## Features

- 8.5 V Supply Voltage
- Voltage Regulator for Stable Operating Conditions
- Microprocessor-controlled Via a Simple Two-wire Bus
- Two Addresses Selectable
- Gain-controlled RF Amplifier with Two Inputs, Selectable Via a Simple Two-wire Bus Control
- Balanced RF Amplifier Inputs
- Gain-controlled RF Mixer
- Four-pin Voltage-controlled Oscillator
- SAW Filter Driver with Differential Low-impedance Output
- AGC Voltage Generation for RF Section, Available at Charge-pump Output (Can Also Be Used to Control a PIN Diode Attenuator)
- Gain-controlled IF Amplifier
- Balanced IF Amplifier Inputs
- Selectable Gain-controlled IF Mixer
- Single-ended IF Output
- AGC Voltage Generation for IF Section, Available at Charge-pump Output
- Separate Differential Input for the IF AGC Block
- All AGC Time Constants Adjustable
- AGC Thresholds Programmable Via a Simple Two-wire Bus
- Three AGC Charge Pump Currents Selectable (Zero, Low, High)
- Reference Oscillator
- Programmable 9-bit Reference Divider
- Programmable 15-bit Counter 1:2048 to 1:32767 Effectively
- Tristate Phase Detector with Programmable Charge Pump
- Superior Phase-noise Performance
- Deactivation of Tuning Output Programmable
- Three Switching Outputs (Open Collector)
- Three D/A Converters (Resolution: 8 Bits)
- Lock Status Indication (Open Collector)

Electrostatic sensitive device. Observe precautions for handling.


## Description

The U2731B is a monolithically integrated Digital Audio Broadcasting one-chip front end circuit manufactured using Atmel's advanced UHF5S technology. Its functionality covers a gain-controlled RF amplifier with two selectable RF inputs, a gain-controlled RF mixer, a VCO which provides the LO signal for the RF mixers, either directly or after passing a frequency divider, a SAW filter driver, an AGC block for the RF section, a gain-controlled IF amplifier, an IF mixer which can also be bypassed, an AGC block for the IF section and a fractional-N frequency synthesizer. The frequency synthesizer controls the VCO to synthesize frequencies in the range of 70 MHz to 500 MHz in a $16-\mathrm{kHz}$ raster; within certain limits the reference divider factor is fully programmable. The lock status of the phase detector is indicated at a special output pin; three switching outputs can be addressed. A reference signal which is generated by an on-chip reference oscillator is available at an output pin. This reference signal is also used to generate the LO signal for the IF mixer, either by doubling the frequency or by using the reference frequency itself. Three D/A converters at a resolution of 8 bits provide a digitally controllable output voltage. The thresholds inside the AGC blocks can be digitally controlled by means of on-chip 4-bit D/A converters. All functions of this IC are controlled via a simple two-wire bus.

Figure 1. Block Diagram


## Pin Configuration

Figure 2. Pinning


## Pin Description

| Pin | Symbol | Function |
| :---: | :---: | :---: |
| 1 | SCL | Clock (simple two-wire bus) |
| 2 | SDA | Data (simple two-wire bus) |
| 3 | SWA | Switching output (open collector) |
| 4 | SWB | Switching output (open collector) |
| 5 | FREF | Reference frequency output (for U2731B) |
| 6 | SWC | Switching output (open collector) |
| 7 | CAO | Output of D/A converter A |
| 8 | CCO | Output of D/A converter B |
| 9 | CBO | Output of D/A converter C |
| 10 | GND | Ground |
| 11 | GND | Ground |
| 12 | RFA1 | Input 1 of RF amplifier A (differential) |
| 13 | RFA2 | Input 2 of RF amplifier A (differential) |
| 14 | RFB1 | Input 1 of RF amplifier B (differential) |
| 15 | RFB2 | Input 2 of RF amplifier B (differential) |
| 16 | CPRF | Charge-pump output (RF AGC block) |
| 17 | GND | Ground |
| 18 | SAW1 | SAW driver output 1 (differential) |
| 19 | SAW2 | SAW driver output 2 (differential) |
| 20 | VS | Supply voltage RF part |
| 21 | SLI | AGC mode selection (charge-pump current high) |
| 22 | WAGC | AGC mode selection (charge-pump current off) |
| 23 | IFIN2 | Input 2 of IF amplifier (differential) |
| 24 | IFIN1 | Input 1 of IF amplifier (differential) |
| 25 | VS | Supply voltage IF part |
| 26 | IFAGCIN2 | Input 2 of IF AGC block (differential) |
| 27 | IFAGCIN1 | Input 1 of IF AGC block (differential) |
| 28 | CPIF | Charge-pump output (IF AGC block) |
| 29 | IFOUT | IF output (single ended) |
| 30 | GND | Ground |
| 31 | GND | Ground |
| 32 | C1VC | Collector 1 of VCO |
| 33 | B2VCO | Base 2 of VCO |
| 34 | B1VCO | Base 1 of VCO |
| 35 | C2VC | Collector 2 of VCO |
| 36 | GND | Ground |
| 37 | GND | Ground |
| 38 | VS | Supply voltage PLL |
| 39 | PD | Tri-state charge pump output |
| 40 | VD | Active filter output |

## Pin Description (Continued)

| Pin | Symbol | Function |
| :---: | :---: | :--- |
| 41 | PLCK | Lock-indicating output (open collector) |
| 42 | OSCI | Input of reference oscillator/buffer |
| 43 | OSCO | Output of reference oscillator/buffer |
| 44 | ADR | Address selection (simple two-wire bus) |

## Functional Description

The U2731B represents a monolithically integrated front end IC designed for applications in DAB receivers. It covers RF and IF signal processing, the PLL section and also supporting functions such as D/A converters or switching outputs.

Two RF input ports offer the possibility of handling various input signals such as a downconverted L-band signal or band II and band III RF signals. The high dynamic range of the RF inputs and the use of a gain-controlled amplifier and a gain-controlled mixer in the RF section offer the possibility of handling even strong RF input signals. The LO signal of the first mixer stage is derived from an on-chip VCO. The VCO frequency is either divided by two or directly fed to the mixer. In this way band II and band III can be covered easily.

In the IF section, it can be selected if the first IF signal is down-converted to a second, lower IF or if it is simply amplified to appear at the IF output. If the down-conversion option is chosen, it can be selected if the LO signal of the IF mixer is directly derived from the reference signal of the PLL, or if it is generated by doubling its frequency. The amplifiers in the IF section are gain-controlled in similar fashion to the RF section.
The RF and the IF part also contain AGC functional blocks which generate the AGC control voltages. The AGC thresholds can be defined by means of three on-chip 4-bit D/A converters.

