# RICOH **E**

# **RP509x Series**

# 0.5A/1A PWM/VFM Step-down DC/DC Converter with Synchronous Rectifier

NO.EA-362-160510

# **OUTLINE**

The RP509x is a low supply current CMOS-based PWM/VFM step-down DC/DC converter with synchronous rectifier featuring 0.5 A / 1 A output current<sup>(1)</sup>. Internally, a single converter consists of a reference voltage unit, an error amplifier, a switching control circuit, a mode control circuit, a soft-start circuit, an under-voltage lockout (UVLO) circuit, a thermal shutdown circuit, and switching transistors. The RP509x is employing synchronous rectification for improving the efficiency of rectification by replacing diodes with built-in switching transistors. Using synchronous rectification not only increases circuit performance but also allows a design to reduce parts count. Output voltage controlling method is selectable between a forced PWM control type and a PWM/VFM auto-switching control type, and can be set by the MODE pin. Output voltage type is selectable between an internally fixed output voltage type and an externally adjustable output voltage type. Protection circuits in the RP509x is current limit circuit and thermal shutdown circuit. LX current limit value (Typ.) is selectable between 1.6 A and 1.0 A.

The RP509Z is available in WLCSP-6-P6 which achieves high-density mounting on boards. Using capacitor of 0402- / 1005-size (inch / mm) and inductor of 0603- /1608-size (inch / mm) as external parts help to save space for devices. The RP509N under development is available in SOT-23-6.

# **FEATURES**

•	Input Voltage Range (Maximum Rating) ·················2.3 V to 5.5 V (6.5 V)
•	Output Voltage Range (Fixed Output Voltage Type) ·······0.6 V to 3.3 V - Settable in 0.1 V Step
	(Adjustable Output Voltage Type) ······0.6 V to 5.5 V
•	Output Voltage Accuracy (Fixed Output Voltage Type) ······±1.5% (V <sub>SET</sub> (2) ≥ 1.2 V), ±18 mV (V <sub>SET</sub> < 1.2 V)
•	Feedback Voltage Accuracy
	(Adjustable Output Voltage Type) ······±9 mV (V <sub>FB</sub> = 0.6 V)
_	Output Valtage/Feedback/Valtage Temperature Coefficient 400 mms/90

- Output Voltage/Feedback Voltage Temperature Coefficient…±100 ppm/°C
- Selectable Oscillator Frequency ......Typ. 6.0 MHz
- Oscillator Maximum Duty -----------Min. 100%
- Built-in Driver ON Resistance (VIN = 3.6 V)......Τγρ. Pch. 0.175 Ω, Nch. 0.155 Ω (RP509Z)
- Standby Current······Typ. 0 μA
- UVLO Detector Threshold · · · · · Typ. 2.0 V
- Soft-start Time ......Typ. 0.15 ms
- Inductor Current Limit Circuit .......Typ. 1.6 A / 1.0 A Selectable Current Limit
- Package ...... WLCSP-6-P6 (1.28 mm x 0.88 mm)

SOT-23-6 (under development)

1

<sup>(1)</sup> This is an approximate value. The output current is dependent on conditions and external components.

<sup>(2)</sup> V<sub>SET</sub> = Set Output Voltage

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# **APPLICATION**

- Power source for Portable communication equipment such as mobile/smart phone, digital camera, and Note-PC
- Power source for Li-ion battery-used equipment

# **SELECTION GUIDE**

The set output voltage, the output voltage type, the auto-discharge function<sup>(1)</sup>, and the LX current limit for the ICs are user-selectable options.

#### **Selection Guide**

<b>Product Name</b>	Package	Quantity per Reel	Pb Free	Halogen Free
RP509ZxxX\$-E2-F	WLCSP-6-P6	5,000 pcs	Yes	Yes
RP509NxxX\$-TR-FE  《under development》	SOT-23-6	3,000 pcs	Yes	Yes

xx: Designation of the set output voltage (V<sub>SET</sub>)

For Fixed Output Voltage Type: 0.6 V (06) to 3.3 V (33) in 0.1 V steps<sup>(2)</sup>

For Adjustable Output Voltage Type: 00 only

X: Designation of LX Current Limit

1) Typ. 1.6 A

2) Typ. 1.0 A

\$: Designation of Version

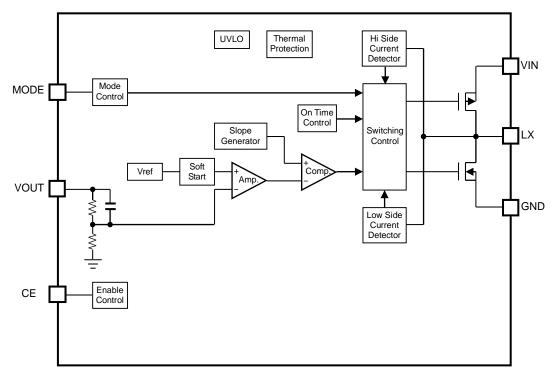
Version	Output Voltage Type	Auto-discharge Function	Oscillator Frequency	V <sub>SET</sub>				
Α	Fixed	No		0.6 V to 3.3 V				
В	rixeu	Yes	6.0 MHz	0.6 V 10 3.5 V				
С	Adiustable	No	6.0 MHZ	0.6 V to 5.5 V				
D	Adjustable	Yes		0.6 V to 5.5 V				

<sup>(1)</sup> Auto-discharge function quickly lowers the output voltage to 0 V, when the chip enable signal is switched from the active mode to the standby mode, by releasing the electrical charge accumulated in the external capacitor.

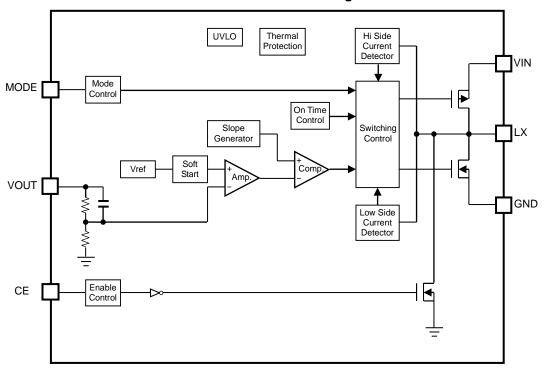
<sup>(2) 0.05</sup> V step is also available as a custom code.

# **BLOCK DIAGRAM**

RP509ZxxXA/B, RP509NxxXA/B **(under development)** (Fixed Output Voltage Type)

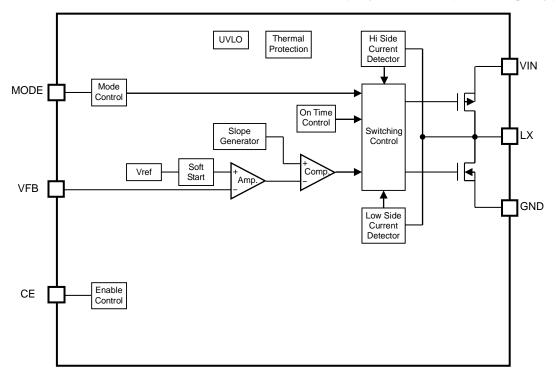


### RP509xxxXA Block Diagram

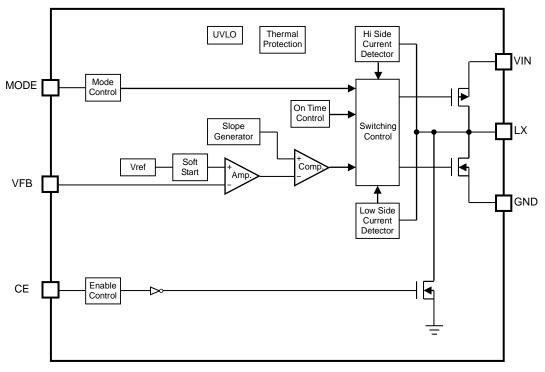


RP509xxxXB Block Diagram

# RP509ZxxXC/D, RP509NxxXC/D **(under development)** (Adjustable Output Voltage Type)

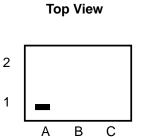


# RP509x00XC Block Diagram

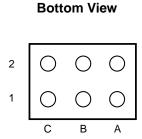


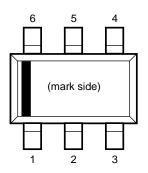
RP509x00XD Block Diagram

# **PIN DESCRIPTION**



В





**WLCSP-6 Pin Configurations** 

**SOT-23-6 Pin Configurations** 

**«under development»** 

**WLCSP-6 Pin Description** 

Pin No.	Symbol	Description
A1	MODE	Mode Control Pin
Al	IVIODE	("H": forced PWM control, "L": PWM/VFM auto-switching control)
B1	LX	Switching Pin
C1	VOUT/ VFB	Output / Feedback Voltage Pin
A2	VIN	Input Voltage Pin
B2	CE	Chip Enable Pin (Active "H")
C2	GND	Ground Pin

