode may provide increased power savings in applications where the MAX186/MAX188 are inactive for long periods of time, but where intermittent bursts of high-speed conversions are required.

External and Internal References

The MAX186 can be used with an internal or external reference, whereas an external reference is required for the MAX188. Diode D1 shown in the *Typical Operating Circuit* ensures correct start-up. Any standard signal diode can be used. For both parts, an external reference can either be connected directly at the VREF terminal or at the REFADJ pin.

An internal buffer is designed to provide 4.096V at VREF for both the MAX186 and MAX188. The MAX186's internally trimmed 2.46V reference is buffered with a gain of 1.678. The MAX188's buffer is trimmed with a buffer gain of 1.638 to scale an external 2.5V reference at REFADJ to 4.096V at VREF.

MAX186 Internal Reference

The full-scale range of the MAX186 with internal reference is 4.096V with unipolar inputs, and $\pm 2.048V$ with bipolar inputs. The internal reference voltage is adjustable to $\pm 1.5\%$ with the Reference-Adjust Circuit of Figure 17.

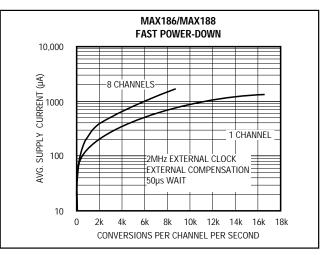


Figure 14b. MAX186/MAX188 Supply Current vs. Sample Rate/Second, FASTPD, 2MHz Clock

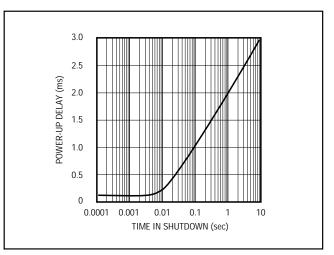


Figure 14c. Typical Power-Up Delay vs. Time in Shutdown

External Reference

With both the MAX186 and MAX188, an external reference can be placed at either the input (REFADJ) or the output (VREF) of the internal buffer amplifier. The REFADJ input impedance is typically $20k\Omega$ for the MAX186 and higher than $100k\Omega$ for the MAX188, where the internal reference is omitted. At VREF, the input impedance is a minimum of $12k\Omega$ for DC currents. During conversion, an external reference at VREF must be able to deliver up to 350μ A DC load current and have an output impedance of 10Ω or less. If the reference has higher output impedance or is noisy, bypass it close to the VREF pin with a 4.7μ F capacitor.



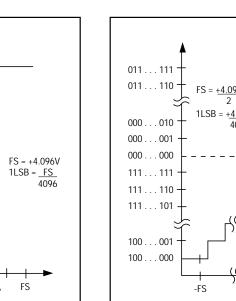


Figure 15. MAX186/MAX188 Unipolar Transfer Function, 4.096V = Full Scale

INPUT VOLTAGE (LSBs)

FULL-SCALE TRANSITION

OUTPUT CODE

11 . . . 111

11 . . . 110

11 . . . 101

00 . . . 011

00 . . . 001

00...000

0 1 2 3

Using the buffered REFADJ input avoids external buffering of the reference. To use the direct VREF input, disable the internal buffer by tying REFADJ to V_{DD} .

Transfer Function and Gain Adjust

FS - 3/2LSB

Figure 15 depicts the nominal, unipolar input/output (I/O) transfer function, and Figure 16 shows the bipolar input/output transfer function. Code transitions occur halfway between successive integer LSB values. Output coding is binary with 1 LSB = 1.00mV (4.096V/4096) for unipolar operation and 1 LSB = 1.00mV ((4.096V/2 - -4.096V/2)/4096) for bipolar operation.

Figure 17, the MAX186 Reference-Adjust Circuit, shows how to adjust the ADC gain in applications that use the internal reference. The circuit provides $\pm 1.5\%$ (± 65 LSBs) of gain adjustment range.

Layout, Grounding, Bypassing

For best performance, use printed circuit boards. Wire-wrap boards are not recommended. Board layout should ensure that digital and analog signal lines are separated from each other. Do not run analog and digital (especially clock) lines parallel to one another, or digital lines underneath the ADC package.

