
HM5164405F Series HM5165405F Series

64 M EDO DRAM (16-Mword $\times$ 4-bit)
8 k Refresh/4 k Refresh

ELPIDA

E0097H10 (1st edition)
(Previous ADE-203-1056C (Z))
Jan. 31, 2001

Description

The HM5164405F Series, HM5165405F Series are 64M-bit dynamic RAMs organized as 16,777,216-word $\times$ 4-bit. They have realized high performance and low power by employing CMOS process technology. HM5164405F Series, HM5165405F Series offer Extended Data Out (EDO) Page Mode as a high speed access mode. They have the package variation of standard 32-pin plastic SOJ and standard 32-pin plastic TSOPII.

Features

- Single 3.3 V supply: 3.3 V $\pm$ 0.3 V
- Access time: 50 ns/60 ns (max)
- Power dissipation
 - Active: 396 mW/360 mW (max) (HM5164405F Series)
: 468 mW/396 mW (max) (HM5165405F Series)
 - Standby : 1.8 mW (max) (CMOS interface)
: 1.1 mW (max) (L-version)
- EDO page mode capability
- Refresh cycles
 - $\overline{\text{RAS}}$ -only refresh
8192 cycles/64 ms (HM5164405F, HM5164405FL)
4096 cycles/64 ms (HM5165405F, HM5165405FL)
 - CBR/Hidden refresh
4096 cycles/64 ms (HM5164405F, HM5164405FL, HM5165405F, HM5165405FL)

HM5164405F Series, HM5165405F Series

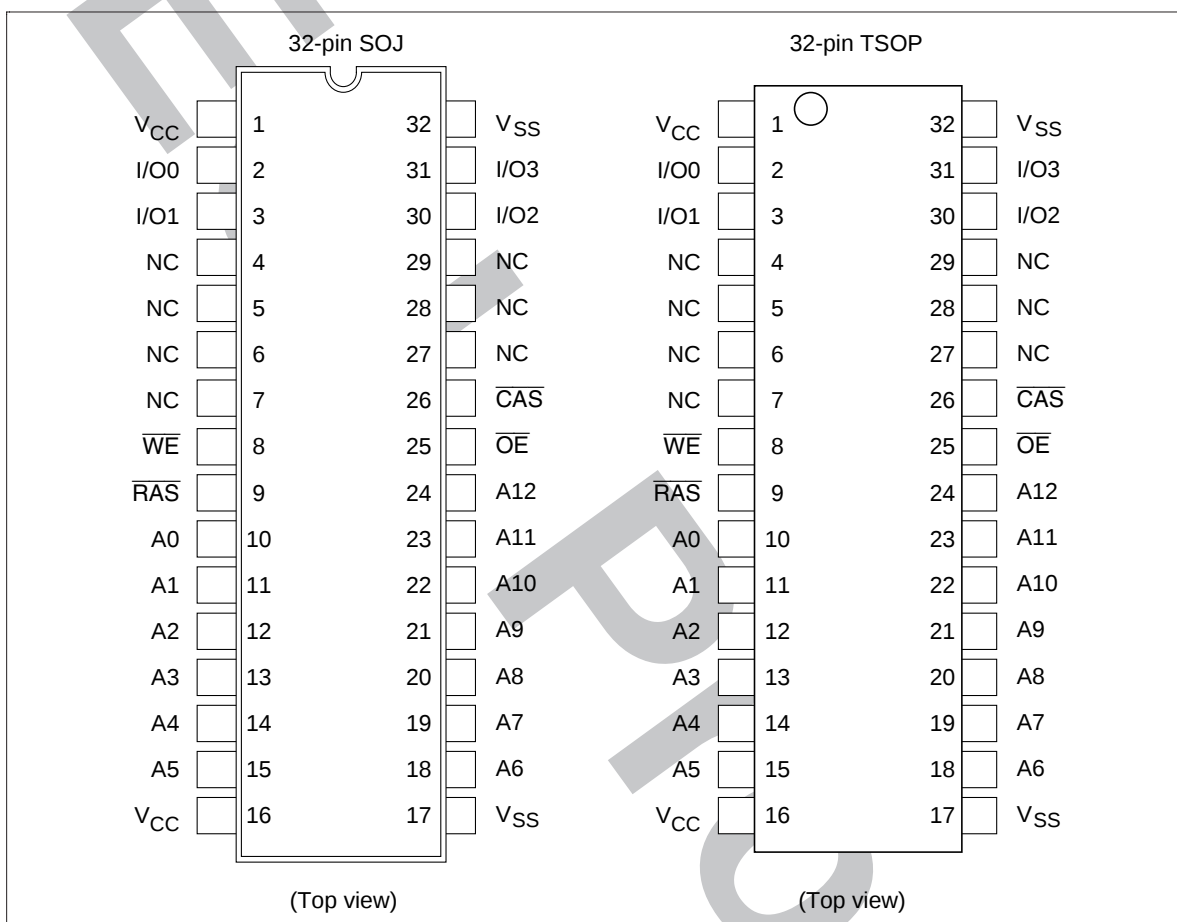
- 4 variations of refresh
 - $\overline{\text{RAS}}$ -only refresh
 - $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh
 - Hidden refresh
 - Self refresh (L-version)
- Battery backup operation (L-version)

Ordering Information

Type No.	Access time	Package
HM5164405FJ-5	50 ns	400-mil 32-pin plastic SOJ (CP-32DC)
HM5164405FJ-6	60 ns	
HM5164405FLJ-5	50 ns	
HM5164405FLJ-6	60 ns	
HM5165405FJ-5	50 ns	
HM5165405FJ-6	60 ns	
HM5165405FLJ-5	50 ns	
HM5165405FLJ-6	60 ns	
HM5164405FTT-5	50 ns	400-mil 32-pin plastic TSOP II (TTP-32DC)
HM5164405FTT-6	60 ns	
HM5164405FLT-5	50 ns	
HM5164405FLT-6	60 ns	
HM5165405FTT-5	50 ns	
HM5165405FTT-6	60 ns	
HM5165405FLT-5	50 ns	
HM5165405FLT-6	60 ns	

HM5164405F Series, HM5165405F Series

Pin Arrangement (HM5164405F Series)

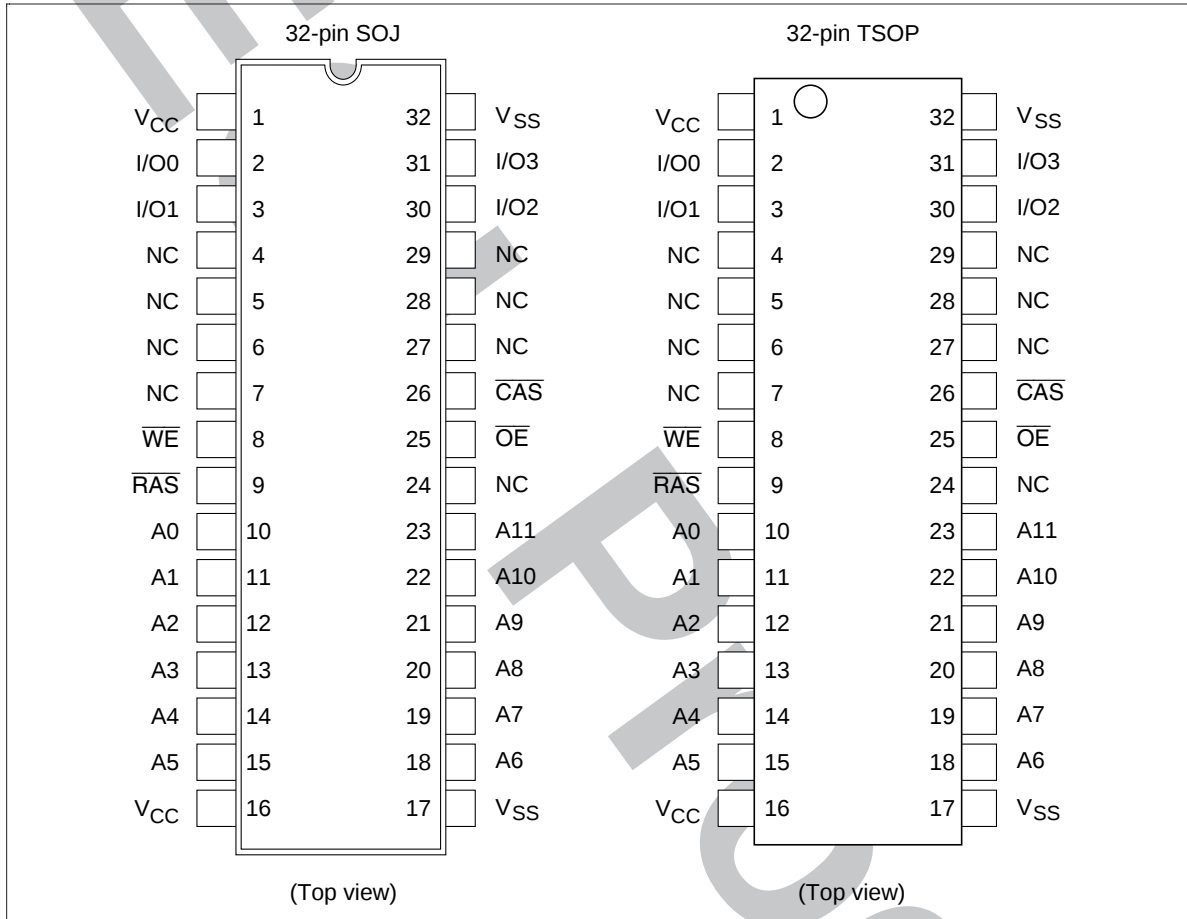


Pin Description

Pin name	Function
A0 to A12	Address input — Row/Refresh address A0 to A12 — Column address A0 to A10
I/O0 to I/O3	Data input/output
RAS	Row address strobe
CAS	Column address strobe
WE	Write enable
OE	Output enable
V _{CC}	Power supply
V _{SS}	Ground
NC	No connection

