



# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

MAX5062/MAX5063/MAX5064

## General Description

The MAX5062/MAX5063/MAX5064 high-frequency, 125V half-bridge, n-channel MOSFET drivers drive high- and low-side MOSFETs in high-voltage applications. These drivers are independently controlled and their 35ns typical propagation delay, from input to output, are matched to within 3ns (typ). The high-voltage operation with very low and matched propagation delay between drivers, and high source/sink current capabilities in a thermally enhanced package make these devices suitable for the high-power, high-frequency telecom power converters. The 125V maximum input voltage range provides plenty of margin over the 100V input transient requirement of telecom standards. A reliable on-chip bootstrap diode connected between  $V_{DD}$  and BST eliminates the need for an external discrete diode.

The MAX5062A/C and the MAX5063A/C offer both noninverting drivers (see the *Selector Guide*). The MAX5062B/D and the MAX5063B/D offer a noninverting high-side driver and an inverting low-side driver. The MAX5064A/B offer two inputs per driver that can be either inverting or noninverting. The MAX5062A/B/C/D and the MAX5064A feature CMOS ( $V_{DD}/2$ ) logic inputs. The MAX5063A/B/C/D and the MAX5064B feature TTL logic inputs. The MAX5064A/B include a break-before-make adjustment input that sets the dead time between drivers from 16ns to 95ns. The drivers are available in the industry-standard 8-pin SO footprint and pin configuration, and a thermally enhanced 8-pin SO and 12-pin (4mm x 4mm) thin QFN packages. All devices operate over the -40°C to +125°C automotive temperature range.

## Applications

- Telecom Half-Bridge Power Supplies
- Two-Switch Forward Converters
- Full-Bridge Converters
- Active-Clamp Forward Converters
- Power-Supply Modules
- Motor Control

## Features

- ◆ HIP2100/HIP2101 Pin Compatible (MAX5062A/MAX5063A)
- ◆ Up to 125V Input Operation
- ◆ 8V to 12.6V  $V_{DD}$  Input Voltage Range
- ◆ 2A Peak Source and Sink Current Drive Capability
- ◆ 35ns Typical Propagation Delay
- ◆ Guaranteed 8ns Propagation Delay Matching Between Drivers
- ◆ Programmable Break-Before-Make Timing (MAX5064)
- ◆ Up to 1MHz Combined Switching Frequency while Driving 100nC Gate Charge (MAX5064)
- ◆ Available in CMOS ( $V_{DD}/2$ ) or TTL Logic-Level Inputs with Hysteresis
- ◆ Up to 15V Logic Inputs Independent of Input Voltage
- ◆ Low 2.5pF Input Capacitance
- ◆ Instant Turn-Off of Drivers During Fault or PWM Start-Stop Synchronization (MAX5064)
- ◆ Low 200 $\mu$ A Supply Current
- ◆ Versions Available With Combination of Noninverting and Inverting Drivers (MAX5062B/D and MAX5063B/D)
- ◆ Available in 8-Pin SO, Thermally Enhanced SO, and 12-Pin Thin QFN Packages

## Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	TOP MARK	PKG CODE
MAX5062AASA	-40°C to +125°C	8 SO	—	S8-5
MAX5062BASA	-40°C to +125°C	8 SO	—	S8-5
MAX5062CASA	-40°C to +125°C	8 SO-EP*	—	S8E-14
MAX5062DASA	-40°C to +125°C	8 SO-EP*	—	S8E-14

\*EP = Exposed paddle.

Devices are available in both leaded and lead-free packaging. Specify lead-free by replacing "-T" with "+T" when ordering.

Ordering Information continued at end of data sheet.

## Selector Guide

PART	HIGH-SIDE DRIVER	LOW-SIDE DRIVER	LOGIC LEVELS	PIN COMPATIBLE
MAX5062AASA	Noninverting	Noninverting	CMOS ( $V_{DD}/2$ )	HIP 2100IB
MAX5062BASA	Noninverting	Inverting	CMOS ( $V_{DD}/2$ )	—
MAX5062CASA	Noninverting	Noninverting	CMOS ( $V_{DD}/2$ )	—
MAX5062DASA	Noninverting	Inverting	CMOS ( $V_{DD}/2$ )	—

Selector Guide continued at end of data sheet.



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## ABSOLUTE MAXIMUM RATINGS

(All voltages referenced to GND, unless otherwise noted.)

V <sub>DD</sub> , IN_H, IN_L, IN_L+, IN_L-, IN_H+, IN_H-	-0.3V to +15V
DL, BBM	-0.3V to (V <sub>DD</sub> + 0.3V)
HS	-5V to +130V
DH to HS	-0.3V to (V <sub>DD</sub> + 0.3V)
BST to HS	-0.3V to +15V
AGND to PGND (MAX5064)	-0.3V to +0.3V
dV/dt at HS	50V/ns
Continuous Power Dissipation (T <sub>A</sub> = +70°C)	
8-Pin SO (derate 5.9mW/°C above +70°C)	470.6mW

8-Pin SO with Exposed Pad (derate 19.2mW/°C above +70°C)*	1538.5mW
12-Pin Thin QFN (derate 24.4mW/°C above +70°C)*	1951.2mW
Maximum Junction Temperature	+150°C
Operating Temperature Range	-40°C to +125°C
Storage Temperature Range	-65°C to +150°C
Lead Temperature (soldering, 10s)	+300°C

\*Per JEDEC 51 standard multilayer board.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ELECTRICAL CHARACTERISTICS

(V<sub>DD</sub> = V<sub>BST</sub> = +8V to +12.6V, V<sub>HS</sub> = GND = 0V, BBM = open, T<sub>A</sub> = -40°C to +125°C, unless otherwise noted. Typical values are at V<sub>DD</sub> = V<sub>BST</sub> = +12V and T<sub>A</sub> = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
<b>POWER SUPPLIES</b>							
Operating Supply Voltage	V <sub>DD</sub>	(Note 2)	8.0		12.6	V	
V <sub>DD</sub> Quiescent Supply Current	I <sub>DD</sub>	IN_H = IN_L = GND (no switching)	MAX5062_/MAX5063_		70	140	μA
			MAX5064_		120	260	
V <sub>DD</sub> Operating Supply Current	I <sub>DDO</sub>	f <sub>sw</sub> = 500kHz, V <sub>DD</sub> = +12V			3	mA	
BST Quiescent Supply Current	I <sub>BST</sub>	IN_H = IN_L = GND (no switching)		15	40	μA	
BST Operating Supply Current	I <sub>BSTO</sub>	f <sub>sw</sub> = 500kHz, V <sub>DD</sub> = V <sub>BST</sub> = +12V			3	mA	
UVLO (V <sub>DD</sub> to GND)	UVLO <sub>VDD</sub>	V <sub>DD</sub> rising	6.5	7.3	8.0	V	
UVLO (BST to HS)	UVLO <sub>BST</sub>	BST rising	6.0	6.9	7.8	V	
UVLO Hysteresis				0.5		V	
<b>LOGIC INPUT</b>							
Input-Logic High	V <sub>IHL</sub>	MAX5062_/MAX5064A, CMOS (V <sub>DD</sub> / 2) version	0.67 x V <sub>DD</sub>	0.55 x V <sub>DD</sub>		V	
		MAX5063_/MAX5064B, TTL version	2	1.65			
Input-Logic Low	V <sub>ILL</sub>	MAX5062_/MAX5064A, CMOS (V <sub>DD</sub> / 2) version		0.4 x V <sub>DD</sub>	0.33 x V <sub>DD</sub>	V	
		MAX5063_/MAX5064B, TTL version		1.4	0.8		
Logic-Input Hysteresis	V <sub>HYS</sub>	MAX5062_/MAX5064A, CMOS (V <sub>DD</sub> / 2) version		1.6		V	
		MAX5063_/MAX5064B, TTL version		0.25			

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**MAX5062/MAX5063/MAX5064**

## ELECTRICAL CHARACTERISTICS (continued)

( $V_{DD} = V_{BST} = +8V$  to  $+12.6V$ ,  $V_{HS} = GND = 0V$ ,  $BBM = \text{open}$ ,  $T_A = -40^\circ\text{C}$  to  $+125^\circ\text{C}$ , unless otherwise noted. Typical values are at  $V_{DD} = V_{BST} = +12V$  and  $T_A = +25^\circ\text{C}$ .) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Logic-Input Current	$I_{IN}$	$V_{IN\_H+}, V_{IN\_L+} = 0V$	-1	0.001	+1	$\mu\text{A}$
		$V_{IN\_L} = V_{DD}$ for MAX5062B/D, MAX5063B/D				
		$V_{IN\_H-}, V_{IN\_L-}, V_{IN\_H} = V_{DD}$				
		$V_{IN\_L} = 0V$ for MAX5062A/C, MAX5063A/C				
Input Resistance	$R_{IN}$	$IN\_H+, IN\_L+ \text{ to } IN\_H, \text{ to } GND$		1		$M\Omega$
		$IN\_L \text{ to } V_{DD}$ for MAX5062B/D, MAX5063B/D				
		$IN\_H-, IN\_L-, IN\_H, \text{ to } V_{DD}$				
		$IN\_L$ for MAX5062A/C, MAX5063A/C to GND				
Input Capacitance	$C_{IN}$		2.5			$\text{pF}$
<b>HIGH-SIDE GATE DRIVER</b>						
HS Maximum Voltage	$V_{HS\_MAX}$		125			V
BST Maximum Voltage	$V_{BST\_MAX}$		140			V
Driver Output Resistance (Sourcing)	$R_{ON\_HP}$	$V_{DD} = 12V, I_{DH} = 100\text{mA}$ (sourcing)	$T_A = +25^\circ\text{C}$	2.5	3.3	$\Omega$
			$T_A = +125^\circ\text{C}$	3.5	4.6	
Driver Output Resistance (Sinking)	$R_{ON\_HN}$	$V_{DD} = 12V, I_{DH} = 100\text{mA}$ (sinking)	$T_A = +25^\circ\text{C}$	2.1	2.8	$\Omega$
			$T_A = +125^\circ\text{C}$	3.2	4.2	
DH Reverse Current (Latchup Protection)		(Note 3)	400			$\text{mA}$
Power-Off Pulldown Clamp Voltage		$V_{BST} = 0V$ or floating, $I_{DH} = 1\text{mA}$ (sinking)		0.94	1.16	V
Peak Output Current (Sourcing)	$I_{DH\_PEAK}$	$C_L = 10\text{nF}, V_{DH} = 0V$		2		A
Peak Output Current (Sinking)		$C_L = 10\text{nF}, V_{DH} = 12V$		2		A
<b>LOW-SIDE GATE DRIVER</b>						
Driver Output Resistance (Sourcing)	$R_{ON\_LP}$	$V_{DD} = 12V, I_{DL} = 100\text{mA}$ (sourcing)	$T_A = +25^\circ\text{C}$	2.5	3.3	$\Omega$
			$T_A = +125^\circ\text{C}$	3.5	4.6	
Driver Output Resistance (Sinking)	$R_{ON\_LN}$	$V_{DD} = 12V, I_{DL} = 100\text{mA}$ (sinking)	$T_A = +25^\circ\text{C}$	2.1	2.8	$\Omega$
			$T_A = +125^\circ\text{C}$	3.2	4.2	
Reverse Current at DL (Latchup Protection)		(Note 3)	400			$\text{mA}$
Power-Off Pulldown Clamp Voltage		$V_{DD} = 0V$ or floating, $I_{DL} = 1\text{mA}$ (sinking)		0.95	1.16	V
Peak Output Current (Sourcing)	$I_{PK\_LP}$	$C_L = 10\text{nF}, V_{DL} = 0V$		2		A
Peak Output Current (Sinking)	$I_{PK\_LN}$	$C_L = 10\text{nF}, V_{DL} = 12V$		2		A
<b>INTERNAL BOOTSTRAP DIODE</b>						
Forward Voltage Drop	$V_f$	$I_{BST} = 100\text{mA}$		0.91	1.11	V
Turn-On and Turn-Off Time	$t_R$	$I_{BST} = 100\text{mA}$		40		ns