SOT-23-6 Pin Description **(under development)** 

Pin No.	Symbol	Description
1	CE	Chip Enable Pin (Active "H")
2	GND	Ground Pin
3	VIN	Input Voltage Pin
4	MODE	Mode Control Pin  ("H": forced PWM control, "L": PWM/VFM auto-switching control)
5	LX	Switching Pin
6	VOUT/ VFB	Output / Feedback Voltage Pin

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# **ABSOLUTE MAXIMUM RATINGS**

#### **Absolute Maximum Ratings**

(GND = 0 V)

Symbol	Ite	em	Rating	Unit
Vin	Input Voltage		-0.3 to 6.5	V
V <sub>L</sub> X	LX Pin Voltage		-0.3 to V <sub>IN</sub> +0.3	V
Vce	CE Pin Voltage		-0.3 to 6.5	V
V <sub>MODE</sub>	MODE Pin Voltage		-0.3 to 6.5	V
V <sub>OUT</sub> /V <sub>FB</sub>	VOUT/VFB Pin Voltage		-0.3 to 6.5	V
I <sub>LX</sub>	LX Pin Output Current		1.6	А
D	Power Dissipation <sup>(1)</sup> (WLCSP6-P6)	JEDEC STD. 51-9 Test Land Pattern	910	mW
$P_D$	Power Dissipation (SOT-23-6)		TBD	mW
Tj	Junction Temperature		-40 to 125	°C
Tstg	Storage Temperature Ra	ange	-55 to 125	°C

#### **ABSOLUTE MAXIMUM RATINGS**

Electronic and mechanical stress momentarily exceeded absolute maximum ratings may cause the permanent damages and may degrade the lifetime and safety for both device and system using the device in the field. The functional operation at or over these absolute maximum ratings is not assured.

#### **RECOMMENDED OPERATING CONDITIONS**

Symbol	Item	Rating	Unit
V <sub>IN</sub>	Input Voltage	2.3 to 5.5	V
Та	Operating Temperature Range	−40 to 85	°C

### **RECOMMENDED OPERATING CONDITIONS**

All of electronic equipment should be designed that the mounted semiconductor devices operate within the recommended operating conditions. The semiconductor devices cannot operate normally over the recommended operating conditions, even if when they are used over such conditions by momentary electronic noise or surge. And the semiconductor devices may receive serious damage when they continue to operate over the recommended operating conditions.

<sup>(1)</sup> Refer to POWER DISSIPATION for detailed information.

# **ELECTRICAL CHARACTERISTICS**

Test circuit is operated with "Open Loop Control" (GND = 0 V), unless otherwise specified.

RP509Zxx1A/B, RP509Nxx1A/B **(under development)** Electrical Characterisitcs

 $(Ta = 25^{\circ}C)$ 

Symbol	Item		Conditio		Min.	Тур.	Max.	Unit
	114	V <sub>IN</sub> = V <sub>CE</sub> =		V <sub>SET</sub> ≥ 1.2 V	x 0.985	.,,	x 1.015	
Vouт	Output Voltage	(V <sub>SET</sub> ≤ 2.6 V), V <sub>IN</sub> =V <sub>CE</sub> =V <sub>SET</sub> +1 V	VSE1 = 1.2 V	X 0.903		X 1.013	V	
		VIN = VCE = V (VSET > 2.6)		V <sub>SET</sub> < 1.2 V	-0.018		+0.018	
ΔV <sub>OUT</sub> / Δ <b>Ta</b>	Output Voltage Temperature Coefficient	-40 °C ≤ Ta	a ≤ 85 °C			±100		ppm/ °C
fosc	Oscillator Frequency	V <sub>IN</sub> = V <sub>CE</sub> "Closed Lo		V <sub>SET</sub> = 1.8 V,	4.8	6.0	7.2	MHz
I <sub>DD</sub>	Supply Current	VIN = VCE =	V <sub>OUT</sub> = 3.6	$V$ , $V_{MODE} = 0 V$		15		μΑ
ISTANDBY	Standby Current	$V_{IN} = 5.5 V_{IN}$	$V_{CE} = 0 V$			0	5	μА
Ісен	CE "High" Input Current	VIN = VCE =	5.5 V		-1	0	1	μА
ICEL	CE "Low" Input Current	V <sub>IN</sub> = 5.5 V	$V_{CE} = 0 V$		-1	0	1	μΑ
I <sub>MODEH</sub>	MODE "High" Input Current	$V_{IN} = V_{MODE}$	= 5.5 V, V	<sub>CE</sub> = 0 V	-1	0	1	μΑ
I <sub>MODEL</sub>	MODE "Low" Input Current	$V_{IN} = 5.5 V_{IN}$	V <sub>CE</sub> = V <sub>MC</sub>	DDE = 0 V	-1	0	1	μΑ
Іνоυтн	Vоит "High" Input Current	V <sub>IN</sub> = V <sub>OUT</sub>	= 5.5 V, Vc	E = 0 V	-1	0	1	μА
Ivoutl	Vout "Low" Input Current	V <sub>IN</sub> = 5.5 V	, Vce = Vol	υτ = 0 V	-1	0	1	μА
RDISTR	On-resistance for Auto Discharger <sup>(1)</sup>	V <sub>IN</sub> = 3.6 V, V <sub>CE</sub> = 0 V				40		Ω
ILXLEAKH	LX "High" Leakage Current	V <sub>IN</sub> = V <sub>LX</sub> =	5.5 V, V <sub>CE</sub>	= 0 V	-1	0	5	μΑ
I <sub>LXLEAKL</sub>	LX "Low" Leakage Current	V <sub>IN</sub> = 5.5 V	, V <sub>CE</sub> = V <sub>LX</sub>	= 0 V	-5	0	1	μА
V <sub>CEH</sub>	CE "High" Input Voltage	V <sub>IN</sub> = 5.5 V			1.0			V
V <sub>CEL</sub>	CE "Low" Input Voltage	V <sub>IN</sub> = 2.3 V					0.4	V
V <sub>MODEH</sub>	MODE "High" Input Voltage	V <sub>IN</sub> = V <sub>CE</sub> =	5.5 V		1.0			V
V <sub>MODEL</sub>	MODE "Low" Input Voltage	V <sub>IN</sub> = V <sub>CE</sub> =	2.3 V				0.4	V
		RP509Z	V <sub>IN</sub> =3.6V	, I <sub>LX</sub> =-100mA		0.175		Ω
Ronp	On-resistance of Pch. transistor	RP509N				TBD		Ω
	C (NI	RP509Z	V <sub>IN</sub> =3.6V	, I <sub>LX</sub> =-100mA		0.155		Ω
R <sub>ONN</sub>	On-resistance of Nch. transistor	RP509N				TBD		Ω
Maxduty	Maximum Duty Cycle		J.		100			%
tstart	Soft-start Time	$V_{IN} = V_{CE} = 3.6 \text{ V } (V_{SET} \le 2.6 \text{ V}),$ $V_{IN} = V_{CE} = V_{SET} + 1 \text{ V } (V_{SET} > 2.6 \text{ V})$			150	300	μS	
I <sub>LXLIM</sub>	LX Current Limit	$V_{IN} = V_{CE} = 3.6 \text{ V (V}_{SET} \le 2.6 \text{ V)},$ $V_{IN} = V_{CE} = V_{SET} + 1 \text{ V (V}_{SET} > 2.6 \text{ V)}$		1200	1600		mA	
V <sub>UVLO1</sub>	LIVI O Threehold Voltore	VIN = VCE, F	alling		1.85	2.00	2.20	V
V <sub>UVLO2</sub>	UVLO Threshold Voltage	VIN = VCE, F	Rising		1.90	2.05	2.25	V
T <sub>TSD</sub>	Thermal Shutdown Threshold	Tj, Rising				140		°C
T <sub>TSR</sub>	Temperature	Tj, Falling			100		°C	
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All test items listed under Electrical Characteristics are done under the pulse load condition (Tj  $\approx$  Ta = 25°C).

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<sup>(1)</sup> RP509xxx1B only

NO.EA-362-160510

Test circuit is operated with "Open Loop Control" (GND = 0 V), unless otherwise specified.

