

## DS36C279 Low Power EIA-RS-485 Transceiver with Sleep Mode

Check for Samples: [DS36C279](#)

### FEATURES

- **100% RS-485 Compliant**
  - Specified RS-485 Device Interoperation
- **Low Power CMOS Design:**  $I_{CC}$  500  $\mu$ A Max
- **Automatic Sensing Sleep Mode**
  - Reduces  $I_{CC}$  to 10  $\mu$ A Maximum
- **Built-in Power Up/Down Glitch-Free Circuitry**
  - Permits Live Transceiver Intersection/Displacement
- **SOIC Packages**
- **Industrial Temperature Range:**  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$
- **On-Board Thermal Shutdown Circuitry**
  - Prevents Damage to the Device in the Event of Excessive Power Dissipation
- **Wide Common Mode Range:**  $-7\text{V}$  to  $+12\text{V}$
- **Receive Open Input Fail-Safe<sup>(1)</sup>**
- **$\frac{1}{4}$  Unit Load (DS36C279):  $\geq 128$  Nodes**
- **$\frac{1}{2}$  Unit Load (DS36C279T):  $\geq 64$  Nodes**
- **ESD (Human Body Model):  $\geq 2$  kV**
- **Drop-In Replacement for:**
  - LTC485 MAX485 DS75176 DS3695

(1) Non-terminated, open input only

### DESCRIPTION

The DS36C279 is a low power differential bus/line transceiver designed to meet the requirements of RS-485 Standard for multipoint data transmission. In addition it is compatible with TIA/EIA-422-B.

The sleep mode feature automatically puts the device in a power saving mode when both the driver and receiver are disabled.<sup>(2)</sup> The device is ideal for use in power conscious applications where the device may be disabled for extended periods of time.

The driver and receiver outputs feature TRI-STATE capability. The driver outputs operate over the entire common mode range of  $-7\text{V}$  to  $+12\text{V}$ . Bus contention or fault situations that cause excessive power dissipation within the device are handled by a thermal shutdown circuit, which forces the driver outputs into a high impedance state.

The receiver incorporates a fail safe circuit which ensures a high output state when the inputs are left open.<sup>(3)</sup>

The DS36C279T is fully specified over the industrial temperature range ( $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ).

(2) Device enters sleep mode if enable conditions are held  $> 600$  ns

(3) Non-terminated, open input only

### Connection and Logic Diagram

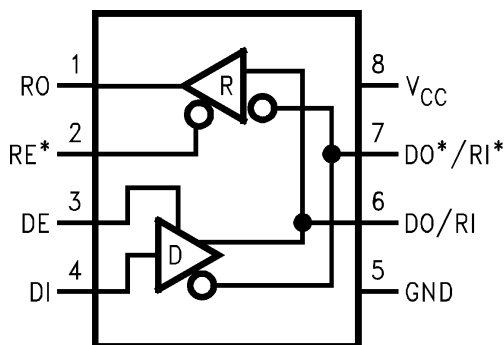


Figure 1. See Package Number D



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

**TRUTH TABLE**

| DRIVER SECTION   |    |                     |       |                  |
|------------------|----|---------------------|-------|------------------|
| RE*              | DE | DI                  | DO/RI | DO*/RI*          |
| X                | H  | H                   | H     | L                |
| X                | H  | L                   | L     | H                |
| X                | L  | X                   | Z     | Z                |
| RECEIVER SECTION |    |                     |       |                  |
| RE*              | DE | RI-RI*              |       | RO               |
| L                | L  | $\geq +0.2V$        |       | H                |
| L                | L  | $\leq -0.2V$        |       | L                |
| H                | L  | X                   |       | Z <sup>(1)</sup> |
| L                | L  | OPEN <sup>(2)</sup> |       | H                |

(1) Device enters sleep mode if enable conditions are held &gt; 600 ns

(2) Non-terminated, open input only



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

**ABSOLUTE MAXIMUM RATINGS <sup>(1)(2)</sup>**

|                                   |                              |                              |
|-----------------------------------|------------------------------|------------------------------|
| Supply Voltage ( $V_{CC}$ )       |                              | +12V                         |
| Input Voltage (DE, RE*, & DI)     |                              | -0.5V to ( $V_{CC} + 0.5V$ ) |
| Common Mode ( $V_{CM}$ )          | Driver Output/Receiver Input | $\pm 15V$                    |
| Input Voltage (DO/RI, DO*/RI*)    |                              | $\pm 14V$                    |
| Receiver Output Voltage           |                              | -0.5V to ( $V_{CC} + 0.5V$ ) |
| Maximum Package Power Dissipation | @ +25°C                      |                              |
|                                   | D Package 1190 mW, derate    | 9.5 mW/°C above +25°C        |
| Storage Temperature Range         |                              | -65°C to +150°C              |
| Lead Temperature                  | (Soldering 4 sec)            | +260°C                       |

(1) Absolute Maximum Ratings are those values beyond which the safety of the device cannot be ensured. They are not meant to imply that the devices should be operated at these limits. The table of [Electrical Characteristics](#) specifies conditions of device operation.

(2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.

**RECOMMENDED OPERATING CONDITIONS**

|                                          |           | Min   | Typ  | Max   | Units |
|------------------------------------------|-----------|-------|------|-------|-------|
| Supply Voltage ( $V_{CC}$ )              |           | +4.75 | +5.0 | +5.25 | V     |
| Bus Voltage                              |           | -7    |      | +12   | V     |
| Operating Free Air Temperature ( $T_A$ ) | DS36C279T | -40   | +25  | +85   | °C    |
|                                          | DS36C279  | 0     | +25  | +70   | °C    |