HM5164405F Series, HM5165405F Series

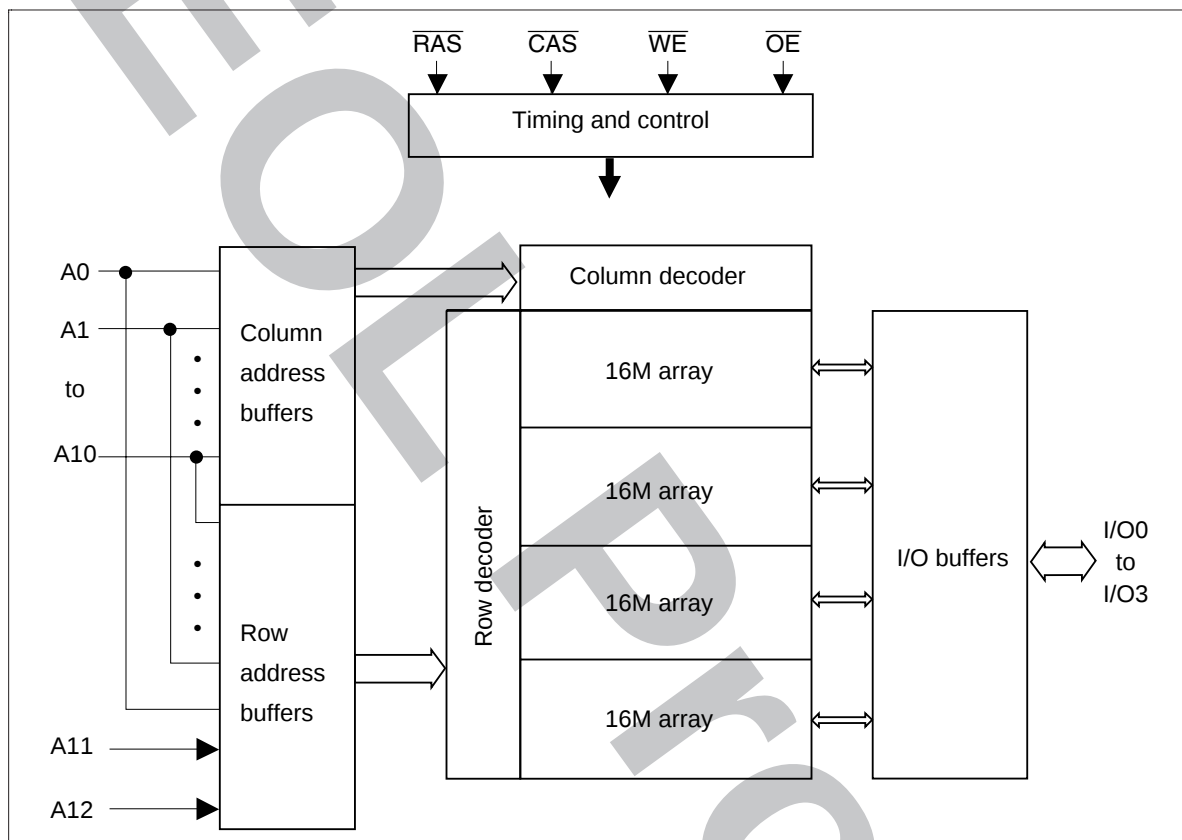
Pin Arrangement (HM5165405F Series)



Pin Description

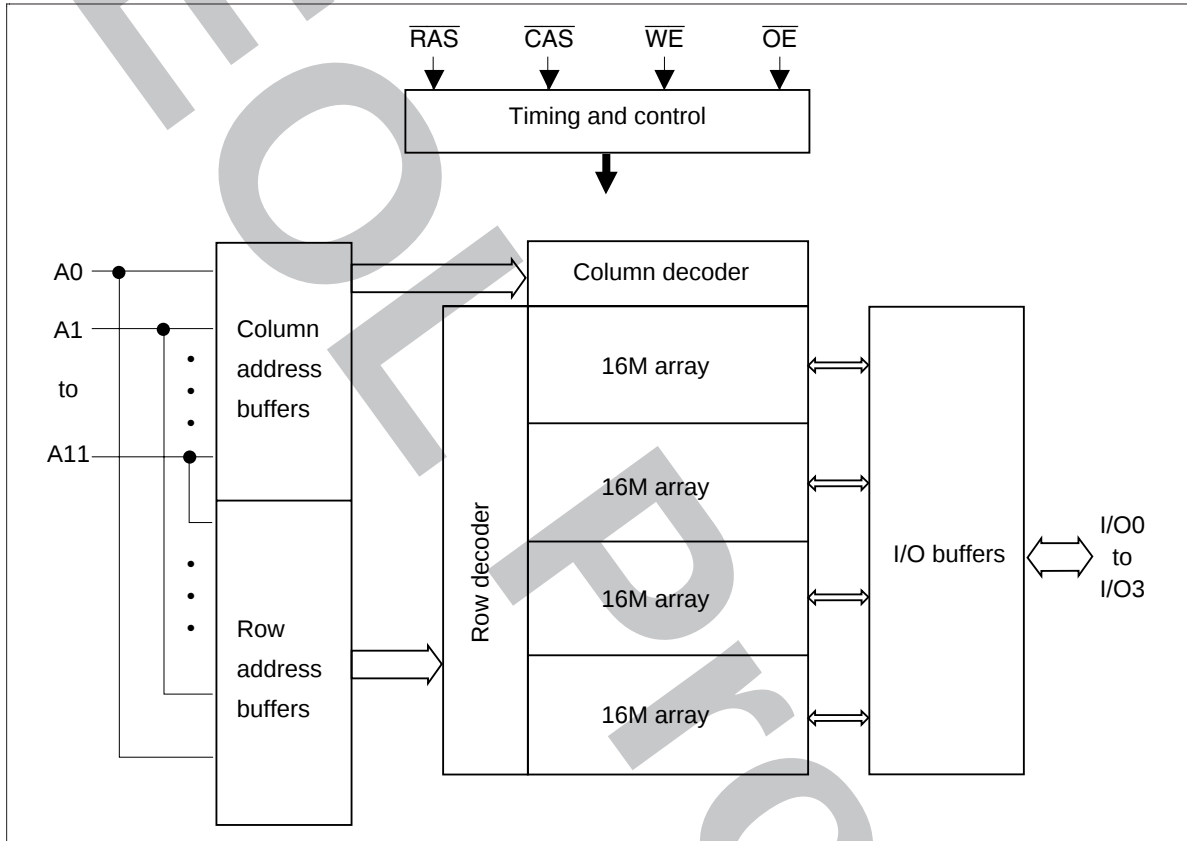
Pin name	Function
A0 to A11	Address input — Row/Refresh address A0 to A11 — Column address A0 to A11
I/O0 to I/O3	Data input/output
RAS	Row address strobe
CAS	Column address strobe
WE	Write enable
OE	Output enable
V _{cc}	Power supply
V _{ss}	Ground
NC	No connection

Block Diagram (HM5164405F Series)



HM5164405F Series, HM5165405F Series

Block Diagram (HM5165405F Series)



HM5164405F Series, HM5165405F Series

Operation Table

$\overline{\text{RAS}}$	$\overline{\text{CAS}}$	$\overline{\text{WE}}$	$\overline{\text{OE}}$	I/O 0 to I/O 3	Operation
H	x	x	x	High-Z	Standby
L	L	H	L	Dout	Read cycle
L	L	L* ²	x	Din	Early write cycle
L	L	L* ²	H	Din	Delayed write cycle
L	L	H to L	L to H	Dout/Din	Read-modify-write cycle
L	H	x	x	High-Z	$\overline{\text{RAS}}$ -only refresh cycle
H to L	L	H	x	High-Z	$\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh cycle or Self refresh cycle (L-version)
L	L	H	H	High-Z	Read cycle (Output disabled)

Notes: 1. H: V_{IH} (inactive), L: V_{IL} (active), x: V_{IH} or V_{IL}

2. $t_{WCS} \geq 0$ ns: Early write cycle

$t_{WCS} < 0$ ns: Delayed write cycle

Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Terminal voltage on any pin relative to V_{SS}	V_T	-0.5 to $V_{CC} + 0.5$ (≤ 4.6 V (max))	V
Power supply voltage relative to V_{SS}	V_{CC}	-0.5 to +4.6	V
Short circuit output current	I_{out}	50	mA
Power dissipation	P_T	1.0	W
Storage temperature	Tstg	-55 to +125	°C

DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit	Notes
Supply voltage	V_{CC}	3.0	3.3	3.6	V	1, 2
	V_{SS}	0	0	0	V	2
Input high voltage	V_{IH}	2.0	—	$V_{CC} + 0.3$	V	1
Input low voltage	V_{IL}	-0.3	—	0.8	V	1
Ambient temperature range	Ta	0	—	70	°C	

Notes: 1. All voltage referred to V_{SS} .

2. The supply voltage with all V_{CC} pins must be on the same level. The supply voltage with all V_{SS} pins must be on the same level.

HM5164405F Series, HM5165405F Series

DC Characteristics (HM5164405F Series)

Parameter	Symbol	HM5164405F				Unit	Test conditions
		-5	-6	Min	Max		
Operating current ^{*1, *2}	I_{CC1}	—	110	—	100	mA	$t_{RC} = \min$
Standby current	I_{CC2}	—	2	—	2	mA	TTL interface $\overline{RAS}, \overline{CAS} = V_{IH}$ Dout = High-Z
		—	0.5	—	0.5	mA	CMOS interface $\overline{RAS}, \overline{CAS} \geq V_{CC} - 0.2 V$ Dout = High-Z
Standby current (L-version)	I_{CC2}	—	300	—	300	μA	CMOS interface $\overline{RAS}, \overline{CAS} \geq V_{CC} - 0.2 V$ Dout = High-Z
RAS-only refresh current ^{*2}	I_{CC3}	—	110	—	100	mA	$t_{RC} = \min$
Standby current ^{*1}	I_{CC5}	—	5	—	5	mA	$\overline{RAS} = V_{IH}, \overline{CAS} = V_{IL}$ Dout = enable
CAS-before-RAS refresh current	I_{CC6}	—	110	—	100	mA	$t_{RC} = \min$
EDO page mode current ^{*1, *3}	I_{CC7}	—	110	—	100	mA	$\overline{RAS} = V_{IL}, \overline{CAS}$ cycle, $t_{HPC} = t_{HPC} \min$
Battery backup current ^{*4} (Standby with CBR refresh) (L-version)	I_{CC10}	—	1.2	—	1.2	mA	CMOS interface Dout = High-Z CBR refresh: $t_{RC} = 15.6 \mu s$ $t_{RAS} \leq 0.3 \mu s$
Self refresh mode current (L-version)	I_{CC11}	—	500	—	500	μA	CMOS interface $\overline{RAS}, \overline{CAS} \leq 0.2 V$ Dout = High-Z
Input leakage current	I_{LI}	-5	5	-5	5	μA	$0 V \leq V_{in} \leq V_{CC} + 0.3 V$
Output leakage current	I_{LO}	-5	5	-5	5	μA	$0 V \leq V_{out} \leq V_{CC}$ Dout = disable
Output high voltage	V_{OH}	2.4	V_{CC}	2.4	V_{CC}	V	High Iout = -2 mA
Output low voltage	V_{OL}	0	0.4	0	0.4	V	Low Iout = 2 mA

Notes: 1. I_{CC} depends on output load condition when the device is selected. $I_{CC} \max$ is specified at the output open condition.

2. Address can be changed once or less while $\overline{RAS} = V_{IL}$.

3. Measured with one sequential address change per EDO cycle, t_{HPC} .

4. $V_{IH} \geq V_{CC} - 0.2 V$, $0 V \leq V_{IL} \leq 0.2 V$.

