

# MACX MCR-EX-SL-RPSS-2I-2I



## 2-channel repeater power supply, Ex i

Data sheet  
105571\_en\_00

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### 1 Description

The 2-channel repeater power supply is designed for the operation of intrinsically safe (Ex-i) 2-wire measuring transducers installed in the Ex area.

The 2-wire measuring transducers are supplied with power and analog 4...20 mA measured values from the Ex area are transferred to the non-Ex area.

The output of the module is active.

The analog measured value on the Ex or non-Ex side can be overlayed with digital (HART) communication signals and transmitted bidirectionally.

Sockets are integrated into the COMBICON connectors for connecting HART communicators.

The module is suitable for safety-related applications up to SIL 3 according to IEC/EN 61508.

#### Features

- 2-channel
- 4 ... 20 mA input, intrinsically safe, [Ex ia], powered
- 4 ... 20 mA output, active
- HART-compatible
- Error indication according to NAMUR NE 43
- Up to SIL 3 according to IEC/EN 61508
- 5-way electrical isolation
- Safe electrical isolation between inputs and outputs, supply
- Power supply possible via DIN rail connector
- Installation in Ex zone 2 permitted
- Plug-in connection terminal blocks, either screw or spring-cage connection technology (Push-in technology)
- Housing width of 12.5 mm
- Low power dissipation
- High transmission accuracy



#### **WARNING: Explosion hazard**

The device is an associated item of equipment (category 1) with “intrinsic safety” protection type and can be installed in zone 2 potentially explosive areas as a category 3 device. It meets the requirements of EN 60079-0:2009, EN 60079-11:2012, and EN 60079-15:2010.

When installing and operating the device, the applicable safety directives (including national safety directives), accident prevention regulations, as well as general technical regulations must be observed.



Make sure you always use the latest documentation.

It can be downloaded from the product at [phoenixcontact.net/products](http://phoenixcontact.net/products).

This data sheet is valid for all products listed on the following page:

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### 3 Ordering data

| Description  | Type                           | Order No. | Pcs. / Pkt. |
|--|--------------------------------|-----------|-------------|
| Ex i measuring transducer repeater power supply, 2-channel; HART-transparent. Supplies Ex i 2-wire measuring transducers and transmits the 4 - 20 mA signal from the Ex area to the safe area. 5-way electrical isolation, up to SIL 3 according to IEC 61508; screw connection.       | MACX MCR-EX-SL-RPSS-2I-2I      | 2865382   | 1           |
| Ex i measuring transducer repeater power supply, 2-channel; HART-transparent. Supplies Ex i 2-wire measuring transducers and transmits the 4 - 20 mA signal from the Ex area to the safe area. 5-way electrical isolation, up to SIL 3 according to IEC 61508; spring-cage connection. | MACX MCR-EX-SL-RPSS-2I-2I-SP   | 2924676   | 1           |
| Accessories  | Type                           | Order No. | Pcs. / Pkt. |
| DIN rail connector for DIN rail mounting. Universal for TBUS housing. Gold-plated contacts, 5-pos. Plug component  | ME 6,2 TBUS-2 1,5/5-ST-3,81 GN | 2869728   | 10          |
| Power and error message module   | MACX MCR-PTB                   | 2865625   | 1           |
| Power and error message module, spring-cage terminal blocks  | MACX MCR-PTB-SP                | 2924184   | 1           |

### 4 Technical data

| Input data                               |   |
|--|---|
| Description of the input                 | Intrinsically safe  |
| Current input signal                     | 4 mA ... 20 mA  |
| Transmitter supply voltage               | > 16 V (at 20 mA)   |
| Underload/overload signal range          | 0 mA ... 24 mA  |
| Output                                   |   |
| Output description                       | Current output  |
| Current output signal                    | 4 mA ... 20 mA (active)   |
| Transmission Behavior                    | 1:1 to input signal   |
| Load/output load current output          | ≤ 450 Ω (20 mA)<br>≤ 375 Ω (24 mA)  |
| Output behavior in the event of an error | < 3.6 mA (In the event of cable break at the input (as per NE 43))<br>> 22.5 mA (In the event of cable short circuit at the input (as per NE 43)) |
| Underload/overload signal range          | 0 mA ... 24 mA  |
| Supply                                   |   |
| Nominal supply voltage                   | 24 V DC   |
| Supply voltage range                     | 19.2 V DC ... 30 V DC (24 V DC (-20% ... +25%))   |
| Max. current consumption                 | < 100 mA (24 V / 20 mA)   |
| Power loss                               | < 1.4 W (at 24 V DC / 20 mA)  |
| General data                             |   |
| HART function                            | Yes   |
| Protocols supported                      | HART  |
| Signal bandwidth                         | as per HART specifications  |
| Transmission error, typical              | < 0.05 % (of final value)   |
| Maximum transmission error               | < 0.1 % (of final value)  |
| Maximum temperature coefficient          | < 0.01 %/K  |
| Step response (10-90%)                   | < 1.3 ms (for 4 mA ... 20 mA step)  |
| Degree of protection                     | IP20  |
| Inflammability class according to UL 94  | V0  |