Figure 18 shows the recommended system ground connections. A single-point analog ground ("star" ground point) should be established at AGND, separate from the logic ground. All other analog grounds

Low-Power, 8-Channel, Serial 12-Bit ADCs

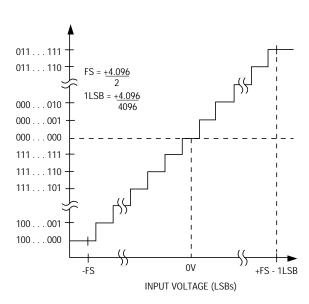


Figure 16. MAX186/MAX188 Bipolar Transfer Function, ±4.096V/2 = Full Scale

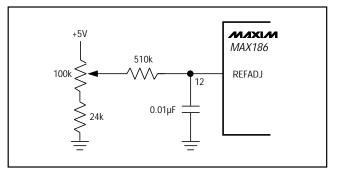


Figure 17. MAX186 Reference-Adjust Circuit

and DGND should be connected to this ground. No other digital system ground should be connected to this single-point analog ground. The ground return to the power supply for this ground should be low impedance and as short as possible for noise-free operation.

High-frequency noise in the V_{DD} power supply may affect the high-speed comparator in the ADC. Bypass these supplies to the single-point analog ground with 0.1µF and 4.7µF bypass capacitors close to the MAX186/MAX188. Minimize capacitor lead lengths for best supply-noise rejection. If the +5V power supply is very noisy, a 10 Ω resistor can be connected as a low-pass filter, as shown in Figure 18.



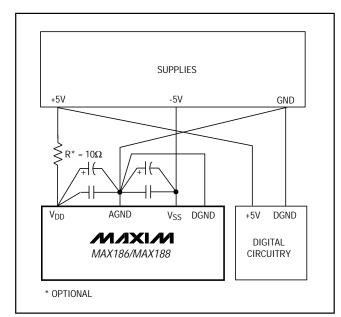


Figure 18. Power-Supply Grounding Connection

High-Speed Digital Interfacing with QSPI

The MAX186/MAX188 can interface with QSPI at high throughput rates using the circuit in Figure 19. This QSPI circuit can be programmed to do a conversion on each of the eight channels. The result is stored in memory without taxing the CPU since QSPI incorporates its own micro-sequencer. Figure 19 depicts the MAX186, but the same circuit could be used with the MAX188 by adding an external reference to VREF and connecting REFADJ to V_{DD}.

Figure 20 details the code that sets up QSPI for autonomous operation. In external clock mode, the MAX186/MAX188 perform a single-ended, unipolar conversion on each of their eight analog input channels. Figure 21, QSPI Assembly-Code Timing, shows the timing associated with the assembly code of Figure 20. The first byte clocked into the MAX186/MAX188 is the control byte, which triggers the first conversion on CH0. The last two bytes clocked into the MAX186/MAX188 are all zero and clock out the results of the CH7 conversion.

