

# **Multifunction LCD Segment Driver**

BU97501KV MAX 204 segments (51SEG×4COM)

#### Features

- Key input function for up to 30 keys (A key scan is performed only when a key is pressed.)
- Either 1/4 or 1/3 duty can be selected 1/4 duty drive : Up to 204 segments 1/3 duty drive : Up to 156 segments
- Integrated RAM for display data (DDRAM)
- Segment/GPO (Max 4port) output mode selectable
- Support standby mode
- Integrated Power-on Reset circuit
- Integrated Oscillator circuit
- No external component
- Low power consumption design

## Applications

- Telephone
- FAX
- Portable equipment (POS, ECR, PDA etc.)
- DSC
- DVC
- Car audio
- Home electrical appliance
- Meter equipment

## **Typical Application Circuit**

## **Key Specifications**

Supply Voltage Range: 2.7V to 6.0V LCD drive power supply Range: 4.5V to 6.0V Operating Temperature Range: -40°C to +85°C 204 Segments Max Segments: Display Duty: 1/3, 1/4 selectable 1/2, 1/3 selectable Bias: Interface: **3wire serial interface** 

#### Package VQFP64

W(Typ.)×D(Typ.)×H(Max.)





(Note1) Insert capacitors between VDD/VLCD and VSS C≥0.1uF.

Figure 1. Typical Application Circuit

OProduct structure : Silicon monolithic integrated circuit OThis product is not designed for protection against radioactive rays.

## Block Diagram / Pin Configuration / Pin Description



Terminal	Terminal No.	I/O	Handling When Unused	Functions					
CSB	59	Ι	VDD	Chip select : "L" active					
SCL	60	Ι	VSS	Serial data transfer clock					
SD	61	I	VSS	Input serial data					
VDD	63	-	-	Power Supply for the logic					
OSC	56	I/O	OPEN/VSS	External Clock Input: Fix to low or open when the internal clock mode setting.					
DO	58	0	OPEN	Output data					
RESB	57	I	VDD	Reset Input: RESB="L" : Display is disabled. RESB="H" : Display is controllable. However, serial data can not be transferred when RESB is "L".					
VSS	64	-	-	Power supply pin. Must be connected to ground.					
VLCD	62	-	-	Power Supply for the LCD driver					
COM1~COM3	41 to 43	0	OPEN	COMMON output for LCD driver					
COM4/S41	44	0	OPEN	COMMON / SEGMENT output for LCD driver. Assigned as SEGMENT output in 1/3Duty mode.					
S1/P1~S4/P4	1 to 4	0	OPEN	SEGMENT output for LCD driving / General Purpose Output S1/P1~S4/P4 pins can also be used as General Purpose Outputs when set up by the control data.					
S5~S40	5 to 40	0	OPEN	SEGMENT output for LCD driver					
KS1/S42~KS6/S47	(S1/S42~KS6/S47 45 to 50 O OPEN		OPEN	Key scan outputs Although normal key scan timing lines require diodes to be inserted in the timing lines to prevent shorts, since these outputs are unbalanced CMOS transistor outputs, these outputs will not be damaged by shorting when these outputs are used to form a key matrix. The KS1/S42 to KS6/S47 pins can be used as segment outputs when specified by the control data.					
KI1/S48~KI5/S52	51 to 55	I/O	OPEN	Key scan inputs These pins have built-in pull-down resistors. The KI1/S48 to KI5/S52 pins can be used as segment outputs when specified by the control data.					

Table 1. Pin Description

## Absolute Maximum Ratings (Ta=25°C, VSS=0.0V)

Parameters	Symbol	Ratings	Unit	Remarks
Power Supply voltage 1	VDD	-0.5 to +7.0	V	Power supply
Power Supply voltage 2	VLCD	-0.5 to +7.0	V	LCD drive voltage
Power Dissipation	Pd	1.00 <sup>(Note2)</sup>	W	
Input voltage range	VIN	-0.5 to VDD+0.5	V	
Operating temperature range	Topr	-40 to +85	°C	
Storage temperature range	Tstg	-55 to +125	°C	

(Note2) When operated higher than Ta=25°C, subtract 10mW per degree. (Using ROHM standard board)

(Board size: 70mm×70mm×1.6mm material: FR4 board copper foil: land pattern only)

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

## **Recommended Operating Conditions**

Parameters	Symbol		Ratings		Unit	Remarks		
i arameters	Symbol	MIN	TYP	MAX	Onit	Hemano		
Power Supply voltage 1	VDD	'DD 2.7 - 6.0		6.0	V	Power supply		
Power Supply voltage 2	tage 2 VLCD 4.5		4.5 - 6.0		V	LCD driver voltage		

(Note3) The power supply condition shall be met VLCD  $\ge$  VDD.

