

EVALUATION KIT
AVAILABLE

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

General Description

The MAX8597/MAX8598/MAX8599 voltage-mode PWM step-down controllers are designed to operate from a 4.5V to 28V input supply and generate output voltages down to 0.6V. A proprietary switching algorithm stretches the duty cycle to >99.5% for low-dropout design. Unlike conventional step-down regulators using a p-channel high-side MOSFET to achieve high duty cycle, the MAX8597/MAX8598/MAX8599 drive n-channel MOSFETs resulting in high efficiency and high-current-capability designs.

The MAX8597 is available in a 20-pin thin QFN package and is designed for applications that use an analog signal to control the output voltage with an adjustable offset, such as DC fan-speed control. This is achieved with an internal uncommitted operational amplifier. The MAX8597 is also targeted for tracking output-voltage applications for chipsets, ASIC and DSP cores, and I/O supplies. The MAX8598/MAX8599 are available in a 16-pin thin QFN package and do not have the uncommitted operational amplifier, reference input, and reference output, but offer an open-drain, power-OK output.

The MAX8597/MAX8598/MAX8599 allow startup with prebias voltage on the output for applications where a backup supply or a tracking device may charge the output capacitor before the MAX8597/MAX8598/MAX8599 are enabled. In addition, the MAX8599 features output overvoltage protection.

These controllers also feature lossless high-side peak inductor current sensing, adjustable current limit, and hiccup-mode short-circuit protection. Switching frequency is set with an external resistor from 200kHz to 1.4MHz. This wide frequency range combined with a wide-bandwidth error amplifier enables the loop compensation scheme to give the user ample flexibility to optimize for cost, size, and efficiency.

Applications

Nonisolated Power Modules

Variable-Speed DC Fan Power Supplies
(MAX8597)

Tracking Power Supplies (MAX8597)

Chipset Power Supplies

Features

- ◆ Low Dropout with >99.5% Duty Cycle
- ◆ Lossless High-Side Current Limit
- ◆ Wide 4.5V to 28V Input Range
- ◆ Dynamic Output Voltage Adjustment with Adjustable Offset (MAX8597)
- ◆ Remote Voltage Sensing for Both Positive and Negative Rails (MAX8597)
- ◆ Tracking Output Through REFIN (MAX8597)
- ◆ Adjustable Switching Frequency from 200kHz to 1.4MHz
- ◆ Adjustable Soft-Start
- ◆ Prebias Startup
- ◆ Enable and Power-OK (MAX8598/MAX8599) for Flexible Sequencing
- ◆ 25MHz Error Amplifier
- ◆ Adjustable Hiccup Current Limit for Output Short-Circuit Protection
- ◆ Output Overvoltage Protection (MAX8599)
- ◆ Small, Low-Profile Thin QFN Package

Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE |
|-------------|----------------|------------------------------------|
| MAX8597ETP | -40°C to +85°C | 20 Thin QFN 4mm x 4mm (T2044-3) |
| MAX8597ETP+ | -40°C to +85°C | 20 Thin QFN 4mm x 4mm (T2044-3) |
| MAX8598ETE | -40°C to +85°C | 16 Thin QFN 4mm x 4mm (T1644-4) |
| MAX8598ETE+ | -40°C to +85°C | 16 Thin QFN 4mm x 4mm (T1644-4) |
| MAX8599ETE | -40°C to +85°C | 16 Thin QFN 4mm x 4mm (T1644-4) |
| MAX8599ETE+ | -40°C to +85°C | 16 Thin QFN 4mm x 4mm (T1644-4) |

+Denotes lead-free package.

Pin Configurations appear at end of data sheet.

MAX8597/MAX8598/MAX8599



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For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

ABSOLUTE MAXIMUM RATINGS

| | |
|---------------------------------------|--|
| V+, ILIM to GND | -0.3V to +30V |
| AVL, VL to GND | -0.3V to +6V |
| PGND to GND | -0.3V to +0.3V |
| FB, EN, POK, AIN-, AIN+, REFIN to GND | -0.3V to +6V |
| AOUT, REFOUT, FREQ, SS, COMP to GND | -0.3V to (V _{AVL} + 0.3V) |
| BST to GND | -0.3V to +36V |
| DH to LX | -0.3V to (V _{BST} + 0.3V) |
| LX to GND | -2V (-2.5V for less than 50ns) to +30V |
| LX to BST | -6V to +0.3V |

| | |
|--|-----------------------------------|
| DL to PGND | -0.3V to (V _{VL} + 0.3V) |
| Continuous Power Dissipation | |
| 16- or 20-Pin Thin QFN | |
| Up to +70°C (derate 16.9mW/°C above +70°C) | 1349mW |
| Operating Temperature Range | -40°C to +85°C |
| Junction Temperature | +150°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (soldering, 10s) | +300°C |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(V_{V+} = V_{VL} = V_{AVL} = V_{EN} = V_{REFIN} = 5V, V_{BST} = 6V, V_{LX} = 1V, C_{VL} = 4.7μF, C_{REFOUT} = 1μF, V_{AIN-} = V_{AOUT}, V_{AIN+} = 2.5V, V_{ILIM} = V_{LX} - 0.2V, V_{FB} = 0.65V, GND = PGND = 0V, C_{SS} = 0.01μF, R_{FREQ} = 20kΩ, **T_A = 0°C to +85°C**, typical values are at T_A = +25°C, unless otherwise noted.)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|------|------|------|-------|
| GENERAL | | | | | |
| V+ Operating Range | | 5.5 | 28.0 | | V |
| V+/VL Operating Range | V+ = VL | 4.5 | 5.5 | | V |
| V+ Operating Supply Current | V _{V+} = 12V, VL unloaded, no MOSFETs connected, V _{FB} = 0V | 3.4 | 5.0 | | mA |
| V+ Standby Supply Current | V _{V+} = 12V, VL unloaded, V _{FB} = 0V | 2.0 | | | mA |
| VL REGULATOR | | | | | |
| Output Voltage | 5.5V < V _{V+} < 28V, 1mA < I _{LOAD} < 35mA | 4.7 | 5.0 | 5.3 | V |
| VL Undervoltage-Lockout Trip Level | Rising edge, typical hysteresis = 460mV | 4.05 | 4.2 | 4.35 | V |
| Thermal Shutdown | Rising temperature, typical hysteresis = 10°C | | +160 | | °C |
| REFERENCE (MAX8597 only) | | | | | |
| REFOUT Output Voltage | I _{REFOUT} = 150μA, V _{V+} = V _{VL} = 4.5V or 5.5V | 2.49 | 2.50 | 2.51 | V |
| REFOUT Load Regulation | I _{REFOUT} = 10μA to 1mA | | | 10 | mV |
| REFOUT Internal Discharge Switch On-Resistance | During VL UVLO | | 15 | | Ω |
| CURRENT-LIMIT COMPARATOR (all current limits are tested at V_{V+} = V_{VL} = 4.5V and 5.5V) | | | | | |
| ILIM Sink Current | 1.8V < V _{LX} < 28V, V _{BST} = V _{LX} + 5V | 180 | 200 | 220 | μA |
| Comparator Input Offset Voltage Error | V _{LX} = 28V, V _{BST} = V _{LX} + 5V | -10 | | +10 | mV |
| SOFT-START | | | | | |
| Soft-Start Source Current | V _{SS} = 100mV | 3 | 5 | 7 | μA |
| Soft-Start Sink Current | V _{SS} = (0.6V or V _{REFIN}) | 3 | 5 | 7 | μA |
| FREQUENCY | | | | | |
| Frequency | R _{FREQ} = 100kΩ | 150 | 200 | 240 | kHz |
| | R _{FREQ} = 20.0kΩ | 800 | 1000 | 1200 | |
| | R _{FREQ} = 14.3kΩ | 1100 | 1400 | 1700 | |

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

ELECTRICAL CHARACTERISTICS (continued)

($V_{V+} = V_{VL} = V_{AVL} = V_{EN} = V_{REFIN} = 5V$, $V_{BST} = 6V$, $V_{LX} = 1V$, $C_{VL} = 4.7\mu F$, $C_{REFOUT} = 1\mu F$, $V_{AIN-} = V_{AOUT}$, $V_{AIN+} = 2.5V$, $V_{ILIM} = V_{LX} - 0.2V$, $V_{FB} = 0.65V$, $GND = PGND = 0V$, $C_{SS} = 0.01\mu F$, $R_{FREQ} = 20k\Omega$, $T_A = 0^\circ C$ to $+85^\circ C$, typical values are at $T_A = +25^\circ C$, unless otherwise noted.)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|------------------|-----------------|-------|------------|
| DH Minimum Off-Time | | 180 | 200 | 220 | ns |
| DH Minimum On-Time | | | 115 | 140 | ns |
| FB ERROR AMPLIFIER | | | | | |
| FB Input Bias Current | | | 100 | | nA |
| FB Input Voltage Set Point | Over load and line | 0.594 | 0.600 | 0.606 | V |
| FB Offset Error | $V_{REFIN} = 1.25V$ and $2.5V$, measured with respect to $REFIN$ | +10 | | -10 | mV |
| Error-Amp Open-Loop Voltage Gain | $V_{COMP} = 1.2V$ to $2.4V$ | 72 | 90 | | dB |
| Slew Rate | $C_{LOAD} = 80pF$ | | 18 | | V/ μ s |
| UNCOMMITTED OPERATIONAL AMPLIFIER (MAX8597 only) | | | | | |
| Open-Loop Voltage Gain (A_{VOL}) | $R_{LOAD} = 100k\Omega$ | 90 | | | dB |
| | $R_{LOAD} = 10k\Omega$ | 70 | | | |
| Output-Voltage Swing High | $V_{AIN+} = 2.5V$, $V_{AIN-} = (V_{AIN+} - 100mV)$, $I_{SOURCE} = 100\mu A$ | $V_{AVL} - 20mV$ | | | V |
| Output-Voltage Swing Low | $V_{AIN+} = 2.5V$, $V_{AIN-} = (V_{AIN+} + 100mV)$, $I_{SINK} = 100\mu A$ | | 20 | | mV |
| Unity-Gain BW | | | 1.5 | | MHz |
| Phase Margin | $C_{LOAD} = 10pF$, $R_{LOAD} = 10k\Omega$ to $100k\Omega$ | +80 | | | Degrees |
| | $C_{LOAD} = 100pF$, $R_{LOAD} = 10k\Omega$ to $100k\Omega$ | +40 | | | |
| Slew Rate | $C_{LOAD} = 100pF$ | | 3.5 | | V/ μ s |
| Input Offset Voltage | $V_{CM} = 1.25V$ and $2.5V$ | -3 | +3 | | mV |
| Input Leakage Current | | -10 | +10 | | nA |
| Input Common-Mode Range (CMVR) | | +0.50 | $V_{AVL} - 2.0$ | | V |
| Common-Mode Rejection Ratio (CMRR) | | | 75 | | dB |
| DRIVERS | | | | | |
| DH, DL Break-Before-Make Time | $C_{LOAD} = 2000pF$ | 20 | | | ns |
| DH On-Resistance in Low State | $V_{BST} - V_{LX} = 5V$ | 1.0 | 2.5 | | Ω |
| DH On-Resistance in High State | $V_{BST} - V_{LX} = 5V$ | 1.5 | 3.3 | | Ω |
| DL On-Resistance in Low State | $V_{VL} = V_{V+} = 5V$ | 0.45 | 1.0 | | Ω |
| DL On-Resistance in High State | $V_{VL} = V_{V+} = 5V$ | 1.3 | 2.5 | | Ω |
| BST Bias Current | $V_{BST} = 33V$, $V_{LX} = 28V$, $V_{EN} = 0V$ | 230 | 520 | | μA |
| LX Bias Current | $V_{BST} = 33V$, $V_{LX} = 28V$, $V_{EN} = 0V$ | -230 | -520 | | μA |
| BST/LX Leakage Current | $V_{BST} = V_{LX} = 28V$, $V_{EN} = 0V$ | | 50 | | μA |
| LOGIC INPUTS (EN) | | | | | |
| Input Low Level | $4.5V < V_{VL} = V_{V+} = V_{AVL} < 5.5V$ | 1.14 | 0.80 | | V |
| Input High Level | $4.5V < V_{VL} = V_{V+} = V_{AVL} < 5.5V$ | 2.40 | 1.73 | | V |
| Input Bias Current | $V_{VL} = V_{V+} = V_{AVL} = 5.5V$, $V_{EN} = 0$ to $5.5V$ | -1 | +1 | | μA |

MAX8597/MAX8598/MAX8599

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

ELECTRICAL CHARACTERISTICS (continued)

