

TLE5014 Programmer

Application Note

About this document

Scope and purpose

This document describes the Evaluation Kit for the TLE5014 GMR based angle sensor.

The purpose of this manual is to describe the software installation process and how to use the TLE5014 angle sensor Evaluation Kit.

Intended audience

This document is intended for anyone who wants to use the TLE5014 Evaluation Kit.

Table of contents

	About this document	1
	Table of contents	2
1	General description	3
1.1	Sensor connection	4
1.2	TLE5014 satellite board	5
1.3	Jumper setting	6
2	Installation	7
3	Programming	8
3.1	Programmer connection	8
3.2	Angle read-out	9
3.3	User menu	10
3.3.1	EEPROM Register	10
3.3.2	Program by feature	11
3.3.2.1	PWM frequency calculation	11
3.3.3	Read SSM	12
3.3.4	Burn Angle Base	13
3.4	Look-up table programming	14
4	EEPROM map PWM interface	15
4.1	EEPROM map	15
4.2	TLE5014 EEPROM 0x00A2 _H : PWI_MD_USR	16
4.3	Angle base calculation	17
4.4	SPC address configuration	17
4.5	Comments	18
5	Revision history	19

General description

1 General description

The programmer consists of an Infineon XMC1100 Boot Kit and a “shield”, which can be plugged onto the Boot Kit.

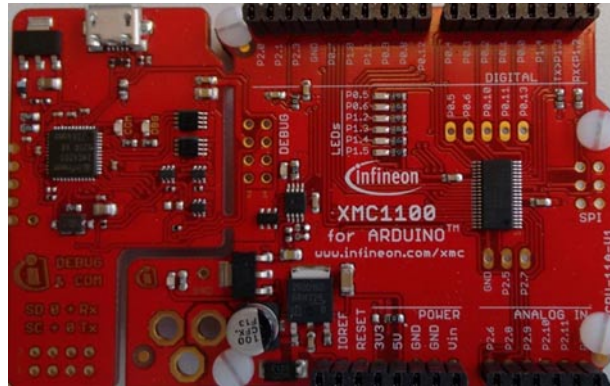


Figure 1 Infineon XMC1100 Boot Kit

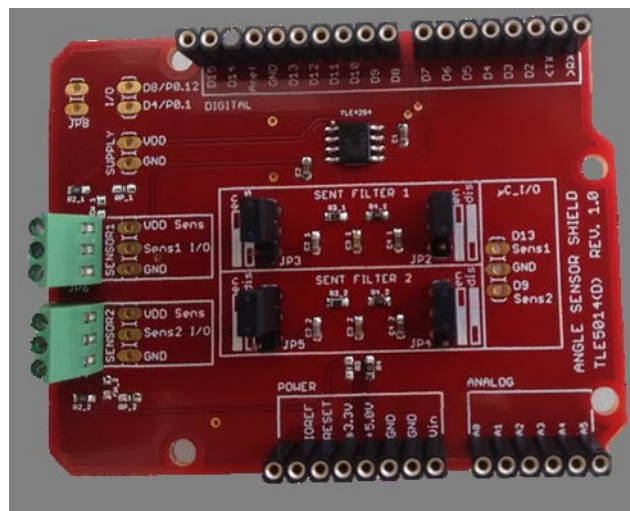


Figure 2 TLE5014 programmer shield

The software consists of one file: TLE5014 - **BootKit** – V2.x.x.zip

For connection to a PC, a USB cable is required.

General description

1.1 Sensor connection

The shield has to be plugged onto the Boot Kit. Care has to be taken that the correct pins are connected. The TLE5014 can be connected via a cable to the shield.

Three connections are required:

- VDD
- I/O
- GND

The shield supports two sensors with separated connectors.

