

# ISL1557

xDSL Differential Line Driver

FN7522  
Rev.5.00  
Nov 7, 2019

The [ISL1557](#) is a dual operational amplifier designed for VDSL2 and ADSL line driving in DMT based solutions. This device features a high drive capability of 750mA while consuming only 6mA of supply current per amplifier and operating from a single 4.5V to 12V supply. The driver achieves a typical distortion of -80dBc at 150kHz into a 25Ω load.

The ISL1557 is available in the thermally-enhanced 16 Ld QFN and 10 Ld HMSOP package and is specified for operation across -40°C to +85°C (IRZ, IUEZ) or -40°C to +125°C (FRZ) temperature ranges. The ISL1557 has control pins C0 and C1 for controlling the bias and enable/disable of the outputs. These controls allow for lowering the power to fit the performance/power ratio for the application.

The ISL1557 is ideal for ADSL2+, SDSL, HDSL2, and VDSL line driving applications, including both 14.5dBm and 21dBm applications.

## Related Literature

For a full list of related documents, visit our website

- [ISL1557](#) product page

## Features

- Full-range industrial temperature (FRZ only): -40°C to +125°C
- 21dBm output power capability
- Drives up to 750mA from a +12V supply
- 20V<sub>P-P</sub> differential output drive into 21Ω
- -80dBc typical driver output distortion at full output at 150kHz
- -75dBc typical driver output distortion at 4MHz
- -71dBc typical driver output distortion at 10MHz
- -75dBc typical driver output distortion at 17MHz
- Low quiescent current of 6mA per amplifier
- Supply range
  - ISL1557IRZ, ISL1557FRZ . . . ±2.25V to ±6V, 4.5V to 12V
  - ISL1557IUEZ . . . . . 4.5V to 12V
- 300MHz bandwidth
- Thermal shutdown
- Pb-free (RoHS compliant)

## Applications

- VDSL2 line drivers
- Power line communications line drivers
- ADSL2+ CPE line driving
- G.SHDSL and HDSL2 line drivers

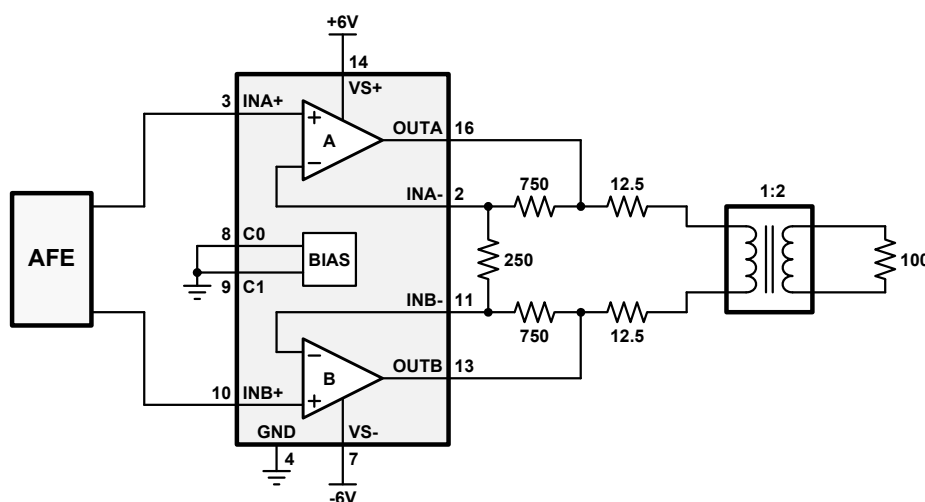
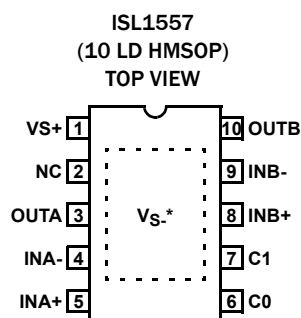


FIGURE 1. TYPICAL OPERATING CIRCUIT



## Pin Descriptions

16 LD QFN (Note 4)	10 LD HMSOP (Note 5)	PIN NAME	FUNCTION
1, 5, 6, 12, 15	2	NC	No Connect
2	4	INA-	Inverting Input of Amplifier A
3	5	INA+	Non-Inverting Input of Amplifier A
4	-	GND	Ground Connect
7	-	VS-	Negative Supply
8	6	CO	Bias Control Pin 0
9	7	C1	Bias Control Pin 1
10	8	INB+	Non-Inverting Input of Amplifier B
11	9	INB-	Inverting Input of Amplifier B
13	10	OUTB	Output of Amplifier B
14	1	VS+	Positive Supply
16	3	OUTA	Output of Amplifier A

**NOTE:**

4. Thermal pad must be connected to negative supply:  $V_{S-}$ . QFN package can be used in single and dual supply applications.
5. Thermal pad must be connected to negative supply:  $V_{S-}$ . HMSOP package can be used in single supply applications only.

**TABLE 1. BIAS MODE CONTROL**

CONTROL INPUTS		BIAS MODES	TYPICAL SUPPLY CURRENT PER AMPLIFIER (mA)
CO (V)	C1 (V)		
0	0	Full	15
0	5	Medium	11
5	0	Low	6.0
5	5	Power Down	0.6

**Absolute Maximum Ratings** ( $T_A = +25^\circ\text{C}$ )

$V_S$ + Voltage to Ground	-0.3V to +13.2V
$V_{IN}$ + Voltage	GND to $V_S$ + 8mA
Current into any Input	8mA
Continuous Output Current	75mA
$C_0$ , $C_1$ to Ground	+6.6V
ESD Rating	
Human Body Model	3kV
Machine Model	250V

**Thermal Information**

Thermal Resistance	$\theta_{JA}$ ( $^\circ\text{C/W}$ )	$\theta_{JC}$ ( $^\circ\text{C/W}$ )
10 Ld HMSOP Package (Notes 6, 7)	62	14
16 Ld QFN Package (Notes 6, 7)	52	14
Ambient Operating Temperature Range		
ISL1557FRZ	-40 $^\circ\text{C}$ to +125 $^\circ\text{C}$	
ISL1557IRZ, ISL1557IUEZ	-40 $^\circ\text{C}$ to +85 $^\circ\text{C}$	
Storage Temperature Range	-60 $^\circ\text{C}$ to +150 $^\circ\text{C}$	
Operating Junction Temperature	+150 $^\circ\text{C}$	
Power Dissipation	See Figure 24 on page 9	
Pb-Free reflow profile	see TB493	

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

**NOTES:**

- $\theta_{JA}$  is measured in free air with the component mounted on a high-effective thermal conductivity test board with "direct attach" features. See TB379.
- For  $\theta_{JC}$ , the "case temp" location is the center of the exposed metal pad on the package underside.