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## ELECTRICAL CHARACTERISTICS (continued)

( $V_{DD} = V_{BST} = +8V$  to  $+12.6V$ ,  $V_{HS} = GND = 0V$ ,  $BBM = open$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ , unless otherwise noted. Typical values are at  $V_{DD} = V_{BST} = +12V$  and  $T_A = +25^{\circ}C$ .) (Note 1)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
<b>SWITCHING CHARACTERISTICS FOR HIGH- AND LOW-SIDE DRIVERS (<math>V_{DD} = V_{BST} = +12V</math>)</b>							
Rise Time	$t_R$	$C_L = 1000pF$			7		ns
		$C_L = 5000pF$			33		
		$C_L = 10,000pF$			65		
Fall Time	$t_F$	$C_L = 1000pF$			7		ns
		$C_L = 5000pF$			33		
		$C_L = 10,000pF$			65		
Turn-On Propagation Delay Time	$t_{D\_ON}$	Figure 1, $C_L = 1000pF$ (Note 3)	CMOS	30	55		ns
			TTL	35	63		
Turn-Off Propagation Delay Time	$t_{D\_OFF}$	Figure 1, $C_L = 1000pF$ (Note 3)	CMOS	30	55		ns
			TTL	35	63		
Delay Matching Between Inverting Input to Output and Noninverting Input to Output	$t_{MATCH1}$	$C_L = 1000pF$ , $BBM$ open for MAX5064, Figure 1 (Note 3)			2	8	ns
Delay Matching Between Driver-Low and Driver-High	$t_{MATCH2}$	$C_L = 1000pF$ , $BBM$ open for MAX5064, Figure 1 (Note 3)			2	8	ns
Break-Before-Make Accuracy (MAX5064 Only)		$R_{BBM} = 10k\Omega$			16		ns
		$R_{BBM} = 47k\Omega$ (Notes 3, 4)		40	56	72	
		$R_{BBM} = 100k\Omega$			95		
Internal Nonoverlap					1		ns
Minimum Pulse-Width Input Logic (High or Low) (Note 5)	$t_{PW-MIN}$	$V_{DD} = V_{BST} = 12V$			135		ns
		$V_{DD} = V_{BST} = 8V$			170		

**Note 1:** All devices are 100% tested at  $T_A = +125^{\circ}C$ . Limits over temperature are guaranteed by design.

**Note 2:** Ensure that the  $V_{DD}$ -to-GND or  $BST$ -to-HS voltage does not exceed 13.2V.

**Note 3:** Guaranteed by design, not production tested.

**Note 4:** Break-before-make time is calculated by  $t_{BBM} = 8ns \times (1 + R_{BBM} / 10k\Omega)$ .

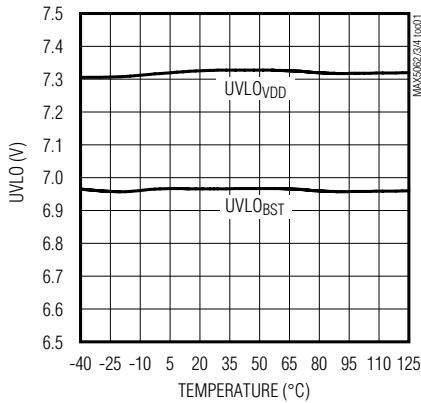
**Note 5:** See the *Minimum Pulse Width* section.

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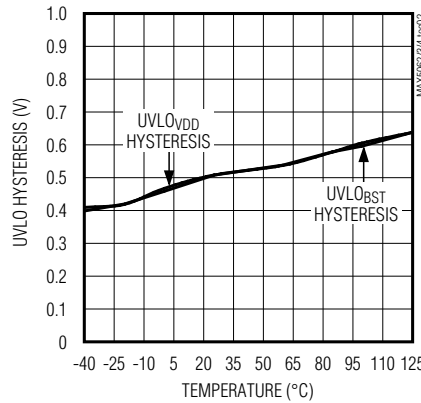
## Typical Operating Characteristics

(Typical values are at  $V_{DD} = V_{BST} = +12V$  and  $T_A = +25^\circ C$ , unless otherwise specified.)

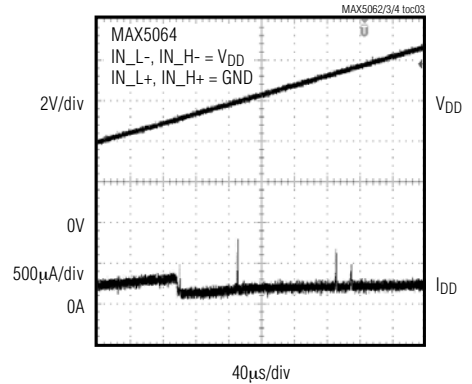
**UNDERVOLTAGE LOCKOUT  
( $V_{DD}$  AND  $V_{BST}$  RISING) vs. TEMPERATURE**



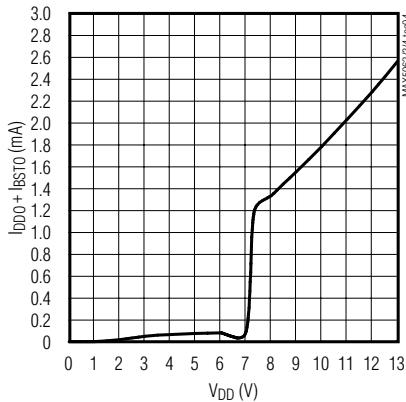
**$V_{DD}$  AND  $BST$  UNDERVOLTAGE LOCKOUT  
HYSTERESIS vs. TEMPERATURE**



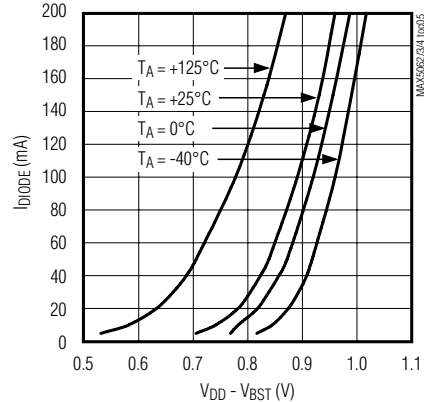
**$I_{DD}$  vs.  $V_{DD}$**



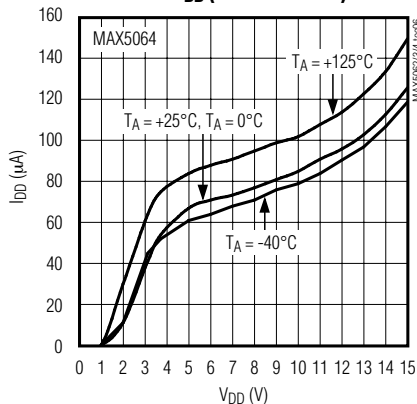
**$I_{DD} + I_{BST}$  vs.  $V_{DD}$   
( $f_{sw} = 250kHz$ )**



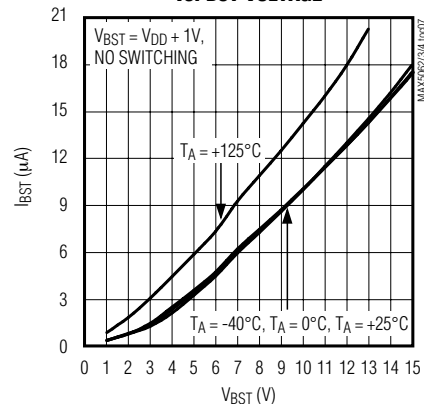
**INTERNAL  $BST$  DIODE  
(I-V) CHARACTERISTICS**