**General data [...]**

|                        |                            |
|------------------------|----------------------------|
| Surge voltage category | II                         |
| Pollution degree       | 2                          |
| Diameter Test socket   | 2.3 mm                     |
| Status display         | Green LED (supply voltage) |
| Dimensions W / H / D   | 12.5 mm / 99 mm / 114.5 mm |
| Type of housing        | PA 66-FR green             |

**Connection data****Screw connection****Spring-cage connection**

|                                   |   |   |
|-----------------------------------|---|---|
| Conductor cross section, solid    | 0.2 mm <sup>2</sup> ... 2.5 mm <sup>2</sup> | 0.2 mm <sup>2</sup> ... 1.5 mm <sup>2</sup> |
| Conductor cross section, stranded | 0.2 mm <sup>2</sup> ... 2.5 mm <sup>2</sup> | 0.2 mm <sup>2</sup> ... 1.5 mm <sup>2</sup> |
| Conductor cross section AWG/kcmil | 24 ... 14                                   | 24 ... 16                                   |
| Stripping length                  | 7 mm  | 8 mm  |
| Tightening torque                 | 0.5 Nm ... 0.6 Nm                           |   |

**Ambient conditions**

|  |  |
|--|--|
| Ambient temperature (operation)          | -20 °C ... 60 °C (Any mounting position) |
| Ambient temperature (storage/transport)  | -40 °C ... 80 °C                         |
| Permissible humidity (operation)         | 10 % ... 95 % (non-condensing)           |
| Maximum altitude for use above sea level | ≤ 2000 m                                 |

**Electrical isolation**

|  |                      |
|--|----------------------|
| Input/output, power supply   |                      |
| Rated insulation voltage (surge voltage category II; pollution degree 2, safe isolation as per EN 61010-1) | 300 V <sub>rms</sub> |
| 50 Hz, 1 min., test voltage  | 2.5 kV               |
| Input/output   |                      |
| Peak value in accordance with EN 60079-11  | 375 V                |
| Input/power supply   |                      |
| Peak value in accordance with EN 60079-11  | 375 V                |
| Output 1/output 2/ power supply  |                      |
| 50 Hz, 1 min., test voltage  | 1.5 kV               |

**Safety data as per ATEX**

|   |                     |
|---|---------------------|
| Max. output voltage U <sub>o</sub>  | 25.2 V              |
| Max. output current I <sub>o</sub>  | 93 mA               |
| Max. output power P <sub>o</sub>  | 587 mW              |
| Group ( Max. external inductivity L <sub>o</sub> / Max. external capacitance C <sub>o</sub> ) | IIB : 4 mH / 820 nF |
|   | IIC : 2 mH / 107 nF |
| Safety-related maximum voltage U <sub>m</sub>   | 253 V AC (125 V DC) |

**Conformance with EMC Directive 2004/108/EC**

Noise immunity according to EN 61000-6-2  
When being exposed to interference, there may be minimal deviations.

Noise emission according to EN 61000-6-4

**Conformance / approvals**

|                              |  |
|------------------------------|--|
| Conformance                  | CE-compliant, additionally EN 61326  |
| ATEX ( BVS 13 ATEX E 001 X ) | <div> <div>Ex</div> <div>II (1) G [Ex ia Ga] IIC/IIB</div> </div> <div> <div>Ex</div> <div>II (1) D [Ex ia Da] IIIC</div> </div> <div> <div>Ex</div> <div>II 3(1) G Ex nA [ia Ga] IIC T4 Gc</div> </div> |
| IECEx ( IECEx BVS 13.0007X ) | <div>[Ex ia Ga] IIC/IIB</div> <div>[Ex ia Da] IIIC</div> <div>Ex nA [ia Ga] IIC T4 Gc</div>  |
| Functional safety (SIL)      | SIL 3  |

