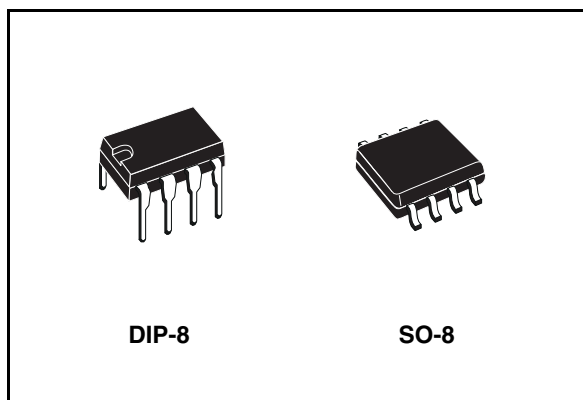


Low power RS-485/RS-422 transceiver

Features

- Low quiescent current: 300 μ A
- Designed for RS-485 interface application
- - 7 V to 12 V common mode input voltage range
- Driver maintains high impedance in 3-state or with the power OFF
- 70 mV typical input hysteresis
- 30 ns propagation delay, 5 ns skew
- Operate from a single 5 V supply
- Current limiting and thermal shutdown for driver overload protection
- Allows up to 64 transceivers on the bus



The ST485 is available in three temperature range: commercial (0 °C to 70 °C), industrial (- 40 °C to 85 °C) and automotive (- 55 °C to 125 °C).

Description

The ST485 is a low power transceiver for RS-485 and RS-422 communication. Each part contains one driver and one receiver.

This transceiver draws 300 μ A (typ.) of supply current when unloaded or fully loaded with disabled drivers.

It operates from a single 5 V supply.

Driver is short-circuit current limited and is protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high-impedance state.

The ST485 is designed for bi-directional data communications on multipoint bus transmission line (half-duplex applications).

Table 1. Device summary

Order code	Temperature range	Package	Packaging
ST485CN	0 to 70 °C	DIP-8	50 parts per tube / 40 tube per box
ST485BN	- 40 to 85 °C	DIP-8	50 parts per tube / 40 tube per box
ST485CDR	0 to 70 °C	SO-8 (tape and reel)	2500 parts per reel
ST485BDR	- 40 to 85 °C	SO-8 (tape and reel)	2500 parts per reel

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1 Pin configuration

Figure 1. Pin connections

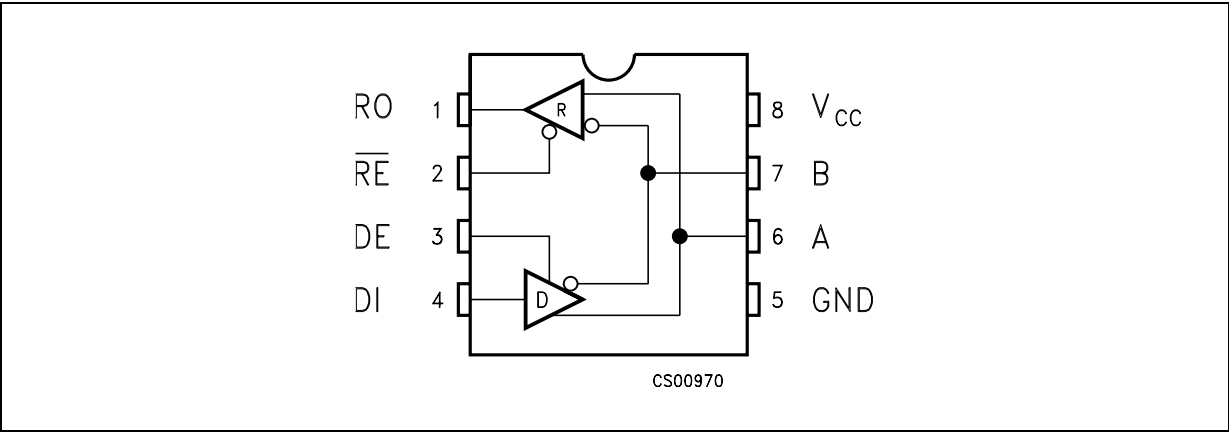


Table 2. Pin description

Pin n°	Symbol	Name and function
1	RO	Receiver output
2	RE	Receiver output enable
3	DE	Driver output enable
4	DI	Driver input
5	GND	Ground
6	A	Non-inverting receiver input and non-inverting driver output
7	B	Inverting receiver input and inverting driver output
8	V _{CC}	Supply voltage

2 Truth tables

Table 3. Truth table (driver)

Inputs			Outputs	
RE	DE	DI	B	A
X	H	H	L	H
X	H	L	H	L
X	L	X	Z	Z

Note: X = Don't care; Z = High impedance

Table 4. Truth table (receiver)

Inputs			Outputs
RE	DE	A-B	RO
L	L	$\geq +0.2V$	H
L	L	$\leq -0.2V$	L
L	L	Inputs open	H
H	L	X	Z

Note: X = Don't care; Z = High impedance

3 Maximum ratings

Table 5. Absolute maximum ratings

Symbol	Parameter	Value	Unit
V_{CC}	Supply voltage	7	V
V_I	Control input voltage ($\overline{RE}$, DE)	-0.5 to ($V_{CC} + 0.5$)	V
V_{DI}	Driver input voltage (DI)	-0.5 to ($V_{CC} + 0.5$)	V
V_{DO}	Driver output voltage (A, B)	± 14	V
V_{RI}	Receiver input voltage (A, B)	± 14	V
V_{RO}	Receiver output voltage (RO)	-0.5 to ($V_{CC} + 0.5$)	V

Note: Absolute maximum ratings are those values beyond which damage to the device may occur. Functional operation under these condition is not implied.