HM5164405F Series, HM5165405F Series

DC Characteristics (HM5165405F Series)

		HM5165405F					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Test conditions
Operating current* ^{1, *2}	I _{CC1}	—	130	—	110	mA	t _{RC} = min
Standby current	I _{CC2}	—	2	—	2	mA	TTL interface RAS, CAS = V _{IH} Dout = High-Z
		—	0.5	—	0.5	mA	CMOS interface RAS, CAS ≥ V _{CC} − 0.2 V Dout = High-Z
Standby current (L-version)	I _{CC2}	—	300	—	300	μA	CMOS interface RAS, CAS ≥ V _{CC} − 0.2 V Dout = High-Z
RAS-only refresh current* ²	I _{CC3}	—	130	—	110	mA	t _{RC} = min
Standby current* ¹	I _{CC5}	—	5	—	5	mA	RAS = V _{IH} , CAS = V _{IL} Dout = enable
CAS-before-RAS refresh current	I _{CC6}	—	130	—	110	mA	t _{RC} = min
EDO page mode current* ^{1, *3}	I _{CC7}	—	110	—	100	mA	RAS = V _{IL} , CAS cycle, t _{HPC} = t _{HPC} min
Battery backup current* ⁴ (Standby with CBR refresh) (L-version)	I _{CC10}	—	1.2	—	1.2	mA	CMOS interface Dout = High-Z CBR refresh: t _{RC} = 15.6 μs t _{RAS} ≤ 0.3 μs
Self refresh mode current (L-version)	I _{CC11}	—	500	—	500	μA	CMOS interface RAS, CAS ≤ 0.2 V Dout = High-Z
Input leakage current	I _{LI}	−5	5	−5	5	μA	0 V ≤ Vin ≤ V _{CC} + 0.3 V
Output leakage current	I _{LO}	−5	5	−5	5	μA	0 V ≤ Vout ≤ V _{CC} Dout = disable
Output high voltage	V _{OH}	2.4	V _{CC}	2.4	V _{CC}	V	High Iout = −2 mA
Output low voltage	V _{OL}	0	0.4	0	0.4	V	Low Iout = 2 mA

Notes: 1. I_{CC} depends on output load condition when the device is selected. I_{CC} max is specified at the output open condition.

2. Address can be changed once or less while $\overline{RAS} = V_{IL}$.

3. Measured with one sequential address change per EDO cycle, t_{HPC} .

4. $V_{IH} \geq V_{CC} - 0.2 V, 0 V \leq V_{IL} \leq 0.2 V$.

HM5164405F Series, HM5165405F Series

Capacitance ($T_a = 25^\circ\text{C}$, $V_{CC} = 3.3\text{ V} \pm 0.3\text{ V}$)

Parameter	Symbol	Typ	Max	Unit	Notes
Input capacitance (Address)	C_{i1}	—	5	pF	1
Input capacitance (Clocks)	C_{i2}	—	7	pF	1
Output capacitance (Data-in, Data-out)	$C_{i/O}$	—	7	pF	1, 2

Notes : 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.

2. $\overline{\text{RAS}}$ and $\overline{\text{CAS}} = V_{IH}$ to disable Dout.

HM5164405F Series, HM5165405F Series

AC Characteristics ($T_a = 0$ to $+70^\circ\text{C}$, $V_{CC} = 3.3\text{ V} \pm 0.3\text{ V}$, $V_{SS} = 0\text{ V}$) *¹, *², *¹⁹

Test Conditions

- Input rise and fall time: 2 ns
- Input pulse levels: $V_{IL} = 0\text{ V}$, $V_{IH} = 3.0\text{ V}$
- Input timing reference levels: 0.8 V, 2.0 V
- Output timing reference levels: 0.8 V, 2.0 V
- Output load: 1 TTL gate + C_L (100 pF) (Including scope and jig)

Read, Write, Read-Modify-Write and Refresh Cycles (Common parameters)

		HM5164405F/HM5165405F					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
Random read or write cycle time	t _{RC}	84	—	104	—	ns	
RAS precharge time	t _{RP}	30	—	40	—	ns	
CAS precharge time	t _{CP}	8	—	10	—	ns	
RAS pulse width	t _{RAS}	50	10000	60	10000	ns	
CAS pulse width	t _{CAS}	8	10000	10	10000	ns	
Row address setup time	t _{ASR}	0	—	0	—	ns	
Row address hold time	t _{RAH}	8	—	10	—	ns	
Column address setup time	t _{ASC}	0	—	0	—	ns	
Column address hold time	t _{CAH}	8	—	10	—	ns	
RAS to CAS delay time	t _{RCD}	12	37	14	45	ns	3
RAS to column address delay time	t _{RAD}	10	25	12	30	ns	4
RAS hold time	t _{RSH}	13	—	15	—	ns	
CAS hold time	t _{CSH}	38	—	40	—	ns	
CAS to RAS precharge time	t _{CRP}	5	—	5	—	ns	
OE to Din delay time	t _{OED}	13	—	15	—	ns	5
OE delay time from Din	t _{DZO}	0	—	0	—	ns	6
CAS delay time from Din	t _{DZC}	0	—	0	—	ns	6
Transition time (rise and fall)	t _T	2	50	2	50	ns	7

HM5164405F Series, HM5165405F Series

Read Cycle

		HM5164405F/HM5165405F					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
Access time from $\overline{\text{RAS}}$	t_{RAC}	—	50	—	60	ns	8, 9
Access time from $\overline{\text{CAS}}$	t_{CAC}	—	13	—	15	ns	9, 10, 17
Access time from address	t_{AA}	—	25	—	30	ns	9, 11, 17
Access time from $\overline{\text{OE}}$	t_{OEA}	—	13	—	15	ns	9
Read command setup time	t_{RCS}	0	—	0	—	ns	
Read command hold time to $\overline{\text{CAS}}$	t_{RCH}	0	—	0	—	ns	12
Read command hold time from $\overline{\text{RAS}}$	t_{RCHR}	50	—	60	—	ns	
Read command hold time to $\overline{\text{RAS}}$	t_{RRH}	0	—	0	—	ns	12
Column address to $\overline{\text{RAS}}$ lead time	t_{RAL}	25	—	30	—	ns	
Column address to $\overline{\text{CAS}}$ lead time	t_{CAL}	15	—	18	—	ns	
$\overline{\text{CAS}}$ to output in low-Z	t_{CLZ}	0	—	0	—	ns	
Output data hold time	t_{OH}	3	—	3	—	ns	21
Output data hold time from $\overline{\text{OE}}$	t_{OHO}	3	—	3	—	ns	
Output buffer turn-off time	t_{OFF}	—	13	—	15	ns	13, 21
Output buffer turn-off to $\overline{\text{OE}}$	t_{OEZ}	—	13	—	15	ns	13
$\overline{\text{CAS}}$ to Din delay time	t_{CDD}	13	—	15	—	ns	5
Output data hold time from $\overline{\text{RAS}}$	t_{OHR}	3	—	3	—	ns	21
Output buffer turn-off to $\overline{\text{RAS}}$	t_{OFR}	—	13	—	15	ns	13, 21
Output buffer turn-off to $\overline{\text{WE}}$	t_{WEZ}	—	13	—	15	ns	13
$\overline{\text{WE}}$ to Din delay time	t_{WED}	13	—	15	—	ns	
$\overline{\text{RAS}}$ to Din delay time	t_{RDD}	13	—	15	—	ns	

HM5164405F Series, HM5165405F Series

Write Cycle

		HM5164405F/HM5165405F					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
Write command setup time	t _{WCS}	0	—	0	—	ns	14
Write command hold time	t _{WCH}	8	—	10	—	ns	
Write command pulse width	t _{WP}	8	—	10	—	ns	
Write command to $\overline{\text{RAS}}$ lead time	t _{RWL}	13	—	15	—	ns	
Write command to $\overline{\text{CAS}}$ lead time	t _{CWL}	8	—	10	—	ns	
Data-in setup time	t _{DS}	0	—	0	—	ns	15
Data-in hold time	t _{DH}	8	—	10	—	ns	15

Read-Modify-Write Cycle

		HM5164405F/HM5165405F					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
Read-modify-write cycle time	t _{RWC}	116	—	140	—	ns	
RAS to WE delay time	t _{RWD}	67	—	79	—	ns	14
CAS to WE delay time	t _{CWD}	30	—	34	—	ns	14
Column address to WE delay time	t _{AWD}	42	—	49	—	ns	14
OE hold time from WE	t _{OEH}	13	—	15	—	ns	

Refresh Cycle

		HM5164405F/HM5165405F					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
CAS setup time (CBR refresh cycle)	t _{CSR}	5	—	5	—	ns	
CAS hold time (CBR refresh cycle)	t _{CHR}	8	—	10	—	ns	
WE setup time (CBR refresh cycle)	t _{WRP}	0	—	0	—	ns	
WE hold time (CBR refresh cycle)	t _{WRH}	8	—	10	—	ns	
RAS precharge to CAS hold time	t _{RPC}	5	—	5	—	ns	

HM5164405F Series, HM5165405F Series

EDO Page Mode Cycle

		HM5164405F/HM5165405F					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
EDO page mode cycle time	t _{HPC}	20	—	25	—	ns	20
EDO page mode RAS pulse width	t _{RASP}	—	100000	—	100000	ns	16
Access time from $\overline{\text{CAS}}$ precharge	t _{CPA}	—	28	—	35	ns	9, 17
RAS hold time from $\overline{\text{CAS}}$ precharge	t _{CPRH}	28	—	35	—	ns	
Output data hold time from $\overline{\text{CAS}}$ low	t _{DOH}	3	—	3	—	ns	9, 22
$\overline{\text{CAS}}$ hold time referred $\overline{\text{OE}}$	t _{COL}	8	—	10	—	ns	
$\overline{\text{CAS}}$ to $\overline{\text{OE}}$ setup time	t _{COP}	5	—	5	—	ns	
Read command hold time from $\overline{\text{CAS}}$ precharge	t _{RCHC}	28	—	35	—	ns	
Write pulse width during $\overline{\text{CAS}}$ precharge	t _{WPE}	8	—	10	—	ns	
$\overline{\text{OE}}$ precharge time	t _{OEP}	8	—	10	—	ns	

EDO Page Mode Read-Modify-Write Cycle

		HM5164405F/HM5165405F					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
EDO page mode read-modify-write cycle time	t _{HPRWC}	57	—	68	—	ns	
$\overline{WE}$ delay time from $\overline{CAS}$ precharge	t _{CPW}	45	—	54	—	ns	14

Refresh (HM5164405F Series)

Parameter	Symbol	Max	Unit	Notes
Refresh period	t_{REF}	64	ms	8192 cycles

Refresh (HM5165405F Series)

