

CY7B991V

3.3 V RoboClock[®] Low Voltage Programmable Skew Clock Buffer

Features

- All output pair skew <100 ps typical (250 ps max)
- 3.75 MHz to 80 MHz output operation
- User-selectable output functions:
	- ❐ Selectable skew up to 18 ns
	- ❐ Inverted and non-inverted
	- ❐ Operation at one-half and one-quarter input frequency
	- ❐ Operation at 2 × and 4 × input frequency (input as low as 3.75 MHz)
- Zero input to output delay
- 50% duty cycle outputs
- Low-voltage transistor-transistor logic (LVTTL) outputs drive 50 Ω terminated lines
- Operates from a single 3.3 V supply
- Low operating current
- 32-pin plastic leaded chip carrier (PLCC) package
- Low cycle-to-cycle jitter (100 ps typical)

Functional Description

The CY7B991V 3.3 V RoboClock[®] low-voltage programmable skew clock buffer (LVPSCB) offers user-selectable control over system clock functions. These multiple output clock drivers provide the system integrator with functions necessary to optimize the timing of high-performance computer systems. Each of the eight individual drivers – arranged in four pairs of user controllable outputs – can drive terminated transmission lines with impedances as low as 50 Ω . This delivers minimal output skews and full-swing logic levels (LVTTL).

Each output is hardwired to one of nine delay or function configurations. Delay increments of 0.7 to 1.5 ns are determined by the operating frequency, with outputs able to skew up to ± 6 time units from their nominal 'zero' skew position. The completely-integrated phase-locked loop (PLL) allows external load and transmission line delay effects to be canceled. When this 'zero delay' capability of the LVPSCB is combined with the selectable output skew functions, the user can create output-to-output delays of up to ±12 time units.

Divide-by-two and divide-by-four output functions are provided for additional flexibility in designing complex clock systems. When combined with the internal PLL, these divide functions enable distribution of a low frequency clock that is multiplied by two or four at the clock destination. This feature minimizes clock distribution difficulty, allowing maximum system clock speed and flexibility.

For a complete list of related resources, [click here.](http://www.cypress.com/?rID=13826)

Logic Block Diagram

Contents

Pinouts

Pin Definitions

Block Diagram Description

Phase Frequency Detector and Filter

The phase frequency detector and filter blocks accept inputs from the reference frequency (REF) input and the feedback (FB) input. They generate correction information to control the frequency of the voltage controlled oscillator (VCO). These blocks, along with the VCO, form a PLL that tracks the incoming REF signal.

VCO and Time Unit Generator

The VCO accepts analog control inputs from the PLL filter block. It generates a frequency that is used by the time unit generator to create discrete time units, selected in the skew select matrix. The operational range of the VCO is determined by the FS control pin. The time unit (t_U) is determined by the operating frequency of the device and the level of the FS pin as shown in [Table 1.](#page-3-4)

Skew Select Matrix

The skew select matrix is comprised of four independent sections. Each section has two low-skew, high fanout drivers (xQ0, xQ1), and two corresponding three-level function select (xF0, xF1) inputs. [Table 2](#page-3-5) shows the nine possible output functions for each section as determined by the function select inputs. All times are measured with respect to the REF input assuming that the output connected to the FB input has $0t_{U}$ selected.

Notes

- 1. For all three state inputs, HIGH indicates a connection to V_{CC} , LOW indicates a connection to GND, and MID indicates an open connection. Internal termination circuitry holds an unconnected input to $V_{CC}/2$.
- 2. The level to be set on FS is determined by the "normal" operating frequency (f_{NOM}) of the V_{CO} and Time Unit Generator (see [Logic Block Diagram](#page-0-0)). Nominal frequency (f_{NOM}) always appears at the outputs when they ar using a divided output as the FB input.
- 3. When the FS pin is selected HIGH, the REF input must not transition upon power up until V_{CC} has reached 2.8 V.

Test Mode

The TEST input is a three-level input. In normal system operation, this pin is connected to ground, allowing the CY7B991V to operate as explained in the [Block Diagram Description on page 4.](#page-3-0) For testing purposes, any of the three-level inputs can have a removable jumper to ground or be tied LOW through a 100- Ω resistor. This enables an external tester to change the state of these pins.

