

REDUCED LATENCY DRAM (RLDRAM)

MT49H8M32 – 1 Meg x 32 x 8 banks
 MT49H16M16 – 2 Meg x 16 x 8 banks

For the latest data sheet, please refer to the Micron
 Web site: www.micron.com/dramds

FEATURES

- 2.5V V_{EXT}, 1.8V V_{DD}, 1.8V V_{DDQ} I/O
- Cyclic bank addressing for maximum data out bandwidth
- Non-multiplexed addresses
- Non-interruptible sequential burst of two (2-bit prefetch) and four (4-bit prefetch) DDR
- Target 600 Mb/s/p data rate
- Programmable Read Latency (RL) of 5-8
- Data valid signal (DVLD) activated as read data is available
- Data Mask signals (DM0/DM1) to mask first and second part of write data burst
- IEEE 1149.1 compliant JTAG boundary scan
- Pseudo-HSTL 1.8V I/O Supply
- Internal Auto Precharge
- Refresh requirements: 32ms at 100°C junction temperature (8K refresh for each bank, 64K refresh command must be issued in total each 32ms)

OPTIONS

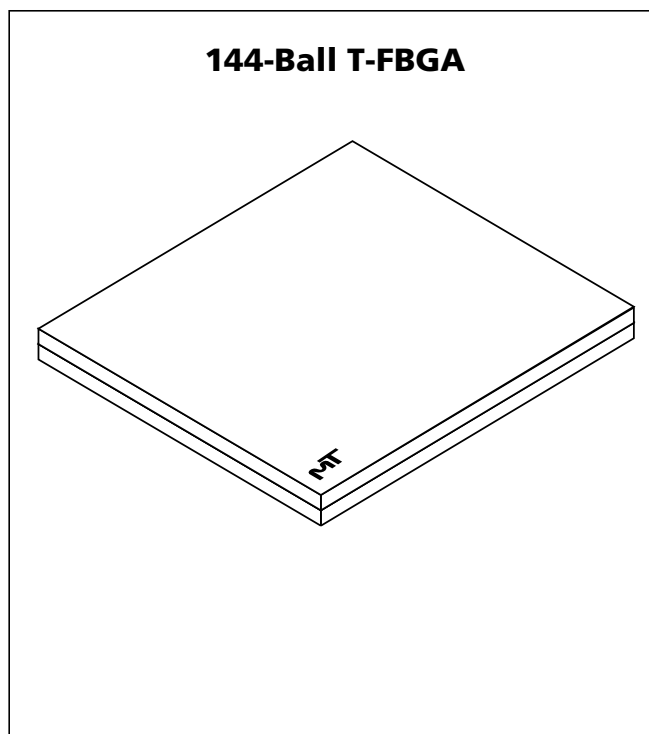
- Clock Cycle Timing

3.3ns (300 MHz)	-3.3
4ns (250 MHz)	-4
5ns (200 MHz)	-5
- Configuration

8 Meg x 32	MT49H8M32FM
(1 Meg x 32 x 8 banks)	
16 Meg x 16	MT49H16M16FM
(2 Meg x 16 x 8 banks)	
- Package

144-ball, 11mm x 18.5mm T-FBGA	FM
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MARKING



row/column address multiplexing and is optimized for fast random access and high-speed bandwidth.

RLDRAM is designed for communication data storages like transmit or receive buffers in telecommunication systems as well as data or instruction cache applications requiring large amounts of memory.

POWER-UP INITIALIZATION

Since the RLD RAM does not have a designated reset function, the following procedure must be executed in order to initialize the internal state machine, regulators, and force the DRAM to be in ready state.

- Apply power, then start clock
- After power on, an initial pause of 200µs is required
- MRS command for 2 clocks and set standard mode register for 1 clock (2 dummies plus 1 valid MRS set)
- 8 refresh cycles (minimum), one on each bank and separated by 2,048 cycles (^tMRSC must be satisfied between MRS and first REF command)
- Ready for normal operation (^tRC cycles after the last refresh command)

VALID PART NUMBERS

PART NUMBER	DESCRIPTION
MT49H8M32FM-xx	8 Meg x 32
MT49H16M16FM-xx	16 Meg x 16

GENERAL DESCRIPTION

The Micron[®] 256Mb Reduced Latency DRAM (RLDRAM) contains 8 banks x32Mb of memory accessible with 32-bit or 16-bit I/Os in a double data rate (DDR) format where the data is provided and synchronized with a differential echo clock signal. RLD RAM does not require

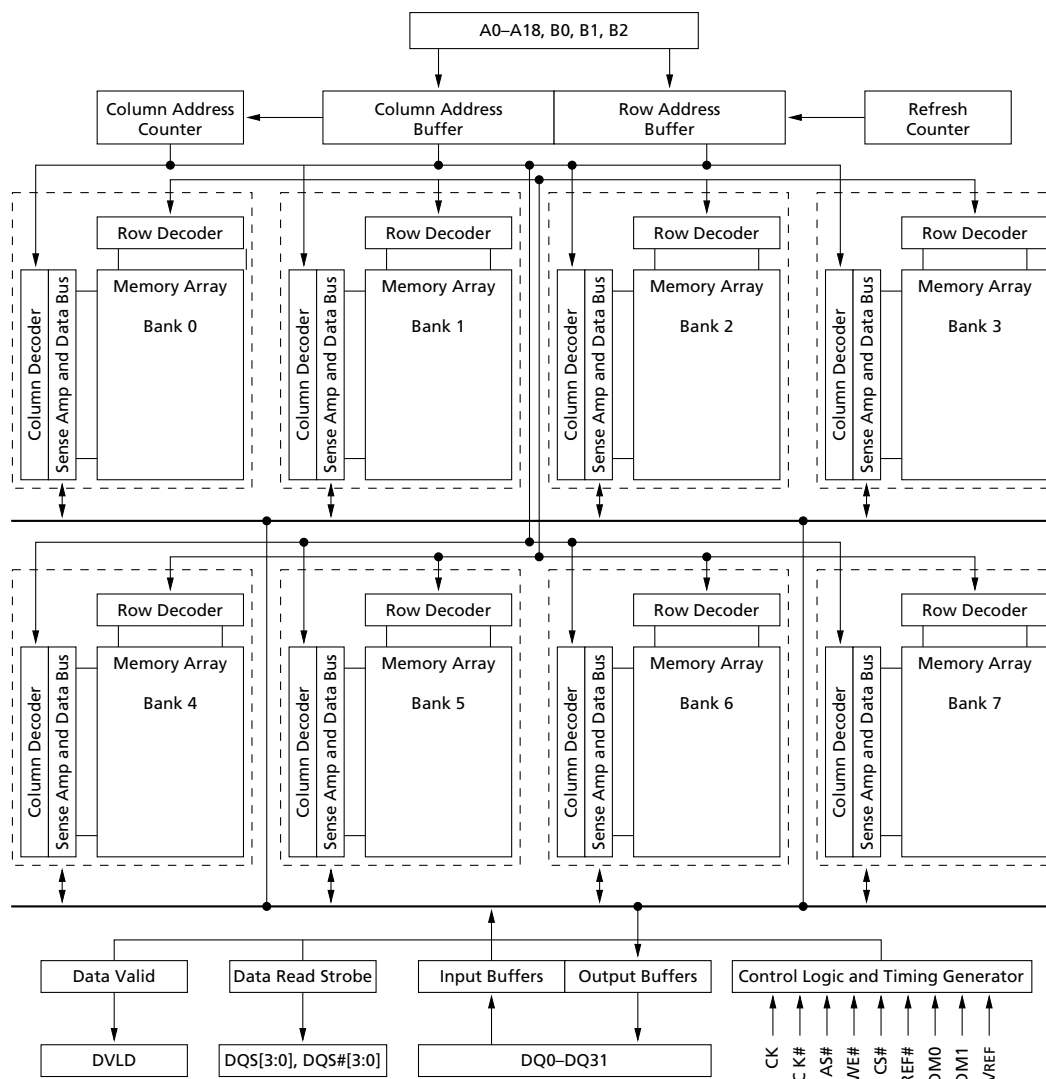
POWER-DOWN

Because the RLD RAM uses multiple power supply voltage, the following sequence is required for power-down.

- Take all input signals to be V_{ss} or High-Z

It is recommended to place Schottky diodes on the board between the 2.5V and 1.8V power supplies.

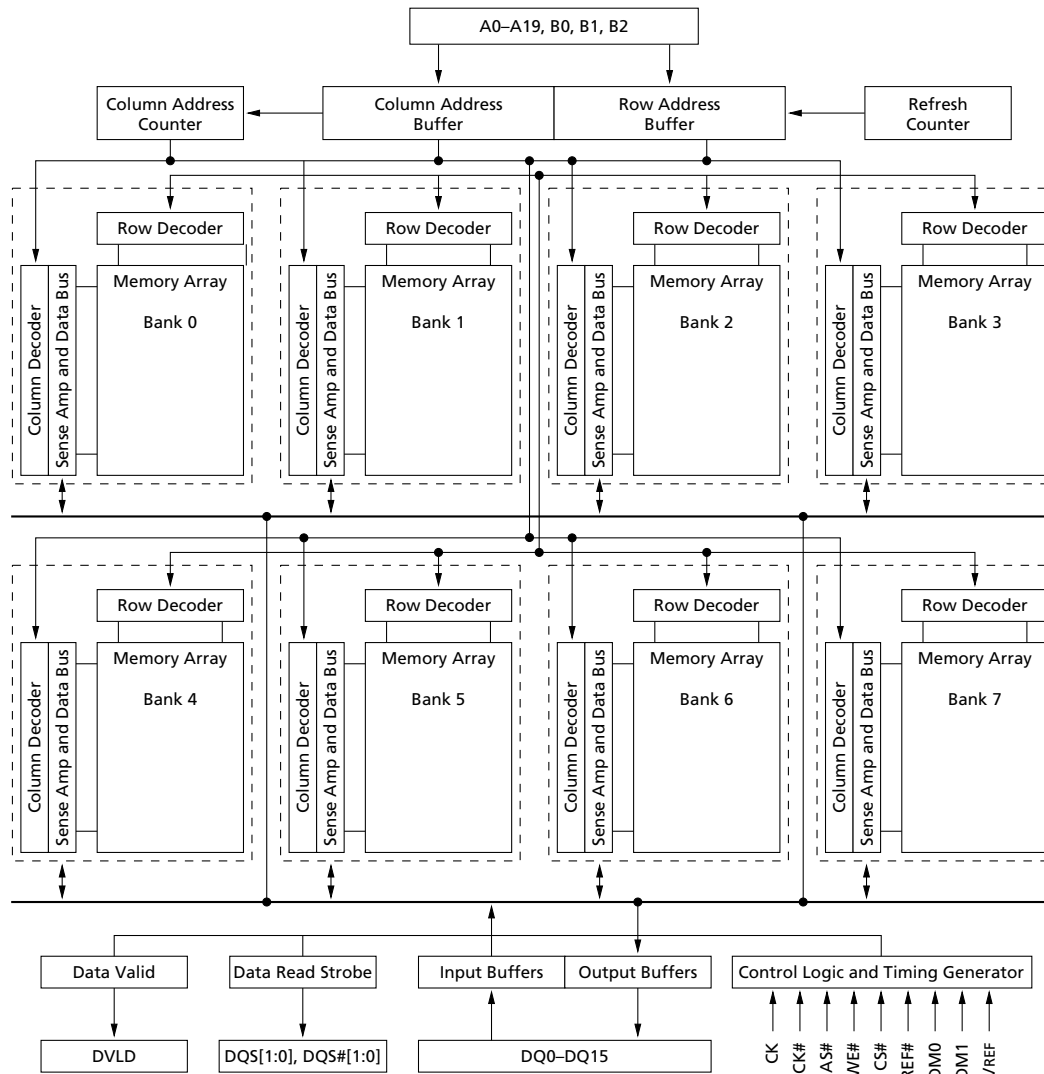
FUNCTIONAL BLOCK DIAGRAM 8 Meg x 32



NOTE: 1. When the BL4 setting is used, A18 is a "Don't Care."

FUNCTIONAL BLOCK DIAGRAM

16 Meg x 16



NOTE: 1. When the BL4 setting is used, A19 is a "Don't Care."
 2. In the 16 Meg x 16 configuration, only DQS[1:0] and DQS#[1:0] are used.