# RP509Z001C/D, RP509N001C/D **(under development)** Electrical Characterisitcs

 $(Ta = 25^{\circ}C)$ 

Symbol	Item		Conditions	Min.	Тур.	Max.	Unit
V <sub>FB</sub>	Feedback Voltage	V <sub>IN</sub> = V <sub>CE</sub> :	= 3.6 V	0.591	0.600	0.609	V
ΔV <sub>FB</sub> / ΔTa	Feedback Voltage Temperature Coefficient	-40 °C ≤ T	a ≤ 85 °C		±100		ppm/ °C
fosc	Oscillator Frequency		= 3.6 V, V <sub>SET</sub> = 1.8 V, pop Control"	4.8	6.0	7.2	MHz
I <sub>DD</sub>	Supply Current	VIN = VCE =	VOUT = 3.6V, VMODE = 0V		15		μΑ
ISTANDBY	Standby Current	V <sub>IN</sub> = 5.5 V	/,V <sub>CE</sub> = 0 V		0	5	μА
I <sub>CEH</sub>	CE "High" Input Current	V <sub>IN</sub> = V <sub>CE</sub> =	= 5.5 V	-1	0	1	μΑ
I <sub>CEL</sub>	CE "Low" Input Current	V <sub>IN</sub> = 5.5 \	$V,V_{CE}=0$ V	-1	0	1	μА
IMODEH	MODE "High" Input Current	VIN = VMOD	E = 5.5 V, V <sub>CE</sub> = 0 V	-1	0	1	μА
IMODEL	MODE "Low" Input Current	V <sub>IN</sub> = 5.5 V	/, Vce = V <sub>MODE</sub> = 0 V	-1	0	1	μА
Іνоυтн	Vout "High" Input Current	V <sub>IN</sub> = V <sub>OUT</sub>	= 5.5 V, V <sub>CE</sub> = 0 V	-1	0	1	μА
Ivoutl	Vout "Low" Input Current	V <sub>IN</sub> = 5.5 \	/, V <sub>CE</sub> = V <sub>OUT</sub> = 0 V	-1	0	1	μА
RDISTR	On-resistance for Auto Discharge <sup>(1)</sup>	V <sub>IN</sub> = 3.6 V, V <sub>CE</sub> = 0 V			40		Ω
ILXLEAKH	LX "High" Leakage Current	V <sub>IN</sub> = V <sub>LX</sub> =	= 5.5 V, V <sub>CE</sub> = 0 V	-1	0	5	μА
ILXLEAKL	LX "Low" Leakage Current	V <sub>IN</sub> = 5.5 \	/, V <sub>CE</sub> = V <sub>LX</sub> = 0 V	-5	0	1	μА
V <sub>CEH</sub>	CE "High" Input Voltage	V <sub>IN</sub> = 5.5 \	l .	1.0			V
V <sub>CEL</sub>	CE "Low" Input Voltage	V <sub>IN</sub> = 2.3 \	l .			0.4	V
V <sub>MODEH</sub>	MODE "High" Input Voltage	V <sub>IN</sub> = V <sub>CE</sub> =	= 5.5 V	1.0			V
V <sub>MODEL</sub>	MODE "Low" Input Voltage	V <sub>IN</sub> = V <sub>CE</sub> :	= 2.3 V			0.4	V
	On-resistance of	RP509Z	V <sub>IN</sub> =3.6V, I <sub>LX</sub> =-100mA		0.175		Ω
Ronp	Pch. Transistor	RP509N			TBD		Ω
	On-resistance of	RP509Z	V <sub>IN</sub> =3.6V, I <sub>LX</sub> =-100mA		0.155		Ω
R <sub>ONN</sub>	Nch. Transistor	RP509N			TBD		Ω
Maxduty	Maximum Duty Cycle			100			%
tstart	Soft-start Time	$V_{IN} = V_{CE} = 3.6 \text{ V } (V_{SET} \le 2.6 \text{ V}),$ $V_{IN} = V_{CE} = V_{SET} + 1 \text{ V } (V_{SET} > 2.6 \text{ V})$			150	300	μS
I <sub>LXLIM</sub>	LX Current Limit	$V_{IN} = V_{CE} = 3.6 \text{ V (V}_{SET} \le 2.6 \text{ V)},$ $V_{IN} = V_{CE} = V_{SET} + 1 \text{ V (V}_{SET} > 2.6 \text{ V)}$		1200	1600		mA
V <sub>UVLO1</sub>	LIVI O Throohold Volto	V <sub>IN</sub> = V <sub>CE</sub> ,	Falling	1.85	2.00	2.20	V
V <sub>UVLO2</sub>	UVLO Threshold Voltage	V <sub>IN</sub> = V <sub>CE</sub> ,	Rising	1.90	2.05	2.25	V
T <sub>TSD</sub>	Thermal Shutdown Threshold	Tj, Rising			140		°C
T <sub>TSR</sub>	Temperature	Tj, Falling			100		°C

All test items listed under Electrical Characteristics are done under the pulse load condition (Tj  $\approx$  Ta = 25 $^{\circ}$ C).

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<sup>(1)</sup> RP509x001D only

Test circuit is operated with "Open Loop Control" (GND = 0 V), unless otherwise specified.

RP509Zxx2A/B, RP509Nxx2A/B **(under development)** Electrical Characterisitcs

 $(Ta = 25^{\circ}C)$ 

Symbol	Item		Condition		Min.	Тур.	Max.	Unit
		V <sub>IN</sub> = V <sub>CE</sub> =		V <sub>SET</sub> ≥ 1.2 V	x 0.985	71	x 1.015	
Vouт	Output Voltage	$V_{SET} \le 2.6$ $V_{IN} = V_{CE} = 0$	6 V),					V
		V (VSET > 2		V <sub>SET</sub> < 1.2 V	-0.018		+0.018	
ΔV <sub>OUT</sub> / Δ <b>Ta</b>	Output Voltage Temperature Coefficient	-40 °C ≤ T	a ≤ 85 °C			±100		ppm/
fosc	Oscillator Frequency	V <sub>IN</sub> = V <sub>CE</sub> = "Closed Lo	3.6 V, V <sub>SET</sub> cop Contro		4.8	6.0	7.2	MHz
I <sub>DD</sub>	Supply Current	VIN = VCE =	= Vouт = 3	$6V, V_{MODE} = 0V$		15		μΑ
ISTANDBY	Standby Current	VIN = 5.5 V	/,V <sub>CE</sub> = 0 \	/		0	5	μΑ
Ісен	CE "High" Input Current	VIN = VCE =	= 5.5 V		-1	0	1	μΑ
ICEL	CE "Low" Input Current	V <sub>IN</sub> = 5.5 \	/,V <sub>CE</sub> = 0 \	/	-1	0	1	μΑ
I <sub>MODEH</sub>	MODE "High" Input Current	V <sub>IN</sub> = V <sub>MOD</sub>	<sub>E</sub> = 5.5 V,	V <sub>CE</sub> = 0 V	-1	0	1	μΑ
I <sub>MODEL</sub>	MODE "Low" Input Current	V <sub>IN</sub> = 5.5 \	, V <sub>CE</sub> = V <sub>I</sub>	MODE = 0 V	-1	0	1	μΑ
Ivouth	Vout "High" Input Current	V <sub>IN</sub> = V <sub>OUT</sub>	= 5.5 V, \	/ce = 0 V	-1	0	1	μΑ
IVOUTL	Vout "Low" Input Current	V <sub>IN</sub> = 5.5 \	/, Vce = V	оит = 0 V	-1	0	1	μΑ
RDISTR	On-resistance for Auto Discharger <sup>(1)</sup>	V <sub>IN</sub> = 3.6 \	/, V <sub>CE</sub> = 0	V		40		Ω
ILXLEAKH	LX "High" Leakage Current	V <sub>IN</sub> = V <sub>LX</sub> =	= 5.5 V, V	ce = 0 V	-1	0	5	μΑ
I <sub>LXLEAKL</sub>	LX "Low" Leakage Current	V <sub>IN</sub> = 5.5 \	/, V <sub>CE</sub> = V	LX = 0 V	-5	0	1	μΑ
V <sub>CEH</sub>	CE "High" Input Voltage	V <sub>IN</sub> = 5.5 \	/		1.0			V
V <sub>CEL</sub>	CE "Low" Input Voltage	V <sub>IN</sub> = 2.3 \	/				0.4	V
V <sub>MODEH</sub>	MODE "High" Input Voltage	VIN = VCE =	= 5.5 V		1.0			V
V <sub>MODEL</sub>	MODE "Low" Input Voltage	VIN = VCE	= 2.3 V				0.4	V
D	On-resistance of	RP509Z	V <sub>IN</sub> =3.6\	/, I <sub>LX</sub> =-100mA		0.175		Ω
Ronp	Pch. transistor	RP509N				TBD		Ω
	On-resistance of	RP509Z	V <sub>IN</sub> =3.6\	/, I <sub>LX</sub> =-100mA		0.155		Ω
R <sub>ONN</sub>	Nch. transistor	RP509N				TBD		Ω
Maxduty	Maximum Duty Cycle		•		100			%
tstart	Soft-start Time	V <sub>IN</sub> = V <sub>CE</sub> = V <sub>IN</sub> = V <sub>CE</sub> =		- ≤ 2.6 V), (V <sub>SET</sub> > 2.6 V)		150	300	μS
I <sub>LXLIM</sub>	LX Current Limit	$V_{IN} = V_{CE} = 3.6 \text{ V } (V_{SET} \le 2.6 \text{ V}),$ $V_{IN} = V_{CE} = V_{SET} + 1 \text{ V } (V_{SET} > 2.6 \text{ V})$		600	1000		mA	
V <sub>UVLO1</sub>	LIVI O Throphold Voltage	VIN = VCE,	Falling		1.85	2.00	2.20	V
V <sub>UVLO2</sub>	UVLO Threshold Voltage	VIN = VCE,	Rising		1.90	2.05	2.25	V
T <sub>TSD</sub>	Thermal Shutdown	Tj, Rising				140		°C
T <sub>TSR</sub>	Threshold Temperature	Tj, Falling				100		°C
	as listed under Electrical Character		ana undar i	ha nulaa laad aan	dition /Ti		°C)	0

All test items listed under Electrical Characteristics are done under the pulse load condition (Tj  $\approx$  Ta = 25°C).

