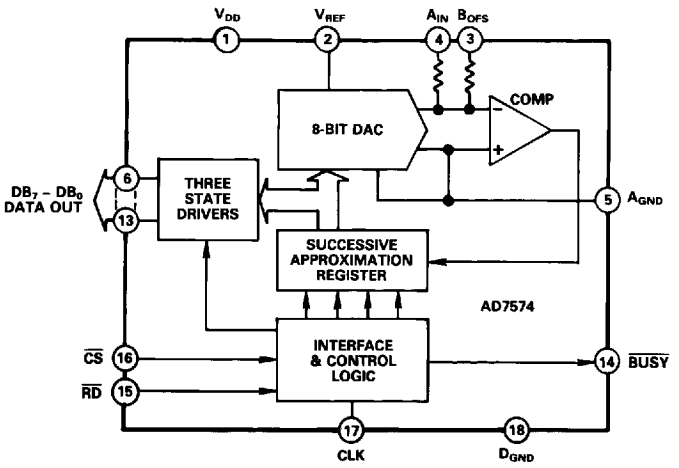
CMOS µP-Compatible 8-Bit ADC

AD7574

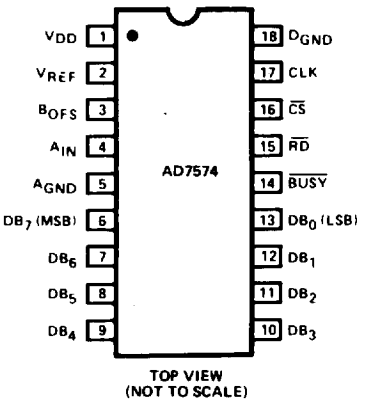
FEATURES

8-Bit Resolution
No Missed Codes over Full Temperature Range
Fast Conversion Time: 15µs
Interfaces to µP like RAM, ROM or Slow - Memory
Low Power Dissipation: 30mW
Ratiometric Capability
Single +5V Supply
Low Cost
Internal Comparator and Clock Oscillator

FUNCTIONAL BLOCK DIAGRAM



PIN CONFIGURATION



TOP VIEW
(NOT TO SCALE)

GENERAL DESCRIPTION

AD7574 is a low-cost, 8-bit µP compatible ADC which uses the successive-approximations technique to provide a conversion time of 15µs.

Designed to be operated as a memory mapped input device, the AD7574 can be interfaced like static RAM, ROM, or slow memory. Its $\overline{CS}$ (decoded device address) and $\overline{RD}$ ($\overline{READ}/\overline{WRITE}$ control) inputs are available in all µP memory systems. These two inputs control all ADC operations such as starting conversion or reading data. The ADC output data bits use three-state logic, allowing direct connection to the µP data bus or system input port.

Internal clock, +5V operation, on-board comparator and interface logic, as well as low power dissipation (30mW) and fast conversion time make the AD7574 ideal for most ADC/µP interface applications. Small size (18-pin DIP) and monolithic reliability will find wide use in avionics, instrumentation, and process automation applications.

ORDERING GUIDE

Model	Temperature Range	Differential Nonlinearity (LSB)	Package Option*
AD7574JN	0°C to +70°C	±7/8 max	N-24
AD7574KN	0°C to +70°C	±3/4 max	N-24
AD7574AQ	−25°C to +85°C	±7/8 max	Q-24
AD7574BQ	−25°C to +85°C	±3/4 max	Q-24
AD7574SQ	−55°C to +125°C	±7/8 max	Q-24
AD7574TQ	−55°C to +125°C	±3/4 max	Q-24

*N = Plastic DIP; Q = Cerdip.

REV. A

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AD7574—SPECIFICATIONS

DC SPECIFICATIONS (V_{DD} = +5V, V_{REF} = −10V, Unipolar Configuration, R_{CLK} = 180kΩ, C_{CLK} = 100pF, unless otherwise noted)