**Electrical Specifications**  $V_S = 12\text{V}$ ,  $R_F = 750\Omega$ ,  $R_{L-DIFF} = 50\Omega$ ,  $T_A = +25^\circ\text{C}$ , unless otherwise specified.

PARAMETER	SYMBOL	CONDITIONS	MIN (Note 8)	TYP	MAX (Note 8)	UNIT
<b>AC PERFORMANCE</b>						
-3dB Bandwidth	BW	$R_F = 499\Omega$ , $A_V = +5$		300		MHz
		$R_F = 750\Omega$ , $A_V = +5$		250		MHz
		$R_F = 750\Omega$ , $A_V = +10$		200		MHz
Total Harmonic Distortion, Differential	THD	$f = 200\text{kHz}$ , $V_O = 16V_{P-P}$ , $R_{L-DIFF} = 100\Omega$	-72	-83		dBc
		$f = 4\text{MHz}$ , $V_O = 2V_{P-P}$ , $R_{L-DIFF} = 100\Omega$		-75		dBc
		$f = 10\text{MHz}$ , $V_O = 2V_{P-P}$ , $R_{L-DIFF} = 100\Omega$		-71		dBc
		$f = 17\text{MHz}$ , $V_O = 2V_{P-P}$ , $R_{L-DIFF} = 100\Omega$		-75		dBc
Slew Rate, Single-Ended	SR	$V_{OUT}$ from -3V to +3V	750	1200		V/ $\mu\text{s}$
<b>DC PERFORMANCE</b>						
Offset Voltage Common-Mode	$V_{OS\_CM}$		-40		+40	mV
Offset Voltage Differential Mode	$V_{OS\_DM}$		-7.5		+7.5	mV
Differential Transimpedance	$R_{OL}$	$V_{OUT} = 12V_{P-P}$ differential, unloaded		3.0		M $\Omega$
<b>INPUT CHARACTERISTICS</b>						
Non-Inverting Input Bias Current	$I_{B^+}$		-7.0		+7.0	$\mu\text{A}$
Inverting Input Bias Current Differential Mode	$I_{B^- DM}$		-75	3	+75	$\mu\text{A}$
Input Noise Voltage	$e_N$			6		$\text{nV}/\sqrt{\text{Hz}}$
-Input Noise Current	$i_N$			13		$\text{pA}/\sqrt{\text{Hz}}$
<b>OUTPUT CHARACTERISTICS</b>						
Loaded Output Swing (Single-Ended)	$V_{OUT}$	$V_S = \pm 6\text{V}$ , $R_{L-DIFF} = 50\Omega$ (FRZ)	$\pm 4.75$	$\pm 5.0$		V
		$V_S = \pm 6\text{V}$ , $R_{L-DIFF} = 20\Omega$ (FRZ)	$\pm 4.20$	$\pm 4.7$		V
		$V_S = \pm 6\text{V}$ , $R_{L-DIFF} = 50\Omega$ (IRZ, IUEZ)	$\pm 4.85$	$\pm 5.0$		V
		$V_S = \pm 6\text{V}$ , $R_{L-DIFF} = 20\Omega$ (IRZ, IUEZ)	$\pm 4.4$	$\pm 4.7$		V
Output Current	$I_{OUT}$	$R_L = 0\Omega$		1000		mA

**Electrical Specifications (continued)**  $V_S = 12V$ ,  $R_F = 750\Omega$ ,  $R_{L-DIFF} = 50\Omega$ ,  $T_A = +25^\circ C$ , unless otherwise specified.

PARAMETER	SYMBOL	CONDITIONS	MIN (Note 8)	TYP	MAX (Note 8)	UNIT
<b>SUPPLY</b>						
Supply Voltage	$V_S$	Single supply	4.5		13.2	V
Positive Supply Current per Amplifier	$I_{S+}$ (Full Bias)	All outputs at 0V, $C_0 = C_1 = 0V$	13	15	19	mA
Positive Supply Current per Amplifier	$I_{S+}$ (Medium Bias)	All outputs at 0V, $C_0 = 5V$ , $C_1 = 0V$		11		mA
Positive Supply Current per Amplifier	$I_{S+}$ (Low Bias)	All outputs at 0V, $C_0 = 0V$ , $C_1 = 5V$		6.0		mA
Positive Supply Current per Amplifier	$I_{S+}$ (Power-down)	All outputs at 0V, $C_0 = C_1 = 5V$		0.6	1.0	mA
$C_0$ , $C_1$ Input Current, High	$I_{INH}$ , $C_0$ or $C_1$	$C_0$ , $C_1 = 6V$	100	175	250	$\mu A$
$C_0$ , $C_1$ Input Current, Low	$I_{INL}$ , $C_0$ or $C_1$	$C_0$ , $C_1 = 0V$	-5		+5	$\mu A$
$C_0$ , $C_1$ Input Voltage, High	$V_{INH}$ , $C_0$ or $C_1$		2.0			V
$C_0$ , $C_1$ Input Voltage, Low	$V_{INL}$ , $C_0$ or $C_1$				0.8	V

