Dual Voltage Supervisory Circuits with I²C Serial 2k-bit CMOS EEPROM

FEATURES

- **Precision V_{CC} Power Supply Voltage Monitor**
  - **5 V, 3.3 V and 3 V systems**
  - **Five threshold voltage options**
- **Additional voltage monitoring**
  - **Externally adjustable down to 1.25 V**
- **Watchdog timer (CAT1027 only)**
- **Active High or Low Reset**
  - **Valid reset guaranteed at V_{CC} = 1 V**
- **400 kHz I^2C Bus**
- **2.7 V to 5.5 V Operation**
- **Low power CMOS technology**
- **16-Byte Page Write Buffer**
- **Built-in inadvertent write protection**
- **1,000,000 Program/Erase cycles**
- **Manual Reset capability**
- **100 year data retention**
- **Industrial and extended temperature ranges**
- **8-pin DIP, SOIC, TSSOP, MSOP or TDFN (3 x 3 mm foot-print) packages**
  - **TDFN max height is 0.8 mm**

For Ordering Information details, see page 19.

DESCRIPTION

The CAT1026 and CAT1027 are complete memory and supervisory solutions for microcontroller-based systems. A 2k-bit serial EEPROM memory and a system power supervisor with brown-out protection are integrated together in low power CMOS techno–logy. Memory interface is via a 400 kHz I^2C bus.

The CAT1026 and CAT1027 provide a precision V_{CC} sense circuit with five reset threshold voltage options that support 5 V, 3.3 V and 3 V systems. The power supply monitor and reset circuit protects memory and systems controllers during power up/down and against brownout conditions. If power supply voltages are out of tolerance reset signals become active preventing the system microcontroller, ASIC, or peripherals from operating.

The CAT1026 features two open drain reset outputs: one (RESET) drives high and the other ($\overline{\text{RESET}}$) drives low whenever V_{CC} falls below the threshold. Reset outputs become inactive typically 200ms after the supply voltage exceeds the reset threshold value. With both active high and low reset signals, interface to microcontrollers and other ICs is simple. CAT1027 has only a $\overline{\text{RESET}}$ output. In addition, the $\overline{\text{RESET}}$ pin can be used as an input for push-button manual reset capability.

The CAT1026 and CAT1027 provide an auxiliary voltage sensor input, V_{SENSE}, which is used to monitor a second system supply. The auxiliary high impedance comparator drives the open drain output, V_{LOW}, whenever the sense voltage is below 1.25 V threshold.

The CAT1027 is designed with a 1.6 second watchdog timer circuit that resets a system to a known state if software or a hardware glitch halts or “hangs” the system. The CAT1027 features a watchdog timer interrupt input, WDI.

The on-chip 2k-bit EEPROM memory features a 16-byte page. In addition, hardware data protection is provided by a V_{CC} sense circuit that prevents writes to memory whenever V_{CC} falls below the reset threshold or until V_{CC} reaches the reset threshold during power up.

Available packages include 8-pin DIP and surface mount, 8-pin SO, 8-pin TSSOP, 8-pin TDFN and 8-pin MSOP packages. The TDFN package thickness is 0.8 mm maximum. TDFN footprint is 3 x 3 mm.

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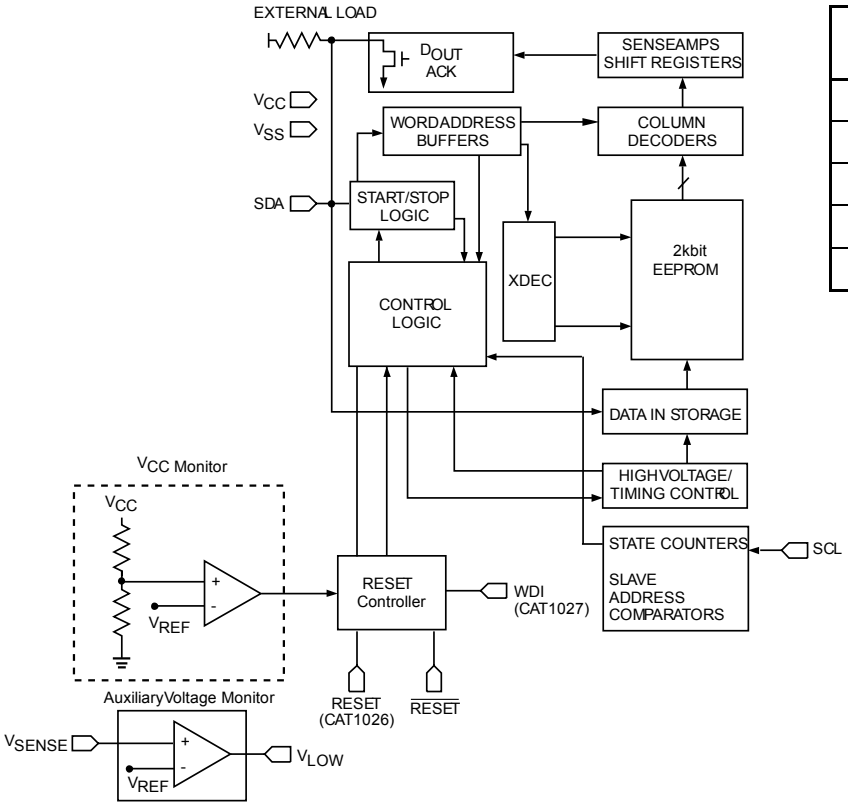
BLOCK DIAGRAM

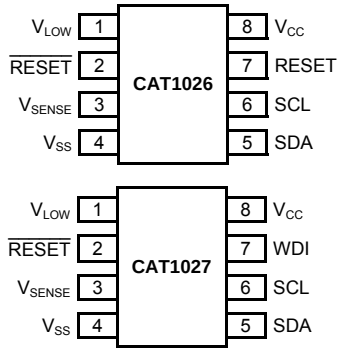


RESET THRESHOLD OPTION

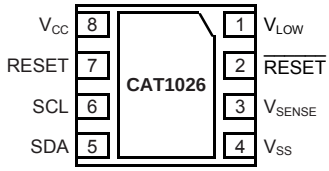
Part Dash Number	Minimum Threshold	Maximum Threshold
-45	4.50	4.75
-42	4.25	4.50
-30	3.00	3.15
-28	2.85	3.00
-25	2.55	2.70

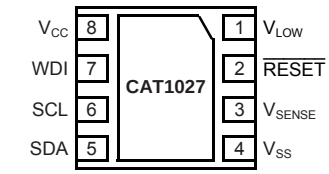
PIN CONFIGURATION

DIP Package (L)
SOIC Package (W)
TSSOP Package (Y)
MSOP Package (Z)



(Bottom View)
TDFN Package: 3mm x 3mm
0.8mm maximum height - (ZD4)





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PIN DESCRIPTION

RESET/$\overline{\text{RESET}}$: RESET OUTPUTs
(RESET CAT1026 Only)
These are open drain pins and $\overline{\text{RESET}}$ can be used as a manual reset trigger input. By forcing a reset condition on the pin the device will initiate and maintain a reset condition. The RESET pin must be connected through a pull-down resistor, and the $\overline{\text{RESET}}$ pin must be connected through a pull-up resistor.

SDA: SERIAL DATA ADDRESS
The bidirectional serial data/address pin is used to transfer all data into and out of the device. The SDA pin is an open drain output and can be wire-ORed with other open drain or open collector outputs.

SCL: SERIAL CLOCK
Serial clock input.

V_{SENSE}: AUXILIARY VOLTAGE MONITOR INPUT
The V_{SENSE} input is a second voltage monitor which is compared against CAT1026 and CAT1027 internal reference voltage of 1.25 V typically. Whenever the input voltage is lower than 1.25 V, the open drain V_{LOW} output will be driven low. An external resistor divider is used to set the voltage level to be sensed. Connect V_{SENSE} to V_{CC} if unused.