($V_{V+} = V_{VL} = V_{AVL} = V_{EN} = V_{REFIN} = 5V$, $V_{BST} = 6V$, $V_{LX} = 1V$, $C_{VL} = 4.7\mu F$, $C_{REFOUT} = 1\mu F$, $V_{AIN-} = V_{AOUT}$, $V_{AIN+} = 2.5V$, $V_{ILIM} = V_{LX} - 0.2V$, $V_{FB} = 0.65V$, $GND = PGND = 0V$, $C_{SS} = 0.01\mu F$, $R_{FREQ} = 20k\Omega$, $T_A = 0^\circ C$ to $+85^\circ C$, typical values are at $T_A = +25^\circ C$, unless otherwise noted.)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|-----------------|-----------------|------|--------------|
| REFIN INPUT (MAX8597 only) | | | | | |
| REFIN Input Voltage Range | | 0 | 2.75 | | V |
| REFIN Dual Mode™ Threshold | | $V_{AVL} - 1.0$ | $V_{AVL} - 0.5$ | | V |
| REFIN Input Bias Current | $V_{REFIN} = 1.25V$ or $2.5V$ | -250 | | +250 | nA |
| OV AND UV FAULT COMPARATORS | | | | | |
| Upper FB Fault Threshold (OV) | Rising edge, hysteresis = 15mV (MAX8599 only) | 115 | 117 | 120 | % |
| Lower FB Fault Threshold (UV) | Falling edge, hysteresis = 15mV | 67 | 70 | 73 | % |
| POWER-OK OUTPUT (POK) (MAX8598/MAX8599 only) | | | | | |
| POK Delay | For both FB rising and falling edges | | 8 | | Clock cycles |
| Lower FB POK Threshold | FB falling, hysteresis = 20mV | 85 | 88 | 90 | % |
| POK Output Low Level | $I_{SINK} = 2mA$ | | 0.4 | | V |
| POK Output High Leakage | $V_{POK} = 5.5V$ | | 5 | | µA |

ELECTRICAL CHARACTERISTICS

($V_{V+} = V_{VL} = V_{AVL} = V_{EN} = V_{REFIN} = 5V$, $V_{BST} = 6V$, $V_{LX} = 1V$, $C_{VL} = 4.7\mu F$, $C_{REFOUT} = 1\mu F$, $V_{AIN-} = V_{AOUT}$, $V_{AIN+} = 2.5V$, $V_{ILIM} = V_{LX} - 0.2V$, $V_{FB} = 0.65V$, $GND = PGND = 0V$, $C_{SS} = 0.01\mu F$, $R_{FREQ} = 20k\Omega$, $T_A = -40^\circ C$ to $+85^\circ C$, typical values are at $T_A = +25^\circ C$, unless otherwise noted.) (Note 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|--|--|------|------|-----|-------|
| GENERAL | | | | | |
| V_+ Operating Range | | 5.5 | 28.0 | | V |
| V_+/VL Operating Range | $V_+ = VL$ | 4.5 | 5.5 | | V |
| V_+ Operating Supply Current | $V_{V+} = 12V$, VL unloaded, no MOSFETs connected, $V_{FB} = 0V$ | | 5.0 | | mA |
| VL REGULATOR | | | | | |
| Output Voltage | $5.5V < V_{V+} < 28V$, $1mA < I_{LOAD} < 35mA$ | 4.7 | 5.3 | | V |
| VL Undervoltage-Lockout Trip Level | Rising edge, typical hysteresis = 460mV | 4.05 | 4.35 | | V |
| REFERENCE (MAX8597 only) | | | | | |
| REFOUT Output Voltage | $I_{REFOUT} = 150\mu A$, $V_{V+} = V_{VL} = 4.5V$ or $5.5V$ | 2.47 | 2.51 | | V |
| REFOUT Load Regulation | $I_{REFOUT} = 10\mu A$ to $1mA$ | | 10 | | mV |
| CURRENT-LIMIT COMPARATOR (all current limits are tested at $V_{V+} = V_{VL} = 4.5V$ and $5.5V$) | | | | | |
| ILIM Sink Current | $V_{ILIM} = V_{LX} - 0.2V$, $1.8V < V_{LX} < 28V$, $V_{BST} = V_{LX} + 5V$ | 180 | 220 | | µA |
| Comparator Input Offset Voltage Error | | -10 | +10 | | mV |
| SOFT-START | | | | | |
| Soft-Start Source Current | $V_{SS} = 100mV$ | 3 | 7 | | µA |
| Soft-Start Sink Current | $V_{SS} = (0.6V$ or $V_{REFIN})$ | 3 | 7 | | µA |

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Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

ELECTRICAL CHARACTERISTICS (continued)

($V_{V+} = V_{VL} = V_{AVL} = V_{EN} = V_{REFIN} = 5V$, $V_{BST} = 6V$, $V_{LX} = 1V$, $C_{VL} = 4.7\mu F$, $C_{REFOUT} = 1\mu F$, $V_{AIN-} = V_{AOUT}$, $V_{AIN+} = 2.5V$, $V_{ILIM} = V_{LX} - 0.2V$, $V_{FB} = 0.65V$, $GND = PGND = 0V$, $C_{SS} = 0.01\mu F$, $R_{FREQ} = 20k\Omega$, $T_A = -40^\circ C$ to $+85^\circ C$, typical values are at $T_A = +25^\circ C$, unless otherwise noted.) (Note 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|------------------|-----------------|-----|----------|
| FREQUENCY | | | | | |
| Frequency | $R_{FREQ} = 100k\Omega$ | 140 | 240 | | kHz |
| | $R_{FREQ} = 20.0k\Omega$ | 800 | 1200 | | |
| | $R_{FREQ} = 14.3k\Omega$ | 1100 | 1700 | | |
| DH Minimum Off-Time | | 180 | 230 | | ns |
| DH Minimum On-Time | | | 140 | | ns |
| FB ERROR AMPLIFIER | | | | | |
| FB Input Bias Current | | | 150 | | nA |
| FB Input Voltage Set Point | Over load and line | 0.591 | 0.606 | | V |
| FB Offset Error | $V_{REFIN} = 1.25V$ and $2.5V$, measured with respect to $REFIN$ | +20 | -20 | | mV |
| Error-Amp Open-Loop Voltage Gain | $V_{COMP} = 1.2V$ to $2.4V$ | 72 | | | dB |
| UNCOMMITTED OPERATIONAL AMPLIFIER (MAX8597 only) | | | | | |
| Output Voltage Swing High | $V_{AIN+} = 2.5V$, $V_{AIN-} = (V_{AIN+} - 100mV)$, $I_{SOURCE} = 100\mu A$ | $V_{AVL} - 20mV$ | | | V |
| Output Voltage Swing Low | $V_{AIN+} = 2.5V$, $V_{AIN-} = (V_{AIN+} + 100mV)$, $I_{SINK} = 100\mu A$ | 20 | | | mV |
| Input Offset Voltage | $V_{CM} = 1.25V$ and $2.5V$ | -3 | +3 | | mV |
| Input Common-Mode Range (CMVR) | | +0.50 | $V_{AVL} - 2.0$ | | V |
| DRIVERS | | | | | |
| DH On-Resistance in Low State | $V_{BST} - V_{LX} = 5V$ | | 2.5 | | Ω |
| DH On-Resistance in High State | $V_{BST} - V_{LX} = 5V$ | | 3.3 | | Ω |
| DL On-Resistance in Low State | $V_{VL} = V_{V+} = 5V$ | | 1.0 | | Ω |
| DL On-Resistance in High State | $V_{VL} = V_{V+} = 5V$ | | 3.5 | | Ω |
| BST Bias Current | $V_{BST} = 33V$, $V_{LX} = 28V$, $V_{EN} = 0V$ | | 520 | | μA |
| LX Bias Current | $V_{BST} = 33V$, $V_{LX} = 28V$, $V_{EN} = 0V$ | | -520 | | μA |
| BST/LX Leakage Current | $V_{BST} = V_{LX} = 28V$, $V_{EN} = 0V$ | | 50 | | μA |
| LOGIC INPUTS (EN) | | | | | |
| Input Low Level | $4.5V < V_{VL} = V_{V+} = V_{AVL} < 5.5V$ | | 0.8 | | V |
| Input High Level | $4.5V < V_{VL} = V_{V+} = V_{AVL} < 5.5V$ | 2.4 | | | V |
| Input Bias Current | $V_{VL} = V_{V+} = V_{AVL} = 5.5V$, $V_{EN} = 0$ to $5.5V$ | -1 | +1 | | μA |
| REFIN INPUT (MAX8597 only) | | | | | |
| REFIN Input Voltage Range | | 0 | 2.75 | | V |
| REFIN Dual-Mode Threshold | | $V_{AVL} - 1.0$ | $V_{AVL} - 0.5$ | | V |
| REFIN Input Bias Current | $V_{REFIN} = 1.25V$ or $2.5V$ | -250 | +250 | | nA |

MAX8597/MAX8598/MAX8599

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

ELECTRICAL CHARACTERISTICS (continued)

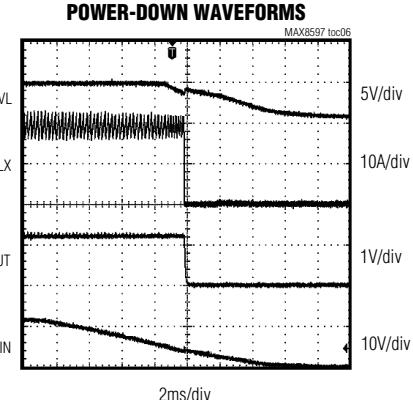
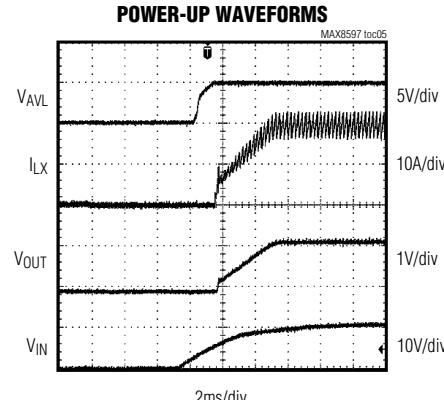
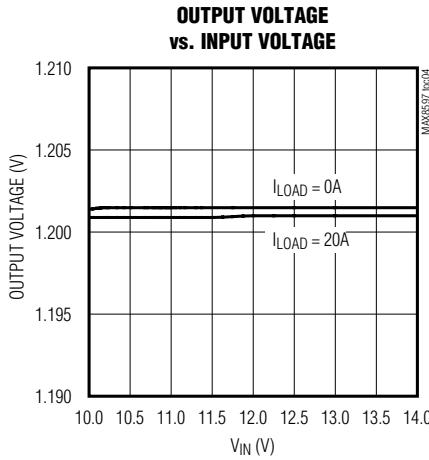
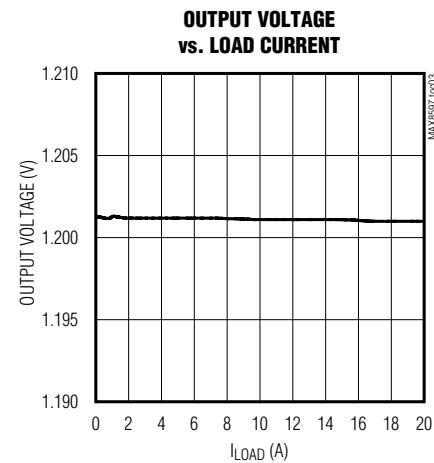
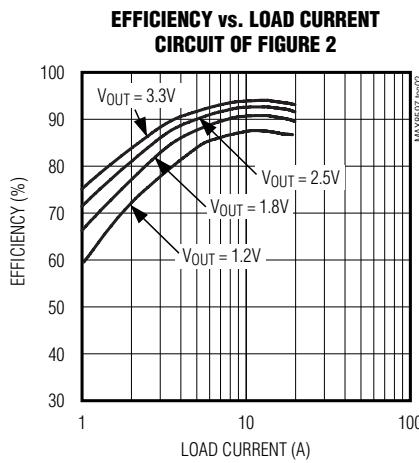
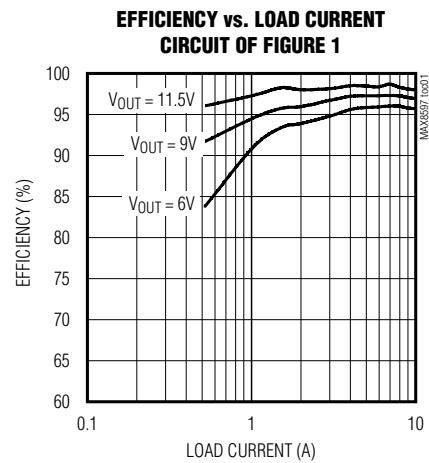
($V_{V+} = V_{VL} = V_{AVL} = V_{EN} = V_{REFIN} = 5V$, $V_{BST} = 6V$, $V_{LX} = 1V$, $C_{VL} = 4.7\mu F$, $C_{REFOUT} = 1\mu F$, $V_{AIN-} = V_{AOUT}$, $V_{AIN+} = 2.5V$, $V_{ILIM} = V_{LX} - 0.2V$, $V_{FB} = 0.65V$, $GND = PGND = 0V$, $C_{SS} = 0.01\mu F$, $R_{FREQ} = 20k\Omega$, $T_A = -40^\circ C$ to $+85^\circ C$, typical values are at $T_A = +25^\circ C$, unless otherwise noted.) (Note 1)

| PARAMETER | CONDITIONS | MIN | TYP | MAX | UNITS |
|---|---|-----|-----|-----|---------|
| OV AND UV FAULT COMPARATORS | | | | | |
| Upper FB Fault Threshold (OV) | Rising edge, hysteresis = 15mV (MAX8599 only) | 115 | 120 | | % |
| Lower FB Fault Threshold (UV) | Falling edge, hysteresis = 15mV | 67 | 73 | | % |
| POWER-OK OUTPUT (POK) (MAX8598/MAX8599 only) | | | | | |
| Lower FB POK Threshold | FB falling, hysteresis = 20mV | 85 | 90 | | % |
| POK Output Low Level | $I_{SINK} = 2mA$ | | 0.4 | | V |
| POK Output High Leakage | $V_{POK} = 5.5V$ | | 5 | | μA |

Note 1: Limits to $-40^\circ C$ are guaranteed by design and characterization.