Parameter	Limits T_A = +25°C	Limits T_{min}, T_{max}[1]	Units	Conditions/Comments
ACCURACY				
Resolution	8	8	Bits	
Relative Accuracy Error				
J, A, S Versions	±3/4	±3/4	LSB max	Relative Accuracy and Differential Nonlinearity are measured
K, B, T Versions	±1/2	±1/2	LSB max	dynamically using the external clock circuit of Figure 7b.
Differential Nonlinearity				Clock frequency is 500kHz (conversion time 15μs).
J, A, S Versions	±7/8	±7/8	LSB max	
K, B, T Versions	±3/4	±3/4	LSB max	
Full Scale Error (Gain Error)				Full Scale Error is measured after calibrating out offset error. See
J, A, S Versions	±5	±6.5	LSB max	Figure 8a and associated calibration procedure for offset. Max Full
K, B, T Versions	±3	±4.5	LSB max	Scale change from +25°C to T_{min} or T_{max} is ±2LSB.
Offset Error[2]				
J, A, S Versions	±60	±80	mV max	Maximum Offset change from +25°C to T_{min} or T_{max} is ±20mV.
K, B, T Versions	±30	±50	mV max	
Mismatch Between B_{OFS} (Pin 3) and A_{IN} (Pin 4) Resistances[3]	±1.5	±1.5	% max	
ANALOG INPUTS				
Input Resistance				
At V_{REF} (Pin 2)	5/10/15	5/10/15	kΩ min/typ/max	
At B_{OFS} (Pin 3)	10/20/30	10/20/30	kΩ min/typ/max	
At A_{IN} (Pin 4)	10/20/30	10/20/30	kΩ min/typ/max	
V_{REF} (for Specified Performance)	−10	−10	V	±5% for specified transfer accuracy.
V_{REF} Range[4]	−5 to −15	−5 to −15	V	Degraded transfer accuracy.
Nominal Analog Input Range				
Unipolar Mode	0 to $+\lvert V_{REF}\rvert$		V	
Bipolar Mode	$-\lvert V_{REF}\rvert$ to $+\lvert V_{REF}\rvert$		V	
LOGIC INPUTS				
RD (Pin 15), CS (Pin 16)				
V_{INH} Logic HIGH Input Voltage	+3.0	+3.0	V min	
V_{INL} Logic LOW input Voltage	+0.8	+0.8	V max	
I_{IN} Input Current	1	10	μA max	V_{IN} = 0V, V_{DD}
C_{IN} Input Capacitance[5]	5	5	pF max	
CLK (Pin 17)				
V_{INH} Logic HIGH Input Voltage	+3.0	+3.0	V min	
V_{INL} Logic LOW Input Voltage	+0.4	+0.4	V max	
I_{INH} Logic HIGH Input Current	+2	+2	mA max	During Conversion: $V_{IN(CLK)} \geq V_{INH(CLK)}$
I_{INL} Logic LOW Input Current	1	10	μA max	During Conversion $V_{IN(CLK)} \leq V_{INL(CLK)}$
				(see circuit of Figure 7b if external clock operation is required).
LOGIC OUTPUTS				
BUSY (Pin 14), DB_7 to DB_0 (Pins 6–13)				
V_{OH} Output HIGH Voltage	+4.0	+4.0	V min	I_{SOURCE} = 40μA
V_{OL} Output LOW Voltage	+0.4	+0.8	V max	I_{SINK} = 1.6mA
I_{LKG} DB_7 to DB_0 Floating Stage Leakage	1	10	μA max	V_{OUT} = 0V or V_{DD}
Floating State Output Capacitance (DB_7 to DB_0)[5]	7	7	pF max	
Output Code	Unipolar Binary, Offset Binary			See Figures 8a, 9a, 10a, and 8b, 9b, 10b.
POWER REQUIREMENTS				
V_{DD}	+5	+5	V	±5% for specified performance.
I_{DD} (STANDBY)	5	5	mA max	A_{IN} = 0V, ADC in RESET condition.
I_{REF}	V_{REF} divided by 5kΩ		max	Conversion complete, prior to RESET.

NOTES

[1]Temperature ranges as follows: J, K, Versions, 0°C to +70°C; A, B Versions, −25°C to +85°C; S, T Versions; −55°C to +125°C.

[2]Typical offset temperature coefficient is ±150μV/°C.

[3]R_{BOFS}/R_{AIN} mismatch causes transfer function rotation about positive Full Scale. The effect is an offset and a gain term when using the circuit of Figure 9a.

[4]Typical value, not guaranteed or subject to test.

[5]Guaranteed but not tested.

Specifications subject to change without notice.

CAUTION

ESD (electrostatic discharge) sensitive device. The digital control inputs are Zener protected; however, permanent damage may occur on unconnected devices subject to high energy electrostatic fields. Unused devices must be stored in conductive foam or shunts. The protective foam should be discharged to the destination socket before devices are removed.

AC SPECIFICATIONS (V_{DD} = +5V, C_{CLK} = 100pF, R_{CLK} = 180kΩ unless otherwise noted)