## ELECTRICAL CHARACTERISTICS<sup>(1)(2)</sup>

Over Supply Voltage and Operating Temperature ranges, unless otherwise specified

| Symbol                              | Parameter                                                            | Conditions                                                                                                     |           | Reference                        |                 | Min  | Typ    | Max  | Unit<br>s |
|-------------------------------------|----------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------|-----------|----------------------------------|-----------------|------|--------|------|-----------|
| DIFFERENTIAL DRIVER CHARACTERISTICS |                                                                      |                                                                                                                |           |                                  |                 |      |        |      |           |
| V <sub>OD1</sub>                    | Differential Output Voltage                                          | I <sub>O</sub> = 0 mA (No Load)                                                                                |           | (422)<br>(485)                   |                 | 1.5  |        | 5.0  | V         |
| V <sub>OD0</sub>                    | Output Voltage                                                       | I <sub>O</sub> = 0 mA<br>(Output to GND)                                                                       |           |                                  |                 | 0    |        | 5.0  | V         |
| V <sub>OD0*</sub>                   | Output Voltage                                                       |                                                                                                                |           |                                  |                 | 0    |        | 5.0  | V         |
| V <sub>OD2</sub>                    | Differential Output Voltage<br>(Termination Load)                    | R <sub>L</sub> = 50Ω                                                                                           |           | (422)                            | See<br>Figure 2 | 2.0  | 2.8    |      | V         |
|                                     |                                                                      | R <sub>L</sub> = 27Ω                                                                                           |           | (485)                            |                 | 1.5  | 2.3    | 5.0  | V         |
| ΔV <sub>OD2</sub>                   | Balance of V <sub>OD2</sub><br> V <sub>OD2</sub> – V <sub>OD2*</sub> | R <sub>L</sub> = 27Ω or 50Ω                                                                                    |           | See <sup>(3)</sup> (422, 485)    |                 | –0.2 | 0.1    | +0.2 | V         |
| V <sub>OD3</sub>                    | Differential Output Voltage<br>(Full Load)                           | R1 = 54Ω, R2 = 375Ω<br>V <sub>TEST</sub> = –7V to +12V                                                         |           | See Figure 3                     |                 | 1.5  | 2.0    | 5.0  | V         |
| V <sub>OC</sub>                     | Driver Common Mode<br>Output Voltage                                 | R <sub>L</sub> = 27Ω                                                                                           |           | (485)                            | See<br>Figure 2 | 0    |        | 3.0  | V         |
|                                     |                                                                      | R <sub>L</sub> = 50Ω                                                                                           |           | (422)                            |                 | 0    |        | 3.0  | V         |
| ΔV <sub>OC</sub>                    | Balance of V <sub>OC</sub><br> V <sub>OC</sub> – V <sub>OC*</sub>    | R <sub>L</sub> = 27Ω or<br>R <sub>L</sub> = 50Ω                                                                |           | See <sup>(3)</sup><br>(422, 485) |                 | –0.2 |        | +0.2 | V         |
| I <sub>OSD</sub>                    | Driver Output Short-Circuit<br>Current                               | V <sub>O</sub> = +12V                                                                                          |           | (485) See Figure 5               |                 |      | 200    | +250 | mA        |
|                                     |                                                                      | V <sub>O</sub> = –7V                                                                                           |           | (485)                            |                 |      | –190   | –250 | mA        |
| RECEIVER CHARACTERISTICS            |                                                                      |                                                                                                                |           |                                  |                 |      |        |      |           |
| V <sub>TH</sub>                     | Differential Input High<br>Threshold Voltage                         | V <sub>O</sub> = V <sub>OH</sub> , I <sub>O</sub> = –0.4 mA<br>–7V ≤ V <sub>CM</sub> ≤ +12V                    |           | See <sup>(4)</sup><br>(422, 485) |                 |      | +0.035 | +0.2 | V         |
| V <sub>TL</sub>                     | Differential Input Low<br>Threshold Voltage                          | V <sub>O</sub> = V <sub>OL</sub> , I <sub>O</sub> = 0.4 mA<br>–7V ≤ V <sub>CM</sub> ≤ +12V                     |           |                                  |                 | –0.2 | –0.035 |      | V         |
| V <sub>HST</sub>                    | Hysteresis                                                           | V <sub>CM</sub> = 0V                                                                                           |           | See <sup>(5)</sup>               |                 |      | 70     |      | mV        |
| R <sub>IN</sub>                     | Input Resistance                                                     | –7V ≤ V <sub>CM</sub> ≤ +12V                                                                                   | DS36C279T |                                  |                 | 24   | 68     |      | kΩ        |
|                                     |                                                                      |                                                                                                                | DS36C279  |                                  |                 | 48   | 68     |      | kΩ        |
| I <sub>IN</sub>                     | Line Input Current<br>See <sup>(6)</sup>                             | Other Input = 0V,<br>DE = V <sub>IL</sub> , RE* = V <sub>IL</sub> ,<br>V <sub>CC</sub> = 4.75 to 5.25<br>or 0V | DS36C279  | V <sub>IN</sub> = +12V           | 0               | 0.19 | 0.25   | mA   |           |
|                                     |                                                                      |                                                                                                                |           | V <sub>IN</sub> = –7V            | 0               | –0.1 | –0.2   | mA   |           |
|                                     |                                                                      |                                                                                                                | DS36C279T | V <sub>IN</sub> = +12V           | 0               | 0.19 | 0.5    | mA   |           |
|                                     |                                                                      |                                                                                                                |           | V <sub>IN</sub> = –7V            | 0               | –0.1 | –0.4   | mA   |           |
| I <sub>ING</sub>                    | Line Input Current Glitch<br>See <sup>(6)</sup>                      | Other Input = 0V,<br>DE = V <sub>IL</sub> , RE* = V <sub>IL</sub> ,                                            | DS36C279  | V <sub>IN</sub> = +12V           | 0               | 0.19 | 0.25   | mA   |           |
|                                     |                                                                      |                                                                                                                |           | V <sub>IN</sub> = –7V            | 0               | –0.1 | –0.2   | mA   |           |
|                                     |                                                                      | V <sub>CC</sub> = +3.0V or 0V,<br>T <sub>A</sub> = 25°C                                                        | DS36C279T | V <sub>IN</sub> = +12V           | 0               | 0.19 | 0.5    | mA   |           |
|                                     |                                                                      |                                                                                                                |           | V <sub>IN</sub> = –7V            | 0               | –0.1 | –0.4   | mA   |           |
| I <sub>B</sub>                      | Input Balance Test                                                   | RS = 500Ω                                                                                                      |           | (422) See <sup>(7)</sup>         |                 |      |        | ±400 | mV        |
| V <sub>OH</sub>                     | High Level Output Voltage                                            | I <sub>OH</sub> = –4 mA, V <sub>ID</sub> = +0.2V                                                               |           | RO<br>See Figure 12              |                 | 3.5  | 4.6    |      | V         |
| V <sub>OL</sub>                     | Low Level Output Voltage                                             | I <sub>OL</sub> = +4 mA, V <sub>ID</sub> = –0.2V                                                               |           |                                  |                 |      | 0.3    | 0.5  | V         |
| I <sub>OSR</sub>                    | Short Circuit Current                                                | V <sub>O</sub> = GND                                                                                           |           | RO                               |                 | 7    | 35     | 85   | mA        |
| I <sub>OZR</sub>                    | TRI-STATE Leakage Current                                            | V <sub>O</sub> = 0.4V to 2.4V                                                                                  |           |                                  |                 |      |        | ±1   | μA        |

- (1) Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except V<sub>OD1</sub> and V<sub>OD2</sub>.
- (2) All typicals are given for: V<sub>CC</sub> = +5.0V, T<sub>A</sub> = + 25°C.
- (3) Delta |V<sub>OD2</sub>| and Delta |V<sub>OC</sub>| are changes in magnitude of V<sub>OD2</sub> and V<sub>OC</sub>, respectively, that occur when input changes state.
- (4) Threshold parameter limits specified as an algebraic value rather than by magnitude.
- (5) Hysteresis defined as V<sub>HST</sub> = V<sub>TH</sub> - V<sub>TL</sub>.
- (6) I<sub>IN</sub> includes the receiver input current and driver TRI-STATE leakage current.
- (7) For complete details of test, see RS-485.