#### **Electrical Characteristics**

(Unless otherwise specified, Ta=-40°C to +85°C, VDD=2.7 to 6.0V, VLCD=4.5 to 6.0V, VSS=0.0V)

Corriess otherwise specified,		,	Limits	,		
Parameters	Symbol	MIN	TYP	MAX	Unit	Conditions
"H" Input Voltage	VIH	0.7VDD	-	VDD	V	SD, SCL, CSB, RESB, OSC
"L" Input Voltage	VIL	VSS	-	0.3VDD	V	SD, SCL, CSB, RESB, OSC
"H" Input Current	IIH	-	-	5.0	μA	SD, SCL, CSB, RESB, OSC, VI=5.5V
"L" Input Current	IIL	-5.0	-	-	μA	SD, SCL, CSB, RESB, OSC, VI=0.0V
Input Floating Voltage	VIF	-	-	0.05VDD	V	KI1 to KI5
Pull-down Resistance	RPD	50	100	250	kΩ	KI1 to KI5, VLCD=5.0V
Output Off Leakage Current	IOFFH	-	-	6.0	μA	DO, Vo=5.5V
	VOH1	VLCD-1.0	-	-		P1 to P4, Io=-1mA
"H" Level Output Voltage	VOH2	VLCD-1.0	-	-	V	S1 to S52, Io=-20µA
The Level Output Voltage	VOH3	VLCD-1.0	-	-	v	COM1 to COM4, lo=-100µA
	VOH4	VLCD-1.0	-	-		KS1 to KS6, lo=-500µA
	VOL1	-	-	1.0		P1 to P4, Io=1mA
	VOL2	-	-	1.0		S1 to S52, lo=20µA
"L" Level Output Voltage	VOL3	-	-	1.0	V	COM1 to COM4, Io=100µA
	VOL4	-	-	1.0		KS1 to KS6, lo=25µA
	VOL5	-	-	0.5		DO, lo=1mA
	VMID1	1/2VLCD	_	1/2VLCD		S1 to S52
	VIVILDI	-1.0		+1.0		1/2 Bias, lo=±20μA
	VMID2	1/2VLCD	-	1/2VLCD		COM1 to COM4
		-1.0		+1.0		1/2 Bias, lo=±100μA
	VMID3	2/3VLCD -1.0	-	2/3VLCD +1.0		S1 to S52
LCD Bias Voltage		1/3VLCD		1/3VLCD	V	1/3 Bias, lo=±20µA S1 to S52
	VMID4	-1.0	-	+1.0		1/3 Bias, lo=±20µA
		2/3VLCD		2/3VLCD		COM1 to COM4
	VMID5	-1.0	-	+1.0		1/3Bias, lo=±100μA
	VMID6	1/3VLCD		1/3VLCD		COM1 to COM4
	VIVIDO	-1.0	-	+1.0		1/3 Bias, lo=±100µA
	IstVDD	-	1	5		Input Pin ALL "L"
						Display off, Disable oscillator
	IstVLCD	-	1	5		Input Pin ALL "L" Display off, Disable oscillator
						VDD=VLCD=5.0V, Output unloaded
Current Consumption	IVDD1	-	2	10	μA	fFR=80Hz
	IVLCD1	-	40	95		VDD=VLCD=5.0V,Output unloaded
		_	- <del>1</del> 0	55		1/2 Bias, fFR=80Hz
	IVLCD2	-	65	140		VDD=VLCD=5.0V, Output unloaded 1/3 Bias, fFR=80Hz
	I					

# **Electrical Characteristics – continued**

Oscillation Characteristics (Ta=-40°C to +85°C, VDD=2.7 to 6.0V, VLCD=4.5V to 6.0V, VSS=0.0V)

Parameters	Symbol		Limits		Unit	Conditions			
Farameters	Symbol	MIN	TYP	MAX	Unit	Conditions			
Frame Frequency1 fFR1		56 80 104		Hz	VLCD=4.5V to 6.0V, fFR = 80Hz setting				
Frame Frequency2	fFR2	68	80	92	Hz	VLCD=5.0V, fFR = 80Hz setting			
External Clock Frequency	fFR3	30	-	600	kHz	External clock mode (DRV CTRL1 setting : P2P1=11)			

Frame frequency is decided external frequency and dividing ratio of DRV CTRL1 setting.

[Reference Data]



Figure 4. Typical temperature characteristics

MPU interface Characteristics (Ta=-40 to +85°C, VDD=2.7V to 6.0V, VLCD=4.5 to 6.0V, VSS=0.0V)

Parameters	Symbol		Limits		Unit	Conditions
i alameters	Symbol	MIN	TYP	MAX	Onit	Conditions
Input Rise Time	tr	-	-	80	ns	
Input Fall Time	tf	-	-	80	ns	
SCL Cycle Time	tSCYC	400	-	-	ns	
"H" SCL Pulse Width	tSHW	100	-	-	ns	
"L" SCL Pulse Width	tSLW	100	-	-	ns	
SD Setup Time	tSDS	20	-	-	ns	
SD Hold Time	tSDH	20	-	-	ns	
CSB Setup Time	tCSS	50	-	-	ns	
CSB Hold Time	tCSH	50	-	-	ns	
"H" CSB Pulse Width	tCHW	50	-	-	ns	
DO Output Delay Time	tDC	-	-	1.5	μs	DO RPU=4.7k $\Omega$ , CL=10pF <sup>(Note4)</sup>
DO Rise Time	tDR	-	-	1.5	μs	DO RPU=4.7k $\Omega$ , CL=10pF <sup>(Note4)</sup>

(Note4) Since DO can be an open-drain output; these values depend on the resistance of the pull-up resistor RPU and the load capacitance CL.