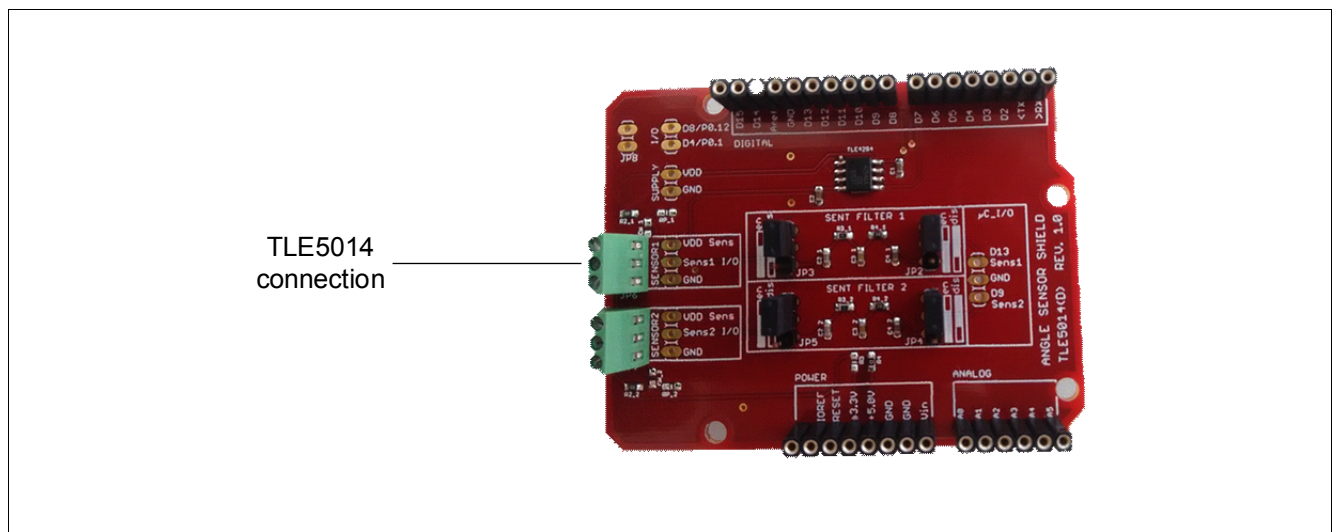


Figure 3 TLE5014 sensor connection

Care has to be taken that all pins of the TLE5014 are connected according to the TLE5014 datasheet.

General description

1.2 TLE5014 satellite board

A satellite board is provided with a TLE5014D dual channel angle sensor which can be connected to the shield of the Eval Kit. The TLE5014 on this board is pre-programmed with the following settings:

- SENT single secure sensor (incl. rolling counter and inverted nibble)
- $UT=3.0\ \mu s$, pause pulse, no short serial message

The sensor is fully configurable and can be set to different protocol options and interfaces (SENT, SPC, PWM).

For a SPC bus mode:

- channel 1 has the default hard-wired address ID=0
- channel 2 has ID=1

It is possible to change the address by changing the “zero-ohm” resistors on the board (see figure and table below).

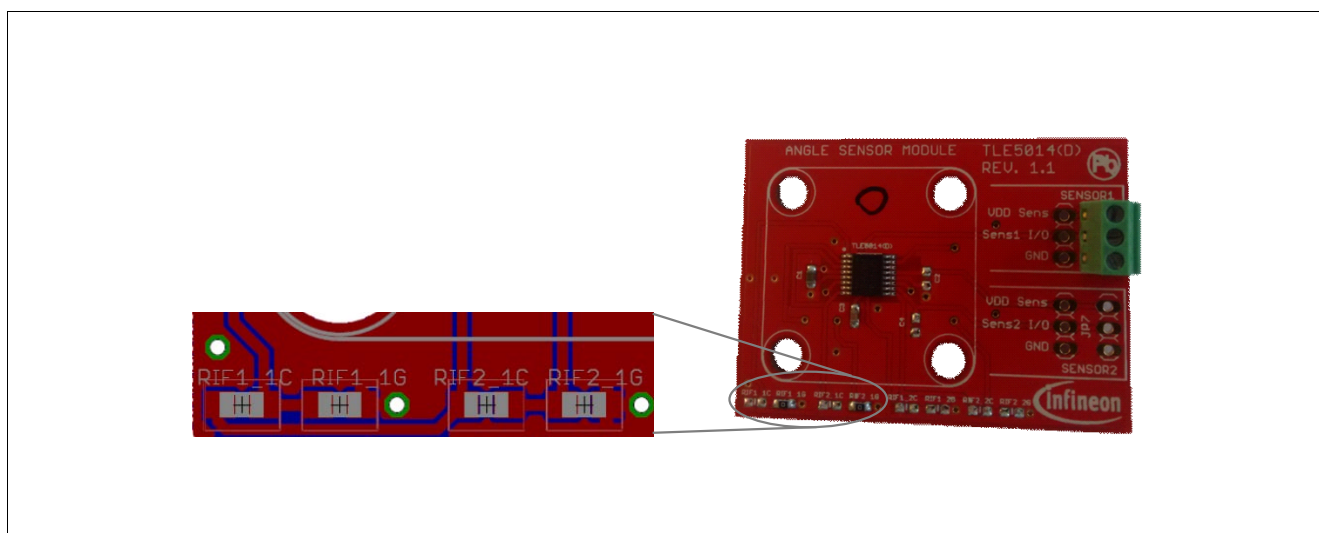


Figure 4 Satellite board

Table 1 Change the address

	RIF1_1C	RIF1_1G	RIF2_1C	RIF2_1G
ID = 0		x		x
ID = 1	x			x
ID = 2		x	x	
ID = 3	x		x	