**$V_{DD}$  QUIESCENT CURRENT  
vs.  $V_{DD}$  (NO SWITCHING)**



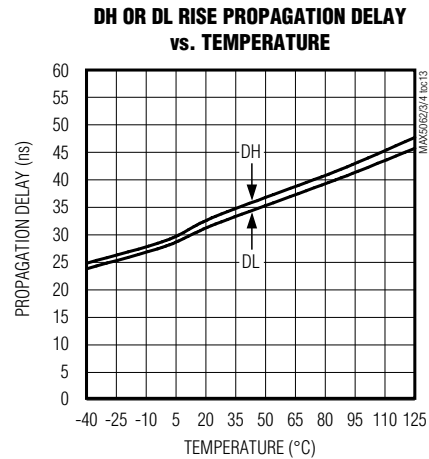
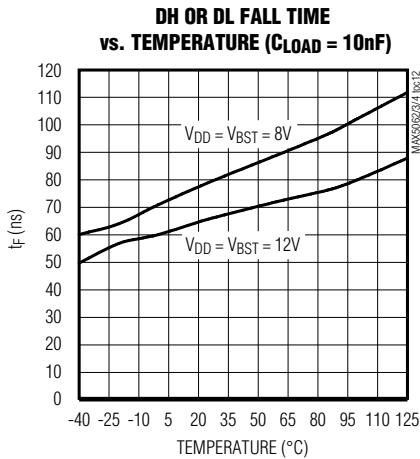
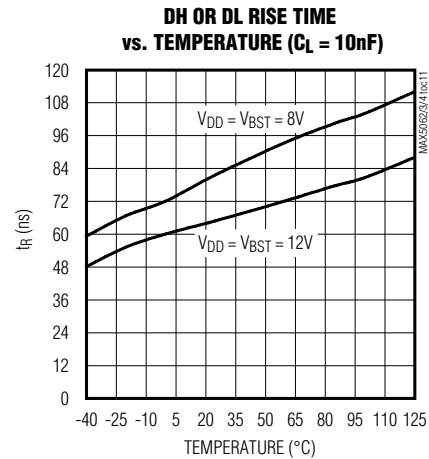
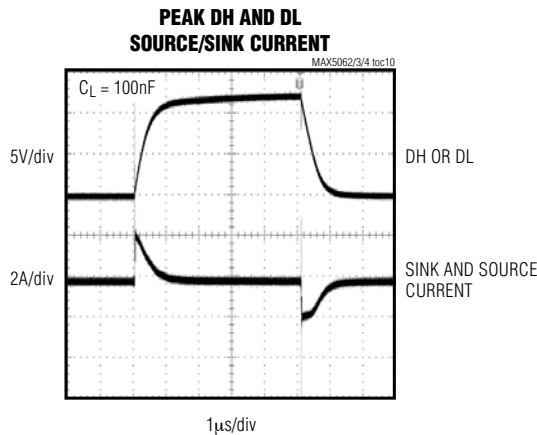
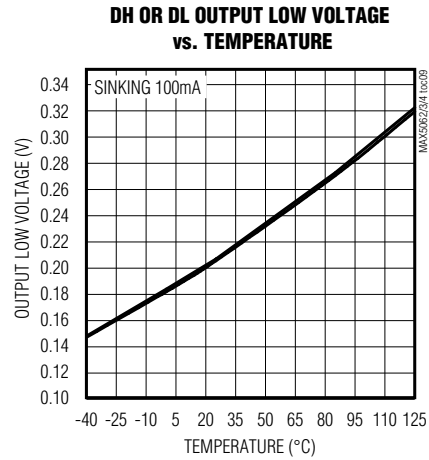
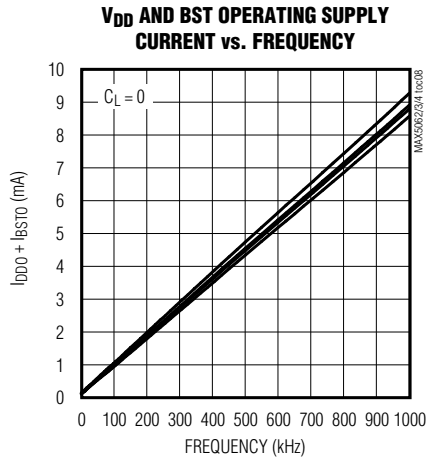
**$BST$  QUIESCENT CURRENT  
vs.  $BST$  VOLTAGE**



# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## Typical Operating Characteristics (continued)

(Typical values are at  $V_{DD} = V_{BST} = +12V$  and  $T_A = +25^\circ C$ , unless otherwise specified.)

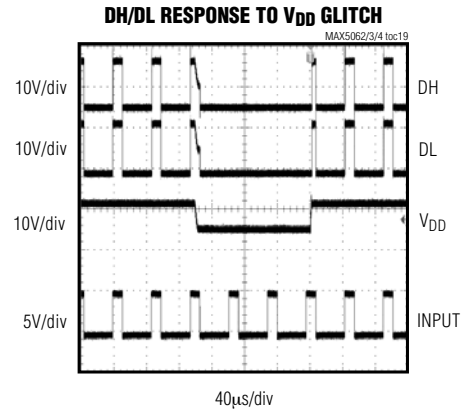
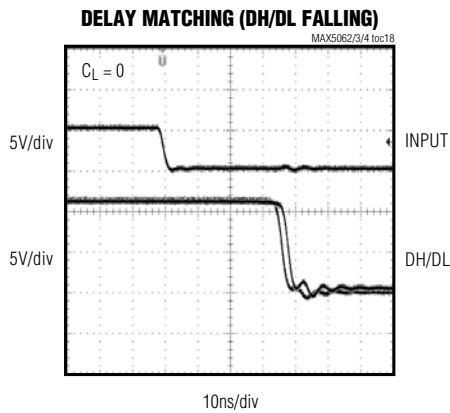
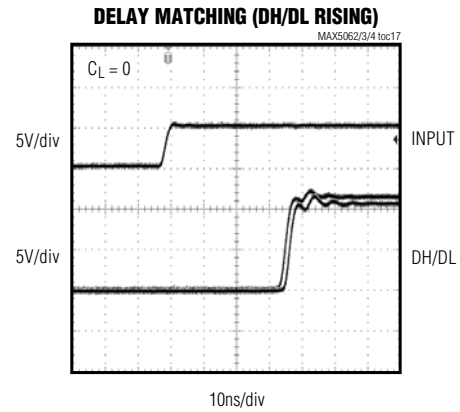
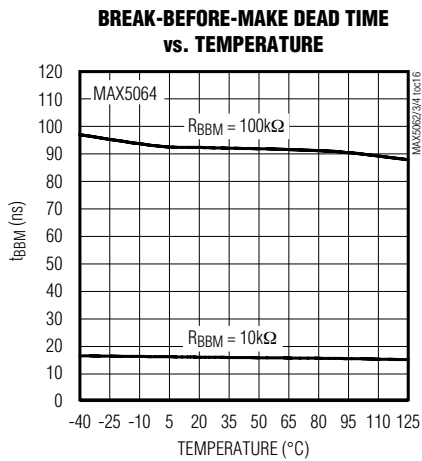
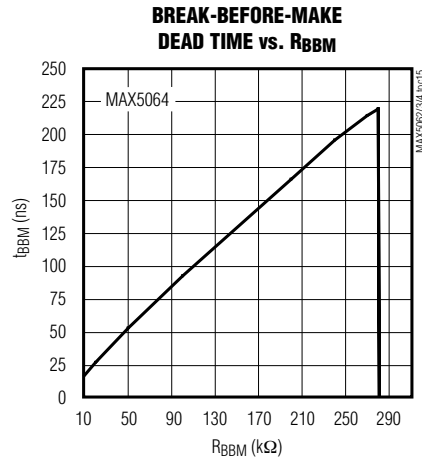
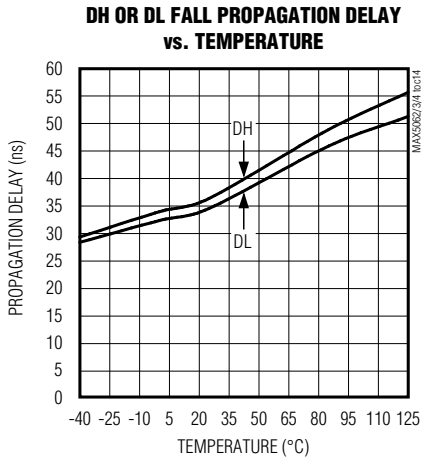


# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

MAX5062/MAX5063/MAX5064

## Typical Operating Characteristics (continued)

(Typical values are at  $V_{DD} = V_{BST} = +12V$  and  $T_A = +25^\circ C$ , unless otherwise specified.)



# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## MAX5062/MAX5063 Pin Description

PIN	NAME	FUNCTION
1	VDD	Power Input. Bypass to GND with a parallel combination of 0.1 $\mu$ F and 1 $\mu$ F ceramic capacitor.
2	BST	Boost Flying Capacitor Connection. Connect a 0.1 $\mu$ F ceramic capacitor between BST and HS for the high-side MOSFET driver supply.
3	DH	High-Side-Gate Driver Output. Driver output for the high-side MOSFET gate.
4	HS	Source Connection for High-Side MOSFET. Also serves as a return terminal for the high-side driver.
5	IN_H	High-Side Noninverting Logic Input
6	IN_L	Low-Side Noninverting Logic Input (MAX5062A/C, MAX5063A/C). Low-side inverting logic input (MAX5062B/D, MAX5063B/D).
7	GND	Ground. Use GND as a return path to the DL driver output and IN_H/IN_L inputs.
8	DL	Low-Side-Gate Driver Output. Drives low-side MOSFET gate.
—	EP	Exposed Pad. Internally connected to GND. Externally connect the exposed pad to a large ground plane to aid in heat dissipation (MAX5062C/D, MAX5063C/D only).

## MAX5064 Pin Description

PIN	NAME	FUNCTION
1	BST	Boost Flying Capacitor Connection. Connect a 0.1 $\mu$ F ceramic capacitor between BST and HS for the high-side MOSFET driver supply.
2	DH	High-Side-Gate Driver Output. Drives high-side MOSFET gate.
3	HS	Source Connection for High-Side MOSFET. Also serves as a return terminal for the high-side driver.
4	AGND	Analog Ground. Return path for low-switching current signals. IN_H/IN_L inputs referenced to
5	BBM	Break-Before-Make Programming Resistor Connection. Connect a 10k $\Omega$ to 100k $\Omega$ resistor from BBM to AGND to program the break-before-make time ( $t_{BBM}$ ) from 16ns to 95ns. Resistance values greater than 200k $\Omega$ disables the BBM function and makes $t_{BBM} = 1$ ns. Bypass this pin with at least a 1nF capacitor to AGND.
6	IN_H-	High-Side Inverting CMOS ( $V_{DD} / 2$ ) (MAX5064A), or TTL (MAX5064B) Logic Input. Connect to AGND when not used.
7	IN_H+	High-Side Noninverting CMOS ( $V_{DD} / 2$ ) (MAX5064A), or TTL (MAX5064B) Logic Input. Connect to $V_{DD}$ when not used.
8	IN_L-	Low-Side Inverting CMOS ( $V_{DD} / 2$ ) (MAX5064A), or TTL (MAX5064B) Logic Input. Connect to AGND when not used.
9	IN_L+	Low-Side Noninverting CMOS ( $V_{DD} / 2$ ) (MAX5064A), or TTL (MAX5064B) Logic Input. Connect to $V_{DD}$ when not used.
10	PGND	Power Ground. Return path for high-switching current signals. Use PGND as a return path for the low-side driver.
11	DL	Low-Side-Gate Driver Output. Drives the low-side MOSFET gate.
12	VDD	Power Input. Bypass to PGND with a 0.1 $\mu$ F ceramic in parallel with a 1 $\mu$ F ceramic capacitor.
—	EP	Exposed Pad. Internally connected to AGND. Externally connect to a large ground plane to aid in heat dissipation.



# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

MAX5062/MAX5063/MAX5064

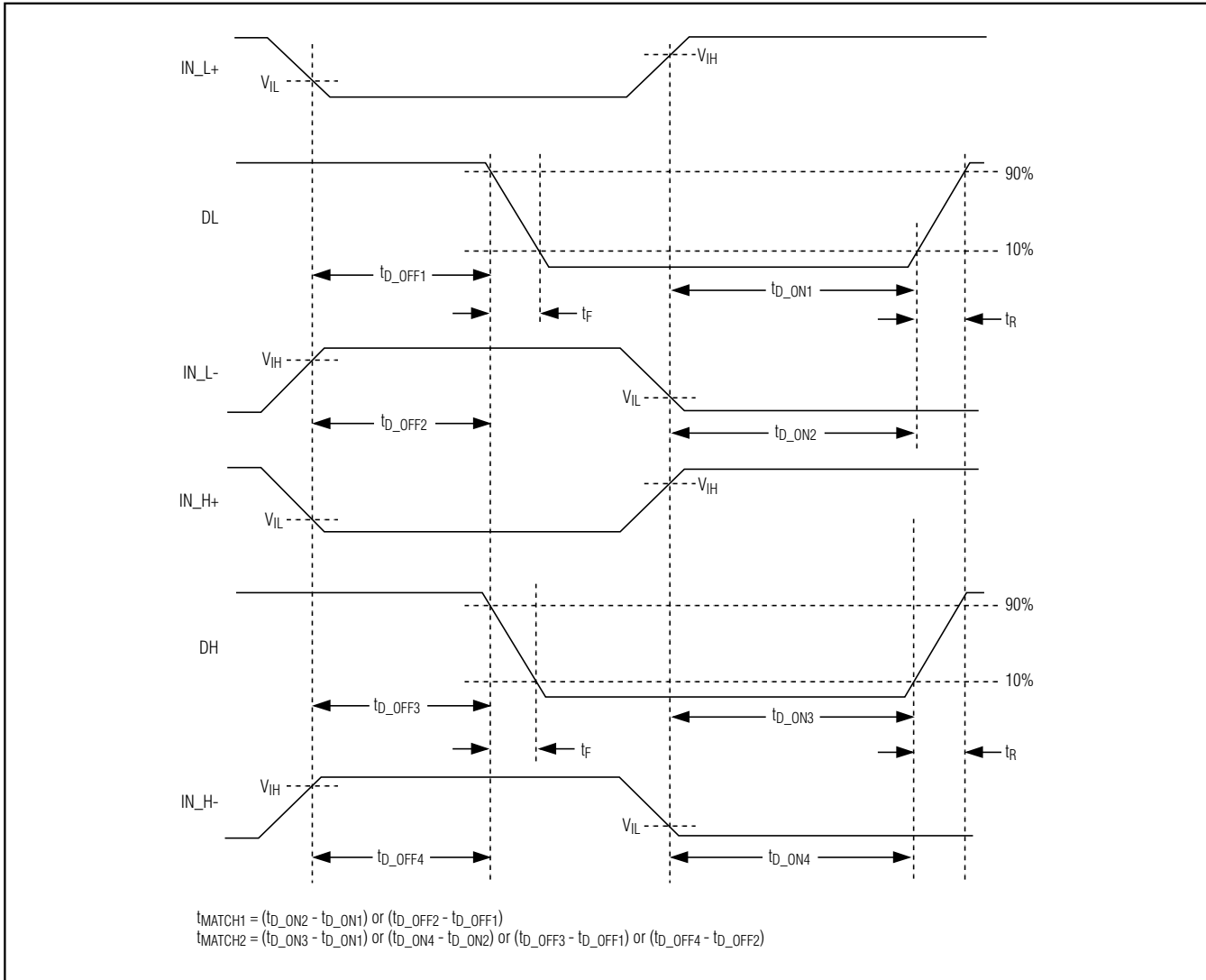


Figure 1. Timing Characteristics for Noninverting and Inverting Logic Inputs

## Detailed Description

The MAX5062/MAX5063/MAX5064 are 125V/2A high-speed, half-bridge MOSFET drivers that operate from a supply voltage of +8V to +12.6V. The drivers are intended to drive a high-side switch without any isolation device like an optocoupler or drive transformer. The high-side driver is controlled by a TTL/CMOS logic signal referenced to ground. The 2A source and sink drive capability is achieved by using low  $R_{DS\_ON}$  p- and n-channel driver output stages. The BiCMOS process allows extremely fast rise/fall times and low

propagation delays. The typical propagation delay from the logic-input signal to the drive output is 35ns with a matched propagation delay of 3ns typical. Matching these propagation delays is as important as the absolute value of the delay itself. The high 125V input voltage range allows plenty of margin above the 100V transient specification per telecom standards.

The MAX5064 is available in a thermally enhanced TQFN package, which can dissipate up to 1.95W (at +70°C) and allow up to 1MHz switching frequency while driving 100nC combined gate-charge MOSFETs.

# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## Undervoltage Lockout

Both the high- and low-side drivers feature undervoltage lockout (UVLO). The low-side driver's UVLO<sub>LOW</sub> threshold is referenced to GND and pulls both driver outputs low when V<sub>DD</sub> falls below 6.8V. The high-side driver has its own undervoltage lockout threshold (UVLO<sub>HIGH</sub>), referenced to HS, and pulls DH low when BST falls below 6.4V with respect to HS.

During turn-on, once V<sub>DD</sub> rises above its UVLO threshold, DL starts switching and follows the IN\_L logic input. At this time, the bootstrap capacitor is not charged and the BST-to-HS voltage is below UVLO<sub>BST</sub>. For synchronous buck and half-bridge converter topologies, the bootstrap capacitor can charge up in one cycle and normal operation begins in a few microseconds after the BST-to-HS voltage exceeds UVLO<sub>BST</sub>. In the two-switch forward topology, the BST capacitor takes some time (a few hundred microseconds) to charge and increase its voltage above UVLO<sub>BST</sub>.

The typical hysteresis for both UVLO thresholds is 0.5V. The bootstrap capacitor value should be selected carefully to avoid unintentional oscillations during turn-on and turn-off at the DH output. Choose the capacitor value about 20 times higher than the total gate capacitance of the MOSFET. Use a low-ESR-type X7R dielectric ceramic capacitor at BST (typically a 0.1μF ceramic is adequate) and a parallel combination of 1μF and 0.1μF ceramic capacitors from V<sub>DD</sub> to GND (MAX5062\_, MAX5063\_) or to PGND (MAX5064\_). The high-side MOSFET's continuous on-time is limited due to the charge loss from the high-side driver's quiescent current. The maximum on-time is dependent on the size of C<sub>BST</sub>, I<sub>BST</sub> (50μA max), and UVLO<sub>BST</sub>.

## Output Driver

The MAX5062/MAX5063/MAX5064 have low 2.5Ω R<sub>DS\_ON</sub> p-channel and n-channel devices (totem pole) in the output stage. This allows for a fast turn-on and turn-off of the high gate-charge switching MOSFETs. The peak source and sink current is typically 2A. Propagation delays from the logic inputs to the driver outputs are matched to within 8ns. The internal p- and n-channel MOSFETs have a 1ns break-before-make logic to avoid any cross conduction between them. This internal break-before-make logic eliminates shoot-through currents reducing the operating supply current as well as the spikes at V<sub>DD</sub>. The DL voltage is approximately equal to V<sub>DD</sub> and the DH-to-HS voltage, a diode drop below V<sub>DD</sub>, when they are in a high state and to zero when in a low state. The driver R<sub>DS\_ON</sub> is lower at higher V<sub>DD</sub>. Lower R<sub>DS\_ON</sub> means higher source and sink currents and faster switching speeds.

## Internal Bootstrap Diode

An internal diode connects from V<sub>DD</sub> to BST and is used in conjunction with a bootstrap capacitor externally connected between BST and HS. The diode charges the capacitor from V<sub>DD</sub> when the DL low-side switch is on and isolates V<sub>DD</sub> when HS is pulled high as the high-side driver turns on (see the *Typical Operating Circuit*).

The internal bootstrap diode has a typical forward voltage drop of 0.9V and has a 10ns typical turn-off/turn-on time. For lower voltage drops from V<sub>DD</sub> to BST, connect an external Schottky diode between V<sub>DD</sub> and BST.

## Programmable Break-Before-Make (MAX5064)

Half-bridge and synchronous buck topologies require that the high- or low-side switch be turned off before the other switch is turned on to avoid shoot-through currents. Shoot-through occurs when both high- and low-side switches are on at the same time. This condition is caused by the mismatch in the propagation delay from IN\_H/IN\_L to DH/DL, driver output impedance, and the MOSFET gate capacitance. Shoot-through currents increase power dissipation, radiate EMI, and can be catastrophic, especially with high input voltages.

The MAX5064 offers a break-before-make (BBM) feature that allows the adjustment of the delay from the input to the output of each driver. The propagation delay from the rising edges of IN\_H and IN\_L to the rising edges of DH and DL, respectively, can be programmed from 16ns to 95ns. Note that the BBM time (t<sub>BBM</sub>) has a higher percentage error at lower value because of the fixed comparator delay in the BBM block. The propagation delay mismatch (t<sub>MATCH\_</sub>) needs to be included when calculating the total t<sub>BBM</sub> error. The low 8ns (maximum) delay mismatch reduces the total t<sub>BBM</sub> variation. Use the following equations to calculate R<sub>BBM</sub> for the required BBM time and t<sub>BBM\_ERROR</sub>:

$$R_{BBM} = 10k\Omega \times \left( \frac{t_{BBM}}{8ns} - 1 \right) \text{ for } R_{BBM} < 200k\Omega$$

$$t_{BBM\_ERROR} = 0.15 \times t_{BBM} + t_{MATCH\_}$$

where t<sub>BBM</sub> is in nanoseconds.