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## I/O equivalent circuit



Figure 6. I/O equivalent circuit

## **Function descriptions**

Command and Data Transfer Method

3-SPI (3-wire Serial Interface)

This device is controlled by a 3-wire signal (CSB, SCL, and SD).

First, Interface counter is initialized with CSB="H"

Setting CSB="L" enables SD and SCL inputs.

First, Interface counter is initialized with CSB="H", and then CSB="L" makes SD and SCL input enable.

The protocol of 3-SPI transfer is shown as follows.

Each command starts with D7 bit as MSB data, followed by D6 to D0 (this is while CSB ="L").

(Internal data is latched at the rising edge of SCL, then the data is converted to an 8-bit parallel data at the falling edge of the 8th CLK.)

When you rise CSB = "H", in case command less than 8bit, command and data are canceled.





## Figure 7. 3-SPI Data Transfer Format

(2) Read Mode (KEY RD command only)

The following occurs when Key Read by KEY RD command.

If KEY RD command is recognized at the rising edge of 8th CLK, it enters Read mode after the falling edge of 8th CLK and then key data is output through DO.

Setting CSB="H" can exit Read mode after or during Serial Data Transfer.



Figure 8. Serial Data Output Format

Command Transfer Method

After CSB="H" $\rightarrow$ "L", the 1st byte shall be a command.

Please refer to "Command Table".

When set command except Data write(DATAWR), the next byte will be (continuously) a command. When set DATAWR command, the following bytes will be display data bytes.

Command	Command	Command	Command	Display Data	
			(DATAWR)		

Once it becomes display data transfer mode, it will not be able to send command. If you send command again, please rise CSB="H".

## Display Data Transfer Method

This LSI has Display Data RAM (DDRAM) of 51×4=204bit.

The relationship between data input and display data, DDRAM data and address are as follows.

Command														
00001010	D1	D2	D3	D4	D5	D6	D7	D8	D9	D10	D11	D12	D13	
	$\rightarrow$ Disp	olay Dat	ta											

Display data will be stored in DDRAM. The address to be written is specified by Address set (ADSET) command and the address is automatically incremented in every 4bit data if 1/4 Duty mode or in every 3 bit if 1/3 Duty mode respectively.

## 1/3 Duty Mode

,		-			DD	RAM Add	dress/Seg	ment Ou	Itputs				
		00h	01h	02h		27h	28h	29h		31h	32h	33h	
	0	D1	D4	D7		D118	D121	D124		D148	D151	D154	COM1
BIT	1	D2	D5	D8		D119	D122	D125		D149	D152	D155	COM2
	2	D3	D6	D9		D120	D123	D126		D150	D153	D156	COM3
	-	S1	S2	S3		S40	S41	S42		S50	S51	S52	-

Transferred data is written to the DDRAM by every 3bits. The write operation is cancelled if it changes  $CSB="L" \rightarrow "H"$  before 3bits data transfer.

1/4 Duty Mode

DDRAM Address/ Segment Outputs 00h ... 30h 32h 01h 02h 27h 28h 29h ••• 31h 0 D1 D5 D157 D161 D165 D193 D197 D201 COM1 D9 COM2 1 D2 D6 D10 D158 D162 D166 D194 D198 D202 BIT 2 D3 D7 D11 D159 D163 D167 D195 D199 D203 COM3 D204 3 D4 D12 D164 D168 D200 COM4 D8 D160 D196 S1 S2 S40 S42 S43 S50 S51 S52 S3

Transferred Data is written to the DDRAM by every 4bits. The write operation is cancelled if it changes CSB="L" $\rightarrow$ "H" before 4bits data transfer.

Relationship between Display Data and Segment Output Pins 1/3 Duty Mode

output terminal	COM1	COM2	COM3	Address	output terminal	COM1	COM2	COM3	address
S1/P1	D1	D2	D3	00	S27	D79	D80	D81	1A
S2/P2	D4	D5	D6	01	S28	D82	D83	D84	1B
S3/P3	D7	D8	D9	02	S29	D85	D86	D87	1C
S4/P4	D10	D11	D12	03	S30	D88	D89	D90	1D
S5	D13	D14	D15	04	S31	D91	D92	D93	1E
S6	D16	D17	D18	05	S32	D94	D95	D96	1F
S7	D19	D20	D21	06	S33	D97	D98	D99	20
S8	D22	D23	D24	07	S34	D100	D101	D102	21
S9	D25	D26	D27	08	S35	D103	D104	D105	22
S10	D28	D29	D30	09	S36	D106	D107	D108	23
S11	D31	D32	D33	0A	S37	D109	D110	D111	24
S12	D34	D35	D36	0B	S38	D112	D113	D114	25
S13	D37	D38	D39	0C	S39	D115	D116	D117	26
S14	D40	D41	D42	0D	S40	D118	D119	D120	27
S15	D43	D44	D45	0E	COM4/S41	D121	D122	D123	28
S16	D46	D47	D48	0F	KS1/S42	D124	D125	D126	29
S17	D49	D50	D51	10	KS2/S43	D127	D128	D129	2A
S18	D52	D53	D54	11	KS3/S44	D130	D131	D132	2B
S19	D55	D56	D57	12	KS4/S45	D133	D134	D135	2C
S20	D58	D59	D60	13	KS5/S46	D136	D137	D138	2D
S21	D61	D62	D63	14	KS6/S47	D139	D140	D141	2E
S22	D64	D65	D66	15	KI1/S48	D142	D143	D144	2F
S23	D67	D68	D69	16	KI2/S49	D145	D146	D147	30
S24	D70	D71	D72	17	KI3/S50	D148	D149	D150	31
S25	D73	D74	D75	18	KI4/S51	D151	D152	D153	32
S26	D76	D77	D78	19	KI5/S52	D154	D155	D156	33

(Note5) In case of S1/P1~S4/P4, COM4/S41, KS1/S42~KS6/S47 and KI1/S48~KI5/S52 are selected for segment output.

