



## **IQS231A/B** Datasheet

Single Channel Capacitive Proximity/Touch Controller for SAR applications

### **1** Device overview

The IQS231A/B ProxSense® IC is a self-capacitance controller designed for applications where an awake/activate on proximity function is required. The IQS231A/B is an ultra-low power solution that uses unique release and/or movement detection for applications that require long- term detection. The IQS231A/B operates standalone or I2C and features configuration via OTP (One Time Programmable) bits. Switching from I2C to standalone during runtime is also possible in order to access all settings while offering the simplicity of a standalone output.

IQS231B offers alternate hardware with identical firmware to the IQS231A. IQS231B hardware offers improved temperature response and low temperature range.

### **1.1 Main Features**

- Integrated SAR user interface offering a simple GPIO output
- Quick release detection effectively prevent false triggers from remaining
- Quick release **sensitivity options**
- Wide range of control for sensing in high power RF environments
- Pin compatible with devices of same package type (IQS229 DFN10, all ProxSense TSOT23-6 devices<sup>1</sup>,IQS211A WLCSP-8 device)
- 1.8V (-2%) to 3.6V Input voltage
- Capacitive resolution down to 0.02fF
- Capacitive load capability up to 200pF
- External threshold adjustment pin (minimize need for pre-empted OTP adjustments)
- Minimal external components (direct input strap)
- Standalone failsafe mode (backwards compatible failsafe output, short pulses on output to indicate operational device)
- Default OTP options focus on safety and passing SAR lab qualification, OTP changes offer performance advantages
- **I2C interface option** (improved compatibility)



- Extended controls in I<sup>2</sup>C mode (setup in I<sup>2</sup>C, runtime with standalone output)
- Optional input for synchronized implementations (input to instruct IC when to sense)
- Synchronization output failsafe pulses may be used by the master to synchronize on. Sensing is done after each pulse
- Synchronization input Sensing is only done while Sync input is low
- Low power sensing: 30Hz (default), 100Hz, 8Hz, 4Hz (sub 6uA mode)
- Constant sampling rates during all power modes with rapidly debounced output changes
- Advanced temperature & interference compensation option

<sup>&</sup>lt;sup>1</sup> Input voltage level and pin functions may differ





## **1.2 Applications**

- SAR sensor
- Integrated hybrid designs (RF and 

   capacitive sensing combined)
- Hold detection for screen activation
  - On-ear detection
- Movement sensing applications (user interaction detection, anti-theft)

T <sub>A</sub>	DFN10	TSOT23-6	WLCSP-8 (1.5 x 0.9 x 0.4mm)
-20°C to 85 °C	IQS231A	IQS231A	IQS231A (NRFND)
-40°C to 85 °C		IQS231B	IQS231B





### 1.3 Block diagram



#### Figure 1.1 Functional block diagram for IQS231A/B

The IQS231A/B supports relative capacitance measurements for detecting capacitance changes.

Basic features of the IQS231A/B include:

- Charge-transfer capacitance measurement technology (Analog ProxSense® Engine)
- Finite state machine to automate detection and environmental compensation without MCU interaction (integrated microprocessor)
- Self-capacitance measurements
- Signal conditioning to provide signal gain (Analog Capacitive offset calibration)
- Signal conditioning to provide offset compensation for parasitic capacitance (Analog Capacitive offset calibration)
- Integrated calibration capacitors (Analog Capacitive offset calibration)
- Integrated timer for timer triggered conversions
- Integrated LDO regulator for increased immunity to power supply noise
- Integrated oscillator
- Processing logic to perform measurement filtering, environmental compensation, threshold detection and movement detection





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		R	
	-	HRESHOLD	



#### **ProxSense<sup>®</sup> Series**



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## 2 Packaging and Pin-Out

## 2.1 TSOT23-6 & DFN10



#### Figure 2.1 IQS231A/B TSOT23-6 pin-out



Figure 2.2 IQS231A DFN10 pin-out

#### Table 2.1 TSOT23-6 Pin-out description

	IQS231A/B TSOT23-6							
Pin	Name	Туре	Function					
1	PRIMARY I/O	Digital Input/Output	Multifunction IO1 / SCL (I <sup>2</sup> C Clock signal)					
2	VSS	Signal GND						
3	SECONDARY I/O	Digital Input/Output	Multifunction IO2 / SDA (I <sup>2</sup> C Data output)					
4	VREG	Regulator output	Requires external capacitor					
5	VDDHI	Supply Input	Supply:1.764V – 3.6V					
6	Сх	Sense electrode	Connect to conductive area intended for sensor					

#### Table 2.2 DFN10 Pin-out description

	IQS231A DFN10								
Pin	Name	Туре	Function						
1	NC								
2	VSS	Signal GND							
3	Сх	Sense electrode	Connect to conductive area intended for sensor						
4	VDDHI	Supply Input	Supply:1.764V – 3.6V						
5	VREG	Regulator output	Requires external capacitor						
6	NC								
7	NC								
8	SECONDARY I/O	Digital Input/Output	Multifunction IO2 / SDA (I <sup>2</sup> C Data output)						
9	PRIMARY I/O	Digital Input/Output	Multifunction IO1 / SCL (I <sup>2</sup> C Clock signal)						
10	NC								



#### Table 2.3 Multifunction pin descriptions

Multifunction pin name	Multifunction pin option	Output type
IO1	Proximity output / Proximity output with heartbeat	Open-drain <sup>2</sup>
102	Sensitivity input / Synchronization input / Movement output / Touch output	Open-drain <sup>2</sup>

## 2.2 WLCSP



#### Figure 2.2 IQS231A 8-pin WLCSP (top view)

#### Table 2.2 8-pin WLCSP Pin-out description

	IQS231A 8-pin WLCSP							
Pin	Name	Туре	Function					
1	Сх	Sense electrode	Connect to conductive area intended for sensor					
2	PRIMARY I/O	Digital Input/Output	Multifunction IO1 / SCL (I <sup>2</sup> C Clock signal)					
3	VREG	Regulator output	Requires external capacitor					
4	VSS	Signal GND						
5	FLOATING IO	Digital Input/Output	Not used. Floating input during runtime. Recommended: Connect to GND					
6	SECONDARY I/O	Digital Input/Output	Multifunction IO2 / SDA (I <sup>2</sup> C Data output)					
7	VDDHI	Supply Input	Supply:1.764V – 3.6V					
8	PGM	Configuration pin	Connection for OTP programming. Floating input during runtime. Recommended: Connect to GND. Connect separate pad/pin for in-circuit programming (separate modules only)					

<sup>&</sup>lt;sup>2</sup> Requires pull-up resistor







Figure 3.1 IQS231A DFN10 reference schematic

Footnotes:

\* R5: Place a  $47\Omega$  resistor in the VDDHI supply line to prevent a potential ESD induced latchup. Maximum supply current should be limited to 80mA on the IQS231A/B VDDHI pin to prevent latch-up.

\*\* C4 & C5: Choose these capacitors based on the selected sampling rate. The target is to prevent the VREG voltage to drop more than 50mV from its regulated value during a sleep cycle (see Figure 9.1).

	30Hz	100Hz	8Hz	4Hz
C4	1uF	1uF	2.2uF	4.7uF
C5	1uF	1uF	4.7uF	10uF

\*\*\*C2: Example load of 10pF. This value may vary to adjust sensitivity. 1pF for higher sensitivity and up to 60pF for proximity detection use. A total load capacitance of 200pF is allowed by the sensing system.

\*\*\*\*R1: Vary this value to control the RC slope of the capacitance measurement signal. Use for harmonic suppression and to enable a high impedance sensing path in a low impedance system.







Figure 3.2 IQS231A/B TSOT23-6 reference schematic

Footnotes:

\* R5: Place a  $47\Omega$  resistor in the VDDHI supply line to prevent a potential ESD induced latchup. Maximum supply current should be limited to 80mA on the IQS231A/B VDDHI pin to prevent latch-up.

\*\* C1 & C3: Choose these capacitors based on the selected sampling rate. The target is to prevent the VREG voltage to drop more than 50mV from its regulated value during a sleep cycle (see Figure 9.1).

	30Hz	100Hz	8Hz	4Hz
C1	1uF	1uF	2.2uF	4.7uF
C3	1uF	1uF	4.7uF	10uF

\*\*\*C5: Example load of 10pF. This value may vary to adjust sensitivity. 1pF for higher sensitivity and up to 60pF for proximity detection use. A total load of 200pF is allowed by the sensing system.

\*\*\*\*R1: Vary this value to control the RC slope of the capacitance measurement signal. Use for harmonic suppression and to enable a high impedance sensing path in a low impedance system.





