

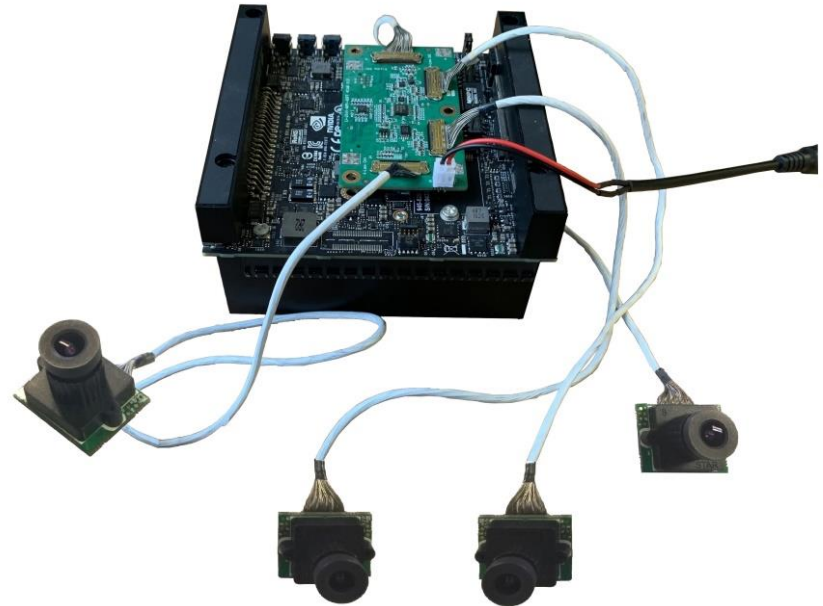


LEOPARD IMAGING INC

# LI-XAVIER-KIT-IMX290M12-X Data Sheet

## Key Features

- Compatible with Nvidia® Jetson AGX Xavier™ Developer Kit
- MIPI CSI-2 interface
- Support up to four 4-lane cameras
- Sony Diagonal 6.46 mm (Type 1/2.8) CMOS Image Sensor IMX290
- Active pixels: 1945H x 1109V
- Pixel size: 2.9 um x 2.9 um
- Color camera
- High sensitivity
- Length of the I-PEX cable: 300mm
- Support multiple length cables
- Connector Part#: 20525-030E-02C
- Support M12 x P0.5 lens
- Provide customization services
- Part#:
  - (1 cam) [LI-XAVIER-KIT-IMX290M12](#)
  - (2 cam) [LI-XAVIER-KIT-IMX290M12-D](#)
  - (3 cam) [LI-XAVIER-KIT-IMX290M12-T](#)
  - (4 cam) [LI-XAVIER-KIT-IMX290M12-Q](#)



## Lens Spec

- Model: LC001E-0530
- Focal length: 3.98 mm +/- 5%
- Aperture, F/#: 2.3 +/- 5%
- Built in 650nm IR cut filter
- FOV (D/H/V): 96 °/ 82.4 °/50 °
- TV Distortion: < 12%
- Mount: M12 x P0.5

## BOM

Nvidia AGX Xavier Developer Kit not included

#	Items	QTY
1	LI-JXAV-MIPI-ADPT-4CAM	1
2	LI-IMX290-MIPI-M12	1, 2,3 or 4
3	FAW-1233-03 cable	1, 2,3 or 4

## Applications

- Industrial Cameras
- Surveillance cameras



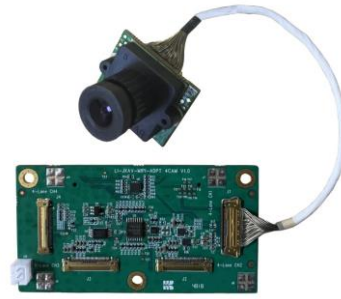
Leopard Imaging Inc.

48820 Kato Rd, Suite 100B, Fremont, CA 94538, USA  
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### LI-XAVIER-KIT-IMX290M12

#### BOM

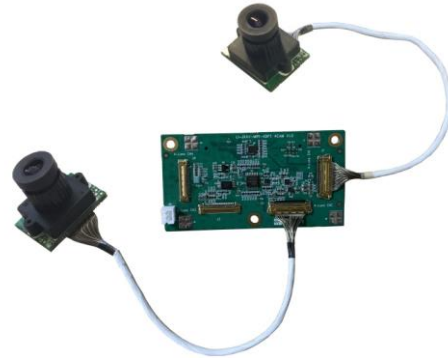
#	Items	QTY
1	LI-JXAV-MIPI-ADPT-4CAM	1
2	LI-IMX290-MIPI-M12	1
3	FAW-1233-03 cable	1



### LI-XAVIER-KIT-IMX290M12-D

#### BOM

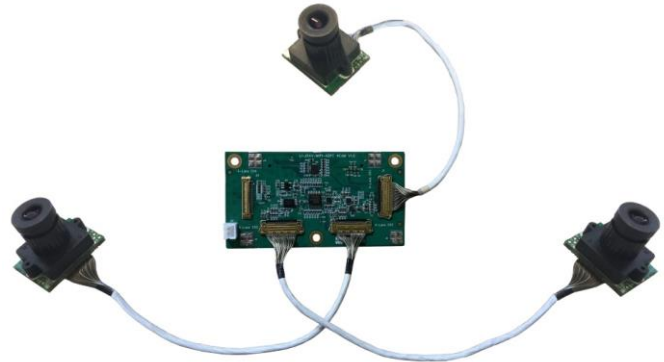
#	Items	QTY
1	LI-JXAV-MIPI-ADPT-4CAM	1
2	LI-IMX290-MIPI-M12	2
3	FAW-1233-03 cable	2



