

# ML62Q1500/1800 Group

16-bit micro controller

## GENERAL DESCRIPTION

ML62Q1500/1800 Group is a high performance CMOS 16-bit microcontroller equipped with an 16-bit CPU nX-U16/100 and integrated with program memory(Flash memory), data memory(RAM), data Flash and rich peripheral functions such as the multiplier/divider, CRC generator, DMA controller, Clock generator, Simplified RTC, Timer, General Purpose Ports, UART, Synchronous serial port, I<sup>2</sup>C bus interface unit (Master, Slave), Buzzer, Voltage Level Supervisor(VLS), Successive approximation type A/D converter, D/A converter, Analog comparator, Safety function(IEC60730/60335 Class B) and so on. The CPU nX-U16/100 is capable of efficient instruction execution in 1-instruction 1-clock mode by pipeline architecture parallel processing.

The built-in on-chip debug function enables debugging and programming the software. Also, ISP(In-System Programming) function supports the Flash programming in production line.

The ML62Q1500/1800 Group has seven packages (48pin - 100pin) and ten kinds of memory sizes(32Kbyte - 512Kbyte).

Table 1 ML62Q1500/1800 Group Product List

Program memory	Data memory (RAM)	Data Flash	48pin TQFP48	52pin TQFP52	64pin QFP64 TQFP64	80pin QFP80	100pin QFP100 TQFP100
512Kbyte	32Kbyte	8Kbyte	—	—	ML62Q1859	ML62Q1869	ML62Q1879
384Kbyte			—	—	ML62Q1858	ML62Q1868	ML62Q1878
256Kbyte	16Kbyte	4Kbyte	—	—	ML62Q1557	ML62Q1567	ML62Q1577
192Kbyte			—	—	ML62Q1556	ML62Q1566	ML62Q1576
160Kbyte			—	—	ML62Q1555	ML62Q1565	ML62Q1575
128Kbyte	16Kbyte		—	—	—	ML62Q1564	ML62Q1574
	8Kbyte		ML62Q1534	ML62Q1544	ML62Q1554	—	—
96Kbyte	16Kbyte		—	—	—	ML62Q1563	ML62Q1573
	8Kbyte		ML62Q1533	ML62Q1543	ML62Q1553	—	—
64Kbyte	8Kbyte		ML62Q1532	ML62Q1542	ML62Q1552	—	—
48Kbyte			ML62Q1531	ML62Q1541	ML62Q1551	—	—
32Kbyte			ML62Q1530	ML62Q1540	ML62Q1550	—	—
		—	—	—	—	—	

## FEATURES

- CPU
  - 16-bit RISC CPU: nX-U16/100(A35 core)
  - Instruction system: 16-bit length instructions
  - Instruction set: Transfer, arithmetic operations, comparison, logic operations, multiplication/division, bit manipulations, bit logic operations, jump, conditional jump, call return stack manipulations, arithmetic shift, and so on
  - Built-in On-chip debug function
  - Built-in ISP (In-System Programming) function
  - Minimum instruction execution time  
Approximately 30.5 μs (at 32.768 kHz system clock)  
Approximately 62.5ns/41.6ns (at 16 MHz/24MHz system clock)

- Coprocessor for multiplication and division
  - Multiplication : 16bit × 16bit (operation time : 4 cycles)
  - Division : 32bit ÷ 16bit (operation time : 8 cycles)
  - Division : 32bit ÷ 32bit (operation time : 16 cycles)
  - Multiply-accumulate (non-saturating): 16bit × 16bit + 32bit (operation time : 4 cycles)
  - Multiply-accumulate (saturating): 16bit × 16bit + 32bit (operation time : 4 cycles)
  - Signed or Unsigned is selectable
- Operating voltage and temperature
  - Operating voltage:  $V_{DD} = 1.6$  to  $5.5$  V ( $V_{DD}$  should be 1.8V or over at Power-on)
  - Operating temperature:  $-40$  °C to  $+105$  °C
- Internal memory
  - Program memory area
    - Rewrite count: 100 cycles
    - Write unit: 32bit(4byte)
    - Erase unit: 16Kbyte/1Kbyte
    - Erase/Write temperature:  $0$  °C to  $+40$  °C
  - Data Flash memory area
    - Rewrite count 10,000 cycles
    - Write unit: 8bit(1byte)
    - Erase unit: all area/128byte
    - Erase/Write temperature:  $-40$  °C to  $+85$  °C
    - Back Ground Operation(CPU can work while erasing and rewriting)

This product uses Super Flash® technology licensed from Silicon Storage Technology, Inc.  
Super Flash® is a registered trademark of Silicon Storage Technology, Inc.
  - Data RAM area
    - Rewrite unit: 8bit/16bit (1byte/2byte)
    - Parity check function is available (interrupt / reset are generatable at Parity error)
- Clock Generation Circuit
  - Low-speed clock (LSCLK)
    - Internal low-speed RC oscillation: Approximately 32.768 kHz
    - External low-speed clock input: Approximately 32.768 kHz
    - External low-speed crystal oscillation: 32.768 kHz crystal resonator is connectable
    - 3 selectable crystal oscillation mode (Tough, Normal, and Low current consumption)
      - Tough mode: Largest oscillation allowance to make highest resistance against leakage between the pins
      - Normal mode: Normal oscillation allowance and current consumption
      - Low current consumption mode: Smallest oscillation allowance to make lower current consumption
  - High-speed clock (HSCLK)
    - PLL oscillation: 2 selectable oscillation frequency (24MHz and 16MHz) by code option
  - Watch Dog Timer (WDT): built-in independent clock for WDT (RC1K: Approximately 1kHz)
- Reset
  - Reset by reset input pin
  - Reset by Power-On Reset
  - Reset by WDT overflow
  - Reset by WDT invalid clear
  - Reset by RAM parity error
  - Reset by unused ROM area access (instruction access)
  - Reset by voltage level supervisor (VLS)
  - Software reset by BRK instruction (reset CPU only)
  - Reset the peripherals individually
  - Collective reset to the all control pins and peripheral circuits

- Power management
  - HALT mode: CPU stops executing instruction, peripheral circuits continue working
  - HALT-H mode: CPU stops executing instruction, high-speed clock oscillation stops and peripheral circuits continue working with low-speed clock
  - STOP mode: CPU and peripheral circuits stops executing instruction, both high-speed oscillation and low-speed oscillation stop.
  - STOP-D mode: CPU and peripheral circuits stops executing instruction, both high-speed oscillation and low-speed oscillation stop. The internal logic voltage ( $V_{DDL}$ ) goes down to reduce the current consumption (RAM data is retained).
  - Clock gear: High-speed system clock frequency can be changed (1/1, 1/2, 1/4, 1/8, 1/16 or 1/32 of HSCLK)
  - Block Control Function: Powers down the unused function blocks (reset the block or stop supplying the clock)
- Interrupt controller
  - External interrupt ports : max 12
  - Non-maskable interrupt source: 1 (Internal source: WDT)
  - Maskable interrupt sources: max.51
  - Four step interrupt levels
- Watchdog timer(WDT)
  - Selectable Operating clock : select RC1K or LSCLK by code option
  - Overflow period: 8selectable (7.8ms, 15.6ms, 31.3ms, 62.5ms, 125ms, 500ms, 2s and 8s)
  - Selectable window function (enable or disable): configurable clear enable period (50% or 75% of overflow period)
  - Selectable WDT operation : select Enable or Disable by code option
  - Readable WDT counter : WDT counter monitor function
- DMA(Direct Memory Access) controller
  - Channel: 2channel
  - Transfer unit: 8bit/16bit
  - Transfer count: 1 to 1024
  - Transfer cycle: 2 cycle transfer
  - Transfer address: Fixed addressing mode, increment addressing mode , and decrement addressing mode
  - Transfer target: Special Function Register (SFR)/RAM → SFR/RAM (Transfer from/to Flash is not supported)
  - Transfer request: External pins, Serial communication unit, Successive approximation type A/D converter, 16bit timer, and Functional timer
- Low-speed Time base counter
  - Generate 8 frequency (128Hz to 1Hz) internal pulse signals by dividing the Low-speed clock (LSCLK)
  - Selectable 3 interrupts from eight frequency internal pulse signals
  - 1Hz or 2Hz output from general purpose port
  - Built-in Frequency adjust function : Adjust range: Approximately -488ppm to +488ppm, adjust resolution: Approximately 0.119ppm
- Simplified RTC
  - Channel: 1channel
  - Count by a unit for one second from "00 min. 00 sec" to "59 min. 59 sec"
  - Selectable Periodical interrupt request from four periods (0.5s, 1s, 30s or 60s)
  - Built-in minute and second writing error protraction function

- Functional timer
  - Channel: Max. 8 channel
  - Built-in timer, capture, and PWM function by 16 bit counter
  - Built-in Repeat mode, One shot mode is available
  - Two types of PWM output with the same period and different duties, and complementary PWM output with the dead time
  - Monitor input signal duty and the period by capture function
  - Generate periodical interrupts, duty interrupts, and interrupts coincided with set value
  - Counter Start, Stop, Counter clear triggered by an external inputs or Timer
  - Generate Emergency stop and emergency stop interrupt triggered by an external input
  - Same start/stop among different channels of the functional timer
  - Selectable counter clock(external clock or divided by 1 to 128 of LSCLK or HSCLK) for each channels
  
- 16-bit General timers
  - Channel: Max. 8channel
  - 8 bits timer mode and 16-bit timer mode
  - Same start/stop among different channels of 16bit (8bit) timer
  - Timer output (toggled by overflow)
  - Selectable counter clock (external clock or divided by 1 to 128 of LSCLK or HSCLK) for each channels
  
- Serial communication unit
  - Synchronous Serial Port (SSIO) mode or UART mode is selectable
  - Channel: Max. 6channel
  
  - < Synchronous Serial Port mode>
    - Selectable from Master and Slave
    - Selectable from LSB first or MSB first
    - Selectable 8-bit length or 16-bit length
  
  - < UART mode>
    - Full-duplex communication (One Full-duplex UART is configurable as two half-duplex UARTs)
    - 5 to 8 bit length, parity or no parity, odd parity or even parity, 1 stop bit or 2 stop bits
    - Selectable from Positive logic or Negative logic
    - Selectable from LSB first or MSB first
    - Configurable wide range communication speed
      - 32.768kHz operation clock : 1 bit/s to 4,800 bit/s
      - 24MHz operation clock : 600 bit/s to 3 Mbit/s
      - 16MHz operation clock : 300 bit/s to 2 Mbit/s
    - Built-in baud rate generator
  
- I<sup>2</sup>C bus unit (Master / Slave)
  - Selectable from Master mode or Slave mode
  - Channel: 1 channel
  
  - < Master function >
    - Standard mode (100 kbit/s), fast mode (400 kbit/s) and 1Mbps mode(1Mbit/s)
    - Handshake (Clock synchronization)
    - 7bit address format (10bit address format is supported)
  
  - < Slave function >
    - Standard mode (100 kbit/s), fast mode (400 kbit/s) and 1Mbps mode(1Mbit/s)
    - Clock stretch function
    - 7bit address format
  
- I<sup>2</sup>C bus Master
  - Channel: 2channel
  - Standard mode (100 kbit/s), fast mode (400 kbit/s) and 1Mbps mode(1Mbit/s)
  - Handshake (Clock synchronization)
  - 7bit address format (10bit address format is supported)

- General-purpose ports (GPIO)
  - I/O port: Max. 92 (Including one pin for on-chip debug and pins for other shared functions)
  - Input port: Max. 2(Including a shared function)
  - External interrupt port: Max. 12
  - LED driver port : Max. 91
  - Carrier frequency output function (used for IR communication)
- Successive approximation type A/D converter (SA-ADC)
  - Channel: Max.16channel
  - Resolution: 10bit
  - Conversion time: Min. 2.25 $\mu$ s /channel (When the conversion clock speed is 8MHz)
  - Reference voltages are selectable  
(V<sub>DD</sub> pin / Internal reference voltage(V<sub>REFI</sub> = Approximately 1.55V) / External reference voltage (V<sub>REF</sub> pin))
  - Selected channel repeat conversion
  - Dedicated result register for each channel
  - Interrupt determining by upper limit or lower limit threshold of conversion result
- Voltage Level Supervisor (VLS)
  - Accuracy:  $\pm$ 4%
  - Threshold voltage: 12 selectable (from 1.85V to 4.00V)
  - Functional Voltage level detection reset (VLS reset)
  - Functional Voltage level detection interrupt (VLS0 interrupt)
- Analog comparator
  - Channel: Max. 2 channel
  - Selectable interrupt from the comparator output (rising edge or falling edge)
  - Selectable from sampling or without sampling
  - Comparable with external 2 inputs
  - Comparable with external input and internal reference voltage (0.8V)
- D/A converter
  - Channel: Max. 2 channel
  - Resolution: 8bit
  - Output impedance: 6k ohm (Typ.)
  - R-2R ladder type
- Buzzer
  - 4 buzzer mode (Continuous sound, Single sound, Intermittent sound 1 and Intermittent sound 2)
  - 8frequencies (4.096kHz to 293Hz)
  - 15 step duty (1/16 to 15/16)
  - Selectable from positive logic buzzer output or negative logic buzzer output
- CRC(Cyclic Redundancy Check) generator
  - Generation equation:  $X^{16}+X^{12}+X^5+1$
  - Selectable from LSB first or MSB first
  - Built-in Automatic program memory CRC calculation mode in HALT mode

- Safety Function (IEC60730/60335 Class B)
  - Automatic switching to the internal low-speed RC oscillation in case the low-speed crystal oscillation stopped
  - RAM/SFR guard
  - Automatic program memory CRC calculation
  - RAM parity error detection
  - ROM unused area access reset (instruction access)
  - Clock mutual monitoring
  - WDT counter monitoring
  - SA-ADC test
  - UART test
  - Synchronous serial I/O test
  - I<sup>2</sup>C bus test
  - GPIO test
  
- Shipping package
  - 48 pin plastic TQFP  
ML62Q1530/1531/1532/1533/1534 - xxxTB  
(Blank part: ML62Q1530/1531/1532/1533/1534-NNNTB)
  - 52 pin plastic TQFP  
ML62Q1540/1541/1542/1543/1544 - xxxTB  
(Blank part: ML62Q1540/1541/1542/1543/1544-NNNTB)
  - 64 pin plastic TQFP  
ML62Q1550/1551/1552/1553/1554/1555/1556/1557/1858/1859 - xxxTB  
(Blank part: ML62Q1550/1551/1552/1553/1554/1555/1556/1557/1858/1859-NNNTB)
  - 64 pin plastic QFP  
ML62Q1550/1551/1552/1553/1554/1555/1556/1557/1858/1859 - xxxGA  
(Blank part: ML62Q1550/1551/1552/1553/1554/1555/1556/1557/1858/1859-NNNGA)
  - 80 pin plastic QFP  
ML62Q1563/1564/1565/1566/1567 /1868/1869- xxxGA  
(Blank part: ML62Q1563/1564/1565/1566/1567/1868/1869-NNNGA)
  - 100 pin plastic TQFP  
ML62Q1573/1574/1575/1576/1577/1878/1879 - xxxTB  
(Blank part: ML62Q1573/1574/1575/1576/1577/1878/1879-NNNTB)
  - 100 pin plastic QFP  
ML62Q1573/1574/1575/1576/1577/1878/1879 - xxxGA  
(Blank part: ML62Q1573/1574/1575/1576/1577/1878/1879-NNNGA)

xxx: ROM code number

ML62Q1500/1800 Group how to read the part number

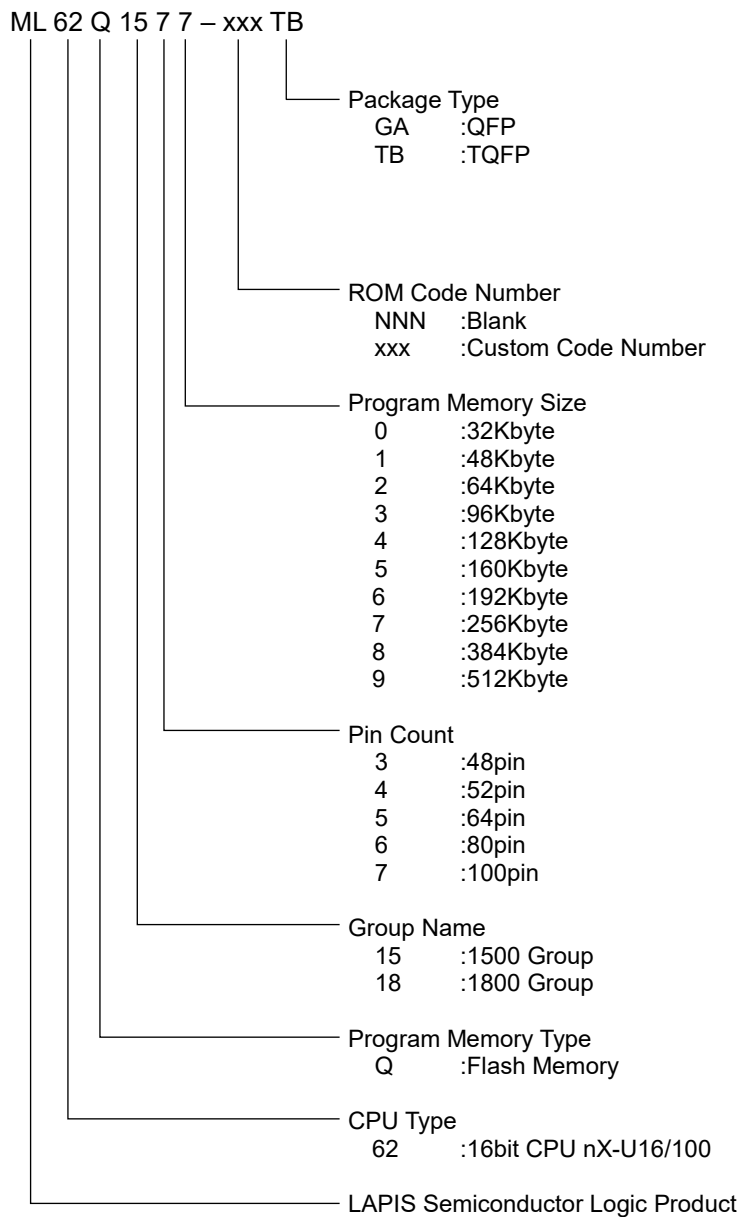


Figure 1 ML62Q1500/1800 Group Part Number

ML62Q1500/1800 Group Main Function List

Table 2 ML62Q1500/1800 Group Main Function List

Part number	Pin				Interrupt	Timer			Serial			Analog				
	Total pin-count	Power pin count	Reset Input pin count	Input pin count <sup>*3</sup>		I/O pin count	LED drive port (shared with the I/O port)	Functional Timer [channel]	16bit General I Timer <sup>*1</sup> [channel]	Simplified RTC [channel]	Serial communication unit (Full-duplex UART or Synchronous serial) [channel] <sup>*2</sup>	I <sup>2</sup> C bus unit (Master/Slave) [channel]	I <sup>2</sup> C bus interface (Master only) [channel]	Successive type A/D converter [channel]	Analog comparator [channel]	Analog comparator [input pin]
ML62Q1530	48	3	2	42	41	31	10	6	6	2	1	2	12	2	4	1
ML62Q1531																
ML62Q1532																
ML62Q1533																
ML62Q1534																
ML62Q1540	52	3	2	46	45	31	10	6	6	2	1	2	12	2	4	1
ML62Q1541																
ML62Q1542																
ML62Q1543																
ML62Q1544																
ML62Q1550	64	3	2	58	57	31	10	6	6	2	1	2	12	2	4	1
ML62Q1551																
ML62Q1552																
ML62Q1553																
ML62Q1554																
ML62Q1555	1	2	58	57	43	12	8	8	6	1	2	16	2	4	2	
ML62Q1556																
ML62Q1557																
ML62Q1858																
ML62Q1859																
ML62Q1563	80	4	2	72	71	43	12	8	8	6	1	2	16	2	4	2
ML62Q1564																
ML62Q1565																
ML62Q1566																
ML62Q1567																
ML62Q1868	100	4	2	92	91	43	12	8	8	6	1	2	16	2	4	2
ML62Q1869																
ML62Q1573																
ML62Q1574																
ML62Q1575																
ML62Q1576																
ML62Q1577																
ML62Q1878																
ML62Q1879																

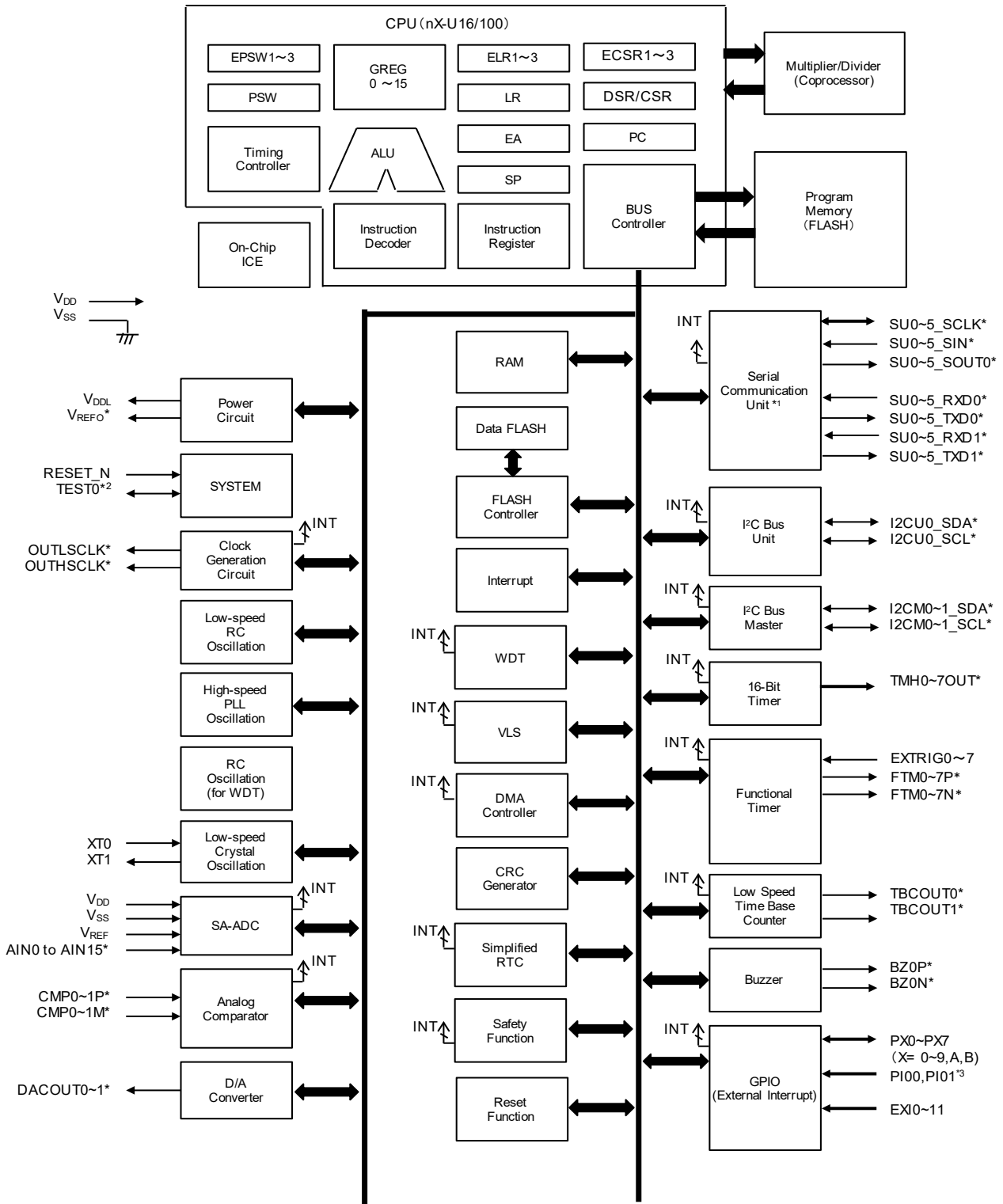
\*<sup>1</sup> : One 16bit timer is configurable as two 8bit timers

\*<sup>2</sup> : Full-duplex UART and Synchronous Serial Port can not be used simultaneously in the same channel.  
One Full-duplex UART is configurable as two half-duplex UARTs.

\*<sup>3</sup> : Shared with pins for crystal oscillation



BLOCK DIAGRAM



\* : Indicates the shared function of general ports.

\*1 : One channel Full-duplex UART is configurable as two channel Half-duplex UART.

\*2 : Not available as the input port when connecting to the on-chip debug emulator.

\*3 : Not available as the input port when connecting to the crystal resonator.

Figure 2 ML62Q1500/1800 Group Block Diagram

PIN CONFIGURATION

The port names in the pin-layout indicate 1<sup>st</sup>-function. Refer to Table-3 or Table-4 about other functions.

