# 10440 (H) x 4800 (V) Interline CCD Image Sensor

### Description

The KAI–50140 image sensor is a 50 megapixel Interline Transfer CCD in a 2.18 to 1 aspect ratio, making it well suited to inspect displays commonly found on modern smartphones. Leveraging a 4.5  $\mu$ m pixel design that provides a 70% resolution increase compared to the KAI–29050 and KAI–29052 devices, the KAI–50140 provides excellent image uniformity and broad dynamic range. A flexible output architecture supports 1, 2, or 4 outputs for full resolution readout of up to 4 frames per second, and a true electronic shutter enables image capture without motion artifacts across a broad range of exposure times.

Parameter	Typical Value
Architecture	Interline CCD, Progressive Scan
Total Number of Pixels	10560 (H) × 4920 (V)
Number of Effective Pixels	10480 (H) × 4840 (V)
Number of Active Pixels	10440 (H) × 4800 (V)
Pixel Size	4.5 μm (H) × 4.5 μm (V)
Active Image Size	46.98 mm (H) × 21.60 mm (V) 51.71 mm (Diag.) 645 1.3× Optical Format
Aspect Ratio	2.175:1
Number of Outputs	1, 2 or 4
Charge Capacity	13,000 electrons
Output Sensitivity	42 μV/e <sup>-</sup>
Quantum Efficiency Pan (-AXA, -QXA) R, G, B (-FXA, -QXA)	45% 27%, 34%, 37%
Read Noise (f = 40 MHz)	13 electrons rms
Dark Current Photodiode VCCD	7 electrons/s 50 electrons/s
Dynamic Range	60 dB
Charge Transfer Efficiency	0.999999
Blooming Suppression	> 300 X
Smear	–98 dB
Image Lag	< 10 electrons
Maximum Pixel Clock Speed	60 MHz
Maximum Frame Rates Quad Output Dual Output Single Output	3.9 fps 2.0 fps 1.1 fps
Package	72 pin PGA
Cover Glass	AR coated, 2 Sides, Sealed Clear Glass, Taped

### **Table 1. GENERAL SPECIFICATIONS**

NOTE: All parameters are specified at T = 40°C unless otherwise noted.



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### Figure 1. KAI–50140 CCD Image Sensor

### Features

- True Electronic Shutter with Broad Exposure Latitude
- Low Noise Architecture
- Excellent Smear Performance
- Monochrome and Bayer Color CFA Configurations

### Applications

- Industrial Imaging and Inspection
- Security and Surveillance

### **ORDERING INFORMATION**

See detailed ordering and shipping information on page 2 of this data sheet.

# **ORDERING INFORMATION**

### Table 2. ORDERING INFORMATION

Part Number	Description	Marking Code
KAI-50140-AXA-JD-B1	Monochrome, Special Microlens, PGA Package, Sealed Clear Cover Glass with AR coating (both sides), Grade 1	KAI-50140-AXA Serial Number
KAI-50140-AXA-JD-B2	Monochrome, Special Microlens, PGA Package, Sealed Clear Cover Glass with AR coating (both sides), Grade 2	
KAI-50140-AXA-JD-AE	Monochrome, Special Microlens, PGA Package, Sealed Clear Cover Glass with AR coating (both sides), Engineering Grade	
KAI-50140-AXA-JP-B1	Monochrome, Special Microlens, PGA Package, Taped Clear Cover Glass (no coatings), Grade 1	KAI-50140-AXA Serial Number
KAI-50140-AXA-JP-B2	Monochrome, Special Microlens, PGA Package, Taped Clear Cover Glass (no coatings), Grade 2	
KAI-50140-AXA-JP-AE	Monochrome, Special Microlens, PGA Package, Taped Clear Cover Glass (no coatings), Engineering Grade	
KAI-50140-FXA-JD-B1	Gen2 Color (Bayer RGB), Special Microlens, PGA Package, Sealed Clear Cover Glass with AR coating (both sides), Grade 1	KAI-50140-FXA Serial Number
KAI-50140-FXA-JD-B2	Gen2 Color (Bayer RGB), Special Microlens, PGA Package, Sealed Clear Cover Glass with AR coating (both sides), Grade 2	
KAI-50140-FXA-JD-AE	Gen2 Color (Bayer RGB), Special Microlens, PGA Package, Sealed Clear Cover Glass with AR coating (both sides), Grade 2	

See the ON Semiconductor *Device Nomenclature* document (TND310/D) for a full description of the naming convention used for image sensors. For reference documentation, including information on evaluation kits, please visit our web site at <a href="http://www.onsemi.com">www.onsemi.com</a>.