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<sup>(1)</sup> RP509xxx2B only

NO.EA-362-160510

Test circuit is operated with "Open Loop Control" (GND = 0 V), unless otherwise specified.

RP509Z002C/D, RP509N002C/D **(under development)** Electrical Characterisitcs

 $(Ta = 25^{\circ}C)$ 

Symbol	Item		Conditions	Min.	Тур.	Max.	Unit
V <sub>FB</sub>	Feedback Voltage	VIN = VCE =	= 3.6 V	0.591	0.600	0.609	V
ΔV <sub>FB</sub> / ΔTa	Feedback Voltage Temperature Coefficient	-40 °C ≤ T		±100		ppm/ °C	
fosc	Oscillator Frequency	V <sub>IN</sub> = V <sub>CE</sub> = 1 Loop Contr	3.6 V, V <sub>SET</sub> = 1.8 V, "Closed ol"	4.8	6.0	7.2	MHz
$I_{DD}$	Supply Current	V <sub>IN</sub> = V <sub>CE</sub> =	= V <sub>OUT</sub> = 3.6V, V <sub>MODE</sub> = 0V		15		μΑ
ISTANDBY	Standby Current	V <sub>IN</sub> = 5.5 V	/,V <sub>CE</sub> = 0 V		0	5	μА
Ісен	CE "High" Input Current	VIN = VCE =	= 5.5 V	-1	0	1	μА
ICEL	CE "Low" Input Current	V <sub>IN</sub> = 5.5 V	/,V <sub>CE</sub> = 0 V	-1	0	1	μА
I <sub>MODEH</sub>	MODE "High" Input Current	VIN = VMOD	E = 5.5 V, VCE = 0 V	-1	0	1	μΑ
I <sub>MODEL</sub>	MODE "Low" Input Current	V <sub>IN</sub> = 5.5 V	/, Vce = Vmode = 0 V	-1	0	1	μΑ
I <sub>VOUTH</sub>	V <sub>OUT</sub> "High" Input Current	V <sub>IN</sub> = V <sub>OUT</sub>	= 5.5 V, V <sub>CE</sub> = 0 V	-1	0	1	μΑ
I <sub>VOUTL</sub>	V <sub>OUT</sub> "Low" Input Current	V <sub>IN</sub> = 5.5 \	/, V <sub>CE</sub> = V <sub>OUT</sub> = 0 V	-1	0	1	μΑ
RDISTR	On-resistance for Auto Discharge <sup>(1)</sup>	V <sub>IN</sub> = 3.6 \		40		Ω	
I <sub>LXLEAKH</sub>	LX "High" Leakage Current	$V_{IN} = V_{LX} =$	= 5.5 V, V <sub>CE</sub> = 0 V	-1	0	5	μА
ILXLEAKL	LX "Low" Leakage Current	V <sub>IN</sub> = 5.5 \	/, V <sub>CE</sub> = V <sub>LX</sub> = 0 V	-5	0	1	μΑ
Vceh	CE "High" Input Voltage	V <sub>IN</sub> = 5.5 \	/	1.0			V
Vcel	CE "Low" Input Voltage	V <sub>IN</sub> = 2.3 \	1			0.4	V
V <sub>MODEH</sub>	MODE "High" Input Voltage	VIN = VCE =	= 5.5 V	1.0			V
V <sub>MODEL</sub>	MODE "Low" Input Voltage	V <sub>IN</sub> = V <sub>CE</sub> =	= 2.3 V			0.4	V
-	On-resistance of	RP509Z	V <sub>IN</sub> =3.6V, I <sub>LX</sub> =-100mA		0.175		Ω
$R_{ONP}$	Pch. Transistor	RP509N			TBD		Ω
	On-resistance of	RP509Z	V <sub>IN</sub> =3.6V, I <sub>LX</sub> =-100mA		0.155		Ω
RONN	Nch. Transistor	RP509N			TBD		Ω
Maxduty	Maximum Duty Cycle			100			%
tstart	Soft-start Time	$V_{IN} = V_{CE} = 3.6 \text{ V } (V_{SET} \le 2.6 \text{ V}),$ $V_{IN} = V_{CE} = V_{SET} + 1 \text{ V } (V_{SET} > 2.6 \text{ V})$			150	300	μS
I <sub>LXLIM</sub>	LX Current Limit	$V_{IN} = V_{CE} = 3.6 \text{ V } (V_{SET} \le 2.6 \text{ V}),$ $V_{IN} = V_{CE} = V_{SET} + 1 \text{ V } (V_{SET} > 2.6 \text{ V})$		600	1000		mA
V <sub>UVLO1</sub>	LIVI O Throohold Voltage	VIN = VCE,	Falling	1.85	2.00	2.20	V
V <sub>UVLO2</sub>	UVLO Threshold Voltage	VIN = VCE,	Rising	1.90	2.05	2.25	V
T <sub>TSD</sub>	Thermal Shutdown	Tj, Rising			140		°C
T <sub>TSR</sub>	Threshold Temperature	Tj, Falling			100		°C

All test items listed under Electrical Characteristics are done under the pulse load condition (Tj  $\approx$  Ta = 25°C).

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<sup>(1)</sup> RP509x002D only

# **Electrical Characteristics by Different Output Voltage**

RP509ZxxXA/B, RP509NxxXA/B <b>(under development)</b> (Fixed Output Voltage Type)						
Product Name		V <sub>оит</sub> [V] (Та = 25°С)				
Froduct Name	Min.	Тур.	Max.			
RP509x06XA/B	0.582	0.600	0.618			
RP509x07XA/B	0.682	0.700	0.718			
RP509x08XA/B	0.782	0.800	0.818			
RP509x09XA/B	0.882	0.900	0.918			
RP509x10XA/B	0.982	1.000	1.018			
RP509x11XA/B	1.082	1.100	1.118			
RP509x12XA/B	1.182	1.200	1.218			
RP509x13XA/B	1.281	1.300	1.319			
RP509x14XA/B	1.379	1.400	1.421			
RP509x15XA/B	1.478	1.500	1.522			
RP509x16XA/B	1.576	1.600	1.624			
RP509x17XA/B	1.675	1.700	1.725			
RP509x18XA/B	1.773	1.800	1.827			
RP509x19XA/B	1.872	1.900	1.928			
RP509x20XA/B	1.970	2.000	2.030			
RP509x21XA/B	2.069	2.100	2.131			
RP509x22XA/B	2.167	2.200	2.233			
RP509x23XA/B	2.266	2.300	2.334			
RP509x24XA/B	2.364	2.400	2.436			
RP509x25XA/B	2.463	2.500	2.537			
RP509x26XA/B	2.561	2.600	2.639			
RP509x27XA/B	2.660	2.700	2.740			
RP509x28XA/B	2.758	2.800	2.842			
RP509x29XA/B	2.857	2.900	2.943			
RP509x30XA/B	2.955	3.000	3.045			
RP509x31XA/B	3.054	3.100	3.146			
RP509x32XA/B	3.152	3.200	3.248			
RP509x33XA/B	3.251	3.300	3.349			

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### OPERATING DESCRIPTIONS

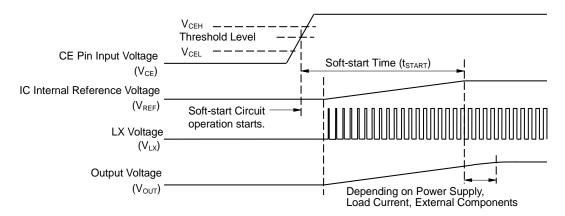
#### **Soft-start Time**

#### Starting-up with CE Pin

The IC starts to operate when the CE pin voltage (V<sub>CE</sub>) exceeds the threshold voltage. The threshold voltage is preset between CE "H" input voltage (V<sub>CEH</sub>) and CE "L" input voltage (V<sub>CEL</sub>).

After the start-of the start-up of the IC, soft-start circuit starts to operate. Then, after a certain period of time, the reference voltage (V<sub>REF</sub>) in the IC gradually increases up to the specified value.

Notes: Soft start time  $(t_{START})^{(1)}$  is not always equal to the turn-on speed of the step-down DC/DC converter. Please note that the turn-on speed could be affected by the power supply capacity, the output current, the inductance value and the  $C_{OUT}$  value.



Timing Chart when Starting-up with CE Pin

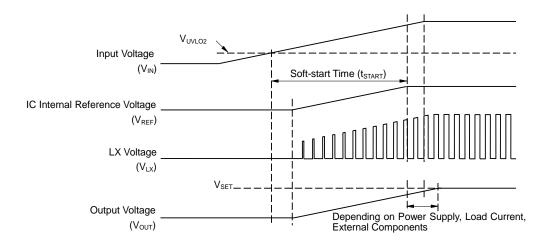
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<sup>(1)</sup> Soft-start time (tstart) indicates the duration until the reference voltage (VREF) reaches the specified voltage after soft-start circuit's activation.