Pin Layout of 48pin TQFP Package

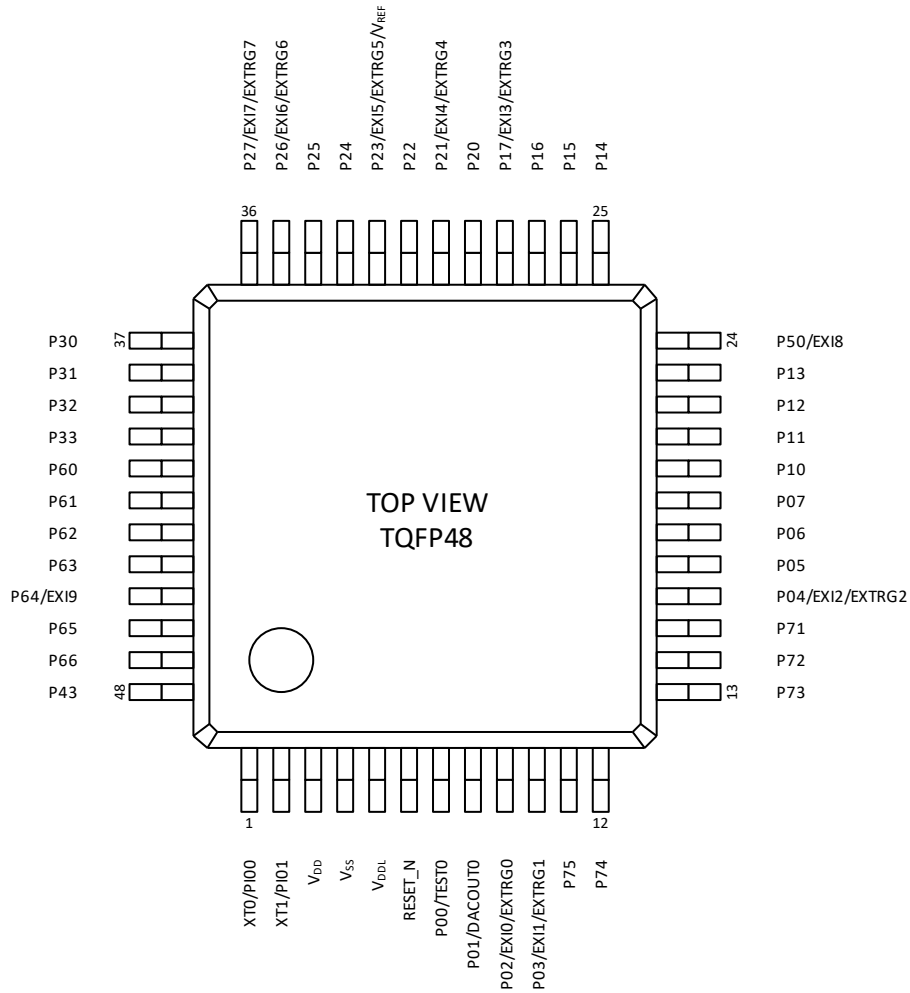


Figure 3 Pin Layout of 48pin TQFP Package

Pin Layout of 52pin TQFP Package

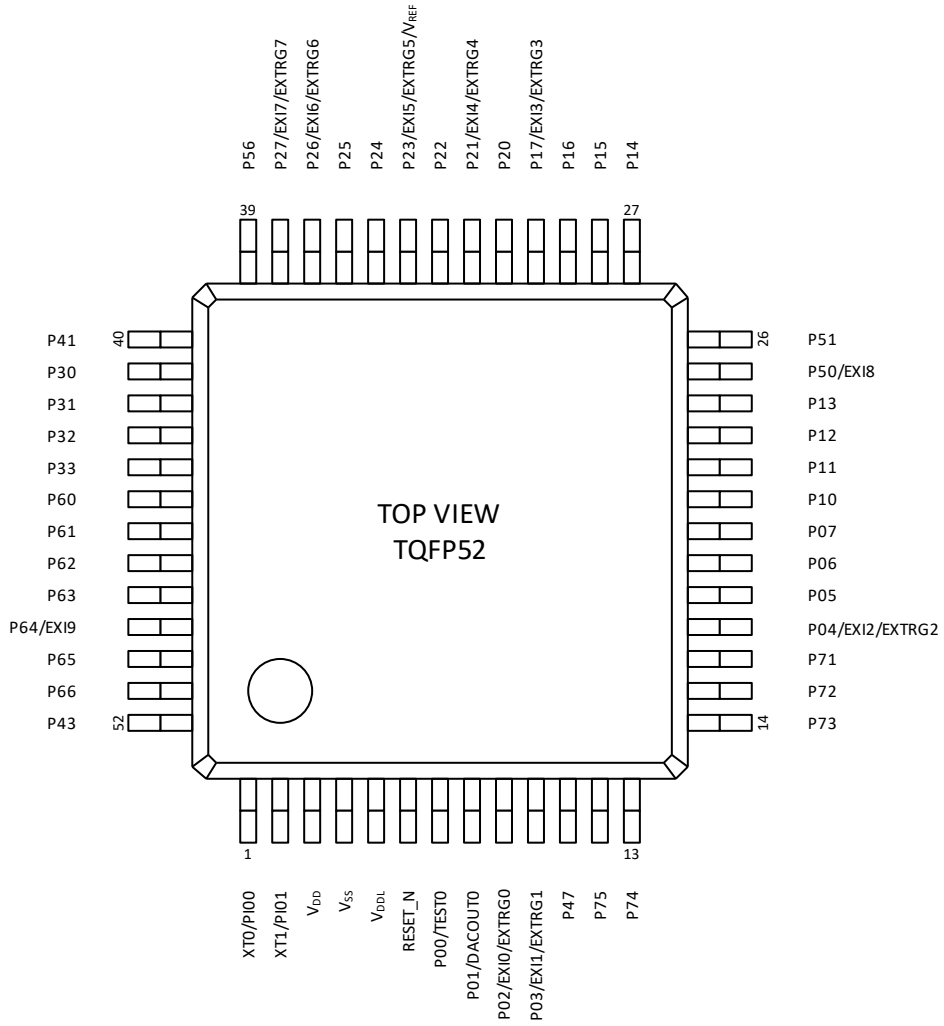


Figure 4 Pin Layout of 52pin TQFP52 Package

Pin Layout of 64pin TQFP/QFP Package

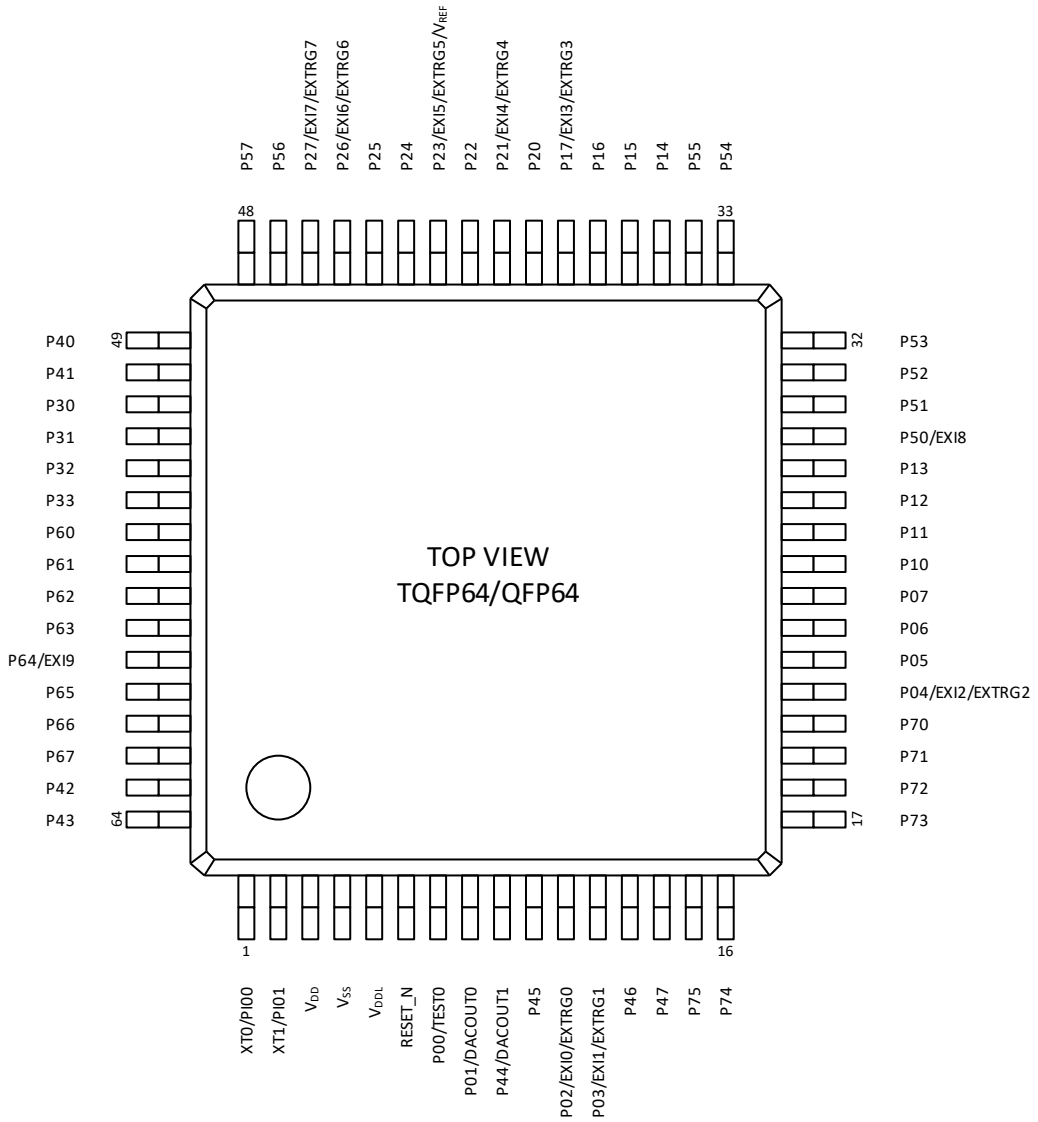


Figure 5 Pin Layout of 64pin TQFP/QFP Package

Pin Layout of 80pin QFP Package

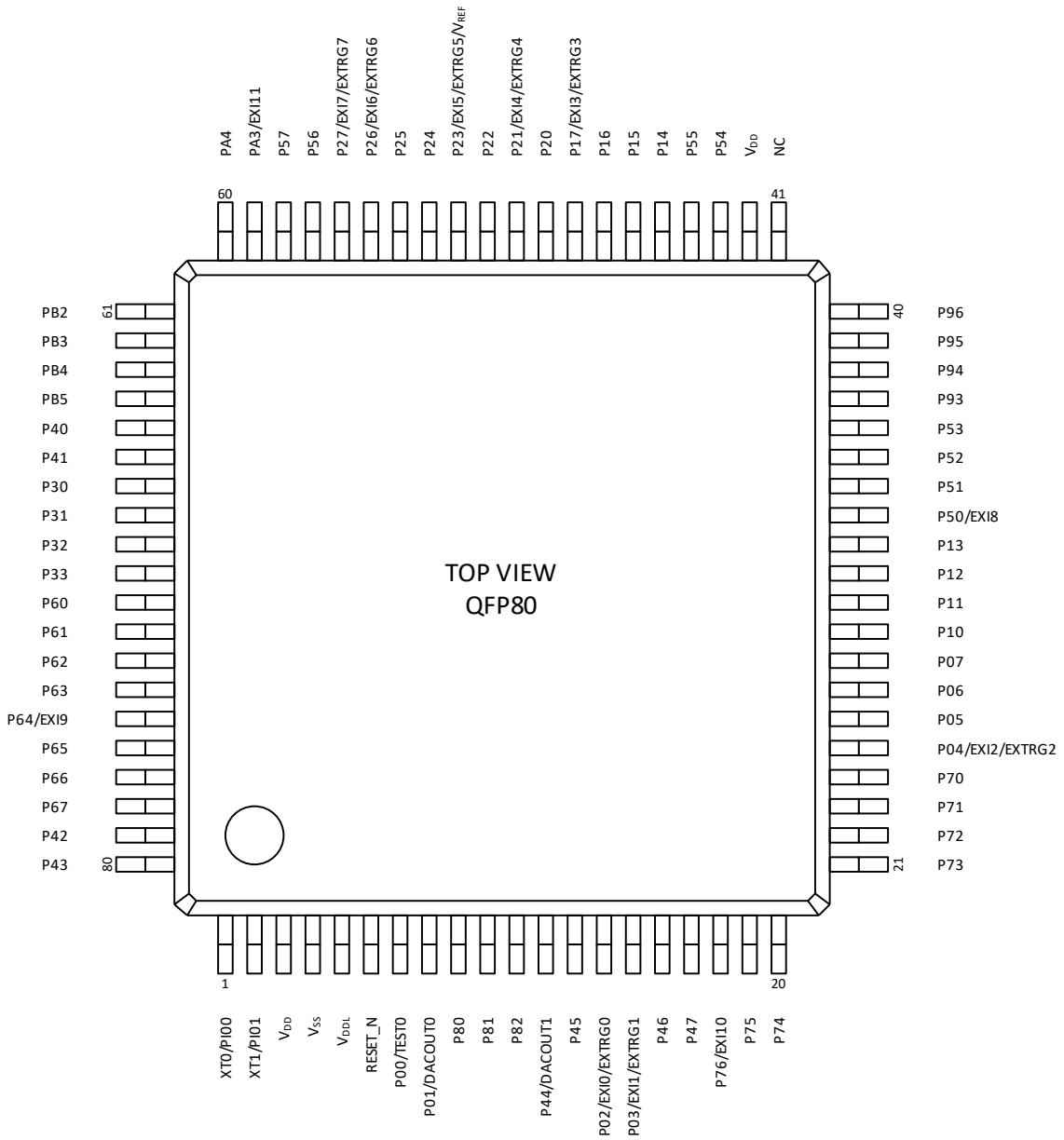


Figure 6 Pin Layout of 80pin QFP Package

## Pin Layout of 100pin TQFP Package

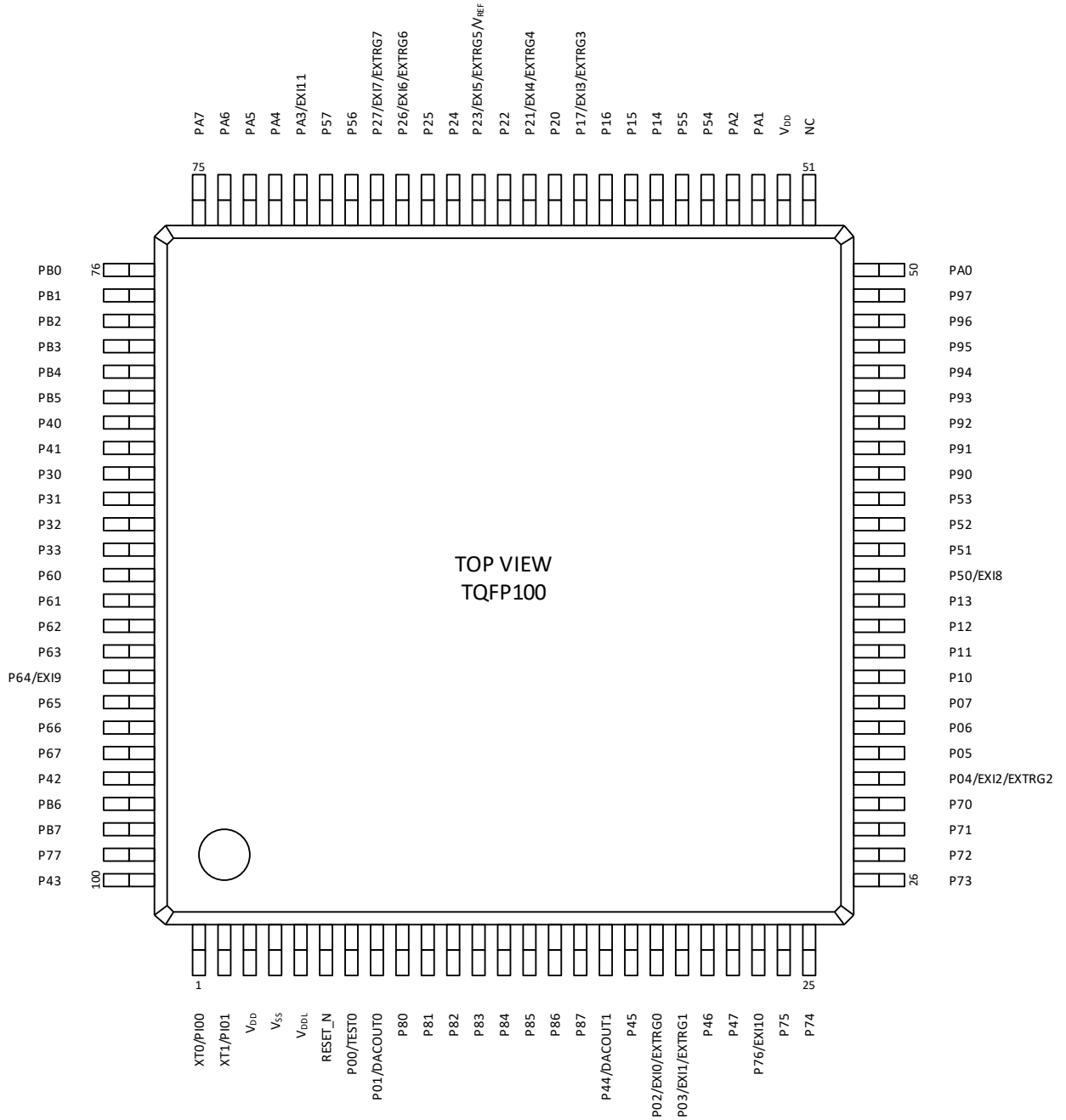


Figure 7 Pin Layout of 100pin TQFP Package

## Pin Layout of 100pin QFP Package

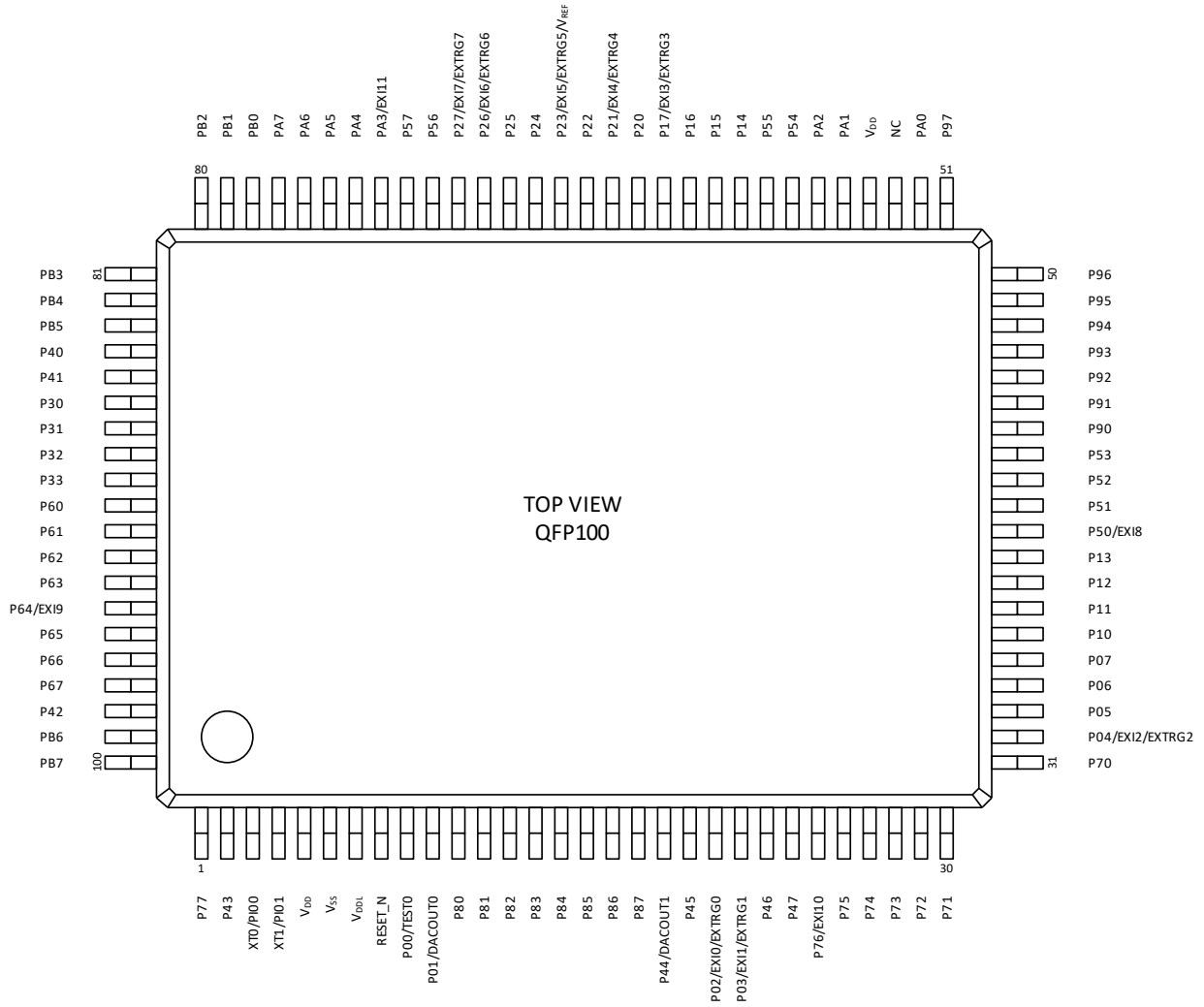


Figure 8 Pin Layout of 100pin QFP Package

PIN LIST

Table 3 Pin List (1/3)

Pin No.						Pin name (Primary func.)	Primary func. Others	2 <sup>nd</sup> func. communica tions	3 <sup>rd</sup> func. communica tions	4 <sup>th</sup> func. communica tions	5 <sup>th</sup> func. Timer	6 <sup>th</sup> func. Others	7 <sup>th</sup> func. Others	8 <sup>th</sup> func. ADC
48Pin	52Pin	64Pin	80Pin	TOFP100	QFP100									
3	3	3	3	3	5	V <sub>DD</sub>	-	-	-	-	-	-	-	-
-	-	-	42	52	54	V <sub>DD</sub>	-	-	-	-	-	-	-	-
4	4	4	4	4	6	V <sub>SS</sub>	-	-	-	-	-	-	-	-
-	-	-	41	51	53	NC	-	-	-	-	-	-	-	-
5	5	5	5	5	7	V <sub>DDL</sub>	-	-	-	-	-	-	-	-
1	1	1	1	1	3	XT0	PI00	-	-	-	-	-	-	-
2	2	2	2	2	4	XT1	PI01	-	-	-	-	-	-	-
6	6	6	6	6	8	RESET_N	-	-	-	-	-	-	-	-
7	7	7	7	7	9	P00	TEST0	-	-	-	-	-	-	-
8	8	8	8	8	10	P01	DACOUT0	-	-	-	-	TBCOUT0	TBCOUT1	-
9	9	11	14	19	21	P02	EXI0 EXTRG0	SU0_RXD0 SU0_SIN	-	-	FTM0P	OUTLSCLK	CMP0M	-
10	10	12	15	20	22	P03	EXI1 EXTRG1	SU0_TXD0 SU0_SOUT	SU0_TXD1	I2CU0_SDA	FTM0N	OUTHCLK	CMP0P	AIN11
16	17	21	25	30	32	P04	EXI2 EXTRG2	SU0_SCLK	-	I2CU0_SCL	TMH0OUT	-	-	-
17	18	22	26	31	33	P05	-	-	-	-	-	-	-	-
18	19	23	27	32	34	P06	-	-	-	I2CM0_SDA	-	-	-	-
19	20	24	28	33	35	P07	-	SU0_RXD1	SU0_RXD0	I2CM0_SCL	-	-	-	-
20	21	25	29	34	36	P10	-	SU0_TXD1	-	-	-	-	-	-
21	22	26	30	35	37	P11	-	SU0_SCLK	-	-	-	-	-	-
22	23	27	31	36	38	P12	-	SU0_RXD0 SU0_SIN	-	-	TMH4OUT	-	-	-
23	24	28	32	37	39	P13	-	SU0_TXD0 SU0_SOUT	SU0_TXD1	-	TMH1OUT	-	TMH3OUT	-
25	27	35	45	57	59	P14	-	-	-	-	-	-	-	-
26	28	36	46	58	60	P15	-	-	-	I2CU0_SDA	-	-	-	-
27	29	37	47	59	61	P16	-	SU1_SCLK	-	I2CU0_SCL	TMH5OUT	-	-	-
28	30	38	48	60	62	P17	EXI3 EXTRG3	SU0_RXD1	SU0_RXD0	-	FTM1P	TBCOUT0	BZ0P	AIN0
29	31	39	49	61	63	P20	-	SU0_TXD1	-	-	FTM1N	TBCOUT1	BZ0N	AIN1
30	32	40	50	62	64	P21	EXI4 EXTRG4	SU1_RXD0 SU1_SIN	-	-	FTM2P	OUTLSCLK	-	AIN2
31	33	41	51	63	65	P22	-	SU1_TXD0 SU1_SOUT	SU1_TXD1	I2CM0_SDA	FTM2N	OUTHCLK	-	AIN3
32	34	42	52	64	66	P23	EXI5 EXTRG5 V <sub>REF</sub>	SU1_SCLK	-	I2CM0_SCL	TMH2OUT	-	-	V <sub>REF0</sub>
33	35	43	53	65	67	P24	-	SU1_RXD0 SU1_SIN	-	-	-	-	-	AIN4
34	36	44	54	66	68	P25	-	SU1_TXD0 SU1_SOUT	SU1_TXD1	-	-	-	-	AIN5
35	37	45	55	67	69	P26	EXI6 EXTRG6	SU1_RXD1	SU1_RXD0	I2CU0_SDA	FTM3P	TBCOUT0	BZ0P	AIN6
36	38	46	56	68	70	P27	EXI7 EXTRG7	SU1_TXD1	-	I2CU0_SCL	FTM3N	TBCOUT1	BZ0N	AIN7



Table 3 Pin List (2/3)

Pin No.						Pin name (Primary func)	Primary func. Others *1	2 <sup>nd</sup> func. communica tions *1	3 <sup>rd</sup> func. communica tions *1	4 <sup>th</sup> func. communica tions	5 <sup>th</sup> func. Timer *1	6 <sup>th</sup> func. Others	7 <sup>th</sup> func. Others	8 <sup>th</sup> func. ADC *1
48Pin	52Pin	64Pin	80Pin	104Pin	QEP100									
37	41	51	67	84	86	P30	-	-	-	-	-	-	-	
38	42	52	68	85	87	P31	-	-	-	-	TBCOUT0	TBCOUT1	-	
39	43	53	69	86	88	P32	-	SU1_RXD1	SU1_RXD0	-	-	-	-	
40	44	54	70	87	89	P33	-	SU1_TXD1	-	-	TMH3OUT	-	-	
-	-	49	65	82	84	P40	-	SU5_TXD1	-	-	-	-	-	
-	40	50	66	83	85	P41	-	-	-	-	-	-	-	
-	-	63	79	96	98	P42	-	SU3_TXD1	-	-	-	-	-	
48	52	64	80	100	2	P43	-	-	-	-	TBCOUT0	TBCOUT1	AIN10	
-	-	9	12	17	19	P44	DACOUT1	SU4_RXD1	SU4_RXD0	-	-	-	-	
-	-	10	13	18	20	P45	-	SU4_TXD1	-	-	-	-	-	
-	-	13	16	21	23	P46	-	-	-	-	-	-	-	
-	11	14	17	22	24	P47	-	-	-	-	-	-	-	
24	25	29	33	38	40	P50	EXI8	-	-	-	-	-	-	
-	26	30	34	39	41	P51	-	-	-	-	-	-	-	
-	-	31	35	40	42	P52	-	SU4_RXD1	SU4_RXD0	-	-	-	-	
-	-	32	36	41	43	P53	-	SU4_TXD1	-	-	-	-	-	
-	-	33	43	55	57	P54	-	SU2_RXD1	SU2_RXD0	-	TMH7OUT	-	-	
-	-	34	44	56	58	P55	-	SU2_TXD1	-	-	-	-	-	
-	39	47	57	69	71	P56	-	SU2_RXD0 SU2_SIN	-	-	-	-	AIN12	
-	-	48	58	70	72	P57	-	SU2_TXD0 SU2_SOUT	SU2_TXD1	-	-	-	AIN13	
41	45	55	71	88	90	P60	-	-	-	I2CM1_SCL	-	-	-	
42	46	56	72	89	91	P61	-	-	-	I2CM1_SDA	-	-	-	
43	47	57	73	90	92	P62	-	-	-	-	FTM4N	-	CMP1P	
44	48	58	74	91	93	P63	-	-	-	-	FTM4P	-	CMP1M	
45	49	59	75	92	94	P64	EXI9	SU3_RXD0 SU3_SIN	-	-	FTM5P	-	-	
46	50	60	76	93	95	P65	-	SU3_TXD0 SU3_SOUT	SU3_TXD1	-	FTM5N	-	AIN8	
47	51	61	77	94	96	P66	-	SU3_SCLK	-	-	-	-	AIN9	
-	-	62	78	95	97	P67	-	SU3_RXD1	SU3_RXD0	-	-	-	-	
-	-	20	24	29	31	P70	-	-	-	-	TMH6OUT	-	-	
15	16	19	23	28	30	P71	-	-	-	-	-	-	-	
14	15	18	22	27	29	P72	-	-	-	-	-	-	-	
13	14	17	21	26	28	P73	-	-	-	-	-	-	-	
12	13	16	20	25	27	P74	-	-	-	-	-	-	-	
11	12	15	19	24	26	P75	-	-	-	-	-	-	-	
-	-	-	18	23	25	P76	EXI10	-	-	-	-	-	-	
-	-	-	-	99	1	P77	-	-	-	-	-	-	-	
-	-	-	9	9	11	P80	-	SU4_RXD0 SU4_SIN	-	-	-	-	-	
-	-	-	10	10	12	P81	-	SU4_TXD0 SU4_SOUT	SU4_TXD1	-	-	-	-	
-	-	-	11	11	13	P82	-	SU4_SCLK	-	-	-	-	-	
-	-	-	-	12	14	P83	-	-	-	-	-	-	-	
-	-	-	-	13	15	P84	-	-	-	-	-	-	-	
-	-	-	-	14	16	P85	-	-	-	-	-	-	-	
-	-	-	-	15	17	P86	-	-	-	-	-	-	-	
-	-	-	-	16	18	P87	-	-	-	-	-	-	-	

\*1: The pins of name with DACOUT1, SU2, SU3, SU4, SU5, TMH6, TMH7, AIN12 or AIN13 are not assigned to products of 48/52/64 PIN-packages.

