

## Automotive Serial EEPROMs

# 125°C SPI BUS ICs

## BR35□□□□ Family



### BR35H□□□-WC Series

No.11001ECT09

**●Description**

BR35H□□□-WC Series is a SPI BUS interface method serial EEPROM.

**●Features**

- 1) High speed clock operation up to 5MHz(Max.)
- 2) 2.5V to 5.5V single power source operation most suitable for battery use.
- 3) Page write mode useful for initial value at factory shipment.
- 4) Highly reliable connection by Au pad and Au wire.
- 5) For SPI bus interface (CPOL,CPHA)=(0,0),(1,1)
- 6) Auto erase and auto end function at data rewrite.
- 7) Low operating current
  - At write operation (5V): 0.6mA(Typ.)
  - At read operation (5V): 1.3mA(Typ.)
  - At standby operation (5V): 0.1μA(Typ.)
- 8) Address auto increment function at read operation.
- 9) Write mistake prevention function
  - Write prohibition at power on.
  - Write prohibition by command code (WRDI)
  - Write mistake prevention function at low voltage.
- 10) MSOP8 / TSSOP-B8 / SOP8 / SOP-J8 Package.
- 11) Data at shipment Memory array:FFh.
- 12) Data Retention : 20 years( $T_a \leq 125^\circ\text{C}$ )
- 13) Endurance : 300,000 cycles( $T_a \leq 125^\circ\text{C}$ )

**●Page Write**

Number of pages	32Byte	64Byte
Product number	BR35H160-WC BR35H320-WC BR35H640-WC	BR35H128-WC

**●BR35H□□□ Series**

Capacity	Bit Format	Product Name	Supply Voltage	MSOP8	TSSOP-B8	SOP8	SOP-J8
16Kbit	2K×8	BR35H160-WC	2.5~5.5V	●	●	●	●
32Kbit	4K×8	BR35H320-WC	2.5~5.5V	●	●	●	●
64Kbit	8K×8	BR35H640-WC	2.5~5.5V	-	●	●	●
128Kbit	16K×8	BR35H128-WC	2.5~5.5V	-	-	●	●

## ● Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Limits	Unit
Impressed Voltage	Vcc	-0.3 to +6.5	V
Permissible Dissipation	Pd	560(SOP8) *1	mW
		560(SOP-J8) *2	
		410(TSSOP-B8) *3	
		380(MSOP8) *4	
Storage Temperature Range	Tstg	-65 to +150	°C
Operating Temperature Range	Topr	-40 to +125	°C
Terminal Voltage	-	-0.3 to Vcc+0.3	V

\* When using at Ta=25°C or higher, 4.5mW (\*1,\*2), 3.3mW (\*3), 3.1 mW (\*4) to be reduced per 1°C

## ● Recommended Operating Conditions

Parameter	Symbol	Limits	Unit
Supply Voltage	Vcc	2.5 to 5.5	V
Input Voltage	Vin	0 to Vcc	

## ● Memory Cell Characteristics (Vcc=2.5V to 5.5V)

Parameter	Limits			Unit	Condition
	Min.	Typ.	Max.		
Endurance *5	1,000,000	-	-	Cycles	Ta ≤ 85°C
	500,000	-	-	Cycles	Ta ≤ 105°C
	300,000	-	-	Cycles	Ta ≤ 125°C
Data Retention *5	40	-	-	Years	Ta ≤ 25°C
	25	-	-	Years	Ta ≤ 105°C
	20	-	-	Years	Ta ≤ 125°C

\*5: Not 100% TESTED

## ● Input / Output Capacitance (Ta=25°C, frequency=5MHz)

Parameter	Symbol	Conditions	Min.	Max.	Unit
Input Capacitance *6	C <sub>IN</sub>	V <sub>IN</sub> =GND	-	8	pF
Output Capacitance *6	C <sub>OUT</sub>	V <sub>OUT</sub> =GND	-	8	

\*6: Not 100% TESTED

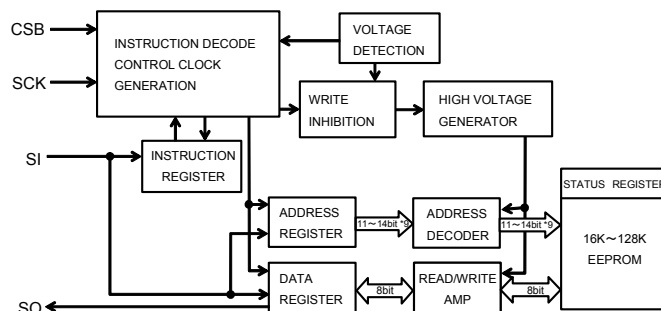
## ● Electrical Characteristics (Unless otherwise specified, Ta=-40 to +125°C, Vcc=2.5 to 5.5V)

Parameter	Symbol	Limits			Unit	Conditions
		Min.	Typ.	Max.		
"H" Input Voltage	VIH	0.7xVcc	-	Vcc+0.3	V	2.5V ≤ Vcc ≤ 5.5V
"L" Input Voltage	VIL	-0.3	-	0.3xVcc	V	2.5V ≤ Vcc ≤ 5.5V
"L" Output Voltage	VOL	0	-	0.4	V	IOL=2.1mA
"H" Output Voltage	VOH	Vcc-0.5	-	Vcc	V	IOH=-0.4mA
Input Leakage Current	ILI	-10	-	10	μA	VIN=0V to Vcc
Output Leakage Current	ILO	-10	-	10	μA	VOUT=0V to Vcc, CSB=Vcc
Operating Current (Write)	ICC1	-	-	2.0 *7	mA	Vcc=2.5V, fSCK=5MHz, tE/W=5ms, VIH/VIL=0.9Vcc/0.1Vcc, SO=OPEN Byte Write, Page Write
				2.5 *8		
	ICC2	-	-	3.0 *7	mA	
				5.5 *8		
Operating Current (Read)	ICC3	-	-	1.5	mA	Vcc=2.5V, fSCK=5MHz, VIH/VIL=0.9Vcc/0.1Vcc SO=OPEN, Read, Read Status Register
	ICC4	-	-	2.0	mA	Vcc=5.5V, fSCK=5MHz, VIH/VIL=0.9Vcc/0.1Vcc SO=OPEN, Read, Read Status Register
Standby Current	ISB	-	-	10	μA	Vcc=5.5V CSB=Vcc, SCK=SI=Vcc or GND, SO=OPEN

\* This product is not designed for protection against radioactive rays.

\*7 BR35H160/320-WC \*8 BR35H640/128-WC

## ● Block Diagram



\*9 11bit: BR35H160-WC  
12bit: BR35H320-WC  
13bit: BR35H640-WC  
14bit: BR35H128-WC

Fig.1 Block Diagram

## ● Pin Assignment and Description

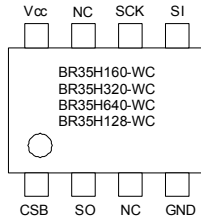


Fig.2 Pin Assignment Diagram

Terminal Name	Input/Output	Function
Vcc	-	Power Supply to be connected
GND	-	All input / output reference voltage, 0V
CSB	Input	Chip select input
SCK	Input	Serial clock input
SI	Input	Start bit, ope code, address, and serial data input
SO	Output	Serial data output
NC	-	Non connection

## ● Operating Timing Characteristics

( $T_a = -40^\circ\text{C}$  to  $+125^\circ\text{C}$ , unless otherwise specified, load capacitance  $C_{L1} = 100\text{pF}$ )