Parameter	Symbol	Max	Unit	Notes
Refresh period	t_{REF}	64	ms	4096 cycles

HM5164405F Series, HM5165405F Series

Self Refresh Mode (L-version)

		HM5164405FL/HM5165405FL					
		-5		-6			
Parameter	Symbol	Min	Max	Min	Max	Unit	Notes
$\overline{\text{RAS}}$ pulse width (self refresh)	t_{RASS}	100	—	100	—	μs	25
$\overline{\text{RAS}}$ precharge time (self refresh)	t_{RPS}	90	—	110	—	ns	25
$\overline{\text{CAS}}$ hold time (self refresh)	t_{CHS}	−50	—	−50	—	ns	

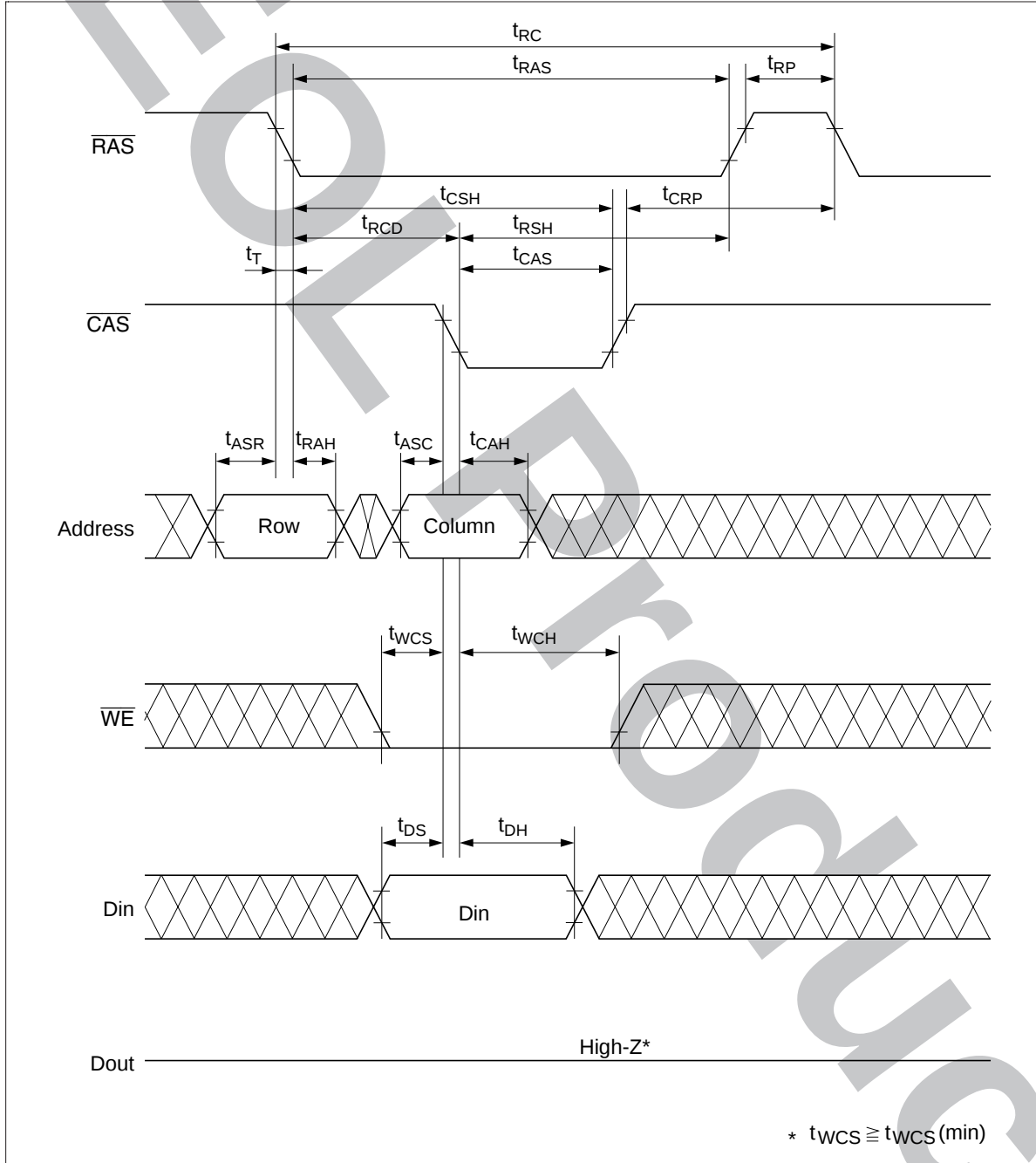
- Notes:
1. AC measurements assume $t_r = 2$ ns.
 2. An initial pause of 200 μs is required after power up followed by a minimum of eight initialization cycles (any combination of cycles containing RAS-only refresh or CAS-before-RAS refresh).
 3. Operation with the t_{RCD} (max) limit insures that t_{RAC} (max) can be met, t_{RCD} (max) is specified as a reference point only; if t_{RCD} is greater than the specified t_{RCD} (max) limit, then the access time is controlled exclusively by t_{CAC} .
 4. Operation with the t_{RAD} (max) limit insures that t_{RAC} (max) can be met, t_{RAD} (max) is specified as a reference point only; if t_{RAD} is greater than the specified t_{RAD} (max) limit, then access time is controlled exclusively by t_{AA} .
 5. Either t_{OED} or t_{CDD} must be satisfied.
 6. Either t_{DZO} or t_{DZC} must be satisfied.
 7. V_{IH} (min) and V_{IL} (max) are reference levels for measuring timing of input signals. Also, transition times are measured between V_{IH} (min) and V_{IL} (max).
 8. Assumes that $t_{RCD} \leq t_{RCD}$ (max) and $t_{RAD} \leq t_{RAD}$ (max). If t_{RCD} or t_{RAD} is greater than the maximum recommended value shown in this table, t_{RAC} exceeds the value shown.
 9. Measured with a load circuit equivalent to 1 TTL loads and 100 pF.
 10. Assumes that $t_{RCD} \geq t_{RCD}$ (max) and $t_{RCD} + t_{CAC}$ (max) $\geq t_{RAD} + t_{AA}$ (max).
 11. Assumes that $t_{RAD} \geq t_{RAD}$ (max) and $t_{RCD} + t_{CAC}$ (max) $\leq t_{RAD} + t_{AA}$ (max).
 12. Either t_{RCH} or t_{RRH} must be satisfied for a read cycles.
 13. t_{OFF} (max), t_{OEZ} (max), t_{WEZ} (max) and t_{OFR} (max) define the time at which the outputs achieve the open circuit condition and are not referred to output voltage levels.
 14. t_{WCS} , t_{RWD} , t_{CWD} , t_{AWD} and t_{CPW} are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only; if $t_{WCS} \geq t_{WCS}$ (min), the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout the entire cycle; if $t_{RWD} \geq t_{RWD}$ (min), $t_{CWD} \geq t_{CWD}$ (min), and $t_{AWD} \geq t_{AWD}$ (min), or $t_{CWD} \geq t_{CWD}$ (min), $t_{AWD} \geq t_{AWD}$ (min) and $t_{CPW} \geq t_{CPW}$ (min), the cycle is a read-modify-write and the data output will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.
 15. t_{DS} and t_{DH} are referred to $\overline{CAS}$ leading edge in early write cycles and to $\overline{WE}$ leading edge in delayed write or read-modify-write cycles.
 16. t_{RASP} defines $\overline{RAS}$ pulse width in EDO page mode cycles.
 17. Access time is determined by the longest among t_{AA} , t_{CAC} and t_{CPA} .
 18. In delayed write or read-modify-write cycles, $\overline{OE}$ must disable output buffer prior to applying data to the device.
 19. When output buffers are enabled once, sustain the low impedance state until valid data is obtained. When output buffer is turned on and off within a very short time, generally it causes large V_{CC}/V_{SS} line noise, which causes to degrade V_{IH} min/ V_{IL} max level.

HM5164405F Series, HM5165405F Series

20. t_{HPC} (min) can be achieved during a series of EDO page mode write cycles or EDO page mode read cycles. If both write and read operation are mixed in a EDO page mode $\overline{RAS}$ cycle (EDO page mode mix cycle (1), (2)), minimum value of $\overline{CAS}$ cycle ($t_{CAS} + t_{CP} + 2 t_T$) becomes greater than the specified t_{HPC} (min) value. The value of $\overline{CAS}$ cycle time of mixed EDO page mode is shown in EDO page mode mix cycle (1) and (2).
21. Data output turns off and becomes high impedance from later rising edge of $\overline{RAS}$ and $\overline{CAS}$. Hold time and turn off time are specified by the timing specifications of later rising edge of $\overline{RAS}$ and $\overline{CAS}$ between t_{OHR} and t_{OH} and between t_{OFR} and t_{OFF} .
22. t_{DOH} defines the time at which the output level go cross. $V_{OL} = 0.8 V$, $V_{OH} = 2.0 V$ of output timing reference level.
23. Before and after self refresh mode, execute CBR refresh to all refresh addresses in or within 64 ms period on the condition a and b below.
- Enter self refresh mode within 15.6 μs after either burst refresh or distributed refresh at equal interval to all refresh addresses are completed.
 - Start burst refresh or distributed refresh at equal interval to all refresh addresses within 15.6 μs after exiting from self refresh mode.
24. In case of entering from $\overline{RAS}$ -only-refresh, it is necessary to execute CBR refresh before and after self refresh mode according as note 23.
25. At $t_{RASS} > 100 \mu s$, self refresh mode is activated, and not activated at $t_{RASS} < 10 \mu s$. It is undefined within the range of $10 \mu s \leq t_{RASS} \leq 100 \mu s$. For $t_{RASS} \geq 10 \mu s$, it is necessary to satisfy t_{RPS} .
26. XXX: H or L (H: $V_{IH}(\min) \leq V_{IN} \leq V_{IH}(\max)$, L: $V_{IL}(\min) \leq V_{IN} \leq V_{IL}(\max)$)
- //////: Invalid Dout
- When the address, clock and input pins are not described on timing waveforms, their pins must be applied V_{IH} or V_{IL} .