### LI-XAVIER-KIT-IMX290M12-T

#### BOM

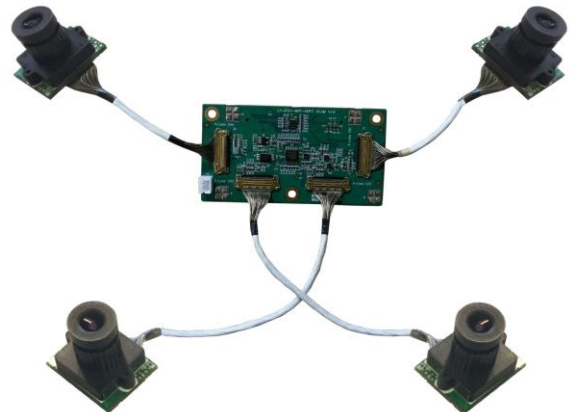
#	Items	QTY
1	LI-JXAV-MIPI-ADPT-4CAM	1
2	LI-IMX290-MIPI-M12	3
3	FAW-1233-03 cable	3



### LI-XAVIER-KIT-IMX290M12-Q

#### BOM

#	Items	QTY
1	LI-JXAV-MIPI-ADPT-4CAM	1
2	LI-IMX290-MIPI-M12	4
3	FAW-1233-03 cable	4

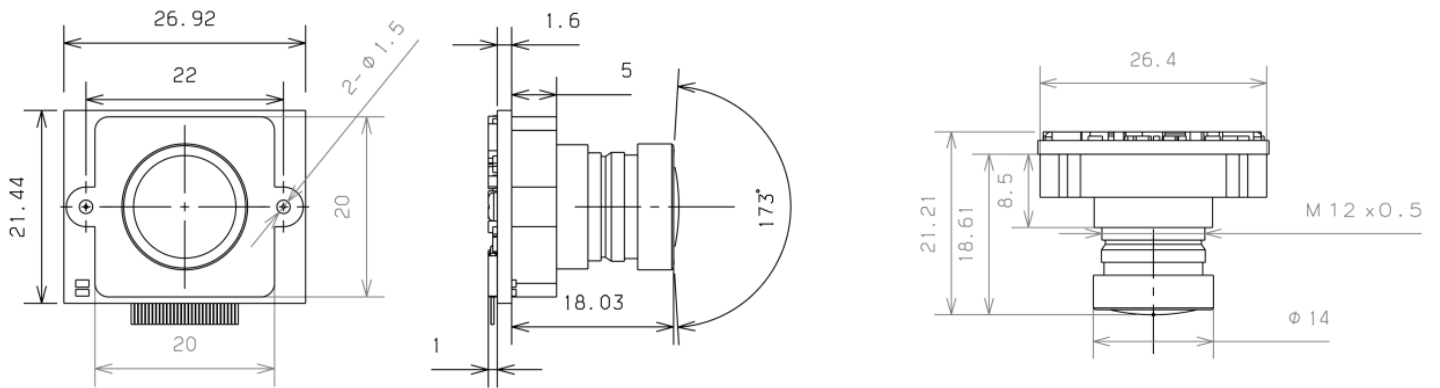


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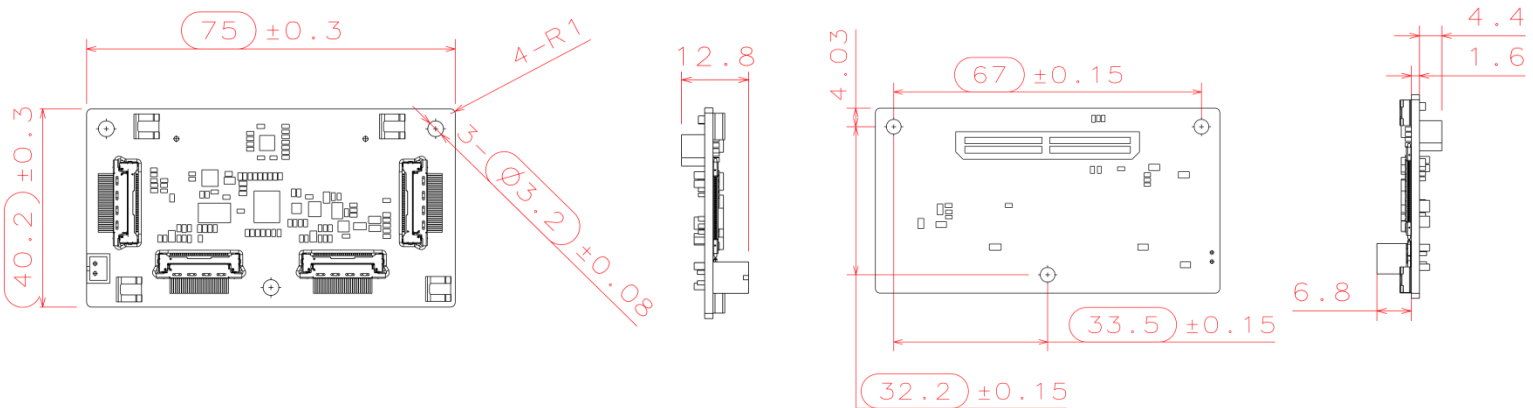
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# Dimensions