V_{LOW}: AUXILIARY VOLTAGE MONITOR OUTPUT
This open drain output goes low when V_{SENSE} is less than 1.25 V and goes high when V_{SENSE} exceeds the reference voltage.

WDI (CAT1027 Only): WATCHDOG TIMER INTERRUPT
Watchdog Timer Interrupt Input is used to reset the watchdog timer. If a transition from high to low or low to high does not occur every 1.6 seconds, the RESET outputs will be driven active.

PIN FUNCTION

Pin Name	Function
$\overline{\text{RESET}}$	Active Low Reset Input/Output
V_{SS}	Ground
SDA	Serial Data/Address
SCL	Clock Input
RESET	Active High Reset Output (CAT1026 only)
V_{CC}	Power Supply
V_{SENSE}	Auxiliary Voltage Monitor Input
V_{LOW}	Auxiliary Voltage Monitor Output
WDI	Watchdog Timer Interrupt (CAT1027 only)

OPERATING TEMPERATURE RANGE

Industrial	-40ºC to 85ºC
Extended	-40ºC to 125ºC

CAT10XX FAMILY OVERVIEW

Device	Manual Reset Input Pin	Watchdog	Watchdog Monitor Pin	Write Protection Pin	Independent Auxiliary Voltage Sense	RESET: Active High and LOW	EEPROM
CAT1021	✓	✓	SDA	✓		✓	2k
CAT1022	✓	✓	SDA				2k
CAT1023	✓	✓	WDI			✓	2k
CAT1024	✓	✓					2k
CAT1025	✓			✓		✓	2k
CAT1026					✓	✓	2k
CAT1027		✓	WDI		✓		2k

For supervisory circuits with embedded 16k EEPROM, please refer to the CAT1161, CAT1162 and CAT1163 data sheets.

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ABSOLUTE MAXIMUM RATINGS[1]

Parameters	Ratings	Units
Temperature Under Bias	–55 to +125	ºC
Storage Temperature	–65 to +150	ºC
Voltage on any Pin with Respect to Ground[2]	–2.0 to V_{CC} + 2.0	V
V_{CC} with Respect to Ground	–2.0 to 7.0	V
Package Power Dissipation Capability (T_A = 25°C)	1.0	W
Lead Soldering Temperature (10 s)	300	ºC
Output Short Circuit Current[3]	100	mA

D.C. OPERATING CHARACTERISTICS

V_{CC} = 2.7 V to 5.5 V and over the recommended temperature conditions unless otherwise specified.

Symbol	Parameter	Test Conditions		Min	Typ	Max	Units
I_{LI}	Input Leakage Current	V_{IN} = GND to V_{CC}		-2		10	µA
I_{LO}	Output Leakage Current	V_{IN} = GND to V_{CC}		-10		10	µA
I_{CC1}	Power Supply Current (Write)	f_{SCL} = 400 kHz V_{CC} = 5.5 V				3	mA
I_{CC2}	Power Supply Current (Read)	f_{SCL} = 400 kHz V_{CC} = 5.5 V				1	mA
I_{SB}	Standby Current	Vcc = 5.5 V, V_{IN} = GND or V_{CC}	CAT1026			50	µA
			CAT1027			60	
V_{IL}[4]	Input Low Voltage			-0.5		0.3 x V_{CC}	V
V_{IH}[4]	Input High Voltage			0.7 x V_{CC}		V_{CC} + 0.5	V
V_{OL}	Output Low Voltage (SDA, $\overline{\text{RESET}}$)	I_{OL} = 3 mA V_{CC} = 2.7 V				0.4	V
V_{OH}	Output High Voltage (RESET)	I_{OH} = -0.4 mA V_{CC} = 2.7 V		V_{CC} - 0.75			V
V_{TH}	Reset Threshold	CAT102x-45 (V_{CC} = 5.0 V)		4.50		4.75	V
		CAT102x-42 (V_{CC} = 5.0 V)		4.25		4.50	
		CAT102x-30 (V_{CC} = 3.3 V)		3.00		3.15	
		CAT102x-28 (V_{CC} = 3.3 V)		2.85		3.00	
		CAT102x-25 (V_{CC} = 3.0 V)		2.55		2.70	
V_{RVALID}	Reset Output Valid V_{CC} Voltage			1.00			V
V_{RT}[5]	Reset Threshold Hysteresis			15			mV
V_{REF}	Auxiliary Voltage Monitor Threshold			1.2	1.25	1.3	VS

Notes:

(1) Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions outside of those listed in the operational sections of this specification is not implied. Exposure to any absolute maximum rating for extended periods may affect device performance and reliability.

(2) The minimum DC input voltage is -0.5 V. During transitions, inputs may undershoot to -2.0 V for periods of less than 20 ns. Maximum DC voltage on output pins is V_{CC} +0.5 V, which may overshoot to V_{CC} +2.0 V for periods of less than 20 ns.

(3) Output shorted for no more than one second. No more than one output shorted at a time.

(4) V_{IL} min and V_{IH} max are reference values only and are not tested.

(5) This parameter is tested initially and after a design or process change that affects the parameter. Not 100% tested.

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CAPACITANCE

T_A = 25ºC, f = 1.0 MHz, V_{CC} = 5 V

Symbol	Test	Test Conditions	Max	Units
C_{OUT}[1]	Output Capacitance	V_{OUT} = 0 V	8	pF
C_{IN}[1]	Input Capacitance	V_{IN} = 0 V	6	pF

AC CHARACTERISTICS

V_{CC} = 2.7 V to 5.5 V and over the recommended temperature conditions, unless otherwise specified.

Memory Read & Write Cycle[2]

Symbol	Parameter	Min	Max	Units
f_{SCL}	Clock Frequency		400	kHz
t_{SP}	Input Filter Spike Suppression (SDA, SCL)		100	ns
t_{LOW}	Clock Low Period	1.3		µs
t_{HIGH}	Clock High Period	0.6		µs
t_R[1]	SDA and SCL Rise Time		300	ns
t_F[1]	SDA and SCL Fall Time		300	ns
$t_{HD;\ STA}$	Start Condition Hold Time	0.6		µs
$t_{SU;\ STA}$	Start Condition Setup Time (for a Repeated Start)	0.6		µs
$t_{HD;\ DAT}$	Data Input Hold Time	0		ns
$t_{SU;\ DAT}$	Data Input Setup Time	100		ns
$t_{SU;\ STO}$	Stop Condition Setup Time	0.6		µs
t_{AA}	SCL Low to Data Out Valid		900	ns
t_{DH}	Data Out Hold Time	50		ns
t_{BUF}[1]	Time the Bus must be Free Before a New Transmission Can Start	1.3		µs
t_{WC}[3]	Write Cycle Time (Byte or Page)		5	ms

Notes:

(1) This parameter is characterized initially and after a design or process change that affects the parameter. Not 100% tested.

(2) Test Conditions according to “AC Test Conditions” table.

(3) The write cycle time is the time from a valid stop condition of a write sequence to the end of the internal program/erase cycle. During the write cycle, the bus interface circuits are disabled, SDA is allowed to remain high and the device does not respond to its slave address.