General description**1.3 Jumper setting****Table 2 Jumper setting**

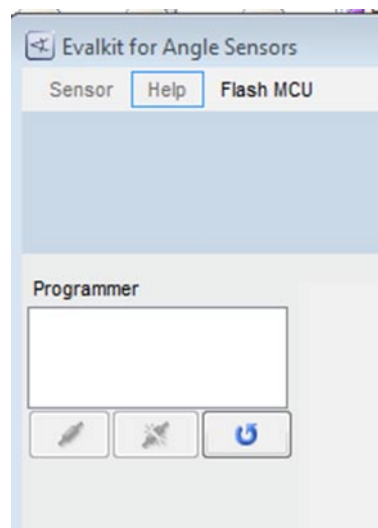
Jumper	Position	Description
J2/J3	en	SENT filter for sensor 1 enabled
J2/J3	dis	SENT filter for sensor 1 disabled
J4/J5	en	SENT filter for sensor 2 enabled
J4/J5	dis	SENT filter for sensor 2 disabled

Note: For reading/writing the EEPROM the SENT filter has to be disabled.

Installation

2 Installation

1. Download and install the Segger driver from following web page:
https://www.segger.com/downloads/jlink/JLink_Windows.exe
2. Connect the programmer with an USB cable to an USB 2.0 port.
3. Install the programmer software by double-clicking on the file: TLE5014 – **BootKit** – V2.x.x.msi.
4. Start the installed software TLE5014 – BootKit.
5. If you use the microcontroller the first time or if you use a new software revision, click on the **Flash MCU** button (μ C is flashed with firmware).



Programming

3 Programming

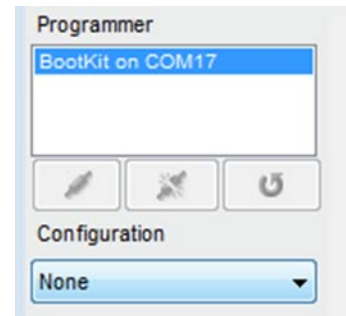
3.1 Programmer connection

After starting the software, click the **Connect** button to connect the Programmer.



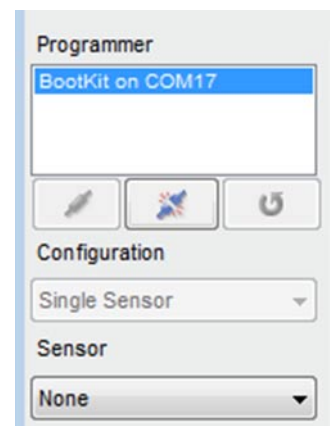
In the **Configuration** drop-down list select your configuration:

- Single sensor (= no bus operation)
- Bus operation (several sensors on one SPC line)



In the **Sensor** drop-down list select the sensor which you want to read. The Eval Kit supports two channels which correspond to the two connectors on the PCB:

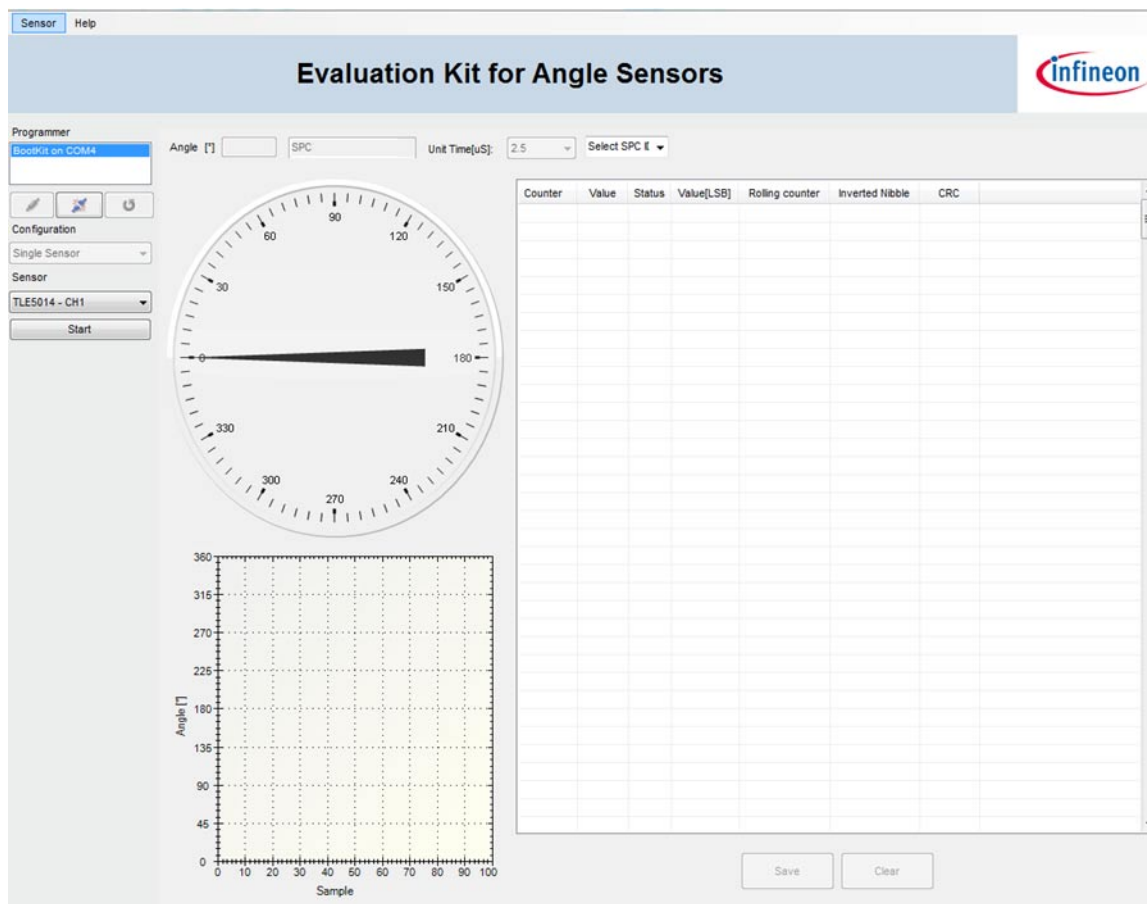
- TLE5014 CH1 = Sens1
- TLE5014 CH2 = Sens2



Programming

3.2 Angle read-out

Click the **Start** button to start the angle read-out. The display shows the real time angle read-out of the sensor and other protocol related values (e.g. status nibble for SENT/SPC).



Click the **Stop** button to stop the sensor read-out.

The tool automatically displays the preprogrammed sensor interface and unit time.

The SPC address has to be set manually:

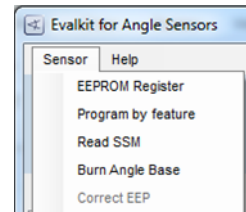
Angle [°] SPC Unit Time[μs]: 2.5

Programming

3.3 User menu

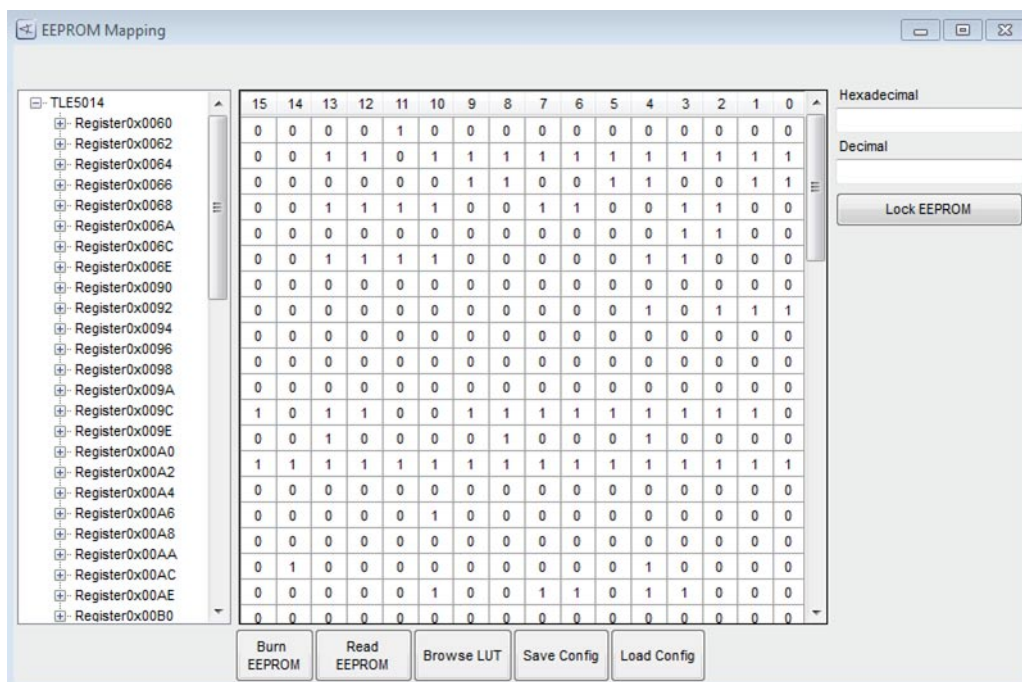
Click on the **Sensor** menu and select one of the following options:

- [EEPROM Register](#)
- [Program by feature](#)
- [Read SSM](#)
- [Burn Angle Base](#)



3.3.1 EEPROM Register

Select **Sensor > EEPROM Register** in the menu bar on the top to display the EEPROM register mapping. Click on the register in the left column to highlight the register and to display the content on the right.



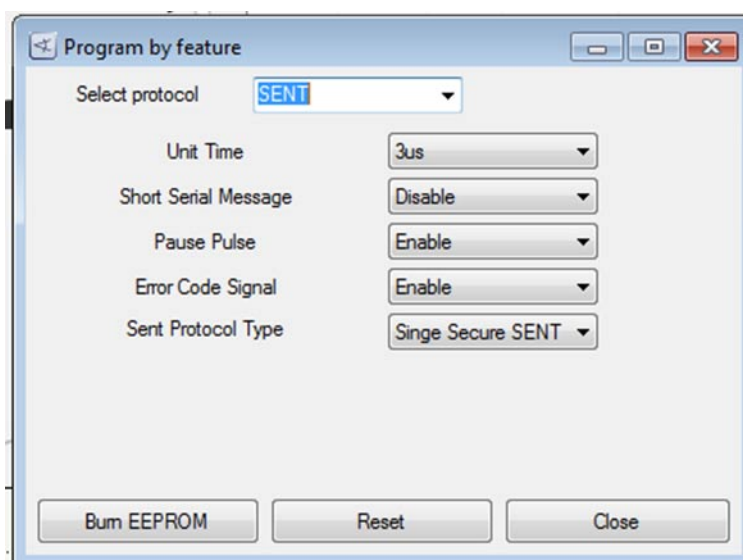
Button	Description
Read EEPROM	Read the current EEPROM values and update the displayed EEPROM content. A register content can be modified by editing the value on the right either in a hexadecimal or a decimal value and pressing RETURN.
Burn EEPROM	Burn the displayed content to the TLE5014 EEPROM. A successfully EEPROM burning is indicated with a "Burn successful!" message. <i>Note:</i> Care has to be taken not to modify EEPROM registers which change the sensor configuration. This could result in a wrong function of the device.
Browse LUT	Browse for a .txt file which contains the values intended to be used in the look-up table. See Chapter 3.4 for more details. <i>Note:</i> After re-loading LUT values (Browse LUT) or EEPROM content (Load Config) the EEPROM has to be burned by pressing Burn EEPROM.

Programming

Button	Description
Save Config	Save the actual EEPROM settings in a .txt file.
Load config	Load the EEPROM content from a .txt file. <i>Note: After re-loading LUT values (Browse LUT) or EEPROM content (Load Config) the EEPROM has to be burned by pressing Burn EEPROM.</i>
Lock EEPROM	Locks the EEPROM. A further re-programming is not possible. <i>Note: There is no "Unlock" function implemented.</i>

3.3.2 Program by feature

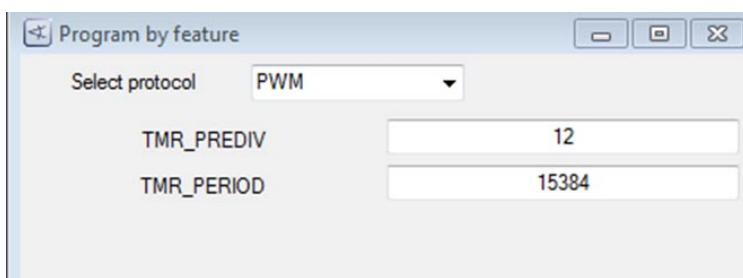
Select **Sensor > Program by feature** in the menu bar on the top to display the actual sensor configuration. Modifications can be done and then burned to the EEPROM.