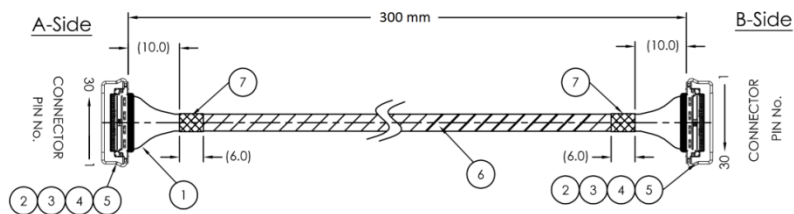
## LI-IMX290-MIPI-M12



## LI-JXAV-MIPI-ADPT-4CAM



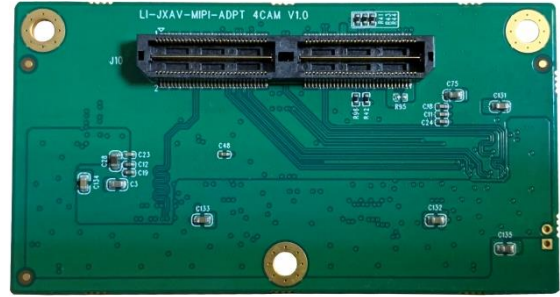
## FAW-1233-03



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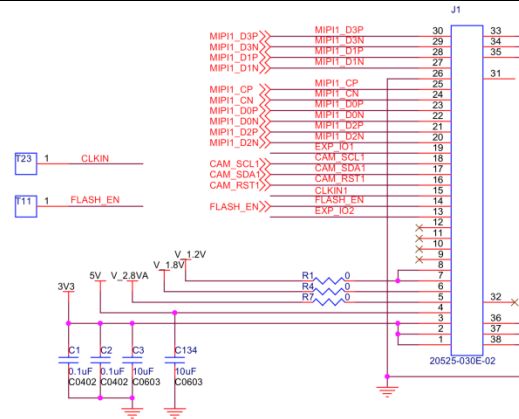
# LI-JXAV-MIPI-ADPT-4CAM



## Interfaces

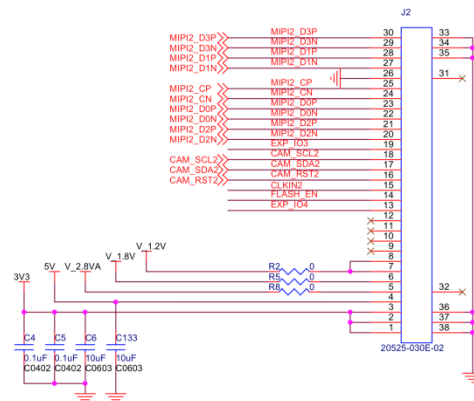
### Interface J1

- Part#: 20525-030E-02C
- Number of Positions: 30
- Pitch: 0.4mm
- Mating I-PEX cable: FAW-1233-03 (300mm)



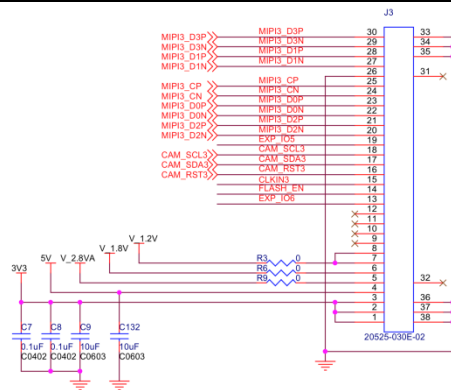
### Interface J2

- Part#: 20525-030E-02C
- Number of Positions: 30
- Pitch: 0.4mm
- Mating I-PEX cable: FAW-1233-03 (300mm)



### Interface J3

- Part#: 20525-030E-02C
- Number of Positions: 30
- Pitch: 0.4mm
- Mating I-PEX cable: FAW-1233-03 (300mm)

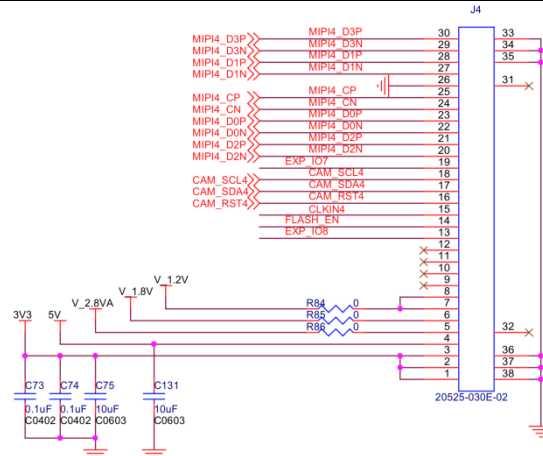


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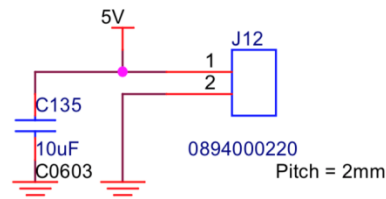
## Interface J4

- Part#: 20525-030E-02C
- Number of Positions: 30
- Pitch: 0.4mm
- Mating I-PEX cable: FAW-1233-03 (300mm)