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VOLTAGE MONITOR AND RESET CIRCUIT AC CHARACTERISTICS

Symbol	Parameter	Test Conditions	Min	Typ	Max	Units
t_{PURST}	Reset Timeout	Note 2	130	200	270	ms
t_{RDP}	V_{TH} to RESET Output Delay	Note 3			5	µs
t_{GLITCH}	V_{CC} Glitch Reject Pulse Width	Note 4, 5			30	ns
t_{WD}	Watchdod Timeout	Note 1[1]	1.0	1.6	2.1	s
t_{RPD2}	V_{SENSE} to V_{LOW} Delay	Note 5			5	µs

POWER-UP TIMING (6), (7)

Symbol	Parameter	Test Conditions	Min	Typ	Max	Units
t_{PUR}	Power-Up to Read Operation				270	ms
t_{PUW}	Power-Up to Write Operation				270	ms

AC TEST CONDITIONS

Parameter	Test Conditions
Input Pulse Voltages	0.2 x V_{CC} to 0.8 x V_{CC}
Input Rise and Fall Times	10 ns
Input Reference Voltages	0.3 x V_{CC}, 0.7 x V_{CC}
Output Reference Voltages	0.5 x V_{CC}
Output Load	Current Source: I_{OL} = 3 mA; C_L = 100 pF

RELIABILITY CHARACTERISTICS

Symbol	Parameter	Reference Test Method	Min	Max	Units
$N_{END}^{(6)}$	Endurance	MIL-STD-883, Test Method 1033	1,000,000		Cycles/Byte
$T_{DR}^{(6)}$	Data Retention	MIL-STD-883, Test Method 1008	100		Years
$V_{ZAP}^{(6)}$	ESD Susceptibility	MIL-STD-883, Test Method 3015	2000		Volts
$I_{LTH}^{(6)(8)}$	Latch-Up	JEDEC Standard 17	100		mA

Notes:

(1) Test Conditions according to “AC Test Conditions” table.

(2) Power-up, Input Reference Voltage $V_{CC} = V_{TH}$, Reset Output Reference Voltage and Load according to “AC Test Conditions” Table

(3) Power-Down, Input Reference Voltage $V_{CC} = V_{TH}$, Reset Output Reference Voltage and Load according to “AC Test Conditions” Table

(4) V_{CC} Glitch Reference Voltage = V_{THmin}; Based on characterization data

5) $0 < V_{SENSE} - V_{CC}$, V_{LOW} Output Reference Voltage and Load according to “AC Test Conditions” Table.

(6) This parameter is characterized initially and after a design or process change that affects the parameter. Not 100% tested.

(7) t_{PUR} and t_{PUW} are the delays required from the time V_{CC} is stable until the specified memory operation can be initiated.

(8) Latch-up protection is provided for stresses up to 100mA on input and output pins from -1 V to V_{CC} + 1 V.

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DEVICE OPERATION

Reset Controller Description

The CAT1026 and CAT1027 precision RESET controllers ensure correct system operation during brownout and power up/down conditions. They are configured with open drain RESET outputs.

During power-up, the RESET outputs remain active until V_{CC} reaches the V_{TH} threshold and will continue driving the outputs for approximately 200 ms (t_{PURST}) after reaching V_{TH}. After the t_{PURST} timeout interval, the device will cease to drive the reset outputs. At this point the reset outputs will be pulled up or down by their respective pull up/down resistors.

During power-down, the RESET outputs will be active when V_{CC} falls below V_{TH}. The $\overline{\text{RESET}}$ output will be valid so long as V_{CC} is >1.0 V (V_{RVALID}). The device is designed to ignore the fast negative going V_{CC} transient pulses (glitches).

Reset output timing is shown in Figure 1.

Manual Reset Capability

The $\overline{\text{RESET}}$ pin can operate as reset output and manual reset input. The input is edge triggered; that is, the $\overline{\text{RESET}}$ input will initiate a reset timeout after detecting a high to low transition.

When $\overline{\text{RESET}}$ I/O is driven to the active state, the 200 ms timer will begin to time the reset interval. If external reset is shorter than 200 ms, Reset outputs will remain active at least 200 ms.

Monitoring Two Voltages

The CAT1026 and CAT1027 feature a second voltage sensor, V_{SENSE}, which drives the open drain V_{LOW} output low whenever the input voltage is below 1.25 V. The auxiliary voltage monitor timing is shown in Figure 2.

By using an external resistor divider the sense circuitry can be set to monitor a second supply in the system. The circuit shown in Figure 3 provides an externally adjustable threshold voltage, V_{TH_ADJ} to monitor the auxiliary voltage. The low leakage current at V_{SENSE} allows the use of large value resistors, to reduce the system power consumption. The V_{LOW} output can be externally connected to the RESET output to generate a reset condition when either of the supplies is invalid. In other applications, V_{LOW} signal can be used to interrupt the system controller for an impending power failure notification.

Data Protection

The CAT1026 and CAT1027 devices have been designed to solve many of the data corruption issues that have long been associated with serial EEPROMs. Data corruption occurs when incorrect data is stored in a memory location which is assumed to hold correct data.

Whenever the device is in a Reset condition, the embedded EEPROM is disabled for all operations, including write operations. If the Reset output(s) are active, in progress communications to the EEPROM are aborted and no new communications are allowed. In this condition an internal write cycle to the memory can not be started, but an in progress internal non-volatile memory write cycle can not be aborted. An internal write cycle initiated before the Reset condition can be successfully finished if there is enough time (5 ms) before V_{CC} reaches the minimum value of 2 V.

In addition, to avoid data corruption due to the loss of power supply voltage during the memory internal write operation, the system controller should monitor the unregulated DC power. Using the second voltage sensor, V_{SENSE}, to monitor an unregulated power supply, the CAT1026 and CAT1027 signals an impending power failure by setting V_{LOW} low.

Watchdog Timer

The Watchdog Timer provides an independent protection for microcontrollers. During a system failure, the CAT1027 device will provide a reset signal after a time-out interval of 1.6 seconds for a lack of activity. CAT1027 is designed with the Watchdog timer feature on the WDI pin. If WDI does not toggle within 1.6 second intervals, the reset condition will be generated on reset output. The watchdog timer is cleared by any transition on monitored line.

As long as reset signal is asserted, the watchdog timer will not count and will stay cleared.

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Figure 1. RESET Output Timing