**NOTE:**

8. Compliance to datasheet limits is assured by one or more methods: production test, characterization and/or design. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore:  $T_J = T_C = T_A$

## Typical Performance Curves

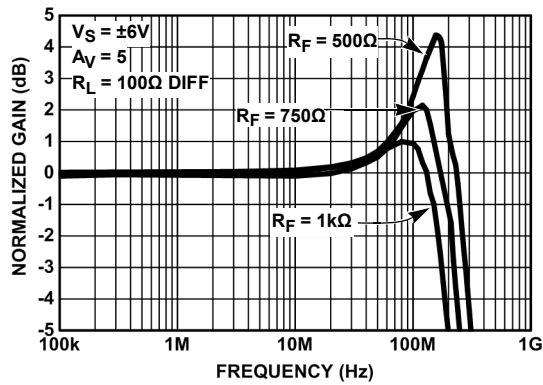


FIGURE 2. DIFFERENTIAL FREQUENCY RESPONSE WITH VARIOUS  $R_F$  (FULL BIAS MODE)

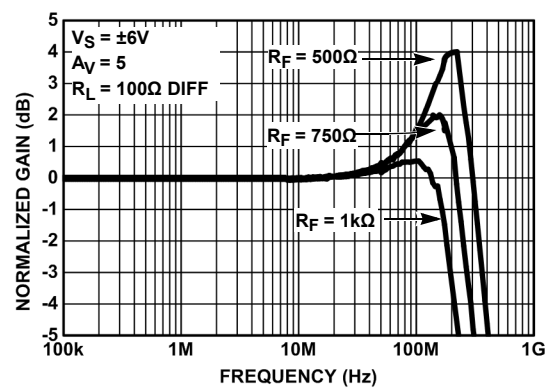


FIGURE 3. DIFFERENTIAL FREQUENCY RESPONSE WITH VARIOUS  $R_F$  (MEDIUM BIAS MODE)

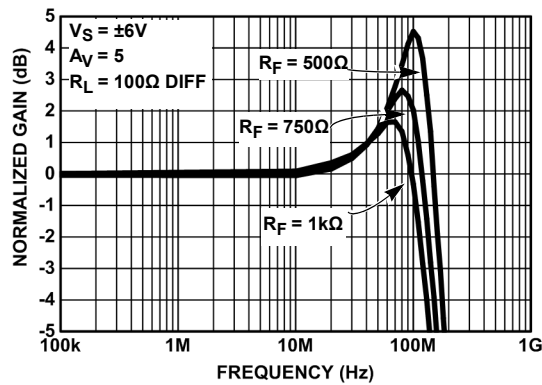


FIGURE 4. DIFFERENTIAL FREQUENCY RESPONSE WITH VARIOUS  $R_F$  (LOW BIAS MODE)

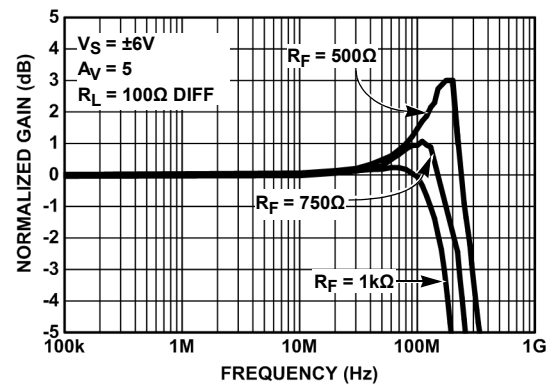


FIGURE 5. DIFFERENTIAL FREQUENCY RESPONSE WITH VARIOUS  $R_F$  (FULL BIAS MODE)

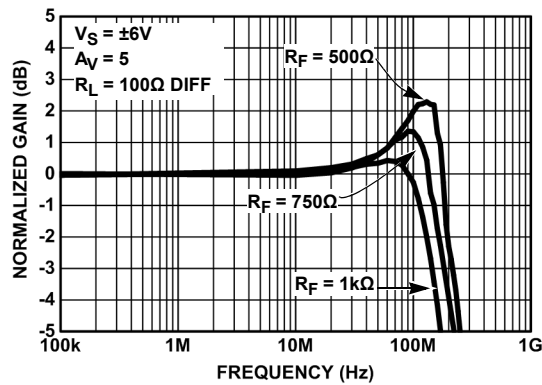


FIGURE 6. DIFFERENTIAL FREQUENCY RESPONSE WITH VARIOUS  $R_F$  (MEDIUM BIAS MODE)

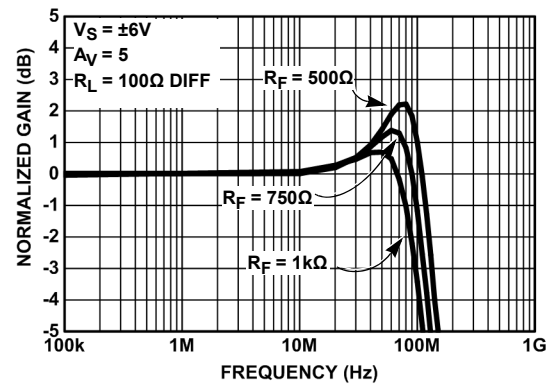


FIGURE 7. DIFFERENTIAL FREQUENCY RESPONSE WITH VARIOUS  $R_F$  (LOW BIAS MODE)