Typical Operating Characteristics

(Circuit of Figure 4, $T_A = +25^\circ C$, 500kHz switching frequency, $V_{IN} = 12V$, unless otherwise noted.)

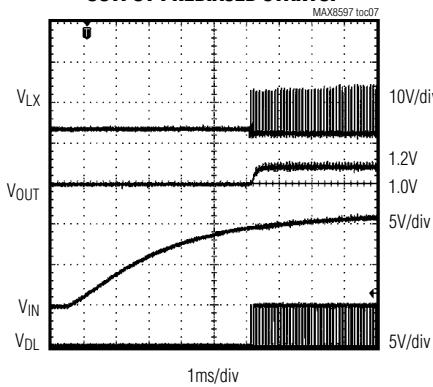


Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

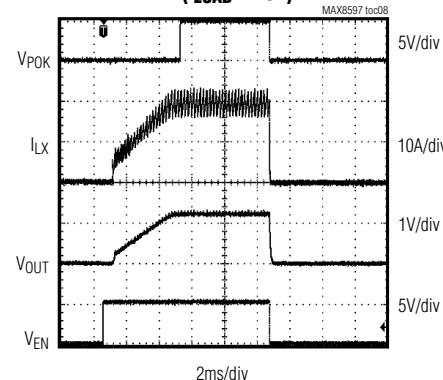
Typical Operating Characteristics (continued)

(Circuit of Figure 4, $T_A = +25^\circ\text{C}$, 500kHz switching frequency, $V_{IN} = 12\text{V}$, unless otherwise noted.)

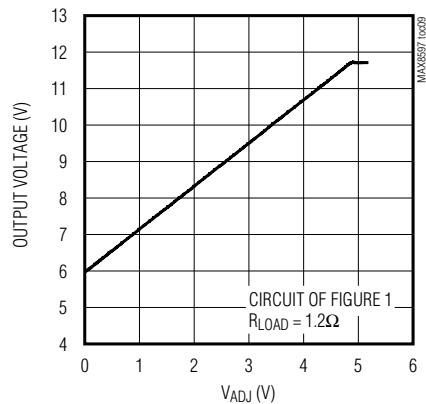
OUTPUT PREBIASED STARTUP



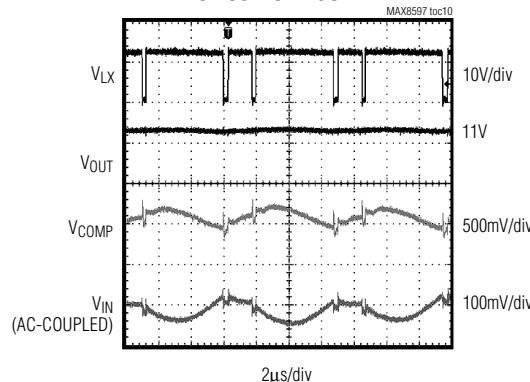
STARTUP/SHUTDOWN WITH
EN ($I_{LOAD} = 20\text{A}$)



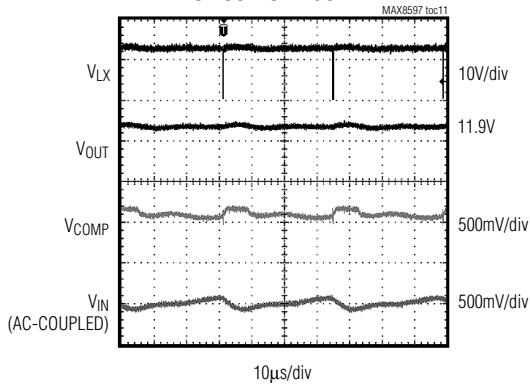
OUTPUT VOLTAGE vs. V_{ADJ}
($V_{IN} = 12\text{V}$)



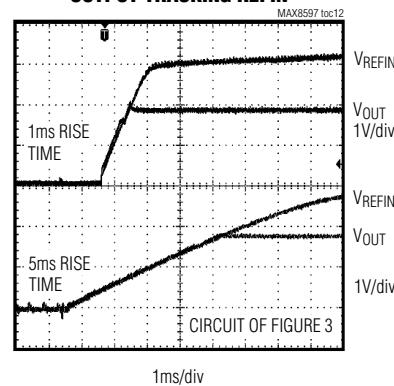
ENTERING DROPOUT WAVEFORMS
CIRCUIT OF FIGURE 1



HEAVY-DROPOUT WAVEFORMS
CIRCUIT OF FIGURE 1



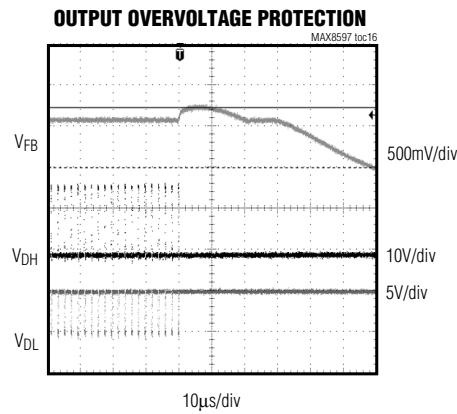
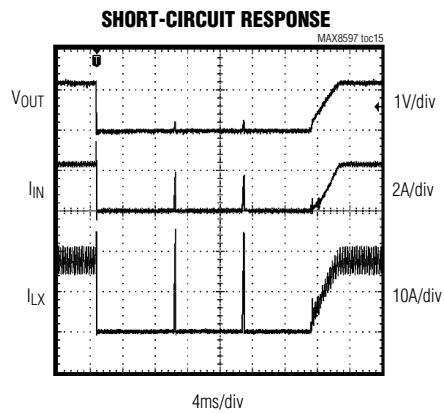
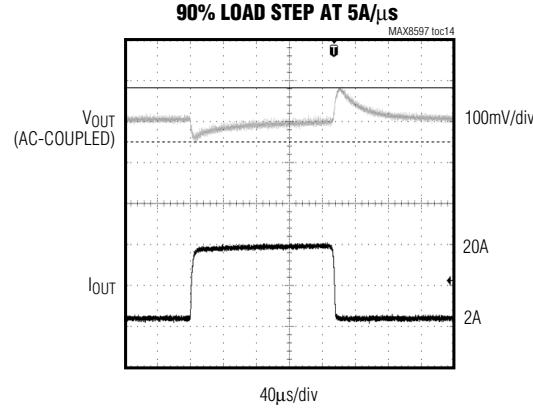
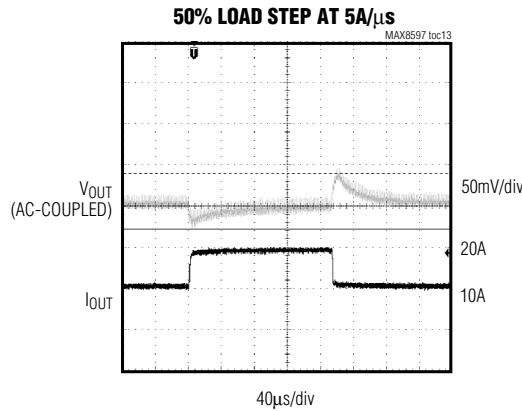
OUTPUT TRACKING REFIN



Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

Typical Operating Characteristics (continued)

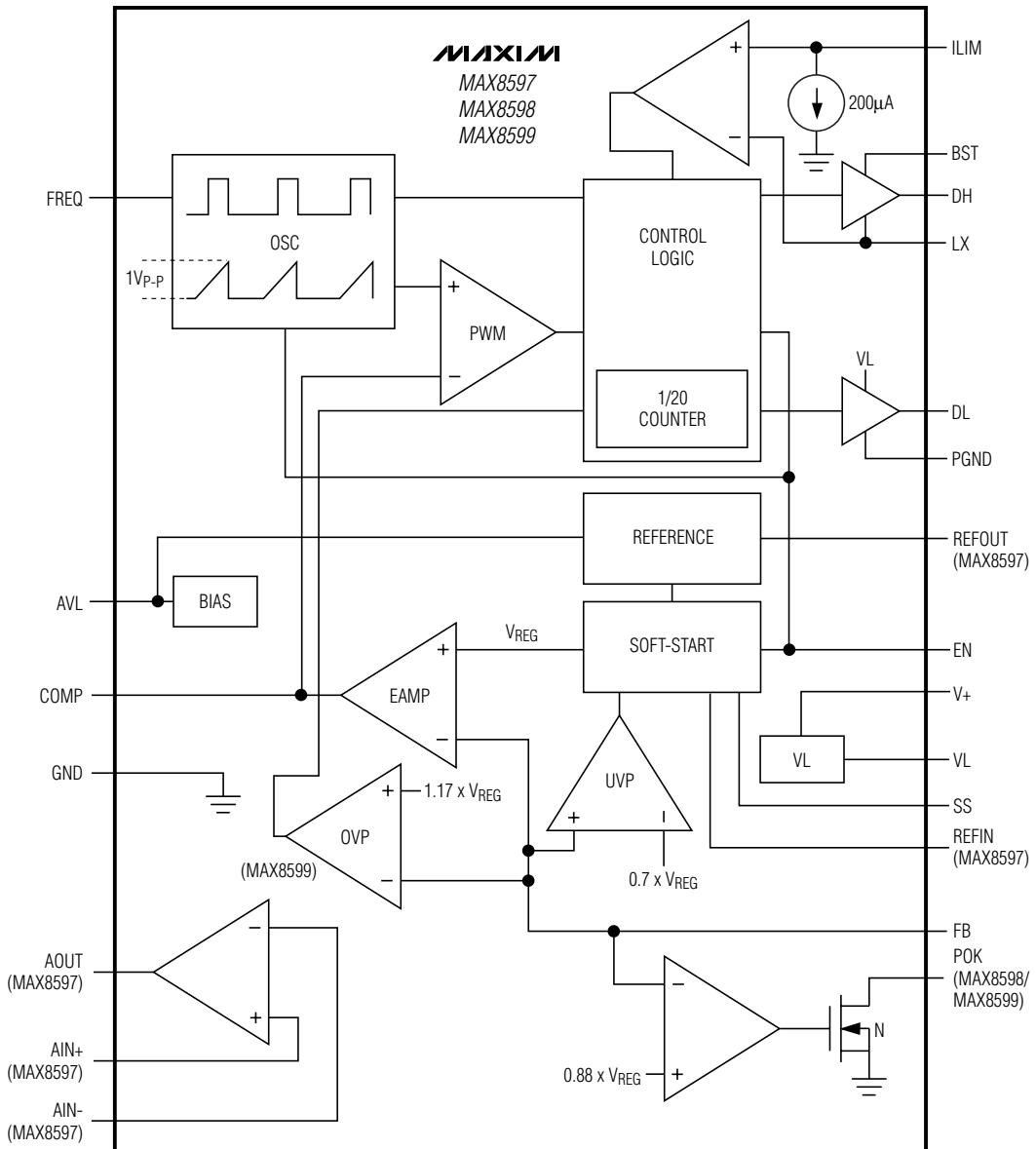
(Circuit of Figure 4, $T_A = +25^\circ\text{C}$, 500kHz switching frequency, $V_{IN} = 12\text{V}$, unless otherwise noted.)



Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

Block Diagram

MAX8597/MAX8598/MAX8599



Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

Pin Description

| PIN | | NAME | FUNCTION |
|---------|---------------------|--------|--|
| MAX8597 | MAX8598/ MAX8599 | | |
| 1 | 1 | AVL | Filtered VL Input. Connect to VL through a 10Ω resistor. Bypass to GND with a $0.22\mu F$ or larger ceramic capacitor. |
| 2 | — | REFIN | External Reference Input. FB tracks the voltage input to REFIN. Connect REFIN to AVL to use the internal 0.6V reference. |
| 3 | 2 | GND | Analog Ground. Connect to the exposed paddle and analog ground plane and then connect to PGND at the output ground. |
| 4 | 3 | SS | Soft-Start Programming Input. Connect a capacitor from SS to GND to set the soft-start time. See the <i>Selecting the Soft-Start Capacitor</i> section for details. |
| 5 | 4 | FB | Feedback Input. Connect to the center tap of an external resistor-divider to set the output voltage. Regulates to 0.6V for the MAX8598/MAX8599 and MAX8597 when REFIN is connected to AVL. Regulates to VREFIN (MAX8597) when using an external reference. |
| 6 | 5 | COMP | Compensation Input. Connect to the required compensation network. See the <i>Compensation Design</i> section for details. |
| 7 | 6 | EN | Enable Input. Drive EN high to enable the IC. Drive low to shut down the IC. |
| 8 | — | REFOUT | Internal Reference Output. REFOUT regulates to 2.5V and can source up to 1mA. REFOUT discharges to GND during UVLO. |
| 9 | 7 | V+ | Input Supply Voltage for Internal VL Regulator. Connect to an input supply in the 4.5V to 28V range. Bypass to GND with a $1\mu F$ or larger ceramic capacitor through a 3Ω resistor. |
| 10 | 8 | VL | Internal 5V Linear-Regulator Output. VL provides power for the internal MOSFET gate drivers. Bypass to PGND with a $1\mu F$ or larger ceramic capacitor. VL is always enabled except in thermal shutdown. See the <i>Internal 5V Linear Regulator</i> section for details. |
| 11 | 9 | DL | Low-Side Gate-Driver Output. Connect to the gate of the synchronous rectifier. DL swings from PGND to VL. DL is held low during shutdown. |
| 12 | 10 | PGND | Power Ground. Connect to the synchronous rectifier's source and PGND plane. |
| 13 | 11 | BST | Bootstrap Input Supply for the High-Side MOSFET Driver. Connect to the cathode of an external diode from VL and connect a $0.1\mu F$ or larger capacitor from BST to LX. |
| 14 | 12 | DH | High-Side Gate-Driver Output. Connect to the gate of the high-side MOSFET. DH swings from LX to BST. DH is low (connected to LX) during shutdown. |
| 15 | 13 | LX | External Inductor Connection. LX is the low supply for the DH gate driver as well as the sense connection for the current-limit circuitry. Connect LX to the switched side of the inductor as well as the source of the high-side MOSFET and the drain of the synchronous rectifier. |
| 16 | 14 | ILIM | Current-Limit Sense Input. Connect a resistor from ILIM to the current-sense point to set the output current limit. See the <i>Setting the Current Limit</i> section for details. |

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

Pin Description (continued)

| PIN | | NAME | FUNCTION |
|---------|---------------------|------|---|
| MAX8597 | MAX8598/ MAX8599 | | |
| 17 | 15 | FREQ | Frequency Adjust Input. Connect a resistor from FREQ to GND to set the switching frequency. The range of the FREQ resistor is 14.3k Ω to 100k Ω (corresponding to 1400kHz to 200kHz). |
| 18 | — | AOUT | Output of the Uncommitted Operational Amplifier. AOUT is high impedance during undervoltage lockout. |
| 19 | — | AIN- | Inverting Input of the Uncommitted Operational Amplifier |
| 20 | — | AIN+ | Noninverting Input of the Uncommitted Operational Amplifier |
| — | 16 | POK | Power-OK Output. POK is an open-drain output that goes high impedance when the regulator output is greater than 88% of the regulation threshold. POK is low during shutdown. |
| — | — | EP | Exposed Paddle. Connect to analog ground plane for improved thermal performance. |

Detailed Description

The MAX8597/MAX8598/MAX8599 voltage-mode PWM step-down controllers are designed to operate from 4.5V to 28V input and generate output voltages down to 0.6V. A proprietary switching algorithm stretches the duty cycle to >99.5% for low-dropout design. Unlike conventional step-down regulators using a p-channel high-side MOSFET to achieve high duty cycle, the MAX8597/MAX8598/MAX8599 drive n-channel MOSFETs permitting high efficiency and high-current designs.

The MAX8597 is available in a 20-pin thin QFN package and is designed for applications that use an analog signal to control the output voltage with adjustable offset, such as DC fan speed control. For example, a 12VDC fan can be driven from 6V to 12V with 12V input power source depending on the system's cooling requirement to minimize fan noise and power consumption. This is achieved with an internal uncommitted operational amplifier. With the addition of an external RC filter, a PWM input can also be used to control the output voltage. The MAX8597 also generates a tracking output for chipsets, ASICs, and DSP where core and I/O supplies are split and require tracking. In applications where tighter output tolerance is required, the MAX8597 output can be set by an external precision reference source feeding to REFIN. The MAX8598/MAX8599 are available in a 16-pin thin QFN package and do not have the uncommitted operational amplifier, reference input, and reference output, but offer a power-OK output (POK). With the enable input and POK output, the MAX8598/MAX8599 can easily be configured to have power sequencing of multiple supply rails.

The MAX8597/MAX8598/MAX8599 allow startup with prebias voltage on the output for applications where a backup supply or a tracking device may charge the output capacitor before the MAX8597/MAX8598/MAX8599 are enabled. The MAX8599 has output overvoltage protection.

These controllers feature lossless high-side peak inductor current sensing, adjustable current limit, and hiccup-mode short-circuit protection. Switching frequency is set with an external resistor from 200kHz to 1.4MHz. This wide frequency range combined with a wide-bandwidth error amplifier enable the loop-compensation scheme to give the user ample flexibility to optimize for cost, size, and efficiency.

DC-DC Controller

The MAX8597/MAX8598/MAX8599 step-down DC-DC controllers use a PWM voltage-mode control scheme. An internal high-bandwidth (25MHz) operational amplifier is used as an error amplifier to regulate the output voltage. The output voltage is sensed and compared with an internal 0.6V reference or REFIN (MAX8597) to generate an error signal. The error signal is then compared with a fixed-frequency ramp by a PWM comparator to give the appropriate duty cycle to maintain output voltage regulation. The high-side MOSFET turns on at the rising edge of the internal clock 20ns after DL (the low-side MOSFET gate drive) goes low. The high-side MOSFET turns off once the internal ramp voltage reaches the error-amplifier output voltage. The process repeats for every clock cycle. During the high-side MOSFET on-time, current flows from the input through the inductor to the output capacitor and load. At the moment the high-side MOSFET turns off, the energy stored in the inductor during the on-time is released to support the load as the inductor

MAX8597/MAX8598/MAX8599

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

current ramps down through the low-side MOSFET body diode; 20ns after DH goes low, the low-side MOSFET turns on, resulting in a lower voltage drop to increase efficiency. The low-side MOSFET turns off at the rising edge of the next clock pulse, and when its gate voltage discharges to zero, the high-side MOSFET turns on and another cycle starts.

These controllers also sense peak inductor current and provide hiccup-overload and short-circuit protection (see the *Current Limit* section). The MAX8597/MAX8598/MAX8599 operate in forced-PWM mode where the inductor current is always continuous. The controller maintains constant switching frequency under all loads, except under dropout conditions where it skips DL pulses.

Current Limit

The MAX8597/MAX8598/MAX8599 DC-DC step-down controllers sense the peak inductor current either with the on-resistance of the high-side MOSFET for lossless sensing, or a series resistor for more accurate sensing. When the voltage across the sensing element exceeds the current-limit threshold set with ILIM, the controller immediately turns off the high-side MOSFET. The low-side MOSFET is then turned on to let the inductor current ramp down. As the output load current increases above the ILIM threshold, the output voltage sags because the truncated duty cycle is insufficient to support the load current. When FB falls 30% below its nominal threshold, the output undervoltage protection is triggered and the controller enters hiccup mode to limit power dissipation. This current-limit method allows the circuit to withstand a continuous output short circuit.

The MAX8597/MAX8598/MAX8599 current-limit threshold is set by an external resistor that works in conjunction with an internal 200 μ A current sink (see the *Setting the Current Limit* section for more details).

Synchronous-Rectifier Driver (DL)

Synchronous rectification reduces the conduction loss in the rectifier by replacing the normal Schottky catch diode with a low-resistance MOSFET switch. The MAX8597/MAX8598/MAX8599 also use the synchronous rectifier to ensure proper startup of the boost gate-drive circuit.

High-Side Gate-Drive Supply (BST)

Gate-drive voltage for the high-side n-channel MOSFET is generated by an external flying capacitor and diode boost circuit (D1 and C5 in Figure 1). When the synchronous rectifier is on, C5 is charged from the VL supply through the Schottky diode. When the synchronous rectifier is turned off, the Schottky is reverse biased and the voltage on C5 is stacked above LX to provide the necessary turn-on voltage for the high-side MOSFET. A low-current Schottky diode, such as Central Semiconductor's CMDSH-3, works well for most applications. The capacitor should be large enough to prevent it from charging to excessive voltage, but small enough to adequately charge during the minimum low-side MOSFET on-time, which occurs at minimum input voltage. A capacitor in the 0.1 μ F to 0.47 μ F range works well for most applications.

Internal 5V Linear Regulator

The MAX8597/MAX8598/MAX8599 contain a low-dropout 5V regulator that provides up to 35mA to supply gate drive for the external MOSFETs, and supplies AVL, which powers the IC's internal circuitry. Bypass the regulator's output (VL) with 1 μ F per 10mA of VL load, or greater ceramic capacitor. The current required to drive the external MOSFET can be estimated by multiplying the total gate charge (at V_{GS} = 5V) of the MOSFETs by the switching frequency.

Undervoltage Lockout (UVLO)

When V_{VL} drops below 3.75V (typ), the MAX8597/MAX8598/MAX8599's undervoltage-lockout (UVLO) circuitry inhibits switching, forces POK (MAX8598/MAX8599) low, and forces DH and DL low. Once V_{VL} rises above 4.2V (typ), the controller powers up the output in startup mode (see the *Startup* section).

Startup

The MAX8597/MAX8598/MAX8599 start switching once all the following conditions are met:

- 1) EN is high.
- 2) V_{VL} > 4.2V (typ).
- 3) Soft-start voltage V_{SS} exceeds V_{FB}.
- 4) Thermal limit is not exceeded.

The third condition ensures that the MAX8597/MAX8598/MAX8599 do not discharge a prebiased output. Once all of these conditions are met, the IC begins switching and the soft-start cycle is initiated.

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

Power-OK Signal (POK, MAX8598/MAX8599 Only)

The power-OK signal (POK) is an open-drain output that goes high impedance when FB is above 91% of its nominal threshold. There is an eight clock-cycle delay before POK goes high impedance. For 500kHz switching frequency, this delay is typically 16µs. To obtain a logic voltage output, connect a pullup resistor from POK to AVL. A 100kΩ resistor works well for most applications. If unused, connect POK to GND or leave it unconnected.

Enable and Soft-Start

The MAX8597/MAX8598/MAX8599 are enabled using the EN input. A logic high on EN enables the output of the IC. Conversely, a logic low on EN disables the output. On the rising edge of EN, the controllers enter soft-start. Soft-start gradually ramps up the reference voltage seen at the error amplifier to control the output rate of rise and reduce the inrush current during start-up. The soft-start period is determined by a capacitor connected from SS to GND (C6 in Figure 1). A 5µA current source charges the external capacitor to the reference voltage (0.6V or VREFIN). The capacitor value is determined as follows:

$$C6 = \frac{5\mu A \times t_{SS}}{V_{FB}}$$

where tss is the soft-start time in seconds and VFB is 0.6V or VREFIN. The output reaches regulation when soft-start is completed.

Output Undervoltage Protection (UVP)

Output UVP begins when the controller is at its current limit and VFB is 30% below its nominal threshold. This condition causes the controller to drive DH and DL low and discharges the soft-start capacitor with a 5µA pull-down current until VSS reaches 50mV. Then the controller begins in soft-start mode. If the overload

condition still exists, the UVP process begins again. The result is “hiccup” mode, where the controller attempts to restart periodically as long as the overload condition exists. In hiccup mode, the soft-start capacitor voltage ramps up to 112% of the nominal VFB threshold and then ramps down to 50mV. For the MAX8597, VREFIN must be greater than 450mV to trigger UVP. The soft-start capacitor voltage then ramps up to 112% of VREFIN and then down to 50mV.

Output Overvoltage Protection (OVP, MAX8599)

The output voltage is continuously monitored for overvoltage (MAX8599 only). If the output voltage is more than 117% of its nominal set value, OVP is triggered after a 12µs (typ) delay. The MAX8599 latches DH low to turn off the high-side MOSFET, and DL high to turn on the low-side MOSFET to clamp the output to PGND. The latch is reset either by toggling EN or by cycling V+ below the UVLO threshold. Note that DL latching high causes a negative spike at the output due to the energy stored in the output LC at the instant of OVP trip. If the load cannot tolerate this negative spike, add a power Schottky diode across the output to act as a reverse polarity clamp.

Thermal-Overload Protection

Thermal-overload protection limits the total power dissipation in the MAX8597/MAX8598/MAX8599. When the junction temperature exceeds +160°C, a thermal sensor shuts down the device, forcing DH and DL low, allowing the IC to cool. The thermal sensor turns the part on after the junction temperature cools by 10°C, resulting in a pulsed output during continuous thermal-overload conditions. During a thermal event, the switching converter is turned off, the reference is turned off, the VL regulator is turned off, POK is high impedance, and the soft-start capacitor is discharged.