**TABLE OF CONTENTS**

General Description	1	Absolute Maximum Ratings	18
Power-Up Initialization	1	Recommended DC Operation Ranges	18
Functional Block Diagram, 8 Meg x 32	2	DC Electrical Characteristics and	
Power-Down	2	Operating Conditions	18
Functional Block Diagram, 16 Meg x 16	3	DC Electrical Characteristics and	
8 Meg x 32 Ball Assignment (Top View)		Operating Conditions	19
144-Ball T-FBGA	5	IDD Electrical Characteristics and	
16 Meg x 16 PIN Assignment (Top View)		Operating Conditions	20
144-Ball T-FBGA	5	Capacitance	21
Ball Descriptions	6	AC Electrical Characteristics and	
Ball Descriptions (continued)	7	Operating Conditions	21
Truth Table 1	8	AC Electrical Characteristics	22
Programming Description	9		
RLDRAM Programming Table	9	Timing Waveforms	
Mode Register Description	10	General Overview and Timing Definition	
Mode Register Command Table	10	(BL2/WL2)	23
IEEE 1149.1 Serial Boundary Scan (JTAG)	11	READ Timing (BL = 2)	24
Disabling the JTAG Feature	11	READ Timing (BL = 4)	25
Figure 1, TAP Controller State Diagram	11	WRITE Timing (BL = 2, RL = 6)	26
Test Access Port (TAP)	11	WRITE Timing (BL = 4, RL = 6)	27
Test Clock (TCK)	11	READ to WRITE Timing (BL = 2, WL = 2)	28
Test MODE SELECT (TMS)	11	WRITE to READ Timing (BL = 2, WL = 2)	29
Test Data-In (TDI)	11	Refresh Timing	30
Test Data-Out (TDO)	12	Example of Refresh Implementation	
Performing a TAP Reset	12	(Cyclic Bank Burst Refresh)	31
TAP Registers	12	WRITE Data Mask Timing (BL = 2, WL = 2)	32
Instruction Register	12	WRITE Data Mask Timing (BL = 4, WL = 1)	33
Figure 2, TAP Controller Block Diagram	12	WRITE/READ and READ/WRITE Timing, Cyclic	
Bypass Register	12	Bank Access (RL = 6, BL = 2, WL = 3)	34
Boundary Scan Register	12	WRITE/READ and READ/WRITE Timing, Cyclic	
Identification (ID) Register	13	Bank Access (RL = 5, BL = 2, WL = 2)	35
TAP Instruction Set	13	WRITE/READ and READ/WRITE Timing, Cyclic	
Overview	13	Bank Access (RL = 6, BL = 4, WL = 2)	36
Extest	13	WRITE/READ and READ/WRITE Timing, Cyclic	
Idcode	13	Bank Access (RL = 5, BL = 4, WL = 1)	37
Sample Z	13	Random Access, Single Bank	
Sample/Preload	13	(RL = 6, BL = 2, WL = 3)	38
Bypass	14	Random Access, Single Bank	
TAP Timing	14	(RL = 5, BL = 2, WL = 2, ^t RC = 6)	39
TAP AC Electrical Characteristics	14	Random Access, Single Bank	
Reserved	14	(RL = 6, BL = 4, WL = 2)	40
TAP DC Electrical Characteristics and		Random Access, Single Bank	
Operating Conditions	15	(RL = 5, BL = 4, WL = 1, ^t RC = 6)	41
Identification Register Definitions	16		
Scan Register Sizes	16	Package Drawing	
Instruction codes	16	144-Ball T-FBGA	42
Boundary Scan (Exit) Order	17		


8 MEG x 32 BALL ASSIGNMENT (Top View)
144-Ball T-FBGA

	1	2	3	4	5	6	7	8	9	10	11	12
A	V _{SS}	V _{EXT}	V _{REF}	V _{SS}					V _{SS}	V _{EXT}	TMS	TCK
B	V _{SS}	DQ8	DQ9	V _{SSQ}					V _{SSQ}	DQ1	DQ0	V _{SS}
C	V _{SS}	DQ10	DQ11	V _{DDQ}					V _{DDQ}	DQ3	DQ2	V _{SS}
D	V _{SS}	DQS1	DQS1#	V _{SSQ}					V _{SSQ}	DQS0#	DQS0	V _{SS}
E	V _{SS}	DQ12	DQ13	V _{DDQ}					V _{DDQ}	DQ5	DQ4	V _{SS}
F	DM0	DQ14	DQ15	V _{SSQ}					V _{SSQ}	DQ7	DQ6	DVLD
G	A5	A6	A7	V _{DD}					V _{DD}	A2	A1	A0
H	A8	A9	V _{SS}	V _{SS}					V _{SS}	V _{SS}	A4	A3
J	AS#	B2	V _{DD}	V _{DD}					V _{DD}	V _{DD}	B0	CK
K	WE#	REF#	V _{DD}	V _{DD}					V _{DD}	V _{DD}	B1	CK#
L	A18	CS#	V _{SS}	V _{SS}					V _{SS}	V _{SS}	A14	A13
M	A15	A16	A17	V _{DD}					V _{DD}	A12	A11	A10
N	DM1	DQ22	DQ23	V _{SSQ}					V _{SSQ}	DQ31	DQ30	NC
P	V _{SS}	DQ20	DQ21	V _{DDQ}					V _{DDQ}	DQ29	DQ28	V _{SS}
R	V _{SS}	DQS2	DQS2#	V _{SSQ}					V _{SSQ}	DQS3#	DQS3	V _{SS}
T	V _{SS}	DQ18	DQ19	V _{DDQ}					V _{DDQ}	DQ27	DQ26	V _{SS}
U	V _{SS}	DQ16	DQ17	V _{SSQ}					V _{SSQ}	DQ25	DQ24	V _{SS}
V	V _{SS}	V _{EXT}	V _{REF}	V _{SS}					V _{SS}	V _{EXT}	TDO	TDI

16 MEG x 16 BALL ASSIGNMENT (Top View)
144-Ball T-FBGA

	1	2	3	4	5	6	7	8	9	10	11	12
A	V _{SS}	V _{EXT}	V _{REF}	V _{SS}					V _{SS}	V _{EXT}	TMS	TCK
B	V _{SS}	NC	NC	V _{SSQ}					V _{SSQ}	DQ1	DQ0	V _{SS}
C	V _{SS}	NC	NC	V _{DDQ}					V _{DDQ}	DQ3	DQ2	V _{SS}
D	V _{SS}	NC	NC	V _{SSQ}					V _{SSQ}	DQS0#	DQS0	V _{SS}
E	V _{SS}	NC	NC	V _{DDQ}					V _{DDQ}	DQ5	DQ4	V _{SS}
F	DM0	NC	NC	V _{SSQ}					V _{SSQ}	DQ7	DQ6	DVLD
G	A5	A6	A7	V _{DD}					V _{DD}	A2	A1	A0
H	A8	A9	V _{SS}	V _{SS}					V _{SS}	V _{SS}	A4	A3
J	AS#	B2	V _{DD}	V _{DD}					V _{DD}	V _{DD}	B0	CK
K	WE#	REF#	V _{DD}	V _{DD}					V _{DD}	V _{DD}	B1	CK#
L	A19	CS#	V _{SS}	V _{SS}					V _{SS}	V _{SS}	A14	A13
M	A15	A16	A17	V _{DD}					V _{DD}	A12	A11	A10
N	DM1	NC	NC	V _{SSQ}					V _{SSQ}	DQ15	DQ14	A18
P	V _{SS}	NC	NC	V _{DDQ}					V _{DDQ}	DQ13	DQ12	V _{SS}
R	V _{SS}	NC	NC	V _{SSQ}					V _{SSQ}	DQS1#	DQS1	V _{SS}
T	V _{SS}	NC	NC	V _{DDQ}					V _{DDQ}	DQ11	DQ10	V _{SS}
U	V _{SS}	NC	NC	V _{SSQ}					V _{SSQ}	DQ9	DQ8	V _{SS}
V	V _{SS}	V _{EXT}	V _{REF}	V _{SS}					V _{SS}	V _{EXT}	TDO	TDI



BALL DESCRIPTIONS

T-FBGA (x32)	T-FBGA (x16)	SYMBOL	TYPE	DESCRIPTION
12J, 12K	12J, 12K	CK, CK#	Input	Differential input clock pair
2L	2L	CS#	Input	Chip select
1J	1J	AS#	Input	Address strobe
1K	1K	WE#	Input	Write enable
2K	2K	REF#	Input	Auto refresh
11J, 11K, 2J	11J, 11K, 2J	B[0:2]	Input	Bank select
12G, 11G, 10G, 12H, 11H, 1G, 2G, 3G, 1H, 2H, 12M, 11M, 10M, 12L, 11L, 1M, 2M, 3M, 1L	12G, 11G, 10G, 12H, 11H, 1G, 2G, 3G, 1H, 2H, 12M, 11M, 10M, 12L, 11L, 1M, 2M, 3M, 12N, 1L	A[0:18] A[0:19]	Input	Address input
1F, 1N	1F, 1N	DM0, DM1	Input	Data Mask
11A 12V	11A 12V	TMS TDI	Input	IEEE 1149.1 Test Inputs: JEDEC-standard 1.8V I/O levels. These pins may be left Not Connected if the JTAG function is not used in the circuit.
12A	12A	TCK	Input	IEEE 1149.1 Clock Input: JEDEC-standard 1.8V I/O levels. This pin must be tied to V _{SS} if the JTAG function is not used in the circuit.
3A, 3V	3A, 3V	V _{REF}	Input	Input Reference Voltage: Nominally V _{DDQ} /2. Provides a reference voltage for the input buffers.
11B, 10B, 11C, 10C, 11E, 10E, 11F, 10F, 2B, 3B, 2C, 3C, 2E, 3E, 2F, 3F, 2U, 3U, 2T, 3T, 2P, 3P, 2N, 3N, 11U, 10U, 11T, 10T, 11P, 10P, 11N, 10N	11B, 10B, 11C, 10C, 11E, 10E, 11F, 10F, 11U, 10U, 11T, 10T, 11P, 10P, 11N, 10N	DQ0–DQ31	Input/ Output	Synchronous Data I/Os: Input data must meet setup and hold times around the rising edges of CK and CK#. Output data is synchronized to DQS and DQS#.
11D, 2D, 2R, 11R, 10D, 3D, 3R, 10R	11D, 11R, 10D, 10R	DQS0–3 (x32) DQS#0–3 (x32) DQS0–1 (x16) DQS#0–1 (x16)	Output	Differential data read strobe
12F	12F	DVLD	Output	Data Valid
11V	11V	TDO	Output	IEEE 1149.1 Test Output: JEDEC-standard 1.8V I/O level.
2A, 2V, 10A, 10V	2A, 2V, 10A, 10V	V _{EXT}	Supply	Power Supply: 2.5V nominal. See DC Electrical Characteristics and Operating Conditions for range.
3J, 3K, 4G, 4J, 4K, 4M, 9G, 9J, 9K, 9M, 10J, 10K	3J, 3K, 4G, 4J, 4K, 4M, 9G, 9J, 9K, 9M, 10J, 10K	V _{DD}	Supply	Power Supply: 1.8V nominal. See DC Electrical Characteristics and Operating Conditions for range.

(continued on next page)


BALL DESCRIPTIONS (continued)

T-FBGA (x32)	T-FBGA (x16)	SYMBOL	TYPE	DESCRIPTION
4C, 4E, 4P, 4T, 9C, 9E, 9P, 9T	4C, 4E, 4P, 4T, 9C, 9E, 9P, 9T	V _{DDQ}	Supply	Power Supply: Isolated Output Buffer Supply. Nominally 1.8V. See DC Electrical Characteristics and Operating Conditions for range.
1A–E, 1P–V, 3H, 3L, 4A, 4H, 4L, 4V, 9A, 9H, 9L, 9V, 10H, 10L, 12B–E, 12P–U	1A–E, 1P–V, 3H, 3L, 4A, 4H, 4L, 4V, 9A, 9H, 9L, 9V, 10H, 10L, 12B–E, 12P–U	V _{SS}	Supply	Power Supply: GND.
4B, 4D, 4F, 4N, 4R, 4U, 9B, 9D, 9F, 9N, 9R, 9U	4B, 4D, 4F, 4N, 4R, 4U, 9B, 9D, 9F, 9N, 9R, 9U	V _{SSQ}	Supply	Power Supply: Isolated Output Buffer Supply. GND.
12N	2B–2F, 2N–2U, 3B–3F, 3N–3U	NC	–	No Connect: These signals are not internally connected and may be connected to ground to improve package heat dissipation.

**TRUTH TABLE¹**

OPERATION	CS#	AS#	WE#	REF#	A[19:0] ²	B[2:0]	DM[1:0]
READ Cycle	L	L	H	H	VALID	VALID	X
WRITE Cycle	L	L	L	H	VALID	VALID	VALID
NOP: No operation	L	H	H	H	X	X	X
Deselect	H	X	X	X	X	X	X
Auto Refresh	L	H	H	L	X	VALID	X
MRS: Mode Register Set ³	L	L	L	L	VALID	X	X

NOTE: 1. X = "Don't Care."
 H = logic HIGH.
 L = logic LOW.
 2. In the x32 configuration A19 is not used.
 3. Only A17–A0 are used for the Mode Register Set Command.

PROGRAMMING DESCRIPTION

The following table shows, for three operating frequencies, the different RLD RAM configurations that can be programmed into the Mode Register. The Read Latency (RL) values and the Write Latencies (WL) used by the

RLD RAM for the two Burst Lengths (BL) are also indicated. Finally, the minimum allowed t_{RC} in clock cycles and in ns are shown as well. The shaded areas correspond to configurations that are not allowed.

RLD RAM Programming Table

		FREQUENCY					
	Unit	-3.3 (300 MHz)					
Config. Nb.		1	2	3	4	5	6
RL	TCK	5	5	5	6	7	8
WL (BL2)	TCK	2	2	2	3	4	5
WL (BL4)	TCK	1	1	1	2	3	4
t_{RC} (MIN)	TCK	5	6	7	8	9	10
t_{RC} (MIN)	ns	16.7	20.0	23.3	26.7	30.0	33.3
		-4 (250 MHz)					
Config. Nb.		1	2	3	4	5	6
RL	TCK	5	5	5	6	7	8
WL (BL2)	TCK	2	2	2	3	4	5
WL (BL4)	TCK	1	1	1	2	3	4
t_{RC} (MIN)	TCK	5	6	7	8	9	10
t_{RC} (MIN)	ns	20	24	28	32	36	40
		-5 (200 MHz)					
Config. Nb.		1	2	3	4	5	6
RL	TCK	5	5	5	6	7	8
WL (BL2)	TCK	2	2	2	3	4	5
WL (BL4)	TCK	1	1	1	2	3	4
t_{RC} (MIN)	TCK	5	6	7	8	9	10
t_{RC} (MIN)	ns	25	30	35	40	45	50

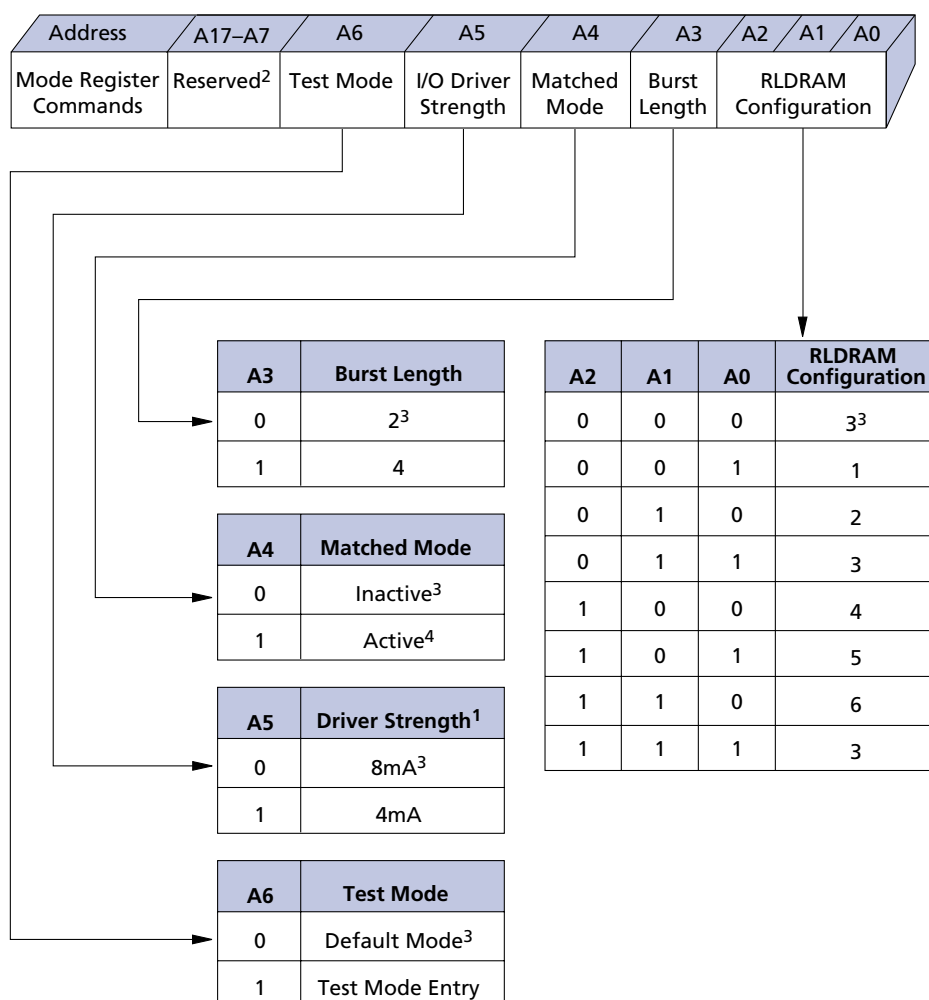
- NOTE:**
1. The speed sort -3.3 provides part functional up to 300 MHz in the configurations 4, 5, and 6 only.
The functionality of the configurations 1, 2, and 3 is not guaranteed for speed sort -3.3.
 2. The speed sort -4 provides part functional up to 250 MHz in the configurations 3, 4, 5, and 6 only.
The functionality of the configurations 1 and 2 is not guaranteed for speed sort -4.
 3. The speed sort -5 provides part functional up to 200 MHz in all configurations.