## 4 Summary: One-Time-Programmable (OTP) options

OTP bank 0 IQS231A/B 000000xx TSR							
Bit7	6	5	4	3	2	1 Bit 0	
Movement ti	-	Reserved	Movement threshold	Quick releas	-	Quick release beta	
00 – 2s 01 – 5s 10 – 10s	01 – 5s		0 – 4 counts 1 – 6 counts	00 – moderate 01 – strict 10 – relaxed 11 – very strict	100 counts 150 50 250	00 – 2 (fast following) 01 – 3 10 – 4 11 – 5 (slow following)	
<u>Prox&amp;Mov Uis</u> 00 - 10s 01 - 30s 10 - 60s 11 - 10min							
	ccuracy section						
OTP Bank			S231A/B 00	000 <u>xx</u> 00 TS			
Bit7 I2C address	6	5 Proximity Thres (low/high)	4 shold	3 AC Filter	2	Touch threshold	
00 – standalone 01 – 44H 10 – 46H 11 – 47H		Sensitivity input low / Sync input active / Mov output / Touch output 00 - 4 counts ('Warning) 01 - 6 10 - 8 11 - 10 Sensitivity input high (internal $20k\Omega$ pull-up) 00 - 8 counts 01 - 10 10 - 12		00 - 1 01 - 2 10 - 3 11 - 0		00 – 32 counts 01 – 64 10 – 256 11 – 320	
*See time-out a	ccuracy section	11 – 14	8001 A /P 00		D		
Bit7	6	5	4	0 <u>xx</u> 0000 TS 3	2	1 Bit 0	
Increase debounce	Target	Base value	4	Failsafe	Quick release	User interface	
0 – 6in, 4out 1 – 12in, 8out	0 = 1200 / 1096 (movement) 1 = 768	00 – 100 counts 01 – 75 10 – 150 11 – 200		0 – Disabled 0 – Enabled 1 – Enabled 1 – Disabled		00 – Prox / No movement 01 – Prox with movement 10 – Prox with movement / Touch with no movement 11 – Same as '10', touch output forced on IO2	
<b>OTP Bank</b>	3	IQ	S231A/B xx	<u>«</u> 000000 TS	R		
Bit7	6	5	4			1 Bit 0	
Charge trans frequency		54Temperature & interference compensationIO2 function				Sample rate	
00 – 500kHz 01 – 125 kHz 10 – 64 kHz 11 – 16.5kHz		0 – Disabled 1 – Enabled	00 – Sensitivity (proximity thres 01 – Sync input 10 – Movement 11 – Ignore inp	hold adjust) t t output	0 – Enabled 1 – Disabled	Sample-to-sample time (Response time) Includes 6 sample debounce burst of 24ms 00 – 30 Hz (57ms) 01 – 100 Hz (34ms) 10 – 8 Hz (154ms) 11 – 4 Hz (280ms) *See time-out accuracy section 8.8 & 8.9	

<sup>1</sup>Careful design is key when using a threshold of 4 combined with a base value of 100 / 75 and a target of 1200. Contact Azoteq.