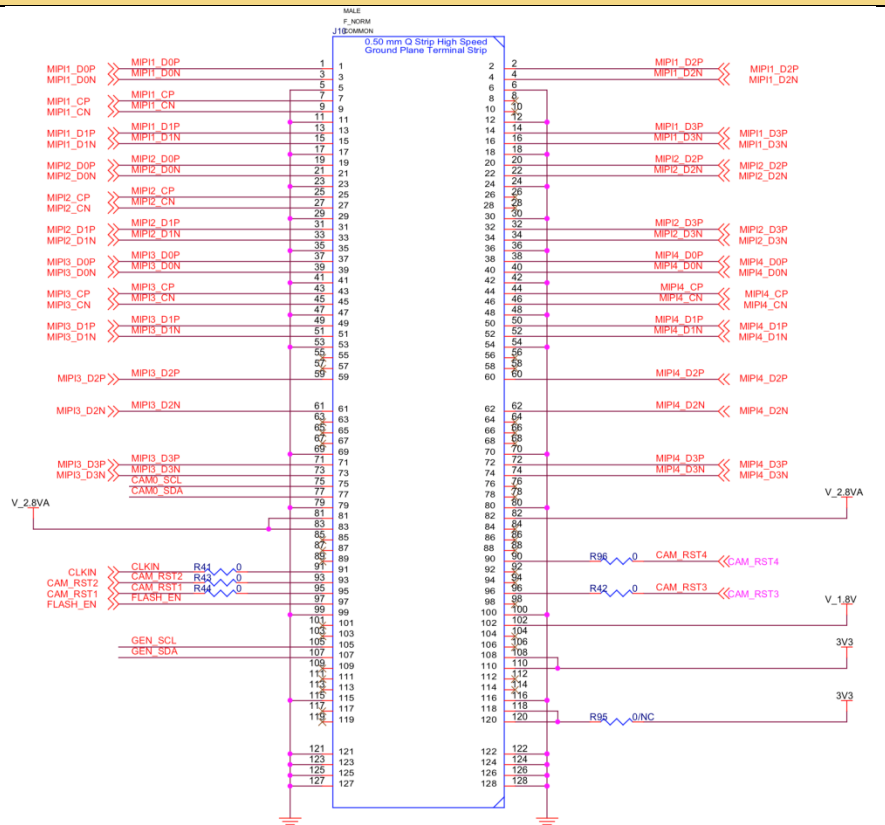
## Interface J5

- Part#: 0894000220
- Number of Positions: 2
- Pitch: 2mm



## Interface J10

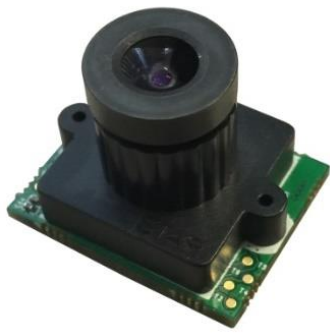
- Part#: QTH-060-01-L-D-A
- Number of Positions: 120
- Number of Rows: 2
- Pitch: 0.5 mm



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# LI-IMX290-MIPI-M12



<b>Camera Spec</b>	
Image Sensor	Sony Diagonal 6.46 mm (Type 1/2.8) CMOS Image Sensor IMX290
Optical format	1/2.8"
Number of active pixels	1945 (H) x 1109(V)
Pixel size	2.9um (H) x 2.9um (V)
Color or Mono	Color
Interface	MIPI interface
Lens mount	M12
Weight	14 g
<b>Interfaces</b>	
Interface J2:	<ul style="list-style-type: none"> <li>Part#: 20525-030E-02C</li> <li>Number of Positions: 30</li> <li>Pitch: 0.4mm</li> <li>Mating I-PEX cable: FAW-1233-03 (300mm)</li> </ul>



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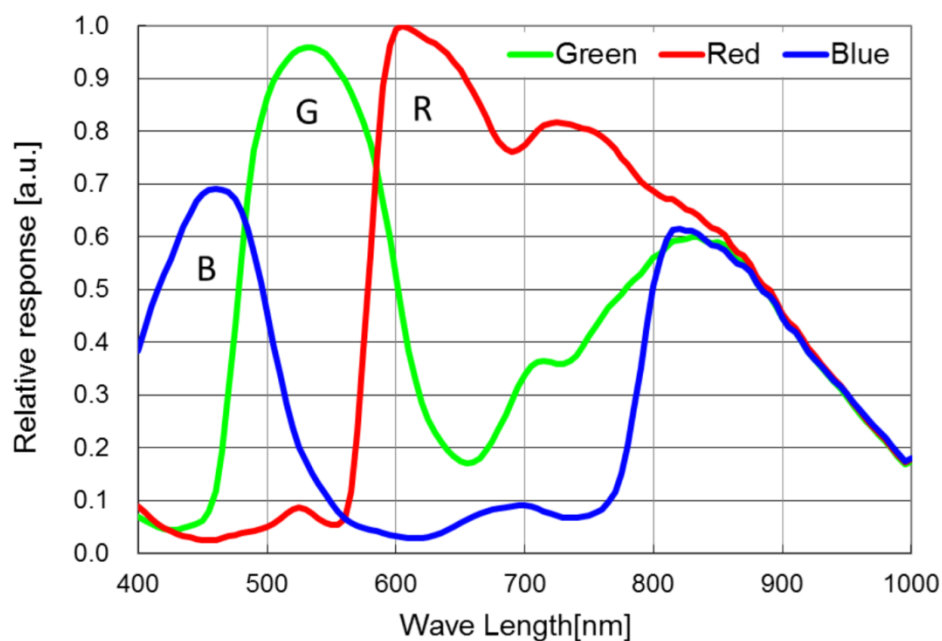
## Absolute Maximum Ratings

Item	Symbol	Min.	Max.	Unit	Remarks
Supply voltage (analog 2.9 V)	AV <sub>DD</sub>	-0.3	3.3	V	
Supply voltage (interface 1.8 V)	OV <sub>DD</sub>	-0.3	3.3	V	
Supply voltage (digital 1.2 V)	DV <sub>DD</sub>	-0.3	2.0	V	
Input voltage	VI	-0.3	OV <sub>DD</sub> + 0.3	V	Not exceed 3.3 V
Output voltage	VO	-0.3	OV <sub>DD</sub> + 0.3	V	Not exceed 3.3 V

## Recommended Operating Conditions

Item	Symbol	Min.	Typ.	Max.	Unit
Supply voltage (analog 2.9 V)	AV <sub>DD</sub>	2.80	2.90	3.00	V
Supply voltage (Interface 1.8 V)	OV <sub>DD</sub>	1.70	1.80	1.90	V
Supply voltage (digital 1.2 V)	DV <sub>DD</sub>	1.10	1.20	1.30	V
Performance guarantee temperature	Tspec	-10	—	60	°C
Operating guarantee temperature	Topr	-30	—	85	°C
Storage guarantee temperature	Tstg	-40	—	85	°C

