
Si114x MULTI-FUNCTION KIT USER'S GUIDE

1. Kit Contents

The Si114x Multi-Function Kit contains the following items:

- Si114x Multi-Function Board
- Si114x-MFB Quick Start Guide
- 2 USB Cables

2. Introduction

The Si114x-MFB is intended as an evaluation and development platform for the Si1143 infrared proximity and ambient light sensor. The board has two sides which are separate systems that only share communications and debug connections to the PC. The active side is chosen using the hardware switch S1, shown in Figure 1. When the switch is in the upward position, the Top-Side is the active side while the Bottom-Side is active when S1 is in the downward position. As shown on the left side of Figure 1, the main components of the top side of the Si114x multi-function board (Si114x-MFB) are the Si1143 sensor (U4), the C8051F931 microcontroller (U1), and the infrared emitters (DS2 through DS4). On this PCB, the infrared emitters used are OSRAM part number SFH 4056. These emitters have a power rating of 40 mW and a half-angle of 22 degrees. As shown on the right side of Figure 1, the main components of the bottom side of the Si114x-MFB are the Si1143 sensor (U6), the C8051F931 microcontroller (U5), and the infrared emitter DS5. This emitter is OSRAM part number SFH 4650 and has a power rating of 45 mW and a half-angle of 15 degrees. Other emitters with different characteristics may also be used, depending on the specific application requirements.

The example firmware for the top-side of the board is a thumb-scroll implementation that measures the infrared light energy detected by the Si1143 while each of three infrared emitters are independently activated. The infrared light from these emitters will be reflected back to the Si1143 by a thumb that is swiped in proximity to the sensor. The firmware is able to detect different gestures using the infrared sensor, as described in Table 3 on page 10. The nine LEDs DS8-DS16 will change state to indicate what gesture was recognized. The Si1143's ambient light sensor (ALS) is also monitored by the firmware. The example firmware is intended to be used in conjunction with the QuickSense™ Performance Analysis Tool to provide user feedback.

The example firmware on the bottom-side of the board is a long-range implementation that measures the infrared light energy detected by the Si1143 while a single infrared emitter is activated. All three of the Si1143's LED drivers are connected to the one emitter to allow multiple drivers to activate the emitter at the same time in order to send more current through the emitter than one driver can provide. Driving more current through the emitters can help achieve longer ranges of detection because the infrared LEDs emit more light with more current. The default firmware only uses one driver at the default pulse width to drive the LED. The five LEDs DS17-DS21 will change state to indicate how much infrared light feedback is being measured. The Si1143's ambient light sensor (ALS) is also monitored by the firmware. The example firmware is intended to be used in conjunction with the QuickSense™ Performance Analysis Tool to provide user feedback.