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

Design Procedure

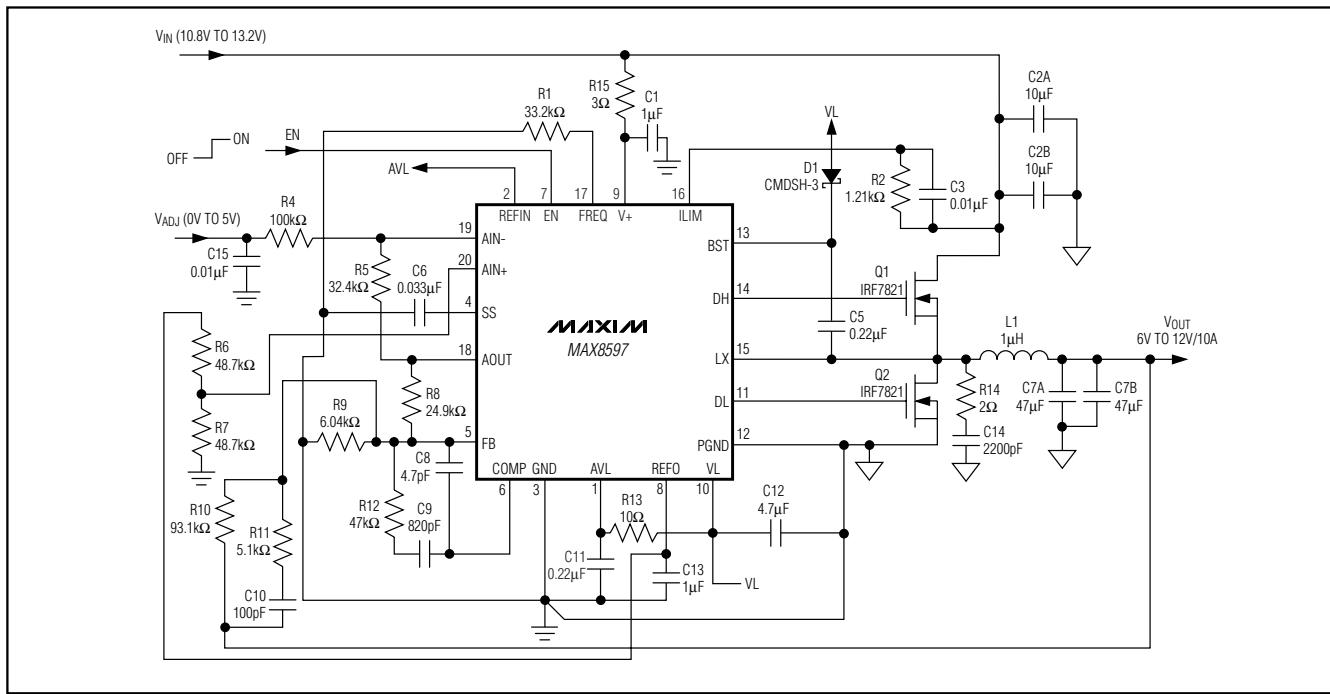


Figure 1. MAX8597 (600kHz): Live Adjustable Output Voltage from 6V to 12V at 10A

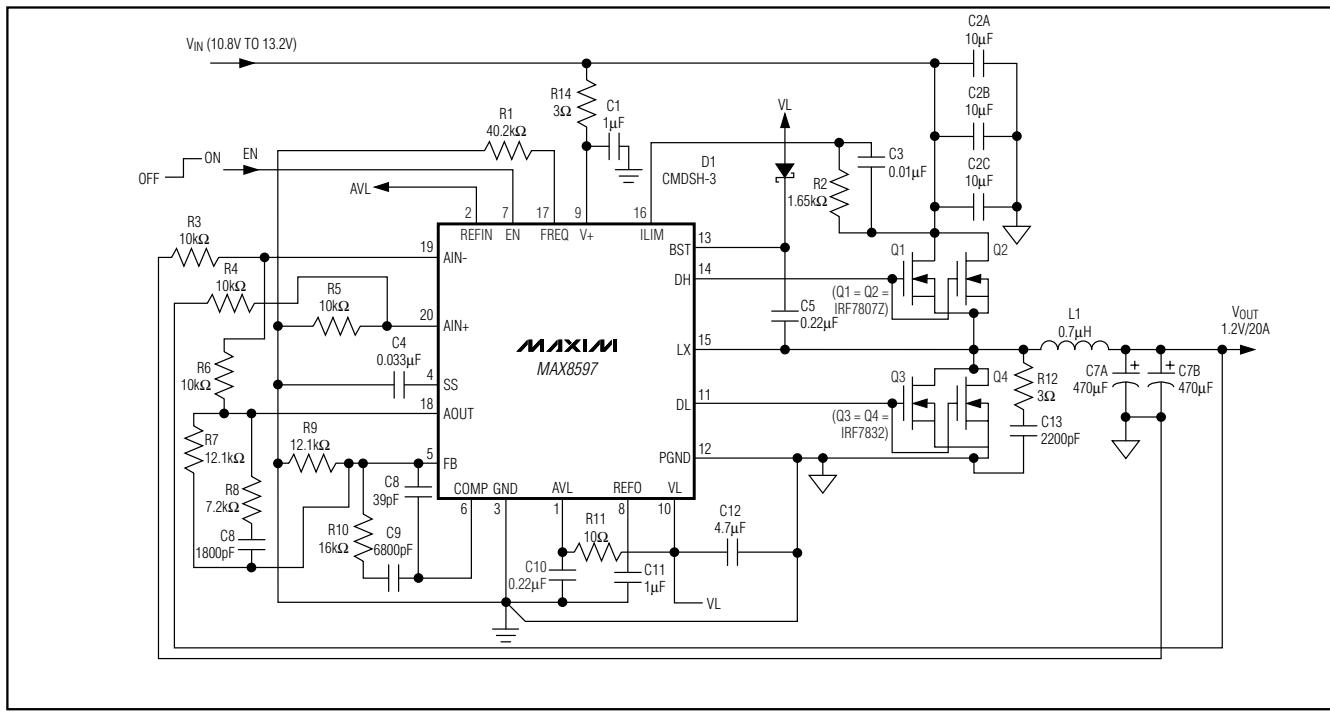


Figure 2. 1.2V at 20A Output with Remote Sensing

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

Design Procedure (continued)

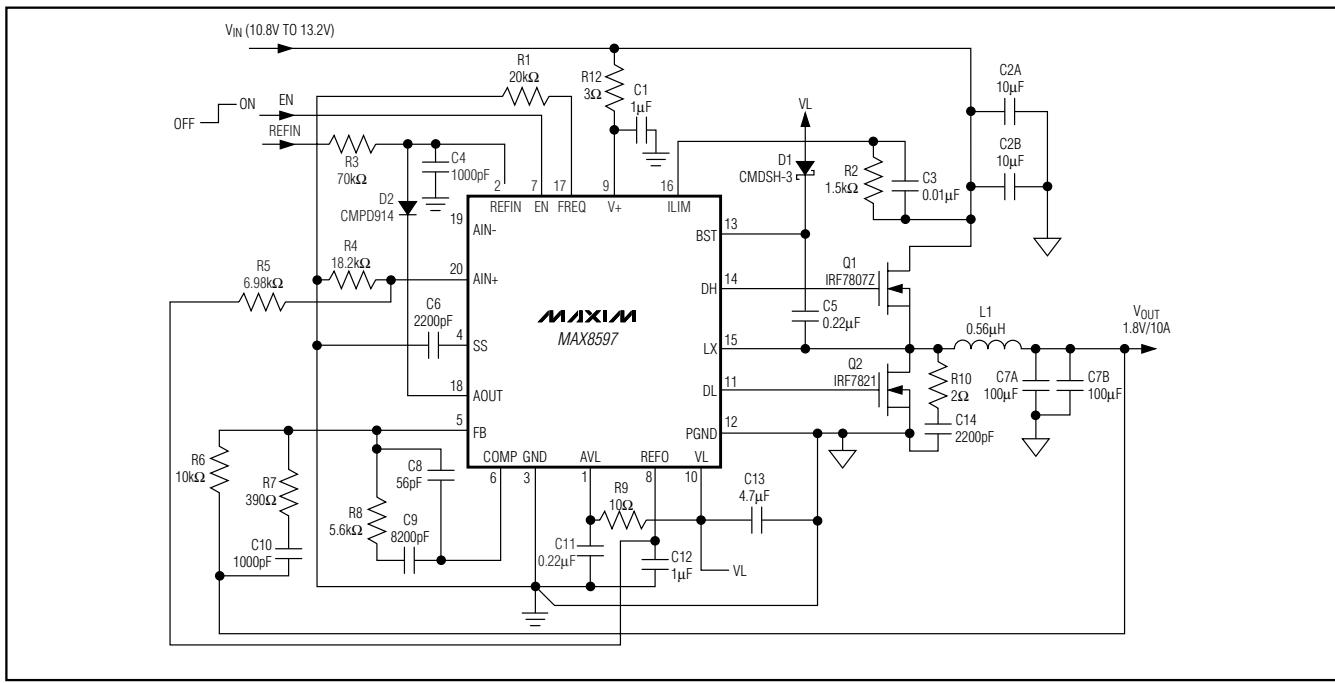


Figure 3. MAX8597 1MHz Tracking Supply with Clamp (Output voltage tracks VREFIN from 0V up to the nominal output regulation voltage.)

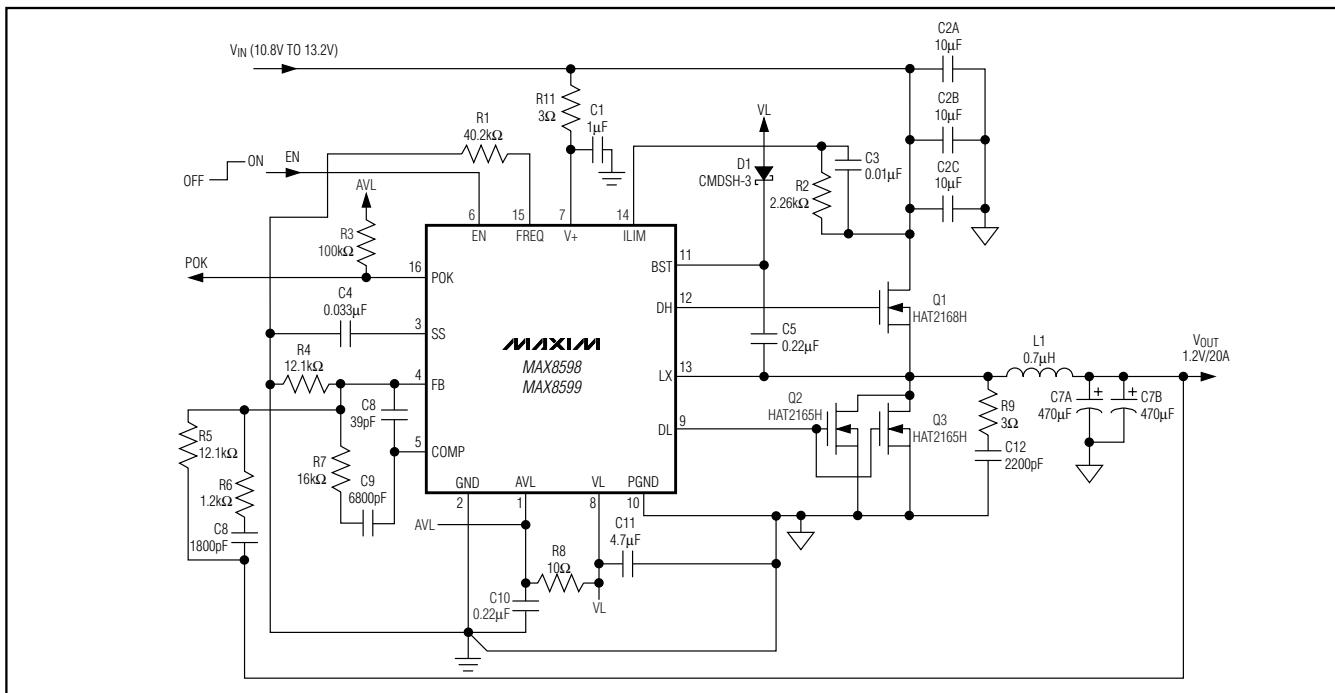


Figure 4. MAX8598/MAX8599 500kHz, 1.2V, 20A Output Power Supply

Low-Dropout, Wide-Input-Voltage, Step-Down Controllers

Setting the Output Voltage

Fixed Output Voltage

The output voltage is set by a resistor-divider network from the output to GND with FB at the center tap (R4 and R5 in Figure 4). Select R4 between 5kΩ and 15kΩ and calculate R5 by:

$$R5 = R4 \times [(V_{OUT} / V_{FB}) - 1]$$

Live Adjustable Output Voltage (see Figure 1)

Using the uncommitted operational amplifier, the MAX8597 can be configured such that the output voltage is adjustable using a voltage source (VADJ). The following parameters must be defined before starting the design:

- The minimum desired output voltage, VOUT_MIN
- The maximum desired output voltage, VOUT_MAX
- The desired input that corresponds to the minimum output voltage, VADJ_MIN
- The desired input that corresponds to the maximum output voltage, VADJ_MAX

Select VAOUT (uncommitted operational-amplifier output) between 0.05V and 3V and VAOUT_MAX higher than VAOUT_MIN. Calculate the required AIN+ reference (VAIN+) as:

$$V_{AIN+} = \frac{V_{AOUT_MAX} \times V_{ADJ_MAX} - V_{AOUT_MIN} \times V_{ADJ_MIN}}{(V_{ADJ_MAX} - V_{ADJ_MIN}) + (V_{AOUT_MAX} - V_{AOUT_MIN})}$$

VAIN+ is set using a resistor-divider from REFOUT to GND (R6 and R7). Select R7 to be approximately 50kΩ as a starting point and then calculate R6 as:

$$R6 = R7 \times [(2.5V / V_{AIN+}) - 1]$$

Select R4 to be 100kΩ and calculate R5 as:

$$R5 = \frac{(V_{AIN+} - V_{AOUT_MIN}) \times R4}{(V_{ADJ_MAX} - V_{AIN+})}$$

Select R9 between 5kΩ and 15kΩ, then calculate R8 and R10 as follows:

$$R8 = \frac{[(V_{OUT_MIN} - V_{FB}) \times (V_{FB} - V_{AOUT_MIN})] + [(V_{OUT_MAX} - V_{FB}) \times (V_{AOUT_MAX} - V_{FB})]}{((V_{OUT_MAX} - V_{FB}) - (V_{OUT_MIN} - V_{FB})) \times V_{FB}} \times R9$$

$$R10 = \frac{R8 \times R9 \times (V_{OUT_MAX} - V_{FB})}{(V_{FB} \times R8) + [(V_{FB} - V_{AOUT_MIN}) \times R9]}$$

where VFB is the feedback regulation voltage (0.6V with REFIN connected to AVL).