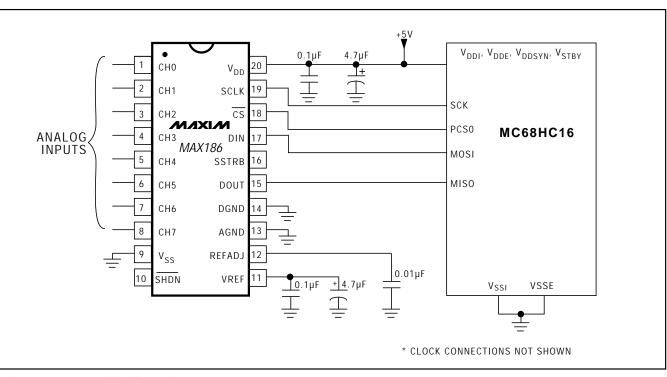


Figure 19. MAX186 QSPI Connection

*Title : MAX186.ASM * Description :	
 This is a shell program is put into bank \$0F 	ram for using a stand-alone 68HC16 without any external memory. The internal 1K RAM ⁻ to maintain 68HC11 code compatibility. This program was written with software torola 68HC16 Evaluation Kit.
 * Roger J.A. Chen, Application * MAXIM Integrated Products * November 20, 1992 	ns Engineer
*	
INCLUDE 'ORG0000 INCLUDE 'ORG0008 ORG \$0200 INCLUDE 'INITSYS.ASM' INCLUDE 'INITRAM.ASM	;set sys clock at 16.78 MHz, COP off
MAIN: JSR INITQSPI MAINLOOP: JSR READ186	
WAIT: LDAA SPSR ANDA #\$80 BEQ WAIT BRA MAINLOOP ENDPROGRAM:	;wait for QSPI to finish
INITQSPI:	
;The sequencer will read all eig ;it is triggered. The A/D conver ;receive data RAM. Each 16 bi	microsequencer to operate on its own. ght channels of a MAX186/MAX188 each time ter results will be left in the t receive data RAM location will f conversion result and three zeros.
;Receive RAM Bits 15 14 13 12 ;A/D Result 0 MSB ***** Initialize the QSPI Registe PSHA PSHB LDAA #%01111000	2 11 10 09 08 07 06 05 04 03 02 01 00 LSB 0 0 0 ers ******
STAA QPDR LDAA #%01111011	;idle state for PCS0-3 = high
	;assign port D to be QSPI
	;only MISO is an input
STD SPCR0	;master mode,16 bits/transfer, ;CPOL=CPHA=0,1MHz Ser Clock
LDD #\$0000 STD SPCR1	;set delay between PCS0 and SCK,



MAX186/MAX188

		##0000	;set d	elay be	etween transfers	
	LDD STD	#\$0800 SPCR2	;set El	NDQP	to \$8 for 9 transfers	
****			ommand RAM			
	LDAA STAA STAA STAA STAA STAA STAA STAA S	#\$80 \$FD40 #\$C0 \$FD41 \$FD42 \$FD43 \$FD44 \$FD45 \$FD46 \$FD46 \$FD47 #\$40 \$FD48 ze QSPI True	;store first ;CONT=1,	byte ir BITSE= BITSE=	=0,DT=0,DSCK=0,PCS0=ACTIVE n COMMAND RAM =1,DT=0,DSCK=0,PCS0=ACTIVE =1,DT=0,DSCK=0,PCS0=ACTIVE	
	LDD	#\$008F				
				STD	\$FD20	
	LDD	#\$00CF		STD	\$FD22	
	LDD	#\$009F		STD	\$FD24	
	LDD	#\$00DF		STD	\$FD26	
	LDD	#\$00AF				
	LDD	#\$00EF		STD	\$FD28	
	LDD	#\$00BF		STD	\$FD2A	
	LDD	#\$00FF		STD	\$FD2C	
				STD	\$FD2E	
	LDD	#\$0000		STD	\$FD30	
	PULB PULA RTS					
;This ;trigg ;conv	ger conv	versions or		s of the ceive d	ncer to autonomously e MAX186. Each ata RAM.	
****	Interru	pts/Excep	tions *****			
BDM	I: BGNE)	;exception ve	ctors p	point here	
Figure	igure 20. MAX186/MAX188 Assembly-Code Listing (continued)					

F

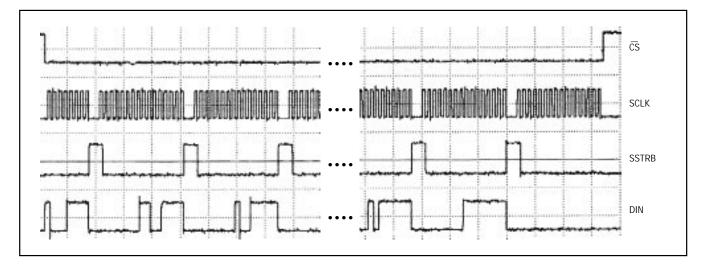


Figure 21. QSPI Assembly-Code Timing

TMS320C3x to MAX186 Interface

Figure 22 shows an application circuit to interface the MAX186/MAX188 to the TMS320 in external clock mode. The timing diagram for this interface circuit is shown in Figure 23.