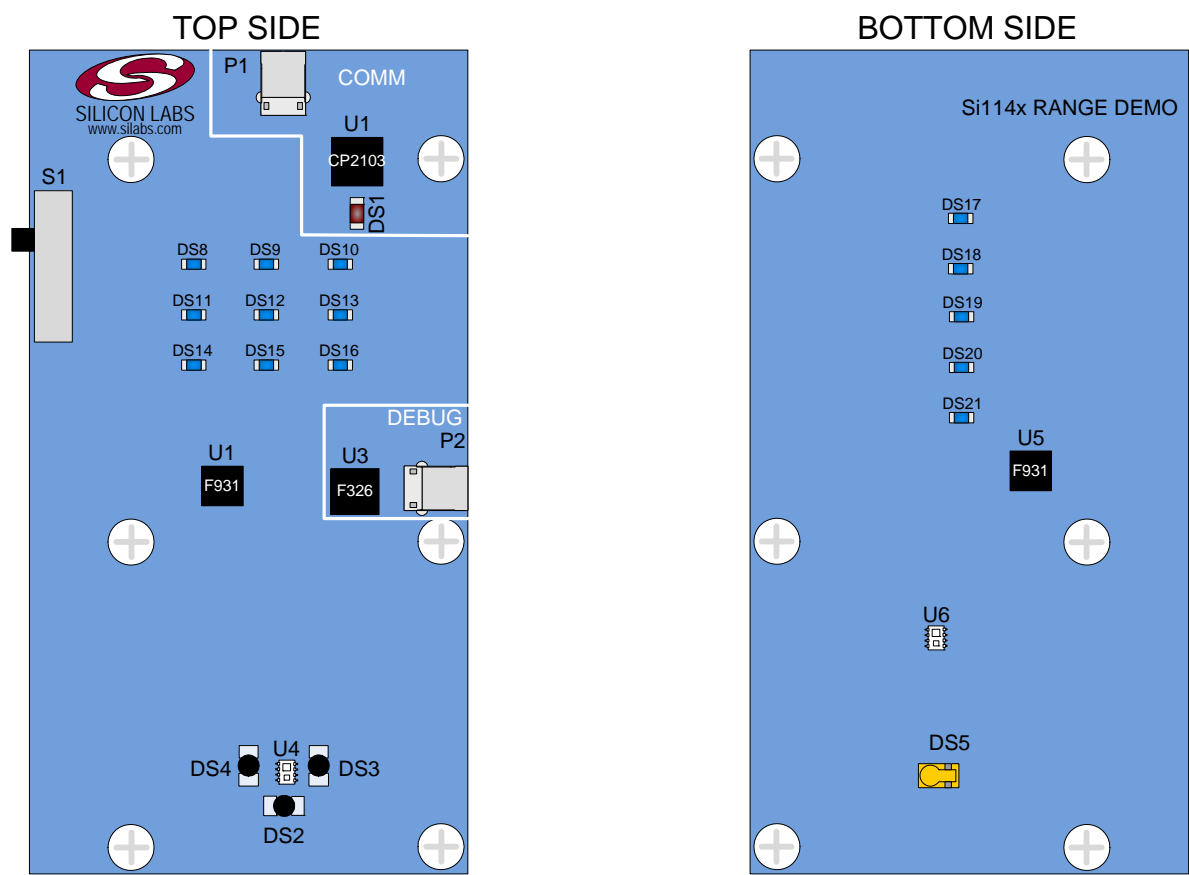


Figure 1. Si1143 Evaluation Board

3. Software Overview

There are several optional software packages available to support the Si114x Multi-Function Kit. QuickSense™ Studio contains the Performance Analysis Tool, which can be used to collect data from the board over the USB interface and display it graphically. The Silicon Labs Integrated Development Environment (IDE) provides a means of developing code for the C8051F931 and uses the USB DEBUG connection on the board to program the MCU and perform in-system debugging. For users wishing to modify the example code or download the latest version of firmware into the board, the Si114x Multi-Function Kit installation package contains board-specific materials, such as the latest version of the pre-built firmware .HEX image and the firmware example source code. All of the supporting software can be downloaded from the web at the URL <http://www.silabs.com/quicksense>.

3.1. QuickSense Studio

The QuickSense Studio software facilitates rapid code development and analysis for applications using the Silicon Labs family of QuickSense products. QuickSense Studio is comprised of multiple programs that guide users through an intuitive development flow, including graphical configuration wizards, firmware templates, and performance monitoring tools. These programs interface with the QuickSense Firmware API, a highly-configurable open-source firmware library that provides support for many different applications, from simple buttons to complex algorithms like gesture recognition. The main component of QuickSense Studio that is used by the Si114x Multi-Function Kit is the Performance Analysis Tool, which is described in more detail in “4. Using the Si114x-MFB with the Performance Analysis Tool”.