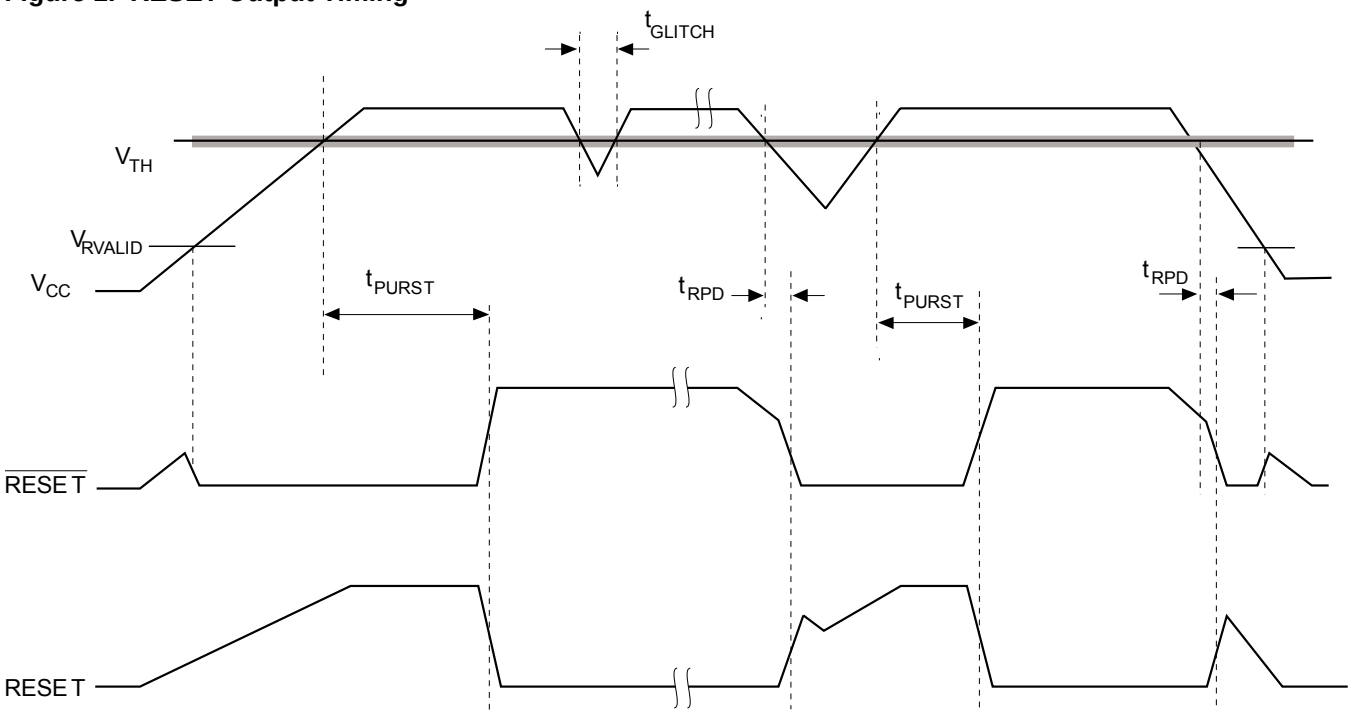


Figure 2: Auxiliary Voltage Monitor Timing

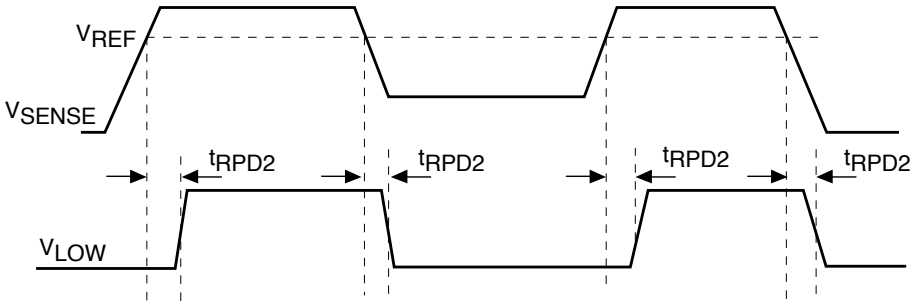
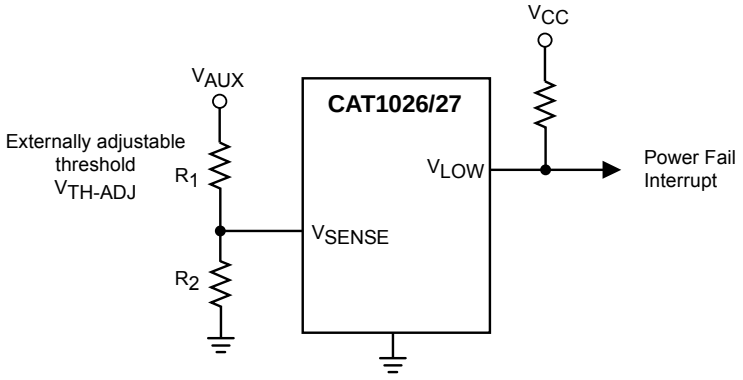


Figure 3: Auxiliary Voltage Monitor



$$V_{TH\text{-}ADJ} = V_{REF} \times \frac{R_1 + R_2}{R_2} = 1.25V \times \frac{R_1 + R_2}{R_2}$$

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EMBEDDED EEPROM OPERATION

The CAT1026 and CAT1027 feature a 2-kbit embedded serial EEPROM that supports the I^2C Bus data transmission protocol. This Inter-Integrated Circuit Bus protocol defines any device that sends data to the bus to be a transmitter and any device receiving data to be a receiver. The transfer is controlled by the Master device which generates the serial clock and all START and STOP conditions for bus access. Both the Master device and Slave device can operate as either transmitter or receiver, but the Master device controls which mode is activated.

I^2C BUS PROTOCOL

The features of the I^2C bus protocol are defined as follows:

(1) Data transfer may be initiated only when the bus is not busy.
(2) During a data transfer, the data line must remain stable whenever the clock line is high. Any changes in the data line while the clock line is high will be interpreted as a START or STOP condition.

START CONDITION

The START Condition precedes all commands to the device, and is defined as a HIGH to LOW transition of SDA when SCL is HIGH. The CAT1026 and CAT1027 monitor the SDA and SCL lines and will not respond until this condition is met.

STOP CONDITION

A LOW to HIGH transition of SDA when SCL is HIGH determines the STOP condition. All operations must end with a STOP condition.

DEVICE ADDRESSING

The Master begins a transmission by sending a START condition. The Master sends the address of the particular slave device it is requesting. The four most significant bits of the 8-bit slave address are programmable in metal and the default is 1010.

The last bit of the slave address specifies whether a Read or Write operation is to be performed. When this bit is set to 1, a Read operation is selected, and when set to 0, a Write operation is selected.

After the Master sends a START condition and the slave address byte, the CAT1026 and CAT1027 monitor the bus and responds with an acknowledge (on the SDA line) when its address matches the transmitted slave address. The CAT1026 and CAT1027 then perform a Read or Write operation depending on the R/$\overline{W}$ bit.

Figure 3. Bus Timing

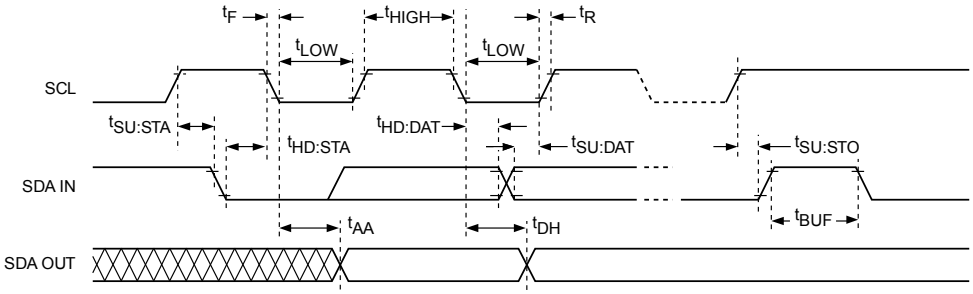
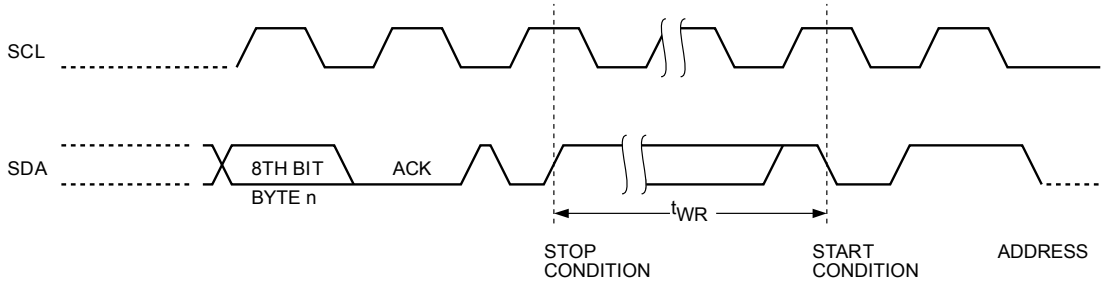


Figure 4. Write Cycle Timing



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ACKNOWLEDGE

After a successful data transfer, each receiving device is required to generate an acknowledge. The acknowledging device pulls down the SDA line during the ninth clock cycle, signaling that it received the 8 bits of data.