The frequency of the VCO is locked to a reference frequency by an on-chip fractional-N PLL circuit which guarantees a superior phase-noise performance. The reference frequency is generated by an on-chip crystal oscillator which can also be overdriven by an external signal. Starting from a minimum value, the reference scaling factor is freely programmable.

Three switching outputs can be used for various switching tasks on the front end board. Three 8 -bit D/A converters providing an output voltage between 0 and 8.5 V are used to improve the tuning voltages of the tuned preselectors which are derived from the tuning voltage of the VCO.

RF Gain-controlled Amplifier

## RF Gain-controlled Mixer, VCO and LO Divider

## RF AGC <br> Voltage-generation Block

In order to support two different channels, two identical input buffers with balanced inputs (RFA1, RFA2; RFB1, RFB2) are integrated. By setting the two-wire bus bits M0 and M1 (see section "Simple Two-wire Bus Functions" on page 11), the active buffer can be selected. The buffers are followed by a gain-controlled amplifier whose output signal is fed to a gain-controlled mixer. The RF amplifiers are capable of handling input signals up to a typical power of -6 dBm without causing third-order intermodulation components stronger than -40 dBc .

The purpose of the RF mixer is to down-convert the incoming signal (band II, band III) to an IF frequency which is typically 38.912 MHz . This IF signal is fed to an AGC voltagegeneration block (which is described in the following section) and an output buffer stage. This driver stage has a low output impedance and is capable of driving a SAW filter directly via its differential output pins SAW1, SAW2. The mixer's LO signal is generated by a balanced voltage-controlled oscillator whose frequency is stabilized by a frac-tional-N phase-locked loop. An example circuit of the VCO is shown in Figure 12 on page 23. The oscillator's tank is applied to the pins B1VC, C1VC, B2VC, C2VC as shown in the application circuit in Figure 8 on page 20. Before the VCO's signal is fed to the RF mixer, it has to pass an LO divider block where the VCO frequency is either divided by 1 or 2 . The setting of this divider is defined by means of the two-wire bus bits M0 and M1 as indicated in the section "Simple Two-wire Bus Functions" on page 11. This feature offers the possibility of covering both band II and band III by tuning the VCO frequency in the range between 200 MHz to 300 MHz .

In this functional block, the output signal of the RF mixer is amplified, weakly bandpass filtered (transition range: X8 MHz to X 80 MHz ), rectified and finally lowpass filtered. The voltage derived in this power-measurement process is compared to a voltage threshold (th1) which can be digitally controlled by an on-chip 4-bit D/A converter. The setting of this converter is defined by means of the two-wire bus bits TAi $(\mathrm{i}=1,2,3,4)$. Depending on the result of this comparison, a charge pump feeds a positive or negative current to pin CPRF in order to charge or discharge an external capacitor. The voltage of this external capacitor can be used to control the gain of an external preamplifier or attenuator stage. Furthermore, it is also used to generate the internal control voltages of an RF amplifier and mixer. For this purpose, the voltage at pin CPRF is compared to a voltage threshold (th2) which is also controlled by an on-chip 4-bit D/A converter whose setting is fixed by the two-wire bus bits TBi $(i=1,2,3,4)$.
By means of the input pins WAGC and SLI the current of the RF AGC charge pump can be selected according to the following table:

Table 1. Current of Charge Pump

| WAGC | SLI | Charge-pump Current/ $\mu \mathbf{A}$ |
| :--- | :---: | :---: |
| HIGH | X | off |
| LOW | LOW | $50 \mu \mathrm{~A}$ (slow mode) |
| LOW | HIGH | $190 \mu \mathrm{~A}$ (fast mode) |

The function can be seen in Figure 11 on page 22.

IF Gain-controlled Amplifier

IF Gain-controlled Amplifier/Mixer Combination

The signal applied to the balanced input pins IFIN1, IFIN2 is amplified by a gain-controlled IF amplifier. The gain-control signal is generated by an IF AGC voltagegeneration block which is described in the next section. To avoid offset problems, the output of the gain-controlled amplifier is fed to an amplifier/mixer combination by AC coupling.

Depending on the setting of the two-wire bus bits M2, M3, the output signal of the gaincontrolled IF amplifier is either mixed down to a lower, second IF or, after passing an output buffer stage, amplified before it appears at the single-ended output pin IFOUT. If the down-conversion option is chosen this circuit still offers two possibilities concerning the synthesis of the IF mixers LO signal. This LO signal is derived from the PLL's onchip reference oscillator. By means of the two-wire bus bits M2, M3, it can be decided whether the reference frequency is doubled before it is given to the mixer's LO port, or if it is used directly. The gain-control voltage of the amplifier/mixer combination is similar to the gain-controlled IF amplifier generated by an internal gain-control circuit.

The purpose of this gain-control circuit in the IF part is to measure the power of the incoming signal at the balanced input pins IFAGCIN1, IFAGCIN2, to compare it with a certain power level and to generate a control voltage for the IF gain-controlled amplifiers and mixer. This architecture offers the possibility of ensuring an optimal use of the dynamic range of the A/D converter which transforms the output signal at pin IFOUT from the analog to the digital domain despite possible insertion losses of (anti-aliasing) filters which are arranged in front of the converter. Such a constellation is indicated in the application circuit in Figure 8 on page 20.

The incoming signal at the balanced input pins IFAGC1, IFAGC2 passes a power-measurement process similar to that described in the section "RF AGC Voltage-generation Block" on page 6. For flexibility reasons, no bandpass filtering is implemented. The voltage derived in this process is compared to a voltage threshold (th3) which is defined by an on-chip 4-bit D/A converter. The setting of this converter is defined by the two-wire bus bits $\mathrm{TCi}(i=1,2,3,4)$. Depending on the result of this comparison, a charge pump feeds a positive or negative current to pin CPIF in order to charge or discharge an external capacitor. By means of the pins WAGC and SLI the current of this charge pump can be selected according to the following table:
Table 2. Current of Charge Pump

| WAGC | SLI | Charge-pump Current/ $\mu \mathbf{A}$ |
| :---: | :---: | :---: |
| HIGH | X | off |
| LOW | LOW | $50 \mu \mathrm{~A}$ (slow mode) |
| LOW | HIGH | $190 \mu \mathrm{~A}$ (fast mode) |

The function can be seen in Figure 12 on page 23.