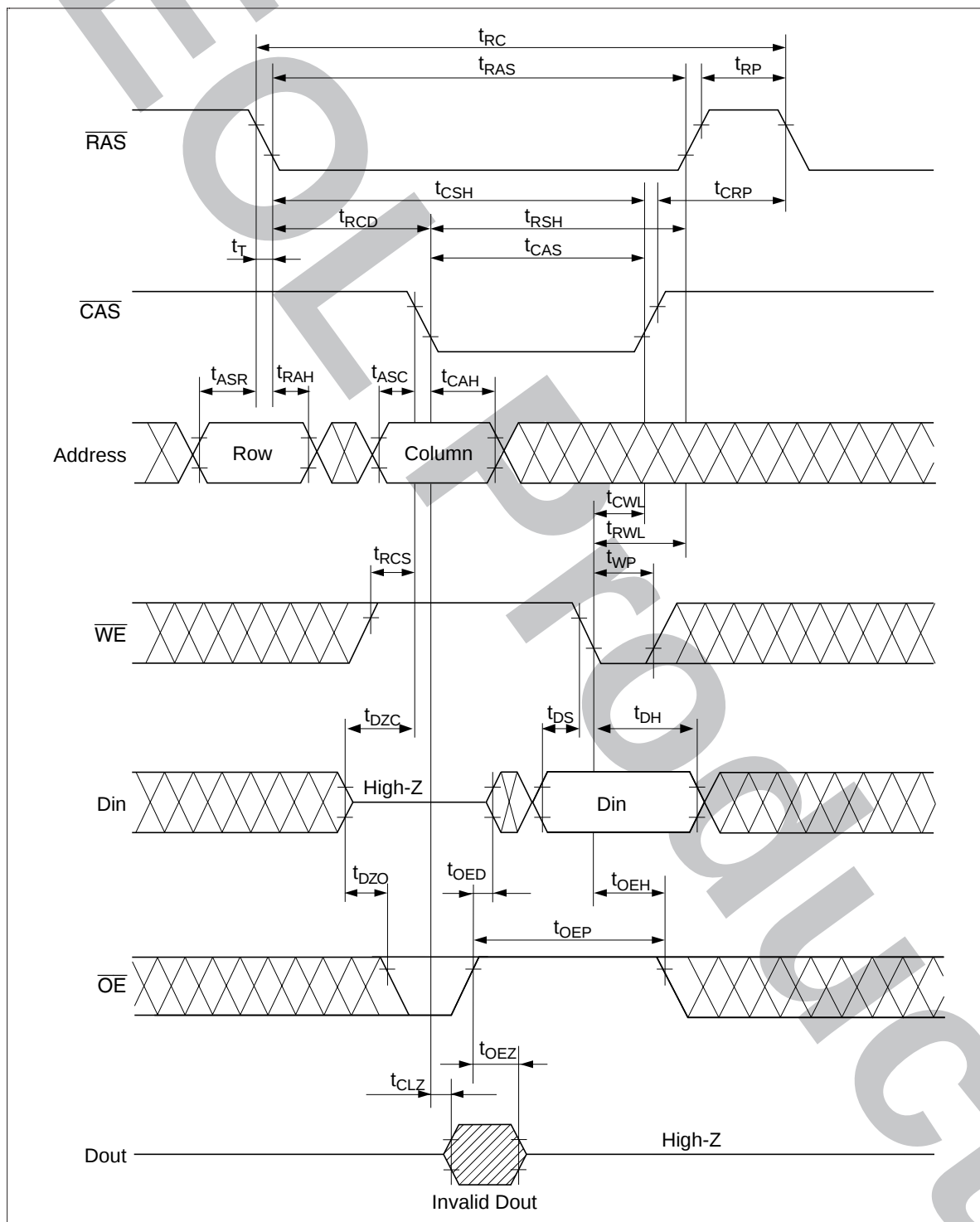
HM5164405F Series, HM5165405F Series

Early Write Cycle



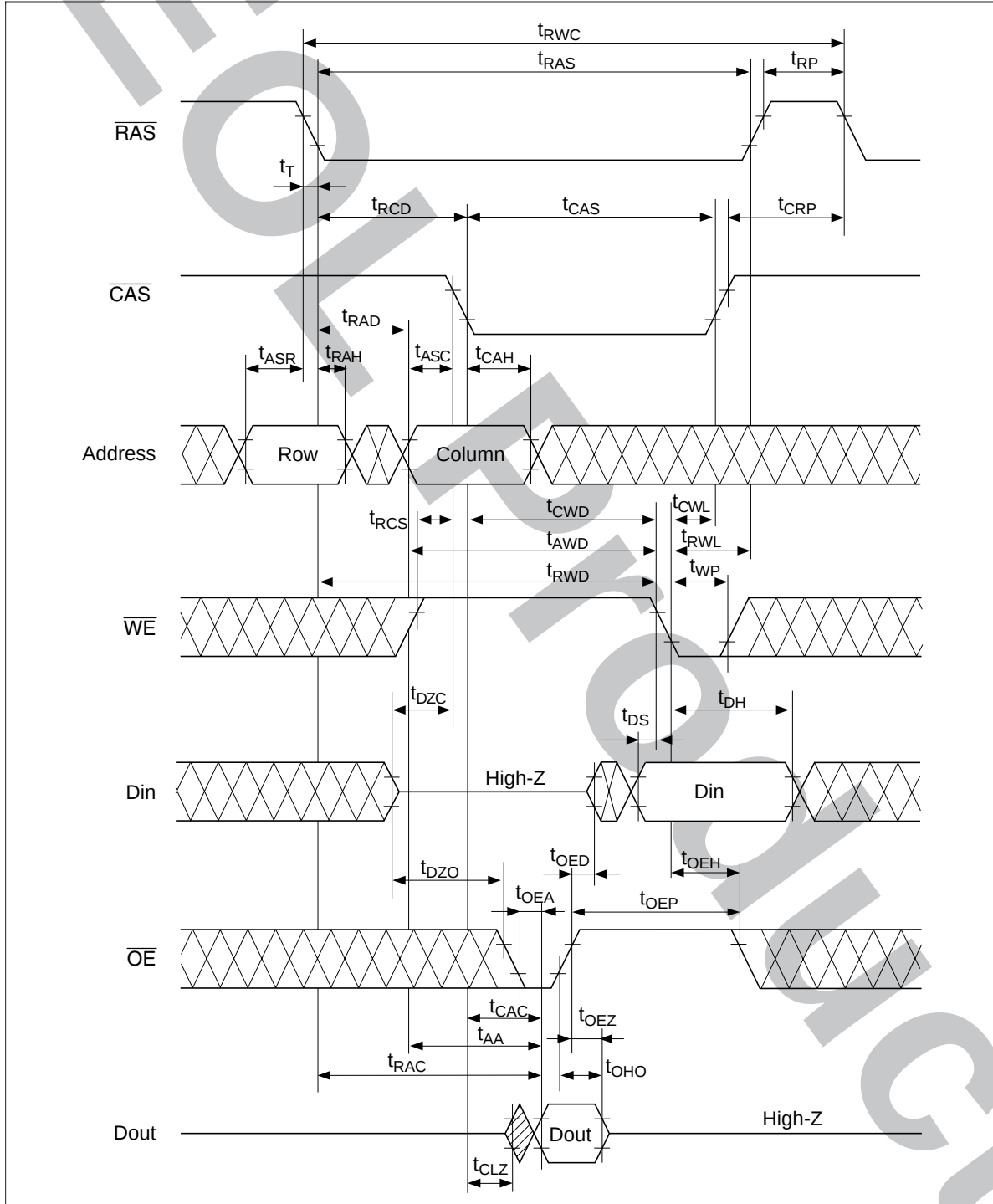
HM5164405F Series, HM5165405F Series

Delayed Write Cycle*18

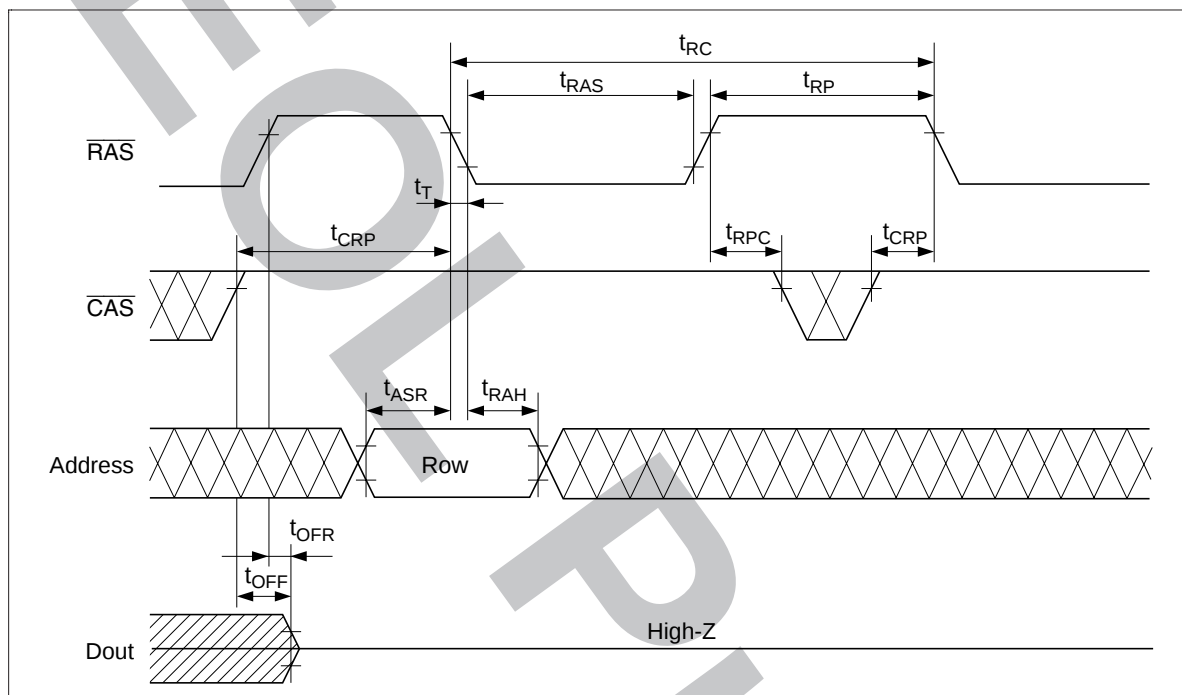


HM5164405F Series, HM5165405F Series