Table 3 Pin List (3/3)

Pin No.						Pin name (Primary func)	Primary func. Others	2 <sup>nd</sup> func. communica tions	3 <sup>rd</sup> func. communica tions	4 <sup>th</sup> func. communica tions	5 <sup>th</sup> func. Timers	6 <sup>th</sup> func. Others	7 <sup>th</sup> func. Others	8 <sup>th</sup> func. ADC
48Pin	52Pin	64Pin	80Pin	TQFP100	QFP100									
-	-	-	-	42	44	P90	-	-	-	-	-	-	-	-
-	-	-	-	43	45	P91	-	-	-	-	-	-	-	-
-	-	-	-	44	46	P92	-	-	-	-	-	-	-	-
-	-	-	37	45	47	P93	-	SU4_RXD0 SU4_SIN	-	-	FTM6P	-	-	-
-	-	-	38	46	48	P94	-	SU4_TXD0 SU4_SOUT	SU4_TXD1	-	FTM6N	-	-	-
-	-	-	39	47	49	P95	-	SU4_SCLK	-	-	-	-	-	-
-	-	-	40	48	50	P96	-	-	-	-	-	-	-	-
-	-	-	-	49	51	P97	-	-	-	-	-	-	-	-
-	-	-	-	50	52	PA0	-	-	-	-	-	-	-	-
-	-	-	-	53	55	PA1	-	-	-	-	-	-	-	-
-	-	-	-	54	56	PA2	-	-	-	-	-	-	-	-
-	-	-	59	71	73	PA3	EXI11	SU2_SCLK	-	-	FTM7P	-	-	AIN14
-	-	-	60	72	74	PA4	-	-	-	-	FTM7N	-	-	AIN15
-	-	-	-	73	75	PA5	-	-	-	-	-	-	-	-
-	-	-	-	74	76	PA6	-	-	-	-	-	-	-	-
-	-	-	-	75	77	PA7	-	-	-	-	-	-	-	-
-	-	-	-	76	78	PB0	-	-	-	-	-	-	-	-
-	-	-	-	77	79	PB1	-	-	-	-	-	-	-	-
-	-	-	61	78	80	PB2	-	SU5_RXD0 SU5_SIN	-	-	-	-	-	-
-	-	-	62	79	81	PB3	-	SU5_TXD0 SU5_SOUT	SU5_TXD1	-	-	-	-	-
-	-	-	63	80	82	PB4	-	SU5_SCLK	-	-	-	-	-	-
-	-	-	64	81	83	PB5	-	SU5_RXD1	SU5_RXD0	-	-	-	-	-
-	-	-	-	97	99	PB6	-	-	-	-	-	-	-	-
-	-	-	-	98	100	PB7	-	-	-	-	-	-	-	-

## PIN DESCRIPTION

Table 4 Pin Description (1/5)

Function	Signal name	Pin name	I/O	Description	Logic
Power	-	V <sub>SS</sub>	-	Negative power supply pin (-)	-
	-	V <sub>DD</sub>	-	Positive power supply pin (+). Connect a capacitor C <sub>V</sub> between this pin and V <sub>SS</sub> .	-
	-	V <sub>DDL</sub>	-	Power supply pin for internal logic (internal regulator's output). Connect a capacitor C <sub>L</sub> (1μF) between this pin and V <sub>SS</sub> .	-
Test	TEST0	P00	I/O	Input for testing, is used as on-chip debug interface and ISP function. P00 is initialized as pull-up input mode by the system reset.	-
Un used	NC	NC	-	Connect to V <sub>SS</sub> .	-
System	V <sub>REF0</sub>	P23	-	Reference voltage output	-
	RESET_N	RESET_N	I	Reset input. Applying "L" level shifts the MCU in system reset mode. Applying "H" level shifts the CPU in program running mode. Used for on-chip debug interface and ISP function. No pull-up resistor is installed.	Negative
	XT0	XT0	I	Low speed crystal oscillation pins Connect 32.768kHz crystal resonator and Connect capacitors between the pin and V <sub>SS</sub> .	-
	XT1	XT1	O		-
	OUTLSCLK	P02 P21	O	Low-speed clock output.	-
	OUTHCLK	P03 P22	O	High-speed clock output.	-
General purpose port	PI00,PI01	XT0,XT1	I	General purpose input. Not available as general inputs when using the crystal resonator.	Positive
	P00	P00	I/O	General purpose I/O port - High-impedance - Input with Pull-UP (initial value) - Input without Pull-UP - CMOS output - N-channel open drain output Not available to use as I/O pin when using for on-chip debug interface or ISP function.	Positive
	P01 to P07	P01 to P07	I/O	General purpose I/O - High-impedance (initial value) - Input with Pull-UP - Input without Pull-UP - CMOS output - N-channel open drain output	Positive
	P10 to P17	P10 to P17	I/O		Positive
	P20 to P27	P20 to P27	I/O		Positive
	P30 to P33	P30 to P33	I/O		Positive
	P40 to P47	P40 to P47	I/O		Positive
	P50 to P57	P50 to P57	I/O		Positive
	P60 to P67	P60 to P67	I/O		Positive
	P70 to P77	P70 to P77	I/O		Positive
	P80 to P87	P80 to P87	I/O		Positive
	P90 to P97	P90 to P97	I/O		Positive
	PA0 to PA7	PA0 to PA7	I/O		Positive
	PB0 to PB7	PB0 to PB7	I/O		Positive

Table 4 Pin Description (2/5)

Function	Signal name	Pin name	I/O	Description	Logic
UART mode	SU0_TXD0	P03	O	Serial communication unit0 UART0 data output	Positive
		P13			
	SU0_RXD0	P02	I	Serial communication unit0 Full-duplex data input Serial communication unit0 UART0 data input	Positive
		P07			
		P12			
		P17			
	SU0_TXD1	P03	O	Serial communication unit0 Full-duplex data output Serial communication unit0 UART1 data output	Positive
		P10			
		P13			
	SU0_RXD1	P07	I	Serial communication unit0 UART1 data input	Positive
		P17			
	SU1_TXD0	P22	O	Serial communication unit1 UART0 data output	Positive
		P25			
	SU1_RXD0	P21	I	Serial communication unit1 Full-duplex data input Serial communication unit1 UART0 data input	Positive
		P24			
		P26			
		P32			
	SU1_TXD1	P22	O	Serial communication unit1 Full-duplex data output Serial communication unit1 UART1 data output	Positive
		P25			
		P27			
		P33			
	SU1_RXD1	P26	I	Serial communication unit1 UART1 data input	Positive
		P32			
	SU2_TXD0	P57	O	Serial communication unit2 UART0 data output	Positive
	SU2_RXD0	P54	I	Serial communication unit2 Full-duplex data input Serial communication unit2 UART0 data input	Positive
		P56			
	SU2_TXD1	P55	O	Serial communication unit2 Full-duplex data output Serial communication unit2 UART1 data output	Positive
		P57			
SU2_RXD1	P54	I	Serial communication unit2 UART1 data input	Positive	
SU3_TXD0	P65	O	Serial communication unit3 UART0 data output	Positive	
SU3_RXD0	P64	I	Serial communication unit3 Full-duplex data input Serial communication unit3 UART0 data input	Positive	
	P67				
SU3_TXD1	P42	O	Serial communication unit3 Full-duplex data output Serial communication unit3 UART1 data output	Positive	
	P65				
SU3_RXD1	P67	I	Serial communication unit3 UART1 data input	Positive	
SU4_TXD0	P81	O	Serial communication unit4 UART0 data output	Positive	
	P94				
SU4_RXD0	P44	I	Serial communication unit4 Full-duplex data input Serial communication unit4 UART0 data input	Positive	
	P52				
	P80				
	P93				
SU4_TXD1	P45	O	Serial communication unit4 Full-duplex data output Serial communication unit4 UART1 data output.	Positive	
	P53				
	P81				
	P94				
SU4_RXD1	P44	I	Serial communication unit4 UART1 data input	Positive	
	P52				
SU5_TXD0	P84	O	Serial communication unit5 UART0 data output	Positive	
	PB3				

Table 4 Pin Description (3/5)

Function	Signal name	Pin name	I/O	Description	Logic
UART mode	SU5_RXD0	P83	I	Serial communication unit5 Full-duplex data input Serial communication unit5 UART0 data input	Positive
		PB2			
		PB5			
	SU5_TXD1	P40	O	Serial communication unit5 Full-duplex data output Serial communication unit5 UART1 data output.	Positive
		P84			
		PB3			
SU5_RXD1	PB5	I	Serial communication unit5 UART1 data input	Positive	
Synchronous Serial Port	SU0_SIN	P02	I	Serial communication unit0 Synchronous serial data input	Positive
		P12			
	SU0_SCLK	P04	I/O	Serial communication unit0 Synchronous serial clock I/O	Positive
		P11			
		P47			
	SU0_SOUT	P03	O	Serial communication unit0 Synchronous serial data output	Positive
		P13			
	SU1_SIN	P21	I	Serial communication unit1 Synchronous serial data input	Positive
		P24			
	SU1_SCLK	P16	I/O	Serial communication unit1 Synchronous serial clock I/O	Positive
		P23			
	SU1_SOUT	P22	O	Serial communication unit1 Synchronous serial data output	Positive
		P25			
	SU2_SIN	P56	I	Serial communication unit2 Synchronous serial data	Positive
	SU2_SCLK	PA3	I/O	Serial communication unit2 Synchronous serial clock I/O	Positive
	SU2_SOUT	P57	O	Serial communication unit2 Synchronous serial data output	Positive
	SU3_SIN	P64	I	Serial communication unit3 Synchronous serial data input	Positive
	SU3_SCLK	P66	I/O	Serial communication unit3 Synchronous serial clock I/O	Positive
	SU3_SOUT	P65	O	Serial communication unit3 Synchronous serial data output	Positive
	SU4_SIN	P80	I	Serial communication unit4 Synchronous serial data input	Positive
P93					
SU4_SCLK	P95	I/O	Serial communication unit4 Synchronous serial clock I/O	Positive	
	P82				
SU4_SOUT	P81	O	Serial communication unit4 Synchronous serial data output	Positive	
	P94				
SU5_SIN	PB2	I	Serial communication unit5 Synchronous serial data input	Positive	
SU5_SCLK	PB4	I/O	Serial communication unit5 Synchronous serial clock I/O	Positive	
SU5_SOUT	PB3	O	Serial communication unit5 Synchronous serial data output	Positive	
I <sup>2</sup> C Bus	I2CU0_SDA	P03	I/O	I <sup>2</sup> C Unit0 (Master and Salve) Data I/O N-channel open drain Connect a pull-up resistor externally	Positive
		P15			
		P26			
		P46			
	I2CU0_SCL	P02	I/O	I <sup>2</sup> C Unit0 (Master and Salve) Clock I/O N-channel open drain output Connect a pull-up resistor externally	Positive
		P04			
		P16			
		P27			
	I2CM0_SDA	P06	I/O	I <sup>2</sup> C Master0 Data I/O pin N-channel open drain output Connect a pull-up resistor externally	Positive
		P22			

Table 4 Pin Description (4/5)

Function	Signal name	Pin name	I/O	Description	Logic
I <sup>2</sup> C Bus	I2CM0_SCL	P07	I/O	I <sup>2</sup> C Master0 Clock I/O N-channel open drain output Connect a pull-up resistor externally	Positive
		P23			
	I2CM1_SDA	P61	I/O	I <sup>2</sup> C Master1 Data I/O N-channel open drain output Connect a pull-up resistor externally	Positive
	I2CM1_SCL	P60	I/O	I <sup>2</sup> C Master1 Clock I/O N-channel open drain output Connect a pull-up resistor externally	Positive
Functional Timer (FTM)	FTM0P	P02	O	Functional Timer0 P output	Positive
	FTM0N	P03	O	Functional Timer0 N output	Negative
	FTM1P	P17	O	Functional Timer1 P output	Positive
		P47			
	FTM1N	P20	O	Functional Timer1 N output	Negative
		P46			
	FTM2P	P21	O	Functional Timer2 P output	Positive
	FTM2N	P22	O	Functional Timer2 N output	Negative
	FTM3P	P01	O	Functional Timer3 P output	Positive
		P26			
	FTM3N	P27	O	Functional Timer3 N output	Negative
		P44			
	FTM4P	P63	O	Functional Timer4 P output	Positive
	FTM4N	P62	O	Functional Timer4 N output	Negative
	FTM5P	P64	O	Functional Timer5 P output	Positive
	FTM5N	P65	O	Functional Timer5 N output	Negative
	FTM6P	P93	O	Functional Timer6 P output	Positive
	FTM6N	P94	O	Functional Timer6 N output	Negative
	FTM7P	P86	O	Functional Timer7 P output	Positive
		PA3			
	FTM7N	P87	O	Functional Timer7 N output	Negative
		PA4			
		EXTRG0	P02	I	Functional Timer event trigger input
	EXTRG1	P03	I	Functional Timer event trigger input	-
	EXTRG2	P04	I	Functional Timer event trigger input	-
	EXTRG3	P17	I	Functional Timer event trigger input	-
	EXTRG4	P21	I	Functional Timer event trigger input	-
	EXTRG5	P23	I	Functional Timer event trigger input	-
	EXTRG6	P26	I	Functional Timer event trigger input	-
	EXTRG7	P27	I	Functional Timer event trigger input	-
16 bit Timer	TMH0OUT	P04	O	16bit General Timer 0 output	Positive
	TMH1OUT	P13	O	16bit General Timer 1 output	Positive
	TMH2OUT	P23	O	16bit General Timer 2 output	Positive
	TMH3OUT	P13	O	16bit General Timer 3 output	Positive
		P33			
	TMH4OUT	P12	O	16bit General Timer 4 output	Positive
	TMH5OUT	P16	O	16bit General Timer 5 output	Positive
	TMH6OUT	P70	O	16bit General Timer 6 output	Positive
	TMH7OUT	P54	O	16bit General Timer 7 output	Positive
		EXTRG0	P02	I	16bit Timer trigger input
	EXTRG1	P03	I	16bit Timer trigger input	-

Table 4 Pin Description (5/5)

Function	Signal name	Pin name	I/O	Description	Logic
Low-speed Time Base Counter	TBCOUT0	P01	O	The virtual frequency adjustment signal output	Positive
		P17			
		P26			
		P31			
		P43			
	TBCOUT1	P01	O	Low-speed Time Base Counter 1Hz/2Hz output	Positive
		P20			
		P27			
		P31			
Buzzer	BZ0P	P17	O	Buzzer output (positive phase)	Positive
		P26			
	BZ0N	P20	O	Buzzer output (negative phase)	Negative
External Interrupt	EXI0	P02	I	External Interrupt 0 Input	-
	EXI1	P03	I	External Interrupt 1 Input	-
	EXI2	P04	I	External Interrupt 2 Input	-
	EXI3	P17	I	External Interrupt 3 Input	-
	EXI4	P21	I	External Interrupt 4 Input	-
	EXI5	P23	I	External Interrupt 5 Input	-
	EXI6	P26	I	External Interrupt 6 Input	-
	EXI7	P27	I	External Interrupt 7 Input	-
	EXI8	P50	I	External Interrupt 8 Input	-
	EXI9	P64	I	External Interrupt 9 Input	-
	EXI10	P76	I	External Interrupt 10 Input	-
EXI11	PA3	I	External Interrupt 11 Input	-	
Successive approximation type A/D converter (SA-ADC)	V <sub>REF</sub>	P23	-	SA-ADC external reference voltage input	-
	AIN0	P17	I	SA-ADC channel 0 input	-
	AIN1	P20	I	SA-ADC channel 1 input	-
	AIN2	P21	I	SA-ADC channel 2 input	-
	AIN3	P22	I	SA-ADC channel 3 input	-
	AIN4	P24	I	SA-ADC channel 4 input	-
	AIN5	P25	I	SA-ADC channel 5 input	-
	AIN6	P26	I	SA-ADC channel 6 input	-
	AIN7	P27	I	SA-ADC channel 7 input	-
	AIN8	P65	I	SA-ADC channel 8 input	-
	AIN9	P66	I	SA-ADC channel 10 input	-
	AIN10	P43	I	SA-ADC channel 11 input	-
	AIN11	P03	I	SA-ADC channel 12 input	-
	AIN12	P56	I	SA-ADC channel 13 input	-
	AIN13	P57	I	SA-ADC channel 14 input	-
	AIN14	PA3	I	SA-ADC channel 15 input	-
AIN15	PA4	I	SA-ADC channel 16 input	-	
Analog comparator	CMP0P	P03	I	Comparator input 0 (noninverting input)	-
	CMP0M	P02	I	Comparator input 0 (inverting input)	-
	CMP1P	P62	I	Comparator input 1 (noninverting input)	-
	CMP1M	P63	I	Comparator input 1 (inverting input)	-
D/A converter	DACOUT0	P01	O	D/A converter 0 output	-
	DACOUT1	P44	O	D/A converter 1 output	-

## TERMINATION OF UNUSED PINS

Table 5 Termination of unused pins

Pin	pin termination
NC	Connect to $V_{SS}$ .
RESET_N	Connect to $V_{DD}$
P00/TEST0	Connect to $V_{DD}$ with initial state (pulled-up input mode)
XT0/PI00, XT1/PI01	Open with initial state(Hi-impedance)
P01 to P07	
P10 to P17	
P20 to P27	
P30 to P33	
P40 to P47	
P50 to P57	
P60 to P67	
P70 to P77	
P80 to P87	
P90 to P97	
PA0 to PA7	
PB0 to PB7	

## Note:

- Terminate unused input pins according to the table 5 in order to avoid unexpected through-current in the pins.



## ELECTRICAL CHARACTERISTICS

## Absolute Maximum Ratings

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Condition	Rating	Unit	
Power supply voltage 1	V <sub>DD</sub>	Ta = +25°C	-0.3 to +6.5	V	
Power supply voltage 2	V <sub>DDL</sub>	Ta = +25°C	-0.3 to +2.0	V	
Input voltage	V <sub>IN</sub>	Ta = +25°C	-0.3 to V <sub>DD</sub> +0.3* <sup>1</sup>	V	
Output voltage1	V <sub>OUT1</sub>	Ta = +25°C	-0.3 to V <sub>DD</sub> +0.3* <sup>1</sup>	V	
Output voltage2	V <sub>OUT2</sub>	Ta = +25°C	-0.3 to +6.5	V	
"H" level output current	I <sub>OUTH</sub>	Ta = +25°C	1pin	-40* <sup>2</sup>	mA
			Total	-180* <sup>2</sup>	
"L" level output current	I <sub>OUTL</sub>	Ta = +25°C	1pin	+40	mA
			Total	+180	
Power dissipation	PD	Ta = +25°C	1	W	
Storage temperature	T <sub>STG</sub>	—	-55 to +150	°C	

\*<sup>1</sup> 6.5V or lower\*<sup>2</sup> The current flowing out the LSI through the pin is described in the negative number.

The applicable maximum current is the absolute value.

For example, -1mA means the maximum current 1mA flows out the LSI through the pin.

[Note]

Stresses above the absolute maximum ratings listed in the above table may cause permanent damage to the device.

These are stress ratings only and functional operation of the device at these conditions is not implied.

## Recommended Operating Conditions

(V<sub>SS</sub> = 0V)

Parameter	Symbol	Condition	Range	Unit
Operating temperature (Ambient)	Ta	—	-40 to +105	°C
Operating temperature (Chip-Junction)	Tj	—	-40 to +115	°C
Operating voltage	V <sub>DD</sub>	—	1.6 to 5.5	V
Operating frequency (CPU)	f <sub>OP</sub>	V <sub>DD</sub> = 1.6 to 5.5V	30k to 4M	Hz
		V <sub>DD</sub> = 1.8 to 5.5V	30k to 25M	
V <sub>DDL</sub> pin external capacitance	C <sub>L</sub>	—	1.0 ±30%	μF

**Thermal characteristics**

The maximum chip-junction temperature,  $T_j \text{ max}$ , may be calculated using the following equation.

$$T_j \text{ max} = T_a \text{ max} + P_D \text{ max} \times \theta_{ja}$$

$T_a \text{ max}$ : maximum ambient temperature

$P_D \text{ max}$ : LSI maximum power dissipation

$\theta_{ja}$ : Package junction to ambient thermal resistance

Design a Mounting board by considering heat radiation such as power dissipation and ambient temperature to satisfy the recommended conditions.

The following table shows the each package's thermal resistance for thermal design reference estimated by simulation based on the PCB (printed circuit board) conditions define as a below.