For example, S11 output case

Bi	ts in a DDR/	AM	Segment Output Pin (S11)							
D31	D32	D33								
0	0	0	Off-state of the LCD elements corresponding to COM1, 2 and 3							
0	0	1	On-state of the LCD element corresponding to COM3							
0	1	0	On-state of the LCD element corresponding to COM2							
0	1	1	On-state of the LCD elements corresponding to COM2 and 3							
1	0	0	On-state of the LCD element corresponding to COM1							
1	0	1	On-state of the LCD elements corresponding to COM1 and 3							
1	1	0	On-state of the LCD elements corresponding to COM1 and 2							
1	1	1	On-state of the LCD elements corresponding to COM1, 2 and 3							

1/4 duty											
output terminal	COM1	COM2	COM3	COM4	Address	output terminal	COM1	COM2	СОМЗ	COM4	address
S1/P1	D1	D2	D3	D4	00	S27	D105	D106	D107	D108	1A
S2/P2	D5	D6	D7	D8	01	S28	D109	D110	D111	D112	1B
S3/P3	D9	D10	D11	D12	02	S29	D113	D114	D115	D116	1C
S4/P4	D13	D14	D15	D16	03	S30	D117	D118	D119	D120	1D
S5	D17	D18	D19	D20	04	S31	D121	D122	D123	D124	1E
S6	D21	D22	D23	D24	05	S32	D125	D126	D127	D128	1F
S7	D25	D26	D27	D28	06	S33	D129	D130	D131	D132	20
S8	D29	D30	D31	D32	07	S34	D133	D134	D135	D136	21
S9	D33	D34	D35	D36	08	S35	D137	D138	D139	D140	22
S10	D37	D38	D39	D40	09	S36	D141	D142	D143	D144	23
S11	D41	D42	D43	D44	0A	S37	D145	D146	D147	D148	24
S12	D45	D46	D47	D48	0B	S38	D149	D150	D151	D152	25
S13	D49	D50	D51	D52	0C	S39	D153	D154	D155	D156	26
S14	D53	D54	D55	D56	0D	S40	D157	D158	D159	D160	27
S15	D57	D58	D59	D60	0E	KS1/S42	D161	D162	D163	D164	28
S16	D61	D62	D63	D64	0F	KS2/S43	D165	D166	D167	D168	29
S17	D65	D66	D67	D68	10	KS3/S44	D169	D170	D171	D172	2A
S18	D69	D70	D71	D72	11	KS4/S45	D173	D174	D175	D176	2B
S19	D73	D74	D75	D76	12	KS5/S46	D177	D178	D179	D180	2C
S20	D77	D78	D79	D80	13	KS6/S47	D181	D182	D183	D184	2D
S21	D81	D82	D83	D84	14	KI1/S48	D185	D186	D187	D188	2E
S22	D85	D86	D87	D88	15	KI2/S49	D189	D190	D191	D192	2F
S23	D89	D90	D91	D92	16	KI3/S50	D193	D194	D195	D196	30
S24	D93	D94	D95	D96	17	KI4/S51	D197	D198	D199	D200	31
S25	D97	D98	D99	D100	18	KI5/S52	D201	D202	D203	D204	32
S26	D101	D102	D103	D104	19		•				

(Note6) In case of S1/P1~S4/P4, KS1/S42~KS6/S47 and KI1/S48~KI5/S52 are selected for segment output.

# For example, S11 output case

	Bits in the DDRAM			Segment Output Pin (S11)			
D41	D42	D43	D44	Gegment Output Fin (GTT)			
0	0	0	0	Off-state of the LCD elements corresponding to COM1,2,3 and4			
0	0	0	1	On-state of the LCD element corresponding to COM4			
0	0	1	0	On-state of the LCD element corresponding to COM3			
0	0	1	1	On-state of the LCD elements corresponding to COM3 and 4			
0	1	0	0	On-state of the LCD element corresponding to COM2			
0	1	0	1	On-state of the LCD elements corresponding to COM2 and 4			
0	1	1	0	On-state of the LCD elements corresponding to COM2 and 3			
0	1	1	1	On-state of the LCD elements corresponding to COM2,3 and 4			
1	0	0	0	On-state of the LCD element corresponding to COM1			
1	0	0	1	On-state of the LCD elements corresponding to COM1 and 4			
1	0	1	0	On-state of the LCD elements corresponding to COM1 and 3			
1	0	1	1	On-state of the LCD elements corresponding to COM1, 3 and 4			
1	1	0	0	On-state of the LCD elements corresponding to COM1 and 2			
1	1	0	1	On-state of the LCD elements corresponding to COM1,2 and 4			
1	1	1	0	On-state of the LCD elements corresponding to COM1,2 and 3			
1	1	1	1	On-state of the LCD elements corresponding to COM1,2 3 and 4			

## Serial Data Output



## Figure 9. Serial Data Output

KD1 to KD30: Key Data SA: Sleep Acknowledge Data Key Data Read Command (KEY RD): 1000\_0101 (Note7) If a key data operation is executed when DO is high, the read key data (KD1 to KD30) and sleep acknowledge data(SA) will be invalid.