Symbol	Specification	Limit at T_A = +25°C	Limit at $T_A = T_{min}$	Limit at $T_A = T_{max}$	Conditions
STATIC RAM INTERFACE MODE (See Figure 1 and Table I)					
t_{CS}	$\overline{CS}$ Pulse Width Requirement	100ns min	150ns min	150ns min	
t_{WSCS}	$\overline{RD}$ to $\overline{CS}$ Setup Time	0 min	0 min	0 min	
t_{CBPD}	$\overline{CS}$ to BUSY Propagation Delay	90ns typ	70ns typ	150ns typ	
		120ns max	120ns max	180ns max	$\overline{BUSY}$ Load = 20pF
		120ns type	100ns typ	180ns typ	
		150ns max	150ns max	200ns max	$\overline{BUSY}$ Load = 100pF
t_{BSR}	$\overline{BUSY}$ to $\overline{RD}$ Setup Time	0 min	0 min	0 min	
t_{BSCS}	BUSY to $\overline{CS}$ Setup Time	0 min	0 min	0 min	
t_{RAD}	Data Access Time	120ns typ	100ns typ	180ns typ	
		150ns max	150ns max	220ns max	DB_0–DB_7 Load = 100pF
		240ns typ	220ns typ	300ns typ	
		300ns max	300ns max	400ns max	DB_0–DB_7 Load = 100pF
t_{RHD}	Data Hold Time	80ns typ	40ns typ	120ns typ	
		50ns min	30ns min	80ns min	
		120ns max	80ns max	180ns max	
t_{RHCS}	$\overline{CS}$ to $\overline{RD}$ Hold Time	250ns max	200 ns max	500ns max	
t_{RESET}	Reset Time Requirement	3µs min	3µs min	3µs min	
$t_{CONVERT}$	Conversion Time				
	Using Internal Clock Oscillator	See Typical Data of Figure 7a			
$t_{CONVERT}$	Conversion Time				f_{CLK} = 500kHz
	Using External Clock	15µs	15µs	15µs	Circuit of Figure 7b
ROM INTERFACE MODE (See Figure 2 and Table II)					
t_{RAD}	Data Access Time	Same as RAM Mode			
t_{RHD}	Data Hold Time	Same as RAM Mode			
t_{WBPD}	RD HIGH to BUSY Propagation Delay	400ns typ	350ns typ	1µs typ	
		1.5µs	1.0µs	2.0µs	$\overline{BUSY}$ Load = 20 pF
t_{BSR}	BUSY to $\overline{RD}$ LOW Setup Time	RD can go LOW prior to BUSY = HIGH, but must not return HIGH until = BUSY HIGH. See Table II.			
$t_{CONVERT}$	Conversion Time	See Typical data of Figure 7a. Add 2µs to			
	Using Internal Clock Oscillator	data shown in Figure 7a for ROM Mode			
SLOW – MEMORY INTERFACE MODE (See Figure 3 and Table III)					
t_{CBPD}	$\overline{CS}$ to BUSY Propagation Delay	Same as RAM Mode			
t_{RESET}	Reset Time Requirement	Same as RAM Mode			
t_{RAD}	Data Access Time	Same as RAM Mode			
t_{RHD}	Data Hold Time	Same as RAM Mode			
$t_{CONVERT}$	Conversion Time	Same as RAM Mode			

ABSOLUTE MAXIMUM RATINGS*

V_{DD} to A_{GND} . . . . . 0V, +7.0V
V_{DD} to D_{GND} . . . . . 0V, +7.0V
A_{GND} to D_{GND} . . . . . −0.3V, V_{DD}
Digital Input Voltage to D_{GND} (Pins 15 and 16) . . . . −0.3V, +15.0V
Digital Output Voltage to D_{GND} (Pins 6–14) . . . . . −0.3V, V_{DD}
CLK Input Voltage (Pin 17) toD_{GND} . . . . . −0.3V, V_{DD}
V_{REF} (Pin 2) . . . . . ±20V
V_{BOFS} (Pin 3) . . . . . ±20V
V_{AIN} (Pin 4) . . . . . ±20V
Operating Temperature Range
Commercial (J, K Versions) . . . . . 0°C to +70°C
Industrial (A, B Versions) . . . . . −25°C to +85°C
Extended (S, T Versions) . . . . . −55°C to +150°C
Storage Temperature Range . . . . . −65°C to +150°C
Lead Temperature (soldering, 10 secs) . . . . . +300°CV
Power Dissipation (Package)
Plastic (Suffix N)
to +70°C 670mW
Derate above +70°C by . . . . . 8.3mW/°C
Cerdip (Suffix Q)
to +75°C 450mW
Derate above +75°C by . . . . . 6mW/°C

*Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation at or above this specification is not implied. Exposure to above maximum rating conditions for extended periods may affect device reliability.

TERMINOLOGY

RESOLUTION: Resolution is a measure of the *nominal* analog change required for a 1-bit change in the A/D converter's digital output. While normally expressed in a number of bits, the analog resolution of an n-bit unipolar A/D converter is (2^{-n}) V_{REF}). Thus, the AD7574, an 8-bit A/D converter, can resolve analog voltages as small as (1/256) (V_{REF}) when operated in a unipolar mode. When operated in a bipolar mode, the resolution is (1/128) (V_{REF}). Resolution does not imply accuracy. *Usable* resolution is limited by the differential nonlinearity of the A/D converter.

RELATIVE ACCURACY: Relative accuracy is the deviation of the ADC's actual code transition points from a straight line drawn between the devices' measured zero and measured full scale transition points. Relative accuracy, therefore, is a measure of code *position.*

DIFFERENTIAL NONLINEARITY: Differential nonlinearity in an ADC is a measure of the size of an anlog voltage range associated with any digitial output code. As such, differential nonlinearity specifies code width (usable resolution). An ADC with a specified differential nonlinearity of ±n bits will exhibit codes ranging in width from 1LSB −n LSB to 1LSB +n LSB. A specified differential nonlinearity of less than ±1LSB guarantees no-missing-codes operation.

TIMING & CONTROL OF THE AD7574

STATIC RAM INTERFACE MODE

Table I and Figure 1 show the truth table and timing requirements for AD7574 operation as a static RAM.

A convert start is initiated by executing a memory WRITE instruction to the address location occupied by the AD7574 (once conversion has started, subsequent memory WRITES have no effect). A data READ is performed by executing a memory READ instruction to the AD7574 address location.

$\overline{BUSY}$ must be HIGH before a data READ is attempted, i.e. the total delay between a convert start and a data READ must be at least as great as the AD7574 conversion time. The delay can be generated by inserting NOP instructions (or other program instructions) between the WRITE (start convert) and READ (read data) operations. Once $\overline{BUSY}$ is HIGH (conversion complete), a data READ is performed by executing a memory READ instruction to the address location occupied by the AD7574. The data readout is destructive, i.e. when RD returns HIGH, the converter is internally reset.