The voltage at BBM is regulated to 1.3V. The BBM circuit adjusts t<sub>BBM</sub> depending on the current drawn by R<sub>BBM</sub>. Bypass BBM to AGND with a 1nF or smaller ceramic capacitor (C<sub>BBM</sub>) to avoid any effect of ground bounce caused during switching. The charging time of C<sub>BBM</sub> does not affect t<sub>BBM</sub> at turn-on because the BBM voltage is stabilized before the UVLO clears the device turn-on.

# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

MAX5062/MAX5063/MAX5064

Topologies like the two-switch forward converter, where both high- and low-side switches are turned on and off simultaneously, can have the BBM function disabled by leaving BBM unconnected. When disabled,  $t_{BBM}$  is typically 1ns.

## Driver Logic Inputs (IN\_H, IN\_L, IN\_H+, IN\_H-, IN\_L+, IN\_L-)

The MAX5062\_/MAX5064A are CMOS ( $V_{DD} / 2$ ) logic-input drivers while the MAX5063\_/MAX5064B have TTL-compatible logic inputs. The logic-input signals are independent of  $V_{DD}$ . For example, the IC can be powered by a 10V supply while the logic inputs are provided from a 12V CMOS logic. Also, the logic inputs are protected against voltage spikes up to 15V, regardless of the  $V_{DD}$  voltage. The TTL and CMOS logic inputs have 400mV and 1.6V hysteresis, respectively, to avoid double pulsing during transition. The logic inputs are high-impedance pins and should not be left floating. The low 2.5pF input capacitance reduces loading and increases switching speed. The noninverting inputs are pulled down to GND and the inverting inputs are pulled up to  $V_{DD}$  internally using a 1M $\Omega$  resistor. The PWM output from the controller must assume a proper state while powering up the device. With the logic inputs floating, the DH and DL outputs pull low as  $V_{DD}$  rises up above the UVLO threshold.

The MAX5064\_ has two logic inputs per driver, which provide greater flexibility in controlling the MOSFET. Use IN\_H+/IN\_L+ for noninverting logic and IN\_H-/IN\_L- for inverting logic operation. Connect IN\_H+/IN\_L+ to  $V_{DD}$  and IN\_H-/IN\_L- to GND if not used. Alternatively, the unused input can be used as an ON/OFF function. Use IN\_+ for active-low and IN\_- for active-high shutdown logic.

Table 1. MAX5064\_ Truth Table

IN_H+/IN_L+	IN_H-/IN_L-	DH/DL
Low	Low	Low
Low	High	Low
High	Low	High
High	High	Low

## Minimum Pulse Width

The MAX5062/MAX5063/MAX5064 uses a single-shot level shifter architecture to achieve low propagation delay. Typical level shifter architecture causes a minimum (high or low) pulse width ( $t_{DMIN}$ ) at the output that may be higher than the logic-input pulse width. For MAX5062/MAX5063/MAX5064 devices, the DH minimum high pulse width ( $t_{DMIN-DH-H}$ ) is lower than the DL minimum low pulse width ( $t_{DMIN-DL-L}$ ) to avoid any

shoot-through in the absence of external BBM delay during the narrow pulse at low duty cycle (see Figure 2).

At high duty cycle (close to 100%) the DH minimum low pulse width ( $t_{DMIN-DH-L}$ ) must be higher than the DL minimum low pulse width ( $t_{DMIN-DL-L}$ ) to avoid overlap and shoot-through (see Figure 3). In the case of MAX5062/MAX5063/MAX5064, there is a possibility of about 40ns overlap if an external BBM delay is not provided. We recommend adding external delay in the INH path so that the minimum low pulse width seen at INH is always longer than  $t_{PW-MIN}$ . See the *Electrical Characteristics* table for the typical values of  $t_{PW-MIN}$ .

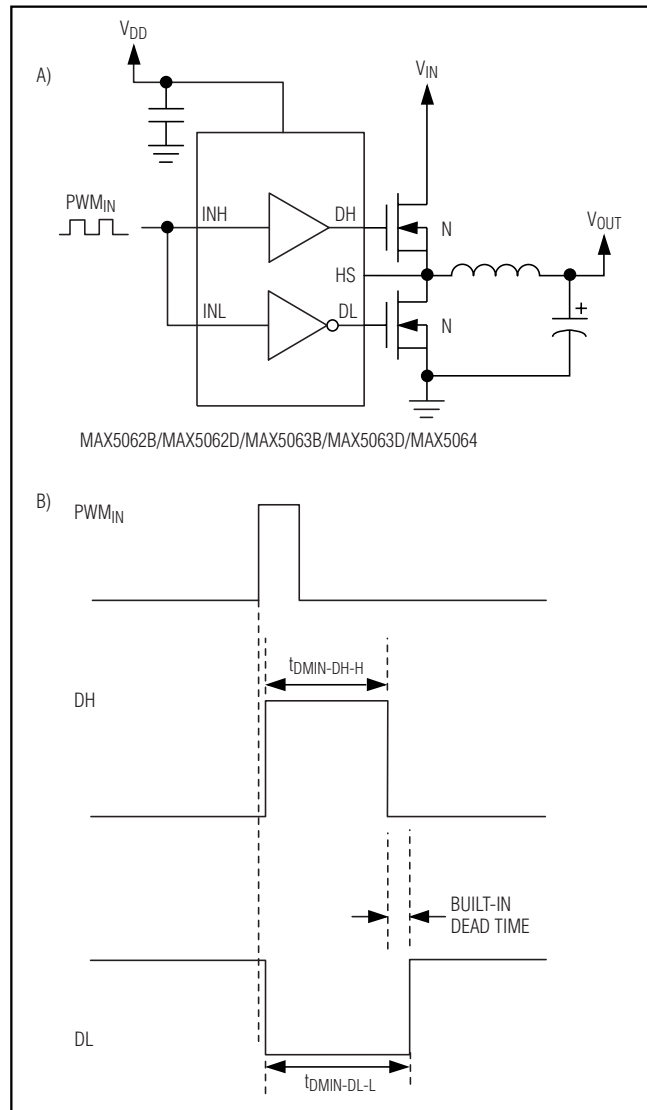


Figure 2. Minimum Pulse-Width Behavior for Narrow Duty-Cycle Input (On-Time <  $t_{PW-MIN}$ )

# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

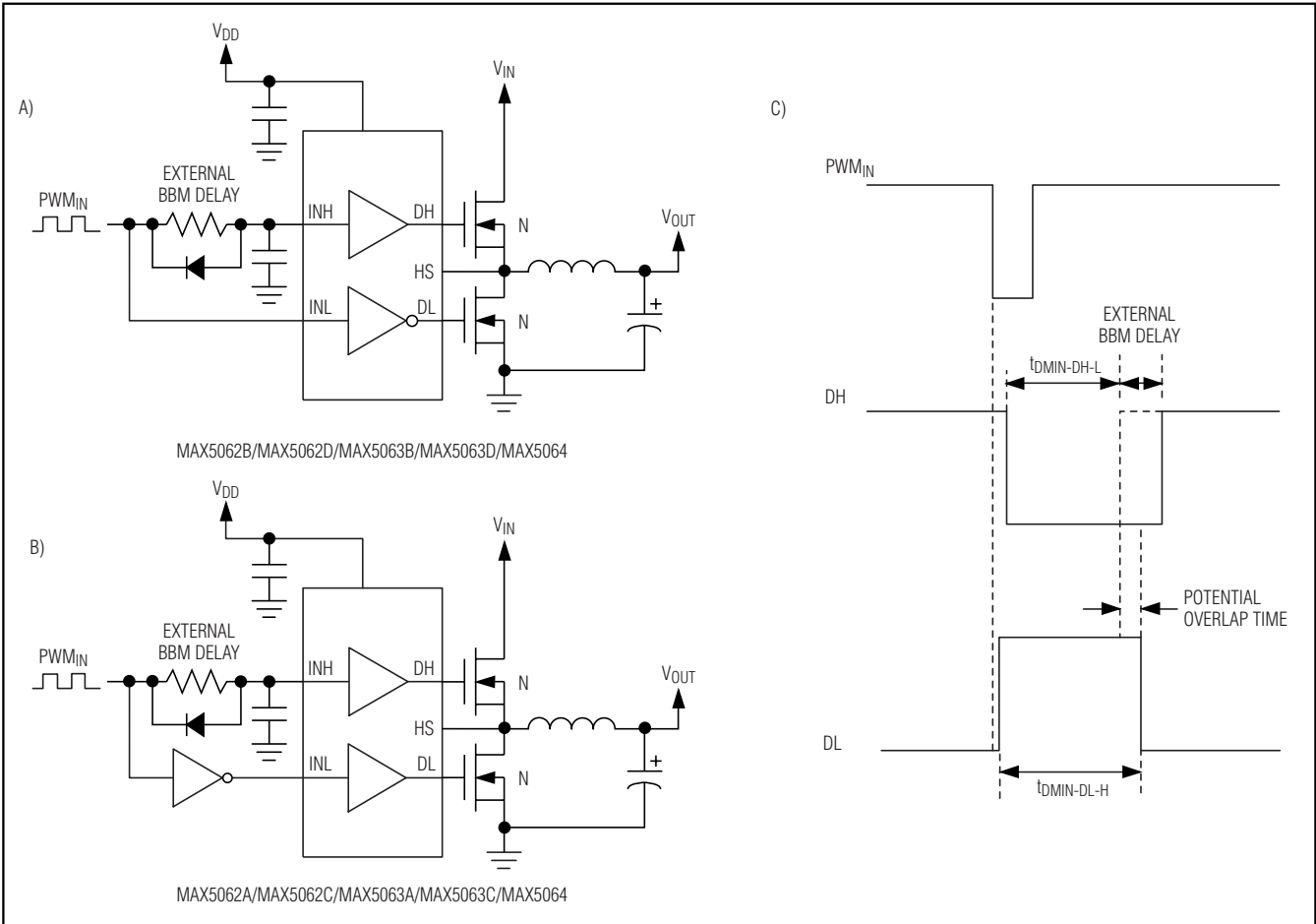


Figure 3. Minimum Pulse-Width Behavior for High Duty-Cycle Input (Off-Time <math>t\_{PW-MIN}</math>)

## Applications Information

### Supply Bypassing and Grounding

Pay extra attention to bypassing and grounding the MAX5062/MAX5063/MAX5064. Peak supply and output currents may exceed 4A when both drivers are driving large external capacitive loads in-phase. Supply drops and ground shifts create forms of negative feedback for inverters and may degrade the delay and transition times. Ground shifts due to insufficient device grounding may also disturb other circuits sharing the same AC ground return path. Any series inductance in the  $V_{DD}$ , DH, DL, and/or GND paths can cause oscillations due to the very high di/dt when switching the MAX5062/MAX5063/MAX5064 with any capacitive load. Place one or more 0.1 $\mu$ F ceramic capacitors in parallel as close to the device as possible to bypass  $V_{DD}$  to GND (MAX5062/MAX5063) or PGND (MAX5064). Use a ground plane to minimize ground return resistance and

series inductance. Place the external MOSFET as close as possible to the MAX5062/MAX5063/MAX5064 to further minimize board inductance and AC path resistance. For the MAX5064\_ the low-power logic ground (AGND) is separated from the high-power driver return (PGND). Apply the logic-input signal between IN\_ to AGND and connect the load (MOSFET gate) between DL and PGND.