Read-Modify-Write Cycle*18

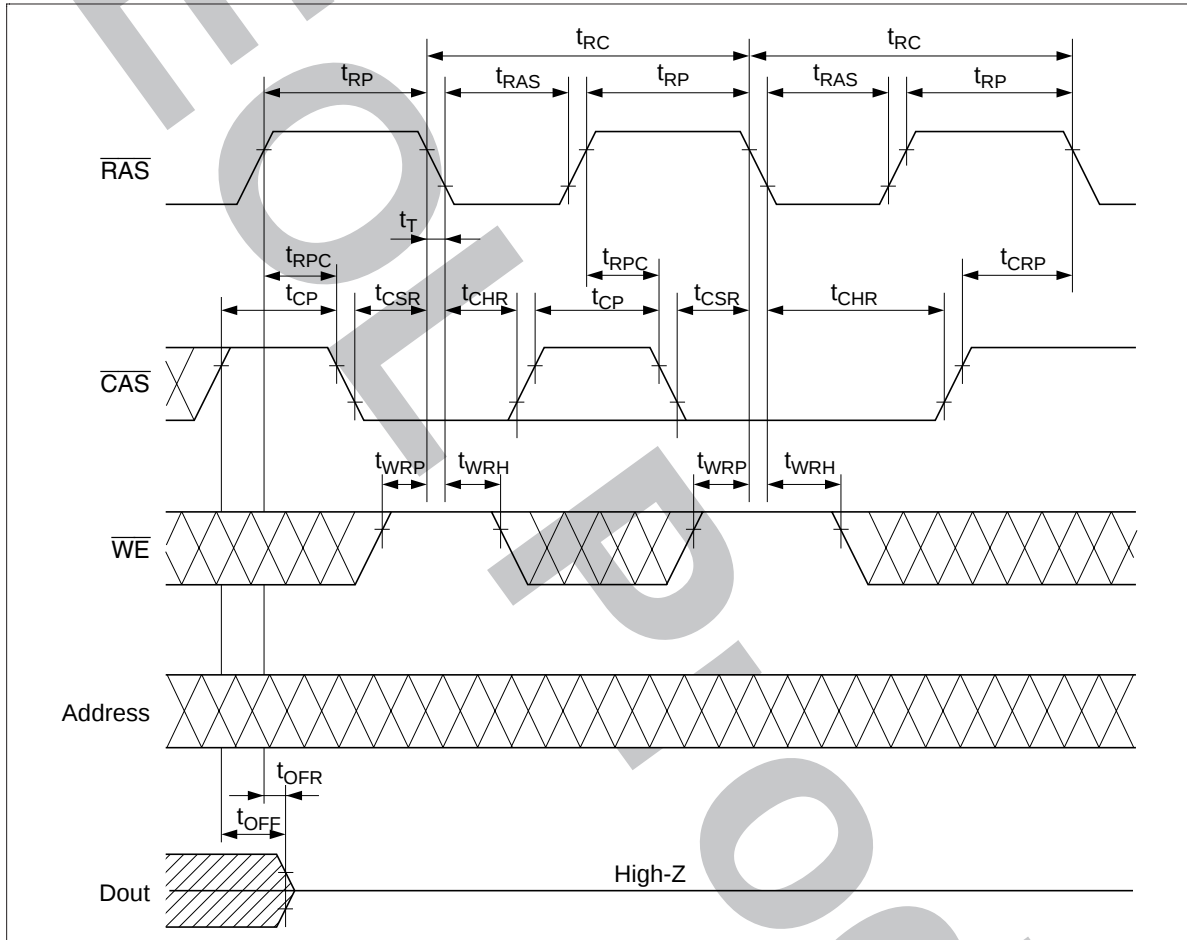


RAS-Only Refresh Cycle

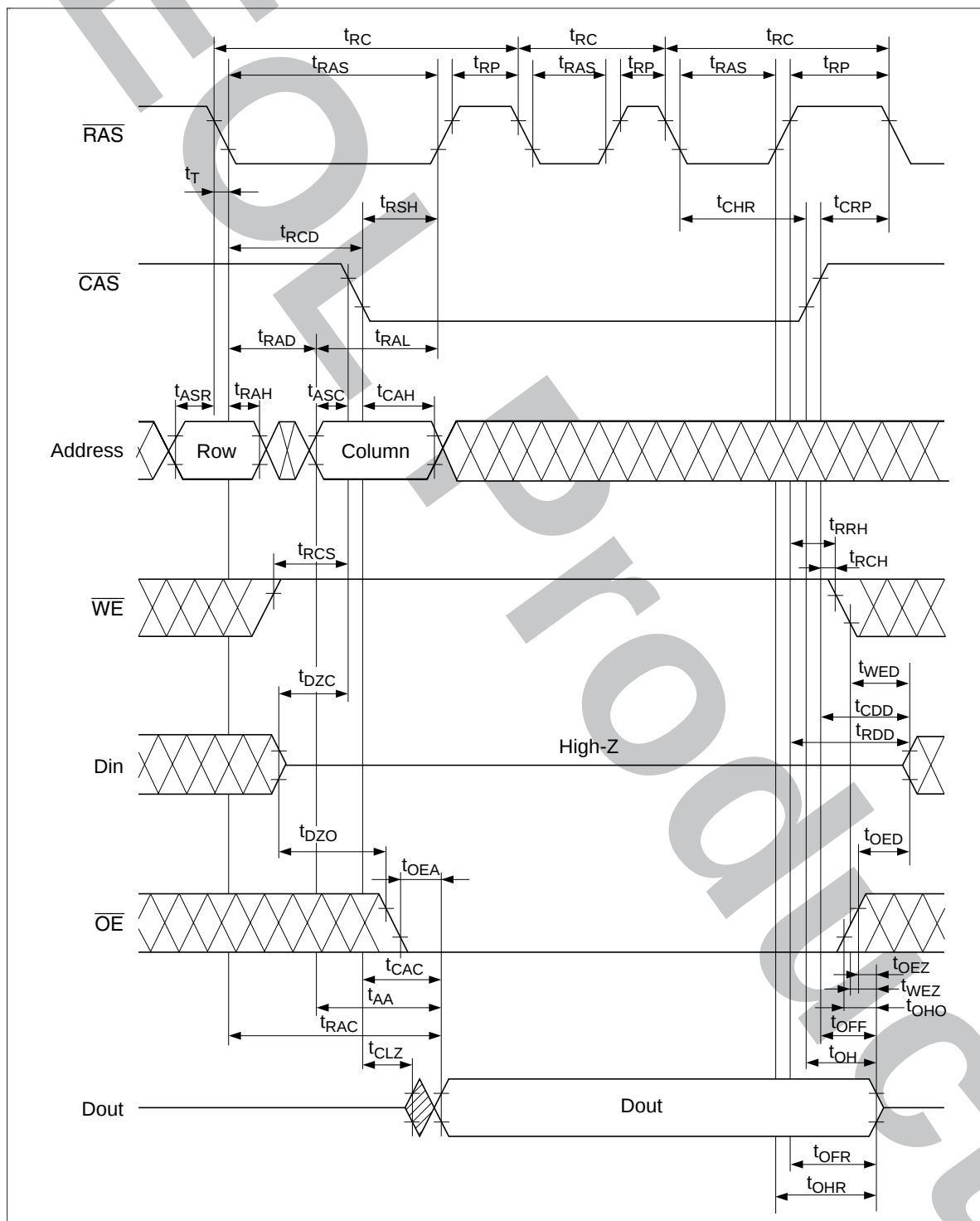


HM5164405F Series, HM5165405F Series

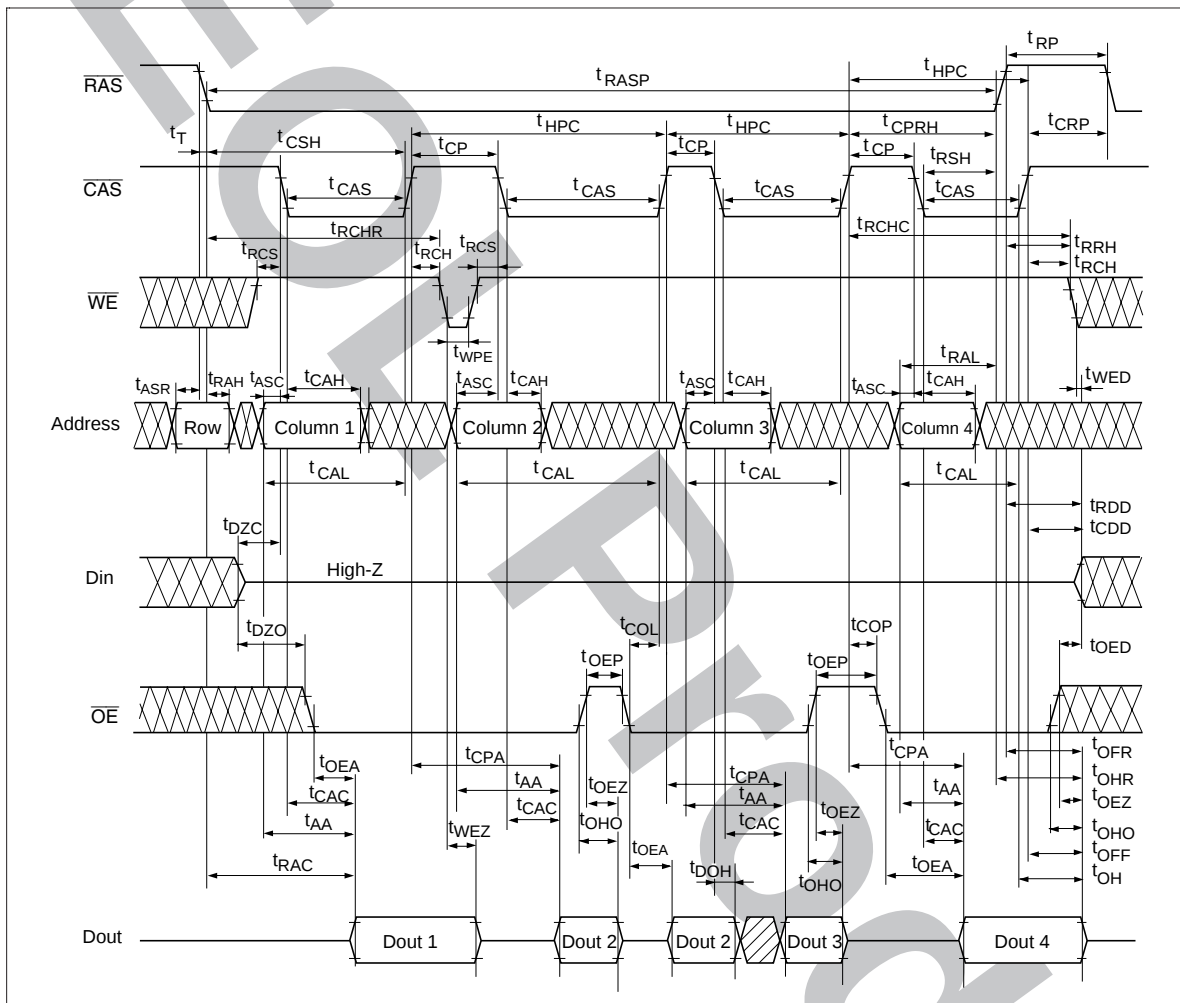
$\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$ Refresh Cycle