The RAM interface mode uses distinctly different commands to start conversion (memory WRITE) or read the data (memory READ). This is in contrast to the ROM mode where a memory READ causes a data READ *and* a conversion restart.

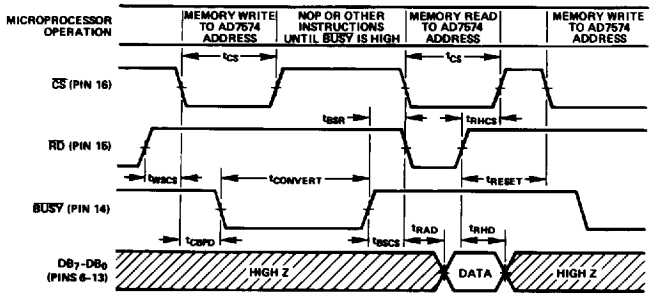


Figure 1. Static RAM Mode Timing Diagram

Table I. Truth Table, Static RAM Mode

AD7574 INPUTS		AD7574 OUTPUTS		AD7574 OPERATION
$\overline{CS}$	$\overline{RD}$	$\overline{BUSY}$	DB_7 - DB_0	
L	H	H	HIGH Z	WRITE CYCLE (START CONVERT)
L	⊓	H	HIGH Z → DATA	READ CYCLE (DATA READ)
L	⊓	H	DATA → HIGH Z	RESET CONVERTER
H	X[1]	X	HIGH Z	NOT SELECTED
L	H	L	HIGH Z	NO EFFECT, CONVERTER BUSY
L	⊓	L	HIGH Z	NO EFFECT, CONVERTER BUSY
L	⊓	L	HIGH Z	NOT ALLOWED, CAUSES INCORRECT CONVERSION

Note 1: If $\overline{RD}$ goes LOW to HIGH when $\overline{CS}$ is LOW, the ADC is internally reset. $\overline{RD}$ has no effect while $\overline{CS}$ is HIGH. See application hint No. 1.

ROM INTERFACE MODE

Table II and Figure 2 show the truth table and timing requirements for interfacing the AD7574 like Read Only Memory.

$\overline{CS}$ is held LOW and converter operation is controlled by the $\overline{RD}$ input. The AD7574 $\overline{RD}$ input is derived from the decoded device address. MEMRD should be used to enable the address decoder in 8080 systems. VMA should be used to enable the address decoder in 6800 systems. A data READ is initiated by executing a memory READ instruction to the AD7574 address location. The converter is automatically restarted when $\overline{RD}$ returns HIGH. As in the RAM mode, attempting a data READ before $\overline{BUSY}$ is HIGH will result in incorrect data being read.

The advantage of the ROM mode is its simplicity. The major disadvantage is that the data obtained is relatively poorly defined in time inasmuch as executing a data READ automatically starts a new conversion. This problem can be overcome by executing two READs separated by NO-OPS (or other program instructions) and using only the data obtained from the second READ.

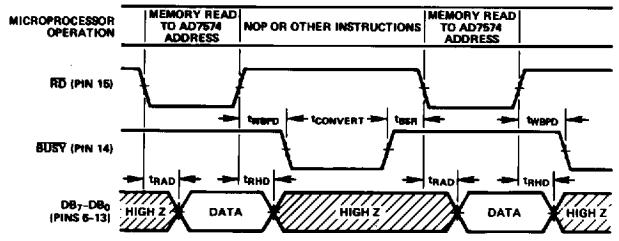


Figure 2. ROM Mode Timing Diagram ($\overline{CS}$ Held LOW)

Table II. Truth Table, ROM Mode

AD7574 INPUTS		AD7574 OUTPUTS		AD7574 OPERATION
$\overline{CS}$	$\overline{RD}$	$\overline{BUSY}$	DB_7 - DB_0	
L	⊓	H	HIGH Z → DATA	DATA READ
L	⊓	⊓	DATA → HIGH Z	RESET AND START NEW CONVERSION
L	⊓	L	HIGH Z	NO EFFECT, CONVERTER BUSY
L	⊓	L	HIGH Z	NOT ALLOWED, CAUSES INCORRECT CONVERSION

SLOW-MEMORY INTERFACE MODE

Table III and Figure 3 show the truth table and timing requirements for interfacing the AD7574 as a slow-memory. This mode is intended for use with processors which can be forced into a WAIT state for at least 12μs (such as the 8080, 8085 and SC/MP). The major advantage of this mode is that it allows the μP to start conversion, WAIT, and then READ data with a single READ instruction.

In the slow-memory mode, $\overline{CS}$ and $\overline{RD}$ are tied together. It is suggested that the system ALE signal (8085 system) or SYNC signal (8080 system) be used to latch the address. The decoded device address is subsequently used to drive the AD7574 $\overline{CS}$ and $\overline{RD}$ inputs. $\overline{BUSY}$ is connected to the microprocessor READY input.