PLL Part

## Reference Oscillator

## Reference Divider

The purpose of the PLL part is to perform a phase lock of the voltage-controlled RF oscillator to an on-chip crystal reference oscillator. This is achieved by means of a special phase-noise-shaping technique based on the fractional-N principle which is already used in Atmel's U2733B frequency synthesizer series. It concentrates the phase detector's phase-noise contribution to the spectrum of the controlled VCO at frequency positions where it does not impair the quality of the received DAB signal. A special property of the transmission technique which is used in DAB is that the phase-noiseweighting function which measures the influence of the LO's phase noise to the phase information of the coded signal in a DAB receiver has zeros, i.e., if phase noise is concentrated in the position of such zeros as discrete lines, the DAB signal is not impaired as long as these lines do not exceed a set limit. For DAB mode I, this phase-noiseweighting function is shown in Figure 3.

Figure 3. Phase-noise-weighting Function


It is important to realize that this function shows zeros in all distances from the center line which are multiples of the carrier spacing. The technique of concentrating the phase noise in the positions of such zeros is patent protected.

An on-chip crystal oscillator generates the reference signal which is fed to the reference divider. As already described in the section "IF Gain-controlled Amplifier/Mixer Combination" on page 7, the LO signal for the mixer in the IF section is derived. By applying a crystal to the pins OSCI, OSCO, see Figure 8 on page 20, this oscillator generates a highly stable reference signal. If an external reference signal is available, the oscillator can be used as an input buffer. In such an application, see Figure 9 on page 21, the reference signal has to be applied to the pin OSCl and the pin OSCO must be left open.

Starting from a minimum value, the scaling factor SFref of the 9-bit reference divider is freely programmable by means of the two-wire bus bits ri $(\mathrm{i}=0, \ldots, 8)$ according to
$S F_{\text {ref }}=\sum r_{i} \times 2^{i}$

If, for example, a frequency raster of 16 kHz is requested, the scaling factor of the reference divider has to be specified in such a way that the division process results in an output frequency which is four times higher than the desired frequency raster, i.e., the comparison frequency of the phase detector equals four times the frequency raster. By changing the division ratio of the main divider from N to $\mathrm{N}+1$ in an appropriate way (fractional- N technique), this frequency raster is interpolated to deliver a frequency spacing of 16 kHz . So effectively a reference scaling divide factor

$$
S F_{\text {ref,eff }}=4 \times \sum_{i} \times 2^{i} \text { is achieved. }
$$

By setting, the two-wire bus bit T, a test signal representing the divided input signal can be monitored at the switching output SWA.

## Main Divider

The main divider consists of a fully programmable 13-bit divider which defines a division ratio N . The applied division ratio is either N or $\mathrm{N}+1$ according to the control of a special control unit. On average, the scaling factors $S F=N+k / 4$ can be selected where $k=0$, 1,2 or 3.
In this way, $V C O$ frequencies $f_{V c o}=4 \times(N+k / 4) \times f_{\text {ref }} /\left(4 \times \mathrm{SF}_{\text {ref }}\right)$ can be synthesized starting from a reference frequency fref. If we define $S F_{\text {eff }}=4 \times N+k$ and $S F_{\text {ref,eff }}=4 \times S F_{\text {ref }}$ (previous section), then $f_{\text {Vco }}=S F_{\text {eff }} \times f_{\text {ref }} / S F_{\text {ref,eff }}$, where $S F_{\text {eff }}$ is defined by 15 bits.

In the following, this circuit is described in terms of $S F_{\text {eff }}$ and $\mathrm{SF}_{\text {ref,eff }} . \mathrm{SF}_{\text {eff }}$ has to be programmed via the two-wire bus interface. An effective scaling factor from 2048 to 32767 can be selected by means of the two-wire bus bits ni $(i=0, \ldots, 14)$ according to

$$
S F_{e f f}=\sum n_{i} \times 2^{i}
$$

By setting the two-wire bus bit T , a test signal representing the divided input signal can be monitored at the switching output SWC.
When the supply voltage is switched on, both the reference divider and the programmable divider are kept in RESET state until a complete scaling factor is written onto the chip. Changes in the setting of the programmable divider become active when the corresponding two-wire bus transmission is completed. An internal synchronization procedure ensures that such changes do not become active while the charge pump is sourcing or sinking current at its output pin. This behavior allows a smooth tuning of the output frequency without restricting the controlled VCO's frequency spectrum.

## Phase Comparator and Charge Pump

The tri-state phase detector causes the charge pump to source or to sink current at the output Pin PD depending on the phase relation of its input signals which are provided by the reference and the main divider respectively. Four different values of this current can be selected by means of the two-wire bus bits 150 and I100. By use of this option, changes of the loop characteristics due to the variation of the VCO gain as a function of the tuning voltage can be reduced. The charge-pump current can be switched off using the two-wire bus bit TRI. A change in the setting of the charge pump current becomes active when the corresponding two-wire bus transmission is completed. As described for the setting of the scaling factor of the programmable divider, an internal synchronization procedure ensures that such changes do not become active while the charge pump is sourcing or sinking current at its output pin. This behavior allows a change in the charge pump current without restricting the controlled VCO's frequency spectrum.

A high-gain amplifier (output pin: VD), which is implemented in order to construct a loop filter, as shown in the application circuit, can be switched off by means of the two-wire bus bit OS.

An internal lock detector checks if the phase difference of the input signals of the phase detector is smaller than approximately 250 ns in seven subsequent comparisons. If phase lock is detected, the open collector output pin PLCK is set to H (logical value). It should be noted that the output current of this pin must be limited by external circuitry as it is not limited internally. If the two-wire bus bit TRI is set to H , the lock detector function is deactivated and the logical value of the PLCK output is undefined.

Three switching outputs controlled by the two-wire bus bits SWA, SWB, SWC can be used for any switching task on the front-end board. The currents of these outputs are not limited internally. They have to be limited by an external circuit.

Three D/A converters, A, B and C, offer the possibility of generating three output voltages at a resolution of 8 bits. These voltages appear at the output pins CAO, CBO and CCO. The converters are controlled via the two-wire bus interface by means of the control bits CA0, ..., CA7, CB0, .., CB7 and CC0, .., CC7 respectively as described in the section "Two-wire Bus Instruction Codes". The output voltages are defined as

$$
\begin{aligned}
& V_{C A O}=\frac{V_{M}}{128} \times \sum_{j=0}^{7} C A j \times 2^{j} \\
& V_{C B O}=\frac{V_{M}}{128} \times \sum_{j=0}^{7} C B j \times 2^{j} \\
& V_{C C O}=\frac{V_{M}}{128} \times \sum_{j=0}^{7} C C j \times 2^{j}
\end{aligned}
$$

where $\mathrm{VM}=4.25 \mathrm{~V}$ nominally. Due to the rail-to-rail outputs of these converters, almost the full voltage range from 0 to 8.5 V can be used. A common application of these converters is the digital synthesis of control signals for the tuning of preselectors. The output pins CAU, CBO and CCO must be blocked externally with capacitors ( 100 nF ) as shown in the application circuit (see Figure 8 on page 20).