## Spectral Sensitivity Characteristics



## DC Characteristics

Item	Pins	Symbol	Condition	Min.	Typ.	Max.	Unit
Supply voltage	analog	VDDHx	$AV_{DD}$	2.80	2.90	3.00	V
	Interface	VDDMx	$OV_{DD}$	1.70	1.80	1.90	V
	digital	VDDLx	$DV_{DD}$	1.10	1.20	1.30	V
Digital input voltage	XHS XVS XCLR INCK XMASTER OMODE SCK SDI XCE XTRIG	VIH	XVS / XHS Slave Mode	0.80V <sub>DD</sub>	—	—	V
		VIL		—	—	0.20V <sub>DD</sub>	V
Digital output voltage	DLOP [A:F] DLOM [A:F] DLCKP DLCKM	VOH	IOH = -2 mA	$OV_{DD}-0.4$	—	—	V
		VOL	IOL = 2 mA	—	—	0.4	V
		VCM	Low voltage LVDS	—	$OV_{DD}/2$	—	V
		VOD	Low voltage LVDS (Termination resistance: 100 Ω)	100	150	220	mV
	XHS XVS SDO TOUT	VOH	XVS / XHS Master Mode	$OV_{DD}-0.4$	—	—	V
		VOL		—	—	0.4	V

## Current Consumption

Item	pin	Symbol	Typ.		Max.		Unit
			Standard luminous intensity	Saturated luminous intensity	Standard luminous intensity	Saturated luminous intensity	
Operating current Low voltage LVDS serial 8 ch 12 bit 60 frame / s Full HD 1080p mode	VDDH	$I_{AV_{DD}}$	54	53	111	108	mA
	VDDM	$IOV_{DD}$	16	15	29	27	mA
	VDDL	$IDV_{DD}$	77	95	123	214	mA
Operating current MIPI CSI-2 / 4 Lane 12 bit, 60 frame/s Full HD 1080p mode	VDDH	$I_{AV_{DD}}$	55	54	111	108	mA
	VDDM	$IOV_{DD}$	1	1	2	2	mA
	VDDL	$IDV_{DD}$	94	111	143	252	mA
Operating current CMOS parallel SDR 12 bit, 30 frame/s Full HD 1080p	VDDH	$I_{AV_{DD}}$	55	54	111	110	mA
	VDDM	$IOV_{DD}$	17	17	28	28	mA
	VDDL	$IDV_{DD}$	49	59	90	159	mA
Standby current	VDDH	$I_{AV_{DD\_STB}}$	—		0.1		mA
	VDDM	$IOV_{DD\_STB}$	—		0.1		mA
	VDDL	$IDV_{DD\_STB}$	—		14.0		mA



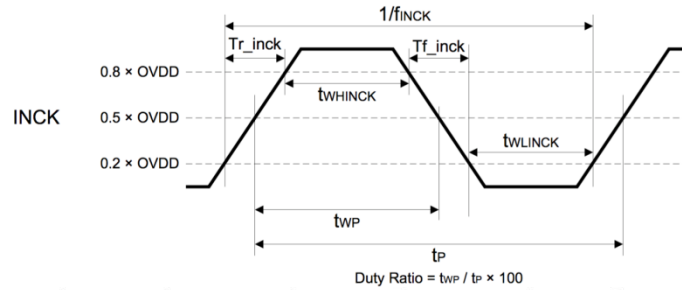
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# AC Characteristics

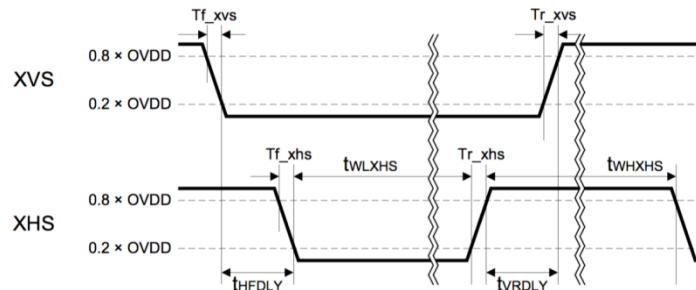
## INCK



Item	Symbol	Min.	Typ.	Max.	Unit	Remarks
INCK clock frequency	$f_{INCK}$	$f_{INCK} \times 0.96$	$f_{INCK}$	$f_{INCK} \times 1.02$	MHz	$f_{INCK} = 37.125\text{ MHz}, 74.25\text{ MHz}$
INCK Low level pulse width	$t_{WLINCK}$	4	—	—	ns	$f_{INCK} = 37.125\text{ MHz}, 74.25\text{ MHz}$
INCK High level pulse width	$t_{WHINCK}$	4	—	—	ns	$f_{INCK} = 37.125\text{ MHz}, 74.25\text{ MHz}$
INCK clock duty	—	45.0	50.0	55.0	%	Define with $0.5 \times OVDD$
INCK Rise time	$Tr\_inck$	—	—	5	ns	20 % to 80 %
INCK Fall time	$Tf\_inck$	—	—	5	ns	80 % to 20 %

\*The INCK fluctuation affects the frame rate.

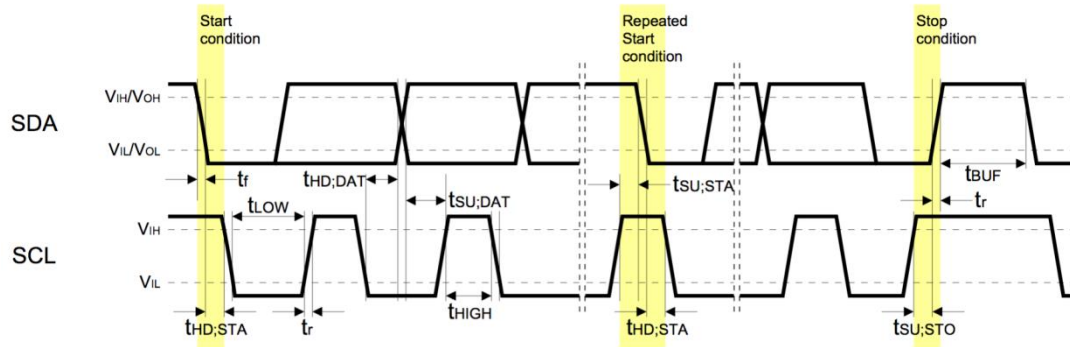
## XHS, XVS Input Characteristics In Slave Mode (XMASTER pin = High)