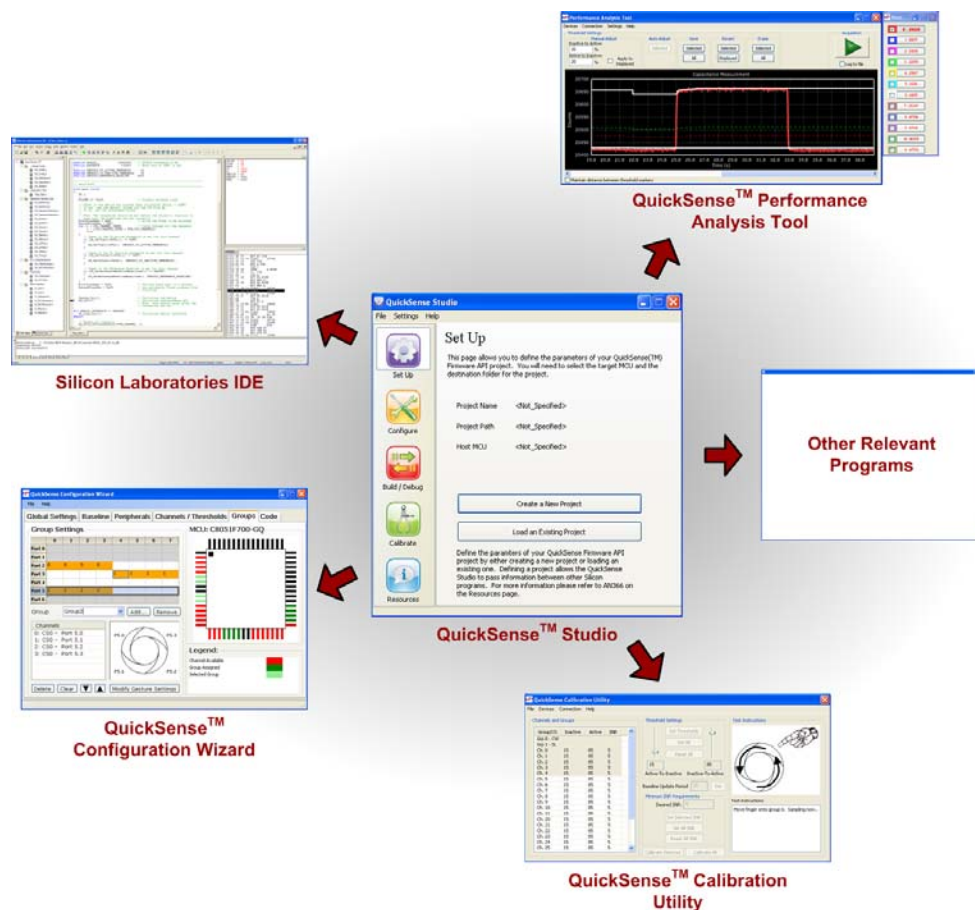


Figure 2. Silicon Labs QuickSense Studio Software

For detailed information on the QuickSense Studio software, see the QuickSense Studio User's Guide available on the Silicon Labs QuickSense webpage (<http://www.silabs.com/quicksense>) in the QuickSense Studio section.

3.2. Silicon Laboratories IDE

The Silicon Laboratories IDE integrates a source-code editor, a source-level debugger, and an in-system flash programmer. This tool can be used to develop and debug code for the C8051F931 MCUs which are included on the Si114x Multi-Function Board. The use of several third-party compilers and assemblers is supported by the IDE.

3.2.1. IDE System Requirements

The Silicon Laboratories IDE requirements:

- Pentium-class host PC running Microsoft Windows 2000 or newer.
- Two available USB ports.

3.2.2. Third Party Toolsets

The Silicon Laboratories IDE has native support for many 8051 compilers. The full list of natively supported tools is as follows:

- Keil
- IAR
- Raisonance
- Tasking
- SDCC

3.2.3. Downloading the Example Firmware Image

The Si114x Multi-Function Board installer package includes the firmware source code as well as a pre-built .HEX image that can be downloaded directly into the board. The firmware source code and an example IDE project is located in the default path `C:\SiLabs\MCU\QuickSense_Studio\Kits\Si114xMFB\Firmware\Top-Side\` for the top-side thumb-scroll code or `\Bottom-Side\` for the bottom-side ranged code. The pre-built .HEX images are located in the default path `C:\SiLabs\MCU\QuickSense_Studio\Kits\Si114xMFB\Firmware\Release\`. Follow the instructions below to update or refresh the .HEX image in the Si114x Multi-Function Board:

1. Connect the Si114x Multi-Function Board to the PC through both USB ports on the board. The connector labeled COMM will provide power to the board while the connector labeled DEBUG will allow programming.
2. Launch the Silicon Labs IDE, and click on *Options->Connection Options*.
3. Select "USB Debug Adapter", and then select the board from the list (it should show up as "TS" followed by a serial number).
4. Select "C2" as the debug interface, and press "OK".
5. Connect to the board by pressing the "Connect" icon or by using the keyboard shortcut, Alt+C.
6. Click on the "Download" icon, or use the keyboard shortcut Alt+D.
7. In the download dialog window, click "Browse".
8. Change to Files of Type "Intel Hex (*.hex)" and then browse to select the file, Top-Side.hex or Bottom-Side.hex, in the default path: `C:\SiLabs\MCU\QuickSense_Studio\Kits\Si114xMFB\Firmware\Release\`
9. Click "Open" then "Download".
10. To run the new image, either press "Run" or "Disconnect" in the IDE.

4. Using the Si114x-MFB with the Performance Analysis Tool

The Si114x Multi-Function Board is supported by the QuickSense Performance Analysis Tool. The Performance Analysis Tool allows users to see real-time infrared proximity and ambient light measurements from the Si1143 in a graphical form. The communications interface to the Si114x Multi-Function Board is provided over the USB connection via the QuickSense Firmware API. For a more detailed description of the QuickSense Firmware API or the Serial Interface, see “AN366: QuickSense™ Firmware API.”

To use the Performance Analysis Tool with the Si114x Multi-Function Board:

1. Connect the Si114x Multi-Function Board to the PC using a cable plugged into the COMM USB port.
2. Launch the Performance Analysis Tool from QuickSense Studio or from the Start menu.
3. Select the board from the “Devices” menu (typically either COM3 or COM4 depending on your system).
4. Select the channels you wish to display on the picture of the slider board that appears. The individual channels available are described in “4.1. Channel Selection”.
5. Click the green “Acquisition” arrow to begin collecting data

Figure 3 shows an example of the Performance Analysis Tool output when connected to the Si114x Multi-Function Board. To generate the graph, a thumb was moved above the thumb-scroll side of the board. The selected traces shown are the raw data measurements for the amount of Infrared light being reflected onto the part. The pink trace represents the proximity measurements from infrared emitter DS3; the green trace represents the measurements from infrared emitter DS4, and the yellow trace represents the measurements from infrared emitter DS2.