Use the following steps to initiate a conversion in the MAX186/MAX188 and to read the results:

- The TMS320 should be configured with CLKX (transmit clock) as an active-high output clock and CLKR (TMS320 receive clock) as an active-high input clock. CLKX and CLKR of the TMS320 are tied together with the SCLK input of the MAX186/MAX188.
- 2) The MAX186/MAX188 CS is driven low by the XF_ I/O port of the TMS320 to enable data to be clocked into DIN of the MAX186/MAX188.
- An 8-bit word (1XXXXX11) should be written to the MAX186/MAX188 to initiate a conversion and place the device into external clock mode. Refer to Table 2 to select the proper XXXXX bit values for your specific application.
- 4) The SSTRB output of the MAX186/MAX188 is monitored via the FSR input of the TMS320. A falling edge on the SSTRB output indicates that the conversion is in progress and data is ready to be received from the MAX186/MAX188.

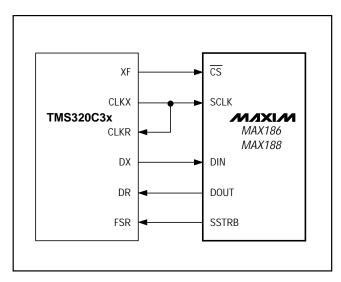


Figure 22. MAX186/MAX188 to TMS320 Serial Interface

- 5) The TMS320 reads in one data bit on each of the next 16 rising edges of SCLK. These data bits represent the 12-bit conversion result followed by four trailing bits, which should be ignored.
- Pull CS high to disable the MAX186/MAX188 until the next conversion is initiated.



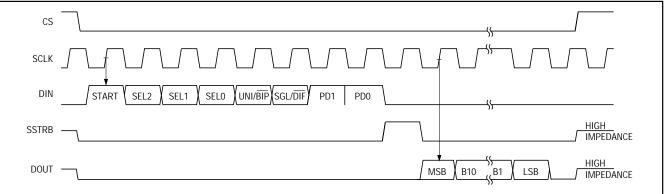
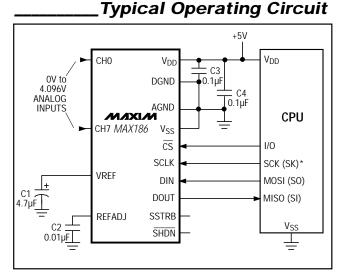


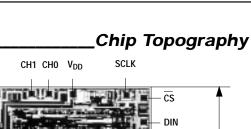
Figure 23. TMS320 Serial Interface Timing Diagram

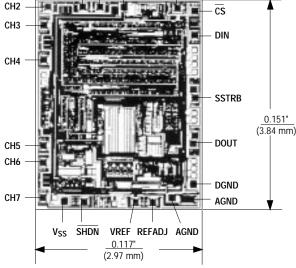


_Ordering Information (continued)

-		
PART [†]	TEMP. RANGE	PIN-PACKAGE
MAX188_CPP	0°C to +70°C	20 Plastic DIP
MAX188_CWP	0°C to +70°C	20 SO
MAX188_CAP	0°C to +70°C	20 SSOP
MAX188DC/D	0°C to +70°C	Dice*
MAX188_EPP	-40°C to +85°C	Plastic DIP
MAX188_EWP	-40°C to +85°C	20 SO
MAX188_EAP	-40°C to +85°C	20 SSOP
MAX188_MJP	-55°C to +125°C	20 CERDIP**
PART	TEMP. RANGE	BOARD TYPE

0°C to +70°C





MAX186/MAX188

TRANSISTOR COUNT: 2278; SUBSTRATE CONNECTED TO VDD

† NOTE: Parts are offered in grades A, B, C and D (grades defined in Electrical Characteristics). When ordering, please specify grade.

Dice are specified at +25°C, DC parameters only.

* * Contact factory for availability and processing to MIL-STD-883.

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

Through-Hole

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- Поставка сложных, дефицитных, либо снятых с производства позиций;
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- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
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- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



Как с нами связаться

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