Additionally, to minimize error, R6 and R7 should be chosen such that:

$$\frac{R6 \times R7}{R6 + R7} = \frac{R4 \times R5}{R4 + R5}$$

Inductor Selection

There are several parameters that must be examined when determining which inductor is to be used: input voltage, output voltage, load current, switching frequency, and LIR. LIR is the ratio of inductor current ripple to DC load current. A higher LIR value allows for a smaller inductor but results in higher losses and higher output ripple. A good compromise between size and efficiency is a 30% LIR. Once all the parameters are chosen, the inductor value is determined as follows:

$$L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times f_s \times I_{LOAD(MAX)} \times LIR}$$

where fs is the switching frequency. Choose a standard value close to the calculated value. The exact inductor value is not critical and can be adjusted in order to make trade-offs among size, cost, and efficiency. Lower inductor values minimize size and cost, but also increase the output ripple and reduce the efficiency due to higher peak currents. On the other hand, higher inductor values increase efficiency, but eventually resistive losses due to extra turns of wire exceed the benefit gained from lower AC current levels. Find a low-loss inductor having the lowest possible DC resistance that fits the allotted dimensions. Ferrite cores are often the best choice, although powdered iron is inexpensive and can work well up to 300kHz. The chosen inductor's saturation current rating must exceed the peak inductor current determined as:

$$I_{PEAK} = I_{LOAD(MAX)} + \left(\frac{LIR}{2} \right) \times I_{LOAD(MAX)}$$

Input Capacitor

The input filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple on the input caused by the circuit's switching. The input capacitor must meet the ripple current requirement (IRMS) imposed by the switching currents defined by the following equation:

$$I_{RMS} = \frac{I_{LOAD} \times \sqrt{V_{OUT} \times (V_{IN} - V_{OUT})}}{V_{IN}}$$

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I_{RMS} has a maximum value when the input voltage equals twice the output voltage ($V_{IN} = 2 \times V_{OUT}$), so $I_{RMS(MAX)} = I_{LOAD} / 2$. Ceramic capacitors are recommended due to their low ESR and ESL at high frequency, with relatively lower cost. Choose a capacitor that exhibits less than 10°C temperature rise at the maximum operating RMS current for optimum long-term reliability.

Output Capacitor

The key selection parameters for the output capacitor are the actual capacitance value, the equivalent series resistance (ESR), the equivalent series inductance (ESL), and the voltage-rating requirements, which affect the overall stability, output ripple voltage, and transient response. The output ripple has three components: variations in the charge stored in the output capacitor, voltage drop across the capacitor's ESR, and voltage drop across the capacitor's ESL, caused by the current into and out of the capacitor. The following equations estimate the worst-case ripple:

$$V_{RIPPLE} = V_{RIPPLE(ESR)} + V_{RIPPLE(ESL)} + V_{RIPPLE(C)}$$

$$V_{RIPPLE(ESR)} = I_{P-P} \times ESR$$

$$V_{RIPPLE(ESL)} = \frac{V_{IN} \times ESL}{L + ESL}$$

$$V_{RIPPLE(C)} = \frac{I_{P-P}}{8 \times C_{OUT} \times f_s}$$

$$I_{P-P} = \left(\frac{V_{IN} - V_{OUT}}{f_s \times L} \right) \times \left(\frac{V_{OUT}}{V_{IN}} \right)$$

where I_{P-P} is the peak-to-peak inductor current.

The response to a load transient depends on the selected output capacitor. After a load transient, the output instantly changes by $(ESR \times \Delta I_{LOAD}) + (ESL \times di/dt)$. Before the controller can respond, the output deviates further depending on the inductor and output capacitor values. After a short period of time (see the *Typical Operating Characteristics*), the controller responds by regulating the output voltage back to its nominal state. The controller response time depends on the closed-loop bandwidth. With higher bandwidth, the response time is faster, preventing the output capacitor voltage from further deviation from its regulation value. Do not exceed the capacitor's voltage or ripple current ratings.

MOSFET Selection

The MAX8597/MAX8598/MAX8599 controllers drive external, logic-level, n-channel MOSFETs as the circuit-switch elements. The key selection parameters are:

- On-resistance ($R_{DS(ON)}$): the lower, the better.
- Maximum drain-to-source voltage (V_{DSS}): should be at least 20% higher than the input supply rail at the high-side MOSFET's drain.
- Gate charges (Q_g , Q_{gd} , Q_{gs}): the lower, the better.

Choose MOSFETs with $R_{DS(ON)}$ rated at $V_{GS} = 4.5V$. For a good compromise between efficiency and cost, choose the high-side MOSFET that has conduction loss equal to the switching loss at the nominal input voltage and maximum output current. For the low-side MOSFET, make sure it does not spuriously turn on due to dv/dt caused by the high-side MOSFET turning on, resulting in efficiency degrading shoot-through current. MOSFETs with a lower Q_{gd}/Q_{gs} ratio have higher immunity to dv/dt .

For proper thermal-management design, the power dissipation must be calculated at the desired maximum operating junction temperature, maximum output current, and worst-case input voltage (for low-side MOSFET, worst case is at $V_{IN(MAX)}$; for high-side MOSFET, it could be either at $V_{IN(MIN)}$ or $V_{IN(MAX)}$).

High-side and low-side MOSFETs have different loss components due to the circuit operation. The low-side MOSFET operates as a zero-voltage switch; therefore, the major losses are the channel-conduction loss (PL_{SCC}) and the body-diode conduction loss (PL_{SDC}):

$$PL_{SCC} = [1 - (V_{OUT} / V_{IN})] \times (I_{LOAD})^2 \times R_{DS(ON)}$$

$$PL_{SDC} = 2 \times I_{LOAD} \times V_F \times t_{dt} \times f_s$$

where V_F is the body-diode forward-voltage drop, t_{dt} is the dead-time between the high-side MOSFET and the low-side MOSFET switching transitions, and f_s is the switching frequency. The high-side MOSFET operates as a duty-cycle control switch and has the following major losses: the channel-conduction loss (PH_{SCC}), the V-I overlapping switching loss (PH_{SSW}), and the drive loss (PH_{SDR}). The high-side MOSFET does not have body-diode conduction loss because the diode never conducts current:

$$PH_{SCC} = (V_{OUT} / V_{IN}) \times I_{LOAD}^2 \times R_{DS(ON)}$$

Use $R_{DS(ON)}$ at $T_{J(MAX)}$:

$$PH_{SSW} = V_{IN} \times I_{LOAD} \times f_s \times [(Q_{gs} + Q_{gd}) / I_{GATE}]$$

where I_{GATE} is the average DH-high driver output-current capability determined by:

$$I_{GATE} = 2.5 / (R_{DH} + R_{GATE})$$

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where R_{DH} is the high-side MOSFET driver's average on-resistance (1.25Ω typ) and R_{GATE} is the internal gate resistance of the MOSFET (typically 0.5Ω to 2Ω):

$$PHSDR = Q_{GS} \times V_{GS} \times f_S \times R_{GATE} / (R_{GATE} + R_{DH})$$

where $V_{GS} \sim V_{VL} = 5V$.

In addition to the losses above, add approximately 20% more for additional losses due to MOSFET output capacitances and low-side MOSFET body-diode reverse-recovery charge dissipated in the high-side MOSFET that exists, but is not well defined in the MOSFET data sheet. Refer to the MOSFET data sheet for thermal-resistance specification to calculate the PC board area needed to maintain the desired maximum operating junction temperature with the above-calculated power dissipation. To reduce EMI caused by switching noise, add a $0.1\mu F$ or larger ceramic capacitor from the high-side switch drain to the low-side switch source or add resistors in series with D_H and D_L to slow down the switching transitions. However, adding a series resistor increases the power dissipation of the MOSFETs, so be sure this does not overheat the MOSFETs. The minimum load current must exceed the high-side MOSFET's maximum leakage plus the maximum LX bias current over temperature.

Setting the Current-Limit

The MAX8597/MAX8598/MAX8599 controllers sense the peak inductor current to provide constant-current and hiccup current limit. The peak current-limit threshold is set by an external resistor (R_2 in Figure 1) together with the internal current sink of $200\mu A$. The voltage drop across the resistor R_2 due to the $200\mu A$ current sets the maximum peak inductor current that can flow through the high-side MOSFET or the optional current-sense resistor (between the high-side MOSFET source and LX) by the equations below:

$$I_{PEAK(MAX)} = 200\mu A \times R_2 / R_{DS(ON)(HSFET)}$$

$$I_{PEAK(MAX)} = 200\mu A \times R_2 / R_{SENSE}$$

The actual corresponding maximum load current is lower than the $I_{PEAK(MAX)}$ by half of the inductor ripple current. If the $R_{DS(ON)}$ of the high-side MOSFET is used for current sensing, use the maximum $R_{DS(ON)}$ at the highest operating junction temperature to avoid false tripping of the current limit at elevated temperature. Consideration should also be given to the tolerance of the $200\mu A$ current sink. When the $R_{DS(ON)}$ of the high-side MOSFET is used for current sensing, ringing on

the LX voltage waveform can interfere with the current limit. Below is the procedure for selecting the value of the series RC snubber circuit (R_{14} and C_{14} in Figure 1):

- 1) Connect a scope probe to measure V_{LX} to GND, and observe the ringing frequency, f_R .
- 2) Find the capacitor value (connected from LX to GND) that reduces the ringing frequency by half. The circuit parasitic capacitance (C_{PAR}) at LX is then equal to $1/3$ the value of the added capacitance above. The circuit parasitic inductance (L_{PAR}) is calculated by:

$$L_{PAR} = \frac{1}{(2\pi \times f_R)^2 \times C_{PAR}}$$

The resistor for critical dampening (R_{14}) is equal to $2\pi \times f_R \times L_{PAR}$. Adjust the resistor value up or down to tailor the desired damping and the peak voltage excursion.

The capacitor (C_{14}) should be at least 2 to 4 times the value of the C_{PAR} in order to be effective. The power loss of the snubber circuit is dissipated in the resistor (R_{14}) and is calculated as:

$$P_{R14} = C_{14} \times (V_{IN})^2 \times f_S$$

where V_{IN} is the input voltage and f_S is the switching frequency. Choose an R_{14} power rating that meets the specific application's derating rule for the power dissipation calculated.