If the TEST input is forced to its MID or HIGH state, the device operates with its internal phase locked loop disconnected, and input levels supplied to REF directly controls all outputs. Relative output to output functions are the same as in normal mode.

In contrast with normal operation (TEST tied LOW), all outputs function based only on the connection of their own function select inputs (xF0 and xF1) and the waveform characteristics of the REF input.

Figure 2. Typical Outputs with FB Connected to a Zero Skew Output Test Mode [4]

Note 4. FB connected to an output selected for "zero" skew (that is, xF1 = xF0 = MID).

Operational Mode Descriptions

[Figure 2](#page-4-1) shows the LVPSCB configured as a zero skew clock buffer. In this mode, the CY7B991V is the basis for a low-skew clock distribution tree. When all of the function select inputs (×F0, ×F1) are left open, the outputs are aligned and drive a terminated transmission line to an independent load. The FB input is tied to any output in this configuration and the operating frequency range is selected with the FS pin. The low skew specification, coupled with the ability to drive terminated transmission lines (with impedances as low as 50 Ω), enables efficient printed circuit board design.

Figure 4. Programmable Skew Clock Driver

[Figure 4](#page-5-1) shows a configuration to equalize skew between metal traces of different lengths. In addition to low skew between outputs, the LVPSCB is programmed to stagger the timing of its outputs. The four groups of output pairs are each programmed to different output timing. Skew timing is adjusted over a wide range in small increments using the function select pins. In this configuration, the 4Q0 output is sent back to FB and configured for zero skew. The other three pairs of outputs are programmed to yield different skews relative to the feedback. By advancing the clock signal on the longer traces or retarding the clock signal on shorter traces, all loads receive the clock pulse at the same time.

[Figure 4](#page-5-1) shows the FB input connected to an output with 0 ns skew (xF1, xF0 = MID) selected. The internal PLL synchronizes the FB and REF inputs and aligns their rising edges to make certain that all outputs have precise phase alignment.

Clock skews are advanced by ±6 time units (tU) when using an output selected for zero skew as the feedback. A wider range of delays is possible if the output connected to FB is also skewed. Since "Zero Skew", +tU, and –tU are defined relative to output groups, and the PLL aligns the rising edges of REF and FB, wider output skews are created by proper selection of the xFn inputs. For example, a +10 tU between REF and 3Qx is achieved by connecting 1Q0 to FB and setting 1F0 = 1F1 = GND, 3F0 = MID, and $3F1 =$ High. (Since FB aligns at -4 tU, and $3Qx$ skews to $+6$ tU, a total of +10 tU skew is realized.) Many other configurations are realized by skewing both the outputs used as the FB input and skewing the other outputs.

Figure 5. Inverted Output Connections

[Figure 5](#page-6-0) shows an example of the invert function of the LVPSCB. In this example the 4Q0 output used as the FB input is programmed for invert (4F0 = $4F1$ = HIGH) while the other three pairs of outputs are programmed for zero skew. When 4F0 and 4F1 are tied high, 4Q0 and 4Q1 become inverted zero phase outputs. The PLL aligns the rising edge of the FB input with the rising edge of the REF. This causes the 1Q, 2Q, and 3Q outputs to become the "inverted" outputs to the REF input. By selecting the output connected to FB, you can have two inverted and six non-inverted outputs or six inverted and two non-inverted outputs. The correct configuration is determined by the need for more (or fewer) inverted outputs. 1Q, 2Q, and 3Q outputs can also be skewed to compensate for varying trace delays independent of inversion on 4Q.

[Figure 6](#page-6-1) shows the LVPSCB configured as a clock multiplier. The 3Q0 output is programmed to divide by four and is sent back to FB. This causes the PLL to increase its frequency until the 3Q0 and 3Q1 outputs are locked at 20 MHz, while the 1Qx and 2Qx outputs run at 80 MHz. The 4Q0 and 4Q1 outputs are programmed to divide by two that results in a 40 MHz waveform at these outputs. Note that the 20- and 40-MHz clocks fall simultaneously and are out of phase on their rising edge. This enables the designer to use the rising edges of the $\sqrt{2}$ frequency and 1⁄4 frequency outputs without concern for rising edge skew. The 2Q0, 2Q1, 1Q0, and 1Q1 outputs run at 80 MHz and are skewed by programming their select inputs accordingly. Note that the FS pin is wired for 80 MHz operation as that is the frequency of the fastest output.