Item	Symbol	Min.	Typ.	Max.	Unit	Remarks
XHS Low level pulse width	$t_{WLXHS}$	$4 / f_{INCK}$	—	—	ns	
XHS High level pulse width	$t_{WHXHS}$	$4 / f_{INCK}$	—	—	ns	
XVS - XHS fall width	$t_{HFDLY}$	$1 / f_{INCK}$	—	—	ns	
XHS - XVS rise width	$t_{VRDLY}$	$1 / f_{INCK}$	—	—	ns	
XVS Rise time	$Tr\_xvs$	—	—	5	ns	20 % to 80 %
XVS Fall time	$Tf\_xvs$	—	—	5	ns	80 % to 20 %
XHS Rise time	$Tr\_xhs$	—	—	5	ns	20 % to 80 %
XHS Fall time	$Tf\_xhs$	—	—	5	ns	80 % to 20 %



## I<sup>2</sup>C Communication



## I<sup>2</sup>C Specification

Item	Symbol	Min.	Typ.	Max.	Unit	条件
Low level input voltage	V <sub>IL</sub>	-0.3	—	$0.3 \times OV_{DD}$	V	
High level input voltage	V <sub>IH</sub>	$0.7 \times OV_{DD}$	—	1.9	V	
Low level input voltage	V <sub>OL</sub>	0	—	$0.2 \times OV_{DD}$	V	OV <sub>DD</sub> < 2 V, Sink 3 mA
High level input voltage	V <sub>OH</sub>	$0.8 \times OV_{DD}$	—	—	V	
Output fall time	t <sub>of</sub>	—	—	250	ns	Load 10 pF – 400 pF, $0.7 \times OV_{DD} - 0.3 \times OV_{DD}$
Input current	i <sub>li</sub>	-10	—	10	μA	$0.1 \times OV_{DD} - 0.9 \times OV_{DD}$
Capacitance for SCK (SCL) /SDI (SDA)	C <sub>i</sub>	—	—	10	pF	