### Power Dissipation

Power dissipation in the MAX5062/MAX5063/MAX5064 is primarily due to power loss in the internal boost diode and the nMOS and pMOS FETS.

For capacitive loads, the total power dissipation for the device is:

$$P_D = (C_L \times V_{DD}^2 \times f_{sw}) + (I_{DDO} + I_{BSTO}) \times V_{DD}$$

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where  $C_L$  is the combined capacitive load at DH and DL.  $V_{DD}$  is the supply voltage and  $f_{SW}$  is the switching frequency of the converter.  $P_D$  includes the power dissipated in the internal bootstrap diode. The internal power dissipation reduces by  $P_{DIODE}$ , if an external bootstrap Schottky diode is used. The power dissipation in the internal boost diode (when driving a capacitive load) will be the charge through the diode per switching period multiplied by the maximum diode forward voltage drop ( $V_f = 1V$ ).

$$P_{DIODE} = C_{DH} \times (V_{DD} - 1) \times f_{SW} \times V_f$$

The total power dissipation when using the internal boost diode will be  $P_D$  and, when using an external Schottky diode, will be  $P_D - P_{DIODE}$ . The total power dissipated in the device must be kept below the maximum of 1.951W for the 12-pin TQFN package, 1.5W for the 8-pin SO with exposed pad, and 0.471W for the regular 8-pin SO package at  $T_A = +70^\circ C$  ambient.

## Layout Information

The MAX5062/MAX5063/MAX5064 drivers source and sink large currents to create very fast rise and fall edges at the gates of the switching MOSFETs. The high  $di/dt$  can cause unacceptable ringing if the trace lengths and impedances are not well controlled. Use the following PC board layout guidelines when designing with the MAX5062/MAX5063/MAX5064:

- It is important that the  $V_{DD}$  voltage (with respect to ground) or BST voltage (with respect to HS) does not exceed 13.2V. Voltage spikes higher than 13.2V

from  $V_{DD}$  to GND or BST to HS can damage the device. Place one or more low ESL 0.1 $\mu F$  decoupling ceramic capacitors from  $V_{DD}$  to GND (MAX5062/MAX5063) or to PGND (MAX5064), and from BST to HS as close as possible to the part. The ceramic decoupling capacitors should be at least 20 times the gate capacitance being driven.

- There are two AC current loops formed between the device and the gate of the MOSFET being driven. The MOSFET looks like a large capacitance from gate to source when the gate is being pulled low. The active current loop is from the MOSFET driver output (DL or DH) to the MOSFET gate, to the MOSFET source, and to the return terminal of the MOSFET driver (either GND or HS). When the gate of the MOSFET is being pulled high, the active current loop is from the MOSFET driver output, (DL or DH), to the MOSFET gate, to the MOSFET source, to the return terminal of the drivers decoupling capacitor, to the positive terminal of the decoupling capacitor, and to the supply connection of the MOSFET driver. The decoupling capacitor will be either the flying capacitor connected between BST and HS or the decoupling capacitor for  $V_{DD}$ . Care must be taken to minimize the physical distance and the impedance of these AC current paths.
- Solder the exposed pad of the TQFN (MAX5064) or SO (MAX5062C/D and MAX5063C/D) package to a large copper plane to achieve the rated power dissipation. Connect AGND and PGND at one point near  $V_{DD}$ 's decoupling capacitor return.

MAX5062/MAX5063/MAX5064

# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## Typical Application Circuits

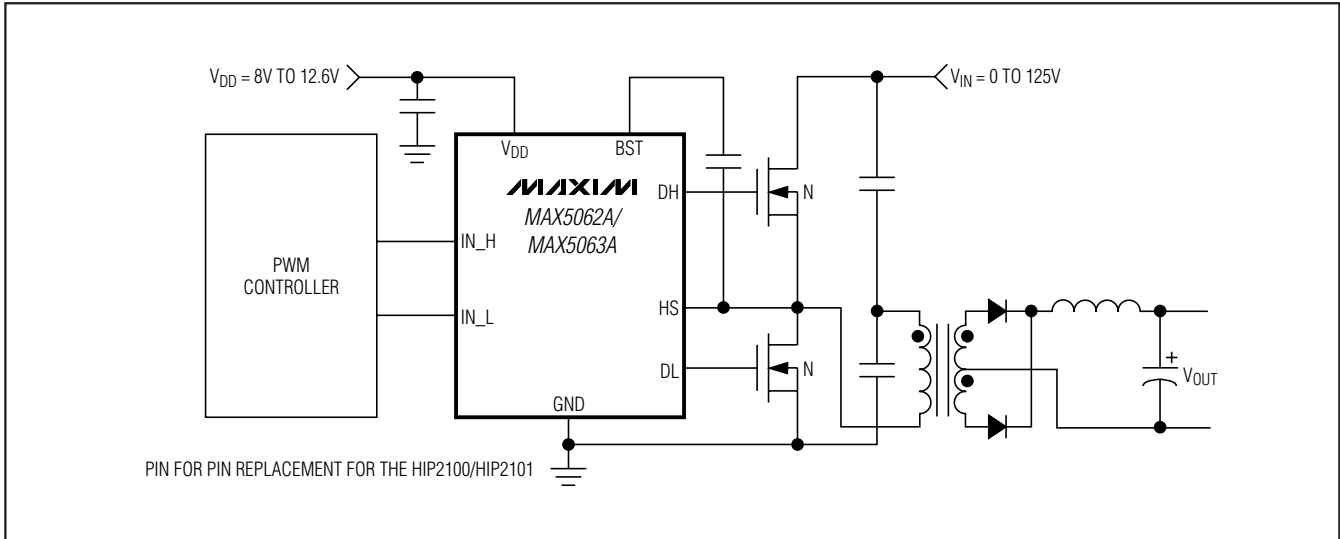


Figure 4. MAX5062 Half-Bridge Conversion

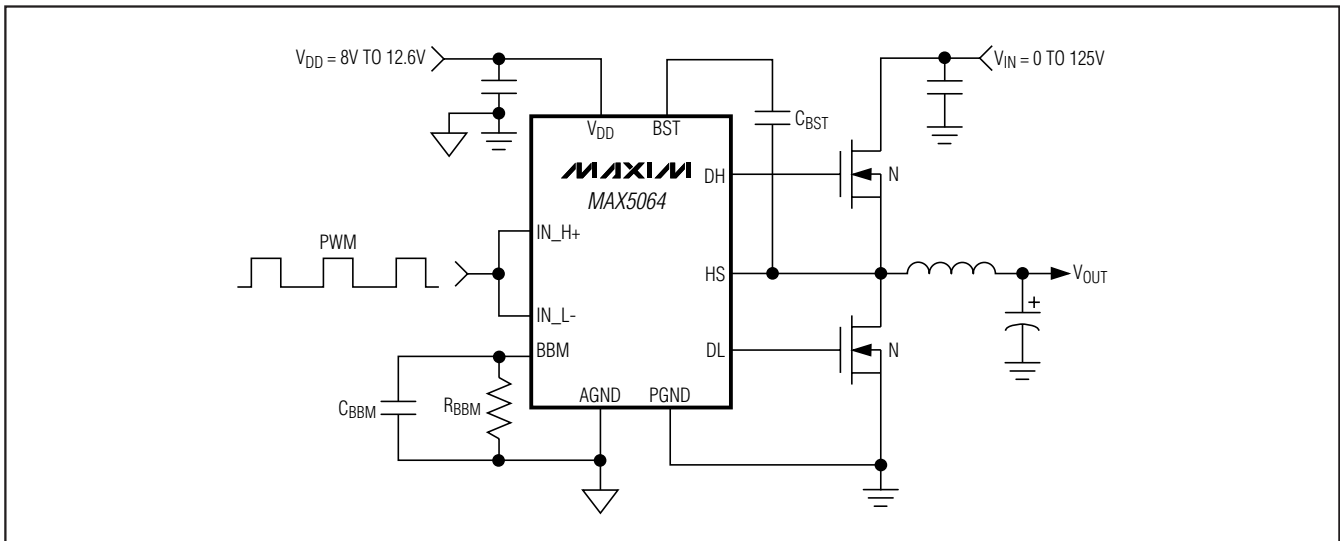


Figure 5. Synchronous Buck Converter

# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## Typical Application Circuits (continued)