## 5 Summary: Programming reference (I<sup>2</sup>C memory map)

<b>A</b> al al an a a a <i>l</i>	De sister a sur s /s	D/14/	Default	Dit 7		inications Layout	Dit 4	Dit 2	D14-2	Dit 4	D'A				
Address/ Command/ Byte	Register name/s	R/W	Value	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit				
DEFAULT COMMS POINTER	MAIN_EVENTS	R	n/a		DEBUG	SENSING DISABLED	WARM BOOT	COLD BOOT	RELEASE	TOUCH	PROX				
				ion returns 'MA	IN_EVENTS' byte	as first byte, follow			ddress						
00H	PRODUCT_NUMBER	R	0x40					:40							
01H	SOFTWARE_VERSION	R	0x06	0x06 (IQS231A), 0x07 (IQS231B – Identical to 0x06 software)				1							
02H	DEBUG_EVENTS	R	n/a	RESERVED	ATI_ERROR	CH0_ATI	RESERVED	QUICK RELEASE	EXIT MOV DETECT	ENTER MOV DETECT	MOVEMEN				
03H	Reserved	R/W	n/a			1	-	RVED		1 .	r				
04H	COMMANDS	R/W	0x00	ATI_CH0	DISABLE SENSING	ENABLE SENSING	TOGGLE AC FILTER	RESERVED	TOGGLE ULP MODE	RESERVED	WARM BOOT				
05H	OTP Bank 1	R/W	0x00	Standalone /	I2C address	Proximity three Read only	shold	AC Filter		Touch thresh Read only	nold				
06H	OTP Bank 2	R/W	0x00	Increase debounce	Target	Base value		Failsafe pulses IO1	Quick release	User interfac	e selection				
07H	OTP Bank 3	R/W	0x00	Charge transf	er frequency	Temperature & interference compensation	IO2 Function		ATI events on IO1	Sample rate					
08H	QUICK RELEASE	R/W	0x00		Quick release	threshold LUT			Quick relea	ase beta					
				0xC = 500 0xD = 750 0xE = 850	0x8 = 75 0x9 = 200 0xA = 300	0x4 = 10 0x5 = 20 0x6 = 25	0x0 = 100 0x1 = 150 0x2 = 50								
09H	MOVEMENT	R/W	0x34	0xF = 1000	0xB = 400 Filter h	0x7 = 30 nalt time	0x3 = 250								
			(2s, 8)	0xC = 10min 0xD = 30min 0xE = 60min	0x8 = 30s 0x9 = 1min 0xA = 2min	0x4 = 4s 0x5 = 5s 0x6 = 10s	0x0 = 0s 0x1 = 0.5s 0x2 = 1s		Movement thresho Available ran 0 = always move	ige: 0 – 30	1				
0AH	TOUCH THRESHOLD	R/W	0x07	0xF = 90min	0xB = 5min	0x7 = 20s		= (Value × 4) + 4	L						
0BH	PROXIMITY	R/W	(32) 0x00		Por	anvad	Available ra	nge: 4 – 1024		00 4 count	c				
ОВП	THRESHOLD	K/ VV	0x00	Reserved         Reserved         00-4 counts           01-6         10-8         11-10				5							
0CH	Temperature & interference threshold	R/W	0x03		Temperature tracking threshold when not in touch / prox detect										
0DH	CH0 Multipliers	R/W	n/a	Reserved	Reserved	CH0 Sensitivi 0 -			CH0 Compensat 0 – 1						
0EH	CH0 Compensation	R/W	n/a			0		255	0 1						
0FH	CH1 Multipliers	R/W	n/a	Reserved	Reserved	CH1 Sensitivi			CH1 Compensat						
10H	CH1 Compensation	R/W	n/a			0 -		255	0 - 1	.5					
11H	System flags	R	n/a	12C	TEMP	CH1_ACTIVE	CURRENT_CH	NO SYNC	CH0_LTA_HALTED	ATI_MODE	ZOOM MOD				
12H	UI flags	R	n/a	TEMP	TEMPERATURE	Reserved	UI AUTO ATI	UI SENSING	QUICK_RELEASE	Reserved	OUTPUT				
13H	ATI flags	R	n/a	CHANNEL ATI	RESEED	Reserved	OFF	DISABLED	QUICK_REEEASE	Neserveu	ACTIVE				
13H 14H	Event flags	R	n/a	CH1_ATI			CH1 Kes	erved CH0_ATI	CH0	CH0	1				
				ERROR	Reserved		MOVEMENT	ERROR	UNDEBOUNCED	TOUCH	CH0_PROX				
15H	CH0 ACF_H	R	n/a			Pr		Filtered count va 2000	lue						
16H	CH0 ACF_L	R	n/a			Dura insita aka	-								
	CH0 LTA_H CH0 LTA_L	R R	n/a n/a			Proximity cha		ount value (Long 2000	(term average)						
17H			II/d		0 – 2000										
18H			n/2	Proximity channel: Quick release detect reference value											
18H 19H	CH0 QRD_H	R	n/a n/a			Proximity				0 – 2000 Movement channel: Filtered count value					
18H	CH0 QRD_H CH0 QRD_L		n/a n/a n/a				0 -	2000							
18H 19H 1AH	CH0 QRD_H	R R	n/a				0 – . vement channel	2000							
18H 19H 1AH 1BH	CH0 QRD_H CH0 QRD_L CH1 ACF_H	R R R	n/a n/a			Mc	0 – 0 vement channel 0 – 0 ent channel: Upp	2000 Filtered count v 2000 per reference cou	alue						
18H 19H 1AH 1BH 1CH 1DH 1EH	CH0 QRD_H CH0 QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L	R R R R R R R	n/a n/a n/a n/a n/a			Movem	0 – vement channel 0 – ent channel: Upp 0 – 2	2000 Filtered count v 2000 Der reference cou 2000	alue int value						
18H 19H 1AH 1BH 1CH 1DH 1EH 1FH	CH0 QRD_H CH0 QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_H	R R R R R R R R	n/a n/a n/a n/a n/a			Movem	0 – vement channel 0 – ent channel: Upp 0 – 2 ent channel: Low	2000 Filtered count v 2000 Per reference cou 2000 Ver reference cou	alue int value						
18H 19H 1AH 1BH 1CH 1DH 1EH 1FH 20H	CH0 QRD_H CH0 QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_H CH1 LMOV_L	R R R R R R R R R	n/a n/a n/a n/a n/a n/a			Movem Movem	0 – vement channel 0 – ent channel: Upp 0 – 2 ent channel: Low 0 – 2	2000 Filtered count v 2000 Der reference cou 2000 Ver reference cou 2000	alue int value int value						
18H 19H 1AH 1BH 1CH 1DH 1EH 1FH 20H 21H	CH0 QRD_H CH0 QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_H CH1 LMOV_L CH1_RAW_H	R R R R R R R R R R	n/a n/a n/a n/a n/a n/a n/a		Tem	Movem Movem	0 – vement channel 0 – ent channel: Upp 0 – 2 ent channel: Low 0 – 2 Unfiltered count	2000 Filtered count v 2000 Der reference cou 2000 Ver reference cou 2000	alue int value	led)					
18H 19H 1AH 1BH 1CH 1DH 1EH 1FH 20H 21H 22H	CH0 QRD_H CH0 QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_L CH1 LMOV_L CH1_RAW_H CH1_RAW_L	R R R R R R R R R R R R	n/a n/a n/a n/a n/a n/a n/a n/a			Movem Movem Movem perature channel:	0 – vement channel 0 – ent channel: Upp 0 – ent channel: Low 0 – Unfiltered coun 0 –	2000 Filtered count v 2000 Der reference cou 2000 ver reference cou 2000 t value (if temper 2000	alue int value int value rature feature enab						
18H 19H 1AH 1BH 1CH 1DH 1EH 1FH 20H 21H	CHO QRD_H CHO QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_L CH1 LMOV_L CH1_RAW_H CH1_RAW_L TEMPERATURE_H	R R R R R R R R R R	n/a n/a n/a n/a n/a n/a n/a n/a n/a			Movem Movem Movem perature channel:	0 – vement channel 0 – ent channel: Upg ent channel: Low 0 – 2 Unfiltered coun 0 –	2000 Filtered count v 2000 Der reference cou 2000 ver reference cou 2000 t value (if temper 2000	alue int value int value						
18H 19H 1AH 1BH 1CH 1DH 1EH 1FH 20H 21H 22H 23H	CH0 QRD_H CH0 QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_L CH1 LMOV_L CH1_RAW_H CH1_RAW_L	R R R R R R R R R R	n/a n/a n/a n/a n/a n/a n/a n/a		Movem	Moverr Moverr perature channel: ent channel temp	0 – vement channel 0 – ent channel: Upp 0 – : ent channel: Low 0 – Unfiltered coun 0 – erature reference 0 –	2000 Filtered count v 2000 per reference cou 2000 value (if temper 2000 e (a previous valu 2000	alue int value int value rature feature enab ee of temperature c	hannel)					
18H 19H 1AH 1BH 1CH 1DH 1EH 1FH 20H 21H 22H 23H 24H	CHO QRD_H CHO QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_L CH1 LMOV_L CH1 RAW_H CH1_RAW_H CH1_RAW_L TEMPERATURE_H TEMPERATURE_L	R R R R R R R R R R R R R	n/a n/a n/a n/a n/a n/a n/a n/a n/a n/a		Movem	Movem Movem perature channel: ent channel temp mer to give active	0- vement channel 0- ent channel: Upp 0- ent channel: Low 0- Unfiltered coun 0- erature reference 0- feedback on the	2000 Filtered count v 2000 per reference cou 2000 value (if temper 2000 e (a previous valu 2000	alue int value int value rature feature enab ie of temperature c ment events will re:	hannel)					
18H 19H 1AH 1BH 1CH 1DH 1EH 1FH 20H 21H 22H 23H 22H 23H 24H 25H 26H 27H	CHO QRD_H CHO QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_L CH1 LMOV_L CH1_RAW_H CH1_RAW_L TEMPERATURE_H TEMPERATURE_L LTA_HALT_TIMER_H LTA_HALT_TIMER_L FILTER_HALT_TIMER	R R R R R R R R R R R R R R R R R R R	n/a n/a n/a n/a n/a n/a n/a n/a n/a n/a	Countdown ti	Movem Countdown ti	Movem Movem perature channel ent channel temp mer to give active (0 – 2 feedback on the 0 – 5	0 vement channel 0 ent channel: Upp 0 ent channel: Low 0 Unfiltered coun 0 erature reference 0 feedback on the 255) × 100ms   Time 0 x 100ms   Time	2000 Filtered count v 2000 per reference cou 2000 ever reference cou 2000 value (if temper 2000 e (a previous valu 2000 time-out. Move imer range: 0 – 5 se	alue int value ature feature enab re of temperature c ment events will re 10min halt mode (before c conds	hannel) set this timer	ity detect)				
18H 19H 1AH 1BH 1CH 1CH 1EH 1FH 20H 21H 22H 23H 24H 25H 26H	CH0 QRD_H CH0 QRD_L CH1 ACF_H CH1 ACF_L CH1 UMOV_H CH1 UMOV_L CH1 LMOV_H CH1 LMOV_L CH1_RAW_H CH1_RAW_H CH1_RAW_L TEMPERATURE_H TEMPERATURE_L LTA_HALT_TIMER_H LTA_HALT_TIMER_L	R R R R R R R R R R R R R R	n/a n/a n/a n/a n/a n/a n/a n/a n/a n/a	Countdown ti	Movem Countdown t mer to give active	Movern Movern perature channel: ent channel temp mer to give active (0 – e feedback on the 0 – 5 Countdown tim (0 – 1	0 – vement channel 0 – ent channel: Upy 0 – : ent channel: Low 0 – Unfiltered count 0 – erature reference 0 – feedback on the 255) × 100ms   Tim fixed Ssec time-c 0 × 100ms   Tim 0) × 100ms   Tim	2000 Filtered count v 2000 per reference cou 2000 ver reference cou 2000 ver value (if temper 2000 er value (if temper 2000 er arvive value 2000 time-out. Move imer range: 0 – 5 se a read operatio er range: 0 – 1 se	alue int value ature feature enab re of temperature c ment events will re 0min halt mode (before - conds n is done on IO2	hannel) set this timer entering Proxim					







## 6 Summary: Features

Pin compatibility	Designs using the IQS229 or IQS128 will benefit from a "drop-in" replacement on a production device for evaluation.				
	Using the added I <sup>2</sup> C capability on the IQS231A/B will require an added connection to the master device.				
	A DYCAL-type implementation (referring to dynamic threshold calibration) is recommended as main stability feature for the latest SAR user interface. Passing the device SAR qualification with this type of interface has been proven successful.				
	"Quick release" detection is the improved "DYCAL"-type implementation and focusses on a release characteristic within a time window.				
N' A	Movement features add a second level of protection against stuck conditions with the quick release detection.				
DYCAL / Quick release	The quick release will be detected on the proximity channel (not the secondary movement channel) and the signal slope will be monitored to enable the quick release. A single action from a touch/proximity state will trigger the quick release event and the event will only remain as long the proximity state holds.				
	A number of features are offered to ensure operation in various designs where high power RF signals may influence the sensing signal:				
Control in RF environments	<ul> <li>Increased low frequency sensing options to allow for high impedance filter circuits</li> <li>Increased debounce option to prevent RF noise triggers</li> <li>Advanced temperature compensation for fast temperature variations caused by high power RF circuits</li> <li>Interference compensation for false triggers caused by conducted/radiated noise.</li> </ul>				
Advanced temperature & interference compensation	An improved compensation feature is offered to prevent false triggers due to quickly varying temperature & high interference environments. This feature effectively tracks temperature changes & compensates for interference only when no proximity trigger is present.				
	The device offers 3 main Uis intended for SAR use. These are:				
UI	<ul> <li>Proximity UI, no continuous movement sensing</li> <li>Proximity UI, continuous movement sensing</li> <li>Proximity &amp; touch UI, continuous movement sensing during proximity, no movement sensing during touch (No time-out during long duration stationary SAR tests)</li> </ul>				
User interface selection	In all cases the use of the quick release feature is recommended to prevent typical non-human activations from remaining.				
	In all cases "no movement" and "movement sensing" refers to the capacitive movement sensing during normal activation. "Hand held detection" and "quick release" features will enable				





movement sensing with a no-movement time-out, irrespective of which UI is selected.