**ELECTRICAL CHARACTERISTICS<sup>(1)(2)</sup> (continued)**

Over Supply Voltage and Operating Temperature ranges, unless otherwise specified

| Symbol                 | Parameter                         | Conditions                        |                      | Reference         | Min | Typ | Max             | Units |
|------------------------|-----------------------------------|-----------------------------------|----------------------|-------------------|-----|-----|-----------------|-------|
| DEVICE CHARACTERISTICS |                                   |                                   |                      |                   |     |     |                 |       |
| V <sub>IH</sub>        | High Level Input Voltage          |                                   |                      | DE,<br>RE*,<br>DI | 2.0 |     | V <sub>CC</sub> | V     |
| V <sub>IL</sub>        | Low Level Input Voltage           |                                   |                      |                   | GND |     | 0.8             | V     |
| I <sub>IH</sub>        | High Level Input Current          | V <sub>IH</sub> = V <sub>CC</sub> |                      |                   |     |     | 2               | μA    |
| I <sub>IL</sub>        | Low Level Input Current           | V <sub>CC</sub> = 5V              | V <sub>IL</sub> = 0V |                   |     |     | −2              | μA    |
|                        |                                   | V <sub>CC</sub> = +3.0V           |                      |                   |     |     | −2              | μA    |
| I <sub>CC</sub>        | Power Supply Current<br>(No Load) | Driver and Receiver ON            |                      | V <sub>CC</sub>   |     | 200 | 500             | μA    |
| I <sub>CCR</sub>       |                                   | Driver OFF, Receiver ON           |                      |                   |     | 200 | 500             | μA    |
| I <sub>CCD</sub>       |                                   | Driver ON, Receiver OFF           |                      |                   |     | 200 | 500             | μA    |
| I <sub>CCX</sub>       |                                   | Sleep Mode                        |                      |                   |     | 0.2 | 10              | μA    |

## SWITCHING CHARACTERISTICS<sup>(1)(2)</sup>

Over Supply Voltage and Operating Temperature ranges, unless otherwise specified

| Symbol                          | Parameter                                      | Conditions                                  | Reference                              | Min | Typ | Max | Units |
|---------------------------------|------------------------------------------------|---------------------------------------------|----------------------------------------|-----|-----|-----|-------|
| <b>DRIVER CHARACTERISTICS</b>   |                                                |                                             |                                        |     |     |     |       |
| $t_{PHLD}$                      | Differential Propagation Delay High to Low     | $R_L = 54\Omega$ , $C_L = 100\text{ pF}$    | See Figure 6 and Figure 7              | 10  | 39  | 80  | ns    |
| $t_{PLHD}$                      | Differential Propagation Delay Low to High     |                                             |                                        | 10  | 40  | 80  | ns    |
| $t_{SKD}$                       | Differential Skew $ t_{PHLD} - t_{PLHD} $      |                                             |                                        | 0   | 1   | 10  | ns    |
| $t_r$                           | Rise Time                                      |                                             |                                        | 3   | 25  | 50  | ns    |
| $t_f$                           | Fall Time                                      |                                             |                                        | 3   | 25  | 50  | ns    |
| $t_{PHZ}$                       | Disable Time High to Z                         | $C_L = 15\text{ pF}$<br>$RE^* = L$          | See Figure 8 and Figure 9              |     | 80  | 200 | ns    |
| $t_{PLZ}$                       | Disable Time Low to Z                          |                                             | See Figure 10 and Figure 11            |     | 80  | 200 | ns    |
| $t_{PZH}$                       | Enable Time Z to High                          | $C_L = 100\text{ pF}$<br>$RE^* = L$         | See Figure 8 and Figure 9              |     | 50  | 200 | ns    |
| $t_{PZL}$                       | Enable Time Z to Low                           |                                             | See Figure 10 and Figure 11            |     | 65  | 200 | ns    |
| $t_{PSH}$                       | Driver Enable from Sleep Mode to Output High   | $C_L = 100\text{ pF}$<br>See <sup>(3)</sup> | See Figure 8 and Figure 9              | 70  | 98  | 250 | ns    |
| $t_{PSL}$                       | Driver Enable from Sleep Mode to Output Low    | $C_L = 100\text{ pF}$<br>See <sup>(3)</sup> | See Figure 10 and Figure 11            | 70  | 98  | 250 | ns    |
| <b>RECEIVER CHARACTERISTICS</b> |                                                |                                             |                                        |     |     |     |       |
| $t_{PHL}$                       | Propagation Delay High to Low                  | $C_L = 15\text{ pF}$                        | See Figure 13 and Figure 14            | 30  | 210 | 400 | ns    |
| $t_{PLH}$                       | Propagation Delay Low to High                  |                                             |                                        | 30  | 190 | 400 | ns    |
| $t_{SK}$                        | Skew, $ t_{PHL} - t_{PLH} $                    |                                             |                                        | 0   | 20  | 50  | ns    |
| $t_{PLZ}$                       | Output Disable Time                            | $C_L = 15\text{ pF}$ DE = H                 | See Figure 15, Figure 16 and Figure 17 |     | 50  | 150 | ns    |
| $t_{PHZ}$                       |                                                |                                             |                                        |     | 55  | 150 | ns    |
| $t_{PZL}$                       | Output Enable Time                             |                                             |                                        |     | 40  | 150 | ns    |
| $t_{PZH}$                       |                                                |                                             |                                        |     | 45  | 150 | ns    |
| $t_{PSH}$                       | Receiver Enable from Sleep Mode to Output High | $C_L = 15\text{ pF}$<br>See <sup>(3)</sup>  | See Figure 15 and Figure 17            | 70  | 97  | 250 | ns    |
| $t_{PSL}$                       | Receiver Enable from Sleep Mode to Output Low  | $C_L = 15\text{ pF}$<br>See <sup>(3)</sup>  | See Figure 15 and Figure 16            | 70  | 95  | 250 | ns    |

(1) All typicals are given for:  $V_{CC} = +5.0V$ ,  $T_A = +25^\circ C$ .