MODE REGISTER DESCRIPTION

The address signals A[17:0] are used to set the mode register.

Mode Register Command Table



- NOTE:**
1. HSTL-compliant current specification
 2. Bits A17–A6 MUST be set LOW (Logic 0)
 3. Default configuration
 4. When Matched Mode is asserted, the automatic I/O impedance calibration is activated
 5. Test Mode entry for vendor test mode only
 6. The Mode Register Set default configuration corresponds to all address bits equal to zero

IEEE 1149.1 SERIAL BOUNDARY SCAN (JTAG)

The RLD RAM incorporates a serial boundary scan Test Access Port (TAP). This port operates in accordance with IEEE Standard 1149.1-1990 but does not have the set of functions required for full 1149.1 compliance. These functions from the IEEE specification are excluded because their inclusion places an added delay in the critical speed path of the RLD RAM. Note that the TAP controller functions in a manner that does not conflict with the operation of other devices using 1149.1 fully compliant TAPs. The TAP operates using JEDEC-standard 1.8V I/O logic levels.

The RLD RAM contains a TAP controller, instruction register, boundary scan register, bypass register, and ID register.

DISABLING THE JTAG FEATURE

It is possible to operate the RLD RAM without using the JTAG feature. To disable the TAP controller, TCK must be tied LOW (V_{SS}) to prevent clocking of the device. TDI and TMS are internally pulled up and may be unconnected. They may alternately be connected to V_{DD} through a pull-up resistor. TDO should be left unconnected. Upon power-up, the device will come up in a reset state which will not interfere with the operation of the device.

TEST ACCESS PORT (TAP)

TEST CLOCK (TCK)

The test clock is used only with the TAP controller. All inputs are captured on the rising edge of TCK. All outputs are driven from the falling edge of TCK.

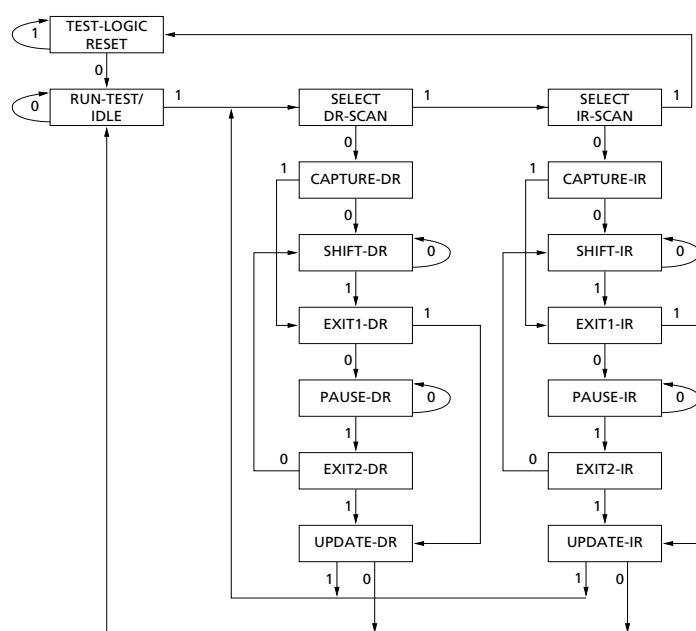
TEST MODE SELECT (TMS)

The TMS input is used to give commands to the TAP controller and is sampled on the rising edge of TCK. It is allowable to leave this pin unconnected if the TAP is not used. The pin is pulled up internally, resulting in a logic HIGH level.

TEST DATA-IN (TDI)

The TDI pin is used to serially input information into the registers and can be connected to the input of any of the registers. The register between TDI and TDO is chosen by the instruction that is loaded into the TAP instruction register. For information on loading the instruction register, see Figure 1. TDI is internally pulled up and can be unconnected if the TAP is unused in an application. TDI is connected to the most significant bit (MSB) of any register. (See Figure 2.)

Figure 1
TAP Controller State Diagram



NOTE: The 0/1 next to each state represents the value of TMS at the rising edge of TCK.



TEST DATA-OUT (TDO)

The TDO output pin is used to serially clock data-out from the registers. The output is active depending upon the current state of the TAP state machine. (See Figure 1.) The output changes on the falling edge of TCK. TDO is connected to the least significant bit (LSB) of any register. (See Figure 2.)

PERFORMING A TAP RESET

A RESET is performed by forcing TMS HIGH (V_{DD}) for five rising edges of TCK. This RESET does not affect the operation of the RLD RAM and may be performed while the RLD RAM is operating.

At power-up, the TAP is reset internally to ensure that TDO comes up in a High-Z state.

TAP REGISTERS

Registers are connected between the TDI and TDO pins and allow data to be scanned into and out of the RLD RAM test circuitry. Only one register can be selected at a time through the instruction register. Data is serially loaded into the TDI pin on the rising edge of TCK. Data is output on the TDO pin on the falling edge of TCK.

INSTRUCTION REGISTER

Three-bit instructions can be serially loaded into the instruction register. This register is loaded when it is placed between the TDI and TDO pins as shown in Figure 2. Upon power-up, the instruction register is loaded with the IDCODE instruction. It is also loaded with the IDCODE instruction if the controller is placed in a reset state as described in the previous section.

When the TAP controller is in the Capture-IR state, the two least significant bits are loaded with a binary “01” pattern to allow for fault isolation of the board-level serial test data path.

BYPASS REGISTER

To save time when serially shifting data through registers, it is sometimes advantageous to skip certain chips. The bypass register is a single-bit register that can be placed between the TDI and TDO pins. This allows data to be shifted through the RLD RAM with minimal delay. The bypass register is set LOW (V_{ss}) when the BYPASS instruction is executed.

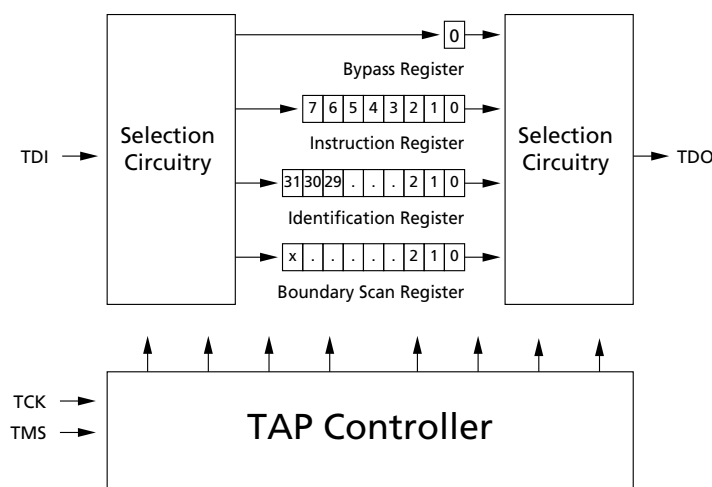
BOUNDARY SCAN REGISTER

The boundary scan register is connected to all the input and bidirectional pins on the RLD RAM. Several no connect (NC) pins are also included in the scan register to reserve pins. The RLD RAM has a 104-bit register.

The boundary scan register is loaded with the contents of the RAM I/O ring when the TAP controller is in the Capture-DR state and is then placed between the TDI and TDO pins when the controller is moved to the Shift-DR state. The EXTEST, SAMPLE/PRELOAD, and SAMPLE Z instructions can be used to capture the contents of the I/O ring.

The Boundary Scan Order tables show the order in which the bits are connected. Each bit corresponds to one of the pins on the RLD RAM package. The MSB of the register is connected to TDI, and the LSB is connected to TDO.

Figure 2
TAP Controller Block Diagram



x = 103 for all configurations.

IDENTIFICATION (ID) REGISTER

The ID register is loaded with a vendor-specific, 32-bit code during the Capture-DR state when the IDCODE command is loaded in the instruction register. The IDCODE is hardwired into the RLD RAM and can be shifted out when the TAP controller is in the Shift-DR state. The ID register has a vendor code and other information described in the Identification Register Definitions table.

TAP INSTRUCTION SET OVERVIEW

Eight different instructions are possible with the three-bit instruction register. All combinations are listed in the Instruction Codes table (see page 16). Three of these instructions are listed as RESERVED and should not be used. The other five instructions are described in detail below.

The TAP controller used in this RLD RAM is not fully compliant to the 1149.1 convention because some of the mandatory 1149.1 instructions are not fully implemented. The TAP controller cannot be used to load address, data or control signals into the RLD RAM and cannot preload the I/O buffers. The RLD RAM does not implement the 1149.1 commands EXTEST or INTEST or the PRELOAD portion of SAMPLE/PRELOAD; rather it performs a capture of the I/O ring when these instructions are executed.

Instructions are loaded into the TAP controller during the Shift-IR state when the instruction register is placed between TDI and TDO. During this state, instructions are shifted through the instruction register through the TDI and TDO pins. To execute the instruction once it is shifted in, the TAP controller needs to be moved into the Update-IR state.

EXTEST

EXTEST is a mandatory 1149.1 instruction which is to be executed whenever the instruction register is loaded with all 0s. EXTEST is not implemented in the TAP controller, hence this device is not IEEE 1149.1 compliant.

The TAP controller does recognize an all-0 instruction. When an EXTEST instruction is loaded into the instruction register, the RLD RAM responds as if a SAMPLE/PRELOAD instruction has been loaded. EXTEST does not place the RLD RAM outputs in a High-Z state, CQ, CQ#.

IDCODE

The IDCODE instruction causes a vendor-specific, 32-bit code to be loaded into the instruction register. It also places the instruction register between the TDI and TDO pins and allows the IDCODE to be shifted out of the device when the TAP controller enters the Shift-DR state. The IDCODE instruction is loaded into the instruction regis-

ter upon power-up or whenever the TAP controller is given a test logic reset state.

SAMPLE/PRELOAD

SAMPLE/PRELOAD is a 1149.1 mandatory instruction. The PRELOAD portion of this instruction is not implemented, so the device TAP controller is not fully 1149.1-compliant.

When the SAMPLE/PRELOAD instruction is loaded into the instruction register and the TAP controller is in the Capture-DR state, a snapshot of data on the inputs and bidirectional pins is captured in the boundary scan register.

The user must be aware that the TAP controller clock can only operate at a frequency up to 10 MHz, while the RLD RAM clock operates more than an order of magnitude faster. Because there is a large difference in the clock frequencies, it is possible that during the Capture-DR state, an input or output will undergo a transition. The TAP may then try to capture a signal while in transition (metastable state). This will not harm the device, but there is no guarantee as to the value that will be captured. Repeatable results may not be possible.

To guarantee that the boundary scan register will capture the correct value of a signal, the RLD RAM signal must be stabilized long enough to meet the TAP controller's capture setup plus hold time (^tCS plus ^tCH). The RLD RAM clock input might not be captured correctly if there is no way in a design to stop (or slow) the clock during a SAMPLE/PRELOAD instruction. If this is an issue, it is still possible to capture all other signals and simply ignore the value of the CK and CK# captured in the boundary scan register.

Once the data is captured, it is possible to shift out the data by putting the TAP into the Shift-DR state. This places the boundary scan register between the TDI and TDO pins.

Note that since the PRELOAD part of the command is not implemented, putting the TAP to the Update-DR state while performing a SAMPLE/PRELOAD instruction will have the same effect as the Pause-DR command.

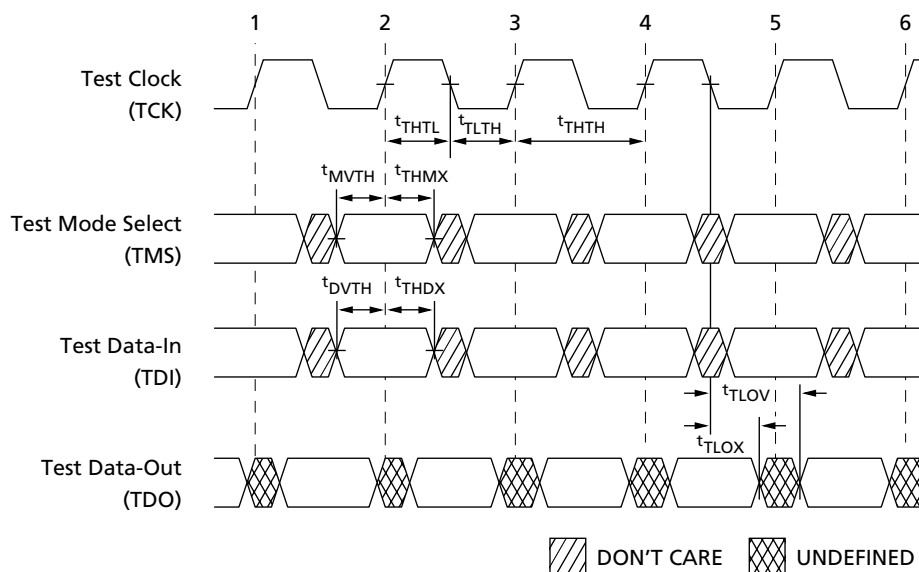
BYPASS

When the BYPASS instruction is loaded in the instruction register and the TAP is placed in a Shift-DR state, the bypass register is placed between TDI and TDO. The advantage of the BYPASS instruction is that it shortens the boundary scan path when multiple devices are connected together on a board.