## Typical Performance Curves (Continued)

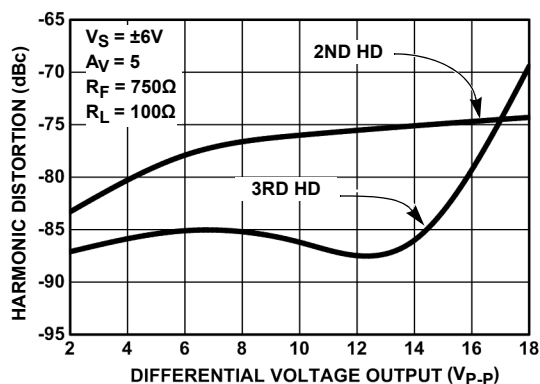


FIGURE 8. HARMONIC DISTORTION AT 2MHz

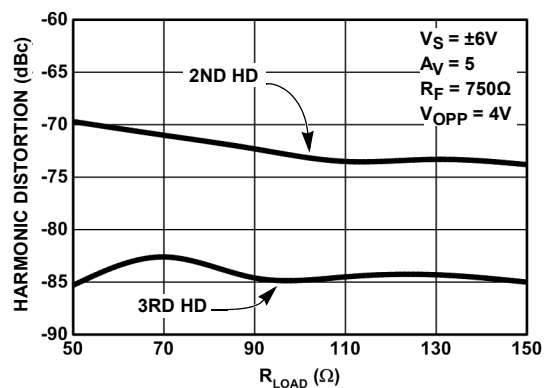
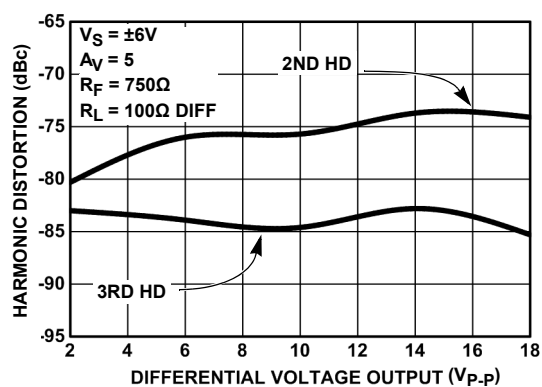
FIGURE 9. 2ND AND 3RD HARMONIC DISTORTION vs  $R_{LOAD}$  AT 2MHz

FIGURE 10. HARMONIC DISTORTION AT 3MHz

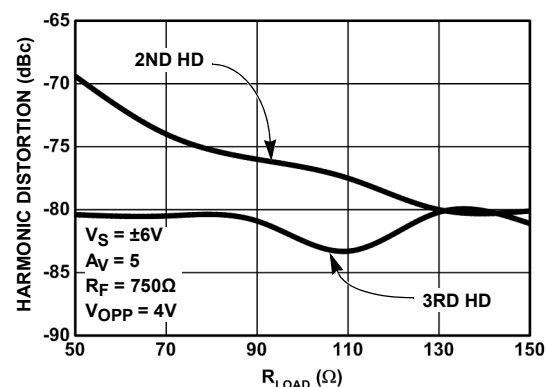
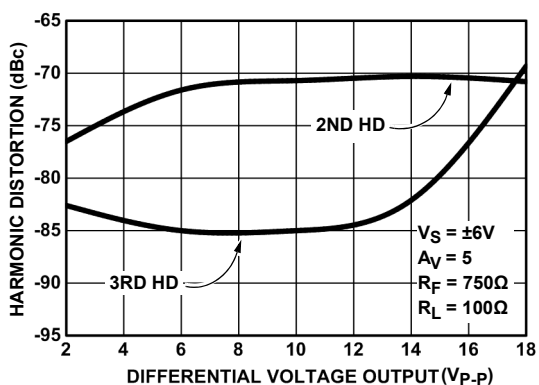
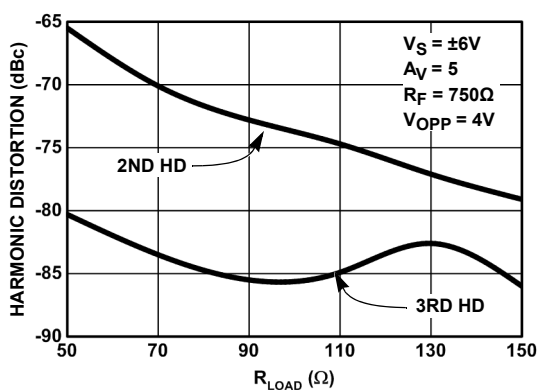
FIGURE 11. 2ND AND 3RD HARMONIC DISTORTION vs  $R_{LOAD}$  AT 3MHz

FIGURE 12. HARMONIC DISTORTION AT 5MHz

FIGURE 13. 2ND AND 3RD HARMONIC DISTORTION vs  $R_{LOAD}$  AT 5MHz

## Typical Performance Curves (Continued)

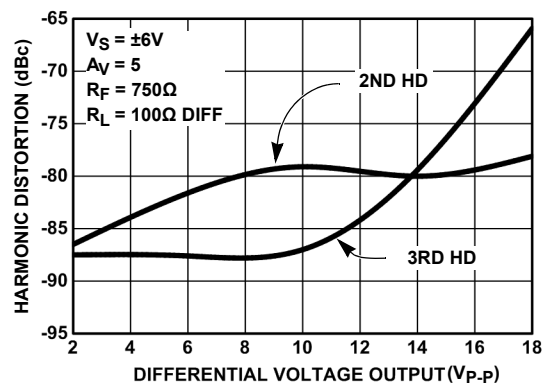


FIGURE 14. HARMONIC DISTORTION AT 10MHz

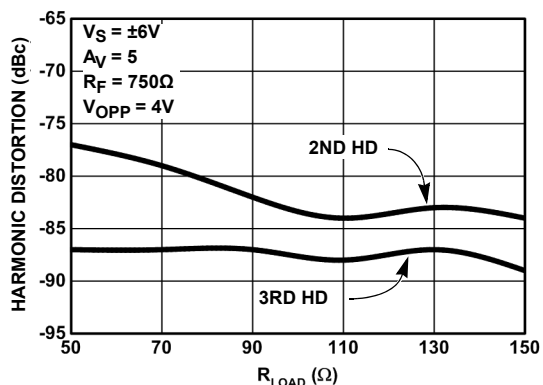
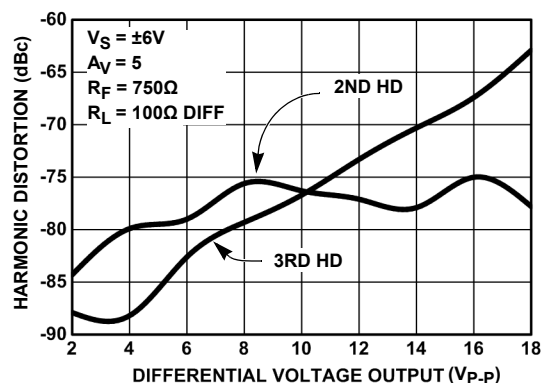
FIGURE 15. 2ND AND 3RD HARMONIC DISTORTION vs  $R_{LOAD}$  AT 10MHz