### Starting-up with Power Supply

After the power-on, when  $V_{IN}$  exceeds the UVLO released voltage ( $V_{UVLO2}$ ), the IC starts to operate. Then, soft-start circuit starts to operate and after a certain period of time,  $V_{REF}$  gradually increases up to the specified value.

Notes: Please note that the turn-on speed of  $V_{OUT}$  could be affected by the power supply capacity, the output current, the inductance value, the  $C_{OUT}$  value and the turn-on speed of  $V_{IN}$  determined by  $C_{IN}$ .



**Timing Chart when Starting-up with Power Supply** 

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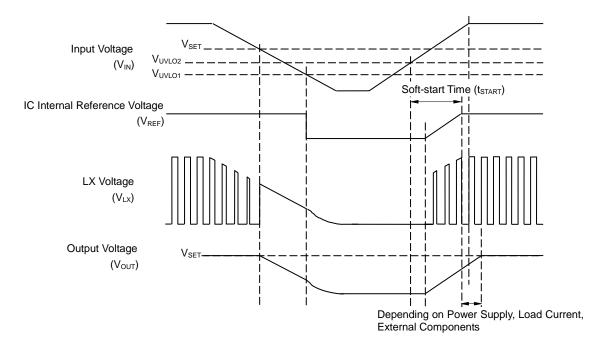
### **Under Voltage Lockout (UVLO) Circuit**

If  $V_{IN}$  becomes lower than  $V_{SET}$ , the step-down DC/DC converter stops the switching operation and ON duty becomes 100%, and then  $V_{OUT}$  gradually drops according to  $V_{IN}$ .

If the  $V_{IN}$  drops more and becomes lower than the UVLO detector threshold ( $V_{UVLO1}$ ), the UVLO circuit starts to operate,  $V_{REF}$  stops, and Pch. and Nch. built-in switch transistors turn "OFF". As a result,  $V_{OUT}$  drops according to the  $C_{OUT}$  capacitance value and the load.

To restart the operation,  $V_{IN}$  needs to be higher than  $V_{UVLO2}$ . The timing chart below shows the voltage shifts of  $V_{REF}$ ,  $V_{LX}$  and  $V_{OUT}$  when  $V_{IN}$  value is varied.

Notes: Falling edge (operating) and rising edge (releasing) waveforms of  $V_{OUT}$  could be affected by the initial voltage of  $C_{OUT}$  and the output current of  $V_{OUT}$ .

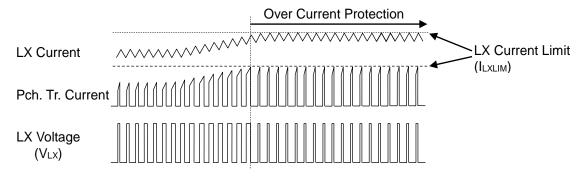


Timing Chart with Variations in Input Voltage (VIN)

#### **Current limit Circuit**

Current limit circuit supervises the inductor peak current (the peak current flowing through Pch. Tr.) in each switching cycle, and if the current exceeds the LX current limit (I<sub>LXLIM</sub>), it turns off Pch. Tr. I<sub>LXLIM</sub> of the RP509x is set to Typ.1.6 A or Typ.1.0 A.

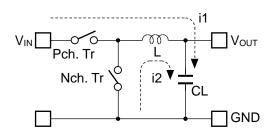
Notes: I<sub>LXLIM</sub> could be easily affected by self-heating or ambient environment. If the V<sub>IN</sub> drops dramatically or becomes unstable due to short-circuit, protection operation could be affected.

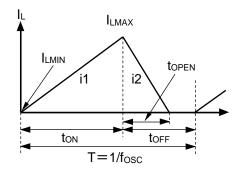


**Over-Current Protection Operation** 

### Operation of Step-down DC/DC Converter and Output Current

The step-down DC/DC converter charges energy in the inductor when LX Tr. turns "ON", and discharges the energy from the inductor when LX Tr. turns "OFF" and controls with less energy loss, so that a lower output voltage ( $V_{OUT}$ ) than the input voltage ( $V_{IN}$ ) can be obtained. The operation of the step-down DC/DC converter is explained in the following figures.





**Basic Circuit** 

Inductor Current (IL) flowing through Inductor (L)

**Step1.** Pch. Tr. turns "ON" and I<sub>L</sub> (i1) flows, L is charged with energy. At this moment, i1 increases from the minimum inductor current (I<sub>LMIN</sub>), which is 0 A, and reaches the maximum inductor current (I<sub>LMAX</sub>) in proportion to the on-time period (t<sub>ON</sub>) of Pch. Tr.

**Step2.** When Pch. Tr. turns "OFF", L tries to maintain  $I_L$  at  $I_{LMAX}$ , so L turns Nch Tr. "ON" and  $I_L$  (i2) flows into L.

**Step3.** i2 decreases gradually and reaches I<sub>LMIN</sub> after the open-time period (t<sub>OPEN</sub>) of Nch. Tr., and then Nch. Tr. turns "OFF". This is called discontinuous current mode.

As the output current ( $I_{OUT}$ ) increases, the off-time period ( $t_{OFF}$ ) of Pch. Tr. runs out before  $I_L$  reaches  $I_{LMIN}$ . The next cycle starts, and Pch. Tr. turns "ON" and Nch. Tr. turns "OFF", which means  $I_L$  starts increasing from  $I_{LMIN}$ . This is called continuous current mode.

In PWM mode,  $V_{\text{OUT}}$  is maintained by controlling ton. The oscillator frequency ( $f_{\text{OSC}}$ ) is maintained constant during PWM mode.

When the step-down DC/DC operation is constant,  $I_{LMIN}$  and  $I_{LMAX}$  during ton of Pch. Tr. would be same as during  $t_{OFF}$  of Pch. Tr. The current differential between  $I_{LMAX}$  and  $I_{LMIN}$  is described as  $\Delta I$ , as the following equation 1.

$$\Delta I = I_{LMAX} - I_{LMIN} = V_{OUT} \times t_{OPEN} / L = (V_{IN} - V_{OUT}) \times t_{ON} / L$$
 Equation 1

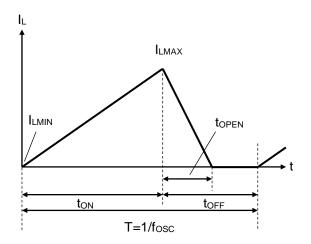
The above equation is predicated on the following requirements.

T = 1 / fosc = ton + toff  
duty (%) = ton / T 
$$\times$$
 100 = ton  $\times$  fosc  $\times$  100  
topen  $\leq$  toff

In Equation 1, " $V_{OUT} \times t_{OPEN} / L$ " shows the amount of current change in "OFF" state. Also, " $(V_{IN} - V_{OUT}) \times t_{ON} / L$ " shows the amount of current change at "ON" state.

#### **Discontinuous Mode and Continuous Mode**

As illustrated in Figure A., when  $l_{\text{OUT}}$  is relatively small,  $t_{\text{OPEN}} < t_{\text{OFF}}$ . In this case, the energy charged into L during  $t_{\text{ON}}$  will be completely discharged during  $t_{\text{OFF}}$ , as a result,  $l_{\text{LMIN}} = 0$ . This is called discontinuous mode. When  $l_{\text{OUT}}$  is gradually increased, eventually  $t_{\text{OPEN}} = t_{\text{OFF}}$  and when  $l_{\text{OUT}}$  is increased further, eventually  $l_{\text{LMIN}} > 0$  as illustrated in Figure B. This is called continuous mode.



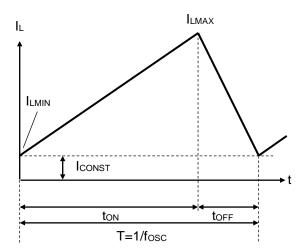


Figure A. Discontinuous Mode

Figure B. Continuous Mode

In the continuous mode, the solution of Equation 1 is described as tonc.

 $tonc = T \times V_{OUT} / V_{IN}$  Equation 2

When  $t_{ONC}$ , it is discontinuous mode, and when  $t_{ONC}$  =  $t_{ONC}$ , it is continuous mode.

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#### Forced PWM Mode and VFM Mode

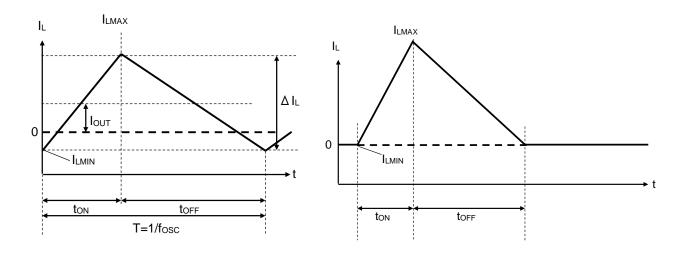
Output voltage controlling method is selectable between a forced PWM control type and a PWM/VFM auto-switching control type, and can be set by the MODE pin. The forced PWM control switches at fixed frequency rate in order to reduce noise in low output current. The PWM/VFM auto-switching control automatically switches from PWM mode to VFM mode in order to achieve high efficiency in low output current.