## 5 Safety regulations and installation notes

### 5.1 Installation notes

- The device is a piece of equipment (category 1) which belongs to the "Intrinsic Safety" ignition protection class and can be installed in Ex zone 2 as a category 3 device. It meets the requirements of EN 60079-0:2012, EN 60079-11:2012, EN 60079-15:2010, IEC 60079-0 ed. 6.0, IEC 60079-11 ed. 6.0, and IEC 60079-15 ed. 4.0.
- Installation, operation, and maintenance may only be carried out by qualified electricians. Follow the installation instructions as described. When installing and operating the device, the applicable regulations and safety directives (including national safety directives), as well as general technical regulations, must be observed. For the safety technology data, see this packing slip and the certificates (EC examination certificate and other approvals if appropriate).
- The device must not be opened or modified. Do not repair the device yourself, replace it with an equivalent device. Repairs may only be carried out by the manufacturer. The manufacturer is not liable for damage resulting from violation.
- The IP20 protection (IEC 60529/EN 60529) of the device is intended for use in a clean and dry environment. The device must not be subject to mechanical strain and/or thermal loads, which exceed the limits described.
- The device complies with the EMC regulations for industrial areas (EMC class A). When using the device in residential areas, it may cause radio interference.

### 5.2 Intrinsic safety

- The device is approved for intrinsically safe (Ex-i) circuits up to Ex zone 0 (gas) and Ex zone 20 (dust). The safety technology values for intrinsically safe equipment and the connecting lines must be observed for the hook-up process (IEC/EC 60079-14) and the values specified in this installation note and/or the EC examination certificate must be observed.
- When carrying out measurements on the intrinsically safe side, observe the relevant regulations regarding the connection of intrinsically safe equipment. Use only these approved measuring devices in intrinsically safe circuits.
- If the device was used in circuits which are not intrinsically safe, it is forbidden to use it again in intrinsically safe circuits. Label the device clearly as being not intrinsically safe.

### 5.3 Installation in Zone 2

- Observe the specified conditions for use in potentially explosive areas! Install the device in a suitable approved housing with a minimum of IP54 protection) that meets the requirements of EN 60079-15. Observe the requirements of EN 60079-14.
- In potentially explosive areas, terminals may only be snapped onto or off the DIN rail connector and wires may only be connected or disconnected when the power is switched off.
- The device must be stopped and immediately removed from the Ex area if it is damaged, was subject to an impermissible load, stored incorrectly or if it malfunctions.

### 5.4 Safety-related applications (SIL)

When using the device in safety-related applications, observe the instructions in "Safety-related applications", as the requirements differ for safety-related functions.

## 6 Installation



### NOTE: Electrostatic discharge

The device contains components that can be damaged or destroyed by electrostatic discharge. When handling the device, observe the necessary safety precautions against electrostatic discharge (ESD) according to EN 61340-5-1 and IEC 61340-5-1.

### 6.1 Structure

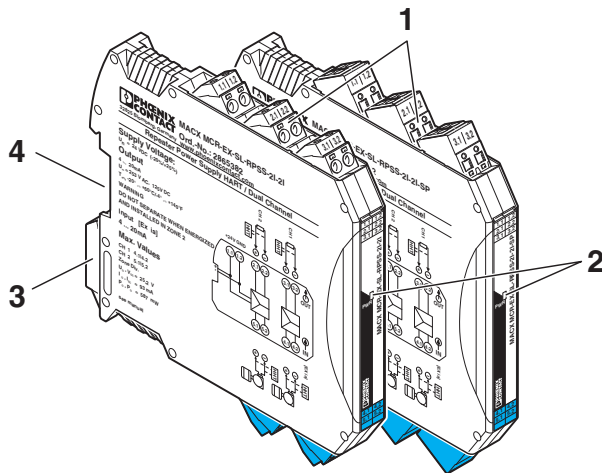


Bild 1 Structure

- 1 Plug-in COMBICON screw or spring-cage terminal block with integrated test socket
- 2 Green "PWR" LED, power supply
- 3 Snap-on foot for DIN rail mounting
- 4 Connection option for DIN rail connector