Parameter	Symbol	$2.5 \leq V_{cc} \leq 5.5\text{V}$			Unit
		Min.	Typ.	Max.	
SCK frequency	fSCK	-	-	5	MHz
SCK high time	tSCKWH	85	-	-	ns
SCK low time	tSCKWL	85	-	-	ns
CSB high time	tCS	85	-	-	ns
CSB setup time	tCSS	90	-	-	ns
CSB hold time	tCSH	85	-	-	ns
SCK setup time	tSCKS	90	-	-	ns
SCK hold time	tSCKH	90	-	-	ns
SI setup time	tDIS	20	-	-	ns
SI hold time	tDIH	30	-	-	ns
Data output delay time1	tPD1	-	-	70	ns
Data output delay time2 ( $C_{L2} = 30\text{pF}$ )	tPD2	-	-	55	ns
Output hold time	tOH	0	-	-	ns
Output disable time	tOZ	-	-	100	ns
SCK rise time	tRC	-	-	1	$\mu\text{s}$
SCK fall time	tFC	-	-	1	$\mu\text{s}$
OUTPUT rise time	tRO	-	-	50	ns
OUTPUT fall time	tFO	-	-	50	ns
Write time	tE/W	-	-	5	ms

\*1 NOT 100% TESTED

## ● Sync data input / output timing

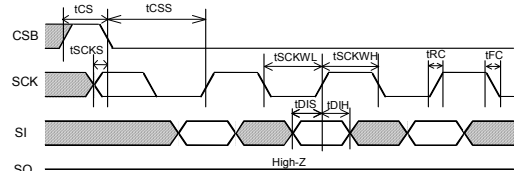


Fig.3 Input timing

Data through SI enters the IC in sync with the data rise edge of SCK. Please input address and data starting from the most significant bit MSB.

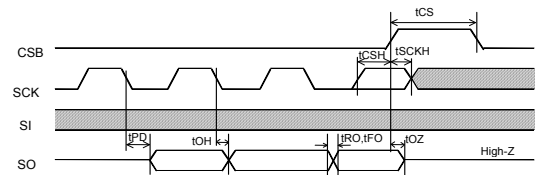


Fig.4 Input / Output timing

Data through SO is output in sync with the data fall edge of SCK. Data is output starting from the most significant bit MSB.

## ● AC measurement conditions

Parameter	Symbol	Limits			Unit
		Min.	Typ.	Max.	
Load capacitance 1	$C_{L1}$	-	-	100	pF
Load capacitance 2	$C_{L2}$	-	-	30	pF
Input rise time	-	-	-	50	ns
Input fall time	-	-	-	50	ns
Input voltage	-	0.2Vcc / 0.8Vcc			V
Input / Output judgment voltage	-	0.3Vcc / 0.7Vcc			V

## ● tOZ measurement condition

IL is the load current that changes the SO voltage to  $0.5 \times V_{cc}$ .  $IL = \pm 1\text{mA}$ .

After CSB starts to rise, the time needed for SO to change to High-Z is defined with 10% changing point from SO=High or SO=Low.

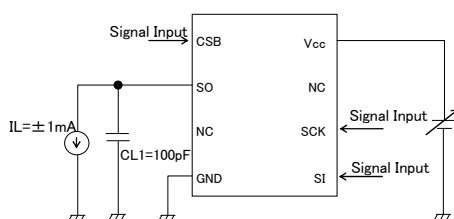


Fig.5 tOZ measurement circuit

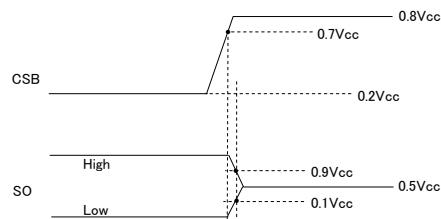


Fig.6 tOZ measurement timing

● Characteristics Data

(The following characteristic data are Typ. value.)

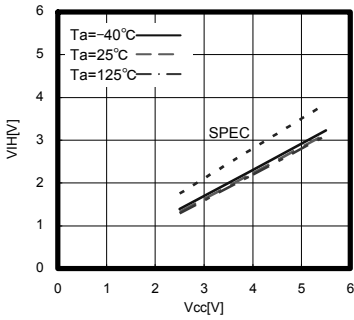


Fig.7 "H" input voltage  $V_{IH}(CSB,SCK,SI)$

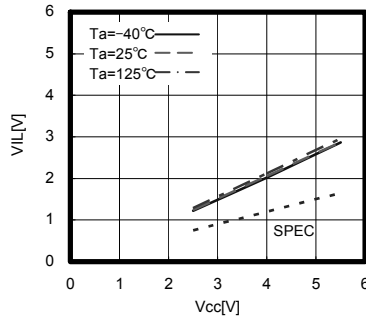


Fig.8 "L" input voltage  $V_{IL}(CSB,SCK,SI)$

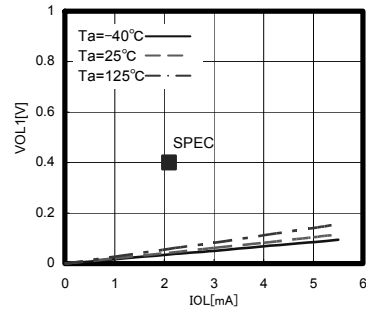


Fig.9 "L" output voltage  $V_{OL1}$  ( $V_{CC}=2.5V$ )

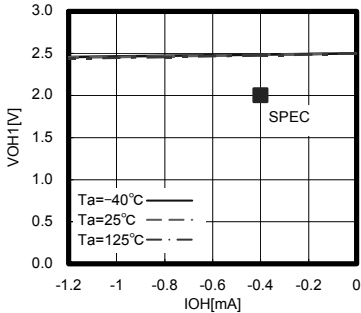


Fig.10 "H" output voltage  $V_{OH1}$  ( $V_{CC}=2.5V$ )

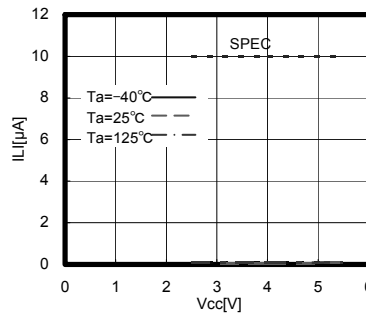


Fig.11 Input leak current  $I_{IL}(CSB,SCK,SI)$

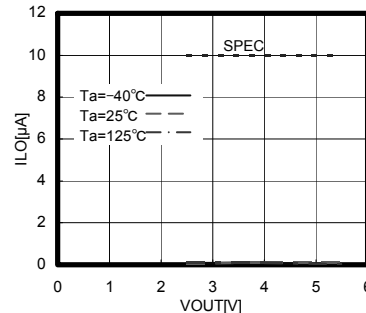


Fig.12 Output leak current  $I_{LO}(SO)$

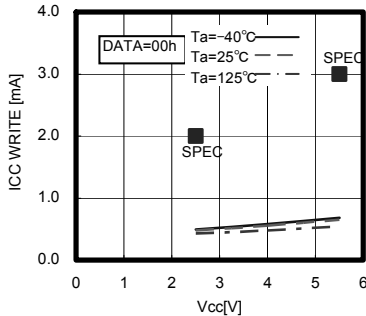


Fig.13 Operating Current (WRITE)  $ICC_{1,2}$  (BR35H160/320-WC)

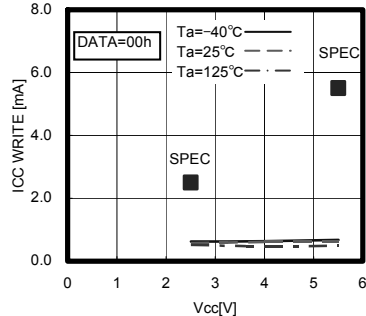


Fig.14 Operating Current (WRITE)  $ICC_{1,2}$  (BR35H640/128-WC)