When the AD7574 is NOT addressed, the $\overline{CS}$ and $\overline{RD}$ inputs are HIGH. Conversion is initiated by executing a memory READ to the AD7574 address. $\overline{BUSY}$ subsequently goes LOW (forcing the μP READY input LOW) placing the μP in a WAIT state. When conversion is complete ($\overline{BUSY}$ is HIGH) the μP completes the memory READ.

Do not attempt to perform a memory WRITE in this mode, since three-state bus conflicts will arise.

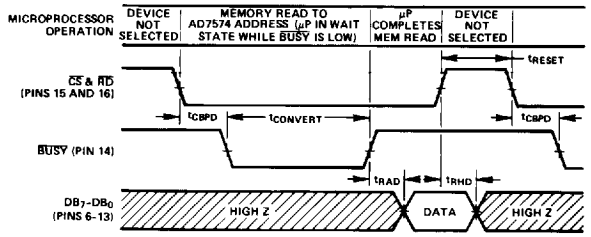


Figure 3. Slow Memory Mode Timing Diagram (CS and RD Tied Together)

Table III. Truth Table, Slow Memory Mode

AD7574 INPUTS	AD7574 OUTPUTS		AD7574 OPERATION
CS & RD	BUSY	DB_7 - DB_0	
H	H	HIGH Z	NOT SELECTED
⌐	H→L	HIGH Z	START CONVERSION
L	L	HIGH Z	CONVERSION IN PROGRESS, μP IN WAIT STATE
L	⌐	HIGH Z→DATA	CONVERSION COMPLETE, μP READS DATA
⌐	H	DATA→HIGH Z	CONVERTER RESET AND DESELECTED
H	H	HIGH Z	NOT SELECTED

GENERAL CIRCUIT INFORMATION

BASIC CIRCUIT DESCRIPTION

The AD7574 uses the successive approximations technique to provide an 8-bit parallel digital output. The control logic was designed to provide easy interface to most microprocessors. Most applications require only passive clock components (R & C), a -10V reference, and +5V power.

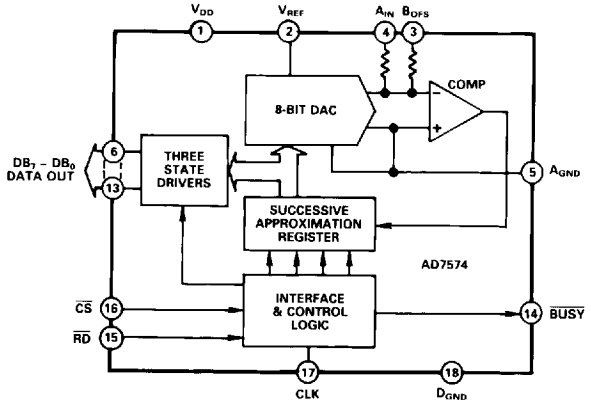


Figure 4. AD7574 Functional Diagram

Figure 4 shows the AD7574 functional diagram. Upon receipt of a start command either via the $\overline{CS}$ or $\overline{RD}$ pins, $\overline{BUSY}$ goes low indicating conversion is in progress. Successive bits, starting with the most significant bit (MSB) are applied to the input of a DAC. The comparator determines whether the addition of each successive bit causes the DAC output to be greater than or less than the analog input, A_{IN}. If the sum of the DAC bits is less than A_{IN}, the trial bit is left ON, and the next smaller bit is tried. If the sum is greater than A_{IN}, the trial bit is turned OFF and the next smaller bit is tried.

Each successively smaller bit is tried and compared to A_{IN} in this manner until the least significant bit (LSB) decision has been made. At this time $\overline{BUSY}$ goes HIGH (conversion is complete) indicating the successive approximation register contains a valid representation of the analog input. The $\overline{RD}$ control (see the previous page for details) can then be exercised to activate the three-state buffers, placing data on the DB_0 - DB_7 data output pins. $\overline{RD}$ returning HIGH causes the clock oscillator to run for 1 cycle, providing an internal ADC reset (i.e. the SAR is loaded with code 10000000).

DAC CIRCUIT DETAILS

The current weighting D/A converter is a precision multiplying DAC. Figure 5 shows the functional diagram of the DAC as used in the AD7574. It consists of a precision Silicon Chromium thin film R/2R ladder network and 8 N-channel MOSFET switches operated in single-pole-double-throw.

The currents in each 2R shunt arm are binarily weighted, i.e. the current in the MSB arm is V_{REF} divided by 2R, in the second arm is V_{REF} divided by 4R, etc. Depending on the DAC logic input (A/D output) from the successive approximation register, the current in the individual shunt arms is steered either to A_{GND} or to the comparator summing point.