## Output Data

## KD1 to KD30: Key Data

When a key matrix of up to 30 keys is formed from the KS1 to KS6 output pins and the KI1 to KI5 input pins and one of those keys is pressed, the key output data corresponding to that key will be set to 1. The table shows the relationship between those pins and the key data bits.

	KI1	KI2	KI3	KI4	KI5
KS1	KD1	KD2	KD3	KD4	KD5
KS2	KD6	KD7	KD8	KD9	KD10
KS3	KD11	KD12	KD13	KD14	KD15
KS4	KD16	KD17	KD18	KD19	KD20
KS5	KD21	KD22	KD23	KD24	KD25
KS6	KD26	KD27	KD28	KD29	KD30

## SA: Sleep Acknowledge Data

This output data is used to set the state when the key is pressed. In this case, DO will go to the low level. If serial data is input during this period and the mode is set (normal mode or sleep mode), the IC will be set to that mode. SA is set to 0 in the sleep mode and to 1 in the normal mode.

Key Scan Operation Key Scan Timing

The key scan period is 288T(s). To reliably determine the on/off state of the keys, the BU97501KV scans the keys twice and determines that a key has been pressed when the key data agrees. It outputs a key data read request (a low level on DO) 615T(s) after starting a key scan. If the key data does not agree and a key is pressed at that point, it scans the keys again. Thus, BU97501KV cannot detect a key press shorter than 615T(s).





## Normal Mode

## KS1/S42 - KS6/S47 pins are set high.

When a key is pressed, a key scan is started and the keys are scanned until all keys are released. Multiple key presses are recognized by determining whether multiple key data bits are set.

If a key is pressed for longer than 615 T(s) (Where T=1/fosc (When External clock input, fosc is a quarter of external clock)), the BU97501KV outputs a key data read request (a low level on DO) to the controller. The controller acknowledges this request and reads the key data. However, if CSB is "L" during a serial data transfer, DO will be set high.

After the controller reads the key data, the key data read request is cleared (DO is set high) and BU97501KV performs another key scan. Also note that DO can be controlled to be an open-drain output or a CMOS output. If set to be an open-drain output, a pull-up resistor (between 1 and  $10K\Omega$ ) is required.





## Sleep Mode

KS1/S42 - KS6/S47 pins are set high or low by SLP CTRL P3,P2 data. (Refer to the SLP CTRL description).

If a key on one of the lines corresponding to a KS1 to KS6 pin which is set high is pressed, the oscillator on the OSC pin is started and a key scan is performed. Keys are scanned until all keys are released. Multiple key presses are recognized by determining whether multiple key data bits are set.

If a key is pressed for longer than 615T(s)(Where T=1/fosc (When External clock input, fosc is a quarter of external clock)) the BU97501KV outputs a key data read request (a low level on DO) to the controller. The controller acknowledges this request and reads the key data. However, if CSB is "L" during a serial data transfer, DO will be set high.

After the controller reads the key data, the key data read request is cleared (DO is set high) and the BU97501KV performs another key scan. However, this does not clear sleep mode. Also note that DO can be controlled to be an open-drain output or a CMOS output. During open-drain output selection, DO is an open-drain output so a pull-up resistor (between 1 K $\Omega$  and 10K $\Omega$ ) is required.

#### Sleep mode key scan example

Example: when SLP CTRL P3= [0], P2= [1] (sleep with only KS6 high)



(Note8) These diodes are required to reliably recognize multiple key presses on the KS6 line when sleep mode state with only KS6 high, as in the above example. That is, these diodes prevent incorrect operations due to sneak currents in the KS6 key scan output signal when keys on the KS1 to KS5 lines are pressed at the same time.





## Multiple Key Presses

Although the BU97501KV is capable of key scanning without inserting diodes for dual key presses, triple key presses on the KI1 to KI5 input pin lines, or multiple key presses on the KS1 to KS6 output pin lines, multiple presses other than these cases may result in keys that were not pressed recognized as having been pressed. Therefore, a diode must be inserted in series with each key. Applications that do not recognize multiple key presses of three or more keys should check the key data for three or more 1 bit and ignore such data.

## OSCILLATOR

Several kinds of clock for logic and analog circuits are generated from internal oscillation circuit or external clock. The OSC pins are open if the internal oscillator is used.

(Note9) To use external clock mode, please set in DRV CTRL1 command.





Figure 13. Internal clock mode



# LCD Driver Bias/Duty Circuit

This LSI generates LCD driving voltage with on-chip Buffer AMP.

And it can drive LCD at low power consumption. \* 1/3 or 1/2Bias and line or frame inversion mode can be selected by DRV CTRL2.

- \* 1/4 or 1/3Duty can be selected by DRV CTRL1 command.
- Refer to "LCD waveform" about each LCD waveform.