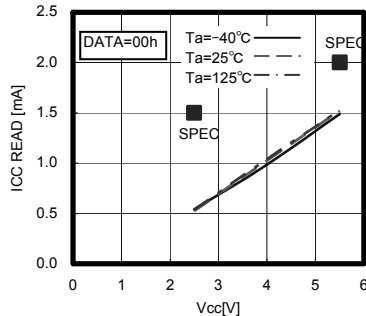


Fig.15 Operating Current (READ)  $ICC_{3,4}$

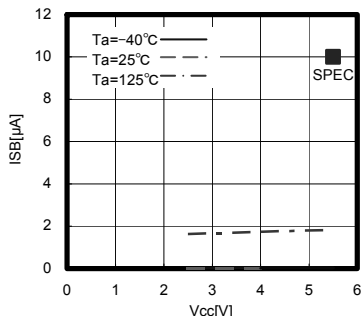


Fig.16 Standby Current  $I_{SB}$

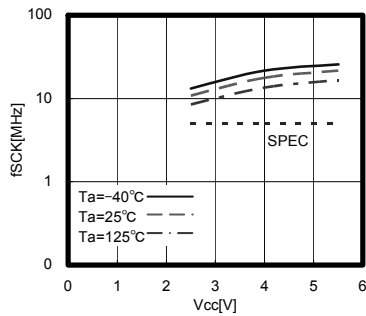


Fig.17 SCK frequency  $f_{SCK}$

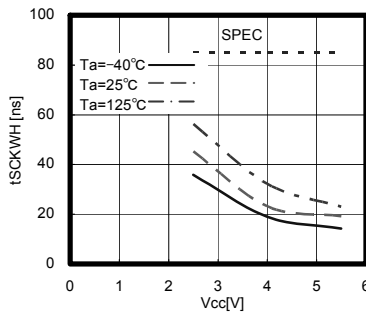


Fig.18 SCK high time  $t_{SCKWH}$

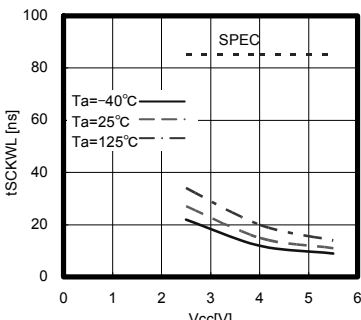


Fig.19 SCK low time  $t_{SCKWL}$

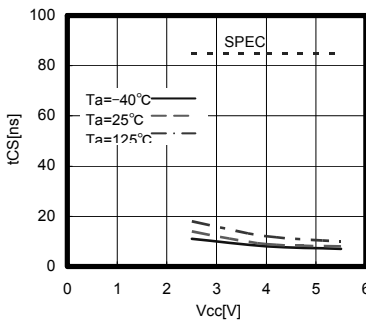


Fig.20 CSB high time  $t_{CS}$

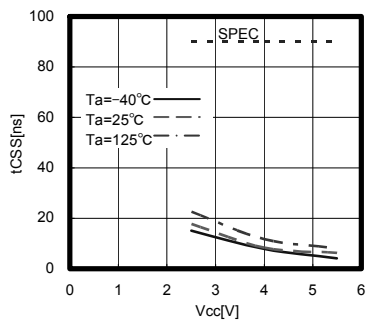


Fig.21 CSB setup time  $t_{CSS}$

● Characteristics Data

(The following characteristic data are Typ. value.)

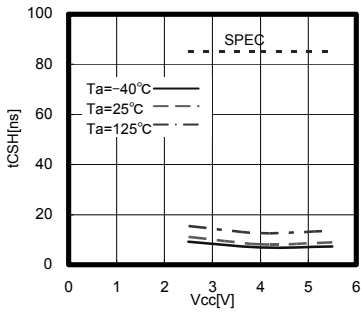


Fig.22 CSB hold time  $t_{CSH}$

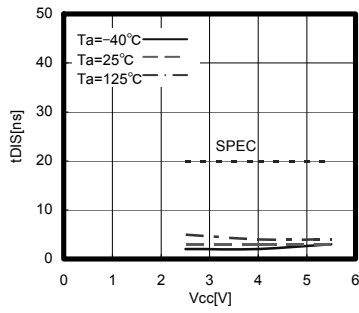


Fig.23 SI setup time  $t_{DIS}$

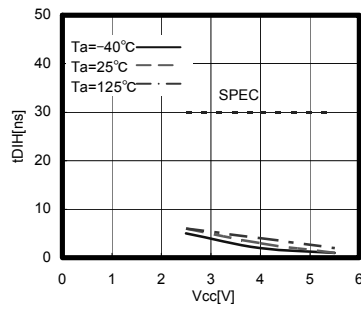


Fig.24 SI hold time  $t_{DIH}$

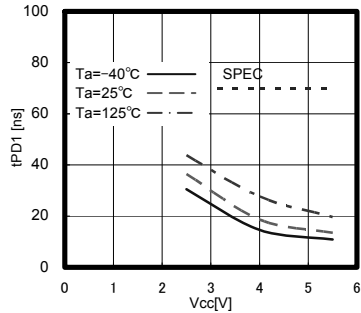


Fig.25 Data output delay time  $t_{PD1}$  ( $C_L=100\text{pF}$ )

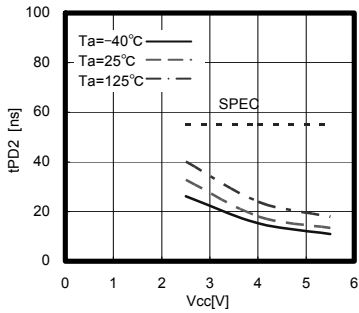


Fig.26 Data output delay time  $t_{PD2}$

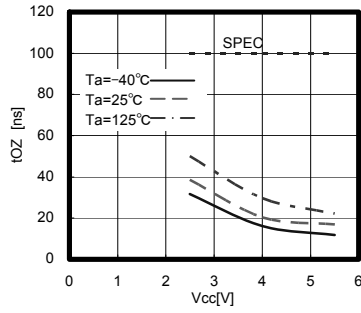


Fig.27 Output disable time  $t_{OZ}$

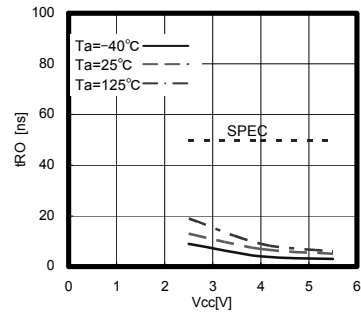


Fig.28 Output rise time  $t_{RO}$

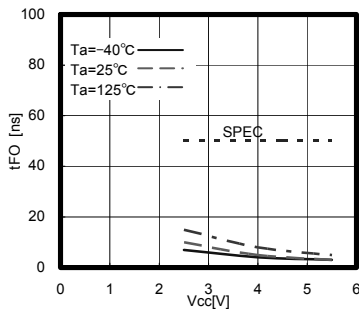


Fig.29 Output fall time  $t_{FO}$

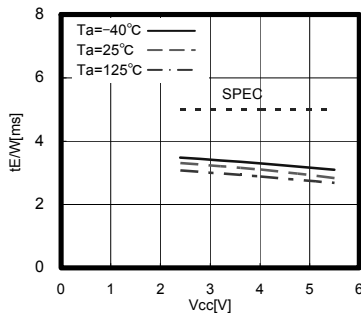


Fig.30 Write cycle time  $t_{E/W}$

●Features

○Status registers

This IC has status registers. The status register has 8 bits and expresses the following parameters.

WEN is set by the write enable command and write disable command. WEN goes into the write disable status when the power source is turned off. The R/B bit is for write confirmation and therefore cannot be set externally.

The status register value can be read by use of the read status command.