FIGURE 16. HARMONIC DISTORTION AT 17MHz

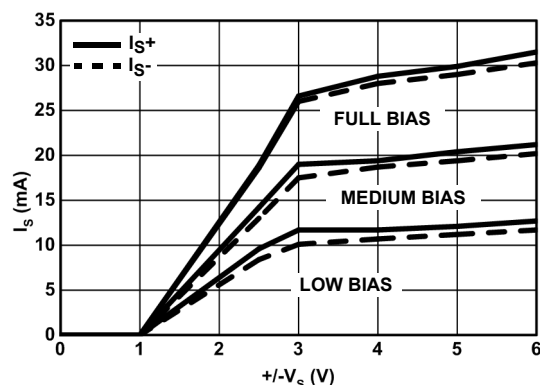
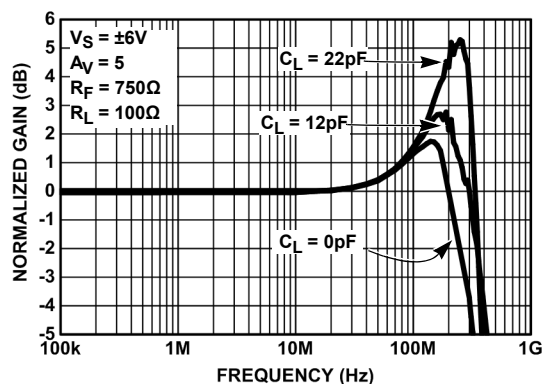
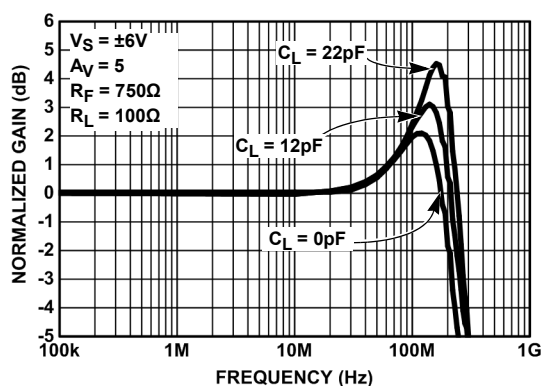


FIGURE 17. SUPPLY CURRENT vs SUPPLY VOLTAGE

FIGURE 18. FREQUENCY RESPONSE WITH VARIOUS  $C_L$  (FULL BIAS MODE)FIGURE 19. FREQUENCY RESPONSE vs VARIOUS  $C_L$  (MEDIUM BIAS MODE)

## Typical Performance Curves (Continued)

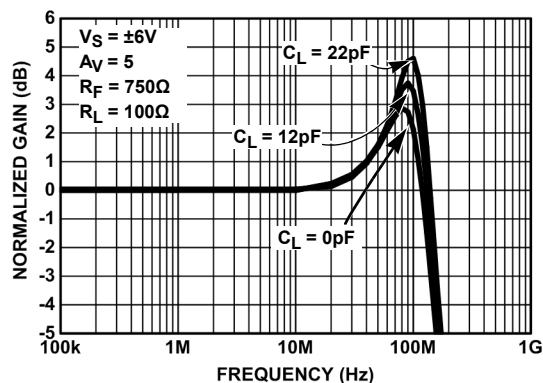


FIGURE 20. FREQUENCY RESPONSE WITH VARIOUS  $C_L$  (LOW BIAS MODE)