## Summary: Features (Continued 1...)

Movement detection	Movement detection is designed to function as human presence detection in a localized area. This device can't be used to fulfil an accelerometer function ("G-sensor" function). Human presence detection requires an exception in SAR testing because the qualification testing only uses stationary "phantom bodies". Optimized human detection is offered through an integrated separate channel, dedicated towards human detection.
Sensitivity adjustment	Default input use: internal pull-up ( $20k\Omega$ ) by default, tie directly to GND for more sensitive option. Apart from the simple external adjustment, an external capacitor is recommended for sensitivity adjustments. 1pF is considered a small change in sensitivity, while 10pF changes are considered large. A maximum of 60pF load is recommended for effective proximity sensing.
Cx IO1 Failsafe heartbeat	A single pulse of 500µs is integrated on IO1. This pulse is the failsafe heartbeat, sent on each sensing event. This pulse will be sent during the "stabilize time" as shown in Figure 9.1. The failsafe indicator signal will precede the conversions (sampling). The failsafe signal will be repeated during burst mode in order to offer synchronization output to the master, indicating exactly when sensitive measurements are done. Measurement times have a fixed maximum which the user can implement. The failsafe signal is disabled by default and may be enabled via OTP option or I <sup>2</sup> C initialize with standalone setup.
High configurability	Through I <sup>2</sup> C the IQS231A/B can be used in many ways and the configuration can be updated during later stages of development than with the OTP route.
Switch I <sup>2</sup> C to standalone	Configure the device via a dedicated I <sup>2</sup> C type connection and switch to any standalone mode for runtime operation. This minimises the processor load and spurious content from communication signals. Unexpected reset conditions should be managed via the failsafe pulse OTP option or by polling the device periodically. When the heartbeat disappears or I2C responds to the polling, default state applies, and the master should reconfigure the device through I <sup>2</sup> C.





## Summary: Features (Continued 2...)

Sync input	In order to ensure a stable sensing environment, sensing may be done in strategic time windows controlled by a master device.	
	The Automatic tuning implementation (ATI) ensures optimal sensitivity during runtime for various sensor environments.	
Automatic tuning (ATI)	Two channels are calibrated (proximity channel and movement channel). Both run on the same Cx pin in different time slots.	
(ATI)	An ATI-block time is defined to prevent re-ATI loops during touch release events. The ATI-block is fixed for the movement channel, and fixed for the standard touch/proximity channel	
Reference signal behaviour	Long-term-average (LTA: signal reference) behavior is optimized for SAR where trigger tests are important in product qualification. The LTA will therefore be slow while still able to prevent typical temperature drift from causing activations.	
Start Control Byte	Standard I <sup>2</sup> C polling for:	
S Adr + WRITE ACK	Debugging & normal use	
Improved I <sup>2</sup> C interface	<ul> <li>Device polling optimized for guaranteed response (within t<sub>CLK_stretch</sub> – clock stretching will be applied to the bus SCL line)</li> </ul>	





## 7 Features: Extended details

### 7.1 ATI (Automatic Tuning Implementation)

External sensor connections are calibrated in the following ways:

- Power On Reset (proximity channel is calibrated at each POR)
- Movement channel is only calibrated with POR when hand-held detection is enabled
- Proximity & movement channel is calibrated when the reference is out of bounds (1/8 of target counts). The reference of the proximity channel is rapidly adapted when capacitance moves away from the trigger threshold OR when an automatic "reseed" is done (Reseed: reference = actual sensor value). The reference of the movement channel is rapidly adapted in any direction of capacitive changes.
- Redo-ATI of the proximity channel can be initiated by the user in I<sup>2</sup>C mode using an I<sup>2</sup>C command.

During each proximity channel ATI event, the proximity output is activated to indicate the event and ensure a safe output during the event and in the case of an ATI-error.

### 7.2 Sensitivity adjustment

Apart from the simple external adjustment, an external capacitor is recommended for sensitivity adjustments. 1pF is considered a small change in sensitivity, while 10pF changes are considered large. A maximum of 60pF load is recommended for effective proximity sensing.





## 8 I<sup>2</sup>C Programming Guide (Summary)

The IQS231A/B device interfaces to a master controller via a 2-wire (SDA and SCL) serial interface bus that is  $I^2C^{TM}$  compatible, with a maximum communication speed of 400kbit/s.

The protocol acknowledges an address request independently. The I<sup>2</sup>C hardware module is awake for address recognition while the IQS231A/B is in sleep mode, giving the ability to wake the device at any time and effectively communicate via serial interface. This is different compared to other ultra-low power Azoteq solutions where the communications module also sleeps during standard IC sleep times. Repeated polling requests where required in such case.

### 8.1 Add I2C connection

When using I<sup>2</sup>C mode, ensure the connections as shown in Figure 2.. Internal pull-up resistors are sufficient for communication speeds up to 100kbits/s with low capacitance on the lines (<15pF). For 400kbit/s, be sure to place pull-up resistors (4.7k $\Omega$  recommended)

#### 8.2 I2C command structure

By writing to address 0x04, commands are sent to the device. The commands are as follows:

Reg 0x04 Bit	Name	Description	Toggle (yes/no)
0	SWITCH TO STANDALONE (warm boot)	Switch from I2C so standalone outputs Soft reset, all registers remain as	No
1	AUTO ATI	written, UI resets Enable or disable automatic calibration when sensing signal is out of bounds	Yes
2-4	RESERVED	n/a	n/a
5	DISABLE SENSING	Disables all conversions	No
6	ENABLE SENSING	Enable capacitive sensing	No
7	ATI CH0	Perform re-calibration on proximity channel	No

#### Table 8.1 I<sup>2</sup>C command structure





### 8.3 Control Byte

The Control byte indicates the 7-bit device address (44H default) and the Read/Write indicator bit. The structure of the control byte is shown in Figure 8.1.



#### Figure 8.1 IQS231A/B control byte

The I<sup>2</sup>C device has a 7 bit Slave Address (default 0x44H) in the control byte as shown in Figure 8.1. To confirm the address, the software compares the received address with the device address. Sub-address values can be set by OTP programming options.

The IQS231A/B has alternate slave address options of 0x46 and 0x47.

#### 8.4 Test mode (address 0x45)

During the power-on period ( $t_{test_mode}$ ) the device will respond to polling requests on address **0x45** (test-mode address). Test-mode is used during IC production and OTP (programming) configuration.

With another device on the  $I^2C$  bus with address 0x45, power-up sequence and communication timing should be considered.

#### 8.5 I2C typical setup

The typical I<sup>2</sup>C setup would adjust the following registers:

- Quick release beta
- Quick release threshold
- Movement threshold
- Touch threshold
- Proximity threshold
- Filter halt time
- User interface
- IC mode

The rest of the settings will only require adjustment with specific requirement.

### 8.6 I2C read (Event register)

Each I2C read will always return the event register (default address pointer) as the first byte. When reading from a specific register (write address before read), 2x reads should be done. See memory map first line for detail on the event register.

When reading without writing an address, the main events register data (default address pointer) is returned. Consecutive reads will step through the memory map, starting from address 0x00 after the default address pointer.





### 8.7 I2C polling and sensing timing

Polling may be done at any time. Polling of the specific device will dictate the sensing rate.

Series resistance (example schematic R6 =  $R_{I2C\_series} \& R7 = R_{I2C\_series}$ ) on the I<sup>2</sup>C lines are effective in preventing interference on sensitive configurations.  $R_{I2C\_series}$  is recommended for using the IQS231A/B on a bus with other devices.

#### 8.8 Movement time-out accuracy

When I<sup>2</sup>C mode is enabled (OTP bank 1 bit7:6 is not "00") the time out settings in register 0x09 bit7:4 will respond as shown in the graph below (typical measured values for a constant polling rate):



Figure 8.2 60 second movement time-out vs polling rate

While any polling rate is acceptable for 100Hz sampling, it is recommended to poll slower than the sampling frequency in order to keep an accurate time-out.