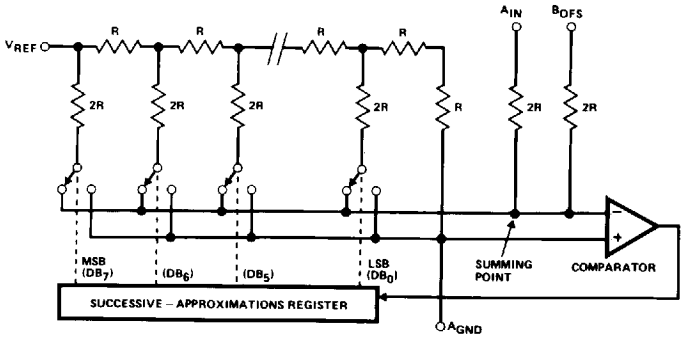


Figure 5. D/A Converter As Used In AD7574

OPERATING THE AD7574

APPLICATION HINTS

1. TIMING & CONTROL
   In the AD7574 when a conversion is finished the fresh data must be read before a new conversion can be started. Failure to observe the timing restrictions of Figures 1, 2 or 3 may cause the AD7574 to change interface modes. For example, in the RAM mode, holding $\overline{CS}$ LOW too long after $\overline{RD}$ goes HIGH will cause a new convert start (i.e. the converter moved into the ROM mode).
2. LOGIC DEGLITCHING IN uP APPLICATIONS
   Unspecified states on the address bus (due to different rise and fall times on the address bus) can cause glitches at the AD7574 $\overline{CS}$ or $\overline{RD}$ terminals. These glitches can cause unwanted convert starts, reads, or resets. The best way to avoid glitches is to gate the address decoding logic with RD or WR (8080) or VMA (6800) when in the ROM or RAM mode. When in the slow-memory mode, the ALE (8085) or SYNC (8080) signal should be used to latch the address.
3. INPUT LOADING AT V_{REF}, A_{IN} AND B_{OFS}
   To prevent loading errors due to the finite input resistance at the V_{REF}, A_{IN} or B_{OFS} pins, low impedance driving sources must be used (i.e. op amp buffers or low output-Z reference).
4. RATIOMETRIC OPERATION
   Ratiometric performance is inherent to A/D converters such as the AD7574 which use a multiplying DAC weighting network. However, the user should recognize that comparator limitations such as offset voltage, input noise and gain will cause degradation of the transfer characteristics when operating with reference voltages less than -10V in magnitude.
5. OFFSET CORRECTION
   Offset error in the transfer characteristic can be trimmed by offsetting the buffer amplifier which drives the AD7574 A_{IN} pin (pin 4). This can be done either by summing a cancellation current into the amplifier's summing junction, or by tapping a voltage divider which sits between V_{DD} and V_{REF} and applying the tap voltage to the amplifier's positive input (an example of a resistive tap offset adjust is shown in Figure 10a where R_8, R_9 and R_{10} can be used to offset the ADC).
6. ANALOG AND DIGITAL GROUND
   It is recommended that A_{GND} and D_{GND} be connected locally to prevent the possibility of injecting noise into the AD7574. In systems where the A_{GND}-D_{GND} intertie is not local, connect back-to-back diodes (IN914 or equivalent) between the AD7574 A_{GND} and D_{GND} pins.
7. INITIALIZATION AFTER POWER – UP
   Execute a memory READ to the AD7574 address location, and subsequently ignore the data. The AD7574 is internally reset when reading out data, i.e. the data readout is destructive.

CLOCK OSCILLATOR

The AD7574 has an internal asynchronous clock oscillator which starts upon receipt of a convert start command, and ceases oscillating when conversion is complete.

The clock oscillator requires an external R and C as shown in Figure 6. Nominal conversion times versus R_{CLK} and C_{CLK} is shown in Figure 7a. The curves shown in Figure 7a are applicable when operating in the RAM or slow-memory interface modes. When operating in the ROM interface mode, add 2μs to the typical conversion time values shown.

The AD7574 is guaranteed to provide transfer accuracy to published specifications for conversion times down to 15μs, as indicated by the unshaded region of Figure 7a. Conversion times faster than 15μs can cause transfer accuracy degradation.

OPERATION WITH EXTERNAL CLOCK

For applications requiring a conversion time close to or equal to 15μs, an external clock is recommended. Using an external clock precludes the possibility of converting faster than 15μs (which can cause transfer accuracy degradation) due to temperature drift – as may be the case when using the internal clock oscillator.

Figure 7b shows how the external clock must be connected. The $\overline{BUSY}$ output of the AD7574 is connected to the three-state enable input of a 74125 three-state buffer. R_1 is used as a pullup, and can be between 6kΩ and 100kΩ. A 500kHz clock will provide a conversion time of 15μs.

The external clock should be used only in the static-RAM or slow-memory interface mode, and *not* in the ROM mode.

Timing constraints for external clock operation are as follows:

STATIC RAM MODE

1. When initiating a conversion, $\overline{CS}$ should go LOW on a positive clock edge to provide optimum settling time for the MSB.
2. A data READ can be initiated any time after $\overline{BUSY}$ = 1.

SLOW-MEMORY MODE

1. When initiating a conversion, $\overline{CS}$ and $\overline{RD}$ should go LOW on a positive clock edge to provide optimum settling time for the MSB.