[Figure 7](#page-6-2) shows the LVPSCB in a clock divider application. 2Q0 is sent back to the FB input and programmed for zero skew. 3Qx is programmed to divide by four. 4Qx is programmed to divide by two. Note that the falling edges of the 4Qx and 3Qx outputs are aligned. This enables use of the rising edges of the $1/2$ frequency and 1⁄4 frequency without concern for skew mismatch. The 1Qx outputs are programmed to zero skew and are aligned with the 2Qx outputs. In this example, the FS input is grounded to configure the device in the 15 to 30 MHz range since the highest frequency output is running at 20 MHz.

[Figure 8 on page 8](#page-7-0) shows some of the functions that are selectable on the 3Qx and 4Qx outputs. These include inverted outputs and outputs that offer divide-by-2 and divide-by-4 timing. An inverted output enables the system designer to clock different subsystems on opposite edges without suffering from the pulse asymmetry typical of non-ideal loading. This function enables each of the two subsystems to clock 180 degrees out of phase, but still is aligned within the skew specification.

The divided outputs offer a zero delay divider for portions of the system that divide the clock by either two or four, and still remain within a narrow skew of the "1X" clock. Without this feature, an external divider is added, and the propagation delay of the divider adds to the skew between the different clock signals.

These divided outputs, coupled with the PLL, enable the LVPSCB to multiply the clock rate at the REF input by either two or four. This mode allows the designer to distribute a low frequency clock between various portions of the system. It also locally multiplies the clock rate to a more suitable frequency, while still maintaining the low skew characteristics of the clock driver. The LVPSCB performs all of the functions described in this section at the same time. It can multiply by two and four or divide by two (and four) at the same time that it shifts its outputs over a wide range or maintains zero skew between selected outputs.

Figure 8. Multi-Function Clock Driver

Figure 9. Board-to-Board Clock Distribution

[Figure 9](#page-7-1) shows the CY7B991V connected in series to construct a zero skew clock distribution tree between boards. Delays of the downstream clock buffers are programmed to compensate for the wire length (that is, select negative skew equal to the wire delay) necessary to connect them to the master clock source, approximating a zero delay clock tree. Cascaded clock buffers accumulate low frequency jitter because of the non-ideal filtering characteristics of the PLL filter. Do not connect more than two clock buffers in a series.

Maximum Ratings

Operating outside these boundaries may affect the performance and life of the device. These user guidelines are not tested.

Operating Range

Electrical Characteristics

Over the Operating Range

Notes

5. See the last page of this specification for Group A subgroup testing information.

6. These inputs are normally wired to V_{CC}, GND, or left unconnected (actual threshold voltages vary as a percentage of V_{CC}). Internal termination resistors hold
unconnected inputs at V_{CC}/2. If these inputs are switc

7. CY7B991V is tested one output at a time, output shorted for less than one second, less than 10% duty cycle. Room temperature only.
8. Total output current per output pair is approximated by the following expression tha

C = capacitive load in pF Z = line impedance in ohms N = number of loaded outputs; 0, 1, or 2

 $FC = F \times C$

Electrical Characteristics (continued)

Over the Operating Range

Capacitance

Thermal Resistance

AC Test Loads and Waveforms

Figure 10. AC Test Loads and Waveforms

R1=100 R2=100 CL = 30 pF (Includes fixture and probe capacitance)

Notes

9. Applies to REF and FB inputs only. Tested initially and after any design or process changes that may affect these parameters. 10. Tested initially and after any design or process changes that may affect these parameters.

Switching Characteristics (-2 option)

Over the Operating Range

Notes

- 11. The level to be set on FS is determined by the "normal" operating frequency (f_{NOM}) of the V_{CO} and Time Unit Generator (see [Logic Block Diagram](#page-0-0)). Nominal frequency
(f_{NOM}) always appears at the outputs when they a
- 12. Test measurement levels for the CY7B991V are TTL levels (1.5 V to 1.5 V). Test conditions assume signal transition times of 2 ns or less and output loading as shown in the AC Test Loads and Waveforms unless otherwise specified.