#### 8.9 Sampling frequency vs sensing frequency

Sampling frequency (Reg 0x07 bit1:0) is the rate at which samples are taken by the sensor. The sensing frequency (Reg 0x07 bit7:6), or "charge transfer frequency" is the frequency at which the complete capacitive load is charged and discharged.

Depending on the charge transfer frequency, the sampling frequency is automatically adapted to accurately complete charge transfers for 30Hz (default) mode. For 100Hz mode, performance is prioritized and sampling time may vary during "Prox with movement" UIs or "Temperature & interference compensation" enabled. In such case, Reg 0x07 bit1:0 is not forced to a different value. The automatic adapt is done as shown in Figure 8.3





Figure 8.3 Actual sampling period vs sampling frequency selected<sup>1</sup>



Figure 8.4 Actual 60 second time-out example<sup>1</sup> at various charge transfer frequencies

<sup>1</sup>Testing was done to obtain typical values using the recommended schematic as in Figure 3.2 (1uF capacitors for C1 & C3) at 25°C.





## 9 Configuration Options

The IQS231A/B offers various user selectable options. The options are defined via I<sup>2</sup>C setup or **one-time programmable (OTP)** configuration. OTP configured devices can be ordered preprogrammed for bulk orders or in-circuit programming techniques may be implemented during the product-testing phase. I<sup>2</sup>C setup allows access to all device settings while entering direct output mode when selected by the MCU.

Azoteq offers a Configuration Tool (CT210 or later) and associated software that can be used to program the OTP user options for prototyping purposes. For further information regarding this subject, please contact your local distributor or submit enquiries to Azoteq at: info@azoteq.com

### 9.1 OTP Details: Bank 0

Movement time- out (bit 7:6)	When no movement is detected within a time period, a movement time-out occurs. The reference is halted until the timer clears. After the timer clears, the reference signal is made equal to the actual signal, nullifying any signal delta that may have caused a proximity or touch event. The timer is reloaded with every movement event detected.
Movement threshold (bit 4)	A low count threshold region is defined for a movement signal internally stored. Movement characteristics accumulate and triggers as soon as it reaches the threshold. The accumulated effect restarts in order to detect the next possible movement event.
Quick release threshold (bit 3:2)	<ul> <li>The quick release feature will operate according to the parameters as specified in:</li> <li>DYCAL / Quick release definition</li> <li>Quick release beta</li> <li>Quick release threshold</li> <li>The quick release threshold defines the trigger point for the feature where the counts deviate from a quick release moving average in a certain direction. The direction is with increasing counts</li> </ul>
Quick release beta (bit 1:0)	The quick release beta forms part of the quick release feature and is the filter intensity of the reference value used to follow the actual counts. The quick release triggers according to the difference between this reference value and the actual counts. When this value is large, the quick release will trigger for a variety of release types from slow to fast releases. When this value is small, the quick release will only trigger for fast releases.





## 9.2 OTP Details: Bank 1

IC mode	Standalone (default), or I2C.
(bit 7:6)	Use I <sup>2</sup> C for runtime operation, or switch to standalone after initializing the device
	The advantage of this "runtime" option is explained in the Switch I <sup>2</sup> C to standalone section of the features summary.
	When choosing I2C, the address options of $0x44$ , $0x46$ and $0x47$ exist. Avoid the use of address $0x45$ on this I <sup>2</sup> C-bus, this could activate a test mode in the IC during a power-up window.
Proximity Threshold	By default this is the only trigger threshold in the system (touch threshold also available).
(low/high) (bit 5:4)	The threshold is adjustable in actual counts values (count values can be seen when streaming I2C value through the IQS231A/B GUI). The threshold is the amount of counts the actual signal <b>falls below</b> the reference signal (long-term average)
	In the default configuration the input pin IO2 will be active. $IO2 = VSS$ will enable the chosen option in the OTP (4-10 counts) $IO2 = VDDHI$ (8-14 counts)
	The system will default to the IO2 = VSS option when sync input or movement output is enabled.
AC Filter (bit 3:2)	Incoming samples are slightly filtered by default (AC filter = 1). This option gives the ability to significantly increase the filter strength. Default is an IIR (infinite impulse response) filter of 2 ( $2^1$ ). The "increased" options enables an IIR filter of 4 ( $2^2$ ) or 8 ( $2^3$ ).
	Movement detection is not affected by this setting. For movement detection the IIR filter is fixed on AC filter = $2$ .
Touch threshold	Threshold in counts that defines the level below the proximity threshold that cancels a quick release event and disables any active movement detection.
(bit 1:0)	

### 9.3 OTP Details: Bank 2

Increase Debounce (bit 7)	Once a threshold is crossed, a rapid debounce action ensures performance in low SNR environments and short reaction time in low power modes. An increased debounce is offered for situations where RF noise coupling into the sensor is large
Target (bit 6)	The target count is an offset value of the actual system capacitance. The actual signal (expressed in counts) will be calibrated as close as possible to this value.
	A larger target optimizes sensitivity at the cost of charge transfer time. A lower target offers more stability, but less sensitivity.
Base value	The base value is a lower target value for the actual signal and implies the system gain. A base value of 100 and target of 1000 implies a x10











#### Quick The guick release feature can be disabled via this bit (enabled by default). release The quick release feature offers improved user experience and does not influence trigger performance. The feature is directed at SAR applications, but (bit 2) also has significant benefits for long-term detection applications. The touch depth and speed of release is used to detect the instance where the user interaction implies a release condition. This is required for cases where the normal threshold release is not triggered for any of the following reasons: Device placed on table while releasing the hand (the capacitive influence of the table remains) Place device inside a bag while releasing the hand (the capacitive influence of the bag remains) Fit a protective cover during use (the capacitive influence of the cover remains) Extreme temperature (cool down) shift causes a shift in capacitive environment Capacitance impulse recovery (drop test, transient bursts etc) When movement UIs are enabled, the timeout is only active in the proximity User region. When in touch, only quick release can get the IC out of a stuck interface condition. In such case no movement time-out for quick release is fixed at 2sec (bit 1:0) and no-movement time-out for proximity is as defined in OTPs POR auto-ATI POR Reference (LTA) Redo ATI out-of-bounds No calibration Prox active convergence 10 sec calibration time-out ATI error complete Idle Prox active Prox clear 2sec !Mov 5sec no prox Normal prox Filter halt release Quick release Prox detect active & Proximity Active Proximity Active QR detect Figure 9.3 Proximity UI no movement

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#### **OTP Details: Bank 2 (...continued)**





### **OTP Details: Bank 2 (...continued)**







## 9.4 OTP Details: Bank 3

Charge Transfer frequency (bit 7:6) Temperature & Interference Compensation	Various charge transfer frequencies are offered to allow for standard reference design filters to highly resistive and reactive filter elements. These options give the ability to retain signal integrity along with the isolation properties of the filter elements. These options are useful for hybrid antenna designs where the RF and sensing signal share the same conductive structure. Advanced temperature compensation is disabled by default. When enabled the IQS231A/B is able to track strong temperature changes when a proximity is not detected. This may be required when the sensor is placed on a PCB with highly				
(bit 5)	varying temperature effects (example: close to an RF amplifier)				
IO2 function (bit 4:3)	By default IO2 will be a sensitivity adjustment input. An internal pull-up (Rinternal) will by default select a less sensitive option (IO2 = VDDHI). By strapping then pin directly to Vss, a more sensitive option is selected (IO2 = VSS). When the movement output is enabled, the input defaults to the "more sensitive option" as shown with IO2 = VSS With the output enabled the movement events are shown on IO2. The output is in an active low, open drain configuration. The output will remain low for t <sub>awake</sub> when movement is detected and this will occur during the sample time after the movement trigger occurs (the movement trigger is delayed with the sample rate) Sync input: The input (pin IO2) may be used to detect when to sense and when to halt the sensing. $MCU \ GPIO \ WREG \ $				
ATI events on IO1 (bit 2)	Calibration events (ATI) are shown on the standalone output pin (IO1). During this time, the calibration is active and proximity events during this time may influence the calibration time. The output is enabled by default and can be disabled through this bit				
Sample rate (bit 1:0)	The various sample rates offered are mainly given for the user to determine an ideal balance between power consumption and response time. Overall response times of the IQS231A/B are improved with SAR trigger testing in mind.It is recommended to reduce or disable AC-filtering when using lower power modes to improve reaction time.				





## 10 Full programming reference

A detailed list of the I<sup>2</sup>C registers follows and follows the structure of the memory map summary on page 11.