●Status registers

Product Number	bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0
BR35H160-WC	0	0	0	0	0	0	WEN	$\bar{R}/B$
BR35H320-WC								
BR35H640-WC								
BR35H128-WC								

bit	Memory location	Function
WEN	Register	Write and write status register write enable / disable status confirmation bit WEN=0=prohibited WEN=1=permitted
$\bar{R}/B$	Register	Write cycle status (READY / BUSY) status confirmation bit $\bar{R}/B$ =0=READY $\bar{R}/B$ =1=BUSY

●Command mode

Command		Contents	Ope code	
			BR35H160-WC	
			BR35H320-WC	
			BR35H640-WC	
			BR35H128-WC	
WREN	Write enable	Write enable command	0000	0110
WRDI	Write disable	Write disable command	0000	0100
READ	Read	Read command	0000	0011
WRITE	Write	Write command	0000	0010
RDSR	Read status register	Status register read command	0000	0101

●Timing chart

1. Write enable (WREN) / disable (WRDI) cycle

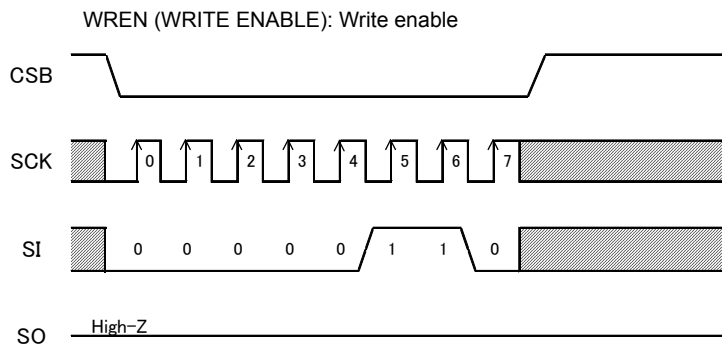


Fig.31 Write enable command

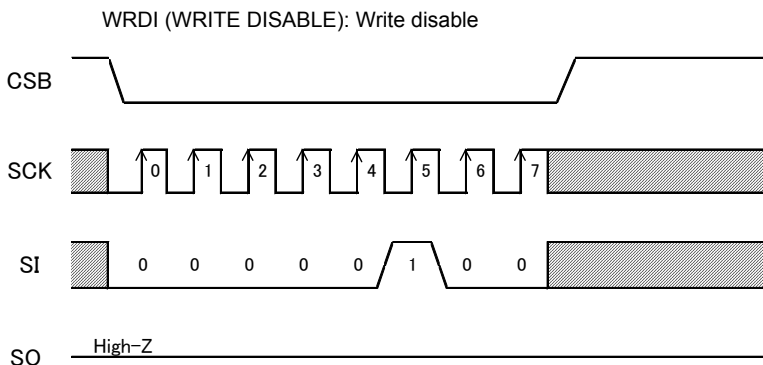
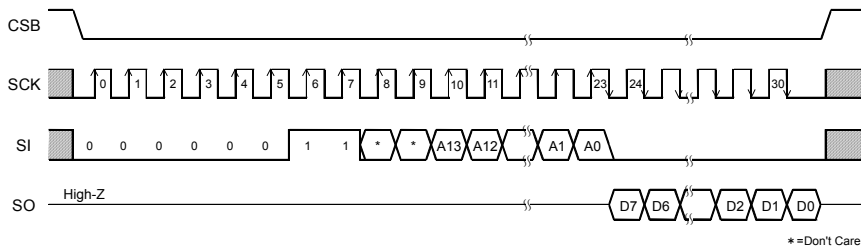


Fig.32 Write disable

○ This IC has a write enable status and a write disable status. Write enable status is achieved by the write enable command and write disable status is achieved by the write disable command. As for these commands, set CSB to LOW and then input the respective ope codes. The respective commands are accepted at the 7-th clock rise. The command is also valid with Inputs over 7 clocks.

In order to perform a write command it is necessary to use the write enable command to set the IC to the write enable status. If a write command is input during write disable status the command will be cancelled. After a write command is input during write enable status the IC will return to the write disable status. When turning on the power the IC will be in write disable status.

2. Read command (READ)

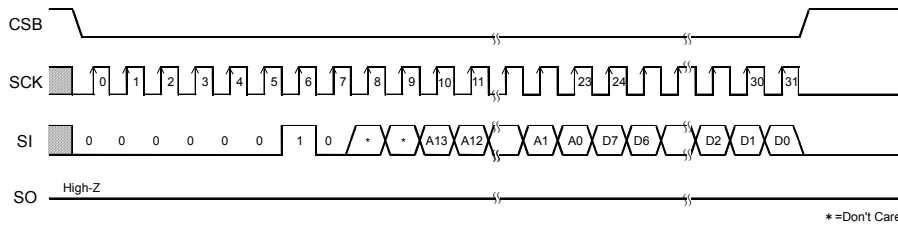


Product number	Address Length
BR35H160-WC	A10-A0
BR35H320-WC	A11-A0
BR35H640-WC	A12-A0
BR35H128-WC	A13-A0

Fig.33 Read command (BR35H160/320/640/128-WC)

By use of the read command, the data of the EEPROM can be read. As for this command, set CSB to LOW, then input the address after the read ope code. EEPROM starts data output of the designated address. Data output is started from the SCK fall of 23 clock and from D7 to D0 sequentially. The IC features an increment read function. After the output of 1 byte (8bits) of data, by continuing input of SCK the next data addresses can be read. Increment read can read all addresses of the EEPROM. After reading the data of the most the significant address, by continuing with the increment read the data of the most insignificant address is read.

3. Write command (WRITE)



Product number	Address Length
BR35H160-WC	A10-A0
BR35H320-WC	A11-A0
BR35H640-WC	A12-A0
BR35H128-WC	A13-A0

Fig.34 Write command (BR35H160/320/640/128-WC)

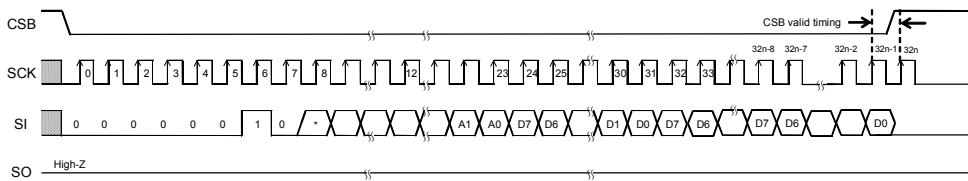


Fig.35 N Byte page write command (BR35H160/320/640-WC)

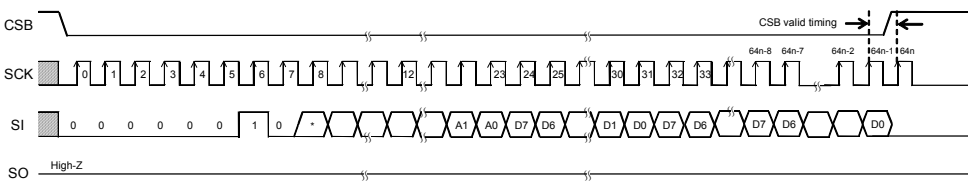


Fig.36 N Byte page write command (BR35H128-WC)

With the write command data can be written to the EEPROM. As for this command, set CSB to LOW, then input address and data after inputting the write ope code. Then, by making CSB HIGH, the EEPROM starts writing. The write time of EEPROM requires time of tE/W (Max 5ms). During tE/W, commands other than the status read command are not accepted. Start CSB after taking the last data (D0) and before the next SCK clock starts. At other timings the write command will not be executed and will be cancelled. The IC has page write functionality. After input 1 byte (8bits) of data, by continuing data input without starting CSB, data up to 32/64<sup>\*1</sup> bytes can be written in one tE/W. In page write, the insignificant 5/6<sup>\*2</sup> bit of the designated address is incremented internally every time 1 byte of data is input, and data is written to the respective addresses. When data larger then the maximum bytes is input the address rolls over and previously input data is overwritten.