4 Electrical characteristics

$V_{CC} = 5\text{ V} \pm 5\%$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise specified. Typical values are referred to $T_A = 25\text{ }^{\circ}\text{C}$

Table 6. DC electrical characteristics

Symbol	Parameter	Test conditions ⁽¹⁾	Value					Unit
			-40 to 85 °C			-55 to 125 °C		
			Min.	Typ.	Max.	Min.	Max.	
V _{OD1}	Differential driver output (no load)				5		5	V
V _{OD2}	Differential driver output (with load)	R _L = 27Ω (RS-485) <i>Figure 2</i> R _L = 50Ω (RS-422) <i>Figure 2</i>	1.5		5 5	1.4	5 5	V V
ΔV _{OD}	Change in magnitude of driver differential output voltage for complementary output states	R _L = 27Ω or 50Ω <i>Figure 2</i>			0.2		0.2	V
V _{OC}	Driver common-mode output voltage	R _L = 27Ω or 50Ω <i>Figure 2</i>			3		3	V
ΔV _{OC}	Change in magnitude of driver common-mode output voltage for complementary output states	R _L = 27Ω or 50Ω <i>Figure 2</i>			0.2		0.2	V
V _{IH}	Input high voltage	$\overline{RE}$, DE, DI	2.0			2.0		V
V _{IL}	Input low voltage	$\overline{RE}$, DE, DI			0.8		0.8	V
I _{IN1}	Input current	$\overline{RE}$, DE, DI			± 2		± 2	μA
I _{IN2}	Input current (A, B)	V _{CM} = 0V or 5.25V, V _{DE} = 0V V _{IN} = 12V V _{IN} = -7V			1 -0.8		1 -0.8	mA mA
V _{TH}	Receiver differential threshold voltage	V _{CM} = -7 to 12V	-0.2		0.2	-0.2	0.2	V
ΔV _{TH}	Receiver input hysteresis	V _{CM} = 0V		70				mV
V _{OH}	Receiver output high voltage	I _O = -4mA, V _{ID} = 200mV	3.5			3.4		V
V _{OL}	Receiver output low voltage	I _O = 4mA, V _{ID} = -200mV			0.4		0.55	V
I _{OZR}	3-state (high impedance) output current at receiver	V _O = 0.4 to 2.4V			± 1		± 1	μA
R _{IN}	Receiver input resistance	V _{CM} = -7 to 12V	24			24		kΩ
I _{CC}	No load supply current ⁽²⁾	V _{RE} = 0V or V _{CC} V _{DE} = V _{CC} V _{DE} = 0V		400 300	900 500		900 500	μA μA

Table 6. DC electrical characteristics (continued)

Symbol	Parameter	Test conditions ⁽¹⁾	Value					Unit
			-40 to 85 °C			-55 to 125 °C		
			Min.	Typ.	Max.	Min.	Max.	
I _{OSD1}	Driver short-circuit current, V _O =High	V _O = -7 to 12V ⁽³⁾	35		250	35	250	mA
I _{OSD2}	Driver short-circuit current, V _O =Low	V _O = -7 to 12V ⁽³⁾	35		250	35	250	mA
I _{OSR}	Receiver short-circuit current	V _O = 0V to V _{CC}	7		95	7	95	mA

1. All currents into device pins are positive; all currents out of device pins are negative; all voltages are referenced to device ground unless specified.
2. Supply current specification is valid for loaded transmitters when V_{DE} = 0V
3. Applies to peak current. See typical Operating Characteristics.

V_{CC} = 5 V ± 5 %, T_A = T_{MIN} to T_{MAX}, unless otherwise specified. Typical values are referred to T_A = 25 °C

Table 7. Driver switching characteristics

Symbol	Parameter	Test conditions ⁽¹⁾	Value					Unit
			-40 to 85 °C			-55 to 125°C		
			Min.	Typ.	Max.	Min.	Max.	
t _{PLH} t _{PHL}	Propagation delay input to output	R _{DIFF} = 54Ω, C _{L1} = C _{L2} = 100pF (See Figure 4 and Figure 6)	10	30	60		70	ns
t _{SK}	Output skew to output	R _{DIFF} = 54Ω, C _{L1} = C _{L2} = 100pF (See Figure 4 and Figure 6)		5	10		10	ns
t _{TLH} t _{THL}	Rise or fall time	R _{DIFF} = 54Ω, C _{L1} = C _{L2} = 100pF (See Figure 4 and Figure 6)	3	15	40	3	45	ns
t _{PZH}	Output enable time	C _L = 100pF, S2 = Closed (See Figure 5 and Figure 7)		70	90		90	ns
t _{PZL}	Output enable time	C _L = 100pF, S1 = Closed (See Figure 5 and Figure 7)		70	90		90	ns
t _{PLZ}	Output disable time	C _L = 15pF, S1 = Closed (See Figure 5 and Figure 7)		70	90		90	ns
t _{PHZ}	Output disable time	C _L = 15pF, S2 = Closed (See Figure 5 and Figure 7)		70	90		90	ns

1. All currents into device pins are positive; all currents out of device pins are negative; all voltages are referenced to device ground unless specified.

