

K-No.: 15101	5-25A Current-Sensor-Module For the electronic measurement of currents: DC, AC, pulsed, mixed ..., with a galvanic Isolation between the primary circuit (high power) and the secondary circuit (electronic circuit)	Date: 26.10.2007
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Description	Characteristics	Applications
<ul style="list-style-type: none"> • Closed loop (compensation) Current Sensor with magnetic field probe • Printed circuit board mounting • Casing and materials UL-listed 	<ul style="list-style-type: none"> • Excellent accuracy • Very low offset current • Very low temperature dependency and offset current drift • Very low hysteresis of offset current • Short response time • Wide frequency bandwidth • Compact design 	Mainly used for stationary operation in industrial applications: <ul style="list-style-type: none"> • AC variabel speed drives and servo motor drives • Static converters for for DC motor drives • Battery supplied applications • Switched Mode Power Supplies (SMPS) • Power Supplies for welding applications • Uninterruptable Power Supplies (UPS)

Electrical Data – Ratings

I _{PN}	Primary rated current, r.m.s	25	A
R _M	Load resistance	0 ... 200	Ω
I _{SN}	Output rated current, r.m.s	12.5	mA
K _N	Turns ratio	1...3 : 2000	

Accuracy – Dynamic performance data (with DRV401 @ V _C = 5V ±5%)		min.	typ	max.	Unit
I _{p,max}	Max. measuring range @ R _M = 12,5 Ω	±85			A
X(T)	Measuring accuracy @ I _{PN} , T _A = -40... +85°C			0.5	%
ε _L	Linearity			0.1	%
I ₀ (T)	Offset current @ I _p =0, T _A = -40... +85°C		0.02	0.05	mA
I _{0H}	Hysteresis		0.02	0.05	mA
t _r	Response time		0.5		μs
Δt(I _{p,max})	Delay time at di/dt = 100 A/μs		0.2		μs
f	Frequency range	DC...100			kHz

General Data

		min.	typ.	max.	Unit
T _A	Ambient temperature	-40		+85	°C
T _S	Storage temperature	-40		+90	°C
m	Mass		15		g
R _S	Secondary coil resistance @ T _A =85°C			80	Ω
R _P	Primary coil resistance per turn @ T _A =25°C		1		mΩ
C _k	Coupling capacity		5		pF
	Mechanical Stress according to M3209/3 Settings: 10 – 2000 Hz, 1 min/Decade, 2 hours			10g	
	Constructed and manufactured and tested in accordance with EN 61800-5-1 (Pin 1 - 6 to Pin 7 – 10) Reinforced insulation, Insulation material group 1, Pollution degree 2				
S _{clear}	clearance (component without solder pad)	10.2			mm
S _{creep}	creepage (component without solder pad)	10.2			mm
V _{sys}	System voltage overvoltage category 3	RMS		600	V
V _{work}	Working voltage (table 7 acc. to EN61800-5-1)	RMS		1020	V
U _{PD}	Rated discharge voltage	peak value		1414	V

Type Testing according EN 61800-5-1 (Pin 1 - 6 to Pin 7 - 10)

V _w	HV transient test according to M3064 (1,2 μs / 50 μs-wave form)		8	kV
V _d	Testing voltage to M3014	(5 s)	3.6	kV
V _e	Partial discharge voltage acc.M3024 (RMS) with V _{vor} (RMS)		1500	V
			1875	V

Datum	Name	Index	Änderung
		81	

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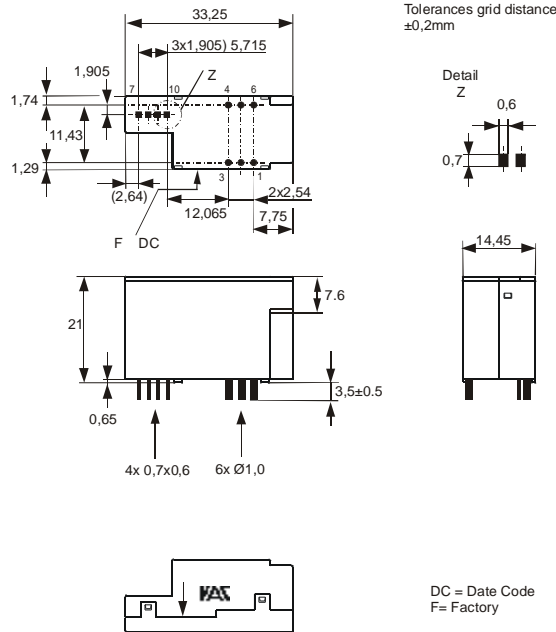
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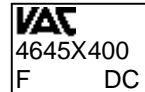
Mechanical outline (mm):