(2)  $C_L$  includes probe and jig capacitance.

(3) For enable from sleep mode delays DE = L and  $RE^* = H$  for greater than 600 ns prior to test (device is in sleep mode).

## PARAMETER MEASUREMENT INFORMATION

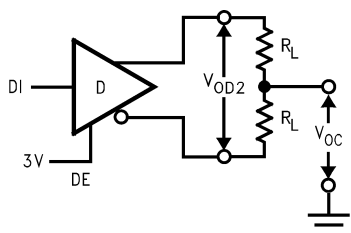
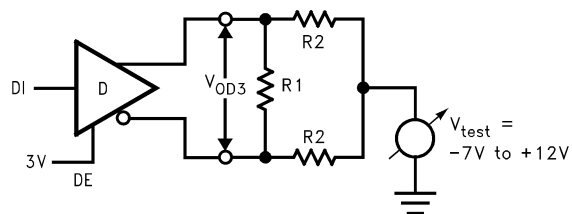
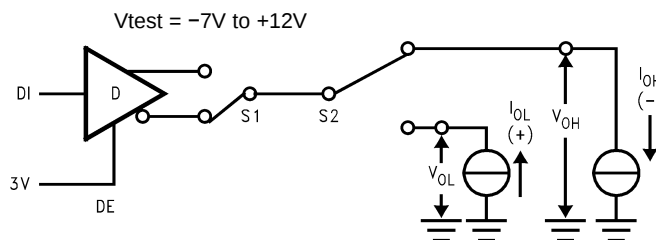
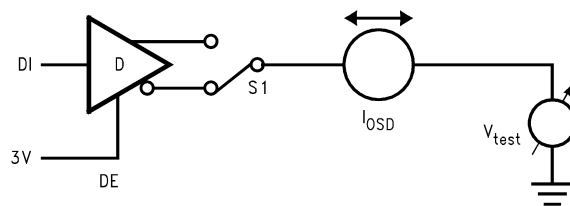
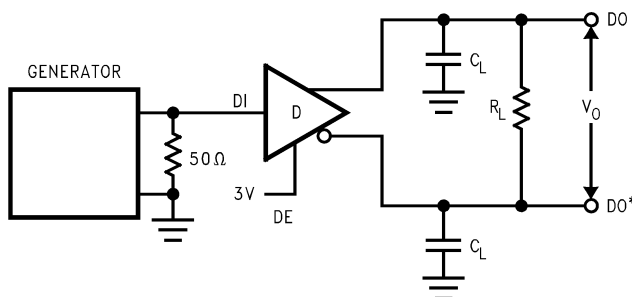
Figure 2. Driver  $V_{OD2}$  and  $V_{OC}$ Figure 3. Driver  $V_{OD3}$ Figure 4. Driver  $V_{OH}$  and  $V_{OL}$ Figure 5. Driver  $I_{ODS}$ 

Figure 6. Driver Differential Propagation Delay Test Circuit

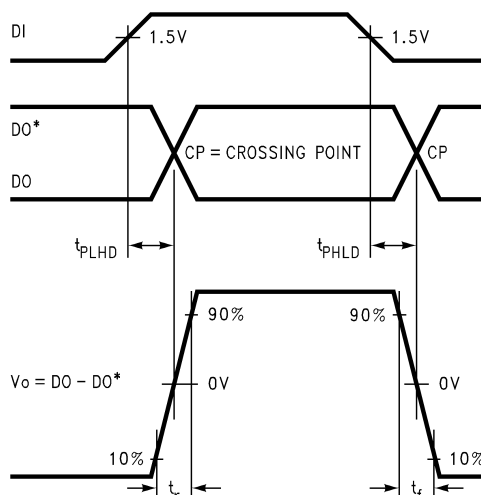


Figure 7. Driver Differential Propagation Delays and Differential Rise and Fall Times

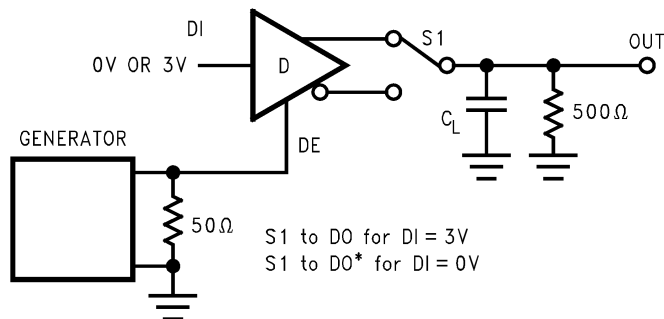


Figure 8. TRI-STATE and Sleep Mode Test Circuit ( $t_{PZH}$ ,  $t_{PSH}$ ,  $t_{PHZ}$ )

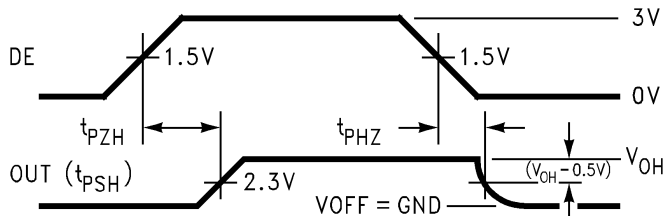


Figure 9. TRI-STATE and Sleep Mode Waveforms ( $t_{PZH}$ ,  $t_{PSH}$ ,  $t_{PHZ}$ )

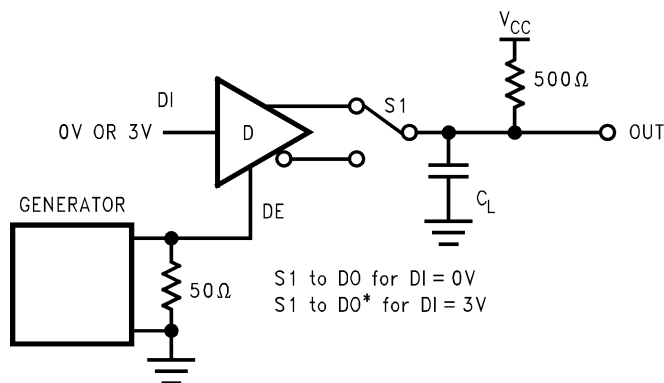


Figure 10. TRI-STATE and Sleep Mode Test Circuit ( $t_{PZL}$ ,  $t_{PSL}$ ,  $t_{PLZ}$ )