RESERVED

These instructions are not implemented but are reserved for future use. Do not use these instructions.

TAP TIMING



TAP AC ELECTRICAL CHARACTERISTICS

(Notes 1, 2) (+20°C ≤ T_J ≤ +100°C, +1.7V ≤ V_{DD} ≤ +1.9V)

DESCRIPTION	SYMBOL	MIN	MAX	UNITS
Clock				
Clock cycle time	t _{THTH}	20		ns
Clock frequency	f _{TF}		50	MHz
Clock HIGH time	t _{THTL}	10		ns
Clock LOW time	t _{TLTH}	10		ns
Output Times				
TCK LOW to TDO unknown	t _{TLOX}	0	10	ns
TCK LOW to TDO valid	t _{TLOV}		10	ns
TDI valid to TCK HIGH	t _{DVTH}	5		ns
TCK HIGH to TDI invalid	t _{THDX}	5		ns
Setup Times				
TMS setup	t _{MVTH}	5		ns
Capture setup	t _{CS}	5		ns
Hold Times				
TMS hold	t _{THMX}	5		ns
Capture hold	t _{CH}	5		ns

NOTE: 1. t_{CS} and t_{CH} refer to the setup and hold time requirements of latching data from the boundary scan register.
2. Test conditions are specified using the load in Figure 4.



TAP DC ELECTRICAL CHARACTERISTICS AND OPERATING CONDITIONS

(+20°C ≤ T_J ≤ 110°C, +2.4V ≤ V_{DD} ≤ +2.6V unless otherwise noted)

DESCRIPTION	CONDITIONS	SYMBOL	MIN	MAX	UNITS	NOTES
Input High (Logic 1) Voltage		V _{IH}	V _{REF} + 0.15	V _{DD} + 0.3	V	1, 2
Input Low (Logic 0) Voltage		V _{IL}	V _{SSQ} - 0.3	V _{REF} - 0.15	V	1, 2
Input Leakage Current	0V ≤ V _{IN} ≤ V _{DD}	I _{LI}	-5.0	5.0	μA	
Output Leakage Current	Output(s) disabled, 0V ≤ V _{IN} ≤ V _{DDQ}	I _{LO}	-5.0	5.0	μA	
Output Low Voltage	I _{OLC} = 100μA	V _{OL1}		V _{REF} - TBD	V	1
Output Low Voltage	I _{OLT} = 2mA	V _{OL2}		V _{REF} - TBD	V	1
Output High Voltage	I _{OHC} = 100μA	V _{OH1}	V _{REF} + TBD		V	1
Output High Voltage	I _{OHT} = 2mA	V _{OH2}	V _{REF} + TBD		V	1

NOTE: 1. All voltages referenced to V_{SS} (GND).

2. Overshoot: V_{IH}(AC) ≤ V_{DD} + 1.5V for t ≤ 'KHKH/2

Undershoot: V_{IL}(AC) ≥ -0.5V for t ≤ 'KHKH/2

Power-up: V_{IH} ≤ +1.9 and V_{DD} ≤ 1.7V and V_{DDQ} ≤ 1.4V for t ≤ 200ms

During normal operation, V_{DDQ} must not exceed V_{DD}. Control input signals (such as LD#, R/W#, etc.) may not have pulse widths less than 'KHKL (MIN) or operate at frequencies exceeding 'KF (MAX).



IDENTIFICATION REGISTER DEFINITIONS

INSTRUCTION FIELD	ALL DEVICES	DESCRIPTION
REVISION NUMBER (31:28)	00ab	ab = 10 for x32, 01 for x16.
DEVICE ID (27:12)	0000000010100111	This represents the part number
MICRON JEDEC ID CODE (11:1)	00000101100	Allows unique identification of RLD RAM vendor.
ID Register Presence Indicator (0)	1	Indicates the presence of an ID register.

SCAN REGISTER SIZES

REGISTER NAME	BIT SIZE
Instruction	8
Bypass	1
ID	32
Boundary Scan	104

INSTRUCTION CODES

INSTRUCTION	CODE	DESCRIPTION
EXTEST	0000 0000	Captures I/O ring contents. Places the boundary scan register between TDI and TDO. This instruction is not 1149.1-compliant. This operation does not affect RLD RAM operations.
IDCODE	0010 0001	Loads the ID register with the vendor ID code and places the register between TDI and TDO. This operation does not affect RLD RAM operations.
SAMPLE/PRELOAD	0000 0101	Captures I/O ring contents. Places the boundary scan register between TDI and TDO. This instruction does not implement 1149.1 preload function and is therefore not 1149.1-compliant.
BYPASS	1111 1111	Places the bypass register between TDI and TDO. This operation does not affect RLD RAM operations.



Boundary Scan (Exit) Order

BIT#	FBGA BALL
1	J1
2	J2
3	H2
4	H1
5	G1
6	G3
7	G2
8	F1
9	F3
10	F3
11	F2
12	F2
13	E3
14	E3
15	E2
16	E2
17	D2
18	D3
19	C2
20	C2
21	C3
22	C3
23	B2
24	B2
25	B3
26	B3
27	B10
28	B10
29	B11
30	B11
31	C10
32	C10
33	C11
34	C11
35	D10

BIT#	FBGA BALL
36	D11
37	E11
38	E11
39	E10
40	E10
41	F11
42	F11
43	F10
44	F10
45	F12
46	G11
47	G10
48	G12
49	H12
50	H11
51	J11
52	J12
53	K12
54	K11
55	L11
56	L12
57	M12
58	M10
59	M11
60	M12
61	N10
62	N10
63	N11
64	N11
65	P10
66	P10
67	P11
68	P11
69	R11
70	R10

BIT#	FBGA BALL
71	T11
72	T11
73	T10
74	T10
75	U11
76	U11
77	U10
78	U10
79	U3
80	U3
81	U2
82	U2
83	T3
84	T3
85	T2
86	T2
87	R3
88	R2
89	P2
90	P2
91	P3
92	P3
93	N2
94	N2
95	N3
96	N3
97	N1
98	M2
99	M3
100	M1
101	L1
102	L2
103	K2
104	K1

NOTE: 1. Any unused pins that are in the order will read as a logic "0."



ABSOLUTE MAXIMUM RATINGS*

Storage Temperature	-55°C to +150°C
I/O Voltage	-0.3V to + V _{DDQ} + 0.3V
Voltage on V _{EXT} Supply Relative to V _{SS} ...	-0.3V to +2.8V
Voltage on V _{DD} Supply Relative to V _{SS}	-0.3V to +2.1V
Voltage on V _{DDQ} Supply Relative to V _{SS} ..	-0.3V to +2.1V
Junction Temperature**	100°C

*Stresses greater than those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only, and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

**Junction temperature depends upon package type, cycle time, loading, ambient temperature, and airflow.

RECOMMENDED DC OPERATION RANGES

All values are recommended operating conditions unless otherwise noted. External on board (PCB) capacitance values are required as follows:

- V_{DDQ} :2 x 0.1μF/device
- V_{DD} :2 x 0.1μF/device
- V_{REF} :0.1μF/device
- V_{EXT} :0.1μF/device

DC ELECTRICAL CHARACTERISTICS AND OPERATING CONDITIONS

(+20°C ≤ T_J ≤ +110°C; +1.75V ≤ V_{DD} ≤ +1.85V unless otherwise noted)

DESCRIPTION	SYMBOL	MIN	MAX	UNITS	NOTES
Supply Voltage	V _{EXT}	2.38	2.63	V	1
Supply Voltage	V _{DD}	1.75	1.85	V	1,
Isolated Output Buffer Supply	V _{DDQ}	1.7	1.9	V	1, 4
Reference Voltage	V _{REF}	0.95 x V _{DDQ} /2	1.05 x V _{DDQ} /2	V	1, 2, 3

- NOTE:**
1. All voltages referenced to V_{SS} (GND).
 2. Typically the value of V_{REF} is expected to be 0.5x V_{DDQ} of the transmitting device. V_{REF} is expected to track variations in V_{DDQ}.
 3. Peak to peak AC noise on V_{REF} must not exceed 2% V_{REF(DC)}.
 4. During normal operation, V_{DDQ} must not exceed V_{DD}.



DC ELECTRICAL CHARACTERISTICS AND OPERATING CONDITIONS

(+20°C ≤ T_J ≤ +110°C; +1.75V ≤ V_{DD} ≤ +1.85V unless otherwise noted)

DESCRIPTION	CONDITIONS	SYM	MIN	MAX	UNITS	NOTES
Input High (Logic 1) Voltage	Matched Impedance Mode	V _{IH}	V _{REF} + 0.15	V _{DDQ} + 0.3	V	1, 2
Input Low (Logic 0) Voltage	Matched Impedance Mode	V _{IL}	V _{SSQ} - 0.3	V _{REF} - 0.15	V	1, 2
Output High Voltage	Matched Impedance Mode	V _{OH}	V _{DDQ}		V	1, 3, 4
Output Low Voltage	Matched Impedance Mode	V _{OL}		0	V	1, 3, 4
Input High (Logic 1) Voltage	HSTL Strong	V _{IH}	V _{REF} + 0.1	V _{DDQ} + 0.3	V	1, 2
Input Low (Logic 0) Voltage	HSTL Strong	V _{IL}	V _{SSQ} - 0.3	V _{REF} - 0.1	V	1, 2
Output High Voltage	HSTL Strong	V _{OH}	V _{DDQ} - 0.4		V	1, 3, 4
Output Low Voltage	HSTL Strong	V _{OL}		0.4	V	1, 3, 4
Input High (Logic 1) Voltage	HSTL Weak	V _{IH}			V	1, 2
Input Low (Logic 0) Voltage	HSTL Weak	V _{IL}			V	1, 2
Output High Voltage	HSTL Weak	V _{OH}			V	1, 3, 4
Output Low Voltage	HSTL Weak	V _{OL}			V	1, 3, 4
Clock Input Leakage Current		I _{LC}	-5	5	μA	
Input Leakage Current	0V ≤ V _{IN} ≤ V _{DDQ}	I _{LI}	-5	5	μA	
Output Leakage Current		I _{LO}	-5	5	μA	
Reference Voltage Current		I _{REF}	-5	5	μA	

- NOTE:**
1. All voltages referenced to V_{SS} (GND).
 2. Overshoot: V_{IH} (AC) ≤ V_{DD} + 0.7V for t ≤ t_{KHKH}/2
 Undershoot: V_{IL} (AC) ≥ -0.5V for t ≤ t_{KHKH}/2
 Power-up: V_{IH} ≤ V_{DDQ} + 0.3V and V_{DD} ≤ 1.7V and V_{DDQ} ≤ 1.4V for t ≤ 200ms
 During normal operation, V_{DDQ} must not exceed V_{DD}. Control input signals may not have pulse widths less than t_{KHKL} (MIN) or operate at cycle rates less than t_{KHKH} (MIN).
 3. AC load current is higher than the shown DC values. AC I/O curves are available upon request.
 4. HSTL outputs meet JEDEC HSTL Class I and Class II standards.


I_{DD} OPERATING CONDITIONS AND MAXIMUM LIMITS

 (+20°C ≤ T_J ≤ +110°C; V_{DD} = MAX unless otherwise noted)

DESCRIPTION	CONDITIONS	SYMBOL	TYPICAL			UNITS	NOTES
			-3.3	-4	-5		
Operating Supply Current	BL = 2, t _{CK} = MIN, t _{RC} = MIN, 1 bank active, Address change up to 8 times during minimum t _{RC}	I _{DD1} (V _{DD})	248	208	168	mA	1
		I _{DD1} (V _{EXT})	17	16	15	mA	1
Operating Supply Current	BL = 4, t _{CK} = MIN, t _{RC} = MIN, 4 banks interleave, Address change up to 8 times during minimum t _{RC} Continuous data	I _{DD4R} (V _{DD})	403	337	271	mA	1
		I _{DD4R} (V _{EXT})	27	25	22	mA	1
Operating Supply Current	BL = 2, t _{CK} = MIN, t _{RC} = MIN, 8 banks interleave, Address change up to 8 times during minimum t _{RC} Continuous data	I _{DD8} (V _{DD})	610	509	409	mA	1
		I _{DD8} (V _{EXT})	41	36	32	mA	1
Standby Current	t _{CK} = MIN, CS# = 1 all banks idle, Command toggling	I _{DDs} (V _{DD})	TBD	TBD	TBD	mA	
		I _{DDs} (V _{EXT})	TBD	TBD	TBD	mA	

NOTE: 1. Values determined with outputs in high impedance state.