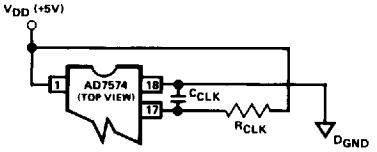


Figure 6. Connecting R_{CLK} and C_{CLK} To CLK Oscillator

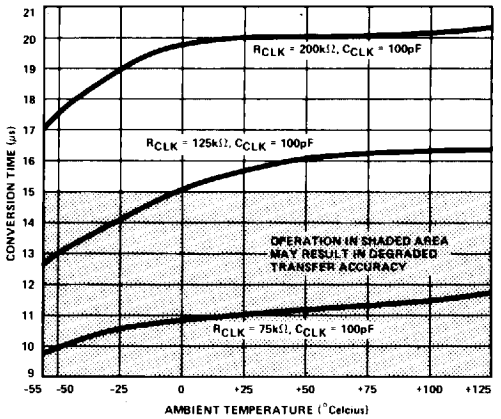


Figure 7a. Typical Conversion Time vs. Temperature For Different R_{CLK} and C_{CLK} (Applicable to RAM and Slow-Memory Modes. For ROM Mode add 2μs to values shown)

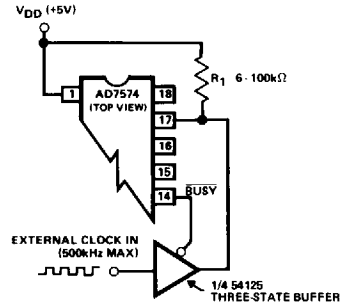


Figure 7b. External Clock Operation (Static RAM and Slow-Memory Mode)

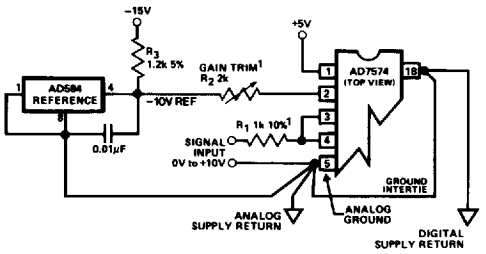
UNIPOLAR BINARY OPERATION

Figures 8a and 8b show the analog circuit connections and typical transfer characteristic for unipolar operation. An AD584 is used as the -10V reference.

Calibration is as follows:

OFFSET

Offset must be trimmed out in the signal conditioning circuitry used to drive the signal input terminals shown in Figure 8a. An example of an offset trim is shown in Figure 10a, where R_8, R_9 and R_{10} comprise a simple voltage tap which is applied to the amplifier's positive input.



Note 1: R_1 and R_2 can be omitted if gain trim is not required

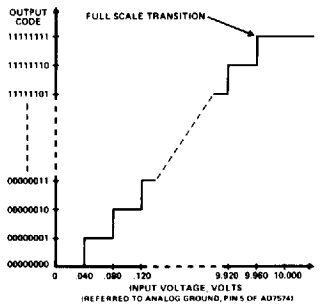
Figure 8a. AD7574 Unipolar (0V to +10V) Operation (Output Code is Straight Binary)

1. Apply -39.1mV (1 LSB) to the input of the buffer amplifier used to drive R_1 (i.e. +39.1mV at R_1).
2. While performing continuous conversions, adjust the offset potentiometer (described above) until DB_7 - DB_1 are LOW and the LSB (DB_0) flickers.

GAIN (FULL SCALE)

Offset adjustment must be performed before gain adjustment.

1. Apply -9.961V to the input of the buffer amplifier used to drive R_1 (i.e. +9.961V at R_1).
2. While performing continuous conversions, adjust trim pot R_2 until DB_7 - DB_1 are HIGH and the LSB (DB_0) flickers.



Note: Approximate bit weights are shown for illustration. Nominal bit weight for a -10V reference is ≈ 39.1mV

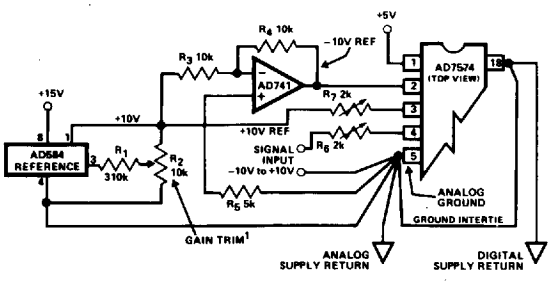
Figure 8b. Nominal Transfer Characteristic For Unipolar Circuit of Figure 8a

BIPOLAR (OFFSET BINARY) OPERATION

Figures 9a and 9b illustrate the analog circuitry and transfer characteristic for bipolar operation. Output coding is offset binary. As in unipolar operation, offset correction can be performed at the buffer amplifier used to drive the signal input terminals of Figure 9a (Resistors R_8, R_9 and R_{10} in Figure 10a show how offset trim can be done at the buffer amplifier).

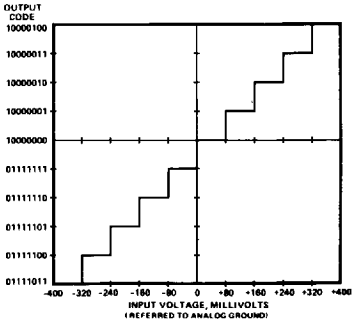
Calibration is as follows:

1. Adjust R_6 and R_7 for minimum resistance across the potentiometers.
2. Apply +10.000V to the buffer amplifier used to drive the signal input (i.e. -10.000V at R_6).
3. While performing continuous conversions, trim R_6 or R_7 (whichever required) until DB_7 - DB_1 are LOW and the LSB (DB_0) flickers.
4. Apply 0V to the buffer amplifier used to drive the signal input terminals.
5. Doing continuous conversions, trim the offset circuit of the buffer amplifier until the ADC output code flickers between 01111111 and 10000000.
6. Apply +10.000V to the input of the buffer amplifier (i.e. -10.000V as applied to R_6).
7. Doing continuous conversions, trim R_2 until DB_7 - DB_1 are LOW and the LSB (DB_0) flickers.
8. Apply -9.922V to the input of the buffer amplifier (i.e. +9.922V at the input side of R_6).
9. If the ADC output code is not 11111110 ±1 bit, repeat the calibration procedure.