Simple Two-wire Bus Interface

Via its two-wire bus interface, various functions can be controlled by a microprocessor. These functions are outlined in the following table "Simple Two-wire Bus Instruction Codes" on page 11 and in the section "Simple Two-wire Bus Functions" on page 11. The programming information is stored in a set of internal registers. By means of the Pin ADR, two different two-wire bus addresses can be selected as described in the section "Electrical Characteristics". In Figure 6 on page 19, the two-wire bus timing parameters are explained, Figure 7 on page 20 shows a typical two-wire bus pulse diagram.

Table 3. Simple Two-wire Bus Instruction Codes

| Description | MSB |  |  |  |  |  |  | LSB |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Address | 1 | 1 | 0 | 0 | 0 | AS1 | 0 | 0 |
| A byte 1 | 0 | 0 | X | X | X | $\mathrm{n}_{14}$ | $\mathrm{n}_{13}$ | $\mathrm{n}_{12}$ |
| A byte 2 | X | X | $\mathrm{n}_{11}$ | $\mathrm{n}_{10}$ | $\mathrm{n}_{9}$ | $\mathrm{n}_{8}$ | $\mathrm{n}_{7}$ | $\mathrm{n}_{6}$ |
| A byte 3 | X | X | $\mathrm{n}_{5}$ | $\mathrm{n}_{4}$ | $\mathrm{n}_{3}$ | $\mathrm{n}_{2}$ | $\mathrm{n}_{1}$ | $\mathrm{n}_{0}$ |
| B byte 1 | 0 | 1 | X | $\mathrm{r}_{8}$ | TA3 | TA2 | TA1 | TA0 |
| B byte 2 | $\mathrm{r}_{7}$ | $\mathrm{r}_{6}$ | $\mathrm{r}_{5}$ | $\mathrm{r}_{4}$ | TB3 | TB2 | TB1 | TB0 |
| B byte 3 | $\mathrm{r}_{3}$ | $\mathrm{r}_{2}$ | $\mathrm{r}_{1}$ | $\mathrm{r}_{0}$ | TC3 | TC2 | TC1 | TC0 |
| C byte 1 | 1 | 0 | X | X | X | X | X | X |
| C byte 2 | CA7 | CA6 | CA5 | CA4 | CA3 | CA2 | CA1 | CAO |
| C byte 3 | CB7 | CB6 | CB5 | CB4 | CB3 | CB2 | CB1 | CB0 |
| D byte 1 | 1 | 1 | 0 | OS | T | TRI | 1100 | 150 |
| D byte 2 | SWA | SWB | SWC | X | M3 | M2 | M1 | M0 |
| D byte 3 | CC7 | CC6 | CC5 | CC4 | CC3 | CC2 | CC1 | CCO |

## Simple Two-wire Bus Functions

$n_{i}$

CAi, CBi, CCi OS

T

TRI

TCi Define the setting of a 4-bit D/A converter controlling the threshold, th3, of the IF AGC to adjust the output power
Defines the two-wire bus address
Deffective scaling factor (SFeff) of the main divider $S F_{\text {eff }}=\sum n_{i} \times 2^{i}$
Scaling factor $\left(\mathrm{SF}_{\text {refe,eff }}\right)$ of the reference divider $\mathrm{SF}_{\text {ref,eff }}=4 \times \mathrm{r}_{\mathrm{i}} \mathrm{z}^{\mathrm{i}}$
Define the setting of a 4-bit D/A converter controlling the threshold, th1, of the RF AGC to adjust the controlled output power

Define the setting of a 4-bit D/A converter controlling the threshold, th2, which determines the activation voltage for the internal RF AGC -
Define the setting of the three $\mathrm{D} / \mathrm{A}$ converters $\mathrm{A}, \mathrm{B}$ and $\mathrm{C}(\mathrm{i}=0, \ldots, 7)$ OS = HIGH switches off the tuning output

For $\mathrm{T}=\mathrm{HIGH}$, reference signals describing the output frequencies of the reference divider and programmable divider are monitored at SWA (reference divider) and SWC (programmable divider).

TRI $=$ HIGH switches off the charge pump

I50 and I100 define the charge pump current:
Table 4. Current of Charge Pump

| I50 | I100 | Charge-pump Current <br> (nominal)/ $\mu \mathrm{A}$ |
| :--- | :---: | :---: |
| LOW | LOW | 50 |
| HIGH | LOW | 100 |
| LOW | HIGH | 150 |
| HIGH | HIGH | 200 |

Mi defines the operation mode:
Table 5. Mode Selection

| M3 | M2 | M1 | M0 | Mode |
| :---: | :---: | :---: | :---: | :---: |
| LOW | LOW | $X$ | $X$ | $f_{\text {LO,IFMIX }}=f_{\text {ref }}$ |
| LOW | HIGH | $X$ | $X$ | $\mathrm{f}_{\text {LO,IFMIX }}=2 \times \mathrm{f}_{\text {ref }}$ |
| HIGH | HIGH | $X$ | $X$ | IF mixer switched off |
| $X$ | $X$ | LOW | LOW | RF mixer A active, $\mathrm{f}_{\text {LO,RFMIX }}=\mathrm{f}_{\text {VCO }}$ |
| $X$ | $X$ | HIGH | LOW | RF mixer B active, $\mathrm{f}_{\text {LO,RFMIX }}=\mathrm{f}_{\text {VCO }}$ |
| $X$ | X | HIGH | HIGH | RF mixer B active, $\mathrm{f}_{\text {LO,RFMIX }}=\mathrm{f}_{\text {VCO }} / 2$ |

Note: $\quad \mathrm{SW} \alpha=$ HIGH switches on the output current $(\alpha=\mathrm{A}, \mathrm{B}, \mathrm{C})$

## Simple Two-wire Bus Data Transfer

Format:
START - ADR - ACK - <instruction set> - STOP
The <instruction set> consists of a sequence of $A$ bytes, $B$ bytes, $C$ bytes and $D$ bytes each followed by ACK. Always a triplet of these bytes (A, B, C or D) has to be completed before a new triplet is started. If no new triplet is started the transmission can be finished before the current triplet is finished.