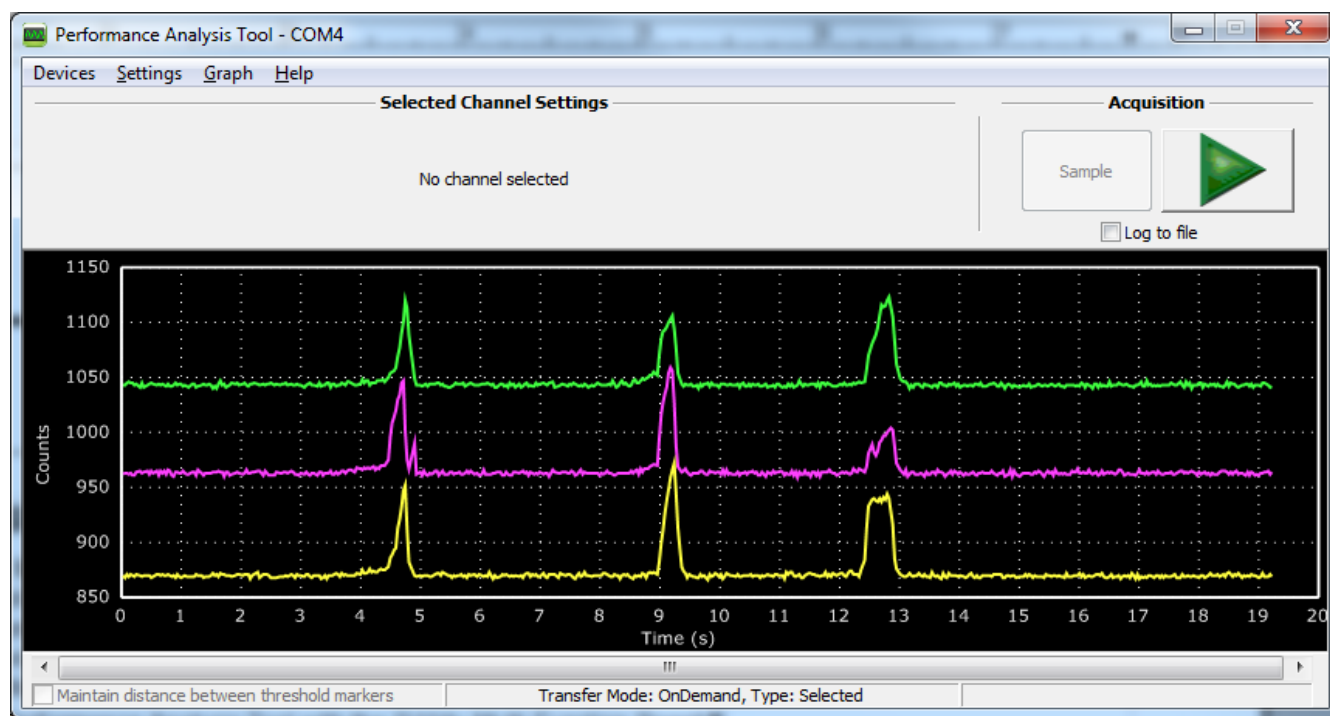


Figure 3. Performance Analysis Tool Main Window

Si114x-MFB

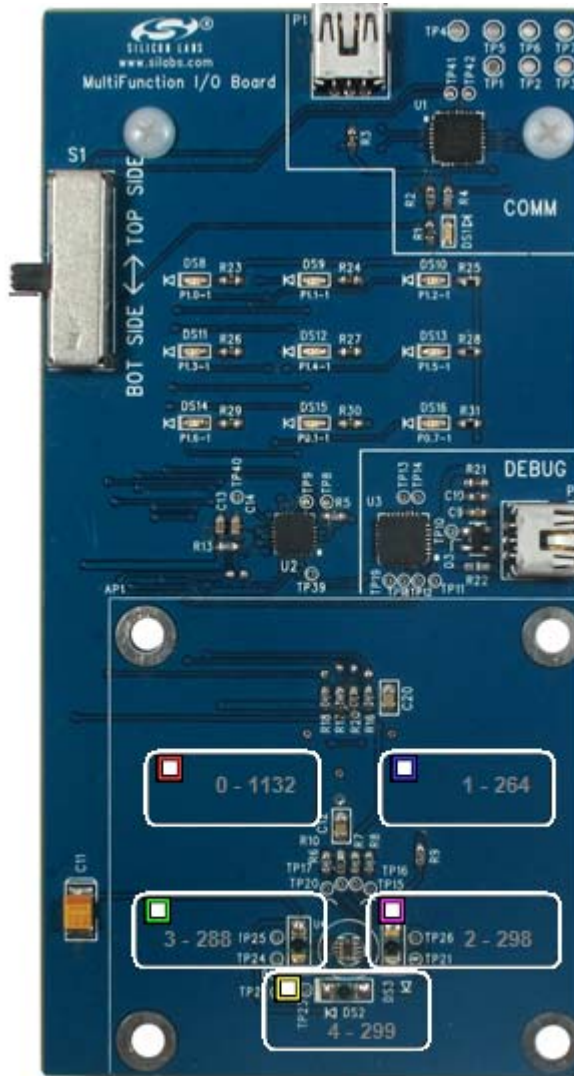
4.1. Channel Selection

Selecting which channels to display is done by checking the appropriate boxes on the Board Representation window, shown in Figure 4, and the Generic Data window, shown in Figure 5. There are two different groups of measurements available from the example firmware: raw data channels and generic data channels.