Button	Description
Burn EEPROM	Burn the EEPROM.
Reset	Restore the default configuration but only as long as the EEPROM has NOT be burned.

3.3.2.1 PWM frequency calculation

When setting the **Select protocol** to **PWM**, two parameters have to be specified which give the PWM frequency.



Programming

The PWM frequency is calculated according following formula:

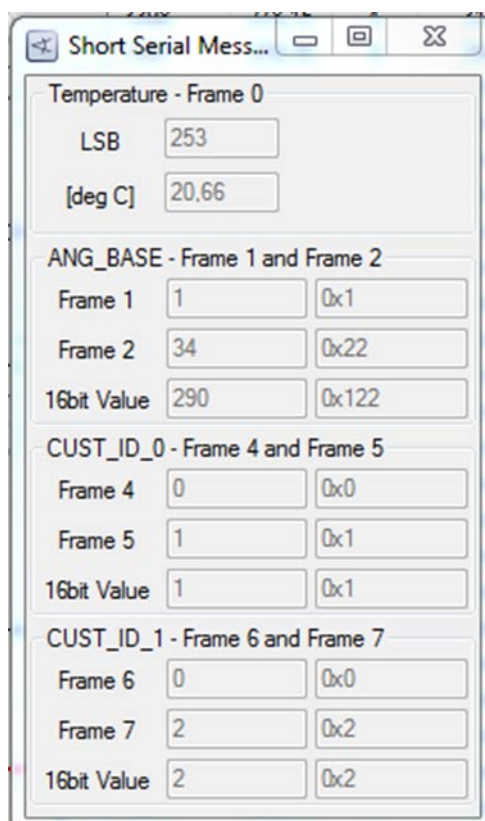
(3.1)

$$f[\text{Hz}] = \frac{40000000}{(1 + \text{TMR_PREDIV})(\text{TMR_PERIOD})}$$

3.3.3 Read SSM

Select **Sensor > Read SSM** in the menu bar on the top to display the actual content of the short serial message SSM:

- Temperature
- Angle base & rotation direction
- 32-bit customer ID



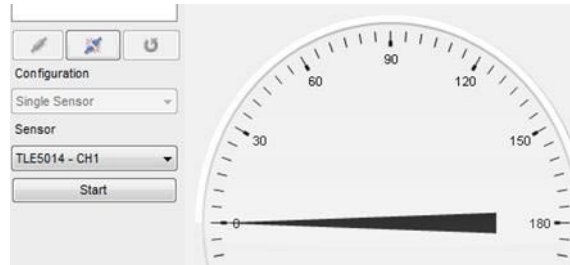
The screenshot shows a window titled "Short Serial Mess..." with a tree view of SSM data. The data is organized into four sections, each with a title, a "Frame" field, a "16bit Value" field, and a "hex" field.

Section	Frame	16bit Value	hex
Temperature - Frame 0	LSB	253	
	[deg C]	20,66	
ANG_BASE - Frame 1 and Frame 2	Frame 1	1	0x1
	Frame 2	34	0x22
	16bit Value	290	0x122
CUST_ID_0 - Frame 4 and Frame 5	Frame 4	0	0x0
	Frame 5	1	0x1
	16bit Value	1	0x1
CUST_ID_1 - Frame 6 and Frame 7	Frame 6	0	0x0
	Frame 7	2	0x2
	16bit Value	2	0x2

Programming

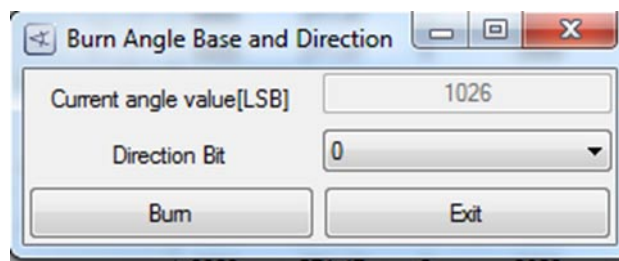
3.3.4 Burn Angle Base

To define a new angle base, first **Start** the read-out of angle values.