$V_{CC} = 5\text{ V} \pm 5\%$, $T_A = T_{MIN}$ to T_{MAX} , unless otherwise specified. Typical values are referred to $T_A = 25\text{ }^{\circ}\text{C}$

Table 8. Receiver switching characteristics

Symbol	Parameter	Test conditions ⁽¹⁾	Value					Unit
			-40 to 85 °C			-55 to 125°C		
			Min.	Typ.	Max.	Min.	Max.	
t _{PLH} t _{PHL}	Propagation delay input to output	R _{DIFF} =54Ω, C _{L1} = C _{L2} = 100pF (See Figure 4 and Figure 8)	20	130	210		230	ns
t _{SKD}	Differential receiver skew	R _{DIFF} =54Ω, C _{L1} = C _{L2} = 100pF (See Figure 4 and Figure 8)		13				ns
t _{PZH}	Output enable time	C _{RL} = 15pF, S1 = Closed (See Fig. 2 and Figure 9)		20	50		56	ns
t _{PZL}	Output enable time	C _{RL} = 15pF, S2 = Closed (See Fig. 2 and Figure 9)		20	50		56	ns
t _{PLZ}	Output disable time	C _{RL} = 15pF, S1 = Closed (See Fig. 2 and Figure 9)		20	50		56	ns
t _{PHZ}	Output disable time	C _{RL} = 15pF, S2 = Closed (See Fig. 2 and Figure 9)		20	50		56	ns
f _{MAX}	Maximum data rate		2.5			2.5		Mbps

1. All currents into device pins are positive; all currents out of device pins are negative; all voltages are referenced to device ground unless specified