The CAT1026 and CAT1027 respond with an acknowledge after receiving a START condition and its slave address. If the device has been selected along with a write operation, it responds with an acknowledge after receiving each 8-bit byte.

When the CAT1026 and CAT1027 begin a READ mode it transmits 8 bits of data, releases the SDA line and monitors the line for an acknowledge. Once it receives this acknowledge, the CAT1026 and CAT1027 will continue to transmit data. If no acknowledge is sent by the Master, the device terminates data transmission and waits for a STOP condition.

WRITE OPERATIONS

Byte Write

In the Byte Write mode, the Master device sends the START condition and the slave address information (with the R/$\overline{W}$ bit set to zero) to the Slave device. After the Slave generates an acknowledge, the Master sends a 8-bit address that is to be written into the address pointers of the device. After receiving another acknowledge from the Slave, the Master device transmits the data to be written into the addressed memory location. The CAT1026 and CAT1027 acknowledge once more and the Master generates the STOP condition. At this time, the device begins an internal programming cycle to non-volatile memory. While the cycle is in progress, the device will not respond to any request from the Master device.

Figure 5. Start/Stop Timing

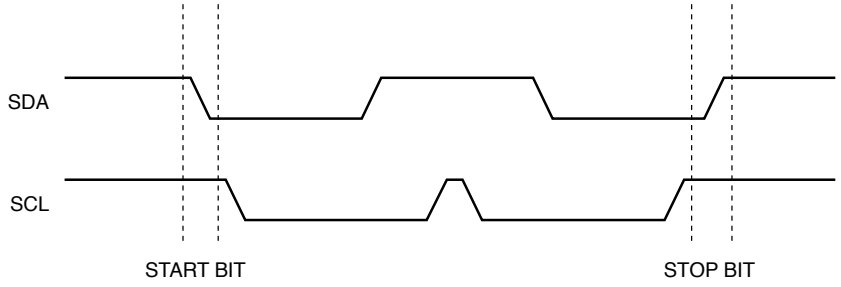

Figure 6. Acknowledge Timing

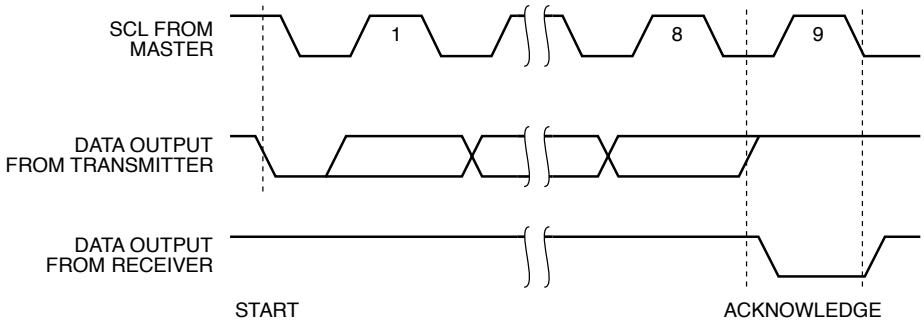

Figure 7: Slave Address Bits

Default Configuration	1	0	1	0	0	0	0	R/$\overline{W}$

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Page Write

The CAT1026 and CAT1027 write up to 16 bytes of data in a single write cycle, using the Page Write operation. The page write operation is initiated in the same manner as the byte write operation, however instead of terminating after the initial byte is transmitted, the Master is allowed to send up to 15 additional bytes. After each byte has been transmitted, the CAT1026 and CAT1027 will respond with an acknowledge and internally increment the lower order address bits by one. The high order bits remain unchanged.

If the Master transmits more than 16 bytes before sending the STOP condition, the address counter 'wraps around,' and previously transmitted data will be overwritten.

When all 16 bytes are received, and the STOP condition has been sent by the Master, the internal programming cycle begins. At this point, all received data is written to the CAT1026 and CAT1027 in a single write cycle.

Figure 8. Byte Write Timing

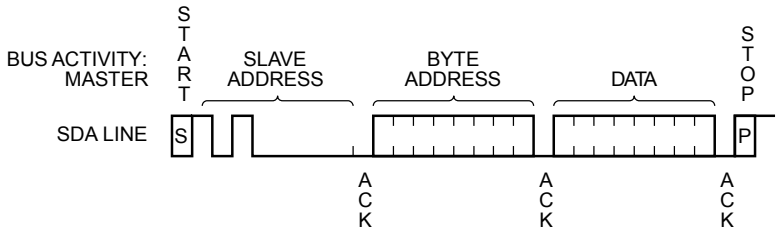
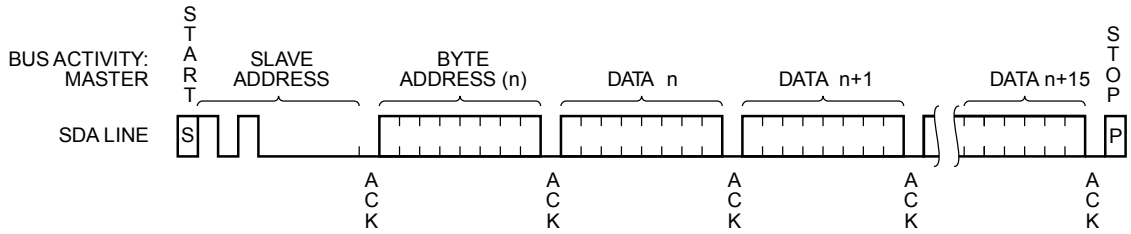


Figure 9: Page Write Timing



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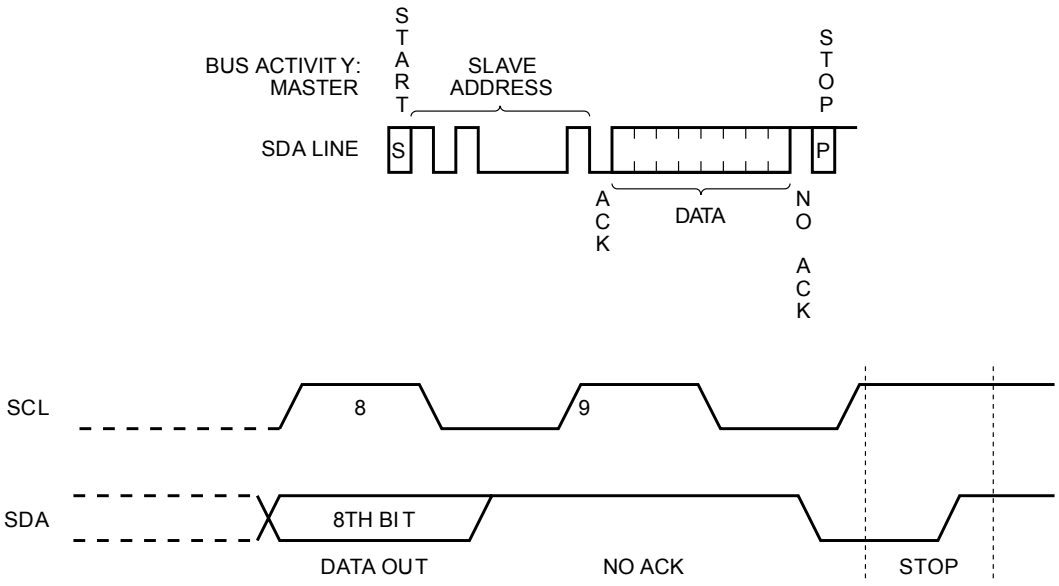
Acknowledge Polling

Disabling of the inputs can be used to take advantage of the typical write cycle time. Once the stop condition is issued to indicate the end of the host's write opration, the CAT1026 and CAT1027 initiates the internal write cycle. ACK polling can be initiated immediately. This involves issuing the start condition followed by the slave address for a write operation. If the device is still busy with the write operation, no ACK will be returned. If a write operation has completed, an ACK will be returned and the host can then proceed with the next read or write operation.