4.1.1. Raw Data Channels

The raw data measurements can be seen by selecting the channels from the Board Representation window, shown in Figure 4. The two types of raw data measurements are ambient light and infrared proximity.

1. Raw ambient light measurements. The ambient light channels are Channel 0 (red) and Channel 1 (blue). Channel 0 displays measurements of the ambient visible light while Channel 1 displays measurements of the ambient infrared light.
2. Raw infrared proximity measurements. The infrared proximity channels are Channel 2 (pink) readings using DS3, Channel 3 (green) readings using DS4, and Channel 4 (yellow) readings using DS2. Channels 3 and 4 will not be available for the Bottom-Side since it is a single LED implementation. The output is proportional to the amount of infrared light being reflected onto the part by an object above the board. These outputs are 16-bit unsigned values.



Top-Side



Bottom-Side

Figure 4. Raw Data Channel Selection

4.1.2. Generic Data Channels

The generic data channels contain any data generated by the host MCU. These 16-bit channels can be anything from simple debug channels to calculated position values. See Table 1 or Table 2 for an explanation of all the channels shown in Figure 5.



Figure 5. Generic Data Channel Selection

Table 1. Generic Data Channels—Top-Side Thumb-Scroll Application

Name	Label	Type	Description
G0	Mid 1	Midpoint Timestamps	The firmware records the timestamps for the entry and exit times of your thumb across each LED. Then a midpoint is calculated between these points, and the timing between these midpoints is used to determine gestures.
G1	Mid 2		
G2	Mid 3		
G3	MdAvg	Midpoint Average	If all three midpoints are very close to the average of all three, then a tap gesture is detected.
G4	N/A	Unused channels	The unused channels are not in use by software, but they are available in firmware to use as needed.
G5	N/A		
G6	iLED1	LED Drive Current Levels	Each LED driver has a specific LED drive current setting for it. These values are given in units of mA.
G7	iLED2		
G8	iLED3		
G9	VIS	AutoRanging Ambient Outputs	AutoRanging will automatically change the modes of the photodiodes to avoid saturation. When changing modes, the raw data output changes levels, but AutoRanging will scale the raw data so that all measurements are on the same scale. The output from this channel is the processed value which can be used without knowledge of the photodiode modes.
G10	IR		
G11	PS1	AutoRanging PS Outputs	These channels are the AutoRanging PS output from the device. Raw data measurements are processed by the AutoRanging firmware to make all the readings across different modes have the same magnitude. Since the device switches modes to compensate for ambient light, the raw data will show jumps when changing modes. These outputs will not display the jumps because the firmware is stitching the raw outputs together.
G12	PS2		
G13	PS3		
G14	VIS s	State of Ambient Visible System	These channels help indicate what mode the sensor is in during each of their respective measurements. The four possible modes are as follows: Low Light, High Sensitivity, High Signal, and Sunlight. These modes are numbered from zero to three. For more information about each mode, please consult the data sheet.
G15	IR st	State of Ambient IR System	
G16	PS st	State of PS System	
G17	PS1bl	PS Baseline Levels	AutoRanging uses baselining to determine the no-detect threshold for readings. Any readings below the values shown on these channels will be considered no-detect readings. Any values higher than this baseline will be shown in the AutoRanging PS Outputs above.
G18	PS2bl		
G19	PS3bl		
G20	N/A	Unused by PAT	These channels are reserved for use by the Si1140 Control Panel.
G21	N/A		

