

Four-channel Power/Energy IC

Features

- Energy Linearity: $\pm 0.1\%$ of Reading over 1000:1 Dynamic Range
- On-chip Functions:
 - Voltage and Current Measurement
 - Active, Reactive, and Apparent Power/Energy
 - RMS Voltage and Current Calculations
 - Current Fault and Voltage Sag Detection
 - Calibration
 - Phase Compensation
 - Temperature Sensor
 - Energy Pulse Outputs
- Meets Accuracy Spec for IEC, ANSI, & JIS
- Low Power Consumption
- Voltage Tamper Correction
- Ground-referenced Inputs with Single Supply
- On-chip 2.5 V Reference (40 ppm / °C typ.)
- Power Supply Monitor Function
- Three-wire Serial Interface to Microcontroller or E²PROM
- Power Supply Configurations
GND: 0 V, VA+: +5 V, VD+: +3.3 V to +5 V

Description

The CS5467 is a watt-hour meter on a chip. It measures line voltage and current and calculates active, reactive, apparent power, energy, power factor, and RMS voltage and current.

An internal RMS voltage reference can be used if voltage measurement is disabled by tampering.

Four $\Delta\Sigma$ analog-to-digital converters are used to measure two voltages and two currents. Optionally, voltage2 channel can be used for temperature measurement.

The CS5467 is designed to interface to a variety of voltage and current sensors.

Additional features include system-level calibration, voltage sag and current fault detection, peak detection, phase compensation, and energy pulse outputs.

ORDERING INFORMATION

See [Page 45](#).

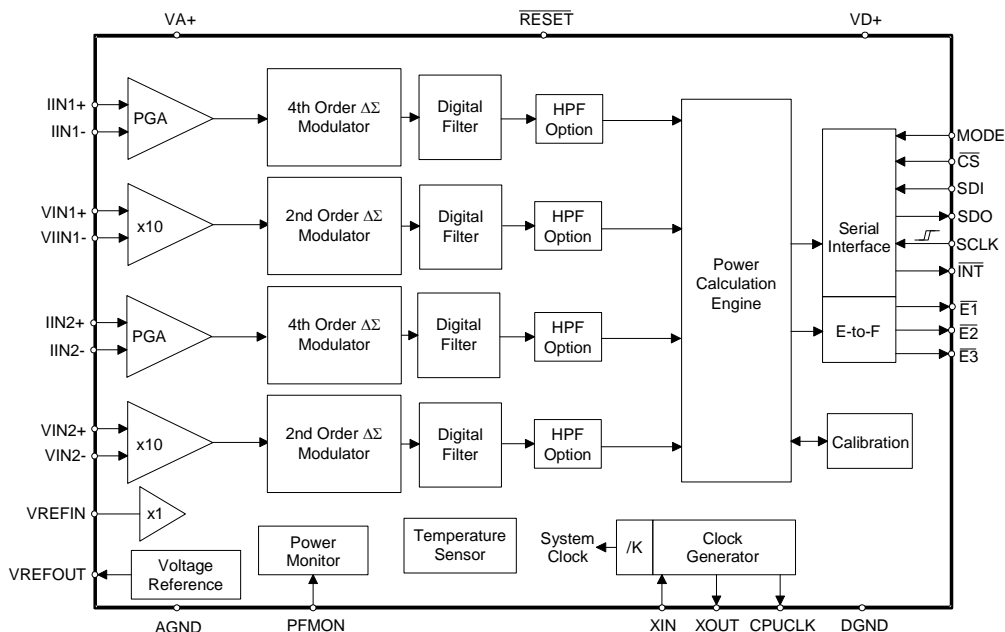


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1. OVERVIEW

The CS5467 is a CMOS power measurement integrated circuit utilizing four $\Delta\Sigma$ analog-to-digital converters to measure two line voltages and two currents. Optionally, voltage2 channel can be used for temperature measurement. It calculates active, reactive, and apparent power as well as RMS and peak voltage and current. It handles other system-related functions, such as pulse output conversion, voltage sag, current fault, voltage zero crossing, line frequency, and voltage tamper correction.

The CS5467 is optimized to interface to current transformers or shunt resistors for current measurement, and to resistive dividers or voltage transformers for voltage measurement. Two full-scale ranges are provided on the current inputs to accommodate both types of current sensors. The CS5467's four differential inputs have a common-mode input range from analog ground (AGND) to the positive analog supply (VA+).

An additional analog input (PFMON) is provided to allow the application to determine when a power failure is in progress. By monitoring the unregulated power supply, the application can take any required action when a power loss occurs.

An on-chip voltage reference (nominally 2.5 volts) is generated and provided at analog output, VREFOUT. This reference can be supplied to the chip by connecting it to the reference voltage input, VREFIN. Alternatively, an external voltage reference can be supplied to the reference input.

Three digital outputs ($\overline{E1}$, $\overline{E2}$, $\overline{E3}$) provide a variety of output signals and, depending on the mode selected, provide energy pulses, power failure indication, or other choices.

The CS5467 includes a three-wire serial host interface to an external microcontroller or serial E²PROM. Signals include serial data input (SDI), serial data output (SDO), serial clock (SCLK), and optionally a chip select (\overline{CS}), which allows the CS5467 to share the SDO signal with other devices. A MODE input is used to control whether an E²PROM will be used instead of a host microcontroller.

2. PIN DESCRIPTION

| | | | | | |
|----------------------------|----------------|-----|------|--------------|----------------------------|
| Crystal Out | XOUT | 1 ● | 28 □ | XIN | Crystal In |
| CPU Clock Output | CPUCLK | 2 | 27 | SDI | Serial Data Input |
| Positive Digital Supply | VD+ | 3 | 26 | E2 | Energy Output 2 |
| Digital Ground | DGND | 4 | 25 | E1 | Energy Output 1 |
| Serial Clock | SCLK | 5 | 24 | INT | Interrupt |
| Serial Data Output | SDO | 6 | 23 | RESET | Reset |
| Chip Select | CS | 7 | 22 | E3 | Energy Output 3 |
| Mode Select | MODE | 8 | 21 | PFMON | Power Fail Monitor |
| Differential Voltage Input | VIN1+ | 9 | 20 | IIN1+ | Differential Current Input |
| Differential Voltage Input | VIN1- | 10 | 19 | IIN1- | Differential Current Input |
| Voltage Reference Output | VREFOUT | 11 | 18 | VA+ | Positive Analog Supply |
| Voltage Reference Input | VREFIN | 12 | 17 | AGND | Analog Ground |
| Differential Voltage Input | VIN2+ | 13 | 16 | IIN2+ | Differential Current Input |
| Differential Voltage Input | VIN2- | 14 | 15 | IIN2- | Differential Current Input |

Clock Generator

| | | |
|-------------------------|------|---|
| Crystal Out | 1,28 | XOUT, XIN — Connect to an external quartz crystal. Alternatively, an external clock can be supplied to the XIN pin to provide the system clock for the device. |
| CPU Clock Output | 2 | CPUCLK — Logic-level output from crystal oscillator. Can be used to clock an external CPU. |

Control Pins and Serial Data I/O

| | | |
|---------------------------|------------|---|
| Serial Clock | 5 | SCLK — Clocks serial data from the SDI pin and to the SDO pin when \overline{CS} is low. SCLK is a Schmitt-trigger input when MODE is low and a driven output when MODE is high. |
| Serial Data Output | 6 | SDO — Serial data output. Data is clocked out by SCLK. |
| Chip Select | 7 | CS — An input that enables the serial interface when MODE is low and a driven output when MODE is high. |
| Mode Select | 8 | MODE — High selects external E ² PROM, Low selects external microcontroller. MODE includes a weak internal pull-down and therefore selects microcontroller mode if not connected. |
| Energy Output | 22, 25, 26 | E3, E1, E2 — Primarily active-low energy pulse outputs. These can be programmed to output other conditions. |
| Reset | 23 | RESET — An active-low Schmitt-trigger input used to reset the chip. |
| Interrupt | 24 | INT — Active-low output, indicates that an enabled condition has occurred. |
| Serial Data Input | 27 | SDI — Serial data input. Data is clocked in by SCLK. |

Analog Inputs/Outputs

| | | |
|------------------------------------|-----------------|---|
| Differential Voltage Inputs | 9,10 13, 14 | VIN1+, VIN1-, VIN2+, VIN2- — Differential analog inputs for the voltage channels. |
| Differential Current Inputs | 20,19, 16,15 | IIN1+, IIN1-, IIN2+, IIN2- — Differential analog inputs for the current channels. |
| Voltage Reference Output | 11 | VREFOUT — The on-chip voltage reference output. Nominally 2.5 V, referenced to AGND. |
| Voltage Reference Input | 12 | VREFIN — The voltage reference input. Can be connected to VREFOUT or external 2.5 V reference. |

Power Supply Connections

| | | |
|--------------------------------|----|--|
| Positive Digital Supply | 3 | VD+ — The positive digital supply. |
| Digital Ground | 4 | DGND — Digital ground. |
| Positive Analog Supply | 18 | VA+ — The positive analog supply. |
| Analog Ground | 17 | AGND — Analog ground. |
| Power Fail Monitor | 21 | PFMON — Used to monitor the unregulated power supply via a resistive divider. If the PFMON voltage drops below its low limit, the low-supply detect (LSD) bit is set in the <i>Status</i> register. |

3. CHARACTERISTICS & SPECIFICATIONS

RECOMMENDED OPERATING CONDITIONS

| Parameter | Symbol | Min | Typ | Max | Unit |
|-------------------------------|----------------|-------|-----|------|------|
| Positive Digital Power Supply | VD+ | 3.135 | 5.0 | 5.25 | V |
| Positive Analog Power Supply | VA+ | 4.75 | 5.0 | 5.25 | V |
| Voltage Reference | VREFIN | - | 2.5 | - | V |
| Specified Temperature Range | T _A | -40 | - | +85 | °C |

ANALOG CHARACTERISTICS

- Min / Max characteristics and specifications are guaranteed over all [Recommended Operating Conditions](#).
- Typical characteristics and specifications are measured at nominal supply voltages and T_A = 25 °C.
- VA+ = VD+ = 5 V ±5%; AGND = DGND = 0 V; VREFIN = +2.5 V. All voltages with respect to 0 V.
- DCLK = 4.096 MHz.

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|---------------------|-------|---------------|-------------|--|
| Accuracy | | | | | |
| Active Power (Note 1) | P _{ACTIVE} | - | ±0.1 | - | % |
| Reactive Power (Note 1 and 2) | Q _{AVG} | - | ±0.2 | - | % |
| Power Factor (Note 1 and 2) | PF | - | ±0.2 ±0.27 | - | % % |
| Current RMS (Note 1) | I _{RMS} | - | ±0.1 ±0.17 | - | % % % |
| Voltage RMS (Note 1) | V _{RMS} | - | ±0.1 | - | % |
| Analog Inputs (All Inputs) | | | | | |
| Common Mode Rejection (DC, 50, 60 Hz) | CMRR | 80 | - | - | dB |
| Common Mode + Signal | | -0.25 | - | VA+ | V |
| Analog Inputs (Current Inputs) | | | | | |
| Differential Input Range [(IIN+) – (IIN-)] | IIN | - | 500 100 | - | mV _{P-P} mV _{P-P} |
| Total Harmonic Distortion | THD | 80 | 94 | - | dB |
| Crosstalk from Voltage input at Full Scale | | - | -115 | - | dB |
| Input Capacitance | IC | - | 27 | - | pF |
| Effective Input Impedance | EII | 30 | - | - | kΩ |
| Noise (Referred to Input) | N _I | - | - | 22.5 4.5 | μV _{rms} μV _{rms} |
| Offset Drift (Without the High-pass Filter) | OD | - | 4.0 | - | μV/°C |
| Gain Error (Note 3) | GE | - | ±0.4 | | % |

Notes: 1. Applies when the HPF option is enabled.

2. Applies when the line frequency is equal to the product of the output word rate (OWR) and the value of *Epsilon*.

ANALOG CHARACTERISTICS (Continued)

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|----------------|---------|------|-----|-------------------|
| Analog Inputs (Voltage Inputs) | | | | | |
| Differential Input Range [(VIN+) – (VIN-)] | VIN | - | 500 | - | mV _{P-P} |
| Total Harmonic Distortion | THD | 65 | 75 | - | dB |
| Crosstalk from Current inputs at Full Scale (50, 60 Hz) | | - | -70 | - | dB |
| Input Capacitance All Gain Ranges | IC | - | 2.0 | - | pF |
| Effective Input Impedance | EII | 2 | - | - | MΩ |
| Noise (Referred to Input) | N _V | - | - | 140 | μV _{rms} |
| Offset Drift (Without the High-pass Filter) | OD | - | 16.0 | - | μV/°C |
| Gain Error (Note 3) | GE | - | ±3.0 | | % |
| Temperature | | | | | |
| Temperature Accuracy | T | - | ±5 | - | °C |
| Power Supplies | | | | | |
| Power Supply Currents (Active State) I _{A+} | PSCA | - | 1.5 | - | mA |
| I _{D+} (VA+ = VD+ = 5 V) | PSCD | - | 3.5 | - | mA |
| I _{D+} (VA+ = 5 V, VD+ = 3.3 V) | PSCD | - | 2.3 | - | mA |
| Power Consumption Active State (VA+ = VD+ = 5 V) | PC | - | 25 | 33 | mW |
| (Note 4) Active State (VA+ = 5 V, VD+ = 3.3 V) | | - | 15 | 20 | mW |
| Stand-by State | | - | 7 | - | mW |
| Sleep State | | - | 10 | - | uW |
| Power Supply Rejection Ratio (50, 60 Hz) (Note 5) | PSRR | Voltage | 48 | 55 | dB |
| Current (Gain = 50x) | | 68 | 75 | - | dB |
| Current (Gain = 10x) | | 60 | 65 | - | dB |
| PFMON Low-voltage Trigger Threshold (Note 6) | PMLO | 2.3 | 2.45 | - | V |
| PFMON High-voltage Power-on Trip Point (Note 7) | PMHI | - | 2.55 | 2.7 | V |

Notes: 3. Applies before system calibration.

4. All outputs unloaded. All inputs CMOS level.

5. Measurement method for PSRR: VREFIN tied to VREFOUT, VA+ = VD+ = 5 V, a 150 mV (zero-to-peak) (60 Hz) sinewave is imposed onto the +5 V DC supply voltage at VA+ and VD+ pins. The "+" and "-" input pins of both input channels are shorted to AGND. The CS5467 is then commanded to continuous conversion acquisition mode, and digital output data is collected for the channel under test. The (zero-to-peak) value of the digital sinusoidal output signal is determined, and this value is converted into the (zero-to-peak) value of the sinusoidal voltage (measured in mV) that would need to be applied at the channel's inputs, in order to cause the same digital sinusoidal output. This voltage is then defined as V_{eq}. PSRR is (in dB):

$$PSRR = 20 \cdot \log \left[\frac{150}{V_{eq}} \right]$$

6. When the voltage level on PFMON is sagging and LSD bit = 0, this is the voltage at which LSD is set to 1.

7. If the LSD bit has been set to 1 (because PFMON voltage fell below PMLO), this is the voltage level on PFMON at which the LSD bit can be permanently reset back to 0.