Examples:
START - ADR - ACK - DB1 - ACK - DB2 - ACK - DB3 - ACK - CB1 - ACK - CB2 - ACK CB3 - ACK - AB1 - ACK - AB2 - ACK - AB3 - ACK - BB1 - ACK - BB2 - ACK - BB3 - ACK - STOP

START - ADR - ACK - CB1 - ACK - CB2 - ACK - STOP
However:
START - ADR - ACK - DB1 - ACK - CB1 -ACK - STOP is not allowed.
Description:

| START | Start condition |
| :--- | :--- |
| STOP | Stop condition |
| ACK | Acknowledge |
| ADR | Address byte |
| $\alpha B i$ | $\alpha$ byte $\mathrm{i}(\alpha=\mathrm{A}, \mathrm{B}, \mathrm{C}, \mathrm{D} ; \mathrm{i}=1,2,3)$ |

## Simple Two-wire Bus Timing

The values of the periods shown are specified in the table "Electrical Characteristics" on page 15. More detailed information can be taken from the "Application Note 1.0 (Twowire Bus Description)". Please note, that due to the two-wire bus specification, the MSB of a byte is transmitted first, the LSB last.

Figure 4. Two-wire Bus Timing


Figure 5. Typical Pulse Diagram



## Absolute Maximum Ratings

| Parameters | Symbol | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: |
| Supply voltage | $\mathrm{V}_{\text {S }}$ | -0.3 | +9.5 | V |
| Junction temperature | $\mathrm{T}_{\mathrm{j}}$ |  | 150 | ${ }^{\circ} \mathrm{C}$ |
| Storage temperature | $\mathrm{T}_{\text {stg }}$ | -40 | +150 | ${ }^{\circ} \mathrm{C}$ |
| Differential input RF amplifier, pins 12 and 13 | $\mathrm{V}_{\text {RFA } 1,2}$ |  | 500 | $\mathrm{mV}_{\text {rms }}$ |
| Pins 14 and 15 | $\mathrm{V}_{\text {RFB1,2 }}$ |  | 500 | $\mathrm{mV}_{\text {rms }}$ |
| Externally applied voltage at RF charge pump output, pin 16 | $\mathrm{V}_{\text {CPRF }}$ | 0.5 | 6.75 | V |
| Pin 28 | $\mathrm{V}_{\text {CPIF }}$ | 0.5 | 6.25 | V |
| WAGC input voltage, pin 22 | $\mathrm{V}_{\text {WAGC }}$ | -0.3 | 5.5 | V |
| SLI input voltage, pin 21 | $\mathrm{V}_{\text {SLI }}$ | -0.3 | 5.5 | V |
| Differential base input VCO, pins 33 and 34 | $\mathrm{V}_{\text {BivC }}$ |  | 500 | $\mathrm{mV}_{\text {rms }}$ |
| Differential input IF amplifier, pins 23 and 24 | $\mathrm{V}_{\text {IFIN }}$ |  | 500 | $\mathrm{mV}_{\text {rms }}$ |
| Differential input IF AGC block, pins 26 and 27 | $\mathrm{V}_{\text {IFAGCIN }}$ |  | 500 | $\mathrm{mV}_{\text {rms }}$ |
| Reference input voltage (AC), pin 42 | $\mathrm{V}_{\text {OSCI }}$ |  | 1 | $\mathrm{V}_{\mathrm{pp}}$ |
| Two-wire bus input/output voltage, pins 1 and 2 | SCL, SDA | -0.3 | 5.5 | V |
| SDA output current, pin 2 | SDA |  | 5 | mA |
| Address select voltage, pin 44 | ADR | -0.3 | 5.5 | V |
| Switch output voltage; pins 3, 4 and 6 | SW $\alpha$ | -0.3 | 9.5 | V |
| Switch output current | SW $\alpha$ |  | 4 | mA |
| PLCK output voltage, pin 41 | PLCK | -0.3 | 5.5 | V |
| PLCK output current, pin 41 | PLCK |  | 0.5 | mA |

## Thermal Resistance

| Parameters | Symbol | Value | Unit |
| :--- | :---: | :---: | :---: |
| Junction ambient (soldered on application board) | $\mathrm{R}_{\mathrm{thJA}}$ | 40 | $\mathrm{~K} / \mathrm{W}$ |

## Operating Range

| Parameters | Symbol | Value | Unit |
| :--- | :---: | :---: | :---: |
| Supply voltage | $\mathrm{V}_{\mathrm{S}}$ | 8.0 to 9.35 | V |
| Ambient temperature range | $\mathrm{T}_{\mathrm{amb}}$ | -40 to +85 | ${ }^{\circ} \mathrm{C}$ |