5 Test circuit and typical characteristics

Figure 2. Driver DC test load

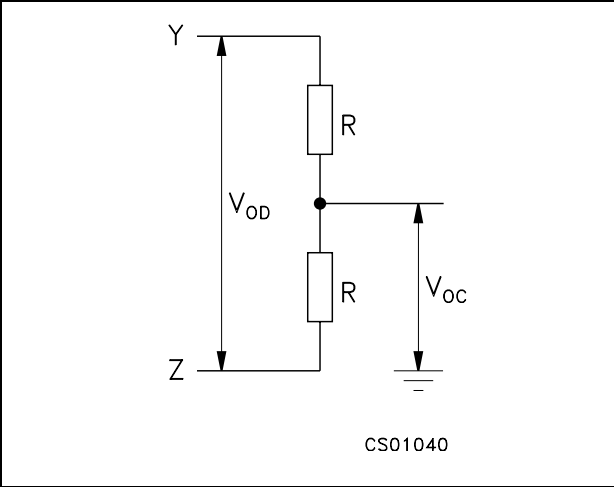


Figure 3. Receiver timing test load

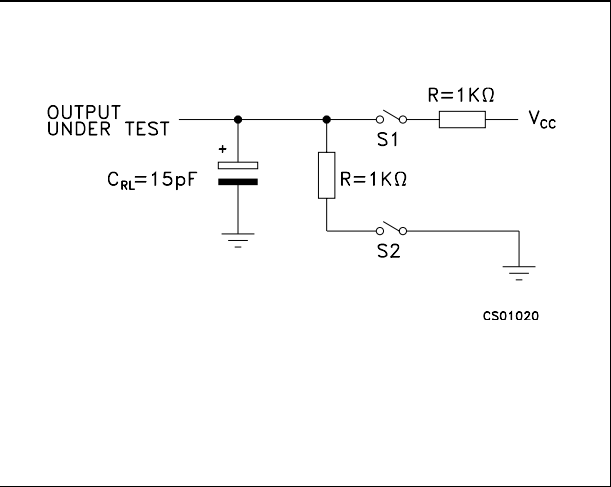


Figure 4. Drive/receiver timing test circuit

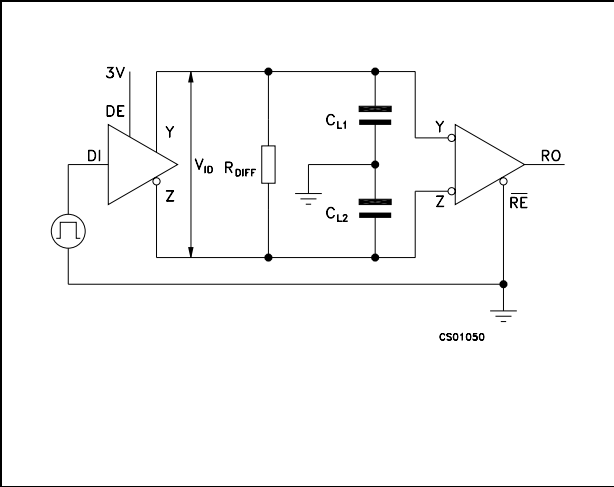


Figure 5. Driver timing test load

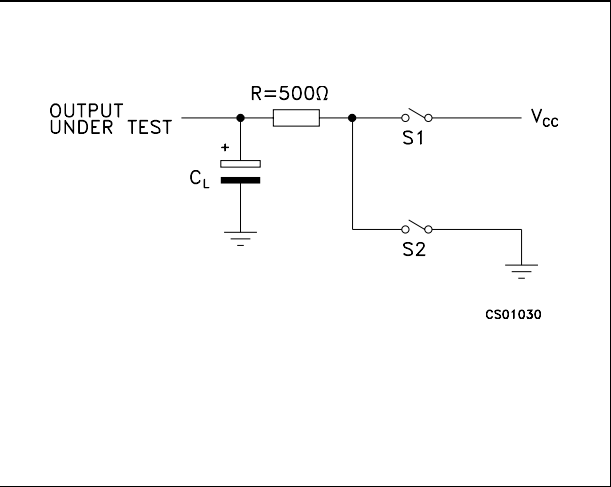


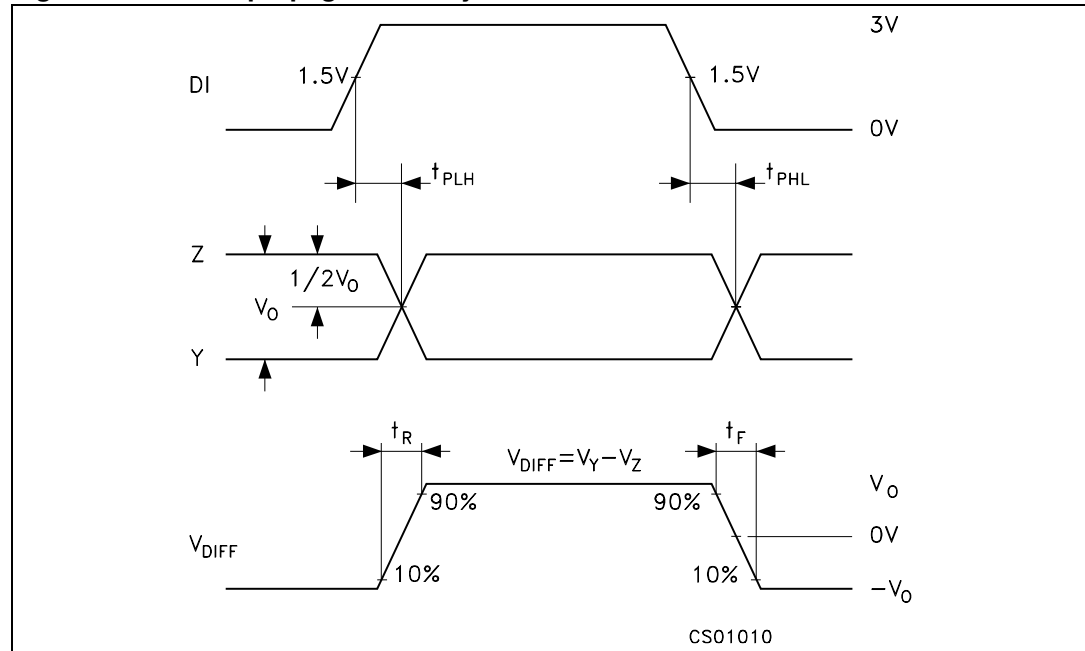
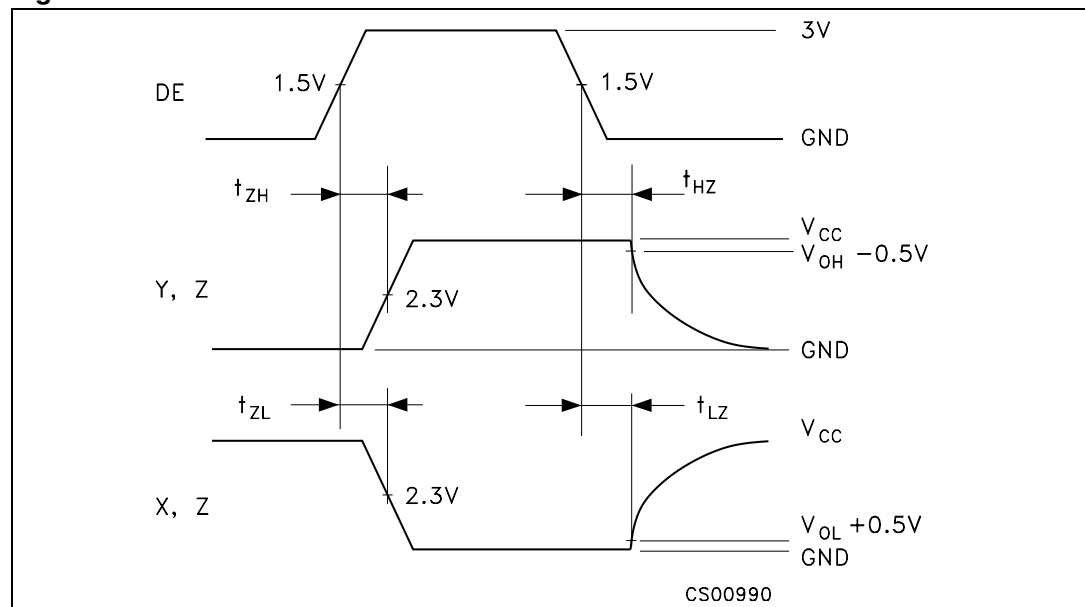
Figure 6. Driver propagation delay**Figure 7. Driver enable and disable time**