### 6.2 Basic circuit diagram with connection terminal blocks

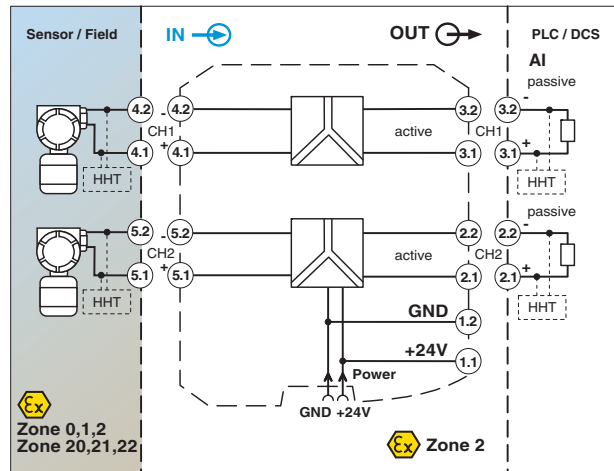


Bild 2 Basic circuit diagram

#### Input (intrinsically safe)

- Channel 1: connection of 2-wire transmitters or 2-wire measuring transducers at terminals 4.1 (+) and 4.2 (-)
- Channel 2: connection of 2-wire transmitters or 2-wire measuring transducers at terminals 5.1 (+) and 5.2 (-)

HART communicators (HHT) can be connected as shown in the basic circuit diagram. Test sockets (diameter 2.3 mm) have been integrated for this purpose.



Always adhere to the safety regulations (1.2. Intrinsic safety).

#### Output

- Channel 1: active output (terminals 3.1 (+) and 3.2 (-)) for connecting passive analog input cards
- Channel 2: active output (terminals 2.1 (+) and 2.2 (-)) for connecting passive analog input cards

HART communicators (HHT) can be connected as shown in the basic circuit diagram. Test sockets (diameter 2.3 mm) have been integrated for this purpose.

### 6.3 Dimensions

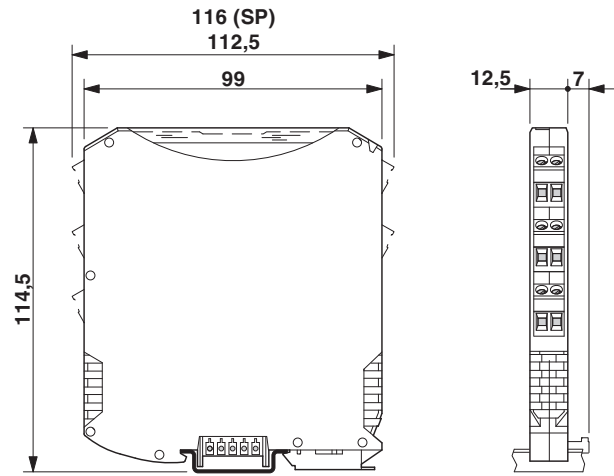


Bild 3 Dimensions

### 6.4 Assembly



#### WARNING: Explosion hazard

If the device has been used in non-intrinsically safe circuits, it must not be used again in intrinsically safe circuits.

The device must be clearly marked as non-intrinsically safe.



#### EN / UL 61010-1:

- Provide for a switch/circuit-breaker in the vicinity of a device that is marked as disconnect device for this device.
- Provide overcurrent protection ( $I \leq 16 \text{ A}$ ) within the installation.
- To protect the device against mechanical or electrical damage, install it in a suitable housing with appropriate degree of protection as per IEC 60529.
- During maintenance work, disconnect the device from all effective power sources.
- If the device is not used as described in the documentation, the intended protection can be negatively affected.
- Thanks to its housing, the device has basic insulation to the neighboring devices, for 300 Veff. If several devices are installed next to each other, this has to be taken into account, and additional insulation has to be installed if necessary! If the neighboring device is equipped with basic insulation, no additional insulation is necessary.
- The voltages present at the input, output, and supply are extra-low voltages (ELV). Depending on the application, hazardous voltage ( $> 30 \text{ V}$ ) to ground may occur. Safe electrical isolation between inputs and outputs and between the inputs and the supply exists for such cases.