VOLTAGE REFERENCE

| Parameter | Symbol | Min | Typ | Max | Unit |
|----------------------------------|--------------------|------|------|------|--------|
| Reference Output | | | | | |
| Output Voltage | VREFOUT | +2.4 | +2.5 | +2.6 | V |
| Temperature Coefficient (Note 8) | TC _{VREF} | - | 40 | - | ppm/°C |
| Load Regulation (Note 9) | ΔV _R | - | 6 | 10 | mV |
| Reference Input | | | | | |
| Input Voltage Range | VREFIN | +2.4 | +2.5 | +2.6 | V |
| Input Capacitance | | - | 4 | - | pF |
| Input CVF Current | | - | 100 | - | nA |

Notes: 8. The voltage at VREFOUT is measured across the temperature range. From these measurements the following formula is used to calculate the VREFOUT temperature coefficient.

$$TC_{VREF} = \left(\frac{VREFOUT_{MAX} - VREFOUT_{MIN}}{VREFOUT_{AVG}} \right) \left(\frac{1}{T_{A_{MAX}} - T_{A_{MIN}}} \right) (1.0 \times 10^6)$$

9. Specified at maximum recommended output of 1 μA, source or sink.

DIGITAL CHARACTERISTICS

- Min / Max characteristics and specifications are guaranteed over all [Recommended Operating Conditions](#).
- Typical characteristics and specifications are measured at nominal supply voltages and $T_A = 25^\circ\text{C}$.
- $V_{A+} = V_{D+} = 5V \pm 5\%$; $AGND = DGND = 0V$. All voltages with respect to 0 V.
- $DCLK = 4.096\text{ MHz}$.

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|-----------|--|-------------|-----------------------------|-------------|
| Master Clock Characteristics | | | | | |
| Master Clock Frequency Internal Gate Oscillator (Note 11) | DCLK | 2.5 | 4.096 | 20 | MHz |
| Master Clock Duty Cycle | | 40 | - | 60 | % |
| CPUCLK Duty Cycle (Note 12 and 13) | | 40 | - | 60 | % |
| Filter Characteristics | | | | | |
| Phase Compensation Range (60 Hz, OWR = 4000 Hz) | | -5.4 | - | +5.4 | ° |
| Input Sampling Rate DCLK = MCLK/K | | - | DCLK/8 | - | Hz |
| Digital Filter Output Word Rate (Both channels) | OWR | - | DCLK/1024 | - | Hz |
| High-pass Filter Corner Frequency -3 dB | | - | 0.5 | - | Hz |
| Full-scale DC Calibration Range (Referred to Input) (Note 14) | FSCR | 25 | - | 100 | %FS |
| Channel-to-channel Time-shift Error (Note 15) | | | 1.0 | | μs |
| Input/Output Characteristics | | | | | |
| High-level Input Voltage All Pins Except XIN and SCLK and $\overline{\text{RESET}}$ XIN SCLK and $\overline{\text{RESET}}$ | V_{IH} | 0.6 V_{D+} (V_{D+}) - 0.5 0.8 V_{D+} | - - - | - - - | V V V |
| Low-level Input Voltage ($V_D = 5V$) All Pins Except XIN and SCLK and $\overline{\text{RESET}}$ XIN SCLK and $\overline{\text{RESET}}$ | V_{IL} | - - - | - - - | 0.8 1.5 0.2 V_{D+} | V V V |
| Low-level Input Voltage ($V_D = 3.3V$) All Pins Except XIN and SCLK and $\overline{\text{RESET}}$ XIN SCLK and $\overline{\text{RESET}}$ | V_{IL} | - - - | - - - | 0.48 0.3 0.2 V_{D+} | V V V |
| High-level Output Voltage $I_{out} = +5\text{ mA}$ | V_{OH} | (V_{D+}) - 1.0 | - | - | V |
| Low-level Output Voltage $I_{out} = -5\text{ mA}$ ($V_D = +5V$) $I_{out} = -2.5\text{ mA}$ ($V_D = +3.3V$) | V_{OL} | - - | - - | 0.4 0.4 | V V |
| Input Leakage Current (Note 16) | I_{in} | - | ±1 | ±10 | μA |
| 3-state Leakage Current | I_{OZ} | - | - | ±10 | μA |
| Digital Output Pin Capacitance | C_{out} | - | 5 | - | pF |

Notes: 10. All measurements performed under static conditions.

- If a crystal is used, XIN frequency must remain between 2.5 MHz - 5.0 MHz. If an external oscillator is used, XIN frequency range is 2.5 MHz - 20 MHz, but K must be set so that MCLK is between 2.5 MHz - 5.0 MHz.
- If external MCLK is used, the duty cycle must be between 45% and 55% to maintain this specification.
- The frequency of CPUCLK is equal to MCLK.
- The minimum FSCR is limited by the maximum allowed gain register value. The maximum FSCR is limited by the full-scale signal applied to the input.
- Configuration register (*Config*) bits PC[6:0] are set to "0000000".
- The MODE pin is pulled low by an internal resistor.

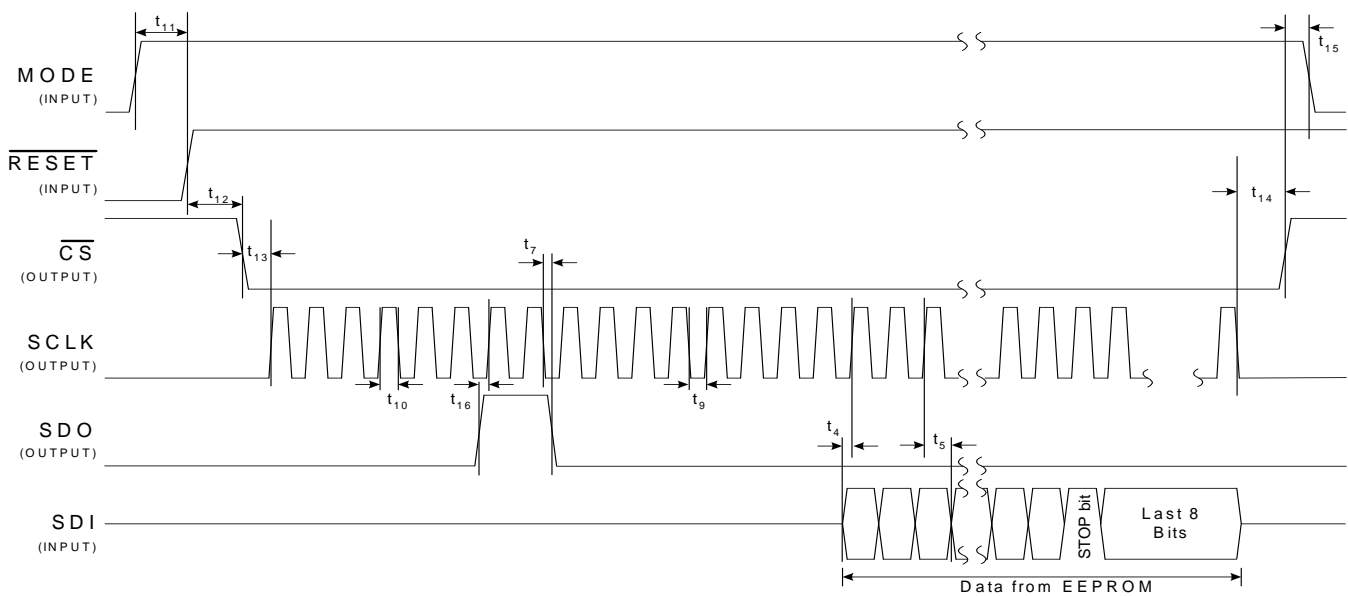
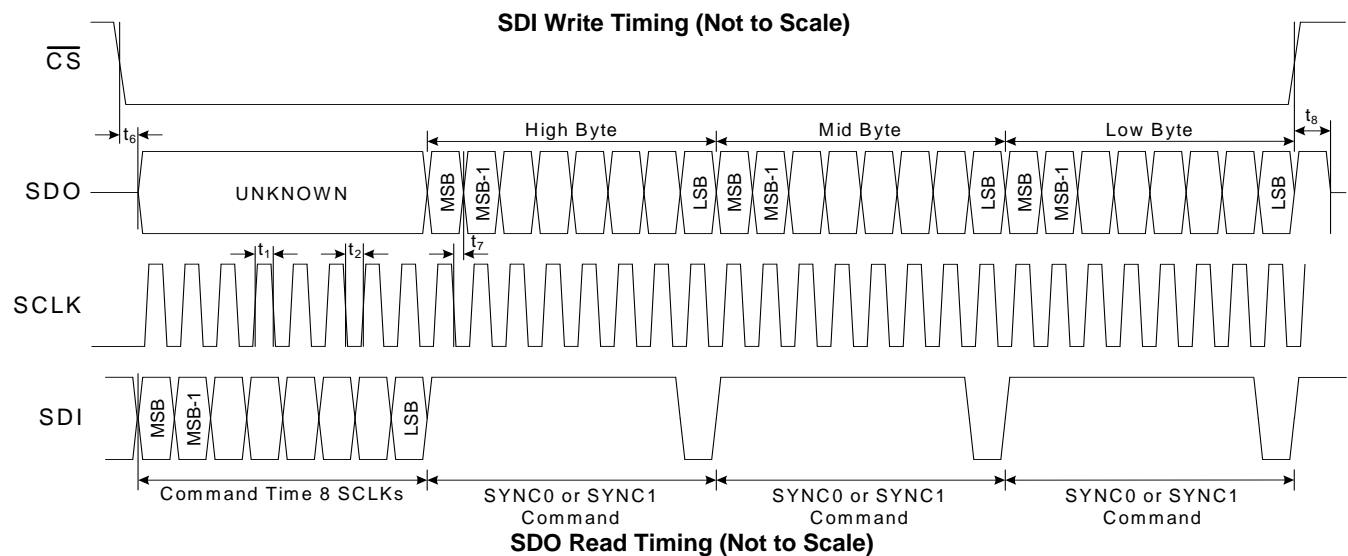
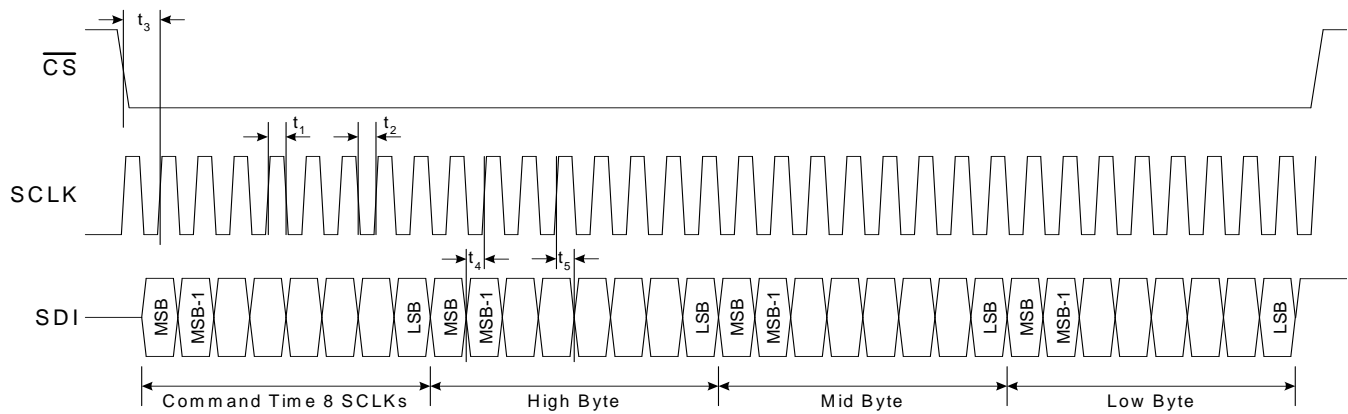
SWITCHING CHARACTERISTICS

- Min / Max characteristics and specifications are guaranteed over all [Recommended Operating Conditions](#).
- Typical characteristics and specifications are measured at nominal supply voltages and $T_A = 25\text{ }^{\circ}\text{C}$.
- $V_{A+} = 5\text{ V} \pm 5\%$ $V_{D+} = 3.3\text{ V} \pm 5\%$ or $5\text{ V} \pm 5\%$; $AGND = DGND = 0\text{ V}$. All voltages with respect to 0 V.
- Logic Levels: Logic 0 = 0 V, Logic 1 = V_{D+} .

| Parameter | Symbol | Min | Typ | Max | Unit |
|--|-------------------|----------|-----|-----|---------------|
| Rise Times (Note 17) | t_{rise} | - | - | 1.0 | μs |
| Any Digital Output | | - | 50 | - | ns |
| Fall Times (Note 17) | t_{fall} | - | - | 1.0 | μs |
| Any Digital Output | | - | 50 | - | ns |
| Start-up | | | | | |
| Oscillator Start-up Time XTAL = 4.096 MHz (Note 18) | t_{ost} | - | 60 | - | ms |
| Serial Port Timing | | | | | |
| Serial Clock Frequency | SCLK | - | - | 2 | MHz |
| Serial Clock | Pulse Width High | t_1 | 200 | - | ns |
| | Pulse Width Low | t_2 | 200 | - | ns |
| SDI Timing | | | | | |
| $\overline{\text{CS}}$ Falling to SCLK Rising | t_3 | 50 | - | - | ns |
| Data Set-up Time Prior to SCLK Rising | t_4 | 50 | - | - | ns |
| Data Hold Time After SCLK Rising | t_5 | 100 | - | - | ns |
| SDO Timing | | | | | |
| $\overline{\text{CS}}$ Falling to SDO Driving | t_6 | - | 20 | 50 | ns |
| SCLK Falling to New Data Bit (hold time) | t_7 | - | 20 | 50 | ns |
| $\overline{\text{CS}}$ Rising to SDO Hi-Z | t_8 | - | 20 | 50 | ns |
| E²PROM mode Timing | | | | | |
| Serial Clock | Pulse Width Low | t_9 | 8 | | DCLK |
| | Pulse Width High | t_{10} | 8 | | DCLK |
| MODE setup time to $\overline{\text{RESET}}$ Rising | t_{11} | 50 | | | ns |
| $\overline{\text{RESET}}$ rising to $\overline{\text{CS}}$ falling | t_{12} | 48 | | | DCLK |
| $\overline{\text{CS}}$ falling to SCLK rising | t_{13} | 100 | 8 | | DCLK |
| SCLK falling to $\overline{\text{CS}}$ rising | t_{14} | | 16 | | DCLK |
| $\overline{\text{CS}}$ rising to driving MODE low | t_{15} | 50 | | | ns |
| SDO setup time to SCLK rising | t_{16} | 100 | | | ns |

Notes: 17. Specified using 10% and 90% points on waveform of interest. Output loaded with 50 pF.

18. Oscillator start-up time varies with crystal parameters. This specification does not apply when using an external clock source.



E2PROM mode Sequence Timing (Not to Scale)

Figure 1. CS5467 Read and Write Timing Diagrams

SWITCHING CHARACTERISTICS (Continued)

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|---------------------|-----|-----|-----|---------------|
| $\overline{E1}$, $\overline{E2}$, and $\overline{E3}$ Timing (Note 19 and 20) | | | | | |
| Period | t_{period} | 500 | - | - | μs |
| Pulse Width | t_{pw} | 244 | - | - | μs |
| Rising Edge to Falling Edge | t_3 | 6 | - | - | μs |
| $\overline{E2}$ Setup to $\overline{E1}$ and/or $\overline{E3}$ Falling Edge | t_4 | 1.5 | - | - | μs |
| $\overline{E1}$ Falling Edge to $\overline{E3}$ Falling Edge | t_5 | 248 | - | - | μs |

Notes: 19. Pulse output timing is specified at DCLK = 4.096 MHz, E2MODE = 0, and E3MODE[1:0] = 0. Refer to [6.7 Energy Pulse Outputs](#) on page 20 for more information on pulse output pins.