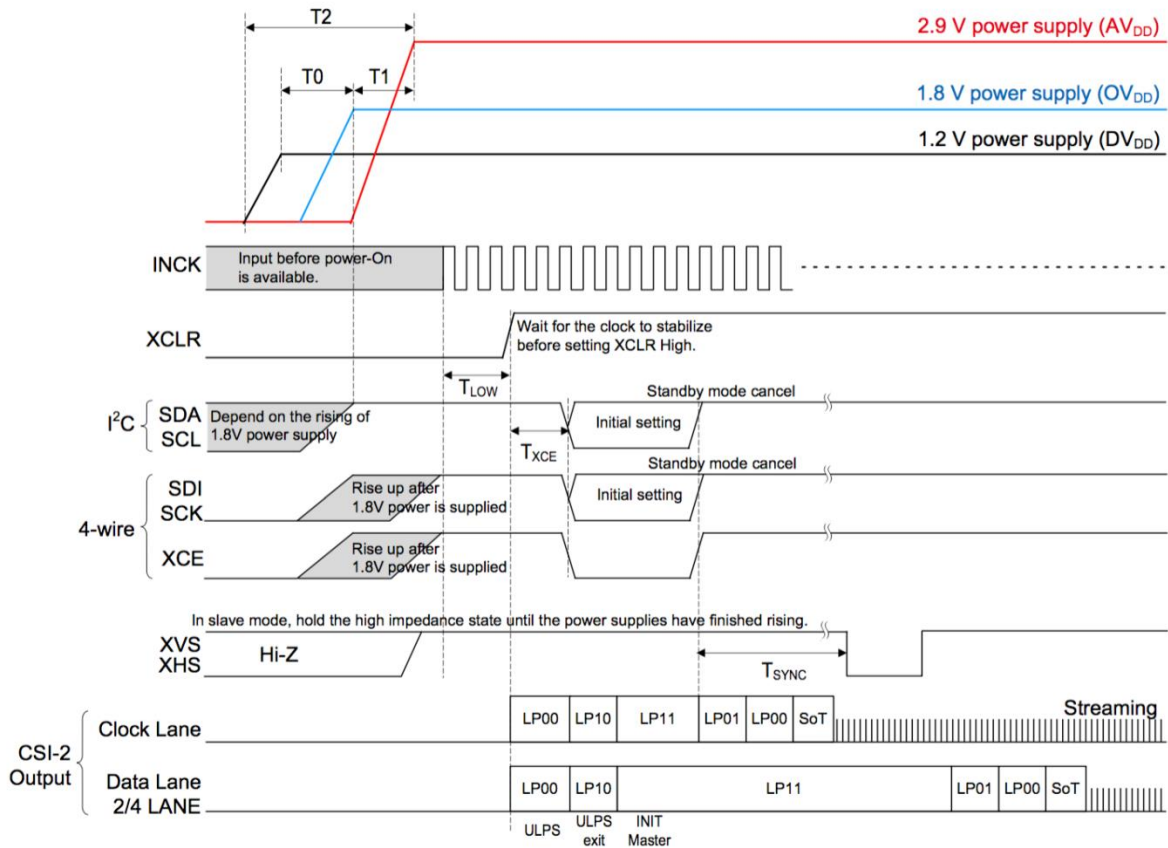
## I<sup>2</sup>C AC Characteristics

Item	Symbol	Min.	Typ.	Max.	Unit
SCL clock frequency	f <sub>SCL</sub>	0	—	400	kHz
Hold time (Start Condition)	t <sub>HD:STA</sub>	0.6	—	—	μs
Low period of the SCL clock	t <sub>LOW</sub>	1.3	—	—	μs
High period of the SCL clock	t <sub>HIGH</sub>	0.6	—	—	μs
Set-up time (Repeated Start Condition)	t <sub>SU:STA</sub>	0.6	—	—	μs
Data hold time	t <sub>HD:DAT</sub>	0	—	0.9	μs
Data set-up time	t <sub>SU:DAT</sub>	100	—	—	ns
Rise time of both SDA and SCL signals	t <sub>r</sub>	—	—	300	ns
Fall time of both SDA and SCL signals	t <sub>f</sub>	—	—	300	ns
Set-up time (Stop Condition)	t <sub>SU:STO</sub>	0.6	—	—	μs
Bus free time between a STOP and START Condition	t <sub>BUF</sub>	1.3	—	—	μs



## Power-on Sequence

1. Turn On the power supplies so that the power supplies rise in order of 1.2 V power supply ( $DV_{DD}$ ) → 1.8 V power supply ( $OV_{DD}$ ) → 2.9 V power supply ( $AV_{DD}$ ). In addition, all power supplies should finish rising within 200 ms.
2. Start master clock (INCK) input after turning On the power supplies.
3. The register values are undefined immediately after power-on, so the system must be cleared. Hold XCLR at Low level for 500 ns or more after all the power supplies have finished rising. (The register values after a system clear are the default values.) In addition, hold XCE to High level during this period. Rise XCE after 1.8 V power supply ( $OV_{DD}$ ).
4. The system clear is applied by setting XCLR to High level. However, the maser clock needs to stabilize before setting the XCLR pin to High level.
5. Make the sensor setting by register communication after the system clear. A period of 20  $\mu$ s or more should be provided after setting XCLR High before inputting the communication enable signal XCE. In  $I^2C$  communication, XCE is fixed to High.

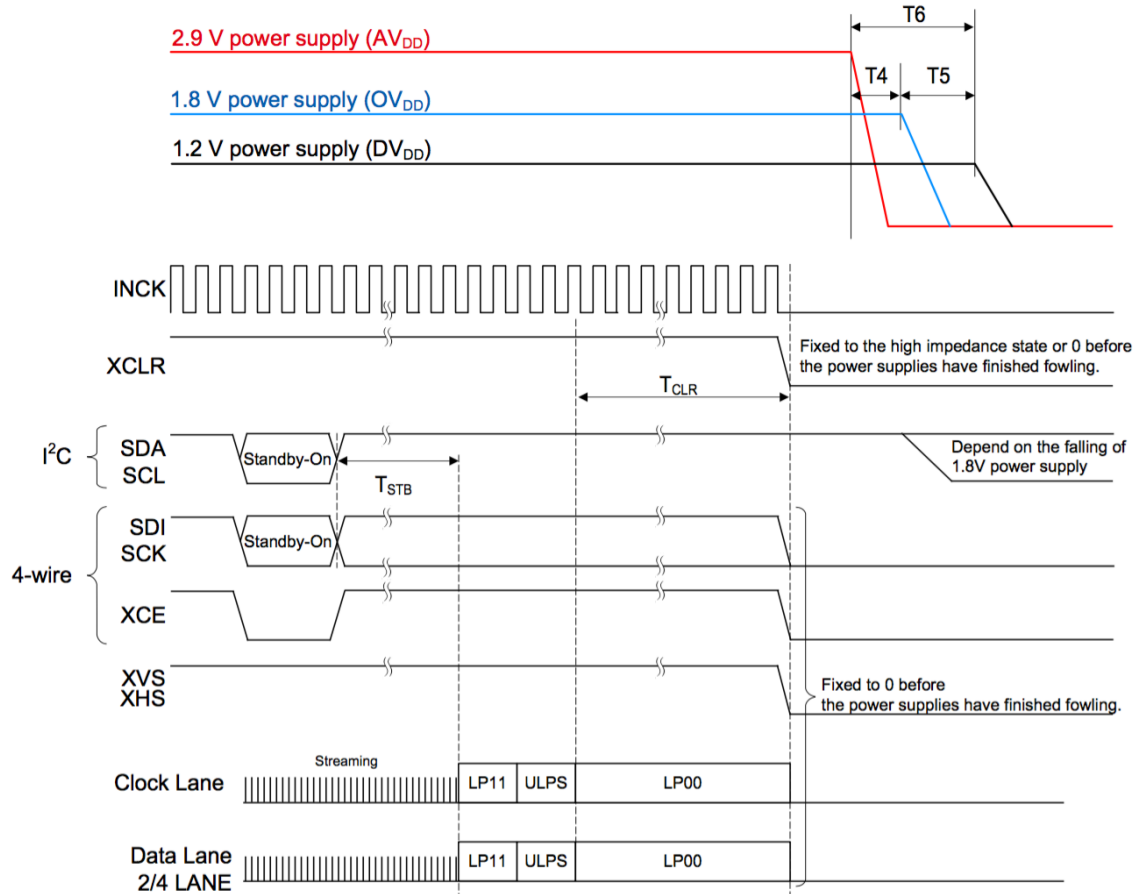


Item	Symbol	Min.	Max.	Unit
1.2 V power supply rising → 1.8 V power supply rising	T0	0	—	ns
1.8 V power supply rising → 2.9 V power supply rising	T1	0	—	ns
Rising time of all power supply	T2	—	200	ms
INCK active → Clear OFF	T <sub>LOW</sub>	500	—	ns
Clear OFF → Communication start	T <sub>XCE</sub>	20	—	$\mu$ s
Standby OFF (communication) → External input XHS,XVS (slave mode only)	T <sub>SYNC</sub>	20	—	ms



## Power-off Sequence

Turn Off the power supplies so that the power supplies fall in order of 2.9 V power supply ( $AV_{DD}$ ) → 1.8 V power supply ( $OV_{DD}$ ) → 1.2 V power supply ( $DV_{DD}$ ). In addition, all power supplies should falling within 200 ms. Set each digital input pin (INCK, XCE, SCK, SDI, XCLR, XMASTER, OMODE, XVS, XHS) to 0 V before the 1.8 V power supply ( $OV_{DD}$ ) falls.