ADDR	Register name	Bit	Description
ххH	MAIN_EVENTS	7	n/a
		6	
		5	SENSING DISABLED – An indication of forced or implied times
			when no sensing signals are applied to the sense pin. When this
			bit is set and bit 2 is cleared, sensing is disabled. When this bit
		4	and bit 2 is set, sensing is enabled again.
		4	WARM BOOT – A software reset command in register 0x04 will
			lead to a warm boot. This will imply a reset for the user interface and re-calibration will be triggered.
		3	COLD BOOT – A hard reset (power supply cycle) will cause all
		5	registers to return to a default value. This indicator will imply the
			need to re-initialize the device.
		2	RELEASE – A touch, prox or sensing event may be paired with
			a release indication to show an exit of the flagged event.
		1	TOUCH – Disabled by default, this bit will be active when a
			touch and prox user interface is chosen.
		0	PROX - The main feedback bit to indicate an activation
00H	PRODUCT_ NUMBER	n/a	The product number is fixed at 0x40
01H	SOFTWARE_	n/a	The software version is 0x06 for IQS231A
	VERSION		The software version is 0x07 for IQS231B (firmware identical to
			0x06)
02H	DEBUG_	7	n/a
	EVENTS	6	ATI_ERROR – when a recalibration cannot converge, due to
			external tampering or instability, this bit will indicate the error
			and implies that the calibration does not offer optimal sensitivity.
			The PROX event in the main events register will be set along with this bit in such case.
		5	CH0_ATI – An indication that a recalibration of the proximity
		U	sensing channel has occurred. With calibration, the PROX
			output in main events will be set and after calibration, the PROX
			output will release.
		4	n/a
		3	QUICK RELEASE – The quick release feature is a single event
			that is indicated here. This event will always imply an "ENTER
			MOV DETECT", but is not the only event that causes movement
			detection to be activated.
		2	EXIT MOV DETECT – The user interface dictates when the
			movement channel is deactivated. The deactivation of
		1	movement sensing will be reported in this bit. ENTER MOV DETECT – Movement detection is user interface
			dependent and not continually active. Movement detection
			implies that a separate movement channel is activated. This
			activation will be reported in this bit.
		0	MOVEMENT – Each trigger detected by the movement
			algorithm is reported as an event that resets along with each
0011	Deserve		read operation.
03H	Reserved	n/a	
04H	COMMANDS	7	ATI_CH0 – Recalibrate the proximity channel. Only after closing





ADDR	Register name	Bit	Description
			the communications window, a recalibration of the proximity
			sensing electrode will be started.
		6	DISABLE SENSING – Sensing can be disabled to save power
			or synchronize sensing in a more complex system and limit
			certain signals from affecting the measurement.
		5	ENABLE SENSING – Sensing can be enabled at strategic times
			to limit interference in the sensitive measurement environment.
			ENABLE / DISABLE sensing will be reflected in the
			MAIN_EVENTS register. ENABLE sensing will result in a
			"SENSING DISABLED" and "RELEASE" bit being set
		4	simultaneously.
		4	RESERVED
		2	ALUTO ATI toggio op/off
		0	AUTO ATI toggle on/off
		0	SWITCH TO STANDALONE – Triggers a user interface restart in standalone (GPIO) mode while keeping all register changes
			made. Sending the command will execute as soon as the
			communications window is closed.
05H	OTP Bank 1	7	Standalone / I <sup>2</sup> C mode selection including I <sup>2</sup> C address options
		6	(see OTP bank definition)
		Ū	*To switch to standalone mode directly from I <sup>2</sup> C mode
			This powerful feature enables the designer to configure the
			device in I <sup>2</sup> C mode and thereafter reduce the I <sup>2</sup> C overhead and
			related EMI by switching to standalone for runtime. The actual
			mode switch occurs as soon as the communications window is
			closed with a stop command.
			It is recommended to enable the failsafe heartbeat when going
			from I <sup>2</sup> C mode to standalone. The absence of the heartbeat
			should be used to indicate an unexpected reset event, implying
			the need for I <sup>2</sup> C reconfiguration.
		5	Proximity Threshold (low/high) read only
		4	For reading OTP setting only. Note that the actual proximity
			threshold is defined in register 0x0B.
		3	AC Filter (see OTP bank definition)
		2	Touch throshold (read only)
		1 0	Touch threshold (read only) For reading OTP setting only. Note that the actual touch
		0	threshold is defined in register 0x0A.
06H	OTP Bank 2	7	Increase debounce (see OTP bank definition)
		6	Target (see OTP bank definition)
		5	Base value (see OTP bank definition)
		4	
		3	Failsafe (see OTP bank definition)
		2	Quick release (see OTP bank definition)
		1	User interface (see OTP bank definition)
		0	
07H	OTP Bank 3	7	Charge transfer frequency
		6	<b>U U U U U U U U U U</b>
		5	Advanced temperature compensation (see OTP bank definition)
		4	IO2 function (see OTP bank definition)
		3	``´´´
	1	_	
		2	ATI events on IO1 (see OTP bank definition)

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ADDR	Register name	Bit	Description
		0	
08H	QUICK RELEASE	0 7 6 5 4	The OTP options for quick release (see Quick release threshold in OTP Bank 0) is extended in $l^2C$ mode to enable a very specific release characteristic. Quick release threshold look-up table: 0x0 = 150 counts 0x1 = 100 0x2 = 50 0x3 = 250 0x4 = 10 0x5 = 20 0x6 = 25 0x7 = 30 0x8 = 75 0x9 = 200 0xA = 300 0xE = 335 0xF = 500 Quick release beta – This beta value is an indication of the filter strength used to track the characteristic of the release signal. The faster the tracking, the less likely the release will be detected (only very quick events will be detected). The slower the tracking, the more likely the quick release occur (quick events and slow events) will be detected as a quick release) Practical values for the beta range between: 0 (fast events only) and 4 (fast and slow events) The maximum of 0xF is impractical and high values are not recommended.
09H	MOVEMENT	7 6 5 4	MOVEMENT TIME-OUT – Depending on the user interface, a movement detection channel may be started along with specific events (proximity / quick release). The timer is set and cleared as mentioned in Movement time- out (OTP Bank 0). No movement time-out value: 0x0 = 0s 0x1 = 0.5s 0x2 = 1s 0x3 = 2s 0x4 = 4s 0x5 = 5s 0x6 = 10s 0x7 = 20s 0x8 = 30s 0x9 = 1min 0xA = 2min 0xA = 2min 0xC = 10min 0xC = 10min 0xE = 60min 0xF = 90min



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ADDR	Register name	Bit	Description
		3	MOVEMENT THRESHOLD.
		2	Movement threshold = (Value $\times$ 2)
		1	Available range: 0 – 30
		0	For description see Movement threshold in OTP Bank 0.
			Note that the movement threshold in OTP Bank 1 is loaded in
			this register at start up and the OTP setting becomes read only.
			All movement threshold adjustments are performed in this
			register. 0 will cause movement to always trigger.
0AH	TOUCH	n/a	Touch threshold = $(Value \times 4) + 4$
	THRESHOLD		Available range: 4 – 1024
			For details on the touch threshold operation and uses see Touch threshold in OTP Bank 1.
			Note that the touch threshold in OTP Bank 1 is loaded in this
			register at start up and the OTP setting becomes read only. All
			touch threshold adjustments are performed in this register.
0BH	PROXIMITY	7	
	THRESHOLD	6	
		5	Deserved
		4	Reserved
		3	
		2	
		1	Proximity threshold
		0	Available range: $4 - 10$ (IO2 low / I <sup>2</sup> C mode)
			Available range: 8 – 14 (IO2 high)
			For details on the proximity threshold operation and uses see
			Proximity Threshold (low/high) in OTP Bank 1. Note that the proximity threshold in OTP Bank 1 is loaded in this
			register at start up and the OTP setting becomes read only. All
			runtime proximity threshold adjustments are performed in this
			register.
0CH	Temperature &	n/a	0 – 255
	interference		Default 3. Low values are recommended for intended effect.
	tracking		Use a higher value when using the feature in a noisy
	threshold		environment.
0DH	CH0 Multipliers	7	Reserved
		6	
		5 4	CH0 Sensitivity Multiplier (Values: 0 – 3)
		4	
		2	
		1	CH0 Compensation multiplier (Values: 0 – 15)
		0	
0EH	CH0	n/a	0.055
	Compensation		0 – 255
0FH	CH1 Multipliers	7	Reserved
		6	
		5	CH1 Sensitivity Multiplier (Values: 0 – 3)
		4	
		3	
		2	CH1 Compensation multiplier (Values: 0 – 15)
		1	
10	CH1	0	0
10H	CH1 Compensation	n/a	0 – 255
	Compensation	1	