20. Timing is proportional to the frequency of DCLK.

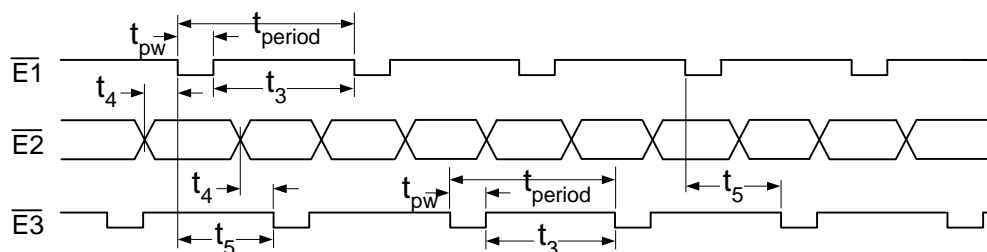


Figure 2. Timing Diagram for $\overline{E1}$, $\overline{E2}$, and $\overline{E3}$

ABSOLUTE MAXIMUM RATINGS

WARNING: Operation at or beyond these limits may result in permanent damage to the device.

Normal operation is not guaranteed at these extremes.

| Parameter | Symbol | Min | Typ | Max | Unit |
|---|------------------|-------|-----|-------------|------|
| DC Power Supplies (Notes 21 and 22) | | | | | |
| Positive Digital | VD+ | -0.3 | - | +6.0 | V |
| Positive Analog | VA+ | -0.3 | - | +6.0 | V |
| Input Current, Any Pin Except Supplies (Notes 23, 24, 25) | I_{IN} | - | - | ± 10 | mA |
| Output Current, Any Pin Except VREFOUT | I_{OUT} | - | - | 100 | mA |
| Power Dissipation (Note 26) | P_D | - | - | 500 | mW |
| Analog Input Voltage All Analog Pins | V_{INA} | - 0.3 | - | (VA+) + 0.3 | V |
| Digital Input Voltage All Digital Pins | V_{IND} | -0.3 | - | (VD+) + 0.3 | V |
| Ambient Operating Temperature | T_A | -40 | - | 85 | °C |
| Storage Temperature | T_{stg} | -65 | - | 150 | °C |

Notes: 21. VA+ and AGND must satisfy $[(VA+) - (AGND)] \leq + 6.0 \text{ V}$.

22. VD+ and AGND must satisfy $[(VD+) - (AGND)] \leq + 6.0 \text{ V}$.

23. Applies to all pins including continuous over-voltage conditions at the analog input pins.

24. Transient current of up to 100 mA will not cause SCR latch-up.

25. Maximum DC input current for a power supply pin is $\pm 50 \text{ mA}$.

26. Total power dissipation, including all input currents and output currents.

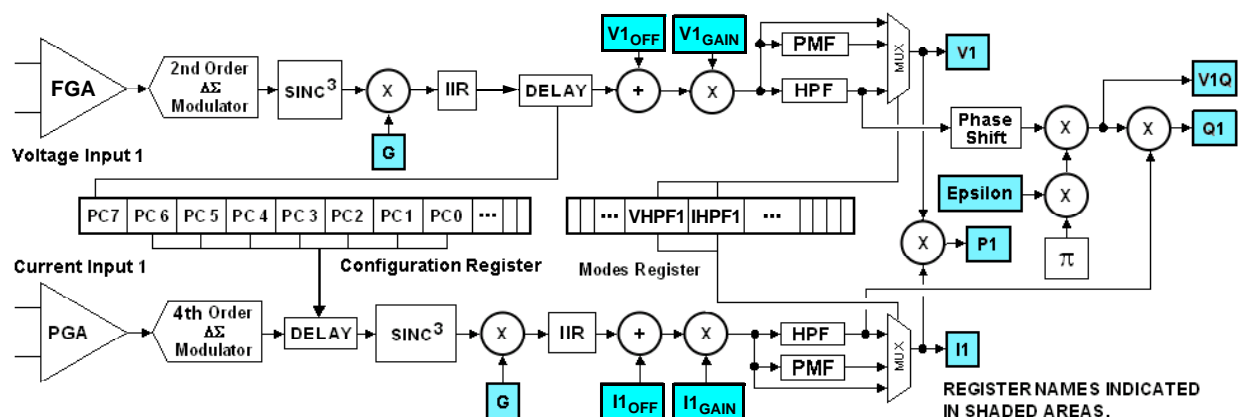


Figure 3. Signal Flow for V1, I1, P1, Q1 Measurements

4. SIGNAL PATH DESCRIPTION

The data flow for voltage and current measurement and the other calculations are shown in Figures 3, 4, and 5.

4.1 Analog-to-Digital Converters

Voltage1 channel and voltage2/temperature channel use second-order delta-sigma modulators and the two current channels use fourth-order delta-sigma modulators to convert the analog inputs to single-bit digital data streams. The converters sample at a rate of DCLK/8. This high sampling provides a wide dynamic range and simplifies anti-alias filter design.

4.2 Decimation Filters

The single-bit modulator output data is widened to 24 bits and down-sampled to DCLK/1024 with low-pass decimation filters. These decimation filters are third-order Sinc. Their outputs are passed through third-order

IIR “anti-sinc” filters, used to compensate for the amplitude roll-off of the decimation filters.

4.3 Phase Compensation

Phase compensation changes the phase of current relative to voltage by changing the sampling time in the decimation filters. The amount of phase shift is set by bits PC[7:0] in the Configuration register (*Config*) for channel 1 and bits PC[7:0] in the Control register (*Ctrl*) for channel 2.

Phase compensation, PC[7:0] is a signed two’s complement binary value in the range of -1.0 to almost +1.0 output word rate (OWR) samples. For a sample rate of 4000 Hz, the delay range is ± 250 μ s, a phase shift of $\pm 4.5^\circ$ at 50 Hz and $\pm 5.4^\circ$ at 60 Hz. The step size would be 0.0352° at 50 Hz and 0.0422° at 60 Hz at this sample rate.

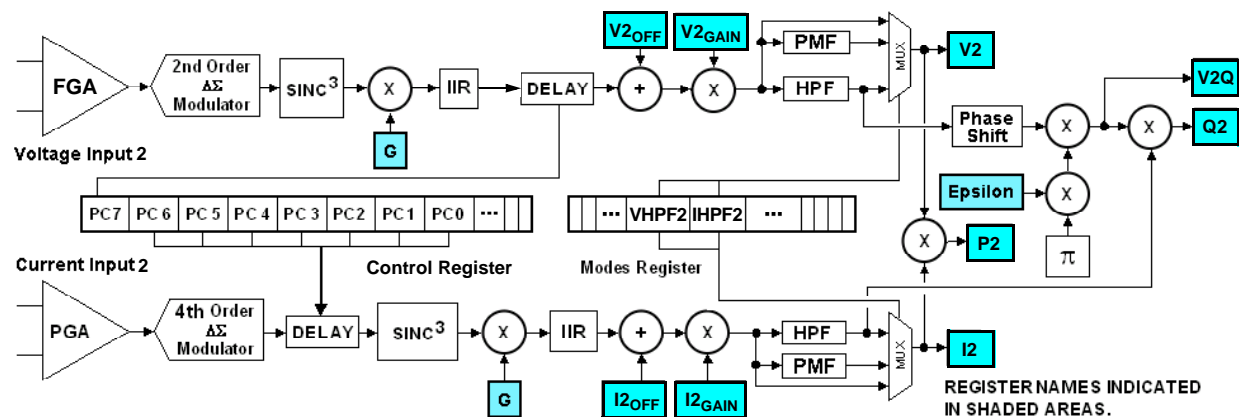


Figure 4. Signal Flow for V2, I2, P2, Q2 Measurements

4.4 DC Offset and Gain Correction

The system and chip inherently have gain and offset errors which can be removed using the gain and offset registers. (See [Section 9. System Calibration](#) on page 40). Each measurement channel has its own registers. For every channel, the output of the IIR filter is added to the offset register and multiplied by the gain register.

4.5 High-pass Filters

Optional high-pass filters (HPF in Figures 3 and 4) remove any DC from the selected signal paths. Subsequently, DC will also be removed from power, and all low-rate results. (see Figures 5).

Each energy channel has a current and voltage path. If an HPF is enabled in only one path, a phase-matching filter (PMF) is applied to the other path which matches the amplitude and phase delay of the HPF in the band

of interest, but passes DC. For more information, see [6.5 High-pass Filters](#) on page 20. The HPF filter multiplexers drive the *I1*, *V1*, *I2*, and *V2* result registers.

4.6 Low-Rate Calculations

Low-rate results are derived from sample-rate results integrated over *N* samples, where *N* is the value stored in the Cycle Count register. The low-rate interval is the sample interval multiplied by *N*.

4.7 RMS Results

The root mean square (*RMS* in [Figure 5](#)) calculations are performed on *N* instantaneous voltage and current samples, using the formula:

$$I_{\text{RMS}} = \sqrt{\frac{\sum_{n=0}^{N-1} I_n^2}{N}}$$

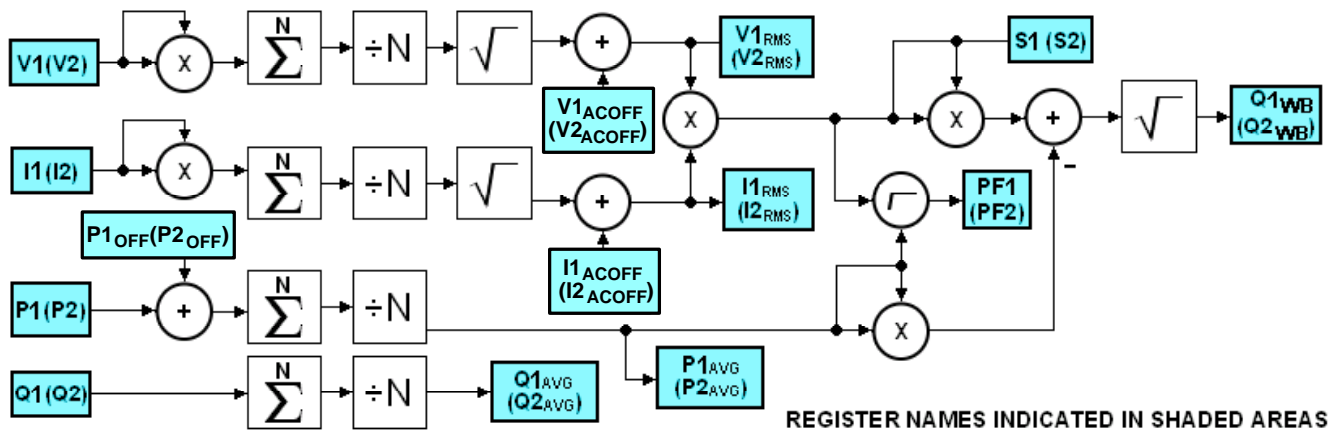


Figure 5. Low-rate Calculations

4.8 Power and Energy Results

The instantaneous voltage and current samples are multiplied to obtain the instantaneous power ($P1$, $P2$) (see Figure 3 and 4). The product is then averaged over N conversions to compute active power ($P1_{AVG}$, $P2_{AVG}$).

Apparent power ($S1$, $S2$) is the product of RMS voltage and current as shown:

$$S = V_{RMS} \times I_{RMS}$$

Power factor ($PF1$, $PF2$) is active power divided by apparent power as shown below. The sign of the power factor is determined by the active power.

$$PF = \frac{P_{Active}}{S}$$

Wideband reactive power ($Q1_{WB}$, $Q2_{WB}$) is calculated by doing a vector subtraction of active power from apparent power.

$$Q_{WB} = \sqrt{S^2 - P_{Active}^2}$$

Quadrature power ($Q1$, $Q2$) are sample rate results obtained by multiplying instantaneous current ($I1$, $I2$) by instantaneous quadrature voltage ($V1Q$, $V2Q$) which are created by phase shifting instantaneous voltage ($V1$, $V2$) 90 degrees using first-order integrators. (See Figure 3 and 4). The gain of these integrators is inversely related to line frequency, so their gain is corrected by the *Epsilon* register, which is based on line frequency.

Reactive power ($Q1_{AVG}$, $Q2_{AVG}$) is generated by integrating the instantaneous quadrature power over N samples.

Active power ($P1_{AVG}$, $P2_{AVG}$), apparent power ($S1$, $S2$), and reactive power ($Q1_{AVG}$, $Q2_{AVG}$) of the two channels are summed up and then divided by 2. The calculation results are placed in E_{PULSE} , S_{PULSE} , and Q_{PULSE} registers which can be configured to drive energy pulse outputs. (See Figure 6.)

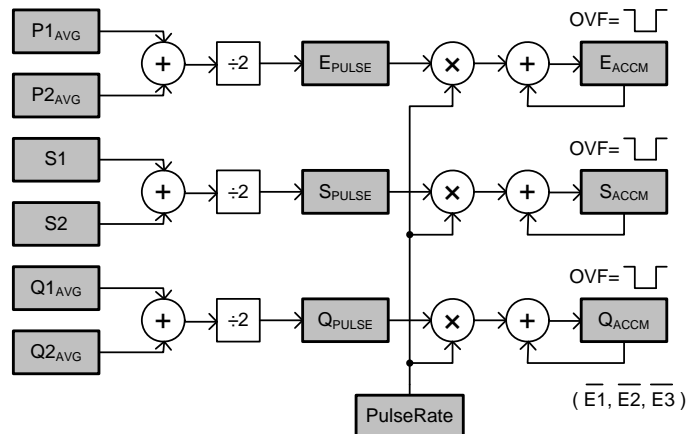


Figure 6. Two-channel Power Summation

4.9 Peak Voltage and Current

Peak current ($I1_{PEAK}$, $I2_{PEAK}$) and peak voltage ($V1_{PEAK}$, $V2_{PEAK}$) are the largest current and voltage samples detected in the previous low-rate interval.

4.10 Power Offset

The power offset registers, $P1_{OFF}$ ($P2_{OFF}$) can be used to offset erroneous power sources resident in the system not originating from the power line. Residual power offsets are usually caused by crosstalk into current paths from voltage paths or from ripple on the meter or

chip's power supply, or from inductance from a nearby transformer.

These offsets can be either positive or negative, indicating crosstalk coupling either in phase or out of phase with the applied voltage input. The power offset registers can compensate for either condition.

To use this feature, measure the average power at no load using either Single or Continuous Conversion commands. Take the measured result (from the $P1_{AVG}$ ($P2_{AVG}$) register), invert (negate) the value and write it to the associated power offset register, $P1_{OFF}$ ($P2_{OFF}$).

5. PIN DESCRIPTIONS

5.1 Analog Pins

The CS5467 has four differential inputs: VIN1±, VIN2±, IIN1±, and IIN2± are the voltage1, voltage2, current1, and current2 inputs, respectively. A single-ended power fail monitor input, voltage reference input, and voltage reference output are also available.

5.1.1 Voltage1 & Voltage2 Inputs

The output of the line voltage resistive divider or transformer is connected to the VIN1+ (VIN2+) and VIN1- (VIN2-) input pins of the CS5467. The voltage channel is equipped with a 10x, fixed-gain amplifier. The full-scale signal level that can be applied to the voltage channel is ±250 mV. If the input signal is a sine wave, the maximum RMS voltage is $250 \text{ mVp} / \sqrt{2} \approx 176.78 \text{ mVRMS}$ which is approximately 70.7% of maximum peak voltage.