Table 2. Generic Data Channels—Bottom-Side Ranging Demo

Name	Label	Type	Description
G0	Avg	Average of PS1	The average of PS1 is more stable and allows for smaller thresholds for long-range detection.
G1	Thr	Detection Threshold	A detect is triggered when the Avg exceeds the Thr.
G2	iLED1	LED Drive Current Level	The LED driver has a specific LED drive current setting for it. This value is given in units of mA.
G3	VIS	AutoRanging Ambient Outputs	AutoRanging will automatically change the modes of the photodiodes to avoid saturation. When changing modes, the raw data output changes levels, but AutoRanging will scale the raw data so that all measurements are on the same scale. The output from this channel is the processed value which can be used without knowledge of the photodiode modes.
G4	IR		
G5	PS1	AutoRanging PS Output	This channel is the AutoRanging PS output from the device. This output helps compensate for the affects of high changes in ambient light levels.
G6	VISst	State of Ambient Visible System	These channels help indicate what mode the sensor is in during each of their respective measurements. The four possible modes are as follows: Low Light, High Sensitivity, High Signal, and Sunlight. These modes are numbered from zero to three. For more information about each mode, please consult the data sheet.
G7	IRst	State of Ambient IR System	
G8	PSst	State of PS System	
G9	PS1bl	PS Baseline Levels	AutoRanging uses baselining to determine the no-detect threshold for readings. Any readings below the values shown on these channels will be considered no-detect readings. Any values higher than this baseline will be shown in the AutoRanging PS Outputs above. For this Ranging application, this baseline algorithm is bypassed to allow for the main Ranging algorithm to perform its own form of baselining.
G10	BLVal	Baseline Value	The Bottom-Side Ranging algorithm has its own baselining algorithm that baselines on the Avg (G0) channel. This channel is the current value that the baseline is set to.
G11	BLcnt	Baseline Counter	The baselining algorithm picks a rolling maximum value from Avg (G0) and tests to see if that value can be used as the new baseline. This is the Baseline Test Value. If the Avg does not stray too far away from the BLtst value for 40 samples in a row, this BLtst value will become the new Baseline Value. The sample counter is on G11 as the Baseline Counter value.
G12	BLtst	Baseline Test Value	
G13	N/A	Unused by PAT	These channels are reserved for use by the Si1140 Control Panel.
G14	N/A		

4.2. Gesture Sensing

In addition to infrared and ambient light measurements, the example firmware for the top side contains algorithms for gesture recognition. When connected to the board with the Performance Analysis Tool, a group window will appear, as shown in Figure 6. When a gesture is recognized by firmware, the gesture name and parameter information will be added to the top of the 3D Gesture group. Five gestures are supported by the example code. The parameters for each gesture are listed in Table 3.

To use the thumb-scroll gestures with high accuracy, the user must be sure to swipe the thumb by starting outside of the orange box on the overlay and swiping across the box and exiting the orange box on the opposite side. The thumb should be lain flat such that the thumb creates the most surface area on the glass. For a Tap gesture, the thumb should enter and exit as straight as possible along the axis which is normal to the surface of the overlay. If a Tap is attempted and the thumb exits at an off-angle, the Tap might be identified as a swipe.

The speed of the swipe can be determined by the Duration value in the Group Window below. The user should be weary that very fast swipes have a higher chance of being recognized incorrectly, and very slow swipes might not be recognized as a gesture because the firmware caps the duration at 255 counts. Each count represents 1.6 ms.

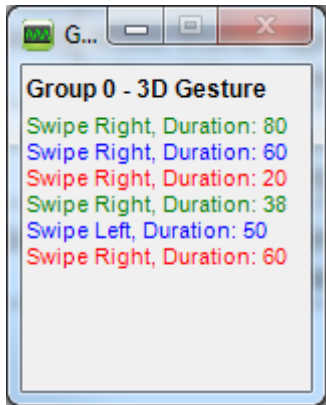


Figure 6. Performance Analysis Tool Group Window

Table 3. Recognized Gestures

Gesture Name	Parameter	Parameter Range	Description of Action
Swipe Left	Duration	1 255 (Fast to Slow)	Move thumb from the right edge to the left edge of the orange square on the overlay.
Swipe Right	Duration	1 255 (Fast to Slow)	Move thumb from the left edge to the right edge of the orange square on the overlay.
Swipe Up	Duration	1 255 (Fast to Slow)	Move thumb from the bottom edge to the top edge of the orange square on the overlay.
Swipe Down	Duration	1 255 (Fast to Slow)	Move thumb from the top edge to the bottom edge of the orange square on the overlay.
Tap	Duration	1 255 (Fast to Slow)	Move thumb from high above the overlay onto the center of the orange square and retract.