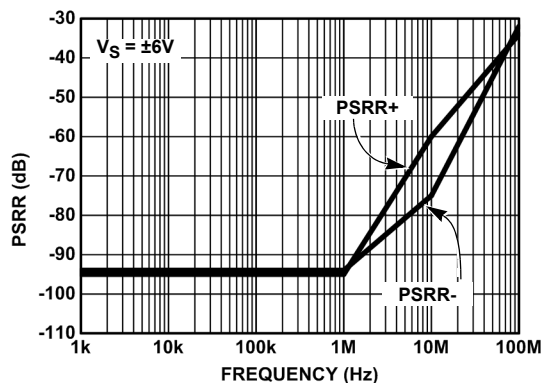


FIGURE 21. PSRR vs FREQUENCY

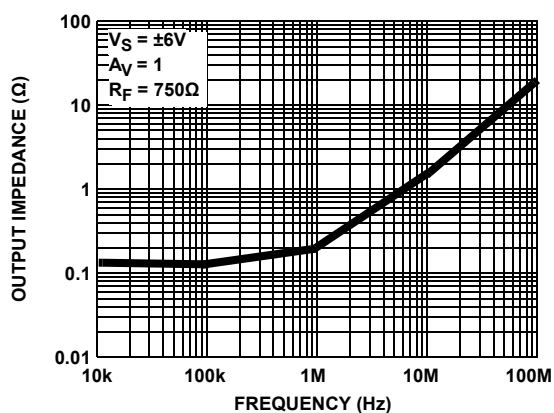


FIGURE 22. OUTPUT IMPEDANCE vs FREQUENCY

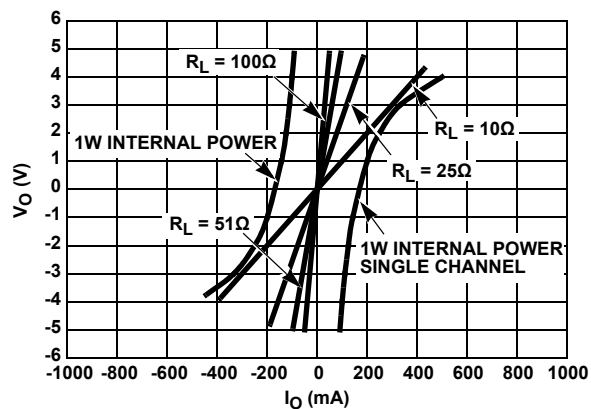


FIGURE 23. OUTPUT VOLTAGE AND CURRENT LIMITATIONS

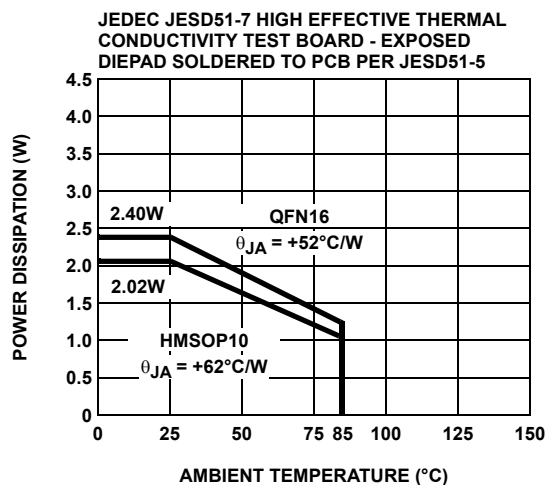


FIGURE 24. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE

## Applications Information

### Product Description

The ISL1557 is a dual operational amplifier designed for line driving in DMT ADSL2+ and VDSL solutions. It is a dual current mode feedback amplifier with low distortion while drawing moderately low supply current. It is built using the Renesas proprietary complimentary bipolar process and is offered in industry standard pinouts. Due to the current feedback architecture, the ISL1557 closed-loop 3dB bandwidth is dependent on the value of the feedback resistor. First, select the desired bandwidth by choosing the feedback resistor,  $R_F$ , then set the gain by choosing the gain resistor,  $R_G$ . The curves at the beginning of the "Typical Performance Curves" section, on [page 6](#), show the effect of varying both  $R_F$  and  $R_G$ . The 3dB bandwidth is somewhat dependent on the power supply voltage.

### Power Supply Bypassing and Printed Circuit Board Layout

As with any high frequency device, good printed circuit board layout is necessary for optimum performance. Ground plane construction is highly recommended. Lead lengths should be as short as possible (below 0.25"). The power supply pins must be well bypassed to reduce the risk of oscillation. A 4.7 $\mu$ F tantalum capacitor in parallel with a 0.1 $\mu$ F ceramic capacitor is adequate for each supply pin. During power-up, it is necessary to limit the slew rate of the rising power supply to within 1V/ $\mu$ s. If the power supply rising time is undetermined, a series 10 $\Omega$  resistor on the power supply line can be used to ensure the proper power supply rise time.

For good AC performance, parasitic capacitances should be kept to a minimum, especially at the inverting input. This implies keeping the ground plane away from this pin. Carbon resistors are acceptable, but avoid using wire-wound resistors because of their parasitic inductance. Similarly, capacitors should be low inductance for best performance.

### Capacitance at the Inverting Input

Due to the topology of the current feedback amplifier, stray capacitance at the inverting input will effect the AC and transient

performance of the ISL1557 when operating in the non-inverting configuration.

In the inverting gain mode, added capacitance at the inverting input has little effect because this point is at a virtual ground and stray capacitance is therefore not "detected" by the amplifier.

### Feedback Resistor Values

The ISL1557 has been designed and specified with  $R_F = 750\Omega$  for  $A_V = +5$ . This value of feedback resistor yields extremely flat frequency response with 1dB peaking out to 250MHz. As with all current feedback amplifiers, wider bandwidth, at the expense of slight peaking, can be obtained by reducing the value of the feedback resistor. Inversely, larger values of feedback resistor will cause rolloff to occur at a lower frequency. See the curves in the "Typical Performance Curves" section, beginning on [page 6](#), which shows 3dB bandwidth and peaking vs frequency for various feedback resistors and various supply voltages.

### Bandwidth vs Temperature

Whereas many amplifier's supply current and consequently 3dB bandwidth drop off at high temperature, the ISL1557 is designed to have little supply current variations with temperature. An immediate benefit is the 3dB bandwidth does not drop off drastically with temperature.

### Supply Voltage Range

The ISL1557IRZ is designed to operate with supply voltages from  $\pm 2.25V$  to  $\pm 6V$  nominal. Optimum bandwidth, slew rate, and video characteristics are obtained at higher supply voltages.

### Single Supply Operation

If a single supply is desired, values from +4.5V to +12V nominal can be used as long as the input common mode range is not exceeded. When using a single supply, be sure to either:

- DC bias the inputs at an appropriate common mode voltage and AC couple the signal ([Figure 25](#)), or:
- Ensure the driving signal is within the common mode range of the ISL1557. The ISL1557IUEZ must be used in single supply applications.