CAPACITANCE

DESCRIPTION	CONDITIONS	SYMBOL	MIN	MAX	UNITS
Address/Control Input Capacitance	$T_A = 25^\circ\text{C}; f = 1 \text{ MHz}$	C_i	2	4	pF
Input/Output Capacitance (DQ)		C_o	2	4	pF
Clock Capacitance		C_{ck}	2	4	pF

AC ELECTRICAL CHARACTERISTICS AND OPERATING CONDITIONS

($+20^\circ\text{C} \leq T_J \leq +110^\circ\text{C}$; $+1.75\text{V} \leq V_{DD} \leq +1.85\text{V}$ unless otherwise noted)

DESCRIPTION	CONDITIONS	SYMBOL	MIN	MAX	UNITS
Input High (Logic 1) Voltage	Matched Impedance Mode	V_{IH}	$V_{REF} + 0.3$	$V_{DDQ} + 0.3$	V
Input Low (Logic 0) Voltage	Matched Impedance Mode	V_{IL}	$V_{SSQ} - 0.3$	$V_{REF} - 0.3$	V
CK Differential Input Voltage	Matched Impedance Mode	V_{ID}	0.6	$V_{DDQ} + 0.6$	V
CK Input Crossing Point	Matched Impedance Mode	V_{IX}	$V_{REF} - 0.15$	$V_{REF} + 0.15$	V
Input High (Logic 1) Voltage	HSTL Strong	V_{IH}	$V_{REF} + 0.2$	$V_{DDQ} + 0.3$	V
Input Low (Logic 0) Voltage	HSTL Strong	V_{IL}	$V_{SSQ} - 0.3$	$V_{REF} - 0.2$	V
CK Differential Input Voltage	HSTL Strong	V_{ID}	0.6	$V_{DDQ} + 0.6$	V
CK Input Crossing Point	HSTL Strong	V_{IX}	$V_{REF} - 0.15$	$V_{REF} + 0.15$	V
Input High (Logic 1) Voltage	HSTL Weak	V_{IH}			V
Input Low (Logic 0) Voltage	HSTL Weak	V_{IL}			V
CK Differential Input Voltage	HSTL Weak	V_{ID}			V
CK Input Crossing Point	HSTL Weak	V_{IX}			V



AC ELECTRICAL CHARACTERISTICS

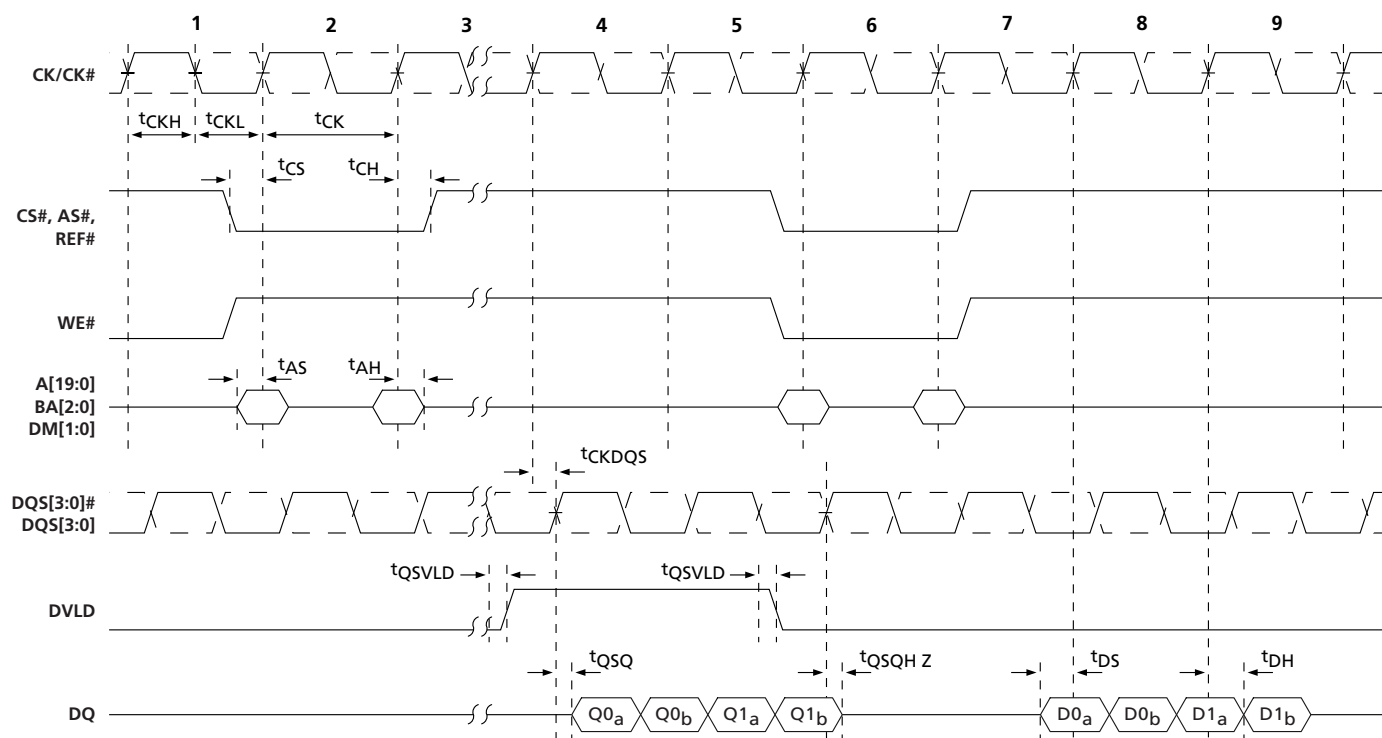
(Notes 4, 5) (+20°C ≤ T_J ≤ +110°C; +1.75V ≤ V_{DD} ≤ +1.85V)

DESCRIPTION		-3.3		-4		-5		UNITS	NOTES
	SYMBOL	MIN	MAX	MIN	MAX	MIN	MAX		
Clock									
Clock cycle time	t _{CK}	3.3		4.0		5.0		ns	
Clock HIGH time	t _{CKH}	0.45	0.55	0.45	0.55	0.45	0.55	t _{CK}	
Clock LOW time	t _{CKL}	0.45	0.55	0.45	0.55	0.45	0.55	t _{CK}	
Clock to DQS,DQS#	t _{CKDQS}	2.3	3.7	2.3	3.7	2.3	3.7	ns	1
DQS,DQS# HIGH time	t _{DQSH}	0.4	0.6	0.4	0.6	0.4	0.6	t _{CK}	
DQS,DQS# LOW time	t _{DQSL}	0.4	0.6	0.4	0.6	0.4	0.6	t _{CK}	
Output Times									
DQS to output valid	t _{QSQ}	-0.3	0.3	-0.3	0.3	-0.3	0.3	ns	2
DQS to output High-Z	t _{QSQHZ}	0.4		0.4		0.4		ns	
DQS# to DVLD	t _{QSVLD}	-0.4	0.4	-0.4	0.4	-0.4	0.4	ns	3
MRS to any command	t _{MRSC}	4		4		4		t _{CK}	4
Setup Times									
Address/Command	t _{AS} /t _{CS}	1.0		1.0		1.0		ns	
Data-in	t _{DS}	0.5		0.5		0.5		ns	
Hold Times									
Address/Command	t _{AH} /t _{CH}	1.0		1.0		1.0		ns	
Data-in	t _{DH}	0.5		0.5		0.5		ns	

- NOTE:**
1. All timing parameters are referenced to V_{REF} or to the signal crossing points for different signals.
 2. Parameter only valid within one DQS/DQ group, e.g., DQS0, DQS0# and DQ0–DQ7; DQS1, DQS1# and DQ8–DQ15.
 3. The rising and falling edges of DVLD are referenced to falling edges of DQS.
 4. In Matched Impedance Mode, TBD cycles are required.



GENERAL OVERVIEW AND TIMING DEFINITION (BL2/WL2)

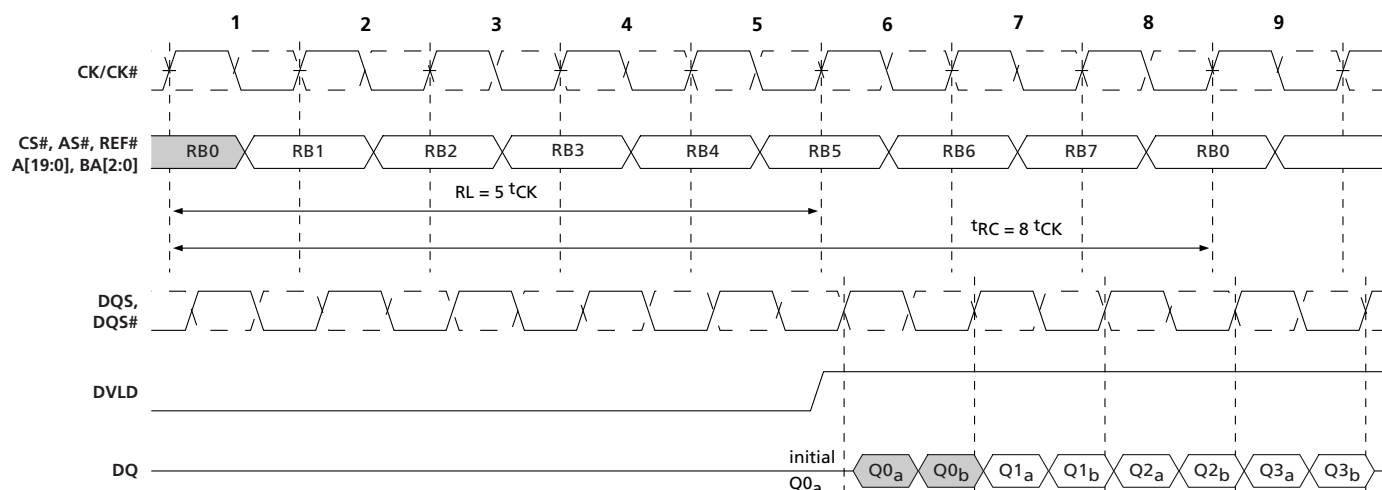


- NOTE:**
1. Address A[19:0] and commands CS#, AS#, WE#, REF# are referenced to the rising edge of the clock CK.
 2. Input Data DQ is referenced to the rising or falling edge of the clock.
 3. DVLD is referenced to the falling edge of DQS.



READ TIMING

(BL = 2)

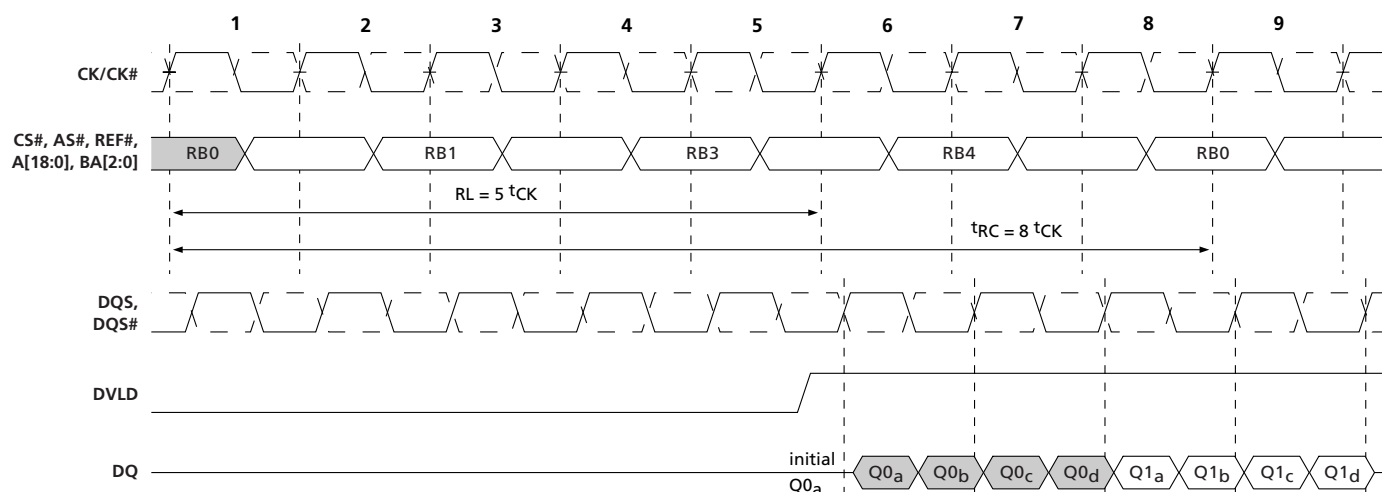


- NOTE:**
1. Starting with all banks closed, 8 banks cyclic access.
 2. 2-bit prefetch, BL = 2.
 3. Read latency (RL) programmable.
 4. CS# = 1 deactivates command inputs. DQS and DQS# not affected.



READ TIMING

(BL = 4)

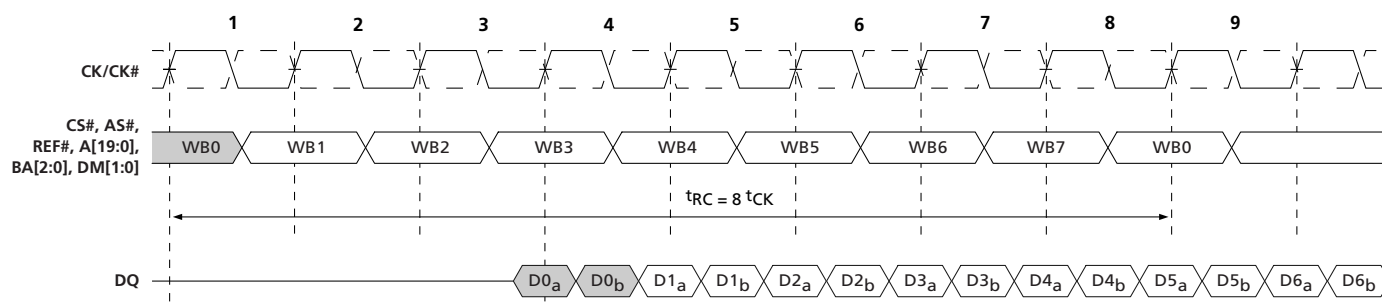


- NOTE:**
1. Starting with all banks closed, 4 bank cyclic access.
 2. 4 bit prefetch, BL = 4.
 3. Read latency (RL) programmable.
 4. CS# = 1 deactivates command inputs. DQS not affected.



WRITE TIMING

(BL = 2, RL = 6)

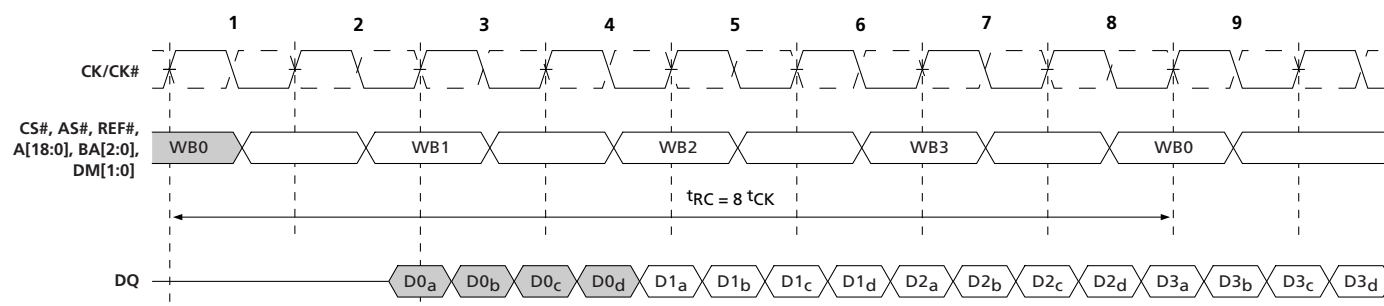


- NOTE:**
1. DQS and DQS# are not relevant during WRITE cycles.
 2. Starting with all banks closed, 8 banks cyclic access.
 3. Write latency $WL = RL - BL/2 - 2 = 3$.