5.1.2 Current1 & Current2 Inputs

The output of the current-sensing resistor or transformer is connected to the IIN1+ (IIN2+) and IIN1- (IIN2-) input pins of the CS5467. To accommodate different current-sensing elements, the current channel incorporates a programmable gain amplifier (PGA) with two selectable input gains. The full-scale signal level for the current channels is ±50 mV or ±250 mV. If the input signal is a sine wave, the maximum RMS voltage is 35.35 mVRMS or 176.78 mVRMS which is approximately 70.7% of maximum peak voltage.

5.1.3 Power Fail Monitor Input

An analog input (PFMON) is provided to determine when a power loss is imminent. By connecting a resistive divider from the unregulated meter power supply to the PFMON input, an interrupt can be generated, or the Low Supply Detected (LSD) *Status* register bit can be monitored to indicate low-supply conditions. The PFMON input has a comparator that trips around the level of the voltage reference input (VREFIN).

5.1.4 Voltage Reference Input

The CS5467 requires a stable voltage reference of 2.5 V applied to the VREFIN pin. This reference can be supplied from an external voltage reference or from the VREFOUT output. A bypass capacitor of at least 0.1 μF is recommended at the VREFIN pin.

5.1.5 Voltage Reference Output

The CS5467 generates a 2.5 V reference (VREFOUT). It is suitable for driving the VREFIN pin, but has very little fan-out capacity and is not recommended for driving external circuits.

5.1.6 Crystal Oscillator

An external quartz crystal can be connected to the XIN and XOUT pins as shown in Figure 7. To reduce system cost, each pin is supplied with an on-chip, phase-shifting capacitor to ground.

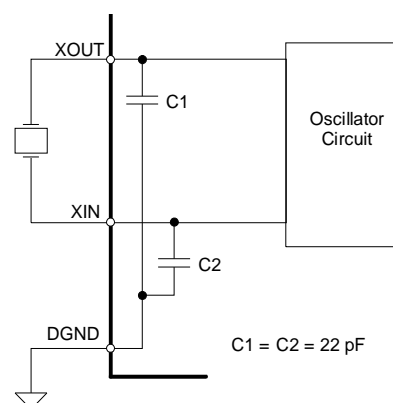


Figure 7. Oscillator Connections

Alternatively, an external clock source can be connected to the XIN pin.

5.2 Digital Pins

5.2.1 Reset Input

The active-low $\overline{\text{RESET}}$ pin, when asserted, will halt all CS5467 operations and reset internal hardware registers and states. When de-asserted, an initialization sequence begins, setting default register values.

5.2.2 CPU Clock Output

A logic-level clock output (CPUCLK) is provided at the crystal frequency to drive an external CPU or microcontroller clock. Two phase choices are available.

5.2.3 Interrupt Output

The $\overline{\text{INT}}$ pin indicates an enabled Internal Status register (*Status*) bit is set. *Status* register bits indicate conditions such as data ready, modulator oscillations, low supply, voltage sag, current faults, numerical overflows, and result updates.

5.2.4 Energy Pulse Outputs

The CS5467 provides three pins ($\overline{\text{E1}}$, $\overline{\text{E2}}$, $\overline{\text{E3}}$) for pulse energy outputs. These pins can also be used to output other conditions, such as voltage1 sign, power fail monitor, or energy sign.

5.2.5 Serial Interface

The CS5467 provides 5 pins, SCLK, SDI, SDO, $\overline{\text{CS}}$, and MODE for communication between a host microcontroller or serial E²PROM and the CS5467.

MODE is an input that, when high, indicates to the CS5467 that a serial E²PROM is being used instead of a host microcontroller. It has a weak pull-down allowing it to be left unconnected if microcontroller mode is used.

SCLK is used to shift and qualify serial data. Serial data changes as a result of the falling edge of SCLK and is valid during the rising edge. It is a Schmitt-trigger input

for host microcontrollers, and a driven output for serial E²PROMs.

SDI is the serial data input to the CS5467.

SDO is the serial data output from the CS5467. It's output drivers are disabled whenever $\overline{\text{CS}}$ is de-asserted, allowing other devices to drive the SDO line.

$\overline{\text{CS}}$ is the chip select input for the serial bus. A high logic level de-asserts it, tri-stating the SDO pin and clearing the serial interface. A low logic level enables the serial port. This pin may be tied low for systems not requiring multiple SDO drivers. $\overline{\text{CS}}$ is a driven output when interfacing to serial E²PROMs.

6. SETTING UP THE CS5467

6.1 Clock Divider

The internal clock to the CS5467 needs to operate around 4 MHz. However, by using the internal clock divider, a higher crystal frequency can be used. This is important when driving an external microcontroller requiring a faster clock and using the CPUCLOCK output.

K is the divide ratio from the crystal input to the internal clock and is selected with Configuration register (*Config*) bits K[3:0]. It has a range of 1 to 16. A value of zero results in a setting of 16.

6.2 CPU Clock Inversion

By default, CPUCLOCK is inverted from XIN. Setting Configuration register bit iCPU removes this inversion. This can be useful when one phase adds more noise to the system than the other.

6.3 Interrupt Pin Behavior

The behavior of the $\overline{\text{INT}}$ pin is controlled by the IMODE and IINV bits in the Configuration register as shown.





| IMODE | IINV | $\overline{\text{INT}}$ Pin |
|-------|------|---|
| 0 | 0 | Active-low Level  |
| 0 | 1 | Active-high Level  |
| 1 | 0 | Low Pulse  |
| 1 | 1 | High Pulse  |

Table 1. Interrupt Configuration

If IMODE = 1, the duration of the $\overline{\text{INT}}$ pulse will be two DCLK cycles, where DCLK = MCLK/K.

6.4 Current Input Gain Ranges

Control register bits I1gain (I2gain) select the input range of the current inputs.

| I1gain, I2gain | Maximum Input | Gain |
|----------------|---------------|------|
| 0 | ±250 mV | 10x |
| 1 | ±50 mV | 50x |

Table 2. Current Input Gain Ranges

6.5 High-pass Filters

Mode Control (*Modes*) register bits VHPF and IHPF activate the HPF in the voltage and current paths, respectively. Each energy channel has separate VHPF and IHPF bits. When a high-pass filter is enabled in only one

path within a channel, a phase matching filter (PMF) is applied to the other path within that channel. The PMF filter matches the amplitude and phase response of the HPF in the band of interest, but passes DC.

| VHPF | IHPF | Filter Configuration |
|------|------|---------------------------------|
| 0 | 0 | No filter on Voltage or Current |
| 0 | 1 | HPF on Current, PMF on Voltage |
| 1 | 0 | HPF on Voltage, PMF on Current |
| 1 | 1 | HPF on Current and Voltage |

Table 3. High-pass Filter Configuration

6.6 Cycle Count

Low-rate calculations, such as average power and RMS voltage and current integrate over several (*N*) output word rate (OWR) samples. The duration of this averaging window is set by the Cycle Count (*N*) register. By default, Cycle Count is set to 4000 (1 second at output word rate [OWR] of 4000 Hz). The minimum value for Cycle Count is 10.

6.7 Energy Pulse Outputs

By default, E1 outputs total active energy, $\overline{\text{E3}}$, total reactive energy, and E2, the sign of both active and reactive energy. (See [Figure 2. Timing Diagram for E1, E2, and E3](#) on page 13.)

Three pairs of bits in the Mode Control (*Modes*) register control the operation of these outputs. These bits are named E1MODE[1:0], E2MODE[1:0], and E3MODE[1:0]. Some combinations of these bits override others, so read the following paragraphs carefully.

The $\overline{\text{E2}}$ pin can output energy sign, or total apparent energy. Table 4 lists the functions of $\overline{\text{E2}}$ as controlled by E2MODE[1:0] in the *Modes* register.

Note: E2MODE[1:0]=3 is a special mode.

| E2MODE1 | E2MODE0 | $\overline{\text{E2}}$ output |
|---------|---------|-------------------------------|
| 0 | 0 | Energy Sign |
| 0 | 1 | Total Apparent Energy |
| 1 | 0 | Not Used |
| 1 | 1 | Enable E1MODE |

Table 4. $\overline{\text{E2}}$ Pin Configuration

The $\overline{\text{E3}}$ pin can output total reactive energy, power fail monitor status, voltage1 sign, or total apparent energy. Table 5 lists the functions of $\overline{\text{E3}}$ as controlled by

E3MODE[1:0] in the *Modes* register when E1MODE is not enabled.

| E3MODE1 | E3MODE0 | $\overline{\text{E3}}$ output |
|---------|---------|-------------------------------|
| 0 | 0 | Total Reactive Energy |
| 0 | 1 | Power Fail Monitor |
| 1 | 0 | Voltage1 Sign |
| 1 | 1 | Total Apparent Energy |

Table 5. $\overline{\text{E3}}$ Pin Configuration

When both E2MODE bits are high, the E1MODE bits are enabled, allowing active, apparent, reactive, or wide band reactive energy for **both** energy channels to be output on E1 and E2. Table 6 lists the functions of $\overline{\text{E1}}$ and $\overline{\text{E2}}$ with E1MODE enabled.

| E1MODE1 | E1MODE0 | $\overline{\text{E1}}$ / $\overline{\text{E2}}$ outputs |
|---------|---------|---|
| 0 | 0 | Active Energy |
| 0 | 1 | Apparent Energy |
| 1 | 0 | Reactive Energy |
| 1 | 1 | Wideband Reactive |

Table 6. $\overline{\text{E1}}$ / $\overline{\text{E2}}$ Modes

When E1MODE bits are enabled, the $\overline{\text{E3}}$ pin outputs either the power fail monitor status, or the sign of the $\overline{\text{E1}}$ and $\overline{\text{E2}}$ outputs. Table 7 list the functions of the $\overline{\text{E3}}$ pin using E3MODE[1:0] in the *Modes* register when E1MODE is enabled.

| E3MODE1 | E3MODE0 | $\overline{\text{E3}}$ output |
|---------|---------|-------------------------------|
| 0 | 0 | Power Fail Monitor |
| 0 | 1 | Energy Sign |
| 1 | 0 | not used |
| 1 | 1 | not used |

Table 7. $\overline{\text{E3}}$ Pin with E1MODE enabled

6.8 No Load Threshold

The No Load Threshold register (Load_{MIN}) is used to zero out the contents of E_{PULSE} and Q_{PULSE} registers if their magnitude is less than the Load_{MIN} register value.

6.9 Energy Pulse Width

Note: Energy Pulse Width (*PulseWidth*) only applies to $\overline{\text{E1}}$, $\overline{\text{E2}}$, or $\overline{\text{E3}}$ pins that are configured to output pulses. When any are configured to output steady-state signals, such as voltage1 sign, power fail monitor, or energy sign, pulse widths and output rates do not apply.

The pulse width time (t_{pw}) in [Figure 2](#), is set by the value in the *PulseWidth* register which is an integer multiple of the sample or output word rate (OWR). At OWR of 4000 Hz (a period of 250 μs) $t_{\text{pw}} = \text{PulseWidth} \times 250 \mu\text{s}$. By default, *PulseWidth* is set to 1.

6.10 Energy Pulse Rate

The full-scale pulse frequency of enabled $\overline{\text{E1}}$, $\overline{\text{E2}}$, $\overline{\text{E3}}$ pins is the value in *PulseRate* x output word rate (OWR)/2. The actual pulse frequency is the full-scale pulse frequency multiplied by the pulse register's (E_{PULSE} , S_{PULSE} , or Q_{PULSE}) value.

Example:

If the output word rate (OWR) is 4000 Hz, and the *PulseRate* register is set to 0.05, the full-rate pulse frequency is $0.05 \times 4000 / 2 = 100 \text{ Hz}$. If the E_{PULSE} register, driving $\overline{\text{E1}}$, is 0.4567, the pulse output rate on $\overline{\text{E1}}$ will be $100 \text{ Hz} \times 0.4567 = 45.67 \text{ Hz}$.

6.11 Voltage Sag/Current Fault Detection

Voltage sag detection is used to determine when averaged voltage falls below a predetermined level for a specified interval of time. Current fault detection determines when averaged current falls below a predetermined level for a specified interval of time.

The specified interval of time (duration) is set by the value in the $V1\text{Sag}_{\text{DUR}}$ ($V2\text{Sag}_{\text{DUR}}$) and $I1\text{Fault}_{\text{DUR}}$ ($I2\text{Fault}_{\text{DUR}}$) registers. Setting any of these to zero (default) disables the detect feature for the given channel. The value is in output word rate (OWR) samples. The predetermined level is set by the values in the $V1\text{Sag}_{\text{LEVEL}}$ ($V2\text{Sag}_{\text{LEVEL}}$) and $I1\text{Fault}_{\text{LEVEL}}$ ($I2\text{Fault}_{\text{LEVEL}}$) registers.

For each enabled input channel, the measured value is rectified and compared to the associated level register. Over the duration window, the number of samples above and below the level are counted. If the number of samples below the level exceeds the number of samples above, a *Status* register bit $V1_{SAG}$ ($V2_{SAG}$), $I1_{FAULT}$ ($I2_{FAULT}$) is set, indicating a sag or fault condition. (see [Figure 8](#)).

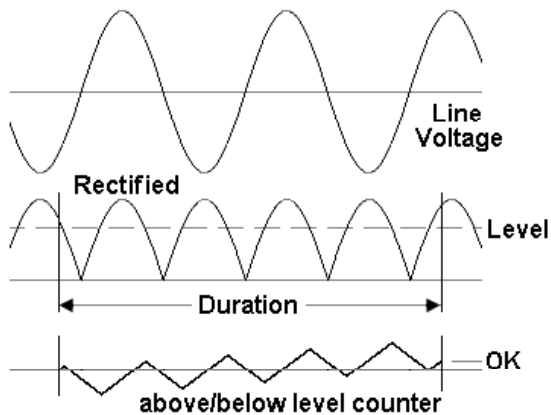


Figure 8. Sag and Fault Detect

6.12 Epsilon

The *Epsilon* register is used to set the gain of the 90° phase shift used in the quadrature power calculation.

The value in the *Epsilon* register is the ratio of the line frequency to the output word rate (OWR). It is, by default, 50/4000 (0.0125), for 50 Hz line and 4000 Hz sample (OWR) frequencies.

For 60 Hz line frequency, it is 60/4000 (0.015). Other output word rates (OWR) can be used.

Epsilon can also be calculated automatically by the CS5467 by setting the AFC bit in the Mode Control (*Modes*) register. The Frequency Update bit (FUP) in the *Status* register is set every time the *Epsilon* register has been automatically updated.

6.13 Temperature Measurement

The on-chip temperature sensor is designed to measure temperature and optionally compensate for temperature drift of the voltage reference. It uses the VBE of a transistor to determine temperature.

In the CS5467, voltage2 and temperature are multiplexed on one ADC channel. To initiate a temperature measurement, write 1 to the Temperature Measurement (T_{MEAS}) register. T_{MEAS} will go through counts 1, 2, 4, and back to 0. Wait for T_{MEAS} to return to 0. When done, Temperature (T) is updated. The *Status* register bit TUP also indicates when the Temperature register is

updated. The Voltage2 register ($V2$) will not update during the temperature measurement, but resume measurement afterwards.