Note 1: R_1 and R_2 can be omitted if gain trim is not required

Figure 9a. AD7574 Bipolar (-10V to +10V) Operation (Output Code is Offset Binary)



Note: Approximate bit weights are shown for illustration. Nominal bit weight for ± 10V full scale is ≈ 78.1mV

Figure 9b. Nominal Transfer Characteristic Around Major Carry for Bipolar Circuit of Figure 9a

OPERATING THE AD7574

BIPOLAR (COMPLEMENTARY OFFSET BINARY) OPERATION

Figure 10a shows the analog connections for complementary offset binary operation. The typical transfer characteristic is shown in Figure 10b. In this bipolar mode, the ADC is fooled into believing it is operated in a unipolar mode - i.e. the +10V to -10V analog input is conditioned into a 0 to +10V signal range. R_2 is the gain adjust, while R_9 is the offset adjust.

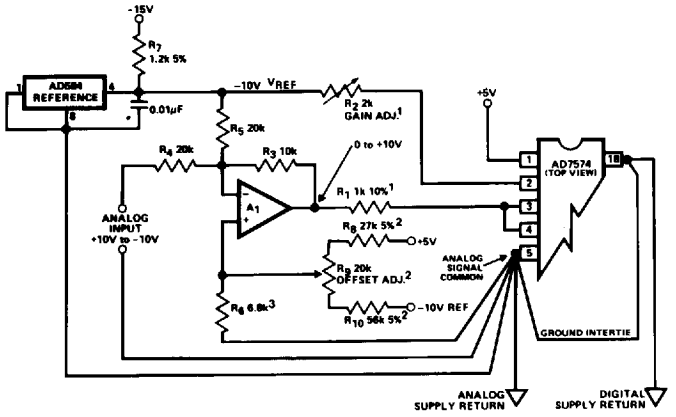
Calibration is as follows (adjust offset before gain):

OFFSET

1. Apply OV to the analog input shown in Figure 10a.
2. While performing continuous conversions, adjust R_9 until the converter output flickers between codes 01111111 and 10000000.

GAIN (FULL SCALE)

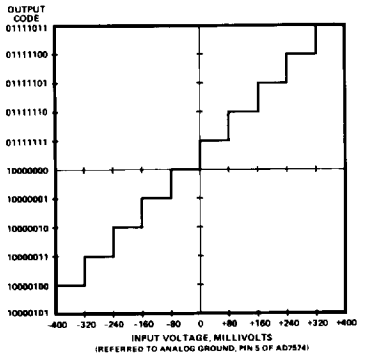
1. Apply -9.922V across the analog input terminals shown in Figure 10a.
2. While performing continuous conversions, adjust R_2 until DB_7 - DB_1 are HIGH and the LSB (DB_0) flickers between HIGH and LOW.



Notes:

1. R_1 and R_2 can be omitted if gain trim is not required
2. R_8, R_9 and R_{10} can be omitted if offset trim is not required
3. $R_6 \| R_8 \| R_{10} = 5k\Omega$. If R_8, R_9 and R_{10} not used, make $R_6 = 5k\Omega$

Figure 10a. AD7574 Bipolar Operation (-10V to +10V) (Output Code is Complementary Offset Binary)



Note: Approximate bit weights are shown for illustration. Nominal bit weight for ±10V full scale is ≈78.1mV

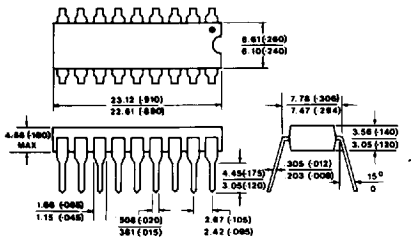
Figure 10b. Nominal Transfer Characteristic Around Major Carry for Bipolar Circuit of Figure 10a

MECHANICAL INFORMATION

OUTLINE DIMENSIONS

Dimensions are shown in inches and (mm).

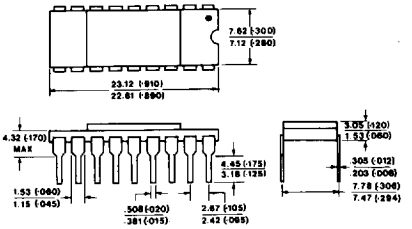
18 PIN PLASTIC DIP



Notes:

1. Lead no.1 identified by dot or notch.
2. Dimensions in mm (in.).
3. Leads are solder plated KOVAR or ALLOY 42.

18 PIN CERAMIC DIP



Notes:

1. Lead no. 1 identified by dot or notch.
2. Leads will be either gold or tin plated in accordance with MIL-M-38510 requirements.
3. Cavity lid is electrically isolated.

C505d-5-6/85

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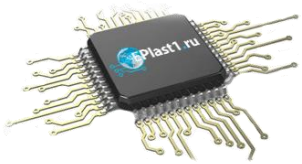
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



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