Parameter	Symbol	Package type	Value		Unit
			L1	L2	
Thermal resistance	$\theta_{ja}$	TQFP48	63.6	57.8	°C/W
		TQFP52	61.7	56.7	
		TQFP64	63.2	58.2	
		QFP64	47.2	43.3	
		QFP80	55.5	51.6	
		TQFP100	48.0	43.3	
		QFP100	104.7	101.3	

**PCB conditions:**

PCB name	L1	L2	Unit
PCB size (L / W / T)	114.3 / 76.2 / 1.6	114.3 / 76.2 / 1.6	mm
Number of layer	1	2	layer
Wiring density	60% (top layer)	60%(top and bottom layer)	—
Wind condition	No wind (0m/s)		—

## Current Consumption 1

Product: ML62Q1530, ML62Q1531, ML62Q1532, ML62Q1533, ML62Q1534, ML62Q1540,  
ML62Q1541, ML62Q1542, ML62Q1543, ML62Q1544, ML62Q1550, ML62Q1551,  
ML62Q1552, ML62Q1553, ML62Q1554

( $V_{DD}=1.6$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.* <sup>3</sup>	Max.	Unit	Measuring circuit
Supply current 0	IDD0	CPU is in STOP-D state. Low-speed RC1K/RC32K and PLL oscillation are stopped.	$T_a = -40$ to $+85^{\circ}C$	—	0.8	23	$\mu A$
			$T_a = -40$ to $+105^{\circ}C$	—		75	
Supply current 1	IDD1	CPU is in STOP state. Low-speed RC1K/RC32K and PLL oscillation are stopped.	$T_a = -40$ to $+85^{\circ}C$	—	1.0	26	$\mu A$
			$T_a = -40$ to $+105^{\circ}C$	—		80	
Supply current 2-1	IDD2-1	Low-speed RC32K Oscillating. CPU is in HALT state (LTBC and WDT are operating* <sup>1</sup> ). PLL oscillation is stopped.	$T_a = -40$ to $+85^{\circ}C$	—	4.7	35	$\mu A$
			$T_a = -40$ to $+105^{\circ}C$	—		85	
Supply current 2-2	IDD2-2	Low-speed Crystal Oscillating.* <sup>4</sup> CPU is in HALT state (LTBC and WDT are operating* <sup>1</sup> ). PLL oscillation is stopped.	$T_a = -40$ to $+85^{\circ}C$	—	3.0	32	$\mu A$
			$T_a = -40$ to $+105^{\circ}C$	—		85	
Supply current 3	IDD3	CPU: Running with low-speed RC32K oscillation clock* <sup>1*2</sup> PLL oscillation is stopped.	$T_a = -40$ to $+105^{\circ}C$	—	17	105	$\mu A$
Supply current 4	IDD4	CPU: Running with 16MHz PLL oscillating clock* <sup>1*2</sup> PLL 16MHz is oscillating. $V_{DD}=1.8\sim 5.5V$	$T_a = -40$ to $+105^{\circ}C$	—	3.3	4.5	mA
Supply current 5	IDD5	CPU: Running with 24MHz PLL oscillating clock* <sup>1*2</sup> PLL 24MHz is oscillating. $V_{DD}=1.8\sim 5.5V$	$T_a = -40$ to $+105^{\circ}C$	—	4.7	6.0	

\*<sup>1</sup> LTBC and WDT is operating, Significant bits of BLKCON0-3 and BRECON0-3 registers are all "1"

\*<sup>2</sup> CPU running in wait mode

\*<sup>3</sup> On the condition of  $V_{DD}=3.0V$ ,  $T_a=+25^{\circ}C$

\*<sup>4</sup> When the noise filter is not used in the low power consumption mode

## Current Consumption 2

Product: ML62Q1555, ML62Q1556, ML62Q1557, ML62Q1563, ML62Q1564, ML62Q1565, ML62Q1566,  
ML62Q1567, ML62Q1573, ML62Q1574, ML62Q1575, ML62Q1576, ML62Q1577

( $V_{DD}=1.6$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.* <sup>3</sup>	Max.	Unit	Measuring circuit	
Supply current 0	IDD0	CPU is in STOP-D state. Low-speed RC1K/RC32K and PLL oscillation are stopped.	Ta = -40 to +85 °C	—	1.0	55	$\mu A$	1
			Ta = -40 to +105 °C	—		110		
Supply current 1	IDD1	CPU is in STOP state. Low-speed RC1K/RC32K and PLL oscillation are stopped.	Ta = -40 to +85 °C	—	1.3	60	$\mu A$	
			Ta = -40 to +105 °C	—		120		
Supply current 2-1	IDD2-1	Low-speed RC32K Oscillating. CPU is in HALT state (LTBC and WDT are operating <sup>*1</sup> ). PLL oscillation is stopped.	Ta = -40 to +85 °C	—	5.5	76	$\mu A$	
			Ta = -40 to +105 °C	—		135		
Supply current 2-2	IDD2-2	Low-speed Crystal Oscillating. <sup>*4</sup> CPU is in HALT state (LTBC and WDT are operating <sup>*1</sup> ). PLL oscillation is stopped.	Ta = -40 to +85 °C	—	4.5	76	$\mu A$	
			Ta = -40 to +105 °C	—		135		
Supply current 3	IDD3	CPU: Running with low-speed RC32K oscillation clock <sup>*1*2</sup> PLL oscillation is stopped.	Ta = -40 to +105 °C	—	20	150	$\mu A$	
Supply current 4	IDD4	CPU: Running with 16MHz PLL oscillating clock <sup>*1*2</sup> PLL 16MHz is oscillating. $V_{DD}=1.8\sim 5.5V$	Ta = -40 to +105 °C	—	5.0	6.2	mA	
Supply current 5	IDD5	CPU: Running with 24MHz PLL oscillating clock <sup>*1*2</sup> PLL 24MHz is oscillating. $V_{DD}=1.8\sim 5.5V$	Ta = -40 to +105 °C	—	6.8	8.5		

\*<sup>1</sup> LTBC and WDT is operating, Significant bits of BLKCON0-3 and BRECON0-3 registers are all "1"

\*<sup>2</sup> CPU running in wait mode

\*<sup>3</sup> On the condition of  $V_{DD}=3.0V$ ,  $T_a=+25^{\circ}C$

\*<sup>4</sup> When the noise filter is not used in the low power consumption mode

## Current Consumption 3

Product: ML62Q1858, ML62Q1859, ML62Q1868, ML62Q1869, ML62Q1878, ML62Q1879

(V<sub>DD</sub>=1.6 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.* <sup>3</sup>	Max.	Unit	Measuring circuit
Supply current 0	IDD0	CPU is in STOP-D state. Low-speed RC1K/RC32K and PLL oscillation are stopped.	Ta = -40 to +85 °C	—	1.2	57	μA
			Ta = -40 to +105 °C	—		140	
Supply current 1	IDD1	CPU is in STOP state. Low-speed RC1K/RC32K and PLL oscillation are stopped.	Ta = -40 to +85 °C	—	1.8	62	μA
			Ta = -40 to +105 °C	—		150	
Supply current 2-1	IDD2-1	Low-speed RC32K Oscillating. CPU is in HALT state (LTBC and WDT are operating <sup>*1</sup> ). PLL oscillation is stopped.	Ta = -40 to +85 °C	—	6.0	78	μA
			Ta = -40 to +105 °C	—		165	
Supply current 2-2	IDD2-2	Low-speed Crystal Oscillating. <sup>*4</sup> CPU is in HALT state (LTBC and WDT are operating <sup>*1</sup> ). PLL oscillation is stopped.	Ta = -40 to +85 °C	—	4.5	78	μA
			Ta = -40 to +105 °C	—		165	
Supply current 3	IDD3	CPU: Running with low-speed RC32K oscillation clock <sup>*1*2</sup> PLL oscillation is stopped.	Ta = -40 to +105 °C	—	20	190	μA
Supply current 4	IDD4	CPU: Running with 16MHz PLL oscillating clock <sup>*1*2</sup> PLL 16MHz is oscillating. V <sub>DD</sub> =1.8~5.5V	Ta = -40 to +105 °C	—	4.0	5.0	mA
Supply current 5	IDD5	CPU: Running with 24MHz PLL oscillating clock <sup>*1*2</sup> PLL 24MHz is oscillating. V <sub>DD</sub> =1.8~5.5V	Ta = -40 to +105 °C	—	5.7	7.0	

1

\*1 LTBC and WDT is operating, Significant bits of BLKCON0-3 and BRECON0-3 registers are all "1"

\*2 CPU running in wait mode

\*3 On the condition of V<sub>DD</sub>=3.0V, Ta=+25°C

\*4 When the noise filter is not used in the low power consumption mode

Low speed Crystal Oscillation

( $V_{DD}=1.6$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

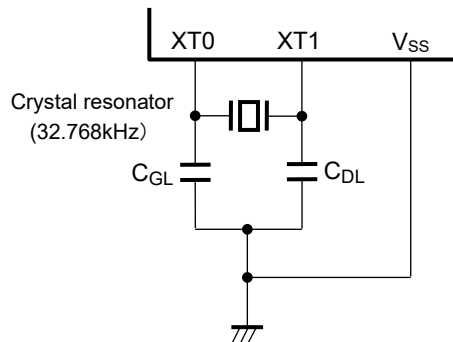
Parameter	Symbol	Condition	Range			Unit
			Min.	Typ.	Max.	
Crystal oscillation frequency *1 *2	$f_{XTL}$	—	—	32.768	—	kHz
Crystal oscillation start time	$T_{XTL}$	—	—	—	2	s

\*1: The oscillation frequency is determined by the oscillation circuit, crystal resonator and the external capacitance ( $C_{GL}/C_{DL}$ ). As those parameters changes depending the crystal resonator, it requires evaluation on the actual PCB circuit for matching. Ask crystal resonator makers for matching and confirm the oscillation characteristics.

\*2: The quality of oscillation characteristics might be lost, depending on material of PCB, condition of wiring capacitance or parasitic capacitance on the external circuits. Note for designing the external circuit.

- Make the wires on the external circuit as short as possible.
- Place the crystal resonator and oscillation circuit as close to the MCU as possible and make the wires between the external capacitance and crystal resonator as short as possible.
- Ensure no signal line flowing big current runs near the oscillation circuit.
- Ensure no signal line runs under and near the oscillation circuit.
- Make ground of external capacitance the same as MCU ground  $V_{SS}$  pin and connect them to the ground that has low variation of current and voltage.
- The quality of oscillation characteristics might be lost depending on operating environment due to moisture absorption of PCB and condensation of PCB surface, recommended to have measures such as covering the oscillation circuit with resin.

Low speed Crystal Oscillation external circuit example



External Clock Input

( $V_{DD}=1.6$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Range			Unit
			Min.	Typ.	Max.	
Input Frequency	$f_{EXCK}$	—	Typ. -1.0%	32.768	Typ. +1.0%	kHz
Input pulse width	$t_{EXCKW}$	—	$1/f_{EXCK} \times 0.4$	—	$1/f_{EXCK} \times 0.6$	s

## On-chip Oscillator

(V<sub>DD</sub>=1.6 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit	Measuring circuit
Low-speed RC oscillator frequency accuracy 1 Without software adjustment	f <sub>RCL1</sub>	Ta= +25°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -1.0%	32.768	Typ. +1.0%	kHz	1
		Ta= -40 to +85°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -2.5%	32.768	Typ. +2.5%		
		Ta= -40 to +105°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -3.0%	32.768	Typ. +3.0%		
		V <sub>DD</sub> = 1.6 to 1.8V	Typ. -3.5%	32.768	Typ. -3.5%		
Low-speed RC oscillator frequency accuracy 2 With software adjustment	f <sub>RCL2</sub>	Ta= -40 to +85°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -1.0%	32.768	Typ. +1.0%		
		Ta= -40 to +105°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -1.5%	32.768	Typ. +1.5%		
PLL oscillation frequency accuracy 1 Without software adjustment	f <sub>PLL1</sub>	Ta= -40 to +85°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -2.5%	16/24	Typ. +2.5%	MHz	
		Ta= -40 to +105°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -3.0%	16/24	Typ. +3.0%		
		V <sub>DD</sub> = 1.6 to 1.8V	Typ. -3.5%	16/24	Typ. +3.5%		
PLL oscillation frequency accuracy 2 With software adjustment	f <sub>PLL2</sub>	Ta= -40 to +85°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -1.0%	16/24	Typ. +1.0%		
		Ta= -40 to +105°C V <sub>DD</sub> = 1.8 to 5.5V	Typ. -1.5%	16/24	Typ. +1.5%		
PLL oscillation start time	T <sub>PLL</sub>	V <sub>DD</sub> = 1.6 to 5.5V	—	—	2	ms	
1kHz Low-speed RC oscillator (for WDT) frequency accuracy	f <sub>RC1K</sub>	Ta= -40 to +105°C V <sub>DD</sub> = 1.6 to 5.5V	0.5	1	2.5	kHz	

## Input / Output pin 1

(V<sub>DD</sub>=1.6 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit	Measuring circuit
Output voltage1 "H"/"L" level (P00-P07) (P10-P17) (P20-P27) (P30-P33) (P40-P47) (P50-P57) (P60-P67) (P70-P77) (P80-P87) (P90-P97) (PA0-PA7) (PB0-PB7)	VOH1	IOH1=-10mA V <sub>DD</sub> ≥4.5V	V <sub>DD</sub> -1.5	—	—	V	2
		IOH1=-1mA V <sub>DD</sub> ≥1.6V	V <sub>DD</sub> -0.5	—	—		
	VOL1	IOL1=+10mA V <sub>DD</sub> ≥4.5V	—	—	1.5		
		IOL1=+1mA V <sub>DD</sub> ≥1.6V	—	—	0.5		
Output voltage2 "L" level (P01-P07) (P10-P17) (P20-P27) (P30-P33) (P40-P47) (P50-P57) (P60-P67) (P70-P77) (P80-P87) (P90-P97) (PA0-PA7) (PB0-PB7)	VOL2	When Nch open drain output mode is selected	IOL2=+15mA V <sub>DD</sub> ≥4.5V	—	—	0.7	
			IOL2=+8mA V <sub>DD</sub> ≥3.0V	—	—	0.5	
			IOL2=+3mA V <sub>DD</sub> ≥2.0V	—	—	0.4	
			IOL2=+2mA V <sub>DD</sub> ≥1.6V	—	—	0.4	



Input / Output pin 2

(V<sub>DD</sub>=1.6 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit	Measuring circuit
“H” level output current1 *6	IOH1	1pin	V <sub>DD</sub> ≥4.5V	-10*3*5	—	—	mA
			V <sub>DD</sub> ≥1.6V	-1*3*5	—	—	
“H” level output total current *1*4	IOH3	Total of ‘P00-P07, P10-P13, P44-P47, P50-P53, P70-P76, P80-P87, P90-P97, PA0’ or ‘P14-P17, P20-P27, P30-P33, P40-P43, P54-P57 P60-P67,P77, PA1-PA7, PB0-PB7’ (duty≤50%)	V <sub>DD</sub> ≥4.5V	-90*5	—	—	
			V <sub>DD</sub> ≥1.6V	-20*5	—	—	
		All pin total (duty≤50%)	V <sub>DD</sub> ≥4.5V	-180*5	—	—	
			V <sub>DD</sub> ≥1.6V	-40*5	—	—	
“L” level output current1 *6	IOL1	1pin (CMOS output mode)	V <sub>DD</sub> ≥4.5V	—	—	10*3	
			V <sub>DD</sub> ≥1.6V	—	—	1*3	
“L” level output current2 *6	IOL2	1pin (Nch open drain output mode)	V <sub>DD</sub> ≥4.5V	—	—	15*3	
			V <sub>DD</sub> ≥3.0V	—	—	8*3	
			V <sub>DD</sub> ≥2.0V	—	—	3*3	
			V <sub>DD</sub> ≥1.6V	—	—	2*3	
“L” level output total current *2*4	IOL3	Total of P00-P07, P10-P13, P44-P47, P50-P53, P70-P76, P80-P87, P90-P97, PA0’ or ‘P14~P17, P20-P27, P30-P33, P40-P43, P54-P57 P60-P67,P77, PA1-PA7, PB0-PB7’ (Nch open drain output mode,duty≤50%)	V <sub>DD</sub> ≥4.5V	—	—	90	
			V <sub>DD</sub> ≥3.0V	—	—	40	
			V <sub>DD</sub> ≥2.0V	—	—	15	
			V <sub>DD</sub> ≥1.6V	—	—	10	
		All pin total (Nch open drain output mode,duty≤50%)	V <sub>DD</sub> ≥4.5V	—	—	180	
			V <sub>DD</sub> ≥1.6V	—	—	20	
Output leak (P00-P07) (P10-P17) (P20-P27) (P30-P33) (P40-P47) (P50-P57) (P60-P67) (P70-P77) (P80-P87) (P90-P97) (PA0-PA7) (PB0-PB7)	IOOH	VOH=V <sub>DD</sub> (High impedance mode)	—	—	+1	μA	
	IOOL	VOL=V <sub>SS</sub> (High impedance mode)	-1*5	—	—		

3

- \*1 Sink-out current from  $V_{DD}$  to the output pin, which can guarantee the device operation.
- \*2 Sink-in current from the output pin to  $V_{SS}$ , which can guarantee the device operation.
- \*3 Do not beyond total current.
- \*4 The total current is on the condition of Duty $\leq$ 50%(same applies to IOH1).  
When the duty $>$ 50% the total current is calculated by following formula.  
Total current =  $IOL3 \times 50/n$  (When the duty is n%)  
<For an example> When  $IOL3=100\text{mA}$  and  $n=80\%$ ,  
Total current =  $IOL3 \times 50/80 = 62.5\text{mA}$   
Current allowed per 1pin is independent of the duty and specified as IOL1 and IOL2.  
Do not apply current larger than Absolute Maximum Ratings.
- \*5 The current flowing out the LSI through the pin is described in the negative number.  
The applicable maximum current is the absolute value.  
For example, -1mA means the maximum current 1mA flows out the LSI through the pin.
- \*6 These values are satisfied with VOH1, VOL1 and VOL2.

## Input / Output pin 3

(V<sub>DD</sub>=1.6 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit	Measuring circuit
Input current1 (RESET_N)	I <sub>IH1</sub>	V <sub>IH1</sub> =V <sub>DD</sub>	—	—	1	μA	4
	I <sub>IL1</sub>	V <sub>IL1</sub> =V <sub>SS</sub>	-1 <sup>*1</sup>	—	—		
Input current2 (P00/TEST0)	I <sub>IL2</sub>	V <sub>IL2</sub> =V <sub>SS</sub> (pull-up mode) <sup>*2</sup>	-1500 <sup>*1</sup>	-300 <sup>*1</sup>	-20 <sup>*1</sup>	kΩ	
	V/I <sub>IL2</sub>	V <sub>IL2</sub> =V <sub>SS</sub> (pull-up mode) <sup>*2</sup>	3.7	10	80	μA	
	I <sub>IH2Z</sub>	V <sub>IH2</sub> =V <sub>DD</sub> (High impedance mode)	—	—	1		
	I <sub>IL2Z</sub>	V <sub>IL2</sub> =V <sub>SS</sub> (High impedance mode)	-1 <sup>*1</sup>	—	—		
Input current3 (P01-P07) (P10-P17) (P20-P27) (P30-P33) (P40-P47) (P50-P57) (P60-P67) (P70-P77) (P80-P87) (P90-P97) (PA0-PA7) (PB0-PB7)	I <sub>IL3</sub>	V <sub>IL1</sub> =V <sub>SS</sub> (pull-up mode) <sup>*2</sup>	-250 <sup>*1</sup>	-30 <sup>*1</sup>	-2 <sup>*1</sup>	kΩ	
	V/I <sub>IL3</sub>	V <sub>IL1</sub> =V <sub>SS</sub> (pull-up mode) <sup>*2</sup>	22	100	800		
	I <sub>IH3Z</sub>	V <sub>IH1</sub> =V <sub>DD</sub> (High impedance mode)	—	—	1	μA	
	I <sub>IL3Z</sub>	V <sub>IL1</sub> =V <sub>SS</sub> (High impedance mode)	-1 <sup>*1</sup>	—	—		
Input current4 (PI00-PI01)	I <sub>IH4</sub>	V <sub>IH1</sub> =V <sub>DD</sub>	—	—	1	—	
	I <sub>IL4</sub>	V <sub>IL1</sub> =V <sub>SS</sub>	-1 <sup>*1</sup>	—	—		
Input voltage1 (RESET_N) (P01-P07) (P10-P17) (P20-P27) (P30-P33) (P40-P47) (P50-P57) (P60-P67) (P70-P77) (P80-P87) (P90-P97) (PA0-PA7) (PB0-PB7) (PI00-PI01)	V <sub>IH1</sub>	—	0.7 x V <sub>DD</sub>	—	V <sub>DD</sub>	V	5
	V <sub>IL1</sub>	—	0	—	0.3 x V <sub>DD</sub>		
Input voltage2 (P00/TEST0)	V <sub>IH2</sub>	—	0.7 x V <sub>DD</sub>	—	V <sub>DD</sub>	—	
	V <sub>IL2</sub>	—	0	—	0.25 x V <sub>DD</sub>		
Pin capacitance (RESET_N) (P00/TEST0) (P01-P07) (P10-P17) (P20-P27) (P30-P33) (P40-P47) (P50-P57) (P60-P67) (P70-P77) (P80-P87) (P90-P97) (PA0-PA7) (PB0-PB7) (PI00-PI01)	C <sub>PIN</sub>	f = 10kHz Ta = +25°C	—	—	10	pF	—

<sup>\*1</sup> The current flowing out the LSI through the pin is described in the negative number. The applicable maximum current is the absolute value. For example, -1mA means the maximum current 1mA flows out the LSI through the pin.

<sup>\*2</sup> Measurement conditions: Typ. : V<sub>DD</sub> = 3.0V, Max. : V<sub>DD</sub> = 1.6V, Min. : V<sub>DD</sub> = 5.5V

Synchronous Serial Port

Slave mode

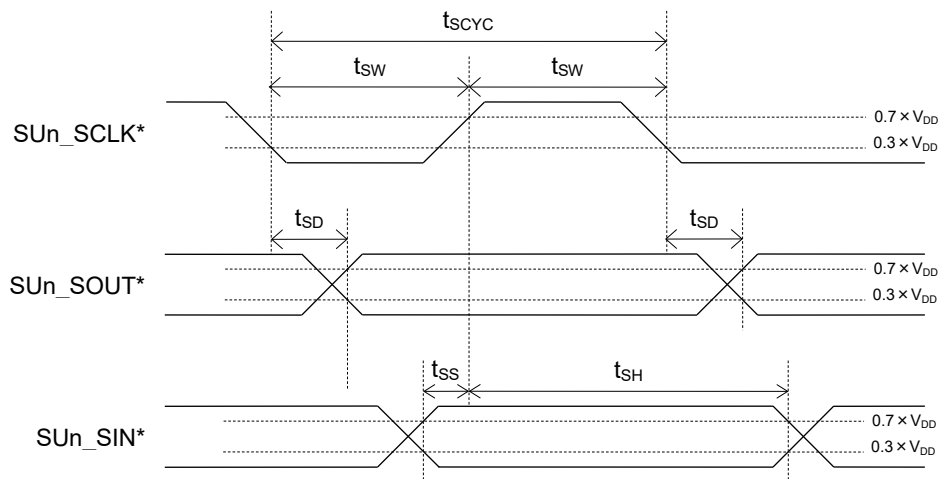
( $V_{DD}=1.8$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
SCK input cycle	$t_{SCYC}$	—	1 <sup>*2</sup>	—	—	$\mu s$
SCK input pulse width	$t_{SW}$	—	0.5 <sup>*3</sup>	—	—	$\mu s$
SOUT output delay time	$t_{SD}$	$V_{DD}=2.4$ to $5.5V$	—	—	$100+HSCLK^{*1} \times 3$	ns
		$V_{DD}=1.8$ to $5.5V$	—	—	$200+HSCLK^{*1} \times 3$	ns
SIN input setup time	$t_{SS}$	—	$HSCLK^{*1} \times 1$	—	—	ns
SIN input hold time	$t_{SH}$	—	$80+HSCLK^{*1} \times 3$	—	—	ns

\*1 Cycle of high speed clock

\*2 Need input cycles of HSLCK x8 or longer

\*3 Need input cycles of HSLCK x4 or longer



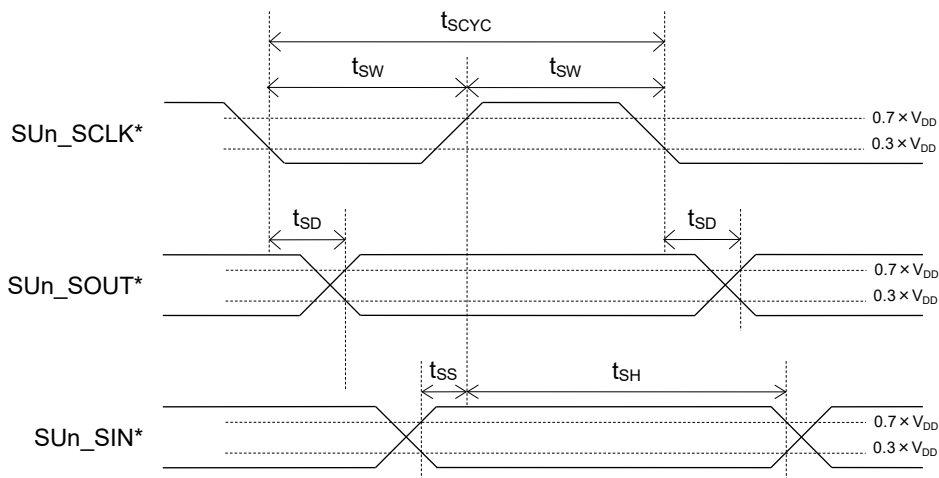
\* 2<sup>nd</sup> to 8<sup>th</sup> function of port, n=0 to 5

Master mode

( $V_{DD}=1.8$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
SCK output cycle	$t_{SCYC}$	—	—	$SCLK^{*1}$	—	ns
SCK output pulse width	$t_{SW}$	—	$SCLK^{*1} \times 0.4$	$SCLK^{*1} \times 0.5$	$SCLK^{*1} \times 0.6$	ns
SOUT output delay time	$t_{SD}$	$V_{DD}=2.4$ to $5.5V$	—	—	100	ns
		$V_{DD}=1.8$ to $5.5V$	—	—	160	ns
SIN input setup time	$t_{SS}$	$V_{DD}=2.4$ to $5.5V$	120	—	—	ns
		$V_{DD}=1.8$ to $5.5V$	180	—	—	ns
SIN input hold time	$t_{SH}$	$V_{DD}=2.4$ to $5.5V$	80	—	—	ns
		$V_{DD}=1.8$ to $5.5V$	100	—	—	ns

\*1 Clock cycle selected by bit12~8(SnCK4~0) of the serial port n mode register (SIO nMOD)  
 $V_{DD} \geq 2.4V$ : min250ns,  $V_{DD} \geq 1.8V$ : min500ns



\* 2<sup>nd</sup> to 8<sup>th</sup> function of port, n=0 to 5

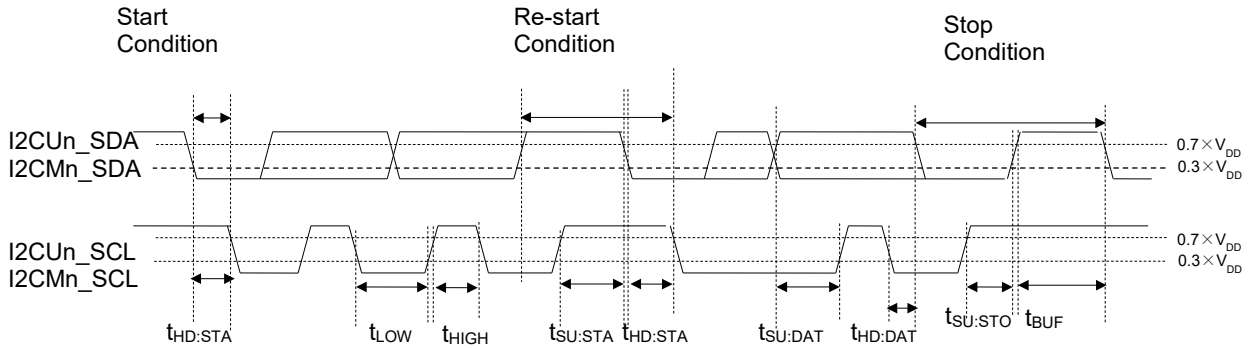
I<sup>2</sup>C Bus Interface

Standard Mode (100kbit/s)

(V<sub>DD</sub>=1.8 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
SCL clock frequency	f <sub>SCL</sub>	—	0	—	100	kHz
SCL hold time (start/restart condition)	t <sub>HD:STA</sub>	—	4.0	—	—	μs
SCL "L" level time	t <sub>LOW</sub>	—	4.7	—	—	μs
SCL "H" level time	t <sub>HIGH</sub>	—	4.0	—	—	μs
SCL setup time (restart condition)	t <sub>SU:STA</sub>	—	4.7	—	—	μs
SDA hold time	t <sub>HD:DAT</sub>	—	0	—	—	μs
SDA setup time	t <sub>SU:DAT</sub>	—	0.25	—	—	μs
SDA setup time (stop condition)	t <sub>SU:STO</sub>	—	4.0	—	—	μs
Bus-free time	t <sub>BUF</sub>	—	4.7	—	—	μs

When using the I<sup>2</sup>C as the master, configure the I<sup>2</sup>C master n mode register(I2MnMOD) and I<sup>2</sup>C bus 0 mode register (master side, I2UM0MOD) so that meet these specifications.