MAX5062/MAX5063/MAX5064

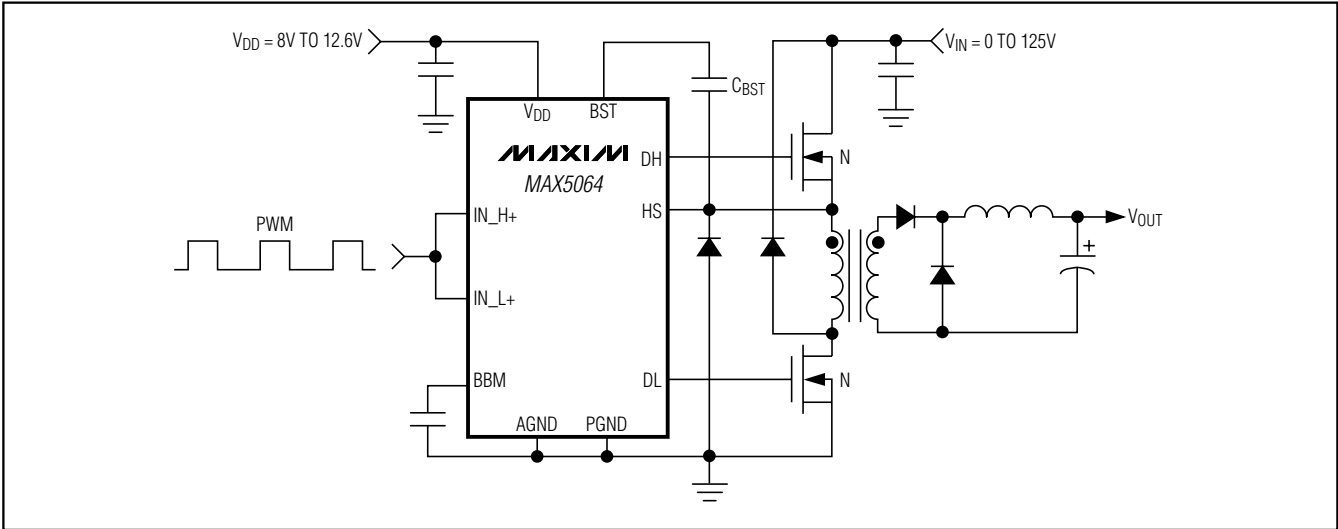


Figure 6. Two-Switch Forward Conversion

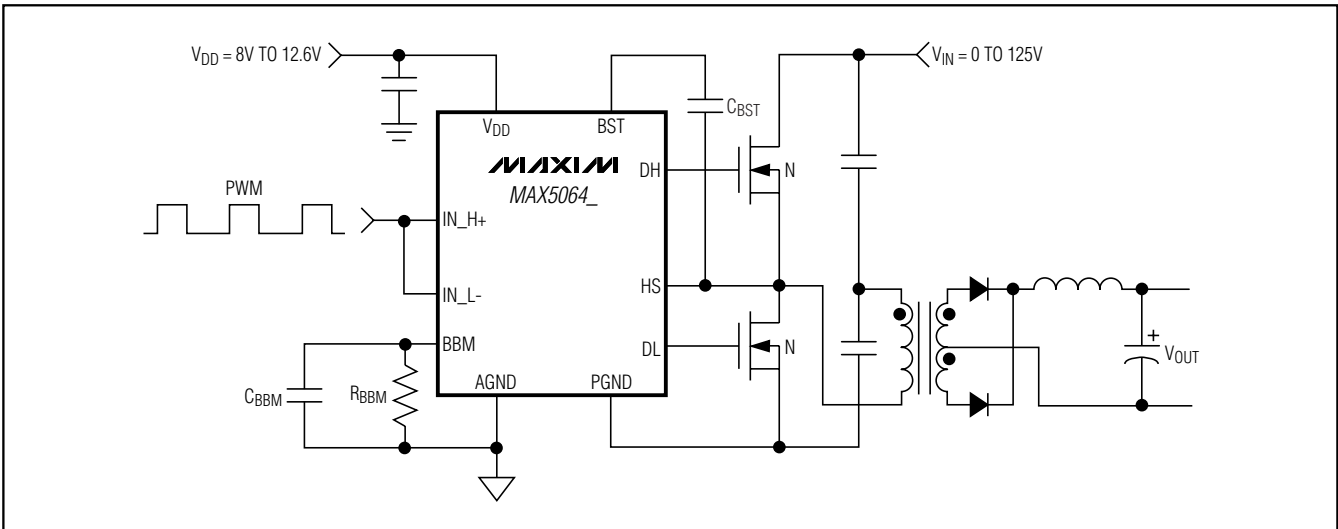
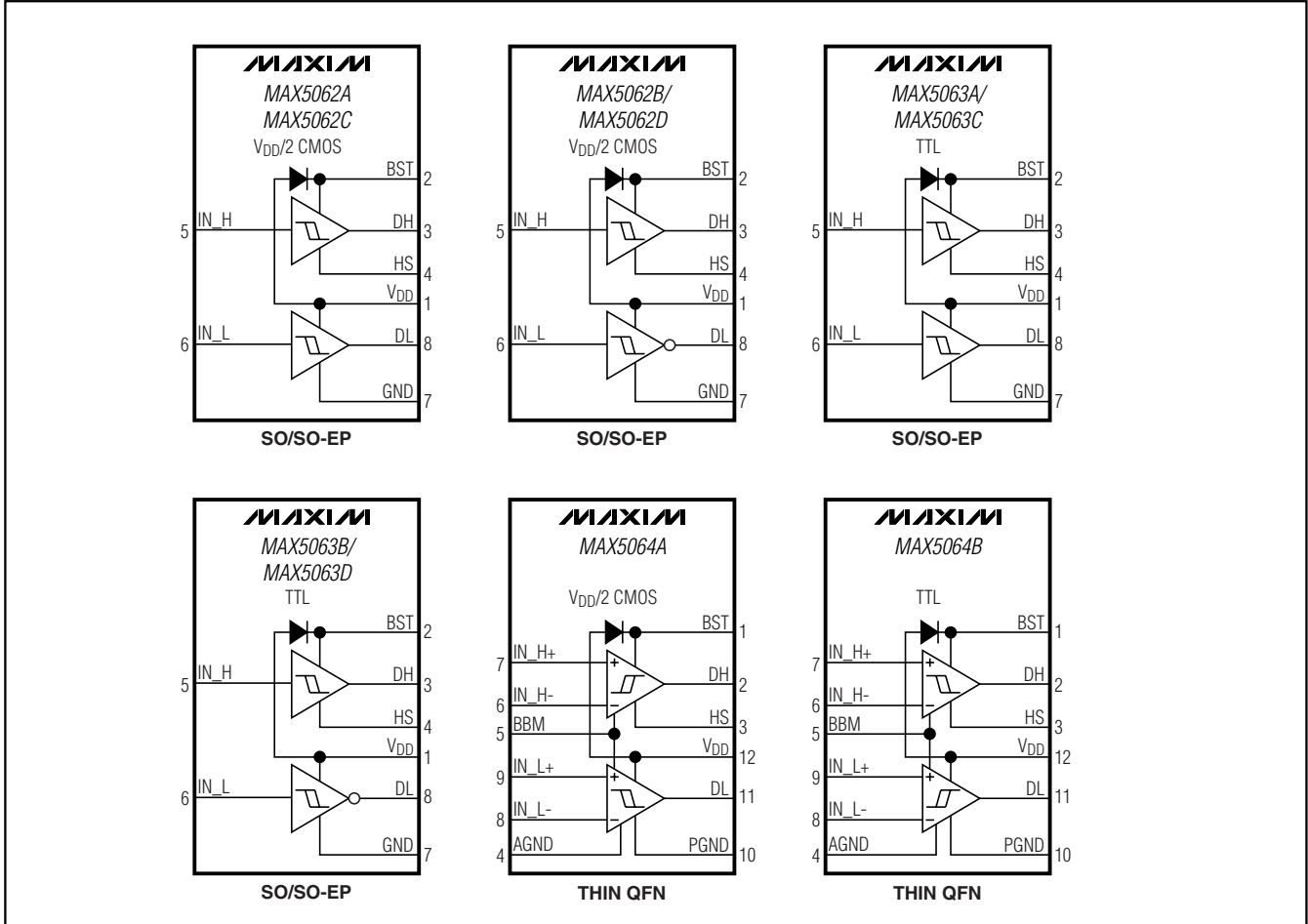