Write command is executed when CSB rises between the SCK clock rising edge to recognize the 8th bit's of data input and the next SCK rising edge. At other timings the write command is not executed and cancelled (Fig.42 valid timing c). In page write, the CSB valid timing is every 8 bits. If CSB rises at other timings page write is cancelled together with the write command and the input data is reset.

\*1 BR35H160/320/640-WC = Max 32 Bytes  
 BR35H128-WC = Max 64 Bytes  
 \*2 BR35H160/320/640-WC = Lower 5 bits  
 BR35H128-WC = Lower 6 bits

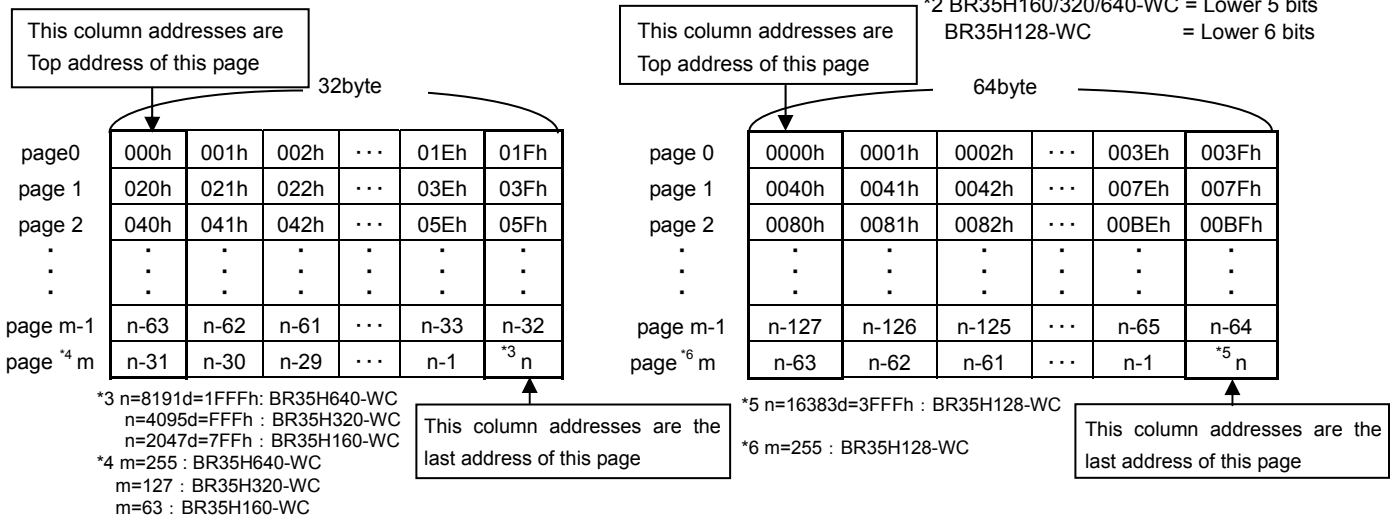


Fig.37 EEPROM physical address for Page write command (32/64Byte)

● Example of Page write command

No.	Addresses of Page0	000h	001h	002h	....	01Eh	01Fh
①	Previous data	00h	01h	02h	....	1Eh	1Fh
②	2 bytes input data	AAh	55h	-	....	-	-
③	After No.②	AAh	55h	02h	....	1Eh	1Fh
④	34 byte input data	AAh	55h	AAh	....	AAh	55h
		FFh	00h	-	....	-	-
⑤	After No.④	FFh	00h	AAh	....	AAh	55h

- a : In case of input the data of No.② which is 2 bytes page write command for the data of No.①, EEPROM data changes like No.③.
- b : In case of input the data of No.④ which is 34 bytes page write command for the data of No.①, EEPROM data changes like No.⑤.
- c : In case of a or b, when write command is cancelled, EEPROM data keep No.①.

In page write command, when data is set to the last address of a page (e.g. address "03Fh" of page 1), the next data will be set to the top address of the same page (e.g. address "020h" of page 1). This is why page write address increment is available in the same page. As a reference, if of 32 bytes, page write command is executed for 2 bytes the data of the other 30 bytes without addresses will not be changed.



## 4. Status register read command

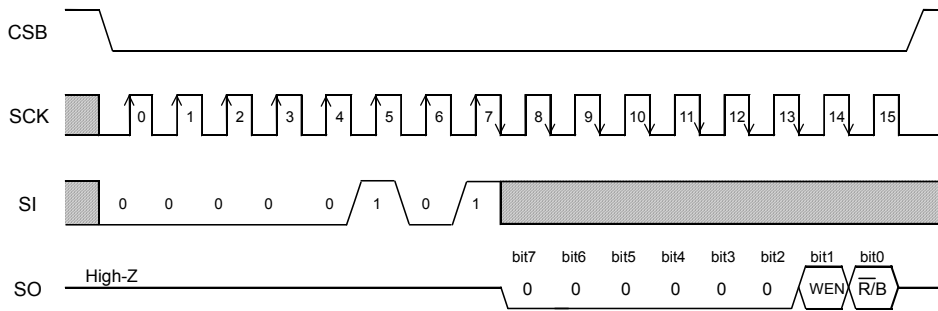


Fig.38 Status register read command (BR35H160/320/640/128-WC)

The EEPROM status can be read by use of the status register read command. For this command set CSB to Low then input the ope code of the status register read command followed by the clock input as shown above. The data of status register will then be read out. This command features increment functionality. When clock input is continued during CSB=Low, 8 bytes of status register data will be continuously read out. When this command is executed from the start of write programming to the end of write programming, the end of write programming can be confirmed by checking the following changes: WEN=Low followed by  $\overline{R/B}$ =Low. After confirming the end of write programming, before inputting the next command CSB first needs to be High and then put back to Low.

## ●At standby

## ○Current at standby

Set CSB "H", and be sure to set SCK, SI input "L" or "H". Do not input intermediate electric potential.

## ○Timing

As shown in Fig.39, at standby, when SCK is "H", even if CSB falls, SI status is not read at fall edge. SI status is read at SCK rise edge after fall of CSB. At standby and at power ON/OFF, set CSB "H" status

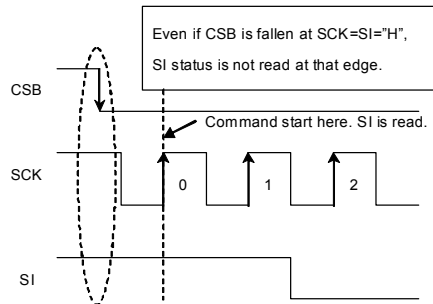


Fig.39 Operating timing

●Method to cancel each command

OREAD

- Cancellation method: cancel by CSB = "H"

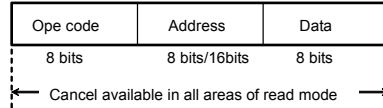


Fig.40 READ cancel valid timing

ORDSR

- Cancellation method: cancel by CSB = "H"

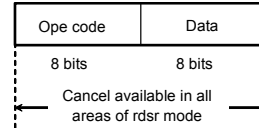


Fig.41 RDSR cancel valid timing

OWRITE, PAGE WRITE

- a : Ope code, address input area.  
Cancellation possible by CSB="H"
  - b : Data input area (D7~D1 input area)  
Cancellation possible by CSB="H"
  - c : Data input area (D0 area)  
Write starts after CSB rise.
  - d : tE/W area.  
After CSB rise, cancellation is no longer possible.
- Cancellation is possible by CSB = "H". However, when write starts (CSB rise) in area c, cancellation is no longer possible. Also, cancellation is not possible by continues inputting of SCK clock. In page write mode, there is a write enable area at every 8 clocks.