## Electrical Characteristics

Test conditions (unless otherwise specified): $\mathrm{V}_{\mathrm{S}}=8.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Overall Characteristics |  | 20, 25, 38 |  |  |  |  |  |  |
| 1.1 | Supply voltage |  |  | $\mathrm{V}_{\mathrm{S}}$ | 8.0 | 8.5 | 9.35 | V |  |
| 1.2 | Minimum supply current | $\begin{aligned} & \mathrm{V}(\mathrm{CPRF})=\mathrm{V}(\mathrm{CPIF})<0.8 \mathrm{~V} \\ & \mathrm{M} 3=\mathrm{M} 2=\mathrm{HIGH} \\ & \mathrm{M} 1=\mathrm{MO}=\mathrm{LOW} \\ & \mathrm{TAi}=\mathrm{TCi}=0000 ; \mathrm{TBi}=1000 \\ & \mathrm{SWA}=\mathrm{SWB}=\mathrm{SWC}=\mathrm{LOW} \\ & \mathrm{TRI}=\mathrm{LOW} ; \mathrm{PLCK}=\mathrm{LOW} \\ & \mathrm{I} 100=150=\text { LOW; V(ADR })=\text { open } \\ & \text { SLI }=\text { LOW } ; \text { WAGC }=\mathrm{HIGH} \end{aligned}$ |  | $\mathrm{I}_{\mathrm{S} \text {, min }}$ |  | 74 |  | mA | B |
| 1.3 | Maximum supply current | $\begin{aligned} & 3.4 \mathrm{~V}=\mathrm{V}(\mathrm{CPRF})=\mathrm{V}(\mathrm{CPIF}) \\ & <3.6 \mathrm{~V} ; \mathrm{M} 3=\mathrm{M} 2=\mathrm{HIGH} \\ & \mathrm{M} 1=\mathrm{MO}=\mathrm{LOW} \\ & \mathrm{TAi}=\mathrm{TCi}=0000 ; \mathrm{TBi}=1000 \\ & \mathrm{SWA}=\mathrm{LOW} ; \mathrm{SWB}=\mathrm{LOW} \\ & \mathrm{SWC}=\mathrm{LOW} ; \mathrm{TRI}=\mathrm{LOW} \\ & \mathrm{PLCK}=\mathrm{LOW} ; \mathrm{I} 100=\mathrm{I} 50=\mathrm{LOW} \\ & \mathrm{~V}(\mathrm{ADR})=\text { open; SLI = LOW } \\ & \mathrm{WAGC}=\mathrm{HIGH} \end{aligned}$ |  | $\mathrm{I}_{\mathrm{S}, \text { max }}$ |  | 79 |  | mA | B |
| 2 | RF Part |  |  |  |  |  |  |  |  |
| 2.1 | Voltage gain | RFA1, RFA2; RFB1, RFB2) $\rightarrow$ SAW1, SAW2 <br> (see Figure 9 on page 21) | $\begin{gathered} 12(14) \\ \rightarrow 18,19 \end{gathered}$ | $\mathrm{G}_{\mathrm{V}, \mathrm{RF}}$ | 20 | 24 | 26 | dB | A |
| 2.2 | AGC range RF |  |  |  | 23 | 27 | 29 | dB | A |
| 2.3 | Noise figure (double side band) | RFA1, (RFB1) $\rightarrow$ SAW1, SAW2; RFA2, RFB2 blocked | $\begin{gathered} 12(14) \\ \rightarrow 19 \end{gathered}$ | $N F_{\text {DSB,RF }}$ |  | 12 |  | dB | D |
| 2.4 | Maximum input power level | Differential, 3rd order intermodulation distance $\geq 40 \mathrm{dBc}$, Pout $=-19 \mathrm{dBm}, \mathrm{TAi}=0000$, $R L(S A W 1, S A W 2)=200 \Omega$ | $\left.\left\lvert\, \begin{array}{c} 12,13 \\ (14,15) \end{array}\right.\right)$ | $\mathrm{P}_{\mathrm{in}, \text { max, MIX }}$ | -10 |  |  | dBm | A |
| 2.5 | Input frequency range |  | $\begin{gathered} 12,13 \\ (14,15) \end{gathered}$ | $\mathrm{f}_{\mathrm{in}, \mathrm{RF}}$ | 70 |  | 260 | MHz | B |
| 2.6 | Input impedance | Single ended | 12 (14) | $\mathrm{Z}_{\mathrm{in}, \mathrm{RF}}$ |  | 1.3 |  | k $\Omega$ | D |
| 2.7 | Output frequency range for AGC-voltage generation |  | 18, 19 | $\mathrm{f}_{\text {out,SAW }}$ |  | $\begin{gathered} 38,912 \\ \pm 5 \end{gathered}$ |  | MHz | D |
| 2.8 | Maximum output power level | Output power, differential; RL (SAW1, SAW2) > $200 \Omega$, TAi $=0000$ | 18, 19 |  |  | -7 |  | dBm | D |
| 2.9 | AGC threshold (th1) $\begin{aligned} & \mathrm{TAi}=' 1000 \prime \\ & \mathrm{TAi}=‘ 1111 \\ & \mathrm{TAi}=‘ 0000 \prime \end{aligned}$ | Output power, differential controlled by two-wire bus bits TAi; RL $($ SAW1, SAW2 $)=200 \Omega$ | 18, 19 | $\mathrm{p}_{\text {TH,RF }}$ | 50 | $\begin{gathered} 90 \\ 160 \\ 10 \end{gathered}$ | 120 | $m V_{\text {rms }}$ | $\begin{aligned} & \text { A } \\ & \text { B } \\ & \text { B } \end{aligned}$ |

${ }^{*}$ ) Type means: $A=100 \%$ tested, $B=100 \%$ correlation tested, $C=$ Characterized on samples, $D=$ Design parameter
Note: 1. The phase detector's phase-noise contribution to the VCO's frequency spectrum is determined by the operating frequency of the phase detector divided by 4 according to the fractional- N technique (regularly: 16 kHz ).