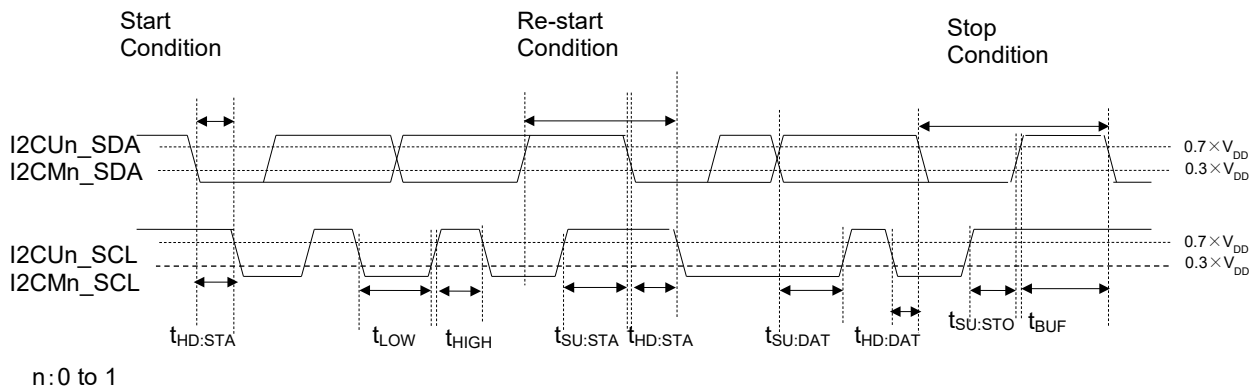
n:0 to 1

Fast Mode (400 kbit/s)

( $V_{DD}=1.8$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
SCL clock frequency	$f_{SCL}$	—	0	—	400	kHz
SCL hold time (start/restart condition)	$t_{HD:STA}$	—	0.6	—	—	$\mu s$
SCL "L" level time	$t_{LOW}$	—	1.3	—	—	$\mu s$
SCL "H" level time	$t_{HIGH}$	—	0.6	—	—	$\mu s$
SCL setup time (restart condition)	$t_{SU:STA}$	—	0.6	—	—	$\mu s$
SDA hold time	$t_{HD:DAT}$	—	0	—	—	$\mu s$
SDA setup time	$t_{SU:DAT}$	—	0.1	—	—	$\mu s$
SDA setup time (stop condition)	$t_{SU:STO}$	—	0.6	—	—	$\mu s$
Bus-free time	$t_{BUF}$	—	1.3	—	—	$\mu s$

When using the I<sup>2</sup>C as the master, configure the I<sup>2</sup>C master n mode register(I2MnMOD) and I<sup>2</sup>C bus 0 mode register (master side, I2UM0MOD) so that meet these specifications.

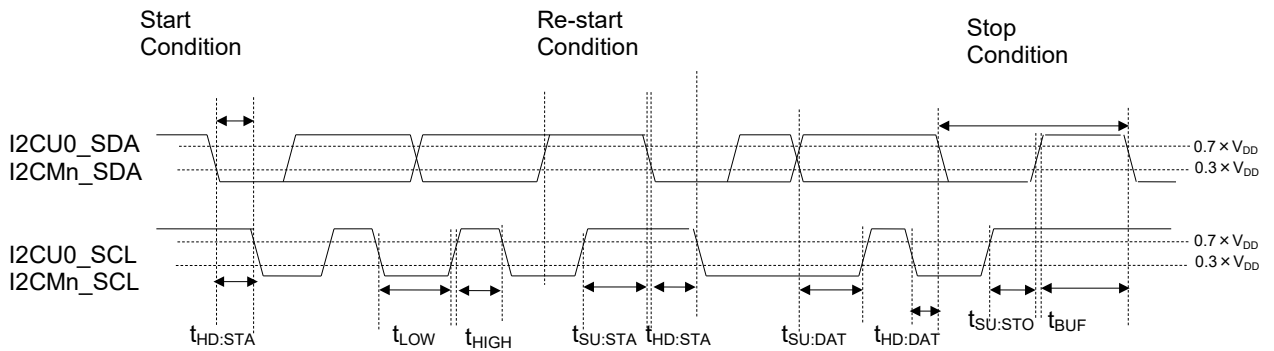


1Mbps Mode (1M bit/s)

( $V_{DD}=2.7$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
SCL clock frequency	$f_{SCL}$	—	0	—	1000	kHz
SCL hold time (start/restart condition)	$t_{HD:STA}$	—	0.26	—	—	$\mu s$
SCL "L" level time	$t_{LOW}$	—	0.5	—	—	$\mu s$
SCL "H" level time	$t_{HIGH}$	—	0.26	—	—	$\mu s$
SCL setup time (restart condition)	$t_{SU:STA}$	—	0.26	—	—	$\mu s$
SDA hold time	$t_{HD:DAT}$	—	0	—	—	$\mu s$
SDA setup time	$t_{SU:DAT}$	—	0.1	—	—	$\mu s$
SDA setup time (stop condition)	$t_{SU:STO}$	—	0.26	—	—	$\mu s$
Bus-free time	$t_{BUF}$	—	0.5	—	—	$\mu s$

When using the I<sup>2</sup>C as the master, configure the I<sup>2</sup>C master n mode register(I2MnMOD) and I<sup>2</sup>C bus 0 mode register (master side, I2UM0MOD) so that meet these specifications.



n: 0 to 1

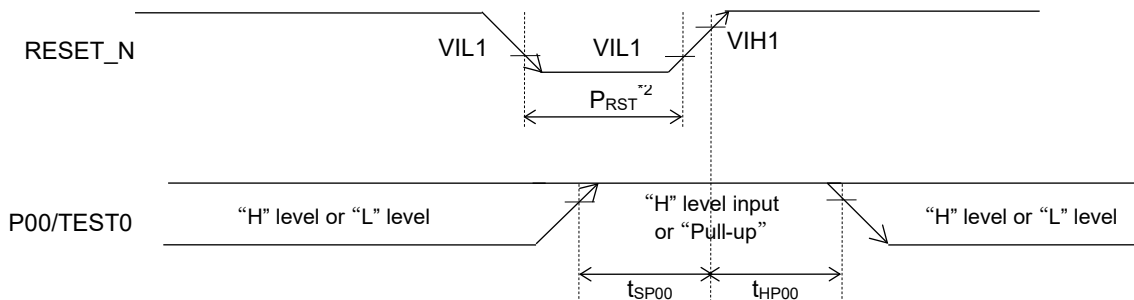


Reset

( $V_{DD}=1.6$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit	Measuring circuit
Reset pulse width	$P_{RST}$	—	2	—	—	ms	1
P00 "H" level setup time	$t_{SP00}$	—	1	—	—	ms	
P00 "H" level hold time <sup>*1</sup>	$t_{HP00}^{*1}$	—	1	—	—	ms	

<sup>\*1</sup>: except ISP mode. Refer to the User's manual "25.4 In-System Programming Function" for the timing in ISP mode.



<sup>\*2</sup>:  $V_{DD}=1.6V$  or over at power on.

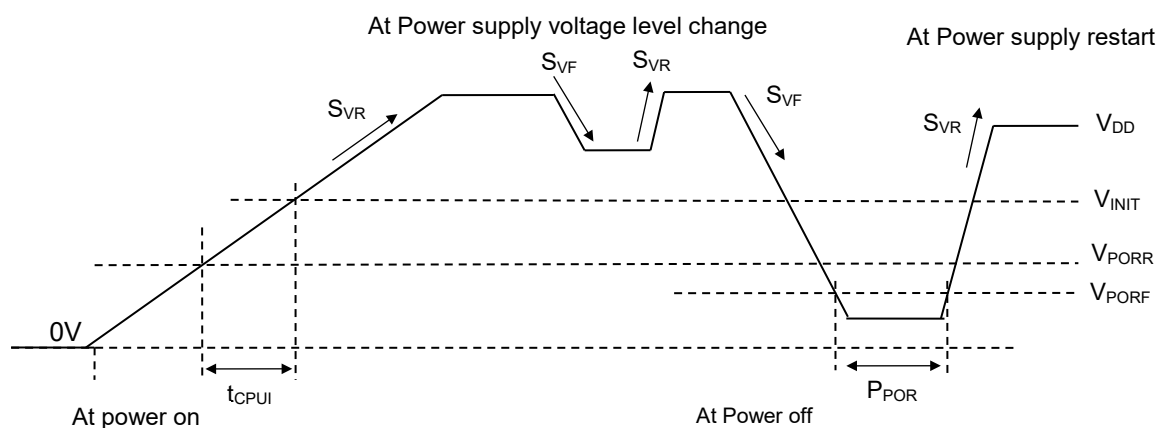
Note:

- RESET\_N input shorter pulse than the Reset pulse width ( $P_{RST}$ ) valid time should be avoided. The shorter pulse input may cause unexpected behavior.

## Slope of Power supply and Power On Reset

( $V_{SS} = 0V$ ,  $T_a = -40$  to  $+105^\circ C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit	Measuring circuit
Power on rising slope	$S_{VR}$	—	—	—	60	V/ms	1
Power on falling slope	$S_{VF}$	—	—	—	2	V/ms	
Power on reset detection voltage	$V_{PORR}$	At Power up (rising)	1.47	1.57	1.80	V	
	$V_{PORF}$	At Power down (falling)	1.33	1.49	1.58	V	
Power on reset minimum pulse width	$P_{POR}$	—	200	—	—	$\mu s$	
Power on voltage	$V_{INIT}$	At power on	1.8	—	—	V	
CPU operation start time (from the release of reset to the CPU starts to run)	$t_{CPUI}$	—	11	16	—	ms	—



**Note:**

- If a pulse shorter than the Power on reset minimum pulse width is asserted to  $V_{DD}$ , it may cause the MCU malfunction. Apply prevent measurement such as bypass capacitors or external reset input, and so on.
- Start the high-speed clock when the  $V_{DD}$  is within the operating voltage.

## VLS

(V<sub>DD</sub>=1.6 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition		Min.	Typ.	Max.	Unit	Measuring circuit
		VLS0LV * <sup>1</sup>						
VLS threshold voltage * <sup>2</sup>	V <sub>VLSR</sub>	00H	Rising	3.86	4.06	4.26	V	1
	V <sub>VLSF</sub>		Falling	3.84	4.00	4.16		
	V <sub>VLSR</sub>	01H	Rising	3.57	3.76	3.95		
	V <sub>VLSF</sub>		Falling	3.55	3.70	3.85		
	V <sub>VLSR</sub>	02H	Rising	2.94	3.11	3.28		
	V <sub>VLSF</sub>		Falling	2.92	3.05	3.18		
	V <sub>VLSR</sub>	03H	Rising	2.85	3.01	3.17		
	V <sub>VLSF</sub>		Falling	2.83	2.95	3.07		
	V <sub>VLSR</sub>	04H	Rising	2.75	2.91	3.07		
	V <sub>VLSF</sub>		Falling	2.73	2.85	2.97		
	V <sub>VLSR</sub>	05H	Rising	2.66	2.81	2.96		
	V <sub>VLSF</sub>		Falling	2.64	2.75	2.86		
	V <sub>VLSR</sub>	06H	Rising	2.56	2.71	2.86		
	V <sub>VLSF</sub>		Falling	2.54	2.65	2.76		
	V <sub>VLSR</sub>	07H	Rising	2.46	2.61	2.76		
	V <sub>VLSF</sub>		Falling	2.44	2.55	2.66		
	V <sub>VLSR</sub>	08H	Rising	2.37	2.51	2.65		
	V <sub>VLSF</sub>		Falling	2.35	2.45	2.55		
	V <sub>VLSR</sub>	09H	Rising	1.98	2.11	2.24		
	V <sub>VLSF</sub>		Falling	1.96	2.05	2.14		
V <sub>VLSR</sub>	0AH	Rising	1.89	2.01	2.13			
V <sub>VLSF</sub>		Falling	1.87	1.95	2.03			
V <sub>VLSR</sub>	0BH	Rising	1.79	1.91	2.03			
V <sub>VLSF</sub>		Falling	1.77	1.85	1.93			
VLS Current	I <sub>VLS</sub>	—		—	50	—	nA	

\*<sup>1</sup> Bit3~Bit0 of voltage level detection circuit 0 level register (VLS0LV).\*<sup>2</sup> The Data VLS0LV = 0CH~0FH is not available to use, if the data is specified it will the same spec as that 0BH is specified.

## Analog Comparator

(V<sub>DD</sub>=1.8 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit	Measuring circuit
Comparator same phase input voltage range	V <sub>CMR</sub>	—	0.1	—	V <sub>DD</sub> -1.5	V	1
Comparator0 input offset	V <sub>CMOF</sub>	Ta=+25°C, V <sub>DD</sub> =5.0V	—	5	—	mV	
Comparator Reference Voltage	V <sub>CMREF</sub>	—	0.75	0.8	0.85	V	

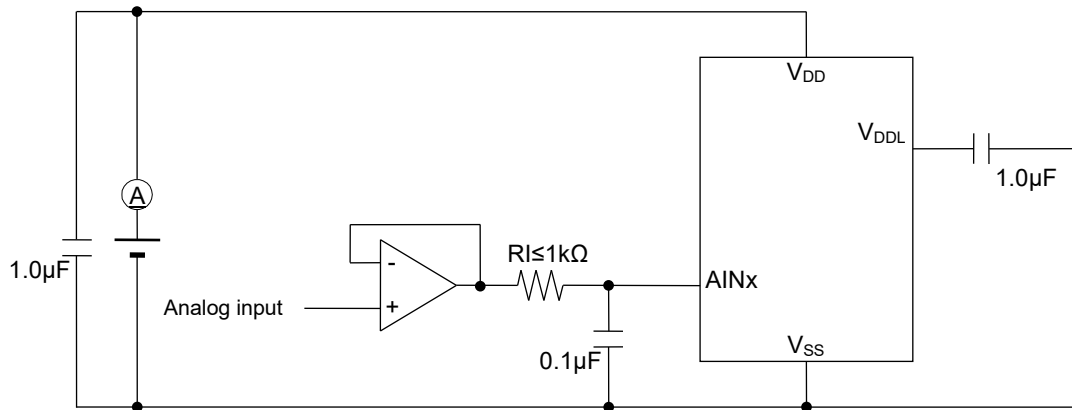
Successive Approximation Type A/D Converter

( $V_{DD}=1.8$  to  $5.5V$ ,  $V_{SS}=0V$ ,  $T_a=-40$  to  $+105^{\circ}C$ , unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Resolution	$n_{AD}$	—	—	—	10	bit
Overall error	—	$4.5V \leq \text{Reference voltage}^{*1} \leq 5.5V$	-3.5	1.2	3.5	LSB
Integral non-linearity error	INL <sub>AD</sub>	$2.7V \leq \text{Reference voltage}^{*1} \leq 5.5V$	-4	—	4	
		$2.2V \leq \text{Reference voltage}^{*1} < 2.7V$	-6	—	6	
		$1.8V \leq \text{Reference voltage}^{*1} < 2.2V$	-10	—	10	
		Reference voltage = Internal reference voltage ( $V_{REFI}$ )	-15	—	15	
Differential non-linearity error	DNL <sub>AD</sub>	$2.7V \leq \text{Reference voltage}^{*1} \leq 5.5V$	-3	—	3	
		$2.2V \leq \text{Reference voltage}^{*1} < 2.7V$	-5	—	5	
		$1.8V \leq \text{Reference voltage}^{*1} < 2.2V$	-9	—	9	
		Reference voltage = Internal reference voltage ( $V_{REFI}$ )	-14	—	14	
Zero-scale error	ZSE	$R_I \leq 1k\Omega$	-6	—	6	V
Full-scale error	FSE	$R_I \leq 1k\Omega$	-6	—	6	
A/D reference voltage	$V_{REF}$	—	1.8	—	$V_{DD}$	V
Internal reference voltage	$V_{REFI}$	—	1.5	1.55	1.6	
Conversion time	$t_{CONV}$	$4.5V \leq V_{DD} \leq 5.5V$	2.25	—	427	$\mu s$
		$2.2V \leq V_{DD} \leq 5.5V$	4.5	—	427	
		$1.8V \leq V_{DD} \leq 5.5V$	18	—	427	

\*1 :  $V_{DD}$  or P23/ $V_{REF}$  is selected for the reference voltage of Successive Approximation Type A/D Converter by setting bit5(VREFP1) and bit4(VREFP0) of Reference voltage control register(VREFCON).

The current flows during the ADC sampling as it takes charging. Make the output impedance of the analog signal source  $1k\Omega$  or smaller. Also, putting  $0.1\mu F$  capacitor on the ADC input pin is recommended to reduce the noise.



## D/A Converter

(V<sub>DD</sub>=1.8 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Resolution	n <sub>DA</sub>	—	—	—	8	bit
Conversion cycle	t <sub>C</sub>	—	10	—	—	μs
Integral non-linearity error	INL <sub>DA</sub>	RL=4MΩ	-2	—	2	LSB
Differential non-linearity error	DNL <sub>DA</sub>	RL=4MΩ	-1	—	1	
Output impedance	R <sub>O</sub>	DACEN bit of D/A converter enable register =1	3	6	9	kΩ

## Reference Voltage Output

(V<sub>DD</sub>=1.8 to 5.5V, V<sub>SS</sub>=0V, Ta=-40 to +105°C, unless otherwise specified)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Output voltage	V <sub>REFO</sub>	—	—	1.55	—	V
Output impedance	R <sub>VREFO</sub>	—	—	—	500	kΩ

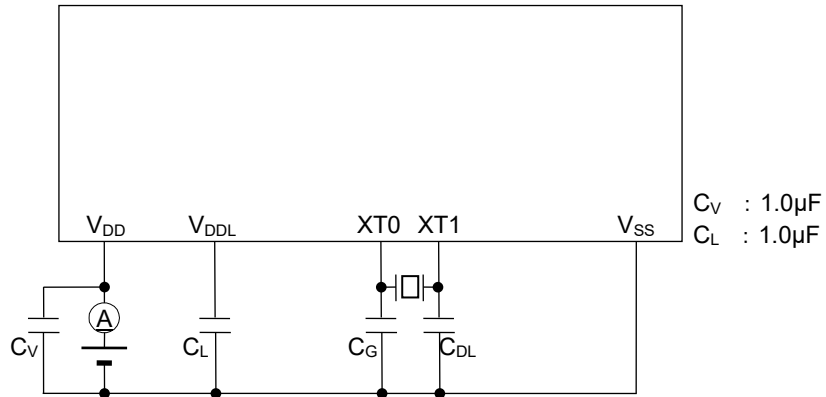
## Flash Memory

(V<sub>SS</sub>= 0V)

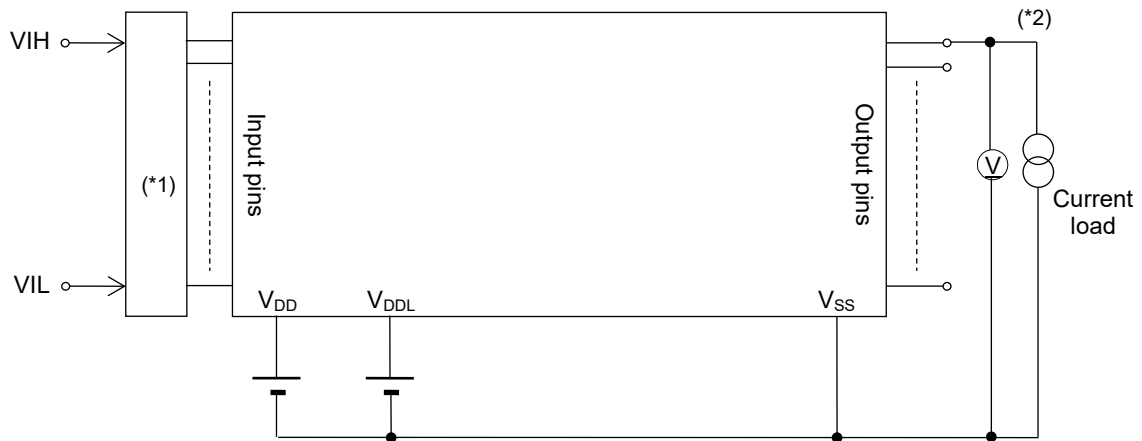
Parameter	Symbol	Condition	Range	Unit	
Operating temperature	T <sub>OP</sub>	Data flash memory, At write/erase	-40 to +85	°C	
		Flash ROM, At write/erase	0 to +40		
Operating voltage	V <sub>DD</sub>	At write/erase	+1.8 to +5.5	V	
Maximum rewrite count	CEPD	Data Flash	10000	times	
	CEPP	Program Flash	100		
Erase unit	—	Block erase	Program Flash	16K	B
			Data Flash	all area	
	—	Sector erase	Program Flash	1K	B
			Data Flash	128	
Erase time (Max.)	—	Block erase / Sector erase	50	ms	
Write unit	—	Program Flash	4	B	
		Data Flash	1		
Write time (Max.)	—	Program Flash	80	μs	
	—	Data Flash	40		
Data retention period	YDR	—	15	years	

Measuring circuit

Measuring circuit 1

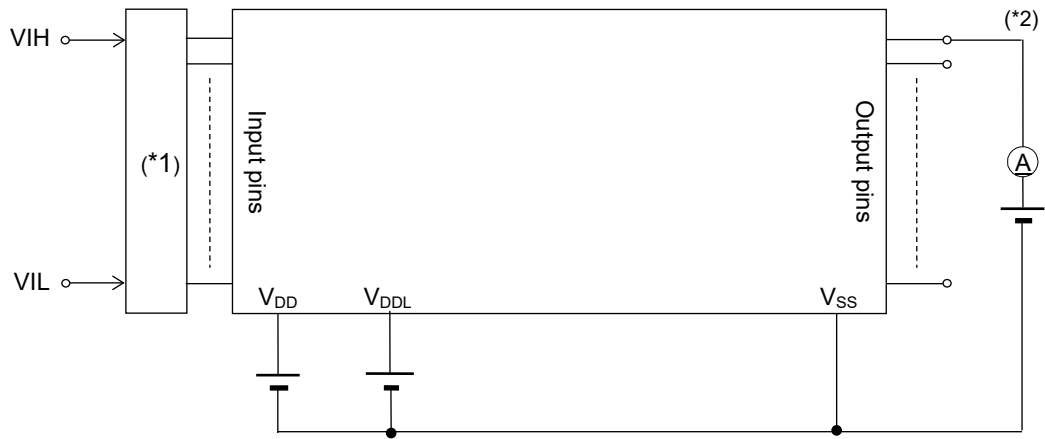


Measuring circuit 2



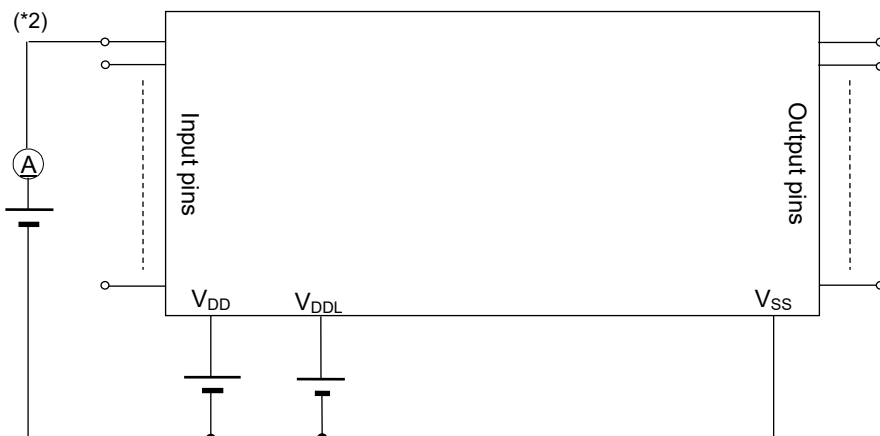
(\*1) Input logic circuit to determine the specified measuring conditions  
 (\*2) Measured connecting specified pins

Measuring circuit 3



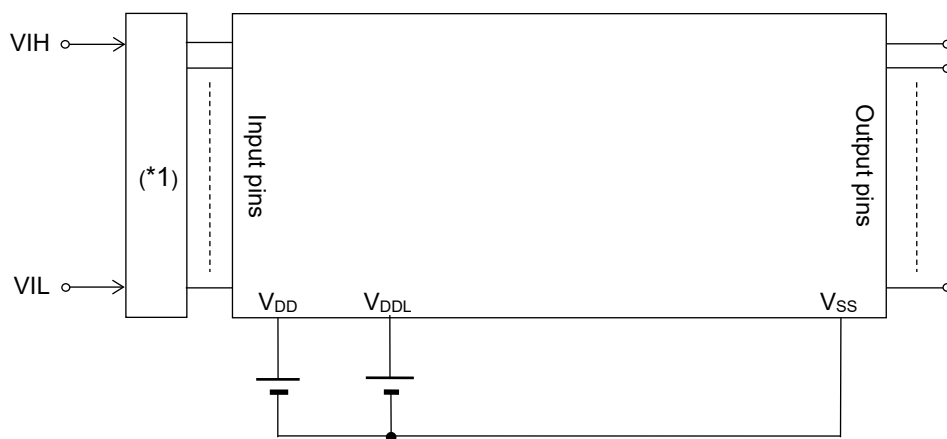
(\*1) Input logic circuit to determine the specified measuring conditions  
 (\*2) Measured connecting specified pins