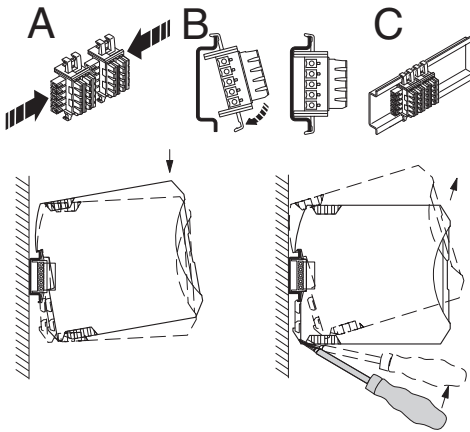


Bild 4 Mounting and removing

- Mount the device on a 35 mm DIN rail according to DIN EN 60715.
- When using the DIN rail connector, first insert it in the 35 mm DIN rail according to EN 60715 (A - C). DIN rails with a height of 7.5 mm or more can be used. The DIN rail connector is used to bridge the power supply and communication.
- The snap-in direction of the device and DIN rail connector must be observed: snap-on foot on the bottom and plug on the left.
- Install the module in a suitable housing to meet the requirements for the protection class.
- Before startup, check that the device is operating and wired correctly, in particular with regard to the wiring and marking of the intrinsically safe circuits.

## 6.5 Connecting the cables

- Screw terminal blocks: fit the litz wires with ferrules, permitted conductor cross section: 0.2 mm<sup>2</sup> to 2.5 mm<sup>2</sup>
- Spring-cage terminal blocks: fit the litz wires with ferrules, permitted conductor cross section: 0.2 mm<sup>2</sup> to 1.5 mm<sup>2</sup>
- Install intrinsically safe and non-intrinsically safe cables separately

### Screw Connection

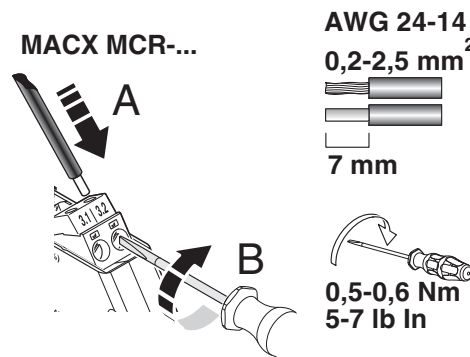


Bild 5 Screw connection

- Insert the wire into the corresponding connection terminal block.
- Use a screwdriver to tighten the screw in the opening above the connection terminal block. Tightening torque: 0.6 Nm

### Spring-cage connection:

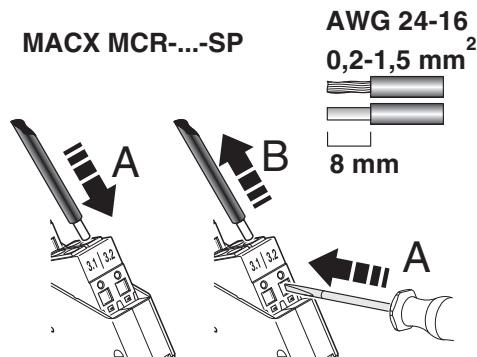


Bild 6 Spring-cage connection

- Insert the wire into the corresponding connection terminal block.



## 6.6 Power supply



### NOTE

Never connect the supply voltage directly to the DIN rail connector. It is not permitted to draw power from the DIN rail connector or from individual modules.

The supply voltage can be supplied via terminal points 1.1 and 1.2 or via the DIN rail connector.

### Supply via the MACX Analog Ex module

Where the total current consumption of the aligned modules does not exceed 400 mA, the power can be supplied directly at the connection terminal blocks of the module.

Up to 16 modules can be supplied depending on the current consumption of the modules.

We recommend connecting a 630 mA fuse (normal-blow or slow-blow) upstream.

### Supply via power and error message module

The MACX MCR-PTB (Order No. 2865625) or the MACX MCR-PTB-SP (Order No. 2924184) supply and error message module is used to provide the supply voltage to the DIN rail connector.

Simple or redundant diode-decoupled power supply is possible.

Depending on the current consumption of the modules, up to 150 individual modules can be supplied by a supply that is protected by a fuse.

The module has integrated error evaluation. An auxiliary supply failure or fuse fault is indicated at a relay contact and displayed via a flashing LED.

## 7 Comparison of the safety data



### WARNING: Explosion hazard

Compare the safety data before connecting a device located in the Ex i area to this device.

Provide proof of intrinsic safety according to standard IEC/EN 60079-14 and other national standards and installation specifications, if applicable.