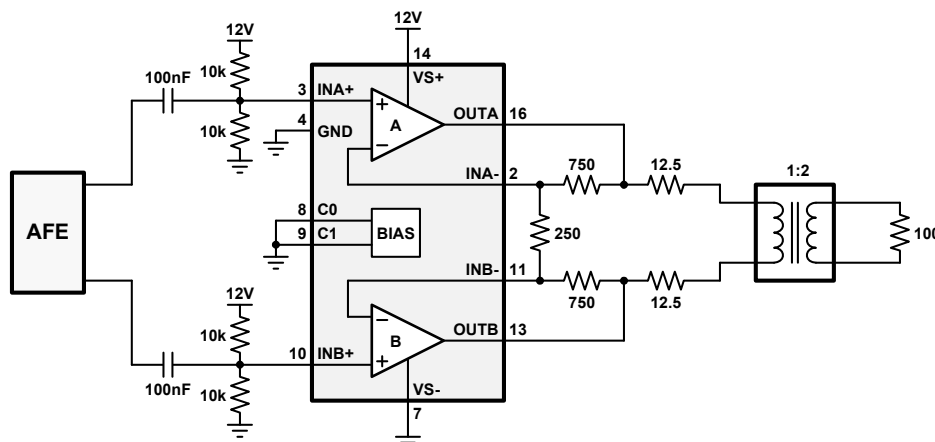


FIGURE 25. SINGLE SUPPLY OPERATION WITH INPUT COMMON-MODE BIASING

## ADSL CPE Applications

The ISL1557 is designed as a line driver for ADSL CPE modems. It is capable of outputting 450mA of output current with a typical supply voltage headroom of 1.3V. It can achieve -85dBc of distortion at low 7.1mA of supply current per amplifier.

The average line power requirement for the ADSL CPE application is 14.5dBm (28mW) into a 100Ω line. The average

line voltage is 1.67V<sub>RMS</sub>. The ADSL DMT peak to average ratio (crest factor) of 5.3 implies peak voltage of 7.5V into the line. Using a differential drive configuration and transformer coupling with standard back termination, a transformer ratio of 1:2 is selected. The circuit configuration is shown in [Figure 26](#).

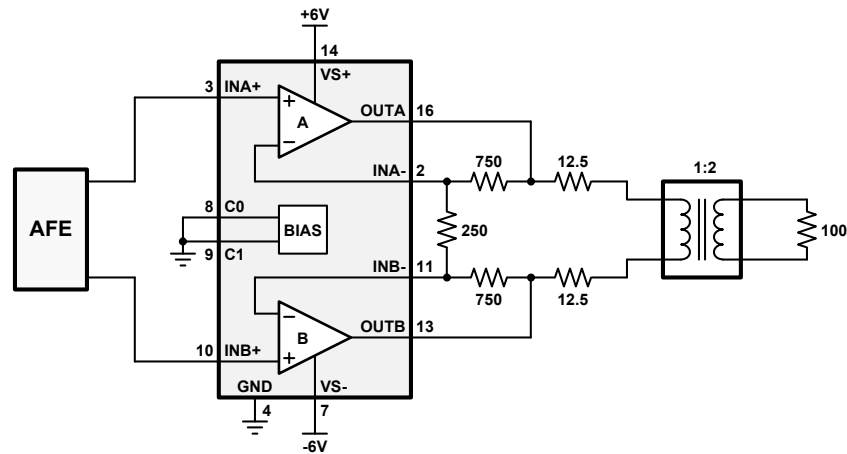


FIGURE 26. ADSL CPE DRIVER

## Revision History

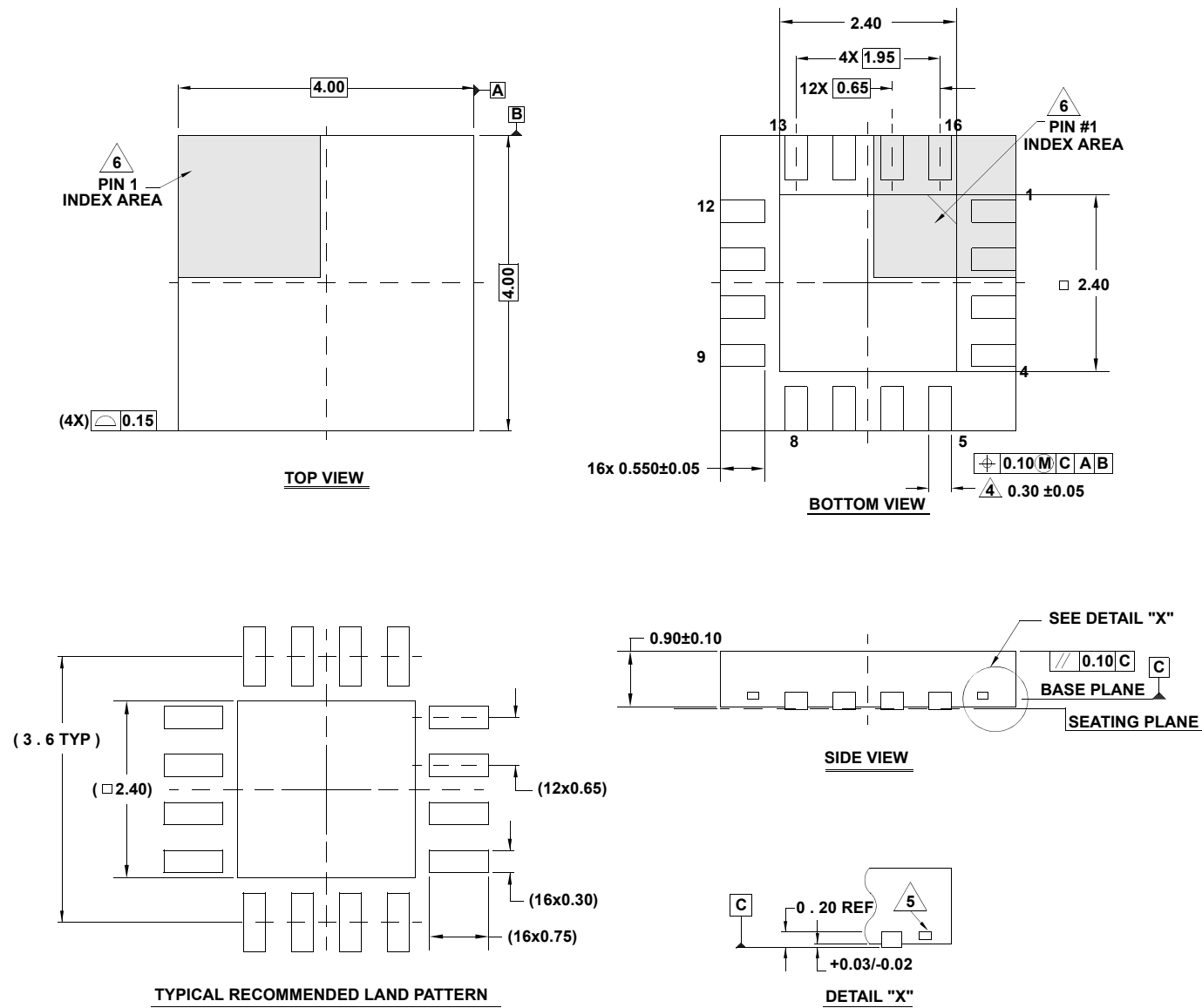
The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please visit our website to make sure you have the latest revision.