READ OPERATIONS

The READ operation for the CAT1026 and CAT1027 is initiated in the same manner as the write operation with one exception, the R/$\overline{W}$ bit is set to one. Three different READ operations are possible: Immediate/Current Address READ, Selective/Random READ and Sequential READ.

Figure 10. Immediate Address Read Timing



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Immediate/Current Address Read

The CAT1026 and CAT1027 address counter contains the address of the last byte accessed, incremented by one. In other words, if the last READ or WRITE access was to address N, the READ immediately following would access data from address N + 1. For N = E = 255, the counter will wrap around to zero and continue to clock out valid data. After the CAT1026and CAT1027 receive its slave address information (with the R/$\overline{W}$ bit set to one), it issues an acknowledge, then transmits the 8-bit byte requested. The master device does not send an acknowledge, but will generate a STOP condition.

Selective/Random Read

Selective/Random READ operations allow the Master device to select at random any memory location for a READ operation. The Master device first performs a 'dummy' write operation by sending the START condition, slave address and byte addresses of the location it wishes to read. After the CAT1026 and CAT1027 acknowledges, the Master device sends the START condition and the slave address again, this time with the R/$\overline{W}$ bit set to one. The CAT1026 and CAT1027 then responds with its acknowledge and sends the 8-bit byte requested. The master device does not send an acknowledge but will generate a STOP condition.

Sequential Read

The Sequential READ operation can be initiated by either the Immediate Address READ or Selective READ operations. After the CAT1026 and CAT1027 sends the inital 8-bit byte requested, the Master will responds with an acknowledge which tells the device it requires more data. The CAT1026 and CAT1027 will continue to output an 8-bit byte for each acknowledge, thus sending the STOP condition.

The data being transmitted from the CAT1026 and CAT1027 is sent sequentially with the data from address N followed by data from address N + 1. The READ operation address counter increments all of the CAT1026 and CAT1027 address bits so that the entire memory array can be read during one operation.

Figure 11. Selective Read Timing

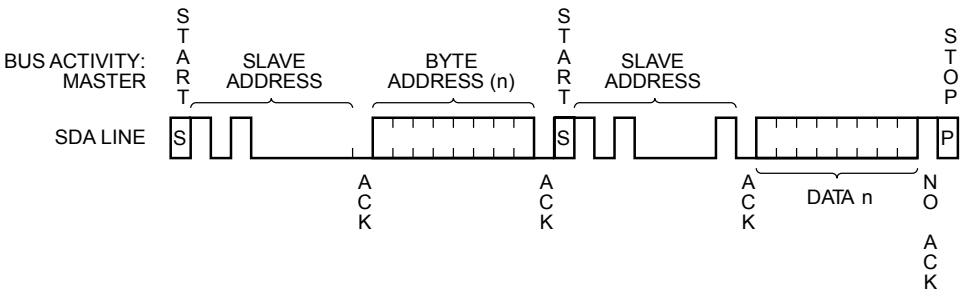
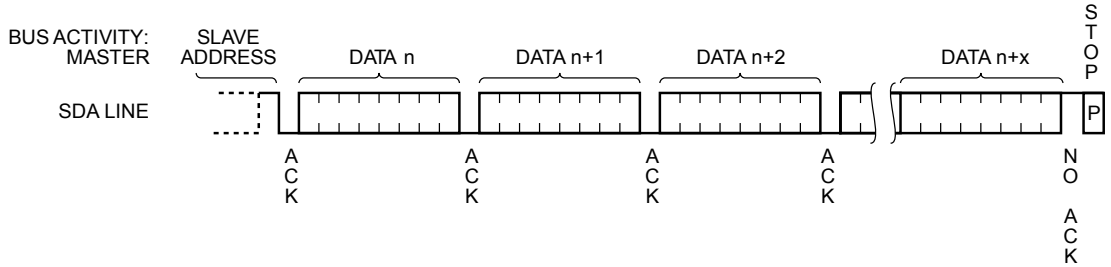


Figure 12. Sequential Read Timing



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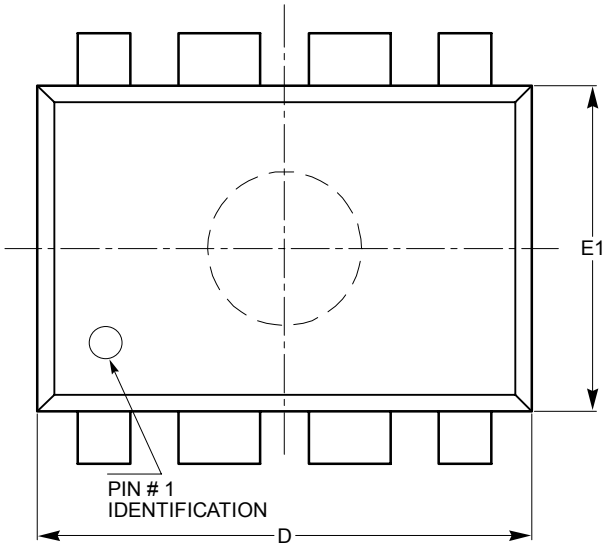
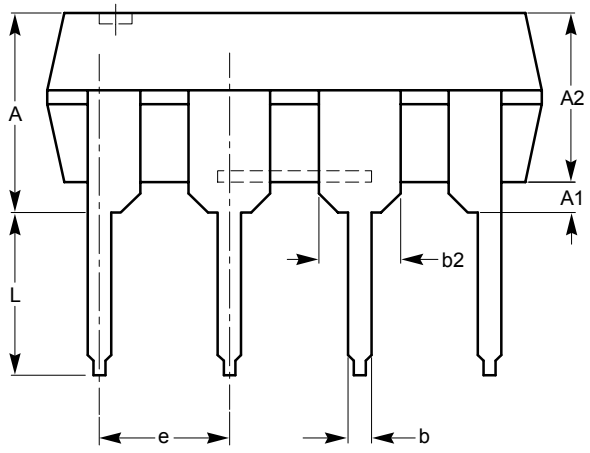
PACKAGE OUTLINE DRAWINGS

PDIP 8-Lead 300 mils (L)[1][2]

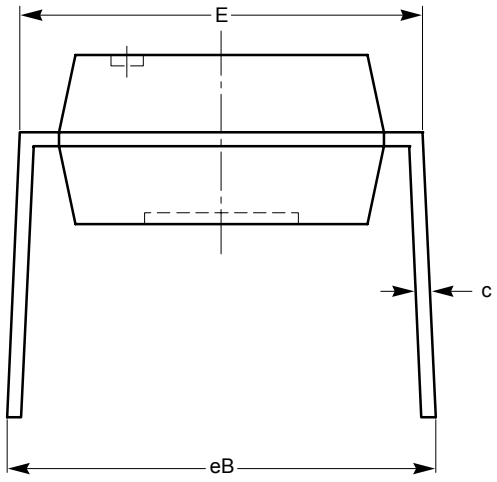


TOP VIEW

SYMBOL	MIN	NOM	MAX
A			5.33
A1	0.38		
A2	2.92	3.30	4.95
b	0.36	0.46	0.56
b2	1.14	1.52	1.78
c	0.20	0.25	0.36
D	9.02	9.27	10.16
E	7.62	7.87	8.25
e		2.54 BSC	
E1	6.10	6.35	7.11
eB	7.87		10.92
L	2.92	3.30	3.80



SIDE VIEW



END VIEW

Notes:
(1) All dimensions are in millimeters.
(2) Complies with JEDEC MS-001.