Safety data

|                          |                           |
|--------------------------|---------------------------|
| Field devices            | $U_i, I_i, P_i, L_i, C_i$ |
| Ex repeater power supply | $U_o, I_o, P_o, L_o, C_o$ |

The values for  $U_o, I_o, P_o, L_o, C_o$  can be found under "Safety data according to ATEX" in the "Technical data" section.

### Example for proof of intrinsic safety (simple circuit)

$$U_i \geq U_o$$

$$I_i \geq I_o$$

$$P_i \geq P_o$$

$$L_i + L_c \leq L_o$$

$$C_i + C_c \leq C_o$$

$L_c$  and  $C_c$  depend on the cables used.

Condition  $L_i \leq 1\% \text{ of } L_o$  or  $C_i \leq 1\% \text{ of } C_o$

## 8 Safety-related applications

### 8.1 Safety characteristic data

The following notes apply for the devices:

| Designation                  | Order No. |
|------------------------------|-----------|
| MACX MCR-EX-SL-RPSS-2I-2I    | 2865382   |
| MACX MCR-EX-SL-RPSS-2I-2I-SP | 2924676   |

#### Single-channel version

In the case of the single-channel version, each of the two channels can be used for a (different) safety function.

The following then applies for the safety function:

- Type A device (according to EN 61508-2)
- Safety integrity level (SIL) 2 and 3
- HFT 0
- MTTR 24 h
- Ambient temperature 40°C

The safety function of the device involves the electrically isolated forwarding of a 4 ... 20 mA standard signal with a maximum deviation of 2%.

The range from 3.6 ... 21 mA is considered the valid signal range.

Output values outside this range are considered as the safe state, which is detected by the subsequent controller.

Safe failures in the device are therefore those errors where the device sends an output signal that deviates from the input signal by no more than 2%.

Dangerous failures are errors where the device does not follow a change in the input signal or deviates from the input signal by more than 2% and is not outside the range.

Errors that can be detected as dangerous failures are those which send a signal outside the standard range (< 3.6 mA and > 21 mA).

The failure rates in FIT for each of the channels are as follows:

| $\lambda_{SU}$ | $\lambda_{SD}$ | $\lambda_{DU}$ | $\lambda_{DD}$ | SFF    | DC <sub>D</sub> |
|----------------|----------------|----------------|----------------|--------|-----------------|
| 316            | 0              | 55             | 345            | 92.27% | 86.25%          |

#### PFD<sub>avg</sub> values

| T [PROOF]          | 1 year                | 4 years               | 5 years               |
|--------------------|-----------------------|-----------------------|-----------------------|
| PFD <sub>avg</sub> | 2.52 10 <sup>-4</sup> | 9.79 10 <sup>-4</sup> | 1.22 10 <sup>-3</sup> |

$$PFH = 5.53 \cdot 10^{-8}/h$$

The device is therefore suitable for SIL 3 applications.

In SIL 2 applications, if the percentage of the device for the entire safety chain is assumed to be a maximum of 10%, a maintenance/test interval of 4 years can be achieved.

| Sensor | Device | Processing | Actuator |
|--------|--------|------------|----------|
| 25 %   | < 10 % | 15 %       | 50 %     |

The maintenance/test interval depends on the characteristic data of all devices involved in the safety chain. The intervals may be shorter or longer depending on this characteristic data.

In SIL 3 applications, it is recommended that the maximum possible test interval is determined together with data from the other devices involved in the safety chain.

#### Two-channel version

With the two-channel version, both channels of the repeater power supply are used for safety-related applications, which means that two different sensors are present at the measurement location and signal conditioning for the standard signal is 2-channel. For this, you must connect suitable measuring transducers and sensors to the inputs of the 2-channel repeater power supply. The subsequent safety-related controller then compares both signals to check that they match.

The following then applies for the safety function:

- Type A device (according to EN 61508-2)
- Safety integrity level (SIL) 3
- HFT 1
- MTTR 24 h
- Ambient temperature 40°C

The safety functions of the device involve the electrically isolated forwarding of 4 ... 20 mA standard signals with a maximum deviation of 2%.

The range from 3.6 ... 21 mA is considered the valid signal range.

Output values outside this range are considered as the safe state, which is detected by the subsequent controller.

Safe failures in the device are therefore errors where the device sends output signals that deviate from the relevant input signals by no more than 2%.