WRITE TIMING

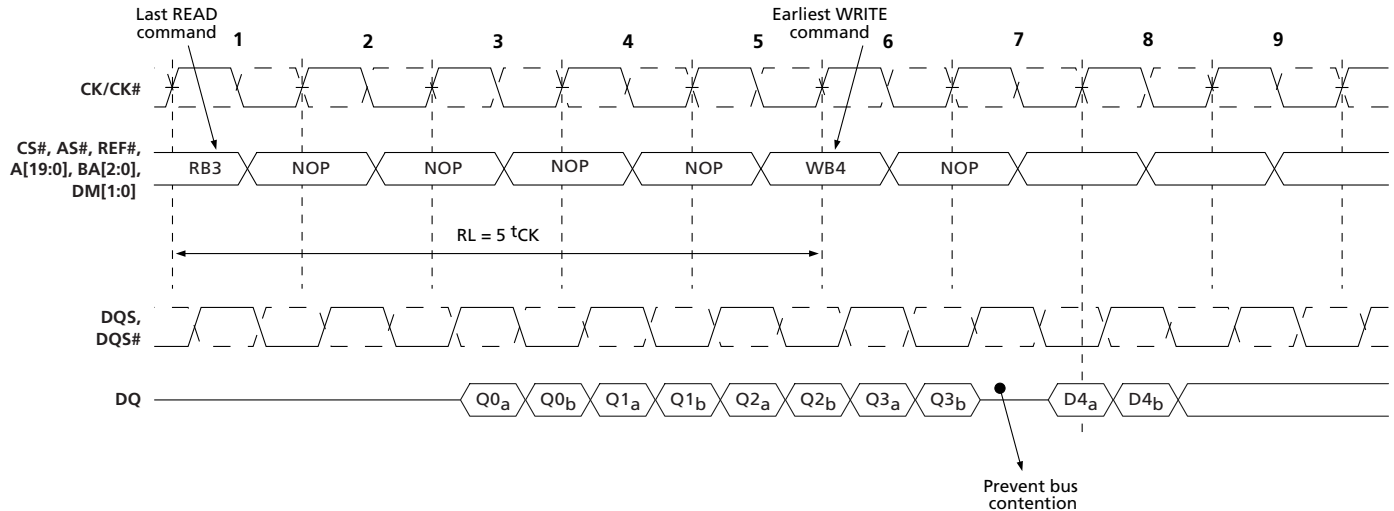
(BL = 4, RL = 6)



- NOTE:**
1. DQS and DQS# are not relevant during WRITE cycles.
 2. Starting with all banks closed, 4 banks cyclic access.
 3. Write latency $WL = RL - BL/2 - 2 = 2$.

READ TO WRITE TIMING

(BL = 2, WL = 2)

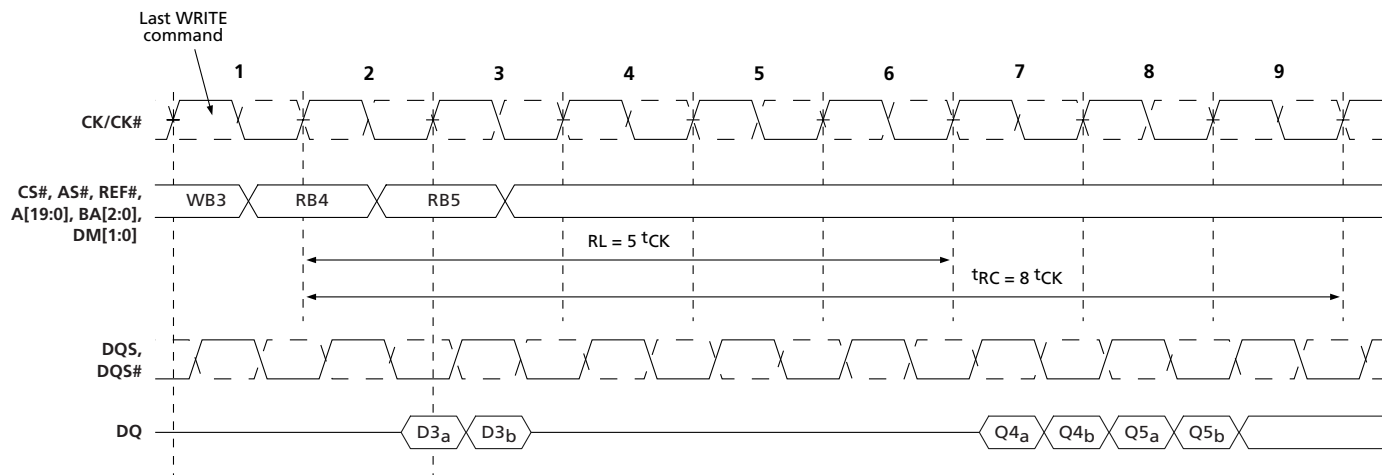


NOTE: 1. In order to avoid bus contention from a READ to a WRITE the proper number of clock cycles has to be inserted.



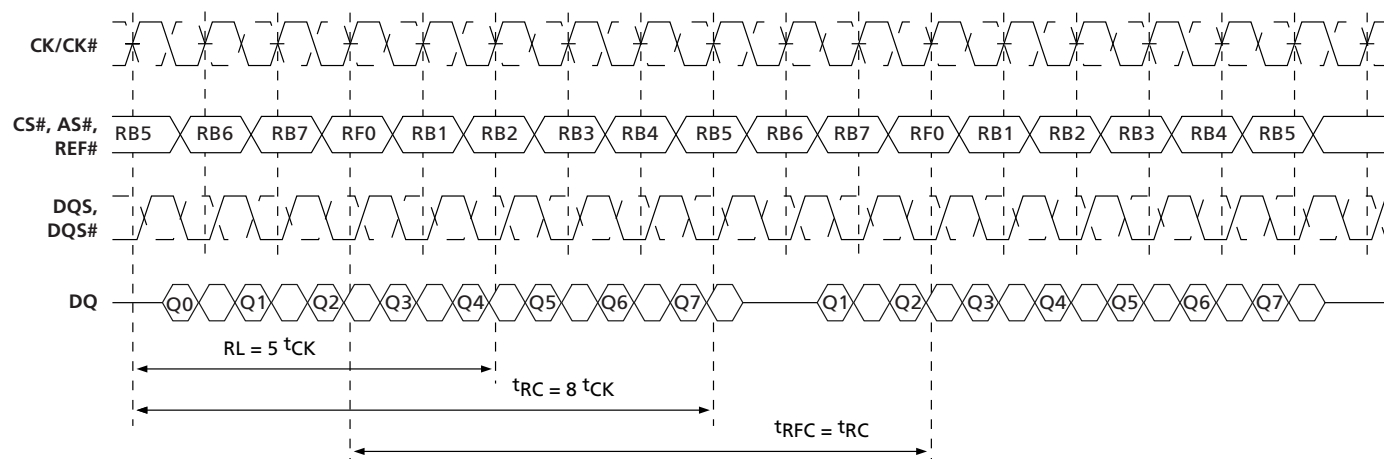
WRITE TO READ TIMING

(BL = 2, WL = 2)





REFRESH TIMING



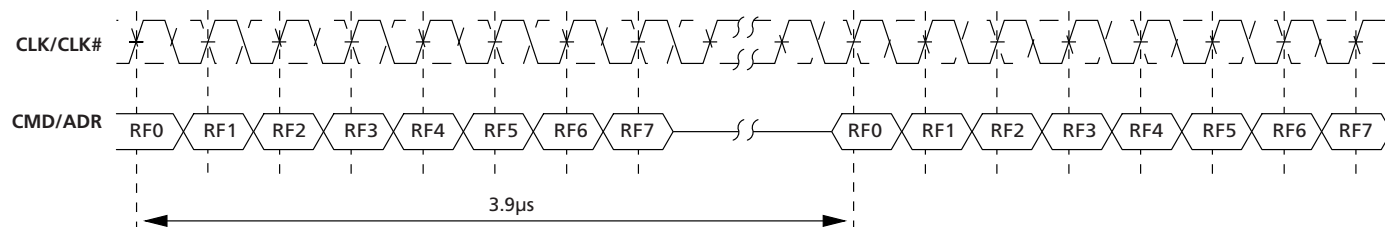
NOTE:

1. Bank scheduled refresh.
2. Refresh cycle to be issued on closed bank.
3. Bank address from controller, row address generated internally.



EXAMPLE OF REFRESH IMPLEMENTATION

(Cyclic Bank Burst Refresh)

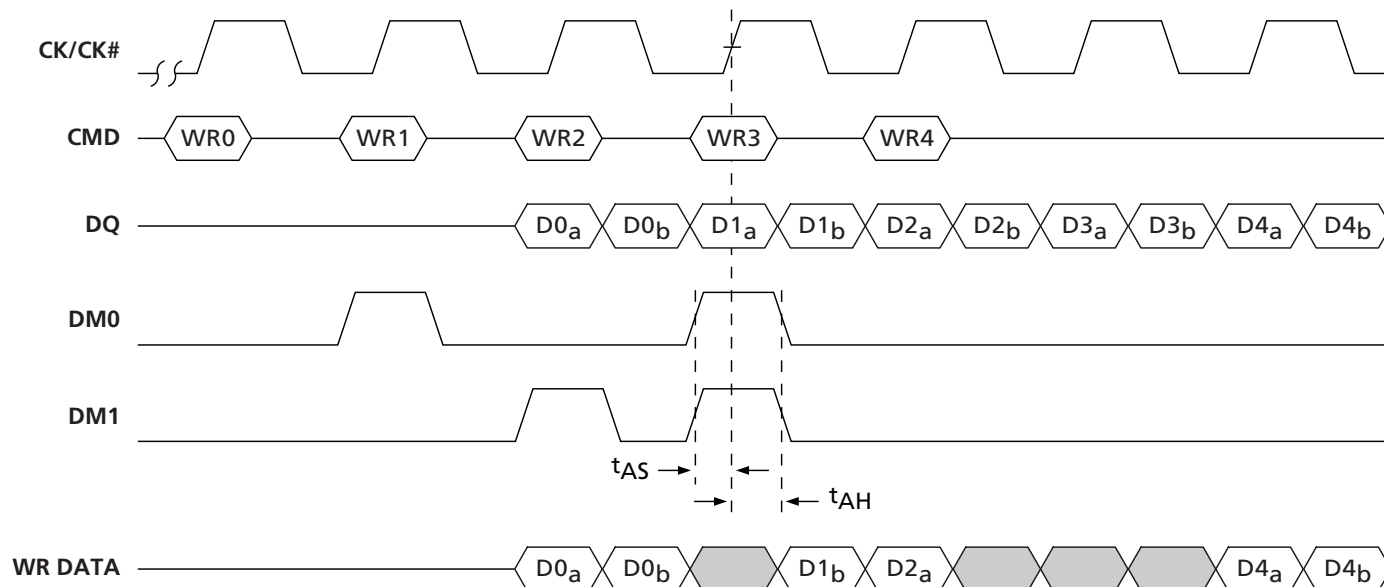


- NOTE:**
1. Cyclic Burst refresh on all Banks.
 2. Each Refresh command on the next Bank is asserted on the next clock rising edge.
 3. Cycle for a burst refresh: $32\text{ms}/8192 = 3.9\mu\text{s}$.



WRITE DATA MASK TIMING

(BL = 2, WL = 2)

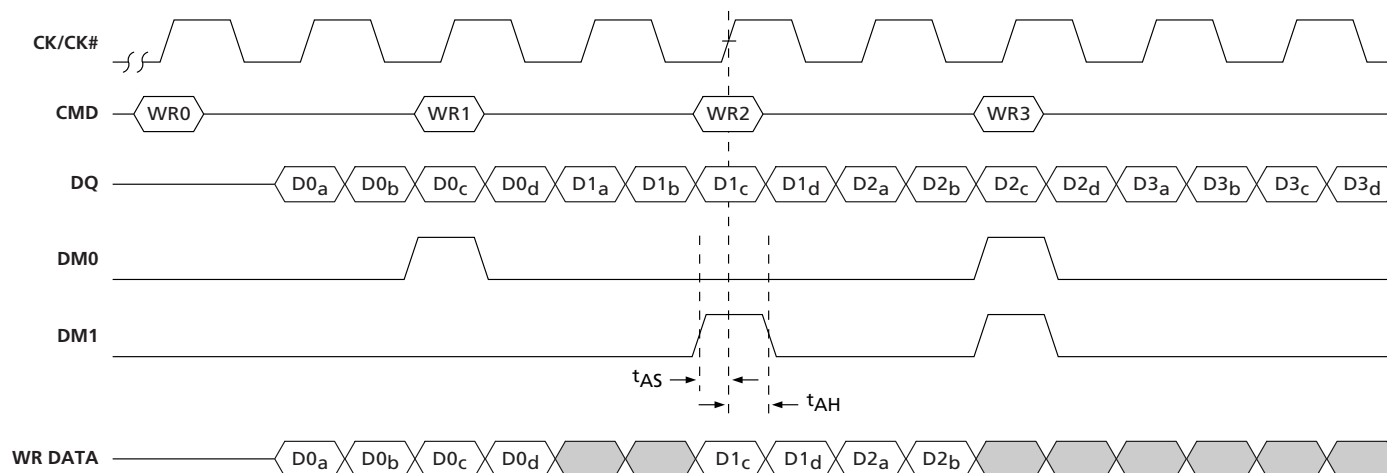


NOTE: 1. Shaded WR Data is not written into the memory.