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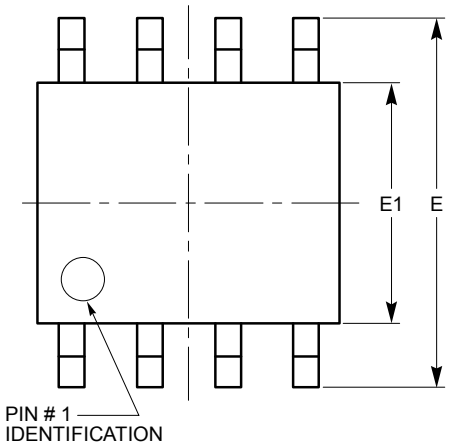
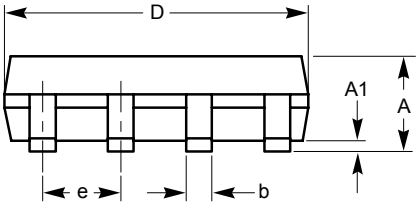
SOIC 8-Lead 150 mils (W) [(1)(2)]

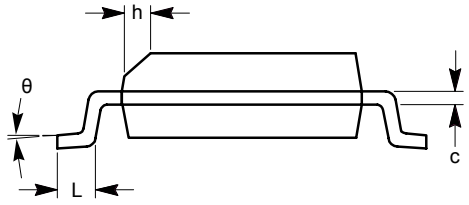


TOP VIEW

SYMBOL	MIN	NOM	MAX
A	1.35		1.75
A1	0.10		0.25
b	0.33		0.51
c	0.19		0.25
D	4.80		5.00
E	5.80		6.20
E1	3.80		4.00
e	1.27 BSC		
h	0.25		0.50
L	0.40		1.27
θ	0º		8º



SIDE VIEW



END VIEW

Notes:
(1) All dimensions are in millimeters. Angles in degrees.
(2) Complies with JEDEC MS-012.

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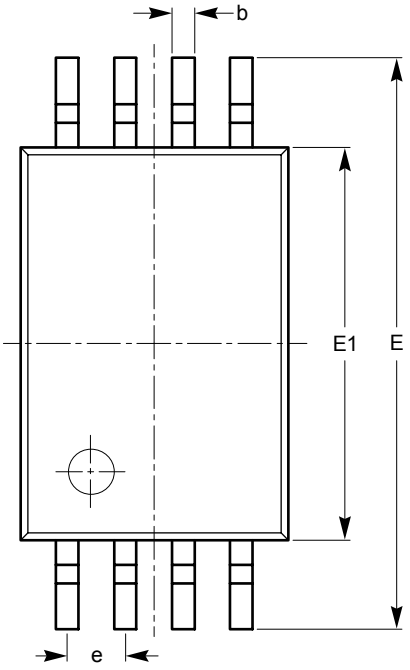
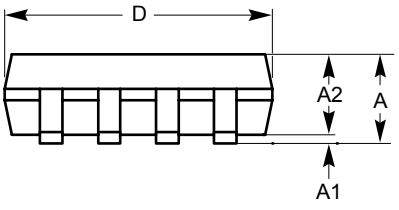
TSSOP 8-Lead (V) (1)(2)

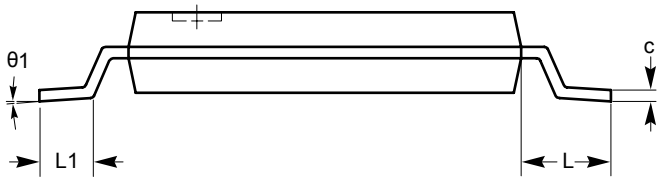


TOP VIEW

SYMBOL	MIN	NOM	MAX
A			1.20
A1	0.05		0.15
A2	0.80	0.90	1.05
b	0.19		0.30
c	0.09		0.20
D	2.90	3.00	3.10
E	6.30	6.40	6.50
E1	4.30	4.40	4.50
e		0.65 BSC	
L		1.00 REF	
L1	0.50	0.60	0.75
θ1	0°		8°



SIDE VIEW



END VIEW

Notes:
(1) All dimensions are in millimeters. Angles in degrees.
(2) Complies with JEDEC MO-153

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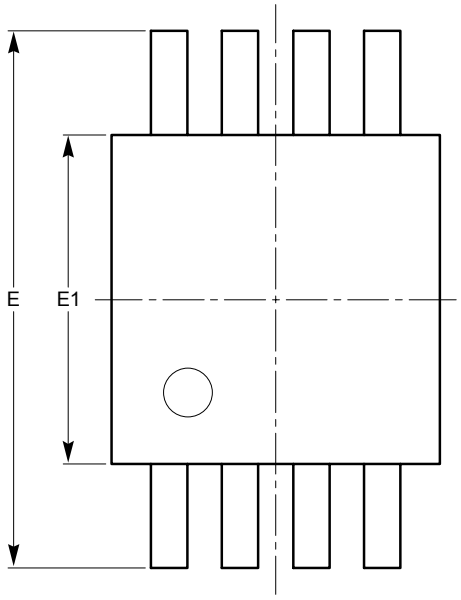
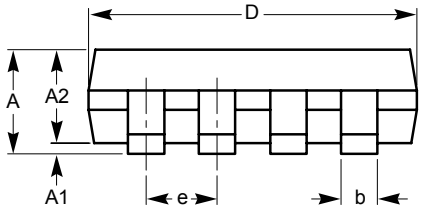
MSOP 8-Lead (Z) (1)(2)

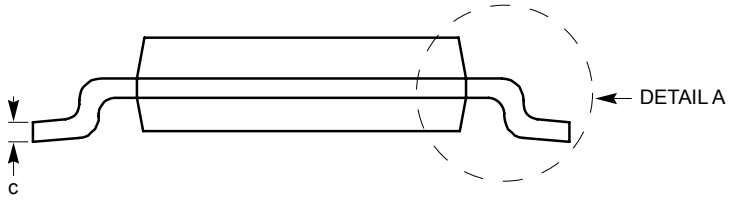


TOP VIEW

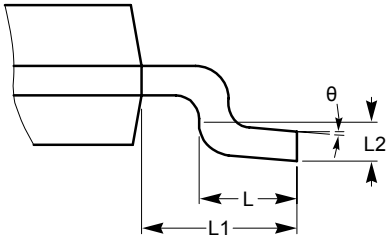
SYMBOL	MIN	NOM	MAX
A			1.10
A1	0.05	0.10	0.15
A2	0.75	0.85	0.95
b	0.22		0.38
c	0.13		0.23
D	2.90	3.00	3.10
E	4.80	4.90	5.00
E1	2.90	3.00	3.10
e		0.65 BSC	
L	0.40	0.60	0.80
L1		0.95 REF	
L2		0.25 BSC	
θ	0°		6°



SIDE VIEW



END VIEW



DETAIL A

Notes:

(1) All dimensions are in millimeters. Angles in degrees.

(2) Complies with JEDEC MO-187.