# **DEVICE DESCRIPTION**

### Architecture



Figure 2. Block Diagram

### **Dark Reference Pixels**

There are 40 dark reference rows at the top and 40 dark rows at the bottom of the image sensor. The dark rows are not entirely dark and so should not be used for a dark reference level. Use the 40 dark columns on the left or right side of the image sensor as a dark reference. Under normal circumstances use only the center 38 columns of the 40 column dark reference due to potential light leakage.

### **Dummy Pixels**

Within each horizontal shift register there are 12 leading additional shift phases. These pixels are designated as dummy pixels and should not be used to determine a dark reference level. In addition, there is one dummy row of pixels at the top and bottom of the image.

### **Active Buffer Pixels**

20 unshielded pixels adjacent to any leading or trailing dark reference regions are classified as active buffer pixels. These pixels are light sensitive but are not tested for defects and non – uniformities. The 8 outer buffer pixels are less

sensitive than the inner buffer pixels. The inner buffer pixels have the same sensitivity as the 10440 by 4800 active pixels.

#### **Image Acquisition**

An electronic representation of an image is formed when incident photons falling on the sensor plane create electron – hole pairs within the individual silicon photodiodes. These photoelectrons are collected locally by the formation of potential wells at each photo–site. Below photodiode saturation, the number of photoelectrons collected at each pixel is linearly dependent upon light level and exposure time and non – linearly dependent on wavelength. When the photodiodes charge capacity is reached, excess electrons are discharged into the substrate to prevent blooming.

### ESD Protection

Adherence to the power – up and power – down sequence is critical. Failure to follow the proper power – up and power – down sequences may cause damage to the sensor. See Power – Up and Power – Down Sequence section.



Figure 3. Bayer Color Filter Pattern

KAI-50140

# PHYSICAL DESCRIPTION

**Pin Description and Device Orientation** 



Figure 4. Package Pin Description – Top View

### Table 3. PIN DESCRIPTION

Pin	Name	Description	Pin	Name	Description
1	V3B	Vertical CCD Clock, Phase 3, Bottom	72	ESD	ESD Protection Disable
			71	V3T	Vertical CCD Clock, Phase 3, Top
3	V1BT	Vertical CCD Clock, Phase 1, Bottom and Top	70	V4T	Vertical CCD Clock, Phase 4, Top
4	V4B	Vertical CCD Clock, Phase 4, Bottom	69	V1BT	Vertical CCD Clock, Phase 1, Bottom and Top
5	VDDa	Output Amplifier Supply, Quadrant a	68	V2T	Vertical CCD Clock, Phase 2, Top
6	V2B	Vertical CCD Clock, Phase 2, Bottom	67	VDDc	Output Amplifier Supply, Quadrant c
7	GND	Ground	66	VOUTc	Video Output, Quadrant c
8	VOUTa	Video Output, Quadrant a	65	GND	Ground
9	Ra	Reset Gate, Quadrant a	64	RDcd	Reset Drain, Quadrants c and d
10	RDab	Reset Drain, Quadrants a and b	63	Rc	Reset Gate, Quadrant c
11	H2SLa	Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant a	62	OGc	Output Gate, Quadrant c
12	OGa	Output Gate, Quadrant a	61	H2SLc	Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant c
13	H1Ba	Horizontal CCD Clock, Phase 1, Barrier, Quadrant a	60	H2Bc	Horizontal CCD Clock, Phase 2, Barrier, Quadrant c
14	H2Ba	Horizontal CCD Clock, Phase 2, Barrier, Quadrant a	59	H1Bc	Horizontal CCD Clock, Phase 1, Barrier, Quadrant c
15	H2Sa	Horizontal CCD Clock, Phase 2, Storage, Quadrant a	58	H1Sc	Horizontal CCD Clock, Phase 1, Storage, Quadrant c
16	H1Sa	Horizontal CCD Clock, Phase 1, Storage, Quadrant a	57	H2Sc	Horizontal CCD Clock, Phase 2, Storage, Quadrant c
17	SUB	Substrate	56	FDGcd	Fast Line Dump Gate, Top
18	FDGab	Fast Line Dump Gate, Bottom	55	N/C	No Connect
19	N/C	No Connect	54	FDGcd	Fast Line Dump Gate, Top
20	FDGab	Fast Line Dump Gate, Bottom	53	SUB	Substrate
21	H2Sb	Horizontal CCD Clock, Phase 2, Storage, Quadrant b	52	H1Sd	Horizontal CCD Clock, Phase 1, Storage, Quadrant d
22	H1Sb	Horizontal CCD Clock, Phase 1, Storage, Quadrant b	51	H2Sd	Horizontal CCD Clock, Phase 2, Storage, Quadrant d
23	H1Bb	Horizontal CCD Clock, Phase 1, Barrier, Quadrant b	50	H2Bd	Horizontal CCD Clock, Phase 2, Barrier, Quadrant d
24	H2Bb	Horizontal CCD Clock, Phase 2, Barrier, Quadrant b	49	H1Bd	Horizontal CCD Clock, Phase 1, Barrier, Quadrant d
25	H2SLb	Horizontal CCD Clock, Phase 2, Storage, Last Phase, Quadrant b	48	OGd	Output Gate, Quadrant b
26	OGb	Output Gate, Quadrant b	47	H2SLd	Horizontal CCD Clock, Phase 2, Storage, Las Phase, Quadrant d
27	Rb	Reset Gate, Quadrant b	46	RDcd	Reset Drain, Quadrants c and d
28	RDab	Reset Drain, Quadrants a and b	45	Rd	Reset Gate, Quadrant d
29	GND	Ground	44	VOUTd	Video Output, Quadrant d
30	VOUTb	Video Output, Quadrant b	43	GND	Ground
31	VDDb	Output Amplifier Supply, Quadrant b	42	V2T	Vertical CCD Clock, Phase 2, Top
32	V2B	Vertical CCD Clock, Phase 2, Bottom	41	VDDd	Output Amplifier Supply, Quadrant d
00	V1BT	Vertical CCD Clock, Phase 1, Bottom and Top	40	V4T	Vertical CCD Clock, Phase 4, Top
33				VADT	Mailed OOD Olast, Dissa 4, Ballass and Ta
33	V4B	Vertical CCD Clock, Phase 4, Bottom	39	V1BT	Vertical CCD Clock, Phase 1, Bottom and Top
	V4B V3B	Vertical CCD Clock, Phase 4, Bottom Vertical CCD Clock, Phase 3, Bottom	39 38	DevID	Device Identification