Electrical Characteristics (Continued)
Test conditions (unless otherwise specified): $\mathrm{V}_{\mathrm{S}}=8.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2.10 | AGC threshold (th2) (internal AGC) <br> upper limit $(\mathrm{TBi}=1111)$ <br> lower limit $(\mathrm{TBi}=0000)$ | Controlled by two-wire bus bits TBi; $\mathrm{P}_{\mathrm{IN}, \mathrm{MAX}}=-25 \mathrm{dBm}$ | 16 | $\mathrm{V}_{\text {int AGC, RF }}$ | 1.0 | $\begin{aligned} & 5.1 \\ & 1.5 \end{aligned}$ | 1.8 | $\begin{aligned} & \text { V } \\ & \text { V } \end{aligned}$ | $\begin{aligned} & \mathrm{B} \\ & \mathrm{~A} \end{aligned}$ |
| 2.11 | Output impedance | Single ended; f(SAW1) = 39 MHz | 18 (19) | $\mathrm{Z}_{\text {out,SAW }}$ |  | 30 |  | $\Omega$ |  |
| 3 | VCO |  |  |  |  |  |  |  |  |
| 3.1 | Phase noise | $\Delta \mathrm{f}=10 \mathrm{kHz}$ |  | L(f) |  | -88 |  | $\mathrm{dBc} / \mathrm{Hz}$ | D |
| 3.2 | Phase noise |  |  | $\mathrm{f}_{\mathrm{LO}}$ | 100 |  | 400 | MHz | D |
| 4 | IF Part |  |  |  |  |  |  |  |  |
| 4.1 | Voltage gain | IFIN2 blocked (see Figure 9 on page 21) $\mathrm{f}_{\text {LO,IFMIX }}=\mathrm{f}_{\text {ref }}$ or $\mathrm{F}_{\text {LO,IFMIX }}=2 \times \mathrm{f}_{\text {ref }}$ | $24 \rightarrow 29$ | $\mathrm{G}_{\mathrm{V}, \text { tot }}$ | 42 | 44 | 48 | dB | A |
| 4.2 | Voltage gain | IFIN2 blocked (see Figure 9 on page 21) IF mixer switched off | $24 \rightarrow 29$ | $\mathrm{G}_{\mathrm{V}, \text { tot }}$ | 45 | 47 | 51 | dB | A |
| 4.3 | AGC range IF |  |  |  | 42 | 44 | 48 | dB | A |
| 4.4 | Noise figure (double side band) | IFIN2 blocked | $24 \rightarrow 29$ | $N F_{\text {DSB }}$ |  | 11 |  | dB | D |
| 4.5 | Maximum input power level | IFIN2 blocked, 3rd order intermodulation distance $\geq 40 \mathrm{dBc}$; RL(IFOUT) $=1 \mathrm{k} ; \mathrm{TCi}=0000$; $\mathrm{R}_{10}=4.7 \mathrm{k}, \mathrm{R}_{11}=1.8 \mathrm{k}$ | 24 | $\mathrm{P}_{\text {in,max }}$ | -20 |  |  | dBm | C |
| 4.6 | Input frequency range |  | 23, 24 | $\mathrm{f}_{\text {in,IFIN }}$ | 10 |  | 60 | MHz | D |
| 4.7 | Input impedance | IFIN2 blocked, $\mathrm{f}_{\text {IF,IFIN }}=38.912 \mathrm{MHz}$ | 23, 24 | $\mathrm{Z}_{\text {in,IFIN }}$ |  | $\begin{aligned} & 600- \\ & \text { j1000 } \end{aligned}$ |  | $\Omega$ | D |
| 4.8 | Output frequency range | Single ended | 29 | $\mathrm{f}_{\text {out, IFO }}$ | 1 |  | 45 | MHz | D |
| 4.9 | Output impedance | Single ended <br> $\mathrm{f}_{\text {out, IFO }}$ (3 MHz) <br> $\mathrm{f}_{\text {out, IFo }}(20 \mathrm{MHz})$ <br> $\mathrm{f}_{\text {out, IFO }}(38.9 \mathrm{MHz}$ ) | 29 | $\mathrm{Z}_{\text {out,IFOUT }}$ |  | $\begin{aligned} & 20+j 50 \\ & 65+j 35 \\ & 58-j 25 \end{aligned}$ |  | $\begin{aligned} & \Omega \\ & \Omega \\ & \Omega \end{aligned}$ | D |
| 5 | RF AGC Unit |  |  |  |  |  |  |  |  |
| 5.1 | Positive charge pump current, fast mode | $\begin{aligned} & \mathrm{V}_{\mathrm{WAGC}}=\mathrm{LOW} \\ & \mathrm{~V}_{\mathrm{SLI}}=\mathrm{HIGH} \end{aligned}$ | 16 | $\mathrm{ICPRF}_{\text {POs, } \mathrm{Fm}}$ | 145 | 180 | 220 | $\mu \mathrm{A}$ | A |
| 5.2 | Negative charge pump current, fast mode | $\begin{aligned} & \mathrm{V}_{\text {WAGC }}=\mathrm{LOW} \\ & \mathrm{~V}_{\mathrm{SLI}}=\mathrm{HIGH} \end{aligned}$ | 16 | ICPRF $_{\text {NEG, FM }}$ | -220 | -180 | -145 | $\mu \mathrm{A}$ | A |
| 5.3 | Positive charge pump current, slow mode | $\begin{aligned} & \mathrm{V}_{\mathrm{WAGC}}=\mathrm{LOW} \\ & \mathrm{~V}_{\mathrm{SLI}}=\mathrm{LOW} \end{aligned}$ | 16 | $\mathrm{ICPRF}_{\text {POS,SM }}$ | 30 | 40 | 52 | $\mu \mathrm{A}$ | A |
| 5.4 | Negative charge pump current, fast mode | $\begin{aligned} & \mathrm{V}_{\mathrm{WAGC}}=\mathrm{LOW} \\ & \mathrm{~V}_{\mathrm{SLI}}=\mathrm{LOW} \end{aligned}$ | 16 | $\mathrm{ICPRF}_{\text {NEG,FM }}$ | -52 | -40 | -30 | $\mu \mathrm{A}$ | A |
| 5.5 | Minimum gain control voltage |  |  | $\mathrm{VAGC}_{\text {min }}$ |  | 0.75 |  | V | C |

${ }^{*}$ ) Type means: $A=100 \%$ tested, $B=100 \%$ correlation tested, $C=$ Characterized on samples, $D=$ Design parameter
Note: 1. The phase detector's phase-noise contribution to the VCO's frequency spectrum is determined by the operating frequency of the phase detector divided by 4 according to the fractional- N technique (regularly: 16 kHz ).