# LCD waveform



Figure 15. LCD waveform in line inversion

Figure 16. LCD waveform in frame inversion

1/4duty, 1/2bias Line inversion



Figure 17. LCD waveform in line inversion

Figure 18. LCD waveform in frame inversion



Figure 19. LCD waveform in line inversion

Figure 20. LCD waveform in frame inversion

1/3duty, 1/2bias Line inversion

Frame inversion



Figure 21. LCD waveform in line inversion

Figure 22. LCD waveform in frame inversion

# Command Table

Command.	BIN								Descriptions	
Command.	D7	D6	D5	D4	D3	D2	D1	D0	Descriptions	
SLP CTRL	1	0	0	1	P3	P2	*	*	Sleep Control	
SEG CTRL	1	0	1	1	P3	P2	P1	*	Segment Control	
DRV CTRL1	1	1	0	0	P3	P2	P1	0	Drive Control1 (Duty Set, OSC Control)	
DRV CTRL2	1	1	0	1	0	P2	P1	0	Drive Control2 (Bias Set, Inversion Mode)	
DRV CTRL3	1	0	1	0	P3	P2	*	P0	Drive Control3 (Keyscan Output Set, DO Set)	
KEY RD	1	0	0	0	0	1	0	1	Key Data Read	
SWRST	1	1	1	1	0	0	0	1	Software Reset	
DISCTRL	1	1	1	1	1	0	P1	*	Display Control (Display On/Off)	
ADSET	0	1	P5	P4	P3	P2	P1	P0	Address Set	
DATA WR	0	0	0	0	1	0	1	0	Data Write	

(\* : Don't care)

# **Detailed command description**

Sleep Control (SLP CTRL)

MSB							LSB			
D7	D6	D5	D4	D3	D2	D1	D0			
1	0	0	1	P3	P2	*	*			
(* : Do	(* : Don't care)									

P3, P2: Normal mode/Sleep mode switching control data

These control data bits select Key Scan Output Pins KS1 to KS6 States of during Key Scan Standby.

	ntrol bits	Mode Intern		Segment outputs/Common	Output Pin States During Key Scan Standby						Reset Conditions
P3	P2		000	Outputs	KS1	KS2	KS3	KS4	KS5	KS6	
0	0	Normal	enabled	Operating	Н	Н	Н	Н	Н	Н	
0	1	Sleep			L	L	L	L	L	Н	0
1	0	Sleep	disabled	Low(VSS)	L	L	L	L	Н	Н	
1	1	Sleep			Н	Н	H	Н	Н	Н	

(Note10) When DRV CTRL3 (P3, P2) = (1, 1), KS1 to KS6 outputs are selected as Segment outputs.

## Segment Control (SEG CTRL)

MSB							LSB			
D7	D6	D5	D4	D3	D2	D1	D0			
1	0	1	1	P3	P2	P1	*			
(* . D -	(* · D · · · ?+ · · · · · )									

(\* : Don't care)

P3 to P1 : Segment Output / General purpose output switching control data These control bits select the function of the S1/P1 to S4/P4 output pins. (Segment Output Pins or General Purpose Output Pins).

Co	Control bits			Status of	Reset conditions		
P3	P2	P1	S1/P1	S2/P2	S3/P3	S4/P4	
0	0	0	S1	S2	S3	S4	0
0	0	1	P1	S2	S3	S4	
0	1	0	P1	P2	S3	S4	
0	1	1	P1	P2	P3	S4	
1	0	0	P1	P2	P3	P4	

assigned as a Segment Output pin (Note11) Sn(n=1 to 4) Pn(n=1 to 4) : assigned as a General Purpose Output pin

Relationship of bit assignment between general purpose output pin and bit in DDRAM

Output Pin	Corresponding bit in DDRAM				
	1/3 Duty	1/4 Duty			
S1/P1	D1	D1			
S2/P2	D4	D5			
S3/P3	D7	D9			
S4/P4	D10	D13			

In case of 1/4 Duty mode and S4/P4 is configured as a general purpose output pins. S4/P4 is set to HIGH (VLCD level) if D13 is set to "1" in DDRAM. S4/P4 is cleared to LOW (VSS level) if D13 is set to "0" in DDRAM.

Drive Control1 (DRV CTRL1)

MSB							LSB
D7	D6	D5	D4	D3	D2	D1	D0
1	1	0	0	P3	P2	P1	0

P3: 1/3 duty drive or 1/4 duty drive switching control data This control data bit selects either 1/3 duty drive or 1/4 duty drive.

THIS C	This control data bit selects either 1/3 duty drive of 1/4 dut									
P3	Duty mode	Status of (COM4/ S41)	Reset conditions							
0	1/4	COM4	0							
1	1/3	S41								

(Note12) COM4: COMMON output

S41: SEGMENT output

P2,P1 : Frame frequency switching control data These control data bits select Frame frequency setting.

Setting	P2	P1	Reset conditions
80Hz	0	0	0
100Hz	0	1	
120Hz	1	0	
External Clock input	1	1	

Relationships between Frame frequency (fFR) and Divide number

P2	P1	Divide	number	fFR [Hz]		
		1/3 Duty	1/4 Duty	1/3 Duty	1/4 Duty	
0	0	510	512	80	80	
0	1	408	408	100	100	
1	0	342	344	120	120	
1	1	2040	2048	-	-	

Formula to calculate Frame frequency from frequency and Divide number: "Frame frequency = frequency / Divide number"

Ex) In case, 1/4 Duty mode, (P2, P1) = (0, 0)fFR = 40.96[KHz] / 512 = 80[Hz] (Note13) Built-in Oscillator circuit frequency = 40.96 KHz (typ).