#### **ProxSense<sup>®</sup> Series**





ADDR	Register name	Bit	Description
11H	System flags	7	I <sup>2</sup> C mode active bit
		6	Advanced temperature tracking active
		5	CH1 ACTIVE – Indicates if the movement channel (CH1) is
		5	activated
		4	RESERVED
		3	NO SYNC – no sync input active bit
			CH0 LTA HALTED – Indicates that some proximity shift has
		2	been detected according to the threshold in register 0x05 bit 7.
		~	This event automatically clears if a proximity is not detected
			within t <sub>filter_halt</sub>
			ATI MODE – Indicates that CH0 or CH1 is busy with the
		1	recalibration routine. Read the ATI in flags in register 0x13 for
			more information
			ZOOM MODE – At each threshold of the proximity channel
		0	(proximity & touch threshold), a signal "debounce" is done
			rapidly. During this rapid event, this bit will be set.
12H	UI flags	7	Deserved
		6	Reserved
		5	
		4	Auto-ATI off bit
		3	Sensing disabled indication bit Quick release – Indicates when a quick release action has been
		2	detected
		1	Reserved
		0	Output active – Indicates an active proximity detection
13H	ATI flags	n/a	Reserved
14H	Event flags	11/0	CH1 ATI ERROR – This will indicate that the movement
	_ ronk nago		channel is not operating under optimal sensitivity and the
		7	calibration will automatically be redone in t <sub>redoATI</sub> . The count-
			down time until next attempt can be read in register 0x25 and
			0x26.
		6	Reserved
		5	Reserved
		4	CH1 MOVEMENT
			CH0_ATI ERROR – Because of external interference, strong
			EMI or extreme capacitive load conditions the calibration will not
			be able to reach the target sensitivity (target count – as defined
		3	in register 0x06 bit 6). The proximity output will be set in such
			case in order to fail towards the safe side. The calibration will
			automatically be redone in $t_{redoATI}$ . The count-down time until
			next attempt can be read in register 0x23 and 0x24.
		2	CH0 UNDEBOUNCED – An indication that a proximity event has been detected before a debounce operation has been done.
			CH0_ TOUCH – The touch event is flagged here for the
		1	duration of the touch
		-	CH0_PROX – The proximity event is flagged here for the
		0	duration of the proximity
15H	CH0 ACF_H	n/a	Proximity channel: Filtered count value
16H	CH0 ACF_L	1	0 – 2000
			This count value is related to an offset actual capacitive load.
			The offset is done though calibration and ensures system
			sensitivity.
17H	CH0 LTA_H	n/a	Proximity channel: Reference count value (Long term average)
18H	CH0 LTA_L		0 – 2000



ADDR	Register name	Bit	Description
19H	CH0 QRD_H	n/a	Proximity channel: Quick release detect reference value
1AH	CH0 QRD_L		0 – 2000
1BH	CH1 ACF_H	n/a	Movement channel: Filtered count value
1CH	CH1 ACF_L		0 – 2000
1DH	CH1 UMOV_H	n/a	Movement channel: Upper reference count value
1EH	CH1 UMOV_L		0 – 2000
1FH	CH1 LMOV_H	n/a	Movement channel: Lower reference count value
20H	CH1 LMOV_L		0 – 2000





1 (DFN-10, TSOT23-6, WLCSP-8)

## **11 Specifications**

### **11.1 Absolute maximum ratings**

Absolute maximum parameters specified for the device:

Exceeding these maximum specifications may cause damage to the device.

- Operating temperature IQS231A: -20°C to 85°C • IQS231B: -40°C to 85°C Supply Voltage (VDDHI – VSS) 3.6V • Maximum pin voltage VDDHI + 0.5V (may not . exceed VDDHI max) Maximum continuous current (for specific Pins) 10mA • Minimum pin voltage VSS - 0.5V • 100V/s Minimum power-on slope • **ESD** protection ±8kV (Human body model) •
- Moisture Sensitivity Level (MSL)



DESCRIPTION	Conditions	PARAME TER	MIN	ТҮР	MAX	UNIT
Supply voltage		V <sub>DDHI</sub>	1.764	n/a	3.6	V
Internal regulator output	1.764 ≤ V <sub>DDHI</sub> ≤ 3.6	$V_{REG}$	1.62	1.65	1.72	V
Default Operating Current	3.3V, Scan time = 30ms	IQS231ALP30		33		μA
Full Power Setting	3.3V, Scan time =9ms	I <sub>IQS231AFP</sub>		80		μA
Low Power Setting 1	3.3V, Scan time =128ms	I <sub>IQS231ALP128</sub>		7.5		μA
Low Power Setting 2	3.3V, Scan time =256ms	I <sub>IQS231ALP256</sub>		5		μA

#### Table 11.1 IQS231A/B General Operating Conditions

#### Table 11.2 Start-up and shut-down slope Characteristics

DESCRIPTION	Conditions	PARAMETER	MIN	MAX	UNIT
Power On Reset	V <sub>DDHI</sub> Slope ≥ 100V/s¹	POR <sub>VDDHI</sub>	0.3 <sup>2</sup>	1.7	V
VDDHI Brown Out Detect	V <sub>DDHI</sub> Slope ≥ 100V/s <sup>1</sup>	BOD <sub>VDDHI</sub>	N/A	1.7	V
VREG Brown Out Detect	V <sub>DDHI</sub> Slope ≥ 100V/s¹	BOD <sub>VREG</sub>	N/A	1.58 <sup>3</sup>	V

<sup>&</sup>lt;sup>1</sup>Applicable to full "operating temperature" range

<sup>&</sup>lt;sup>2</sup>For a power cycle, ensure lowering VDDHI below the minimum value before ramping VDDHI past the maximum POR value

<sup>&</sup>lt;sup>3</sup>Figure 3.1 Capacitors C4 & C5 should be chosen to comply with this specification







\*Proximity or touches made during t<sub>stabilize</sub> will not be recognized but rather be part of the calibration.

Figure 11.1 Timing specification during power-on



DESCRIPTION	MIN	TYP	MAX	UNIT
t <sub>init</sub>		15		ms
t <sub>test_mode</sub>		340		ms
tsensing_inactive 30Hz – default	396		436	ms
t <sub>ATI</sub>	41	41	81	ms
t <sub>stabilize</sub> 30Hz – default		340		ms
t <sub>stabilize</sub> 100Hz		128		ms
t <sub>stabilize 8Hz</sub>		1192		ms
t <sub>stabilize</sub> 4Hz		2344		ms
t <sub>comms_timeout</sub>	-	20	-	ms
t <sub>failsafe</sub>		500		us
t <sub>CLK_stretch</sub>		5		ms
t <sub>filter_halt</sub>		5		S
t <sub>redoATI</sub>		10		S
t <sub>awake</sub>		9		ms
R <sub>internal</sub>		20		kΩ
R <sub>I2C_series</sub>			100	Ω
f <sub>sampling</sub>	16.5	500	500	kHz

#### Table 11.3 Various IQS231A/B characteristics

#### Table 11.4 Digital input trigger levels

DESCRIPTION	Conditions	PARAMETER	MIN	MAX	UNIT
All digital inputs	Full VDDHI range	Input low level voltage	0.3 * VDDHI	n/a	V
All digital inputs	Full VDDHI range	Input high level voltage	n/a	0.7 * VDDHI	V

#### Table 11.5 Digital output levels

DESCRIPTION	Conditions	PARAMETER	@1mA*	@10mA*	UNIT
Output voltage low	VDDHI = 3.3V	V <sub>OL</sub>	0.01	0.1	V
Output voltage high	VDDHI = 3.3V	V <sub>OH</sub>	n/a**	n/a**	V

\* Current sinked into output pin

\*\* Only open drain output offered. Pull-up resistor to VDD recommended





## 11.2 I<sup>2</sup>C timing specifications

Table	11.6	I <sup>2</sup> C	timing	limits <sup>4</sup>
-------	------	------------------	--------	---------------------