Temperature measurements are stored in the Temperature register (T) which, by default, is configured to a range of ± 128 degrees on the Celsius ($^{\circ}\text{C}$) scale.

The application program can change both the scale and range of Temperature (T) by changing the Temperature Gain (T_{GAIN}) and Temperature Offset (T_{OFF}) registers.

Two values must be known — the transistor's ΔV_{BE} per degree, and the transistor's V_{BE} at 0 degrees. At the time of this publication, these values are:

$$\Delta V_{BE} \text{ (per degree)} = 0.2769523 \text{ mV}/^{\circ}\text{C or } ^{\circ}\text{K}$$

$$V_{BE0} = 79.2604368 \text{ mV at } 0^{\circ}\text{C}$$

To determine the values to write to T_{GAIN} and T_{OFF} , use the following formulae:

$$T_{GAIN} = AD_{FS} / \Delta V_{BE} / T_{FS} \times 2^{17}$$

$$T_{OFF} = -V_{BE0} / AD_{FS} \times 2^{23}$$

In the above equations, AD_{FS} is the full-scale input range of the temperature A/D converter or 833.333 mV and T_{FS} is the desired full-scale range of the Temperature (T) register. The binary exponents are the bit positions of the binary point of these registers.

To use the Celsius scale ($^{\circ}\text{C}$) and cover the chip's operating temperature range of -40°C to $+85^{\circ}\text{C}$, the Temperature register range needs to be ± 128 degrees. T_{FS} should be 128 degrees.

$$\begin{aligned} T_{GAIN} &= 833.333 / 0.2769523 / 128 \times 131072 \\ &= 3081155 \text{ (0x2F03C3)} \end{aligned}$$

$$\begin{aligned} T_{OFF} &= -79.2604368 / 833.333 \times 8388608 \\ &= -797862 \text{ (0xF3D35A)} \end{aligned}$$

These are the actual default values for these registers.

T_{GAIN} and T_{OFF} can also be used to calibrate the gain and/or offset of the temperature sensor or A/D converter. (See [Section 9. System Calibration](#) on page 40).

To use the Kelvin ($^{\circ}\text{K}$) scale, simply add 273 times $\Delta V_{BE} / AD_{FS} \times 2^{23}$ to T_{OFF} since $0^{\circ}\text{C} = 273^{\circ}\text{K}$. You will also need more range. Since -40°C to $+85^{\circ}\text{C}$ is 233°K to 358°K , a T_{FS} of 512 degrees should be used in the T_{GAIN} calculation.

To use the Fahrenheit ($^{\circ}\text{F}$) scale, multiply ΔV_{BE} by 5/9 and add 32 times the new $\Delta V_{BE} / AD_{FS} \times 2^{23}$ to T_{OFF} since $0^{\circ}\text{C} = 32^{\circ}\text{F}$. You will also want to use a T_{FS} of 256 degrees to cover the -40°C to $+85^{\circ}\text{C}$ range.

7. USING THE CS5467

7.1 Initialization

The CS5467 uses a power-on-reset circuit (POR) to provide an internal reset until the analog voltage reaches 4.0 V. The $\overline{\text{RESET}}$ input pin can also be used by the application circuit to reset the part.

After $\overline{\text{RESET}}$ is removed and the oscillator is stable, an initialization program is executed to set the default register values.

A Software Reset command is also provided to allow the application to run the initialization program without removing power or asserting $\overline{\text{RESET}}$.

The application should avoid sending commands during initialization. The DRDY bit in the *Status* register indicates when the initialization program has completed.

7.2 Power-down States

The CS5467 has two power-down states, stand-by and sleep. In the stand-by state, all circuitry except the voltage reference and crystal oscillator is powered off. In sleep state, all circuitry except the instruction decoder is powered off.

To return the device to the active state, send a Wake-up/Halt command to the device. When returning from stand-by mode, registers will retain their contents prior

to entering the stand-by state. When returning from sleep mode, a complete initialization occurs.

7.3 Voltage Tamper Correction

The CS5467 provides compensation for meter tampering on voltage channels.

If the application detects that the voltage input has been impaired it may choose to use the fixed internal RMS voltage reference by setting the VFIX bit in the *Modes* register. The value of this reference ($V_{F_{RMS}}$) is by default 0.707107 (full-scale RMS) but can be changed by the application program. (See figure 9)

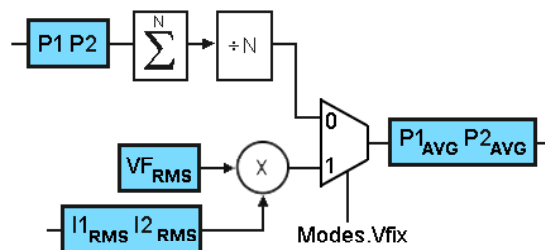


Figure 9. Fixed RMS Voltage Selection

7.4 Command Interface

Commands and data are transferred most-significant bit (MSB) first. [Figure 1](#) on page 12, defines the serial port timing. Commands are clocked in on SDI using SCLK. They are a single byte (8 bits) long and fall into one of four basic types:

1. Register Read
2. Register Write
3. Synchronizing
4. Instructions

Register reads will cause up to four bytes of register data to be clocked out, MSB first on the SDO pin by SCLK. During this time, other commands can be clocked in on the SDI pin. Other commands will not interrupt read data, except another register read, which will cause the new read data to appear on SDO.

Synchronizing can be sent while read data is being clocked out if no other commands need to be sent.

Synchronizing commands are also used to synchronize the serial port to a byte boundary. The \overline{CS} and \overline{RESET} pins will also synchronize the serial port.

Register writes require three bytes of write data to follow, clocked in on the SDI pin, MSB first by SCLK.

Instructions are commands that will interrupt any instruction currently executing and begin the new instruction. These include conversions, calibrations, power control, and soft reset.

(See [Section 7.6 Commands](#) on page 25).

7.5 Register Paging

Read and Write commands access one of 32 registers within a specified page. The Register Page Select register's (*Page*) default value is 0. To access registers in another page, write the desired page number to the *Page* register. The *Page* register is always at address 31 and is accessible from within any page.

7.6 Commands

All commands are 1 byte (8 bits) long. Many command values are unused and should NOT be written by the application program. All commands except register reads, register writes, or synchronizing commands will abort any conversion, calibration, or any initialization sequence currently executing. This includes reset. No commands other than reads or synchronizing should be executed until the reset sequence completes.

7.6.1 Conversion

| B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|----|----|----|----|----|----|----|----|
| 1 | 1 | 1 | 0 | CC | 0 | 0 | 0 |

Executes a conversion (measurement) program.

CC Continuous/Single Conversion
 0 = Perform a Single Conversion (0xE0)
 1 = Perform Continuous Conversion (0xE8)

7.6.2 Synchronization (SYNC0 and SYNC1)

| B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|----|----|----|----|----|----|----|------|
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | SYNC |

The serial interface is bidirectional. While reading data on the SDO output, the SDI input must be receiving commands. If no command is needed during a read, SYNC0 or SYNC1 commands can be sent while read data is received on SDO.

The serial port is normally initialized by de-asserting \overline{CS} . An alternative method of initialization is to send 3 or more SYNC1 commands followed by a SYNC0. This is useful in systems where \overline{CS} is not used and tied low.

7.6.3 Power Control (Stand-by, Sleep, Wake-up/Halt and Software Reset)

| B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|----|----|----|----|----|----|----|----|
| 1 | 0 | S1 | S0 | 0 | 0 | 0 | 0 |

The CS5467 has two power-down states, stand-by and sleep. In stand-by, all circuitry except the voltage reference and clocks are turned off. In sleep mode, all circuitry except the command decoder is turned off. A Wake-up/Halt command restores full-power operation after stand-by and issues a hardware reset after sleep. The Software Reset command is a program that emulates a pin reset and is not a power control function.

S[1:0] 00 = Software Reset
 01 = Sleep
 10 = Wake-up/Halt
 11 = Stand-by

7.6.4 Calibration

| B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|----|----|------|------|------|------|------|------|
| 1 | 0 | CAL5 | CAL4 | CAL3 | CAL2 | CAL1 | CAL0 |

The CS5467 can perform gain and offset calibrations using either DC or AC signals. Proper input levels must be applied to the current inputs and voltage input before performing calibrations.

CAL[5:4]* 00 = DC Offset
 01 = DC Gain
 10 = AC Offset
 11 = AC Gain

CAL[3:0] 0001 = Current for Channel 1
 0010 = Voltage for Channel 1
 0100 = Current for Channel 2
 1000 = Voltage for Channel 2

Note: Anywhere from 1 to all 4 channels can be calibrated simultaneously.

7.6.5 Register Read and Write

| B7 | B6 | B5 | B4 | B3 | B2 | B1 | B0 |
|----|-----|-----|-----|-----|-----|-----|----|
| 0 | W/R | RA4 | RA3 | RA2 | RA1 | RA0 | 0 |

Read and Write commands provide access to on-chip registers. After a Read command, the addressed data can be clocked out the SDO pin by SCLK. After a Write command, 24 bits of write data must follow. The data is transferred to the addressed register after the 24th data bit is received. Registers are organized into pages of 32 addresses each. To access a desired page, write its number to the *Page* register at address 31.

W/R Write/Read control
 0 = Read
 1 = Write

RA[4:0] Register address.

Page 0 Registers

| Address | RA[4:0] | Name | Description |
|---------|---------|--------------------|--|
| 0 | 00000 | Config | Configuration |
| 1 | 00001 | I1 | Instantaneous Current Channel 1 |
| 2 | 00010 | V1 | Instantaneous Voltage Channel 1 |
| 3 | 00011 | P1 | Instantaneous Power Channel 1 |
| 4 | 00100 | P1 _{AVG} | Active Power Channel 1 |
| 5 | 00101 | I1 _{RMS} | RMS Current Channel 1 |
| 6 | 00110 | V1 _{RMS} | RMS Voltage Channel 1 |
| 7 | 00111 | I2 | Instantaneous Current Channel 2 |
| 8 | 01000 | V2 | Instantaneous Voltage Channel 2 |
| 9 | 01001 | P2 | Instantaneous Power Channel 2 |
| 10 | 01010 | P2 _{AVG} | Active Power Channel 2 |
| 11 | 01011 | I2 _{RMS} | RMS Current Channel 2 |
| 12 | 01100 | V2 _{RMS} | RMS Voltage Channel 2 |
| 13 | 01101 | Q1 _{AVG} | Reactive Power Channel 1 |
| 14 | 01110 | Q1 | Instantaneous Quadrature Power Channel 1 |
| 15 | 01111 | Status | Internal Status |
| 16 | 10000 | Q2 _{AVG} | Reactive Power Channel 2 |
| 17 | 10001 | Q2 | Instantaneous Quadrature Power Channel 2 |
| 18 | 10010 | I1 _{PEAK} | Peak Current Channel 1 |
| 19 | 10011 | V1 _{PEAK} | Peak Voltage Channel 1 |
| 20 | 10100 | S1 | Apparent Power Channel 1 |
| 21 | 10101 | PF1 | Power Factor Channel 1 |
| 22 | 10110 | I2 _{PEAK} | Peak Current Channel 2 |
| 23 | 10111 | V2 _{PEAK} | Peak Voltage Channel 2 |
| 24 | 11000 | S2 | Apparent Power Channel 2 |
| 25 | 11001 | PF2 | Power Factor Channel 2 |
| 26 | 11010 | Mask | Interrupt Mask |
| 27 | 11011 | T | Temperature |
| 28 | 11100 | Ctrl | Control |
| 29 | 11101 | E _{PULSE} | Active Energy Pulse Output |
| 30 | 11110 | S _{PULSE} | Apparent Energy Pulse Output |
| 31 R | 11111 | Q _{PULSE} | Reactive Energy Pulse Output |
| 31 W | 11111 | Page | Register Page Select |

Warning: Do not write to unpublished register locations.

Page1 Registers

| <u>Address</u> | <u>RA[4:0]</u> | <u>Name</u> | <u>Description</u> |
|----------------|----------------|-------------------------------|--|
| 0 | 00000 | I1 _{OFF} | Current DC Offset Channel 1 |
| 1 | 00001 | I1 _{GAIN} | Current Gain Channel 1 |
| 2 | 00010 | V1 _{OFF} | Voltage DC Offset Channel 1 |
| 3 | 00011 | V1 _{GAIN} | Voltage Gain Channel 1 |
| 4 | 00100 | P1 _{OFF} | Power Offset Channel 1 |
| 5 | 00101 | I1 _{ACOFF} | Current AC (RMS) Offset Channel 1 |
| 6 | 00110 | V1 _{ACOFF} | Voltage AC (RMS) Offset Channel 1 |
| 7 | 00111 | I2 _{OFF} | Current DC Offset Channel 2 |
| 8 | 01000 | I2 _{GAIN} | Current Gain Channel 2 |
| 9 | 01001 | V2 _{OFF} | Voltage DC Offset Channel 2 |
| 10 | 01010 | V2 _{GAIN} | Voltage Gain Channel 2 |
| 11 | 01011 | P2 _{OFF} | Power Offset Channel 2 |
| 12 | 01100 | I2 _{ACOFF} | Current AC (RMS) Offset Channel 2 |
| 13 | 01101 | V2 _{ACOFF} | Voltage AC (RMS) Offset Channel 2 |
| 14 | 01110 | PulseWidth | Pulse Output Width |
| 15 | 01111 | PulseRate | Pulse Output Rate (frequency) |
| 16 | 10000 | Modes | Mode Control |
| 17 | 10001 | Epsilon | Ratio of Line to Sample Frequency |
| 19 | 10011 | N | Cycle Count (Number of OWR Samples in One Low-rate Interval) |
| 20 | 10100 | Q1 _{WB} | Wideband Reactive Power from Power Triangle Channel 1 |
| 21 | 10101 | Q2 _{WB} | Wideband Reactive Power from Power Triangle Channel 2 |
| 22 | 10110 | T _{GAIN} | Temperature Sensor Gain |
| 23 | 10111 | T _{OFF} | Temperature Sensor Offset |
| 25 | 11001 | T _{SETTLE} | Filter Settling Time for Conversion Startup |
| 26 | 11010 | Load _{MIN} | No Load Threshold |
| 27 | 11011 | V _F _{RMS} | Voltage RMS Fixed Reference |
| 28 | 11100 | G | System Gain |
| 29 | 11101 | Time | System Time (in samples) |
| 31 W | 11111 | Page | Register Page Select |

Page2 Registers

| <u>Address</u> | <u>RA[4:0]</u> | <u>Name</u> | <u>Description</u> |
|----------------|----------------|--------------------------|----------------------------|
| 0 | 00000 | V1Sag _{DUR} | V Sag Duration Channel 1 |
| 1 | 00001 | V1Sag _{LEVEL} | V Sag Level Channel 1 |
| 4 | 00100 | I1Fault _{DUR} | I Fault Duration Channel 1 |
| 5 | 00101 | I1Fault _{LEVEL} | I Fault Level Channel 1 |
| 8 | 01000 | V2Sag _{DUR} | V Sag Duration Channel 2 |
| 9 | 01001 | V2Sag _{LEVEL} | V Sag Level Channel 2 |
| 12 | 01100 | I2Fault _{DUR} | I Fault Duration Channel 2 |
| 13 | 01101 | I2Fault _{LEVEL} | I Fault Level Channel 2 |
| 31 W | 11111 | Page | Register Page Select |

Page5 Register

| <u>Address</u> | <u>RA[4:0]</u> | <u>Name</u> | <u>Description</u> |
|----------------|----------------|-------------------|-------------------------|
| 26 | 11010 | T _{MEAS} | Temperature Measurement |
| 31 W | 11111 | Page | Register Page Select |

Warning: *Do not* write to unpublished register locations.