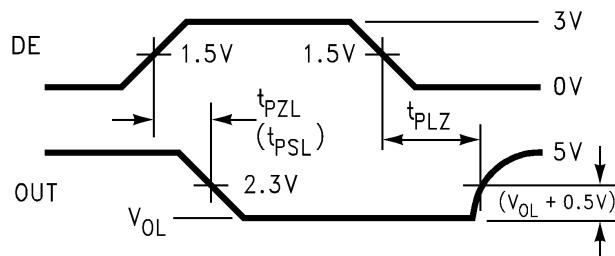


Figure 11. TRI-STATE and Sleep Mode Waveforms ( $t_{PZL}$ ,  $t_{PSL}$ ,  $t_{PLZ}$ )

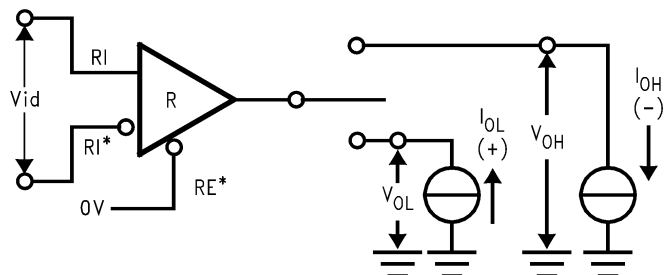


Figure 12. Receiver  $V_{OH}$  and  $V_{OL}$

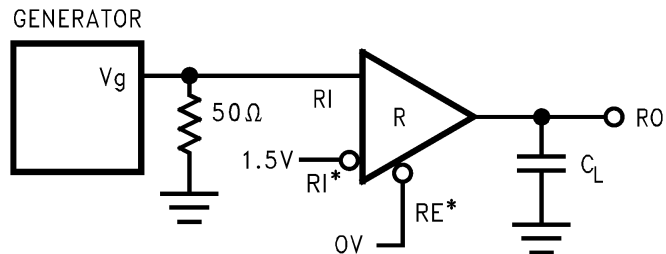


Figure 13. Receiver Differential Propagation Delay Test Circuit

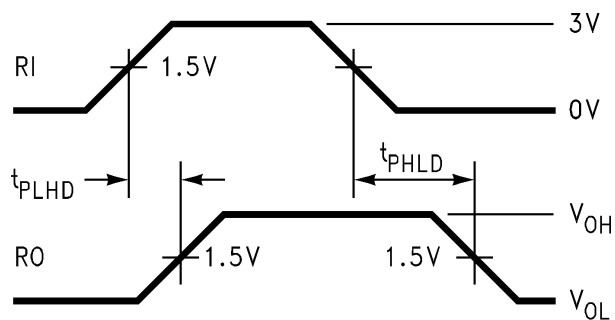


Figure 14. Receiver Differential Propagation Delay Waveforms

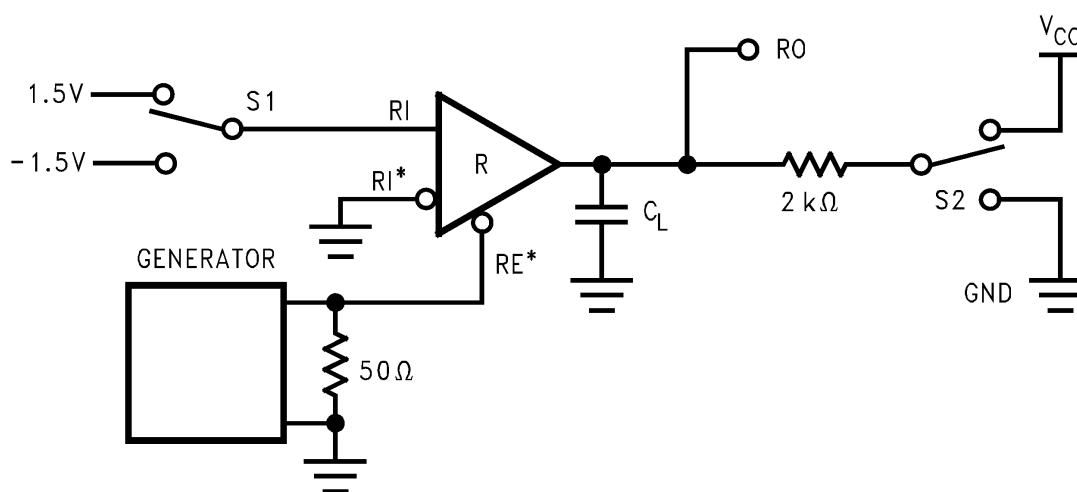
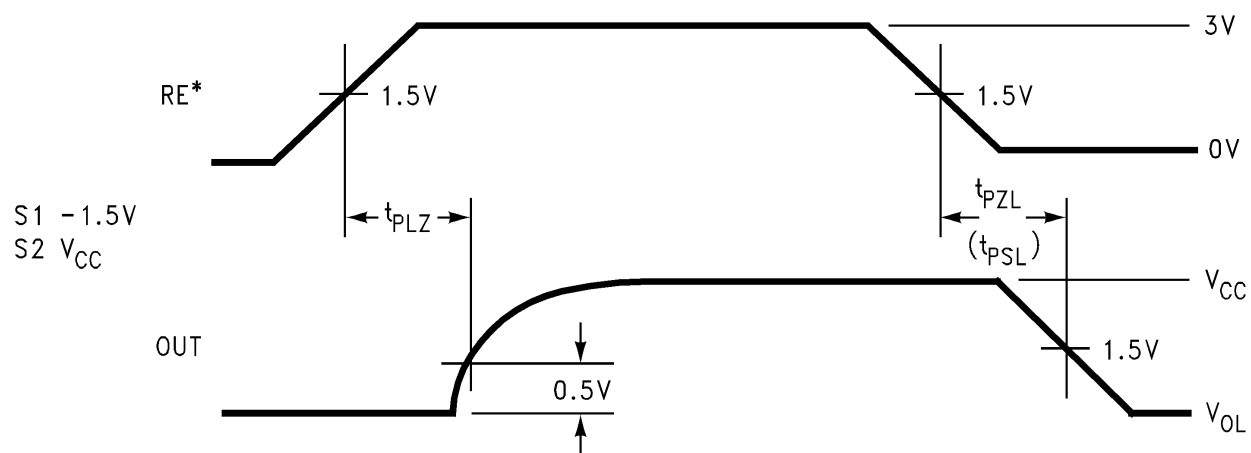


Figure 15. Receiver TRI-STATE and Sleep Mode Test Circuit

Figure 16. Receiver Enable and Disable Waveforms ( $t_{PLZ}$ ,  $t_{PZL}$ , ( $t_{PSL}$ ))