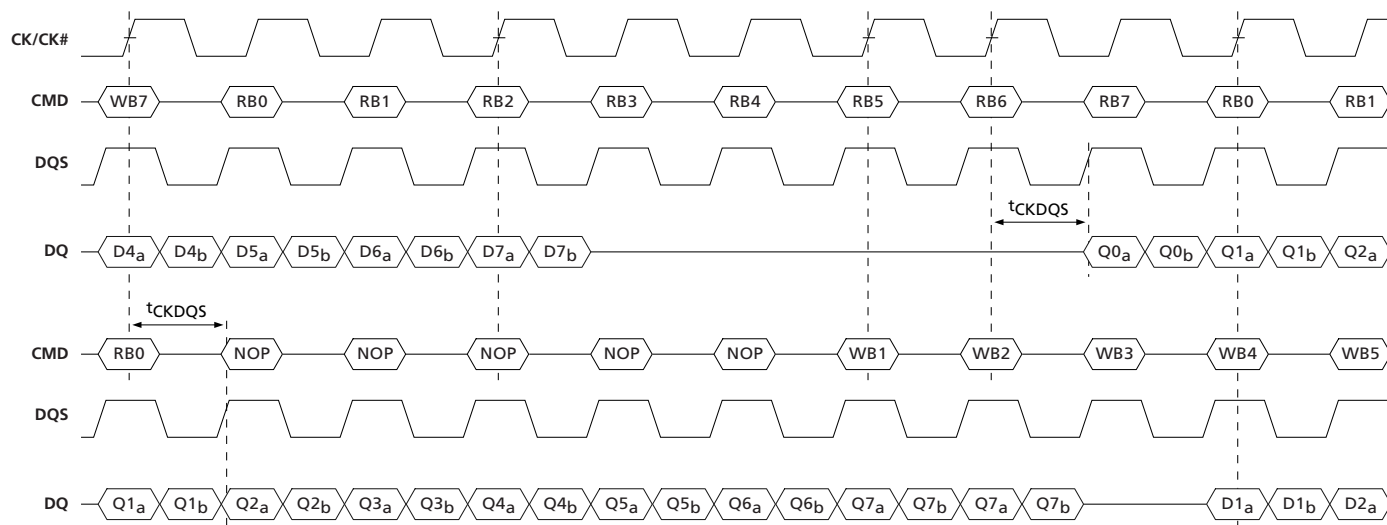


WRITE DATA MASK TIMING

(BL = 4, WL = 1)

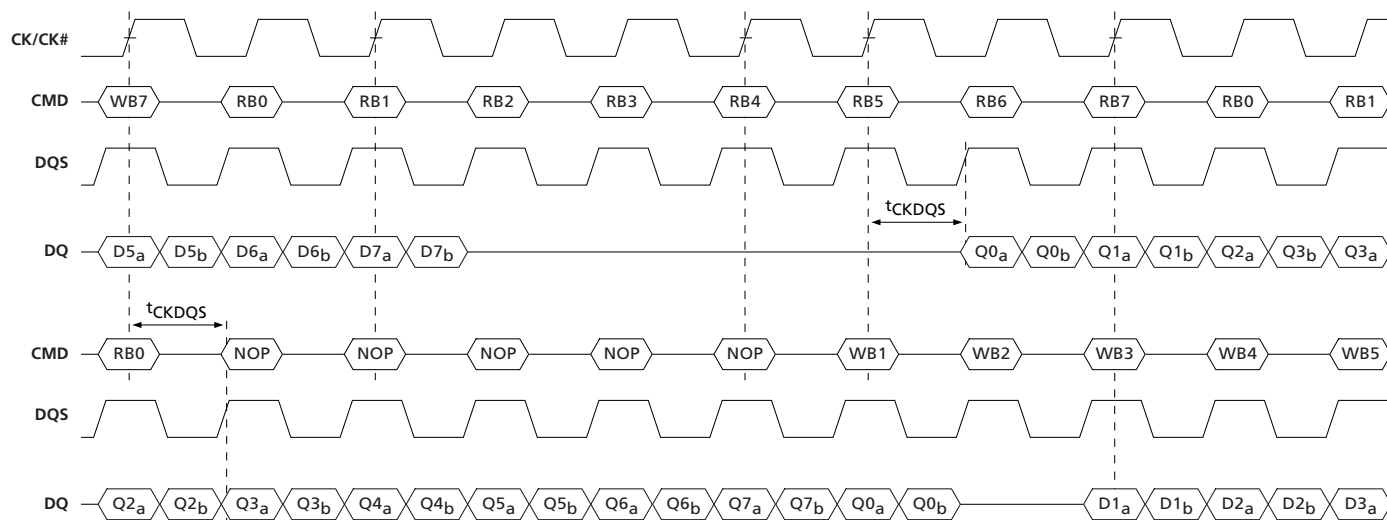


NOTE: 1. Shaded WR Data is not written into the memory.


WRITE/READ AND READ/WRITE TIMING, CYCLIC BANK ACCESS
(RL = 6, BL = 2, WL = 3)


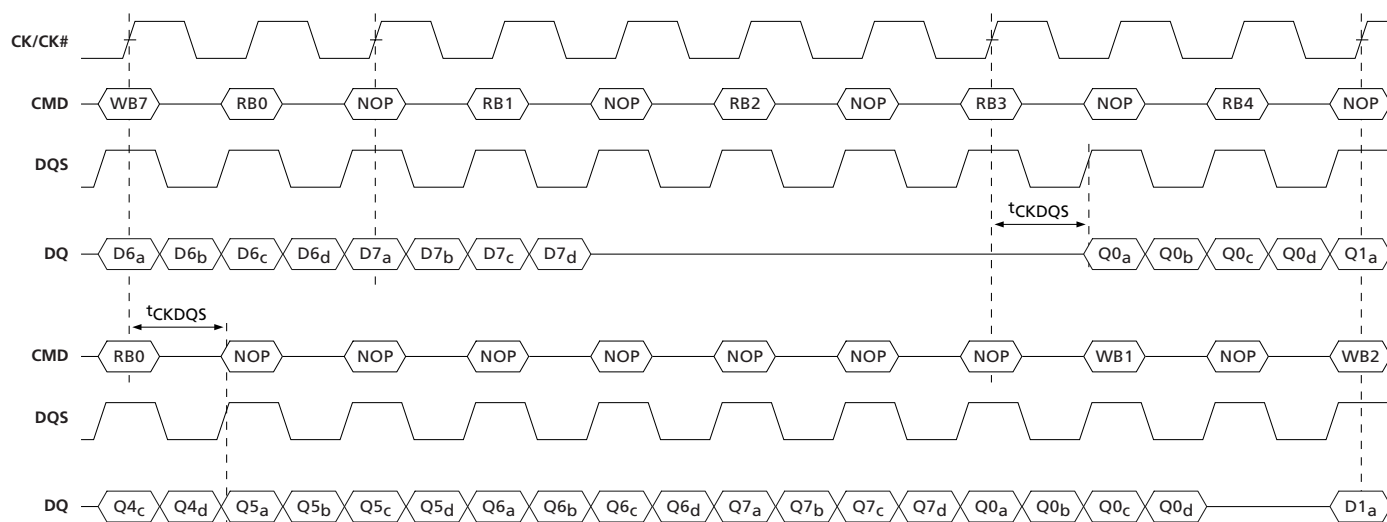

WRITE/READ AND READ/WRITE TIMING, CYCLIC BANK ACCESS

(RL = 5, BL = 2, WL = 2)