Like named pins are internally connected and should have a common drive signal.
 N/C pins (19, 55) should be left floating.

# **IMAGING PERFORMANCE**

### **Table 4. TYPICAL OPERATION CONDITIONS**

Unless otherwise noted, the Imaging Performance Specifications are measured using the following conditions.

Description	Condition	Notes
Light Source	Continuous Red, Green and Blue LED Illumination	For monochrome sensor, only green LED used
Operation	Nominal operating voltages and timing	

### **Table 5. PERFORMANCE PARAMETERS**

Performance parameters are by design

Description		Symbol	Nom.	Units	Notes
Maximum Photo-response Nonlinearity			2	%	2
Horizontal CCD Charge Capacity		HNe	40	ke⁻	
Vertical CCD Charge Capacity		VNe	16	ke⁻	
Photodiode Charge Capacity		PNe	13	ke⁻	3
Image Lag		Lag	< 10	e-	
Anti-blooming Factor		Xab	> 300X		
Vertical Smear			-98	dB	7
Read Noise			13	e⁻rms	4
Dynamic Range		DR	60	dB	4, 5
Output Amplifier DC Offset		Vodc	8	V	
Output Amplifier Bandwidth		f <sub>-3db</sub>	398	MHz	6
Output Amplifier Impedance		Rout	80	Ω	
Output Amplifier Sensitivity		$\Delta V / \Delta N$	42	μV/e⁻	
Peak Quantum Efficiency (KAI – 50140 – AXA and KAI – 50140 – QXA Configurations)		QEmax	45	%	
Peak Quantum Efficiency (KAI – 50140 – AXA and KAI – 50140 – QXA Configurations)	Blue Green Red	QEmax	37 34 27	%	

### **Table 6. PERFORMANCE SPECIFICATIONS**

Description	Symbol	Min.	Nom.	Max.	Units	Temperature Tested At (°C)	Notes
Dark Field Global Non–Uniformity	DSNU	-	-	5	mVpp	40	
Bright Field Global Non-Uniformity	BSNU	-	-	5	%rms	20, 40	1
Bright Field Global Peak to Peak Non-Uniformity	PRNU	-	-	30	%pp	20, 40	1
Maximum Gain Difference Between Outputs	ΔG	-	-	10	%	20, 40	2
Horizontal CCD Charge Transfer Efficiency	HCTE	0.999995	0.999999	-		20, 40	
Vertical CCD Charge Transfer Efficiency	VCTE	0.999995	0.999999	-		20, 40	
Photodiode Dark Current	lpd	-	7	50	e/p/s	20, 40	
Vertical CCD Dark Current	lvd	-	50	200	e/p/s	20, 40	

1. Per color.

2. Value is over the range of 10% to 90% of photodiode saturation.

3. The operating value of the substrate voltage, VAB, will be marked on the shipping container for each device. The value of VAB is set such that the photodiode charge capacity is 546 mV.