#### **Forced PWM Mode**

By setting the MODE pin to "H", the IC switches the frequency at the fixed rate to reduce noise even when the output load is light. Therefore, when  $I_{OUT}$  is  $\Delta I_L/2$  or less,  $I_{LMIN}$  becomes less than "0". That is, the accumulated electricity in CL is discharged through the IC side while  $I_L$  is increasing from  $I_{LMIN}$  to "0" during ton, and also while  $I_L$  is decreasing from "0" to  $I_{LMIN}$  during  $I_{LMIN}$  during  $I_{LMIN}$  during top.

#### **VFM Mode**

By setting the MODE pin to "L", in low output current, the IC automatically switches into VFM mode in order to achieve high efficiency. In VFM mode, ton is determined depending on V<sub>IN</sub> and V<sub>OUT</sub>.



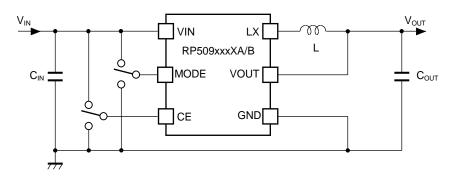
**Forced PWM Mode** 

**VFM Mode** 

# **APPLICATION INFORMATION**

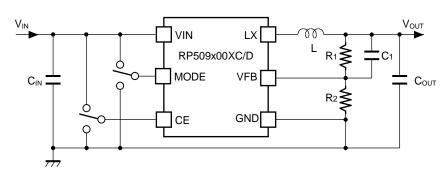
# **Application Circuits**

MODE = "H": forced PWM control, MODE = "L": PWM/VFM auto-switching control



RP509xxxXA/B (Fixed Output Voltage Type)

MODE = "H": forced PWM control, MODE = "L": PWM/VFM auto-switching control



RP509x00XC/D (Adjustable Output Voltage Type)

# **Recommended External Components**

Symbol	Descriptions
Cin	4.7 μF and more, Ceramic Capacitor,
	See the table of "Input Voltage vs. Capacitance" in the following page.
0	10 μF, Ceramic Capacitor,
Соит	See the table of "Set Output Voltage (VSET) vs. Capacitance" in the following page.
L	0.47 μH to 0.56 μH,
	See the table of "Inductance Range vs. PWM Frequency" in the following page.

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# Input Voltage vs. Capacitance

V <sub>IN</sub> [V]	Size [mm]	C <sub>IN</sub> [µF]	Rated Voltage [V]	Model
	1005	4.7	6.3	JMK105BBJ475MV (Taiyo Yuden)
		10	6.3	C1005X5R0J106M050BC (TDK)
	1608	4.7		GRM188R60J475ME84 (Murata)
			6.3	GRM188R60J475ME19 (Murata)
Up to 4.5			0.3	C1608X5R0J475M080AB (TDK)
				JMK107BJ475MA (Taiyo Yuden)
		10		GRM188R60J106ME47 (Murata)
			6.3	C1608X5R0J106M080AB (TDK)
				JMK107ABJ106MA (Taiyo Yuden)
	1005	10	6.3	C1005X5R0J106M050BC (TDK)
	1608	4.7		GRM188R60J475ME84 (Murata)
Up to 5.5			6.3	GRM188R60J475ME19 (Murata)
				JMK107BJ475MA (Taiyo Yuden)
		10		GRM188R60J106ME47 (Murata)
			6.3	C1608X5R0J106M080AB (TDK)
				JMK107ABJ106MA (Taiyo Yuden)

# Set Output Voltage ( $V_{\text{SET}}$ ) vs. Capacitance

Version	V <sub>SET</sub> [V]	Size [mm]	С <sub>оит</sub> [µF]	Rated Voltage [V]	Model
	0.6 to 1.8	1005	10	4	GRM155R60G106ME44 (Murata) C1005X5R0G106M050BB (TDK) AMK105CBJ106MV (Taiyo Yuden)
			10	6.3	C1005X5R0J106M050BC (TDK)
RP509xxxXA/B		1608	10	6.3	GRM188R60J106ME47 (Murata) C1608X5R0J106M080AB (TDK) JMK107ABJ106MA (Taiyo Yuden)
or RP509x00X/C/D	1.9 to 3.3	1005	10	4	GRM155R60G106ME44(Murata) C1005X5R0G106M050BB (TDK) AMK105CBJ106MV (Taiyo Yuden)
			10	6.3	C1005X5R0J106M050BC (TDK)
		1608	10	6.3	GRM188R60J106ME47 (Murata) C1608X5R0J106M080AB (TDK) JMK107ABJ106MA (Taiyo Yuden)
RP509x00XC/D	3.4 to 4.5	1608	10	6.3	GRM188R60J106ME47 (Murata) C1608X5R0J106M080AB (TDK) JMK107ABJ106MA (Taiyo Yuden)

**Inductance Range vs. PWM Frequency** 

Version	PWM Frequency [MHz]	Size [mm]	Height(Max) [mm]	L [µH]	Rdc(Typ) [mΩ]	Model
RP509xxxXA/B or RP509x00XC/D	6.0	1608	0.95	0.47	110	MDT1608-CHR47M (TOKO)
					90	MDT1608-CRR47M (TOKO)
		2012	1.0	0.5	60	MIPSZ2012D0R5 (FDK)
				0.56	65	MDT2012-CRR56N (TOKO)
				0.47	70	MLP2012HR47MT (TDK)
				0.54	65	MLP2012HR54MT (TDK)
				0.47	60	CKP2012NR47M-T (Taiyo Yuden)
				0.47	48	BRL2012TR47M6 (Taiyo Yuden)
				0.47	75	LQM21PNR47MG0 (Murata)

### Cautions in selecting external parts

- Choose a low ESR ceramic capacitor. The capacitance of C<sub>IN</sub> between V<sub>IN</sub> and GND should be more than or equal to 4.7 μF. The capacitance of a ceramic capacitor (C<sub>OUT</sub>) should be 10 μF. Also, choose the capacitor with consideration for bias characteristics and input/output voltages. See the above tables of "Input Voltage vs. Capacitance" and "Set Output Voltage vs. Capacitance".
- The phase compensation of this device is designed according to the C<sub>OUT</sub> and L values. The inductance range of an inductor should be between 0.47μH to 0.56 μH in order to gain stability. See the above table of "Inductance Range vs. PWM Frequency".
- Choose an inductor that has small DC resistance, has enough permissible current and is hard to cause magnetic saturation. If the inductance value of the inductor becomes extremely small under the load conditions, the peak current of LX may increase along with the load current. As a result, over current protection circuit may start to operate when the peak current of LX reaches to LX limit current. Therefore, choose an inductor with consideration for the value of I<sub>LXMAX</sub>. See the following page of "Calculation Conditions of LX Pin Maximum Output Current (I<sub>LXMAX</sub>)".
- As for the fixed output voltage type (RP509x00XC/D), Output Voltage (V<sub>SET</sub>) is settable by changing values
  of R1 and R2. V<sub>SET</sub> is given by the following expression.
- As for the adjustable output voltage type, the set output voltage (V<sub>SET</sub>) is adjustable by changing the
  resistance values of resistors (R1, R2) as follows. See the following table for each recommended value
  of R1, R2 and C1.

 $V_{SET} = V_{FB} \times (R1 + R2) / R2$ 

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#### Set Output Voltage (V<sub>SET</sub>) vs. R1 / R2 / C1 (Adjustable Output Voltage Type)

V <sub>SET</sub> [V]	R1 [kΩ]	R2 [kΩ]	C1 [pF]
0.6	0	220	Open
$0.6 < V_{SET} \le 0.9$		220	47
0.9 < <b>V</b> <sub>SET</sub> ≤ 1.8	R1 = (V <sub>SET</sub> / V <sub>FB</sub> -1 ) x R2	220	33
1.8 < <b>V</b> <sub>SET</sub> ≤ 2.1		150	10
2.1 < <b>V</b> <sub>SET</sub> ≤ 2.4		100	10
2.4 < <b>V</b> <sub>SET</sub> ≤ 2.7		68	10
2.7 < <b>V</b> <sub>SET</sub> ≤ 3.0		47	10
3.0 < <b>V</b> SET ≤ VIN		47	6.8

### Calculation Conditions of LX Pin Maximum Output Current (ILXMAX)

The following equations explain the relationship to determine  $I_{LXMAX}$  at the ideal operation of the ICs in continuous mode.

Ripple Current P-P value is described as I<sub>RP</sub>, ON resistance of Pch. Tr. is described as R<sub>ONP</sub>, ON resistance of Nch. Tr. is described as R<sub>ONN</sub>, and DC resistor of the inductor is described as R<sub>L</sub>.