Hidden Refresh Cycle

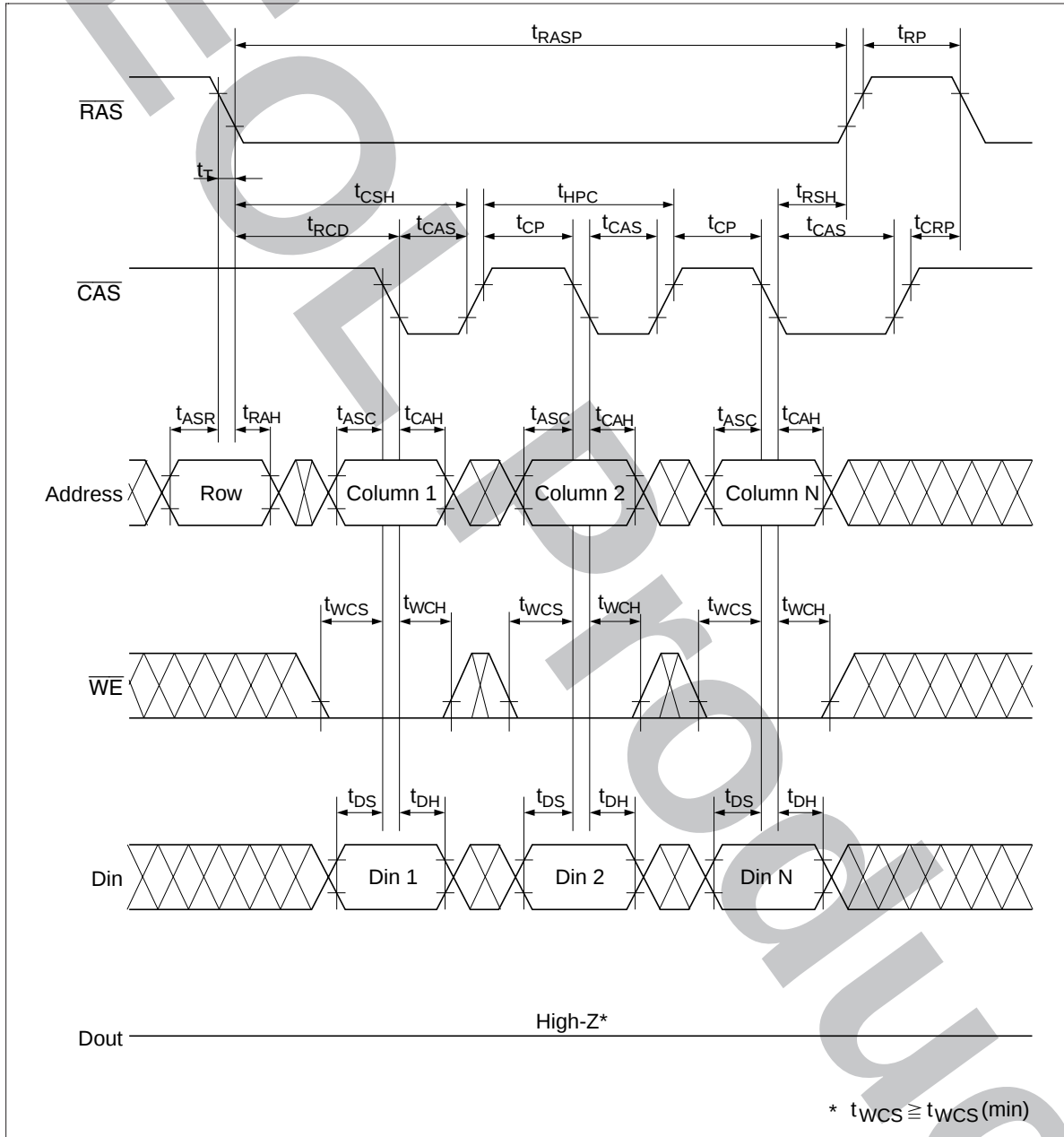


EDO Page Mode Read Cycle (1)