General tolerances DIN ISO 2768-c



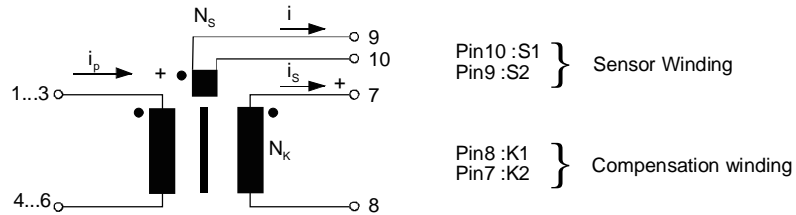
Connections:
1...6: Ø 1.0 mm
7..10: 0.7*0.6 mm

Marking:



DC = Date Code
F = Factory

Schematic diagram



Pin10 :S1
Pin9 :S2 } Sensor Winding

Pin8 :K1
Pin7 :K2 } Compensation winding

Inspection (Measurements after temperature balance of the samples at room temperature.)

K_N (N1/N2)	(V)	M3011/6c:	Turns ratio ($I_p=3^*8A$, 40...80 Hz)	3 : 2000 ± 0,5	%
I_0		M3226:	Offset current	< 0.05	mA
$\Delta\Phi$ (K1-K2)	(V)	M3090:	Magnetic Flux compensation core	4,5...7	nVs
$\Delta\Phi$ (S1-S2)	(V)	M3090:	Magnetic Flux sensor	20...35	nVs
R_S (K1-K2)	(V)	M3011/5:	Winding resistance compensation coil	52...60	Ω
R (S1-S2)	(V)	M3011/5:	Winding resistance magnetic probe coil	2.3...3.0	Ω
V_d	(V)	M3014:	Testing voltage, rms, 1s Pin 1 - 6 to Pin 7 - 10	1.8	kV
V_e	(AQL1/S4)	M3024:	Partial discharge voltage (RMS) with V_{vor} (RMS)	>1500 1875	V V

Applicable documents

Current direction: A positive output current appears at point I_s , by primary current in direction of the arrow.
Temperature of the primary conductor should not exceed 110°C
Housing and bobbin material: UL-listed. Flammability class UL 94V-0.
Enclosures according to IEC 60529: IP50.

Additional data available on request.
This specification is no declaration of warranty acc. BGB §443.

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Explanation of several of the terms used in the tablets (in alphabetical order)
 I_{0H} : Zero variation of I_0 after overloading with a DC of tenfold the rated value ($R_M = R_{MN}$)

 I_{0t} : Long term drift of I_0 after 100 temperature cycles in the range -40 bis 85 °C.

 t_r : Response time (describe the dynamic performance for the specified measurement range), measured as delay time at $I_P = 0,9 \cdot I_{Pmax}$ between a rectangular current and the output current.

 $\Delta t (I_{Pmax})$: Delay time (describe the dynamic performance for the rapid current pulse rate e.g short circuit current) measured between I_{Pmax} and the output current i_a with a primary current rise of $di/dt = 100 A/\mu s$.

 U_{PD} Rated discharge voltage (recurring peak voltage separated by the insulation) proved with a sinusoidal voltage V_e
 $U_{PD} = \sqrt{2} \cdot V_e / 1,5$
 V_{vor} Defined voltage is the RMS value of a sinusoidal voltage with peak value of $1,875 \cdot U_{PD}$ required for partial discharge test in IEC 61800-5-1

$$V_{vor} = 1,875 \cdot U_{PD} / \sqrt{2}$$

 V_{sys} System voltage RMS value of rated voltage according to IEC 61800-5-1

 V_{work} Working voltage voltage according to IEC 61800-5-1 which occurs by design in a circuit or across insulation

 $X_{ges}(I_{PN})$: The sum of all possible errors over the temperature range by measuring a current I_{PN} :

$$X_{ges} = 100 \cdot \left| \frac{I_S(I_{PN})}{K_N \cdot I_{SN}} - 1 \right| \%$$

X: Permissible measurement error in the final inspection at RT, defined by

$$X = 100 \cdot \left| \frac{I_{SB}}{I_{SN}} - 1 \right| \%$$

 where I_{SB} is the output DC value of an input DC current of the same magnitude as the (positive) rated current ($I_0 = 0$)

 X_{Ti} : Temperature drift of the rated value orientated output term. I_{SN} (cf. Notes on F_i) in a specified temperature range, obtained by:

$$X_{Ti} = 100 \cdot \left| \frac{I_{SB}(T_{A2}) - I_{SB}(T_{A1})}{I_{SN}} \right| \%$$

 ϵ_L : Linearity fault defined by $e_L = 100 \cdot \left| \frac{I_P}{I_{PN}} - \frac{I_{Sx}}{I_{SN}} \right| \%$

 Where I_P is any input DC and I_{Sx} the corresponding output term. I_{SN} : see notes of F_i ($I_0 = 0$).

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- Техническая поддержка проекта;
- Защита от снятия компонента с производства.



Как с нами связаться

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