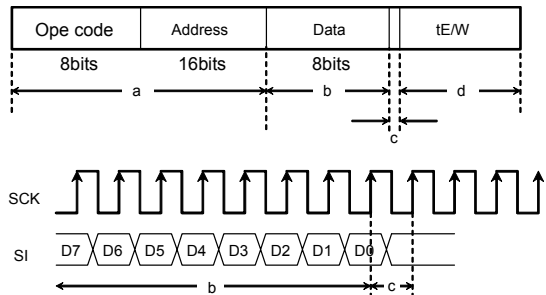


Fig.42 WRITE cancel valid timing

Note 1) If Vcc is set to OFF during execution of write the data of the designated address is not guaranteed. Please execute write again.

Note 2) If CSB rises at the same timing as that the SCK rises, write execution / cancel will become unstable. Therefore, it is recommended to let CSB rise in the SCK = "L" area. As for SCK rise, ensure a timing of tCSS / tCSH or higher.

OWREN/WRDI

- a : From ope code to 7-th clock rise, cancel by CSB = "H".
- b : Cancellation is not possible when CSB rises after the 7-th clock.

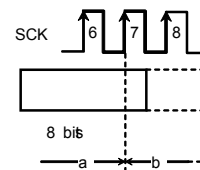


Fig.43 WREN/WRDI cancel valid timing

### ●High speed operations

In order to realize stable high speed operations, pay attention to the following input / output pin conditions.

#### ○Input pin pull up, pull down resistance

When attaching pull up, pull down resistance to the EEPROM input pin, select an appropriate value for the microcontroller VOL, IOL from the VIL characteristics of this IC.

#### ○Pull up resistance

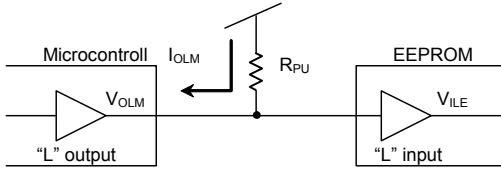


Fig.44 Pull up resistance

$$R_{PU} \geq \frac{V_{CC} - V_{OLM}}{I_{OLM}} \quad \dots \textcircled{1}$$

$$V_{OLM} \leq V_{ILE} \quad \dots \textcircled{2}$$

Example) When  $V_{CC}=5V$ ,  $V_{ILE}=1.5V$ ,  $V_{OLM}=0.4V$ ,  $I_{OLM}=2mA$ , from the equation  $\textcircled{1}$ ,

$$R_{PU} \geq \frac{5 - 0.4}{2 \times 10^{-3}}$$

$$\therefore R_{PU} \geq 2.3[k\Omega]$$

With the value of  $R_{PU}$  to satisfy the above equation,  $V_{OLM}$  becomes 0.4V or lower, and with  $V_{ILE}(=1.5V)$ , the equation  $\textcircled{2}$  is also satisfied.

- $V_{ILE}$  :EEPROM  $V_{IL}$  specifications
- $V_{OLM}$  :Microcontroller  $V_{OL}$  specifications
- $I_{OLM}$  :Microcontroller  $I_{OL}$  specifications

Also, in order to prevent malfunction or erroneous write at power ON/OFF, be sure to make CSB pull up.

#### ○Pull down resistance

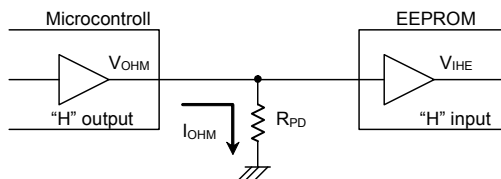


Fig.45 Pull down resistance

$$R_{PD} \geq \frac{V_{OHM}}{I_{OIH}} \quad \dots \textcircled{3}$$

$$V_{OHM} \geq V_{IHE} \quad \dots \textcircled{4}$$

Example) When  $V_{CC}=5V$ ,  $V_{OHM}=V_{CC}-0.5V$ ,  $I_{OIH}=0.4mA$ ,  $V_{IHE}=V_{CC} \times 0.7V$ , from the equation  $\textcircled{3}$ ,

$$R_{PD} \geq \frac{5 - 0.5}{0.4 \times 10^{-3}}$$

$$\therefore R_{PD} \geq 11.3[k\Omega]$$

The operations speed changes according to the amplitude  $V_{IHE}$ ,  $V_{ILE}$  of the signals input to the EEPROM. More stable high speed operations can be realized by inputting signals with  $V_{CC} / GND$  levels of amplitude. On the contrary, when signals with an amplitude of  $0.8V_{CC} / 0.2V_{CC}$  are input, operation speed slows down.<sup>1)</sup>

In order to realize more stable high speed operation, it is recommended to set the values of  $R_{PU}$ ,  $R_{PD}$  as large as possible, and to have the amplitude of the signals input to the EEPROM close to the  $V_{CC} / GND$  amplitude level.

(<sup>1</sup> In this case, the guaranteed value of operating timing is guaranteed.)

#### ○SO load capacitance condition

The load capacitance of the SO output pin affects the SO output delay characteristic. (Data output delay time, time from HOLDB to High-Z, output rise time, output fall time.). Make the SO load capacitance small to improve the output delay characteristic.

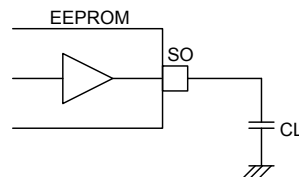


Fig.46 SO load dependency of data output delay time  $t_{PD}$

#### ○Other cautions

Make all wires from the microcontroller to EEPROM input pin the same length. This in order to prevent setup / hold violation to the EEPROM.

●Equivalent circuit

○Output circuit

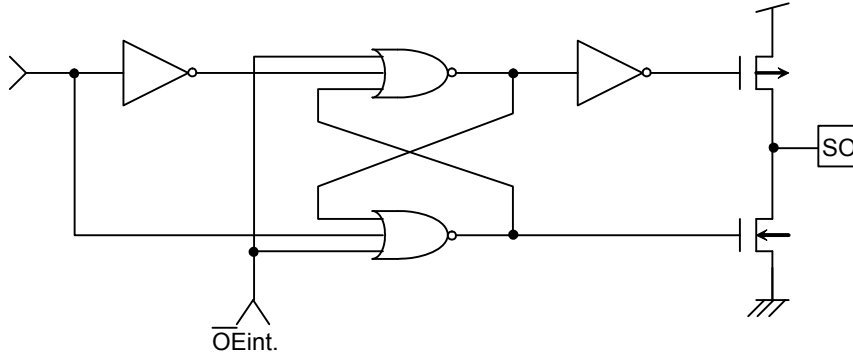


Fig.47 SO output equivalent circuit

○Input circuit

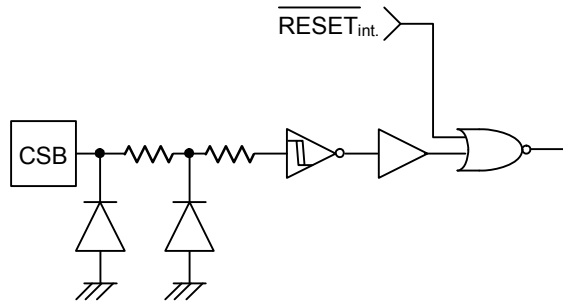


Fig.48 CSB input equivalent circuit

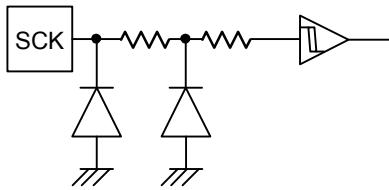


Fig.49 SCK input equivalent circuit

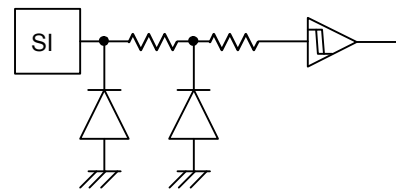


Fig.50 SI input equivalent circuit

### ●Notes on power ON/OFF

○At power ON/OFF set CSB="H" (=Vcc).

When CSB is "L", the IC goes into input accept status (active). If power is turned on in this status noises, etc. may cause malfunction or erroneous write. To prevent this, set CSB to "H" at power ON. (When CSB is in "H" status, all inputs are canceled.)