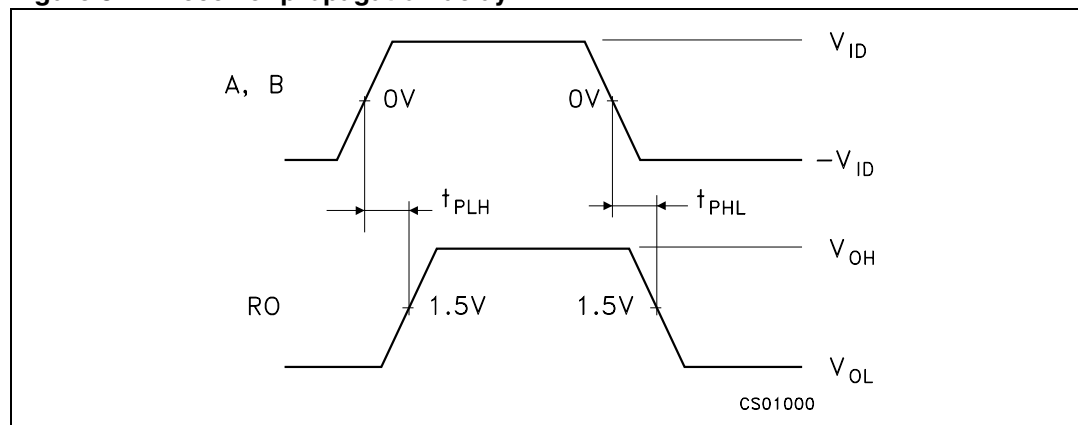
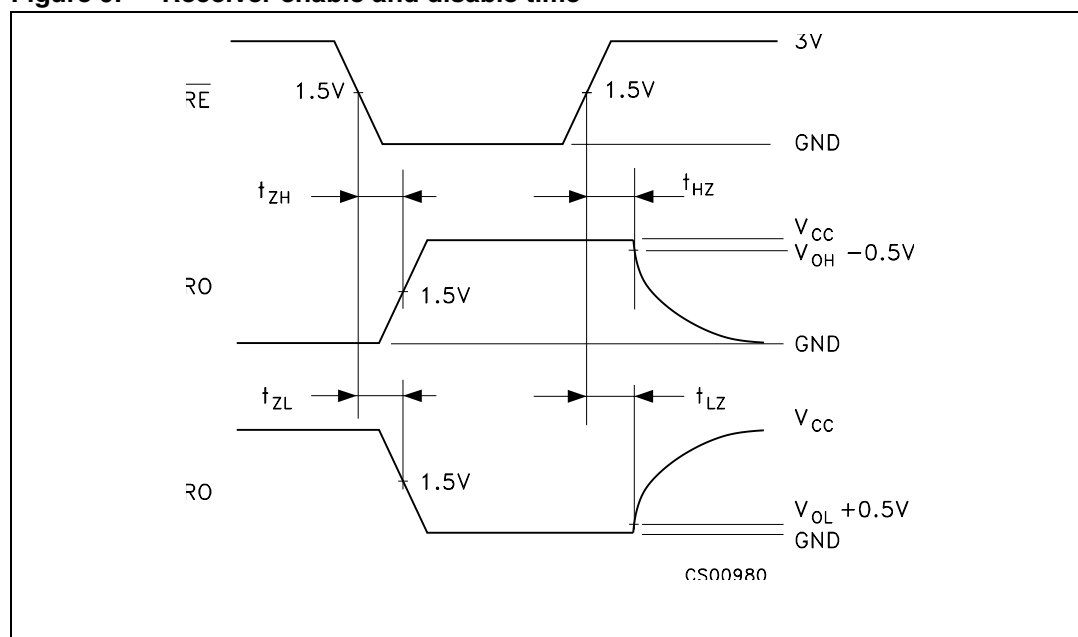
Figure 8. Receiver propagation delay**Figure 9. Receiver enable and disable time**