Figure 7. Si1143 Evaluation Board Schematic (1 of 3)

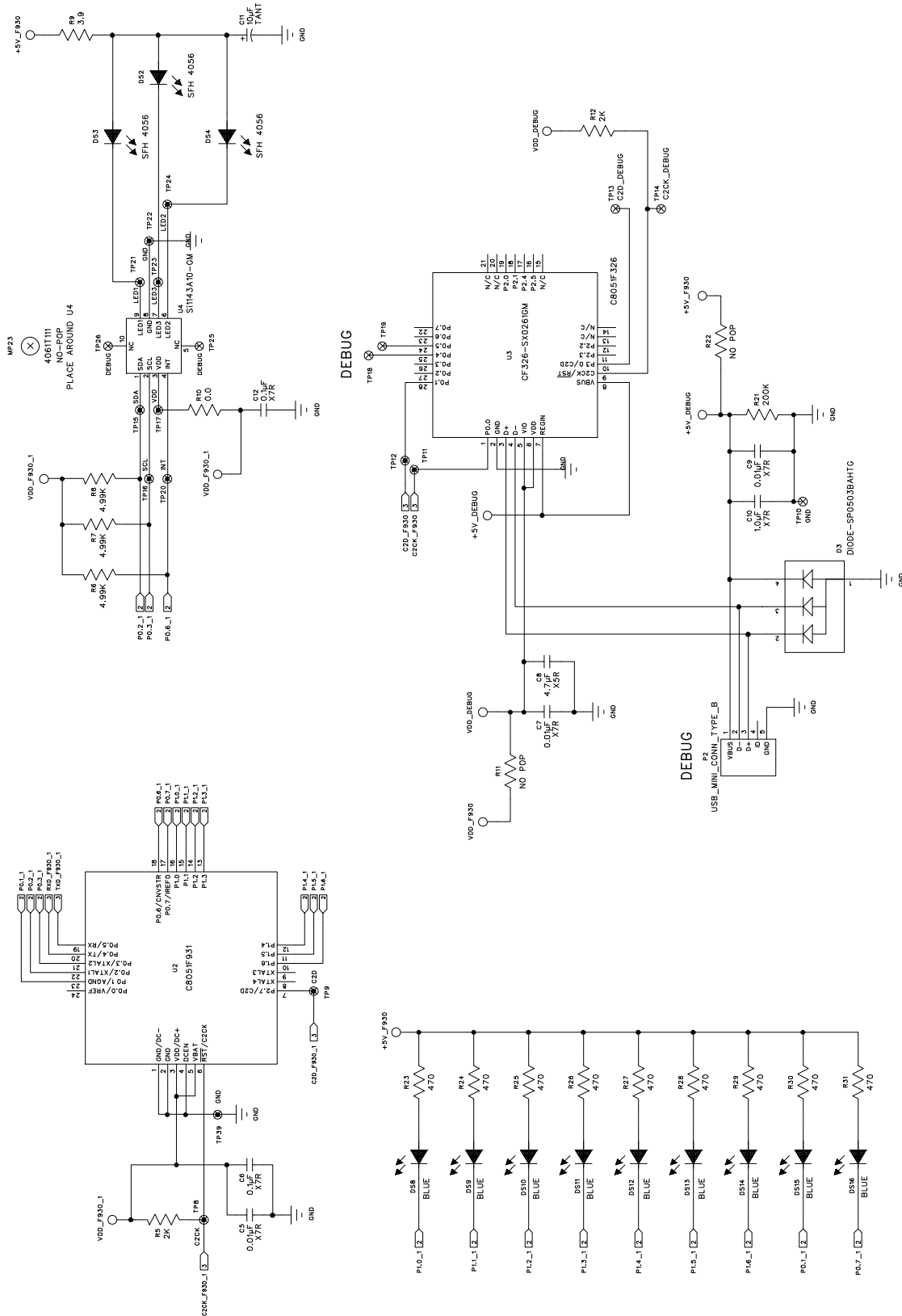


Figure 8. Si1143 Evaluation Board Schematic (2 of 3)



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