4. At 60 MHz. 5. Uses  $20 \times LOG$  (PNe/  $n_{e-T}$ ). 6.  $f_{-3dB} = 1 / (2\pi \cdot R_{OUT} \cdot C_{LOAD})$  where  $C_{LOAD} = 5$  pF. 7. Green LED illumination.

# **TYPICAL PERFORMANCE CURVES**

# **Quantum Efficiency**

Monochrome with Microlens



Gen2 Color (Bayer RGB) with Microlens



Figure 6. Gen2 Color (Bayer RGB) with Microlens Quantum Efficiency

### Angular Quantum Efficiency

For the curves marked "Horizontal", the incident light angle is varied in a plane parallel to the HCCD. For the curves marked "Vertical", the incident light angle is varied in a plane parallel to the VCCD.

# Monochrome with Microlens



Figure 7. Monochrome with Microlens Angular Quantum Efficiency

### Dark Current versus Temperature



Figure 8. Dark Current vs. Temperature

# **Power-Estimated**



Figure 9. Power



Frame Rates

Figure 10. Frame Rates

# **DEFECT DEFINITIONS**

### **Table 7. OPERATING CONDITIONS**

Description	Condition	Notes
Light Source	Continuous Red, Green, Blue, and/or Blue LED Illumination	For the monochrome sensor, only the green LED is used
Operation	Nominal Operating Voltages and Timing	

### **Table 8. OPERATING PARAMETERS**

Description	1 Output	4 Outputs
HCCD Clock Frequency	20 MHz	20 MHz
Pixels Per Line	10560	5280
Lines Per Frame	4920	2460
Line Time	549.6 μs	285.6 μs
Frame Time	2704.1 ms	702.7 ms

### **Table 9. TIMING MODES**

Timing Modes	Conditions
Mode A	1 Output, no electronic shutter used. Photodiode integration time is equal to the Frame Time
Mode B	4 Outputs, no electronic shutter used. Photodiode integration time is equal to the Frame time

### Table 10. DEFECT DEFINITIONS

Description	Definition	Grade 1	Grade 2 (mono)	Grade 2 (color)
Column Defect	A group of more than 10 contiguous pixels along a single column that deviate from the neighboring columns by: • more than 97 mV in the dark field using Timing Mode A at 40°C • more than 97 mV in the dark field using Timing Mode A at 20°C • more than -12% or +16% in the bright field using Timing Mode A at 20°C or 40°C	0	7	2
Cluster Defect	A group of 2 to N contiguous defective pixels, but no more than W adjacent defects horizontally, that deviate from the neighboring pixels by: • more than 570 mV in the dark field using Timing Mode A at 40°C • more than 268 mV in the dark field using Timing Mode A at 20°C • more than -12% or +16% in the bright field using Timing Mode A at 20°C or 40°C	30 W = 4 N–19	70 W = 5 N–38	70 W = 5 N–38
Major Point Defect	A single defective pixel that deviates from the neighboring pixels by: • more than 570 mV in the dark field using Timing Mode A at 40°C • more than 268 mV in the dark field using Timing Mode A at 20°C • more than -12% or +16% in the bright field using Timing Mode A at 20°C or 40°C	400	800	800
Minor Point Defect	A single defective pixel that deviates from the neighboring pixels by: • more than 285 mV in the dark field using Timing Mode A at 40°C	4000	8000	8000

Bright field is define as where the average signal level of the sensor is 382 mV, with the substrate voltage set to the recommend VAB setting such that the capacity of the photodiodes is 546 mV (13,000 electrons).
 For the color devices (KAI-50140-FXA or KAI-50140-QXA), a bright field defective pixel is with respect to pixels of the same color.
 Column and cluster defects are separated by no less than two (2) non-defective pixels in any direction (excluding single pixel defects).

### **Defect Map**

The defect map supplied with each sensor is based upon testing at an ambient  $(27^{\circ}C)$  temperature. Minor point

defects are not included in the defect map. All defective pixels are reference to pixel 1, 1 in the defect maps.



### Figure 11. Pixel 1, 1 Location

### **OPERATION**

### **Absolute Maximum Ratings**

Absolute maximum rating is defined as a level or condition that should not be exceeded at any time per the description. If the level or the condition is exceeded, the device will be degraded and may be damaged. Operation at these values will reduce MTTF.