Measuring circuit 4



$(*2)$  Measured connecting specified pins

Measuring circuit 5



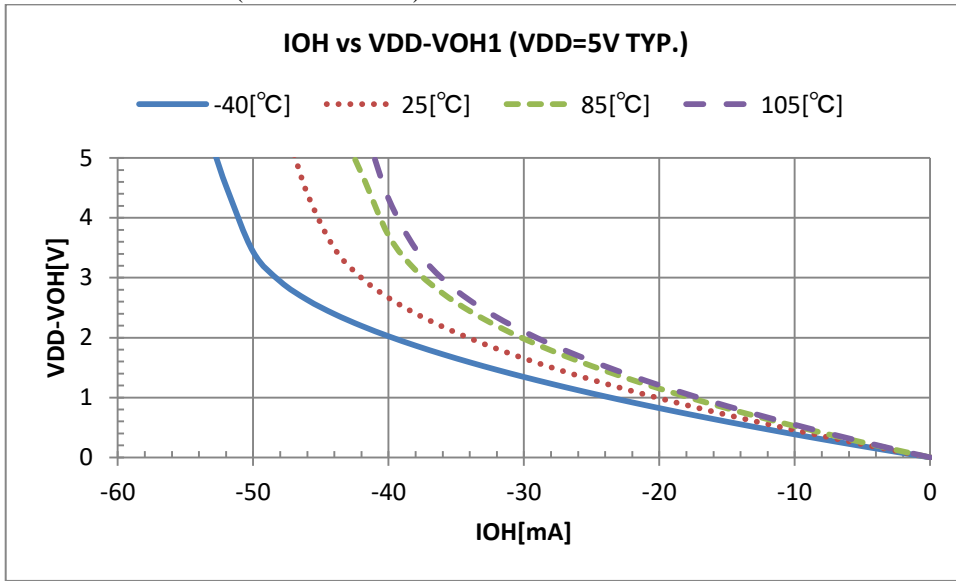
$(*1)$  Input logic circuit to determine the specified measuring conditions

## Characteristics graphs

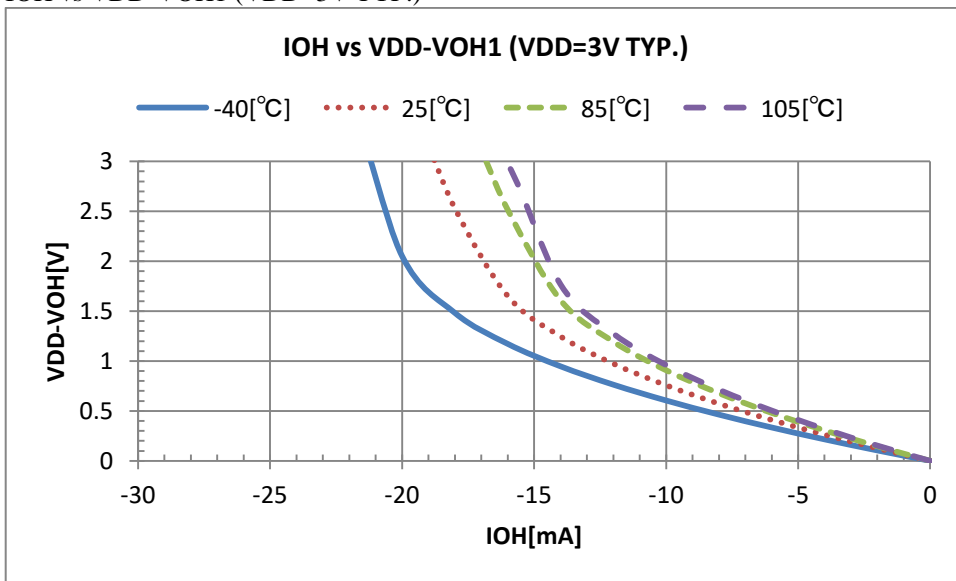
These Graphs on the following pages are references for designing an application.



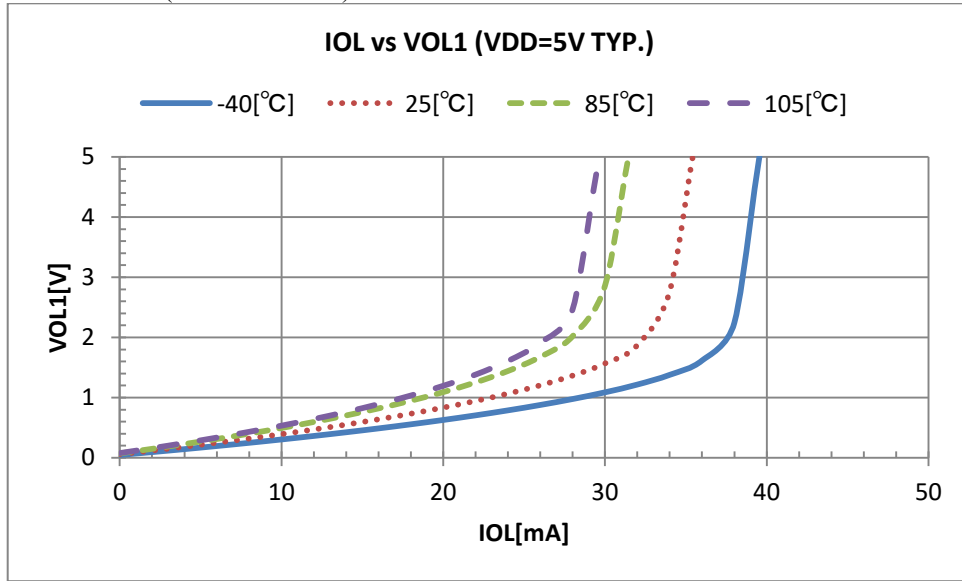
IOH vs VDD-VOH1 (VDD=5V TYP.)



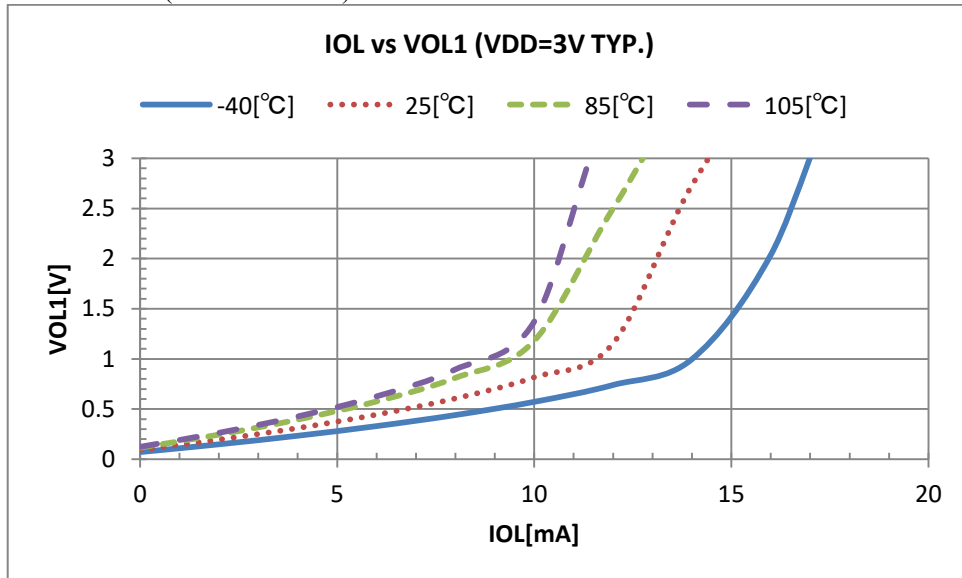
IOH vs VDD-VOH1 (VDD=3V TYP.)



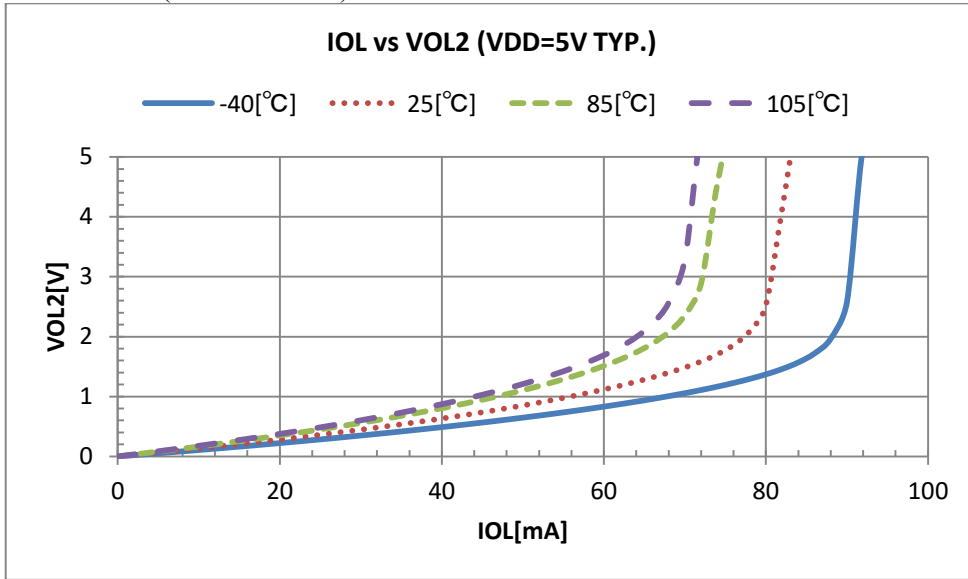
IOL vs VOL1 (VDD=5V TYP.)



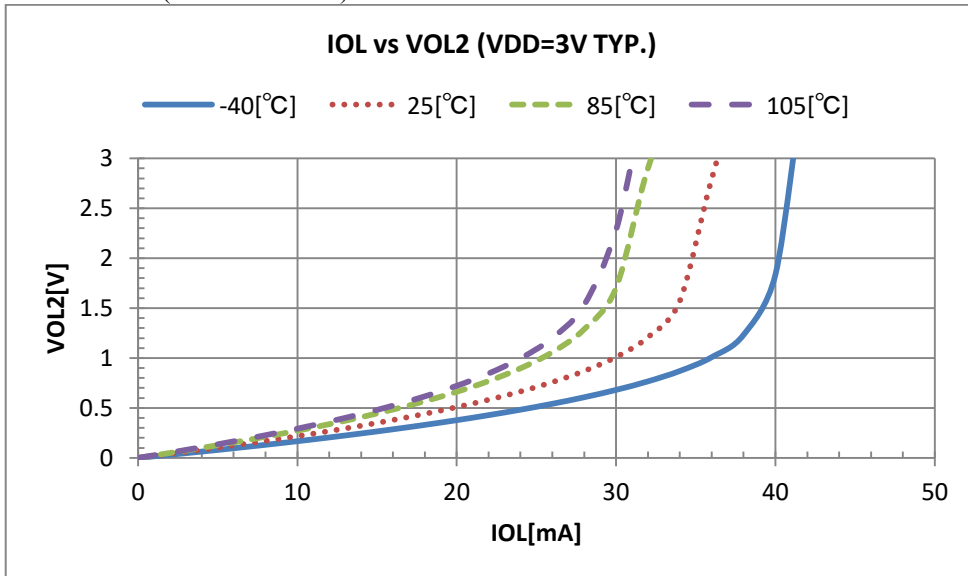
IOL vs VOL1 (VDD=3V TYP.)



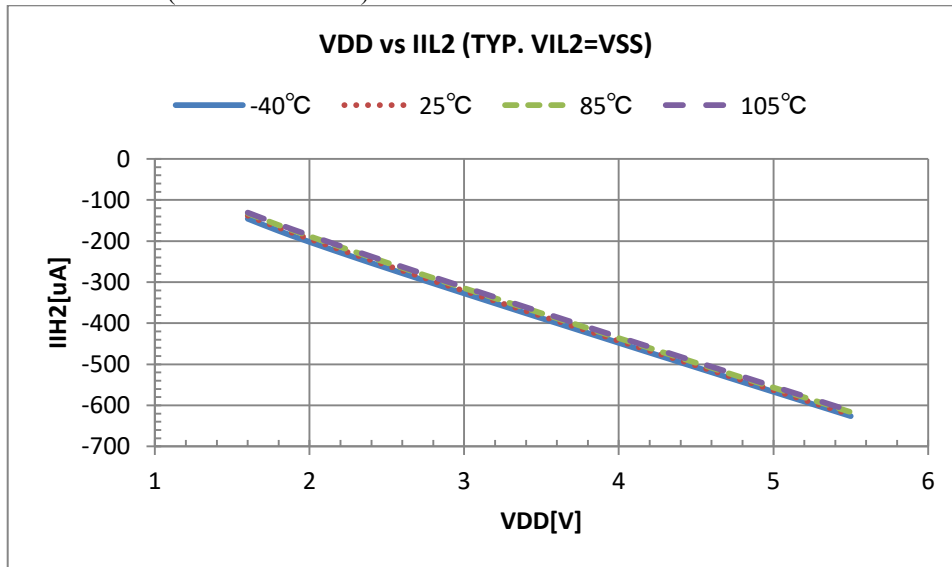
IOL vs VOL2 (VDD=5V TYP.)



IOL vs VOL2 (VDD=3V TYP.)

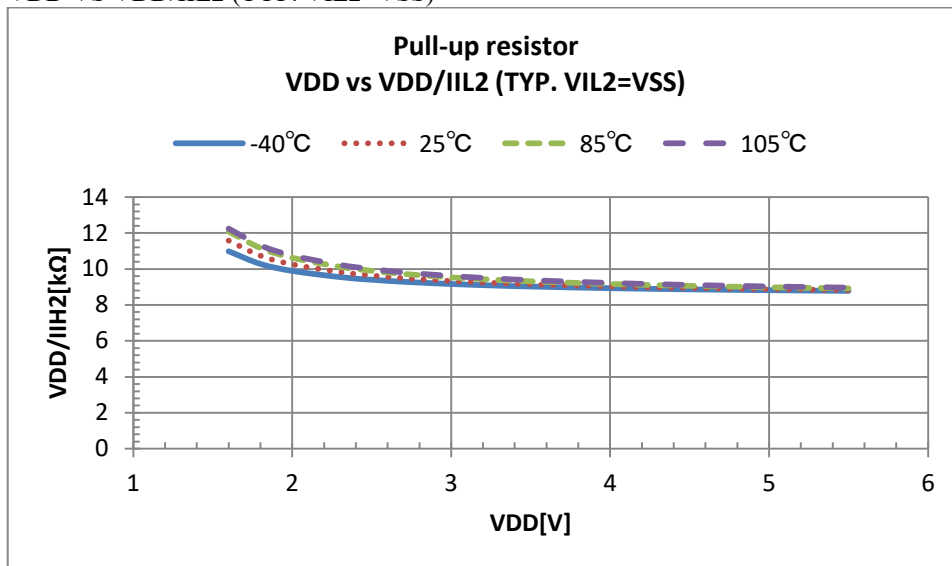


VDD VS IIL2 (TYP. VIL2=VSS)

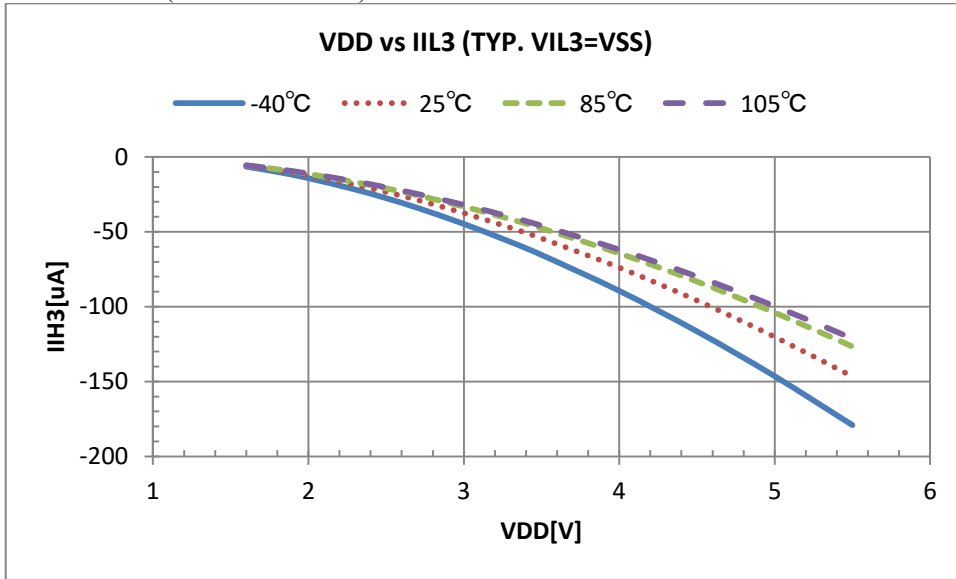


Pull-up resistor

VDD VS VDD/IIL2 (TYP. VIL2=VSS)

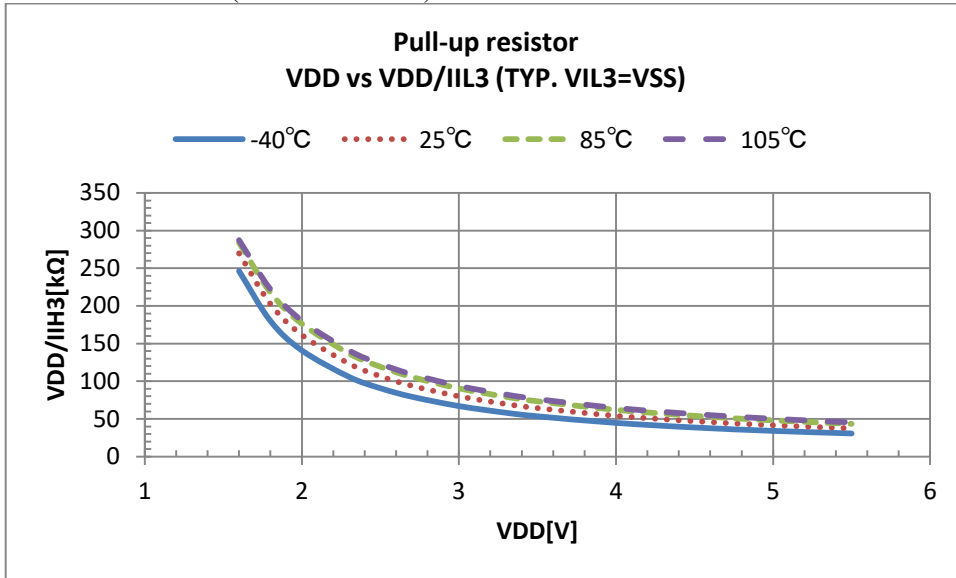


VDD VS IIL3 (TYP. VIL3=VSS)



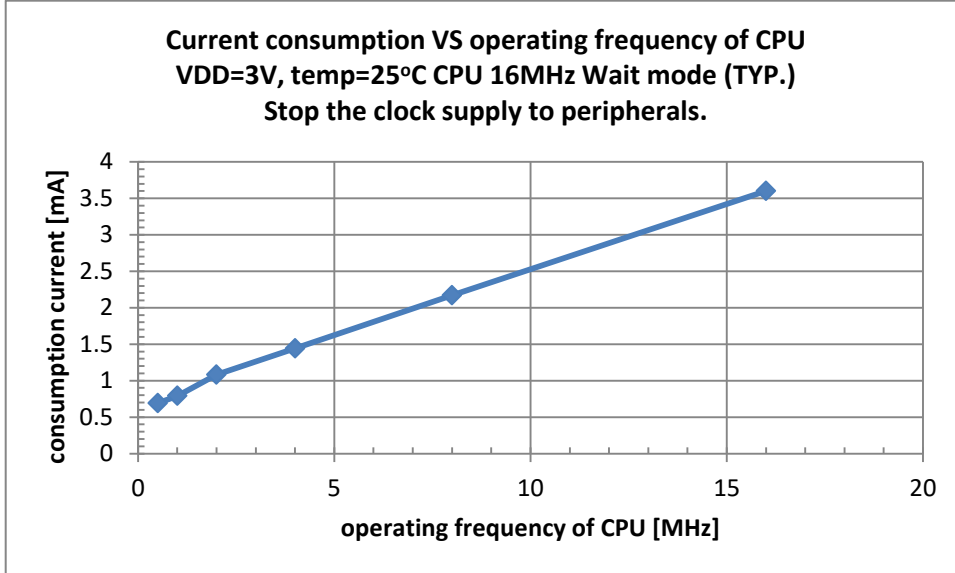
Pull-up resistor

VDD VS VDD/IIL3 (TYP. VIL3=VSS)

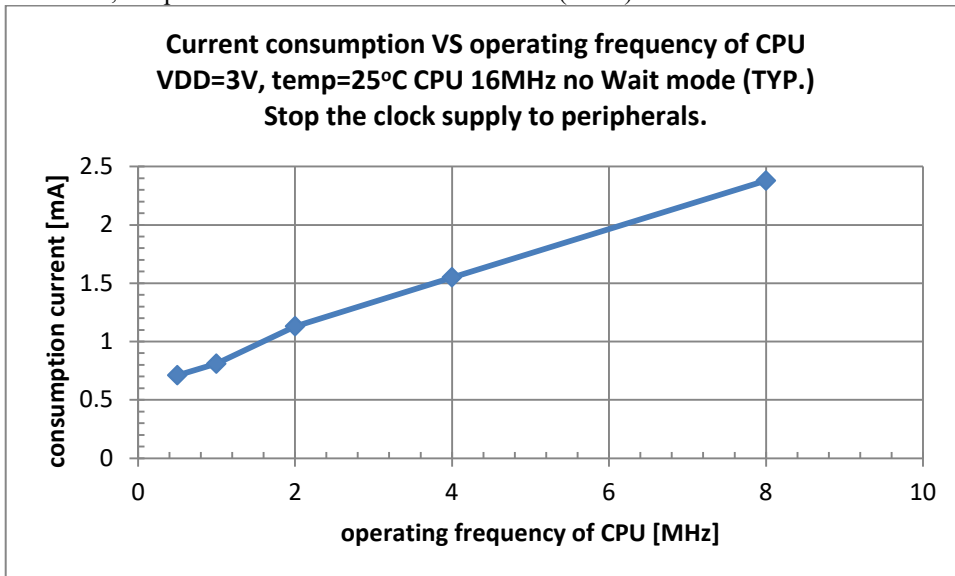


Product: ML62Q1530, ML62Q1531, ML62Q1532, ML62Q1533, ML62Q1534, ML62Q1540, ML62Q1541, ML62Q1542, ML62Q1543, ML62Q1544, ML62Q1550, ML62Q1551, ML62Q1552, ML62Q1553, ML62Q1554

Current consumption VS operating frequency of CPU  
VDD=3V, temp=25°C CPU 16MHz Wait mode (TYP.)  
Stop the clock supply to peripherals.

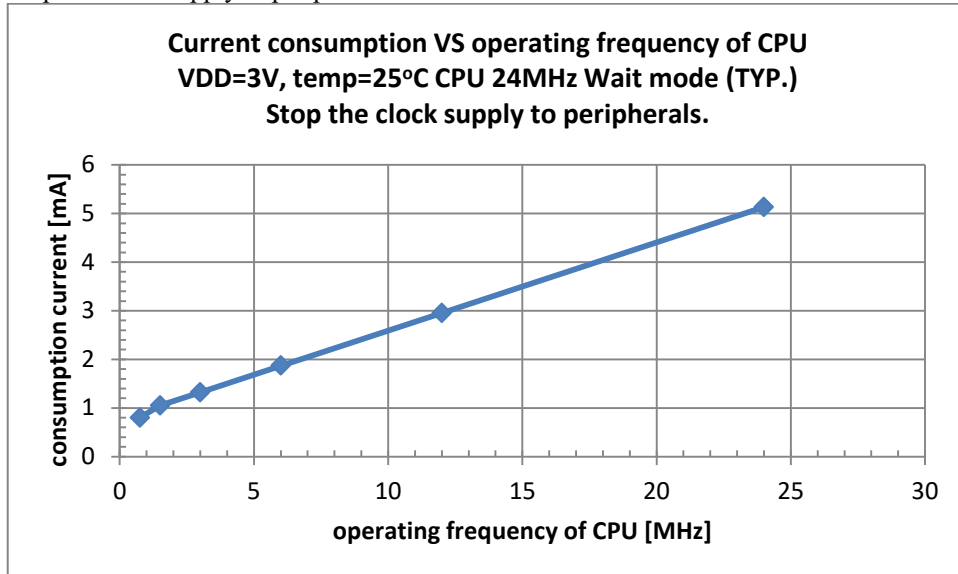


VDD=3V, temp=25°C CPU 16MHz no Wait mode (TYP.)

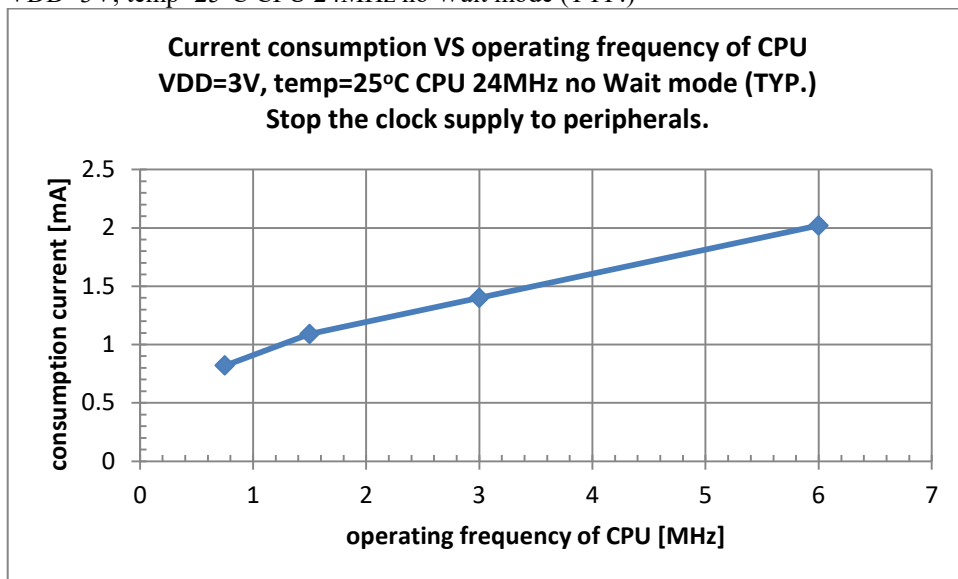


Product: ML62Q1530, ML62Q1531, ML62Q1532, ML62Q1533, ML62Q1534, ML62Q1540, ML62Q1541, ML62Q1542, ML62Q1543, ML62Q1544, ML62Q1550, ML62Q1551, ML62Q1552, ML62Q1553, ML62Q1554

Current consumption VS operating frequency of CPU  
 VDD=3V, temp=25°C CPU 24MHz Wait mode (TYP.)  
 Stop the clock supply to peripherals.