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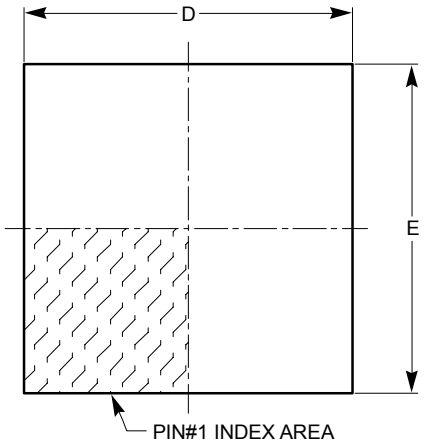
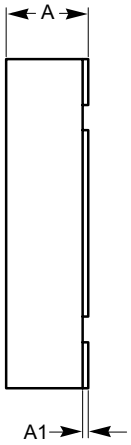
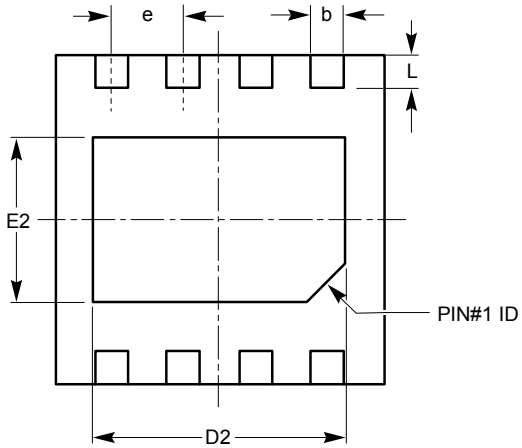
TDFN 8-Pad 3 x 3 mm (ZD4) [(1)(2)]



TOP VIEW

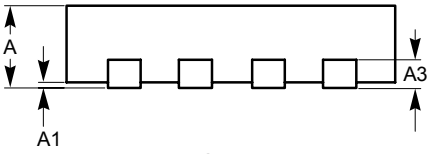


SIDE VIEW



BOTTOM VIEW

SYMBOL	MIN	NOM	MAX
A	0.70	0.75	0.80
A1	0.00	0.02	0.05
A3		0.20 REF	
b	0.23	0.30	0.37
D	2.90	3.00	3.10
D2	2.20	—	2.50
E	2.90	3.00	3.10
E2	1.40	—	1.80
e		0.65 TYP	
L	0.20	0.30	0.40



FRONT VIEW

Notes:
(1) All dimensions are in millimeters. Angles in degrees.
(2) Complies with JEDEC MO-229.

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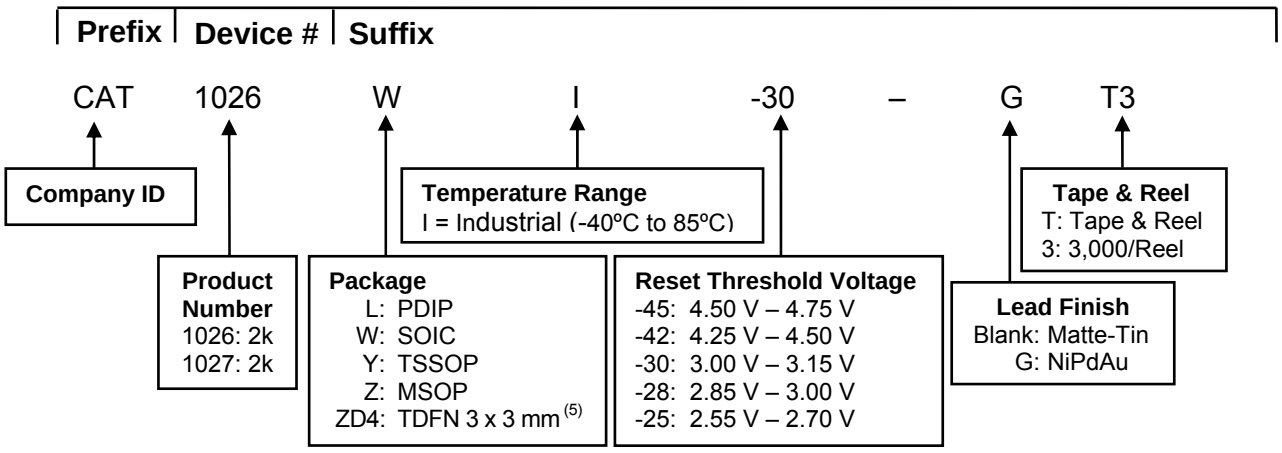
EXAMPLE OF ORDERING INFORMATION



ORDERING INFORMATION

Orderable Part Number – CAT1026xx	
CAT1026LI-45-G	CAT1026ZI-45-GT3
CAT1026LI-42-G	CAT1026ZI-42-GT3
CAT1026LI-30-G	CAT1026ZI-30-GT3
CAT1026LI-28-G	CAT1026ZI-28-GT3
CAT1026LI-25-G	CAT1026ZI-25-GT3
CAT1026WI-45-GT3	CAT1026ZD4I-45T3*
CAT1026WI-42-GT3	CAT1026ZD4I-42T3*
CAT1026WI-30-GT3	CAT1026ZD4I-30T3*
CAT1026WI-28-GT3	CAT1026ZD4I-28T3*
CAT1026WI-25-GT3	CAT1026ZD4I-25T3*
CAT1026YI-45-GT3	
CAT1026YI-42-GT3	
CAT1026YI-30-GT3	
CAT1026YI-28-GT3	
CAT1026YI-25-GT3	

Orderable Part Number – CAT1027xx	
CAT1027LI-45-G	CAT1027ZI-45-GT3
CAT1027LI-42-G	CAT1027ZI-42-GT3
CAT1027LI-30-G	CAT1027ZI-30-GT3
CAT1027LI-28-G	CAT1027ZI-28-GT3
CAT1027LI-25-G	CAT1027ZI-25-GT3
CAT1027WI-45-GT3	CAT1027ZD4I-45T3*
CAT1027WI-42-GT3	CAT1027ZD4I-42T3*
CAT1027WI-30-GT3	CAT1027ZD4I-30T3*
CAT1027WI-28-GT3	CAT1027ZD4I-28T3*
CAT1027WI-25-GT3	CAT1027ZD4I-25T3*
CAT1027YI-45-GT3	
CAT1027YI-42-GT3	
CAT1027YI-30-GT3	
CAT1027YI-28-GT3	
CAT1027YI-25-GT3	

* Part number is not exactly the same as the “Example of Ordering Information” shown above. For part numbers marked with ***** there is only one hyphen in the orderable part number, which is placed before the “Reset Threshold Voltage”.

Notes:

(1) All packages are RoHS-compliant (Lead-free, Halogen-free).

(2) The standard lead finish is NiPdAu.

(3) The device used in the above example is a CAT1026WI-30-GT3 (SOIC, Industrial Temperature, 3.0 - 3.15 V, NiPdAu, Tape & Reel, 3,000/Reel).

(4) For additional package and temperature options, please contact your nearest ON Semiconductor Sales office.

(5) TDFN not available in NiPdAu (–G) version.

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REVISION HISTORY

Date	Rev.	Reason
9/25/2003	F	Added Green Package logo. Updated DC Operating Characteristic notes. Updated Reliability Characteristics notes
11/07/2003	G	Eliminated Automotive temperature range. Updated Ordering Information with “Green” package marking codes
4/12/2004	H	Eliminated data sheet designation. Updated Reel Ordering Information
11/01/2004	I	Changed SOIC package designators. Eliminated 8-pad TDFN (3 x 4.9 mm) package. Added package outlines
11/04/2004	J	Update Pin Configuration
11/11/2004	K	Update Feature Update Description Update DC Operating Characteristic Update AC Characteristics
02/02/2007	L	Update Example of Ordering Information
11/28/2007	M	Update Package Outline Drawings Update Example of Ordering Information Add “MD-“ to document number
7-Nov-08	N	Change logo and fine print to ON Semiconductor
05-Mar-09	O	Update Ordering Information (Remove 2,000/Reel)
14-Jul-09	P	Update Ordering Information table

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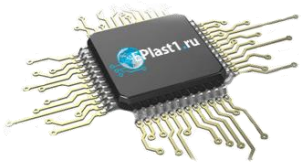
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



Как с нами связаться

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