The KAI–50140 image sensors have configurations with epoxy sealed cover glass. The seal formed is non-hermetic,

and may allow moisture ingress over time, depending on the storage environment. As a result, care must be taken to avoid cooling the device below the dew point inside the package cavity, since this may result in condensation on the sensor. For all KAI–50140 configurations, no warranty, expressed or implied, covers condensation.

Table 11. ABSOLUTE MAXIMUM RATINGS	Table 11.	ABSOLUTE	MAXIMUM	RATINGS
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Description	Symbol	Minimum	Maximum	Units	Notes
Operating Temperature	Тор	-50	+60	°C	1
Parameter Specification Temperature Range	TPSR	+20	+40	°C	2
Output Bias Current, Total for Each Output	lout	-	-15	mA	3

Stresses exceeding those listed in the Maximum Ratings table may damage the device. If any of these limits are exceeded, device functionality should not be assumed, damage may occur and reliability may be affected.

1. Device degradation is not evaluated outside of these temperature ranges.

2. The device will operate effectively within a specified temperature range. Performance may not be guaranteed per the <u>PERFORMANCE</u> <u>SPECIFICATION</u> table for temperatures that are different than those specified within. Noise performance may degrade beyond the specification at die temperatures higher than specified here. Additionally, charge transfer may degrade beyond the specification at temperatures lower than specified here.

3. Avoid shorting output pins to ground or any low impedance source during operation. Irreparable damage will occur and is not covered by warranty. Amplifier bandwidth increases at higher current and lower load capacitance at the expense of reduced gain (sensitivity).

# KAI-50140

Description	Minimum	Maximum	Units	Notes
VDDα, VOUTα	-0.4	+17.5	V	1
RDα	-0.4	+15.5	V	1
V1TB	ESD – 0.4	ESD + 24.0	V	
V2B, V2T, V3B, V3T, V3B, V3T	ESD – 0.4	ESD + 14.0	V	
FDGab, FDGcd	ESD – 0.4	ESD + 15.0	V	
Η1α, Η2α, Η2Lα	ESD – 0.4	ESD + 14.0	V	1
Rα	ESD – 0.4	ESD + 20.0	V	1
ESD	-10.0	0.0	V	
SUB	-0.4	40.0	V	2

1.  $\alpha$  refers to a, b, c, or d.

2. Refer to Application Note Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions.

### Power-Up and Power-Down Sequence

Adherence to the power-up and power-down sequence is critical. Failure to follow the proper power-up and power-down sequences may cause damage to the sensor.



#### NOTES:

- 1. Activate all other biases when ESD is stable and SUB is above 3 V.
- 2. Do not pulse the electronic shutter until ESD is stable.
- 3. VDD cannot be +15 V when SUB is 0 V.
- 4. The VCCD clock waveform must not have a negative overshoot more than 0.4 V below the ESD voltage. See Figure 13.
- 5. The image sensor can be protected from an accidental improper ESD voltage by current limiting the SUB current to less than 10 mA. SUB and VDD must always be greater than GND. ESD must always be less than GND. Placing diodes between SUB, VDD, ESD and ground will protect the sensor from accidental overshoots of SUB, VDD and ESD during power on and power off. See Figure 14.

### Figure 12. Power-Up and Power-Down Sequence

# KAI-50140

The VCCD clock waveform must not have a negative overshoot more than 0.4 V below the ESD voltage.









Description	Pins	Symbol	Minimum	Nominal	Maximum	Units	Max. DC Current	Notes
Reset Drain	RDα	RD	+12.3	+12.5	+12.7	V	10 μA	1
Output Gate	OGα	OG	+2.0	+2.2	+2.4	V	10 μA	1
Output Amplifier Supply	VDDα	VDD	+14.5	+15.0	+15.5	V	11 mA	1, 2
Ground	GND	GND	+0.0	+0.0	+0.0	V	–1.0 mA	
Substrate	SUB	VSUB	+5.0	VAB	VDD	V	50 μA	3, 8
ESD Protection Disable	ESD	ESD	-9.2	-9.0	-8.8	V	50 μA	6, 7
Output Bias Current	VOUTα	lout	-3.0	-5.0	-10.0	mA		1, 4, 5

### **Table 13. DC BIAS OPERATING CONDITIONS**

1.  $\alpha$  denotes a, b, c, or d.