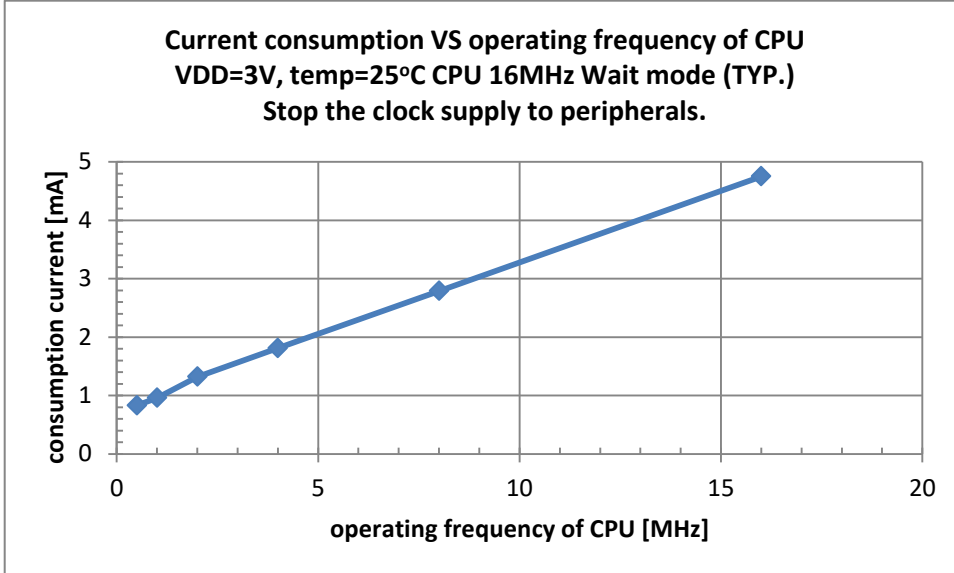


VDD=3V, temp=25°C CPU 24MHz no Wait mode (TYP.)

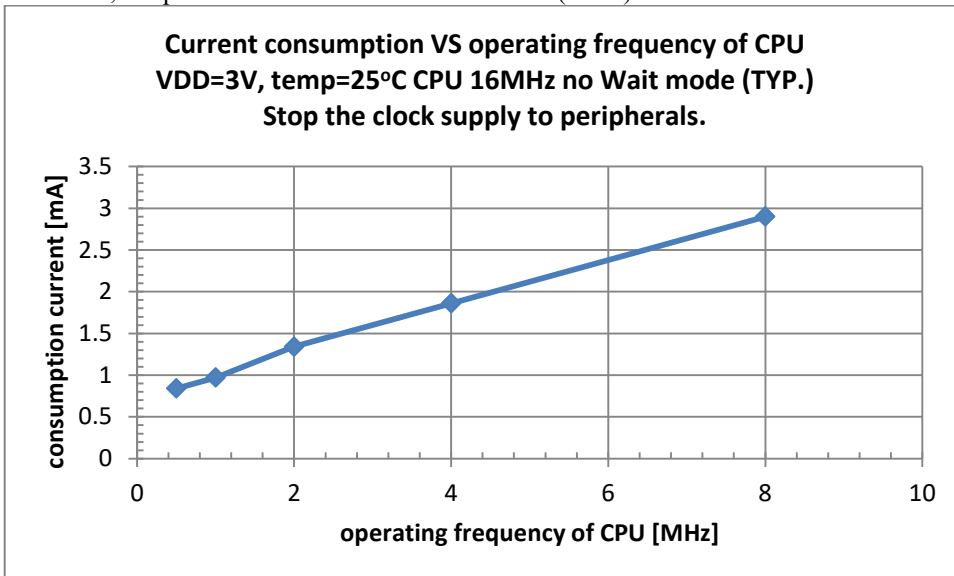


Product: ML62Q1555, ML62Q1556, ML62Q1557, ML62Q1563, ML62Q1564, ML62Q1565, ML62Q1566, ML62Q1567, ML62Q1573, ML62Q1574, ML62Q1575, ML62Q1576, ML62Q1577

Current consumption VS operating frequency of CPU  
VDD=3V, temp=25°C CPU 16MHz Wait mode (TYP.)  
Stop the clock supply to peripherals.



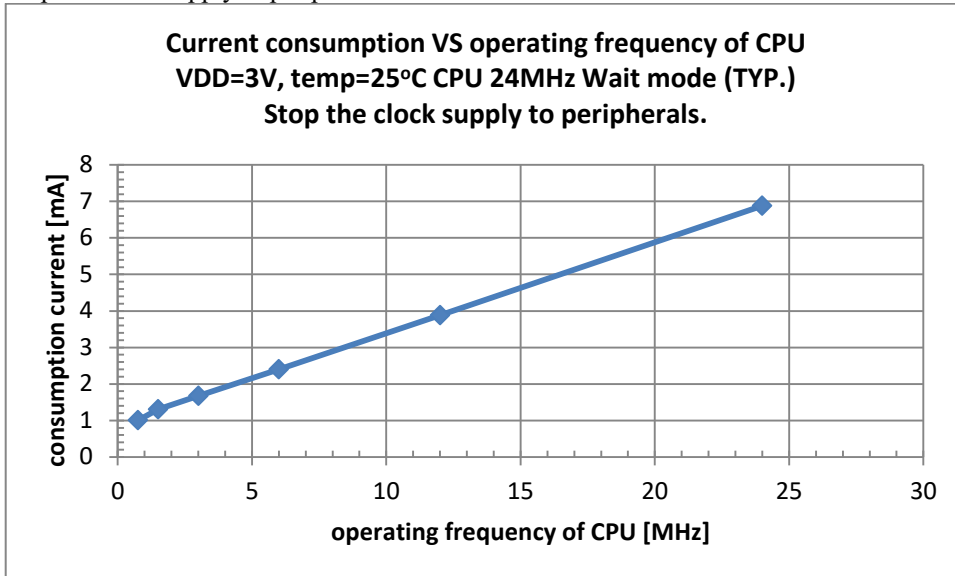
VDD=3V, temp=25°C CPU 16MHz no Wait mode (TYP.)



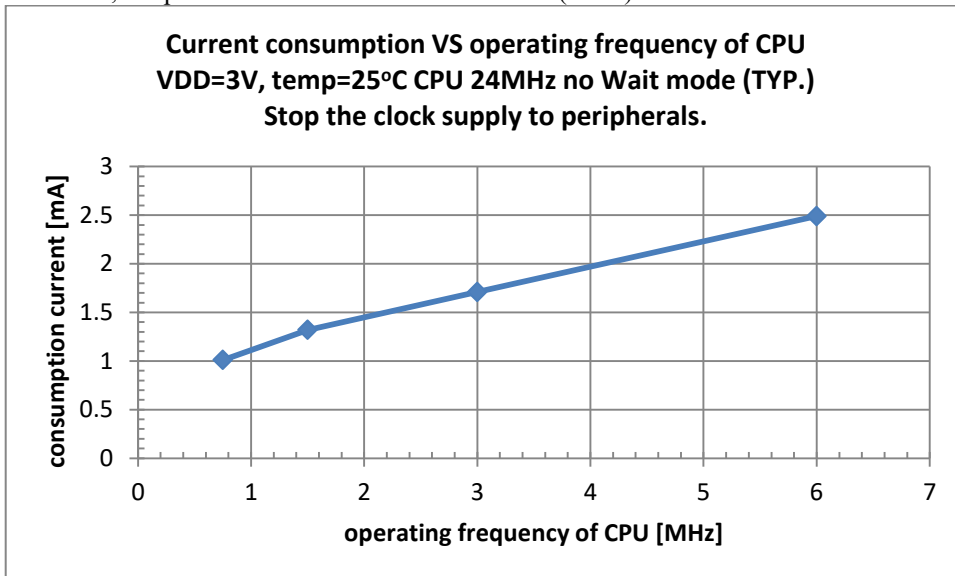


Product: ML62Q1555, ML62Q1556, ML62Q1557, ML62Q1563, ML62Q1564, ML62Q1565, ML62Q1566, ML62Q1567, ML62Q1573, ML62Q1574, ML62Q1575, ML62Q1576, ML62Q1577

Current consumption VS operating frequency of CPU  
VDD=3V, temp=25°C CPU 24MHz Wait mode (TYP.)  
Stop the clock supply to peripherals.

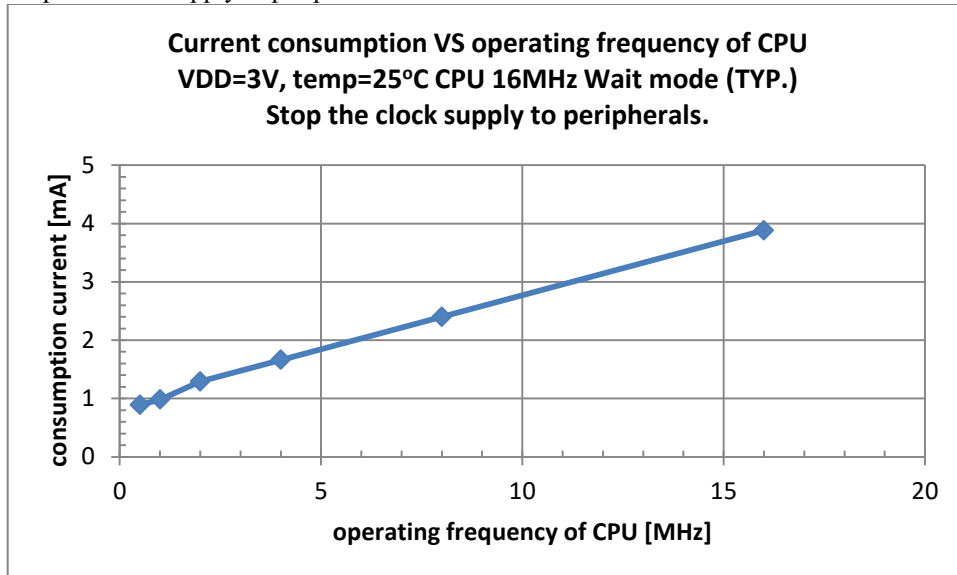


VDD=3V, temp=25°C CPU 24MHz no Wait mode (TYP.)

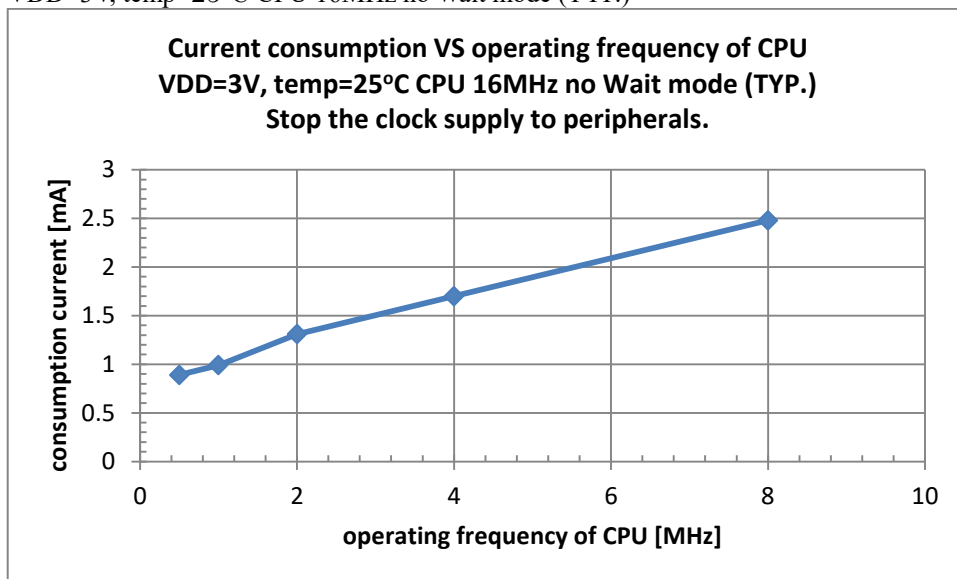


Product: ML62Q1858, ML62Q1859, ML62Q1868, ML62Q1869, ML62Q1878, ML62Q1879

Current consumption VS operating frequency of CPU  
 VDD=3V, temp=25°C CPU 16MHz Wait mode (TYP.)  
 Stop the clock supply to peripherals.

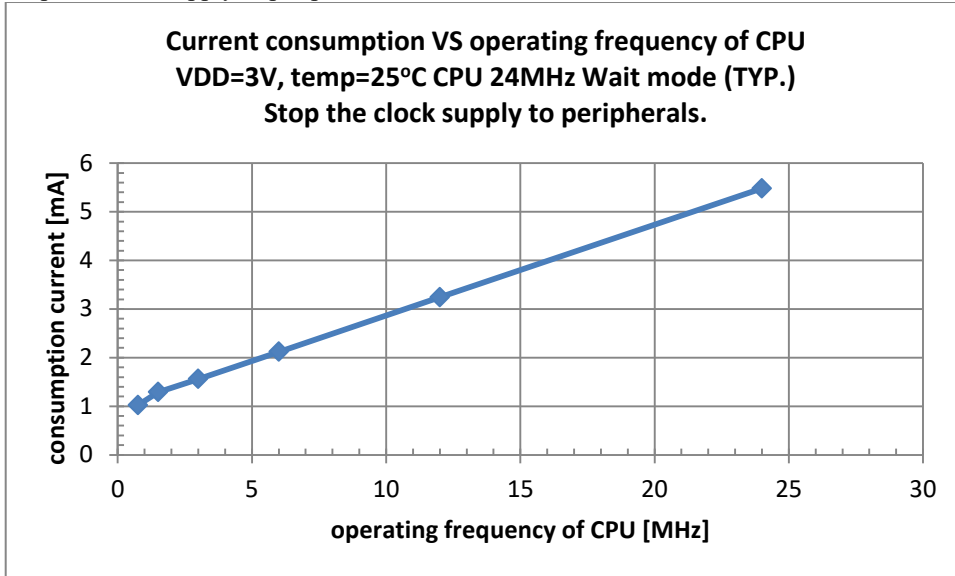


VDD=3V, temp=25°C CPU 16MHz no Wait mode (TYP.)

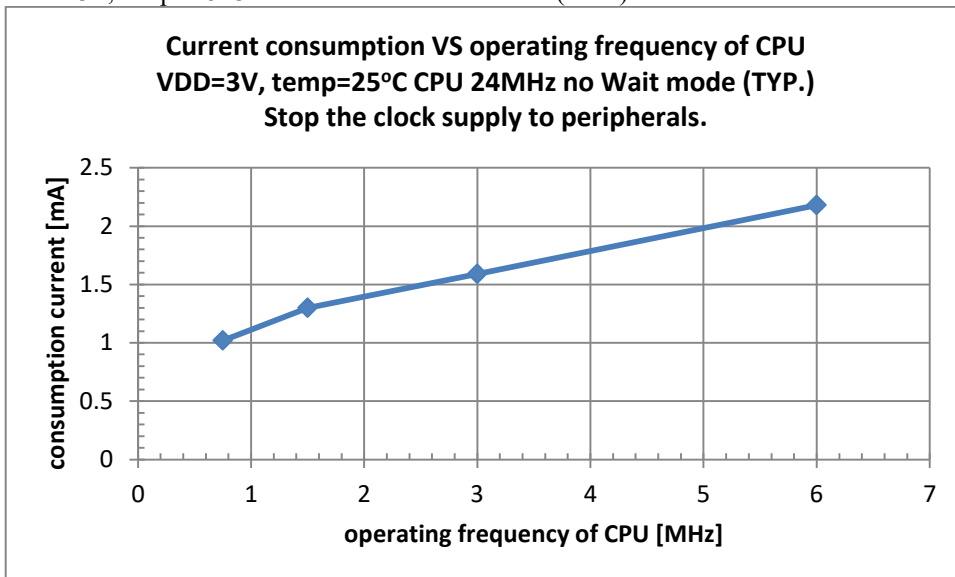


Product: ML62Q1858, ML62Q1859, ML62Q1868, ML62Q1869, ML62Q1878, ML62Q1879

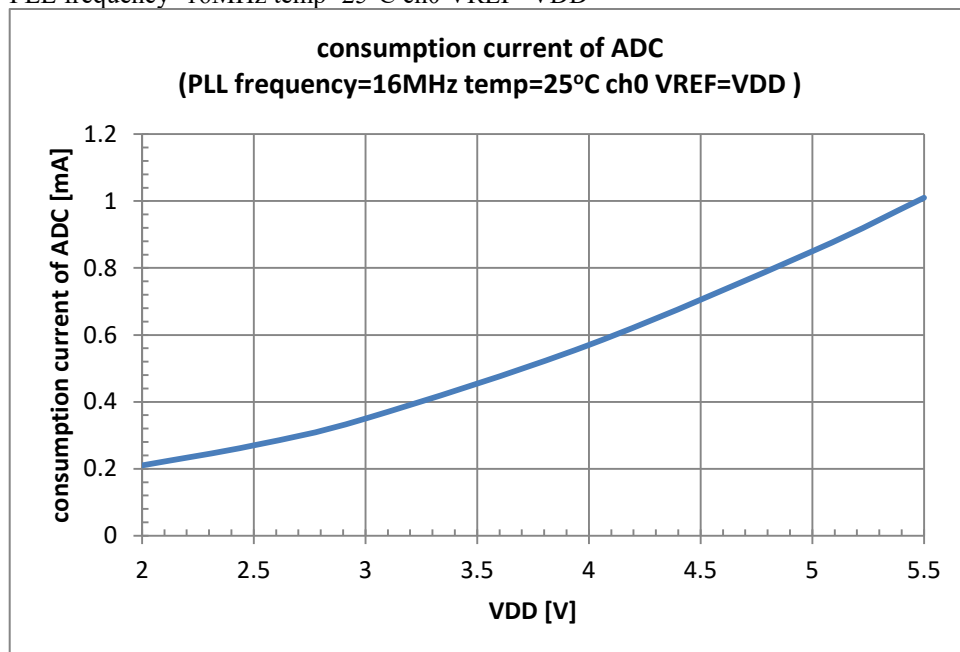
Current consumption VS operating frequency of CPU  
VDD=3V, temp=25°C CPU 24MHz Wait mode (TYP.)  
Stop the clock supply to peripherals.



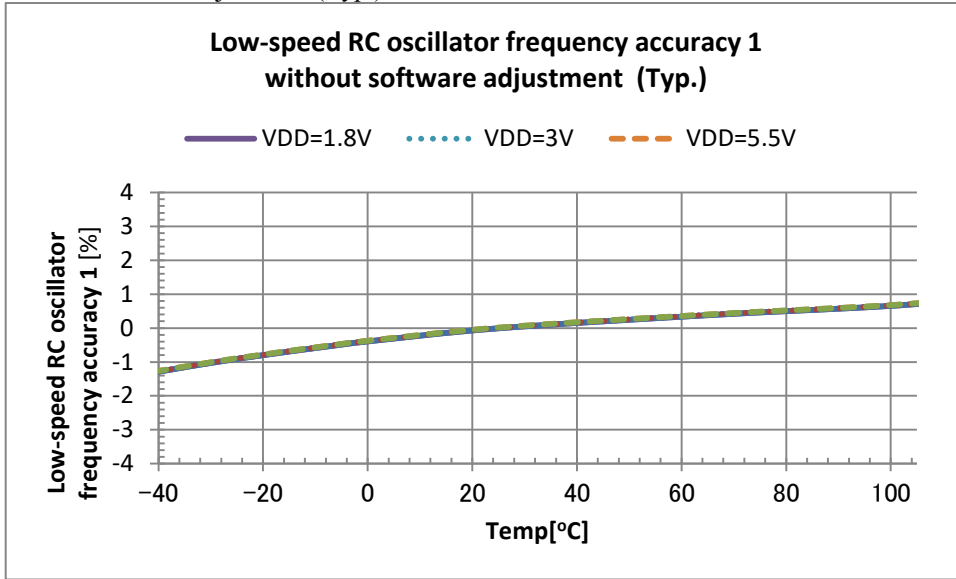
VDD=3V, temp=25°C CPU 24MHz no Wait mode (TYP.)



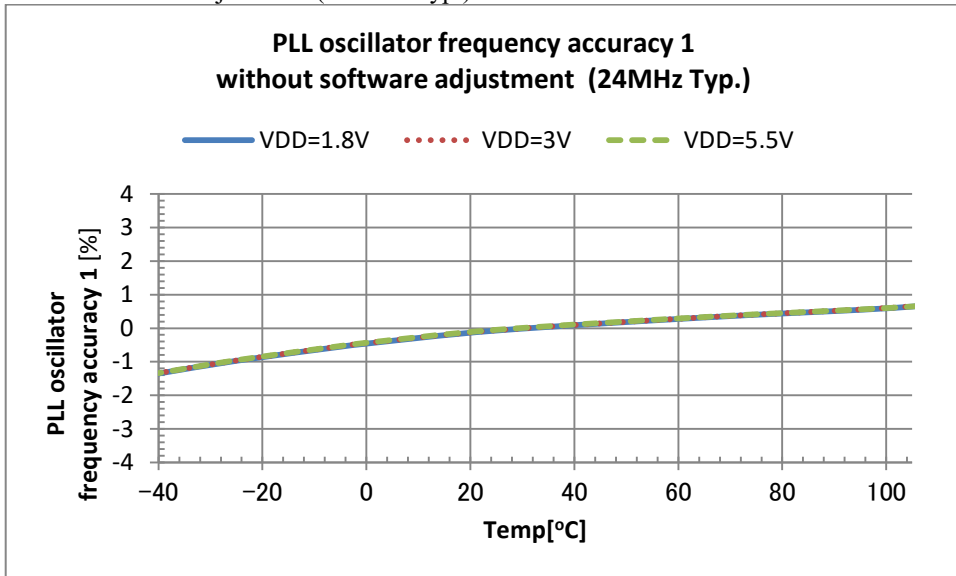
Consumption current of ADC VS operating voltage  
PLL frequency=16MHz temp=25°C ch0 VREF=VDD



TEMP VS Low-speed RC oscillator frequency accuracy 1 without software adjustment (Typ.)

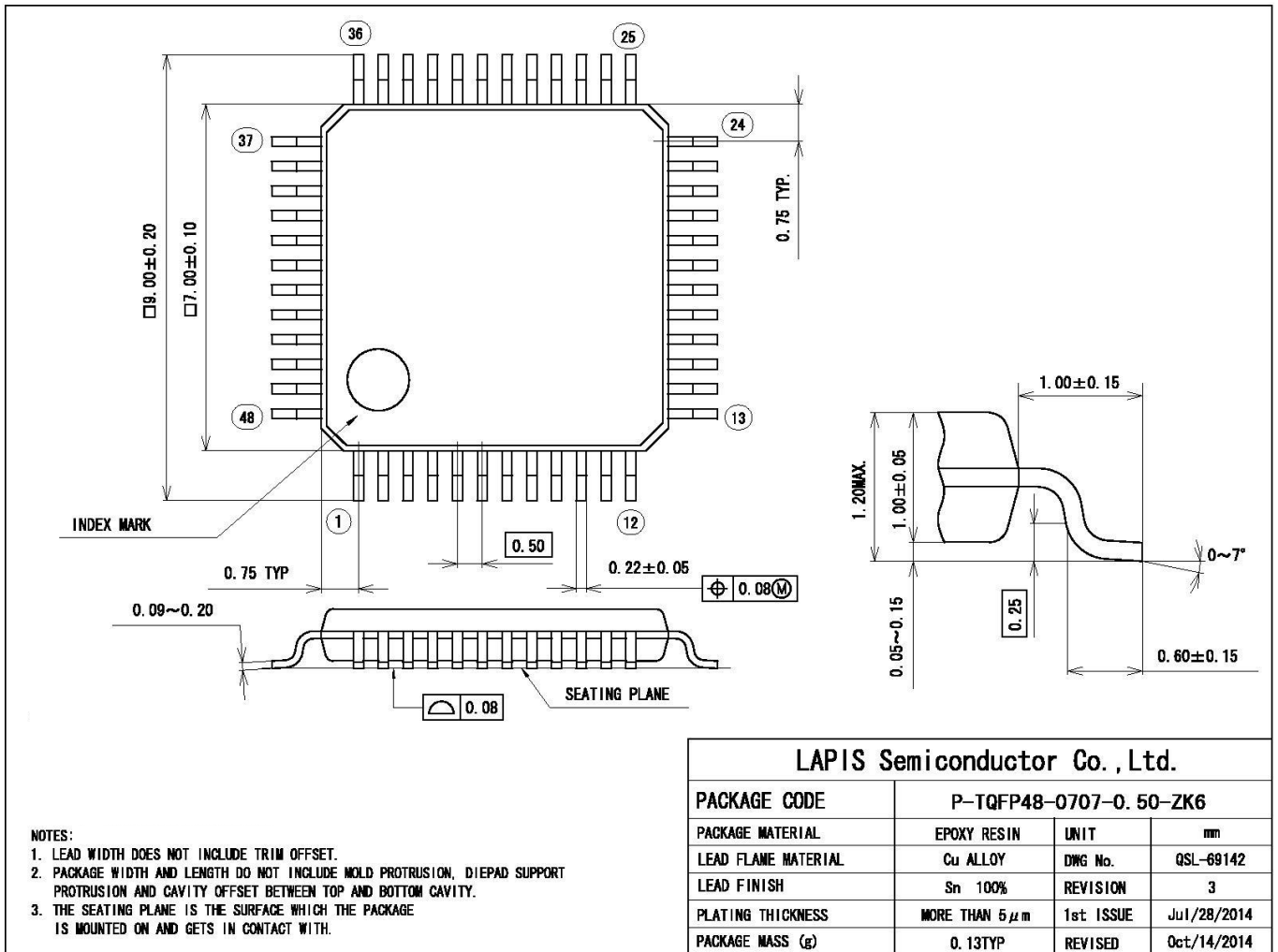


TEMP VS PLL oscillator frequency accuracy 1 without software adjustment (24MHz Typ.)