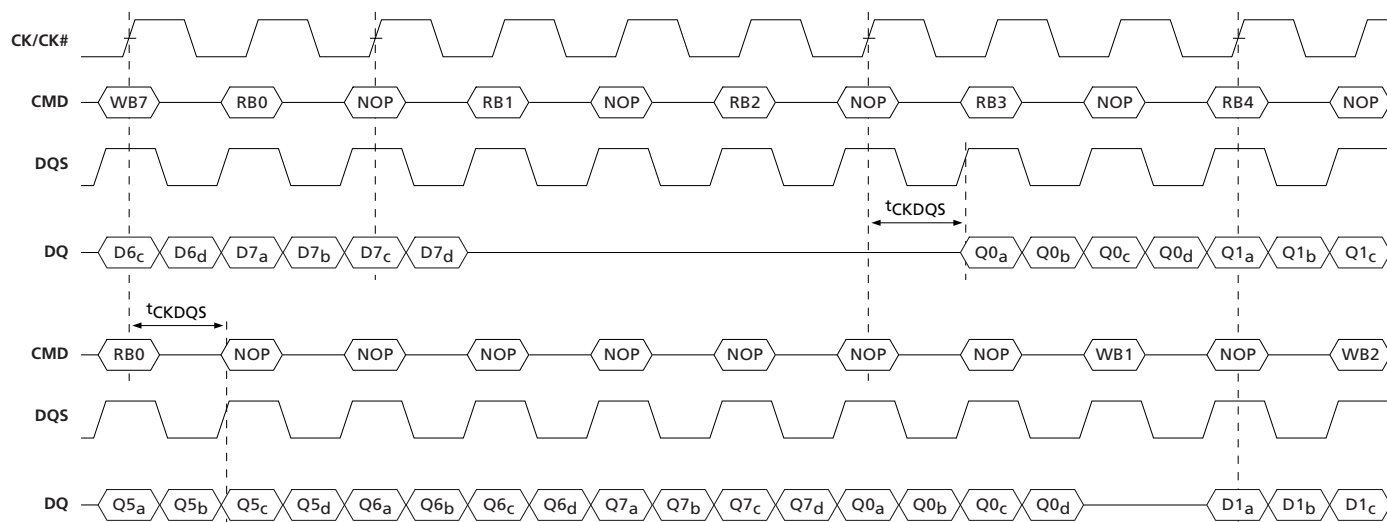


WRITE/READ AND READ/WRITE TIMING, CYCLIC BANK ACCESS **(RL = 6, BL = 4, WL = 2)**



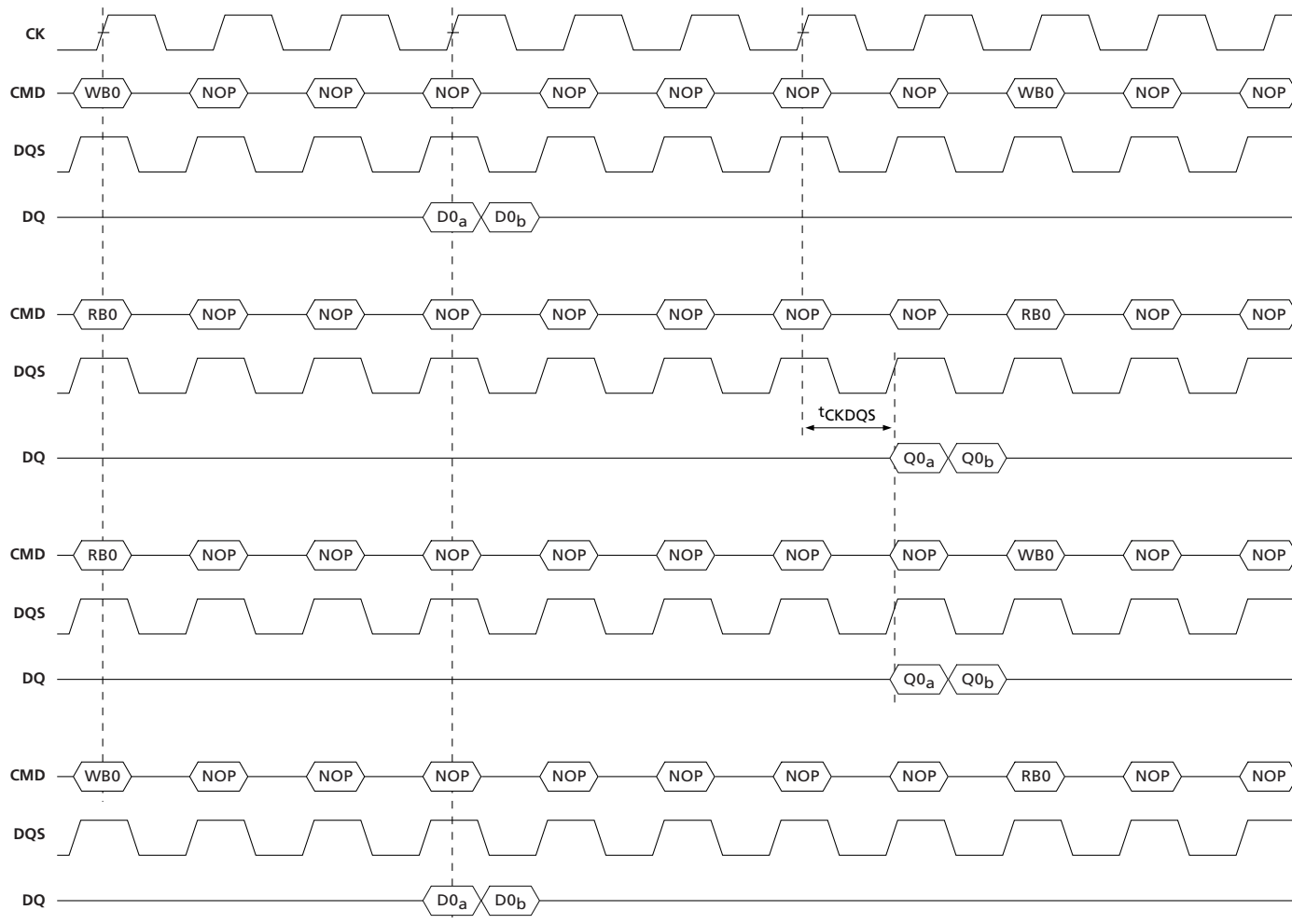


WRITE/READ AND READ/WRITE TIMING, CYCLIC BANK ACCESS **(RL = 5, BL = 4, WL = 1)**

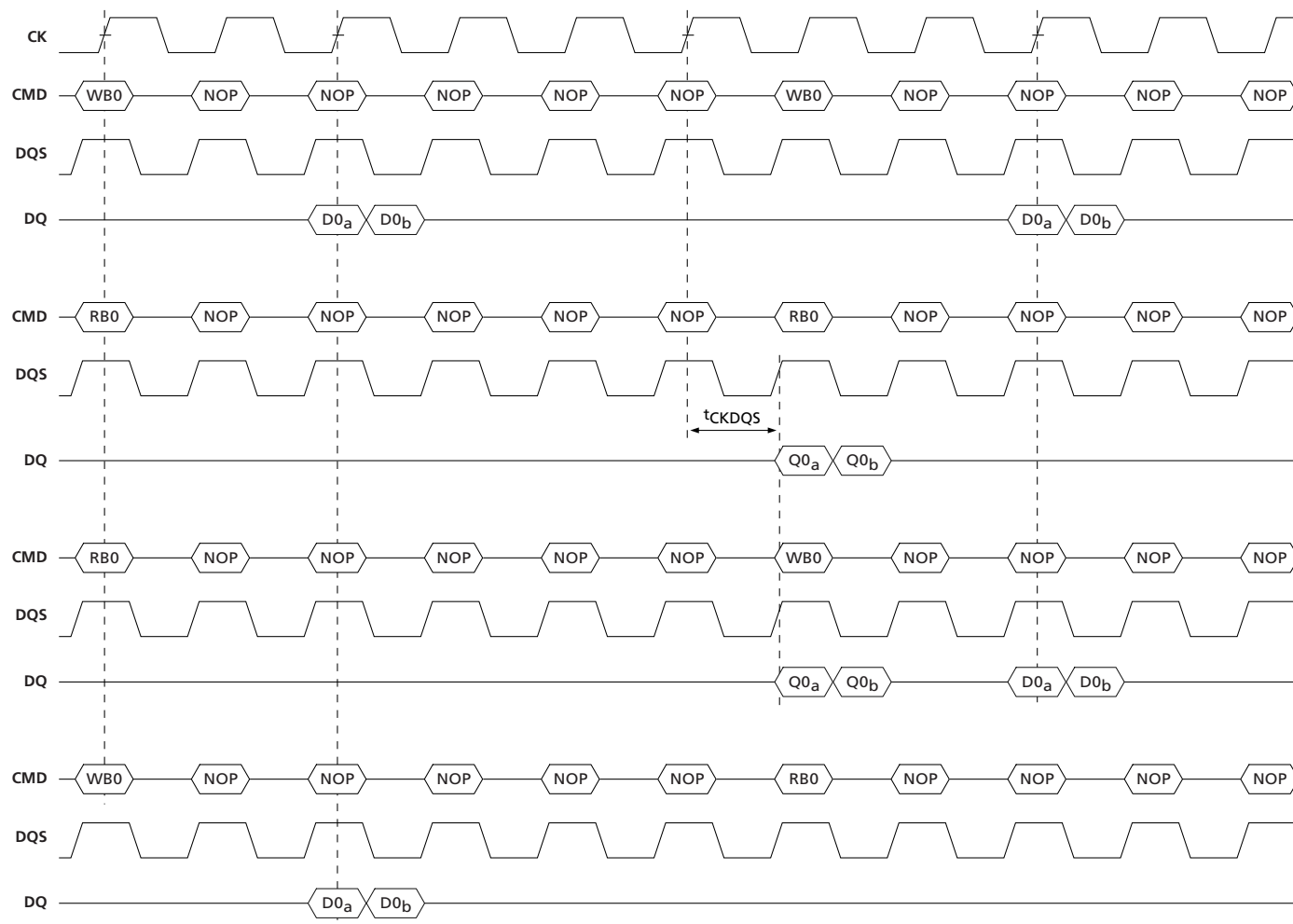




RANDOM ACCESS, SINGLE BANK **(RL = 6, BL = 2, WL = 3)**

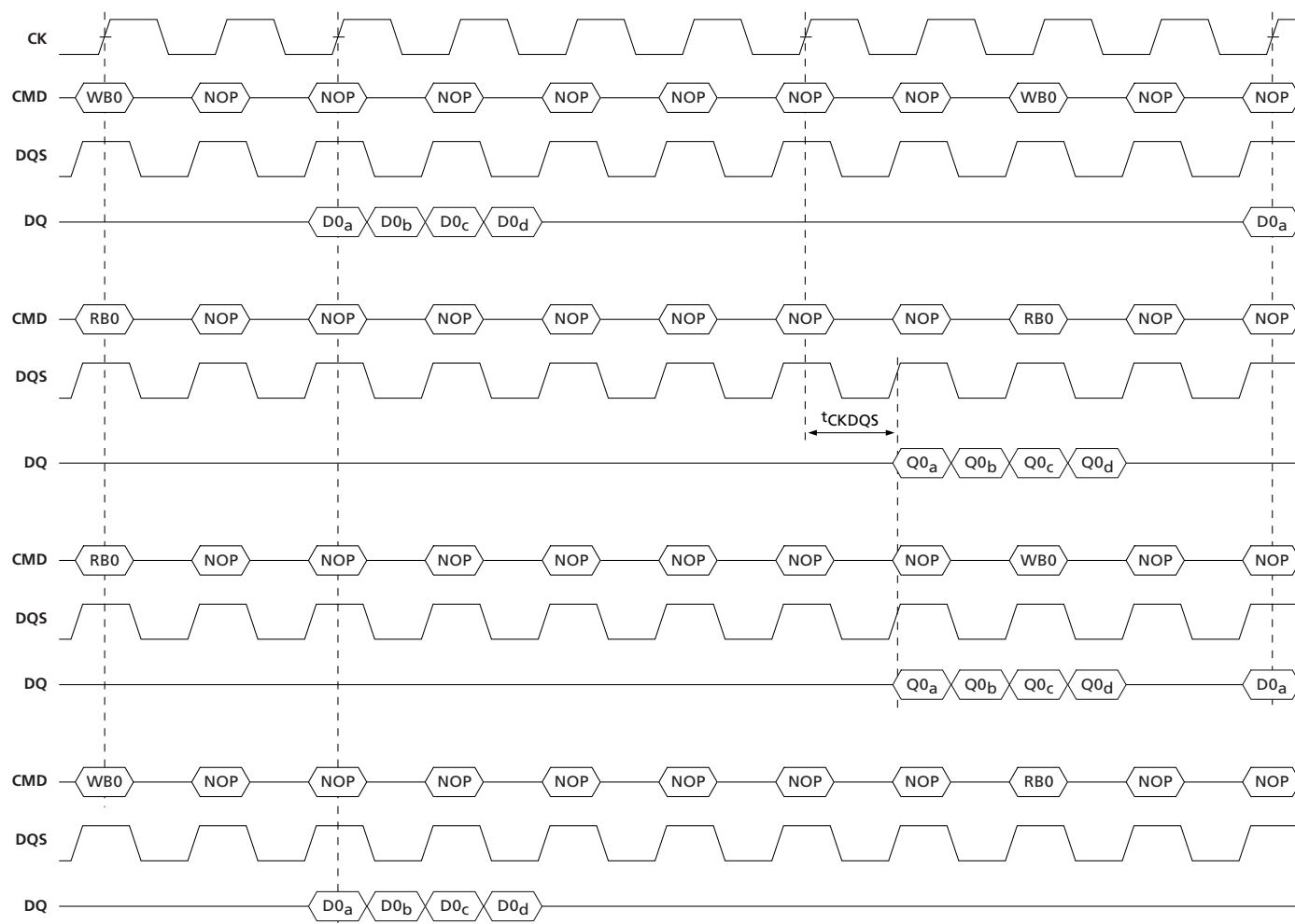



RANDOM ACCESS, SINGLE BANK

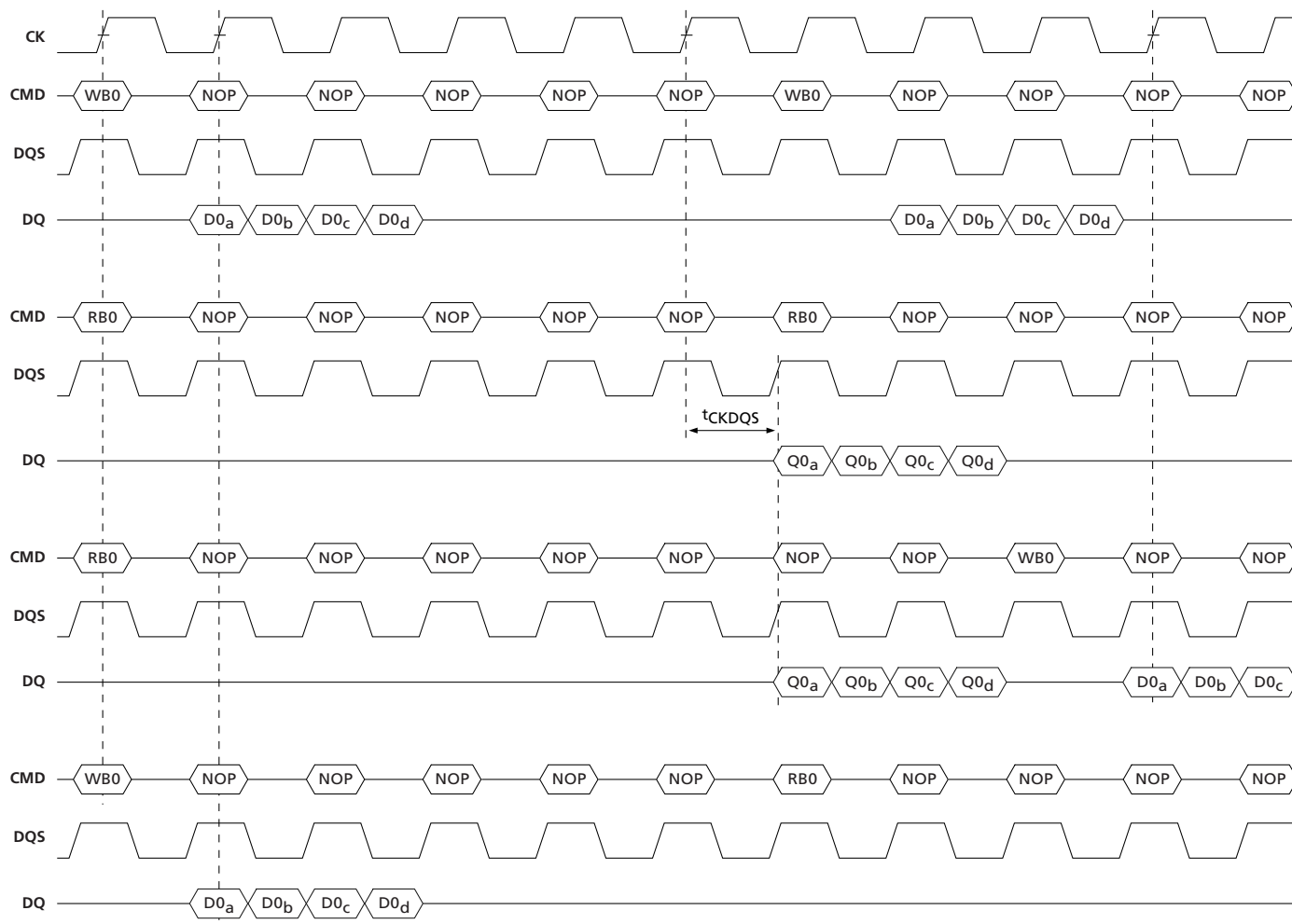
 (RL = 5, BL = 2, WL = 2, $t_{RC} = 6$)


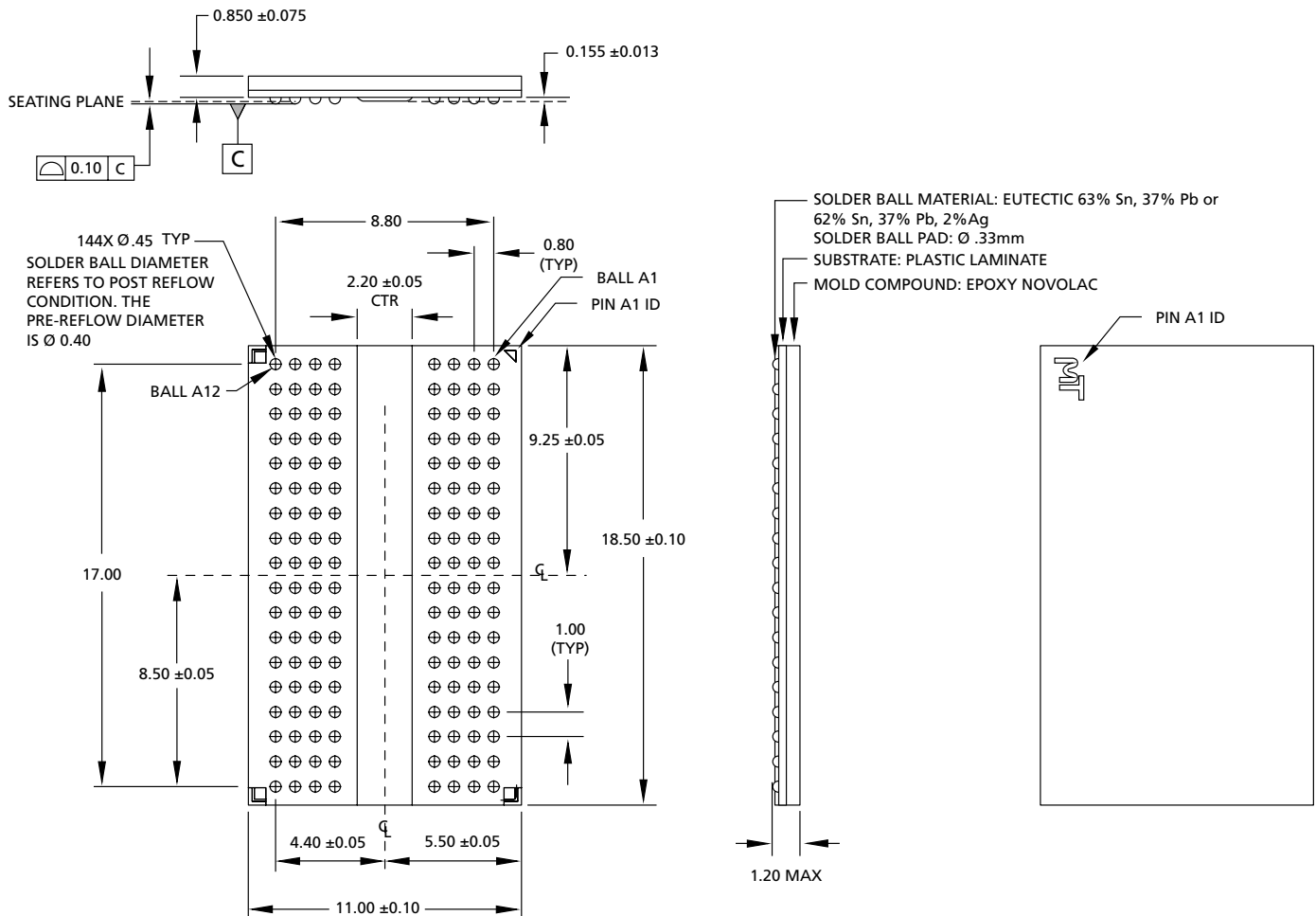


RANDOM ACCESS, SINGLE BANK **(RL = 6, BL = 4, WL = 2)**



RANDOM ACCESS, SINGLE BANK

 (RL = 5, BL = 4, WL = 1, $t_{RC} = 6$)


144-BALL T-FBGA


NOTE: 1. All dimensions in millimeters.

DATA SHEET DESIGNATION

Advance: This data sheet contains initial descriptions of products still under development.



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REVISION HISTORY

Rev. 3, Advance	6/02
• Removed confidential mark	
Rev. 2, Advance	2/02
• ?	
• ?	
Original document, Advance	12/01



Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



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