The application has to be turned to the desired new zero-value and read-out has to be stopped by clicking **Stop**.

Select **Sensor > Burn Angle Base** in the menu bar on the top to display the Burn Angle Base window.



Click **Burn** to burn the value to the EEPROM as new angle base.

Programming

3.4 Look-up table programming

The **Browse LUT** button opens a window to select a .txt file with the data which should be programmed into the look-up table (LUT).

Opening the .txt file loads the content in the displayed EEPROM mapping.

After loading the file press **Burn EEPROM** to burn the LUT values to the EEPROM.

txt file with values for LUT

The .txt file for the LUT values consists of a header and 32 pair of data, separated by a comma. One pair consists of the real angle value and the read out of the sensor at this position as a 12-bit value. The 32 real angle values can not be modified and have to be 0°, 11.25°, 22.5°, ... 348.75°.

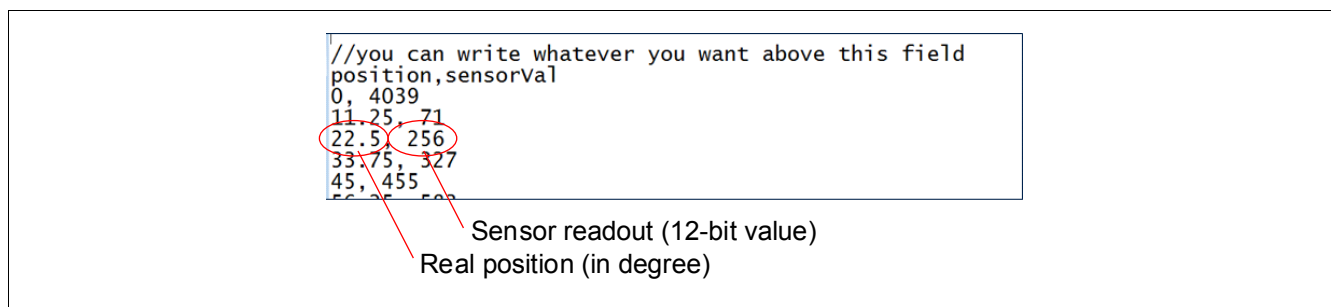


Figure 5 Pair of data

EEPROM map PWM interface

4 EEPROM map PWM interface

Table 3 EEPROM map PMW interface

Register address	Register name	Bit	Description
0x0060 _H	Data duty cycle min. value	[13:0]	0% ... 100% mapped to 0 ... 16383
0x0062 _H	Data duty cycle max. value	[13:0]	0% ... 100% mapped to 0 ... 16383
0x0064 _H	Diagnostic value low	[13:0]	0% ... 100% mapped to 0 ... 16383
0x0066 _H	Diagnostic value high	[13:0]	0% ... 100% mapped to 0 ... 16383
0x0068 _H	PWM predivider	[7:0]	TMP_PREDIV
0x006A _H	PWM period	[13:0]	TMP_PERIOD

Example: Data duty cycle range

0x0060_H = 2048 → 12.5%

0x0062_H = 14335 → 87.5%

0° ... 360° mapped to 12.5% ... 87.5%

Example: Diagnostic range

0x0064_H = 819 → 5% (diagnostic low value)

0x0066_H = 15564 → 95% (diagnostic high value)

4.1 EEPROM map

Only a few registers should be modified by the user, all others are pre-programmed. Changing these registers might change sensor behavior and accuracy.

The following registers can be changed by the user:

Table 4 EEPROM map overview

Register address	Register name	Bit	Description
0x00A0 _H	ANG_BASE	[15:2]	14-bit angle base
0x00A0 _H	ANG_BASE	[1]	Rotation direction
0x00A2 _H	PWI_MD_USR	[15:0]	Protocol and interface settings
0x00A4 _H	SPC_ADDR	[9:8]	Determines the SPC address of the sensor
0x00B0 _H ... EE _H	LUT	[15:0]	Look-up table, 32 registers in total
0x00F2 _H	Cust_ID	[15:0]	Customer ID, will be transmitted via SSM
0x00F4 _H	Cust_ID	[15:0]	Customer ID, will be transmitted via SSM
0x00F6 _H ... FE _H	Cust_ID	[15:0]	Customer ID