Dangerous failures are errors where the device does not follow a change in the input signal or deviates from the input signal by more than 2% and is not outside the range.

Errors that can be detected as dangerous failures are those which send a signal outside the standard range (< 3.6 mA and > 21 mA).

The failure rates in FIT for the entire device are as follows:

| $\lambda_{SU}$ | $\lambda_{SD}$ | $\lambda_{DU}$ | $\lambda_{DD}$ | SFF    | DC <sub>D</sub> |
|----------------|----------------|----------------|----------------|--------|-----------------|
| 549            | 0              | 92             | 567            | 92.36% | 86.04%          |

**PFD<sub>avg</sub> values**

| T [PROOF]          | 1 year                | 5 years               | 10 years              |
|--------------------|-----------------------|-----------------------|-----------------------|
| PFD <sub>avg</sub> | 0.91 10 <sup>-4</sup> | 4.15 10 <sup>-4</sup> | 8.27 10 <sup>-4</sup> |

$$PFH = 1.99 \cdot 10^{-8}/h$$

When calculating the average probability of a dangerous failure on demand, errors with the same cause were taken into consideration and a  $\beta$  or  $\beta_D$  factor of 2% was determined.

The device is therefore suitable for SIL 3 applications.

In SIL 2 applications, if the percentage of the device for the entire safety chain is assumed to be a maximum of 10%, a maintenance/test interval of 10 years can be achieved.

| Sensor | Device | Processing | Actuator |
|--------|--------|------------|----------|
| 25 %   | < 10 % | 15 %       | 50 %     |

The maintenance/test interval depends on the characteristic data of all devices involved in the safety chain. The intervals may be shorter or longer depending on this characteristic data.

In SIL 3 applications, it is recommended that the maximum possible test interval is determined together with data from the other devices involved in the safety chain.

**8.2 Conditions**

- The failure rates of the components used remain constant throughout the period of use.
- The propagation of errors by the device in the system is not taken into consideration.
- The failure rates of the external power supply are not taken into consideration.
- The specified error rates are based on an ambient temperature of +40°C. For an ambient temperature of +60°C, the error rates must be multiplied by factor 2.5. Factor 2.5 is based on guide values.

**8.3 Installation and startup**

**NOTE:** Installation, operation, and maintenance may only be carried out by qualified specialist personnel.

During installation, observe the instructions in the package slip:

| Designation                     | MNR No. |
|---------------------------------|---------|
| PACKB.MACX MCR-EX-SL-RPSS-2I-2I | 9060873 |

The package slip is supplied with the device. It can also be downloaded at: [phoenixcontact.net/products](http://phoenixcontact.net/products).

Lockable housing with IP54 protection is recommended for the installation of the devices.

- Connect the device according to the installation notes.
- Make sure that the connected sensor and measuring transducer correspond to the intended configuration.
- Check that the device operates correctly with the measuring transducer and sensor connected.
- A calibrated sensor simulator and a calibrated digital multimeter may be required in order to check the device with the measuring transducer connected.
- Start up the safety circuit and check that it operates correctly.

**8.4 Notes on operation**

In normal operation, only the green LED (PWR) is on.

If a failure occurs during operation, the output signal is usually set to a value outside the "normal" signal range of 3.6 ... 21 mA. The connected SIS should therefore check the validity of the read signal values and initiate appropriate measures in the event of deviations from the normal values.

You should also check whether the connected measuring transducer responds to line faults at the sensors. After being switched off and on again, the required voltages are established in the device. Signal transmission is then performed without further action.

### 8.5 Recurring checks

The function of the entire safety loop must be checked regularly according to EN 61508 and EN 61511.

The intervals for checking are specified by the intervals of each individual device within the safety loop.

It is the operator's responsibility to select the type of checks and the checking intervals in the specified time period.

In SIL 2 applications, the repeater power supplies/signal conditioners must be checked at least every 4 (10) years (maximum proof test interval, if they represent 10% of the entire safety chain).

Checking must be carried out in such a way that the correct function of the safety equipment in conjunction with all components can be verified.

#### Possible procedure for recurring checks for discovering dangerous and undetected device failures

A calibrated simulator (0/4 ... 20 mA current) or a sensor simulator and one or ideally two calibrated digital multimeters are required in order to check the devices.