Figure 10. Receiver output current vs. output low voltage

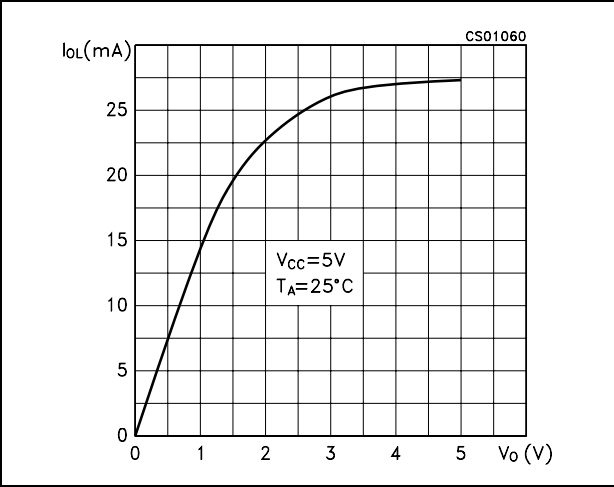


Figure 11. Receiver output current vs. output high voltage

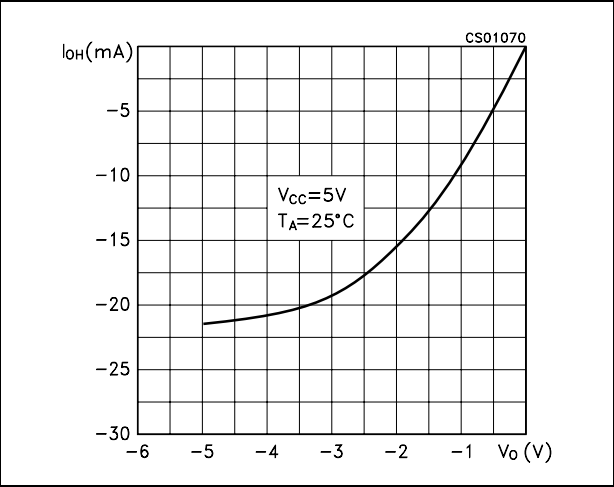


Figure 12. Driver output current vs. output low voltage

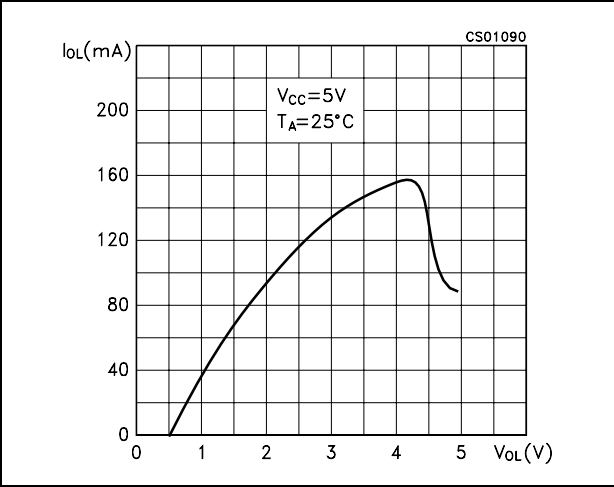


Figure 13. Driver output current vs. output high voltage

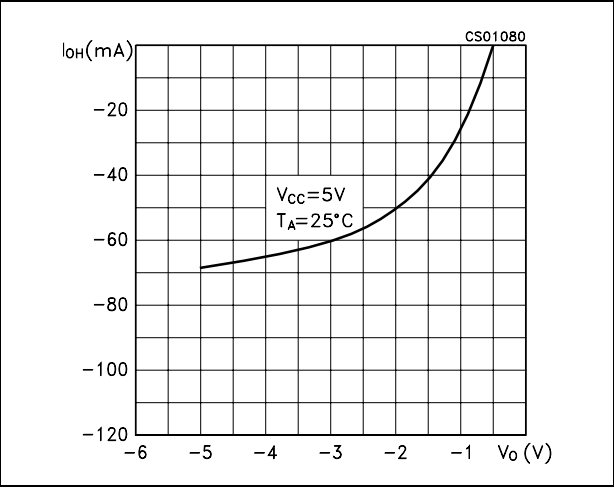


Figure 14. Supply current vs. temperature

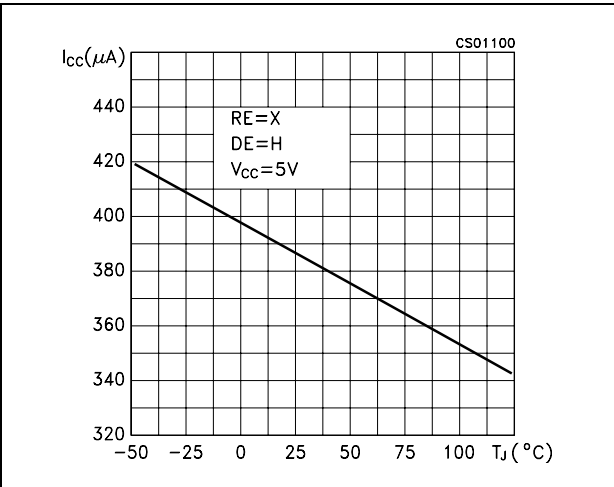