EEPROM map PWM interface

4.2 TLE5014 EEPROM 0x00A2_H: PWI_MD_USR

Table 5 PWI_MD_USR

Name	Bit	Description	Value
PWI_MODE	[15:13]	Interface selection	100 _B : PWM 010 _B : SENT 001 _B : SPC
PWM_EDGE	[12]	PWM starting edge	0 _B : Rising 1 _B : Falling
SENT/SPC_LT_5_3	[11]	SENT/SPC low time	0 _B : 5UT 1 _B : 3UT
SPC_TEMP	[10]	Temperature information	0 _B : No temp. nibble 1 _B : Temperature nibble
SPC_RCNIB	[9]	Rolling counter	0 _B : RC nibble enabled 1 _B : No RC nibble
SPC_RCCRC	[8]	Rolling counter in CRC	0 _B : No RC in CRC 1 _B : RC in CRC
SPC_TRIG	[7]	SPC bus mode	0 _B : 90 µs trigger length fix 1 _B : variable trigger length
SENT_PROMO	[6]	SENT protocol type	0 _B : Single secure sensor 1 _B : Standard SENT
SENT_ERR_SIG	[5]	SENT Error indication	0 _B : error code "4091" in data range and status nibble 1 _B : Error in status nibble only
SENT_PAPU	[4]	Pause pulse activation	0 _B : No pause pulse 1 _B : Pause pulse
SENT/SPC_PWI_SSM	[3]	SENT/SPC short serial message	0 _B : No short serial message 1 _B : Short serial message
SENT/SPC_UT	[2:0]	Unit time setting	000 _B : 3.0 µs 001 _B : 2.5 µs 010 _B : 2.0 µs 011 _B : 1.5 µs 100 _B : 1.0 µs

Note: Depending on the software version not all interface settings may be supported and the angle value and/or additional protocol information may not be displayed EEPROM reading and programming is possible in any case, however.

4.3 Angle base calculation

For PWM/SPC protocol and SENT when feature error code “4091” is disabled

- Determine the position where “0°” should occur.
- Read out the 12-bit angle value at this position (in LSB).
- Multiply this value by 16.
- Write this (decimal) value in register 0x00A0_H and burn EEPROM.
- To change the rotation direction:
 - Add “2” to this value in case bit[1] in 0x00A0_H is “0” and burn EEPROM again.
 - Subtract “2” from this value in case bit[1] in 0x00A0_H is “1” and burn EEPROM again.

For SENT protocol when feature error code “4091” is enabled

- Determine the position where “0°” should occur.
- Read out the 12-bit angle value at this position (in LSB) -> LSB12’.
- Calculate: $4 * \text{trunc}[16384/4088 * (\text{LSB12}' - 1)]$.
- Write this (decimal) value in register 0x00A0_H and burn EEPROM.
- To change the rotation direction:
 - add “2” to this value in case bit[1] in 0x00A0_H is “0” and burn EEPROM again
 - subtract “2” from this value in case bit[1] in 0x00A0_H is “1” and burn EEPROM again

4.4 SPC address configuration

If SPC in bus mode is used it is mandatory that the address of each sensor is written in the corresponding EEPROM. This address must match with the address which is assigned via hardware pinout to this sensor.

Following values have to be written to address 0x00A4_H:

- For ID = 0: 0x0400_H
- For ID = 1: 0x0500_H
- For ID = 2: 0x0600_H
- For ID = 3: 0x0700_H

Note: The bit [7:0] of register 0x00A4_H contain the CRC for protecting the sensor configuration. After a change of the configuration (e.g. angle base or SPC ID) is written to the EEPROM (EEPROM is burned) the CRC is updated automatically.

4.5 Comments

If using SPC bus mode, the first step should be to write the corresponding SPC ID in address 0x00A4_H ([Chapter 4.4](#)).

The sensor comes with an enabled, default programmed look-up table (LUT) to reach the specified accuracy. The default LUT values may not be changed as long as no own data are available. A change causes an increased angle error.

The default values of the LUT can be overwritten in case own data are generated (for e.g. to correct for magnetic circuit assembly tolerances).

If look-up table is used, the angle base correction (bit [15:2] of address 0x00A0_H) has to be performed before look-up table values are modified.

No other bits as the described may be changed as this could cause an unpredictable sensor behavior.

Revision history**5 Revision history**

Revision	Date	Changes
Rev. 1.0	2017-08-02	Initial creation.

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Edition 2017-08-02
Published by
Infineon Technologies AG
81726 Munich, Germany

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