Additionally, there is parasitic inductance of the current-sensing element, whether the high-side MOSFET (L_{SENSE_FET}) or the optional current-sense resistor (L_{RSENSE}) are used, which is in series with the output filter inductor. This parasitic inductance, together with the output inductor, forms an inductive divider and causes error in the current-sensing voltage. To compensate for this error, a series RC circuit can be added in parallel with the sensing element (see Figure 5). The RC time constant should equal L_{RSENSE} / R_{SENSE} , or $L_{SENSE_FET} / R_{DS(ON)}$. First, set the value of R equal to or less than $R_2 / 100$. Then, the value of C is calculated as:

$$C = L_{RSENSE} / (R_{SENSE} \times R) \text{ or}$$

$$C = L_{SENSE_FET} / (R_{DS(ON)} \times R)$$

Any PC board trace inductance in series with the sensing element and output inductor should be added to the specified FET or resistor inductance per the respective manufacturer's data sheet. For the case of

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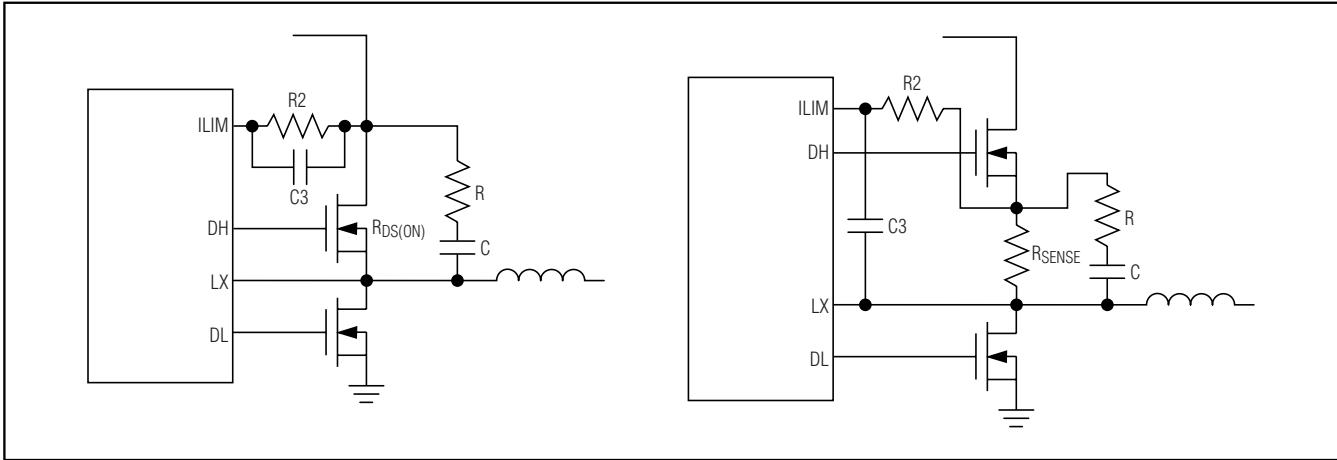


Figure 5. Adding RC for More Accurate Sensing

the MOSFET, it is the inductance from the drain to the source lead.

Alternately, to save board space and cost, the RC networks above can be omitted; however, the value of R_{ILIM} should be raised to account for the voltage step caused by the inductive divider.

An additional switching noise filter may be needed at ILIM by connecting a capacitor in parallel with R2 (in the case of RDS(ON) sensing) or from ILIM to LX (in the case of resistor sensing). For the case of RDS(ON) sensing, the value of the capacitor should be:

$$C_3 > 15 / (\pi \times f_S \times R_2)$$

For the case of resistor sensing:

$$C_3 < 25 \times 10^{-9} / R_2$$

Selecting the Soft-Start Capacitor

An external capacitor from SS to GND is charged by an internal 5 μ A current source, to the corresponding feedback threshold. Therefore, the soft-start time is calculated as:

$$t_{SS} = C_{SS} \times V_{FB} / 5\mu A$$

For example, 0.033 μ F from SS to GND yields approximately a 3.96ms soft-start period.

In the tracking application (see Figure 3), the output voltage is required to track REFIN during REFIN rise and fall time. C_{SS} must be chosen so that t_{SS} is less than REFIN rise and fall time.

Compensation Design

The MAX8597/MAX8598/MAX8599 use a voltage-mode control scheme that regulates the output voltage by

comparing the error-amplifier output (COMP) with a fixed internal ramp to produce the required duty cycle. The error amplifier is an operational amplifier with 25MHz bandwidth to provide fast response. The output lowpass LC filter creates a double pole at the resonant frequency that introduces a gain drop of 40dB per decade and a phase shift of 180 degrees per decade. The error amplifier must compensate for this gain drop and phase shift to achieve a stable high-bandwidth closed-loop system. The Type III compensation scheme (Figure 6) is used to achieve this stability.

The basic regulator loop can be thought of as consisting of a power modulator and an error amplifier. The power modulator has a DC gain set by V_{IN} / V_{RAMP} , with a double pole, f_{P_LC} , and a single zero, f_{Z_ESR} , set by the output inductor (L), the output capacitor (C_O), and its equivalent series resistance (R_{ESR}). Below are the equations that define the power modulator:

$$G_{MOD(DC)} = \frac{V_{IN}}{V_{RAMP}}, \text{ where } V_{RAMP} = 1V \text{ (typ)}$$

$$f_{P_LC} = \frac{1}{2\pi\sqrt{L \times C_O}}$$

$$f_{Z_ESR} = \frac{1}{2\pi \times R_{ESR} \times C_O}$$

where C_O is the total output capacitance and R_{ESR} is the total ESR of the output capacitors.

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When the output capacitor is comprised of paralleling n number of the same capacitors, then:

$$C_O = n \times C_{EACH}$$

and

$$R_{ESR} = R_{ESR_EACH} / n$$

Thus, the resulting f_{Z_ESR} is the same as that of a single capacitor.

The total closed-loop gain must be equal to unity at the crossover frequency, where the crossover frequency is less than or equal to 1/5 the switching frequency (f_S):

$$f_C \leq f_S / 5$$

So the loop-gain equation at the crossover frequency is:

$$G_{EA}(f_C) \times G_{MOD}(f_C) = 1$$

where $G_{EA}(f_C)$ is the error-amplifier gain at f_C , and $G_{MOD}(f_C)$ is the power-modulator gain at f_C .

The loop compensation is affected by the choice of output filter capacitor due to the position of its ESR-zero frequency with respect to the desired closed-loop crossover frequency. Ceramic capacitors are used for higher switching frequencies and have low capacitance and low ESR; therefore, the ESR-zero frequency is higher than the closed-loop crossover frequency. Electrolytic capacitors (e.g., tantalum, solid polymer, and OS-CON) are needed for lower switching frequencies and have high capacitance (and some have higher ESR); therefore, the ESR-zero frequency can be lower than the closed-loop crossover frequency. Thus, the compensation design procedures are separated into two cases:

Case 1: Crossover frequency is less than the output-capacitor ESR-zero ($f_C < f_{Z_ESR}$).

The modulator gain at f_C is:

$$G_{MOD}(f_C) = G_{MOD}(DC) \times (f_{P_LC} / f_C)^2$$

Since the crossover frequency is lower than the output capacitor ESR-zero frequency and higher than the LC double-pole frequency, the error-amplifier gain must have a +1 slope at f_C so that, together with the -2 slope of the LC double pole, the loop crosses over at the desired -1 slope.

The error amplifier has a dominant pole at a very low frequency (~0Hz), and two additional zeros and two additional poles as indicated by the equations below and illustrated in Figure 7:

$$f_{Z1_EA} = 1 / (2 \pi \times R4 \times C2)$$

$$f_{Z2_EA} = 1 / (2 \pi \times (R1 + R3) \times C1)$$

$$f_{P2_EA} = 1 / (2 \pi \times R3 \times C1)$$

$$f_{P3_EA} = 1 / (2 \pi \times R4 \times (C2 \times C3 / (C2 + C3)))$$

Note that f_{Z2_EA} and f_{P2_EA} are chosen to have the converter closed-loop crossover frequency, f_C , occur when the error-amplifier gain has +1 slope, between f_{Z2_EA} and f_{P2_EA} . The error-amplifier gain at f_C must meet the requirement below:

$$G_{EA}(f_C) = 1 / G_{MOD}(f_C)$$

The gain of the error amplifier between f_{Z1_EA} and f_{Z2_EA} is:

$$G_{EA}(f_{Z1_EA} - f_{Z2_EA}) = G_{EA}(f_C) \times f_{Z2_EA} / f_C = f_{Z2_EA} / (f_C \times G_{MOD}(f_C))$$

This gain is set by the ratio of $R4/R1$ (Figure 6), where $R1$ is calculated as illustrated in the *Setting the Output Voltage* section. Thus:

$$R4 = R1 \times f_{Z2_EA} / (f_C \times G_{MOD}(f_C))$$

where $f_{Z2_EA} = f_{P_LC}$.

Due to the underdamped ($Q > 1$) nature of the output LC double pole, the first error-amplifier zero frequency must be set less than the LC double-pole frequency in order to provide adequate phase boost. Set the error-amplifier first zero, f_{Z1_EA} , at 1/4 of the LC double-pole frequency. Hence:

$$C2 = 2 / (\pi \times R4 \times f_{P_LC})$$

Set the error amplifier f_{P2_EA} at f_{Z_ESR} and

$$f_{P3_EA} \text{ at } \frac{f_S}{2} \text{ if } f_{Z_ESR} \text{ is less than } \frac{f_S}{2}.$$

$$\text{If } f_{Z_ESR} \text{ is greater than } \frac{f_S}{2}, \text{ then set}$$

$$f_{P2_EA} \text{ at } \frac{f_S}{2} \text{ and } f_{P3_EA} \text{ at } f_{Z_ESR}.$$

The error-amplifier gain between f_{P2_EA} and f_{P3_EA} is set by the ratio of $R4/RM$ and is equal to:

$$G_{EA}(f_{Z1_EA} - f_{Z2_EA}) \times (f_{P2_EA} / f_{P_LC})$$

where $RM = R1 \times R3 / (R1 + R3)$. Then:

$$\begin{aligned} RM &= R4 \times f_{P_LC} / (G_{EA}(f_{Z1_EA} - f_{Z2_EA}) \times f_{P2_EA}) \\ &= R4 \times f_C \times G_{MOD}(f_C) / f_{P2_EA} \end{aligned}$$

The value of $R3$ can then be calculated as:

$$R3 = R1 \times RM / (R1 - RM)$$

Now we can calculate the value of $C1$ as:

$$C1 = 1 / (2 \pi \times R3 \times f_{P2_EA})$$

and $C3$ as:

$$C3 = C2 / ((2 \pi \times C2 \times R4 \times f_{P3_EA}) - 1)$$

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Case 2: Crossover frequency is greater than the output-capacitor ESR zero ($f_C > f_{Z_ESR}$).

The modulator gain at f_C is:

$$GMOD(FC) = GMOD(DC) \times (f_{P_LC})^2 / (f_{Z_ESR} \times f_C)$$

Since the output-capacitor ESR-zero frequency is higher than the LC double-pole frequency but lower than the closed-loop crossover frequency, where the modulator already has -1 slope, the error-amplifier gain must have zero slope at f_C so the loop crosses over at the desired -1 slope.

The error-amplifier circuit configuration is the same as case 1 above; however, the closed-loop crossover frequency is now between f_{P2} and f_{P3} as illustrated in Figure 8.

The equations that define the error amplifier's zeros (f_{Z1_EA} , f_{Z2_EA}) and poles (f_{P2_EA} , f_{P3_EA}) are the same as case 1; however, f_{P2_EA} is now lower than the closed-loop crossover frequency. Therefore, the error-amplifier gain between f_{Z1_EA} and f_{Z2_EA} is now calculated as:

$$GEA(f_{Z1_EA} - f_{Z2_EA}) = GEA(FC) \times f_{Z2_EA} / f_{P2_EA} = f_{Z2_EA} / (f_{P2_EA} \times GMOD(FC))$$

This gain is set by the ratio of $R4/R1$, where $R1$ is calculated as illustrated in the *Setting the Output Voltage* section. Thus:

$$R4 = R1 \times f_{Z2_EA} / (f_{P2_EA} \times GMOD(FC))$$

where $f_{Z2_EA} = f_{P_LC}$ and $f_{P2_EA} = f_{Z_ESR}$.

Similar to case 1, $C2$ is calculated as:

$$C2 = 2 / (\pi \times R4 \times f_{P_LC})$$

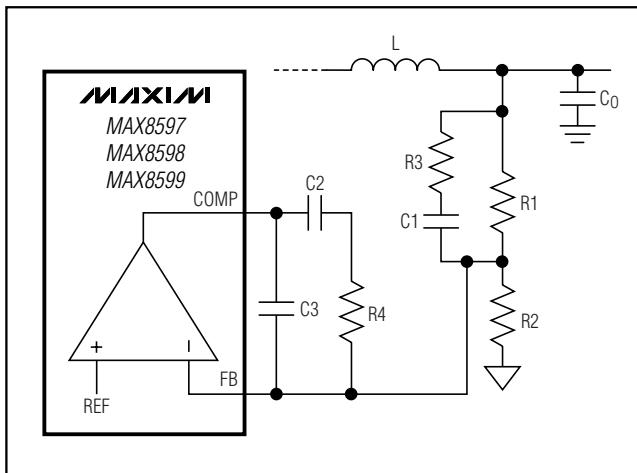


Figure 6. Type III Compensation Network

Set the error-amplifier third pole, f_{P3_EA} , at half the switching frequency, and let $RM = (R1 \times R3) / (R1 + R3)$. The gain of the error amplifier between f_{P2_EA} and f_{P3_EA} is set by the ratio of $R4/RM$ and is equal to $GEA(FC) = 1 / GMOD(FC)$. Then:

$$RM = R4 \times GMOD(FC)$$

Similar to case 1, $R3$, $C1$, and $C3$ are calculated as:

$$R3 = R1 \times RM / (R1 - RM)$$

$$C1 = 1 / (2\pi \times R3 \times f_{Z_ESR})$$

$$C3 = C2 / ((2\pi \times C2 \times R4 \times f_{P3_EA}) - 1)$$

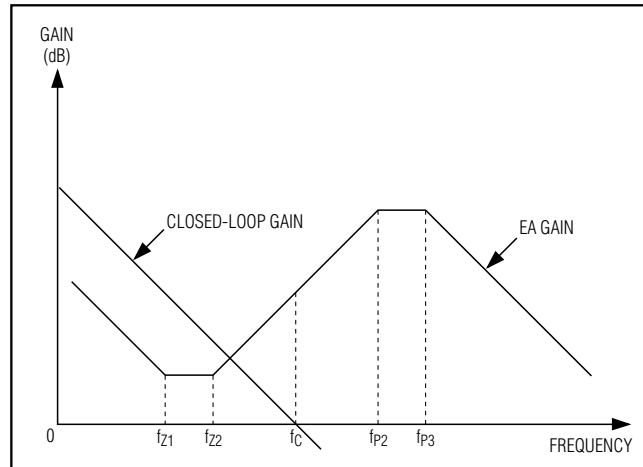


Figure 7. Closed-Loop and Error-Amplifier Gain Plot for Case 1

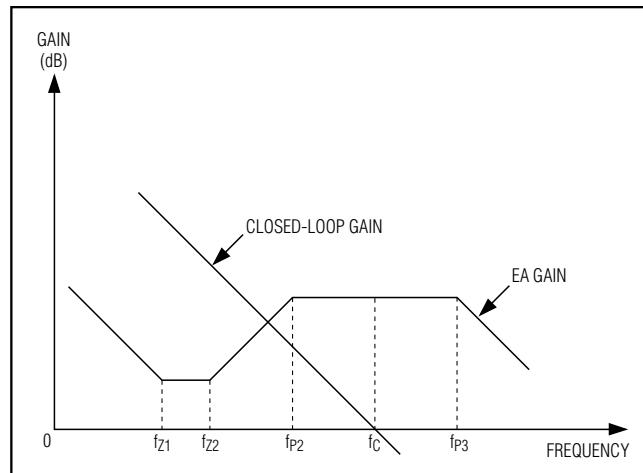


Figure 8. Closed-Loop and Error-Amplifier Gain Plot for Case 2

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Applications Information

PC Board Layout Guide

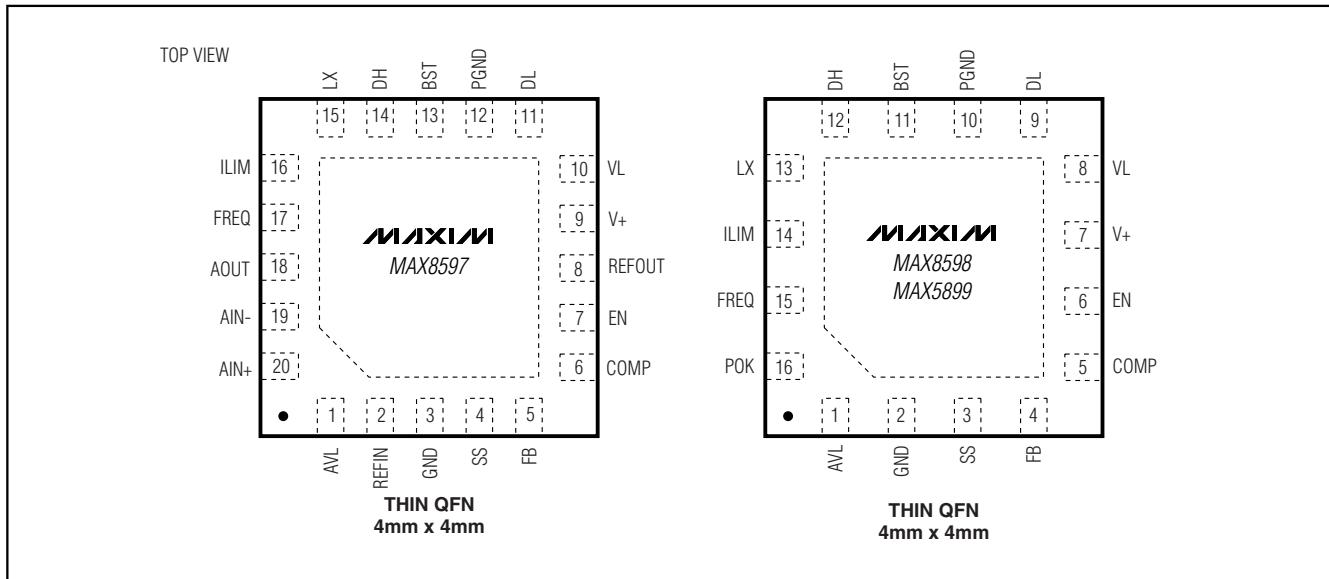
Careful PC board layout is critical to achieve low switching losses and clean, stable operation. The switching power stage requires particular attention. Follow these guidelines for good PC board layout:

- 1) Place the high-side MOSFET close to the low-side MOSFET and arrange them in such a way that the drain of the high-side MOSFET and the source of the low-side MOSFET can be tightly decoupled with a 10 μ F or larger ceramic capacitor. The MOSFETs should also be placed close to the controller IC, preferably not more than 1.5in away from the IC.
- 2) Place the IC's pin decoupling capacitors as close to pins as possible.
- 3) A current-limit setting resistor must be connected from ILIM directly to the drain of the high-side MOSFET.
- 4) Try to keep the LX node connection to the IC pin separate from the connection to the flying boost capacitor.

- 5) Keep the power ground plane (connected to the source of the low-side MOSFET, PGND pin, input and output capacitors' ground, VL decoupling ground) and the signal ground plane (connected to GND pin and the rest of the circuit ground returns) separate. Connect the two ground planes together at the ground of the output capacitor(s).
- 6) Place the RC snubber circuit as close to the low-side MOSFET as possible.
- 7) Keep the high-current paths as short as possible.
- 8) Connect the drains of the MOSFETs to a large copper area to help cool the devices and further improve efficiency and long-term reliability.
- 9) Ensure the feedback connection is short and direct. Place the feedback resistors as close to the IC as possible.
- 10) Route high-speed switching nodes, such as LX, DH, and DL away from sensitive analog areas (FB, COMP, ILIM, AIN+, AIN-).

Refer to the MAX8597/MAX8598/MAX8599 evaluation kit for a sample board layout.

Pin Configurations



Chip Information

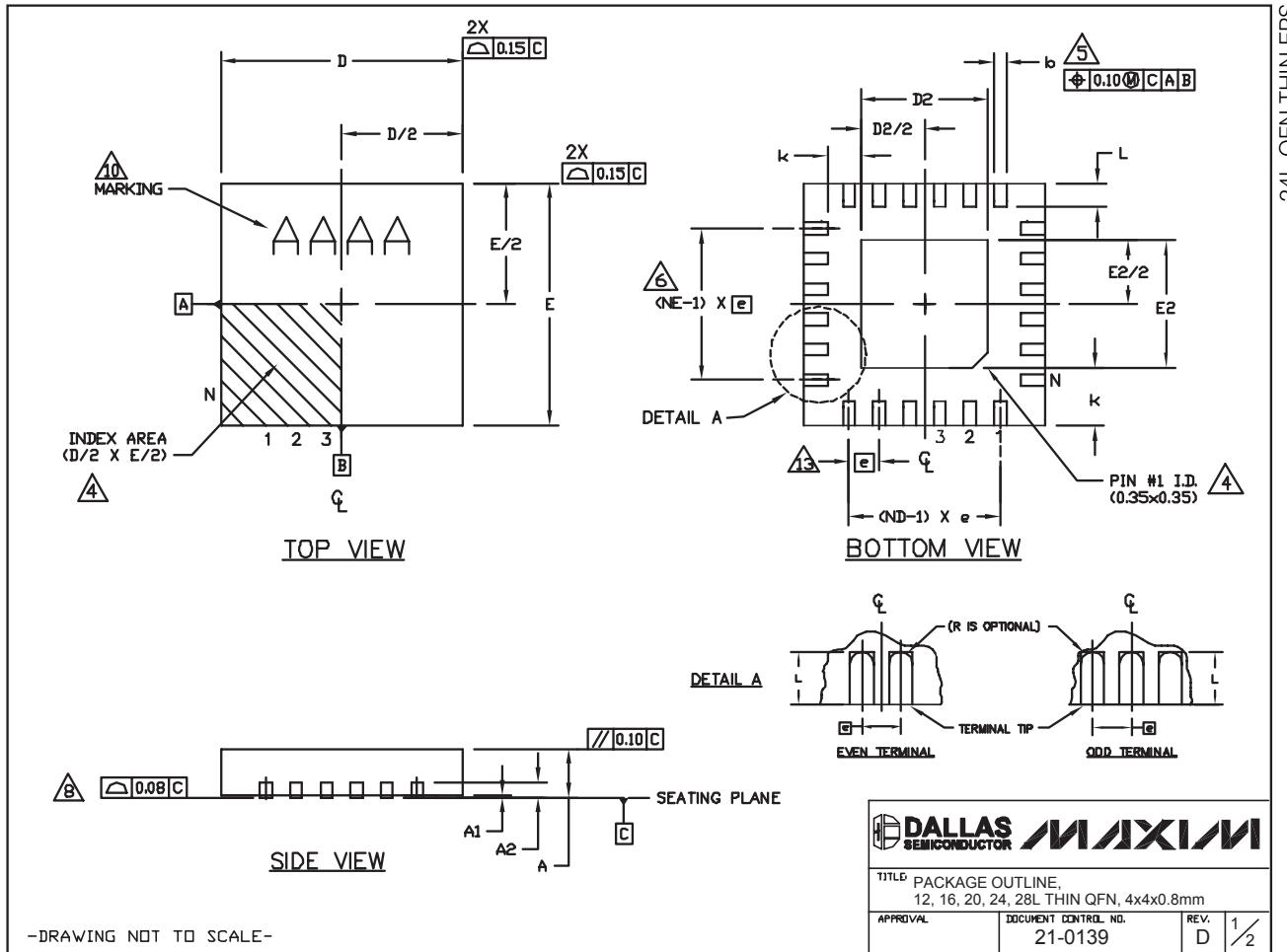
TRANSISTOR COUNT: 4493

PROCESS: BiCMOS

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Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)



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Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)

| COMMON DIMENSIONS | | | | | | | | | | | | EXPOSED PAD VARIATIONS | | | | | | |
|-------------------|-----------|------|------|-----------|------|------|-----------|------|------|-----------|------|------------------------|-----------|------|------|----|----|--------------------|
| PKG CODE | 12L 4x4 | | | 16L 4x4 | | | 20L 4x4 | | | 24L 4x4 | | | 28L 4x4 | | | D2 | E2 | DOWN BONDS ALLOWED |
| | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. | | | |
| A | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | | | |
| A1 | 0.0 | 0.02 | 0.05 | 0.0 | 0.02 | 0.05 | 0.0 | 0.02 | 0.05 | 0.0 | 0.02 | 0.05 | 0.0 | 0.02 | 0.05 | | | |
| A2 | 0.20 REF | | | 0.20 REF | | | | | |
| b | 0.25 | 0.30 | 0.35 | 0.25 | 0.30 | 0.35 | 0.20 | 0.25 | 0.30 | 0.18 | 0.23 | 0.30 | 0.15 | 0.20 | 0.25 | | | |
| D | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | | | |
| E | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | 3.90 | 4.00 | 4.10 | | | |
| e | 0.80 BSC. | | | 0.65 BSC. | | | 0.50 BSC. | | | 0.50 BSC. | | | 0.40 BSC. | | | | | |
| K | 0.25 | - | - | 0.25 | - | - | 0.25 | - | - | 0.25 | - | - | 0.25 | - | - | | | |
| L | 0.45 | 0.55 | 0.65 | 0.45 | 0.55 | 0.65 | 0.45 | 0.55 | 0.65 | 0.30 | 0.40 | 0.50 | 0.30 | 0.40 | 0.50 | | | |
| N | 12 | | | 16 | | | 20 | | | 24 | | | 28 | | | | | |
| ND | 3 | | | 4 | | | 5 | | | 6 | | | 7 | | | | | |
| NE | 3 | | | 4 | | | 5 | | | 6 | | | 7 | | | | | |
| Jedec Ver. | VGG3 | | | VGGC | | | WGDD-1 | | | WGDD-2 | | | WGGE | | | | | |

NOTES:

1. DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS. ANGLES ARE IN DEGREES.
3. N IS THE TOTAL NUMBER OF TERMINALS.
4. THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JEDEC JESD 95-1 SPP-012. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.
5. DIMENSION b APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 mm AND 0.30 mm FROM TERMINAL TIP.
6. ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
7. DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
8. COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
9. DRAWING CONFORMS TO JEDEC MO220, EXCEPT FOR T2444-1, T2444-3, T2444-4 AND T2844-1.
10. MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY.
11. COPLANARITY SHALL NOT EXCEED 0.08mm
12. WARPAGE SHALL NOT EXCEED 0.10mm
13. LEAD CENTERLINES TO BE AT TRUE POSITION AS DEFINED BY BASIC DIMENSION "e", ± 0.05 .

-DRAWING NOT TO SCALE-

| | | |
|--|---|---------------|
|  DALLAS SEMICONDUCTOR |  | |
| TITLE PACKAGE OUTLINE, 12, 16, 20, 24, 28L THIN QFN, 4x4x0.8mm | | |
| APPROVAL | DOCUMENT CONTROL NO. 21-0139 | REV. D 2/2 |

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- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помошь в подборе аналогов, поставка прототипов;
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- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



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