13. For all three state inputs, HIGH indicates a connection to V_{CC}, LOW indicates a connection to GND, and MID indicates an open connection. Internal termination circuitry holds an unconnected input to V_{CC}/2.

- 14. When the FS pin is selected HIGH, the REF input must not transition upon power up until V_{CC} has reached 2.8 V.
15. SKEW is defined as the time between the earliest and the latest output transition among all outputs
-

16. t_{SKEWPR} is defined as the skew between a pair of outputs (XQ0 and XQ1) when all eight outputs are selected for 0t_U.
17. t_{SKEW0} is defined as the skew between outputs when they are selected for 0t_U. Other output

- 18. There are three classes of outputs: Nominal (multiple of t_U delay), Inverted (4Q0 and 4Q1 only with 4F0 = 4F1 = HIGH), and Divided (3Qx and 4Qx only in Divide-by-2 or Divide-by-4 mode).
- 19. Guaranteed by statistical correlation. Tested initially and after any design or process changes that may affect these parameters.

20. $t_{\rm DEV}$ is the output-to-output skew between any two devices operating under the same conditions ($V_{\rm CC}$ ambient temperature, air flow, etc.)

23. t_{ORISE} and t_{OFALL} measured between 0.8 V and 2.0 V.

24. t_{LOCK} is the time that is required before synchronization is achieved. This specification is valid only after V_{CC} is stable and within normal operating limits. This parameter is measured from the application of a new signal or frequency at REF or FB until t_{PD} is within specified limits.

^{21.} t_{ODCV} is the deviation of the output from a 50% duty cycle. Output pulse width variations are included in t_{SKEW2} and t_{SKEW4} specifications.
22. Specified with outputs loaded with 30 pF for the CY7B991V–5 and –7 at 0.8 V.

Switching Characteristics (-5 Option)

Over the Operating Range

Notes

25. The level to be set on FS is determined by the "normal" operating frequency (f_{NOM}) of the V_{CO} and Time Unit Generator (see [Logic Block Diagram](#page-0-0)). Nominal frequency (f_{NOM}) always appears at the outputs when they a using a divided output as the FB input.

26. Test measurement levels for the CY7B991V are TTL levels (1.5 V to 1.5 V). Test conditions assume signal transition times of 2 ns or less and output loading as shown in the
AC Test Loads and Waveforms unless otherwise s

27. For all three state inputs, HIGH indicates a connection to V_{CC}, LOW indicates a connection to GND, and MID indicates an open connection. Internal termination circuitry holds an unconnected input to V_{CC}/2.

28. t_{SKEWPR} is defined as the skew between a pair of outputs (XQ0 and XQ1) when all eight outputs are selected for $0t_{1}$.

29. t_{SKEW0} is defined as the skew between outputs when they are selected for 0t_U. Other outputs are divided or inverted but not shifted.
30. t_{DEV} is the output-to-output skew between any two devices operating under t

31. C_L = 0 pF. For C_L = 30 pF, t_{SKEW0} = 0.35 ns.
32. SKEW is defined as the time between the earliest and the latest output transition among all outputs for which the same t_U delay has been selected when all are lo with 30 pF and terminated with 50 Ω to V_{CC}/2 (CY7B991V).

33. $t_{\rm ODCV}$ is the deviation of the output from a 50% duty cycle. Output pulse width variations are included in t_{SKEW2} and t_{SKEW4} specifications.

34. Specified with outputs loaded with 30 pF for the CY7B991V–5 and –7 devices. Devices are terminated through 5002 to $V_{\rm CC}/2$. t_{PWH} is measured at 2.0 V. t_{PWL} is measured at 0.8 V.

35. t_{ORISE} and t_{OFALL} measured between 0.8 V and 2.0 V.