## Drive Control2 (DRV CTRL2)

MSB LSB D7 D6 D5 D4 D3 D2 D1 D0 P1 1 1 0 1 0 P2 0

P2: 1/3 bias drive or 1/2 bias drive switching control data This control data bit selects either 1/3 bias drive or 1/2 bias drive.

P2	Bias mode	Reset conditions
0	1/2	
1	1/3	0

P1: Line Inversion or Frame Inversion switching control data

This control data bit selects either line inversion drive or frame inversion drive.

P1	Inversion mode	Reset conditions
0	Line	0
1	Frame	

Drive Control3 (DRV CTRL3)

.....

	MSB							LSB
	D7	D6	D5	D4	D3	D2	D1	D0
	1	0	1	0	P3	P2	*	P0
2	(.h. D.	1.	1					

(\* : Don't care)

P3 to P2: Key Scan output port/Segment output port switching control data These control data bits select Key Scan outputs or Segment outputs.

Control Bits				Output F		Maximum Number of	Reset		
P3	P2	KS1/ S42	KS2/ S43	KS3/ S44	KS4/ S45	KS5/ S46	KS6/ S47	Input keys	Conditions
0	0	KS1	KS2	KS3	KS4	KS5	KS6	30	
0	1	S42	KS2	KS3	KS4	KS5	KS6	25	
1	0	S42	S43	KS3	KS4	KS5	KS6	20	
1	1	S42	S43	S44	S45	S46	S47	0	0

When (P3,P2)=(1,1), Keyscan doesn't function. Key scan pins are all segment outputs. Thus, maximum segment display number and RAM last address change based on this value

Co	ntrol	Status of Pins						Segment Number	Last Address		
P3	P2	KS1/ S42	KS2/ S43	KS3/ S44	KS4/ S45	KS5/ S46	KS6/ S47	1/3 Duty	1/4 Duty	1/3 Duty	1/4 Duty
0	0	KS1	KS2	KS3	KS4	KS5	KS6	123	160	28h	27h
0	1	S42	KS2	KS3	KS4	KS5	KS6	126	164	29h	28h
1	0	S42	S43	KS3	KS4	KS5	KS6	129	168	2Ah	29h
1	1	S42	S43	S44	S45	S46	S47	156	204	33h	32h

P0: Output setting for DO

This control data bit selects either open drain output or CMOS output.

P0	Setting	Reset Conditions
0	open drain output	0
1	CMOS output	

Pull up resistor  $(1k\Omega - 10k\Omega)$  is required when selecting Open Drain Output setting for DO. Be careful the Pull up voltage not to be higher than VDD voltage.

Key Data Read (KEY RD)

MSB							
D7	D6	D5	D4	D3	D2	D1	D0
1	0	0	0	0	1	0	1

## Display Control (DISCTRL)

MSB							LSB	
D7	D6	D5	D4	D3	D2	D1	D0	
1	1	1	1	1	0	P1	*	

(\* : Don't care)

P1: Segment on/off control data

This control data bit controls the on/off state of the segments.

P1	Display status	Reset conditions
1	ON	
0	OFF	0

Software Reset (SWRST)

NΛ	c	D	
ινι	J	D	

MSB							
D7	D6	D5	D4	D3	D2	D1	D0
1	1	1	1	0	0	0	1

This is the Software Reset command.

After sending this command, each register, DDRAM data and DDRAM address are initialized.

Address Set (ADSET)

MSB							LSB
D7	D6	D5	D4	D3	D2	D1	D0
0	1	P5	P4	P3	P2	P1	P0

Address which could be set starts from 00(Hex) until RAM last address. Setting of values other than the above is not allowed. (Otherwise, address is set to 0.) Refer to "Display Data Transfer Method" for RAM last address.

Data Write (DATAWR)

MSB							LSB
D7	D6	D5	D4	D3	D2	D1	D0
0	0	0	0	1	0	1	0

Data transfer can be started by this command. Set the CSB pin to High to terminate the data transfer. Refer to "Command and Data Transfer Method".

## Initialize sequence

Recommended sequence after Power-On to set this device to initial condition.

Software reset sequence	Hardware reset sequence				
Power on	Power on				
CSB 'H' …Initialized I/F	RESB 'L'				
CSB 'L'Start transferring I/F Data	RESB 'H'				
↓ SWRST (execute Software Reset)	CSB <sup>↓</sup> 'H' …Initialized I/F				
DISCTRL (Display off)	CSB 'L'Start transferring I/F Data				
Set each Command	↓ SWRST (execute Software Reset)				
DATA WR	↓ DISCTRL (Display off)				
CSB 'H'	↓ Set each Command				
CSB 'L'	JATA WR				
	CSB 'H'				
↓ DISCTRL (Display on)	↓ CSB 'L'				
↓ Start display	↓ SLP CTRL				
	$\downarrow$ DISCTRL (Display on)				
	↓ Start display				

(Note14) Each register value, DDRAM address and DDRAM data are random condition after power on till initialize sequence is executed. (Note15) Each register value, DDRAM address are reset by a hardware reset operation.