Figure 15. Receiver high level output voltage vs. temperature

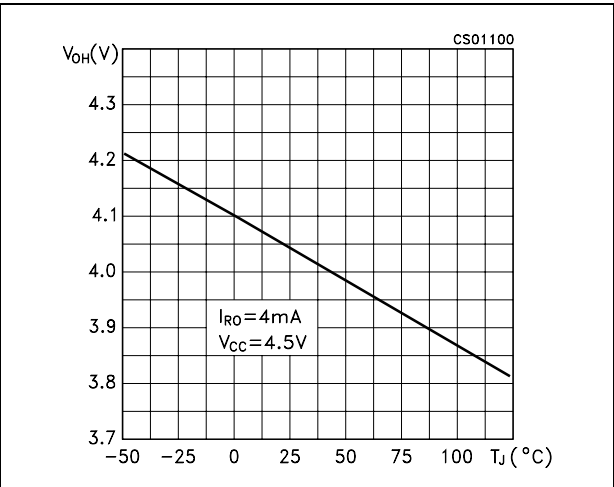


Figure 16. Receiver low level output voltage vs. temperature

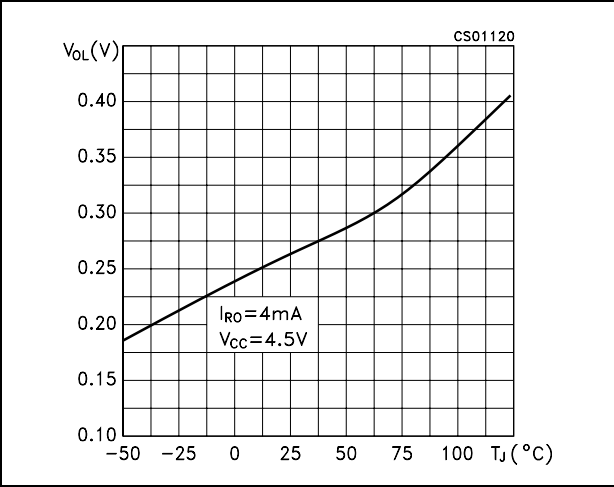
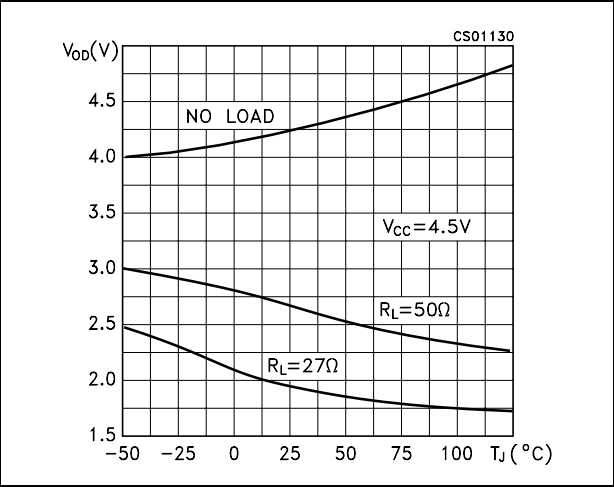


Figure 17. Differential driver output voltage vs. temperature

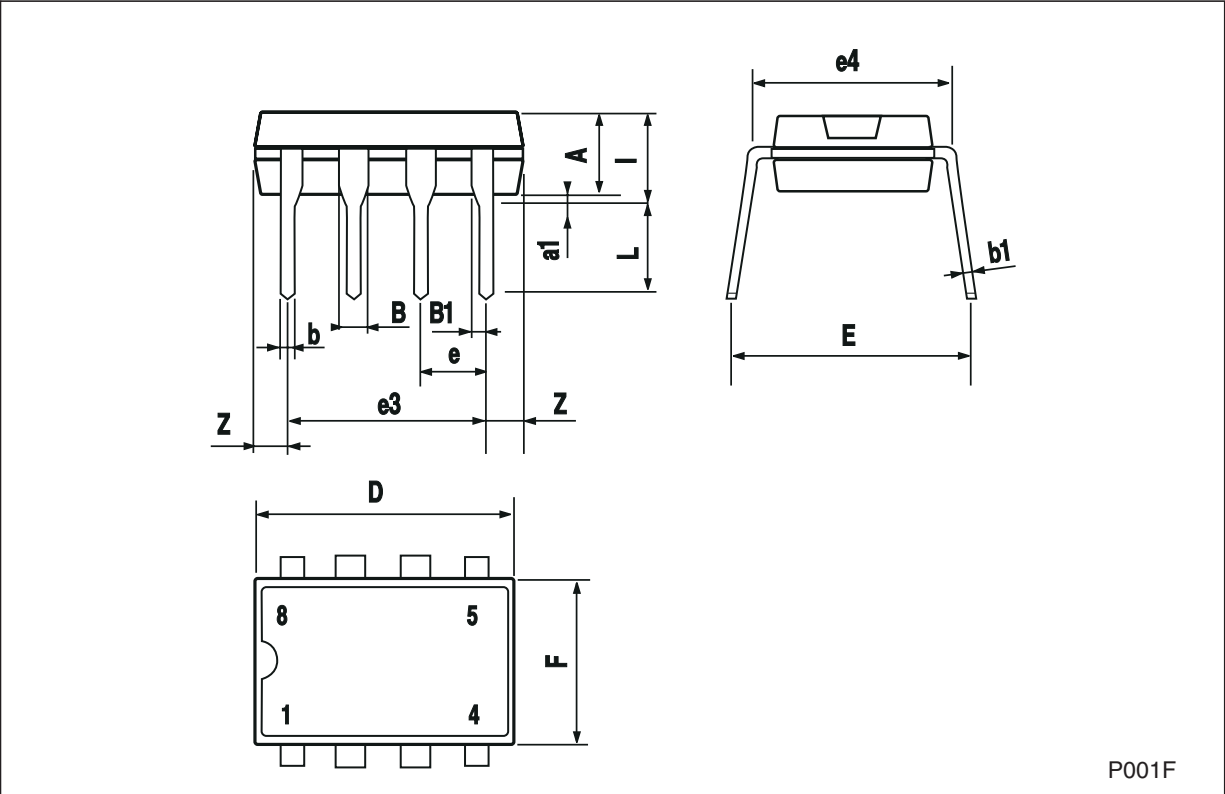


6 Package mechanical data

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Plastic DIP-8 mechanical data