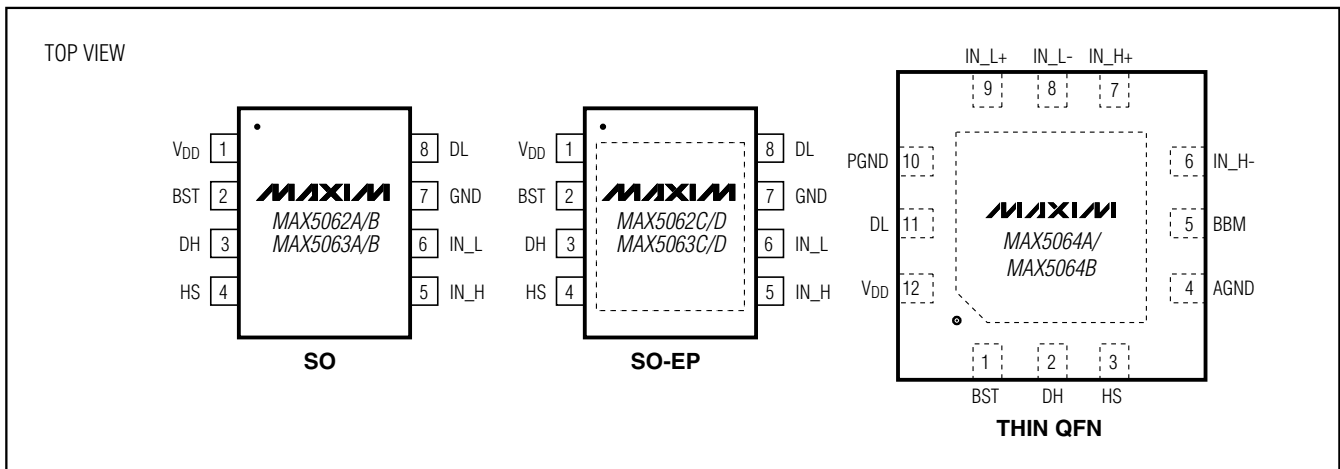
Figure 7. MAX5064 Half-Bridge Converter

# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## Functional Diagrams



## Pin Configurations



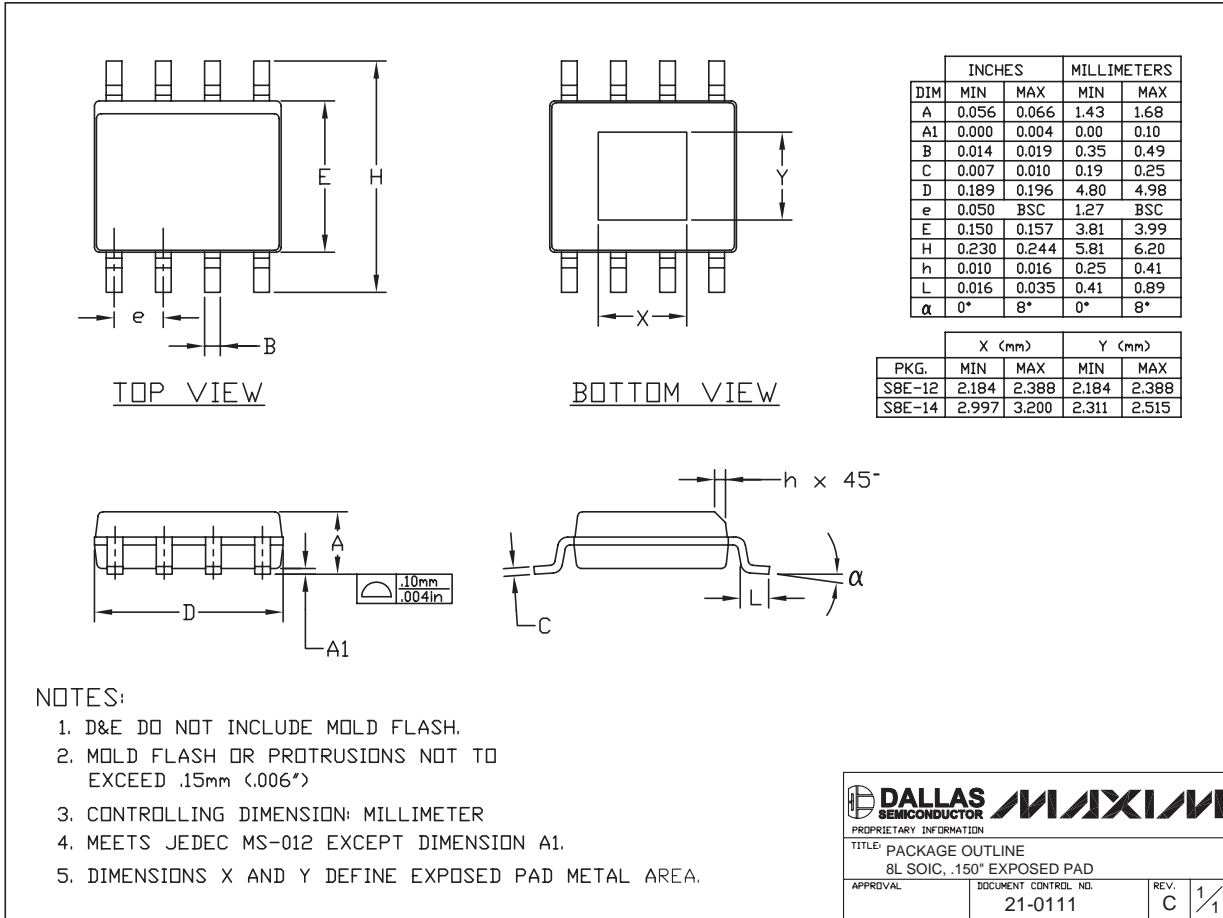




# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).)



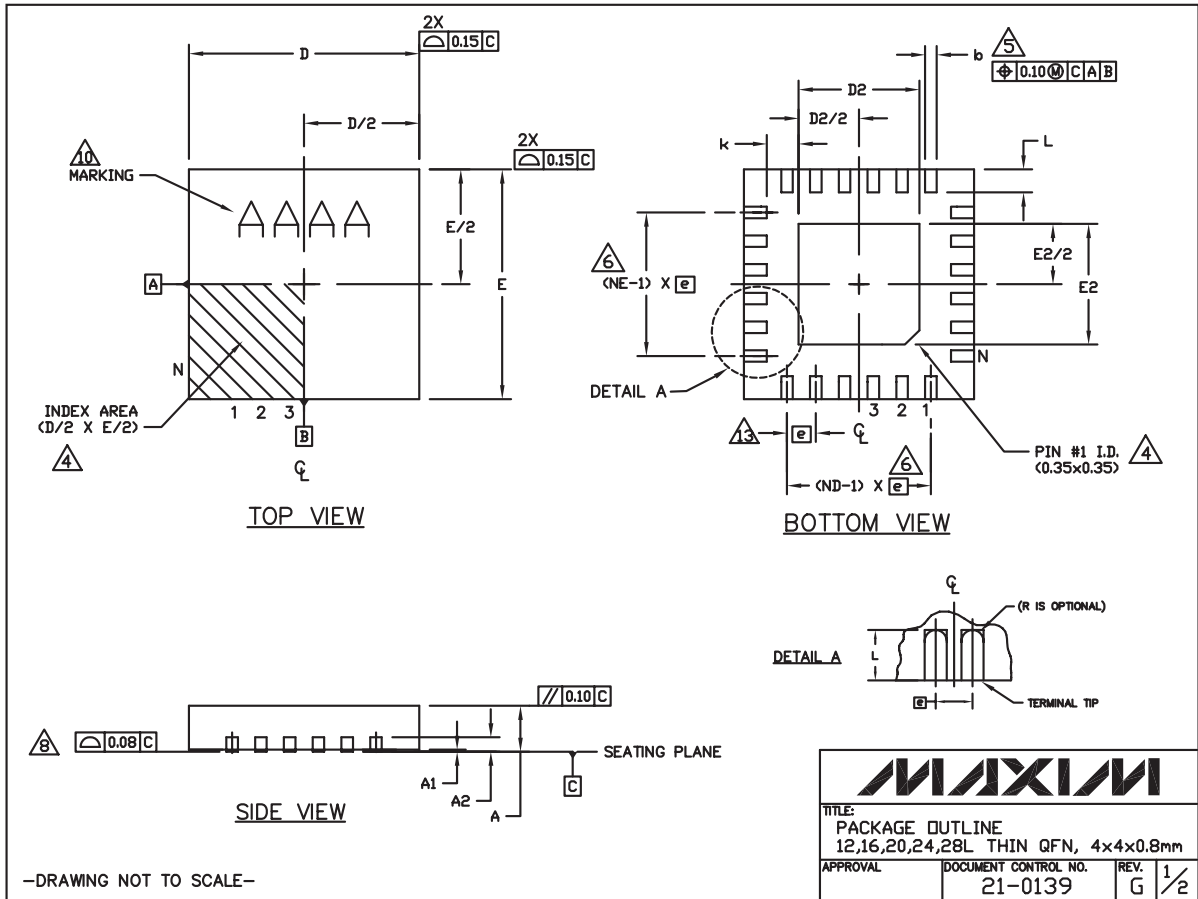
8L SOIC EXP. PAD.EPS

# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).)

MAX5062/MAX5063/MAX5064



# 125V/2A, High-Speed, Half-Bridge MOSFET Drivers

## Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to [www.maxim-ic.com/packages](http://www.maxim-ic.com/packages).)

COMMON DIMENSIONS															
PKG	12L 4x4			16L 4x4			20L 4x4			24L 4x4			28L 4x4		
REF.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80	0.70	0.75	0.80
A1	0.0	0.02	0.05	0.0	0.02	0.05	0.0	0.02	0.05	0.0	0.02	0.05	0.0	0.02	0.05
A2	0.20 REF			0.20 REF			0.20 REF			0.20 REF			0.20 REF		
b	0.25	0.30	0.35	0.25	0.30	0.35	0.20	0.25	0.30	0.18	0.23	0.30	0.15	0.20	0.25
D	3.90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10
E	3.90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10	3.90	4.00	4.10
e	0.80 BSC.			0.65 BSC.			0.50 BSC.			0.50 BSC.			0.40 BSC.		
k	0.25	-	-	0.25	-	-	0.25	-	-	0.25	-	-	0.25	-	-
L	0.45	0.55	0.65	0.45	0.55	0.65	0.45	0.55	0.65	0.30	0.40	0.50	0.30	0.40	0.50
N	12			16			20			24			28		
ND	3			4			5			6			7		
NE	3			4			5			6			7		
JeDEC Var.	WGGB			WGGC			WGGD-1			WGGD-2			WGGE		


EXPOSED PAD VARIATIONS						
PKG. CODES	D2			E2		
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
T1244-3	1.95	2.10	2.25	1.95	2.10	2.25
T1244-4	1.95	2.10	2.25	1.95	2.10	2.25
T1644-3	1.95	2.10	2.25	1.95	2.10	2.25
T1644-4	1.95	2.10	2.25	1.95	2.10	2.25
T2044-2	1.95	2.10	2.25	1.95	2.10	2.25
T2044-3	1.95	2.10	2.25	1.95	2.10	2.25
T2444-2	1.95	2.10	2.25	1.95	2.10	2.25
T2444-3	2.45	2.60	2.63	2.45	2.60	2.63
T2444-4	2.45	2.60	2.63	2.45	2.60	2.63
T2844-1	2.50	2.60	2.70	2.50	2.60	2.70

NOTES:

- DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
- ALL DIMENSIONS ARE IN MILLIMETERS. ANGLES ARE IN DEGREES.
- N IS THE TOTAL NUMBER OF TERMINALS.
- THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JEDEC 95-1 SPP-012. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.
- DIMENSION b APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25mm AND 0.30mm FROM TERMINAL TIP.
- ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
- DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
- COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
- DRAWING CONFORMS TO JEDEC MD220, EXCEPT FOR T2444-3, T2444-4 AND T2844-1.
- MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY.
- COPLANARITY SHALL NOT EXCEED 0.08mm.
- WARPAGE SHALL NOT EXCEED 0.10mm.
- LEAD CENTERLINES TO BE AT TRUE POSITION AS DEFINED BY BASIC DIMENSION 'e', ±0.05.
- NUMBER OF LEADS SHOWN ARE FOR REFERENCE ONLY.
- ALL DIMENSIONS ARE THE SAME FOR LEADED (-) & PbfREE (+) PACKAGE CODES.

-DRAWING NOT TO SCALE-



TITLE:  
PACKAGE OUTLINE  
12,16,20,24,28L THIN GFN, 4x4x0.8mm

APPROVAL	DOCUMENT CONTROL NO. 21-0139	REV. G	2/2
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## Revision History

Pages changed at Rev 5: 1, 2, 4, 5, 11-15, 19, 20

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- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



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