First, when Pch. Tr. is "ON", Equation 1 is satisfied.

$$V_{IN} = V_{OUT} + (R_{ONP} + R_L) \times I_{OUT} + L \times I_{RP} / t_{ON}$$
 Equation 1

Second, when Pch. Tr. is "OFF" (Nch. Tr. is "ON"), Equation 2 is satisfied.

$$L \times I_{RP}$$
 / toff = Ronn × Iout + Vout + R<sub>L</sub> × Iout - Equation 2

Put Equation 2 into Equation 1 to solve ON duty of Pch. Tr. ( $D_{ON} = t_{ON} / (t_{OFF} + t_{ON})$ ):

$$D_{\text{ON}} = \left( V_{\text{OUT}} + R_{\text{ONN}} \times I_{\text{OUT}} + R_{\text{L}} \times I_{\text{OUT}} \right) / \left( V_{\text{IN}} + R_{\text{ONN}} \times I_{\text{OUT}} - R_{\text{ONP}} \times I_{\text{OUT}} \right) \cdots$$
 Equation 3

Ripple Current is described as follows:

$$I_{RP} = (V_{IN} - V_{OUT} - R_{ONP} \times I_{OUT} - R_{L} \times I_{OUT}) \times D_{ON} / f_{OSC} / L$$
Equation 4

Peak current that flows through L, and LX Tr. is described as follows:

$$I_{LXMAX} = I_{OUT} + I_{RP} / 2 \dots$$
 Equation 5

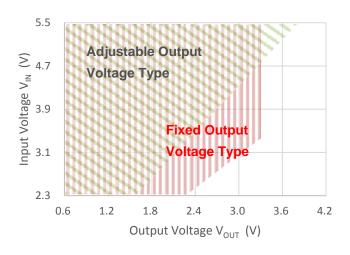
#### **TECHNICAL NOTES**

The performance of power source circuits using this IC largely depends on peripheral circuits. When selecting the peripheral components, please consider the conditions of use. Do not allow each component, PCB pattern or the IC to exceed their respected rated values (voltage, current, and power) when designing the peripheral circuits.

- Set the external components as close as possible to the IC and minimize the wiring between the components and the IC. Especially, place a capacitor (C<sub>IN</sub>) as close as possible to the VIN pin and GND.
- Ensure the VIN and GND lines are sufficiently robust. If their impedance is too high, noise pickup or unstable operation may result.
- The VIN line, the GND line, the VOUT line, an inductor, and LX should make special considerations for the large switching current flows.
- The wiring between the VOUT pin and an inductor (L) (RP509xxxXA/B) or between a resistor for setting output voltage (R1) and L (RP509x00XC/D) should be separated from the wiring between L and Load.
- Over current protection circuit may be affected by self-heating or power dissipation environment.
- In the case of the adjustable output voltage type, the input / output voltage ratio must become the following condition to achieve a high-efficiency with stable VFM mode at light load when the MODE pin is "L".

 $V_{OUT} / V_{IN} < 0.7$ 

V<sub>MODE</sub> = "L" PWM/VFM Auto Switching



Available Voltage Area with Stable VFM Mode (Adjustable Output Voltage Type)

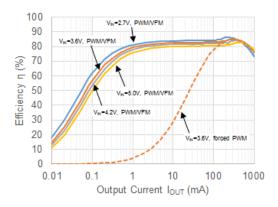
NO.EA-362-160510

# TYPICAL CHARACTERISTICS

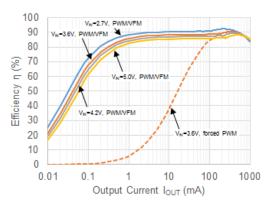
Typical Characteristics in RP509Z are intended to be used as reference data, and they are not guaranteed.

#### 1) Efficiency vs. Output Current

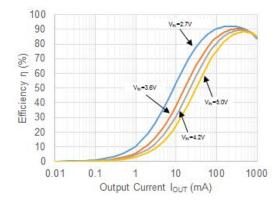
 $V_{OUT} = 1.0 \text{ V}$  $V_{MODE} = \text{"L" PWM/VFM Auto Switching L} = \text{MIPSZ2012D0R5}$ 



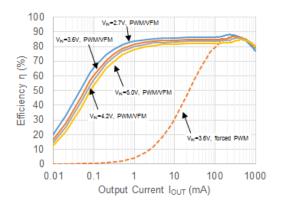
 $V_{OUT} = 1.8 \text{ V}$   $V_{MODE} = \text{"L" PWM/VFM Auto Switching}$  L = MIPSZ2012D0R5



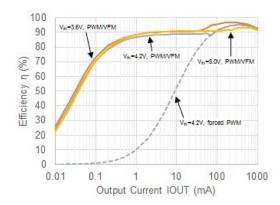
 $V_{OUT} = 1.8 \text{ V}$   $V_{MODE} = "H" \text{ Forced PWM Mode}$ L = MIPSZ2012D0R5



 $V_{OUT} = 1.2 \text{ V}$  $V_{MODE} = \text{"L" PWM/VFM Auto Switching L} = \text{MIPSZ2012D0R5}$ 



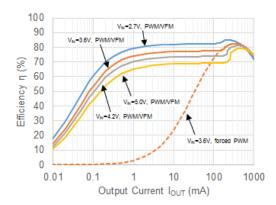
 $V_{\text{OUT}} = 3.3 \text{ V (Fixed Output Voltage Type)}$   $V_{\text{MODE}} = \text{"L" PWM/VFM Auto Switching}$  L = MIPSZ2012D0R5



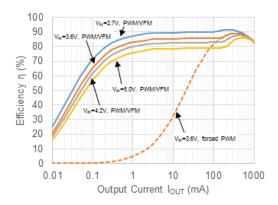
[Small Mount Solution]

Vout = 1.0 V

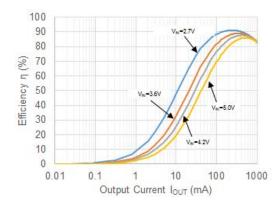
VMODE = "L" PWM/VFM Auto Switching
L = MDT1608-CRR47M



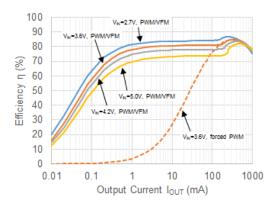
 $V_{OUT} = 1.8 \text{ V}$  $V_{MODE} = \text{"L" PWM/VFM Auto Switching L} = \text{MDT1608-CRR47M}$ 



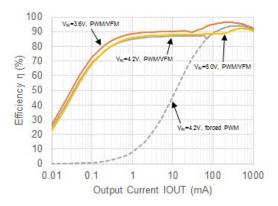
 $V_{OUT}$  = 1.8 V  $V_{MODE}$  = "H" Forced PWM Mode L = MDT1608-CRR47M



 $V_{OUT}$  = 1.2 V  $V_{MODE}$  = "L" PWM/VFM Auto Switching L = MDT1608-CRR47M



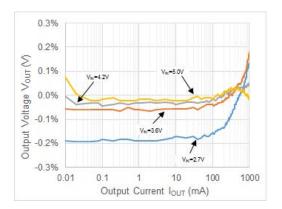
 $V_{OUT} = 3.3 \text{ V (Fixed Output Voltage Type)}$   $V_{MODE} = \text{"L" PWM/VFM Auto Switching}$ L = MDT1608-CRR47M



NO.EA-362-160510

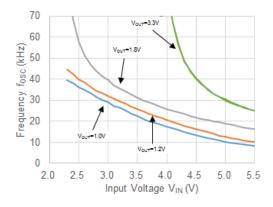
# 2) Output Voltage vs. Output Current

 $V_{IN} = 3.6 \text{ V}, V_{OUT} = 1.8 \text{ V}$  $V_{MODE} = \text{"L" PWM/VFM Auto Switching}$ 

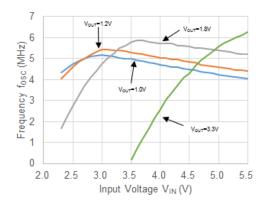


# 3) Oscillator Frequency vs. Input Voltage

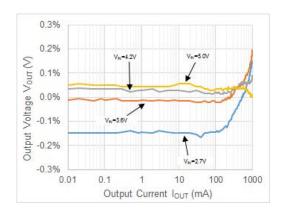
 $I_{OUT} = 1.0 \text{ mA}$  $V_{MODE} = \text{"L" PWM/VFM Auto Switching}$ 



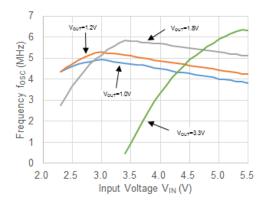
 $I_{OUT} = 500 \text{ mA}$   $V_{MODE} = "H" \text{ Forced PWM Mode}$ 



 $V_{\text{IN}} = 3.6 \text{ V}, V_{\text{OUT}} = 1.8 \text{ V}$   $V_{\text{MODE}} =$  "H" Forced PWM Mode

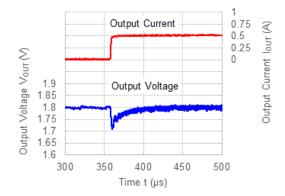


 $I_{OUT} = 1.0 \text{ mA}$  $V_{MODE} = "H" \text{ Forced PWM Mode}$ 

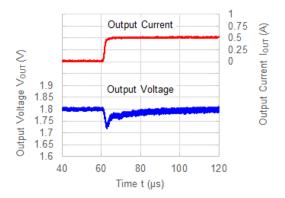


#### 4) Load Transient Response Waveform

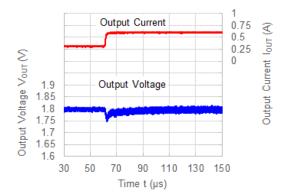
 $V_{IN} = 3.6 \text{ V}, V_{OUT} = 1.8 \text{ V}$   $V_{MODE} = \text{"L" PWM/VFM Auto Switching I}_{OUT} = 1.0 -> 500 \text{ mA}$ 