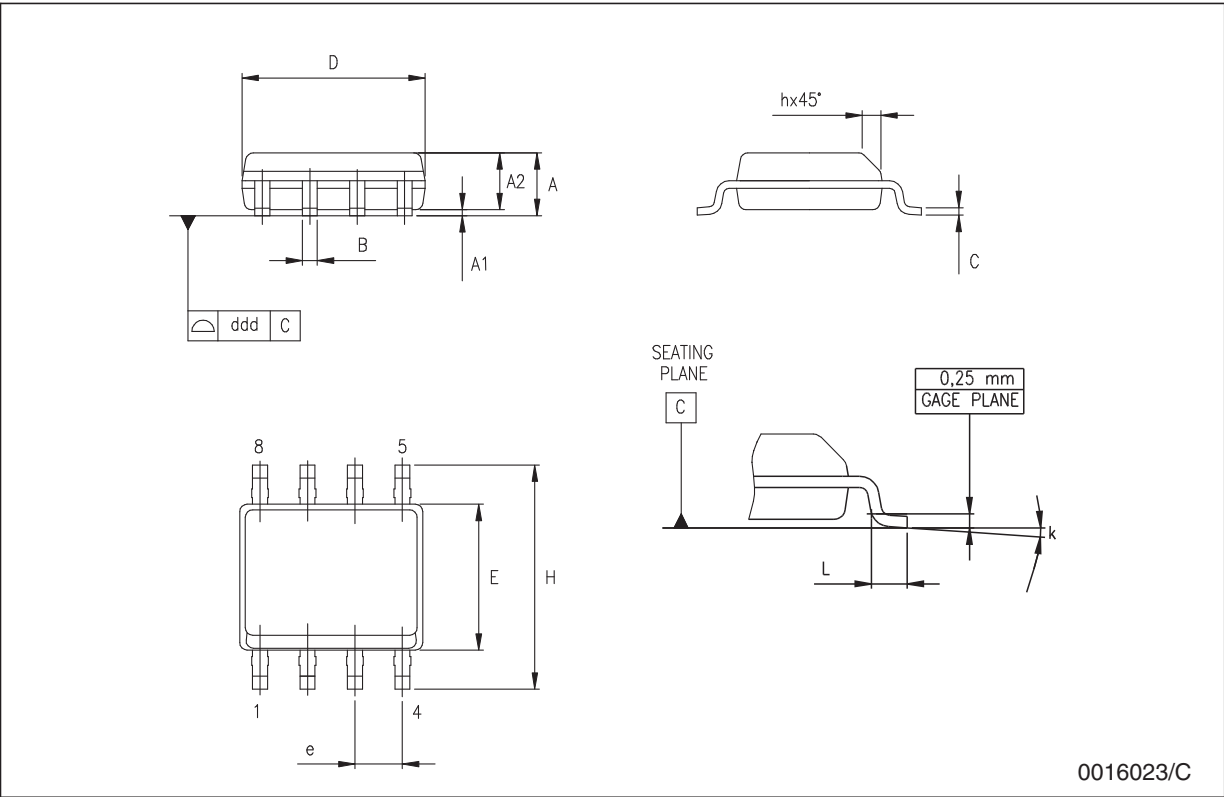
Dim.	mm.			inch.		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A		3.3			0.130	
a1	0.7			0.028		
B	1.39		1.65	0.055		0.065
B1	0.91		1.04	0.036		0.041
b		0.5			0.020	
b1	0.38		0.5	0.015		0.020
D			9.8			0.386
E		8.8			0.346	
e		2.54			0.100	
e3		7.62			0.300	
e4		7.62			0.300	
F			7.1			0.280
I			4.8			0.189
L		3.3			0.130	
Z	0.44		1.6	0.017		0.063



P001F

SO-8 mechanical data

Dim.	mm.			inch.		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A	1.35		1.75	0.053		0.069
A1	0.10		0.25	0.04		0.010
A2	1.10		1.65	0.043		0.065
B	0.33		0.51	0.013		0.020
C	0.19		0.25	0.007		0.010
D	4.80		5.00	0.189		0.197
E	3.80		4.00	0.150		0.157
e		1.27			0.050	
H	5.80		6.20	0.228		0.244
h	0.25		0.50	0.010		0.020
L	0.40		1.27	0.016		0.050
k	8° (max.)					
ddd			0.1			0.04



Tape & reel SO-8 mechanical data

Dim.	mm.			inch.		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A			330			12.992
C	12.8		13.2	0.504		0.519
D	20.2			0.795		
N	60			2.362		
T			22.4			0.882
Ao	8.1		8.5	0.319		0.335
Bo	5.5		5.9	0.216		0.232
Ko	2.1		2.3	0.082		0.090
Po	3.9		4.1	0.153		0.161
P	7.9		8.1	0.311		0.319



7 Revision history

Table 9. Document revision history

Date	Revision	Changes
21-Mar-2006	12	Order codes has been updated and new template.
02-Aug-2006	13	Mistake in cover page first row mA ==> μ A.
08-Nov-2006	14	Added: Table 1 .
07-Feb-2008	15	Modified: Table 1 on page 1 .
16-Feb-2009	16	Modified Note: on page 5 .

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- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



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