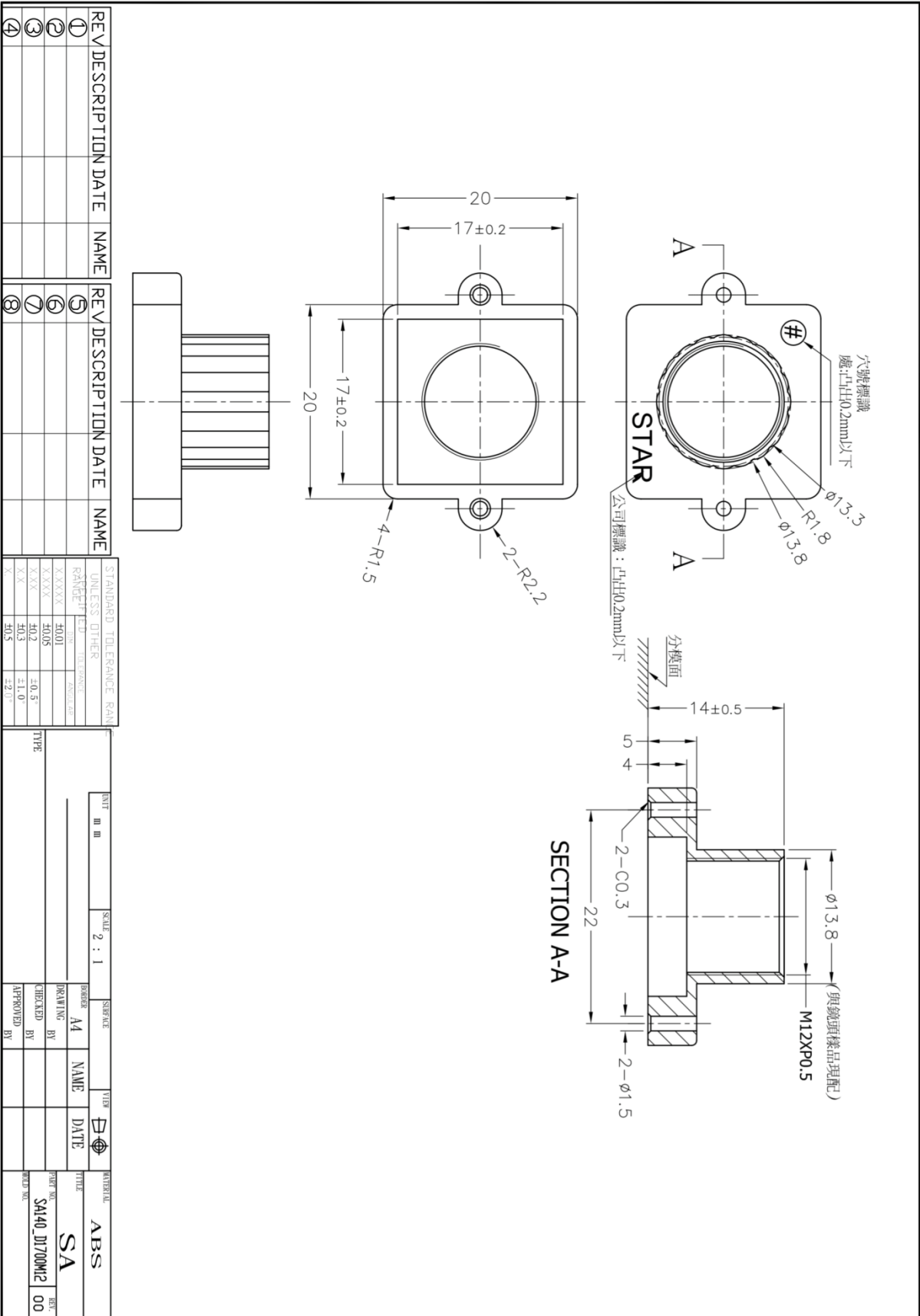
Item	Symbol	Min.	Max.	Unit
Standby ON (communication) → LP11 mode start	$T_{STB}$	Until FE		—
LP00 → XCLR falling	$T_{CLR}$	128	—	cycle
2.9 V power shut down → 1.8 V power shut down	$T_4$	0	—	ns
1.8 V power shut down → 1.2 V power shut down	$T_5$	0	—	ns
Shut down time of all power supply	$T_6$	—	200	ms



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# SA140 lens mount Spec



REV	DESCRIPTION	DATE	NAME	REV	DESCRIPTION	DATE	NAME
①				⑤			
②				⑥			
③				⑦			
④				⑧			

STANDARD TOLERANCE RAN		UNLESS OTHER	
RANGE	TOLERANCE	RANGE	TOLERANCE
X.XXXXX	$\pm 0.01$	X.XXXXX	$\pm 0.05$
X.XXXX	$\pm 0.02$	X.XXX	$\pm 0.5$
X.XX	$\pm 0.3$	X.X	$\pm 1.0$
X.X	$\pm 2.0$	X	$\pm 2.0$

UNIT	SCALE	SINCE	VIEW	TITLE	MATERIAL
mm	2 : 1	M		SA	ABS

DRIVING BY	CHECKED BY	APPROVED BY	DATE	DATE	DATE

PART NO.	REV.
SA140_01700M12	00



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## Revision History

Revision	Description	Release Date
1.0	First Release	11. May. 2019



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Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



#### Как с нами связаться

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