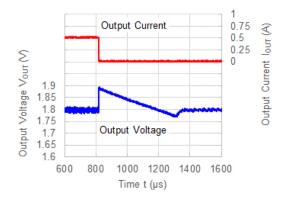
 $V_{IN}$  = 3.6 V,  $V_{OUT}$  = 1.8 V  $V_{MODE}$  = "H" Forced PWM Mode  $I_{OUT}$  = 1.0 -> 500 mA



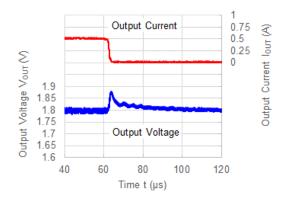
 $V_{\text{IN}}$  = 3.6 V,  $V_{\text{OUT}}$  = 1.8 V  $V_{\text{MODE}}$  = "L" PWM/VFM Auto Switching  $I_{\text{OUT}}$  = 300 -> 600 mA



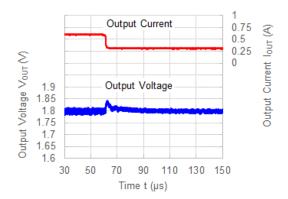
 $V_{\text{IN}} = 3.6$  V,  $V_{\text{OUT}} = 1.8$  V  $V_{\text{MODE}} =$  "L" PWM/VFM Auto Switching  $I_{\text{OUT}} = 500$  -> 1.0 mA



 $V_{IN}$  = 3.6 V,  $V_{OUT}$  = 1.8 V  $V_{MODE}$  = "H" Forced PWM Mode  $V_{OUT}$  = 500 -> 1.0 mA

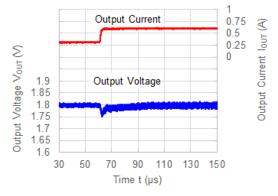


 $V_{\text{IN}} = 3.6 \text{ V}, \, V_{\text{OUT}} = 1.8 \text{ V}$   $V_{\text{MODE}} =$  "L" PWM/VFM Auto Switching  $I_{\text{OUT}} = 600$  -> 300 mA



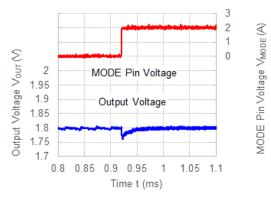
#### NO.EA-362-160510

 $V_{IN} = 3.6 \text{ V}, V_{OUT} = 1.8 \text{ V}$   $V_{MODE} = "H"$  Forced PWM Mode  $I_{OUT} = 300 \rightarrow 600 \text{ mA}$ 



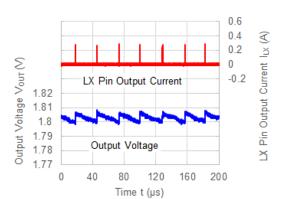
# 5) Mode Switching Waveform

 $V_{IN} = 3.6 \text{ V}, V_{OUT} = 1.8 \text{ V}$   $I_{OUT} = 1.0 \text{ mA}$   $V_{MODE} = "L" -> "H"$ 

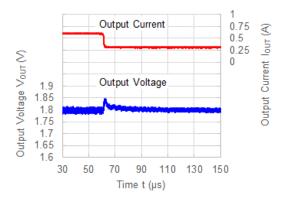


# 6) Output Voltage Waveform

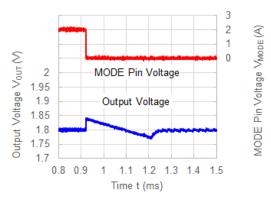
VIN = 3.6 V, V<sub>OUT</sub> = 1.8 V V<sub>MODE</sub> = "L" PWM/VFM Auto Switching I<sub>OUT</sub> = 1.0 mA



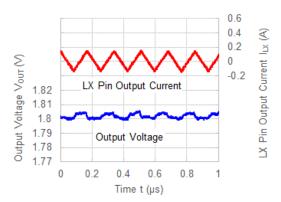
 $V_{IN} = 3.6 \text{ V}, V_{OUT} = 1.8 \text{ V}$   $V_{MODE} = \text{"H" Forced PWM Mode}$   $I_{OUT} = 600 \text{ -> } 300 \text{ mA}$ 



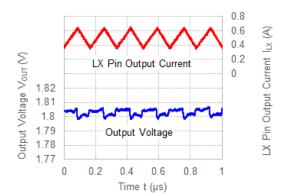
$$\begin{split} V_{\text{IN}} &= 3.6 \text{ V, } V_{\text{OUT}} = 1.8 \text{ V} \\ I_{\text{OUT}} &= 1.0 \text{ mA} \\ V_{\text{MODE}} &= "H" \rightarrow "L" \end{split}$$



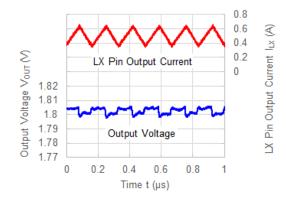
 $V_{\text{IN}} = 3.6 \text{ V}, \, V_{\text{OUT}} = 1.8 \text{ V}$   $V_{\text{MODE}} =$  "H" Forced PWM Mode  $I_{\text{OUT}} = 1.0 \text{ mA}$ 



 $V_{\text{IN}}$  = 3.6 V,  $V_{\text{OUT}}$  = 1.8 V  $V_{\text{MODE}}$  = "L" PWM/VFM Auto Switching  $I_{\text{OUT}}$  = 500 mA



 $V_{\text{IN}} = 3.6 \text{ V}, \, V_{\text{OUT}} = 1.8 \text{ V}$   $V_{\text{MODE}} =$  "H" Forced PWM Mode  $I_{\text{OUT}} = 500 \text{ mA}$ 



Ver. B

The power dissipation of the package is dependent on PCB material, layout, and environmental conditions. The following conditions are used in this measurement.

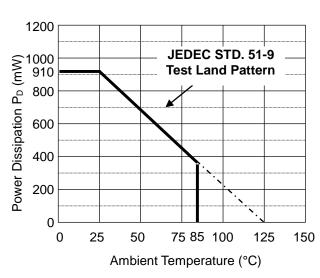
#### **Measurement Conditions**

	JEDEC STD. 51-9 Test Land Pattern
Environment	Mounting on Board (Wind Velocity = 0 m/s)
Board Material	Glass Cloth Epoxy Plastic (Four-Layer Board)
Board Dimensions	101.5 mm x 114.5 mm x 1.6 mm
Copper Ratio	Outer Layers (First and Fourth Layers): 60% Inner Layers (Second and Third Layers): 100%

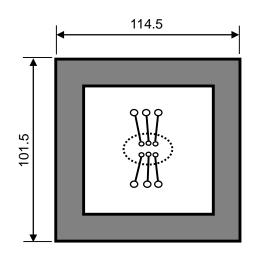
#### **Measurement Result**

(Ta = 25°C, Tjmax = 125°C)

	JEDEC STD. 51-9 Test Land Pattern
Power Dissipation	910 mW
Thermal Resistance	θja = (125 - 25°C) / 0.91 W = 109 °C/W



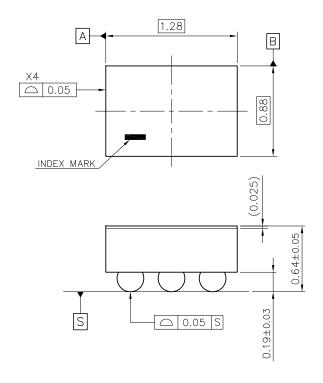
Power Dissipation vs. Ambient Temperature

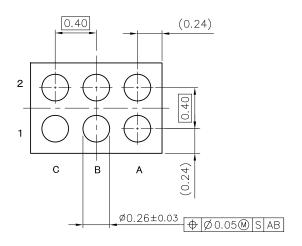


() IC Mount Area (mm)

Measurement Board Pattern

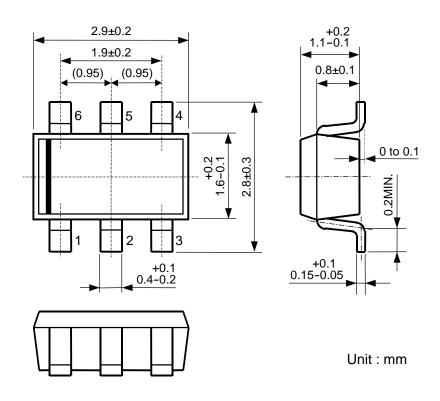
Ver. B





WLCSP-6-P6 Package Dimensions (Unit: mm)

Ver. A



SOT-23-6 Package Dimensions (Unit: mm)



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