2. The maximum DC current is for one output. Idd = lout + Iss. See Figure 15.

The operating value of the substrate voltage, VAB, will be marked on the shipping container for each device. The value of VAB is set such З. that the photodiode charge capacity is the nominal PNe (see Specifications).

An output load sink must be applied to each VOUT pin to activate each output amplifier.
 Nominal value required for 60 MHz operation per output. May be reduced for slower data rates and lower noise.

6. Adherence to the power-up and power-down sequence is critical. See Power-Up and Power-Down Sequence section.

7. ESD maximum value must be less than or equal to V1\_L - 0.4 V and V2\_L - 0.4 V.

8. Refer to Application Note Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions.



Figure 15. Output Amplifier

## **AC Operating Conditions**

### Table 14. CLOCK LEVELS

Description	Pins (Note 1)	Symbol	Level	Minimum	Nominal	Maximum	Units	Capacitance (Note 2)
Vertical CCD Clock, Phase 1	V1B, V1T	V1_L	Low	-8.2	-8.0	-7.8	V	490 nF
		V1_M	Mid	-0.2	0.0	0.2		
		V1_H	High	+10.3	+10.5	+10.7		
Vertical CCD Clock, Phase 2	V2B, V2T	V2_L	Low	-8.2	-8.0	-7.8	V	280 nF
		V2_H	High	-0.2	0.0	+0.2		
Vertical CCD Clock, Phase 3	V3B, V3T	V3_L	Low	-8.2	-8.0	-7.8	V	300 nF
		V3_H	High	-0.2	0.0	+0.2		
Vertical CCD Clock, Phase 4	V4B, V4T	V4_L	Low	-8.2	-8.0	-7.8	V	280 nF
		V4_H	High	-0.2	0.0	+0.2		
Horizontal CCD Clock,	H1Sa	H1S_L	Low	-0.2	0.0	+0.2	V	840 pF
Phase 1 Storage		H1S_H	High	+4.8	+5.0	+5.2		
Horizontal CCD Clock, Phase 1 Barrier	Η1Βα	H1B_L	Low	-0.2	0.0	+0.2	V	880 pF
		H1B_H	High	+4.8	+5.0	+5.2		
Horizontal CCD Clock,	H2Sa	H2S_L	Low	-0.2	0.0	+0.2	V	720 pF
Phase 2 Storage		H2S_H	High	+4.8	+5.0	+5.2		
Horizontal CCD Clock,	Η2Βα	H2B_L	Low	-0.2	0.0	+0.2	V	600 pF
Phase 2 Barrier		H2B_H	High	+4.8	+5.0	+5.2		
Horizontal CCD Clock,	H2SLa	H2SL_L	Low	-0.2	0.0	+0.2	V	20 pF
Last Phase (Note 3)		H2LS_A	High	4.8	+5.0	+5.2		
Reset Gate	Rα	R_L (Note 4)	Low	+2.0	+.3.0	+3.2	V	20 pF
		R_H	High	+6.8	+7.0	+7.2		
Electronic Shutter (Note 5, 8)	SUB	VES	High	-	-	+40	V	14 nF
		VES_ Offset	Offset	VAB+24	VAB+25	-	V	1
Fast Line Dump Gate	FDGab,	FDG_L	Low	-8.2	-8.0	-7.8	V	260 pF
	FDGcd	FDG_H	High	+4.5	+5.0	+5.5	1	

1.  $\alpha$  denotes a, b, c, or d.

2. Capacitance is total for all like named pins.

3. Use separate clock driver for improved speed performance.

4. Reset low should be set to +2.0 volts for signal levels greater than 26,000 electrons.

5. Refer to Application Note Using Interline CCD Image Sensors in High Intensity Visible Lighting Conditions.

6. Capacitance values are estimated.

7. If the minimum horizontal clock low level is used (-0.2 V), then the maximum horizontal clock amplitude should be used (5 V amplitude) to create a -2.0 V to 4.8 V clock.

8. Figure 16 shows the DC bias (VSUB) and AC clock (VES) applied to the SUB pin. Both the DC bias and AC clock are referenced to ground. The VES\_Offset is referenced to VSUB.



Figure 16. VSUB and VES Reference

# **Device Identification**

The device identification pin (DevID) may be used to determine which ON Semiconductor 4.5 micron pixel interline CCD sensor is being used.

# Table 15. DEVICE IDENTIFICATION

Description	Pins	Symbol	Minimum	Nominal	Maximum	Units	Max. DC Current	Notes
Device Identification	DevID	DevID	4,000	5,000	6,000	Ω	50 μA	1, 2, 3

1. Nominal value subject to verification and/or change during release of preliminary specifications.

2. If the Device Identification is not used, it may be left disconnected.

After Device Identification resistance has been read during camera initialization, it is recommended that the circuit be disabled to prevent localized heating of the sensor due to current flow through the R\_DeviceID resistor.