PARAME	ETER	Standard-mo	ode	Fast-mo	de	UNI
		Min	Max	Min	Max	
VIL	SDA/SCL digital input trigger low- level	-0.5	0.3*VDDHI	-0.5	0.3*VDDHI	V
V <sub>IH</sub>	SDA/SCL digital input trigger high- level	0.7*VDDHI	VDDHI +0.5	0.7*VDDHI	VDDHI +0.5	V
f <sub>SCL</sub>	SCL clock frequency	0	100	0	400	kHz
t <sub>LOW</sub>	LOW period of the SCL clock	4.7		1.3		μs
t <sub>HIGH</sub>	HIGH period of the SCL clock	4		0.6		μs
t <sub>hd,sta</sub>	Hold time (repeated) START	4		0.6		μs
t <sub>su,sta</sub>	Setup time for a repeated START	4.7		0.6		μs
t <sub>HD,DAT</sub>	Data hold time	0		0		μs
t <sub>SU,DAT</sub>	Data setup time	100		100		ns
$t_{VD,DAT}$	Data valid time	0	3.45	0	0.9	μs
t <sub>VD,ACK</sub>	Data valid acknowledge time	0	3.45	0	0.9	μs
t <sub>SU,STO</sub>	Setup time for STOP	4		0.6		μs
t <sub>BUF</sub>	Bus free time between a STOP and START condition	4.7		1.3		μs
tr	Rise time for SDA and SCL		1000		300	ns
t <sub>f</sub>	Fall time for SDA and SCL		300		300	ns
C <sub>b</sub>	Capacitive load for each bus line		400		400	
t <sub>SP</sub>	Pulse duration of spikes suppressed by input filter	No noise	pulse suppres	ssion filter im	plemented	ns
t <sub>WDT</sub>	Clock low time-out (watchdog)	130	140	130	140	ms





 $<sup>^{\</sup>rm 4}$  Applicable over the full temperature range at VDDHI = 3.3V





## **12 Package information**

The device is available in three packages: TSOT23-6, DFN-10 & WLCSP-8.

### 12.1 TSOT23-6





Figure 12.1 TSOT23-6 Packaging<sup>5</sup>

#### Table 12.1 TSOT23-6 Dimensions

Dimension	Min (mm)	Max (mm)	
А	2.60	3.00	
В	1.50	1.70	
С	2.80	3.00	
D	0.30	0.50	
Е	0.95 Basic		
F	0.84	1.00	
G	0.00	0.10	
Н	0.30	0.50	
I	0°	8°	
J	0.03	0.20	

<sup>&</sup>lt;sup>5</sup> Drawing not on Scale







Figure 12.2 DFN-10 Package dimensions (bottom view) Table 12.2 DFN-10 Package dimensions (bottom)

Dimension	[mm]
А	3 ±0.1
В	0.5
С	0.25
D	n/a
F	3 ±0.1
L	0.4
Р	2.4
Q	1.65

#### Table 12.3 DFN-10 Package dimensions (side)

Dimension	[mm]
G	0.05
н	0.65
I	0.7-0.8







Figure 12.3 DFN-10 Package dimensions (side)



Figure 12.4 Recommended DFN-10 Landing dimensions

Dimension	[mm]	
А	2.4	
В	1.65	
С	0.8	
D	0.5	
E	0.3	
F	3.2	

#### Table 12.4 DFN-10 Landing dimensions





### 12.3 WLCSP-8





Dimensional Ref.						
REF.	Min.	No <b>m</b> .	Max.			
А	0.310	0.350	0.390			
A1	0.085	0.100	0.115			
A2	0.225	0.250	0.275			
D	0.865	0.880	0.895			
E	1.455	1.470	1.485			
D1	0.300	0.350	0.400			
E1	1.000	1.050	1.100			
Ь	0.125	0.150	0.175			
е	0	.350 BS	C			
SD	0	.175 BS	С			
SE	0.175 BSC					
Tol. of Form&Position						
ааа	0.10					
ЬЪЬ	0.10					
CCC	0.05					
ddd	0.05					

SEATING PLANE

Figure 12.5 IQS231A WLCSP-8 dimensions (in mm)





## **13 Ordering and Part-number Information**

### **13.1 Ordering Information**

Please check stock availability with your local distributor.



IC NAME	231A	=	IQS231A
	231B	=	IQS231B
CONFIGURATION	zzz zzz zz	=	IC configuration (hexadecimal)
			Default 000 000 00 (other configurations
			available on special request)
PACKAGE TYPE	DN	=	DFN(3x3)-10 (IQS231A only)
	TS	=	TSOT23-6 package
	CS	=	WLCSP-8 package
BULK PACKAGING	R	=	Reel (3000pcs/reel) – MOQ = 3000pcs
			MOQ = 1 reel (orders shipped as full reels)

**13.2 Device Numbering Convention – TSOT23-6** 

Тор



**Bottom** 







## 13.3 Device numbering convention: 8-pin WLCSP





#### **Bottom**

No marking present

### **13.4 Device Numbering Convention – DFN10**

Azoteq ABC DE			
DEVICE NAME	Α	=	IQS231A
REVISION	В	=	v (IC Version Number)
TEMPERATURE RANGE	С	=	t (-20°C to 85°C)
DATE CODE	D	=	p (Internal use)
	Е	=	wwyy (Batch number)
PIN 1 MARKING	F	=	Dot to indicate pin 1



# 14 Tape and reel information





#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



Device	Package Type	Package Drawing	Dine	per	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
Device	Type	Drawing	FIIIS	Teer	(1111)	••••	(1111)	(11111)	(1111)	(1111)	(1111)	Quadrant
IQS231AzzzzzzzTSR	TSOT23/6	TSOT23-6	6	3000	178	9.5	3.1	3.1	1.3	4	8	Q3
IQS231BzzzzzzzTSR	TSOT23/6	TSOT23-6	6	3000	178	9.5	3.1	3.1	1.3	4	8	Q3
IQS231AzzzzzzzDNR	DFN10	DFN-10	10	3000	330	12.4	3.3	3.3	1.1	8	12	Q1
IQS231AzzzzzzZCSR	WLCSP8	WLCSP-8	8	3000	179	8.4	1	1.55	0.48	4	8	Q3
IQS231BzzzzzzzCSR	WLCSP8	WLCSP-8	8	3000	179	8.4	1	1.55	0.48	4	8	Q3





# 15 Revision History

Revision Number	Description	Date of issue
v1.0	IC release version	16 March 2016
V1.1	TSOT23-6 package added BOD and POR values updated	18 July 2016
V1.2	Reference schematic updated. Component selection guide also included	8 September 2016
V1.3	Introduction added to first page Start-up and ATI time description added	13 December 2016
V1.4	Switch from I2C to standalone mode information updated	10 February 2017
V1.5	WLCSP package information added	13 March 2017
V1.6	Proximity threshold options in I <sup>2</sup> C mode corrected Commands updated to include "Auto ATI on/off" Temperature compensation feature renamed to include the detection of radiated and conducted interference "I2C and sensing timing" section added. Schematics updated with recommended components.	18 July 2017
V1.7	Movement threshold option in I <sup>2</sup> C mode errata Capacitive resolution and load capability added to introduction page WLCSP package pin 5 recommendation	4 September 2017
V1.8	Added functional block diagram with basic function descriptions Added warning to section 4 OTP table when using the most sensitive settings. Updated and added AC filter information to section 9.2 Added section 8.8 & 8.9 with timing accuracy information Bottom marking changes for new device versions: see product change notices IQS231A minimum temperature has changed from -40°C to -20°C	10 November 2017
V2.0	IQS231B TSOT23-6 option added	28 May 2019
V2.2	Tape and reel information added	9 January 2020
V2.3	IQS231B WLCSP details added	22 January 2020





Appendix A	<b>Contact Information</b>	
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	USA	Asia	South Africa
Physical Address	6507 Jester Blvd Bldg 5, suite 510G Austin TX 78750 USA	Rm2125, Glittery City Shennan Rd Futian District Shenzhen, 518033 China	1 Bergsig Avenue Paarl 7646 South Africa
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Please visit www.azoteq.com for a list of distributors and worldwide representation.

The following patents relate to the device or usage of the device: US 6,249,089 B1; US 6,621,225 B2; US 6,650,066 B2; US 6,952,084 B2; US 6,984,900 B1; US 7,084,526 B2; US 7,084,531 B2; US 7,265,494 B2; US 7,291,940 B2; US 7,329,970 B2; US 7,336,037 B2; US 7,443,101 B2; US 7,466,040 B2 ; US 7,498,749 B2; US 7,528,508 B2; US 7,755,219 B2; US 7,772,781 B2; US 7,781,980 B2; US 7,915,765 B2; US 7,994,726 B2; US 8,035,623 B2; US RE43,606 E; US 8,288,952 B2; US 8,395,395 B2; US 8,531,120 B2; US 8,659,306 B2; US 8,823,273 B2; EP 1 120 018 B2; EP 1 206 168 B1; EP 1 308 913 B1; EP 1 530 178 A1; EP 2 351 220 B1; EP 2 559 164 B1; CN 1330853; CN 1783573; AUS 761094; HK 104 1401

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