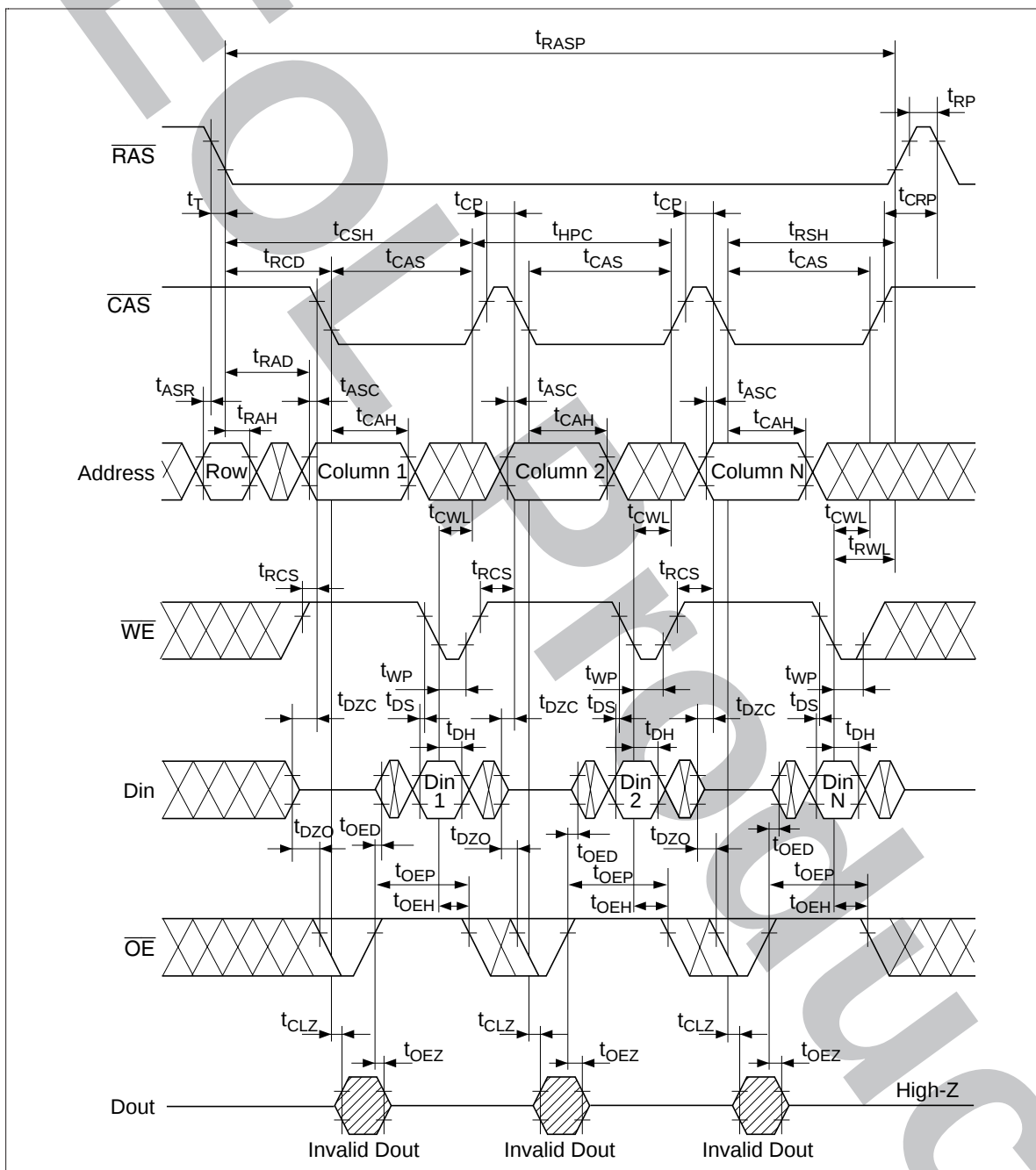
HM5164405F Series, HM5165405F Series

EDO Page Mode Early Write Cycle

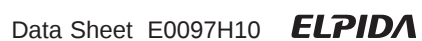


HM5164405F Series, HM5165405F Series

EDO Page Mode Delayed Write Cycle*18

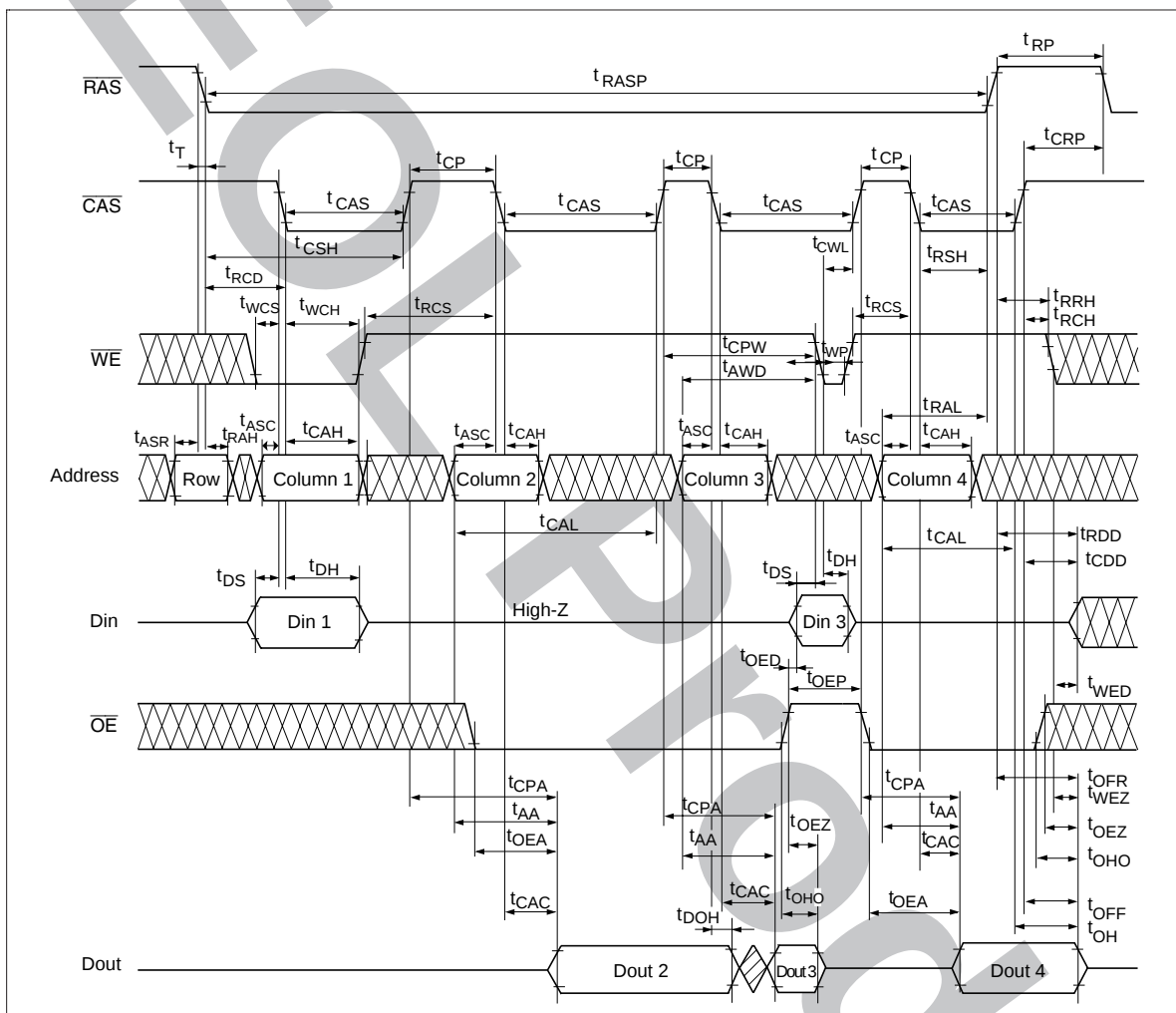


EDO Page Mode Read-Modify-Write Cycle*¹⁸



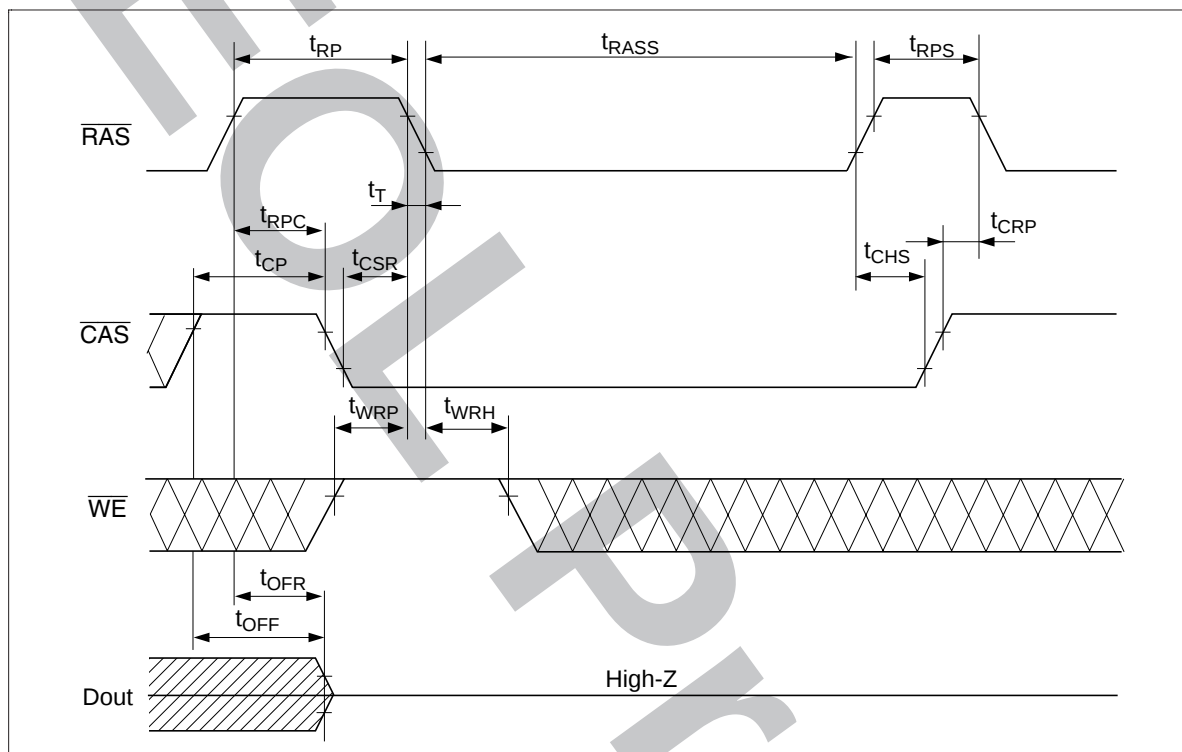
HM5164405F Series, HM5165405F Series

EDO Page Mode Mix Cycle (1)*²⁰



HM5164405F Series, HM5165405F Series

Self Refresh Cycle (L-version)* 23, 24, 25



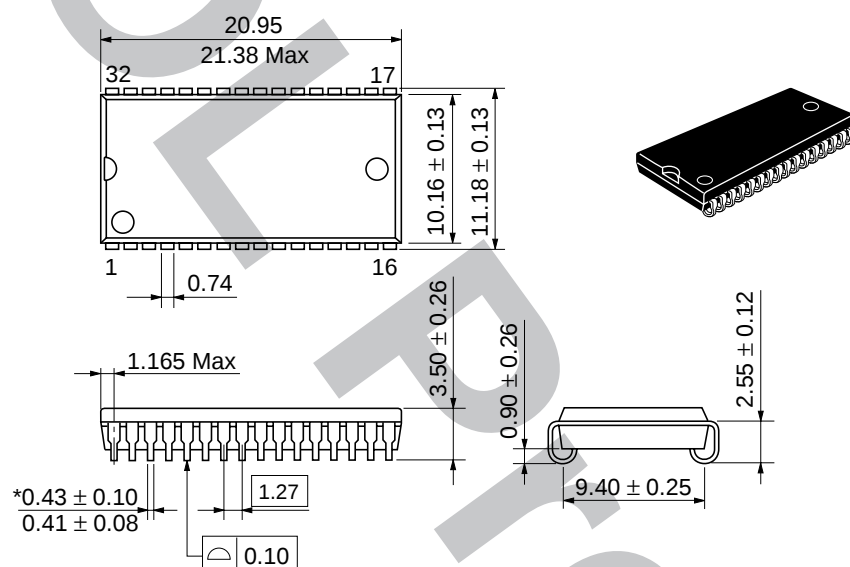
HM5164405F Series, HM5165405F Series

Package Dimensions

HM5164405FJ/FLJ Series

HM5165405FJ/FLJ Series (CP-32DC)

Unit: mm

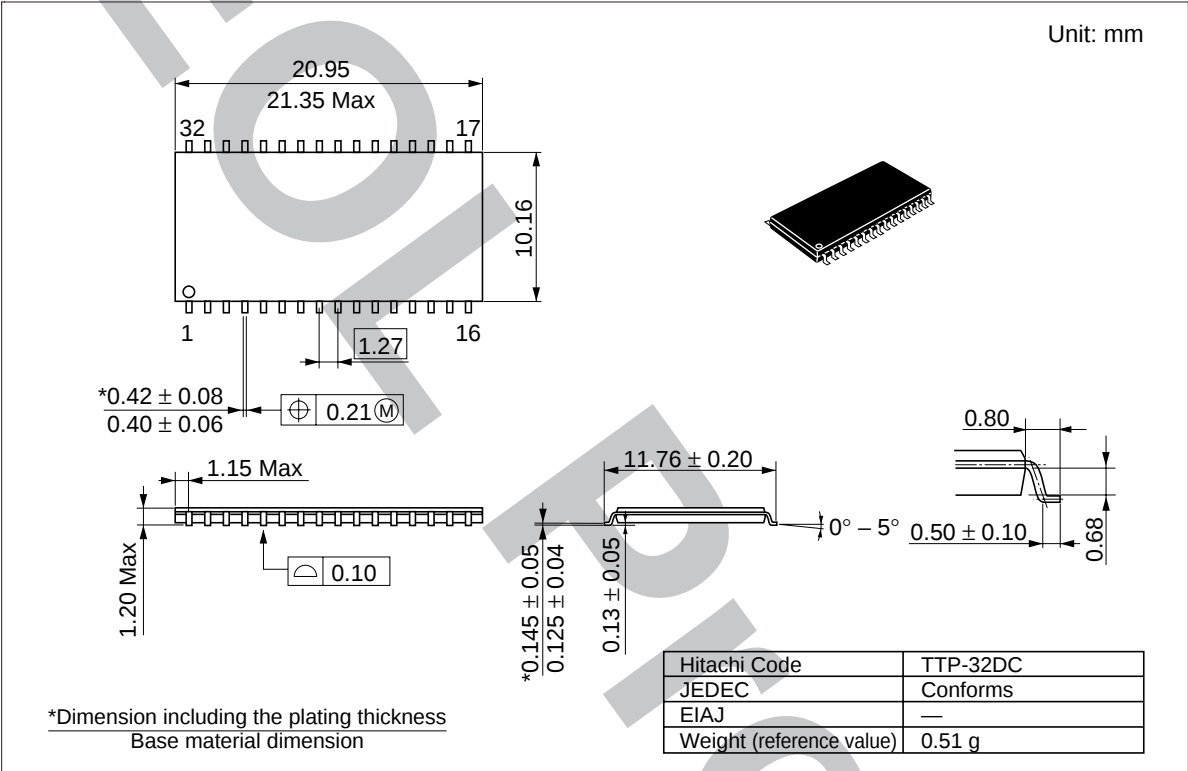


*Dimension including the plating thickness
Base material dimension

Hitachi Code	CP-32DC
JEDEC	—
EIAJ	Conforms
Weight (reference value)	1.2 g

HM5164405F Series, HM5165405F Series

HM5164405FTT/FLTT Series
HM5165405FTT/FLTT Series (TTP-32DC)



HM5164405F Series, HM5165405F Series

Cautions

1. Elpida Memory, Inc. neither warrants nor grants licenses of any rights of Elpida Memory, Inc.'s or any third party's patent, copyright, trademark, or other intellectual property rights for information contained in this document. Elpida Memory, Inc. bears no responsibility for problems that may arise with third party's rights, including intellectual property rights, in connection with use of the information contained in this document.
2. Products and product specifications may be subject to change without notice. Confirm that you have received the latest product standards or specifications before final design, purchase or use.
3. Elpida Memory, Inc. makes every attempt to ensure that its products are of high quality and reliability. However, contact Elpida Memory, Inc. before using the product in an application that demands especially high quality and reliability or where its failure or malfunction may directly threaten human life or cause risk of bodily injury, such as aerospace, aeronautics, nuclear power, combustion control, transportation, traffic, safety equipment or medical equipment for life support.
4. Design your application so that the product is used within the ranges guaranteed by Elpida Memory, Inc. particularly for maximum rating, operating supply voltage range, heat radiation characteristics, installation conditions and other characteristics. Elpida Memory, Inc. bears no responsibility for failure or damage when used beyond the guaranteed ranges. Even within the guaranteed ranges, consider normally foreseeable failure rates or failure modes in semiconductor devices and employ systemic measures such as fail-safes, so that the equipment incorporating Elpida Memory, Inc. product does not cause bodily injury, fire or other consequential damage due to operation of the Elpida Memory, Inc. product.
5. This product is not designed to be radiation resistant.
6. No one is permitted to reproduce or duplicate, in any form, the whole or part of this document without written approval from Elpida Memory, Inc..
7. Contact Elpida Memory, Inc. for any questions regarding this document or Elpida Memory, Inc. semiconductor products.

© Elpida Memory, Inc. 2001



Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



Как с нами связаться

Телефон: 8 (812) 309 58 32 (многоканальный)

Факс: 8 (812) 320-02-42

Электронная почта: org@eplast1.ru

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.