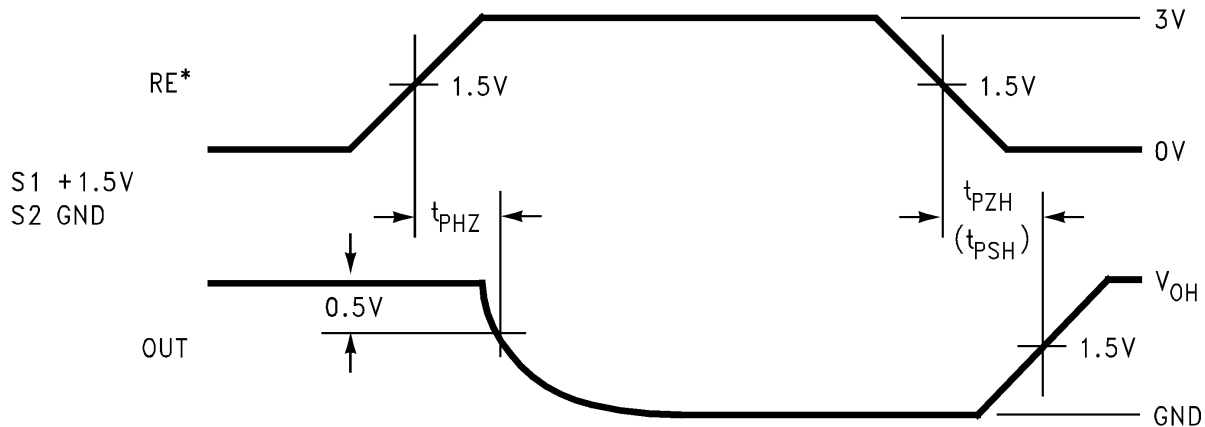


Figure 17. Receiver Enable and Disable Waveforms ( $t_{PHZ}$ ,  $t_{PZH}$ , ( $t_{PSH}$ ))