# **Cautions in Power-On Sequence**

Power-On Reset (POR) Circuit

This LSI has "P.O.R" (Power-On Reset) circuit and Software Reset function. When the power is ON, IC internal circuit and reset pass through unstable low-voltage region. Internal IC is not totally reset because VDD rises and this may result to malfunction. Thus, POR circuit and function of software reset are installed in order to prevent this. Please follow the following recommended Power-On sequences to allow the reset action to complete.

Set the power up conditions to meet the recommended tR, tF, tOFF, and Vbot spec below in order to ensure P.O.R operation.



Figure 23. Power ON/OFF waveform

If it is difficult to meet above conditions, execute the following sequence after Power-On.

- (1) Set CSB to High
- (2) Clear CSB to Low and then issue a SWRST command.



# Figure 24. SWRST Command Sequence

Power Up Sequence and Power Down Sequence To prevent the malfunction, in power up sequence, VDD shall be turned on before VLCD. In power down sequence, VDD shall be turned off after VLCD. Please satisfies VLCD≥VDD, t1≧0ns t1 t1



Figure 25. Power On/Off Sequence

## DISPLAY DDRAM DATA EXAMPLE

If LCD layout pattern is shown as in Figure 26 and 27 and DDRAM data is shown as in Table2, display pattern will be shown as in Figure 28.



Figure 26. Example COM Line pattern



Figure 27. Example of SEG Line pattern



Figure 28. Example of display pattern

		S 1	S 2	S 3	S 4	S 5	S 6	S 7	S 8	S 9	S 10	S 11	S 12	S 13	S 14	S 15	S 16	S 17	S 18	S 19	S 20
COM1	D0	1	1	0	1	1	1	1	0	1	1	0	0	0	0	0	0	0	0	0	0
COM2	D1	0	1	1	1	0	0	1	0	1	0	0	0	0	0	0	0	0	0	0	0
COM3	D2	0	0	1	0	1	0	0	1	1	1	0	0	0	0	0	0	0	0	0	0
COM4	D3	0	1	1	0	0	0	1	0	1	0	0	0	0	0	0	0	0	0	0	0
Address		00h	01h	02h	03h	04h	05h	06h	07h	08h	09h	0Ah	0Bh	0Ch	0Dh	0Eh	0Fh	10h	11h	12h	13h
	Table 0. DDDAM Date man																				

Table 2. DDRAM Data map

## **Operational Notes**

## 1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply terminals.

## 2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

## 3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

## 4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

## 5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. The absolute maximum rating of the Pd stated in this specification is when the IC is mounted on a 70mm x 70mm x 1.6mm glass epoxy board. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

## 6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

## 7. Rush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

## 8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

## 9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

## 10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

## 11. Unused Input Terminals

Input terminals of an IC are often connected to the gate of a MOS transistor (CMOS?). The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input terminals should be connected to the power supply or ground line.

## 12. Regarding the Input Pin of the IC

In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the ground voltage should be avoided. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input terminals have voltages within the values specified in the electrical characteristics of this IC.

## 13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

## 14. Area of Safe Operation (ASO)

Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

## 15. Thermal Shutdown Circuit(TSD)

This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's power dissipation rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

## 16. Over Current Protection Circuit (OCP)

This IC incorporates an integrated overcurrent protection circuit that is activated when the load is shorted. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation or transitioning of the protection circuit.

# **Ordering Information**



## Marking Diagram(s)(TOP VIEW)



Physical Dimension, Tape and Reel Information



Version / Revision History

Version	date	description						
001	07. Aug. 2013	1 <sup>st</sup> ver						
002	07. Nov. 2013	Page.4 Add Electrical Characteristics of External Clock Frequency						
003	31. Jan. 2014	Page.2 Modify Pin Description OSC, DO, RESB, VSS and S1/P1~S4/P4 Functions   Page.3 Modify Absolute Maximum Ratings Power Dissipation   Page.3 Modify Electrical Characteristics precondition   Page.3 Modify Electrical Characteristics ELOB Bias Voltage VMID1 Conditions   Page.4 Modify Electrical Characteristics ELOB Bias Voltage VMID1 Conditions   Page.4 Modify Flectrical Characteristics ELOB Bias Voltage VMID1 Conditions   Page.4 Modify Pul Interface Characteristics VDD condition   Page.4 Modify MPU Interface Characteristics tCHW Parameter name   Page.5 Modify Command and Data Transfer Method description   Page.6 Modify Command Transfer Method description   Page.6 Modify Command Transfer Method description   Page.10 Modify Key Scan Operation description   Page.11 Modify Key Scan Operation description   Page.13 Minor translation change Sleep Control command description to have more conformity between Japanese and English version   Page.20 Minor translation change Drive Control1 command description to have more conformity between Japanese and English version   Page.21 Minor translation change Drive Control2 command description to have more conformity between Japanese and English version   Page.21 Minor translation change Drive Cont						
004	11.Apr.2014	Page.12Add fosc explanation when External clock inputPage.24Add the condition when power up and power down						

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  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

## Precaution for Mounting / Circuit board design

- 1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

## **Precautions Regarding Application Examples and External Circuits**

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  - [d] the Products are exposed to high Electrostatic
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Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



#### Как с нами связаться

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