36. t_{LOCK} is the time that is required before synchronization is achieved. This specification is valid only after V_{CC} is stable and within normal operating limits. This parameter is measured from the application of a

Switching Characteristics (-7 Option)

Over the Operating Range

Notes

- 37. The level to be set on FS is determined by the "normal" operating frequency (f_{NOM}) of the V_{CO} and Time Unit Generator (see [Logic Block Diagram](#page-0-0)). Nominal frequency (f_{NOM}) always appears at the outputs when they a using a divided output as the FB input.
- 38. Test measurement levels for the CY7B991V are TTL levels (1.5 V to 1.5 V). Test conditions assume signal transition times of 2 ns or less and output loading as shown in the
AC Test Loads and Waveforms unless otherwise s

39. For all three state inputs, HIGH indicates a connection to V_{CC} , LOW indicates a connection to GND, and MID indicates an open connection. Internal termination circuitry holds an unconnected input to $V_{CC}/2$.

40. t_{SKEWPR} is defined as the skew between a pair of outputs (XQ0 and XQ1) when all eight outputs are selected for $0t_U$.

41. t_{SKEW0} is defined as the skew between outputs when they are selected for 0t_U. Other outputs are divided or inverted but not shifted.

42. C_L = 0 pF. For C_L = 30 pF, t_{SKEW0} = 0.35 ns.
43. SKEW is defined as the time between the earliest and the latest output transition among all outputs for which the same t_U delay has been selected when all are lo with 30 pF and terminated with 50Ω to $V_{\text{CC}}/2$ (CY7B991V).

44. There are three classes of outputs: Nominal (multiple of t_U delay), Inverted (4Q0 and 4Q1 only with 4F0 = 4F1 = HIGH), and Divided (3Qx and 4Qx only in Divide-by-2 or
Divide-by-4 mode).

45. t_{DEV} is the output-to-output skew between any two devices operating under the same conditions (V_{CC} ambient temperature, air flow, etc.)

46. t_{ODCV} is the deviation of the output from a 50% duty cycle. Output pulse width variations are included in t_{SKEW2} and t_{SKEW4} specifications.
47. Specified with outputs loaded with 30 pF for the CY7B991V–5 and –7 at 0.8 V.

48. t_{ORISE} and t_{OFALL} measured between 0.8 V and 2.0 V.
49. t_{LOCK} is the time that is required before synchronization is achieved. This specification is valid only after V_{CC} is stable and within normal operating li

50. Guaranteed by statistical correlation. Tested initially and after any design or process changes that may affect these parameters.

AC Timing Diagrams

Ordering Information

Ordering Code Definitions

Package Diagram

Figure 11. 32-pin PLCC (0.453 × 0.553 Inches) J32 Package Outline, 51-85002

51-85002 *E

Table 3. Acronyms Used in this Document Units of Measure

Acronyms **Document Conventions**

Table 4. Units of Measure

Document History Page

Document History Page (continued)

Sales, Solutions, and Legal Information

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at [Cypress Locations](http://www.cypress.com/go/locations).

[Products](http://www.cypress.com/go/products)

[PSoC](http://www.cypress.com/psoc)[® Solutions](http://www.cypress.com/psoc) [PSoC 1](http://www.cypress.com/products/psoc-1) | [PSoC 3](http://www.cypress.com/products/psoc-3) | [PSoC 4](http://www.cypress.com/products/psoc-4) [| PSoC 5LP |](http://www.cypress.com/products/32-bit-arm-cortex-m3-psoc-5lp) [PSoC 6 MCU](http://cypress.com/psoc6)

[Cypress Developer Community](http://www.cypress.com/cdc) [Community |](https://community.cypress.com/welcome) [Projects](http://www.cypress.com/projects) | [Video](http://www.cypress.com/video-library) | [Blogs](http://www.cypress.com/blog) | [Training](http://www.cypress.com/training) | [Components](http://www.cypress.com/cdc/community-components)

[Technical Support](http://www.cypress.com/support) [cypress.com/support](http://www.cypress.com/support)

© Cypress Semiconductor Corporation, 2001-2018. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to
modify and reproduce t (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as rovided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation provided by Cypress, unmoder
of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably
expected to cause the fail apposes to other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.

Document Number: 38-07141 Rev. *M Revised January 3, 2018 Page 20 of 20

Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits,General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.

Как с нами связаться

Телефон: 8 (812) 309 58 32 (многоканальный) **Факс:** 8 (812) 320-02-42 **Электронная почта:** org@eplast1.ru **Адрес:** 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.