## Electrical Characteristics (Continued)

Test conditions (unless otherwise specified): $\mathrm{V}_{\mathrm{S}}=8.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 5.6 | Maximum gain control voltage |  |  | $\mathrm{VAGC}_{\text {max }}$ |  | 6.6 |  | V | C |
| 6 | IF AGC Unit |  |  |  |  |  |  |  |  |
| 6.1 | Positive charge pump current, fast mode | $\begin{aligned} & \mathrm{V}_{\text {WAGC }}=\mathrm{LOW} \\ & \mathrm{~V}_{\mathrm{SLI}}=\mathrm{HIGH} \end{aligned}$ | 28 | $\mathrm{ICPIF}_{\text {POS,FM }}$ | 145 | 180 | 220 | $\mu \mathrm{A}$ | A |
| 6.2 | Negative charge pump current, fast mode | $\begin{aligned} & \mathrm{V}_{\text {WAGC }}=\mathrm{LOW} \\ & \mathrm{~V}_{\mathrm{SLI}}=\mathrm{HIGH} \end{aligned}$ | 28 | $\mathrm{ICPIF}_{\text {NEG, FM }}$ | -220 | -180 | -145 | $\mu \mathrm{A}$ | A |
| 6.3 | Positive charge pump current, slow mode | $\begin{aligned} & \mathrm{V}_{\text {WAGC }}=\mathrm{LOW} \\ & \mathrm{~V}_{\mathrm{SLI}}=\mathrm{LOW} \end{aligned}$ | 28 | $\mathrm{ICPIF}_{\mathrm{POS}, \mathrm{sm}}$ | 30 | 40 | 52 | $\mu \mathrm{A}$ | A |
| 6.4 | Negative charge pump current, slow mode | $\begin{aligned} & \mathrm{V}_{\text {WAGC }}=\mathrm{LOW} \\ & \mathrm{~V}_{\mathrm{SLI}}=\mathrm{LOW} \end{aligned}$ | 28 | $\mathrm{ICPIF}_{\text {NEG, SM }}$ | -52 | -40 | -30 | $\mu \mathrm{A}$ | A |
| 6.5 | Window AGC mode charge pump current | $\mathrm{V}_{\text {WAGC }}=\mathrm{HIGH}$ | 28 | $I_{\text {ICPIF }}^{\text {WAGC }}$ | -4 | 0 | +4 | $\mu \mathrm{A}$ | A |
| 6.6 | Minimum gain control voltage |  | 28 | $\mathrm{VAGCIF}_{\text {min }}$ |  | 0.75 |  | V | C |
| 6.7 | Maximum gain control voltage |  | 28 | VAGCIF $_{\text {max }}$ |  | 5.9 |  | V | C |
| 6.8 | Control voltage for activated WAGC | WAGC $=$ HIGH | 22 | VWAGC $_{\text {High }}$ | 2.0 |  |  | V | A |
| 6.9 | Control voltage for deactivated WAGC | WAGC = LOW | 22 | VWAGC ${ }_{\text {Low }}$ |  |  | 0.7 | V | A |
| 6.10 | Control voltage for activated SLI | SLI $=$ HIGH | 21 | $\mathrm{VSLI}_{\text {High }}$ | 2.0 |  |  | V | A |
| 6.11 | Control voltage for deactivated SLI | SLI = LOW | 21 | VSLI ${ }_{\text {Low }}$ |  |  | 0.7 |  | A |
| 7 | PLL Part |  |  |  |  |  |  |  |  |
| 7.1 | Effective scaling factor of programmable divider |  |  | $\mathrm{SF}_{\text {eff }}$ | 2048 |  | 32766 |  | D |
| 7.2 | Effective scaling factor of reference divider |  |  | $S F_{\text {ref,eff }}$ | 144 |  | 2047 |  | D |
| 7.3 | Tuning step |  |  |  |  | 16 |  | kHz | D |
| 8 | REF Input 42 |  |  |  |  |  |  |  |  |
| 8.1 | Input frequency range | Internal oscillator overdriven |  | $\mathrm{f}_{\text {ref }}$ | 5 |  | 30 | MHz | B |
| 8.2 | Input sensitivity | Internal oscillator overdriven |  | $\mathrm{V}_{\text {ref, min }}$ |  |  | 50 | $\mathrm{mV}_{\text {rms }}$ | A |
| 8.3 | Maximum input signal | Internal oscillator overdriven |  | $\mathrm{V}_{\text {ref,max }}$ | 300 |  |  | $\mathrm{mV}_{\text {rms }}$ | D |
| 8.4 | Input impedance | Single ended |  | $\mathrm{Z}_{\text {ref }}$ |  | 2 \|| 2.5 |  | k $/$ /pF | D |
| 9 | REF Output 5 |  |  |  |  |  |  |  |  |
| 9.1 | Output voltage | $1.5 \mathrm{k} \Omega$ \|| 2.5 pF load |  | $\mathrm{V}_{\text {out,ref }}$ | 65 | 100 |  | $\mathrm{mV}_{\text {rms }}$ | A |

*) Type means: $A=100 \%$ tested, $B=100 \%$ correlation tested, $C=$ Characterized on samples, $D=$ Design parameter
Note: 1. The phase detector's phase-noise contribution to the VCO's frequency spectrum is determined by the operating frequency of the phase detector divided by 4 according to the fractional- N technique (regularly: 16 kHz ).

Electrical Characteristics (Continued)
Test conditions (unless otherwise specified): $\mathrm{V}_{\mathrm{S}}=8.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$

${ }^{*}$ ) Type means: $A=100 \%$ tested, $B=100 \%$ correlation tested, $C=$ Characterized on samples, $D=$ Design parameter
Note: 1. The phase detector's phase-noise contribution to the VCO's frequency spectrum is determined by the operating frequency of the phase detector divided by 4 according to the fractional- N technique (regularly: 16 kHz ).

## Electrical Characteristics (Continued)

Test conditions (unless otherwise specified): $\mathrm{V}_{\mathrm{S}}=8.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{amb}}=25^{\circ} \mathrm{C}$

| No. | Parameters | Test Conditions | Pin | Symbol | Min. | Typ. | Max. | Unit | Type* |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 15.8 | SCL HIGH period |  |  | $\mathrm{t}_{\text {high }}$ | 4 |  |  | $\mu \mathrm{s}$ | D |
| 15.9 | SCL LOW period |  |  | $t_{\text {low }}$ | 4.7 |  |  | $\mu \mathrm{s}$ | D |
| 15.10 | Hold time START |  |  | $\mathrm{t}_{\text {hdsta }}$ | 4 |  |  | $\mu \mathrm{s}$ | D |
| 15.11 | Setup time START |  |  | $\mathrm{t}_{\text {susta }}$ | 4.7 |  |  | $\mu \mathrm{s}$ | D |
| 15.12 | Setup time STOP |  |  | $\mathrm{t}_{\text {sustp }}$ | 4.7 |  |  | $\mu \mathrm{s}$ | D |
| 15.13 | Hold time DATA |  |  | $t_{\text {nddat }}$ | 0 |  |  | $\mu \mathrm{s}$ | D |
| 15.14 | Setup time DATA |  |  | $\mathrm{t}_{\text {sudat }}$ | 250 |  |  | ns | D |

${ }^{*}$ ) Type means: $A=100 \%$ tested, $B=100 \%$ correlation tested, $C=$ Characterized on samples, $D=$ Design parameter
Note: 1. The phase detector's phase-noise contribution to the VCO's frequency spectrum is determined by the operating frequency of the phase detector divided by 4 according to the fractional- N technique (regularly: 16 kHz ).

Figure 6. Application Circuit


## Application Circuits of the Reference Oscillator

Figure 7. Oscillator Operation


Figure 8. Oscillator Overdriven


Figure 9. Measurement Circuit for Electrical Characteristics


Figure 10. RFAGC Voltage-generation Block Circuit


Figure 11. IFAGC Voltage-generation Block Circuit


Figure 12. VCO Circuit


Phase-noise Performance
(Example: $\mathrm{SF}_{\text {eff }}=16899, \mathrm{SF}_{\text {ref,eff }}=1120, \mathrm{f}_{\mathrm{ref}}=17.92 \mathrm{MHz}, \mathrm{I}_{\mathrm{PD}}=200 \mathrm{~mA}$, spectrum analysis: HP7000)

Figure 13. Phase-noise Over Frequency

$10.00 \mathrm{~dB} /$ DIV


CENTER 270.384 MHz RB $1.00 \mathrm{kHz} \quad$ VB 1.00 kHz

SPAN 200.0 kHz ST 600.0 msec

Ordering Information

| Extended Type Number | Package | Remarks |
| :--- | :---: | :--- |
| U2731B-NFN | SSO44 | Tube |
| U2731B-NFNG1 | SSO44 | Taped and reeled |

Package Information


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- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.


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