### Recommended Circuit

Note that V1 must be a different value than V2.



Figure 17. Device Identification Recommended Circuit

# TIMING

# Table 16. REQUIREMENTS AND CHARACTERISTICS

Description	Symbol	Minimum	Nominal	Maximum	Units	Notes
Photodiode Transfer	T <sub>PD</sub>	6	-	_	μs	
VCCD Leading Pedestal	T <sub>3P</sub>	16	-	-	μs	
VCCD Trailing Pedestal	T <sub>3D</sub>	16	-	-	μs	
VCCD Transfer Delay	T <sub>D</sub>	4	-	-	μs	
VCCD Transfer	T <sub>V</sub>	10	-	-	μs	
VCCD Clock Cross-Over	V <sub>VCR</sub>	75	-	100	%	1
VCCD Rise, Fall Time	T <sub>VR</sub> , T <sub>VF</sub>	5	-	10	%	1, 2
FDG Delay	T <sub>FDG</sub>	5	-	-	μs	
HCCD Delay	T <sub>HS</sub>	1	-	-	μs	
HCCD Transfer	T <sub>E</sub>	16.66	-	-	ns	
Shutter Transfer	T <sub>SUB</sub>	1	-	-	μs	
Shutter Delay	T <sub>HD</sub>	1	-	-	μs	
Reset Pulse	T <sub>R</sub>	2.5	-	-	ns	
Reset - Video Delay	T <sub>RV</sub>	-	2.2	-	ns	
H2SL - Video Delay	T <sub>HV</sub>	-	3.1	-	ns	
Line Time	T <sub>LINE</sub>	104.2	-	-	μs	Dual/Quad HCCD Readout
		192.2	-	-		Single HCCD Readout
Frame Time	T <sub>FRAME</sub>	256.4	-	-	ms	Quad HCCD Readout
		512.7	-	-		Dual HCCD Readout
		945.7	-	-		Single HCCD Readout

Refer to Figure 22: VCCD Clock Rise Time, Fall Time and Edge Alignment.
 Relative to the pulse width.

# **Timing Flow Charts**

The timing sequence for the clocked device pins may be represented as one of seven patterns (P1 - P7) as shown in the table below. The patterns are defined in Figure 18 and Figure 19. Contact ON Semiconductor Application Engineering for other readout modes.

Device Pin	Quad Readout	Dual Readout VOUTa, VOUTb	Dual Readout VOUTa, VOUTc	Single Readout VOUTa		
V1BT	P1BT	P1BT	P1BT	P1BT		
V2T	P2T	P4B	P2T	P4B		
V3T	P3T	P3B	P3T	P3B		
V4T	P4T	P2B	P4T	P2B		
V1BT						
V2B		P2	2B			
V3B		P	3B			
V4B		P4	4B			
H1Sa		P	25			
H1Ba						
H2Sa (Note 2)		P	26			
H2Ba						
Ra		P	7			
H1Sb		P5	P5			
H1Bb			P6			
H2Sb (Note 2)		P6	P6			
H2Bb			F	25		
Rb		P7	P7 (Note 1) or Off (Note 3)	P7 (Note 1) or Off (Note 3)		
H1Sc	P5	P5 (Note 1) or Off (Note 3)	P5	P5 (Note 1) or Off (Note 3)		
H1Bc						
H2Sc (Note 2)	P6	P6 (Note 1) or Off (Note 3)	P6	P6 (Note 1) or Off (Note 3		
H2Bc						
Rc	P7	P7 (Note 1) or Off (Note 3)	P7	P7 (Note 1) or Off (Note 3)		
H1Sd	P5	P5 (Note 1) or Off (Note 3)	B) P5 P5 (Note 1) or Off (No			
H1Bd			P6			
H2Sd (Note 2)	P6	P6 (Note 1) or Off (Note 3)	P6	P6 (Note 1) or Off (Note 3)		
H2Bd			P5	1		
Rd	P7	P7 (Note 1) or Off (Note 3)	P7 (Note 1) or Off (Note 3)	P7 (Note 1) or Off (Note 3)		

### **Table 17. TIMING SEQUENCES**

# Lines/Frame (Minimum)	2460	4920	2460	4920
# Pixels/Line (Minimum)	52	92	105	572

1. For optimal performance of the sensor. May be clocked at a lower frequency. If clocked at a lower frequency, the frequency selected should be a multiple of the frequency used on the a and b register.H2SLx follows the same pattern as H2Sx For optimal speed performance, use a separate clock driver.