1. Take appropriate steps to prevent incorrect use.
2. Disconnect the safety circuit from further processing.
3. Connect the current simulator to the input of the repeater power supply/signal conditioner, or the sensor simulator to the input of the measuring transducer.
4. Connect the digital multimeters to the input and output of the repeater power supply/signal conditioner.
5. At the input of the device, set a signal in the range from 4 ... 20 mA or at the input of the connected measuring transducer, set a suitable signal with the sensor simulator.
6. Measure the current in the repeater power supply/signal conditioner. The output must be set to the same value.
7. Setting  $\leq 3.6$  mA or  $> 22$  mA verifies that the subsequent processing can detect signals that are out of range and evaluate them accordingly. If the output value deviates from the input value by more than 3 times the specified class accuracy rating, the device should be checked. In the event of an error, the device should be replaced with an equivalent device.
8. Restore the safety circuit to full functionality.
9. Resume normal operation.

### 8.6 Repair

The devices have a long service life, are protected against malfunctions, and are maintenance-free.

However, if a device should fail, send it back to Phoenix Contact immediately. The type of malfunction and possible cause must also be stated.

Please use the original packaging or other suitable safe packaging when sending devices back for repairs or recalibration.

Phoenix Contact GmbH & Co. KG  
Abteilung Service und Reparatur  
Flachmarktstr. 8  
32825 Blomberg  
GERMANY

### 8.7 Standards

The devices are developed and tested according to the following standards:

|                            |  |
|----------------------------|--|
| <b>EN 61508: 2011</b>      | Functional safety of electrical/electronic/programmable electronic safety-related systems  |
| <b>EN 61326-1: 2006</b>    | Electrical equipment for measurement, control and laboratory use - EMC requirements  |
| <b>IEC 61326-3-2: 2006</b> | Electrical equipment for measurement, control and laboratory use - EMC requirements - Part 3-2: Immunity requirements for safety-related systems and for equipment intended to perform safety-related functions (functional safety) - Industrial applications with specified electromagnetic environment |

## 8.8 Abbreviations

| Abbreviation       |   | Meaning   |
|--------------------|---|---|
| DC <sub>D</sub>    | Diagnostic coverage of dangerous failures   | Diagnostic coverage of dangerous failures: $DC_D = \lambda_{DD}/(\lambda_{DU} + \lambda_{DD})$  |
| DC <sub>S</sub>    | Diagnostic coverage of safe failures        | Diagnostic coverage of safe failures: $DC_S = \lambda_{SD}/(\lambda_{SU} + \lambda_{SD})$   |
| FIT                | Failure in time                             | 1 FIT = 1 failure/10 <sup>9</sup> h   |
| HFT                | Hardware fault tolerance                    | Hardware fault tolerance: ability of a function unit to continue with the execution of a demanded function despite existing faults or deviations  |
| $\beta$            | Common cause factor                         | Proportion of undetected failures as a result of a common cause   |
| $\beta_D$          | Common cause factor, diagnostic             | Proportion of failures as a result of a common cause which are detected by the diagnostic test.   |
| $\lambda_D$        | Rate of dangerous failures                  | Proportion of dangerous failures per hour   |
| $\lambda_{DD}$     | Rate of dangerous detected failures         | Proportion of detected dangerous failures per hour  |
| $\lambda_{DU}$     | Rate of dangerous undetected failures       | Proportion of undetected dangerous failures per hour  |
| $\lambda_S$        | Rate of safe failures                       | Proportion of safe failures per hour  |
| $\lambda_{SD}$     | Rate of safe detectable failures            | Proportion of detectable safe failures per hour   |
| $\lambda_{SU}$     | Rate of safe undetectable failures          | Proportion of undetectable safe failures per hour   |
| MTBF               | Mean time between failures                  | Mean time between consecutive failures  |
| PFD <sub>avg</sub> | Average probability of failure on demand    | Average probability of dangerous failure on demand of a safety function   |
| PFH                | Probability of a dangerous failure per hour | Probability of failure per hour for the safety function   |
| SFF                | Safe failure fraction                       | Proportion of safe failures: proportion of failures without the potential to set the safety-related system to a dangerous or impermissible function state   |
| SIL                | Safety integrity level                      | International standard IEC 61508 defines four discrete safety integrity levels (SIL 1 to 4). Each level corresponds to a probability range for the failure of a safety function. The higher the safety integrity level of safety-related systems, the lower the probability that the demanded safety functions will not be performed. |



Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



#### Как с нами связаться

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