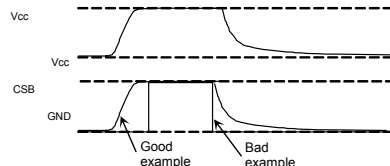


Fig.51 CSB timing at power ON/OFF

(Good example) CSB terminal is pulled up to Vcc.

After turning power off allow for 10ms or more before turning power on again. If power is turned on without observing this condition, the IC internal circuit may not be reset.

(Bad example) CSB terminal is "L" at power ON/OFF.

In this case, CSB always becomes "L" (active status), and the EEPROM may malfunction or perform an erroneous write due to noises, etc.

This can even occur when CSB input is High-Z.

### ○LVCC circuit

LVCC (Vcc-Lockout) circuit prevents data rewrite action at low power and prevents erroneous write.

At LVCC voltage (Typ. =1.9V) or below, it prevents data rewrite.

### ○P.O.R. circuit

This IC has a POR (Power On Reset) circuit as countermeasure against erroneous write. After the POR operation is performed, write disable status is entered. The POR circuit is only valid when power is ON and does not work when power is OFF. When power is ON and the following recommended  $t_R$ ,  $t_{OFF}$ ,  $V_{bot}$  conditions are not satisfied, write enable status might be entered due to noise etc.

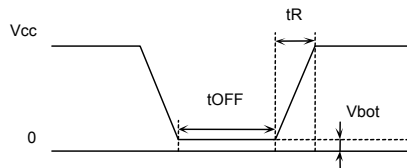


Fig.52 Rise waveform

Recommended conditions for  $t_R$ ,  $t_{OFF}$ ,  $V_{bot}$

$t_R$	$t_{OFF}$	$V_{bot}$
10ms or below	10ms or higher	0.3V or below
100ms or below	10ms or higher	0.2V or below

### ●Noise countermeasures

#### ○Vcc noise (bypass capacitor)

When noise or surge gets in the power source line, malfunction may occur. To prevent this, it is recommended to attach a bypass capacitor (0.1 $\mu$ F) between IC Vcc and GND, as close to IC as possible.

It is also recommended to attach a bypass capacitor between the board Vcc and GND.

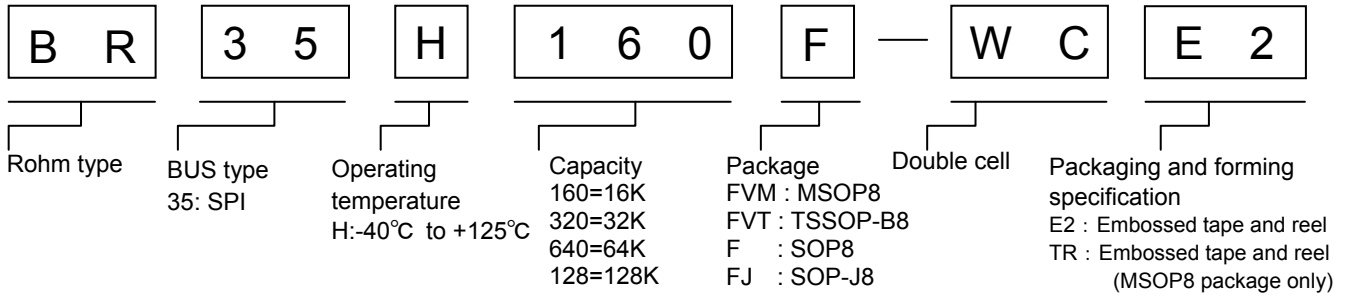
#### ○SCK noise

When the rise time of SCK ( $t_{RC}$ ) is long and there is a certain degree of noise, malfunction may occur due to clock bit displacement. To avoid this, a Schmitt trigger circuit is built in the SCK input. The hysteresis width of this circuit is set to about 0.2V. If noises exist at the SCK input set the noise amplitude to 0.2Vp-p or below. Also, it is recommended to set the rise time of SCK ( $t_{RC}$ ) to 100ns or below. In case the rise time is 100ns or higher, sufficient noise countermeasures are needed. Clock rise, fall time should be as small as possible.

**●Notes for use**

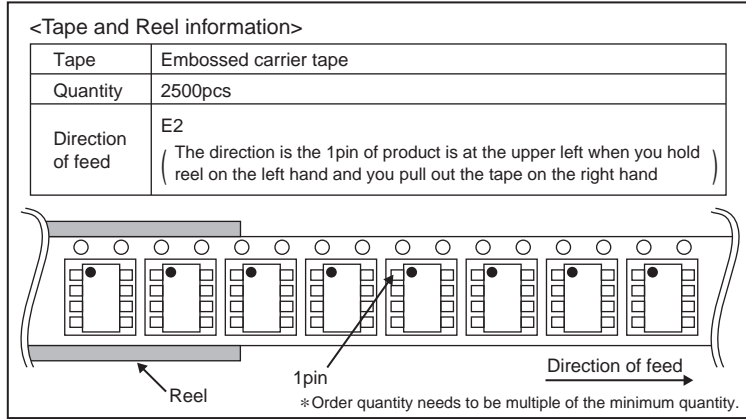
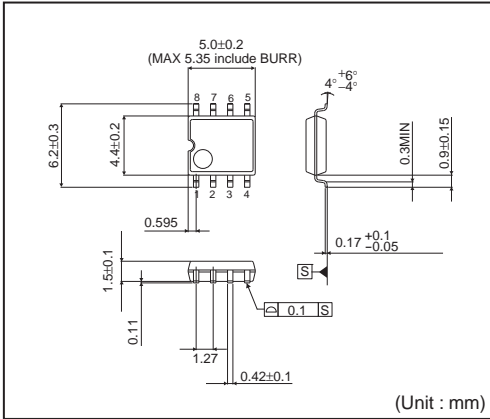
- (1) Described numeric values and data are design representative values and not guaranteed.
- (2) We believe that the application circuit examples are recommendable. However, in actual use, please sufficiently further characteristics. When changing the fixed number of external parts, make your decision with sufficient margin, in consideration of static characteristics, transition characteristics and fluctuations of external parts and our LSI.
- (3) Absolute maximum ratings  
If the absolute maximum ratings such as impressed voltage, operating temperature range, etc. are exceeded, the LSI might be damaged. Please do not impress voltage or temperature exceeding the absolute maximum ratings. In case of fear of exceeding the absolute maximum ratings please take physical safety countermeasures such as fuses and see to it that conditions exceeding the absolute maximum ratings are impressed to LSI.
- (4) GND electric potential  
Set the voltage of the GND terminal as low as possible with all action conditions. Ensure that that all terminal voltages are higher than that of the GND terminal.
- (5) Heat design  
In consideration of permissible dissipation in actual use condition, please carry out the heat design with sufficient margin.
- (6) Inter-terminal short circuit and wrong packaging  
When packaging the LSI onto a board, pay sufficient attention to the LSI direction and displacement. Wrong packaging may damage LSI. Short circuit between LSI terminals, terminals and power source, terminal and GND due to foreign matters may also result in LSI damage.
- (7) Use in strong electromagnetic fields may cause malfunction. Therefore, please evaluate the design sufficiently.