8. REGISTER DESCRIPTIONS

1. "Default" = bit states after power-on or reset
2. DO NOT write a "1" to any unpublished register bit.
3. DO NOT write to any unpublished register address.

8.1 Page Register

8.1.1 *Page* – Address: 31, Write-only, can be written from ANY page.

| MSB | | | | | LSB | |
|----------------|----------------|----------------|----------------|----------------|----------------|----------------|
| 2 ⁶ | 2 ⁵ | 2 ⁴ | 2 ³ | 2 ² | 2 ¹ | 2 ⁰ |

Default = 0

Register Read and Write commands contain only 5 address bits. But the internal address bus of the CS5467 is 12 bits wide. Therefore, registers are organized into "Pages". There are 128 pages of 32 registers each. The *Page* register provides the 7 high-order address bits and selects one of the 128 register pages. Not all pages are used,

Page is a write-only integer containing 7 bits.

8.2 Page 0 Registers

8.2.1 *Configuration (Config)* – Address: 0

| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
|-----|-----|-----|-------|------|-----|-----|-----|
| PC7 | PC6 | PC5 | PC4 | PC3 | PC2 | PC1 | PC0 |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| EWA | - | - | IMODE | IINV | - | - | - |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| - | - | - | iCPU | K3 | K2 | K1 | K0 |

Default = 1 (K=1)

PC[7:0] Phase compensation for channel 1. Sets a delay in voltage, relative to current. Phase is signed and in the range of $-1.0 \leq \text{value} < 1.0$ sample (OWR) intervals.

EWA Allows the $\overline{E1}$ and $\overline{E2}$ pins to be configured as open-drain outputs.
 0 = Normal Outputs
 1 = Open-drain Outputs

IMODE, IINV Interrupt configuration. Selects \overline{INT} pin behavior.
 00 = Low Logic Level When Asserted
 01 = High Logic Level When Asserted
 10 = Low-going Pulse on New Interrupt
 11 = High-going Pulse on New Interrupt

iCPU Inverts the CPUCLK output.
 0 = Default
 1 = Invert CPUCLK.

K[3:0] Clock divider. Divides MCLK by K to generate internal clock DCLK. (DCLK = MCLK/K). K is unsigned and in the range of 1 to 16. When zero, K = 16. At reset, K = 1.

8.2.2 Instantaneous Current ($I1$, $I2$), Voltage ($V1$, $V2$), and Power ($P1$, $P2$)

Address: 1 ($I1$), 2 ($V1$), 3 ($P2$), 7 ($I2$), 8 ($V2$), 9 ($P2$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

$I1$ ($I2$) and $V1$ ($V2$) contain instantaneous current and voltage, respectively, which are multiplied to yield instantaneous power, $P1$ ($P2$). These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.2.3 Active Power ($P1_{AVG}$, $P2_{AVG}$)

Address: 4 ($P1_{AVG}$), 10 ($P2_{AVG}$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Instantaneous power is averaged over each low-rate interval (N samples) to compute active power, $P1_{AVG}$ ($P2_{AVG}$). These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.2.4 RMS Current ($I1_{RMS}$, $I2_{RMS}$) and Voltage ($V1_{RMS}$, $V2_{RMS}$)

Address: 5 ($I1_{RMS}$), 6 ($V1_{RMS}$), 11 ($I2_{RMS}$), 12 ($V2_{RMS}$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | 2^{-8} | | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} | 2^{-24} |

$I1_{RMS}$ ($I2_{RMS}$) and $V1_{RMS}$ ($V2_{RMS}$) contain the root mean square (RMS) values of $I1$ ($I2$) and $V1$ ($V2$), calculated each low-rate interval. These are unsigned values in the range of $0 \leq \text{value} < 1.0$, with the binary point to the left of the MSB.

8.2.5 Instantaneous Quadrature Power ($Q1$, $Q2$)

Address: 14 ($Q1$), 17 ($Q2$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Instantaneous quadrature power, $Q1$ ($Q2$), the product of voltage1 (voltage2) shifted 90 degrees and current1 (current2). These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.2.6 Reactive Power ($Q1_{AVG}$, $Q2_{AVG}$)

Address: 13 ($Q1_{AVG}$), 16 ($Q2_{AVG}$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Reactive power $Q1_{AVG}$ ($Q2_{AVG}$) is $Q1$ ($Q2$) averaged over every N samples. These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.2.7 Peak Current ($I1_{PEAK}$, $I2_{PEAK}$) and Peak Voltage ($V1_{PEAK}$, $V2_{PEAK}$)

Address: 18 ($I1_{PEAK}$), 19 ($V1_{PEAK}$), 22 ($I2_{PEAK}$), 23 ($V2_{PEAK}$)

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Peak current, $I1_{PEAK}$ ($I2_{PEAK}$) and peak voltage, $V1_{PEAK}$ ($V2_{PEAK}$) are the instantaneous current and voltage samples with the greatest magnitude detected during the last low-rate interval. These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.2.8 Apparent Power ($S1$, $S2$)

Address: 20 ($S1$), 24 ($S2$)

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Apparent power $S1$ ($S2$) is the product of $V1_{RMS}$ and $I1_{RMS}$ ($V2_{RMS}$ and $I2_{RMS}$). These are two's complement values in the range of $0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.2.9 Power Factor ($PF1$, $PF2$)

Address: 21 ($PF1$), 25 ($PF2$)

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Power factor is calculated by dividing active power by apparent power. The sign is determined by the active power sign. These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.2.10 Temperature (T) – Address: 27

| MSB | | | | | | | | | LSB | | | | | | |
|----------|-------|-------|-------|-------|-------|-------|-------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^7)$ | 2^6 | 2^5 | 2^4 | 2^3 | 2^2 | 2^1 | 2^0 | | 2^{-10} | 2^{-11} | 2^{-12} | 2^{-13} | 2^{-14} | 2^{-15} | 2^{-16} |

T contains results from the on-chip temperature measurement. By default, T uses the Celsius scale, and is a two's complement value in the range of $-128.0 \leq \text{value} < 128.0$ ($^{\circ}\text{C}$), with the binary point to the right of bit 16.

T can be rescaled by the application using the T_{GAIN} and T_{OFF} registers.

8.2.11 Active, Apparent, and Reactive Energy Pulse Outputs (E_{PULSE} , S_{PULSE} , Q_{PULSE})

Address: 29 (E_{PULSE}), 30 (S_{PULSE}), 31 (Q_{PULSE})

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

These drive the pulse outputs when configured to do so. These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB. Refer to [4.8 Power and Energy Results](#) on page 16.

8.2.12 Internal Status (Status) and Interrupt Mask (Mask)

Address: 15 (Status); 26 (Mask)

| | | | | | | | |
|-----------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
| DRDY | I2OR | V2OR | CRDY | I2ROR | V2ROR | I1OR | V1OR |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| E2OR | I1ROR | V1ROR | E1OR | I1FAULT | V1SAG | I2FAULT | V2SAG |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| TUP | V2OD | I2OD | V1OD | I1OD | LSD | FUP | IC |

Default = 1 (Status), 0 (Mask)

The *Status* register indicates a variety of conditions within the chip. Writing a '1' to a *Status* register bit will clear that bit if the condition that set it has been removed. Writing a '0' to any bit has no effect.

The *Mask* register is used to control the activation of the $\overline{\text{INT}}$ pin. Writing a '1' to a *Mask* register bit will allow the corresponding *Status* register bit to activate the $\overline{\text{INT}}$ pin when set.

| | |
|-------------------|--|
| DRDY | Data Ready. During conversion, this bit indicates that low-rate results have been updated. It indicates completion of other commands and the reset sequence. |
| I1OR (I2OR) | Current Out of Range. Set when the measured current would cause the <i>I1</i> (<i>I2</i>) register to overflow. |
| V1OR (V2OR) | Voltage Out of Range. Set when the measured voltage would cause the <i>V1</i> (<i>V2</i>) register to overflow. |
| CRDY | Conversion Ready. Indicates that sample rate (output word rate) results have been updated. |
| I1ROR (I2ROR) | RMS Current Out of Range. Set when RMS current would cause the <i>I1_{RMS}</i> (<i>I2_{RMS}</i>) register to overflow. |
| V1ROR (V2ROR) | RMS Voltage Out of Range. Set when RMS voltage would cause the <i>V1_{RMS}</i> (<i>V2_{RMS}</i>) register to overflow. |
| E1OR (E2OR) | Energy Out of Range. Set when average power would cause <i>P1_{AVG}</i> (<i>P2_{AVG}</i>) to overflow. |
| I1FAULT (I2FAULT) | Indicates when a current fault condition has occurred. |
| V1SAG (V2SAG) | Indicates when a voltage sag condition has occurred. |
| TUP | Indicates when the Temperature register (<i>T</i>) has been updated. |
| V1OD (V2OD) | Modulator oscillation has been detected in the voltage1 (voltage2) A/D. |
| I1OD (I2OD) | Modulator oscillation has been detected in the current1 (current2) A/D. |
| LSD | Low Supply Detect. Set when the voltage on the PFMON pin falls below the specified low level. The LSD bit cannot be reset until the voltage rises above the specified high level. |
| FUP | Frequency Updated. Indicates the <i>Epsilon</i> register has been updated. |
| IC | Invalid Command. Normally logic 1. Set to 0 when an invalid command is received. It may also indicate loss of serial command synchronization and the part may need to be re-initialized. |

8.2.13 Control (Ctrl) – Address: 28

| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
|-----|-----|--------|--------|-----|-------|-------|------|
| PC7 | PC6 | PC5 | PC4 | PC3 | PC2 | PC1 | PC0 |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| - | - | - | I2gain | - | - | - | STOP |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| - | - | I1gain | INTOD | - | NOCPU | NOOSC | - |

Default = 0

PC[7:0] Phase compensation for channel 2. Sets a delay in voltage relative to current. Phase is signed and in the range of $-1.0 \leq \text{value} < 1.0$ sample (OWR) intervals.

I1gain (I2gain) Sets the gain of the current1 (current2) input.
 0 = Gain is set for $\pm 250\text{mV}$ range.
 1 = Gain is set for $\pm 50\text{mV}$ range.

STOP Terminates E²PROM command sequence (if used).
 0 = No Action
 1 = Stop E²PROM Commands.

INTOD Converts $\overline{\text{INT}}$ output pin to an open drain output.
 0 = Normal Output
 1 = Open-drain Output

NOCPU Saves power by disabling the CPUCLK output pin.
 0 = CPUCLK Enabled
 1 = CPUCLK Disabled

NOOSC Disables the crystal oscillator, making XIN a logic-level input.
 0 = Crystal Oscillator Enabled
 1 = Crystal Oscillator Disabled

8.3 Page 1 Registers

8.3.1 DC Offset for Current ($I1_{OFF}$, $I2_{OFF}$) and Voltage ($V1_{OFF}$, $V2_{OFF}$)

Address: 0 ($I1_{OFF}$), 2 ($V1_{OFF}$), 7 ($I2_{OFF}$), 9 ($V2_{OFF}$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = 0

DC offset registers $I1_{OFF}$ & $V1_{OFF}$ ($I2_{OFF}$ & $V2_{OFF}$) are initialized to zero on reset. During DC offset calibration, selected registers are written with the inverse of the DC offset measured. The application program can also write the DC offset register values. These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.3.2 Gain for Current ($I1_{GAIN}$, $I2_{GAIN}$) and Voltage ($V1_{GAIN}$, $V2_{GAIN}$)

Address: 1 ($I1_{GAIN}$), 3 ($V1_{GAIN}$), 8 ($I2_{GAIN}$), 10 ($V2_{GAIN}$)

| MSB | | | | | | | | LSB | | | | | | | |
|-------|-------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| 2^1 | 2^0 | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | | 2^{-16} | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} |

Default = 1.0

Gain registers $I1_{GAIN}$ & $V1_{GAIN}$ ($I2_{GAIN}$ & $V2_{GAIN}$) are initialized to 1.0 on reset. During AC or DC gain calibration, selected register are written with the multiplicative inverse of the gain measured. These are unsigned fixed-point values in the range of $0 \leq \text{value} < 4.0$, with the binary point to the right of the second MSB.

8.3.3 Power Offset ($P1_{OFF}$, $P2_{OFF}$)

Address: 4 ($P1_{OFF}$), 11 ($P2_{OFF}$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = 0

Power offset $P1_{OFF}$ ($P2_{OFF}$) is added to instantaneous power and averaged over a low-rate interval to yield $P1_{AVG}$ ($P2_{AVG}$) register results. It can be used to reduce systematic energy errors. These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.3.4 AC Offset for Current ($I1_{ACOFF}$, $I2_{ACOFF}$) and Voltage ($V1_{ACOFF}$, $V2_{ACOFF}$)

Address: 5 ($I1_{ACOFF}$), 6 ($V1_{ACOFF}$), 12 ($I2_{ACOFF}$), 13 ($V2_{ACOFF}$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = 0

AC offset registers $I1_{ACOFF}$ & $V1_{ACOFF}$ ($I2_{ACOFF}$ & $V2_{ACOFF}$) are initialized to zero on reset. These are added to the RMS results before being stored to the RMS result registers. They can be used to reduce systematic errors in the RMS results. These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB.

8.3.5 Mode Control (Modes) – Address: 16

| 23 | 22 | 21 | 20 | 19 | 18 | 17 | 16 |
|-------|---------|---------|----|---------|---------|---------|-------|
| - | VFIX | - | - | - | - | - | - |
| 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 |
| - | E1MODE1 | E1MODE0 | - | - | E2MODE1 | E2MODE0 | VHPF2 |
| 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| IHPF2 | VHPF1 | IHPF1 | - | E3MODE1 | E3MODE0 | POS | AFC |

Default = 0

| | |
|-------------|---|
| VFIX | Use internal RMS voltage reference instead of voltage input for average active power. 0 = Use voltage input. 1 = Use internal RMS voltage reference, V_{RMS} . |
| E1MODE[1:0] | $\overline{E1}$, $\overline{E2}$, and $\overline{E3}$ alternate output mode (when enabled by E2MODE). 00 = $\overline{E1}$, $\overline{E2}$ = $P1_{AVG}$, $P2_{AVG}$ 01 = $\overline{E1}$, $\overline{E2}$ = $S1$, $S2$ 10 = $\overline{E1}$, $\overline{E2}$ = $Q1_{AVG}$, $Q2_{AVG}$ 11 = $\overline{E1}$, $\overline{E2}$ = $Q1_{WB}$, $Q2_{WB}$ |
| E2MODE[1:0] | $\overline{E2}$ Output Mode 00 = Energy Sign 01 = Total Apparent Energy 10 = Not Used 11 = Enable E1MODE |
| VHPF2:IHPF2 | High-pass Filter Enable for Energy Channel 2 00 = No Filter 01 = HPF on Current, PMF on Voltage 10 = HPF on Voltage, PMF on Current 11 = HPF on both Voltage and Current |
| VHPF1:IHPF1 | High-pass Filter Enable for Energy Channel 1 00 = No Filter 01 = HPF on Current, PMF on Voltage 10 = HPF on Voltage, PMF on Current 11 = HPF on both Voltage and Current |
| E3MODE[1:0] | $\overline{E3}$ Output Mode (with E1MODE disabled) 00 = Total Reactive Energy (default) 01 = Power Fail Monitor 10 = Voltage1 Sign 11 = Total Apparent Energy |
| E3MODE[1:0] | $\overline{E3}$ Output Mode (with E1MODE enabled) 00 = Power Fail Monitor 01 = Energy Sign 10 = Not Used 11 = Not Used |
| POS | Positive Energy Only. Suppresses negative values in $P1_{AVG}$ and $P2_{AVG}$. If a negative value is calculated, zero will be stored instead. |
| AFC | Enables automatic line frequency measurement which sets <i>Epsilon</i> every time a new line frequency measurement completes. <i>Epsilon</i> is used to control the gain of the 90 degree phase shift integrator used in quadrature power calculations. |

8.3.6 Line to Sample Frequency Ratio (Epsilon) – Address: 17

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = 0.0125 (4.0 kHz x 0.0125 or 50 Hz)

Epsilon is the ratio of the input line frequency to the output word rate (OWR). It can either be written by the application program or calculated automatically from the line frequency (from the voltage input) using the AFC bit in the *Modes* register. It is a two's complement value in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB. Negative values are not used.