PACKAGE DIMENSIONS

48pin TQFP Package

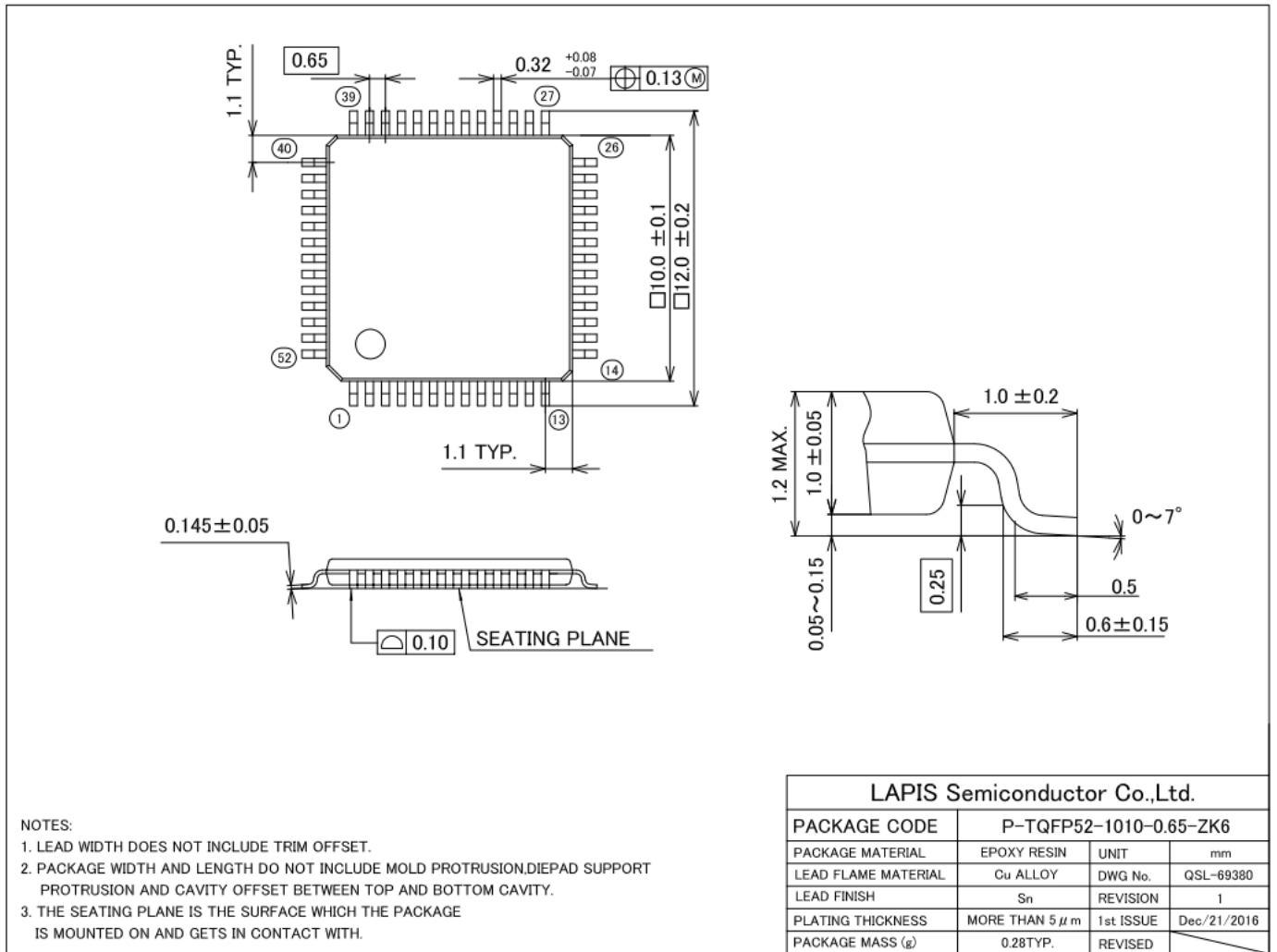


(Unit: mm)

Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact a ROHM sales office for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

52pin TQFP Package

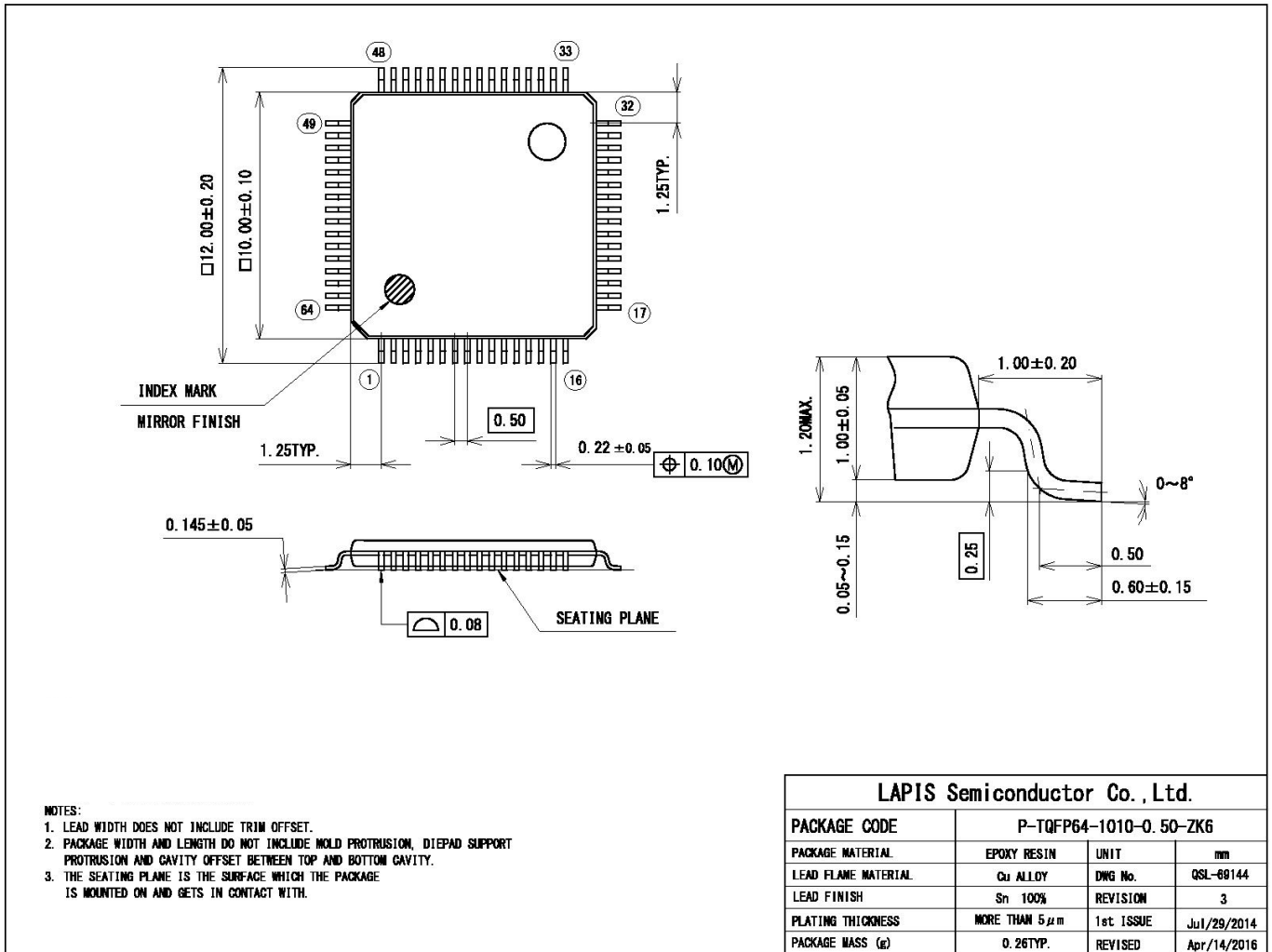


(Unit: mm)

Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact a ROHM sales office for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

64pin TQFP Package



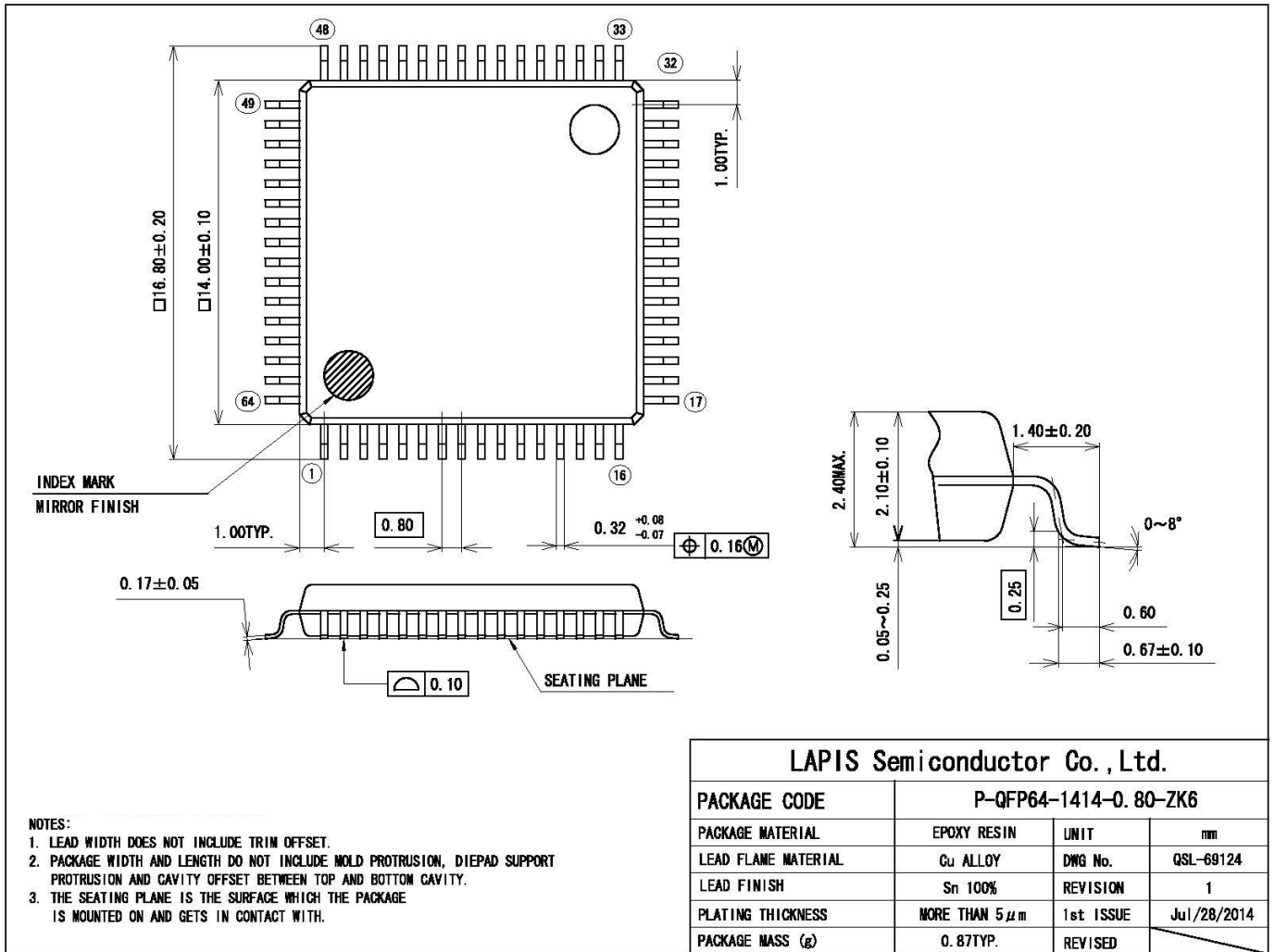
(Unit: mm)

Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact a ROHM sales office for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).



64pin QFP Package

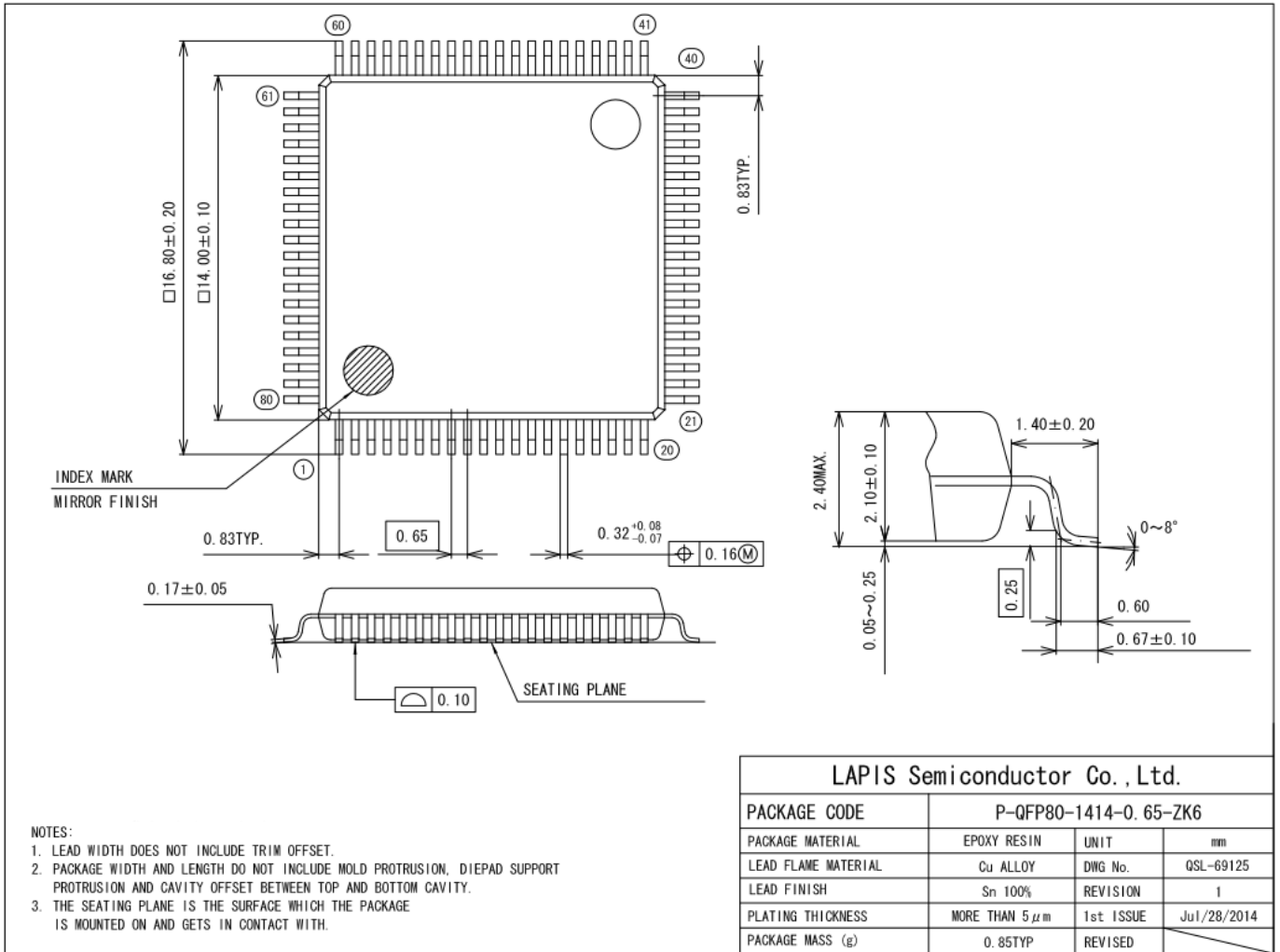


(Unit: mm)

Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact a ROHM sales office for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

80pin QFP Package

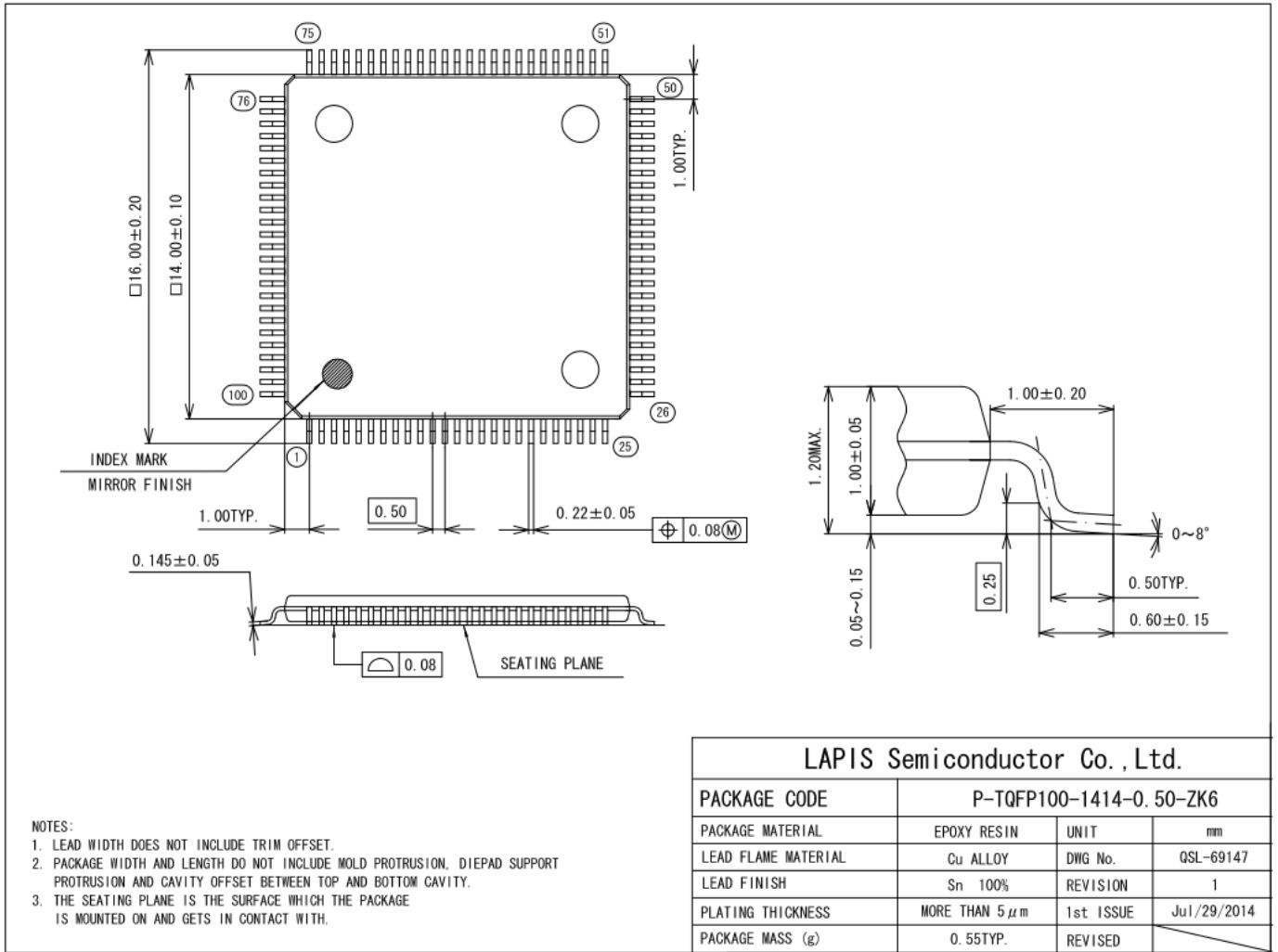


(Unit: mm)

Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact a ROHM sales office for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

100pin TQFP Package

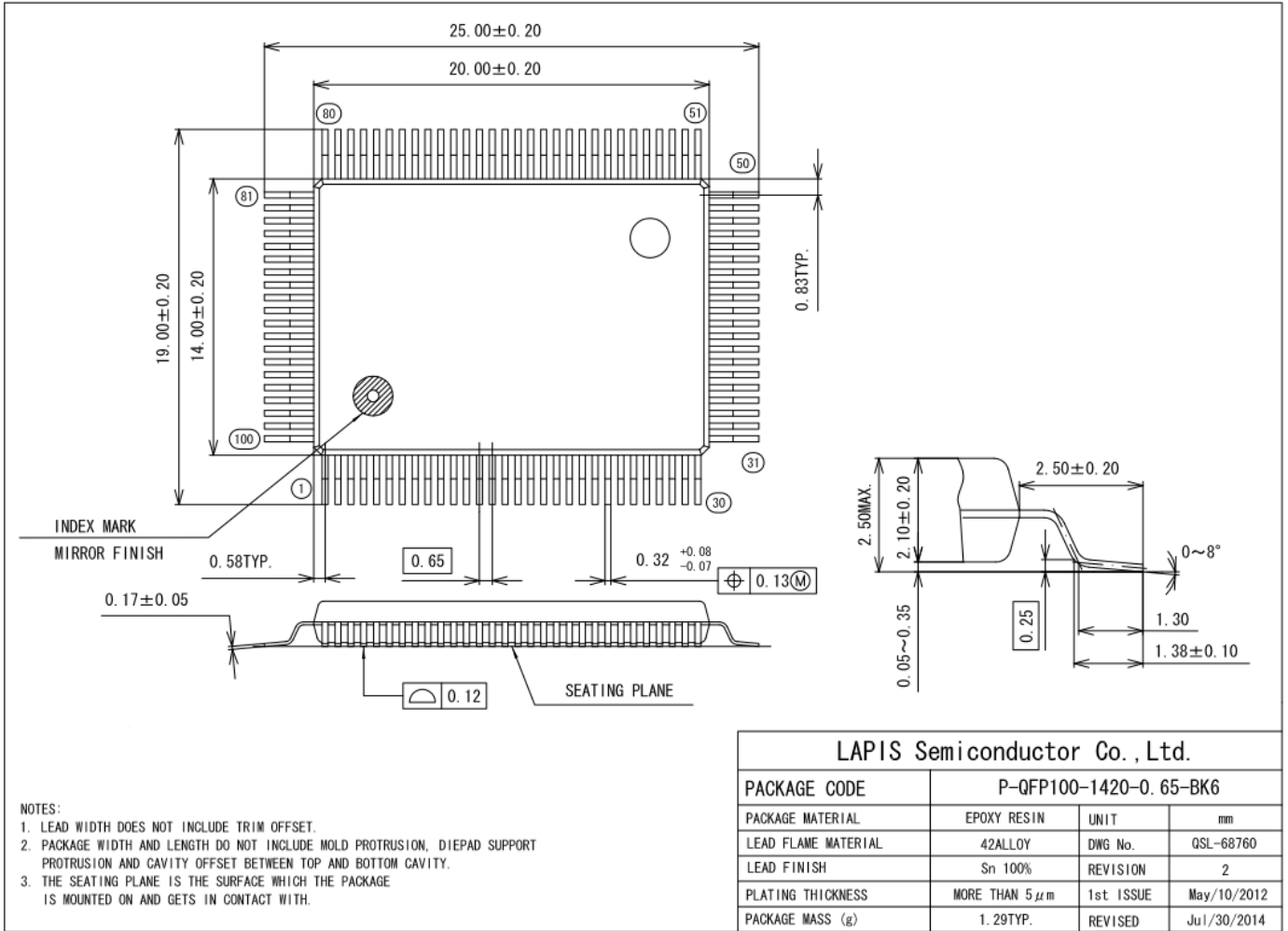


(Unit: mm)

Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact a ROHM sales office for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

## 100pin QFP Package



(Unit: mm)

### Notes for Mounting the Surface Mount Type Package

The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage. Therefore, before you perform reflow mounting, contact a ROHM sales office for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

## REVISION HISTORY

Document No.	Date	Page		Description
		Previous Edition	Current Edition	
FEDL62Q1500-01	Dec 17, 2018	-	-	1 <sup>st</sup> Revision.
FEDL62Q1500-02	Jan 9, 2019	1	1	Changed the products under developing (Table 1 ML62Q1500 Group Product List)
		26	26	Deleted "(TBD)" of Current Consumption 1
FEDL62Q1500-03	May 15, 2019	1	1	Changed the products under developing (Table 1 ML62Q1500 Group Product List)
		28	28	Updated Current Consumption 3
		32	32	Added comment "*6" to the IOHL.
		52	52	Updated 16MHz Characteristics graphs
		53,55	53,55	Updated 24MHz Characteristics graphs
		-	56,57	Added 16MHz and 24MHz Characteristics graphs
FEDL62Q1500-04	May 31, 2019	3,4	3,4	Updated the descriptions of DMA and Functional Timer.
		25	25	Changed I <sub>OUTH</sub> (total) and I <sub>OUTL</sub> (total) of Absolute Maximum Ratings to 180mA from 150mA.
		32	32	Corrected comment of the IOHLs.
FEDL62Q1500-05	Mar 19, 2020	24	24	Changed termination of unused pins
		25	25	Added parameter "Operating temperature(Chip-Junction)" in Recommended Operating Conditions
		25	—	Removed the section "Operation Confirmed Crystal Unit(32.768kHz)". This section is mentioned in Applications Note; "Operation-confirmed oscillator for ML62Q1000 series".
		—	26	Added thermal characteristics section
		40	41	Added comments and notes to the reset characteristics
		40	42	Revised overall of "Power On Reset" section as "Slope of Power supply and Power On Reset" section. The major revisions are Added definitions of Power on rising/falling slope, Power on voltage, CPU operation start time, and added Note.
		*	*	Corrected typo

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## LAPIS Semiconductor Co.,Ltd.

2-4-8 Shinyokohama, Kouhoku-ku,  
Yokohama 222-8575, Japan  
<http://www.lapis-semi.com/en/>



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#### Как с нами связаться

**Телефон:** 8 (812) 309 58 32 (многоканальный)

**Факс:** 8 (812) 320-02-42

**Электронная почта:** [org@eplast1.ru](mailto:org@eplast1.ru)

**Адрес:** 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.