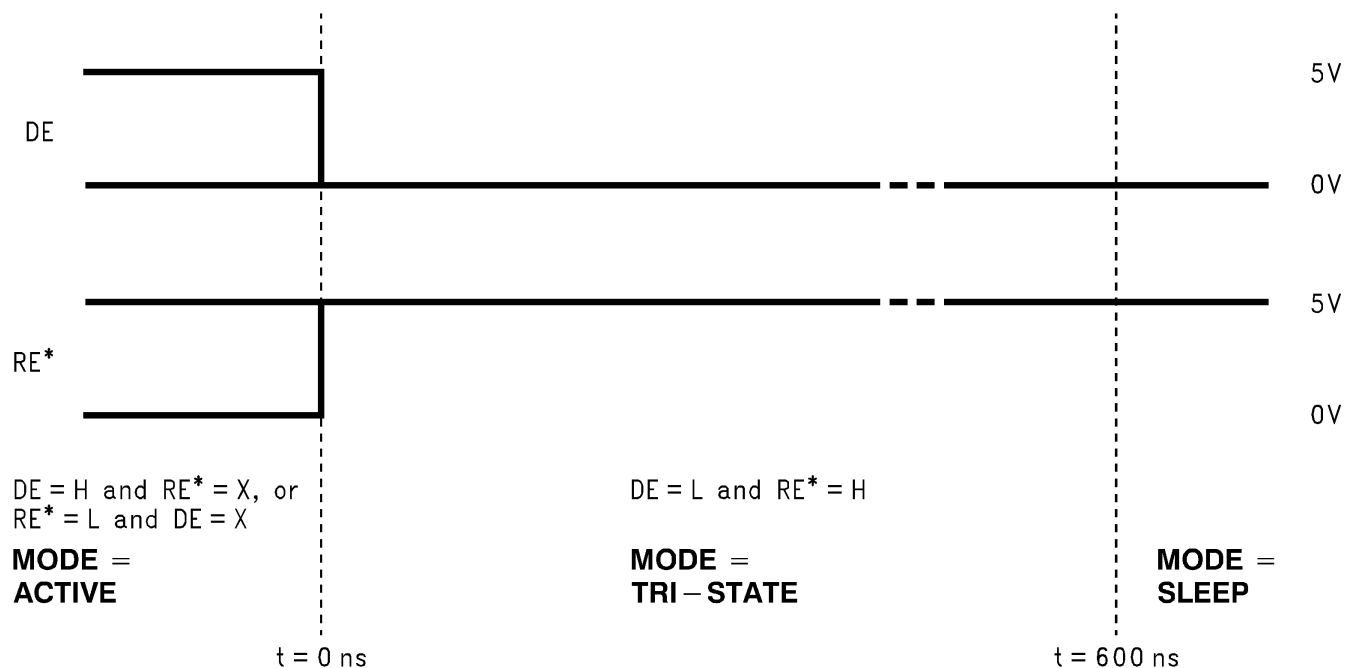


Figure 18. Entering Sleep Mode Conditions

## TYPICAL APPLICATION INFORMATION

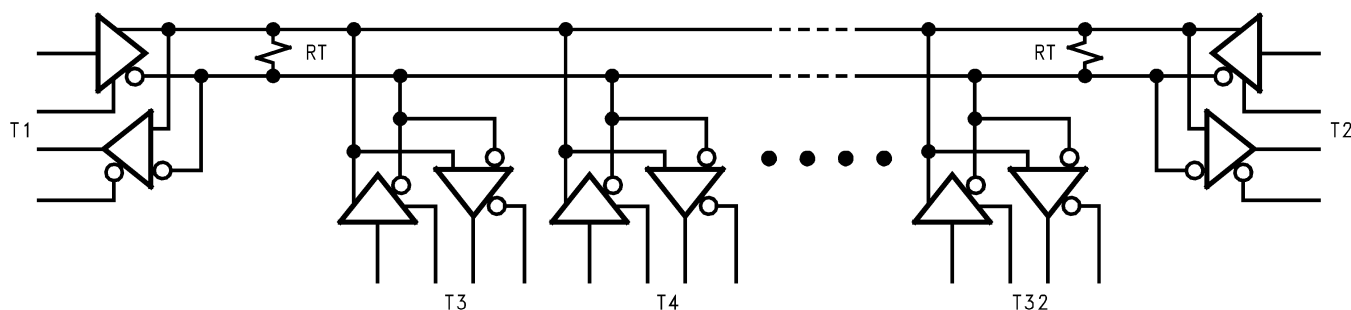


Figure 19. Typical RS-485 Bus Interface

Table 1. DEVICE PIN DESCRIPTIONS

| Pin No. | Name            | Description                                                                                                                                                                                                                                                |
|---------|-----------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1       | RO              | Receiver Output: When RE (Receiver Enable) is LOW, the receiver is enabled (ON), if $DO/RI \geq DO^*/RI^*$ by 200 mV, RO will be HIGH. If $DO/RI \leq DO^*/RI^*$ by 200 mV, RO will be LOW. Additionally RO will be HIGH for OPEN (Non-terminated) Inputs. |
| 2       | RE*             | Receiver Output Enable: When RE* is LOW the receiver output is enabled. When RE* is HIGH, the receiver output is in TRI-STATE (OFF). When RE* is HIGH and DE is LOW, the device will enter a low-current sleep mode after 600 ns.                          |
| 3       | DE              | Driver Output Enable: When DE is HIGH, the driver outputs are enabled. When DE is LOW, the driver outputs are in TRI-STATE (OFF). When RE* is HIGH and DE is LOW, the device will enter a low-current sleep mode after 600 ns.                             |
| 4       | DI              | Driver Input: When DE (Driver Enable) is HIGH, the driver is enabled, if DI is LOW, then DO/RI will be LOW and $DO^*/RI^*$ will be HIGH. If DI is HIGH, then DO/RI is HIGH and $DO^*/RI^*$ is LOW.                                                         |
| 5       | GND             | Ground Connection.                                                                                                                                                                                                                                         |
| 6       | DO/RI           | Driver Output/Receiver Input, 485 Bus Pin.                                                                                                                                                                                                                 |
| 7       | DO*/RI*         | Driver Output/Receiver Input, 485 Bus Pin.                                                                                                                                                                                                                 |
| 8       | V <sub>CC</sub> | Positive Power Supply Connection: Recommended operating range for V <sub>CC</sub> is +4.75V to +5.25V.                                                                                                                                                     |

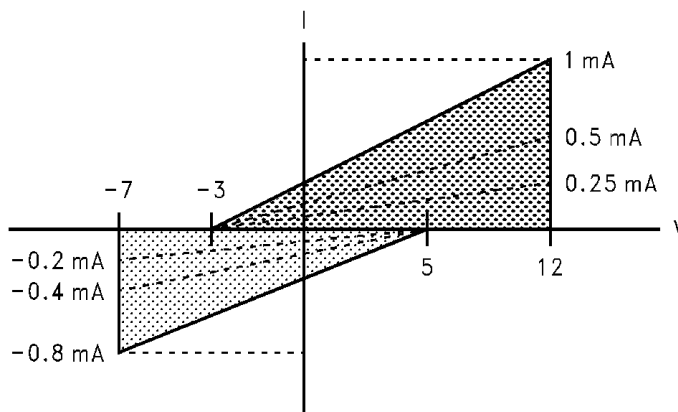
## UNIT LOAD

A unit load for an RS-485 receiver is defined by the input current versus the input voltage curve. The gray shaded region is the defined operating range from -7V to +12V. The top border extending from -3V at 0 mA to +12V at +1 mA is defined as one unit load. Likewise, the bottom border extending from +5V at 0 mA to -7V at -0.8 mA is also defined as one unit load (see Figure 20). An RS-485 driver is capable of driving up to 32 unit loads. This allows up to 32 nodes on a single bus. Although sufficient for many applications, it is sometimes desirable to have even more nodes. For example, an aircraft that has 32 rows with 4 seats per row would benefit from having 128 nodes on one bus. This would allow signals to be transferred to and from each individual seat to 1 main station. Usually there is one or two less seats in the last row of the aircraft near the restrooms and food storage area. This frees the node for the main station.

The DS36C278, the DS36C279, and the DS36C280 all have ½ unit load and ¼ unit load (UL) options available. These devices will allow up to 64 nodes or 128 nodes specified over temperature depending upon which option is selected. The ½ UL option is available in industrial temperature and the ¼ UL is available in commercial temperature.

First, for a ½ UL device the top and bottom borders shown in Figure 20 are scaled. Both 0 mA reference points at +5V and -3V stay the same. The other reference points are +12V at +0.5 mA for the top border and -7V at -0.4 mA for the bottom border (see Figure 20). Second, for a ¼ UL device the top and bottom borders shown in Figure 20 are scaled also. Again, both 0 mA reference points at +5V and -3V stay the same. The other reference points are +12V at +0.25 mA for the top border and -7V at -0.2 mA for the bottom border (see Figure 20).

The advantage of the  $\frac{1}{2}$  UL and  $\frac{1}{4}$  UL devices is the increased number of nodes on one bus. In a single master multi-slave type of application where the number of slaves exceeds 32, the DS36C278/279/280 may save in the cost of extra devices like repeaters, extra media like cable, and/or extra components like resistors.



**Figure 20. Input Current vs Input Voltage Operating Range**

The DS36C279 and DS36C280 have an additional feature which offers more advantages. The DS36C279 has an automatic sleep mode function for power conscious applications. The DS36C280 has a slew rate control for EMI conscious applications. Refer to the sleep mode and slew rate control portion of the application information section in the corresponding datasheet for more information on these features.

## SLEEP MODE

The DS36C279 features an automatic shutdown mode that allows the device to save power when not transmitting data. Since the shutdown mode is automatic, no external components are required. It may be used as little or as much as the application requires. The more the feature is utilized, the more power it saves.

The sleep mode is automatically entered when both the driver and receiver are disabled. This occurs when both the DE pin is asserted to a logic low and the RE\* pin is asserted to a logic high. Once both pins are asserted the device will enter sleep mode typically in 50 ns. The DS36C279 is ensured to go into sleep mode within 600 ns after both pins are asserted. The device wakes up (comes out of sleep mode) when either the DE pin is asserted to a logic high and/or the RE\* pin is asserted to a logic low. After the device enters sleep mode it will take longer for the device to wake up than it does for the device to enable from TRI-STATE. Refer to data specifications  $t_{PSL}$  and  $t_{PSH}$  and compare with  $t_{PZL}$  and  $t_{PZH}$  for timing differences.

The benefit of the DS36C279 is definitely its power savings. When active the device has a maximum  $I_{CC}$  of 500  $\mu$ A. When in sleep mode the device has a maximum  $I_{CC}$  of only 10  $\mu$ A, which is 50 times less power than when active. The  $I_{CC}$  when the device is active is already very low but when in sleep mode the  $I_{CC}$  is ultra low.