DATE	REVISION	CHANGE
Nov 7, 2019	FN7522.5	Updated links throughout. Replaced POD MDP0050 with POD M10.118B in the ordering information table and the Package Outline Drawings section. Updated disclaimer
May 2, 2018	FN7522.4	Added Figure 1. Added ISL1557FRZ part information throughout document. Added Pin Description table Added Table 1. Added Theta JA and JC information under the Thermal Information section. Updated Figures 8 through 16. Added Figure 25. Updated Figure 26.
Apr 6, 2018	FN7522.3	Added Related Literature section. Updated Ordering information table. Added Note 3. Moved and updated Note 4 to end of EC table. Added Revision History. Replaced POD MDP0046 (multiple lead counts) with L16.4x4H POD. Updated Disclaimer.

## Package Outline Drawings

**L16.4x4H**  
**16 LEAD QUAD FLAT NO-LEAD PLASTIC PACKAGE**  
**Rev 0, 1/12**

For the most recent package outline drawing, see [L16.4x4H](#).



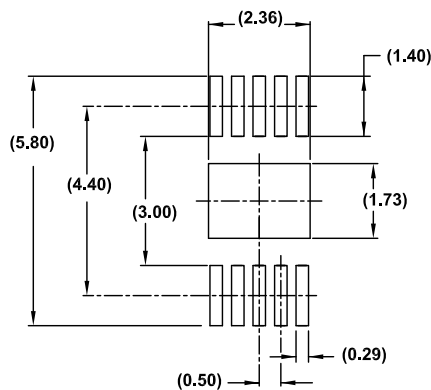
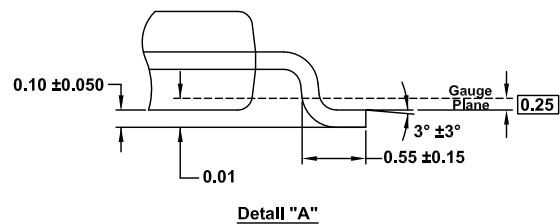
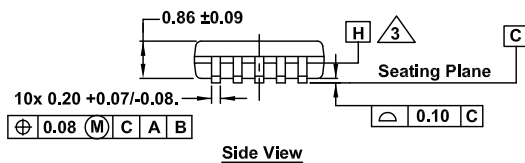
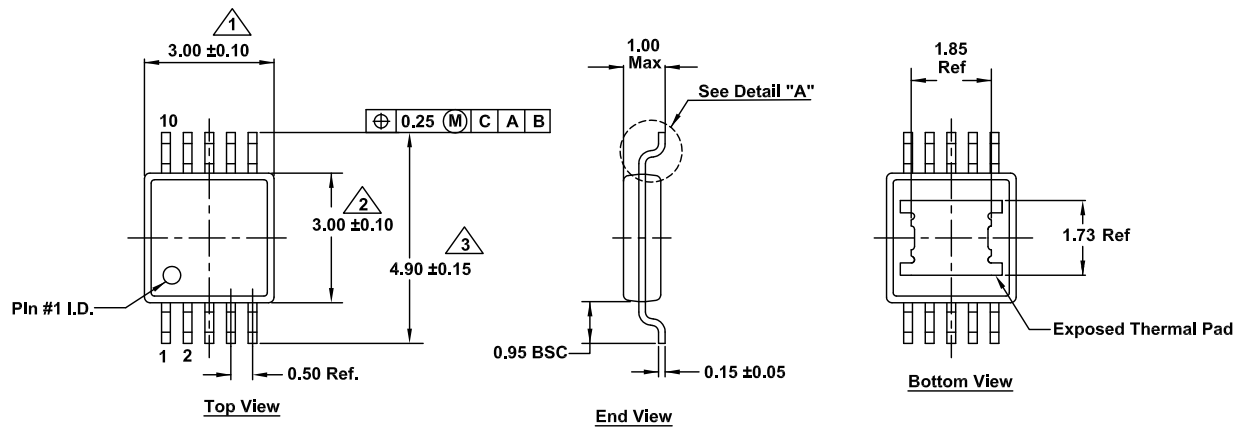
**NOTES:**

1. Dimensions are in millimeters.  
Dimensions in ( ) for Reference Only.
2. Dimensioning and tolerancing conform to ASME Y14.5m-1994.
3. Unless otherwise specified, tolerance : Decimal  $\pm 0.05$
4. Dimension applies to the metallized terminal and is measured between 0.15mm and 0.30mm from the terminal tip.
5. Tiebar shown (if present) is a non-functional feature.
6. The configuration of the pin #1 identifier is optional, but must be located within the zone indicated. The pin #1 identifier may be either a mold or mark feature.

## M10.118B

10 Lead Heatsink Mini Small Outline Plastic Package (HMSOP, Heatsink MSOP)

Rev 2, 10/19

For the most recent package outline drawing, see [M10.118B](#).

Recommended Land Pattern

## Notes:

1. Plastic or metal protrusions of 0.15 maximum per side are not included.
2. Plastic interlead protrusions of 0.25 maximum per side are not included.
3. Package body length and width dimensions are measured at Datum Plane "H".
4. Dimensioning and tolerancing conform to ASME Y14.5M-1994.
5. Dimensions are in millimeters.  
Dimensions in ( ) for reference only.

## Notice

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