8.3.7 Pulse Output Width (PulseWidth) – Address: 14

| MSB | | | | | | | | | LSB | | | | | | |
|-----|----------|----------|----------|----------|----------|----------|----------|-------|-------|-------|-------|-------|-------|-------|-------|
| 0 | 2^{22} | 2^{21} | 2^{20} | 2^{19} | 2^{18} | 2^{17} | 2^{16} | | 2^6 | 2^5 | 2^4 | 2^3 | 2^2 | 2^1 | 2^0 |

Default = 1 (250 uS at OWR = 4 kHz)

PulseWidth sets the duration of energy pulses. The actual pulse duration is the contents of *PulseWidth* divided by the output word rate (OWR). *PulseWidth* is an integer in the range of 1 to 8,388,607.

8.3.8 Pulse Output Rate (PulseRate) – Address: 15

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = -1

PulseRate sets the full-scale frequency for $\overline{E1}$, $\overline{E2}$, $\overline{E3}$ pulse outputs. For a 4 kHz sample rate, the maximum pulse rate is 2 kHz. This is a two's complement value in the range of $-1 \leq \text{value} < 1$, with the binary point to the left of the MSB.

Refer to [6.10 Energy Pulse Rate](#) on page 21 for more information.

8.3.9 Cycle Count (N) – Address: 19

| MSB | | | | | | | | | LSB | | | | | | |
|-----|----------|----------|----------|----------|----------|----------|----------|-------|-------|-------|-------|-------|-------|-------|-------|
| 0 | 2^{22} | 2^{21} | 2^{20} | 2^{19} | 2^{18} | 2^{17} | 2^{16} | | 2^6 | 2^5 | 2^4 | 2^3 | 2^2 | 2^1 | 2^0 |

Default = 4000

Determines the number of output word rate (OWR) samples to use in calculating low-rate results. Cycle Count (*N*) is an integer in the range of 10 to 8,388,607. Values less than 10 should not be used.

8.3.10 Wideband Reactive Power ($Q1_{WB}$, $Q2_{WB}$)

Address: 20 ($Q1_{WB}$), 21 ($Q2_{WB}$)

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Wideband reactive power is calculated using vector subtraction. (See [Section 4.8 Power and Energy Results](#) on page 16). The value is signed, but has a range of $0 \leq \text{value} < 1.0$. The binary point is to the right of the MSB.

8.3.11 Temperature Gain (T_{GAIN}) – Address: 22

| MSB | | | | | | | | | LSB | | | | | | |
|-------|-------|-------|-------|-------|-------|-------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| 2^6 | 2^5 | 2^4 | 2^3 | 2^2 | 2^1 | 2^0 | 2^{-1} | | 2^{-11} | 2^{-12} | 2^{-13} | 2^{-14} | 2^{-15} | 2^{-16} | 2^{-17} |

Default = 0x2F02C3

Refer to [6.13 Temperature Measurement](#) on page 22 for more information.

8.3.12 Temperature Offset (T_{OFF}) – Address: 23

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = 0xF3D35A

Refer to [6.13 Temperature Measurement](#) on page 22 for more information.

8.3.13 Filter Settling Time for Conversion Startup (T_{SETTLE}) – Address: 25

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-------|-------|-------|-------|-------|-------|-------|
| 2^{23} | 2^{22} | 2^{21} | 2^{20} | 2^{19} | 2^{18} | 2^{17} | 2^{16} | | 2^6 | 2^5 | 2^4 | 2^3 | 2^2 | 2^1 | 2^0 |

Default = 30

Sets the number of output word rate (OWR) samples that will be used to allow filters to settle at the beginning of Conversion and Calibration commands. This is an integer in the range of 0 to 8,388,607 samples.

8.3.14 No Load Threshold ($Load_{MIN}$) – Address: 26

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = 0

$Load_{MIN}$ is used to set the no load threshold. When the magnitude of the E_{PULSE} register is less than $Load_{MIN}$, E_{PULSE} will be zeroed. If the magnitude of the Q_{PULSE} register is less than $Load_{MIN}$, Q_{pulse} will be zeroed. $Load_{MIN}$ is a two's complement value in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB. Negative values are not used.

8.3.15 Voltage Fixed RMS Reference (VF_{RMS}) – Address 27

| MSB | | | | | | | | | LSB | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = 0.7071068 (full scale RMS)

If the application program detects that the meter has possibly been tampered with in such a manner that the voltage input is no longer working, it may choose to use this internal RMS reference instead of the disabled voltage input by setting the VFIX bit in the *Modes* register. This is a two's complement value in the range of $0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB. Negative values are not used.

8.3.16 System Gain (*G*) – Address: 28

| MSB | | | | | | | | LSB | | | | | | | |
|----------|-------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^1)$ | 2^0 | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | | 2^{-16} | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} |

Default = 1.25

System Gain (*G*) is applied to all channels. By default, $G = 1.25$, but can be finely adjusted to compensate for voltage reference error. It is a two's complement value in the range of $-2.0 \leq \text{value} < 2.0$, with the binary point to the right of the second MSB. Values should be kept within 5% of 1.25.

8.3.17 System Time (*Time*) – Address: 29

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-------|-------|-------|-------|-------|-------|-------|
| 2^{23} | 2^{22} | 2^{21} | 2^{20} | 2^{19} | 2^{18} | 2^{17} | 2^{16} | | 2^6 | 2^5 | 2^4 | 2^3 | 2^2 | 2^1 | 2^0 |

Default = 0

System Time (*Time*) is measured in output word rate (OWR) samples. This is an unsigned integer in the range of 0 to 16,777,215 samples. At $\text{OWR} = 4.0 \text{ kHz}$, OWR will overflow every 1 hour, 9 minutes, and 54 seconds. *Time* can be used by the application to manage real-time events.

8.4 Page 2 Registers

8.4.1 Voltage Sag and Current Fault Duration ($V1Sag_{DUR}$, $V2Sag_{DUR}$, $I1Fault_{DUR}$, $I2Fault_{DUR}$)

Address: 0 ($V1Sag_{DUR}$), 8 ($V2Sag_{DUR}$), 4 ($I1Fault_{DUR}$), 12 ($I2Fault_{DUR}$)

| MSB | | | | | | | | LSB | | | | | | | |
|-----|----------|----------|----------|----------|----------|----------|----------|-------|-------|-------|-------|-------|-------|-------|-------|
| 0 | 2^{22} | 2^{21} | 2^{20} | 2^{19} | 2^{18} | 2^{17} | 2^{16} | | 2^6 | 2^5 | 2^4 | 2^3 | 2^2 | 2^1 | 2^0 |

Default = 0

Voltage sag duration, $V1Sag_{DUR}$ ($V2Sag_{DUR}$) and current fault duration, $I1Fault_{DUR}$ ($I2Fault_{DUR}$) determine the count of output word rate (OWR) samples utilized to determine a sag or fault event. These are integers in the range of 0 to 8,388,607 samples. A value of zero disables the feature.

8.4.2 Voltage Sag and Current Fault Level ($V1Sag_{LEVEL}$, $V2Sag_{LEVEL}$, $I1Fault_{LEVEL}$, $I2Fault_{LEVEL}$)

Address: 1 ($V1Sag_{LEVEL}$), 9 ($V2Sag_{LEVEL}$), 5 ($I1Fault_{LEVEL}$), 13 ($I2Fault_{LEVEL}$)

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-----------|-----------|-----------|-----------|-----------|-----------|-----------|
| $-(2^0)$ | 2^{-1} | 2^{-2} | 2^{-3} | 2^{-4} | 2^{-5} | 2^{-6} | 2^{-7} | | 2^{-17} | 2^{-18} | 2^{-19} | 2^{-20} | 2^{-21} | 2^{-22} | 2^{-23} |

Default = 0

Voltage sag level, $V1Sag_{LEVEL}$ ($V2Sag_{LEVEL}$) and current fault level, $I1Fault_{LEVEL}$ ($I2Fault_{LEVEL}$) establish an input level below which a sag or fault is triggered. These are two's complement values in the range of $-1.0 \leq \text{value} < 1.0$, with the binary point to the right of the MSB. Negative values are not used.

8.5 Page 5 Register

8.5.1 Temperature Measurement (T_{MEAS}) – Address: 26

| MSB | | | | | | | | LSB | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|-------|-------|-------|-------|-------|-------|-------|-------|
| 2^{23} | 2^{22} | 2^{21} | 2^{20} | 2^{19} | 2^{18} | 2^{17} | 2^{16} | | 2^6 | 2^5 | 2^4 | 2^3 | 2^2 | 2^1 | 2^0 |

Default = 0

The Temperature Measurement (T_{MEAS}) register is used to cycle-steal voltage channel2 for temperature measurement. Writing a one to the LSB causes the temperature to be measured and the Temperature register (T) to be updated.

Refer to [6.13 Temperature Measurement](#) on page 22 for more information.

9. SYSTEM CALIBRATION

9.1 Calibration

The CS5467 provides DC offset and gain calibration that can be applied to the voltage and current measurements, and AC offset calibration which can be applied to the voltage and current RMS calculations.

Since the voltage and current channels have independent offset and gain registers, offset and gain calibration can be performed on any channel independently.

The data flow of the calibration is shown in Figure 10.

The CS5467 must be operating in its active state and ready to accept valid commands. Refer to 7.6 *Commands* on page 25.

The value in the Cycle Count register (N) determines the number of output word rate (OWR) samples that are averaged during a calibration. DC offset and gain calibrations take at least $N + T_{SETTLE}$ samples. AC offset calibrations take at least $6(N) + T_{SETTLE}$ samples. As N is increased, the accuracy of calibration results tends to also increase.

The DRDY bit in the *Status* register will be set at the completion of Calibration commands. If an overflow occurs during calibration, other *Status* register bits may be set as well.

9.1.1 Offset Calibration

During offset calibrations, no line voltage or current should be applied to the meter. A zero-volt differential signal can also be applied to the voltage inputs $VIN1\pm$ ($VIN2\pm$) or current inputs $IIN1\pm$ ($IIN2\pm$) of the CS5467. (see Figure 11.)

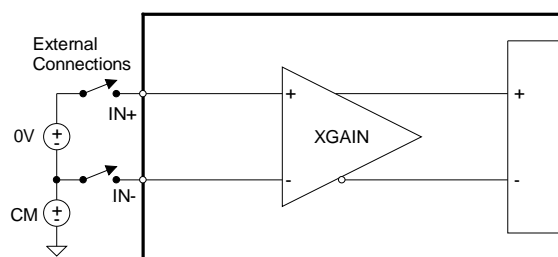


Figure 11. System Calibration of Offset

9.1.1.1 DC Offset Calibration

The DC Offset Calibration command measures and averages DC values read on specified voltage or current channels at zero input and stores the inverse result in the associated offset registers. This will be added to instantaneous measurements in subsequent conversions, removing the offset.

Gain registers for channels being calibrated should be set to 1.0 prior to performing DC offset calibration.

9.1.1.2 AC Offset Calibration

The AC Offset Calibration command measures the residual RMS values read on specified voltage or current channels at zero input and stores the inverse result in the associated AC offset registers. This will be added to RMS measurements in subsequent conversions, removing the offset.

AC offset registers for channels being calibrated should first be cleared prior to performing the calibration.

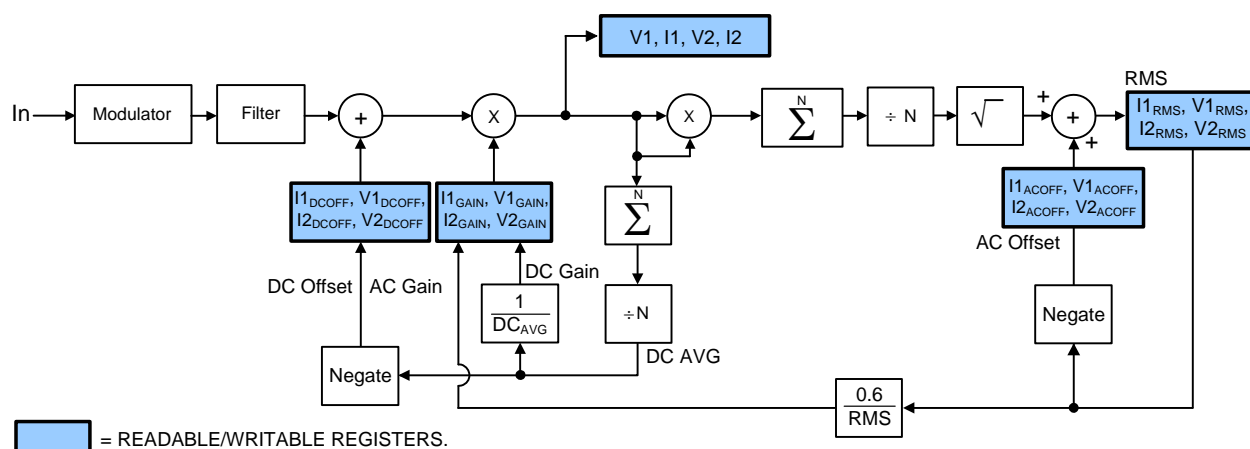


Figure 10. Calibration Data Flow

9.1.2 Gain Calibration

During gain calibration, a full-scale reference signal must be applied to the meter or optionally, scaled to the $VIN1\pm$ ($VIN2\pm$), $IIN1\pm$ ($IIN2\pm$) pins of the CS5467. A DC reference must be used for DC gain calibration. Either an AC or DC reference can be used for RMS AC calibrations. If DC is used, the associated high-pass filter (HPF) must be off.

Figure 12 shows the basic setup for gain calibration.

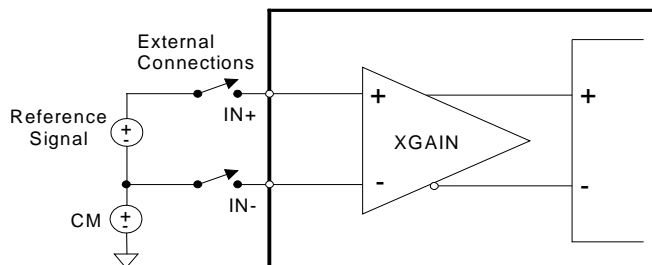


Figure 12. System Calibration of Gain.

Using a reference that is too large or too small can cause an over-range condition during calibration. Either condition can set *Status* register bits $I1OR$ ($I2OR$) $V1OR$ ($V2OR$) for DC and $I1ROR$ ($I2ROR$) $V1ROR$ ($V2ROR$) for AC calibration.