●Ordering part number

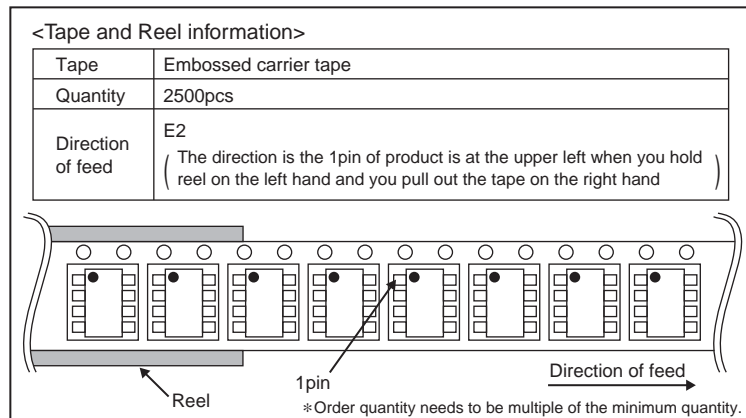
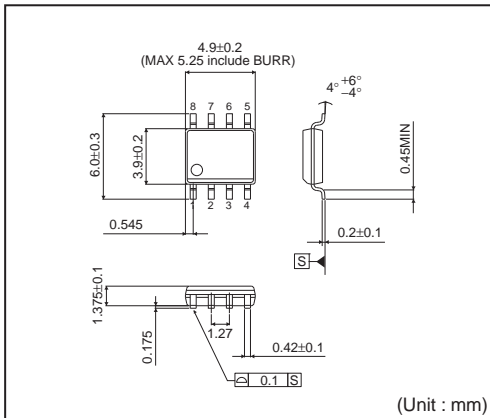


●Package specifications

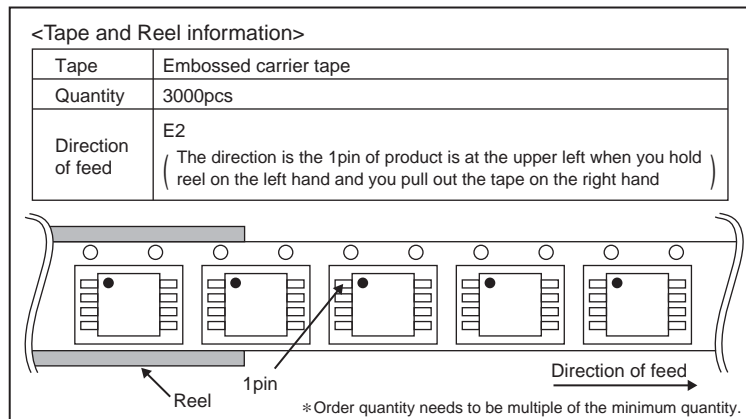
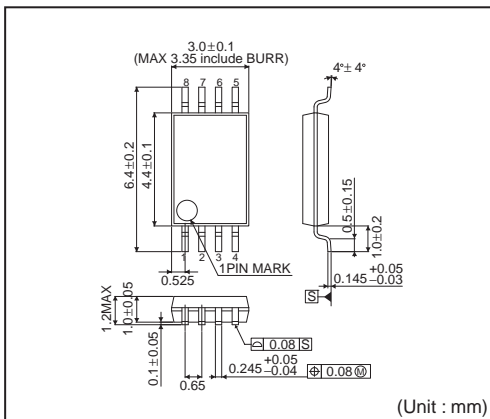
SOP8



SOP-J8

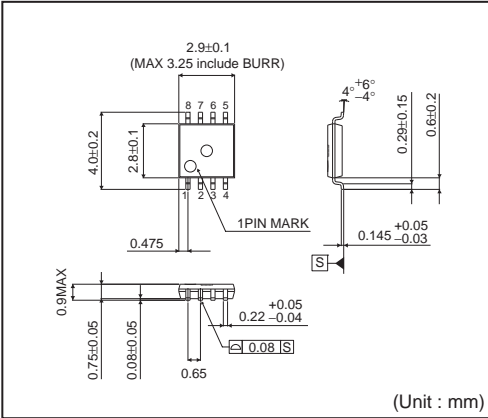


TSSOP-B8



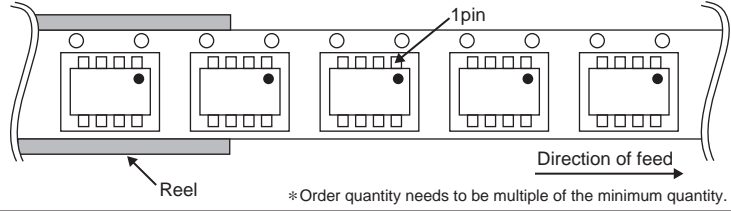
●Package specifications (Continue)

MSOP8



<Tape and Reel information>

Tape	Embossed carrier tape
Quantity	3000pcs
Direction of feed	TR ( The direction is the 1pin of product is at the upper right when you hold reel on the left hand and you pull out the tape on the right hand )





## Notes

No copying or reproduction of this document, in part or in whole, is permitted without the consent of ROHM Co.,Ltd.

The content specified herein is subject to change for improvement without notice.

The content specified herein is for the purpose of introducing ROHM's products (hereinafter "Products"). If you wish to use any such Product, please be sure to refer to the specifications, which can be obtained from ROHM upon request.

Examples of application circuits, circuit constants and any other information contained herein illustrate the standard usage and operations of the Products. The peripheral conditions must be taken into account when designing circuits for mass production.

Great care was taken in ensuring the accuracy of the information specified in this document. However, should you incur any damage arising from any inaccuracy or misprint of such information, ROHM shall bear no responsibility for such damage.

The technical information specified herein is intended only to show the typical functions of and examples of application circuits for the Products. ROHM does not grant you, explicitly or implicitly, any license to use or exercise intellectual property or other rights held by ROHM and other parties. ROHM shall bear no responsibility whatsoever for any dispute arising from the use of such technical information.

The Products specified in this document are intended to be used with general-use electronic equipment or devices (such as audio visual equipment, office-automation equipment, communication devices, electronic appliances and amusement devices).

The Products specified in this document are not designed to be radiation tolerant.

While ROHM always makes efforts to enhance the quality and reliability of its Products, a Product may fail or malfunction for a variety of reasons.

Please be sure to implement in your equipment using the Products safety measures to guard against the possibility of physical injury, fire or any other damage caused in the event of the failure of any Product, such as derating, redundancy, fire control and fail-safe designs. ROHM shall bear no responsibility whatsoever for your use of any Product outside of the prescribed scope or not in accordance with the instruction manual.

The Products are not designed or manufactured to be used with any equipment, device or system which requires an extremely high level of reliability the failure or malfunction of which may result in a direct threat to human life or create a risk of human injury (such as a medical instrument, transportation equipment, aerospace machinery, nuclear-reactor controller, fuel-controller or other safety device). ROHM shall bear no responsibility in any way for use of any of the Products for the above special purposes. If a Product is intended to be used for any such special purpose, please contact a ROHM sales representative before purchasing.

If you intend to export or ship overseas any Product or technology specified herein that may be controlled under the Foreign Exchange and the Foreign Trade Law, you will be required to obtain a license or permit under the Law.



Thank you for your accessing to ROHM product informations.  
More detail product informations and catalogs are available, please contact us.

**ROHM Customer Support System**

<http://www.rohm.com/contact/>



Компания «ЭлектроПласт» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Оперативные поставки широкого спектра электронных компонентов отечественного и импортного производства напрямую от производителей и с крупнейших мировых складов;
- Поставка более 17-ти миллионов наименований электронных компонентов;
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- Лицензия ФСБ на осуществление работ с использованием сведений, составляющих государственную тайну;
- Поставка специализированных компонентов (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Aeroflex, Peregrine, Syfer, Eurofarad, Texas Instrument, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Помимо этого, одним из направлений компании «ЭлектроПласт» является направление «Источники питания». Мы предлагаем Вам помощь Конструкторского отдела:

- Подбор оптимального решения, техническое обоснование при выборе компонента;
- Подбор аналогов;
- Консультации по применению компонента;
- Поставка образцов и прототипов;
- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



#### Как с нами связаться

**Телефон:** 8 (812) 309 58 32 (многоканальный)

**Факс:** 8 (812) 320-02-42

**Электронная почта:** [org@eplast1.ru](mailto:org@eplast1.ru)

**Адрес:** 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.