3. Off = R\_H for the Reset Gate and H\_H for the Horizontal CCD gates. Note that there may be operating conditions (high temperature and/or very bright light sources) that will cause blooming from the unused c/d register into the image area.

# Photodiode Transfer Timing

A row of charge is transferred to the HCCD on the falling edge of V1 as indicated in the P1 pattern below. Using this timing sequence, the leading dummy row or line is combined with the first dark row in the HCCD. The "Last Line" is dependent on readout mode – either 5292 or 10572 minimum counts required. It is important to note that, in general, the rising edge of a vertical clock (patterns P1 – P4) should be coincident or slightly leading a falling edge at the same time interval. This is particularly true at the point where P1 returns from the high ( $3^{rd}$  level) state to the mid – state when P4 transitions from the low state to the high state.



Figure 18. Photodiode Transfer Timing

### Line and Pixel Timing

Each row of charge is transferred to the output, as illustrated below, on the falling edge of H2SL (indicated as P6 pattern). The number of pixels in a row is dependent on

readout mode – either 5292 or 10572 minimum counts required.



Figure 19. Line and Pixel Timing

**Pixel Timing Detail** 



Figure 20. Pixel Timing Detail

# Frame/Electronic Shutter Timing

The SUB pin may be optionally clocked to provide electronic shuttering capability as shown below. The

resulting photodiode integration time is defined from the falling edge of SUB to the falling edge of V1 (P1 pattern).



Figure 21. Electronic Shutter Timing



Figure 22. VCCD Clock Rise Time, Fall Time and Edge Alignment

VCCD Clock Edge Alignment

### Line and Pixel Timing – Vertical Binning by 2



Figure 23. Line and Pixel Timing – Vertical Binning by 2

### **Fast Line Dump Timing**

The FDG pins may be optionally clocked to efficiently remove unwanted lines in the image resulting for increased

frame rates at the expense of resolution. Below is an example of a 2 line dump sequence followed by a normal readout line.



Figure 24. Fast Line Dump Timing

# STORAGE AND HANDLING DETAILS

For information on ESD and cover glass care and cleanliness, please download the *Image Sensor Handling and Best Practices* Application Note (AN52561/D) from <u>www.onsemi.com</u>. Please note that CCD products are not shipped or stored in Moisture Barrier Bags (MBB) and Moisture Sensitivity Level (MSL) ratings are not specified.

For information on soldering recommendations, please download the Soldering and Mounting Techniques Reference Manual (SOLDERRM/D) from www.onsemi.com.

For information on charge binning, please download the KAE-08151 Charge Binning Application Note (AND9569/D) from <u>www.onsemi.com</u>.

For quality and reliability information, please download the *Quality & Reliability* Handbook (HBD851/D) from www.onsemi.com.

For information on device numbering and ordering codes, please download the *Device Nomenclature* technical note (TND310/D) from <u>www.onsemi.com</u>.

For information on Standard terms and Conditions of Sale, please download <u>Terms and Conditions</u> from <u>www.onsemi.com</u>.

# **MECHANICAL INFORMATION**

# **Completed Assembly**



### Notes:

- 1. See Ordering Information for marking code.
- Glass epoxy not to extend over image array.
   No materials to interfere with clearance through package holes.
- 4. Units: mm

# Figure 25. Completed Assembly (1 of 2)

# KAI-50140



Notes:

1. Units: mm



### **Cover Glass**



Notes:

- 1. Substrate = Schott D263T eco
- 2. Dust, Scratch, Inclusion Specification:
- a. 20 µm Max size in Zone A
- 3. MAR coated both sides
- 4. Spectral Transmission
  - . a. 350 365 nm: T ≥ 88%
  - b. 365 405 nm: T  $\geq$  94%
  - c. 405 450 nm: T  $\geq 98\%$
  - c. 450 650 nm: T  $\ge 99\%$ e. 650 690 nm: T  $\ge 98\%$

  - f. 690 770 nm: T  $\ge$  94%
- g. 770 870 nm: T ≥ 88% 5. Units: mm

Figure 27. Cover Glass with AR Coatings

# KAI-50140



Substrate = Schott D263T eco
 Dust, Scratch, Inclusion Specification:

 a. 20 microns maximum size in Zone A
 Units: mm
 Cover glass does not have epoxy

Figure 28. Cover Glass without AR Coatings

### **Cover Glass Transmission**



Figure 29. Cover Glass Transmission

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