**PACKAGING INFORMATION**

| Orderable Device | Status<br>(1) | Package Type | Package<br>Drawing | Pins | Package Qty | Eco Plan<br>(2)            | Lead/Ball Finish | MSL Peak Temp<br>(3) | Op Temp (°C) | Top-Side Markings<br>(4) | Samples                 |
|------------------|---------------|--------------|--------------------|------|-------------|----------------------------|------------------|----------------------|--------------|--------------------------|-------------------------|
| DS36C279M/NOPB   | ACTIVE        | SOIC         | D                  | 8    | 95          | Green (RoHS<br>& no Sb/Br) | CU SN            | Level-1-260C-UNLIM   | -40 to 85    | 36C27<br>9M              | <a href="#">Samples</a> |
| DS36C279MX       | ACTIVE        | SOIC         | D                  | 8    | 2500        | TBD                        | Call TI          | Call TI              | -40 to 85    | 36C27<br>9M              | <a href="#">Samples</a> |
| DS36C279MX/NOPB  | ACTIVE        | SOIC         | D                  | 8    | 2500        | Green (RoHS<br>& no Sb/Br) | CU SN            | Level-1-260C-UNLIM   | -40 to 85    | 36C27<br>9M              | <a href="#">Samples</a> |

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check <http://www.ti.com/productcontent> for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

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**Green (RoHS & no Sb/Br):** TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) Only one of markings shown within the brackets will appear on the physical device.

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**TAPE AND REEL INFORMATION**


\*All dimensions are nominal

| Device          | Package Type | Package Drawing | Pins | SPQ  | Reel Diameter (mm) | Reel Width W1 (mm) | A0 (mm) | B0 (mm) | K0 (mm) | P1 (mm) | W (mm) | Pin1 Quadrant |
|-----------------|--------------|-----------------|------|------|--------------------|--------------------|---------|---------|---------|---------|--------|---------------|
| DS36C279MX      | SOIC         | D               | 8    | 2500 | 330.0              | 12.4               | 6.5     | 5.4     | 2.0     | 8.0     | 12.0   | Q1            |
| DS36C279MX/NOPB | SOIC         | D               | 8    | 2500 | 330.0              | 12.4               | 6.5     | 5.4     | 2.0     | 8.0     | 12.0   | Q1            |

## TAPE AND REEL BOX DIMENSIONS

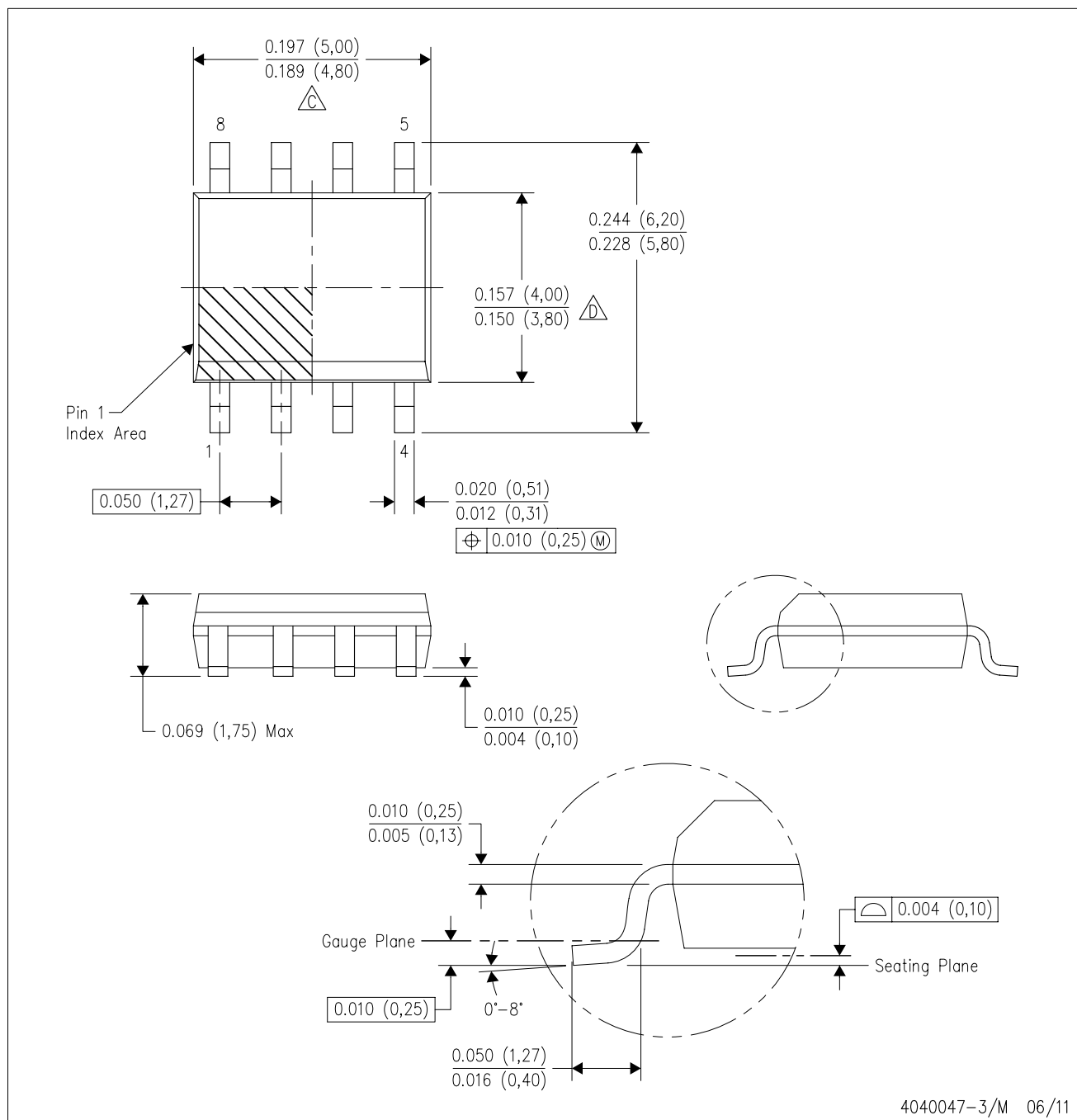


\*All dimensions are nominal

| Device          | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|-----------------|--------------|-----------------|------|------|-------------|------------|-------------|
| DS36C279MX      | SOIC         | D               | 8    | 2500 | 349.0       | 337.0      | 45.0        |
| DS36C279MX/NOPB | SOIC         | D               | 8    | 2500 | 349.0       | 337.0      | 45.0        |

D (R-PDSO-G8)

PLASTIC SMALL OUTLINE



## NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- $\triangle C$  Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- $\triangle D$  Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AA.

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#### Как с нами связаться

**Телефон:** 8 (812) 309 58 32 (многоканальный)

**Факс:** 8 (812) 320-02-42

**Электронная почта:** [org@eplast1.ru](mailto:org@eplast1.ru)

**Адрес:** 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.