Full scale (FS) for the voltage input is ± 250 mV peak and for the current inputs is ± 250 mV or ± 50 mV peak depending on selected gain range. The normal peak voltage applied to these pins should not exceed these levels during calibration or normal operation.

The range of the gain registers limits the gain calibration range and subsequently the range of the reference level that can be applied. The reference should not exceed FS or be lower than FS/4.

9.1.2.1 AC Gain Calibration

Full scale for AC RMS gain calibrations is 60% of the input's full-scale range, which is either 250 mV or 50 mV depending on the gain range selected. That's 150 mV or 30 mV, again depending on range. So the normal reference input level should be either 150 or 30 mV_{RMS}, AC or DC.

Prior to executing an AC Gain Calibration command, gain registers for any channel to be calibrated should be set to 1.0 if the reference level mentioned above is used, or to that level divided by the actual reference level used.

During AC gain calibration the RMS level of the applied reference is measured with the preset gain, then divided into 0.6 and the quotient stored back into the corresponding gain register.

9.1.2.2 DC Gain Calibration

With a DC reference applied, the DC Gain Calibration command measures and averages DC values read on the specified voltage or current channels and stores the reciprocal result in the associated gain registers, converting measured voltage into needed gain. Subsequent conversions will use the new gain value.

9.1.3 Calibration Order

1. DC offset.
2. DC or AC gain.
3. AC offset (if needed).

If both AC gain and offset calibrations were performed, it is possible to repeat both to obtain additional accuracy as AC gain and offset may interact.

9.1.4 Temperature Sensor Calibration

Temperature sensor calibration involves the adjustment of two parameters - ΔV_{BE} and V_{BE0} . These values must be known in order to calibrate the temperature sensor. See [Section 6.13 Temperature Measurement](#) on page 22 for an explanation of ΔV_{BE} and V_{BE0} and how to calculate T_{GAIN} and T_{OFF} register values from them.

9.1.4.1 Temperature Offset Calibration

Offset calibration can be done at any temperature, but should be done mid-scale if any gain error exists.

Subtract the measured T register temperature from the actual temperature to determine the offset error. Multiply this error by ΔV_{BE} and add it to V_{BE0} to yield a new V_{BE0} value. Recalculate T_{OFF} using this new value.

9.1.4.2 Temperature Gain Calibration

Two temperature points far enough apart to give reasonable accuracy, for example 25°C and 85°C, are required to calibrate temperature gain.

Divide the actual temperature difference by the measured (T register) difference for the two temperatures. This gives a gain correction factor. Update the T_{GAIN} register by multiplying its value by this correction factor.

Update ΔV_{BE} by dividing its old value by the gain correction factor. It will be needed for subsequent offset calibrations.

10. E²PROM OPERATION

The CS5467 can accept commands from a serial E²PROM connected to the serial interface instead of a host microcontroller. A high level (logic 1) on the MODE input indicates that an E²PROM is connected. This makes the $\overline{\text{CS}}$ and SCLK pins become driven outputs. After reset and after running the initialization program, the CS5467 begins reading commands from the connected E²PROM.

10.1 E²PROM Configuration

A typical connection between the CS5467 and a E²PROM is shown in Figure 13.

The CS5467 asserts $\overline{\text{CS}}$ (logic 0), clocks SCLK, and sends Read commands to the E²PROM on SDO.

Command format is identical to microcontroller mode, except the CS5467 will not attempt to write to the EEPROM device. The command sequence stops when the STOP bit in the Control register (*Ctrl*) is written by the command sequence.

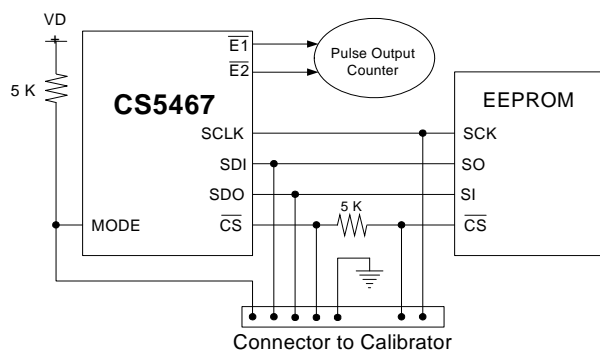


Figure 13. Typical Interface of E²PROM to CS5467

Figure 13 also shows the external connections that would be made to a calibration device, such as a notebook computer, handheld calibrator, or tester during meter assembly. The calibrator or tester can be used to control the CS5467 during calibration and program the required values into the E²PROM.

10.2 E²PROM Code

The EEPROM code should do the following:

1. Set any Configuration or Control register bits, such as HPF enables and phase compensation settings.
2. Write any calibration data to gain and offset registers.
3. Set energy output pulse width, rate, and formats.
4. Execute a Continuous Conversion command.
5. Set the STOP bit in the Control register (last).

Below is an example E²PROM code set.

```
-7E 00 00 01
  Change to page 1.
-60 00 01 E0
  Write Modes Register, turn high-pass filters on.
-42 7F C4 A9
  Write value of 0x7FC4A9 to I1_GAIN register.
-46 FF B2 53
  Write value of 0xFFB253 to V1_GAIN register.
-50 7F C4 A9
  Write value of 0x7FC4A9 to I2_GAIN register.
-54 FF B2 53
  Write value of 0xFFB253 to V2_GAIN register.
-7E 00 00 00
  Change to page 0.
-74 00 00 04
  Set LSD bit to 1 in the Mask register.
-E8
  Start continuous conversions
-78 00 01 00
  Write STOP bit to the Control register (Ctrl) to
  terminate E2PROM command sequence.
```

10.3 Which E²PROMs Can Be Used?

Several industry-standard serial E²PROMs can be used with the CS5467. Some are listed below:

- Atmel AT25010, AT25020 or AT25040
- National Semiconductor NM25C040M8 or NM25020M8
- Xicor X25040SI

These serial E²PROMs expect a specific 8-bit command (00000011) in order to perform a memory read. The CS5467 has been hardware programmed to transmit this 8-bit command to the E²PROM after reset.

11. BASIC APPLICATION CIRCUITS

Figure 14 shows the CS5467 configured to measure power in a single-phase, 3-wire system while operating in a single-supply configuration. In this diagram, current

transformers (CT) are used to sense the line currents and voltage dividers are used to sense the line voltages.

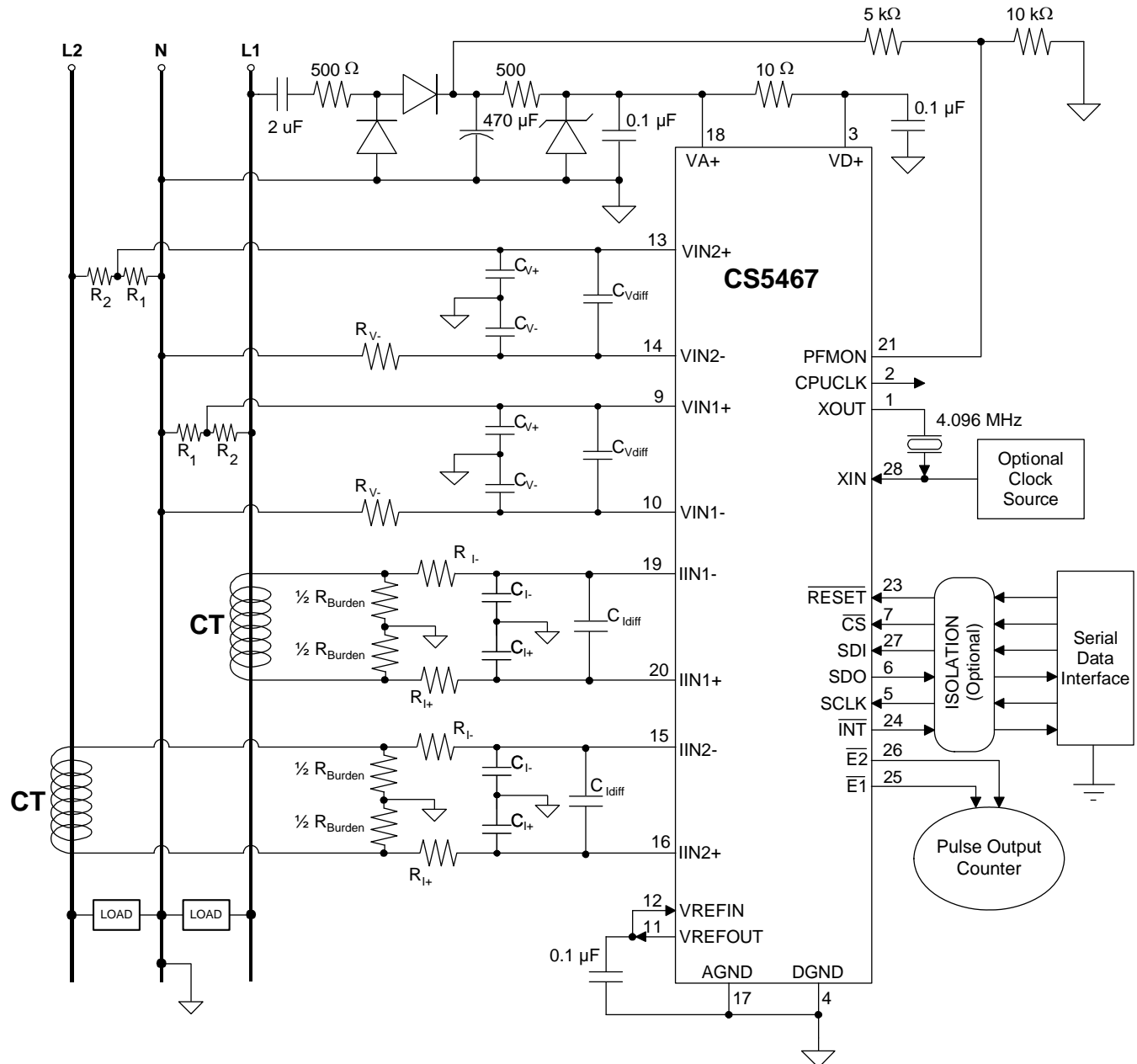
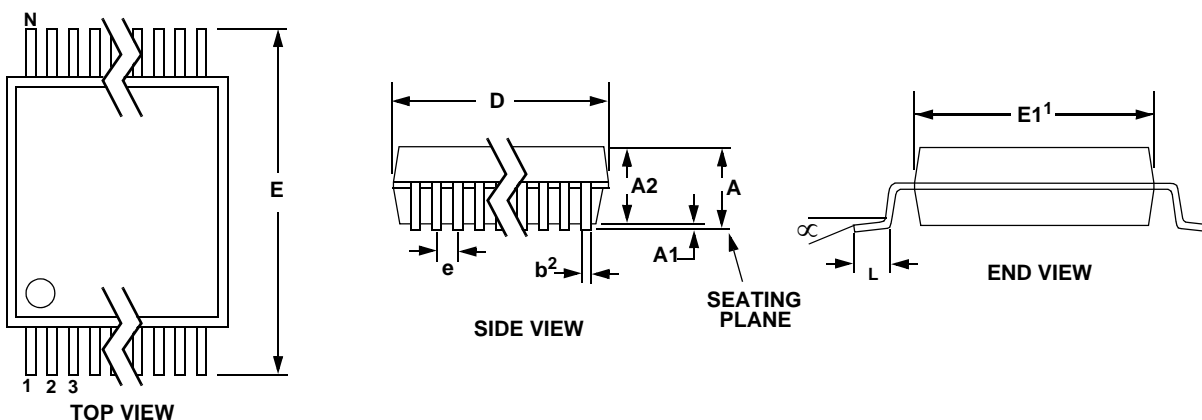


Figure 14. Typical Connection Diagram (Single-phase, 3-wire – Direct Connect to Power Line)

12. PACKAGE DIMENSIONS

28L SSOP PACKAGE DRAWING



| DIM | INCHES | | | MILLIMETERS | | | NOTE |
|----------|--------|--------|-------|-------------|-------|-------|------|
| | MIN | NOM | MAX | MIN | NOM | MAX | |
| A | -- | -- | 0.084 | -- | -- | 2.13 | |
| A1 | 0.002 | 0.006 | 0.010 | 0.05 | 0.15 | 0.25 | |
| A2 | 0.064 | 0.069 | 0.074 | 1.62 | 1.75 | 1.88 | |
| b | 0.009 | -- | 0.015 | 0.22 | -- | 0.38 | 2,3 |
| D | 0.390 | 0.4015 | 0.413 | 9.90 | 10.20 | 10.50 | 1 |
| E | 0.291 | 0.307 | 0.323 | 7.40 | 7.80 | 8.20 | |
| E1 | 0.197 | 0.209 | 0.220 | 5.00 | 5.30 | 5.60 | 1 |
| e | 0.022 | 0.026 | 0.030 | 0.55 | 0.65 | 0.75 | |
| L | 0.025 | 0.0354 | 0.041 | 0.63 | 0.90 | 1.03 | |
| ∞ | 0° | 4° | 8° | 0° | 4° | 8° | |

JEDEC #: MO-150

Controlling Dimension is Millimeters

- Notes:
1. "D" and "E1" are reference datums and do not include mold flash or protrusions, but do include mold mismatch and are measured at the parting line, mold flash or protrusions shall not exceed 0.20 mm per side.
 2. Dimension "b" does not include dambar protrusion/intrusion. Allowable dambar protrusion shall be 0.13 mm total in excess of "b" dimension at maximum material condition. Dambar intrusion shall not reduce dimension "b" by more than 0.07 mm at least material condition.
 3. These dimensions apply to the flat section of the lead between 0.10 and 0.25 mm from lead tips.

13. ORDERING INFORMATION

| Model | Temperature | Package |
|------------------------|---------------|-------------|
| CS5467-ISZ (lead free) | -40 to +85 °C | 28-pin SSOP |

14. ENVIRONMENTAL, MANUFACTURING, & HANDLING INFORMATION

| Model Number | Peak Reflow Temp | MSL Rating* | Max Floor Life |
|------------------------|------------------|-------------|----------------|
| CS5467-ISZ (lead free) | 260 °C | 3 | 7 Days |

* MSL (Moisture Sensitivity Level) as specified by IPC/JEDEC J-STD-020.

15. REVISION HISTORY

| Revision | Date | Changes |
|----------|----------|--|
| PP1 | FEB 2007 | Initial release. |
| PP2 | FEB 2007 | Corrections to implicitly state that temperature measurement is a secondary function of voltage2 channel. Updated typical connection diagram. Changed Phase Compensation Range from $\pm 2.8^\circ$ to $\pm 5.4^\circ$. |
| F1 | MAR 2007 | Updated to F1 for quality process level (QPL). |
| F2 | JAN 2010 | Increased on-chip reference temperature coefficient from 25 ppm / $^\circ\text{C}$ typ. to 40 ppm / $^\circ\text{C}$ typ. |
| F3 | APR 2011 | Removed lead-containing (Pb) device ordering information. |

Contacting Cirrus Logic Support

For all product questions and inquiries contact a Cirrus Logic Sales Representative.

To find the one nearest to you go to www.cirrus.com

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"Preliminary" product information describes products that are in production, but for which full characterization data is not yet available.

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Как с нами связаться

Телефон: 8 (812) 309 58 32 (многоканальный)

Факс: 8 (812) 320-02-42

Электронная почта: org@eplast1.ru

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, дом 2, корпус 4, литера А.